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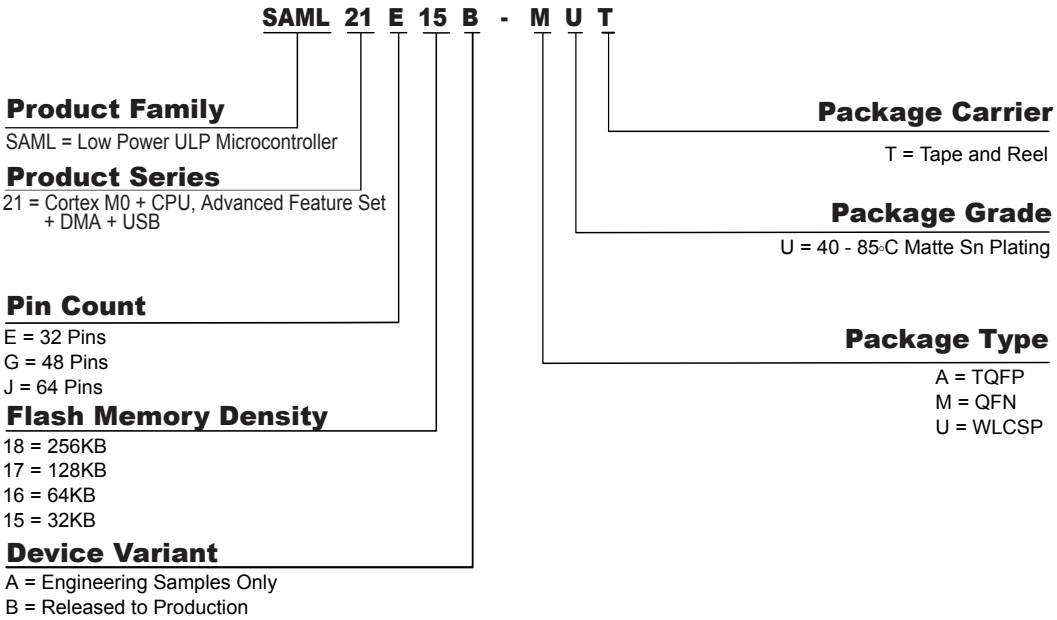
"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	ARM® Cortex®-M0+
Core Size	32-Bit Single-Core
Speed	48MHz
Connectivity	I²C, LINbus, SCI, SPI, UART/USART, USB
Peripherals	DMA, POR, PWM, WDT
Number of I/O	37
Program Memory Size	64KB (64K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	8K x 8
Voltage - Supply (Vcc/Vdd)	1.62V ~ 3.63V
Data Converters	A/D 14x12b; D/A 2x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	48-TQFP
Supplier Device Package	48-TQFP (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/atsaml21g16b-aut

3. Ordering Information



Note: The device variant (last letter of the ordering number) is independent of the die revision (DSU.DID.REVISION): The device variant denotes functional differences, whereas the die revision marks evolution of the die.

3.1. SAM L21J

Table 3-1. SAM L21J Ordering Codes

Ordering Code	FLASH (bytes)	SRAM (bytes)	Package	Carrier Type
ATSAML21J16B-AUT	64K	8K	TQFP64	Tape & Reel
ATSAML21J16B-MUT			QFN64	
ATSAML21J17B-AUT	128K	16K	TQFP64	Tape & Reel
ATSAML21J17B-MUT			QFN64	
ATSAML21J17B-UUT			WLCSP64	
ATSAML21J18B-AUT	256K	32K	TQFP64	Tape & Reel
ATSAML21J18B-MUT			QFN64	
ATSAML21J18B-UUT			WLCSP64	

Bit 2 – RSTC: Interrupt Flag for RSTC

Bit 1 – MCLK: Interrupt Flag for MCLK

Bit 0 – PM: Interrupt Flag for PM

20.8.4. Interrupt Enable Clear

This register allows the user to disable an interrupt without doing a read-modify-write operation. Changes in this register will also be reflected in the Interrupt Enable Set (INTENSET) register.

Name: INTENCLR
Offset: 0x04
Reset: 0x00
Property: PAC Write-Protection

Bit	7	6	5	4	3	2	1	0
								PLRDY
Access								R/W
Reset								0

Bit 0 – PLRDY: Performance Level Interrupt Enable
Writing a '0' to this bit has no effect.

Writing a '1' to this bit will clear the Performance Ready Interrupt Enable bit and the corresponding interrupt request.

Value	Description
0	The Performance Ready interrupt is disabled.
1	The Performance Ready interrupt is enabled and will generate an interrupt request when the Performance Ready Interrupt Flag is set.

When the Automatic Power Switch configuration is selected, the Automatic Power Switch Ready bit in the Status register (STATUS.APWSRDY) is set when the Automatic Power Switch is ready to operate. The Automatic Power Switch Ready bit in the Interrupt Flag Status and Clear (INTFLAG.APSWRDY) will be set at the same time.

