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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded - Microcontrollers</u>"

Details	
Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	40MHz
Connectivity	I ² C, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, HLVD, POR, PWM, WDT
Number of I/O	36
Program Memory Size	48KB (24K x 16)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	3.8K x 8
Voltage - Supply (Vcc/Vdd)	4.2V ~ 5.5V
Data Converters	A/D 13x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	44-TQFP
Supplier Device Package	44-TQFP (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic18f4515-i-pt

TABLE 2-1: PIN DESCRIPTIONS (DURING PROGRAMMING): PIC18F2XXX/4XXX FAMILY

	During Programming			
Pin Name	Pin Name Pin Type Pin Description		Pin Description	
MCLR/VPP/RE3	VPP	Р	Programming Enable	
VDD ⁽²⁾	VDD	Р	Power Supply	
VSS ⁽²⁾	Vss	Р	Ground	
RB5	PGM	I	Low-Voltage ICSP™ Input when LVP Configuration bit equals '1'(1)	
RB6	PGC	Ţ	Serial Clock	
RB7	PGD	I/O	Serial Data	

Legend: I = Input, O = Output, P = Power **Note 1:** See Figure 5-1 for more information.

2: All power supply (VDD) and ground (VSS) pins must be connected.

The following devices are included in 28-pin SPDIP, PDIP and SOIC parts:

• PIC18F2221

• PIC18F2480

• PIC18F2580

• PIC18F2321

• PIC18F2510

• PIC18F2585

• PIC18F2410

• PIC18F2515

• PIC18F2610

PIC18F2420

• PIC18F2520

• PIC18F2620

PIC18F2423

• PIC18F2523

• PIC18F2680

• PIC18F2450

• PIC18F2525

• PIC18F2682

PIC18F2455PIC18F2458

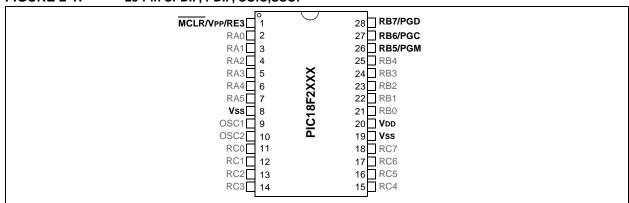
PIC18F2550PIC18F2553

PIC18F2685

The following devices are included in 28-pin SSOP parts:

PIC18F2221
 PIC18F2321

FIGURE 2-1: 28-Pin SPDIP, PDIP, SOIC, SSOP

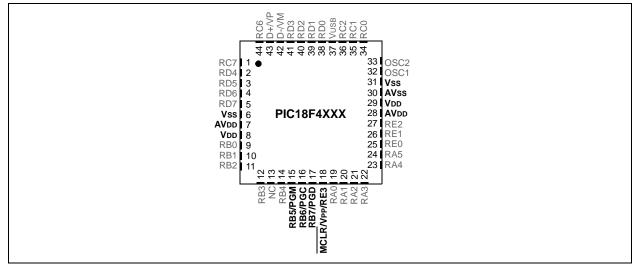


The following devices are included in 44-pin QFN parts:

- PIC18F4221
- PIC18F4321
- PIC18F4410
- PIC18F4420
- PIC18F4423
- PIC18F4450
- PIC18F4455
- PIC18F4458
- PIC18F4480
- PIC18F4510
- PIC18F4520
- PIC18F4515

- PIC18F4523
- PIC18F4525
- PIC18F4550
- PIC18F4553
- PIC18F4580
- PIC18F4585
- PIC18F4610
- PIC18F4620
- PIC18F4680
- PIC18F4682
- PIC18F4685

FIGURE 2-5: 44-PIN QFN



2.3 **Memory Maps**

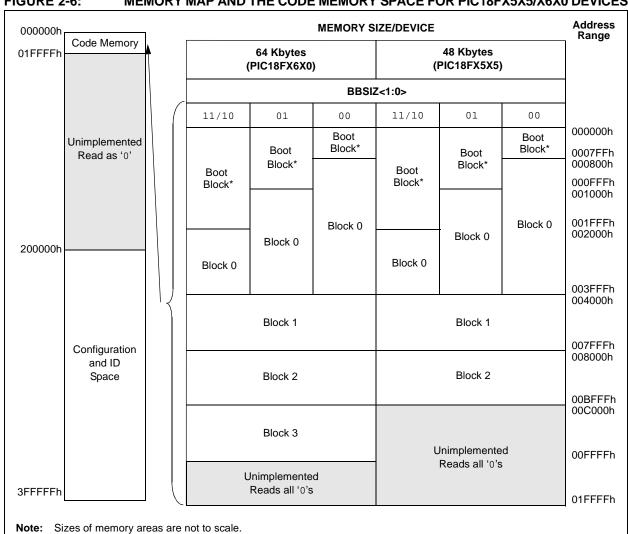
For PIC18FX6X0 devices, the code memory space extends from 0000h to 0FFFFh (64 Kbytes) in four 16-Kbyte blocks. For PIC18FX5X5 devices, the code memory space extends from 0000h to 0BFFFFh (48 Kbytes) in three 16-Kbyte blocks. Addresses, 0000h through 07FFh, however, define a "Boot Block" region that is treated separately from Block 0. All of these blocks define code protection boundaries within the code memory space.

