E·XFL

XMOS - XS1-L16A-128-QF124-I10 Datasheet



Welcome to E-XFL.COM

What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

Details

Product Status	Active
Core Processor	XCore
Core Size	32-Bit 16-Core
Speed	1000MIPS
Connectivity	Configurable
Peripherals	-
Number of I/O	84
Program Memory Size	128KB (32K x 32)
Program Memory Type	SRAM
EEPROM Size	-
RAM Size	•
Voltage - Supply (Vcc/Vdd)	0.95V ~ 3.6V
Data Converters	•
Oscillator Type	External
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	124-TFQFN Dual Rows, Exposed Pad
Supplier Device Package	124-QFN DualRow (10x10)
Purchase URL	https://www.e-xfl.com/product-detail/xmos/xs1-l16a-128-qf124-i10

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

Table of Contents

1	xCORE Multicore Microcontrollers
2	XS1-L16A-128-QF124 Features
3	Pin Configuration
4	Signal Description
5	Product Overview
6	PLL
7	Boot Procedure
8	Memory
9	JTAG
10	Board Integration
11	DC and Switching Characteristics
12	Package Information
13	Ordering Information
App	endices
Α	Configuration of the XS1
В	Processor Status Configuration
С	Tile Configuration
D	Node Configuration
E	XMOS USB Interface
F	Device Errata
G	JTAG, xSCOPE and Debugging
Н	Schematics Design Check List
1	PCB Layout Design Check List
J	Associated Design Documentation
K	Related Documentation
L	Revision History

TO OUR VALUED CUSTOMERS

It is our intention to provide you with accurate and comprehensive documentation for the hardware and software components used in this product. To subscribe to receive updates, visit http://www.xmos.com/.

XMOS Ltd. is the owner or licensee of the information in this document and is providing it to you "AS IS" with no warranty of any kind, express or implied and shall have no liability in relation to its use. XMOS Ltd. makes no representation that the information, or any particular implementation thereof, is or will be free from any claims of infringement and again, shall have no liability in relation to any such claims.

XMOS and the XMOS logo are registered trademarks of XMOS Ltd in the United Kingdom and other countries, and may not be used without written permission. Company and product names mentioned in this document are the trademarks or registered trademarks of their respective owners.

- Channels and channel ends Tasks running on logical cores communicate using channels formed between two channel ends. Data can be passed synchronously or asynchronously between the channel ends assigned to the communicating tasks. Section 5.5
- xCONNECT Switch and Links Between tiles, channel communications are implemented over a high performance network of xCONNECT Links and routed through a hardware xCONNECT Switch. Section 5.6
- Ports The I/O pins are connected to the processing cores by Hardware Response ports. The port logic can drive its pins high and low, or it can sample the value on its pins optionally waiting for a particular condition. Section 5.3
- Clock blocks xCORE devices include a set of programmable clock blocks that can be used to govern the rate at which ports execute. Section 5.4
- Memory Each xCORE Tile integrates a bank of SRAM for instructions and data, and a block of one-time programmable (OTP) memory that can be configured for system wide security features. Section 8
- PLL The PLL is used to create a high-speed processor clock given a low speed external oscillator. Section 6
- JTAG The JTAG module can be used for loading programs, boundary scan testing, in-circuit source-level debugging and programming the OTP memory. Section 9

1.1 Software

Devices are programmed using C, C++ or xC (C with multicore extensions). XMOS provides tested and proven software libraries, which allow you to quickly add interface and processor functionality such as USB, Ethernet, PWM, graphics driver, and audio EQ to your applications.

