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Applications of "[Embedded - Microcontrollers](#)"

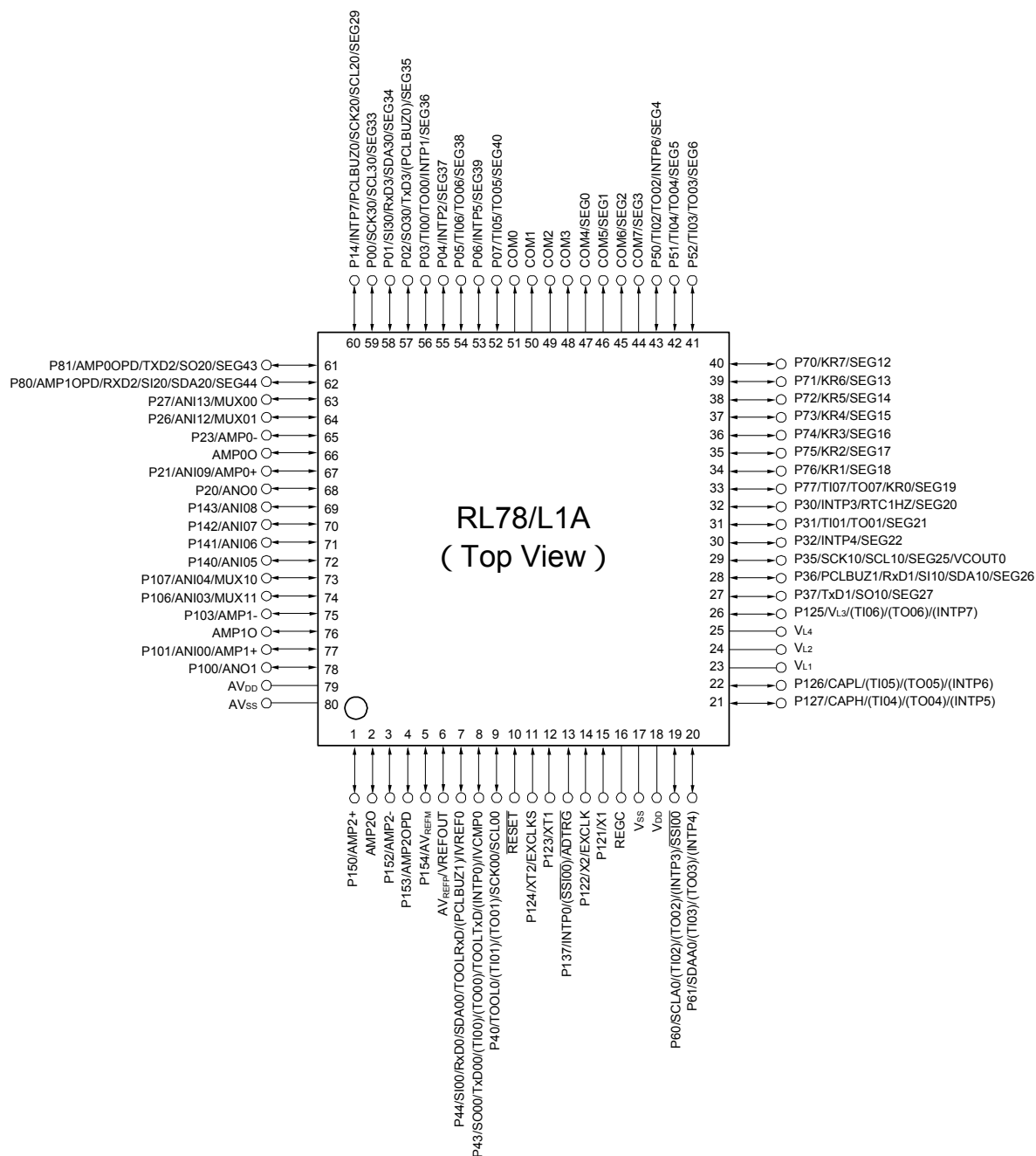
Details

Product Status	Active
Core Processor	RL78
Core Size	16-Bit
Speed	24MHz
Connectivity	CSI, I ² C, LINbus, SPI, UART/USART
Peripherals	LCD, LVD, POR, PWM, WDT
Number of I/O	79
Program Memory Size	64KB (64K x 8)
Program Memory Type	FLASH
EEPROM Size	8K x 8
RAM Size	5.5K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 14x12b; D/A 2x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	100-LQFP
Supplier Device Package	100-LFQFP (14x14)
Purchase URL	https://www.e-xfl.com/product-detail/renesas-electronics-america/r5f11mpeafb-50