Related Links

Electrical Characteristics on page 1144

BOD33 Power Switch

When the Configuration bit field in the Battery Backup Power Switch register (BBPS.CONF) are selecting the BOD33, BOD33 will function as Battery Backup Power Switch. In this case, when the VDD voltage is below the BOD33 threshold, the backup domain supply is switched to VBAT.

Main Power Supply OK (PSOK) Pin Enable

The state of the Main Power VDD can be used to switch between supply sources as long as the Battery Backup Power Switch is not configured as Automatic Power Switch (i.e., BBPS.CONF not set to APWS): when the Main Power Supply OK Pin Enable bit in the BBPS register is written to '1' (BBPS.PSOKEN), restoring VDD will form a low-to-high transition on the PSOK pin. This low-to-high transition will switch the Backup Power Supply back to VDD.

Note: With BBPS.PSOKEN=0 and BBPS.CONF not configured to APWS, the device can not be restarted.

Backup Battery Power Switch Status

The Battery Backup Power Switch bit in the Status register (STATUS.BBPS) indicates whether the backup domain is currently powered by VDD or VBAT.

23.6.3.4. Sleep Mode Operation

The Battery Backup Power Switch is not stopped in any sleep mode.

Entering Battery Backup Mode

Entering backup mode can be triggered by either:

- Wait-for-interrupt (WFI) instruction.
- Automatic Power Switch (BBPS.CONF=APWS). When the Automatic Power Switch detects loss of Main Power, the Backup Domain will be powered by battery and the device will enter the backup mode.
- BOD33 detection: When the BOD33 detects loss of Main Power, the Backup Domain will be powered by battery and the device will enter the backup mode. For this trigger, the following register configuration is required: BOD33.ACTION=BKUP, BOD33.VMON=VDD, and BBPS.CONF=BOD33.

Related Links

PM – Power Manager on page 192

Leaving Battery Backup Mode

Leaving backup mode can be triggered by either:

- RTC requests and externally triggered RSTC requests, under one of these conditions:
  - The Backup Domain is supplied by Main Power, and the Battery Backup Power Switch is *not* forced (BBPS.CONF not set to FORCED)
  - The Battery Backup Power Switch *is* forced (BBPS.CONF is FORCED)

  The device is kept in battery-powered backup mode until Main Power is restored to supply the device. Then, the backup domain will be powered by Main Power.

24.8.4. Interrupt Enable Clear

This register allows the user to disable an interrupt without doing a read-modify-write operation. Changes in this register will also be reflected in the Interrupt Enable Set (INTENSET) register.

Name: INTENCLR
Offset: 0x04
Reset: 0x00
Property: PAC Write-Protection

Bit	7	6	5	4	3	2	1	0
								EW
Access								R/W
Reset								0

Bit 0 – EW: Early Warning Interrupt Enable
Writing a '0' to this bit has no effect.

Writing a '1' to this bit clears the Early Warning Interrupt Enable bit, which disables the Early Warning interrupt.

Value	Description
0	The Early Warning interrupt is disabled.
1	The Early Warning interrupt is enabled.

25.12.1. Control A in Clock/Calendar mode (CTRLA.MODE=2)

Name: CTRLA
Offset: 0x00
Reset: 0x0000
Property: PAC Write-Protection, Enable-Protected, Write-Synchronized

Bit	15	14	13	12	11	10	9	8
	CLOCKSYNC				PRESCALER[3:0]			
Access	R/W				R/W	R/W	R/W	R/W
Reset	0				0	0	0	0

Bit	7	6	5	4	3	2	1	0
	MATCHCLR	CLKREP			MODE[1:0]		ENABLE	SWRST
Access	R/W	R/W			R/W	R/W	R/W	R/W
Reset	0	0			0	0	0	0

Bit 15 – CLOCKSYNC: CLOCK Read Synchronization Enable
The CLOCK register requires synchronization when reading. Disabling the synchronization will prevent reading valid values from the CLOCK register.
This bit is not enable-protected.

Value	Description
0	CLOCK read synchronization is disabled
1	CLOCK read synchronization is enabled

Bits 11:8 – PRESCALER[3:0]: Prescaler
These bits define the prescaling factor for the RTC clock source (GCLK_RTC) to generate the counter clock (CLK_RTC_CNT). Periodic events and interrupts are not available when the prescaler is off. These bits are not synchronized.

Value	Name	Description
0x0	OFF	CLK_RTC_CNT = GCLK_RTC/1
0x1	DIV1	CLK_RTC_CNT = GCLK_RTC/1
0x2	DIV2	CLK_RTC_CNT = GCLK_RTC/2
0x3	DIV4	CLK_RTC_CNT = GCLK_RTC/4
0x4	DIV8	CLK_RTC_CNT = GCLK_RTC/8
0x5	DIV16	CLK_RTC_CNT = GCLK_RTC/16
0x6	DIV32	CLK_RTC_CNT = GCLK_RTC/32
0x7	DIV64	CLK_RTC_CNT = GCLK_RTC/64
0x8	DIV128	CLK_RTC_CNT = GCLK_RTC/128
0x9	DIV256	CLK_RTC_CNT = GCLK_RTC/256
0xA	DIV512	CLK_RTC_CNT = GCLK_RTC/512

Bit 3 – EVIE: Channel Event Input Enable
This bit is available only for the least significant DMA channels. Refer to table: *User Multiplexer Selection* and *Event Generator Selection* of the Event System for details.