1.2 xTIMEcomposer Studio

The xTIMEcomposer Studio development environment provides all the tools you need to write and debug your programs, profile your application, and write images into flash memory or OTP memory on the device. Because xCORE devices operate deterministically, they can be simulated like hardware within xTIMEcomposer: uniquely in the embedded world, xTIMEcomposer Studio therefore includes a static timing analyzer, cycle-accurate simulator, and high-speed in-circuit instrumentation.

xTIMEcomposer can be driven from either a graphical development environment, or the command line. The tools are supported on Windows, Linux and MacOS X and available at no cost from xmos.com/downloads. Information on using the tools is provided in the xTIMEcomposer User Guide, X3766.

 $-X \wedge ()S$

5 Product Overview

The XS1-L16A-128-QF124 is a powerful device that consists of two xCORE Tiles, each comprising a flexible logical processing cores with tightly integrated I/O and on-chip memory.

5.1 Logical cores

MIPS

800 MIPS

1000 MIPS

Frequency

400 MHz

500 MHz

Speed

grade

8

10

Each tile has 8 active logical cores, which issue instructions down a shared fourstage pipeline. Instructions from the active cores are issued round-robin. If up to four logical cores are active, each core is allocated a quarter of the processing cycles. If more than four logical cores are active, each core is allocated at least 1/ncycles (for *n* cores). Figure 2 shows the guaranteed core performance depending on the number of cores used.

2

100

125

3

100

125

Minimum MIPS per core (for *n* cores)

5

80

100

6

67

83

7

57

71

8

50

63

4

100

125

Figure 2: Logical core performance

There is no way that the performance of a logical core can be reduced below these predicted levels. Because cores may be delayed on I/O, however, their unused processing cycles can be taken by other cores. This means that for more than four logical cores, the performance of each core is often higher than the predicted minimum but cannot be guaranteed.

1

100

125

The logical cores are triggered by events instead of interrupts and run to completion. A logical core can be paused to wait for an event.

5.2 xTIME scheduler

The xTIME scheduler handles the events generated by xCORE Tile resources, such as channel ends, timers and I/O pins. It ensures that all events are serviced and synchronized, without the need for an RTOS. Events that occur at the I/O pins are handled by the Hardware-Response ports and fed directly to the appropriate xCORE Tile. An xCORE Tile can also choose to wait for a specified time to elapse, or for data to become available on a channel.

Tasks do not need to be prioritised as each of them runs on their own logical xCORE. It is possible to share a set of low priority tasks on a single core using cooperative multitasking.

5.3 Hardware Response Ports

Hardware Response ports connect an xCORE tile to one or more physical pins and as such define the interface between hardware attached to the XS1-L16A-128-QF124, and the software running on it. A combination of 1 bit, 4bit, 8bit, 16bit and 32bit ports are available. All pins of a port provide either output or input. Signals in different directions cannot be mapped onto the same port.



Figure 5: Switch, links and channel ends

Information on the supported routing topologies that can be used to connect multiple devices together can be found in the XS1-L Link Performance and Design Guide, X2999.

6 PLL

The PLL creates a high-speed clock that is used for the switch, tile, and reference clock.

The PLL multiplication value is selected through the two MODE pins, and can be changed by software to speed up the tile or use less power. The MODE pins are set as shown in Figure 6:

	Oscillator	MC	DDE	Tile	PLL Ratio	PLL settings			
_	Frequency	1	0	Frequency		OD	F	R	
6:	5-13 MHz	0	0	130-399.75 MHz	30.75	1	122	0	
er	13-20 MHz	1	1	260-400.00 MHz	20	2	119	0	
d	20-48 MHz	1	0	167-400.00 MHz	8.33	2	49	0	
S	48-100 MHz	0	1	196-400.00 MHz	4	2	23	0	

Figure 6 PLL multiplier values and MODE pins

Figure 6 also lists the values of *OD*, *F* and *R*, which are the registers that define the ratio of the tile frequency to the oscillator frequency:

$$F_{core} = F_{osc} \times \frac{F+1}{2} \times \frac{1}{R+1} \times \frac{1}{OD+1}$$

-XMOS"

The JTAG usercode register can be read by using the USERCODE instruction. Its contents are specified in Figure 13. The OTP User ID field is read from bits [22:31] of the security register on xCORE Tile 0, *see* §8.1 (all zero on unprogrammed devices).

