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Applications of "Embedded - Microcontrollers"

Details	
Product Status	Obsolete
Core Processor	HCS12
Core Size	16-Bit
Speed	25MHz
Connectivity	EBI/EMI, SCI, SPI
Peripherals	POR, PWM, WDT
Number of I/O	60
Program Memory Size	128KB (128K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	4K x 8
Voltage - Supply (Vcc/Vdd)	2.35V ~ 5.5V
Data Converters	A/D 8x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	80-QFP
Supplier Device Package	80-QFP (14x14)
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/mc9s12gc128vfue

Address	Name		Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0x005F	TC7 (lo)	Read:	Bit 7	6	5	4	3	2	1	Bit 0
		Write:								
0x0060	PACTL	Read:	0	PAEN	PAMOD	PEDGE	CLK1	CLK0	PAOVI	PAI
		Write:								
0x0061	PAFLG	Read:	0	0	0	0	0	0	PAOVF	PAIF
		Write:								
0x0062	PACNT (hi)	Read:	Bit 15	14	13	12	11	10	9	Bit 8
		Write:								
0x0063	PACNT (lo)	Read:	Bit 7	6	5	4	3	2	1	Bit 0
		Write:								
0x0064	Reserved	Read:	0	0	0	0	0	0	0	0
		Write:								
0x0065	Reserved	Read:	0	0	0	0	0	0	0	0
		Write:								
0x0066	Reserved	Read:	0	0	0	0	0	0	0	0
		Write:								
0x0067	Reserved	Read:	0	0	0	0	0	0	0	0
		Write:								
0x0068	Reserved	Read:	0	0	0	0	0	0	0	0
		Write:								
0x0069	Reserved	Read:	0	0	0	0	0	0	0	0
		Write:								
0x006A	Reserved	Read:	0	0	0	0	0	0	0	0
		Write:								
0x006B	Reserved	Read:	0	0	0	0	0	0	0	0
		Write:								
0x006C	Reserved	Read:	0	0	0	0	0	0	0	0
		Write:								
0x006D	Reserved	Read:	0	0	0	0	0	0	0	0
		Write:								
0x006E	Reserved	Read:	0	0	0	0	0	0	0	0
		Write:								
0x006F	Reserved	Read:	0	0	0	0	0	0	0	0
		Write:								

0x0070–0x007F Reserved

Address	Name		Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0
0x0070–0x007F	Reserved	Read:	0	0	0	0	0	0	0	0
		Write:								

Address	Name		Bit 7	6	5	4	3	2	1	Bit 0
0x0006	Reserved	R	0	0	0	0	0	0	0	0
		W								
0x0007	MODRR	R	0	0	0	MODRR4	MODRR3	MODRR2	MODRR1	MODRR0
		W								
0x0008	PTS	R	0	0	0	0	PTS3	PTS2	PTS1	PTS0
		W								
		SCI	—	—	—	—	—	—	TXD	RXD
0x0009	PTIS	R	0	0	0	0	PTIS3	PTIS2	PTIS1	PTIS0
		W								
0x000A	DDRS	R	0	0	0	0	DDRS3	DDRS2	DDRS1	DDRS0
		W								
0x000B	RDRS	R	0	0	0	0	RDRS3	RDRS2	RDRS1	RDRS0
		W								
0x000C	PERS	R	0	0	0	0	PERS3	PERS2	PERS1	PERS0
		W								
0x000D	PPSS	R	0	0	0	0	PPSS3	PPSS2	PPSS1	PPSS0
		W								
0x000E	WOMS	R	0	0	0	0	WOMS3	WOMS2	WOMS1	WOMS0
		W								
0x000F	Reserved	R	0	0	0	0	0	0	0	0
		W								
0x0010	PTM	R	0	0	PTM5	PTM4	PTM3	PTM2	PTM1	PTM0
		W								
		MSCAN / SPI	—	—	SCK	MOSI	$\overline{SS}$	MISO	TXCAN	RXCAN
0x0011	PTIM	R	0	0	PTIM5	PTIM4	PTIM3	PTIM2	PTIM1	PTIM0
		W								
0x0012	DDRM	R	0	0	DDRM5	DDRM4	DDRM3	DDRM2	DDRM1	DDRM0
		W								
0x0013	RDRM	R	0	0	RDRM5	RDRM4	RDRM3	RDRM2	RDRM1	RDRM0
		W								
0x0014	PERM	R	0	0	PERM5	PERM4	PERM3	PERM2	PERM1	PERM0
		W								
0x0015	PPSM	R	0	0	PPSM5	PPSM4	PPSM3	PPSM2	PPSM1	PPSM0
		W								
0x0016	WOMM	R	0	0	WOMM5	WOMM4	WOMM3	WOMM2	WOMM1	WOMM0
		W								
0x0017	Reserved	R	0	0	0	0	0	0	0	0
		W								
0x0018	PTP	R	PTP7	PTP6	PTP5	PTP4	PTP3	PTP2	PTP1	PTP0
		W								
		PWM	—	—	PWM5	PWM4	PWM3	PWM2	PWM1	PWM0
0x0019	PTIP	R	PTIP7	PTIP6	PTIP5	PTIP4	PTIP3	PTIP2	PTIP1	PTIP0
		W								

= Unimplemented or Reserved

Figure 2-2. Quick Reference to PIM Registers (Sheet 2 of 3)

2.3.2.6.3 Port AD Data Direction Register (DDRAD)

Module Base + 0x0032

	7	6	5	4	3	2	1	0
R W	DDRAD7	DDRAD6	DDRAD5	DDRAD4	DDRAD3	DDRAD2	DDRAD1	DDRAD0
Reset	0	0	0	0	0	0	0	0

Figure 2-42. Port AD Data Direction Register (DDRAD)

Read: Anytime.