Value	Description
0	Channel event action will not be executed on any incoming event.
1	Channel event action will be executed on any incoming event.

Bits 2:0 – EVACT[2:0]: Event Input Action
These bits define the event input action, as shown below. The action is executed only if the corresponding EVIE bit in CHCTRLB register of the channel is set.

These bits are available only for the least significant DMA channels. Refer to table: *User Multiplexer Selection* and *Event Generator Selection* of the Event System for details.

EVACT[2:0]	Name	Description
0x0	NOACT	No action
0x1	TRIG	Normal Transfer and Conditional Transfer on Strobe trigger
0x2	CTRIG	Conditional transfer trigger
0x3	CBLOCK	Conditional block transfer
0x4	SUSPEND	Channel suspend operation
0x5	RESUME	Channel resume operation
0x6	SSKIP	Skip next block suspend action
0x7	-	Reserved

Writing a '0' to this bit has no effect.

Writing a '1' to this bit will clear the status.

Value	Description
0	No collision detected on last data byte sent.
1	Collision detected on last data byte sent.

Bit 0 – BUSERR: Bus Error
The Bus Error bit (STATUS.BUSERR) indicates that an illegal bus condition has occurred on the bus, regardless of bus ownership. An illegal bus condition is detected if a protocol violating start, repeated start or stop is detected on the I2C bus lines. A start condition directly followed by a stop condition is one example of a protocol violation. If a time-out occurs during a frame, this is also considered a protocol violation, and will set STATUS.BUSERR.

This bit is cleared automatically if responding to an address match with an ACK or a NACK (writing 0x3 to CTRLB.CMD) or INTFLAG.AMATCH is cleared.

Writing a '1' to this bit will clear the status.

Writing a '0' to this bit has no effect.

Value	Description
0	No bus error detected.
1	Bus error detected.

register values. When down-counting, the WO[x] is cleared at start or compare match between the COUNT and ZERO values, and set on compare match between COUNT and CCx register values.

The following equation calculates the exact resolution for a single-slope PWM (R_{PWM_SS}) waveform:

$$R_{PWM\_SS} = \frac{\log(TOP+1)}{\log(2)}$$

The PWM frequency (f_{PWM_SS}) depends on TOP value and the peripheral clock frequency (f_{GCLK_TCC}), and can be calculated by the following equation:

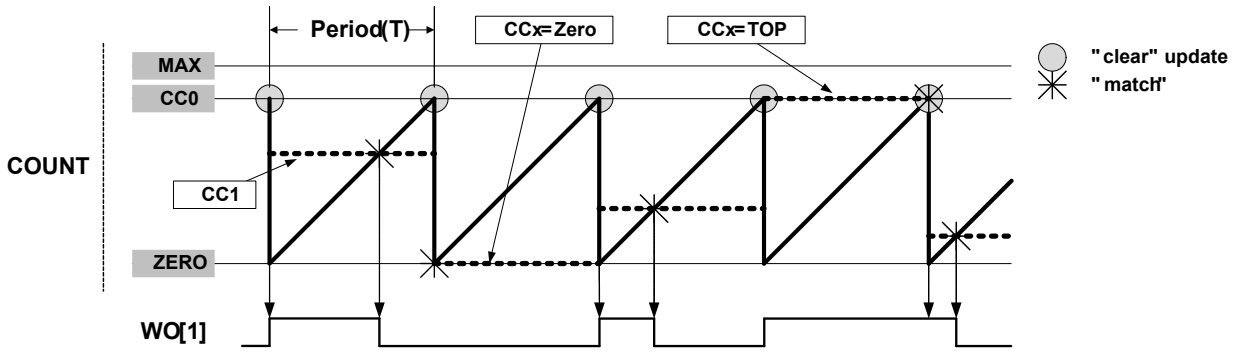
$$f_{PWM\_SS} = \frac{f_{GCLK\_TC}}{N(TOP+1)}$$

Where N represents the prescaler divider used (1, 2, 4, 8, 16, 64, 256, 1024).

Match Pulse-Width Modulation Operation (MPWM)

In MPWM, the output of WO[1] is depending on CC1 as shown in the figure below. On on every overflow/underflow, a one-TC-clock-cycle negative pulse is put out on WO[0] (not shown in the figure).

Figure 35-6. Match PWM Operation



The table below shows the update counter and overflow event/interrupt generation conditions in different operation modes.