The size of the Boot Block in PIC18F2585/2680/4585/4680 devices can be configured as 1, 2 or 4K words (see Figure 2-6). This is done through the BBSIZ<1:0> bits in the Configuration register, CONFIG4L. It is important to note that increasing the size of the Boot Block decreases the size of Block 0.

TABLE 2-2: IMPLEMENTATION OF CODE MEMORY

Device	Code Memory Size (Bytes)	
PIC18F2515		
PIC18F2525		
PIC18F2585	000000h 00DFFFh (40K)	
PIC18F4515	000000h-00BFFFh (48K)	
PIC18F4525		
PIC18F4585		
PIC18F2610		
PIC18F2620		
PIC18F2680	000000h 005555h (64K)	
PIC18F4610	000000h-00FFFFh (64K)	
PIC18F4620		
PIC18F4680		

MEMORY MAP AND THE CODE MEMORY SPACE FOR PIC18FX5X5/X6X0 DEVICES FIGURE 2-6:

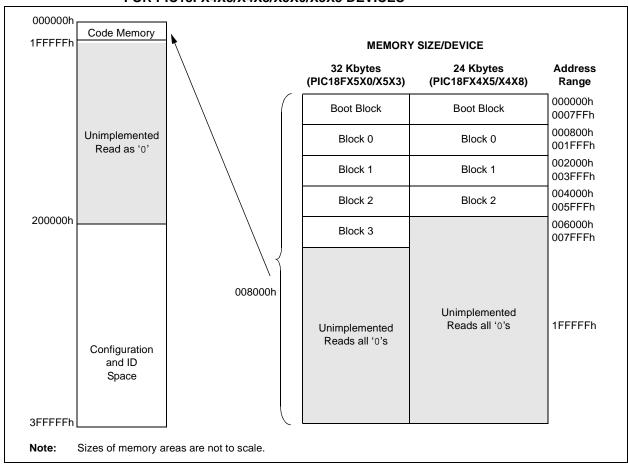


Boot Block size is determined by the BBSIZ<1:0> bits in the CONFIG4L register.

TABLE 2-4: IMPLEMENTATION OF CODE MEMORY

Device	Code Memory Size (Bytes)
PIC18F2455	
PIC18F2458	000000h 005FFFh (24K)
PIC18F4455	000000h-005FFFh (24K)
PIC18F4458	
PIC18F2510	
PIC18F2520	
PIC18F2523	
PIC18F2550	
PIC18F2553	000000h 007FFFh (20K)
PIC18F4510	000000h-007FFFh (32K)
PIC18F4520	
PIC18F4523	
PIC18F4550	
PIC18F4553	

FIGURE 2-8: MEMORY MAP AND THE CODE MEMORY SPACE FOR PIC18FX4X5/X4X8/X5X0/X5X3 DEVICES

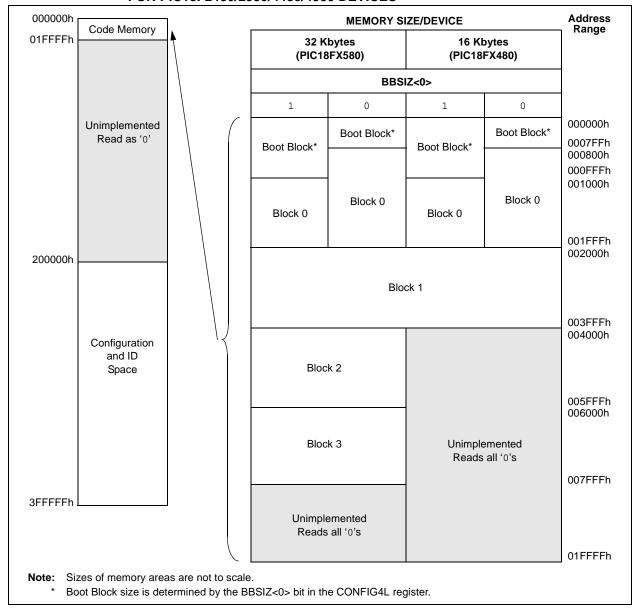


For PIC18FX4X0/X4X3 devices, the code memory space extends from 000000h to 003FFh (16 Kbytes) in two 8-Kbyte blocks. Addresses, 000000h through 0003FFh, however, define a "Boot Block" region that is treated separately from Block 0. All of these blocks define code protection boundaries within the code memory space.

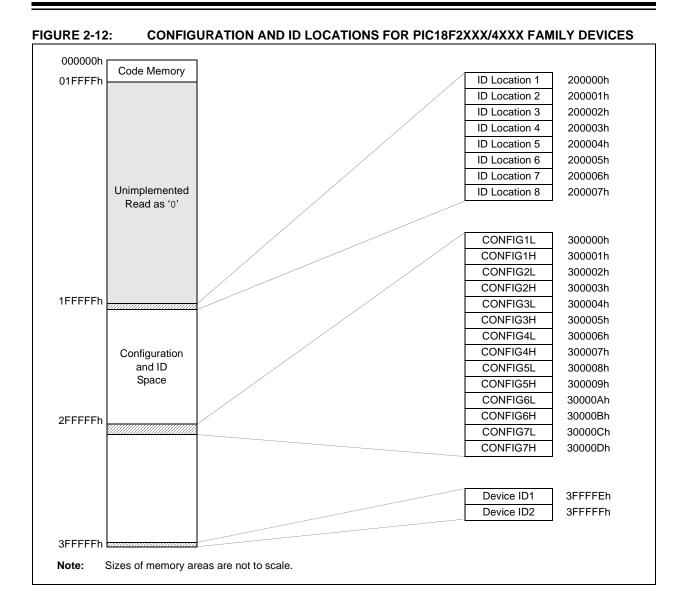
TABLE 2-6: IMPLEMENTATION OF CODE MEMORY

