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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

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Details

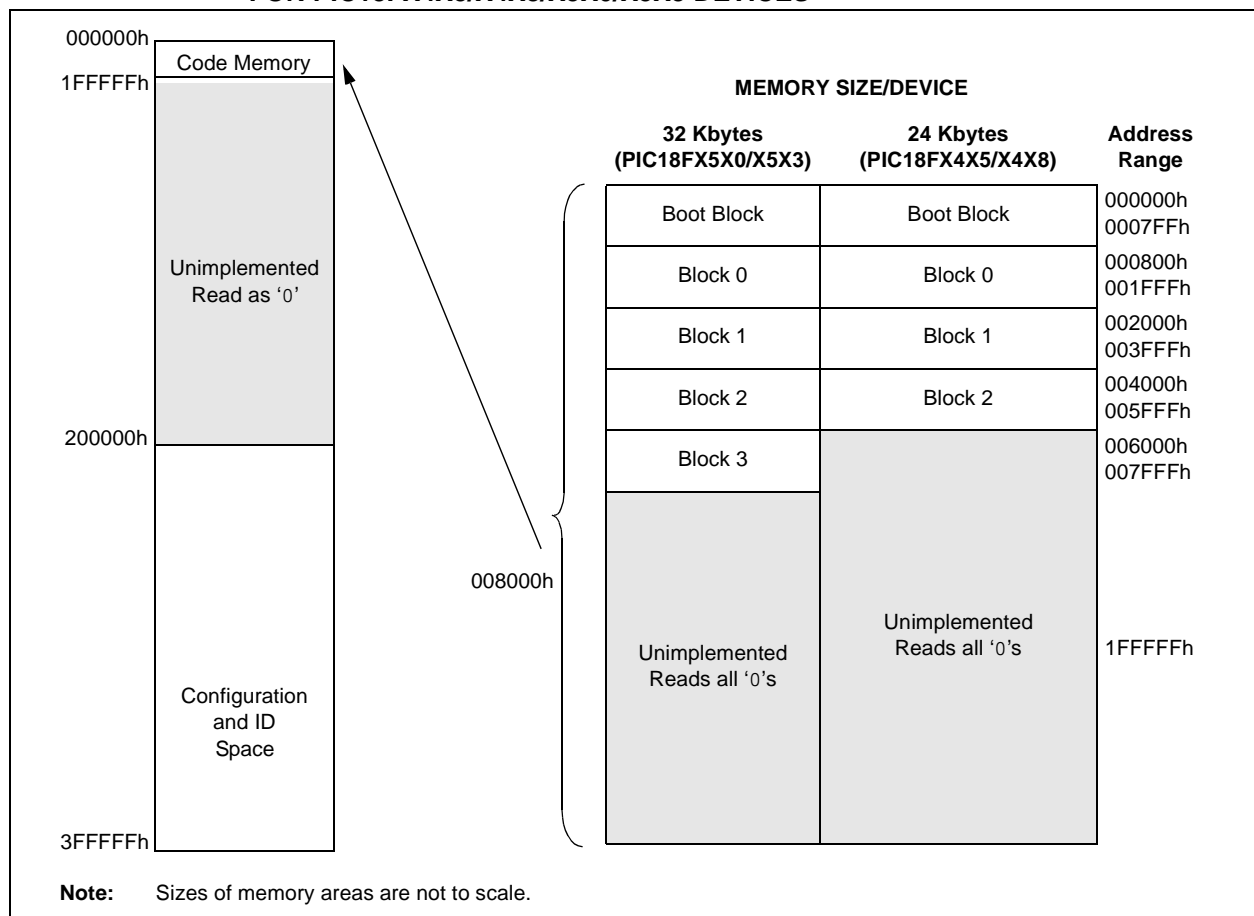
Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	25MHz
Connectivity	I ² C, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, HLVD, POR, PWM, WDT
Number of I/O	36
Program Memory Size	48KB (24K x 16)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	3.8K x 8
Voltage - Supply (Vcc/Vdd)	4.2V ~ 5.5V
Data Converters	A/D 13x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Through Hole
Package / Case	40-DIP (0.600", 15.24mm)
Supplier Device Package	40-PDIP
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic18f4515-e-p

PIC18F2XXX/4XXX FAMILY

TABLE 2-4: IMPLEMENTATION OF CODE MEMORY

Device	Code Memory Size (Bytes)
PIC18F2455	000000h-005FFFh (24K)
PIC18F2458	
PIC18F4455	
PIC18F4458	
PIC18F2510	000000h-007FFFh (32K)
PIC18F2520	
PIC18F2523	
PIC18F2550	
PIC18F2553	
PIC18F4510	
PIC18F4520	
PIC18F4523	
PIC18F4550	
PIC18F4553	

FIGURE 2-8: MEMORY MAP AND THE CODE MEMORY SPACE FOR PIC18FX4X5/X4X8/X5X0/X5X3 DEVICES



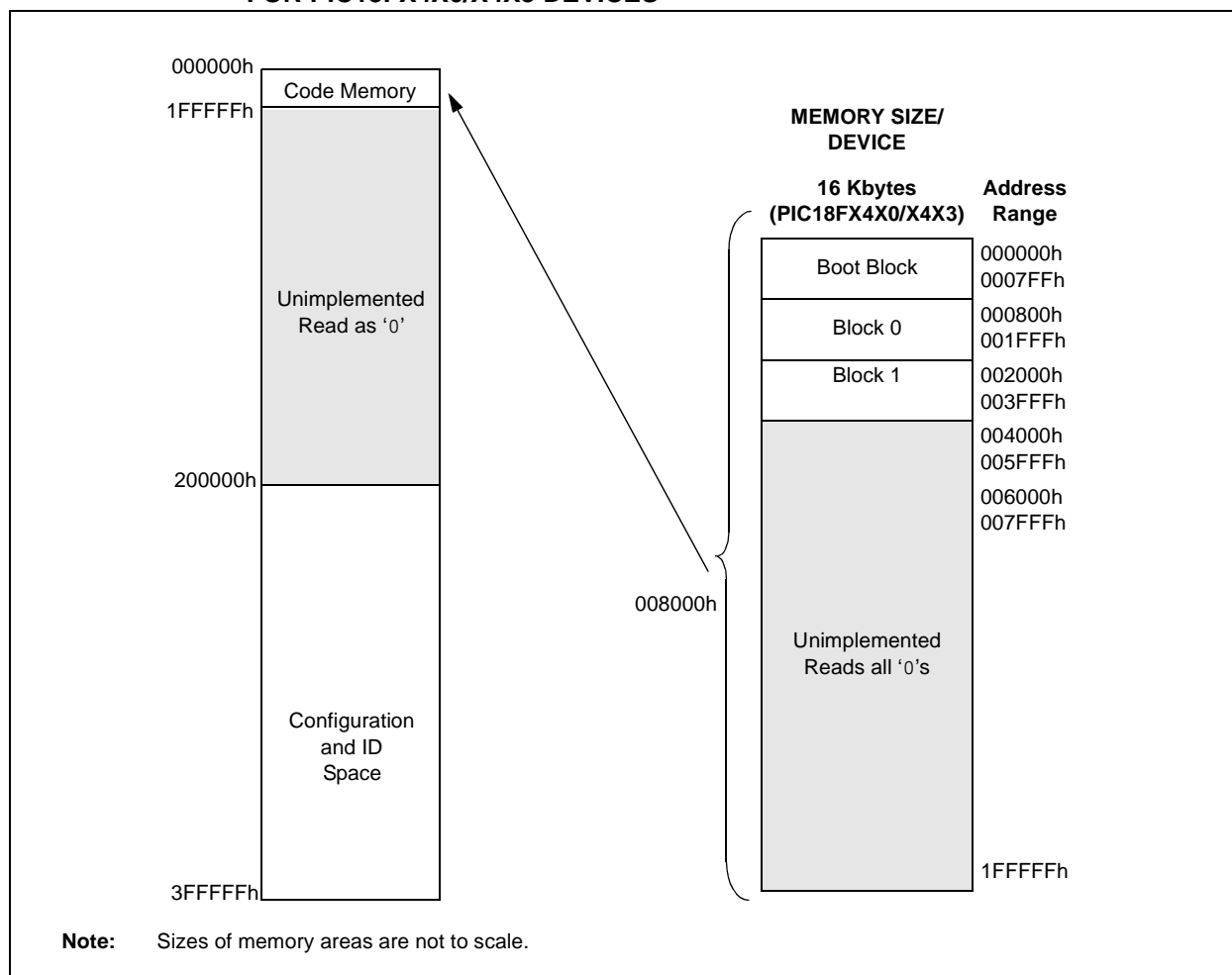
For PIC18FX4X0/X4X3 devices, the code memory space extends from 000000h to 003FFFh (16 Kbytes) in two 8-Kbyte blocks. Addresses, 000000h through 0003FFFh, however, define a "Boot Block" region that is treated separately from Block 0. All of these blocks define code protection boundaries within the code memory space.