Table 35-3. Counter Update and Overflow Event/interrupt Conditions in TC

Name	Operation	TOP	Update	Output Waveform		OVFIF/Event	
				On Match	On Update	Up	Down
NFRQ	Normal Frequency	PER	TOP/ ZERO	Toggle	Stable	TOP	ZERO
MFRQ	Match Frequency	CC0	TOP/ ZERO	Toggle	Stable	TOP	ZERO
NPWM	Single-slope PWM	PER	TOP/ ZERO	See description above.		TOP	ZERO
MPWM	Single-slope PWM	CC0	TOP/ ZERO	Toggle	Toggle	TOP	ZERO

Related Links

PORT: IO Pin Controller on page 512

35.6.2.7. Double Buffering

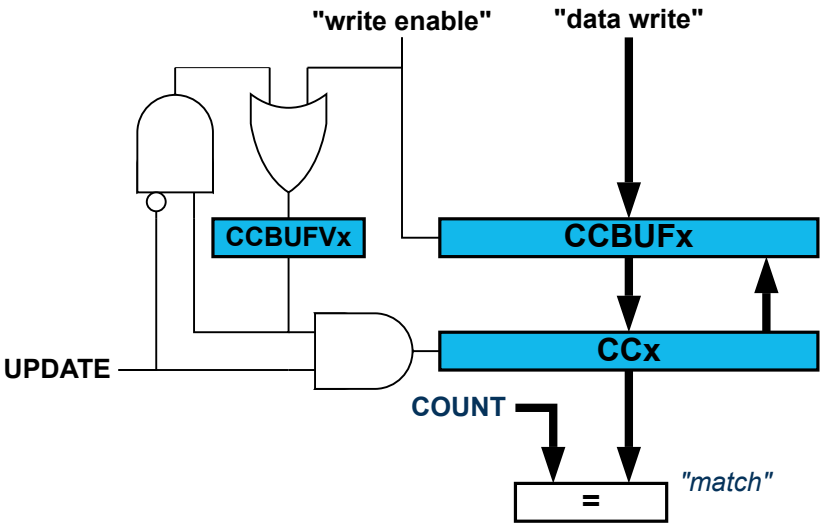
The Compare Channels (CCx) registers, and the Period (PER) register in 8-bit mode are double buffered. Each buffer register has a buffer valid bit (CCBUFVx or PERBUFV) in the STATUS register, which indicates that the buffer register contains a new valid value that can be copied into the corresponding register. As long as the respective buffer valid status flag (PERBUFV or CCBUFVx) are set to '1', related syncbusy bits are set (SYNCBUSY.PER or SYNCBUSY.CCx), a write to the respective PER/PERBUF or

CCx/CCBUFx registers will generate a PAC error, and access to the respective PER or CCx register is invalid.

When the buffer valid flag bit in the STATUS register is '1' and the Lock Update bit in the CTRLB register is set to '0', (writing CTRLBCLR.LUPD to '1'), double buffering is enabled: the data from buffer registers will be copied into the corresponding register under hardware UPDATE conditions, then the buffer valid flags bit in the STATUS register are automatically cleared by hardware.
Note: The software update command (CTRLBSET.CMD=0x3) is acting independently of the LUPD value.

A compare register is double buffered as in the following figure.

Figure 35-7. Compare Channel Double Buffering



Both the registers (PER/CCx) and corresponding buffer registers (PERBUF/CCBUFx) are available in the I/O register map, and the double buffering feature is not mandatory. The double buffering is disabled by writing a '1' to CTRLBSET.LUPD.

Note: In NFRQ, MFRQ or PWM down-counting counter mode (CTRLBSET.DIR=1), when double buffering is enabled (CTRLBCLR.LUPD=1), PERBUF register is continously copied into the PER independently of update conditions.

Changing the Period

The counter period can be changed by writing a new TOP value to the Period register (PER or CC0, depending on the waveform generation mode), any period update on registers (PER or CCx) is effective after the synchronization delay, whatever double buffering enabling is.

36.8.12. Interrupt Flag Status and Clear

Name: INTFLAG
Offset: 0x2C
Reset: 0x000000
Property: -

Bit	23	22	21	20	19	18	17	16
					MC3	MC2	MC1	MC0
Access					R/W	R/W	R/W	R/W
Reset					0	0	0	0

Bit	15	14	13	12	11	10	9	8
	FAULT1	FAULT0	FAULTB	FAULTA	DFS			
Access	R/W	R/W	R/W	R/W	R/W			
Reset	0	0	0	0	0			

Bit	7	6	5	4	3	2	1	0
					ERR	CNT	TRG	OVF
Access					R/W	R/W	R/W	R/W
Reset					0	0	0	0

Bit 13 – FAULTB: Recoverable Fault B Interrupt Flag
This flag is set on the next CLK_TCC_COUNT cycle after a Recoverable Fault B occurs.

Writing a '0' to this bit has no effect.

Writing a '1' to this bit clears the Recoverable Fault B interrupt flag.

Bit 12 – FAULTA: Recoverable Fault A Interrupt Flag
This flag is set on the next CLK_TCC_COUNT cycle after a Recoverable Fault B occurs.

Writing a '0' to this bit has no effect.

Writing a '1' to this bit clears the Recoverable Fault B interrupt flag.

Bit 11 – DFS: Debug Fault State Interrupt Flag
This flag is set on the next CLK_TCC_COUNT cycle after an Debug Fault State occurs.

Writing a '0' to this bit has no effect.