Figure 13: USERCODE return value

Bit	31		Usercode Register Bit0																												
OTP User ID					Unused Silicon Revision																										
0	0	0	0	0	0	0	0	0	0	0	0	0	0	1	0	1	0	0	0	0	0	0	0	0	0	0	0	0	0	0	0
0 0 0		0 2			2	8			0				0				()													

9.1 PCU

PCU_WAKE should be left unconnected, PCU_GATE should be left unconnected and PCU_CLK must be tied to CLK.

10 Board Integration

The device has the following power supply pins:

- VDD pins for the xCORE Tile
- ► VDDIO pins for the I/O lines
- PLL_AVDD pins for the PLL
- PCU_VDD and PCU_VDDIO pins for the PCU
- OTP_VCC pins for the OTP

Several pins of each type are provided to minimize the effect of inductance within the package, all of which must be connected. The power supplies must be brought up monotonically and input voltages must not exceed specification at any time.

The VDD supply must ramp from 0V to its final value within 10 ms to ensure correct startup.

The VDDIO and OTP_VCC supply must ramp to its final value before VDD reaches 0.4 V.

The PLL_AVDD supply should be separated from the other noisier supplies on the board. The PLL requires a very clean power supply, and a low pass filter (for example, a 2.2Ω resistor and 100 nF multi-layer ceramic capacitor) is recommended on this pin.

The PCU_VDD supply must be connected to the VDD supply.

The PCU_VDDIO supply must be connected to the VDDIO supply.

The OTP_VCC supply should be connected to the VDDIO supply.

The following ground pins are provided:

- PLL_AGND for PLL_AVDD
- ► GND for all other supplies

All ground pins must be connected directly to the board ground.

The VDD and VDDIO supplies should be decoupled close to the chip by several 100 nF low inductance multi-layer ceramic capacitors between the supplies and GND (for example, 4x100nF 0402 low inductance MLCCs per supply rail). The ground side of the decoupling capacitors should have as short a path back to the GND pins as possible. A bulk decoupling capacitor of at least 10 uF should be placed on each of these supplies.

RST_N is an active-low asynchronous-assertion global reset signal. Following a reset, the PLL re-establishes lock after which the device boots up according to the boot mode (*see* §7). RST_N and must be asserted low during and after power up for 100 ns.

10.1 Land patterns and solder stencils

The land pattern recommendations in this document are based on a RoHS compliant process and derived, where possible, from the nominal *Generic Requirements for Surface Mount Design and Land Pattern Standards* IPC-7351B specifications. This standard aims to achieve desired targets of heel, toe and side fillets for solder-joints.

Solder paste and ground via recommendations are based on our engineering and development kit board production. They have been found to work and optimized as appropriate to achieve a high yield. The size, type and number of vias used in the center pad affects how much solder wicks down the vias during reflow. This in turn, along with solder paster coverage, affects the final assembled package height. These factors should be taken into account during design and manufacturing of the PCB.

The following land patterns and solder paste contains recommendations. Final land pattern and solder paste decisions are the responsibility of the customer. These should be tuned during manufacture to suit the manufacturing process.

The package is a 124 pin dual row Quad Flat No lead package with exposed heat slug on a 0.5mm pitch. An example land pattern is shown in Figure 14.

Pad widths and spacings are such that solder mask can still be applied between the pads using standard design rules. This is highly recommended to reduce solder shorts between pads. See the recommended PCB solder mask diagram in Figure 15.

10.2 Solder Stencil

The solder joints in the QFN package are formed exclusively from the solder paste deposited from the solder stencil. At the small aperture sizes required, the design of the stencil becomes important to ensure a reliable final solder joint volume and reliable solder joints.



