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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	dsPIC
Core Size	16-Bit
Speed	70 MIPS
Connectivity	CANbus, I ² C, IrDA, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, I ² S, POR, PWM, WDT
Number of I/O	51
Program Memory Size	128KB (43K x 24)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	8K x 8
Voltage - Supply (Vcc/Vdd)	3V ~ 3.6V
Data Converters	A/D 22x12b; D/A 2x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-TQFP
Supplier Device Package	64-TQFP (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/dspic33ep128gs806-i-pt

dsPIC33EPXXXGS70X/80X FAMILY

4.3.5 X AND Y DATA SPACES

The dsPIC33EPXXXGS70X/80X core has two Data Spaces, X and Y. These Data Spaces can be considered either separate (for some DSP instructions) or as one unified linear address range (for MCU instructions). The Data Spaces are accessed using two Address Generation Units (AGUs) and separate data paths. This feature allows certain instructions to concurrently fetch two words from RAM, thereby enabling efficient execution of DSP algorithms, such as Finite Impulse Response (FIR) filtering and Fast Fourier Transform (FFT).

The X Data Space is used by all instructions and supports all addressing modes. X Data Space has separate read and write data buses. The X read data bus is the read data path for all instructions that view Data Space as combined X and Y address space. It is also the X data prefetch path for the dual operand DSP instructions (MAC class).

The Y Data Space is used in concert with the X Data Space by the MAC class of instructions (CLR, ED, EDAC, MAC, MOVSA, MPY, MPY.N and MSC) to provide two concurrent data read paths.

Both the X and Y Data Spaces support Modulo Addressing mode for all instructions, subject to addressing mode restrictions. Bit-Reversed Addressing mode is only supported for writes to X Data Space.

All data memory writes, including in DSP instructions, view Data Space as combined X and Y address space. The boundary between the X and Y Data Spaces is device-dependent and is not user-programmable.

4.4 Memory Resources

Many useful resources are provided on the main product page of the Microchip web site for the devices listed in this data sheet. This product page contains the latest updates and additional information.

4.4.1 KEY RESOURCES

- **“dsPIC33E/PIC24E Program Memory”** (DS70000613) in the *“dsPIC33/PIC24 Family Reference Manual”*
- Code Samples
- Application Notes
- Software Libraries
- Webinars
- All Related *“dsPIC33/PIC24 Family Reference Manual”* Sections
- Development Tools

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TABLE 4-4: SFR BLOCK 200h

Register	Address	All Resets	Register	Address	All Resets	Register	Address	All Resets
I2C1 and I2C2			U1STA	222	0000000010010000	SPI1BRGH	252	0000000000000000
I2C1CONL	200	0001000000000000	U1TXREG	224	0000000xxxxxxx	SPI1IMSKL	254	0000000000000000
I2C1CONH	202	0000000000000000	U1RXREG	226	0000000000000000	SPI1IMSKH	256	0000000000000000
I2C1STAT	204	0000000000000000	U1BRG	228	0000000000000000	SPI1URDTL	258	0000000000000000
I2C1ADD	206	0000000000000000	U2MODE	230	0000000000000000	SPI1URDTH	25A	0000000000000000
I2C1MSK	208	0000000000000000	U2STA	232	0000000010010000	SPI2CON1L	260	0000000000000000
I2C1BRG	20A	0000000000000000	U2TXREG	234	0000000xxxxxxx	SPI2CON1H	262	0000000000000000
I2C1TRN	20C	0000000011111111	U2RXREG	236	0000000000000000	SPI2CON2L	264	0000000000000000
I2C1RCV	20E	0000000000000000	U2BRG	238	0000000000000000	SPI2CON2H	266	0000000000000000
I2C2CON1	210	0001000000000000	SPI			SPI2STATL	268	000000000101000
I2C2CON2	212	0000000000000000	SPI1CON1L	240	0000000000000000	SPI2STATH	26A	0000000000000000
I2C2STAT	214	0000000000000000	SPI1CON1H	242	0000000000000000	SPI2BUFL	26C	0000000000000000
I2C2ADD	216	0000000000000000	SPI1CON2L	244	0000000000000000	SPI2BUFH	26E	0000000000000000
I2C2MSK	218	0000000000000000	SPI1CON2H	246	0000000000000000	SPI3STAT	270	000xxxxxxx
I2C2BRG	21A	0000000000000000	SPI1STATL	248	000000000101000	SPI2BRGH	272	0000000000000000
I2C2TRN	21C	0000000011111111	SPI1STATH	24A	0000000000000000	SPI2IMSKL	274	0000000000000000
I2C2RCV	21E	0000000000000000	SPI1BUFL	24C	0000000000000000	SPI2IMSKH	276	0000000000000000
UART1 and UART2			SPI1BUFH	24E	0000000000000000	SPI2URDTL	278	0000000000000000
U1MODE	220	0000000000000000	SPI1BRGL	250	000xxxxxxx	SPI2URDTH	27A	0000000000000000

Legend: x = unknown or indeterminate value. Address values are in hexadecimal. Reset values are in binary.