Write: Anytime.

Table 2-34. DDRAD Field Descriptions

Field	Description
7–0 DDRAD[7:0]	**Data Direction Port AD** — This register configures port pins AD[7:0] as either input or output. 0 Associated pin is configured as input. 1 Associated pin is configured as output. **Note:** Due to internal synchronization circuits, it can take up to 2 bus cycles until the correct value is read on PTAD or PTIAD registers, when changing the DDRAD register.

2.3.2.6.4 Port AD Reduced Drive Register (RDRAD)

Module Base + 0x0033

	7	6	5	4	3	2	1	0
R W	RDRAD7	RDRAD6	RDRAD5	RDRAD4	RDRAD3	RDRAD2	RDRAD1	RDRAD0
Reset	0	0	0	0	0	0	0	0

Figure 2-43. Port AD Reduced Drive Register (RDRAD)

Read: Anytime.

Write: Anytime.

Table 2-35. RDRAD Field Descriptions

Field	Description
7–0 RDRAD[7:0]	**Reduced Drive Port AD** — This register configures the drive strength of each port AD output pin as either full or reduced. If the port is used as input this bit is ignored. 0 Full drive strength at output. 1 Associated pin drives at about 1/3 of the full drive strength.

3.3.2.9 Program Page Index Register (PPAGE)

Module Base + 0x0030
Starting address location affected by INITRG register setting.

	7	6	5	4	3	2	1	0
R	0	0	PIX5	PIX4	PIX3	PIX2	PIX1	PIX0
W								
Reset[1]	—	—	—	—	—	—	—	—

1. The reset state of this register is controlled at chip integration. Please refer to the device overview section to determine the actual reset state of this register.

= Unimplemented or Reserved

Figure 3-11. Program Page Index Register (PPAGE)

Read: Anytime

Write: Determined at chip integration. Generally it's: "write anytime in all modes;" on some devices it will be: "write only in special modes." Check specific device documentation to determine which applies.

Reset: Defined at chip integration as either 0x00 (paired with write in any mode) or 0x3C (paired with write only in special modes), see device overview chapter.

The HCS12 core architecture limits the physical address space available to 64K bytes. The program page index register allows for integrating up to 1M byte of FLASH or ROM into the system by using the six page index bits to page 16K byte blocks into the program page window located from 0x8000 to 0xBFFF as defined in Table 3-14. CALL and RTC instructions have special access to read and write this register without using the address bus.

NOTE

Normal writes to this register take one cycle to go into effect. Writes to this register using the special access of the CALL and RTC instructions will be complete before the end of the associated instruction.

Table 3-13. MEMSIZ0 Field Descriptions

Field	Description
5:0 PIX[5:0]	**Program Page Index Bits 5:0** — These page index bits are used to select which of the 64 FLASH or ROM array pages is to be accessed in the program page window as shown in Table 3-14.

7.3.2.9 Debug Comparator A Extended Register (DBGCAX)

Module Base + 0x002A
Starting address location affected by INITRG register setting.

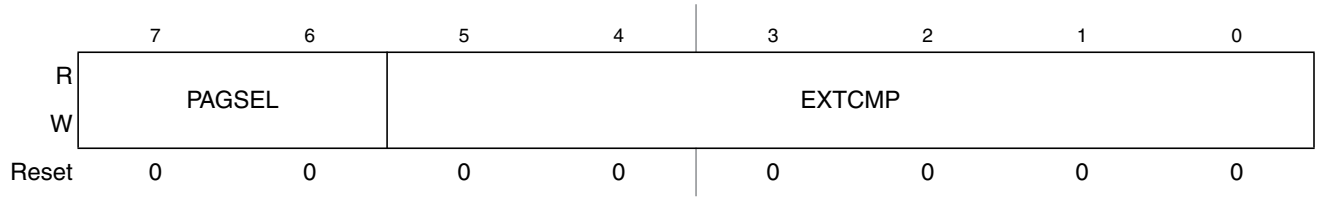

Figure 7-15. Debug Comparator A Extended Register (DBGCAX)

Table 7-19. DBGCAX Field Descriptions

Field	Description
7:6 PAGSEL	**Page Selector Field** — If DBGEN is set in DBGC1, then PAGSEL selects the type of paging as shown in Table 7-20. DPAGE and EPAGE are not yet implemented so the value in bit 7 will be ignored (i.e., PAGSEL values of 10 and 11 will be interpreted as values of 00 and 01, respectively). In BKP mode, PAGSEL has no meaning and EXTCMP[5:0] are compared to address bits [19:14] if the address is in the FLASH/ROM memory space.
5:0 EXTCMP	**Comparator A Extended Compare Bits** — The EXTCMP bits are used as comparison address bits as shown in Table 7-20 along with the appropriate PPAGE, DPAGE, or EPAGE signal from the core.

