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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Active
Core Processor	S08
Core Size	8-Bit
Speed	20MHz
Connectivity	SCI
Peripherals	LVD, PWM, WDT
Number of I/O	30
Program Memory Size	8KB (8K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	768 x 8
Voltage - Supply (Vcc/Vdd)	4.5V ~ 5.5V
Data Converters	A/D 12x8b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	32-LQFP
Supplier Device Package	32-LQFP (7x7)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/nxp-semiconductors/mc9s08fl8clc">https://www.e-xfl.com/product-detail/nxp-semiconductors/mc9s08fl8clc</a>

# Table of Contents

1	MCU Block Diagram	3		
2	System Clock Distribution	4		
3	Pin Assignments	5		
4	Memory Map	8		
5	Electrical Characteristics	9		
5.1	Introduction	9		
5.2	Parameter Classification	9		
5.3	Absolute Maximum Ratings	9		
5.4	Thermal Characteristics	10		
5.5	ESD Protection and Latch-Up Immunity	11		
5.6	DC Characteristics	12		
5.7	Supply Current Characteristics	17		
5.8	External Oscillator (XOSC) and ICS			
	Characteristics	19		
5.9	AC Characteristics	21		
5.9.1	Control Timing	22		
5.9.2	TPM Module Timing	23		
5.10	ADC Characteristics	24		
5.11	Flash Specifications	26		
5.12	EMC Performance	27		
5.12.1	Radiated Emissions	27		
6	Ordering Information	27		
7	Package Information	28		
7.1	Mechanical Drawings	28		

## Revision History

To provide the most up-to-date information, the revision of our documents on the World Wide Web will be the most current. Your printed copy may be an earlier revision. To verify you have the latest information available, refer to:

<http://freescale.com/>

The following revision history table summarizes changes contained in this document.

Rev	Date	Description of Changes
1	March 18, 2009	Initial public release.
2	July 20, 2009	Updated <a href="#">Section 5.12, "EMC Performance."</a> and corrected <a href="#">Figure 1</a> and <a href="#">Table 1</a> . Corrected default trim value to 31.25 kHz.
3	Nov. 29, 2010	Updated <a href="#">Table 7</a> .
4	May, 2015	Corrected pin 12 of the <a href="#">Figure 3</a> .

## Related Documentation

Find the most current versions of all documents at: <http://www.freescale.com>

### Reference Manual (MC9S08FL16RM)

Contains extensive product information including modes of operation, memory, resets and interrupts, register definition, port pins, CPU, and all module information.

## 2 System Clock Distribution

MC9S08FL16 series use ICS module as clock sources. The ICS module can use internal or external clock source as reference to provide up to 20 MHz CPU clock. The output of ICS module includes,

- OSCOUT — XOSC output provides external reference clock to ADC.
- ICSFFCLK — ICS fixed frequency clock reference (around 32.768 kHz) provides double of the fixed lock signal to TPMs and MTIM16.
- ICSOUT — ICS CPU clock provides double of the bus clock which is basic clock reference of peripherals.
- ICSLCLK — Alternate BDC clock provides debug signal to BDC module.

The TCLK pin is an extra external clock source. When TCLK is enabled, it can provide alternate clock source to TPMs and MTIM16. The on-chip 1 kHz clock provides clock source of COP module.