TABLE 4-5: SFR BLOCK 300h

Register	Address	All Resets	Register	Address	All Resets	Register	Address	All Resets
ADC			ADCMPOENH	33A	0000000000000000	ADTRIG4L	390	0000000000000000
ADCON1L	300	0000000000000000	ADCMPOLO	33C	0000000000000000	ADTRIG4H	392	0000000000000000
ADCON1H	302	0000000001100000	ADCMPOHI	33E	0000000000000000	ADCMPOCON	3A0	0000000000000000
ADCON2L	304	0000000000000000	ADCMPIENL	340	0000000000000000	ADCMPICON	3A4	0000000000000000
ADCON2H	306	0000000000000000	ADCMPIENH	342	0000000000000000	ADBASE	3C0	0000000000000000
ADCON3L	308	0000000000000000	ADCMP1LO	344	0000000000000000	ADLVLTRGL	3D0	0000000000000000
ADCON3H	30A	0000000000000000	ADCMP1HI	346	0000000000000000	ADLVLTRGH	3D2	0000000000000000
ADCON4L	30C	0000000000000000	ADFL0DAT	368	0000000000000000	ADCORE0L	3D4	0000000000000000
ADCON4H	30E	0000000000000000	ADFL0CON	36A	0000000000000000	ADCORE0H	3D6	0000001100000000
ADMOD0L	310	0000000000000000	ADFL1DAT	36C	0000000000000000	ADCORE1L	3D8	0000000000000000
ADMOD0H	312	0000000000000000	ADFL1CON	36E	0000000000000000	ADCORE1H	3DA	0000001100000000
ADMOD1L	314	0000000000000000	ADTRIG0L	380	0000000000000000	ADCORE2L	3DC	0000000000000000
ADIEL	320	0000000000000000	ADTRIG0H	382	0000000000000000	ADCORE2H	3DE	0000001100000000
ADIEH	322	0000000000000000	ADTRIG1L	384	0000000000000000	ADCORE3L	3E0	0000000000000000
ADCSS1L	328	0000000000000000	ADTRIG1H	386	0000000000000000	ADCORE3H	3E2	0000001100000000
ADCSS1H	32A	0000000000000000	ADTRIG2L	388	0000000000000000	ADEIEL	3F0	0000000000000000
ADSTATL	330	0000000000000000	ADTRIG2H	38A	0000000000000000	ADEIEH	3F2	0000000000000000
ADSTATH	332	0000000000000000	ADTRIG3L	38C	0000000000000000	ADEISTATL	3F8	0000000000000000
ADCMPOENL	338	0000000000000000	ADTRIG3H	38E	0000000000000000	ADEISTATH	3FA	0000000000000000

Legend: x = unknown or indeterminate value. Address values are in hexadecimal. Reset values are in binary.

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REGISTER 8-11: DMAPWC: DMA PERIPHERAL WRITE COLLISION STATUS REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	U-0	U-0
—	—	—	—	—	—	—	—
bit 15							bit 8

U-0	U-0	U-0	U-0	R-0	R-0	R-0	R-0
—	—	—	—	PWCOL3	PWCOL2	PWCOL1	PWCOL0
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

- bit 15-4 **Unimplemented:** Read as '0'
- bit 3 **PWCOL3:** Channel 3 Peripheral Write Collision Flag bit
 1 = Write collision is detected
 0 = No write collision is detected
- bit 2 **PWCOL2:** Channel 2 Peripheral Write Collision Flag bit
 1 = Write collision is detected
 0 = No write collision is detected
- bit 1 **PWCOL1:** Channel 1 Peripheral Write Collision Flag bit
 1 = Write collision is detected
 0 = No write collision is detected
- bit 0 **PWCOL0:** Channel 0 Peripheral Write Collision Flag bit
 1 = Write collision is detected
 0 = No write collision is detected

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REGISTER 11-29: RPINR42: PERIPHERAL PIN SELECT INPUT REGISTER 42

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
FLT6R7	FLT6R6	FLT6R5	FLT6R4	FLT6R3	FLT6R2	FLT6R1	FLT6R0
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
FLT5R7	FLT5R6	FLT5R5	FLT5R4	FLT5R3	FLT5R2	FLT5R1	FLT5R0
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-8 **FLT6R<7:0>**: Assign PWM Fault 6 (FLT6) to the Corresponding RPn Pin bits
See Table 11-11 which contains a list of remappable inputs for the index value.

bit 7-0 **FLT5R<7:0>**: Assign PWM Fault 5 (FLT5) to the Corresponding RPn Pin bits
See Table 11-11 which contains a list of remappable inputs for the index value.

REGISTER 11-30: RPINR43: PERIPHERAL PIN SELECT INPUT REGISTER 43

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
FLT8R7	FLT8R6	FLT8R5	FLT8R4	FLT8R3	FLT8R2	FLT8R1	FLT8R0
bit 15							bit 8

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
FLT7R7	FLT7R6	FLT7R5	FLT7R4	FLT7R3	FLT7R2	FLT7R1	FLT7R0
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 15-8 **FLT8R<7:0>**: Assign PWM Fault 8 (FLT8) to the Corresponding RPn Pin bits
See Table 11-11 which contains a list of remappable inputs for the index value.

bit 7-0 **FLT7R<7:0>**: Assign PWM Fault 7 (FLT7) to the Corresponding RPn Pin bits
See Table 11-11 which contains a list of remappable inputs for the index value.

