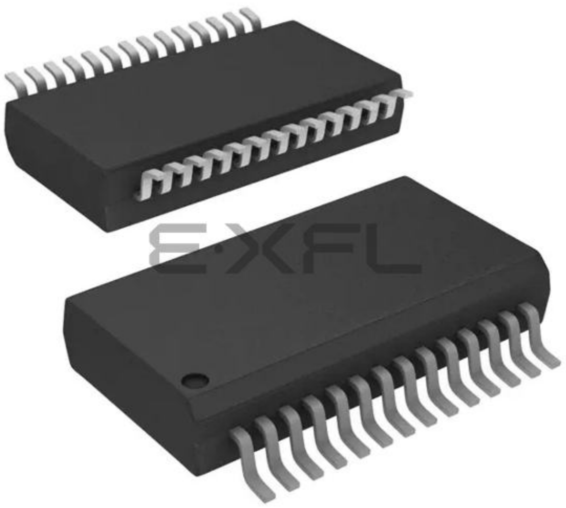
Microchip Technology - PIC16LF1906-I/SS Datasheet



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## What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

## Applications of "Embedded - Microcontrollers"

| Details | |
|---|---|
| Product Status | Active |
| Core Processor | PIC |
| Core Size | 8-Bit |
| Speed | 20MHz |
| Connectivity | LINbus, UART/USART |
| Peripherals | Brown-out Detect/Reset, LCD, POR, PWM, WDT |
| Number of I/O | 25 |
| Program Memory Size | 14KB (8K x 14) |
| Program Memory Type | FLASH |
| EEPROM Size | - |
| RAM Size | 512 x 8 |
| Voltage - Supply (Vcc/Vdd) | 1.8V ~ 3.6V |
| Data Converters | A/D 11x10b |
| Oscillator Type | Internal |
| Operating Temperature | -40°C ~ 85°C (TA) |
| Mounting Type | Surface Mount |
| Package / Case | 28-SSOP (0.209", 5.30mm Width) |
| Supplier Device Package | 28-SSOP |
| Purchase URL | https://www.e-xfl.com/product-detail/microchip-technology/pic16lf1906-i-ss |

**TABLE 1-2: PIC16LF1904/6/7 PINOUT DESCRIPTION**

| Name | Function | Input Type | Output Type | Description |
|---|---|---|---|---|
| RA0/AN0/SEG12 | RA0 | TTL | CMOS | General purpose I/O. |
| | AN0 | AN | — | A/D Channel 0 input. |
| | SEG12 | — | AN | LCD Analog output. |
| RA1/AN1/SEG7 | RA1 | TTL | CMOS | General purpose I/O. |
| | AN1 | AN | — | A/D Channel 1 input. |
| | SEG7 | — | AN | LCD Analog output. |
| RA2/AN2/COM2 | RA2 | TTL | CMOS | General purpose I/O. |
| | AN2 | AN | — | A/D Channel 2 input. |
| | COM2 | — | AN | LCD Analog output. |
| RA3/AN3/VREF+/COM3(2)/SEG15 | RA3 | TTL | CMOS | General purpose I/O. |
| | AN3 | AN | — | A/D Channel 3 input. |
| | VREF+ | AN | — | A/D Voltage Reference input. |
| | COM3 | — | AN | LCD Analog output. |
| | SEG15 | — | AN | LCD Analog output. |
| RA4/T0CKI/SEG4 | RA4 | TTL | CMOS | General purpose I/O. |
| | T0CKI | ST | — | Timer0 clock input. |
| | SEG4 | — | AN | LCD Analog output. |
| RA5/AN4/SEG5 | RA5 | TTL | CMOS | General purpose I/O. |
| | AN4 | AN | — | A/D Channel 4 input. |
| | SEG5 | — | AN | LCD Analog output. |
| RA6/CLKOUT/SEG1 | RA6 | TTL | CMOS | General purpose I/O. |
| | CLKOUT | — | CMOS | FOSC/4 output. |
| | SEG1 | — | AN | LCD Analog output. |
| RA7/CLKIN/SEG2 | RA7 | TTL | CMOS | General purpose I/O. |
| | CLKIN | CMOS | — | External clock input (EC mode). |
| | SEG2 | — | AN | LCD Analog output. |
| RB0/AN12/INT/SEG0 | RB0 | TTL | CMOS | General purpose I/O. |
| | AN12 | AN | — | A/D Channel 12 input. |
| | INT | ST | — | External interrupt. |
| | SEG0 | — | AN | LCD Analog output. |
| RB1(1)/AN10/SEG24/VLCD1 | RB1 | TTL | CMOS | General purpose I/O. |
| | AN10 | AN | — | A/D Channel 10 input. |
| | SEG24 | — | AN | LCD Analog output. |
| | VLCD1 | AN | — | LCD analog input. |
| RB2(1)/AN8/SEG25/VLCD2 | RB2 | TTL | CMOS | General purpose I/O. |
| | AN8 | AN | — | A/D Channel 8 input. |
| | SEG25 | — | AN | LCD Analog output. |
| | VLCD2 | AN | — | LCD analog input. |

**Legend:** AN = Analog input or output; CMOS = CMOS compatible input or output; OD = Open-Drain; TTL = TTL compatible input; ST = Schmitt Trigger input with CMOS levels; $I^2C$ = Schmitt Trigger input with $I^2C$ levels; HV = High Voltage; XTAL = Crystal

**Note 1:** These pins have interrupt-on-change functionality.

**2:** PIC16LF1906/7 only.

# 2.0 ENHANCED MID-RANGE CPU

This family of devices contain an enhanced mid-range 8-bit CPU core. The CPU has 49 instructions. Interrupt capability includes automatic context saving. The hardware stack is 16 levels deep and has Overflow and Underflow Reset capability. Direct, Indirect, and Relative addressing modes are available. Two File Select Registers (FSRs) provide the ability to read program and data memory.

- Automatic Interrupt Context Saving
- 16-level Stack with Overflow and Underflow
- File Select Registers
- Instruction Set

## 2.1 Automatic Interrupt Context Saving

During interrupts, certain registers are automatically saved in shadow registers and restored when returning from the interrupt. This saves stack space and user code. See **Section 7.5 "Automatic Context Saving"**, for more information.

## 2.2 16-Level Stack with Overflow and Underflow

These devices have an external stack memory 15 bits wide and 16 words deep. A Stack Overflow or Underflow will set the appropriate bit (STKOVF or STKUNF) in the PCON register, and if enabled, will cause a software Reset. See **Section 3.4 "Stack"** for more details.

## 2.3 File Select Registers

There are two 16-bit File Select Registers (FSR). FSRs can access all file registers and program memory, which allows one Data Pointer for all memory. When an FSR points to program memory, there is one additional instruction cycle in instructions using INDF to allow the data to be fetched. General purpose memory can now also be addressed linearly, providing the ability to access contiguous data larger than 80 bytes. There are also new instructions to support the FSRs. See **Section 3.5 "Indirect Addressing"** for more details.

## 2.4 Instruction Set

There are 49 instructions for the enhanced mid-range CPU to support the features of the CPU. See **Section 21.0 "Instruction Set Summary"** for more details.