Table 7-20. Comparator A or B Compares

Mode		EXTCMP Compare	High-Byte Compare
BKP[1]	Not FLASH/ROM access	No compare	DBGCxH[7:0] = AB[15:8]
	FLASH/ROM access	EXTCMP[5:0] = XAB[19:14]	DBGCxH[5:0] = AB[13:8]
DBG[2]	PAGSEL = 00	No compare	DBGCxH[7:0] = AB[15:8]
	PAGSEL = 01	EXTCMP[5:0] = XAB[21:16]	DBGCxH[7:0] = XAB[15:14], AB[13:8]

1. See Figure 7-16.
2. See Figure 7-10 (note that while this figure provides extended comparisons for comparator C, the figure also pertains to comparators A and B in DBG mode only).

7.4.2.3 Begin- and End-Trigger

The definitions of begin- and end-trigger as used in the DBG module are as follows:

- Begin-trigger: Storage in trace buffer occurs after the trigger and continues until 64 locations are filled.
- End-trigger: Storage in trace buffer occurs until the trigger, with the least recent data falling out of the trace buffer if more than 64 words are collected.

7.4.2.4 Arming the DBG Module

In DBG mode, arming occurs by setting DBGEN and ARM in DBGC1. The ARM bit in DBGC1 is cleared when the trigger condition is met in end-trigger mode or when the Trace Buffer is filled in begin-trigger mode. The TBC logic determines whether a trigger condition has been met based on the trigger mode and the trigger selection.

7.4.2.5 Trigger Modes

The DBG module supports nine trigger modes. The trigger modes are encoded as shown in Table 7-6. The trigger mode is used as a qualifier for either starting or ending the storing of data in the trace buffer. When the match condition is met, the appropriate flag A or B is set in DBGSC. Arming the DBG module clears the A, B, and C flags in DBGSC. In all trigger modes except for the event-only modes and DETAIL capture mode, change-of-flow addresses are stored in the trace buffer. In the event-only modes only the value on the data bus at the trigger event B will be stored. In DETAIL capture mode address and data for all cycles except program fetch (P) and free (f) cycles are stored in trace buffer.

7.4.2.5.1 A Only

In the A only trigger mode, if the match condition for A is met, the A flag in DBGSC is set and a trigger occurs.

7.4.2.5.2 A or B

In the A or B trigger mode, if the match condition for A or B is met, the corresponding flag in DBGSC is set and a trigger occurs.

7.4.2.5.3 A then B

In the A then B trigger mode, the match condition for A must be met before the match condition for B is compared. When the match condition for A or B is met, the corresponding flag in DBGSC is set. The trigger occurs only after A then B have matched.

NOTE

When tagging and using A then B, if addresses A and B are close together, then B may not complete the trigger sequence. This occurs when A and B are in the instruction queue at the same time. Basically the A trigger has not yet occurred, so the B instruction is not tagged. Generally, if address B is at

Chapter 9
Clocks and Reset Generator (CRGV4) Block Description

9.1 Introduction

This specification describes the function of the clocks and reset generator (CRGV4).

9.1.1 Features

The main features of this block are:

- Phase-locked loop (PLL) frequency multiplier
  - Reference divider
  - Automatic bandwidth control mode for low-jitter operation
  - Automatic frequency lock detector
  - CPU interrupt on entry or exit from locked condition
  - Self-clock mode in absence of reference clock
- System clock generator
  - Clock quality check
  - Clock switch for either oscillator- or PLL-based system clocks
  - User selectable disabling of clocks during wait mode for reduced power consumption
- Computer operating properly (COP) watchdog timer with time-out clear window
- System reset generation from the following possible sources:
  - Power-on reset
  - Low voltage reset
    Refer to the device overview section for availability of this feature.
  - COP reset
  - Loss of clock reset
  - External pin reset
- Real-time interrupt (RTI)

Table 9-5. PLLCTL Field Descriptions (continued)

Field	Description
5 AUTO	**Automatic Bandwidth Control Bit** — AUTO selects either the high bandwidth (acquisition) mode or the low bandwidth (tracking) mode depending on how close to the desired frequency the VCO is running. Write anytime except when PLLWAI=1, because PLLWAI sets the AUTO bit to 1. 0 Automatic mode control is disabled and the PLL is under software control, using ACQ bit. 1 Automatic mode control is enabled and ACQ bit has no effect.
4 ACQ	**Acquisition Bit** — Write anytime. If AUTO=1 this bit has no effect. 0 Low bandwidth filter is selected. 1 High bandwidth filter is selected.
2 PRE	**RTI Enable during Pseudo-Stop Bit** — PRE enables the RTI during pseudo-stop mode. Write anytime. 0 RTI stops running during pseudo-stop mode. 1 RTI continues running during pseudo-stop mode. **Note:** If the PRE bit is cleared the RTI dividers will go static while pseudo-stop mode is active. The RTI dividers will not initialize like in wait mode with RTIWAI bit set.
1 PCE	**COP Enable during Pseudo-Stop Bit** — PCE enables the COP during pseudo-stop mode. Write anytime. 0 COP stops running during pseudo-stop mode 1 COP continues running during pseudo-stop mode **Note:** If the PCE bit is cleared the COP dividers will go static while pseudo-stop mode is active. The COP dividers will *not* initialize like in wait mode with COPWAI bit set.
0 SCME	**Self-Clock Mode Enable Bit** — Normal modes: Write once —Special modes: Write anytime — SCME can not be cleared while operating in self-clock mode (SCM=1). 0 Detection of crystal clock failure causes clock monitor reset (see Section 9.5.1, “Clock Monitor Reset”). 1 Detection of crystal clock failure forces the MCU in self-clock mode (see Section 9.4.7.2, “Self-Clock Mode”).

9.3.2.8 CRG RTI Control Register (RTICTL)

This register selects the timeout period for the real-time interrupt.