PIC18F2XXX/4XXX FAMILY

TABLE 2-5: IMPLEMENTATION OF CODE MEMORY

Device	Code Memory Size (Bytes)
PIC18F2410	000000h-003FFFh (16K)
PIC18F2420	
PIC18F2423	
PIC18F2450	
PIC18F4410	
PIC18F4420	
PIC18F4450	

FIGURE 2-9: MEMORY MAP AND THE CODE MEMORY SPACE FOR PIC18FX4X0/X4X3 DEVICES



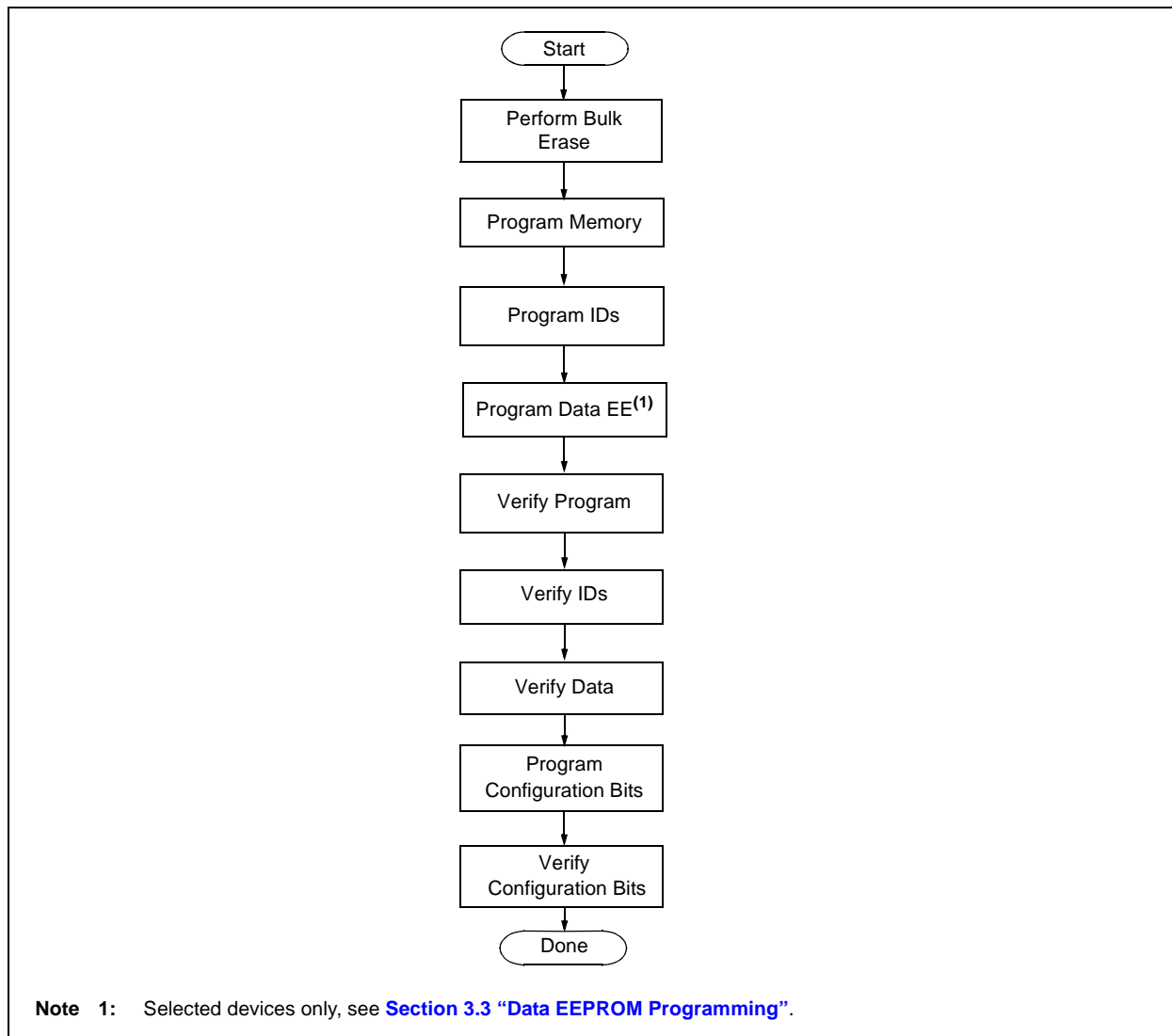
For PIC18F2480/4480 devices, the code memory space extends from 0000h to 03FFFh (16 Kbytes) in one 16-Kbyte block. For PIC18F2580/4580 devices, the code memory space extends from 0000h to 07FFFh (32 Kbytes) in two 16-Kbyte blocks. Addresses, 0000h through 07FFFh, however, define a “Boot Block” region that is treated separately from Block 0. All of these blocks define code protection boundaries within the code memory space.

The size of the Boot Block in PIC18F2480/2580/4480/4580 devices can be configured as 1 or 2K words (see [Figure 2-10](#)). This is done through the BBSIZ<0> bit in the Configuration register, CONFIG4L. It is important to note that increasing the size of the Boot Block decreases the size of Block 0.

2.4 High-Level Overview of the Programming Process

Figure 2-13 shows the high-level overview of the programming process. First, a Bulk Erase is performed. Next, the code memory, ID locations and data EEPROM are programmed (selected devices only, see [Section 3.3 “Data EEPROM Programming”](#)). These memories are then verified to ensure that programming was successful. If no errors are detected, the Configuration bits are then programmed and verified.

FIGURE 2-13: HIGH-LEVEL PROGRAMMING FLOW



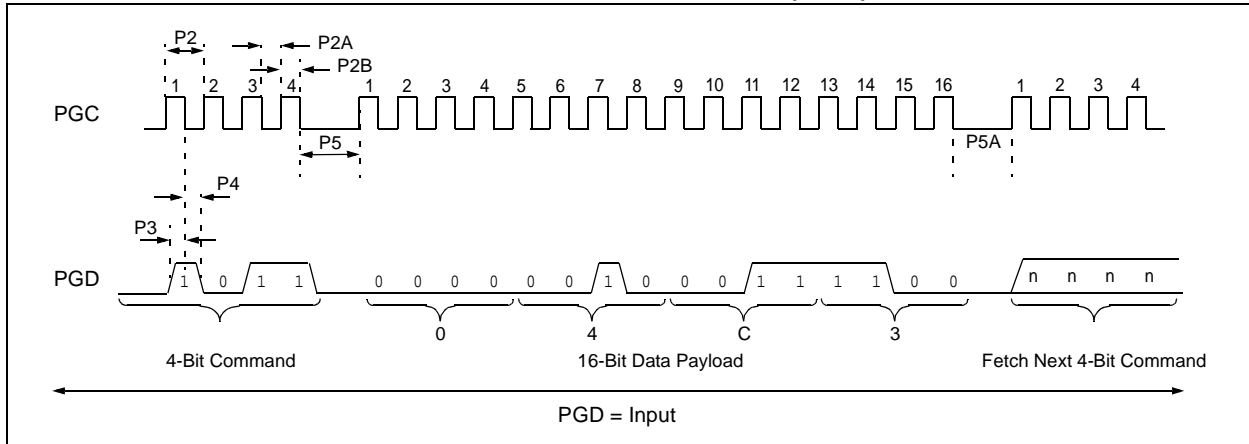
[illegible]

The sequence that enters the device into the Program/Verify mode places all unused I/Os in the high-impedance state.

Timing diagram for D110, MCLR/VPP/RE3, VDD, PGD, and PGC. The diagram shows the relationship between these signals during a programming sequence. Key timing parameters are indicated: P1 (pulse width of MCLR/VPP/RE3), P12 (time from VDD rise to PGD rise), and P13 (time from VDD rise to PGC start). A note indicates PGD = Input.

PIC18F2XXX/4XXX FAMILY

FIGURE 2-18: TABLE WRITE, POST-INCREMENT TIMING (1101)



2.8 Dedicated ICSP/ICD Port (44-Pin TQFP Only)

The PIC18F4455/4458/4550/4553 44-pin TQFP devices are designed to support an alternate programming input: the dedicated ICSP/ICD port. The primary purpose of this port is to provide an alternate In-Circuit Debugging (ICD) option and free the pins (RB6, RB7 and MCLR) that would normally be used for debugging the application. In conjunction with ICD capability, however, the dedicated ICSP/ICD port also provides an alternate port for ICSP.