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REGISTER 15-2: OCxCON2: OUTPUT COMPARE x CONTROL REGISTER 2 (CONTINUED)

bit 4-0 **SYNCSEL<4:0>**: Trigger/Synchronization Source Selection bits

- 11111 = OCxRS compare event is used for synchronization
- 11110 = INT2 pin synchronizes or triggers OCx
- 11101 = INT1 pin synchronizes or triggers OCx
- 11100 = Reserved
- 11011 = CMP4 module synchronizes or triggers OCx
- 11010 = CMP3 module synchronizes or triggers OCx
- 11001 = CMP2 module synchronizes or triggers OCx
- 11000 = CMP1 module synchronizes or triggers OCx
- 10111 = Reserved
- 10110 = Reserved
- 10101 = Reserved
- 10100 = Reserved
- 10011 = IC4 input capture interrupt event synchronizes or triggers OCx
- 10010 = IC3 input capture interrupt event synchronizes or triggers OCx
- 10001 = IC2 input capture interrupt event synchronizes or triggers OCx
- 10000 = IC1 input capture interrupt event synchronizes or triggers OCx
- 01111 = Timer5 synchronizes or triggers OCx
- 01110 = Timer4 synchronizes or triggers OCx
- 01101 = Timer3 synchronizes or triggers OCx
- 01100 = Timer2 synchronizes or triggers OCx **(default)**
- 01011 = Timer1 synchronizes or triggers OCx
- 01010 = PTG Trigger Output x⁽³⁾
- 01001 = Reserved
- 01000 = IC4 input capture event synchronizes or triggers OCx
- 00111 = IC3 input capture event synchronizes or triggers OCx
- 00110 = IC2 input capture event synchronizes or triggers OCx
- 00101 = IC1 input capture event synchronizes or triggers OCx
- 00100 = OC4 module synchronizes or triggers OCx^(1,2)
- 00011 = OC3 module synchronizes or triggers OCx^(1,2)
- 00010 = OC2 module synchronizes or triggers OCx^(1,2)
- 00001 = OC1 module synchronizes or triggers OCx^(1,2)
- 00000 = No sync or trigger source for OCx

- Note 1:** Do not use the OCx module as its own synchronization or trigger source.
- 2:** When the OCy module is turned off, it sends a trigger out signal. If the OCx module uses the OCy module as a trigger source, the OCy module must be unselected as a trigger source prior to disabling it.
- 3:** For each OCMPx instance, a different PTG trigger out is used:
- OCMP1 – PTG trigger out [0]
 - OCMP2 – PTG trigger out [1]
 - OCMP3 – PTG trigger out [2]
 - OCMP4 – PTG trigger out [3]

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TABLE 21-1: CLC1 MULTIPLEXER INPUT SOURCES

DSx<2:0>		Signal Source
DS1<2:0>	000	CLCINA
	001	System Clock
	010	Timer1 Match
	011	PWM1H
	100	PWM5L
	101	High-Speed PWM Clock
	110	Timer2 Match
	111	Timer3 Match
DS2<2:0>	000	CLCINB
	001	CLC2 Out
	010	CMP1 Out
	011	UART1 TX Out
	100	ADC End-of-Conversion
	101	DMA Channel 0 Interrupt
	110	PWM1L
	111	PWM5H
DS3<2:0>	000	CLCINA
	001	CLC1 Out
	010	CMP2 Out
	011	SPI1 SDO Out
	100	UART1 RX
	101	PWM2H
	110	PWM6L
	111	OCMP2
DS4<2:0>	000	CLCINB
	001	CLC2 Out
	010	CMP3 Out
	011	SDI1
	100	PTG
	101	ECAN1
	110	PWM2L
	111	PWM6H

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REGISTER 21-4: CLCxGLSL: CLCx GATE LOGIC INPUT SELECT LOW REGISTER (CONTINUED)