Module Base + 0x0007

	7	6	5	4	3	2	1	0
R	0	RTR6	RTR5	RTR4	RTR3	RTR2	RTR1	RTR0
W								
Reset	0	0	0	0	0	0	0	0

= Unimplemented or Reserved

Figure 9-11. CRG RTI Control Register (RTICTL)

Read: anytime

Write: anytime

NOTE

A write to this register initializes the RTI counter.

Table 9-6. RTICTL Field Descriptions

Field	Description
6:4 RTR[6:4]	**Real-Time Interrupt Prescale Rate Select Bits** — These bits select the prescale rate for the RTI. See Table 9-7.
3:0 RTR[3:0]	**Real-Time Interrupt Modulus Counter Select Bits** — These bits select the modulus counter target value to provide additional granularity. Table 9-7 shows all possible divide values selectable by the RTICTL register. The source clock for the RTI is OSCCLK.

Table 9-7. RTI Frequency Divide Rates

RTR[3:0]	RTR[6:4] =							
	000 (OFF)	**001 (2^{10})**	**010 (2^{11})**	**011 (2^{12})**	**100 (2^{13})**	**101 (2^{14})**	**110 (2^{15})**	**111 (2^{16})**
0000 (÷1)	OFF*	2^{10}	2^{11}	2^{12}	2^{13}	2^{14}	2^{15}	2^{16}
0001 (÷2)	OFF*	$2x2^{10}$	$2x2^{11}$	$2x2^{12}$	$2x2^{13}$	$2x2^{14}$	$2x2^{15}$	$2x2^{16}$
0010 (÷3)	OFF*	$3x2^{10}$	$3x2^{11}$	$3x2^{12}$	$3x2^{13}$	$3x2^{14}$	$3x2^{15}$	$3x2^{16}$
0011 (÷4)	OFF*	$4x2^{10}$	$4x2^{11}$	$4x2^{12}$	$4x2^{13}$	$4x2^{14}$	$4x2^{15}$	$4x2^{16}$
0100 (÷5)	OFF*	$5x2^{10}$	$5x2^{11}$	$5x2^{12}$	$5x2^{13}$	$5x2^{14}$	$5x2^{15}$	$5x2^{16}$
0101 (÷6)	OFF*	$6x2^{10}$	$6x2^{11}$	$6x2^{12}$	$6x2^{13}$	$6x2^{14}$	$6x2^{15}$	$6x2^{16}$
0110 (÷7)	OFF*	$7x2^{10}$	$7x2^{11}$	$7x2^{12}$	$7x2^{13}$	$7x2^{14}$	$7x2^{15}$	$7x2^{16}$
0111 (÷8)	OFF*	$8x2^{10}$	$8x2^{11}$	$8x2^{12}$	$8x2^{13}$	$8x2^{14}$	$8x2^{15}$	$8x2^{16}$
1000 (÷9)	OFF*	$9x2^{10}$	$9x2^{11}$	$9x2^{12}$	$9x2^{13}$	$9x2^{14}$	$9x2^{15}$	$9x2^{16}$
1001 (÷10)	OFF*	$10x2^{10}$	$10x2^{11}$	$10x2^{12}$	$10x2^{13}$	$10x2^{14}$	$10x2^{15}$	$10x2^{16}$
1010 (÷11)	OFF*	$11x2^{10}$	$11x2^{11}$	$11x2^{12}$	$11x2^{13}$	$11x2^{14}$	$11x2^{15}$	$11x2^{16}$
1011 (÷12)	OFF*	$12x2^{10}$	$12x2^{11}$	$12x2^{12}$	$12x2^{13}$	$12x2^{14}$	$12x2^{15}$	$12x2^{16}$
1100 (÷ 13)	OFF*	$13x2^{10}$	$13x2^{11}$	$13x2^{12}$	$13x2^{13}$	$13x2^{14}$	$13x2^{15}$	$13x2^{16}$
1101 (÷14)	OFF*	$14x2^{10}$	$14x2^{11}$	$14x2^{12}$	$14x2^{13}$	$14x2^{14}$	$14x2^{15}$	$14x2^{16}$
1110 (÷15)	OFF*	$15x2^{10}$	$15x2^{11}$	$15x2^{12}$	$15x2^{13}$	$15x2^{14}$	$15x2^{15}$	$15x2^{16}$
1111 (÷ 16)	OFF*	$16x2^{10}$	$16x2^{11}$	$16x2^{12}$	$16x2^{13}$	$16x2^{14}$	$16x2^{15}$	$16x2^{16}$

* Denotes the default value out of reset.This value should be used to disable the RTI to ensure future backwards compatibility.

There are five different scenarios for the CRG to restart the MCU from wait mode:

- External reset
- Clock monitor reset
- COP reset
- Self-clock mode interrupt
- Real-time interrupt (RTI)

If the MCU gets an external reset during wait mode active, the CRG asynchronously restores all configuration bits in the register space to its default settings and starts the reset generator. After completing the reset sequence processing begins by fetching the normal reset vector. Wait mode is exited and the MCU is in run mode again.