Writing a '1' to this bit clears the Debug Fault State interrupt flag.

Bit 3 – ERR: Error Interrupt Flag
This flag is set if a new capture occurs on a channel when the corresponding Match or Capture Channel x interrupt flag is one. In which case there is nowhere to store the new capture.

Writing a '0' to this bit has no effect.

Writing a '1' to this bit clears the error interrupt flag.

Bit 2 – CNT: Counter Interrupt Flag
This flag is set on the next CLK_TCC_COUNT cycle after a counter event occurs.

Writing a '0' to this bit has no effect.

36.8.15. Pattern

Name: PATT
Offset: 0x38
Reset: 0x0000
Property: Write-Synchronized, Read-Synchronized

Bit	15	14	13	12	11	10	9	8
	PGV7	PGV6	PGV5	PGV4	PGV3	PGV2	PGV1	PGV0
Access	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	0	0	0	0	0	0	0	0

Bit	7	6	5	4	3	2	1	0
	PGE7	PGE6	PGE5	PGE4	PGE3	PGE2	PGE1	PGE0
Access	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Reset	0	0	0	0	0	0	0	0

Bits 8, 9, 10, 11, 12, 13, 14, 15 – PGVn: Pattern Generation Output Value
This register holds the values of pattern for each waveform output.

Bits 0, 1, 2, 3, 4, 5, 6, 7 – PGEn: Pattern Generation Output Enable
This register holds the enable status of pattern generation for each waveform output. A bit written to '1' will override the corresponding SWAP output with the corresponding PGVn value.

Value	Name	Description						
		Operation	Top	Update	Waveform Output On Match	Waveform Output On Update	OVFIF/Event Up Down	
0x0	NFRQ	Normal Frequency	PER	TOP/Zero	Toggle	Stable	TOP	Zero
0x1	MFRQ	Match Frequency	CC0	TOP/Zero	Toggle	Stable	TOP	Zero
0x2	NPWM	Normal PWM	PER	TOP/Zero	Set	Clear	TOP	Zero
0x3	Reserved	–	–	–	–	–	–	–
0x4	DSCRITICAL	Dual-slope PWM	PER	Zero	~DIR	Stable	–	Zero
0x5	DSBOTTOM	Dual-slope PWM	PER	Zero	~DIR	Stable	–	Zero
0x6	DSBOTH	Dual-slope PWM	PER	TOP & Zero	~DIR	Stable	TOP	Zero
0x7	DSTOP	Dual-slope PWM	PER	Zero	~DIR	Stable	TOP	–

Bits 24, 25, 26, 27 – SWAPn: Swap DTI Output Pair x
Setting these bits enables output swap of DTI outputs [x] and [x+WO_NUM/2]. Note the DTIxEN settings will not affect the swap operation.

Bits 16, 17, 18, 19 – POLn: Channel Polarity x
Setting these bits enables the output polarity in single-slope and dual-slope PWM operations.

Value	Name	Description
0	(single-slope PWM waveform generation)	Compare output is initialized to ~DIR and set to DIR when TCC counter matches CCx value
1	(single-slope PWM waveform generation)	Compare output is initialized to DIR and set to ~DIR when TCC counter matches CCx value.
0	(dual-slope PWM waveform generation)	Compare output is set to ~DIR when TCC counter matches CCx value
1	(dual-slope PWM waveform generation)	Compare output is set to DIR when TCC counter matches CCx value.

Bits 8, 9, 10, 11 – CICCENn: Circular CC Enable x
Setting this bits enables the compare circular buffer option on channel. When the bit is set, CCx register value is copied-back into the CCx register on UPDATE condition.

39.8.2.8. Endpoint Interrupt Summary

Name: EPINTSMRY
Offset: 0x20
Reset: 0x00000000
Property: -

Bit	15	14	13	12	11	10	9	8
	EPINT[15:8]							
Access	R	R	R	R	R	R	R	R
Reset	0	0	0	0	0	0	0	0

Bit	7	6	5	4	3	2	1	0
	EPINT[7:0]							
Access	R	R	R	R	R	R	R	R
Reset	0	0	0	0	0	0	0	0

Bits 15:0 – EPINT[15:0]: EndPoint Interrupt
The flag EPINT[n] is set when an interrupt is triggered by the EndPoint n. See EPINTFLAGn register in the device EndPoint section.

This bit will be cleared when no interrupts are pending for EndPoint n.

39.8.3. Device Registers - Endpoint

39.8.6.5. Pipe Status Register n

Name: PSTATUS
Offset: 0x106 + (n x 0x20)
Reset: 0x0000
Property: PAC Write-Protection

Bit	7	6	5	4	3	2	1	0
	BK1RDY	BK0RDY		PFREEZE		CURBK		DTGL
Access	R	R		R		R		R
Reset	0	0		0		0		0

Bit 7 – BK1RDY: Bank 1 is ready
Writing a one to the bit EPSTATUSCLR.BK1RDY will clear this bit.

Writing a one to the bit EPSTATUSSET.BK1RDY will set this bit.

This bank is not used for Control pipe.