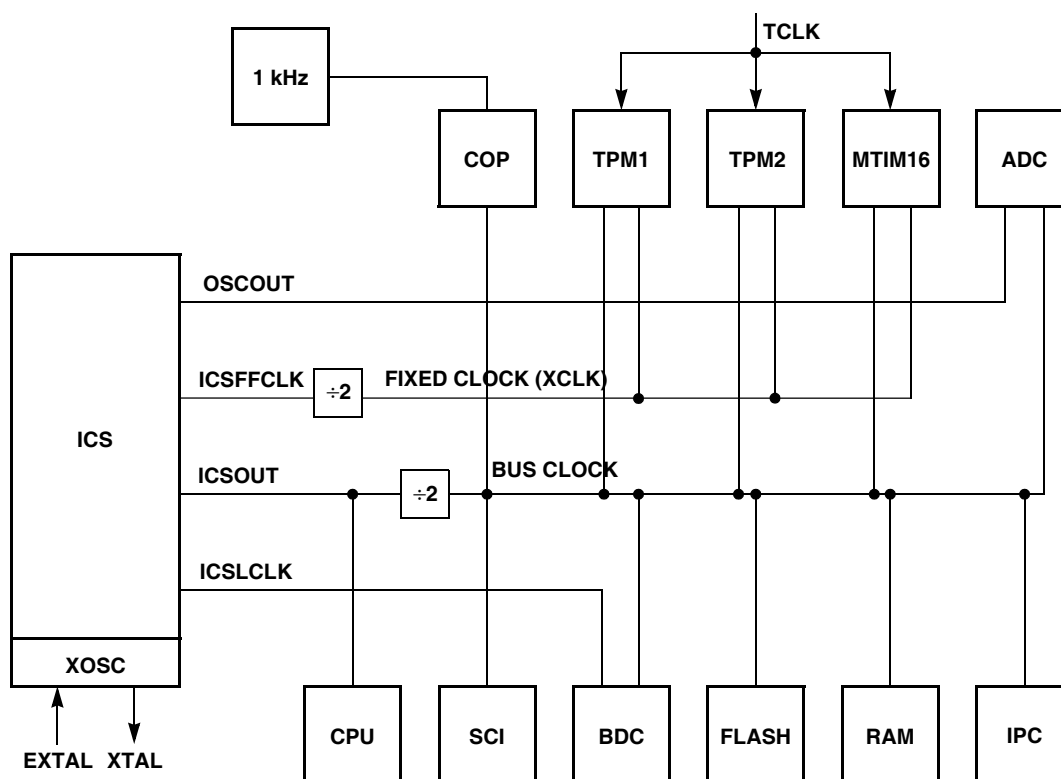


Figure 2. System Clock Distribution Diagram

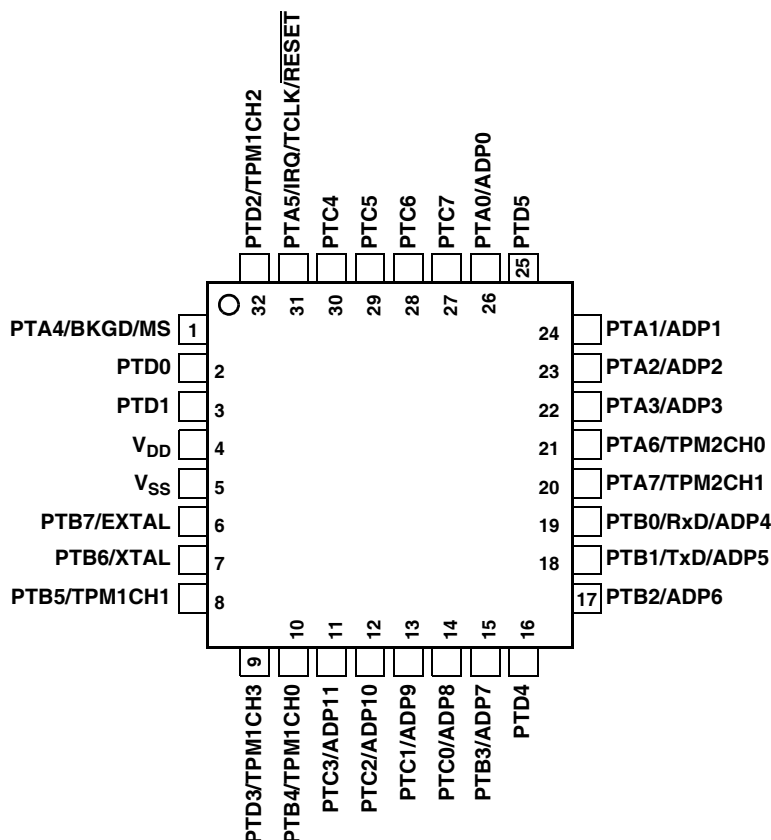


Figure 4. MC9S08FL16 Series 32-Pin LQFP Package

Table 1. Pin Availability by Package Pin-Count

Pin Number		<-- Lowest Priority --> Highest							
32-SDIP	32-LQFP	Port Pin	I/O	Alt 1	I/O	Alt 2	I/O	Alt 3	I/O
1	29	PTC5	I/O						
2	30	PTC4	I/O						
3	31	PTA5	I	IRQ	I	TCLK	I	RESET	I
4	32	PTD2	I/O			TPM1CH2	I/O		
5	1	PTA4	O			BKGD	I	MS	I
6	2	PTD0	I/O						
7	3	PTD1	I/O						
8	4							V <sub>DD</sub>	I
9	5							V <sub>SS</sub>	I
10	6	PTB7	I/O	EXTAL	I				
11	7	PTB6	I/O	XTAL	O				
12	8	PTB5	I/O			TPM1CH1	I/O		
13	9	PTD3	I/O			TPM1CH3	I/O		
14	10	PTB4	I/O			TPM1CH0	I/O		
15	11	PTC3	I/O			ADP11	I		

**Table 1. Pin Availability by Package Pin-Count (continued)**

Pin Number		<-- Lowest <b>Priority</b> --> Highest							
32-SDIP	32-LQFP	Port Pin	I/O	Alt 1	I/O	Alt 2	I/O	Alt 3	I/O
16	12	PTC2	I/O			ADP10	I		
17	13	PTC1	I/O			ADP9	I		
18	14	PTC0	I/O			ADP8	I		
19	15	PTB3	I/O			ADP7	I		
20	16	PTD4	I/O						
21	17	PTB2	I/O			ADP6	I		
22	18	PTB1	I/O			TxD	I/O	ADP5	I
23	19	PTB0	I/O			RxD	I	ADP4	I
24	20	PTA7	I/O			TPM2CH1	I/O		
25	21	PTA6	I/O			TPM2CH0	I/O		
26	22	PTA3	I/O			ADP3	I		
27	23	PTA2	I/O			ADP2	I		
28	24	PTA1	I/O			ADP1	I		
29	25	PTD5	I/O						
30	26	PTA0	I/O			ADP0	I		
31	27	PTC7	I/O						
32	28	PTC6	I/O						

## NOTE

When an alternative function is first enabled, it is possible to get a spurious edge to the module. User software must clear out any associated flags before interrupts are enabled. [Table 1](#) illustrates the priority if multiple modules are enabled. The highest priority module will have control over the pin. Selecting a higher priority pin function with a lower priority function already enabled can cause spurious edges to the lower priority module. Disable all modules that share a pin before enabling another module.

## 5 Electrical Characteristics

### 5.1 Introduction

This section contains electrical and timing specifications for the MC9S08FL16 series of microcontrollers available at the time of publication.

### 5.2 Parameter Classification

The electrical parameters shown in this supplement are guaranteed by various methods. To give the customer a better understanding, the following classification is used and the parameters are tagged accordingly in the tables where appropriate:

**Table 2. Parameter Classifications**

<b>P</b>	Those parameters are guaranteed during production testing on each individual device.
<b>C</b>	Those parameters are achieved by the design characterization by measuring a statistically relevant sample size across process variations.
<b>T</b>	Those parameters are achieved by design characterization on a small sample size from typical devices under typical conditions unless otherwise noted. All values shown in the typical column are within this category.
<b>D</b>	Those parameters are derived mainly from simulations.

#### NOTE

The classification is shown in the column labeled “C” in the parameter tables where appropriate.

### 5.3 Absolute Maximum Ratings

Absolute maximum ratings are stress ratings only, and functional operation at the maxima is not guaranteed. Stress beyond the limits specified in [Table 3](#) may affect device reliability or cause permanent damage to the device. For functional operating conditions, refer to the remaining tables in this section.

This device contains circuitry protecting against damage due to high static voltage or electrical fields; however, it is advised that normal precautions be taken to avoid application of any voltages higher than maximum-rated voltages to this high-impedance circuit. Reliability of operation is enhanced if unused inputs are tied to an appropriate logic voltage level (for instance, either  $V_{SS}$  or  $V_{DD}$ ) or the programmable pullup resistor associated with the pin is enabled.

**Table 3. Absolute Maximum Ratings**

Rating	Symbol	Value	Unit
Supply voltage	$V_{DD}$	-0.3 to 5.8	V
Maximum current into $V_{DD}$	$I_{DD}$	120	mA
Digital input voltage	$V_{In}$	-0.3 to $V_{DD} + 0.3$	V
Instantaneous maximum current Single pin limit (applies to all port pins) <sup>1, 2, 3</sup>	$I_D$	±25	mA
Storage temperature range	$T_{stg}$	-55 to 150	°C

- <sup>1</sup> Input must be current limited to the value specified. To determine the value of the required current-limiting resistor, calculate resistance values for positive ( $V_{DD}$ ) and negative ( $V_{SS}$ ) clamp voltages, then use the larger of the two resistance values.
- <sup>2</sup> All functional non-supply pins, except for PTA5 are internally clamped to  $V_{SS}$  and  $V_{DD}$ .
- <sup>3</sup> Power supply must maintain regulation within operating  $V_{DD}$  range during instantaneous and operating maximum current conditions. If positive injection current ( $V_{In} > V_{DD}$ ) is greater than  $I_{DD}$ , the injection current may flow out of  $V_{DD}$  and could result in external power supply going out of regulation. Ensure external  $V_{DD}$  load will shunt current greater than maximum injection current. This will be the greatest risk when the MCU is not consuming power. Examples are: if no system clock is present, or if the clock rate is very low (which would reduce overall power consumption).

## 5.4 Thermal Characteristics

This section provides information about operating temperature range, power dissipation, and package thermal resistance. Power dissipation on I/O pins is usually small compared to the power dissipation in on-chip logic and voltage regulator circuits, and it is user-determined rather than being controlled by the MCU design. To take  $P_{I/O}$  into account in power calculations, determine the difference between actual pin voltage and  $V_{SS}$  or  $V_{DD}$  and multiply by the pin current for each I/O pin. Except in cases of unusually high pin current (heavy loads), the difference between pin voltage and  $V_{SS}$  or  $V_{DD}$  will be very small.

**Table 4. Thermal Characteristics**

Rating	Symbol	Value	Unit
Operating temperature range (packaged)	T <sub>A</sub>	T <sub>L</sub> to T <sub>H</sub> −40 to 85	°C
Thermal resistance Single-layer board			
32-pin SDIP	θ <sub>JA</sub>	60	°C/W
32-pin LQFP		85	
Thermal resistance Four-layer board			
32-pin SDIP	θ <sub>JA</sub>	35	°C/W
32-pin LQFP		56	

The average chip-junction temperature ( $T_J$ ) in °C can be obtained from:

**Table 6. ESD and Latch-Up Protection Characteristics**

No.	Rating <sup>1</sup>	Symbol	Min	Max	Unit
1	Human body model (HBM)	$V_{\text{HBM}}$	$\pm 2000$	—	V
2	Charge device model (CDM)	$V_{\text{CDM}}$	$\pm 500$	—	V
3	Latch-up current at $T_A = 85^\circ\text{C}$	$I_{\text{LAT}}$	$\pm 100$	—	mA

<sup>1</sup> Parameter is achieved by design characterization on a small sample size from typical devices under typical conditions unless otherwise noted.

## 5.6 DC Characteristics

This section includes information about power supply requirements and I/O pin characteristics.

**Table 7. DC Characteristics**

Num	C	Characteristic	Symbol	Condition	Min.	Typical <sup>1</sup>	Max.	Unit
1	P	Operating voltage	—	—	4.5	—	5.5	V
2	C	Output high voltage All I/O pins, low-drive strength	$V_{\text{OH}}$	$I_{\text{Load}} = -2 \text{ mA}$	$V_{\text{DD}} - 1.5$	—	—	V
	P	Output high voltage All I/O pins, high-drive strength		$I_{\text{Load}} = -10 \text{ mA}$	$V_{\text{DD}} - 1.5$	—	—	
3	D	Output high current Max total $I_{\text{OH}}$ for all ports	$I_{\text{OHT}}$	—	—	—	100	mA
4	C	Output low voltage All I/O pins, low-drive strength	$V_{\text{OL}}$	$I_{\text{Load}} = 2 \text{ mA}$	—	—	1.5	V
	P	Output low voltage All I/O pins, high-drive strength		$I_{\text{Load}} = 10 \text{ mA}$	—	—	1.5	
5	D	Output low current Max total $I_{\text{OL}}$ for all ports	$I_{\text{OLT}}$	—	—	—	100	mA
6	P	Input high voltage All digital inputs	$V_{\text{IH}}$	—	$0.65 \times V_{\text{DD}}$	—	—	V
7	P	Input low voltage All digital inputs	$V_{\text{IL}}$	—	—	—	$0.35 \times V_{\text{DD}}$	V
8	C	Input hysteresis All digital inputs	$V_{\text{hys}}$	—	$0.06 \times V_{\text{DD}}$	—	—	mV
9	P	Input leakage current All input only pins (per pin)	$ I_{\text{In}} $	$V_{\text{In}} = V_{\text{DD}} \text{ or } V_{\text{SS}}$	—	0.1	1	$\mu\text{A}$
10	P	Hi-Z (off-state) leakage current All input/output (per pin)	$ I_{\text{OZ}} $	$V_{\text{In}} = V_{\text{DD}} \text{ or } V_{\text{SS}}$	—	0.1	1	$\mu\text{A}$
11a	C	Pullup, pulldown resistors All digital inputs, when enabled (all I/O pins other than PTA5/IRQ/TCLK/RESET)	$R_{\text{PU}}, R_{\text{PD}}$	—	17.5	36.5	52.5	$\text{k}\Omega$
11b	C	Pullup, pulldown resistors (PTA5/IRQ/TCLK/RESET)	$R_{\text{PU}}, R_{\text{PD}}$ (Note <sup>2</sup> )	—	17.5	36.5	52.5	$\text{k}\Omega$



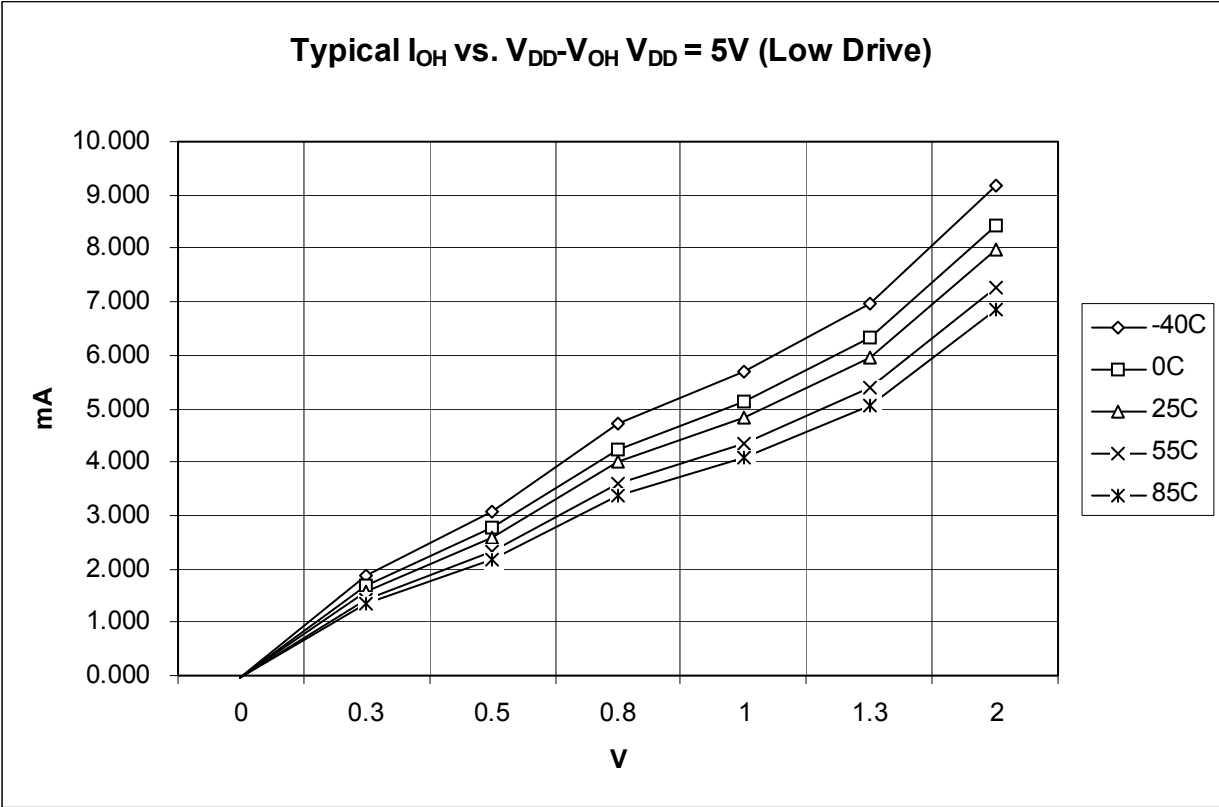


Figure 7. Typical  $I_{OH}$  Vs  $V_{DD}-V_{OH}$  ( $V_{DD} = 5.0 V$ ) (Low Drive)

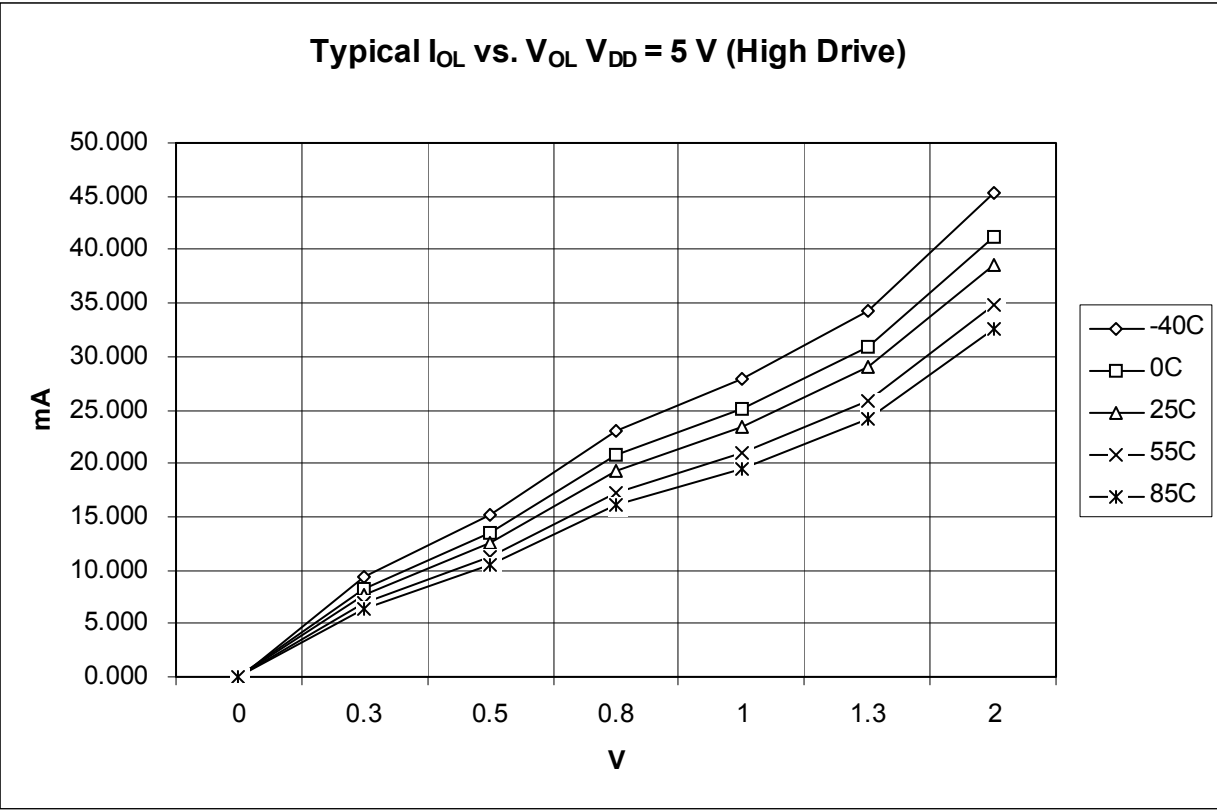


Figure 8. Typical  $I_{OH}$  Vs  $V_{OL}$  ( $V_{DD} = 5.0\text{ V}$ ) (High Drive)

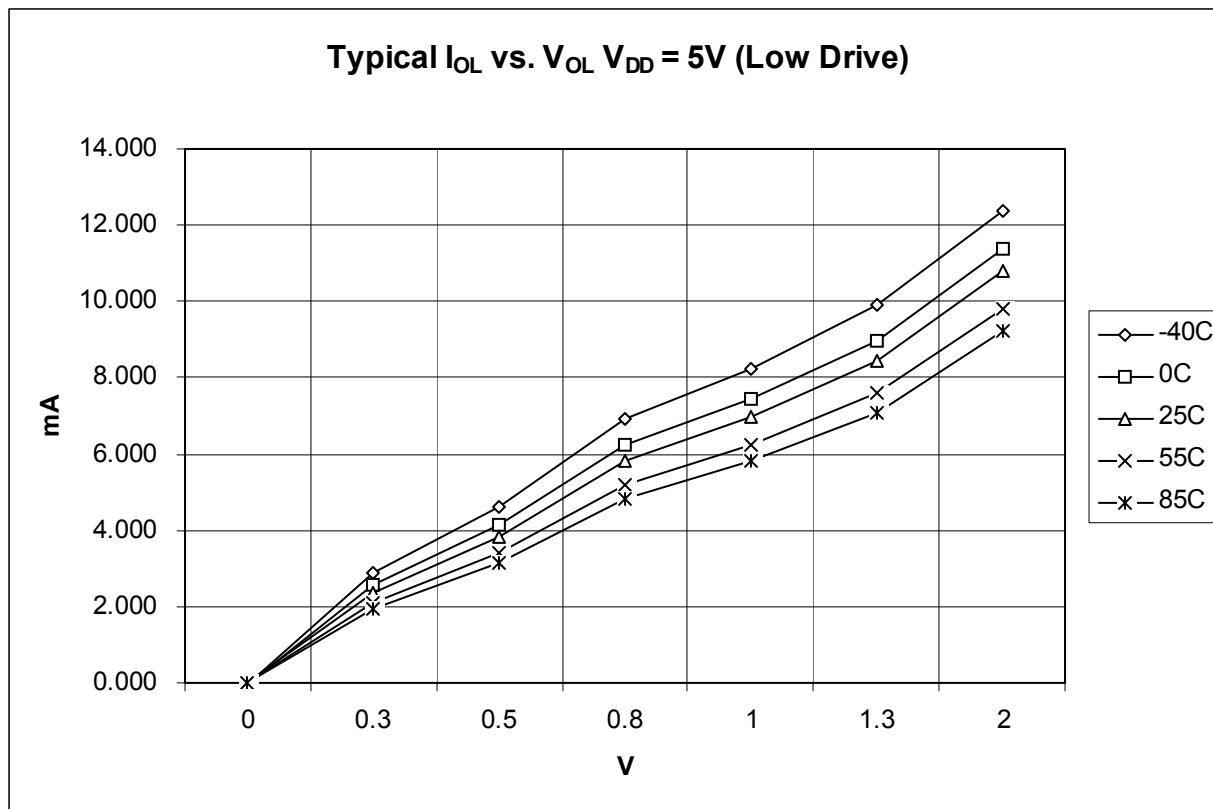


Figure 9. Typical  $I_{OH}$  Vs  $V_{OL}$  ( $V_{DD} = 5.0 V$ ) (Low Drive)

## 5.7 Supply Current Characteristics

This section includes information about power supply current in various operating modes.

Table 8. Supply Current Characteristics

Num	C	Parameter	Symbol	Bus Freq	V <sub>DD</sub> (V)	Typical <sup>1</sup>	Max	Unit	Temp
1	P	Run supply current FEI mode, all modules off	R <sub>I</sub> DD	10 MHz	5	5.66 5.75 5.80	—	mA	–40 °C 25 °C 85 °C
	P			1 MHz		1.61 1.65 1.78	—		–40 °C 25 °C 85 °C
2	C	Wait mode supply current FEI mode, all modules off	W <sub>I</sub> DD	10 MHz	5	2.79 2.86 2.88	—	μA	–40 °C 25 °C 85 °C
	C			1 MHz		1.05 1.06 1.06	—		–40 °C 25 °C 85 °C
3	C	Stop2 mode supply current	S2 <sub>I</sub> DD	—	5	1.06	—	μA	–40 to 85 °C
	C	Stop3 mode supply current no clocks active	S3 <sub>I</sub> DD	—	5	1.17	—	μA	–40 to 85 °C
4	C	ADC adder to stop3	—	—	5	163.88	—	μA	25 °C
5	C	ICS adder to stop3 EREFSTEN = 1	—	—	5	1.25	—	μA	25 °C
6	C	LVD adder to stop3	—	—	5	161.3	—	μA	25 °C

<sup>1</sup> Data in Typical column was characterized at 5.0 V, 25 °C or is typical recommended value.

## 5.8 External Oscillator (XOSC) and ICS Characteristics

Refer to [Figure 11](#) for crystal or resonator circuits.

**Table 9. XOSC and ICS Specifications (Temperature Range = –40 to 85 °C Ambient)**

Num	C	Characteristic	Symbol	Min	Typical <sup>1</sup>	Max	Unit
1	C	Oscillator crystal or resonator (EREFS = 1, ERCLKEN = 1) Low range (RANGE = 0)	$f_{lo}$	32	—	38.4	kHz
		High range (RANGE = 1) FEE or FBE mode <sup>2</sup>	$f_{hi}$	1	—	5	MHz
		High range (RANGE = 1), high gain (HGO = 1), FBELP mode	$f_{hi}$	1	—	16	MHz
		High range (RANGE = 1), low power (HGO = 0), FBELP mode	$f_{hi}$	1	—	8	MHz
2	D	Load capacitors	$C_1$ $C_2$	See Note <sup>3</sup>			
3	D	Feedback resistor Low range (32 kHz to 38.4 kHz) High range (1 MHz to 16 MHz)	$R_F$		10 1		MΩ MΩ
4	D	Series resistor — Low range Low gain (HGO = 0) High gain (HGO = 1)	$R_S$	— —	0 100	— —	kΩ
5	D	Series resistor — High range Low Gain (HGO = 0) High Gain (HGO = 1) ≥ 8 MHz 4 MHz 1 MHz	$R_S$	— — —	0 0 0	0 10 20	kΩ
6	C	Crystal startup time <sup>4, 5</sup> Low range, low power Low range, high power High range, low power High range, high power	$t_{CSTL}$ $t_{CSTH}$	— — — —	200 400 5 15	— — — —	ms
7	T	Internal reference start-up time	$t_{IRST}$	—	60	100	μs
8	D	Square wave input clock frequency (EREFS = 0, ERCLKEN = 1) FEE or FBE mode <sup>2</sup> FBELP mode	$f_{extal}$	0.03125 0	— —	5 20	MHz MHz
9	P	Average internal reference frequency — trimmed	$f_{int\_t}$	—	31.25	—	kHz
10	P	DCO output frequency range — trimmed <sup>6</sup> Low range (DRS = 00)	$f_{dco\_t}$	16	—	20	MHz
11	C	Total deviation of DCO output from trimmed frequency <sup>4</sup> Over full voltage and temperature range Over fixed voltage and temperature range of 0 to 70°C	$\Delta f_{dco\_t}$	—	–1.0 to 0.5 ±0.5	± 2 ± 1	% $f_{dco}$
12	C	FLL acquisition time <sup>4, 7</sup>	$t_{Acquire}$			1	ms

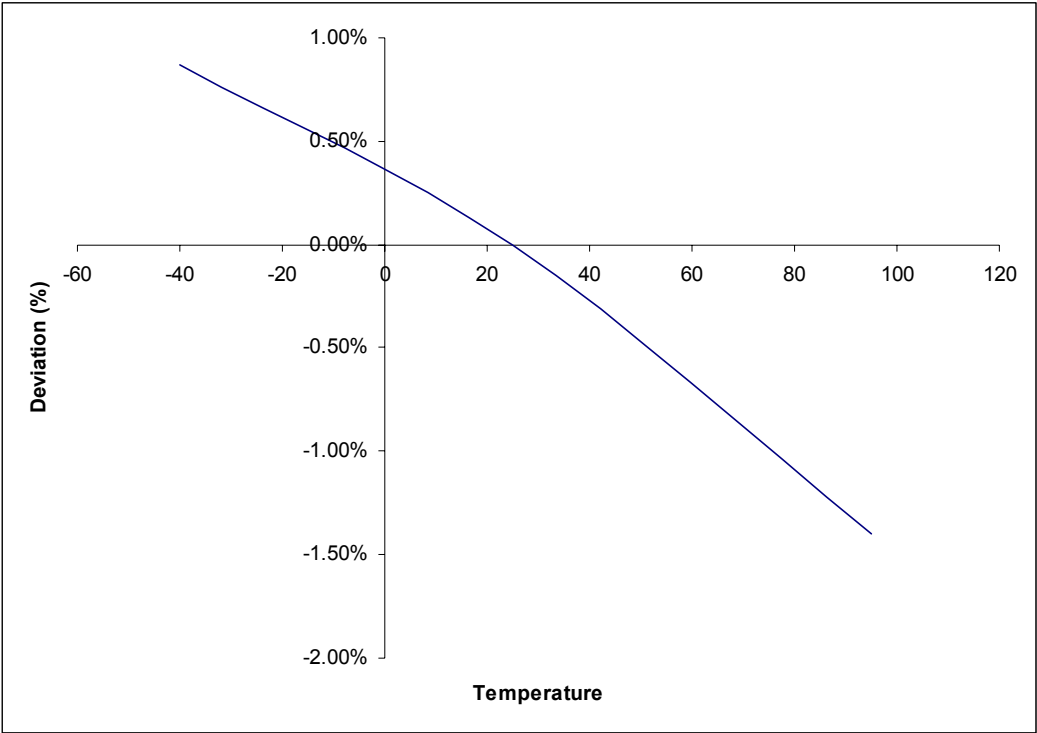


Figure 11. Deviation of DCO Output from Trimmed Frequency (20 MHz, 5.0 V)

### 5.9 AC Characteristics

This section describes timing characteristics for each peripheral system.

## 5.9.1 Control Timing

Table 10. Control Timing

Num	C	Rating	Symbol	Min	Typical <sup>1</sup>	Max	Unit
1	D	Bus frequency ( $t_{cyc} = 1/f_{Bus}$ )	$f_{Bus}$	dc	—	10	MHz
2	D	Internal low power oscillator period	$t_{LPO}$	700	—	1300	$\mu s$
3	D	External reset pulse width <sup>2</sup>	$t_{extrst}$	100	—	—	ns
4	D	Reset low drive	$t_{rstdrv}$	$34 \times t_{cyc}$	—	—	ns
5	D	BKGD/MS setup time after issuing background debug force reset to enter user or BDM modes	$t_{MSSU}$	500	—	—	ns
6	D	BKGD/MS hold time after issuing background debug force reset to enter user or BDM modes <sup>3</sup>	$t_{MSH}$	100	—	—	$\mu s$
7	D	IRQ pulse width Asynchronous path <sup>2</sup> Synchronous path <sup>4</sup>	$t_{ILIH}, t_{IHIL}$	100 $1.5 \times t_{cyc}$	— —	— —	ns
8	D	Keyboard interrupt pulse width Asynchronous path <sup>2</sup> Synchronous path <sup>4</sup>	$t_{ILIH}, t_{IHIL}$	100 $1.5 \times t_{cyc}$	— —	— —	ns
9	C	Port rise and fall time — Low output drive ( $PTxDS = 0$ ) (load = 50 pF) <sup>5</sup> Slew rate control disabled ( $PTxSE = 0$ ) Slew rate control enabled ( $PTxSE = 1$ )	$t_{Rise}, t_{Fall}$	— —	16 23	— —	ns
		Port rise and fall time — High output drive ( $PTxDS = 1$ ) (load = 50 pF) <sup>5</sup> Slew rate control disabled ( $PTxSE = 0$ ) Slew rate control enabled ( $PTxSE = 1$ )	$t_{Rise}, t_{Fall}$	— —	5 9	— —	ns

<sup>1</sup> Typical values are based on characterization data at  $V_{DD} = 5.0 V$ , 25 °C unless otherwise stated.

<sup>2</sup> This is the shortest pulse that is guaranteed to be recognized as a reset pin request.

<sup>3</sup> To enter BDM mode following a POR, BKGD/MS must be held low during the power-up and for a hold time of  $t_{MSH}$  after  $V_{DD}$  rises above  $V_{LVD}$ .

<sup>4</sup> This is the minimum pulse width that is guaranteed to pass through the pin synchronization circuitry. Shorter pulses may or may not be recognized. In stop mode, the synchronizer is bypassed so shorter pulses can be recognized.

<sup>5</sup> Timing is shown with respect to 20%  $V_{DD}$  and 80%  $V_{DD}$  levels. Temperature range –40 °C to 85 °C.

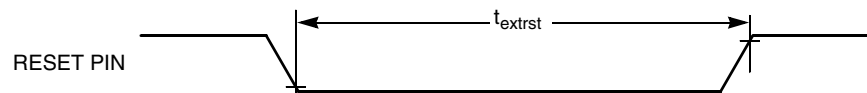
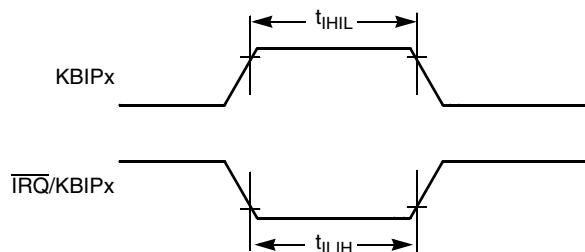


Figure 12. Reset Timing


Figure 13.  $\overline{IRQ}/KBIPx$  Timing

## 5.9.2 TPM Module Timing

Synchronizer circuits determine the shortest input pulses that can be recognized or the fastest clock that can be used as the optional external source to the timer counter. These synchronizers operate from the current bus rate clock.

Table 11. TPM Input Timing

No.	C	Function	Symbol	Min	Max	Unit
1	D	External clock frequency	$f_{TCLK}$	0	$f_{Bus}/4$	Hz
2	D	External clock period	$t_{TCLK}$	4	—	$t_{cyc}$
3	D	External clock high time	$t_{clkh}$	1.5	—	$t_{cyc}$
4	D	External clock low time	$t_{clkl}$	1.5	—	$t_{cyc}$
5	D	Input capture pulse width	$t_{ICPW}$	1.5	—	$t_{cyc}$

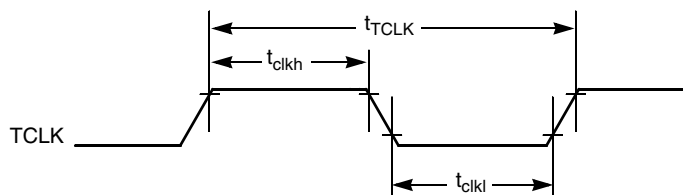


Figure 14. Timer External Clock

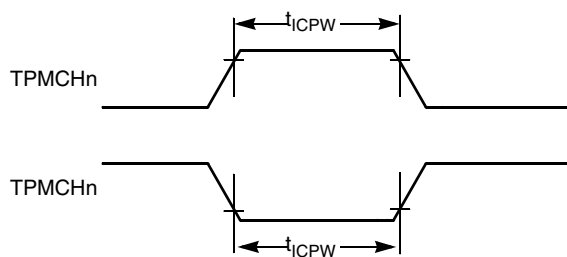


Figure 15. Timer Input Capture Pulse



## 5.10 ADC Characteristics

Table 12. 8-Bit ADC Operating Conditions

Characteristic	Conditions	Symb	Min	Typical <sup>1</sup>	Max	Unit	Comment
Supply voltage	Absolute	$V_{DDA}$	4.5	—	5.5	V	
	Delta to $V_{DD}$ ( $V_{DD} - V_{DDA}$ ) <sup>2</sup>	$\Delta V_{DDA}$	-100	0	100	mV	
Ground voltage	Absolute	$V_{SSA}$	-0.5	—	0	V	
	Delta to $V_{SS}$ ( $V_{SS} - V_{SSA}$ ) <sup>2</sup>	$\Delta V_{SSA}$	-100	0	100	mV	
Input voltage	—	$V_{ADIN}$	$V_{REFL}$	—	$V_{REFH}$	V	
Input capacitance	—	$C_{ADIN}$	—	4.5	5.5	pF	
Input resistance	—	$R_{ADIN}$	—	3	5	k $\Omega$	
Analog source resistance	8-bit mode (all valid $f_{ADCK}$ )	$R_{AS}$	—	—	10	k $\Omega$	External to MCU
ADC conversion clock frequency	High speed (ADLPC = 0)	$f_{ADCK}$	0.4	—	8.0	MHz	
	Low power (ADLPC = 1)		0.4	—	4.0		

<sup>1</sup> Typical values assume  $V_{DDA} = 5.0$  V, Temp = 25 °C,  $f_{ADCK} = 1.0$  MHz unless otherwise stated. Typical values are for reference only and are not tested in production.

<sup>2</sup> DC potential difference.

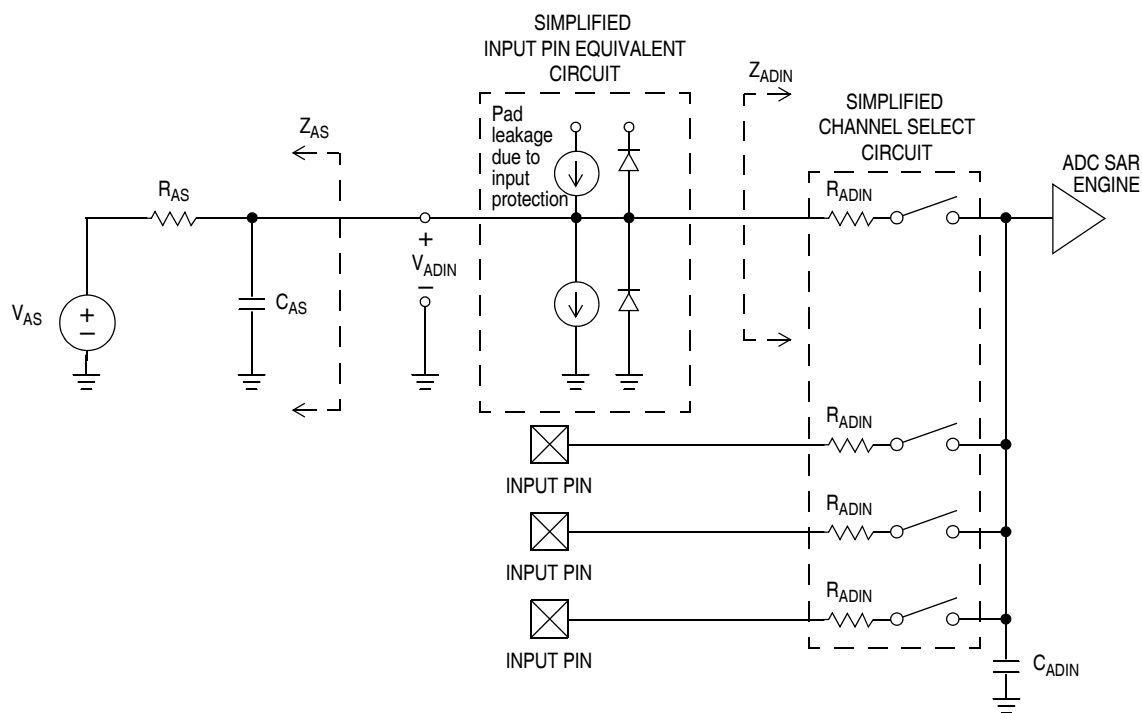


Figure 16. ADC Input Impedance Equivalency Diagram

**Table 13. 8-Bit ADC Characteristics ( $V_{REFH} = V_{DDA}$ ,  $V_{REFL} = V_{SSA}$ )**

C	Characteristic	Conditions	Symb	Min	Typ <sup>1</sup>	Max	Unit	Comment
T	Supply Current ADLPC=1 ADLSMP=1 ADCO=1		I <sub>DDA</sub>	—	133	—	μA	
T	Supply Current ADLPC=1 ADLSMP=0 ADCO=1		I <sub>DDA</sub>	—	218	—	μA	
T	Supply Current ADLPC=0 ADLSMP=1 ADCO=1		I <sub>DDA</sub>	—	327	—	μA	
P	Supply Current ADLPC=0 ADLSMP=0 ADCO=1		I <sub>DDA</sub>	—	0.582	1	mA	
C	Supply Current	Stop, Reset, Module Off	I <sub>DDA</sub>	—	0.011	1	μA	
P	ADC Asynchronous Clock Source	High Speed (ADLPC = 0)	f <sub>ADACK</sub>	2	3.3	5	MHz	t <sub>ADACK</sub> = 1/f <sub>ADACK</sub>
		Low Power (ADLPC = 1)		1.25	2	3.3		
P	Conversion Time (Including sample time)	Short Sample (ADLSMP = 0)	t <sub>ADC</sub>	—	20	—	ADCK cycles	See reference manual for conversion time variances
		Long Sample (ADLSMP = 1)		—	40	—		
P	Sample Time	Short Sample (ADLSMP = 0)	t <sub>ADS</sub>	—	3.5	—	ADCK cycles	
		Long Sample (ADLSMP = 1)		—	23.5	—		
D	Temp Sensor Slope	–40°C– 25°C	m	—	3.266	—	mV/°C	
		25°C– 125°C		—	3.638	—		
D	Temp Sensor Voltage	25 °C	V <sub>TEMP25</sub>	—	1.396	—	mV	
P	Total Unadjusted Error	8-bit mode	E <sub>TUE</sub>	—	±0.5	±1.0	LSB <sup>2</sup>	Includes quantization
P	Differential Non-Linearity	8-bit mode <sup>3</sup>	DNL	—	±0.3	±0.5	LSB <sup>2</sup>	
T	Integral Non-Linearity	8-bit mode	INL	—	±0.3	±0.5	LSB <sup>2</sup>	
P	Zero-Scale Error	8-bit mode	E <sub>ZS</sub>	—	±0.5	±0.5	LSB <sup>2</sup>	V <sub>ADIN</sub> = V <sub>SSA</sub>
T	Full-Scale Error	8-bit mode	E <sub>FS</sub>	—	±0.5	±0.5	LSB <sup>2</sup>	V <sub>ADIN</sub> = V <sub>DDA</sub>

**Table 13. 8-Bit ADC Characteristics ( $V_{REFH} = V_{DDA}$ ,  $V_{REFL} = V_{SSA}$ ) (continued)**

C	Characteristic	Conditions	Symb	Min	Typ <sup>1</sup>	Max	Unit	Comment
D	Quantization Error	8-bit mode	$E_Q$	—	—	$\pm 0.5$	LSB <sup>2</sup>	
D	Input Leakage Error	8-bit mode	$E_{IL}$	—	$\pm 0.1$	$\pm 1$	LSB <sup>2</sup>	Pad leakage <sup>2</sup> * $R_{AS}$

<sup>1</sup> Typical values assume  $V_{DDA} = 5.0$  V, Temp = 25 °C,  $f_{ADCK} = 1.0$  MHz unless otherwise stated. Typical values are for reference only and are not tested in production.

<sup>2</sup> Based on input pad leakage current. Refer to pad electricals.

## 5.11 Flash Specifications

This section provides details about program/erase times and program-erase endurance for the flash memory.

Program and erase operations do not require any special power sources other than the normal  $V_{DD}$  supply. For more detailed information about program/erase operations, see the Memory section.

**Table 14. Flash Characteristics**

C	Characteristic	Symbol	Min	Typical	Max	Unit
D	Supply voltage for program/erase –40 °C to 85 °C	$V_{prog/erase}$	4.5	—	5.5	V
D	Supply voltage for read operation	$V_{Read}$	4.5	—	5.5	V
D	Internal FCLK frequency <sup>1</sup>	$f_{FCLK}$	150	—	200	kHz
D	Internal FCLK period (1/FCLK)	$t_{Fcyc}$	5	—	6.67	μs
P	Byte program time (random location) <sup>2</sup>	$t_{prog}$	9			$t_{Fcyc}$
P	Byte program time (burst mode) <sup>2</sup>	$t_{Burst}$	4			$t_{Fcyc}$
P	Page erase time <sup>2</sup>	$t_{Page}$	4000			$t_{Fcyc}$
P	Mass erase time <sup>2</sup>	$t_{Mass}$	20,000			$t_{Fcyc}$
	Byte program current <sup>3</sup>	$RI_{DDBP}$	—	4	—	mA
	Page erase current <sup>3</sup>	$RI_{DDPE}$	—	6	—	mA
C	Program/erase endurance <sup>4</sup> $T_L$ to $T_H = -40$ °C to 85 °C $T = 25$ °C		—	10,000	—	cycles
C	Data retention <sup>5</sup>	$t_{D\_ret}$	5	100	—	years

<sup>1</sup> The frequency of this clock is controlled by a software setting.

<sup>2</sup> These values are hardware state machine controlled. User code does not need to count cycles. This information supplied for calculating approximate time to program and erase.

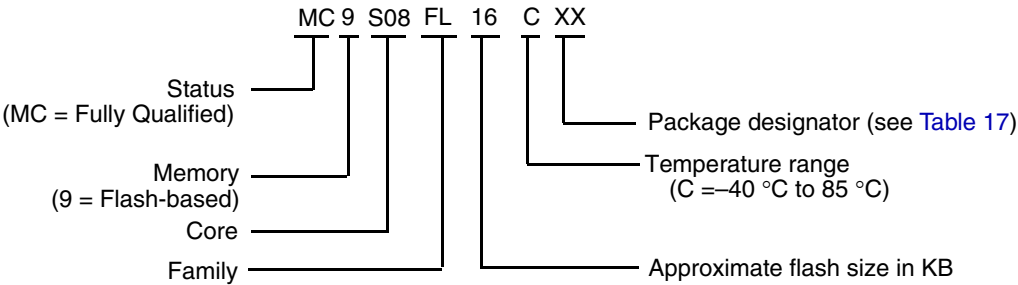
<sup>3</sup> The program and erase currents are additional to the standard run  $I_{DD}$ . These values are measured at room temperatures with  $V_{DD} = 5.0$  V, bus frequency = 4.0 MHz.

<sup>4</sup> **Typical endurance for flash** was evaluated for this product family on the 9S12Dx64. For additional information on how Freescale defines typical endurance, please refer to Engineering Bulletin EB619, *Typical Endurance for Nonvolatile Memory*.

## Package Information

- <sup>1</sup> See the reference manual, *MC9S08FL16 Series Reference Manual*, for a complete description of modules included on each device.
- <sup>2</sup> See [Table 17](#) for package information.

Example of the device numbering system:



# 7 Package Information

Table 17. Package Descriptions

Pin Count	Package Type	Abbreviation	Designator	Case No.	Document No.
32	Low Quad Flat Package	LQFP	LC	873A-03	98ASH70029A
32	Shrink Dual In-line Package	SDIP	BM	1376-02	98ASA99330D

## 7.1 Mechanical Drawings

The following pages are mechanical drawings for the packages described in [Table 17](#).