### REGISTER 4-1: CONFIGURATION WORD 1

| U-1 | U-1 | R/P-1 | R/P-1 | R/P-1 | U-1 |
|---|---|---|---|---|---|
| — | — | $\overline{\text{CLKOUTEN}}$ | BOREN<1:0> | | — |
| bit 13 | | | | | bit 8 |

| R/P-1 | R/P-1 | R/P-1 | R/P-1 | R/P-1 | U-1 | R/P-1 | R/P-1 |
|---|---|---|---|---|---|---|---|
| $\overline{\text{CP}}$ | MCLRE | $\overline{\text{PWRTE}}$ | WDTE<1:0> | | — | FOSC<1:0> | |
| bit 7 | | | | | | | bit 0 |

| Legend: | | |
|---|---|---|
| R = Readable bit | P = Programmable bit | U = Unimplemented bit, read as '1' |
| '0' = Bit is cleared | '1' = Bit is set | -n = Value when blank or after Bulk Erase |

bit 13-12 **Unimplemented:** Read as '1'

bit 11 **$\overline{\text{CLKOUTEN}}$:** Clock Out Enable bit
1 = CLKOUT function is disabled. I/O function on the CLKOUT pin.
0 = CLKOUT function is enabled on the CLKOUT pin

bit 10-9 **BOREN<1:0>:** Brown-out Reset Enable bits
11 = BOR enabled
10 = BOR enabled during operation and disabled in Sleep
01 = BOR controlled by SBOREN bit of the BORCON register
00 = BOR disabled

bit 8 **Unimplemented:** Read as '1'

bit 7 **$\overline{\text{CP}}$:** Code Protection bit
1 = Program memory code protection is disabled
0 = Program memory code protection is enabled

bit 6 **MCLRE:** $\overline{\text{MCLR}}$/VPP Pin Function Select bit
If LVP bit = 1:
This bit is ignored.
If LVP bit = 0:
1 = $\overline{\text{MCLR}}$/VPP pin function is $\overline{\text{MCLR}}$; Weak pull-up enabled.
0 = $\overline{\text{MCLR}}$/VPP pin function is digital input; $\overline{\text{MCLR}}$ internally disabled; Weak pull-up under control of WPUE3 bit.

bit 5 **$\overline{\text{PWRTE}}$:** Power-up Timer Enable bit
1 = PWRT disabled
0 = PWRT enabled

bit 4-3 **WDTE<1:0>:** Watchdog Timer Enable bit
11 = WDT enabled
10 = WDT enabled while running and disabled in Sleep
01 = WDT controlled by the SWDTEN bit in the WDTCON register
00 = WDT disabled

bit 2 **Unimplemented:** Read as '1'

bit 1-0 **FOSC<1:0>:** Oscillator Selection bits
00 = INTOSC oscillator: I/O function on CLKIN pin
01 = ECL: External Clock, Low-Power mode (0-0.5 MHz): device clock supplied to CLKIN pin
10 = ECM: External Clock, Medium-Power mode (0.5-4 MHz): device clock supplied to CLKIN pin
11 = ECH: External Clock, High-Power mode (4-20 MHz): device clock supplied to CLKIN pin

## 5.3 Low-Power Brown-out Reset (LPBOR)

The Low-Power Brown-Out Reset (LPBOR) is an essential part of the Reset subsystem. Refer to Figure 5-1 to see how the BOR interacts with other modules.

The LPBOR is used to monitor the external VDD pin. When too low of a voltage is detected, the device is held in Reset. When this occurs, a register bit (BOR) is changed to indicate that a BOR Reset has occurred. The same bit is set for both the BOR and the LPBOR. Refer to Register 5-2.

### 5.3.1 ENABLING LPBOR

The LPBOR is controlled by the LPBOR bit of Configuration Word 2. When the device is erased, the LPBOR module defaults to disabled.

#### 5.3.1.1 LPBOR Module Output

The output of the LPBOR module is a signal indicating whether or not a Reset is to be asserted. This signal is to be OR'd together with the Reset signal of the BOR module to provide the generic BOR signal, which goes to the PCON register and to the power control block.

## 5.4 MCLR

The MCLR is an optional external input that can reset the device. The MCLR function is controlled by the MCLRE bit of Configuration Word 1 and the LVP bit of Configuration Word 2 (Table 5-2).

**TABLE 5-2: MCLR CONFIGURATION**

| MCLRE | LVP | MCLR |
|---|---|---|
| 0 | 0 | Disabled |
| 1 | 0 | Enabled |
| x | 1 | Enabled |

### 5.4.1 MCLR ENABLED

When MCLR is enabled and the pin is held low, the device is held in Reset. The MCLR pin is connected to VDD through an internal weak pull-up.

The device has a noise filter in the MCLR Reset path. The filter will detect and ignore small pulses.

**Note:** A Reset does not drive the MCLR pin low.

### 5.4.2 MCLR DISABLED

When MCLR is disabled, the pin functions as a general purpose input and the internal weak pull-up is under software control. See **Section 11.5 "PORTE Registers"** for more information.

## 5.5 Watchdog Timer (WDT) Reset

The Watchdog Timer generates a Reset if the firmware does not issue a `CLRWDT` instruction within the time-out period. The TO and PD bits in the STATUS register are changed to indicate the WDT Reset. See **Section 9.0 "Watchdog Timer"** for more information.

## 5.6 RESET Instruction

A `RESET` instruction will cause a device Reset. The RI bit in the PCON register will be set to '0'. See Table 5-4 for default conditions after a `RESET` instruction has occurred.

## 5.7 Stack Overflow/Underflow Reset

The device can reset when the Stack Overflows or Underflows. The STKOVF or STKUNF bits of the PCON register indicate the Reset condition. These Resets are enabled by setting the STVREN bit in Configuration Word 2. See **Section 5.7 "Stack Overflow/Underflow Reset"** for more information.

## 5.8 Programming Mode Exit

Upon exit of Programming mode, the device will behave as if a POR had just occurred.

## 5.9 Power-Up Timer

The Power-up Timer optionally delays device execution after a BOR or POR event. This timer is typically used to allow VDD to stabilize before allowing the device to start running.

The Power-up Timer is controlled by the PWRTE bit of Configuration Word 1.

## 5.10 Start-up Sequence

Upon the release of a POR or BOR, the following must occur before the device will begin executing:

1. Power-up Timer runs to completion (if enabled).
2. Oscillator start-up timer runs to completion (if required for oscillator source).
3. MCLR must be released (if enabled).

The total time-out will vary based on oscillator configuration and Power-up Timer configuration. See **Section 6.0 "Oscillator Module"** for more information.

The Power-up Timer and oscillator start-up timer run independently of MCLR Reset. If MCLR is kept low long enough, the Power-up Timer and oscillator start-up timer will expire. Upon bringing MCLR high, the device will begin execution immediately (see Figure 5-3). This is useful for testing purposes or to synchronize more than one device operating in parallel.