Value	Description
0	The bank number 1 is not ready: For IN the bank is empty. For Control/OUT the bank is not yet fill in.
1	The bank number 1 is ready: For IN the bank is filled full. For Control/OUT the bank is filled in.

Bit 6 – BK0RDY: Bank 0 is ready
Writing a one to the bit EPSTATUSCLR.BK0RDY will clear this bit.

Writing a one to the bit EPSTATUSSET.BK0RDY will set this bit.

This bank is the only one used for Control pipe.

Value	Description
0	The bank number 0 is not ready: For IN the bank is not empty. For Control/OUT the bank is not yet fill in.
1	The bank number 0 is ready: For IN the bank is filled full. For Control/OUT the bank is filled in.

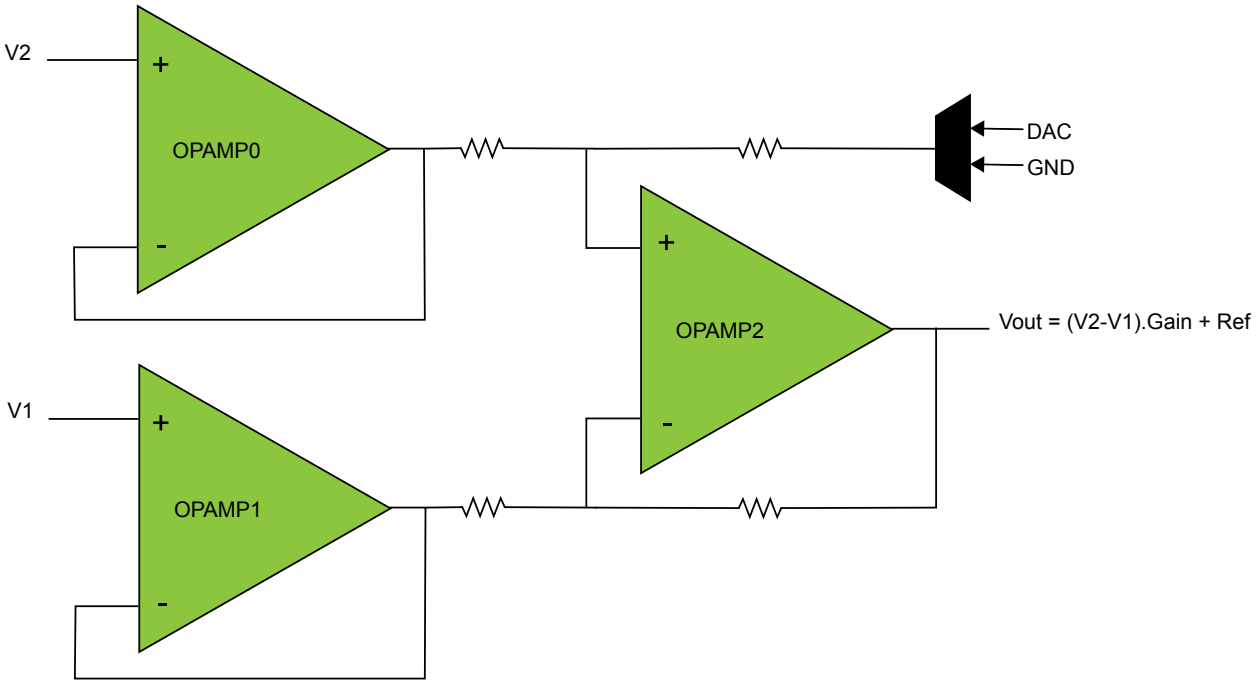
Bit 4 – PFREEZE: Pipe Freeze
Writing a one to the bit EPSTATUSCLR.PFREEZE will clear this bit.

Writing a one to the bit EPSTATUSSET.PFREEZE will set this bit.

This bit is also set by the hardware:

- When a STALL handshake has been received.
- After a PIPE has been enabled (rising of bit PEN.N).
- When an LPM transaction has completed whatever handshake is returned or the transaction was timed-out.
- When a pipe transfer was completed with a pipe error. See PINTFLAG register.

Figure 41-8. Instrumentation amplifier



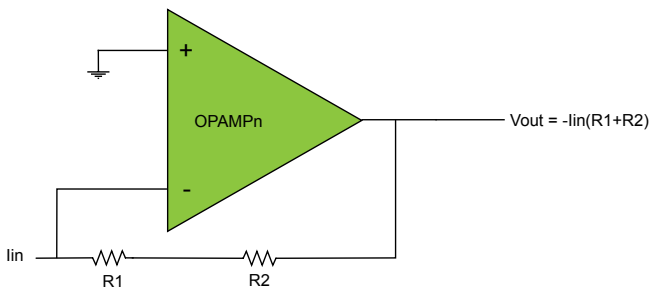
41.6.10.8. Transimpedance amplifier

Each OPAMP can be configured as a transimpedance amplifier (current to voltage converter). In this mode the positive input is connected to ground. The negative input is connected to the output through the resistor ladder. The OPAMPCTRLx register can be configured as follows:

Table 41-11. Transimpedance Amplifier

	MUXPOS	MUXNEG	RES1MUX	POTMUX	RES2VCC	RES2OUT	RES1EN	ANAOUT
OPAMP0	011	000	01	000	0	1	1	0
OPAMP1	011	000	01	000	0	1	1	0
OPAMP2	011	000	01	000	0	1	1	0

Figure 41-9. Transimpedance Amplifier



41.6.10.9. Programmable Hysteresis

Each OPAMP can be configured as an inverting or non-inverting comparator with programmable hysteresis. Applying hysteresis will prevent constant toggling of the output, caused by noise when the input signals are close to each other.