Setting the ICPRT Configuration bit enables the dedicated ICSP/ICD port. The dedicated ICSP/ICD port functions the same as the default ICSP/ICD port; however, alternate pins are used instead of the default pins. Table 2-10 identifies the functionally equivalent pins for ICSP purposes:

The dedicated ICSP/ICD port is an alternate port. Thus, ICSP is still available through the default port even though the ICPRT Configuration bit is set. When the V_{IH} is seen on the MCLR/VPP/RE3 pin prior to applying V_{IH} to the ICRST/ICVPP pin, then the state of the ICRST/ICVPP pin is ignored. Likewise, when the V_{IH} is seen on ICRST/ICVPP prior to applying V_{IH} to MCLR/VPP/RE3, then the state of the MCLR/VPP/RE3 pin is ignored.

Note: The ICPRT Configuration bit can only be programmed through the default ICSP port. Chip Erase functions through the dedicated ICSP/ICD port do not affect this bit.

When the ICPRT Configuration bit is set (dedicated ICSP/ICD port enabled), the NC/ICPORTS pin must be tied to either VDD or VSS.

The ICPRT Configuration bit must be maintained clear for all 28-pin and 40-pin devices; otherwise, unexpected operation may occur.

TABLE 2-10: ICSP™ EQUIVALENT PINS

Pin Name	During Programming			
	Pin Name	Pin Type	Dedicated Pins	Pin Description
MCLR/VPP/RE3	VPP	P	NC/ICRST/ICVPP	Programming Enable
RB6	PGC	I	NC/ICCK/ICPGC	Serial Clock
RB7	PGD	I/O	NC/ICDT/ICPGD	Serial Data

Legend: I = Input, O = Output, P = Power

PIC18F2XXX/4XXX FAMILY

3.0 DEVICE PROGRAMMING

Programming includes the ability to erase or write the various memory regions within the device.

In all cases, except high-voltage ICSP Bulk Erase, the EECON1 register must be configured in order to operate on a particular memory region.

When using the EECON1 register to act on code memory, the EEPGD bit must be set (EECON1<7> = 1) and the CFGS bit must be cleared (EECON1<6> = 0). The WREN bit must be set (EECON1<2> = 1) to enable writes of any sort (e.g., erases) and this must be done prior to initiating a write sequence. The FREE bit must be set (EECON1<4> = 1) in order to erase the program space being pointed to by the Table Pointer. The erase or write sequence is initiated by setting the WR bit (EECON1<1> = 1). It is strongly recommended that the WREN bit only be set immediately prior to a program erase.

3.1 ICSP Erase

3.1.1 HIGH-VOLTAGE ICSP BULK ERASE

Erasing code or data EEPROM is accomplished by configuring two Bulk Erase Control registers located at 3C0004h and 3C0005h. Code memory may be erased, portions at a time, or the user may erase the entire device in one action. Bulk Erase operations will also clear any code-protect settings associated with the memory block being erased. Erase options are detailed in [Table 3-1](#). If data EEPROM is code-protected (CPD = 0), the user must request an erase of data EEPROM (e.g., 0084h as shown in [Table 3-1](#)).

TABLE 3-1: BULK ERASE OPTIONS

Description	Data (3C0005h:3C0004h)
Chip Erase	3F8Fh
Erase Data EEPROM ⁽¹⁾	0084h
Erase Boot Block	0081h
Erase Configuration Bits	0082h
Erase Code EEPROM Block 0	0180h
Erase Code EEPROM Block 1	0280h
Erase Code EEPROM Block 2	0480h
Erase Code EEPROM Block 3	0880h
Erase Code EEPROM Block 4	1080h
Erase Code EEPROM Block 5	2080h

Note 1: Selected devices only, see [Section 3.3 “Data EEPROM Programming”](#).

The actual Bulk Erase function is a self-timed operation. Once the erase has started (falling edge of the 4th PGC after the NOP command), serial execution will cease until the erase completes (Parameter P11). During this time, PGC may continue to toggle but PGD must be held low.

The code sequence to erase the entire device is shown in [Table](#) and the flowchart is shown in [Figure 3-1](#).

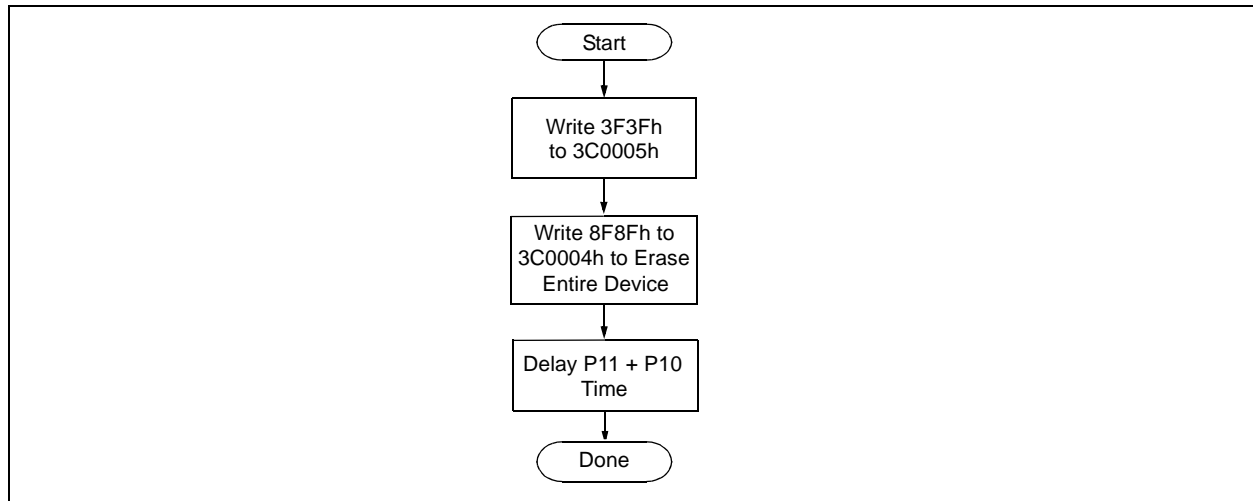
Note: A Bulk Erase is the only way to reprogram code-protect bits from an ON state to an OFF state.

PIC18F2XXX/4XXX FAMILY

TABLE 3-2: BULK ERASE COMMAND SEQUENCE

4-Bit Command	Data Payload	Core Instruction
0000	0E 3C	MOVLW 3Ch
0000	6E F8	MOVWF TBLPTRU
0000	0E 00	MOVLW 00h
0000	6E F7	MOVWF TBLPTRH
0000	0E 05	MOVLW 05h
0000	6E F6	MOVWF TBLPTRL
1100	3F 3F	Write 3F3Fh to 3C0005h
0000	0E 3C	MOVLW 3Ch
0000	6E F8	MOVWF TBLPTRU
0000	0E 00	MOVLW 00h
0000	6E F7	MOVWF TBLPTRH
0000	0E 04	MOVLW 04h
0000	6E F6	MOVWF TBLPTRL
1100	8F 8F	Write 8F8Fh TO 3C0004h to erase entire device.
		NOP
		Hold PGD low until erase completes.
0000	00 00	
0000	00 00	