## 6.4 Oscillator Control Registers

### REGISTER 6-1: OSCCON: OSCILLATOR CONTROL REGISTER

| U-0 | R/W-0/0 | R/W-1/1 | R/W-1/1 | R/W-1/1 | U-0 | R/W-0/0 | R/W-0/0 |
|---|---|---|---|---|---|---|---|
| — | IRCF<3:0> | | | | — | SCS<1:0> | |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | |
|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' |
| u = Bit is unchanged | x = Bit is unknown | -n/n = Value at POR and BOR/Value at all other Resets |
| '1' = Bit is set | '0' = Bit is cleared | |

bit 7 **Unimplemented:** Read as '0'

bit 6-3 **IRCF<3:0>:** Internal Oscillator Frequency Select bits
000x = 31 kHz LF
001x = 31.25 kHz
0100 = 62.5 kHz
0101 = 125 kHz
0110 = 250 kHz
0111 = 500 kHz (default upon Reset)
1000 = 125 kHz(1)
1001 = 250 kHz(1)
1010 = 500 kHz(1)
1011 = 1 MHz
1100 = 2 MHz
1101 = 4 MHz
1110 = 8 MHz
1111 = 16 MHz

bit 2 **Unimplemented:** Read as '0'

bit 1-0 **SCS<1:0>:** System Clock Select bits
1x = Internal oscillator block
01 = Secondary oscillator
00 = Clock determined by FOSC<1:0> in Configuration Word 1.

**Note 1:** Duplicate frequency derived from HFINTOSC.

## 7.0 INTERRUPTS

The interrupt feature allows certain events to preempt normal program flow. Firmware is used to determine the source of the interrupt and act accordingly. Some interrupts can be configured to wake the MCU from Sleep mode.

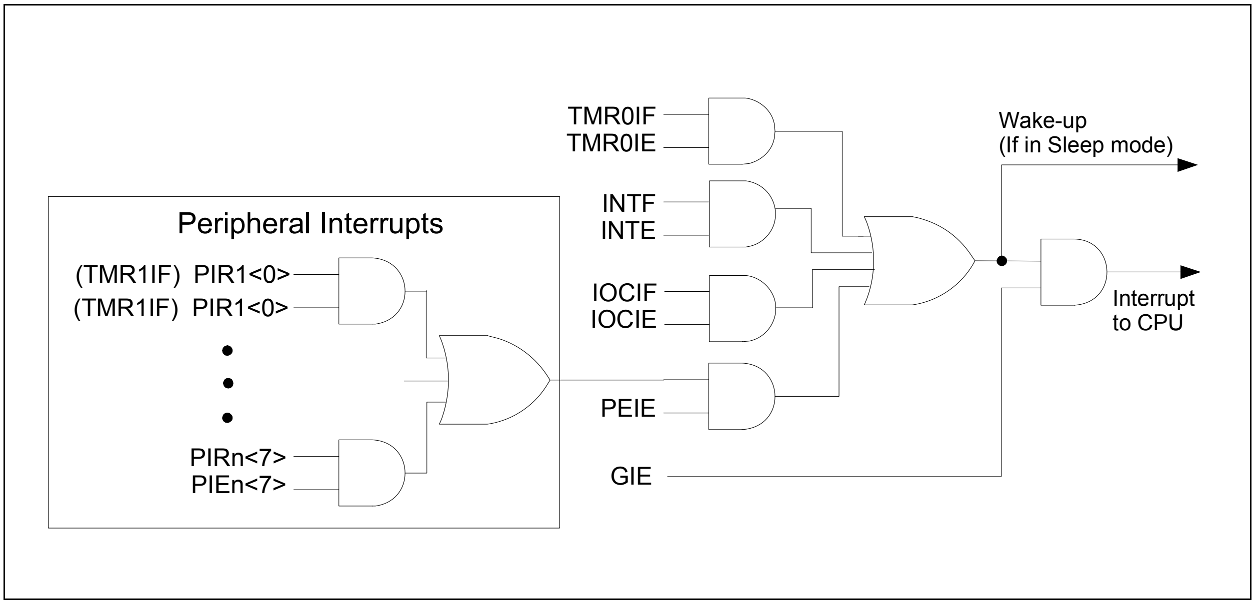
This chapter contains the following information for Interrupts:

- Operation
- Interrupt Latency
- Interrupts During Sleep
- INT Pin
- Automatic Context Saving

Many peripherals produce Interrupts. Refer to the corresponding chapters for details.

A block diagram of the interrupt logic is shown in Figure 7.1.

**FIGURE 7-1: INTERRUPT LOGIC**



## 7.6 Interrupt Control Registers

### 7.6.1 INTCON REGISTER

The INTCON register is a readable and writable register, which contains the various enable and flag bits for TMR0 register overflow, interrupt-on-change and external INT pin interrupts.

| | |
|---|---|
| **Note:** | Interrupt flag bits are set when an interrupt condition occurs, regardless of the state of its corresponding enable bit or the Global Enable bit, GIE of the INTCON register. User software should ensure the appropriate interrupt flag bits are clear prior to enabling an interrupt. |

**REGISTER 7-1: INTCON: INTERRUPT CONTROL REGISTER**

| R/W-0/0 | R/W-0/0 | R/W-0/0 | R/W-0/0 | R/W-0/0 | R/W-0/0 | R/W-0/0 | R-0/0 |
|---|---|---|---|---|---|---|---|
| GIE | PEIE | TMR0IE | INTE | IOCIE | TMR0IF | INTF | IOCIF |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | |
|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as ‘0’ |
| u = Bit is unchanged | x = Bit is unknown | -n/n = Value at POR and BOR/Value at all other Resets |
| ‘1’ = Bit is set | ‘0’ = Bit is cleared | |

| | |
|---|---|
| bit 7 | **GIE:** Global Interrupt Enable bit<br>1 = Enables all active interrupts<br>0 = Disables all interrupts |
| bit 6 | **PEIE:** Peripheral Interrupt Enable bit<br>1 = Enables all active peripheral interrupts<br>0 = Disables all peripheral interrupts |
| bit 5 | **TMR0IE:** Timer0 Overflow Interrupt Enable bit<br>1 = Enables the Timer0 interrupt<br>0 = Disables the Timer0 interrupt |
| bit 4 | **INTE:** INT External Interrupt Enable bit<br>1 = Enables the INT external interrupt<br>0 = Disables the INT external interrupt |
| bit 3 | **IOCIE:** Interrupt-on-Change Interrupt Enable bit<br>1 = Enables the interrupt-on-change interrupt<br>0 = Disables the interrupt-on-change interrupt |
| bit 2 | **TMR0IF:** Timer0 Overflow Interrupt Flag bit<br>1 = TMR0 register has overflowed<br>0 = TMR0 register did not overflow |
| bit 1 | **INTF:** INT External Interrupt Flag bit<br>1 = The INT external interrupt occurred<br>0 = The INT external interrupt did not occur |
| bit 0 | **IOCIF:** Interrupt-on-Change Interrupt Flag bit<br>1 = When at least one of the interrupt-on-change pins changed state<br>0 = None of the interrupt-on-change pins have changed state |

### 7.6.4 PIR1 REGISTER

The PIR1 register contains the interrupt flag bits, as shown in Register 7-4.

| **Note:** | Interrupt flag bits are set when an interrupt condition occurs, regardless of the state of its corresponding enable bit or the Global Enable bit, GIE, of the INTCON register. User software should ensure the appropriate interrupt flag bits are clear prior to enabling an interrupt. |
|---|---|