12 Package Information



-XMOS[®]

 \Rightarrow ref, ...), where tileref is the name of the xCORE Tile, e.g. tile[1]. These functions implement the protocols described below.

Instead of using the functions above, a channel-end can be allocated to communicate with the xCORE tile configuration registers. The destination of the channel-end should be set to 0xnnnnC20C where nnnnn is the tile-identifier.

A write message comprises the following:

control-token	24-bit response	16-bit	32-bit	control-token
192	channel-end identifier	register number	data	1

The response to a write message comprises either control tokens 3 and 1 (for success), or control tokens 4 and 1 (for failure).

A read message comprises the following:

control-token	24-bit response	16-bit	control-token
193	channel-end identifier	register number	1

The response to the read message comprises either control token 3, 32-bit of data, and control-token 1 (for success), or control tokens 4 and 1 (for failure).

A.3 Accessing node configuration

Node configuration registers can be accessed through the interconnect using the functions write_node_config_reg(device, ...) and read_node_config_reg(device, ...), where device is the name of the node. These functions implement the protocols described below.

Instead of using the functions above, a channel-end can be allocated to communicate with the node configuration registers. The destination of the channel-end should be set to 0xnnnnC30C where nnnn is the node-identifier.

A write message comprises the following:

control-token	24-bit response	16-bit	32-bit	control-token
192	channel-end identifier	register number	data	1

The response to a write message comprises either control tokens 3 and 1 (for success), or control tokens 4 and 1 (for failure).

A read message comprises the following:

control-token	24-bit response	16-bit	control-token		
193	channel-end identifier	register number	1		

The response to a read message comprises either control token 3, 32-bit of data, and control-token 1 (for success), or control tokens 4 and 1 (for failure).

-XM()S

B.1 RAM base address: 0x00

This register contains the base address of the RAM. It is initialized to 0x00010000.

0x00: RAM base address

- -	Bits	Perm	Init	Description
e.	31:2	RW		Most significant 16 bits of all addresses.
s	1:0	RO	-	Reserved

B.2 Vector base address: 0x01

Base address of event vectors in each resource. On an interrupt or event, the 16 most significant bits of the destination address are provided by this register; the least significant 16 bits come from the event vector.

0x01: Vector base address

Bits	Perm	Init	Description
31:16	RW		The most significant bits for all event and interrupt vectors.
15:0	RO	-	Reserved

B.3 xCORE Tile control: 0x02

Register to control features in the xCORE tile

Bits	Perm	Init	Description
31:6	RO	-	Reserved
5	RW	0	Set to 1 to select the dynamic mode for the clock divider when the clock divider is enabled. In dynamic mode the clock divider is only activated when all active logical cores are paused. In static mode the clock divider is always enabled.
4	RW	0	Set to 1 to enable the clock divider. This slows down the xCORE tile clock in order to use less power.
3:0	RO	-	Reserved

0x02: xCORE Tile control

B.4 xCORE Tile boot status: 0x03

This read-only register describes the boot status of the xCORE tile.

-XMOS-

0x11:	Bits	Perm	Init	Description
Debug SPC	31:0	DRW		Value.

B.13 Debug SSP: 0x12

This register contains the value of the SSP register when the debugger was called.

0x12:	Bits	Perm	Init	Description
Debug SSP	31:0	DRW		Value.

B.14 DGETREG operand 1: 0x13

The resource ID of the logical core whose state is to be read.

0x13: DGETREG	Bits	Perm	Init	Description
	31:8	RO	-	Reserved
operand 1	7:0	DRW		Thread number to be read

B.15 DGETREG operand 2: 0x14

Register number to be read by DGETREG

0x14: DGETREG operand 2

Bits	Perm	Init	Description
31:5	RO	-	Reserved
4:0	DRW		Register number to be read

B.16 Debug interrupt type: 0x15

Register that specifies what activated the debug interrupt.

-XMC

0x80 .. 0x83: Resources breakpoint mask

rces oint	Bits	Perm	Init	Description
nask	31:0	DRW		Value.

B.26 Resources breakpoint value: 0x90 .. 0x93

This set of registers contains the value for the four resource watchpoints.

0x90 .. 0x93: Resources breakpoint value

s It	Bits	Perm	Init	Description
e	31:0	DRW		Value.

B.27 Resources breakpoint control register: 0x9C .. 0x9F

This set of registers controls each of the four resource watchpoints.

	Bits	Perm	Init	Description
	31:24	RO	-	Reserved
	23:16	DRW	0	A bit for each logical core in the tile allowing the breakpoint to be enabled individually for each logical core.
	15:2	RO	-	Reserved
0x9C 0x9F: Resources breakpoint control	1	DRW	0	By default, resource watchpoints trigger when the resource id masked with the set Mask equals the Value. If set to 1, resource watchpoints trigger when the resource id masked with the set Mask is not equal to the Value.
register	0	DRW	0	When 1 the instruction breakpoint is enabled.

-XMOS°

40

C Tile Configuration

The xCORE Tile control registers can be accessed using configuration reads and writes (use write_tile_config_reg(tileref, ...) and read_tile_config_reg(tileref, ...) for reads and writes).

Number	Perm	Description
0x00	RO	Device identification
0x01	RO	xCORE Tile description 1
0x02	RO	xCORE Tile description 2
0x04	CRW	Control PSwitch permissions to debug registers
0×05	CRW	Cause debug interrupts
0x06	RW	xCORE Tile clock divider
0x07	RO	Security configuration
0x10 0x13	RO	PLink status
0x20 0x27	CRW	Debug scratch
0x40	RO	PC of logical core 0
0x41	RO	PC of logical core 1
0x42	RO	PC of logical core 2
0x43	RO	PC of logical core 3
0x44	RO	PC of logical core 4
0x45	RO	PC of logical core 5
0x46	RO	PC of logical core 6
0x47	RO	PC of logical core 7
0x60	RO	SR of logical core 0
0x61	RO	SR of logical core 1
0x62	RO	SR of logical core 2
0x63	RO	SR of logical core 3
0x64	RO	SR of logical core 4
0x65	RO	SR of logical core 5
0x66	RO	SR of logical core 6
0x67	RO	SR of logical core 7
0x80 0x9F	RO	Chanend status

-XMOS°

Figure 31: Summary 0x04: Control PSwitch permissions to debug registers

Bits	Perm	Init	Description	
31:1	RO	-	Reserved	
0	CRW		Set to 1 to restrict PSwitch access to all CRW marked registers to become read-only rather than read-write.	

C.5 Cause debug interrupts: 0x05

This register can be used to raise a debug interrupt in this xCORE tile.

0x05: Cause debug interrupts

Bit	ts	Perm	Init	Description	
31:	:2	RO	-	Reserved	
	1	RO	0	Set to 1 when the processor is in debug mode.	
	0	CRW	0	Set to 1 to request a debug interrupt on the processor.	

C.6 xCORE Tile clock divider: 0x06

This register contains the value used to divide the PLL clock to create the xCORE tile clock. The divider is enabled under control of the tile control register

0x06: xCORE Tile clock divider

	Bits	Perm	Init	Description
e.	31:8	RO	-	Reserved
r	7:0	RW		Value of the clock divider minus one.

C.7 Security configuration: 0x07

Copy of the security register as read from OTP.

0x07: Security configuration

ity	Bits	Perm	Init	Description
on	31:0	RO		Value.

C.8 PLink status: 0x10 .. 0x13

Status of each of the four processor links; connecting the xCORE tile to the switch.

-XMOS[®]

C.11 PC of logical core 1: 0x41

Ox41:
PC of logical
core 1BitsPermInitDescription31:0ROValue.

C.12 PC of logical core 2: 0x42

0x42: PC of logical	Bits	Perm	Init	Description
core 2	31:0	RO		Value.