1.3 Pin Configuration (Top View)

1.3.1 80-pin products

- 80-pin plastic LQFP (fine pitch) (12 × 12 mm, 0.5 mm pitch)



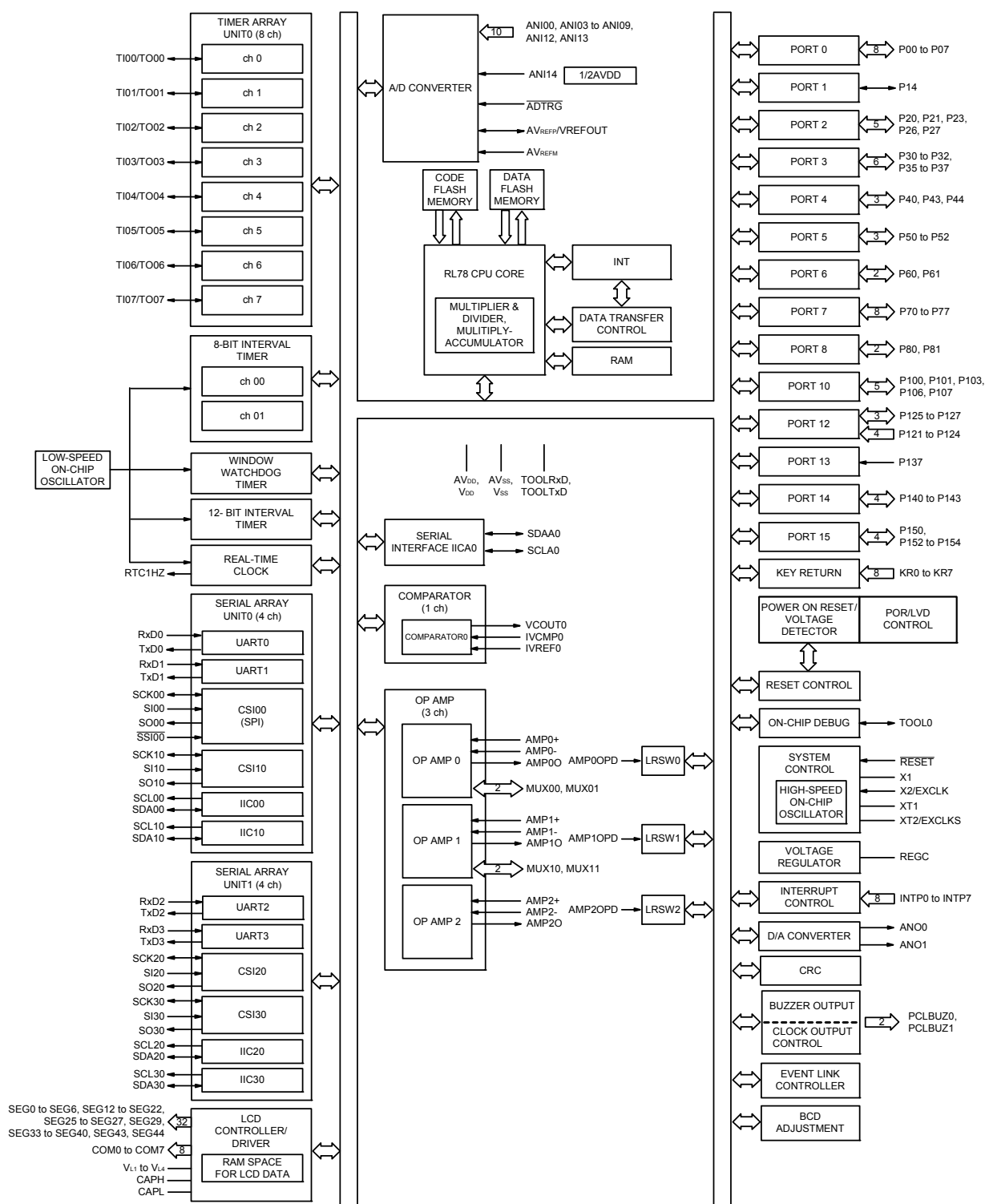
Caution Connect the REGC pin to VSS pin via a capacitor (0.47 to 1 μF).

Remark 1. For pin identification, see 1.4 Pin Identification.