**REGISTER 7-4: PIR1: PERIPHERAL INTERRUPT REQUEST REGISTER 1**

| R/W-0/0 | R/W-0/0 | R/W-0/0 | R/W-0/0 | U-0 | U-0 | U-0 | R/W-0/0 |
|---|---|---|---|---|---|---|---|
| TMR1GIF | ADIF | RCIF | TXIF | — | — | — | TMR1IF |
| bit 7 | | | | | | | bit 0 |

| **Legend:** | | |
|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as ‘0’ |
| u = Bit is unchanged | x = Bit is unknown | -n/n = Value at POR and BOR/Value at all other Resets |
| ‘1’ = Bit is set | ‘0’ = Bit is cleared | |

bit 7 **TMR1GIF:** Timer1 Gate Interrupt Flag bit
1 = Interrupt is pending
0 = Interrupt is not pending

bit 6 **ADIF:** A/D Converter Interrupt Flag bit
1 = Interrupt is pending
0 = Interrupt is not pending

bit 5 **RCIF:** USART Receive Interrupt Flag bit
1 = Interrupt is pending
0 = Interrupt is not pending

bit 4 **TXIF:** USART Transmit Interrupt Flag bit
1 = Interrupt is pending
0 = Interrupt is not pending

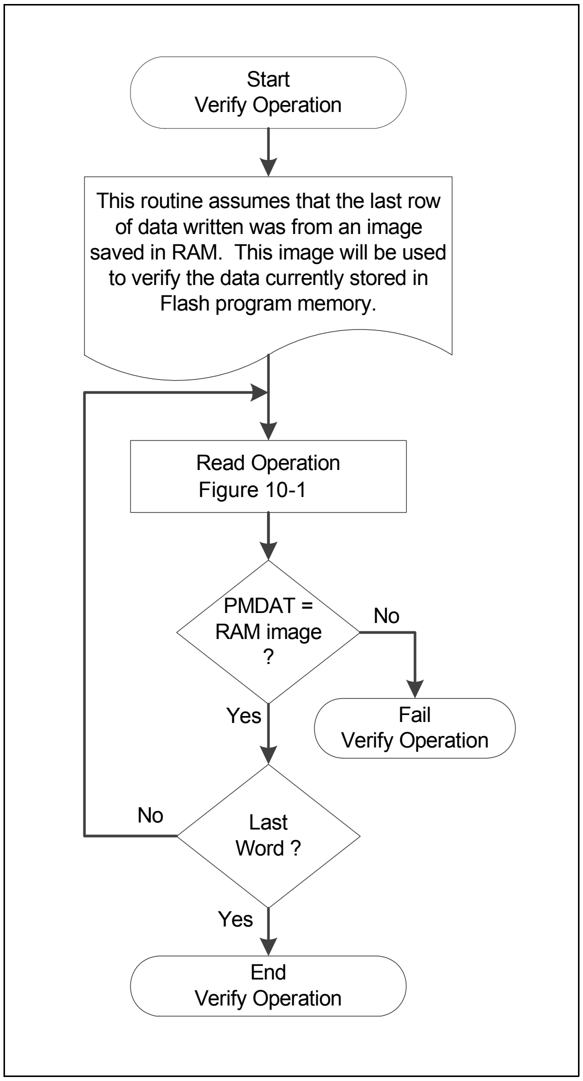
bit 3-1 **Unimplemented:** Read as ‘0’

bit 0 **TMR1IF:** Timer1 Overflow Interrupt Flag bit
1 = Interrupt is pending
0 = Interrupt is not pending

## 10.5 Write Verify

It is considered good programming practice to verify that program memory writes agree with the intended value. Since program memory is stored as a full page then the stored program memory contents are compared with the intended data stored in RAM after the last write is complete.

**FIGURE 10-8: FLASH PROGRAM MEMORY VERIFY FLOWCHART**



## 10.6 Flash Program Memory Control Registers

### REGISTER 10-1: PMDATL: PROGRAM MEMORY DATA LOW BYTE REGISTER

| R/W-x/u | R/W-x/u | R/W-x/u | R/W-x/u | R/W-x/u | R/W-x/u | R/W-x/u | R/W-x/u |
|---|---|---|---|---|---|---|---|
| PMDAT<7:0> | | | | | | | |
| bit 7 | | | | | | | bit 0 |

| Legend: | | |
|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as ‘0’ |
| u = Bit is unchanged | x = Bit is unknown | -n/n = Value at POR and BOR/Value at all other Resets |
| ‘1’ = Bit is set | ‘0’ = Bit is cleared | |

bit 7-0 **PMDAT<7:0>**: Read/write value for Least Significant bits of program memory

### REGISTER 10-2: PMDATH: PROGRAM MEMORY DATA HIGH BYTE REGISTER

| U-0 | U-0 | R/W-x/u | R/W-x/u | R/W-x/u | R/W-x/u | R/W-x/u | R/W-x/u |
|---|---|---|---|---|---|---|---|
| — | — | PMDAT<13:8> | | | | | |
| bit 7 | | | | | | | bit 0 |

| Legend: | | |
|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as ‘0’ |
| u = Bit is unchanged | x = Bit is unknown | -n/n = Value at POR and BOR/Value at all other Resets |
| ‘1’ = Bit is set | ‘0’ = Bit is cleared | |

bit 7-6 **Unimplemented:** Read as ‘0’

bit 5-0 **PMDAT<13:8>**: Read/write value for Most Significant bits of program memory

### REGISTER 10-3: PMADRL: PROGRAM MEMORY ADDRESS LOW BYTE REGISTER

| R/W-0/0 | R/W-0/0 | R/W-0/0 | R/W-0/0 | R/W-0/0 | R/W-0/0 | R/W-0/0 | R/W-0/0 |
|---|---|---|---|---|---|---|---|
| PMADR<7:0> | | | | | | | |
| bit 7 | | | | | | | bit 0 |

| Legend: | | |
|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as ‘0’ |
| u = Bit is unchanged | x = Bit is unknown | -n/n = Value at POR and BOR/Value at all other Resets |
| ‘1’ = Bit is set | ‘0’ = Bit is cleared | |

bit 7-0 **PMADR<7:0>**: Specifies the Least Significant bits for program memory address

### REGISTER 10-4: PMADRH: PROGRAM MEMORY ADDRESS HIGH BYTE REGISTER

| U-1 | R/W-0/0 | R/W-0/0 | R/W-0/0 | R/W-0/0 | R/W-0/0 | R/W-0/0 | R/W-0/0 |
|---|---|---|---|---|---|---|---|
| — | PMADR<14:8> | | | | | | |
| bit 7 | | | | | | | bit 0 |

| Legend: | | |
|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as ‘0’ |
| u = Bit is unchanged | x = Bit is unknown | -n/n = Value at POR and BOR/Value at all other Resets |
| ‘1’ = Bit is set | ‘0’ = Bit is cleared | |

bit 7 **Unimplemented:** Read as ‘1’

bit 6-0 **PMADR<14:8>**: Specifies the Most Significant bits for program memory address

### REGISTER 11-5: PORTB: PORTB REGISTER

| R/W-x/u | R/W-x/u | R/W-x/u | R/W-x/u | R/W-x/u | R/W-x/u | R/W-x/u | R/W-x/u |
|---|---|---|---|---|---|---|---|
| RB7 | RB6 | RB5 | RB4 | RB3 | RB2 | RB1 | RB0 |
| bit 7 | | | | | | | bit 0 |

| Legend: | | |
|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as ‘0’ |
| u = Bit is unchanged | x = Bit is unknown | -n/n = Value at POR and BOR/Value at all other Resets |
| ‘1’ = Bit is set | ‘0’ = Bit is cleared | |

bit 7-0 **RB<7:0>**: PORTB General Purpose I/O Pin bits(1)
`1` = Port pin is ≥ $V_{IH}$
`0` = Port pin is ≤ $V_{IL}$

**Note 1:** Writes to PORTB are actually written to the corresponding LATB register. Reads from the PORTB register is return of actual I/O pin values.