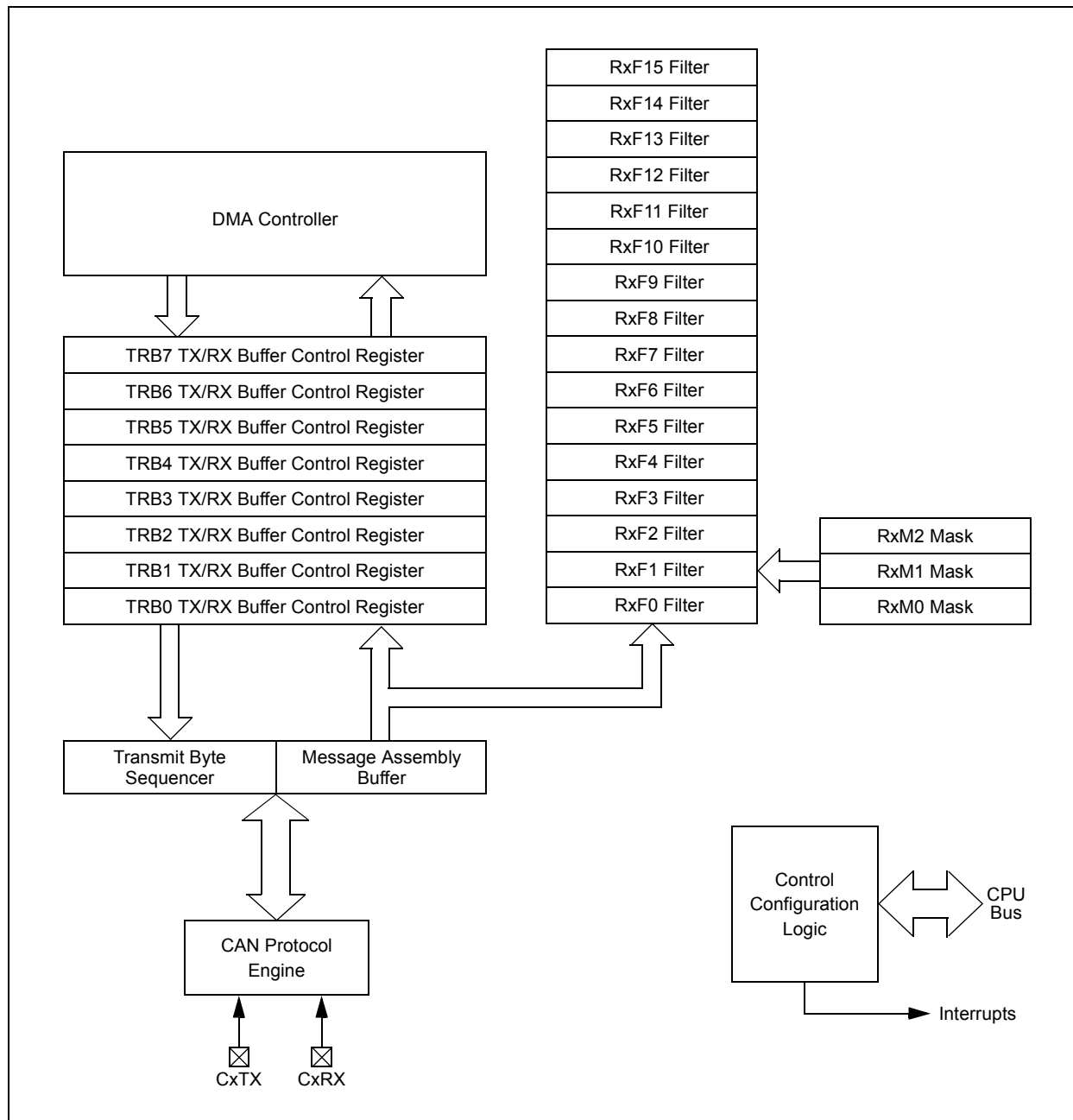
- bit 3 **G1D2T:** Gate 1 Data Source 2 True Enable bit
1 = Data Source 2 non-inverted signal is enabled for Gate 1
0 = Data Source 2 non-inverted signal is disabled for Gate 1
- bit 2 **G1D2N:** Gate 1 Data Source 2 Negated Enable bit
1 = Data Source 2 inverted signal is enabled for Gate 1
0 = Data Source 2 inverted signal is disabled for Gate 1
- bit 1 **G1D1T:** Gate 1 Data Source 1 True Enable bit
1 = Data Source 1 non-inverted signal is enabled for Gate 1
0 = Data Source 1 non-inverted signal is disabled for Gate 1
- bit 0 **G1D1N:** Gate 1 Data Source 1 Negated Enable bit
1 = Data Source 1 inverted signal is enabled for Gate 1
0 = Data Source 1 inverted signal is disabled for Gate 1

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NOTES:

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FIGURE 23-1: CANx MODULE BLOCK DIAGRAM



23.2 Modes of Operation

The CANx module can operate in one of several operation modes selected by the user. These modes include:

- Initialization mode
- Disable mode
- Normal Operation mode
- Listen Only mode
- Listen All Messages mode
- Loopback mode

Modes are requested by setting the REQOP<2:0> bits (CxCTRL1<10:8>). Entry into a mode is Acknowledged by monitoring the OPMODE<2:0> bits (CxCTRL1<7:5>). The module does not change the mode and the OPMODEx bits until a change in mode is acceptable, generally during bus Idle time, which is defined as at least 11 consecutive recessive bits.

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NOTES:

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24.3 Module Applications

This module provides a means for the SMPS dsPIC[®] DSC devices to monitor voltage and currents in a power conversion application. The ability to detect transient conditions and stimulate the dsPIC DSC processor and/or peripherals, without requiring the processor and ADC to constantly monitor voltages or currents, frees the dsPIC DSC to perform other tasks.

The comparator module has a high-speed comparator and an associated 12-bit DAC that provides a programmable reference voltage to the inverting input of the comparator. The polarity of the comparator output is user-programmable. The output of the module can be used in the following modes:

- Generate an Interrupt
- Trigger an ADC Sample and Convert Process
- Truncate the PWMx Signal (current limit)
- Truncate the PWMx Period (current minimum)
- Disable the PWMx Outputs (Fault latch)

The output of the comparator module may be used in multiple modes at the same time, such as: 1) generate an interrupt, 2) have the ADC take a sample and convert it, and 3) truncate the PWMx output in response to a voltage being detected beyond its expected value.

The comparator module can also be used to wake-up the system from Sleep or Idle mode when the analog input voltage exceeds the programmed threshold voltage.

24.4 Digital-to-Analog Comparator (DAC)

Each analog comparator has a dedicated 12-bit DAC that is used to program the comparator threshold voltage via the CMPxDAC register. The DAC voltage reference source is selected using the EXTREF and RANGE bits in the CMPxCON register.

The EXTREF bit selects either the external voltage reference, EXTREFx, or an internal source as the voltage reference source. The EXTREFx input enables users to connect to a voltage reference that better suits their application. The RANGE bit enables AVDD as the voltage reference source for the DAC when an internal voltage reference is selected.

Note: EXTREF2 is not available on all devices.

Each DACx has an output enable bit, DACOE, in the CMPxCON register that enables the DACx reference voltage to be routed to an external output pin (DACOUTx). Refer to Figure 24-1 for connecting the DACx output voltage to the DACOUTx pins.