FIGURE 3-1: BULK ERASE FLOW

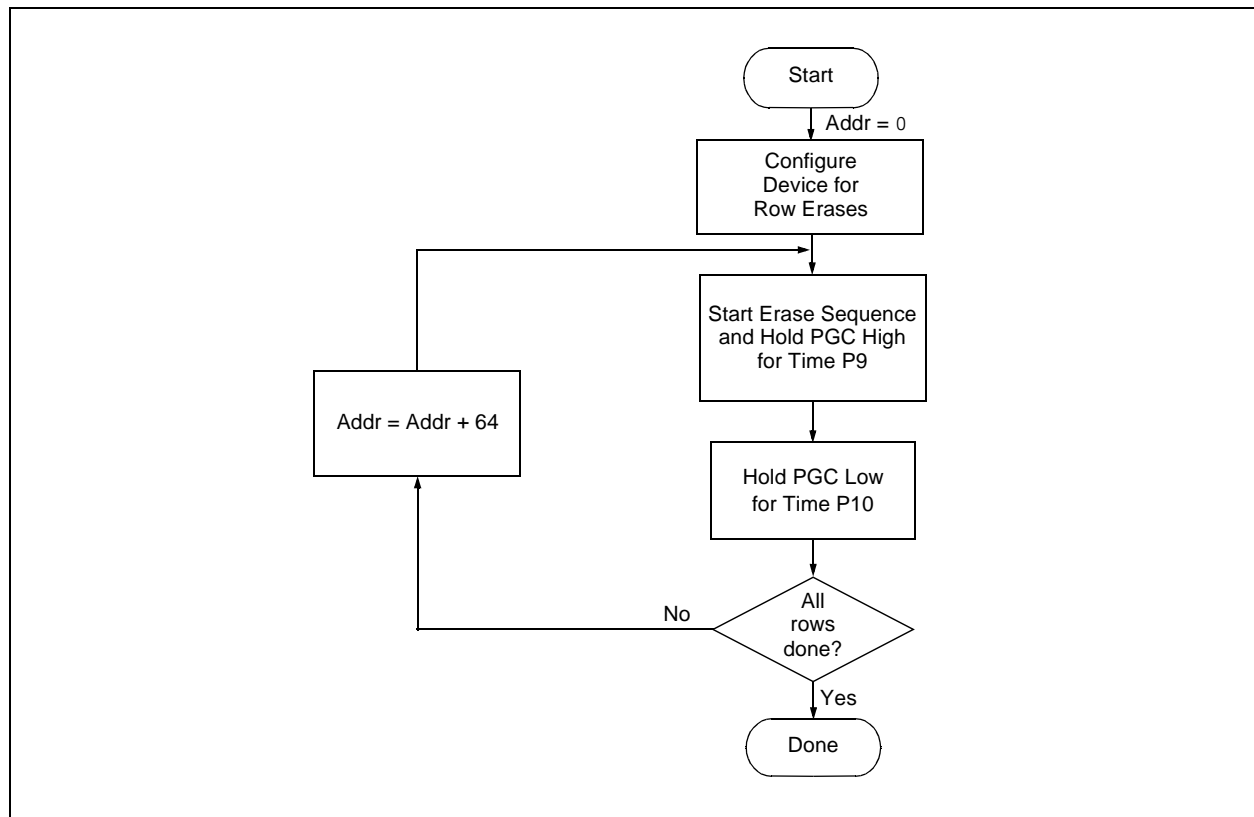


PIC18F2XXX/4XXX FAMILY

TABLE 3-3: ERASE CODE MEMORY CODE SEQUENCE

4-Bit Command	Data Payload	Core Instruction
Step 1: Direct access to code memory and enable writes.		
0000	8E A6	BSF EECON1, EEPGD
0000	9C A6	BCF EECON1, CFGS
0000	84 A6	BSF EECON1, WREN
Step 2: Point to first row in code memory.		
0000	6A F8	CLRF TBLPTRU
0000	6A F7	CLRF TBLPTRH
0000	6A F6	CLRF TBLPTRL
Step 3: Enable erase and erase single row.		
0000	88 A6	BSF EECON1, FREE
0000	82 A6	BSF EECON1, WR
0000	00 00	NOP - hold PGC high for time P9 and low for time P10.
Step 4: Repeat Step 3, with the Address Pointer incremented by 64 until all rows are erased.		

FIGURE 3-3: SINGLE ROW ERASE CODE MEMORY FLOW



PIC18F2XXX/4XXX FAMILY

3.2 Code Memory Programming

Programming code memory is accomplished by first loading data into the write buffer and then initiating a programming sequence. The write and erase buffer sizes, shown in [Table 3-4](#), can be mapped to any location of the same size, beginning at 000000h. The actual memory write sequence takes the contents of this buffer and programs the proper amount of code memory that contains the Table Pointer.

The programming duration is externally timed and is controlled by PGC. After a Start Programming command is issued (4-bit command, '1111'), a NOP is issued, where the 4th PGC is held high for the duration of the programming time, P9.

After PGC is brought low, the programming sequence is terminated. PGC must be held low for the time specified by Parameter P10 to allow high-voltage discharge of the memory array.

The code sequence to program a PIC18F2XXX/4XXX Family device is shown in [Table 3-5](#). The flowchart, shown in [Figure 3-4](#), depicts the logic necessary to completely write a PIC18F2XXX/4XXX Family device. The timing diagram that details the Start Programming command and Parameters P9 and P10 is shown in [Figure 3-5](#).

Note: The TBLPTR register must point to the same region when initiating the programming sequence as it did when the write buffers were loaded.

TABLE 3-4: WRITE AND ERASE BUFFER SIZES

Devices (Arranged by Family)	Write Buffer Size (Bytes)	Erase Buffer Size (Bytes)
PIC18F2221, PIC18F2321, PIC18F4221, PIC18F4321	8	64
PIC18F2450, PIC18F4450	16	64
PIC18F2410, PIC18F2510, PIC18F4410, PIC18F4510	32	64
PIC18F2420, PIC18F2520, PIC18F4420, PIC18F4520		
PIC18F2423, PIC18F2523, PIC18F4423, PIC18F4523		
PIC18F2480, PIC18F2580, PIC18F4480, PIC18F4580		
PIC18F2455, PIC18F2550, PIC18F4455, PIC18F4550		
PIC18F2458, PIC18F2553, PIC18F4458, PIC18F4553		
PIC18F2515, PIC18F2610, PIC18F4515, PIC18F4610	64	64
PIC18F2525, PIC18F2620, PIC18F4525, PIC18F4620		
PIC18F2585, PIC18F2680, PIC18F4585, PIC18F4680		
PIC18F2682, PIC18F2685, PIC18F4682, PIC18F4685		

PIC18F2XXX/4XXX FAMILY

TABLE 3-5: WRITE CODE MEMORY CODE SEQUENCE

4-Bit Command	Data Payload	Core Instruction
Step 1: Direct access to code memory and enable writes.		
0000	8E A6	BSF EECON1, EEPGD
0000	9C A6	BCF EECON1, CFGS
Step 2: Load write buffer.		
0000	0E <Addr[21:16]>	MOVLW <Addr[21:16]>
0000	6E F8	MOVWF TBLPTRU
0000	0E <Addr[15:8]>	MOVLW <Addr[15:8]>
0000	6E F7	MOVWF TBLPTRH
0000	0E <Addr[7:0]>	MOVLW <Addr[7:0]>
0000	6E F6	MOVWF TBLPTRL
Step 3: Repeat for all but the last two bytes.		
1101	<MSB><LSB>	Write 2 bytes and post-increment address by 2.
Step 4: Load write buffer for last two bytes.		
1111	<MSB><LSB>	Write 2 bytes and start programming.
0000	00 00	NOP - hold PGC high for time P9 and low for time P10.
To continue writing data, repeat Steps 2 through 4, where the Address Pointer is incremented by 2 at each iteration of the loop.		