C.13 PC of logical core 3: 0x43

0x43.				
PC of logical	Bits	Perm	Init	Description
core 3	31:0	RO		Value.

C.14 PC of logical core 4: 0x44

0x44: PC of logical core 4

Bits	Perm	Init	Description
31:0	RO		Value.

C.15 PC of logical core 5: 0x45

0.45				
PC of logical	Bits	Perm	Init	Description
core 5	31:0	RO		Value.

-XMOS

C.16 PC of logical core 6: 0x46

0x46: PC of logical core 6

 Bits
 Perm
 Init
 Description

 31:0
 RO
 Value.

C.17 PC of logical core 7: 0x47

0x47: PC of logical core 7

Bits	Perm	Init	Description
31:0	RO		Value.

C.18 SR of logical core 0: 0x60

Value of the SR of logical core 0

0x60: SR of logical core 0

Bits

31:0

Perm	Init	Description
RO		Value.

C.19 SR of logical core 1: 0x61

0x61: SR of logical core 1

1: al	Bits	Perm	Init	Description
1	31:0	RO		Value.

C.20 SR of logical core 2: 0x62

0x62: SR of logical core 2

Bits	Perm	Init	Description
31:0	RO		Value.



C.21 SR of logical core 3: 0x63

Ox63:
SR of logical
core 3BitsPermInitDescription31:0ROValue.

C.22 SR of logical core 4: 0x64

SR of logical	Bits	Perm	Init	Description
core 4	31:0	RO		Value.

C.23 SR of logical core 5: 0x65

0x65				
SR of logical	Bits	Perm	Init	Description
core 5	31:0	RO		Value.

C.24 SR of logical core 6: 0x66

0x66: SR of logical core 6

Bits

31:0

Perm	Init	Description
RO		Value.

C.25 SR of logical core 7: 0x67

0,467				
SR of logical core 7	Bits	Perm	Init	Description
	31:0	RO		Value.

C.26 Chanend status: 0x80 .. 0x9F

These registers record the status of each channel-end on the tile.

47

D Node Configuration

The digital node control registers can be accessed using configuration reads and writes (use write_node_config_reg(device, ...) and read_node_config_reg(device, ...) for reads and writes).

Number	Perm	Description
0x00	RO	Device identification
0x01	RO	System switch description
0x04	RW	Switch configuration
0x05	RW	Switch node identifier
0x06	RW	PLL settings
0x07	RW	System switch clock divider
0x08	RW	Reference clock
0x0C	RW	Directions 0-7
0x0D	RW	Directions 8-15
0x10	RW	DEBUG_N configuration
0x1F	RO	Debug source
0x20 0x27	RW	Link status, direction, and network
0x40 0x43	RW	PLink status and network
0x80 0x87	RW	Link configuration and initialization
0xA0 0xA7	RW	Static link configuration

Figure 32: Summary

D.1 Device identification: 0x00

This register contains version and revision identifiers and the mode-pins as sampled at boot-time.

	Bits	Perm	Init	Description
	31:24	RO	0x00	Chip identifier.
0×00:	23:16	RO		Sampled values of pins MODE0, MODE1, on reset.
Device	15:8	RO		SSwitch revision.
identification	7:0	RO		SSwitch version.

D.2 System switch description: 0x01

This register specifies the number of processors and links that are connected to this switch.

-XMOS

Bits	Perm	Init	Description
31:26	RO	-	Reserved
25:23	RW		OD: Output divider value The initial value depends on pins MODE0 and MODE1.
22:21	RO	-	Reserved
20:8	RW		F: Feedback multiplication ratio The initial value depends on pins MODE0 and MODE1.
7	RO	-	Reserved
6:0	RW		R: Oscilator input divider value The initial value depends on pins MODE0 and MODE1.

0x06: PLL settings

D.6 System switch clock divider: 0x07

Sets the ratio of the PLL clock and the switch clock.