42. ADC – Analog-to-Digital Converter

42.1. Overview

The Analog-to-Digital Converter (ADC) converts analog signals to digital values. The ADC has up to 12-bit resolution, and is capable of a sampling rate of up to 1MSPS. The input selection is flexible, and both differential and single-ended measurements can be performed. In addition, several internal signal inputs are available. The ADC can provide both signed and unsigned results.

ADC measurements can be started by either application software or an incoming event from another peripheral in the device. ADC measurements can be started with predictable timing, and without software intervention.

Both internal and external reference voltages can be used.

An integrated temperature sensor is available for use with the ADC. The bandgap voltage as well as the scaled I/O and core voltages can also be measured by the ADC.

The ADC has a compare function for accurate monitoring of user-defined thresholds, with minimum software intervention required.

The ADC can be configured for 8-, 10- or 12-bit results. ADC conversion results are provided left- or right-adjusted, which eases calculation when the result is represented as a signed value. It is possible to use DMA to move ADC results directly to memory or peripherals when conversions are done.

42.2. Features

- 8-, 10- or 12-bit resolution
- Up to 1,000,000 samples per second (1MSPS)
- Differential and single-ended inputs
  - Up to 20 analog inputs
    28 positive and 10 negative, including internal and external
- Internal inputs:
  - Internal temperature sensor
  - Bandgap voltage
  - Scaled core supply
  - Scaled I/O supply
  - DAC
- Single, continuous and sequencing options
- Windowing monitor with selectable channel
- Conversion range: V_{ref} = [1.0V to VDD_{ANA}]
- Built-in internal reference and external reference options
- Event-triggered conversion for accurate timing (one event input)
- Optional DMA transfer of conversion settings or result
- Hardware gain and offset compensation
- Averaging and oversampling with decimation to support up to 16-bit result
- Selectable sampling time
- Flexible Power / Throughput rate management

42.7. Register Summary

Offset	Name	Bit Pos.								
0x00	CTRLA	7:0	ONDEMAND	RUNSTDBY					ENABLE	SWRST
0x01	CTRLB	7:0						PRESCALER[2:0]		
0x02	REFCTRL	7:0	REFCOMP				REFSEL[3:0]			
0x03	EVCTRL	7:0			WINMONEO	RESRDYEO	STARTINV	FLUSHINV	STARTEI	FLUSHEI
0x04	INTENCLR	7:0						WINMON	OVERRUN	RESRDY
0x05	INTENSET	7:0						WINMON	OVERRUN	RESRDY
0x06	INTFLAG	7:0						WINMON	OVERRUN	RESRDY
0x07	SEQSTATUS	7:0	SEQBUSY			SEQSTATE[4:0]				
0x08	INPUTCTRL	7:0				MUXPOS[4:0]				
0x09		15:8				MUXNEG[4:0]				
0x0A	CTRLC	7:0			RESSEL[1:0]		CORREN	FREERUN	LEFTADJ	DIFFMODE
0x0B		15:8						WINMODE[2:0]		
0x0C	AVGCTRL	7:0		ADJRES[2:0]			SAMPLENUM[3:0]			
0x0D	SAMPCTRL	7:0	OFFCOMP		SAMPLEN[5:0]					
0x0E	WINLT	7:0	WINLT[7:0]							
0x0F		15:8	WINLT[15:8]							
0x10	WINUT	7:0	WINUT[7:0]							
0x11		15:8	WINUT[15:8]							
0x12	GAINCORR	7:0	GAINCORR[7:0]							
0x13		15:8					GAINCORR[11:8]			
0x14	OFFSETCORR	7:0	OFFSETCORR[7:0]							
0x15		15:8					OFFSETCORR[11:8]			
0x16 ... 0x17	Reserved									
0x18	SWTRIG	7:0							START	FLUSH
0x19 ... 0x1B	Reserved									
0x1C	DBGCTRL	7:0								DBGRUN
0x1D ... 0x1F	Reserved									
0x20	SYNCBUSY	7:0	WINUT	WINLT	SAMPCTRL	AVGCTRL	CTRLC	INPUTCTRL	ENABLE	SWRST
0x21		15:8						SWTRIG	OFFSETCOR R	GAINCORR
0x22 ... 0x23	Reserved									
0x24	RESULT	7:0	RESULT[7:0]							
0x25		15:8	RESULT[15:8]							
0x26 ... 0x27	Reserved									