PIC18F2XXX/4XXX FAMILY

FIGURE 3-4: PROGRAM CODE MEMORY FLOW

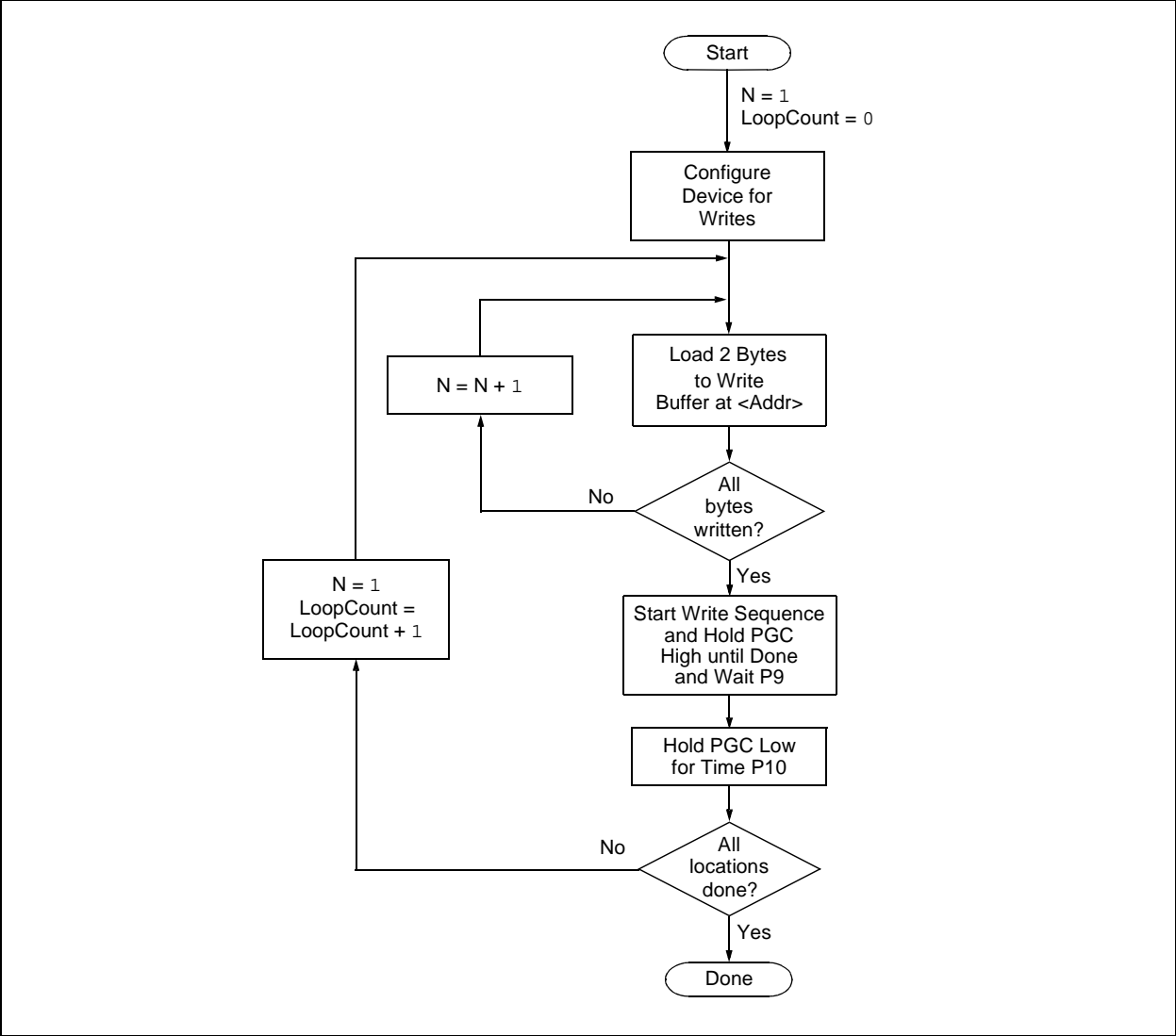
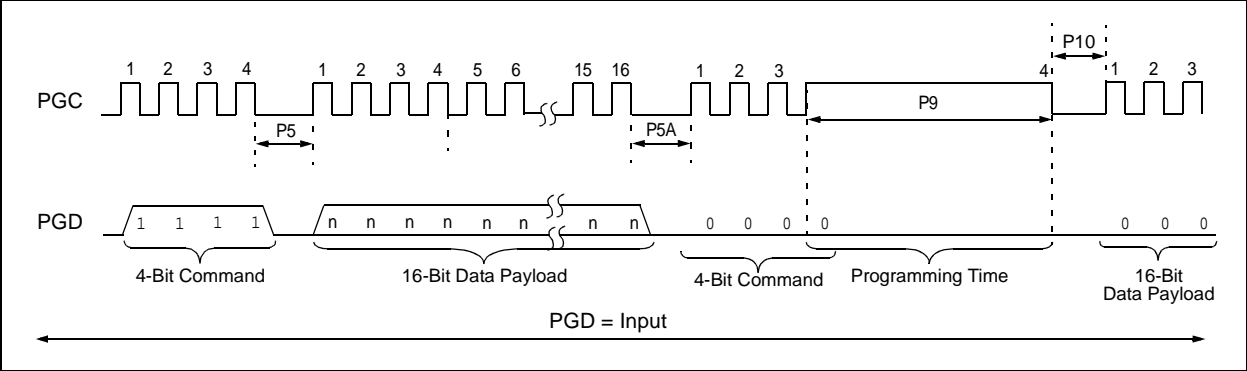


FIGURE 3-5: TABLE WRITE AND START PROGRAMMING INSTRUCTION TIMING (1111)



PIC18F2XXX/4XXX FAMILY

3.3 Data EEPROM Programming

Note: Data EEPROM programming is not available on the following devices:	
PIC18F2410	PIC18F4410
PIC18F2450	PIC18F4450
PIC18F2510	PIC18F4510
PIC18F2515	PIC18F4515
PIC18F2610	PIC18F4610

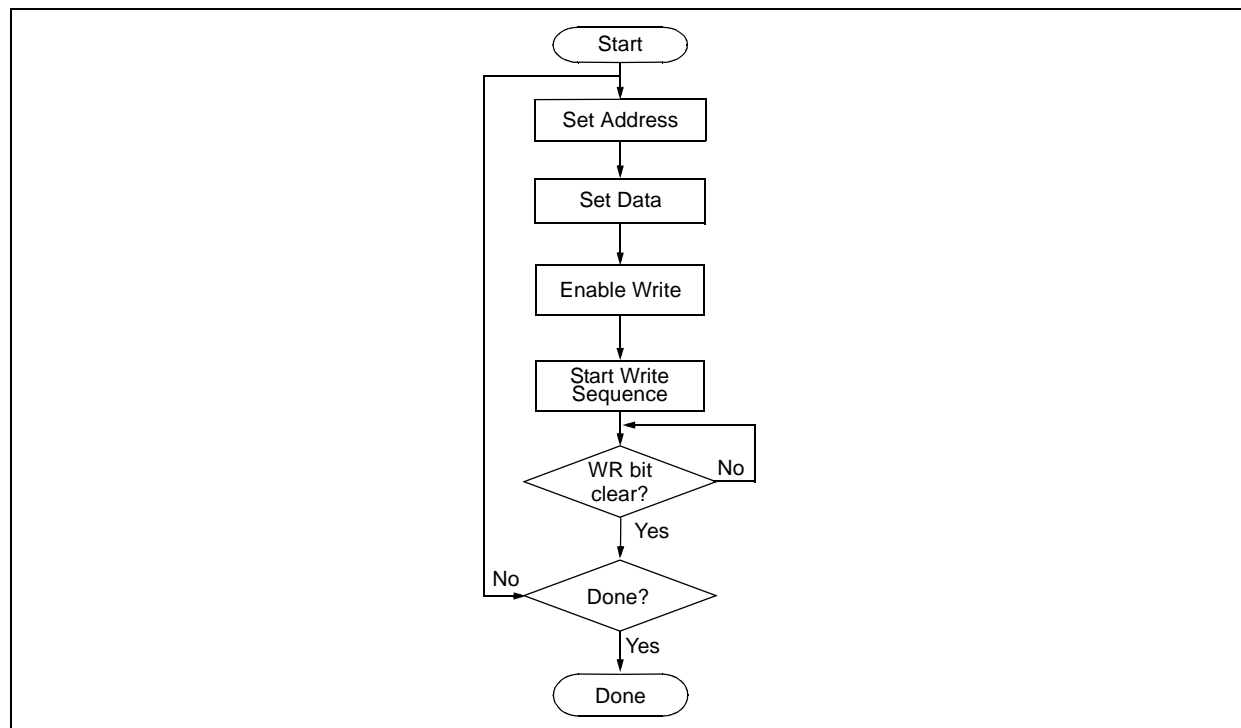
Data EEPROM is accessed one byte at a time via an Address Pointer (register pair: EEADRH:EEADR) and a data latch (EEDATA). Data EEPROM is written by loading EEADRH:EEADR with the desired memory location, EEDATA, with the data to be written and initiating a memory write by appropriately configuring the EECON1 register. A byte write automatically erases the location and writes the new data (erase-before-write).

When using the EECON1 register to perform a data EEPROM write, both the EEPGD and CFGS bits must be cleared (EECON1<7:6> = 00). The WREN bit must be set (EECON1<2> = 1) to enable writes of any sort and this must be done prior to initiating a write sequence. The write sequence is initiated by setting the WR bit (EECON1<1> = 1).

The write begins on the falling edge of the 4th PGC after the WR bit is set. It ends when the WR bit is cleared by hardware.

After the programming sequence terminates, PGC must still be held low for the time specified by Parameter P10 to allow high-voltage discharge of the memory array.

FIGURE 3-6: PROGRAM DATA FLOW



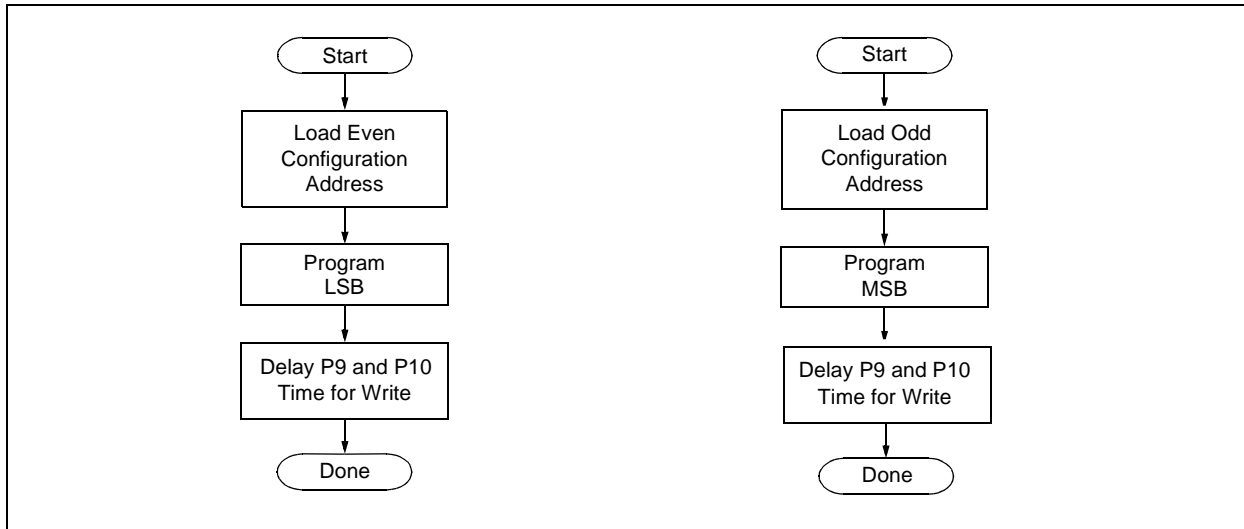
PIC18F2XXX/4XXX FAMILY

TABLE 3-9: SET ADDRESS POINTER TO CONFIGURATION LOCATION

4-Bit Command	Data Payload	Core Instruction
Step 1: Enable writes and direct access to configuration memory.		
0000	8E A6	BSF EECON1, EEPGD
0000	8C A6	BSF EECON1, CFGS
Step 2: Set Table Pointer for configuration byte to be written. Write even/odd addresses. ⁽¹⁾		
0000	0E 30	MOVLW 30h
0000	6E F8	MOVWF TBLPTRU
0000	0E 00	MOVLW 00h
0000	6E F7	MOVWF TBLPRTH
0000	0E 00	MOVLW 00h
0000	6E F6	MOVWF TBLPTRL
1111	<MSB ignored><LSB>	Load 2 bytes and start programming.
0000	00 00	NOP - hold PGC high for time P9 and low for time P10.
0000	0E 01	MOVLW 01h
0000	6E F6	MOVWF TBLPTRL
1111	<MSB><LSB ignored>	Load 2 bytes and start programming.
0000	00 00	NOP - hold PGC high for time P9 and low for time P10.

Note 1: Enabling the write protection of Configuration bits (WRTC = 0 in CONFIG6H) will prevent further writing of the Configuration bits. Always write all the Configuration bits before enabling the write protection for Configuration bits.

FIGURE 3-8: CONFIGURATION PROGRAMMING FLOW



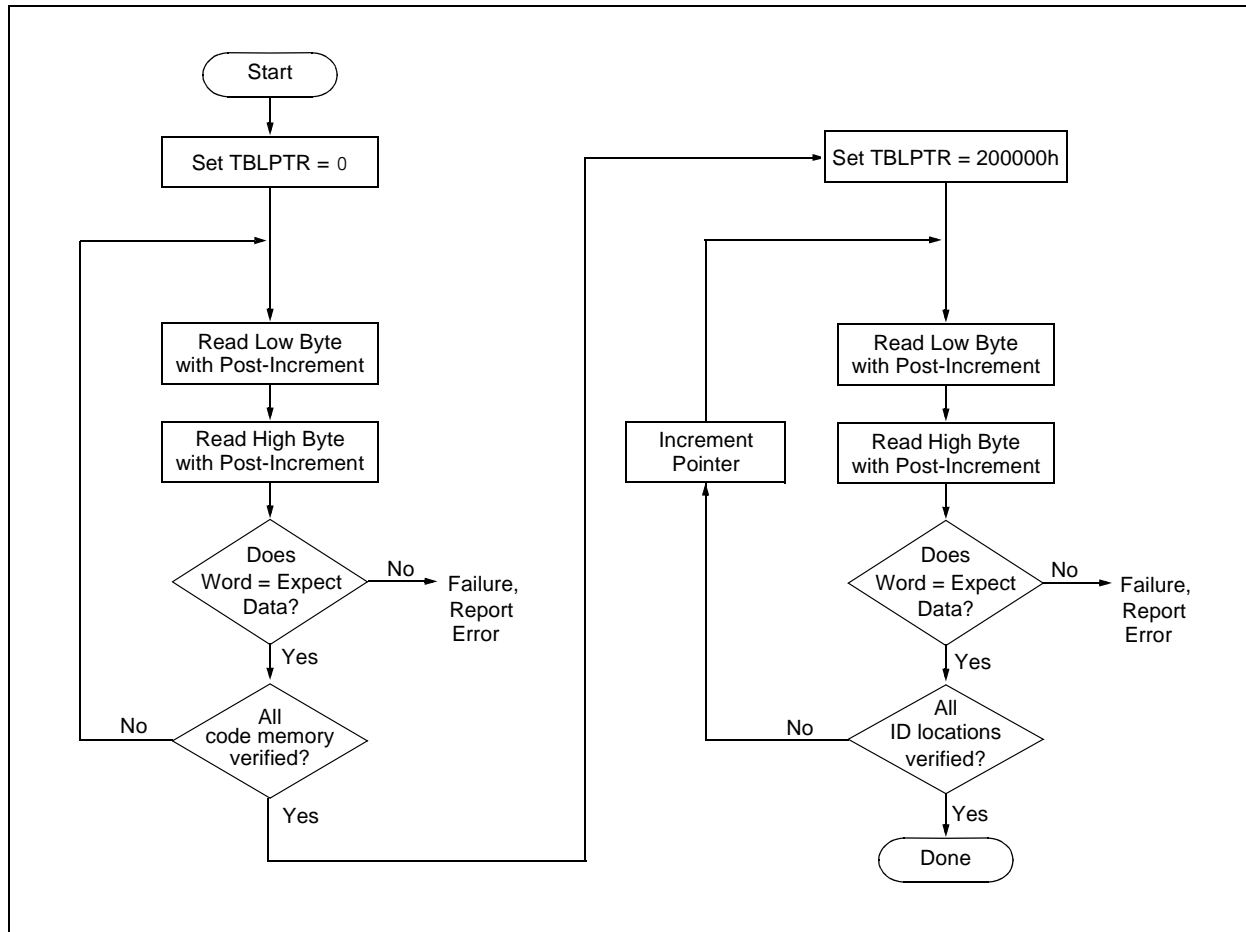
PIC18F2XXX/4XXX FAMILY

4.2 Verify Code Memory and ID Locations

The verify step involves reading back the code memory space and comparing it against the copy held in the programmer's buffer. Memory reads occur a single byte at a time, so two bytes must be read to compare against the word in the programmer's buffer. Refer to [Section 4.1 "Read Code Memory, ID Locations and Configuration Bits"](#) for implementation details of reading code memory.

The Table Pointer must be manually set to 200000h (base address of the ID locations) once the code memory has been verified. The post-increment feature of the Table Read 4-bit command may not be used to increment the Table Pointer beyond the code memory space. In a 64-Kbyte device, for example, a post-increment read of address, FFFFh, will wrap the Table Pointer back to 000000h, rather than point to the unimplemented address, 010000h.

FIGURE 4-2: VERIFY CODE MEMORY FLOW



4.3 Verify Configuration Bits

A configuration address may be read and output on PGD via the 4-bit command, '1001'. Configuration data is read and written in a byte-wise fashion, so it is not necessary to merge two bytes into a word prior to a compare. The result may then be immediately compared to the appropriate configuration data in the programmer's memory for verification. Refer to [Section 4.1 "Read Code Memory, ID Locations and Configuration Bits"](#) for implementation details of reading configuration data.

PIC18F2XXX/4XXX FAMILY

TABLE 5-1: CONFIGURATION BITS AND DEVICE IDS

File Name		Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Default/ Unprogrammed Value
300000h ^(1,8)	CONFIG1L	—	—	USBDIV	CPUDIV1	CPUDIV0	PLLDIV2	PLLDIV1	PLLDIV0	--00 0000
300001h	CONFIG1H	IESO	FCMEN	—	—	FOSC3	FOSC2	FOSC1	FOSC0	00-- 0111 00-- 0101 ^(1,8)
300002h	CONFIG2L	—	—	— VREGEN ^(1,8)	BORV1	BORV0	BOREN1	BOREN0	PWRTEN	---1 1111 --01 1111 ^(1,8)
300003h	CONFIG2H	—	—	—	WDTPS3	WDTPS2	WDTPS1	WDTPS0	WDTEN	---1 1111
300005h	CONFIG3H	MCLRE	—	—	—	—	LPT1OSC	PBADEN	CCP2MX ⁽⁷⁾	1--- -011 ⁽⁷⁾ 1--- -01-
300006h	CONFIG4L	DEBUG	XINST	ICPRT ⁽¹⁾	—	—	LVP	—	STVREN	100- -1-1 ⁽¹⁾ 1000 -1-1 10-0 -1-1 ⁽³⁾ 100- 01-1 ⁽⁸⁾ 1000 -1-1 ⁽²⁾
				BBSIZ1	BBSIZ0	—				
				—	BBSIZ ⁽³⁾	—				
				ICPRT ⁽⁸⁾	—	BBSIZ ⁽⁸⁾				
				BBSIZ1 ⁽²⁾	BBSIZ2 ⁽²⁾	—				
300008h	CONFIG5L	—	—	CP5 ⁽¹⁰⁾	CP4 ⁽⁹⁾	CP3 ⁽⁴⁾	CP2 ⁽⁴⁾	CP1	CP0	--11 1111
300009h	CONFIG5H	CPD	CPB	—	—	—	—	—	—	11-- ----
30000Ah	CONFIG6L	—	—	WRT5 ⁽¹⁰⁾	WRT4 ⁽⁹⁾	WRT3 ⁽⁴⁾	WRT2 ⁽⁴⁾	WRT1	WRT0	--11 1111
30000Bh	CONFIG6H	WRTD	WRTB	WRTC ⁽⁵⁾	—	—	—	—	—	111- ----
30000Ch	CONFIG7L	—	—	EBTR5 ⁽¹⁰⁾	EBTR4 ⁽⁹⁾	EBTR3 ⁽⁴⁾	EBTR2 ⁽⁴⁾	EBTR1	EBTR0	--11 1111
30000Dh	CONFIG7H	—	EBTRB	—	—	—	—	—	—	-1-- ----
3FFFFEh	DEVID1 ⁽⁶⁾	DEV2	DEV1	DEV0	REV4	REV3	REV2	REV1	REV0	See Table 5-2
3FFFFFh	DEVID2 ⁽⁶⁾	DEV10	DEV9	DEV8	DEV7	DEV6	DEV5	DEV4	DEV3	See Table 5-2