### REGISTER 11-6: TRISB: PORTB TRI-STATE REGISTER

| R/W-1/1 | R/W-1/1 | R/W-1/1 | R/W-1/1 | R/W-1/1 | R/W-1/1 | R/W-1/1 | R/W-1/1 |
|---|---|---|---|---|---|---|---|
| TRISB7 | TRISB6 | TRISB5 | TRISB4 | TRISB3 | TRISB2 | TRISB1 | TRISB0 |
| bit 7 | | | | | | | bit 0 |

| Legend: | | |
|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as ‘0’ |
| u = Bit is unchanged | x = Bit is unknown | -n/n = Value at POR and BOR/Value at all other Resets |
| ‘1’ = Bit is set | ‘0’ = Bit is cleared | |

bit 7-0 **TRISB<7:0>:** PORTB Tri-State Control bits
`1` = PORTB pin configured as an input (tri-stated)
`0` = PORTB pin configured as an output

### REGISTER 11-7: LATB: PORTB DATA LATCH REGISTER

| R/W-x/u | R/W-x/u | R/W-x/u | R/W-x/u | R/W-x/u | R/W-x/u | R/W-x/u | R/W-x/u |
|---|---|---|---|---|---|---|---|
| LATB7 | LATB6 | LATB5 | LATB4 | LATB3 | LATB2 | LATB1 | LATB0 |
| bit 7 | | | | | | | bit 0 |

| Legend: | | |
|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as ‘0’ |
| u = Bit is unchanged | x = Bit is unknown | -n/n = Value at POR and BOR/Value at all other Resets |
| ‘1’ = Bit is set | ‘0’ = Bit is cleared | |

bit 7-0 **LATB<7:0>**: PORTB Output Latch Value bits(1)

**Note 1:** Writes to PORTB are actually written to the corresponding LATB register. Reads from the PORTB register is return of actual I/O pin values.

## 11.5 PORTE Registers

RE3 is input only, and also functions as $\overline{\text{MCLR}}$. The $\overline{\text{MCLR}}$ feature can be disabled via a configuration fuse. RE3 also supplies the programming voltage. The TRIS bit for RE3 (TRISE3) always reads '1'.

### 11.5.1 PORTE FUNCTIONS AND OUTPUT PRIORITIES

No output priorities, RE3 is an input only pin.

**REGISTER 11-16: PORTE: PORTE REGISTER**

| U-0 | U-0 | U-0 | U-0 | R-x/u | U-0 | U-0 | U-0 |
|---|---|---|---|---|---|---|---|
| — | — | — | — | RE3 | RE2(1) | RE1(1) | RE0(1) |
| bit 7 | | | | | | | bit 0 |

| Legend: | | |
|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' |
| u = Bit is unchanged | x = Bit is unknown | -n/n = Value at POR and BOR/Value at all other Resets |
| '1' = Bit is set | '0' = Bit is cleared | |

bit 7-4 **Unimplemented**: Read as '0'

bit 3-0 **RE<3:0>**: PORTE Input Pin bit(1)
1 = Port pin is > $V_{IH}$
0 = Port pin is < $V_{IL}$

**2:** RE<2:0> are not implemented on the PIC16LF1906. Read as '0'. Writes to RE<2:0> are actually written to the corresponding LATE register. Reads from the PORTE register is the return of actual I/O pin values.

**REGISTER 11-17: TRISE: PORTE TRI-STATE REGISTER**

| U-0 | U-0 | U-0 | U-0 | U-1(1) | R/W-1/1(2) | R/W-1/1(2) | R/W-1/1(2) |
|---|---|---|---|---|---|---|---|
| — | — | — | — | — | TRISE2 | TRISE1 | TRISE0 |
| bit 7 | | | | | | | bit 0 |

| Legend: | | |
|---|---|---|
| R = Readable bit | W = Writable bit | U = Unimplemented bit, read as '0' |
| u = bit is unchanged | x = Bit is unknown | -n/n = Value at POR and BOR/Value at all other Resets |
| '1' = Bit is set | '0' = Bit is cleared | |

bit 7-4 **Unimplemented**: Read as '0'

bit 3 **Unimplemented**: Read as '1'

bit 2-0 **TRISE<2:0>:** PORTE Tri-State Control bits(2)
1 = Port output driver is disabled
0 = Port output driver is enabled

**Note 1:** Unimplemented, read as '1'.

**2:** TRISE<2:0> are not implemented on the PIC16LF1906. Read as '0'.

# 13.0 FIXED VOLTAGE REFERENCE (FVR)

The Fixed Voltage Reference (FVR) is a stable voltage reference, independent of VDD, with 1.024V or 2.048V selectable output levels. The output of the FVR can be configured as the FVR input channel on the ADC.

The FVR can be enabled by setting the FVREN bit of the FVRCON register.

## 13.1 Independent Gain Amplifiers

The output of the FVR supplied to the ADC is routed through two independent programmable gain amplifiers. Each amplifier can be configured to amplify the reference voltage by 1x or 2x, to produce the two possible voltage levels.

The ADFVR<1:0> bits of the FVRCON register are used to enable and configure the gain amplifier settings for the reference supplied to the ADC module. Reference **Section 15.0 “Analog-to-Digital Converter (ADC) Module”** for additional information.

## 13.2 FVR Stabilization Period

When the Fixed Voltage Reference module is enabled, it requires time for the reference and amplifier circuits to stabilize. Once the circuits stabilize and are ready for use, the FVRRDY bit of the FVRCON register will be set. See **Section 22.0 “Electrical Specifications”** for the minimum delay requirement.