Note 1: Ensure that multiple DACOE bits are not set in software. The output on the DACOUTx pin will be indeterminate if multiple comparators enable the DACx output.

2: DACOUT2 is not available on all devices.

24.5 Pulse Stretcher and Digital Logic

The analog comparator can respond to very fast transient signals. After the comparator output is given the desired polarity, the signal is passed to a pulse stretching circuit. The pulse stretching circuit has an asynchronous set function and a delay circuit that ensures the minimum pulse width is three system clock cycles wide to allow the attached circuitry to properly respond to a narrow pulse event.

The pulse stretcher circuit is followed by a digital filter. The digital filter is enabled via the FLTREN bit in the CMPxCON register. The digital filter operates with the clock specified via the FCLKSEL bit in the CMPxCON register. The comparator signal must be stable in a high or low state, for at least three of the selected clock cycles, for it to pass through the digital filter.

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25.0 PROGRAMMABLE GAIN AMPLIFIER (PGA)

Note 1: This data sheet summarizes the features of the dsPIC33EPXXXGS70X/80X family of devices. It is not intended to be a comprehensive reference source. To complement the information in this data sheet, refer to “**Programmable Gain Amplifier (PGA)**” (DS70005146) in the “dsPIC33/PIC24 Family Reference Manual”, which is available from the Microchip web site (www.microchip.com).

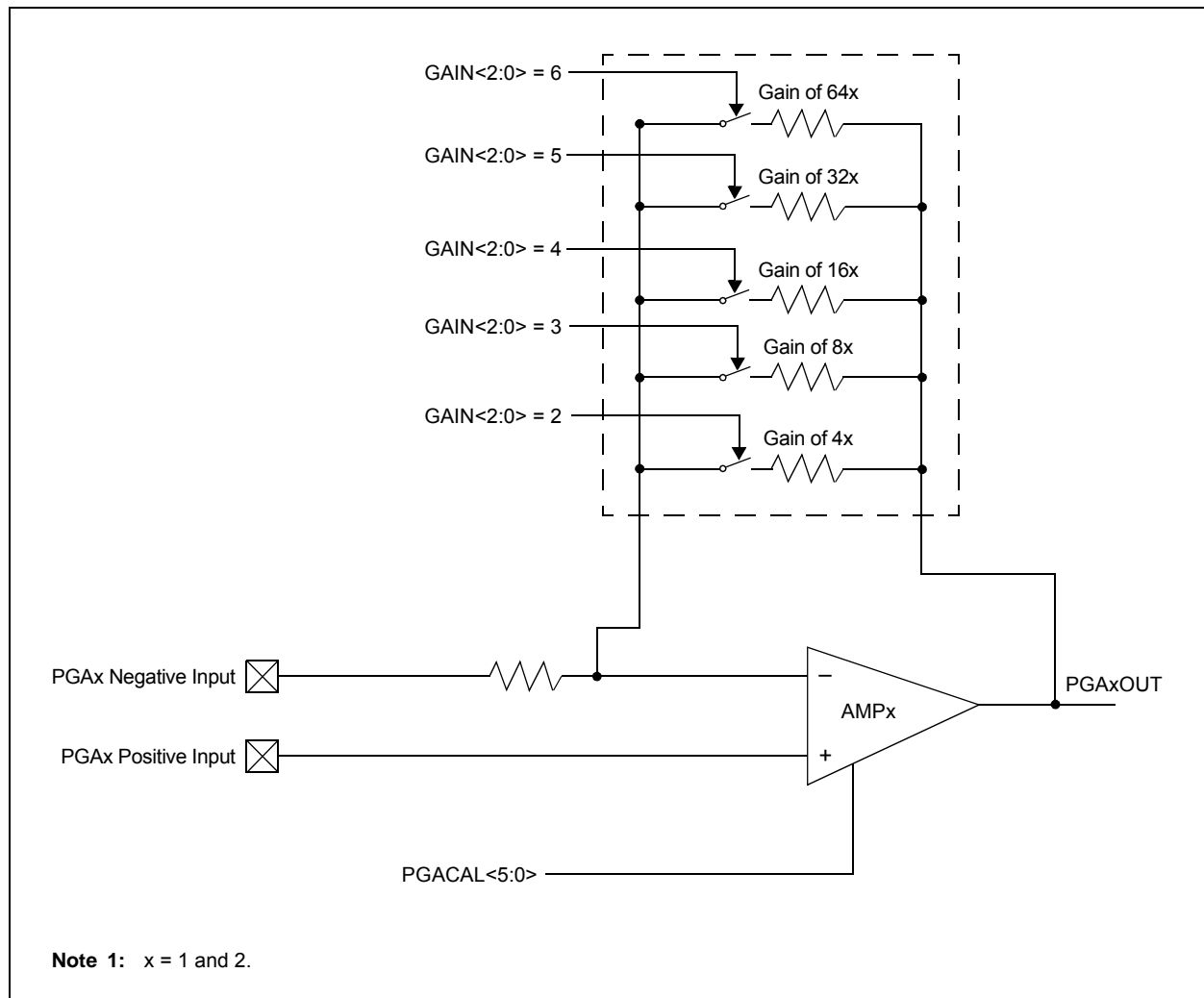
2: Some registers and associated bits described in this section may not be available on all devices. Refer to **Section 4.0 “Memory Organization”** in this data sheet for device-specific register and bit information.