Legend: — = unimplemented. Shaded cells are unimplemented, read as '0'.

Note 1: Implemented only on PIC18F2455/2550/4455/4550 and PIC18F2458/2553/4458/4553 devices.

2: Implemented on PIC18F2585/2680/4585/4680, PIC18F2682/2685 and PIC18F4682/4685 devices only.

3: Implemented on PIC18F2480/2580/4480/4580 devices only.

4: These bits are only implemented on specific devices based on available memory. Refer to [Section 2.3 "Memory Maps"](#).

5: In PIC18F2480/2580/4480/4580 devices, this bit is read-only in Normal Execution mode; it can be written only in Program mode.

6: DEVID registers are read-only and cannot be programmed by the user.

7: Implemented on all devices with the exception of the PIC18FXX8X and PIC18F2450/4450 devices.

8: Implemented on PIC18F2450/4450 devices only.

9: Implemented on PIC18F2682/2685 and PIC18F4682/4685 devices only.

10: Implemented on PIC18F2685/4685 devices only.

PIC18F2XXX/4XXX FAMILY

TABLE 5-2: DEVICE ID VALUES (CONTINUED)

Device	Device ID Value	
	DEVID2	DEVID1
PIC18F4585	0Eh	101x xxxx
PIC18F4610	0Ch	001x xxxx
PIC18F4620	0Ch	000x xxxx
PIC18F4680	0Eh	100x xxxx
PIC18F4682	27h	010x xxxx
PIC18F4685	27h	011x xxxx

Legend: The 'x's in DEVID1 contain the device revision code.

Note 1: DEVID1 bit 4 is used to determine the device type (REV4 = 0).

2: DEVID1 bit 4 is used to determine the device type (REV4 = 1).

PIC18F2XXX/4XXX FAMILY

TABLE 5-3: PIC18F2XXX/4XXX FAMILY BIT DESCRIPTIONS

Bit Name	Configuration Words	Description
IESO	CONFIG1H	Internal External Switchover bit 1 = Internal External Switchover mode is enabled 0 = Internal External Switchover mode is disabled
FCMEN	CONFIG1H	Fail-Safe Clock Monitor Enable bit 1 = Fail-Safe Clock Monitor is enabled 0 = Fail-Safe Clock Monitor is disabled
FOSC<3:0>	CONFIG1H	Oscillator Selection bits 11xx = External RC oscillator, CLKO function on RA6 101x = External RC oscillator, CLKO function on RA6 1001 = Internal RC oscillator, CLKO function on RA6, port function on RA7 1000 = Internal RC oscillator, port function on RA6, port function on RA7 0111 = External RC oscillator, port function on RA6 0110 = HS oscillator, PLL is enabled (Clock Frequency = 4 x FOSC1) 0101 = EC oscillator, port function on RA6 0100 = EC oscillator, CLKO function on RA6 0011 = External RC oscillator, CLKO function on RA6 0010 = HS oscillator 0001 = XT oscillator 0000 = LP oscillator
FOSC<3:0>	CONFIG1H	Oscillator Selection bits (PIC18F2455/2550/4455/4550, PIC18F2458/2553/4458/4553 and PIC18F2450/4450 devices only) 111x = HS oscillator, PLL is enabled, HS is used by USB 110x = HS oscillator, HS is used by USB 1011 = Internal oscillator, HS is used by USB 1010 = Internal oscillator, XT is used by USB 1001 = Internal oscillator, CLKO function on RA6, EC is used by USB 1000 = Internal oscillator, port function on RA6, EC is used by USB 0111 = EC oscillator, PLL is enabled, CLKO function on RA6, EC is used by USB 0110 = EC oscillator, PLL is enabled, port function on RA6, EC is used by USB 0101 = EC oscillator, CLKO function on RA6, EC is used by USB 0100 = EC oscillator, port function on RA6, EC is used by USB 001x = XT oscillator, PLL is enabled, XT is used by USB 000x = XT oscillator, XT is used by USB
USBDIV	CONFIG1L	USB Clock Selection bit (PIC18F2455/2550/4455/4550, PIC18F2458/2553/4458/4553 and PIC18F2450/4450 devices only) Selects the clock source for full-speed USB operation: 1 = USB clock source comes from the 96 MHz PLL divided by 2 0 = USB clock source comes directly from the OSC1/OSC2 oscillator block; no divide
CPUDIV<1:0>	CONFIG1L	CPU System Clock Selection bits (PIC18F2455/2550/4455/4550, PIC18F2458/2553/4458/4553 and PIC18F2450/4450 devices only) 11 = CPU system clock divided by 4 10 = CPU system clock divided by 3 01 = CPU system clock divided by 2 00 = No CPU system clock divide

Note 1: The BBSIZ bits, BBSIZ<1:0> and BBSIZ<2:1> bits, cannot be changed once any of the following code-protect bits are enabled: CPB or CP0, WRTB or WRT0, EBTRB or EBTR0.

2: Not available in PIC18FXX8X and PIC18F2450/4450 devices.