If the clock monitor is enabled (CME=1) the MCU is able to leave wait mode when loss of oscillator/external clock is detected by a clock monitor fail. If the SCME bit is not asserted the CRG generates a clock monitor fail reset (CMRESET). The CRG's behavior for CMRESET is the same compared to external reset, but another reset vector is fetched after completion of the reset sequence. If the SCME bit is asserted the CRG generates a SCM interrupt if enabled (SCMIE=1). After generating the interrupt the CRG enters self-clock mode and starts the clock quality checker (see Section 9.4.4, "Clock Quality Checker"). Then the MCU continues with normal operation.If the SCM interrupt is blocked by SCMIE = 0, the SCMIF flag will be asserted and clock quality checks will be performed but the MCU will not wake-up from wait mode.

If any other interrupt source (e.g. RTI) triggers exit from wait mode the MCU immediately continues with normal operation. If the PLL has been powered-down during wait mode the PLLSEL bit is cleared and the MCU runs on OSCCLK after leaving wait mode. The software must manually set the PLLSEL bit again, in order to switch system and core clocks to the PLLCLK.

If wait mode is entered from self-clock mode, the CRG will continue to check the clock quality until clock check is successful. The PLL and voltage regulator (VREG) will remain enabled.

Table 9-11 summarizes the outcome of a clock loss while in wait mode.

Table 10-2. CANCTL1 Register Field Descriptions (continued)

Field	Description
1 SLPAK	**Sleep Mode Acknowledge** — This flag indicates whether the MSCAN module has entered sleep mode (see Section 10.4.5.4, "MSCAN Sleep Mode"). It is used as a handshake flag for the SLPRQ sleep mode request. Sleep mode is active when SLPRQ = 1 and SLPAK = 1. Depending on the setting of WUPE, the MSCAN will clear the flag if it detects activity on the CAN bus while in sleep mode. 0 Running — The MSCAN operates normally 1 Sleep mode active — The MSCAN has entered sleep mode
0 INITAK	**Initialization Mode Acknowledge** — This flag indicates whether the MSCAN module is in initialization mode (see Section 10.4.5.5, "MSCAN Initialization Mode"). It is used as a handshake flag for the INITRQ initialization mode request. Initialization mode is active when INITRQ = 1 and INITAK = 1. The registers CANCTL1, CANBTR0, CANBTR1, CANIDAC, CANIDAR0–CANIDAR7, and CANIDMR0–CANIDMR7 can be written only by the CPU when the MSCAN is in initialization mode. 0 Running — The MSCAN operates normally 1 Initialization mode active — The MSCAN has entered initialization mode

10.3.2.12 MSCAN Identifier Acceptance Control Register (CANIDAC)

The CANIDAC register is used for identifier acceptance control as described below.

Module Base + 0x000B

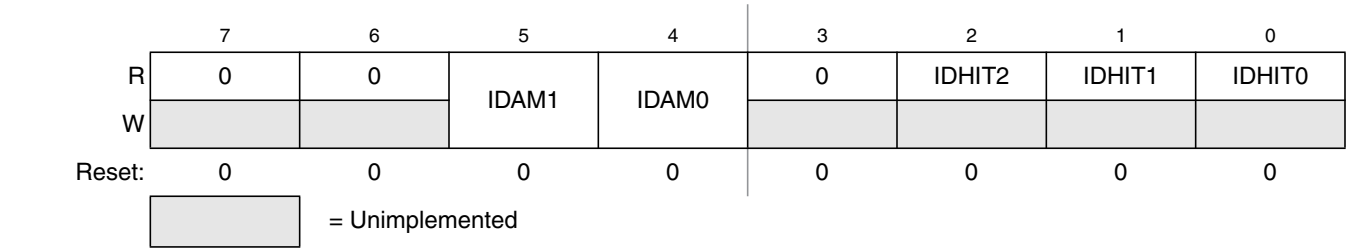

Figure 10-15. MSCAN Identifier Acceptance Control Register (CANIDAC)

Read: Anytime
Write: Anytime in initialization mode (INITRQ = 1 and INITAK = 1), except bits IDHITx, which are read-only

Table 10-16. CANIDAC Register Field Descriptions

Field	Description
5:4 IDAM[1:0]	**Identifier Acceptance Mode** — The CPU sets these flags to define the identifier acceptance filter organization (see Section 10.4.3, "Identifier Acceptance Filter"). Table 10-17 summarizes the different settings. In filter closed mode, no message is accepted such that the foreground buffer is never reloaded.
2:0 IDHIT[2:0]	Identifier Acceptance Hit Indicator — The MSCAN sets these flags to indicate an identifier acceptance hit (see Section 10.4.3, "Identifier Acceptance Filter"). Table 10-18 summarizes the different settings.

Table 10-17. Identifier Acceptance Mode Settings

IDAM1	IDAM0	Identifier Acceptance Mode
0	0	Two 32-bit acceptance filters
0	1	Four 16-bit acceptance filters
1	0	Eight 8-bit acceptance filters
1	1	Filter closed

Table 10-18. Identifier Acceptance Hit Indication

IDHIT2	IDHIT1	IDHIT0	Identifier Acceptance Hit
0	0	0	Filter 0 hit
0	0	1	Filter 1 hit
0	1	0	Filter 2 hit
0	1	1	Filter 3 hit
1	0	0	Filter 4 hit
1	0	1	Filter 5 hit
1	1	0	Filter 6 hit
1	1	1	Filter 7 hit

10.3.2.17 MSCAN Identifier Mask Registers (CANIDMR0–CANIDMR7)

The identifier mask register specifies which of the corresponding bits in the identifier acceptance register are relevant for acceptance filtering. To receive standard identifiers in 32 bit filter mode, it is required to program the last three bits (AM[2:0]) in the mask registers CANIDMR1 and CANIDMR5 to "don't care." To receive standard identifiers in 16 bit filter mode, it is required to program the last three bits (AM[2:0]) in the mask registers CANIDMR1, CANIDMR3, CANIDMR5, and CANIDMR7 to "don't care."

Module Base + 0x0014 (CANIDMR0)
0x0015 (CANIDMR1)
0x0016 (CANIDMR2)
0x0017 (CANIDMR3)

	7	6	5	4	3	2	1	0
R W	AM7	AM6	AM5	AM4	AM3	AM2	AM1	AM0
Reset	0	0	0	0	0	0	0	0

	7	6	5	4	3	2	1	0
R W	AM7	AM6	AM5	AM4	AM3	AM2	AM1	AM0
Reset	0	0	0	0	0	0	0	0

	7	6	5	4	3	2	1	0
R W	AM7	AM6	AM5	AM4	AM3	AM2	AM1	AM0
Reset	0	0	0	0	0	0	0	0

	7	6	5	4	3	2	1	0
R W	AM7	AM6	AM5	AM4	AM3	AM2	AM1	AM0
Reset	0	0	0	0	0	0	0	0

Figure 10-21. MSCAN Identifier Mask Registers (First Bank) — CANIDMR0–CANIDMR3

Read: Anytime
Write: Anytime in initialization mode (INITRQ = 1 and INITAK = 1)

Table 10-21. CANIDMR0–CANIDMR3 Register Field Descriptions

Field	Description
7:0 AM[7:0]	**Acceptance Mask Bits** — If a particular bit in this register is cleared, this indicates that the corresponding bit in the identifier acceptance register must be the same as its identifier bit before a match is detected. The message is accepted if all such bits match. If a bit is set, it indicates that the state of the corresponding bit in the identifier acceptance register does not affect whether or not the message is accepted. 0 Match corresponding acceptance code register and identifier bits 1 Ignore corresponding acceptance code register bit

In Figure 13-16, a large burst of noise is perceived as the beginning of a start bit, although the test sample at RT5 is high. The RT5 sample sets the noise flag. Although this is a worst-case misalignment of perceived bit time, the data samples RT8, RT9, and RT10 are within the bit time and data recovery is successful.

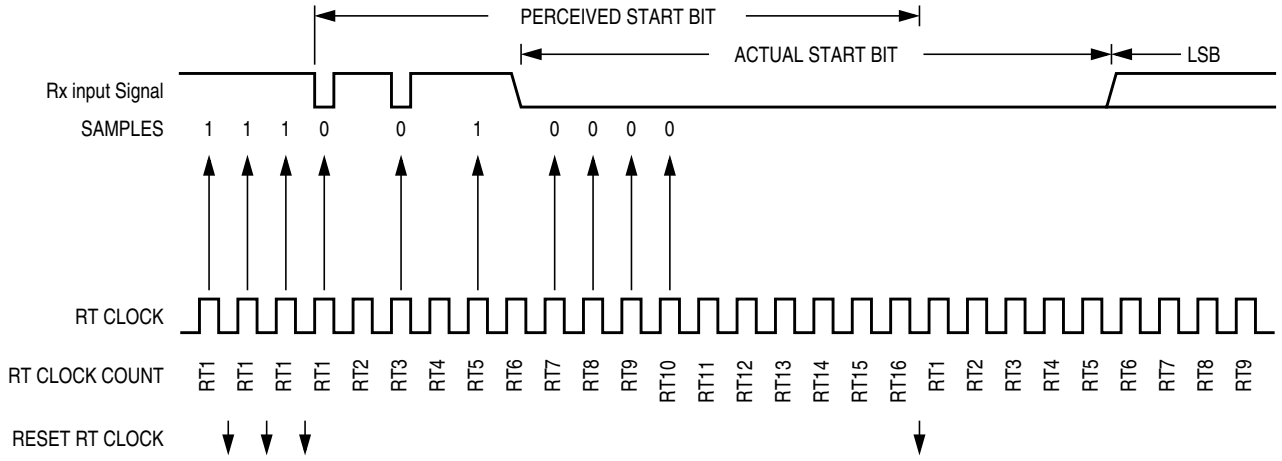

Figure 13-16. Start Bit Search Example 3

Figure 13-17 shows the effect of noise early in the start bit time. Although this noise does not affect proper synchronization with the start bit time, it does set the noise flag.

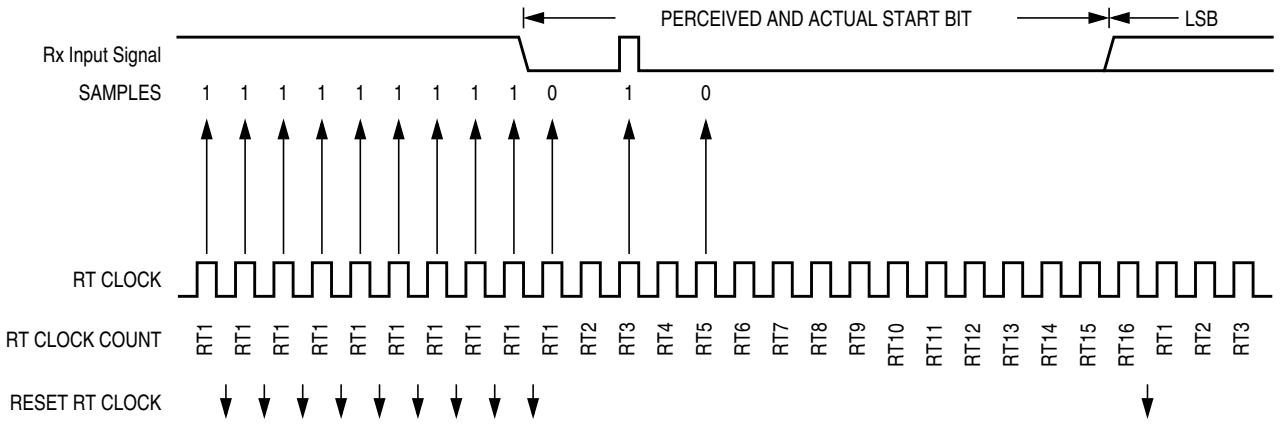

Figure 13-17. Start Bit Search Example 4

address 0x8000 to 0xBFFF to any physical 16K byte page in the Flash array memory.[1] The FPROT register (see Section 19.3.2.5) can be set to globally protect the entire Flash array. Three separate areas, one starting from the Flash array starting address (called lower) towards higher addresses, one growing downward from the Flash array end address (called higher), and the remaining addresses, can be activated for protection. The Flash array addresses covered by these protectable regions are shown in Figure 19-3Figure 19-4. The higher address area is mainly targeted to hold the boot loader code since it covers the vector space. The lower address area can be used for EEPROM emulation in an MCU without an EEPROM module since it can be left unprotected while the remaining addresses are protected from program or erase. Default protection settings as well as security information that allows the MCU to restrict access to the Flash module are stored in the Flash configuration field described in Table 19-1.

Table 19-1. Flash Configuration Field

Flash Address	Size (bytes)	Description
0xFF00–0xFF07	8	Backdoor Key to unlock security
0xFF08–0xFF0C	5	Reserved
0xFF0D	1	Flash Protection byte Refer to Section 19.3.2.5, “Flash Protection Register (FPROT)”
0xFF0E	1	Reserved
0xFF0F	1	Flash Security/Options byte Refer to Section 19.3.2.2, “Flash Security Register (FSEC)”

1. By placing 0x3E/0x3F in the HCS12 Core PPAGE register, the bottom/top fixed 16 Kbyte pages can be seen twice in the MCU memory map.

Table 20-15. FCMD Field Descriptions

Field	Description
6, 5, 2, 0 CMDB[6:5] CMDB[2] CMDB[0]	Valid Flash commands are shown in Table 20-16. An attempt to execute any command other than those listed in Table 20-16 will set the ACCERR bit in the FSTAT register (see Section 20.3.2.6).

Table 20-16. Valid Flash Command List

CMDB	NVM Command
0x05	Erase verify
0x20	Word program
0x40	Sector erase
0x41	Mass erase

20.3.2.8 RESERVED2

This register is reserved for factory testing and is not accessible to the user.

Module Base + 0x0007

	7	6	5	4	3	2	1	0
R	0	0	0	0	0	0	0	0
W								
Reset	0	0	0	0	0	0	0	0

= Unimplemented or Reserved

Figure 20-14. RESERVED2

All bits read 0 and are not writable.

20.3.2.9 Flash Address Register (FADDR)

FADDRHI and FADDRLO are the Flash address registers.

Module Base + 0x0008

	7	6	5	4	3	2	1	0
R	FABHI							
W								
Reset	0	0	0	0	0	0	0	0

Figure 20-15. Flash Address High Register (FADDRHI)

20.4.1.3 Valid Flash Commands

Table 20-17 summarizes the valid Flash commands along with the effects of the commands on the Flash array.

Table 20-17. Valid Flash Commands

FCMD	Meaning	Function on Flash Array
0x05	Erase Verify	Verify all bytes in the Flash array are erased. If the Flash array is erased, the BLANK bit will set in the FSTAT register upon command completion.
0x20	Program	Program a word (2 bytes) in the Flash array.
0x40	Sector Erase	Erase all 1024 bytes in a sector of the Flash array.
0x41	Mass Erase	Erase all bytes in the Flash array. A mass erase of the full Flash array is only possible when FPLDIS, FPHDIS, and FPOPEN bits in the FPROT register are set prior to launching the command.

CAUTION

A Flash word must be in the erased state before being programmed. Cumulative programming of bits within a Flash word is not allowed.

Table 21-9. Flash Protection Function

FPOPEN	FPHDIS	FPHS[1]	FPHS[0]	FPLDIS	FPLS[1]	FPLS[0]	Function[1]
1	1	x	x	1	x	x	No protection
1	1	x	x	0	x	x	Protect low range
1	0	x	x	1	x	x	Protect high range
1	0	x	x	0	x	x	Protect high and low ranges
0	1	x	x	1	x	x	Full Flash array protected
0	0	x	x	1	x	x	Unprotected high range
0	1	x	x	0	x	x	Unprotected low range
0	0	x	x	0	x	x	Unprotected high and low ranges

1. For range sizes refer to Table 21-10 and Table 21-11 or .

Table 21-10. Flash Protection Higher Address Range

FPHS[1:0]	Address Range	Range Size
00	0xF800–0xFFFF	2 Kbytes
01	0xF000–0xFFFF	4 Kbytes
10	0xE000–0xFFFF	8 Kbytes
11	0xC000–0xFFFF	16 Kbytes

Table 21-11. Flash Protection Lower Address Range

FPLS[1:0]	Address Range	Range Size
00	0x4000–0x43FF	1 Kbyte
01	0x4000–0x47FF	2 Kbytes
10	0x4000–0x4FFF	4 Kbytes
11	0x4000–0x5FFF	8 Kbytes

Figure 21-9 illustrates all possible protection scenarios. Although the protection scheme is loaded from the Flash array after reset, it is allowed to change in normal modes. This protection scheme can be used by applications requiring re-programming in single chip mode while providing as much protection as possible if no re-programming is required.

injection current may flow out of V_{DD5} and could result in external power supply going out of regulation. Insure external V_{DD5} load will shunt current greater than maximum injection current. This will be the greatest risk when the MCU is not consuming power; e.g. if no system clock is present, or if clock rate is very low which would reduce overall power consumption.