The dsPIC33EPXXXGS70X/80X family devices have two Programmable Gain Amplifiers (PGA1, PGA2). The PGA is an op amp-based, non-inverting amplifier with user-programmable gains. The output of the PGA can be connected to a number of dedicated Sample-and-Hold inputs of the Analog-to-Digital Converter and/or to the high-speed analog comparator module. The PGA has five selectable gains and may be used as a ground referenced amplifier (single-ended) or used with an independent ground reference point.

Key features of the PGA module include:

- Single-Ended or Independent Ground Reference
- Selectable Gains: 4x, 8x, 16x, 32x and 64x
- High Gain Bandwidth
- Rail-to-Rail Output Voltage
- Wide Input Voltage Range

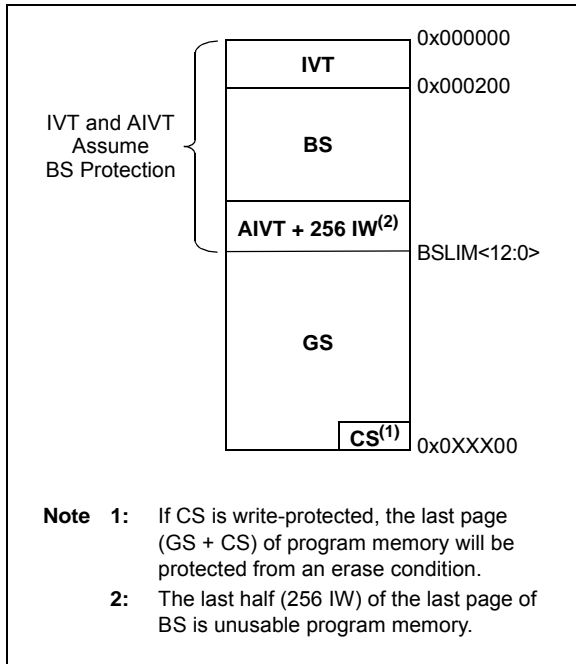
FIGURE 25-1: PGAx MODULE BLOCK DIAGRAM



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The different device security segments are shown in Figure 27-3. Here, all three segments are shown but are not required. If only basic code protection is required, then GS can be enabled independently or combined with CS, if desired.

FIGURE 27-3: SECURITY SEGMENTS EXAMPLE FOR dsPIC33EPXXXGS70X/80X DEVICES

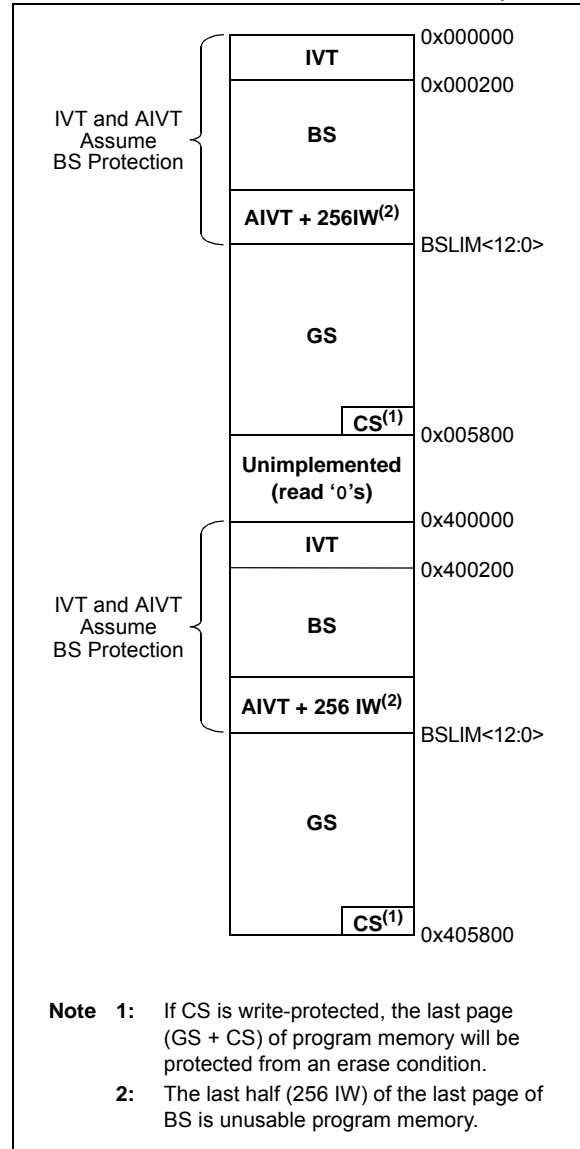


dsPIC33EPXXXGS70X/80X family devices can be operated in Dual Partition mode, where security is required for each partition. When operating in Dual Partition mode, the Active and Inactive Partitions both contain unique copies of the Reset vector, Interrupt Vector Tables (IVT and AIVT, if enabled) and the Flash Configuration Words. Both partitions have the three security segments described previously. Code may not be executed from the Inactive Partition, but it may be programmed by, and read from, the Active Partition, subject to defined code protection. Figure 27-4 and Figure 27-5 show the different security segments for devices operating in Dual Partition mode.

The device may also operate in a Protected Dual Partition mode or in Privileged Dual Partition mode. In Protected Dual Partition mode, Partition 1 is permanently erase/write-protected. This implementation allows for a “Factory Default” mode, which provides a fail-safe backup image to be stored in Partition 1. For example, a fail-safe bootloader can be placed in Partition 1, along with a fail-safe backup code image, which can be used or rewritten into Partition 2 in the event of a failed Flash update to Partition 2.