PIC18F2XXX/4XXX FAMILY

TABLE 5-5: CONFIGURATION WORD MASKS FOR COMPUTING CHECKSUMS

Device	Configuration Word (CONFIGxx)													
	1L	1H	2L	2H	3L	3H	4L	4H	5L	5H	6L	6H	7L	7H
	Address (30000xh)													
	0h	1h	2h	3h	4h	5h	6h	7h	8h	9h	Ah	Bh	Ch	Dh
PIC18F2221	00	CF	1F	1F	00	87	F5	00	03	C0	03	E0	03	40
PIC18F2321	00	CF	1F	1F	00	87	F5	00	03	C0	03	E0	03	40
PIC18F2410	00	CF	1F	1F	00	87	C5	00	03	C0	03	E0	03	40
PIC18F2420	00	CF	1F	1F	00	87	C5	00	03	C0	03	E0	03	40
PIC18F2423	00	CF	1F	1F	00	87	C5	00	03	C0	03	E0	03	40
PIC18F2450	3F	CF	3F	1F	00	86	ED	00	03	40	03	60	03	40
PIC18F2455	3F	CF	3F	1F	00	87	E5	00	07	C0	07	E0	07	40
PIC18F2458	3F	CF	3F	1F	00	87	E5	00	07	C0	07	E0	07	40
PIC18F2480	00	CF	1F	1F	00	86	D5	00	03	C0	03	E0	03	40
PIC18F2510	00	1F	1F	1F	00	87	C5	00	0F	C0	0F	E0	0F	40
PIC18F2515	00	CF	1F	1F	00	87	C5	00	0F	C0	0F	E0	0F	40
PIC18F2520	00	CF	1F	1F	00	87	C5	00	0F	C0	0F	E0	0F	40
PIC18F2523	00	CF	1F	1F	00	87	C5	00	0F	C0	0F	E0	0F	40
PIC18F2525	00	CF	1F	1F	00	87	C5	00	0F	C0	0F	E0	0F	40
PIC18F2550	3F	CF	3F	1F	00	87	E5	00	0F	C0	0F	E0	0F	40
PIC18F2553	3F	CF	3F	1F	00	87	E5	00	0F	C0	0F	E0	0F	40
PIC18F2580	00	CF	1F	1F	00	86	D5	00	0F	C0	0F	E0	0F	40
PIC18F2585	00	CF	1F	1F	00	86	C5	00	0F	C0	0F	E0	0F	40
PIC18F2610	00	CF	1F	1F	00	87	C5	00	0F	C0	0F	E0	0F	40
PIC18F2620	00	CF	1F	1F	00	87	C5	00	0F	C0	0F	E0	0F	40
PIC18F2680	00	CF	1F	1F	00	86	C5	00	0F	C0	0F	E0	0F	40
PIC18F2682	00	CF	1F	1F	00	86	C5	00	3F	C0	3F	E0	3F	40
PIC18F2685	00	CF	1F	1F	00	86	C5	00	3F	C0	3F	E0	3F	40
PIC18F4221	00	CF	1F	1F	00	87	F5	00	03	C0	03	E0	03	40
PIC18F4321	00	CF	1F	1F	00	87	F5	00	03	C0	03	E0	03	40
PIC18F4410	00	CF	1F	1F	00	87	C5	00	03	C0	03	E0	03	40
PIC18F4420	00	CF	1F	1F	00	87	C5	00	03	C0	03	E0	03	40
PIC18F4423	00	CF	1F	1F	00	87	C5	00	03	C0	03	E0	03	40
PIC18F4450	3F	CF	3F	1F	00	86	ED	00	03	40	03	60	03	40
PIC18F4455	3F	CF	3F	1F	00	87	E5	00	07	C0	07	E0	07	40
PIC18F4458	3F	CF	3F	1F	00	87	E5	00	07	C0	07	E0	07	40
PIC18F4480	00	CF	1F	1F	00	86	D5	00	03	C0	03	E0	03	40
PIC18F4510	00	CF	1F	1F	00	87	C5	00	0F	C0	0F	E0	0F	40
PIC18F4515	00	CF	1F	1F	00	87	C5	00	0F	C0	0F	E0	0F	40
PIC18F4520	00	CF	1F	1F	00	87	C5	00	0F	C0	0F	E0	0F	40
PIC18F4523	00	CF	1F	1F	00	87	C5	00	0F	C0	0F	E0	0F	40
PIC18F4525	00	CF	1F	1F	00	87	C5	00	0F	C0	0F	E0	0F	40
PIC18F4550	3F	CF	3F	1F	00	87	E5	00	0F	C0	0F	E0	0F	40
PIC18F4553	3F	CF	3F	1F	00	87	E5	00	0F	C0	0F	E0	0F	40
PIC18F4580	00	CF	1F	1F	00	86	D5	00	0F	C0	0F	E0	0F	40
PIC18F4585	00	CF	1F	1F	00	86	C5	00	0F	C0	0F	E0	0F	40
PIC18F4610	00	CF	1F	1F	00	87	C5	00	0F	C0	0F	E0	0F	40

Legend: Shaded cells are unimplemented.

PIC18F2XXX/4XXX FAMILY

6.0 AC/DC CHARACTERISTICS TIMING REQUIREMENTS FOR PROGRAM/VERIFY TEST MODE

Standard Operating Conditions						
Operating Temperature: 25°C is recommended						
Param No.	Sym	Characteristic	Min	Max	Units	Conditions
D110	VIHH	High-Voltage Programming Voltage on MCLR/VPP/RE3	VDD + 4.0	12.5	V	(Note 2)
D110A	VIHL	Low-Voltage Programming Voltage on MCLR/VPP/RE3	2.00	5.50	V	(Note 2)
D111	VDD	Supply Voltage During Programming	2.00	5.50	V	Externally timed, Row Erases and all writes
			3.0	5.50	V	Self-timed, Bulk Erases only (Note 3)
D112	I _{PP}	Programming Current on MCLR/VPP/RE3	—	300	μA	(Note 2)
D113	I _{DDP}	Supply Current During Programming	—	10	mA	
D031	V _{IL}	Input Low Voltage	V _{SS}	0.2 V _{DD}	V	
D041	V _{IH}	Input High Voltage	0.8 V _{DD}	V _{DD}	V	
D080	V _{OL}	Output Low Voltage	—	0.6	V	I _{OL} = 8.5 mA @ 4.5V
D090	V _{OH}	Output High Voltage	V _{DD} – 0.7	—	V	I _{OH} = -3.0 mA @ 4.5V
D012	C _{IO}	Capacitive Loading on I/O pin (PGD)	—	50	pF	To meet AC specifications
P1	T _R	MCLR/VPP/RE3 Rise Time to Enter Program/Verify mode	—	1.0	μs	(Notes 1, 2)
P2	T _{PGC}	Serial Clock (PGC) Period	100	—	ns	V _{DD} = 5.0V
			1	—	μs	V _{DD} = 2.0V
P2A	T _{PGCL}	Serial Clock (PGC) Low Time	40	—	ns	V _{DD} = 5.0V
			400	—	ns	V _{DD} = 2.0V
P2B	T _{PGCH}	Serial Clock (PGC) High Time	40	—	ns	V _{DD} = 5.0V
			400	—	ns	V _{DD} = 2.0V
P3	T _{SET1}	Input Data Setup Time to Serial Clock ↓	15	—	ns	
P4	T _{HLD1}	Input Data Hold Time from PGC ↓	15	—	ns	
P5	T _{DLY1}	Delay Between 4-Bit Command and Command Operand	40	—	ns	
P5A	T _{DLY1A}	Delay Between 4-Bit Command Operand and Next 4-Bit Command	40	—	ns	
P6	T _{DLY2}	Delay Between Last PGC ↓ of Command Byte to First PGC ↑ of Read of Data Word	20	—	ns	
P9	T _{DLY5}	PGC High Time (minimum programming time)	1	—	ms	Externally timed
P10	T _{DLY6}	PGC Low Time After Programming (high-voltage discharge time)	100	—	μs	
P11	T _{DLY7}	Delay to Allow Self-Timed Data Write or Bulk Erase to Occur	5	—	ms	

Note 1: Do not allow excess time when transitioning MCLR between V_{IL} and V_{IH}. This can cause spurious program executions to occur. The maximum transition time is:

1 T_{CY} + T_{PWRT} (if enabled) + 1024 T_{OSC} (for LP, HS, HS/PLL and XT modes only) +

2 ms (for HS/PLL mode only) + 1.5 μs (for EC mode only)

where T_{CY} is the instruction cycle time, T_{PWRT} is the Power-up Timer period and T_{OSC} is the oscillator period. For specific values, refer to the Electrical Characteristics section of the device data sheet for the particular device.

2: When ICPRT = 1, this specification also applies to ICVPP.

3: At 0°C-50°C.

PIC18F2XXX/4XXX FAMILY

6.0 AC/DC CHARACTERISTICS TIMING REQUIREMENTS FOR PROGRAM/VERIFY TEST MODE (CONTINUED)

Standard Operating Conditions						
Operating Temperature: 25°C is recommended						
Param No.	Sym	Characteristic	Min	Max	Units	Conditions
P11A	TDRWT	Data Write Polling Time	4	—	ms	
P12	THLD2	Input Data Hold Time from $\overline{\text{MCLR}}/\text{VPP}/\text{RE3} \uparrow$	2	—	μs	
P13	TSET2	$\text{VDD} \uparrow$ Setup Time to $\overline{\text{MCLR}}/\text{VPP}/\text{RE3} \uparrow$	100	—	ns	(Note 2)
P14	TVALID	Data Out Valid from $\text{PGC} \uparrow$	10	—	ns	
P15	TSET3	$\text{PGM} \uparrow$ Setup Time to $\overline{\text{MCLR}}/\text{VPP}/\text{RE3} \uparrow$	2	—	μs	(Note 2)
P16	TDLY8	Delay Between Last $\text{PGC} \downarrow$ and $\overline{\text{MCLR}}/\text{VPP}/\text{RE3} \downarrow$	0	—	s	
P17	THLD3	$\overline{\text{MCLR}}/\text{VPP}/\text{RE3} \downarrow$ to $\text{VDD} \downarrow$	—	100	ns	
P18	THLD4	$\overline{\text{MCLR}}/\text{VPP}/\text{RE3} \downarrow$ to $\text{PGM} \downarrow$	0	—	s	

- Note 1:** Do not allow excess time when transitioning $\overline{\text{MCLR}}$ between VIL and VIHH . This can cause spurious program executions to occur. The maximum transition time is:
1 $\text{T}_{\text{CY}} + \text{T}_{\text{PWRT}}$ (if enabled) + 1024 T_{OSC} (for LP, HS, HS/PLL and XT modes only) +
2 ms (for HS/PLL mode only) + 1.5 μs (for EC mode only)
where T_{CY} is the instruction cycle time, T_{PWRT} is the Power-up Timer period and T_{OSC} is the oscillator period. For specific values, refer to the Electrical Characteristics section of the device data sheet for the particular device.
- 2:** When $\text{ICPRT} = 1$, this specification also applies to ICVPP .
- 3:** At 0°C-50°C.