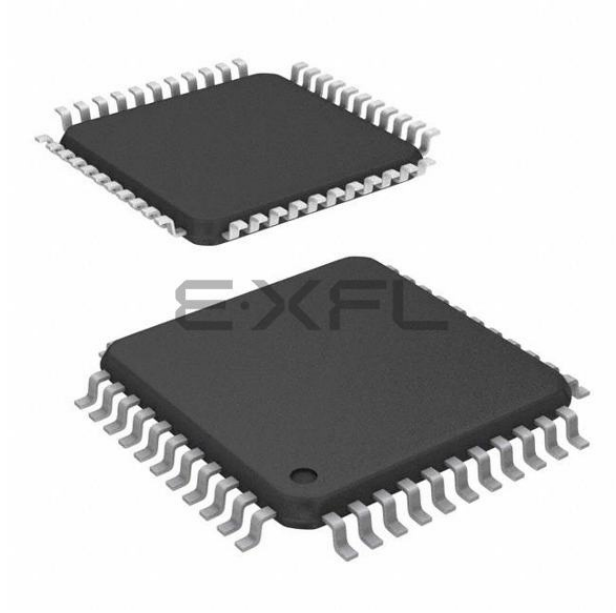


Welcome to E-XFL.COM

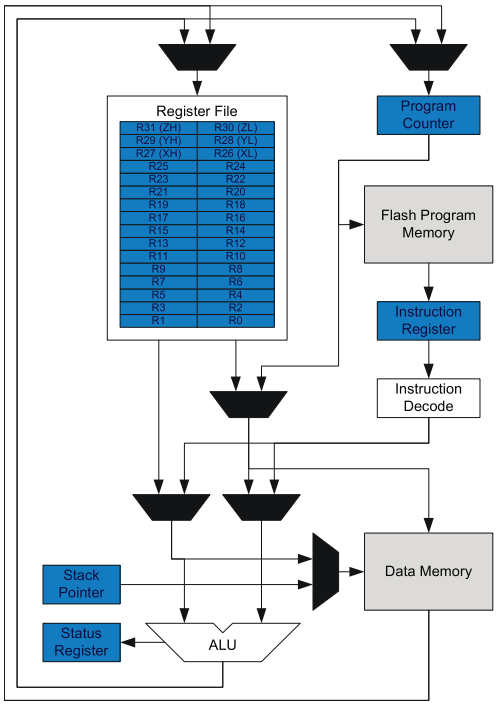
What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	AVR
Core Size	8/16-Bit
Speed	32MHz
Connectivity	I²C, IrDA, SPI, UART/USART, USB
Peripherals	Brown-out Detect/Reset, DMA, POR, PWM, WDT
Number of I/O	34
Program Memory Size	32KB (16K x 16)
Program Memory Type	FLASH
EEPROM Size	1K x 8
RAM Size	4K x 8
Voltage - Supply (Vcc/Vdd)	1.6V ~ 3.6V
Data Converters	A/D 12x12b; D/A 2x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	44-TQFP
Supplier Device Package	44-TQFP (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/atxmega32a4u-au

Figure 6-1. Block diagram of the AVR CPU architecture.



The arithmetic logic unit (ALU) supports arithmetic and logic operations between registers or between a constant and a register. Single-register operations can also be executed in the ALU. After an arithmetic operation, the status register is updated to reflect information about the result of the operation.

The ALU is directly connected to the fast-access register file. The 32 x 8-bit general purpose working registers all have single clock cycle access time allowing single-cycle arithmetic logic unit (ALU) operation between registers or between a register and an immediate. Six of the 32 registers can be used as three 16-bit address pointers for program and data space addressing, enabling efficient address calculations.

The memory spaces are linear. The data memory space and the program memory space are two different memory spaces.

The data memory space is divided into I/O registers, SRAM, and external RAM. In addition, the EEPROM can be memory mapped in the data memory.

All I/O status and control registers reside in the lowest 4KB addresses of the data memory. This is referred to as the I/O memory space. The lowest 64 addresses can be accessed directly, or as the data space locations from 0x00 to 0x3F. The rest is the extended I/O memory space, ranging from 0x0040 to 0x0FFF. I/O registers here must be accessed as data space locations using load (LD/LDS/LDD) and store (ST/STS/STD) instructions.

The SRAM holds data. Code execution from SRAM is not supported. It can easily be accessed through the five different addressing modes supported in the AVR architecture. The first SRAM address is 0x2000.

Data addresses 0x1000 to 0x1FFF are reserved for memory mapping of EEPROM.

The program memory is divided in two sections, the application program section and the boot program section. Both sections have dedicated lock bits for write and read/write protection. The SPM instruction that is used for self-programming of the application flash memory must reside in the boot program section. The application section contains an application table section with separate lock bits for write and read/write protection. The application table section can be used for safe storing of nonvolatile data in the program memory.

6.4 ALU - Arithmetic Logic Unit

The arithmetic logic unit (ALU) supports arithmetic and logic operations between registers or between a constant and a register. Single-register operations can also be executed. The ALU operates in direct connection with all 32 general

36.2.6 ADC characteristics

Table 36-40. Power supply, reference and input range.

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
AV_{CC}	Analog supply voltage		V_{CC}- 0.3		V_{CC}+ 0.3	V
V_{REF}	Reference voltage		1		AV_{CC}- 0.6	V
R_{in}	Input resistance	Switched		4.0		kΩ
C_{sample}	Input capacitance	Switched		4.4		pF
R_{AREF}	Reference input resistance	(leakage only)		>10		MΩ
C_{AREF}	Reference input capacitance	Static load		7		pF
V_{IN}	Input range		-0.1		AV_{CC}+0.1	V
	Conversion range	Differential mode, Vinp - Vinn	$-V_{REF}$		V_{REF}	V
	Conversion range	Single ended unsigned mode, Vinp	-ΔV		V_{REF}-ΔV	V
ΔV	Fixed offset voltage			190		LSB

Table 36-41. Clock and timing.

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
Clk_{ADC}	ADC clock frequency	Maximum is 1/4 of peripheral clock frequency	100		2000	kHz
		Measuring internal signals	100		125	
f_{ADC}	Sample rate	Current limitation (CURRLIMIT) off	100		2000	ksps
		CURRLIMIT = LOW	100		1500	
		CURRLIMIT = MEDIUM	100		1000	
		CURRLIMIT = HIGH	100		500	
	Sampling time	1/2 Clk_{ADC} cycle	0.25		5	µs
	Conversion time (latency)	(RES+2)/2+(GAIN !=0) RES (Resolution) = 8 or 12	5		8	Clk_{ADC} cycles
	Start-up time	ADC clock cycles		12	24	Clk_{ADC} cycles
	ADC settling time	After changing reference or input mode		7	7	Clk_{ADC} cycles
		After ADC flush		1	1	

36.3.14.4 32kHz Internal ULP Oscillator characteristics

Table 36-89. 32kHz internal ULP oscillator characteristics.

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
	Factory calibrated frequency			32		kHz
	Factory calibrated accuracy	T = 85°C, V_{CC} = 3.0V	-12		12	%
	Accuracy		-30		30	%

36.3.14.5 Internal Phase Locked Loop (PLL) characteristics

Table 36-90. Internal PLL characteristics.

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
f_{IN}	Input frequency	Output frequency must be within f_{OUT}	0.4		64	MHz
f_{OUT}	Output frequency (1)	V_{CC}= 1.6 - 1.8V	20		48	MHz
		V_{CC}= 2.7 - 3.6V	20		128	
	Start-up time			25		µs
	Re-lock time			25		µs

Note: 1. The maximum output frequency vs. supply voltage is linear between 1.8V and 2.7V, and can never be higher than four times the maximum CPU frequency.

36.3.14.6 External clock characteristics

Figure 36-17. External clock drive waveform

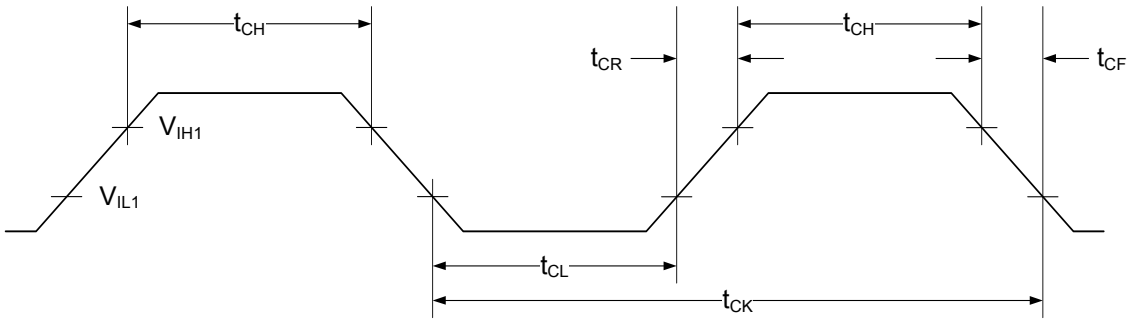


Table 36-91. External clock used as system clock without prescaling.

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
$1/t_{CK}$	Clock Frequency (1)	V_{CC} = 1.6 - 1.8V	0		12	MHz
		V_{CC} = 2.7 - 3.6V	0		32	
t_{CK}	Clock Period	V_{CC} = 1.6 - 1.8V	83.3			ns
		V_{CC} = 2.7 - 3.6V	31.5			
t_{CH}	Clock High Time	V_{CC} = 1.6 - 1.8V	30.0			ns
		V_{CC} = 2.7 - 3.6V	12.5			

Table 36-95. SPI timing characteristics and requirements.

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
t_{SCK}	SCK period	Master		(See Table 21-4 in XMEGA AU Manual)		ns
t_{SCKW}	SCK high/low width	Master		0.5*SCK		
t_{SCKR}	SCK rise time	Master		2.7		
t_{SCKF}	SCK fall time	Master		2.7		
t_{MIS}	MISO setup to SCK	Master		11		
t_{MIH}	MISO hold after SCK	Master		0		
t_{MOS}	MOSI setup SCK	Master		0.5*SCK		
t_{MOH}	MOSI hold after SCK	Master		1.0		
t_{SSCK}	Slave SCK Period	Slave	4*t Clk_{PER}			
t_{SSCKW}	SCK high/low width	Slave	2*t Clk_{PER}			
t_{SSCKR}	SCK rise time	Slave			1600	
t_{SSCKF}	SCK fall time	Slave			1600	
t_{SIS}	MOSI setup to SCK	Slave	3.0			
t_{SIH}	MOSI hold after SCK	Slave	t_{PER}			
t_{SSS}	$\overline{SS}$ setup to SCK	Slave	20			
t_{SSH}	$\overline{SS}$ hold after SCK	Slave	20			
t_{SOS}	MISO setup SCK	Slave		8.0		
t_{SOH}	MISO hold after SCK	Slave		13.0		
t_{SOSS}	MISO setup after $\overline{SS}$ low	Slave		11.0		
t_{SOSH}	MISO hold after $\overline{SS}$ high	Slave		8.0		

36.4.4 Wake-up time from sleep modes

Table 36-102. Device wake-up time from sleep modes with various system clock sources.

Symbol	Parameter	Condition	Min.	Typ. (1)	Max.	Units
t_{wakeup}	Wake-up time from idle, standby, and extended standby mode	External 2MHz clock		2.0		µs
		32.768kHz internal oscillator		120		
		2MHz internal oscillator		2.0		
		32MHz internal oscillator		0.2		
	Wake-up time from power-save and power-down mode	External 2MHz clock		4.5		µs
		32.768kHz internal oscillator		320		
		2MHz internal oscillator		9.0		
		32MHz internal oscillator		5.0		

Note: 1. The wake-up time is the time from the wake-up request is given until the peripheral clock is available on pin, see Figure 36-23. All peripherals and modules start execution from the first clock cycle, expect the CPU that is halted for four clock cycles before program execution starts.

Figure 36-23.Wake-up time definition.

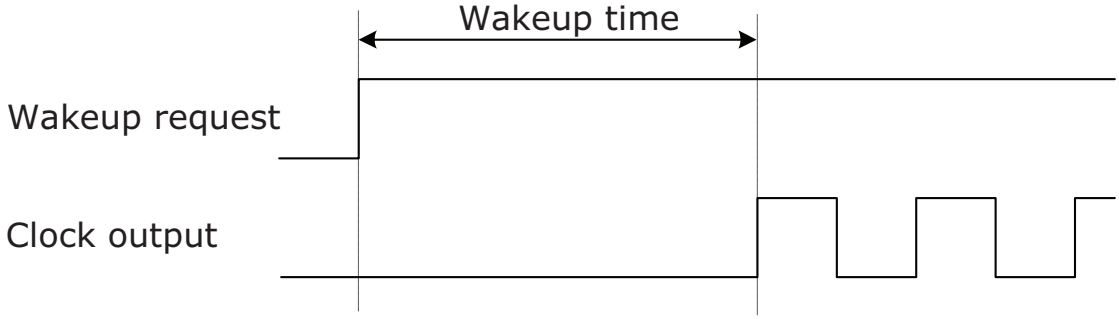


Table 36-110.Accuracy characteristics.

Symbol	Parameter	Condition		Min.	Typ.	Max.	Units
RES	Input resolution					12	Bits
INL [1]	Integral non-linearity	V_{REF}= Ext 1.0V	V_{CC} = 1.6V		±2.0	±3.0	lsb
			V_{CC} = 3.6V		±1.5	±2.5	
		V_{REF}=AV_{CC}	V_{CC} = 1.6V		±2.0	±4.0	
			V_{CC} = 3.6V		±1.5	±4.0	
		V_{REF}=INT1V	V_{CC} = 1.6V		±5.0		
			V_{CC} = 3.6V		±5.0		
DNL [1]	Differential non-linearity	V_{REF}=Ext 1.0V	V_{CC} = 1.6V		±1.5	3.0	lsb
			V_{CC} = 3.6V		±0.6	1.5	
		V_{REF}=AV_{CC}	V_{CC} = 1.6V		±1.0	3.5	
			V_{CC} = 3.6V		±0.6	1.5	
		V_{REF}=INT1V	V_{CC} = 1.6V		±4.5		
			V_{CC} = 3.6V		±4.5		
	Gain error	After calibration			<4.0		lsb
	Gain calibration step size				4.0		lsb
	Gain calibration drift	V_{REF}= Ext 1.0V			<0.2		mV/K
	Offset error	After calibration			<1.0		lsb
	Offset calibration step size				1.0		

Note: 1. Maximum numbers are based on characterisation and not tested in production, and valid for 5% to 95% output voltage range.

Table 36-127. SPI timing characteristics and requirements.

Symbol	Parameter	Condition	Min.	Typ.	Max.	Units
t_{SCK}	SCK Period	Master		(See Table 21-4 in XMEGA AU Manual)		ns
t_{SCKW}	SCK high/low width	Master		0.5×SCK		
t_{SCKR}	SCK Rise time	Master		2.7		
t_{SCKF}	SCK Fall time	Master		2.7		
t_{MIS}	MISO setup to SCK	Master		10		
t_{MIH}	MISO hold after SCK	Master		10		
t_{MOS}	MOSI setup SCK	Master		0.5×SCK		
t_{MOH}	MOSI hold after SCK	Master		1		
t_{SSCK}	Slave SCK Period	Slave	4×t Clk_{PER}			
t_{SSCKW}	SCK high/low width	Slave	2×t Clk_{PER}			
t_{SSCKR}	SCK Rise time	Slave			1600	
t_{SSCKF}	SCK Fall time	Slave			1600	
t_{SIS}	MOSI setup to SCK	Slave	3			
t_{SIH}	MOSI hold after SCK	Slave	t Clk_{PER}			
t_{SSS}	$\overline{SS}$ setup to SCK	Slave	21			
t_{SSH}	$\overline{SS}$ hold after SCK	Slave	20			
t_{SOS}	MISO setup SCK	Slave		8		
t_{SOH}	MISO hold after SCK	Slave		13		
t_{SOSS}	MISO setup after $\overline{SS}$ low	Slave		11		
t_{SOSH}	MISO hold after $\overline{SS}$ high	Slave		8		

37.1.1.5 Standby mode supply current

Figure 37-19. Standby supply current vs. V_{CC}.

Standby, f_{SYS} = 1MHz.

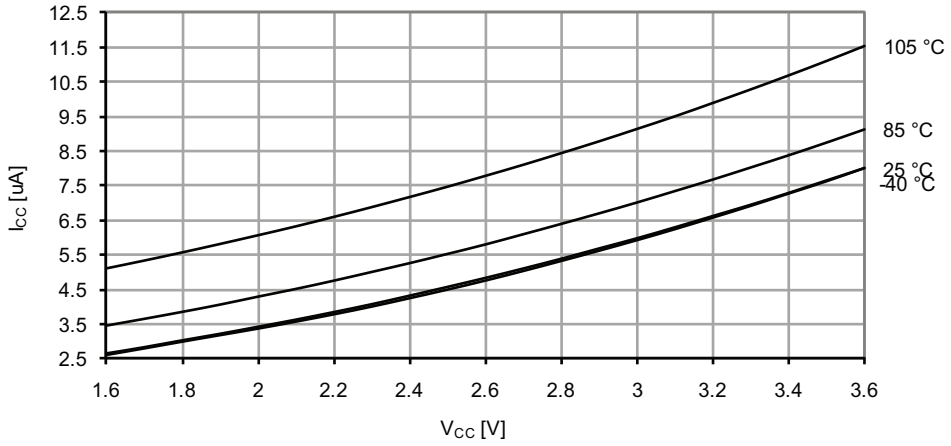


Figure 37-20. Standby supply current vs. V_{CC}.

25°C, running from different crystal oscillators.

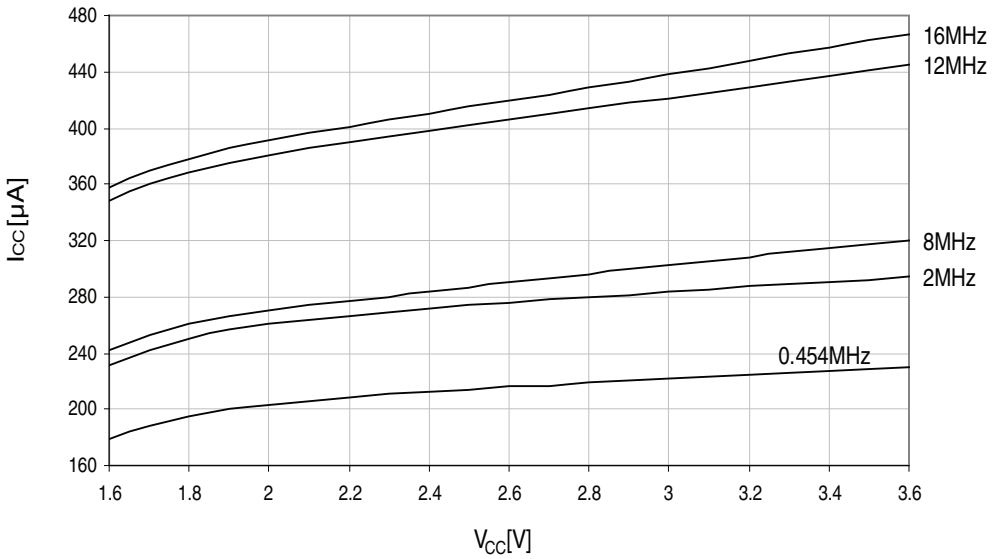


Figure 37-46. Offset error vs. V_{CC}.

T = 25°C, V_{REF} = external 1.0V, ADC sampling speed = 500ksps.

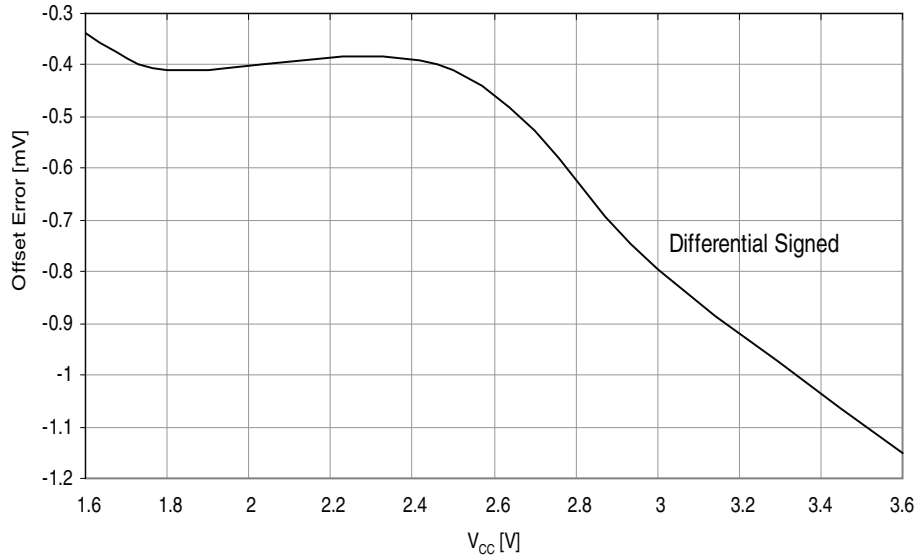


Figure 37-47. Noise vs. V_{REF}.

T = 25°C, V_{CC} = 3.6V, ADC sampling speed = 500ksps.

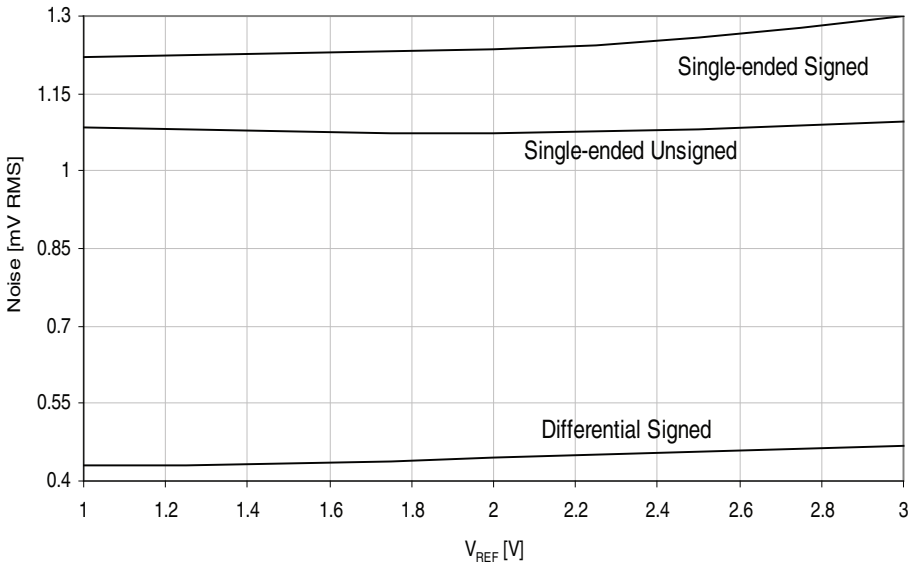


Figure 37-124. DNL error vs. sample rate.

T = 25°C, V_{CC} = 3.6V, V_{REF} = 3.0V external.

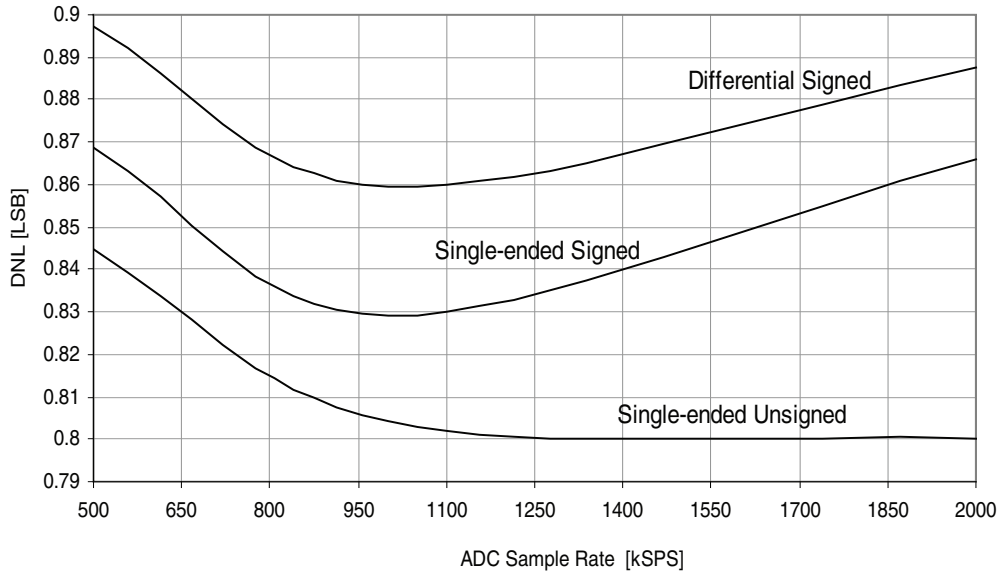


Figure 37-125. DNL error vs. input code.

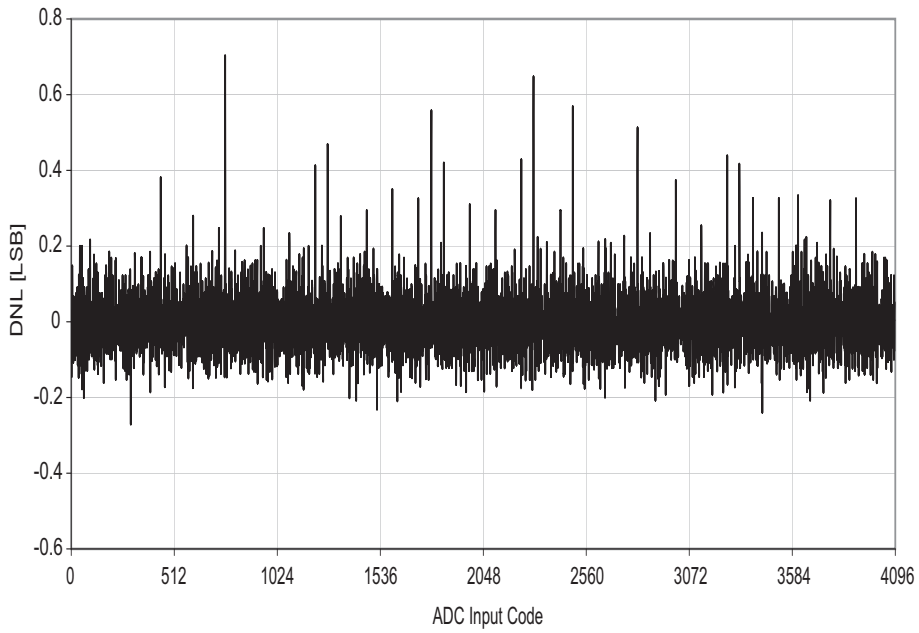


Figure 37-140. Analog comparator current source vs. calibration value.

Temperature = 25°C.

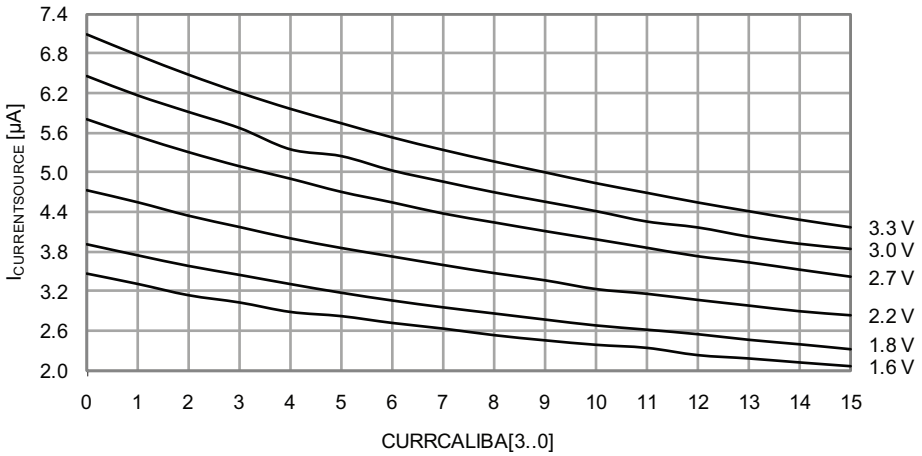
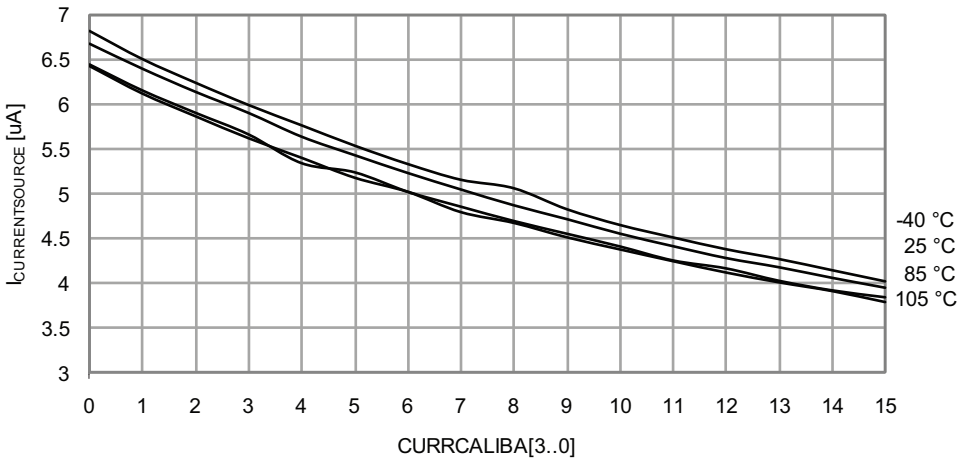


Figure 37-141. Analog comparator current source vs. calibration value.

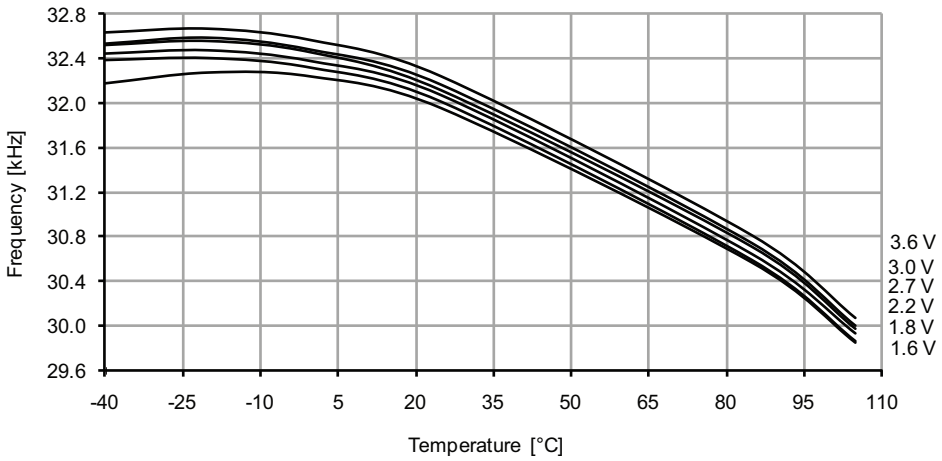
V_{CC} = 3.0V.



37.2.10 Oscillator Characteristics

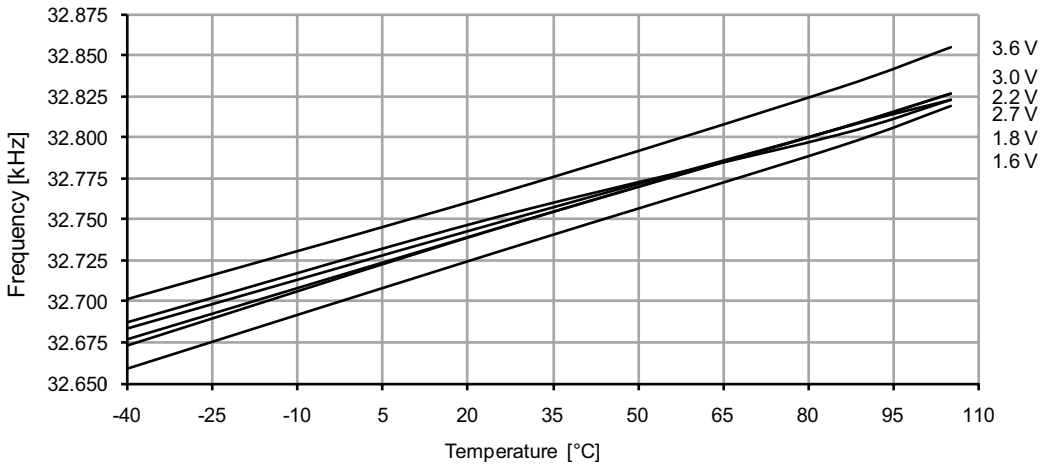
37.2.10.1 Ultra Low-Power internal oscillator

Figure 37-154. Ultra Low-Power internal oscillator frequency vs. temperature.



37.2.10.2 32.768kHz Internal Oscillator

Figure 37-155. 32.768kHz internal oscillator frequency vs. temperature.



37.2.10.4 32MHz Internal Oscillator

Figure 37-160. 32MHz internal oscillator frequency vs. temperature.

DFLL disabled.

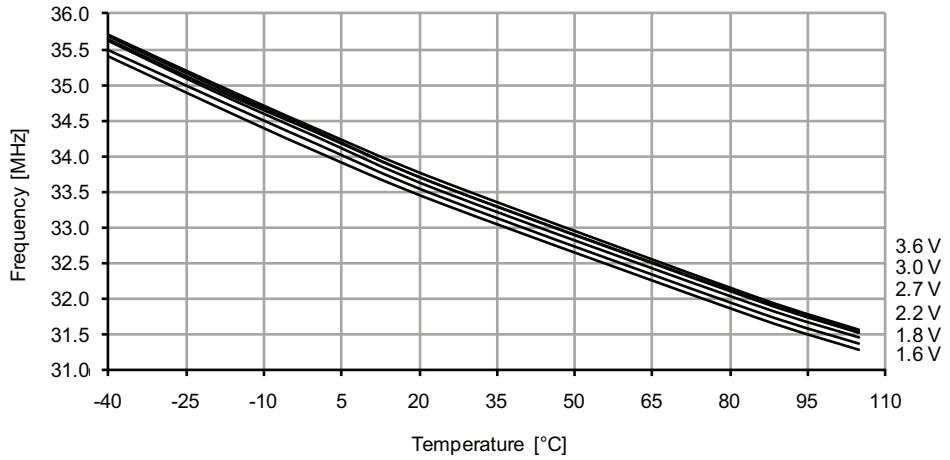


Figure 37-161. 32MHz internal oscillator frequency vs. temperature.

DFLL enabled, from the 32.768kHz internal oscillator.

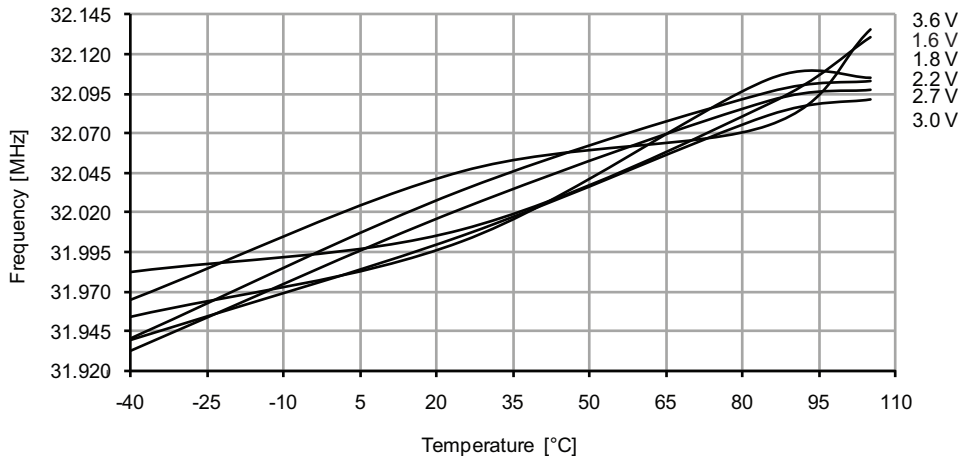


Figure 37-193. I/O pin output voltage vs. source current.

V_{CC} = 3.0V.

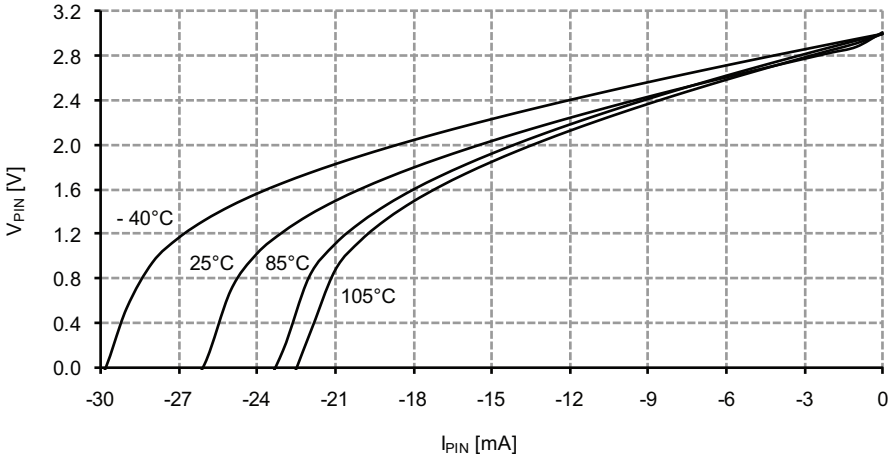


Figure 37-194. I/O pin output voltage vs. source current.

V_{CC} = 3.3V.

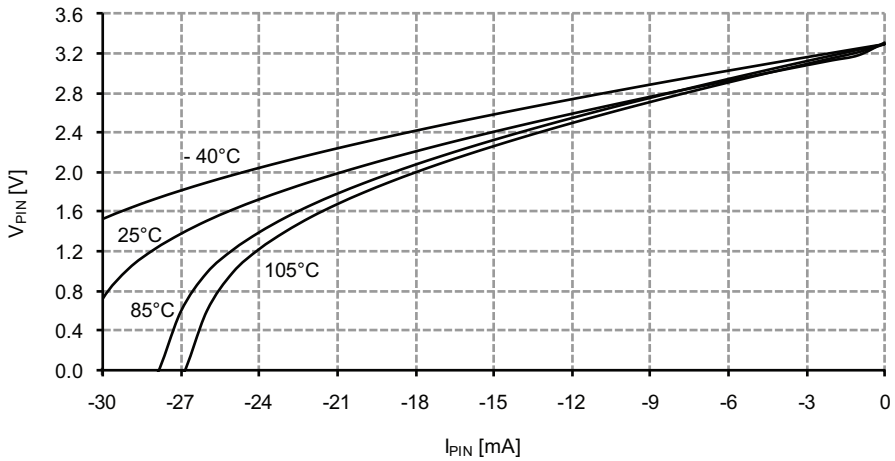
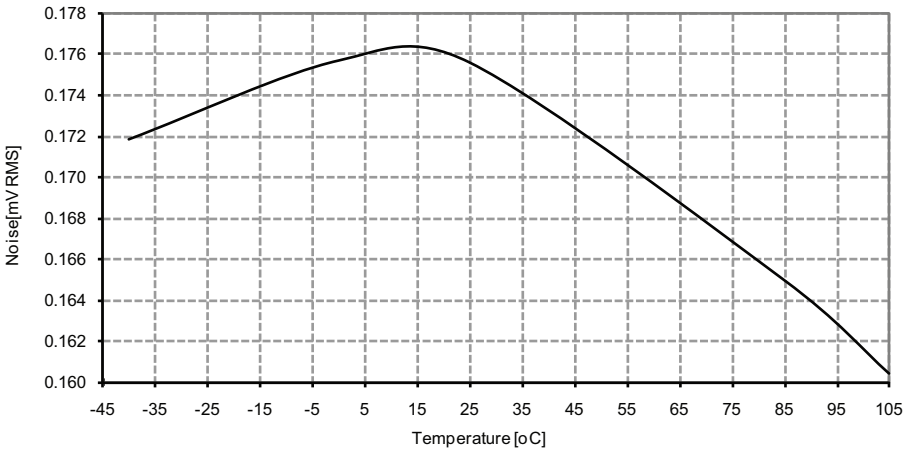


Figure 37-219. DAC noise vs. temperature.

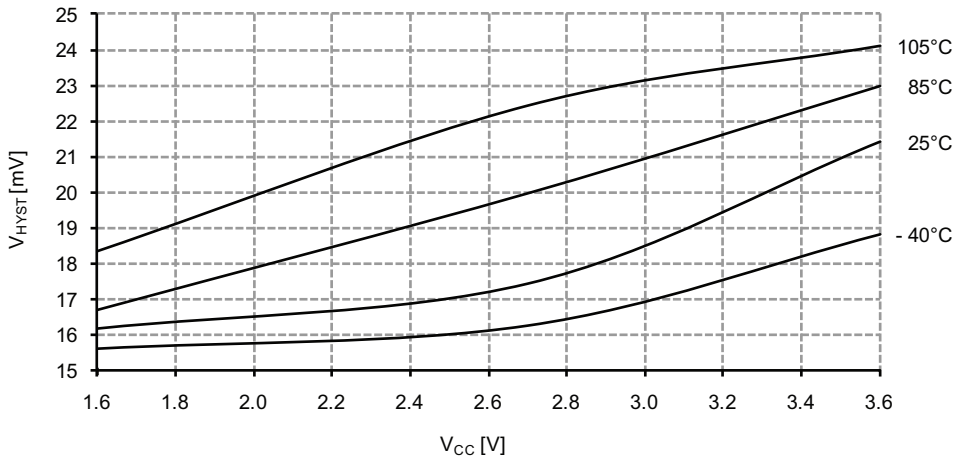
V_{CC} = 2.7V, V_{REF} = 1.0V .



37.3.5 Analog Comparator Characteristics

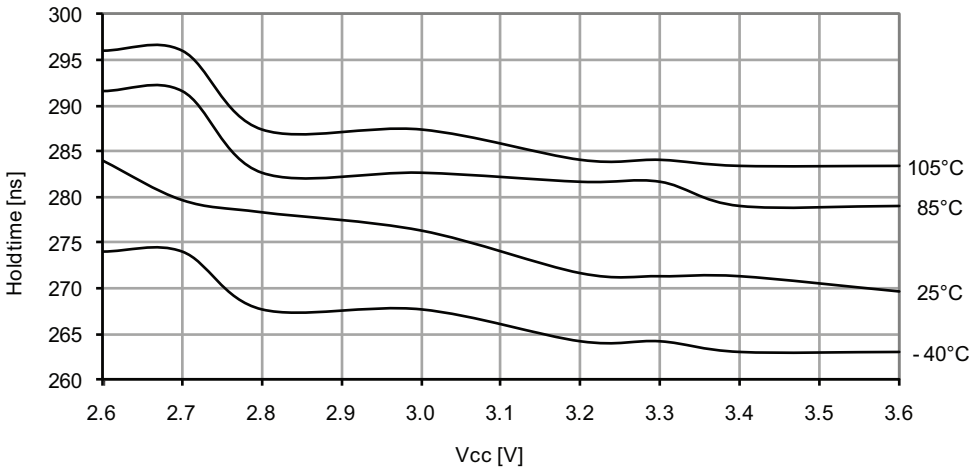
Figure 37-220. Analog comparator hysteresis vs. V_{CC}.

***High-speed, small hysteresis*.**



37.3.11 Two-Wire Interface characteristics

Figure 37-251. SDA hold time vs. supply voltage.



37.3.12 PDI characteristics

Figure 37-252. Maximum PDI frequency vs. V_{CC}.

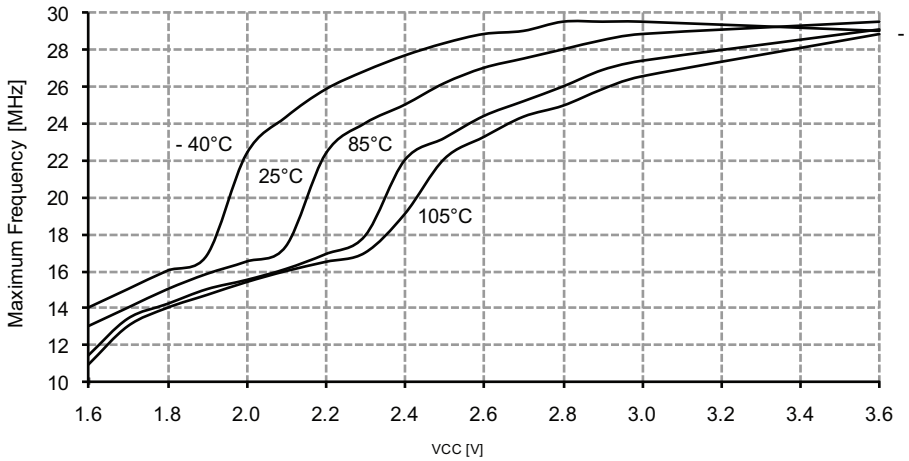


Figure 37-255. Active mode supply current vs. V_{CC}.

f_{SYS} = 32.768kHz internal oscillator

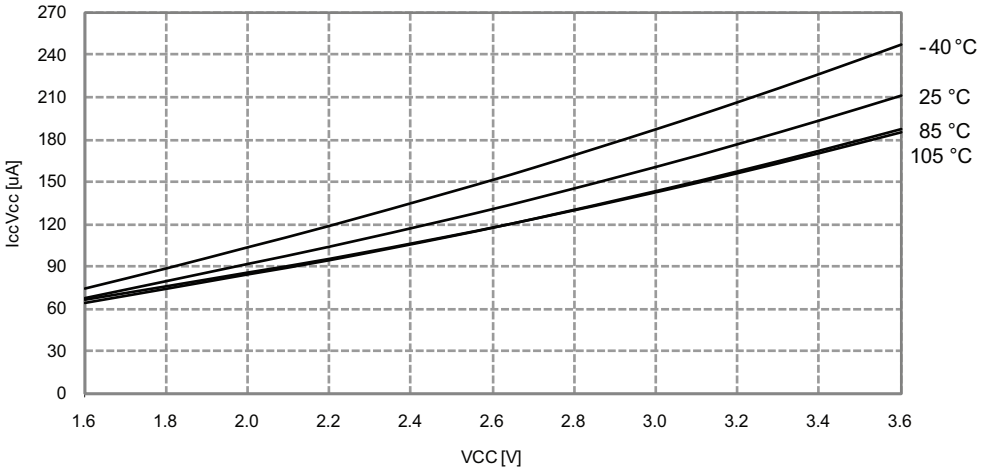


Figure 37-256. Active mode supply current vs. V_{CC}.

f_{SYS} = 1MHz external clock.

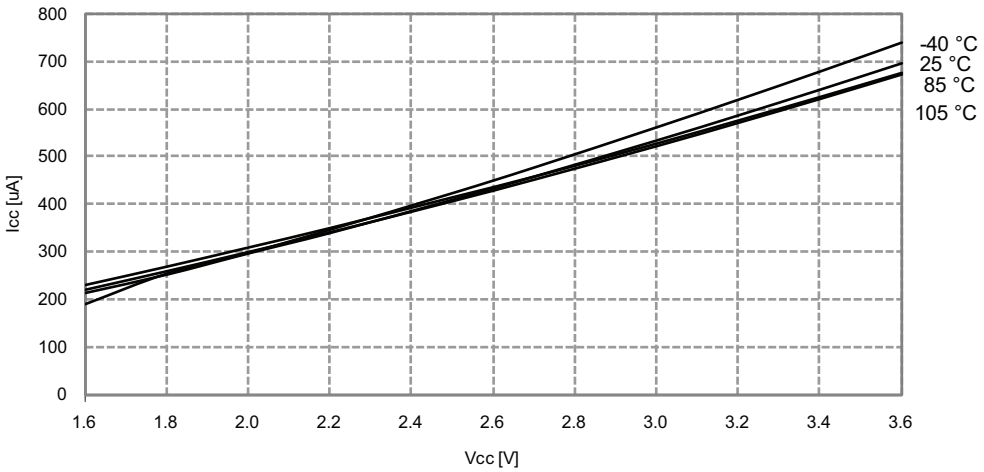
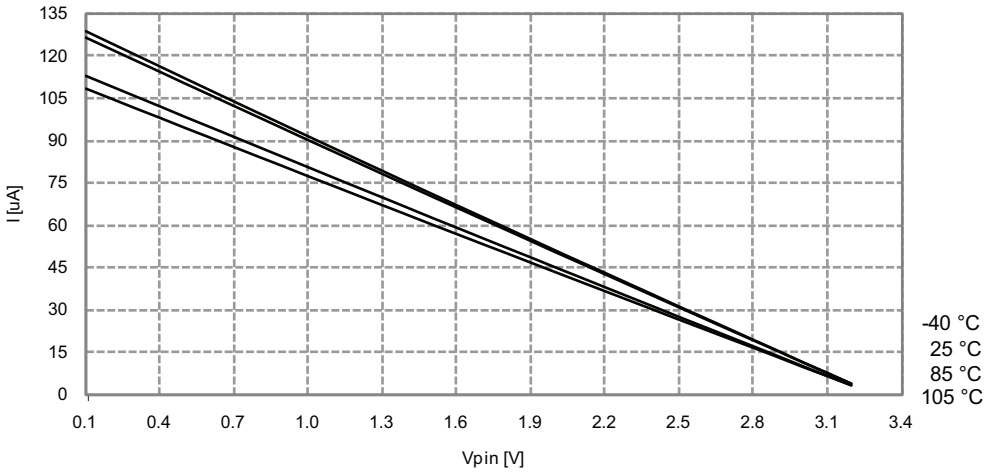


Figure 37-275. I/O pin pull-up resistor current vs. input voltage.

V_{CC} = 3.3V.



37.4.2.2 Output Voltage vs. Sink/Source Current

Figure 37-276. I/O pin output voltage vs. source current.

V_{CC} = 1.8V

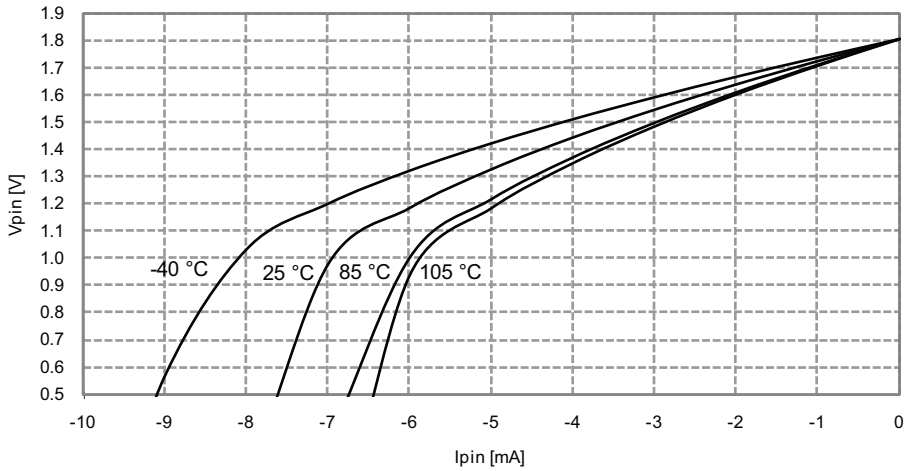


Figure 37-305. Analog comparator hysteresis vs. V_{CC}.

Low power, small hysteresis

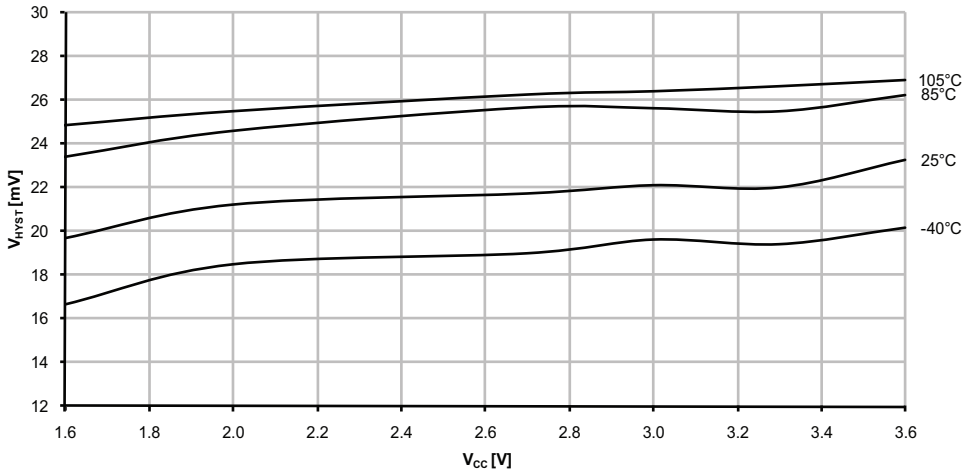
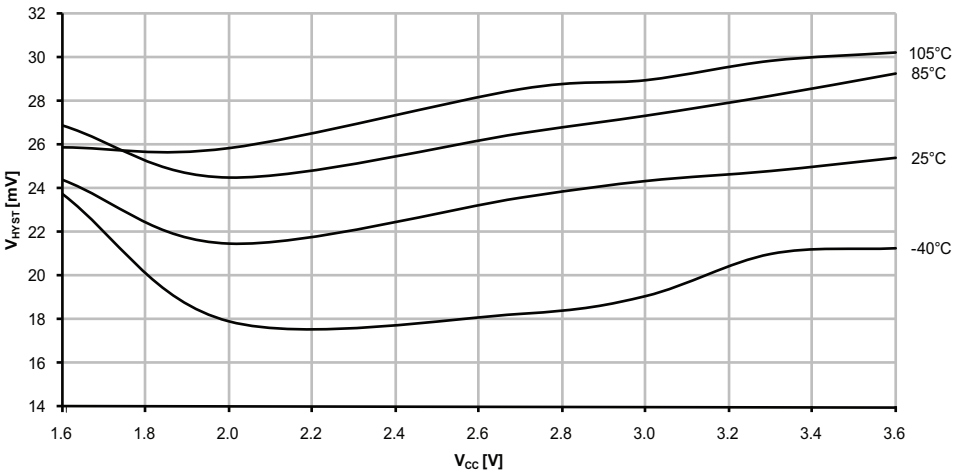


Figure 37-306. Analog comparator hysteresis vs. V_{CC}.

High-speed mode, large hysteresis



37.4.10.2 32.768kHz Internal Oscillator

Figure 37-323. 32.768kHz internal oscillator frequency vs. temperature

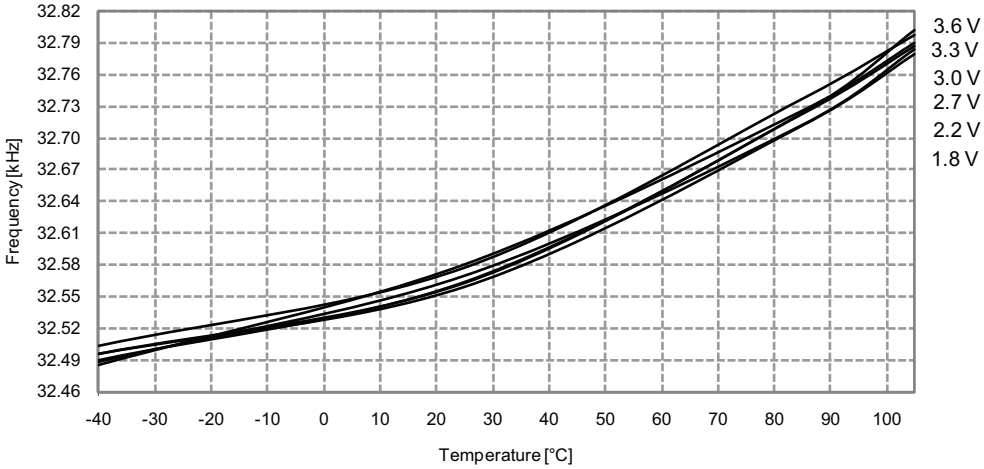


Figure 37-324. 32.768kHz internal oscillator frequency vs. calibration value

V_{CC} = 3.0V, T = 25°C