Privileged Dual Partition mode performs the same function as Protected Dual Partition mode, except additional constraints are applied in an effort to prevent code in the Boot Segment and General Segment from being used against each other.

FIGURE 27-4: SECURITY SEGMENTS EXAMPLE FOR dsPIC33EP64GS70X/80X DEVICES (DUAL PARTITION MODES)



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NOTES:

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TABLE 30-20: INTERNAL FRC ACCURACY

AC CHARACTERISTICS		Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended					
Param No.	Characteristic	Min.	Typ.	Max.	Units	Conditions	
Internal FRC Accuracy @ FRC Frequency = 7.37 MHz ⁽¹⁾							
F20a	FRC	-2	0.5	+2	%	-40°C ≤ TA ≤ -10°C	VDD = 3.0-3.6V
		-0.9	0.5	+0.9	%	-10°C ≤ TA ≤ +85°C	VDD = 3.0-3.6V
F20b	FRC	-2	1	+2	%	+85°C ≤ TA ≤ +125°C	VDD = 3.0-3.6V

Note 1: Frequency is calibrated at +25°C and 3.3V. TUNx bits can be used to compensate for temperature drift.

TABLE 30-21: INTERNAL LPRC ACCURACY

AC CHARACTERISTICS		Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature $-40^{\circ}\text{C} \leq T_A \leq +85^{\circ}\text{C}$ for Industrial $-40^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$ for Extended					
Param No.	Characteristic	Min.	Typ.	Max.	Units	Conditions	
LPRC @ 32.768 kHz ⁽¹⁾							
F21a	LPRC	-30	—	+30	%	$-40^{\circ}\text{C} \leq T_A \leq -10^{\circ}\text{C}$	VDD = 3.0-3.6V
		-20	—	+20	%	$-10^{\circ}\text{C} \leq T_A \leq +85^{\circ}\text{C}$	VDD = 3.0-3.6V
F21b	LPRC	-30	—	+30	%	$+85^{\circ}\text{C} \leq T_A \leq +125^{\circ}\text{C}$	VDD = 3.0-3.6V

Note 1: This is the change of the LPRC frequency as VDD changes.

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**TABLE 30-45: SPI3 SLAVE MODE (FULL-DUPLEX, CKE = 0, CKP = 1, SMP = 0)
TIMING REQUIREMENTS⁽⁵⁾**

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param.	Symbol	Characteristic ⁽¹⁾	Min.	Typ. ⁽²⁾	Max.	Units	Conditions
SP70	FscP	Maximum SCK3 Input Frequency	—	—	25	MHz	(Note 3)
SP72	TscF	SCK3 Input Fall Time	—	—	—	ns	See Parameter DO32 (Note 4)
SP73	TscR	SCK3 Input Rise Time	—	—	—	ns	See Parameter DO31 (Note 4)
SP30	TdoF	SDO3 Data Output Fall Time	—	—	—	ns	See Parameter DO32 (Note 4)
SP31	TdoR	SDO3 Data Output Rise Time	—	—	—	ns	See Parameter DO31 (Note 4)
SP35	Tsch2doV, TscL2doV	SDO3 Data Output Valid after SCK3 Edge	—	6	20	ns	
SP36	TdoV2scH, TdoV2scL	SDO3 Data Output Setup to First SCK3 Edge	20	—	—	ns	
SP40	TdiV2scH, TdiV2scL	Setup Time of SDI3 Data Input to SCK3 Edge	20	—	—	ns	
SP41	Tsch2diL, TscL2diL	Hold Time of SDI3 Data Input to SCK3 Edge	15	—	—	ns	
SP50	TssL2scH, TssL2scL	$\overline{SS3} \downarrow$ to SCK3 \uparrow or SCK3 \downarrow Input	120	—	—	ns	
SP51	TssH2doZ	$\overline{SS3} \uparrow$ to SDO3 Output High-Impedance	10	—	50	ns	(Note 4)
SP52	Tsch2ssH, TscL2ssH	$\overline{SS3} \uparrow$ after SCK3 Edge	1.5 TCY + 40	—	—	ns	(Note 4)

- Note 1:** These parameters are characterized, but are not tested in manufacturing.
- 2:** Data in “Typical” column is at 3.3V, +25°C unless otherwise stated.
- 3:** The minimum clock period for SCK3 is 66.7 ns. Therefore, the SCK3 clock generated by the master must not violate this specification.
- 4:** Assumes 50 pF load on all SPI3 pins.
- 5:** For dsPIC33EPXXXGSX06 and dsPIC33EPXXXGSX08 devices with a fixed SCK3 pin.

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TABLE 30-53: ANALOG-TO-DIGITAL CONVERSION TIMING REQUIREMENTS

AC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) ⁽²⁾ Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	Symbol	Characteristics	Min.	Typ. ⁽¹⁾	Max.	Units	Conditions
Clock Parameters							
AD50	TAD	ADC Clock Period	14.28	—	—	ns	
Throughput Rate							
AD51	FTP	SH0-SH3	—	—	3.25	Msp/s	70 MHz ADC clock, 12 bits, no pending conversion at time of trigger
		SH4	—	—	3.25	Msp/s	

Note 1: These parameters are characterized but not tested in manufacturing.

Note 2: The ADC module is functional at VBORMIN < VDD < VDDMIN, but with degraded performance. Unless otherwise stated, module functionality is ensured, but not characterized.