Device	Code Memory Size (Bytes)	
PIC18F2480	000000h 003EEEh (16K)	
PIC18F4480	000000h-003FFFh (16K)	
PIC18F2580	000000h-007FFFh (32K)	
PIC18F4580		

FIGURE 2-10: MEMORY MAP AND THE CODE MEMORY SPACE FOR PIC18F2480/2580/4480/4580 DEVICES



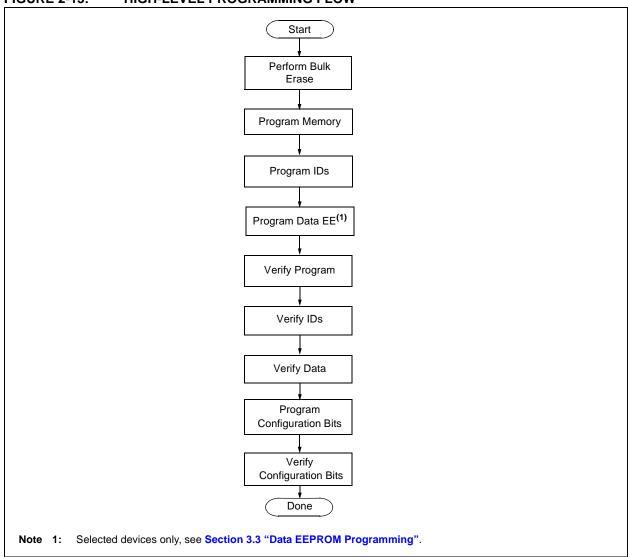
For PIC18F2221/4221 devices, the code memory space extends from 0000h to 00FFFh (4 Kbytes) in one 4-Kbyte block. For PIC18F2321/4321 devices, the code memory space extends from 0000h to 01FFFh (8 Kbytes) in two 4-Kbyte blocks. Addresses, 0000h through 07FFh, however, define a variable "Boot Block" region that is treated separately from Block 0. All of these blocks define code protection boundaries within the code memory space.



2.4 High-Level Overview of the Programming Process

Figure 2-13 shows the high-level overview of the programming process. First, a Bulk Erase is performed. Next, the code memory, ID locations and data EEPROM are programmed (selected devices only, see **Section 3.3 "Data EEPROM Programming"**). These memories are then verified to ensure that programming was successful. If no errors are detected, the Configuration bits are then programmed and verified.

FIGURE 2-13: HIGH-LEVEL PROGRAMMING FLOW

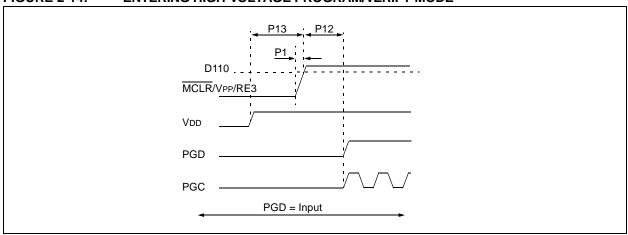


2.5 Entering and Exiting High-Voltage ICSP Program/Verify Mode

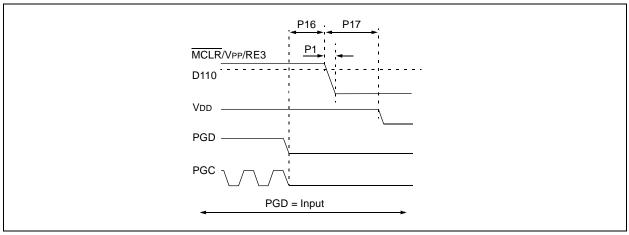
As shown in Figure 2-14, the High-Voltage ICSP Program/Verify mode is entered by holding PGC and PGD low and then raising MCLR/VPP/RE3 to VIHH (high voltage). Once in this mode, the code memory, data EEPROM (selected devices only, see **Section 3.3 "Data EEPROM Programming"**), ID locations and Configuration bits can be accessed and programmed in serial fashion. Figure 2-15 shows the exit sequence.

The sequence that enters the device into the Program/Verify mode places all unused I/Os in the high-impedance state.

FIGURE 2-14: ENTERING HIGH-VOLTAGE PROGRAM/VERIFY MODE







2.6 Entering and Exiting Low-Voltage ICSP Program/Verify Mode

When the LVP Configuration bit is '1' (see Section 5.3 "Single-Supply ICSP Programming"), the Low-Voltage ICSP mode is enabled. As shown in Figure 2-16, Low-Voltage ICSP Program/Verify mode is entered by holding PGC and PGD low, placing a logic high on PGM and then raising $\overline{\text{MCLR}/\text{VPP/RE3}}$ to VIH. In this mode, the RB5/PGM pin is dedicated to the programming function and ceases to be a general purpose I/O pin. Figure 2-17 shows the exit sequence.

The sequence that enters the device into the Program/Verify mode places all unused I/Os in the high-impedance state.

FIGURE 2-16: ENTERING LOW-VOLTAGE PROGRAM/VERIFY MODE

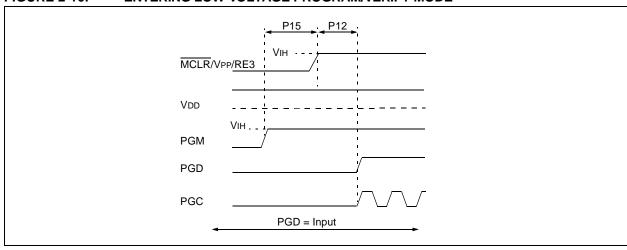
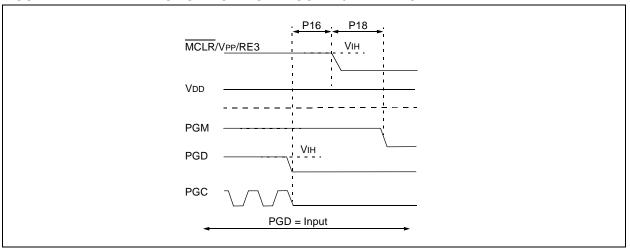


FIGURE 2-17: EXITING LOW-VOLTAGE PROGRAM/VERIFY MODE



2.8 Dedicated ICSP/ICD Port (44-Pin TQFP Only)

The PIC18F4455/4458/4550/4553 44-pin TQFP devices are designed to support an alternate programming input: the dedicated ICSP/ICD port. The primary purpose of this port is to provide an alternate In-Circuit Debugging (ICD) option and free the pins (RB6, RB7 and \overline{MCLR}) that would normally be used for debugging the application. In conjunction with ICD capability, however, the dedicated ICSP/ICD port also provides an alternate port for ICSP.

Setting the ICPRT Configuration bit enables the dedicated ICSP/ICD port. The dedicated ICSP/ICD port functions the same as the default ICSP/ICD port; however, alternate pins are used instead of the default pins. Table 2-10 identifies the functionally equivalent pins for ICSP purposes:

The dedicated ICSP/ICD port is an alternate port. Thus, ICSP is still available through the default port even though the ICPRT Configuration bit is set. When the VIH is seen on the MCLR/VPP/RE3 pin prior to applying VIH to the ICRST/ICVPP pin, then the state of the ICRST/ICVPP pin is ignored. Likewise, when the VIH is seen on ICRST/ICVPP prior to applying VIH to MCLR/VPP/RE3, then the state of the MCLR/VPP/RE3 pin is ignored.

Note: The ICPRT Configuration bit can only be programmed through the default ICSP port. Chip Erase functions through the dedicated ICSP/ICD port do not affect this bit.

When the ICPRT Configuration bit is set (dedicated ICSP/ICD port enabled), the NC/ICPORTS pin must be tied to either VDD or VSS.

The ICPRT Configuration bit must be maintained clear for all 28-pin and 40-pin devices; otherwise, unexpected operation may occur.

TABLE 2-10: ICSP™ EQUIVALENT PINS

Pin Name	During Programming			
Pili Name	Pin Name	Pin Type	Dedicated Pins	Pin Description
MCLR/Vpp/RE3	VPP	Р	NC/ICRST/ICVPP	Programming Enable
RB6	PGC	I	NC/ICCK/ICPGC	Serial Clock
RB7	PGD	I/O	NC/ICDT/ICPGD	Serial Data

Legend: I = Input, O = Output, P = Power

TABLE 3-5: WRITE CODE MEMORY CODE SEQUENCE

4-Bit Command	Data Payload	Core Instruction	
Step 1: Direct acc	ess to code memory an	d enable writes.	
0000	8E A6 9C A6	BSF EECON1, EEPGD BCF EECON1, CFGS	
Step 2: Load write	e buffer.		
0000 0000 0000 0000 0000	0E <addr[21:16]> 6E F8 0E <addr[15:8]> 6E F7 0E <addr[7:0]> 6E F6</addr[7:0]></addr[15:8]></addr[21:16]>	MOVLW <addr[21:16]> MOVWF TBLPTRU MOVLW <addr[15:8]> MOVWF TBLPTRH MOVLW <addr[7:0]> MOVWF TBLPTRL</addr[7:0]></addr[15:8]></addr[21:16]>	
Step 3: Repeat for	Step 3: Repeat for all but the last two bytes.		
1101	<msb><lsb></lsb></msb>	Write 2 bytes and post-increment address by 2.	
Step 4: Load write	Step 4: Load write buffer for last two bytes.		
1111 0000	<msb><lsb></lsb></msb>	Write 2 bytes and start programming. NOP - hold PGC high for time P9 and low for time P10.	
To continue writing data, repeat Steps 2 through 4, where the Address Pointer is incremented by 2 at each iteration of the loop.			

3.4 ID Location Programming

The ID locations are programmed much like the code memory. The ID registers are mapped in addresses, 200000h through 200007h. These locations read out normally even after code protection.

Note: The user only needs to fill the first 8 bytes of the write buffer in order to write the ID locations.

Table 3-8 demonstrates the code sequence required to write the ID locations.

In order to modify the ID locations, refer to the methodology described in **Section 3.2.1 "Modifying Code Memory"**. As with code memory, the ID locations must be erased before being modified.

TABLE 3-8: WRITE ID SEQUENCE

4-Bit Command	Data Payload	Core Instruction
Step 1: Direct acc	ess to code memory and en	nable writes.
0000	8E A6 9C A6	BSF EECON1, EEPGD BCF EECON1, CFGS
Step 2: Load write	buffer with 8 bytes and writ	te.
0000 0000 0000 0000 0000 0000 1101	0E 20 6E F8 0E 00 6E F7 0E 00 6E F6 <msb><lsb></lsb></msb>	MOVLW 20h MOVWF TBLPTRU MOVLW 00h MOVWF TBLPTRH MOVLW 00h MOVWF TBLPTRL Write 2 bytes and post-increment address by 2.
1101 1101 1111 0000	<msb><lsb> <msb><lsb> <msb><lsb> 00 00</lsb></msb></lsb></msb></lsb></msb>	Write 2 bytes and post-increment address by 2. Write 2 bytes and post-increment address by 2. Write 2 bytes and start programming. NOP - hold PGC high for time P9 and low for time P10.

3.5 Boot Block Programming

The code sequence detailed in Table 3-5 should be used, except that the address used in "Step 2" will be in the range of 000000h to 0007FFh.

3.6 Configuration Bits Programming

Unlike code memory, the Configuration bits are programmed a byte at a time. The Table Write, Begin Programming 4-bit command ('1111') is used, but only eight bits of the following 16-bit payload will be written. The LSB of the payload will be written to even addresses and the MSB will be written to odd addresses. The code sequence to program two consecutive configuration locations is shown in Table 3-9.

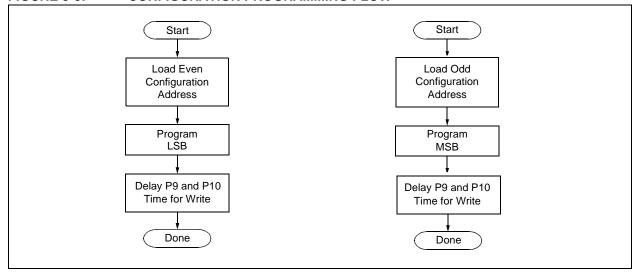
Note: The address must be explicitly written for each byte programmed. The addresses can not be incremented in this mode.

TABLE 3-9: SET ADDRESS POINTER TO CONFIGURATION LOCATION

4-Bit Command	Data Payload	Core Instruction
Step 1: Enable wr	ites and direct access to cor	nfiguration memory.
0000	8E A6 8C A6	BSF EECON1, EEPGD BSF EECON1, CFGS
		e to be written. Write even/odd addresses. ⁽¹⁾
0000	0E 30	MOVLW 30h
0000	6E F8	MOVWF TBLPTRU
0000	0E 00	MOVLW 00h
0000	6E F7	MOVWF TBLPRTH
0000	0E 00	MOVLW 00h
0000	6E F6	MOVWF TBLPTRL
1111	<msb ignored=""><lsb></lsb></msb>	Load 2 bytes and start programming.
0000	00 00	NOP - hold PGC high for time P9 and low for time P10.
0000	0E 01	MOVLW 01h
0000	6E F6	MOVWF TBLPTRL
1111	<msb><lsb ignored=""></lsb></msb>	Load 2 bytes and start programming.
0000	00 00	NOP - hold PGC high for time P9 and low for time P10.

Note 1: Enabling the write protection of Configuration bits (WRTC = 0 in CONFIG6H) will prevent further writing of the Configuration bits. Always write all the Configuration bits before enabling the write protection for Configuration bits.

FIGURE 3-8: CONFIGURATION PROGRAMMING FLOW



4.4 Read Data EEPROM Memory

Data EEPROM is accessed, one byte at a time, via an Address Pointer (register pair: EEADRH:EEADR) and a data latch (EEDATA). Data EEPROM is read by loading EEADRH:EEADR with the desired memory location and initiating a memory read by appropriately configuring the EECON1 register. The data will be loaded into EEDATA, where it may be serially output on PGD via the 4-bit command, '0010' (Shift Out Data Holding register). A delay of P6 must be introduced after the falling edge of the 8th PGC of the operand to allow PGD to transition from an input to an output. During this time, PGC must be held low (see Figure 4-4).

The command sequence to read a single byte of data is shown in Table 4-2.

FIGURE 4-3: READ DATA EEPROM FLOW

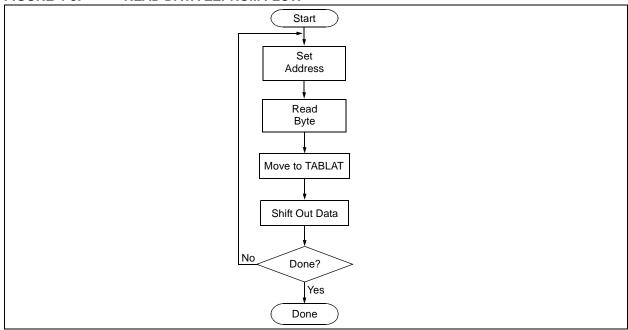


TABLE 4-2: READ DATA EEPROM MEMORY

4-Bit Command	Data Payload	Core Instruction	
Step 1: Direct ac	cess to data EEPROM.		
0000	9E A6 9C A6	BCF EECON1, EEPGD BCF EECON1, CFGS	
Step 2: Set the d	ata EEPROM Address Pointe	er.	
0000 0000 0000 0000	0E <addr> 6E A9 0E <addrh> 6E AA</addrh></addr>	MOVLW <addr> MOVWF EEADR MOVLW <addrh> MOVWF EEADRH</addrh></addr>	
Step 3: Initiate a	Step 3: Initiate a memory read.		
0000	80 A6	BSF EECON1, RD	
Step 4: Load data	a into the Serial Data Holding	register.	
0000 0000 0000 0010	50 A8 6E F5 00 00 <msb><lsb></lsb></msb>	MOVF EEDATA, W, 0 MOVWF TABLAT NOP Shift Out Data ⁽¹⁾	

Note 1: The <LSB> is undefined. The <MSB> is the data.