0x07 System switch clock divider

7.	Bits	Perm	Init	Description
m.	31:16	RO	-	Reserved
ck er	15:0	RW	0	Switch clock divider. The PLL clock will be divided by this value plus one to derive the switch clock.

D.7 Reference clock: 0x08

Sets the ratio of the PLL clock and the reference clock used by the node.

0x08: Reference clock

Bits	Perm	Init	Description
31:16	RO	-	Reserved
15:0	RW	3	Architecture reference clock divider. The PLL clock will be divided by this value plus one to derive the 100 MHz reference clock.

D.8 Directions 0-7: 0x0C

This register contains eight directions, for packets with a mismatch in bits 7..0 of the node-identifier. The direction in which a packet will be routed is goverened by the most significant mismatching bit.

XS1-L16A-128-QF124

Bits	Perm	Init	Description
31:28	RW	0	The direction for packets whose first mismatching bit is 7.
27:24	RW	0	The direction for packets whose first mismatching bit is 6.
23:20	RW	0	The direction for packets whose first mismatching bit is 5.
19:16	RW	0	The direction for packets whose first mismatching bit is 4.
15:12	RW	0	The direction for packets whose first mismatching bit is 3.
11:8	RW	0	The direction for packets whose first mismatching bit is 2.
7:4	RW	0	The direction for packets whose first mismatching bit is 1.
3:0	RW	0	The direction for packets whose first mismatching bit is 0.

0x0C: Directions 0-7

D.9 Directions 8-15: 0x0D

This register contains eight directions, for packets with a mismatch in bits 15..8 of the node-identifier. The direction in which a packet will be routed is goverened by the most significant mismatching bit.

Bits	Perm	Init	Description
31:28	RW	0	The direction for packets whose first mismatching bit is 15.
27:24	RW	0	The direction for packets whose first mismatching bit is 14.
23:20	RW	0	The direction for packets whose first mismatching bit is 13.
19:16	RW	0	The direction for packets whose first mismatching bit is 12.
15:12	RW	0	The direction for packets whose first mismatching bit is 11.
11:8	RW	0	The direction for packets whose first mismatching bit is 10.
7:4	RW	0	The direction for packets whose first mismatching bit is 9.
3:0	RW	0	The direction for packets whose first mismatching bit is 8.

0x0D: Directions 8-15

D.10 DEBUG_N configuration: 0x10

Configures the behavior of the DEBUG_N pin.

	Bits	Perm	Init	Description
	31:2	RO	-	Reserved
-):	1	RW	0	Set to 1 to enable signals on DEBUG_N to generate DCALL on the core.
N n	0	RW	0	When set to 1, the DEBUG_N wire will be pulled down when the node enters debug mode.

0x10 DEBUG_N configuratior 52

I PCB Layout Design Check List

✓ This section is a checklist for use by PCB designers using the XS1-L16A-128-QF124. Each of the following sections contains items to check for each design.

I.1 Land pattern and solder stencil

- \Box You have used a land pattern suitable for the small QFN pads. (Section 10.1)
- You have used a solder stencil with the correct aperture and thinness. (Section 10.1)

I.2 Ground Plane

- □ Multiple vias (eg, 9) have been used to connect the center pad to the PCB ground plane. These minimize impedance and conduct heat away from the device. (Section 10.3).
- Other than ground vias, there are no (or only a few) vias underneath or closely around the device. This create a good, solid, ground plane.

I.3 Power supply decoupling

- \Box The decoupling capacitors are all placed close to a supply pin (Section 10).
- \Box The decoupling capacitors are spaced around the device (Section 10).
- The ground side of each decoupling capacitor has a direct path back to the center ground of the device.

I.4 PLL_AVDD

The PLL_AVDD filter (especially the capacitor) is placed close to the PLL_AVDD pin (Section 10).

-XM()S

62