A.1.5 Absolute Maximum Ratings

Absolute maximum ratings are stress ratings only. A functional operation under or outside those maxima is not guaranteed. Stress beyond those limits may affect the reliability or cause permanent damage of the device.

This device contains circuitry protecting against damage due to high static voltage or electrical fields; however, it is advised that normal precautions be taken to avoid application of any voltages higher than maximum-rated voltages to this high-impedance circuit. Reliability of operation is enhanced if unused inputs are tied to an appropriate logic voltage level (e.g., either V_{SS5} or V_{DD5}).

Table A-1. Absolute Maximum Ratings

Num	Rating	Symbol	Min	Max	Unit
1	I/O, Regulator and Analog Supply Voltage	V_{DD5}	–0.3	6.5	V
2	Digital Logic Supply Voltage(1)	V_{DD}	–0.3	3.0	V
3	PLL Supply Voltage [1]	V_{DDPLL}	–0.3	3.0	V
4	Voltage difference V_{DDX} to V_{DDR} and V_{DDA}	Δ_{VDDX}	–0.3	0.3	V
5	Voltage difference V_{SSX} to V_{SSR} and V_{SSA}	Δ_{VSSX}	–0.3	0.3	V
6	Digital I/O Input Voltage	V_{IN}	–0.3	6.5	V
7	Analog Reference	V_{RH}, V_{RL}	–0.3	6.5	V
8	XFC, EXTAL, XTAL inputs	V_{ILV}	–0.3	3.0	V
9	TEST input	V_{TEST}	–0.3	10.0	V
10	Instantaneous Maximum Current Single pin limit for all digital I/O pins (2)	I_D	–25	+25	mA
11	Instantaneous Maximum Current Single pin limit for XFC, EXTAL, XTAL(3)	I_{DL}	–25	+25	mA
12	Instantaneous Maximum Current Single pin limit for TEST(4)	I_{DT}	–0.25	0	mA
13	Operating Temperature Range (packaged)	T_A	– 40	125	°C
14	Operating Temperature Range (junction)	T_J	– 40	140	°C
15	Storage Temperature Range	T_{stg}	– 65	155	°C

1. The device contains an internal voltage regulator to generate the logic and PLL supply out of the I/O supply. The absolute maximum ratings apply when the device is powered from an external source.
2. All digital I/O pins are internally clamped to V_{SSX} and V_{DDX}, V_{SSR} and V_{DDR} or V_{SSA} and V_{DDA}.
3. These pins are internally clamped to V_{SSPLL} and V_{DDPLL}
4. This pin is clamped low to V_{SSX}, but not clamped high. This pin must be tied low in applications.

Table A-18. NVM Timing Characteristics

Conditions are shown in Table A-4 unless otherwise noted							
Num	**C**	**Rating**	**Symbol**	**Min**	**Typ**	**Max**	**Unit**
1	D	External Oscillator Clock	f_{NVMOSC}	0.5	—	50(1)	MHz
2	D	Bus frequency for Programming or Erase Operations	f_{NVMBUS}	1	—		MHz
3	D	Operating Frequency	f_{NVMOP}	150	—	200	kHz
4	P	Single Word Programming Time	t_{swpgm}	46(2)	—	74.5(3)	µs
5	D	Flash Burst Programming consecutive word	t_{bwpgm}	20.4[2]	—	31[3]	µs
6	D	Flash Burst Programming Time for 32 Word row	t_{brpgm}	678.4[2]	—	1035.5[3]	µs
6	D	Flash Burst Programming Time for 64 Word row	t_{brpgm}	1331.2[2]	—	2027.5[3]	µs
7	P	Sector Erase Time	t_{era}	20(4)	—	26.7[3]	ms
8	P	Mass Erase Time	t_{mass}	100[4]	—	133[3]	ms
9	D	Blank Check Time Flash per block	t_{check}	11(5)	—	32778(6)	(7)t_{cyc}
9	D	Blank Check Time Flash per block	t_{check}	11(8)	—	65546(9)	[7]t_{cyc}

1. Restrictions for oscillator in crystal mode apply!
2. Minimum Programming times are achieved under maximum NVM operating frequency f_{NVMOP} and maximum bus frequency f_{bus}.
3. Maximum Erase and Programming times are achieved under particular combinations of f_{NVMOP} and bus frequency f bus. Refer to formulae in Sections A.3.1.1 - A.3.1.4 for guidance.
4. Minimum Erase times are achieved under maximum NVM operating frequency f_{NVMOP}
5. Minimum time, if first word in the array is not blank (512 byte sector size).
6. Maximum time to complete check on an erased block (512 byte sector size)
7. Where t_{cyc} is the system bus clock period.
8. Minimum time, if first word in the array is not blank (1024 byte sector size)
9. Maximum time to complete check on an erased block (1024 byte sector size).