**FIGURE 13-1: VOLTAGE REFERENCE BLOCK DIAGRAM**

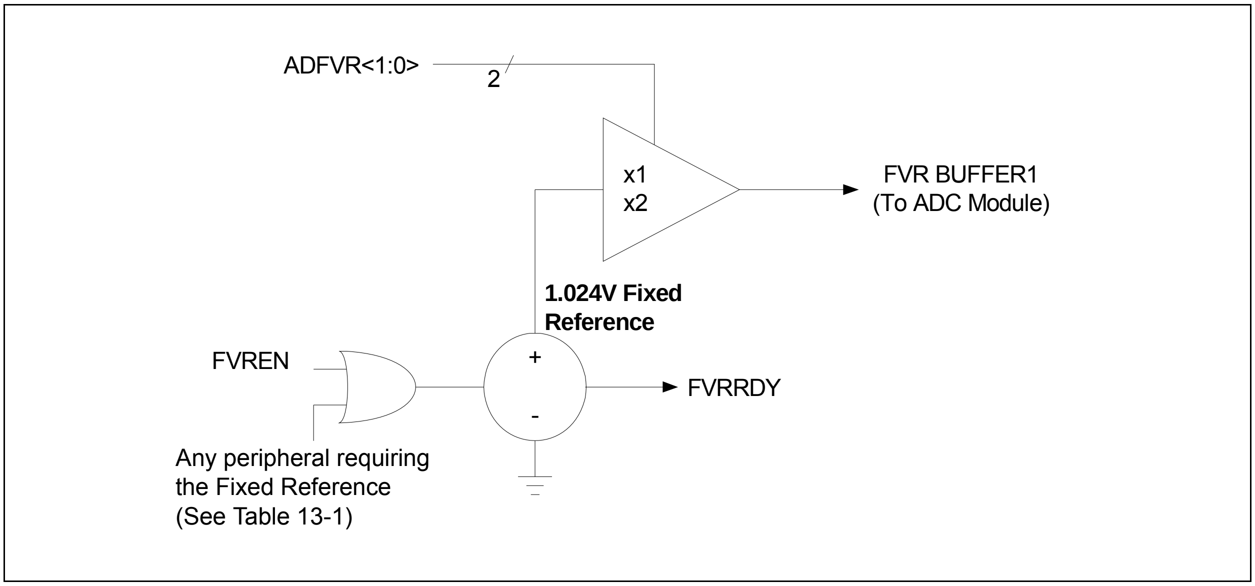



**TABLE 13-1: PERIPHERALS REQUIRING THE FIXED VOLTAGE REFERENCE (FVR)**

| Peripheral | Conditions | Description |
|---|---|---|
| HFINTOSC | FOSC<2:0> = `100` and IRCF<3:0> = `000x` | INTOSC is active and device is not in Sleep. |
| BOR | BOREN<1:0> = `11` | BOR always enabled. |
| | BOREN<1:0> = `10` and BORFS = `1` | BOR disabled in Sleep mode, BOR Fast Start enabled. |
| | BOREN<1:0> = `01` and BORFS = `1` | BOR under software control, BOR Fast Start enabled. |

### 15.1.5 INTERRUPTS

The ADC module allows for the ability to generate an interrupt upon completion of an Analog-to-Digital conversion. The ADC Interrupt Flag is the ADIF bit in the PIR1 register. The ADC Interrupt Enable is the ADIE bit in the PIE1 register. The ADIF bit must be cleared in software.

> **Note 1:** The ADIF bit is set at the completion of every conversion, regardless of whether or not the ADC interrupt is enabled.
>
> **2:** The ADC operates during Sleep only when the FRC oscillator is selected.

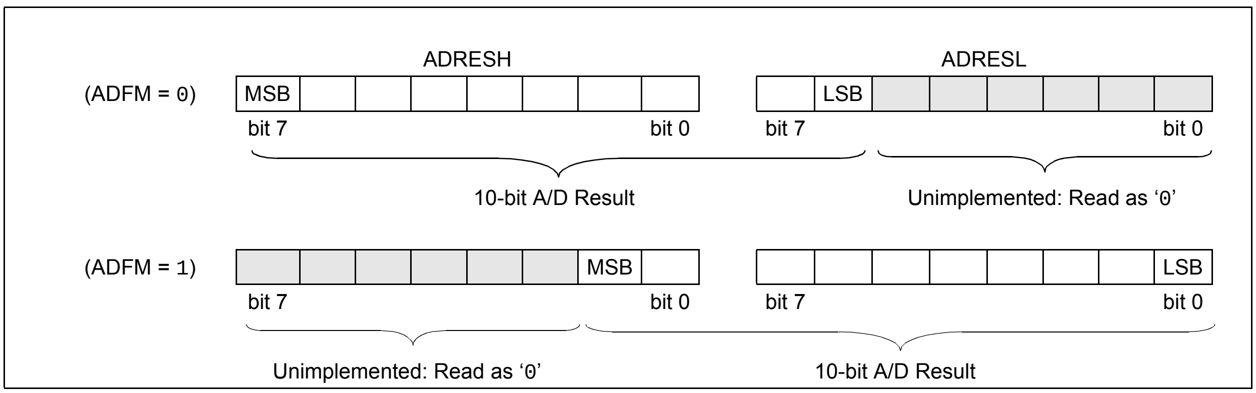
This interrupt can be generated while the device is operating or while in Sleep. If the device is in Sleep, the interrupt will wake-up the device. Upon waking from Sleep, the next instruction following the `SLEEP` instruction is always executed. If the user is attempting to wake-up from Sleep and resume in-line code execution, the GIE and PEIE bits of the INTCON register must be disabled. If the GIE and PEIE bits of the INTCON register are enabled, execution will switch to the Interrupt Service Routine.

### 15.1.6 RESULT FORMATTING

The 10-bit A/D conversion result can be supplied in two formats, left justified or right justified. The ADFM bit of the ADCON1 register controls the output format.

Figure 15-3 shows the two output formats.

**FIGURE 15-3: 10-BIT A/D CONVERSION RESULT FORMAT**



## 17.7 Timer1 Interrupt

The Timer1 register pair (TMR1H:TMR1L) increments to FFFFh and rolls over to 0000h. When Timer1 rolls over, the Timer1 interrupt flag bit of the PIR1 register is set. To enable the interrupt on rollover, you must set these bits:

- TMR1ON bit of the T1CON register
- TMR1IE bit of the PIE1 register
- PEIE bit of the INTCON register
- GIE bit of the INTCON register

The interrupt is cleared by clearing the TMR1IF bit in the Interrupt Service Routine.

| **Note:** | The TMR1H:TMR1L register pair and the TMR1IF bit should be cleared before enabling interrupts. |
|---|---|

## 17.8 Timer1 Operation During Sleep

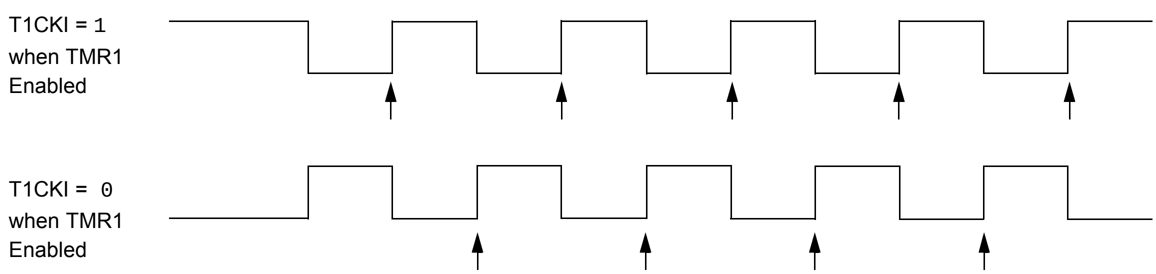
Timer1 can only operate during Sleep when setup in Asynchronous Counter mode. In this mode, an external crystal or clock source can be used to increment the counter. To set up the timer to wake the device:

- TMR1ON bit of the T1CON register must be set
- TMR1IE bit of the PIE1 register must be set
- PEIE bit of the INTCON register must be set
- $\overline{\text{T1SYNC}}$ bit of the T1CON register must be set
- TMR1CS bits of the T1CON register must be configured
- T1OSCEN bit of the T1CON register must be configured

The device will wake-up on an overflow and execute the next instructions. If the GIE bit of the INTCON register is set, the device will call the Interrupt Service Routine.

Timer1 oscillator will continue to operate in Sleep regardless of the $\overline{\text{T1SYNC}}$ bit setting.

**FIGURE 17-2: TIMER1 INCREMENTING EDGE**




**Note 1:** Arrows indicate counter increments.

**2:** In Counter mode, a falling edge must be registered by the counter prior to the first incrementing rising edge of the clock.