TABLE 30-54: HIGH-SPEED ANALOG COMPARATOR MODULE SPECIFICATIONS

AC/DC CHARACTERISTICS			Standard Operating Conditions: 3.0V to 3.6V (unless otherwise stated) ⁽²⁾ Operating temperature -40°C ≤ TA ≤ +85°C for Industrial -40°C ≤ TA ≤ +125°C for Extended				
Param No.	Symbol	Characteristic	Min.	Typ.	Max.	Units	Comments
CM10	VIOFF	Input Offset Voltage	-35	±5	35	mV	
CM11	VICM	Input Common-Mode Voltage Range ⁽¹⁾	0	—	AVDD	V	
CM13	CMRR	Common-Mode Rejection Ratio	60	—	—	dB	
CM14	TRESP	Large Signal Response	—	15	—	ns	V+ input step of 100 mV while V- input is held at AVDD/2. Delay measured from analog input pin to PWMx output pin.
CM15	VHYST	Input Hysteresis	5	10	20	mV	Depends on HYSSEL<1:0>
CM16	TON	Comparator Enabled to Valid Output	—	—	1	μs	

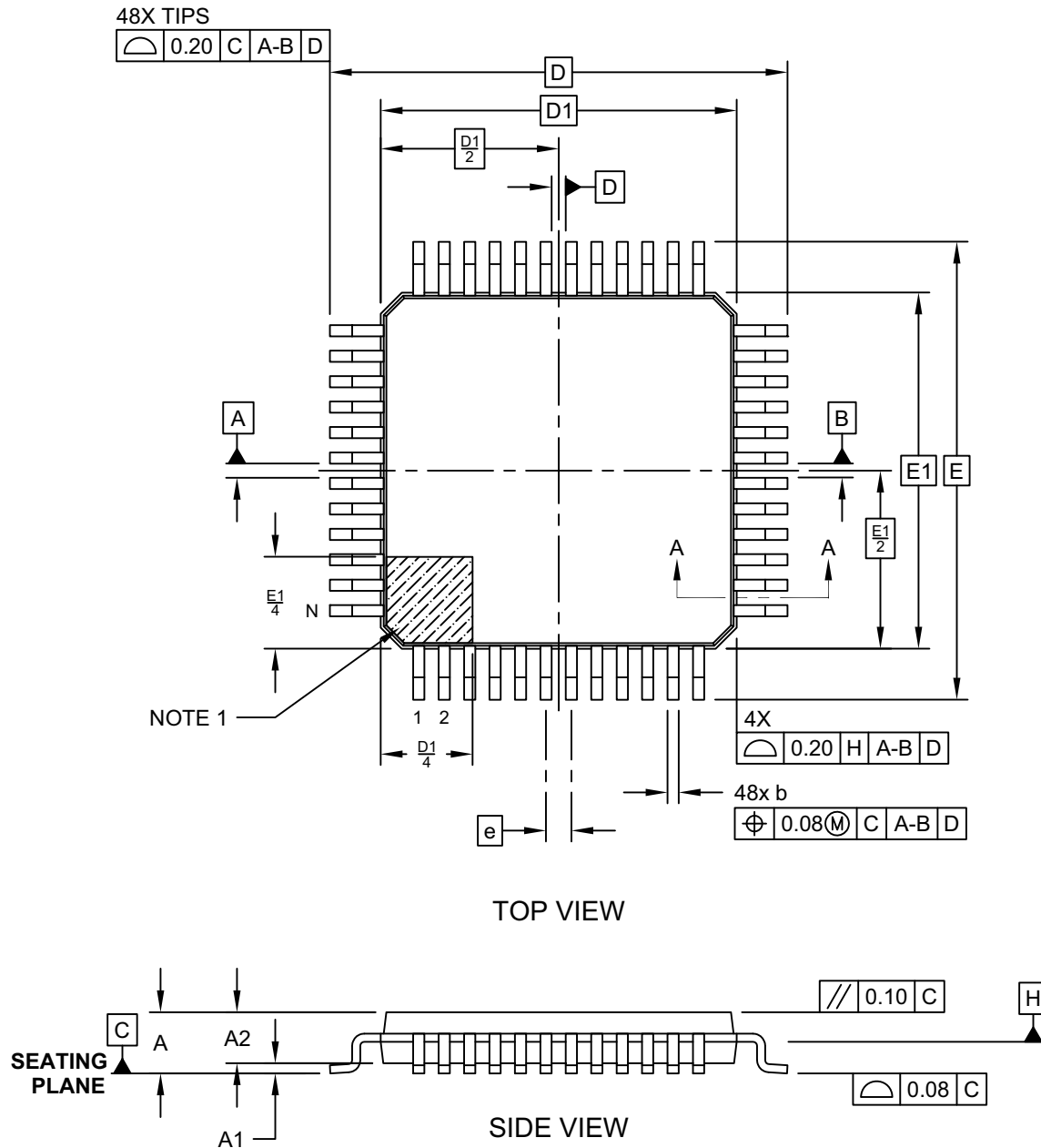
Note 1: These parameters are for design guidance only and are not tested in manufacturing.

Note 2: The comparator module is functional at VBORMIN < VDD < VDDMIN, but with degraded performance. Unless otherwise stated, module functionality is tested, but not characterized.

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48-Lead Thin Quad Flatpack (PT) - 7x7x1.0 mm Body [TQFP]

Note: For the most current package drawings, please see the Microchip Packaging Specification located at <http://www.microchip.com/packaging>



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NOTES: