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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

Details

Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	40MHz
Connectivity	I²C, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, HLVD, POR, PWM, WDT
Number of I/O	25
Program Memory Size	32KB (16K x 16)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	1.5K x 8
Voltage - Supply (Vcc/Vdd)	4.2V ~ 5.5V
Data Converters	A/D 10x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	28-VQFN Exposed Pad
Supplier Device Package	28-QFN (6x6)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic18f2510t-i-ml

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

The following devices are included in 28-pin QFN parts:

PIC18F2221PIC18F2321

• PIC18F2410

• PIC18F2420

PIC18F2423PIC18F2450

.

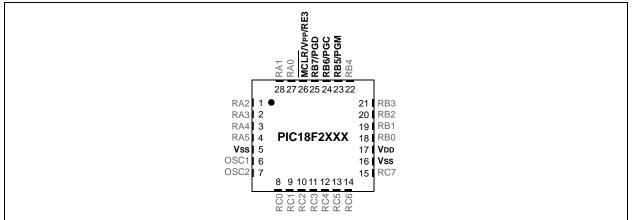
• PIC18F2480

- PIC18F2510
 DIC18F2520
 - PIC18F2520

.

- PIC18F2523
- PIC18F2580
- PIC18F2682
- PIC18F2685

FIGURE 2-2: 28-Pin QFN



The following devices are included in 40-pin PDIP parts:

- PIC18F4221
- PIC18F4321
- PIC18F4410
- PIC18F4420
- PIC18F4423
- PIC18F4450
- PIC18F4458PIC18F4480PIC18F4510

• PIC18F4455

- PIC18F4515PIC18F4520
- PIC18F4523PIC18F4525
- PIC18F4550
- PIC18F4553
- PIC18F4580
- PIC18F4585

- PIC18F4610
- PIC18F4620
- PIC18F4680
- PIC18F4682
- PIC18F4685

•

FIGURE 2-3: 40-P

40-Pin PDIP

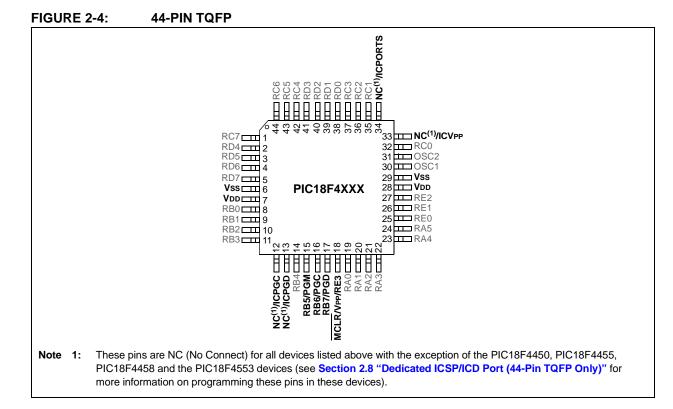
MCLR/Vpp/RE3	°	40 RB7/PGD
RAO		39 B RB6/PGC
RA1		38 🗖 RB5/PGM
RA2		37 🗖 RB4
RA3		36 🗖 RB3
RA4	6	35 🗖 RB2
RA5	7	34 🗖 RB1
RE0	8 🎽	33 🗖 RB0
RE1	9 🗙	32 🗍 VDD
RE2		31 🗖 Vss
VDD	11 8	30 🗌 RD7
Vss	12 Ú	29 🗖 RD6
OSC1		28 RD5
OSC2		27 🗖 RD4
RC0		26 🗖 RC7
RC1		25 RC6
RC2		24 C5
RC3		23 RC4
RD0		22 RD3
RD1	20	21 RD2

The following devices are included in 44-pin TQFP parts:

- PIC18F4221
- PIC18F4321
- PIC18F4410
- PIC18F4420
- PIC18F4423
- PIC18F4450
- PIC18F4455
- PIC18F4458
- PIC18F4480
- PIC18F4510
- PIC18F4520
- PIC18F4515

PIC18F4523

- PIC18F4525
- PIC18F4550
- PIC18F4553
- PIC18F4580
- PIC18F4585
- PIC18F4610
- PIC18F4620
- PIC18F4680
- PIC18F4682
- PIC18F4685



The following devices are included in 44-pin QFN parts:

- PIC18F4221
- PIC18F4321
- PIC18F4410
- PIC18F4420
- PIC18F4423
- PIC18F4450
- PIC18F4455
- PIC18F4458
- PIC18F4480
- PIC18F4510
- PIC18F4520
- PIC18F4515

PIC18F4553
 PIC18F4580
 PIC18F4585
 PIC18F4610
 PIC18F4620
 PIC18F4680

• PIC18F4523

PIC18F4525

PIC18F4550

- PIC18F4682
- PIC18F4685

FIGURE 2-5: 44-PIN QFN RD2 RD1 VUSB VUSB RC1 RC1 RC1 RC1 33 OSC2 32 OSC1 RD4 2 RD5 3 RD6 4 31 Vss 30 AVss RD7 5 29 VDD PIC18F4XXX 28 AVDD Vss 6 AVDD 7 27 RE2 **VDD** 8 RB0 9 26 RE1 25 RE0 24 RA5 RB1 10 RB2 RA4 23 11 ទទ RA3 S S G^RB4 RA2 ш RB5/P RB6/P RB7/P MCLR/VPP/R

2.3 Memory Maps

For PIC18FX6X0 devices, the code memory space extends from 0000h to 0FFFFh (64 Kbytes) in four 16-Kbyte blocks. For PIC18FX5X5 devices, the code memory space extends from 0000h to 0BFFFFh (48 Kbytes) in three 16-Kbyte blocks. Addresses, 0000h through 07FFh, however, define a "Boot Block" region that is treated separately from Block 0. All of these blocks define code protection boundaries within the code memory space.

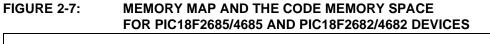
The size of the Boot Block in PIC18F2585/2680/4585/4680 devices can be configured as 1, 2 or 4K words (see Figure 2-6). This is done through the BBSIZ<1:0> bits in the Configuration register, CONFIG4L. It is important to note that increasing the size of the Boot Block decreases the size of Block 0.

For PIC18F2685/4685 devices, the code memory space extends from 0000h to 017FFFh (96 Kbytes) in five 16-Kbyte blocks. For PIC18F2682/4682 devices, the code memory space extends from 0000h to 0013FFFh (80 Kbytes) in four 16-Kbyte blocks. Addresses, 0000h through 0FFFh, however, define a "Boot Block" region that is treated separately from Block 0. All of these blocks define code protection boundaries within the code memory space.

The size of the Boot Block in PIC18F2685/4685 and PIC18F2682/4682 devices can be configured as 1, 2 or 4K words (see Figure 2-7). This is done through the BBSIZ<2:1> bits in the Configuration register, CONFIG4L. It is important to note that increasing the size of the Boot Block decreases the size of Block 0.

	TABLE 2-3:	IMPLEMENTATION OF CODE MEMORY
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Device	Code Memory Size (Bytes)				
PIC18F2682	000000h 012EEEh (80K)				
PIC18F4682	– 000000h-013FFFh (80K)				
PIC18F2685					
PIC18F4685	000000h-017FFFh (96K)				



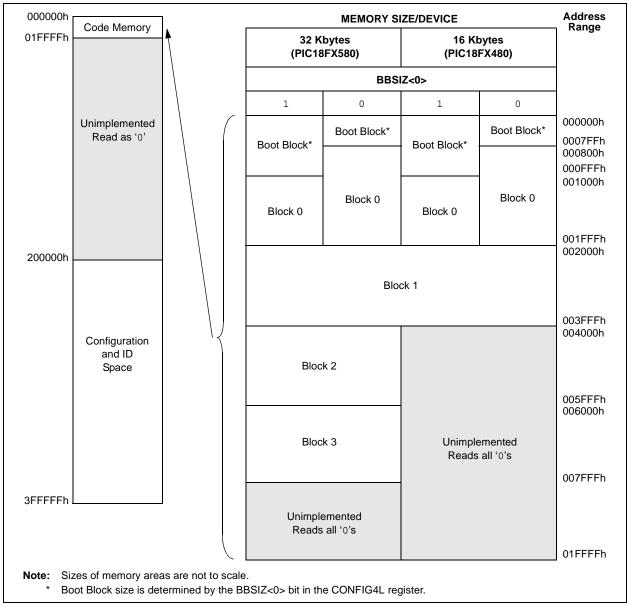
000000h			MEMORY SIZE/DEVICE						Addre Rang
01FFFFh			96 Kbytes (PIC18F2685/4685)			80 Kbytes (PIC18F2682/4682)			Tung
			BBSIZ1:BBSIZ2						
			11/10	01	00	11/10	01	00	
				Boot	Boot Block*		Boot	Boot Block*	00000 0007F
	Unimplemented Read as '0'		Boot Block*	Block*		Boot Block*	Block*		00080 000FF
					Block 0			Block 0	00100 001FF
			Block 0	Block 0	DIOCK	Block 0	Block 0	DIUCK U	00200
200000h									003FF 00400
		Block 1			Block 1				
				Block 2			Block 2		007FF 00800
	Configuration and ID			Block 3			Block 3		00BFF 00C00
	Space			Block 4			Block 4		00FFF 01000
									013FF 01400
		Block 5			Unimplemented			017FF	
BFFFFFh				Inimplemented Reads all '0's	b		Reads all '0's		01FFF

For PIC18FX5X0/X5X3 devices, the code memory space extends from 000000h to 007FFFh (32 Kbytes) in four 8-Kbyte blocks. For PIC18FX4X5/X4X8 devices, the code memory space extends from 000000h to 005FFFh (24 Kbytes) in three 8-Kbyte blocks. Addresses, 000000h through 0007FFh, however, define a "Boot Block" region that is treated separately from Block 0. All of these blocks define code protection boundaries within the code memory space.

TABLE 2-6:IMPLEMENTATION OF CODE MEMORY

Device	Code Memory Size (Bytes)
PIC18F2480	
PIC18F4480	000000h-003FFFh (16K)
PIC18F2580	000000h 007EEEh (22K)
PIC18F4580	000000h-007FFFh (32K)

FIGURE 2-10: MEMORY MAP AND THE CODE MEMORY SPACE FOR PIC18F2480/2580/4480/4580 DEVICES

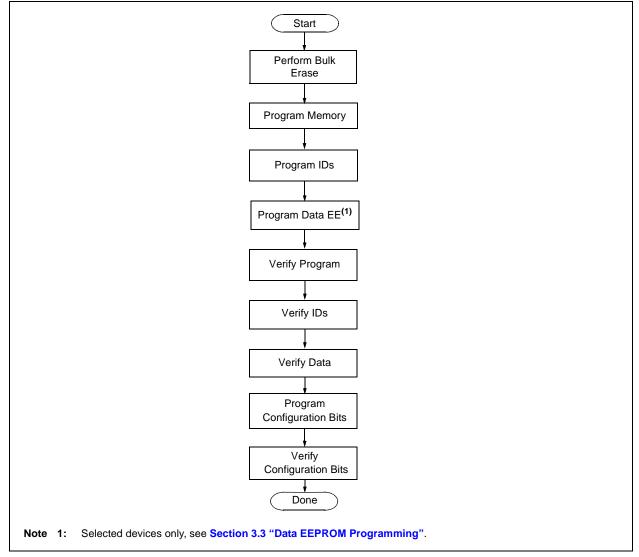


For PIC18F2221/4221 devices, the code memory space extends from 0000h to 00FFFh (4 Kbytes) in one 4-Kbyte block. For PIC18F2321/4321 devices, the code memory space extends from 0000h to 01FFFh (8 Kbytes) in two 4-Kbyte blocks. Addresses, 0000h through 07FFh, however, define a variable "Boot Block" region that is treated separately from Block 0. All of these blocks define code protection boundaries within the code memory space.

2.4 High-Level Overview of the Programming Process

Figure 2-13 shows the high-level overview of the programming process. First, a Bulk Erase is performed. Next, the code memory, ID locations and data EEPROM are programmed (selected devices only, see Section 3.3 "Data EEPROM Programming"). These memories are then verified to ensure that programming was successful. If no errors are detected, the Configuration bits are then programmed and verified.





2.7 Serial Program/Verify Operation

The PGC pin is used as a clock input pin and the PGD pin is used for entering command bits and data input/output during serial operation. Commands and data are transmitted on the rising edge of PGC, latched on the falling edge of PGC and are Least Significant bit (LSb) first.

2.7.1 4-BIT COMMANDS

All instructions are 20 bits, consisting of a leading 4-bit command followed by a 16-bit operand, which depends on the type of command being executed. To input a command, PGC is cycled four times. The commands needed for programming and verification are shown in Table 2-8.

Depending on the 4-bit command, the 16-bit operand represents 16 bits of input data or 8 bits of input data and 8 bits of output data.

Throughout this specification, commands and data are presented as illustrated in Table 2-9. The 4-bit command is shown Most Significant bit (MSb) first. The command operand, or "Data Payload", is shown as <MSB><LSB>. Figure 2-18 demonstrates how to serially present a 20-bit command/operand to the device.

2.7.2 CORE INSTRUCTION

The core instruction passes a 16-bit instruction to the CPU core for execution. This is needed to set up registers as appropriate for use with other commands.

TABLE 2-8: COMMANDS FOR PROGRAMMING

Description	4-Bit Command
Core Instruction (Shift in16-bit instruction)	0000
Shift Out TABLAT Register	0010
Table Read	1000
Table Read, Post-Increment	1001
Table Read, Post-Decrement	1010
Table Read, Pre-Increment	1011
Table Write	1100
Table Write, Post-Increment by 2	1101
Table Write, Start Programming, Post-Increment by 2	1110
Table Write, Start Programming	1111

TABLE 2-9: SAMPLE COMMAND SEQUENCE

4-Bit Command	Data Payload	Core Instruction
1101	3C 40	Table Write,
		post-increment by 2

3.2.1 MODIFYING CODE MEMORY

The previous programming example assumed that the device had been Bulk Erased prior to programming (see **Section 3.1.1 "High-Voltage ICSP Bulk Erase**"). It may be the case, however, that the user wishes to modify only a section of an already programmed device.

The appropriate number of bytes required for the erase buffer must be read out of code memory (as described in Section 4.2 "Verify Code Memory and ID Locations") and buffered. Modifications can be made on this buffer. Then, the block of code memory that was read out must be erased and rewritten with the modified data.

The WREN bit must be set if the WR bit in EECON1 is used to initiate a write sequence.

4-Bit Command	Data Payload	Core Instruction
Step 1: Direct ac	ccess to code memory.	
Step 2: Read an	d modify code memory (see S	ection 4.1 "Read Code Memory, ID Locations and Configuration Bits").
0000	8E A6	BSF EECON1, EEPGD
0000	9C A6	BCF EECON1, CFGS
Step 3: Set the T	Table Pointer for the block to b	e erased.
0000	0E <addr[21:16]></addr[21:16]>	MOVLW <addr[21:16]></addr[21:16]>
0000	6E F8	MOVWF TBLPTRU
0000	0E <addr[8:15]></addr[8:15]>	MOVLW <addr[8:15]></addr[8:15]>
0000	6E F7	MOVWF TBLPTRH
0000	0E <addr[7:0]></addr[7:0]>	MOVLW <addr[7:0]></addr[7:0]>
0000	6E F6	MOVWF TBLPTRL
Step 4: Enable r	nemory writes and set up an e	rase.
0000	84 A6	BSF EECON1, WREN
0000	88 A6	BSF EECON1, FREE
Step 5: Initiate e	rase.	
0000	82 A6	BSF EECON1, WR
0000	00 00	NOP - hold PGC high for time P9 and low for time P10.
Step 6: Load wri	te buffer. The correct bytes wi	Il be selected based on the Table Pointer.
0000	0E <addr[21:16]></addr[21:16]>	MOVLW <addr[21:16]></addr[21:16]>
0000	6E F8	MOVWF TBLPTRU
0000	0E <addr[8:15]></addr[8:15]>	MOVLW <addr[8:15]></addr[8:15]>
0000	6E F7	MOVWF TBLPTRH
0000	0E <addr[7:0]></addr[7:0]>	MOVLW <addr[7:0]></addr[7:0]>
0000	6E F6	MOVWF TBLPTRL
1101	<msb><lsb></lsb></msb>	Write 2 bytes and post-increment address by 2.
•		Repeat as many times as necessary to fill the write buffer
1111	<msb><lsb></lsb></msb>	Write 2 bytes and start programming.
0000	00 00	NOP - hold PGC high for time P9 and low for time P10.
	at each iteration of the loop. T	bugh 6, where the Address Pointer is incremented by the appropriate number of byte he write cycle must be repeated enough times to completely rewrite the contents of
Step 7: Disable	writes.	
0000	94 A6	BCF EECON1, WREN

TABLE 3-6: MODIFYING CODE MEMORY

3.3 Data EEPROM Programming

Note: Data EEPROM programming is not available on the following devices:						
PIC18F2410	PIC18F4410					
PIC18F2450	PIC18F4450					
PIC18F2510	PIC18F4510					
PIC18F2515	PIC18F4515					
PIC18F2610	PIC18F4610					

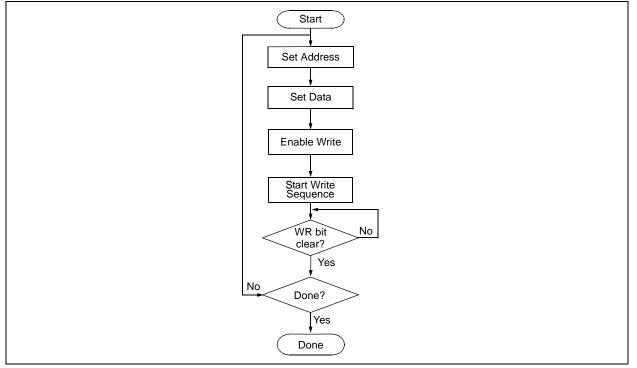
Data EEPROM is accessed one byte at a time via an Address Pointer (register pair: EEADRH:EEADR) and a data latch (EEDATA). Data EEPROM is written by loading EEADRH:EEADR with the desired memory location, EEDATA, with the data to be written and initiating a memory write by appropriately configuring the EECON1 register. A byte write automatically erases the location and writes the new data (erase-before-write).

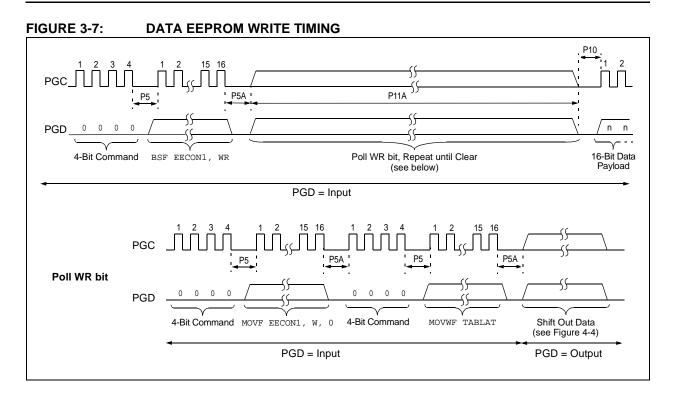
When using the EECON1 register to perform a data EEPROM write, both the EEPGD and CFGS bits must be cleared (EECON1<7:6> = 00). The WREN bit must be set (EECON1<2> = 1) to enable writes of any sort and this must be done prior to initiating a write sequence. The write sequence is initiated by setting the WR bit (EECON1<1> = 1).

The write begins on the falling edge of the 4th PGC after the WR bit is set. It ends when the WR bit is cleared by hardware.

After the programming sequence terminates, PGC must still be held low for the time specified by Parameter P10 to allow high-voltage discharge of the memory array.

FIGURE 3-6: PROGRAM DATA FLOW





3.4 ID Location Programming

The ID locations are programmed much like the code memory. The ID registers are mapped in addresses, 200000h through 200007h. These locations read out normally even after code protection.

Note: The user only needs to fill the first 8 bytes of the write buffer in order to write the ID locations.

Table 3-8 demonstrates the code sequence required to write the ID locations.

In order to modify the ID locations, refer to the methodology described in **Section 3.2.1** "**Modifying Code Memory**". As with code memory, the ID locations must be erased before being modified.

TABLE 3-8: WRITE ID SEQUENCE

4-Bit Command	Data Payload	Core Instruction						
Step 1: Direct acc	Step 1: Direct access to code memory and enable writes.							
0000 0000	8E A6 9C A6	BSF EECON1, EEPGD BCF EECON1, CFGS						
Step 2: Load write	e buffer with 8 bytes and writ	e.						
0000 0000 0000 0000 0000 1101 1101 110	0E 20 6E F8 0E 00 6E F7 0E 00 6E F6 <msb><lsb> <msb><lsb> <msb><lsb> <msb><lsb></lsb></msb></lsb></msb></lsb></msb></lsb></msb>	MOVLW 20h MOVWF TBLPTRU MOVUW 00h MOVWF TBLPTRH MOVLW 00h MOVWF TBLPTRL Write 2 bytes and post-increment address by 2. Write 2 bytes and post-increment address by 2. Write 2 bytes and post-increment address by 2. Write 2 bytes and start programming. NOP - hold PGC high for time P9 and low for time P10.						

3.5 Boot Block Programming

The code sequence detailed in Table 3-5 should be used, except that the address used in "Step 2" will be in the range of 000000h to 0007FFh.

3.6 Configuration Bits Programming

Unlike code memory, the Configuration bits are programmed a byte at a time. The Table Write, Begin Programming 4-bit command ('1111') is used, but only eight bits of the following 16-bit payload will be written. The LSB of the payload will be written to even addresses and the MSB will be written to odd addresses. The code sequence to program two consecutive configuration locations is shown in Table 3-9.

Note: The address must be explicitly written for each byte programmed. The addresses can not be incremented in this mode.

4.2 Verify Code Memory and ID Locations

The verify step involves reading back the code memory space and comparing it against the copy held in the programmer's buffer. Memory reads occur a single byte at a time, so two bytes must be read to compare against the word in the programmer's buffer. Refer to Section 4.1 "Read Code Memory, ID Locations and Configuration Bits" for implementation details of reading code memory.

The Table Pointer must be manually set to 200000h (base address of the ID locations) once the code memory has been verified. The post-increment feature of the Table Read 4-bit command may not be used to increment the Table Pointer beyond the code memory space. In a 64-Kbyte device, for example, a post-increment read of address, FFFFh, will wrap the Table Pointer back to 000000h, rather than point to the unimplemented address, 010000h.

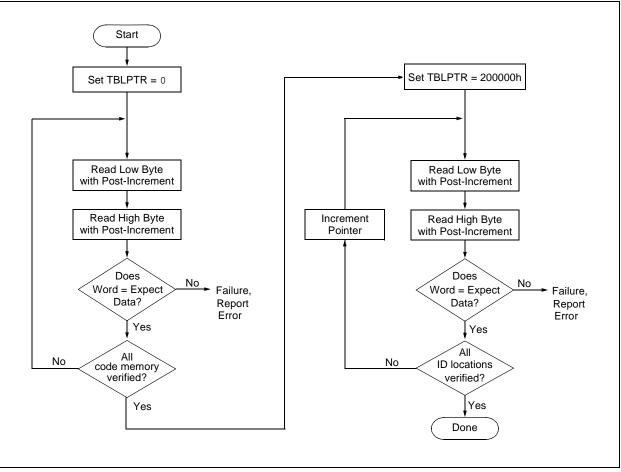


FIGURE 4-2: VERIFY CODE MEMORY FLOW

4.3 Verify Configuration Bits

A configuration address may be read and output on PGD via the 4-bit command, '1001'. Configuration data is read and written in a byte-wise fashion, so it is not necessary to merge two bytes into a word prior to a compare. The result may then be immediately compared to the appropriate configuration data in the programmer's memory for verification. Refer to **Section 4.1 "Read Code Memory, ID Locations and Configuration Bits**" for implementation details of reading configuration data.

TABLE 5-1: CONFIGURATION BITS AND DEVICE IDS

File 1	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Default/ Unprogrammed Value						
300000h ^(1,8)	CONFIG1L		_	USBDIV	CPUDIV1	CPUDIV0	PLLDIV2	PLLDIV1	PLLDIV0	00 0000						
300001h	CONFIG1H	IESO	FCMEN		_	FOSC3 FOSC	FOSC2	FOSC1	FOSC0	00 0111						
30000111	CONTONT	1200	TOWEN			10000	10002	10001	10000	00 0101 ^(1,8)						
300002h	CONFIG2L			_	BORV1	BORV0	BOREN1	BOREN0	PWRTEN	1 1111						
30000211				VREGEN ^(1,8)	BORVI	BORVU	BORLINI	BORLINU	PWRIEN	01 1111 (1,8)						
300003h	CONFIG2H	—	—	_	WDTPS3	WDTPS2	WDTPS1	WDTPS0	WDTEN	1 1111						
300005h	CONFIG3H	MCLRE	_	_	_	_	LPT1OSC	PBADEN CCP	CCP2MX ⁽⁷⁾	1011 (7)						
00000011		MOEINE					LI I I OOO		—	101-						
				ICPRT ⁽¹⁾	—	-	LVP							_		1001-1 ⁽¹⁾
				BBSIZ1	BBSIZ0	_		— s	— STVREN	1000 -1-1						
300006h	CONFIG4L	DEBUG	XINST	_	BBSIZ ⁽³⁾	_				10-0 -1-1 (3)						
				ICPRT ⁽⁸⁾	—	BBSIZ ⁽⁸⁾				100- 01-1 ⁽⁸⁾						
				BBSIZ1 ⁽²⁾	BBSIZ2(2)	-				1000 -1-1 (2)						
300008h	CONFIG5L	_	—	CP5 ⁽¹⁰⁾	CP4 ⁽⁹⁾	CP3 ⁽⁴⁾	CP2 ⁽⁴⁾	CP1	CP0	11 1111						
300009h	CONFIG5H	CPD	CPB	_	—	-	—	-	—	11						
30000Ah	CONFIG6L	_	—	WRT5 ⁽¹⁰⁾	WRT4 ⁽⁹⁾	WRT3 ⁽⁴⁾	WRT2 ⁽⁴⁾	WRT1	WRT0	11 1111						
30000Bh	CONFIG6H	WRTD	WRTB	WRTC ⁽⁵⁾	—		_		—	111						
30000Ch	CONFIG7L		_	EBTR5 ⁽¹⁰⁾	EBTR4 ⁽⁹⁾	EBTR3 ⁽⁴⁾	EBTR2 ⁽⁴⁾	EBTR1	EBTR0	11 1111						
30000Dh	CONFIG7H		EBTRB		_		_		_	-1						
3FFFFEh	DEVID1 ⁽⁶⁾	DEV2	DEV1	DEV0	REV4	REV3	REV2	REV1	REV0	See Table 5-2						
3FFFFFh	DEVID2 ⁽⁶⁾	DEV10	DEV9	DEV8	DEV7	DEV6	DEV5	DEV4	DEV3	See Table 5-2						

Legend: -= unimplemented. Shaded cells are unimplemented, read as '0'.

Note 1: Implemented only on PIC18F2455/2550/4455/4550 and PIC18F2458/2553/4458/4553 devices.

2: Implemented on PIC18F2585/2680/4585/4680, PIC18F2682/2685 and PIC18F4682/4685 devices only.

3: Implemented on PIC18F2480/2580/4480/4580 devices only.

4: These bits are only implemented on specific devices based on available memory. Refer to Section 2.3 "Memory Maps".

5: In PIC18F2480/2580/4480/4580 devices, this bit is read-only in Normal Execution mode; it can be written only in Program mode.

6: DEVID registers are read-only and cannot be programmed by the user.

7: Implemented on all devices with the exception of the PIC18FXX8X and PIC18F2450/4450 devices.

8: Implemented on PIC18F2450/4450 devices only.

9: Implemented on PIC18F2682/2685 and PIC18F4682/4685 devices only.

10: Implemented on PIC18F2685/4685 devices only.

TABLE 5-2: DEVICE ID VALUES

Device	Device ID Value				
Device	DEVID2	DEVID1			
PIC18F2221	21h	011x xxxx			
PIC18F2321	21h	001x xxxx			
PIC18F2410	11h	011x xxxx			
PIC18F2420	11h	010x xxxx(1)			
PIC18F2423	11h	010x xxxx (2)			
PIC18F2450	24h	001x xxxx			
PIC18F2455	12h	011x xxxx			
PIC18F2458	2Ah	011x xxxx			
PIC18F2480	1Ah	111x xxxx			
PIC18F2510	11h	001x xxxx			
PIC18F2515	0Ch	111x xxxx			
PIC18F2520	11h	000x xxxx(1)			
PIC18F2523	11h	000x xxxx (2)			
PIC18F2525	0Ch	110x xxxx			
PIC18F2550	12h	010x xxxx			
PIC18F2553	2Ah	010x xxxx			
PIC18F2580	1Ah	110x xxxx			
PIC18F2585	0Eh	111x xxxx			
PIC18F2610	0Ch	101x xxxx			
PIC18F2620	0Ch	100x xxxx			
PIC18F2680	0Eh	110x xxxx			
PIC18F2682	27h	000x xxxx			
PIC18F2685	27h	001x xxxx			
PIC18F4221	21h	010x xxxx			
PIC18F4321	21h	000x xxxx			
PIC18F4410	10h	111x xxxx			
PIC18F4420	10h	110x xxxx(1)			
PIC18F4423	10h	110x xxxx(2)			
PIC18F4450	24h	000x xxxx			
PIC18F4455	12h	001x xxxx			
PIC18F4458	2Ah	001x xxxx			
PIC18F4480	1Ah	101x xxxx			
PIC18F4510	10h	101x xxxx			
PIC18F4515	0Ch	011x xxxx			
PIC18F4520	10h	100x xxxx(1)			
PIC18F4523	10h	100x xxxx (2)			
PIC18F4525	0Ch	010x xxxx			
PIC18F4550	12h	000x xxxx			
PIC18F4553	2Ah	000x xxxx			
PIC18F4580	1Ah	100x xxxx			

Legend: The 'x's in DEVID1 contain the device revision code.

Note 1: DEVID1 bit 4 is used to determine the device type (REV4 = 0).

2: DEVID1 bit 4 is used to determine the device type (REV4 = 1).

TABLE 5-2: DEVICE ID VALUES (CONTINUED)

Device	Device ID Value					
Device	DEVID2	DEVID1				
PIC18F4585	0Eh	101x xxxx				
PIC18F4610	0Ch	001x xxxx				
PIC18F4620	0Ch	000x xxxx				
PIC18F4680	0Eh	100x xxxx				
PIC18F4682	27h	010x xxxx				
PIC18F4685	27h	011x xxxx				

Legend: The 'x's in DEVID1 contain the device revision code.

Note 1: DEVID1 bit 4 is used to determine the device type (REV4 = 0).

2: DEVID1 bit 4 is used to determine the device type (REV4 = 1).

Bit Name	Configuration Words	Description					
IESO	CONFIG1H	 Internal External Switchover bit 1 = Internal External Switchover mode is enabled 0 = Internal External Switchover mode is disabled 					
FCMEN	CONFIG1H	Fail-Safe Clock Monitor Enable bit 1 = Fail-Safe Clock Monitor is enabled 0 = Fail-Safe Clock Monitor is disabled					
FOSC<3:0>	CONFIG1H	Oscillator Selection bits 11xx = External RC oscillator, CLKO function on RA6 101x = External RC oscillator, CLKO function on RA6 1001 = Internal RC oscillator, CLKO function on RA6 1000 = Internal RC oscillator, port function on RA6, port function on RA7 1010 = Internal RC oscillator, port function on RA6 0110 = HS oscillator, PLL is enabled (Clock Frequency = 4 x FOSC1) 0101 = EC oscillator, port function on RA6 0100 = EC oscillator, CLKO function on RA6 0011 = External RC oscillator, CLKO function on RA6 0011 = External RC oscillator, CLKO function on RA6 0011 = External RC oscillator, CLKO function on RA6 0010 = HS oscillator 0010 = XT oscillator 0000 = LP oscillator					
FOSC<3:0>	CONFIG1H	Oscillator Selection bits (PIC18F2455/2550/4455/4550, PIC18F2458/2553/4458/4553 and PIC18F2450/4450 devices only) 111x = HS oscillator, PLL is enabled, HS is used by USB 110x = HS oscillator, HS is used by USB 1011 = Internal oscillator, HS is used by USB 1010 = Internal oscillator, XT is used by USB 1001 = Internal oscillator, CLKO function on RA6, EC is used by USB 1010 = Internal oscillator, port function on RA6, EC is used by USB 1011 = EC oscillator, PLL is enabled, CLKO function on RA6, EC is used by USE 0110 = EC oscillator, PLL is enabled, port function on RA6, EC is used by USE 0110 = EC oscillator, CLKO function on RA6, EC is used by USE 0101 = EC oscillator, PLL is enabled, port function on RA6, EC is used by USE 0101 = EC oscillator, port function on RA6, EC is used by USE 0101 = EC oscillator, PLL is enabled, XT is used by USB 0102 = XT oscillator, PLL is enabled, XT is used by USB					
USBDIV	CONFIG1L	USB Clock Selection bit (PIC18F2455/2550/4455/4550, PIC18F2458/2553/4458/4553 and PIC18F2450/4450 devices only) Selects the clock source for full-speed USB operation: 1 = USB clock source comes from the 96 MHz PLL divided by 2 0 = USB clock source comes directly from the OSC1/OSC2 oscillator block; no divide					
CPUDIV<1:0> Note 1: The BE	CONFIG1L	CPU System Clock Selection bits (PIC18F2455/2550/4455/4550, PIC18F2458/2553/4458/4553 and PIC18F2450/4450 devices only) 11 = CPU system clock divided by 4 10 = CPU system clock divided by 3 01 = CPU system clock divided by 2 00 = No CPU system clock divide :0> and BBSIZ<2:1> bits, cannot be changed once any of the following					

TABLE 5-3: PIC18F2XXX/4XXX FAMILY BIT DESCRIPTIONS

Note 1: The BBSIZ bits, BBSIZ<1:0> and BBSIZ<2:1> bits, cannot be changed once any of the following code-protect bits are enabled: CPB or CP0, WRTB or WRT0, EBTRB or EBTR0.

2: Not available in PIC18FXX8X and PIC18F2450/4450 devices.

Bit Name	Configuration Words	Description
EBTR0	CONFIG7L	Table Read Protection bit (Block 0 code memory area)
		 1 = Block 0 is not protected from Table Reads executed in other blocks 0 = Block 0 is protected from Table Reads executed in other blocks
EBTRB	CONFIG7H	Table Read Protection bit (Boot Block memory area)
		 1 = Boot Block is not protected from Table Reads executed in other blocks 0 = Boot Block is protected from Table Reads executed in other blocks
DEV<10:3>	DEVID2	Device ID bits
		These bits are used with the DEV<2:0> bits in the DEVID1 register to identify part number.
DEV<2:0>	DEVID1	Device ID bits
		These bits are used with the DEV<10:3> bits in the DEVID2 register to identify part number.
REV<4:0>	DEVID1	Revision ID bits
		These bits are used to indicate the revision of the device. The REV4 bit is sometimes used to fully specify the device type.

TABLE 5-3: PIC18F2XXX/4XXX FAMILY BIT DESCRIPTIONS (CONTINUED)

Note 1: The BBSIZ bits, BBSIZ<1:0> and BBSIZ<2:1> bits, cannot be changed once any of the following code-protect bits are enabled: CPB or CP0, WRTB or WRT0, EBTRB or EBTR0.

2: Not available in PIC18FXX8X and PIC18F2450/4450 devices.

	•••													
	Configuration Word (CONFIGxx)													
Device	1L	1H	2L	2H	3L	3H	4L	4H	5L	5H	6L	6H	7L	7H
Device	Address (30000xh)													
	0h	1h	2h	3h	4h	5h	6h	7h	8h	9h	Ah	Bh	Ch	Dh
PIC18F4620	00	CF	1F	1F	00	87	C5	00	0F	C0	0F	E0	0F	40
PIC18F4680	00	CF	1F	1F	00	86	C5	00	0F	C0	0F	E0	0F	40
PIC18F4682	00	CF	1F	1F	00	86	C5	00	3F	C0	3F	E0	3F	40
PIC18F4685	00	CF	1F	1F	00	86	C5	00	3F	C0	3F	E0	3F	40

TABLE 5-5: CONFIGURATION WORD MASKS FOR COMPUTING CHECKSUMS (CONTINUED)

Legend: Shaded cells are unimplemented.

6.0 AC/DC CHARACTERISTICS TIMING REQUIREMENTS FOR PROGRAM/VERIFY TEST MODE

Param No.	Sym	Characteristic	Min	Max	Units	Conditions
D110	Vihh	High-Voltage Programming Voltage on MCLR/VPP/RE3	VDD + 4.0	12.5	V	(Note 2)
D110A	VIHL	Low-Voltage Programming Voltage on MCLR/VPP/RE3	2.00	5.50	V	(Note 2)
D111	Vdd	Supply Voltage During Programming	2.00	5.50	V	Externally timed, Row Erases and all writes
			3.0	5.50	V	Self-timed, Bulk Erases only (Note 3)
D112	IPP	Programming Current on MCLR/VPP/RE3	_	300	μA	(Note 2)
D113	IDDP	Supply Current During Programming	_	10	mA	
D031	VIL	Input Low Voltage	Vss	0.2 Vdd	V	
D041	Viн	Input High Voltage	0.8 Vdd	Vdd	V	
D080	Vol	Output Low Voltage	_	0.6	V	IOL = 8.5 mA @ 4.5V
D090	Vон	Output High Voltage	Vdd - 0.7	_	V	IOH = -3.0 mA @ 4.5V
D012	Сю	Capacitive Loading on I/O pin (PGD)		50	pF	To meet AC specifications
P1	Tr	MCLR/VPP/RE3 Rise Time to Enter Program/Verify mode	-	1.0	μS	(Notes 1, 2)
P2	TPGC	Serial Clock (PGC) Period	100	_	ns	VDD = 5.0V
			1		μS	VDD = 2.0V
P2A	TPGCL	Serial Clock (PGC) Low Time	40	_	ns	VDD = 5.0V
			400	_	ns	VDD = 2.0V
P2B	TPGCH	Serial Clock (PGC) High Time	40	_	ns	VDD = 5.0V
			400	_	ns	VDD = 2.0V
P3	TSET1	Input Data Setup Time to Serial Clock \downarrow	15	—	ns	
P4	THLD1	Input Data Hold Time from PGC \downarrow	15		ns	
P5	TDLY1	Delay Between 4-Bit Command and Command Operand	40	—	ns	
P5A	TDLY1A	Delay Between 4-Bit Command Operand and Next 4-Bit Command	40	_	ns	
P6	TDLY2	Delay Between Last PGC \downarrow of Command Byte to First PGC \uparrow of Read of Data Word	20	_	ns	
P9	TDLY5	PGC High Time (minimum programming time)	1	—	ms	Externally timed
P10	TDLY6	PGC Low Time After Programming (high-voltage discharge time)	100	—	μS	
P11	TDLY7	Delay to Allow Self-Timed Data Write or Bulk Erase to Occur	5	_	ms	

Note 1: Do not allow excess time when transitioning MCLR between VIL and VIHH. This can cause spurious program executions to occur. The maximum transition time is:

1 TCY + TPWRT (if enabled) + 1024 TOSC (for LP, HS, HS/PLL and XT modes only) +

2 ms (for HS/PLL mode only) + 1.5 μ s (for EC mode only)

where TCY is the instruction cycle time, TPWRT is the Power-up Timer period and TOSC is the oscillator period. For specific values, refer to the Electrical Characteristics section of the device data sheet for the particular device.

2: When ICPRT = 1, this specification also applies to ICVPP.

3: At 0°C-50°C.