Mode	Conditions	Regulator	PL	Clock	Vcc	Ta	Typ.	Max.	Units
ACTIVE	WHILE1	LDO	PL0	OSC 12MHz	1.8V	Max at 85°C Typ at 25°C	60	80	µA/MHz
					3.3V		62	87	
				OSC 8MHz	1.8V		63	95	
					3.3V		65	106	
				OSC 4MHz	1.8V		72	138	
					3.3V		75	153	
			PL2	DFLL 48MHz	1.8V		73	80	
					3.3V		73	81	
		BUCK	PL0	OSC 12MHz	1.8V		38	51	
					3.3V		26	41	
				OSC 8MHz	1.8V		40	61	
					3.3V		29	51	
				OSC 4MHz	1.8V		47	90	
					3.3V		36	79	
			PL2	DFLL 48MHz	1.8V		52	59	
					3.3V		31	35	
IDLE			PL0	OSC 12MHz	1.8V		17	30	
					3.3V		13	24	

Note: 1. These values are based on characterization.

48.2.6. 32 pin TQFP

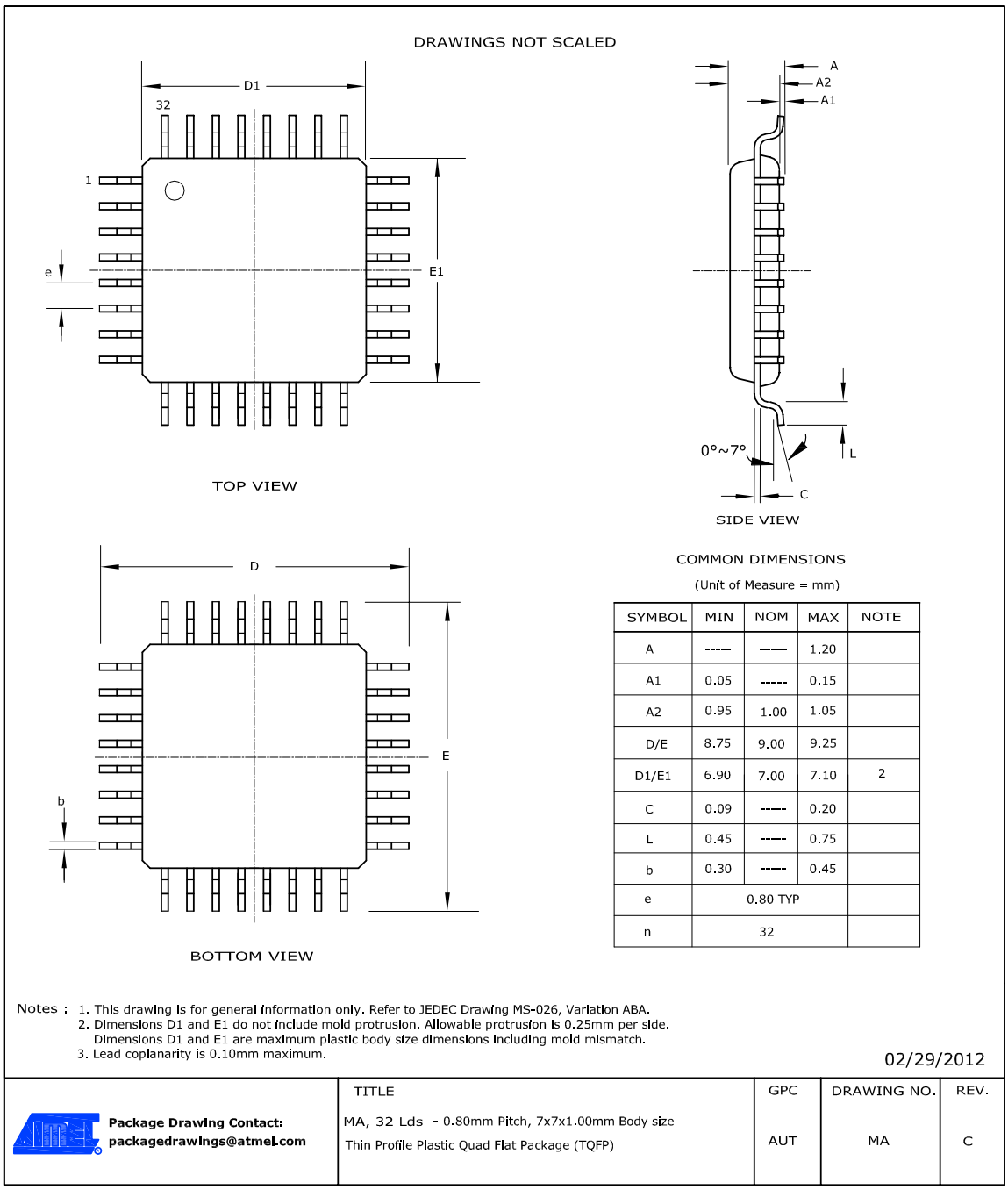


Table 48-17. Device and Package Maximum Weight

100	mg

Table 48-18. Package Charateristics

Moisture Sensitivity Level	MSL3