TABLE 5-2: DEVICE ID VALUES (CONTINUED)

Device	Device ID Value		
Device	DEVID2	DEVID1	
PIC18F4585	0Eh	101x xxxx	
PIC18F4610	0Ch	001x xxxx	
PIC18F4620	0Ch	000x xxxx	
PIC18F4680	0Eh	100x xxxx	
PIC18F4682	27h	010x xxxx	
PIC18F4685	27h	011x xxxx	

Legend: The 'x's in DEVID1 contain the device revision code.

Note 1: DEVID1 bit 4 is used to determine the device type (REV4 = 0).

2: DEVID1 bit 4 is used to determine the device type (REV4 = 1).

TABLE 5-3: PIC18F2XXX/4XXX FAMILY BIT DESCRIPTIONS (CONTINUED)

Bit Name	Configuration Words	Description
PLLDIV<2:0>	CONFIG1L	Oscillator Selection bits (PIC18F2455/2550/4455/4550, PIC18F2458/2553/4458/4553 and PIC18F2450/4450 devices only)
		Divider must be selected to provide a 4 MHz input into the 96 MHz PLL: 111 = Oscillator divided by 12 (48 MHz input) 110 = Oscillator divided by 10 (40 MHz input) 101 = Oscillator divided by 6 (24 MHz input) 100 = Oscillator divided by 5 (20 MHz input) 011 = Oscillator divided by 4 (16 MHz input) 010 = Oscillator divided by 3 (12 MHz input) 001 = Oscillator divided by 2 (8 MHz input) 000 = No divide - oscillator used directly (4 MHz input)
VREGEN	CONFIG2L	USB Voltage Regulator Enable bit (PIC18F2455/2550/4455/4550, PIC18F2458/2553/4458/4553 and PIC18F2450/4450 devices only) 1 = USB voltage regulator is enabled 0 = USB voltage regulator is disabled
BORV<1:0>	CONFIG2L	Brown-out Reset Voltage bits 11 = VBOR is set to 2.0V 10 = VBOR is set to 2.7V 01 = VBOR is set to 4.2V 00 = VBOR is set to 4.5V
BOREN<1:0>	CONFIG2L	Brown-out Reset Enable bits 11 = Brown-out Reset is enabled in hardware only (SBOREN is disabled) 10 = Brown-out Reset is enabled in hardware only and disabled in Sleep mode SBOREN is disabled) 01 = Brown-out Reset is enabled and controlled by software (SBOREN is enabled) 00 = Brown-out Reset is disabled in hardware and software
PWRTEN	CONFIG2L	Power-up Timer Enable bit 1 = PWRT is disabled 0 = PWRT is enabled
WDPS<3:0>	CONFIG2H	Watchdog Timer Postscaler Select bits 1111 = 1:32,768 1110 = 1:16,384 1101 = 1:8,192 1100 = 1:4,096 1011 = 1:2,048 1010 = 1:512 1000 = 1:256 0111 = 1:128 0110 = 1:64 0101 = 1:32 0100 = 1:16 0011 = 1:8 0010 = 1:4 0001 = 1:2 0000 = 1:1

Note 1: The BBSIZ bits, BBSIZ<1:0> and BBSIZ<2:1> bits, cannot be changed once any of the following code-protect bits are enabled: CPB or CP0, WRTB or WRT0, EBTRB or EBTR0.

^{2:} Not available in PIC18FXX8X and PIC18F2450/4450 devices.

TABLE 5-4: DEVICE BLOCK LOCATIONS AND SIZES (CONTINUED)