#### 18.5.1.5 Synchronous Master Reception

Data is received at the RX/DT pin. The RX/DT pin output driver must be disabled by setting the corresponding TRIS bits when the EUSART is configured for synchronous master receive operation.

In Synchronous mode, reception is enabled by setting either the Single Receive Enable bit (SREN of the RCSTA register) or the Continuous Receive Enable bit (CREN of the RCSTA register).

When SREN is set and CREN is clear, only as many clock cycles are generated as there are data bits in a single character. The SREN bit is automatically cleared at the completion of one character. When CREN is set, clocks are continuously generated until CREN is cleared. If CREN is cleared in the middle of a character the CK clock stops immediately and the partial character is discarded. If SREN and CREN are both set, then SREN is cleared at the completion of the first character and CREN takes precedence.

To initiate reception, set either SREN or CREN. Data is sampled at the RX/DT pin on the trailing edge of the TX/CK clock pin and is shifted into the Receive Shift Register (RSR). When a complete character is received into the RSR, the RCIF bit is set and the character is automatically transferred to the two character receive FIFO. The Least Significant eight bits of the top character in the receive FIFO are available in RCREG. The RCIF bit remains set as long as there are un-read characters in the receive FIFO.

#### 18.5.1.6 Slave Clock

Synchronous data transfers use a separate clock line, which is synchronous with the data. A device configured as a slave receives the clock on the TX/CK line. The TX/CK pin output driver must be disabled by setting the associated TRIS bit when the device is configured for synchronous slave transmit or receive operation. Serial data bits change on the leading edge to ensure they are valid at the trailing edge of each clock. One data bit is transferred for each clock cycle. Only as many clock cycles should be received as there are data bits.

#### 18.5.1.7 Receive Overrun Error

The receive FIFO buffer can hold two characters. An overrun error will be generated if a third character, in its entirety, is received before RCREG is read to access the FIFO. When this happens the OERR bit of the RCSTA register is set. Previous data in the FIFO will not be overwritten. The two characters in the FIFO buffer can be read, however, no additional characters will be received until the error is cleared. The OERR bit can only be cleared by clearing the overrun condition. If the overrun error occurred when the SREN bit is set and CREN is clear then the error is cleared by reading RCREG.

If the overrun occurred when the CREN bit is set then the error condition is cleared by either clearing the CREN bit of the RCSTA register or by clearing the SPEN bit which resets the EUSART.

#### 18.5.1.8 Receiving 9-bit Characters

The EUSART supports 9-bit character reception. When the RX9 bit of the RCSTA register is set the EUSART will shift nine bits into the RSR for each character received. The RX9D bit of the RCSTA register is the ninth, and Most Significant, data bit of the top unread character in the receive FIFO. When reading 9-bit data from the receive FIFO buffer, the RX9D data bit must be read before reading the eight Least Significant bits from the RCREG.

#### 18.5.1.9 Synchronous Master Reception Set-up:

1. Initialize the SPBRGH, SPBRGL register pair for the appropriate baud rate. Set or clear the BRGH and BRG16 bits, as required, to achieve the desired baud rate.
2. Set the RX/DT and TX/CK TRIS controls to ‘1’.
3. Enable the synchronous master serial port by setting bits SYNC, SPEN and CSRC. Disable RX/DT and TX/CK output drivers by setting the corresponding TRIS bits.
4. Ensure bits CREN and SREN are clear.
5. If using interrupts, set the GIE and PEIE bits of the INTCON register and set RCIE.
6. If 9-bit reception is desired, set bit RX9.
7. Start reception by setting the SREN bit or for continuous reception, set the CREN bit.
8. Interrupt flag bit RCIF will be set when reception of a character is complete. An interrupt will be generated if the enable bit RCIE was set.
9. Read the RCSTA register to get the ninth bit (if enabled) and determine if any error occurred during reception.
10. Read the 8-bit received data by reading the RCREG register.
11. If an overrun error occurs, clear the error by either clearing the CREN bit of the RCSTA register or by clearing the SPEN bit which resets the EUSART.

## 19.2 LCD Clock Source Selection

The LCD module has three possible clock sources:

- FOSC/256
- T1OSC
- LFINTOSC

The first clock source is the system clock divided by 256 (FOSC/256). This divider ratio is chosen to provide about 1 kHz output when the system clock is 8 MHz. The divider is not programmable. Instead, the LCD prescaler bits LP<3:0> of the LCDPS register are used to set the LCD frame clock rate.

The second clock source is the T1OSC. This also gives about 1 kHz when a 32.768 kHz crystal is used with the Timer1 oscillator. To use the Timer1 oscillator as a clock source, the T1OSCEN bit of the T1CON register should be set.

The third clock source is the 31 kHz LFINTOSC, which provides approximately 1 kHz output.

The second and third clock sources may be used to continue running the LCD while the processor is in Sleep.

Using bits CS<1:0> of the LCDCON register can select any of these clock sources.

### 19.2.1 LCD PRESCALER

A 4-bit counter is available as a prescaler for the LCD clock. The prescaler is not directly readable or writable; its value is set by the LP<3:0> bits of the LCDPS register, which determine the prescaler assignment and prescale ratio.

The prescale values are selectable from 1:1 through 1:16.

**FIGURE 19-2: LCD CLOCK GENERATION**

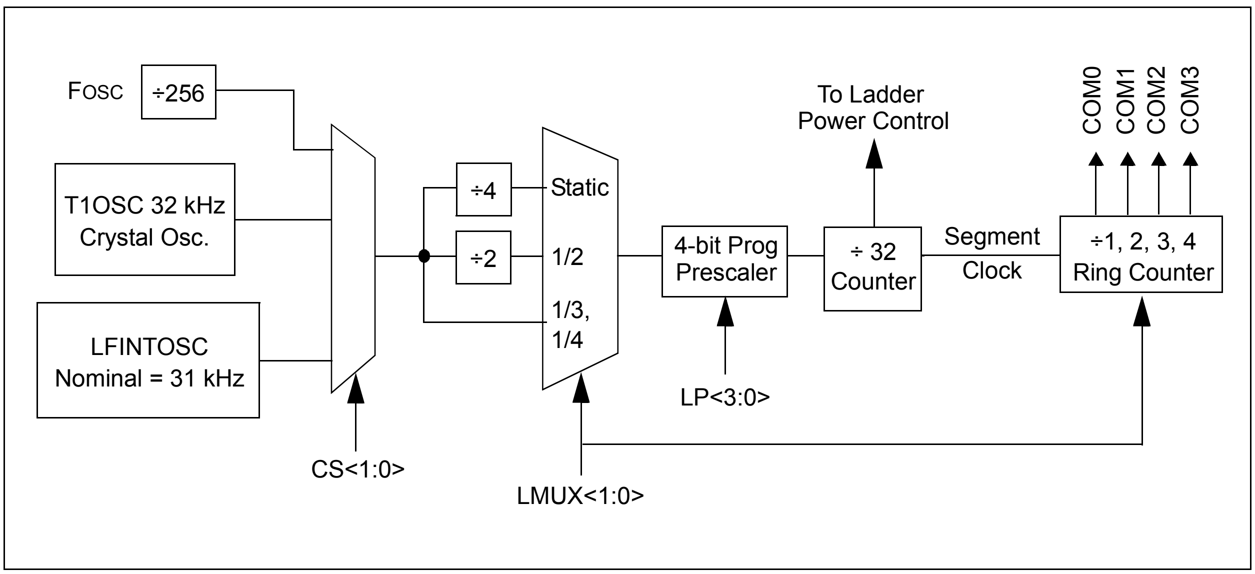


**FIGURE 21-1: GENERAL FORMAT FOR INSTRUCTIONS**

**Byte-oriented file register operations**

| 13 ... 8 | 7 | 6 ... 0 |
|---|---|---|
| OPCODE | d | f (FILE #) |

d = 0 for destination W
d = 1 for destination f
f = 7-bit file register address

**Bit-oriented file register operations**

| 13 ... 10 | 9 ... 7 | 6 ... 0 |
|---|---|---|
| OPCODE | b (BIT #) | f (FILE #) |

b = 3-bit bit address
f = 7-bit file register address

**Literal and control operations**

General

| 13 ... 8 | 7 ... 0 |
|---|---|
| OPCODE | k (literal) |

k = 8-bit immediate value

`CALL` and `GOTO` instructions only

| 13 ... 11 | 10 ... 0 |
|---|---|
| OPCODE | k (literal) |

k = 11-bit immediate value

`MOVLP` instruction only

| 13 ... 7 | 6 ... 0 |
|---|---|
| OPCODE | k (literal) |

k = 7-bit immediate value

`MOVLB` instruction only

| 13 ... 5 | 4 ... 0 |
|---|---|
| OPCODE | k (literal) |

k = 5-bit immediate value

BRA instruction only

| 13 ... 9 | 8 ... 0 |
|---|---|
| OPCODE | k (literal) |

k = 9-bit immediate value

FSR Offset instructions

| 13 ... 7 | 6 | 5 ... 0 |
|---|---|---|
| OPCODE | n | k (literal) |

n = appropriate FSR
k = 6-bit immediate value

FSR Increment instructions

| 13 ... 3 | 2 | 1 ... 0 |
|---|---|---|
| OPCODE | n | m (mode) |

n = appropriate FSR
m = 2-bit mode value

OPCODE only

| 13 ... 0 |
|---|
| OPCODE |

## 24.0 DEVELOPMENT SUPPORT

The PIC® microcontrollers (MCU) and dsPIC® digital signal controllers (DSC) are supported with a full range of software and hardware development tools:

- Integrated Development Environment
  - MPLAB® X IDE Software
- Compilers/Assemblers/Linkers
  - MPLAB XC Compiler
  - MPASM™ Assembler
  - MPLINK™ Object Linker/ MPLIB™ Object Librarian
  - MPLAB Assembler/Linker/Librarian for Various Device Families
- Simulators
  - MPLAB X SIM Software Simulator
- Emulators
  - MPLAB REAL ICE™ In-Circuit Emulator
- In-Circuit Debuggers/Programmers
  - MPLAB ICD 3
  - PICkit™ 3
- Device Programmers
  - MPLAB PM3 Device Programmer
- Low-Cost Demonstration/Development Boards, Evaluation Kits and Starter Kits
- Third-party development tools

### 24.1 MPLAB X Integrated Development Environment Software

The MPLAB X IDE is a single, unified graphical user interface for Microchip and third-party software, and hardware development tool that runs on Windows®, Linux and Mac OS® X. Based on the NetBeans IDE, MPLAB X IDE is an entirely new IDE with a host of free software components and plug-ins for high-performance application development and debugging. Moving between tools and upgrading from software simulators to hardware debugging and programming tools is simple with the seamless user interface.

With complete project management, visual call graphs, a configurable watch window and a feature-rich editor that includes code completion and context menus, MPLAB X IDE is flexible and friendly enough for new users. With the ability to support multiple tools on multiple projects with simultaneous debugging, MPLAB X IDE is also suitable for the needs of experienced users.

Feature-Rich Editor:

- Color syntax highlighting
- Smart code completion makes suggestions and provides hints as you type
- Automatic code formatting based on user-defined rules
- Live parsing

User-Friendly, Customizable Interface:

- Fully customizable interface: toolbars, toolbar buttons, windows, window placement, etc.
- Call graph window

Project-Based Workspaces:

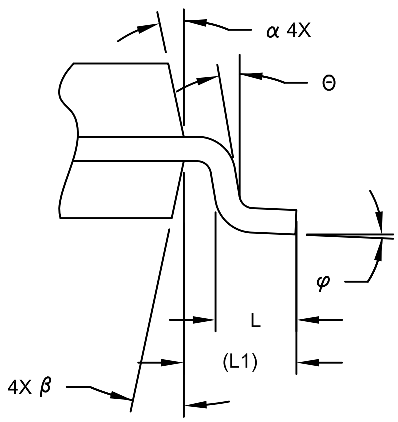
- Multiple projects
- Multiple tools
- Multiple configurations
- Simultaneous debugging sessions

File History and Bug Tracking:

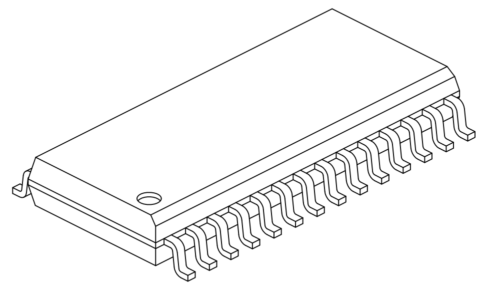
- Local file history feature
- Built-in support for Bugzilla issue tracker

## 28-Lead Plastic Small Outline (SO) - Wide, 7.50 mm Body [SOIC]

| | |
|---|---|
| **Note:** | For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging |




**VIEW C**



| Units | | MILLIMETERS | | |
|---|---|---|---|---|
| Dimension Limits | | MIN | NOM | MAX |
| Number of Pins | N | 28 | | |
| Pitch | e | 1.27 BSC | | |
| Overall Height | A | - | - | 2.65 |
| Molded Package Thickness | A2 | 2.05 | - | - |
| Standoff § | A1 | 0.10 | - | 0.30 |
| Overall Width | E | 10.30 BSC | | |
| Molded Package Width | E1 | 7.50 BSC | | |
| Overall Length | D | 17.90 BSC | | |
| Chamfer (Optional) | h | 0.25 | - | 0.75 |
| Foot Length | L | 0.40 | - | 1.27 |
| Footprint | L1 | 1.40 REF | | |
| Lead Angle | Θ | 0° | - | - |
| Foot Angle | φ | 0° | - | 8° |
| Lead Thickness | c | 0.18 | - | 0.33 |
| Lead Width | b | 0.31 | - | 0.51 |
| Mold Draft Angle Top | α | 5° | - | 15° |
| Mold Draft Angle Bottom | β | 5° | - | 15° |

**Notes:**

1. Pin 1 visual index feature may vary, but must be located within the hatched area.
2. § Significant Characteristic
3. Dimension D does not include mold flash, protrusions or gate burrs, which shall not exceed 0.15 mm per end. Dimension E1 does not include interlead flash or protrusion, which shall not exceed 0.25 mm per side.
4. Dimensioning and tolerancing per ASME Y14.5M

   BSC: Basic Dimension. Theoretically exact value shown without tolerances.

   REF: Reference Dimension, usually without tolerance, for information purposes only.
5. Datums A & B to be determined at Datum H.

Microchip Technology Drawing C04-052C Sheet 2 of 2