	Memory Size (Bytes)	Pins	Ending Address							Size (Bytes)			
Device			Boot Block	Block 0	Block 1	Block 2	Block 3	Block 4	Block 5	Boot Block	Block 0	Remaining Blocks	Device Total
PIC18F4455	24K	40	0007FF	001FFF	003FFF	005FFF	_	_	_	2048	6144	16384	24576
PIC18F4458	24K	40	0007FF	001FFF	003FFF	005FFF	_	_	_	2048	6144	16384	24576
PIC18F4480	16K	40	0007FF	001FFF	003FFF	_	-	_	_	2048	6144	8192	16384
PIC 18F4480			000FFF							4096	4096		
PIC18F4510	32K	40	0007FF	001FFF	003FFF	005FFF	007FFF	_	_	2048	6144	24576	32768
PIC18F4515	48K	40	0007FF	003FFF	007FFF	00BFFF	_	_	_	2048	14336	32768	49152
PIC18F4520	32K	40	0007FF	001FFF	003FFF	005FFF	007FFF	_	_	2048	14336	16384	32768
PIC18F4523	32K	40	0007FF	001FFF	003FFF	005FFF	007FFF	_	_	2048	14336	16384	32768
PIC18F4525	48K	40	0007FF	003FFF	007FFF	00BFFF	_	_	_	2048	14336	32768	49152
PIC18F4550	32K	40	0007FF	001FFF	003FFF	005FFF	007FFF	_	_	2048	6144	24576	32768
PIC18F4553	32K	40	0007FF	001FFF	003FFF	005FFF	007FFF	_	_	2048	6144	24576	32768
PIC18F4580	32K	40	0007FF	001FFF	003FFF	005FFF	007FFF	_	_	2048	6144	24576	32768
PIC 10F4500			000FFF							4096	4096		
	48K	40	0007FF	003FFF	007FFF	00BFFF	_	_	_	2048	14336	32768	49152
PIC18F4585			000FFF							4096	12288		
			001FFF							8192	8192		
PIC18F4610	64K	40	0007FF	003FFF	007FFF	00BFFF	00FFFF	_	_	2048	14336	49152	65536
PIC18F4620	64K	40	0007FF	003FFF	007FFF	00BFFF	00FFFF	_	_	2048	14336	49152	65536
	64K	40	0007FF	003FFF	007FFF	00BFFF	00FFFF	_	_	2048	14336	49152	65536
PIC18F4680			000FFF							4096	12288		
			001FFF							8192	8192		
PIC18F4682	80K	40	0007FF	003FFF	007FFF	00BFFF	00FFFF	013FFF	_	2048	14336	65536	81920
			000FFF							4096	12288		
			001FFF							8192	8192		
	96K	44	0007FF				00FFFF	FF 013FFF	017FFF	2048	14336	81920	98304
PIC18F4685			000FFF	003FFF	007FFF	00BFFF				4096	12288		
			001FFF							8192	8192		

Legend: — = unimplemented.

TABLE 5-5: CONFIGURATION WORD MASKS FOR COMPUTING CHECKSUMS

TABLE 5-5:	5: CONFIGURATION WORD MASKS FOR COMPUTING CHECKSUMS													
	Configuration Word (CONFIGxx)													
Davisa	1L	1H	2L	2H	3L	3H	4L	4H	5L	5H	6L	6H	7L	7H
Device	Address (30000xh)													
	0h	1h	2h	3h	4h	5h	6h	7h	8h	9h	Ah	Bh	Ch	Dh
PIC18F2221	00	CF	1F	1F	00	87	F5	00	03	C0	03	E0	03	40
PIC18F2321	00	CF	1F	1F	00	87	F5	00	03	C0	03	E0	03	40
PIC18F2410	00	CF	1F	1F	00	87	C5	00	03	C0	03	E0	03	40
PIC18F2420	00	CF	1F	1F	00	87	C5	00	03	C0	03	E0	03	40
PIC18F2423	00	CF	1F	1F	00	87	C5	00	03	C0	03	E0	03	40
PIC18F2450	3F	CF	3F	1F	00	86	ED	00	03	40	03	60	03	40
PIC18F2455	3F	CF	3F	1F	00	87	E5	00	07	C0	07	E0	07	40
PIC18F2458	3F	CF	3F	1F	00	87	E5	00	07	C0	07	E0	07	40
PIC18F2480	00	CF	1F	1F	00	86	D5	00	03	C0	03	E0	03	40
PIC18F2510	00	1F	1F	1F	00	87	C5	00	0F	C0	0F	E0	0F	40
PIC18F2515	00	CF	1F	1F	00	87	C5	00	0F	C0	0F	E0	0F	40
PIC18F2520	00	CF	1F	1F	00	87	C5	00	0F	C0	0F	E0	0F	40
PIC18F2523	00	CF	1F	1F	00	87	C5	00	0F	C0	0F	E0	0F	40
PIC18F2525	00	CF	1F	1F	00	87	C5	00	0F	C0	0F	E0	0F	40
PIC18F2550	3F	CF	3F	1F	00	87	E5	00	0F	C0	0F	E0	0F	40
PIC18F2553	3F	CF	3F	1F	00	87	E5	00	0F	C0	0F	E0	0F	40
PIC18F2580	00	CF	1F	1F	00	86	D5	00	0F	C0	0F	E0	0F	40
PIC18F2585	00	CF	1F	1F	00	86	C5	00	0F	C0	0F	E0	0F	40
PIC18F2610	00	CF	1F	1F	00	87	C5	00	0F	C0	0F	E0	0F	40
PIC18F2620	00	CF	1F	1F	00	87	C5	00	0F	C0	0F	E0	0F	40
PIC18F2680	00	CF	1F	1F	00	86	C5	00	0F	C0	0F	E0	0F	40
PIC18F2682	00	CF	1F	1F	00	86	C5	00	3F	C0	3F	E0	3F	40
PIC18F2685	00	CF	1F	1F	00	86	C5	00	3F	C0	3F	E0	3F	40
PIC18F4221	00	CF	1F	1F	00	87	F5	00	03	C0	03	E0	03	40
PIC18F4321	00	CF	1F	1F	00	87	F5	00	03	C0	03	E0	03	40
PIC18F4410	00	CF	1F	1F	00	87	C5	00	03	C0	03	E0	03	40
PIC18F4420	00	CF CF	1F 1F	1F 1F	00	87 87	C5	00	03	C0	03	E0 E0	03	40 40
PIC18F4423 PIC18F4450	00 3F	CF	3F	1F	00		C5	00	03	C0	03		03	40
PIC18F4455	3F	CF	3F	1F	00	86 87	ED E5	00	03 07	40 C0	03 07	60 E0	03 07	40
PIC18F4458	3F	CF	3F	1F	00	87	E5	00	07	CO	07	E0	07	40
PIC18F4480	00	CF	1F	1F	00	86	D5	00	03	CO	03	E0	03	40
PIC18F4510	00	CF	1F	1F	00	87	C5	00	05 0F	CO	05 0F	E0	05 0F	40
PIC18F4515	00	CF	1F	1F	00	87	C5	00	0F	CO	0F	E0	0F	40
PIC18F4515	00	CF	1F	1F	00	87	C5	00	0F	CO	0F	E0	0F	40
PIC18F4523	00	CF	1F	1F	00	87	C5	00	0F	CO	0F	E0	0F	40
PIC18F4525	00	CF	1F	1F	00	87	C5	00	0F	CO	0F	E0	0F	40
PIC18F4550	3F	CF	3F	1F	00	87	E5	00	0F	CO	0F	E0	0F	40
PIC18F4553	3F	CF	3F	1F	00	87	E5	00	0F	CO	0F	E0	0F	40
PIC18F4580	00	CF	1F	1F	00	86	D5	00	0F	CO	0F	E0	0F	40
PIC18F4585	00	CF	1F	1F	00	86	C5	00	0F	CO	0F	E0	0F	40
PIC18F4610	00	CF	1F	1F	00	87	C5	00	0F	C0	0F	E0	0F	40
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Legend: Shaded cells are unimplemented.

6.0 AC/DC CHARACTERISTICS TIMING REQUIREMENTS FOR PROGRAM/VERIFY TEST MODE

Standard Operating Conditions

Operating Temperature: 25°C is recommended

Operat	ing rem	perature: 25°C is recommended	<u> </u>	1	1	i
Param No.	Sym	Characteristic	Min	Max	Units	Conditions
D110	VIHH	High-Voltage Programming Voltage on MCLR/Vpp/RE3	VDD + 4.0	12.5	V	(Note 2)
D110A	VIHL	Low-Voltage Programming Voltage on MCLR/VPP/RE3	2.00	5.50	V	(Note 2)
D111	VDD	Supply Voltage During Programming	2.00	5.50	V	Externally timed, Row Erases and all writes
			3.0	5.50	V	Self-timed, Bulk Erases only (Note 3)
D112	IPP	Programming Current on MCLR/VPP/RE3	_	300	μΑ	(Note 2)
D113	IDDP	Supply Current During Programming	_	10	mA	
D031	VIL	Input Low Voltage	Vss	0.2 VDD	V	
D041	VIH	Input High Voltage	0.8 VDD	Vdd	V	
D080	Vol	Output Low Voltage	_	0.6	V	IOL = 8.5 mA @ 4.5V
D090	Vон	Output High Voltage	VDD - 0.7	_	V	IOH = -3.0 mA @ 4.5V
D012	Сю	Capacitive Loading on I/O pin (PGD)	_	50	pF	To meet AC specifications
	•					
P1	TR	MCLR/VPP/RE3 Rise Time to Enter Program/Verify mode	_	1.0	μS	(Notes 1, 2)
P2	TPGC	Serial Clock (PGC) Period	100	_	ns	VDD = 5.0V
			1	_	μS	VDD = 2.0V
P2A	TPGCL	Serial Clock (PGC) Low Time	40	_	ns	VDD = 5.0V
			400	_	ns	VDD = 2.0V
P2B	TPGCH	Serial Clock (PGC) High Time	40	_	ns	VDD = 5.0V
			400	_	ns	VDD = 2.0V
P3	TSET1	Input Data Setup Time to Serial Clock ↓	15	_	ns	
P4	THLD1	Input Data Hold Time from PGC ↓	15	_	ns	
P5	TDLY1	Delay Between 4-Bit Command and Command Operand	40	_	ns	
P5A	TDLY1A	Delay Between 4-Bit Command Operand and Next 4-Bit Command	40	_	ns	
P6	TDLY2	Delay Between Last PGC ↓ of Command Byte to First PGC ↑ of Read of Data Word	20	_	ns	
P9	TDLY5	PGC High Time (minimum programming time)	1	_	ms	Externally timed
P10	TDLY6	PGC Low Time After Programming (high-voltage discharge time)	100	_	μS	
P11	TDLY7	Delay to Allow Self-Timed Data Write or Bulk Erase to Occur	5	_	ms	

Note 1: Do not allow excess time when transitioning MCLR between VIL and VIHH. This can cause spurious program executions to occur. The maximum transition time is:

¹ TCY + TPWRT (if enabled) + 1024 Tosc (for LP, HS, HS/PLL and XT modes only) +

² ms (for HS/PLL mode only) + 1.5 μ s (for EC mode only)

where TCY is the instruction cycle time, TPWRT is the Power-up Timer period and ToSC is the oscillator period. For specific values, refer to the Electrical Characteristics section of the device data sheet for the particular device.

^{2:} When ICPRT = 1, this specification also applies to ICVPP.

^{3:} At 0°C-50°C.

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ISBN: 978-1-63277-856-7

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