Remark 2. Functions in parentheses in the above figure can be assigned via settings in the peripheral I/O redirection register (PIOR).

1.5 Block Diagram

1.5.1 80-pin products



2.1 Absolute Maximum Ratings

Absolute Maximum Ratings (TA = 25°C)

(1/3)

Parameter	Symbols	Conditions	Ratings	Unit
Supply voltage	V _{DD}		-0.5 to +6.5	V
	AV _{DD}	AV _{DD} ≤ V _{DD}	-0.5 to +4.6	V
REGC pin input voltage	V _{IREGC}	REGC	-0.3 to +2.8 and -0.3 to V _{DD} + 0.3 Note 1	V
Input voltage	V _{I1}	P00 to P07, P11 to P17, P30 to P37, P40 to P44, P50 to P57, P70 to P77, P80, P81, P125 to P127, P137, EXCLK, EXCLKS, RESET	-0.3 to V _{DD} + 0.3 Note 2	V
	V _{I2}	P60, P61 (N-ch open-drain)	-0.3 to +6.5	V
	V _{I4}	IVCMP0	-0.7 to V _{DD} + 0.7	V
	V _{I5}	P20, P21, P23 to P27, P100, P101, P103 to P107, P140 to P143, P150, P152 to P154	-0.3 to AV _{DD} + 0.3 Note 3	V
Output voltage	V _{O1}	P00 to P07, P11 to P17, P30 to P37, P40 to P44, P50 to P57, P60, P61, P70 to P77, P80, P81, P125 to P127, P130	-0.3 to V _{DD} + 0.3 Note 2	V
	V _{O2}	P20, P21, P23 to P27, P100, P101, P103 to P107, P140 to P143, P150, P152 to P154	-0.3 to AV _{DD} + 0.3 Note 3	V
Analog input voltage	V _{AI1}	ANI0 to ANI13	-0.3 to AV _{DD} + 0.3 and AV _{REF(+)} + 0.3 Notes 2, 4	V

Note 1. Connect the REGC pin to V_{SS} via a capacitor (0.47 to 1 μF). This value regulates the absolute maximum rating of the REGC pin. Do not use this pin with voltage applied to it.

Note 2. Must be 6.5 V or lower.

Note 3. Must be 4.6 V or lower.

Note 4. Do not exceed AV_{REF(+)} + 0.3 V in case of A/D conversion target pin.

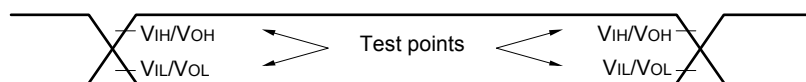
Caution Product quality may suffer if the absolute maximum rating is exceeded even momentarily for any parameter. That is, the absolute maximum ratings are rated values at which the product is on the verge of suffering physical damage, and therefore the product must be used under conditions that ensure that the absolute maximum ratings are not exceeded.

Remark 1. Unless specified otherwise, the characteristics of alternate-function pins are the same as those of the port pins.

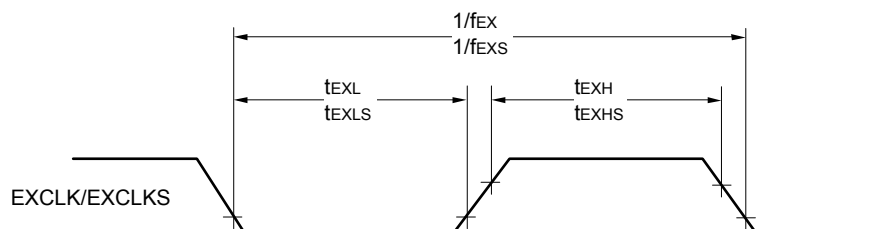
Remark 2. AV_{REF(+)}: + side reference voltage of the A/D converter.

Remark 3. V_{SS}: Reference voltage

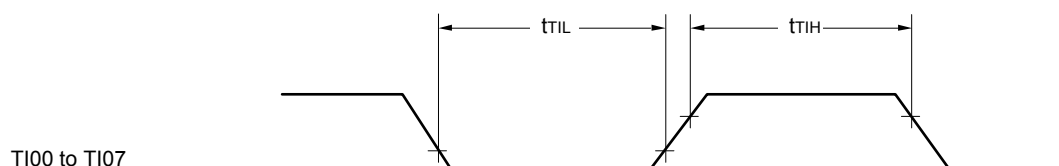
AC Timing Test Points



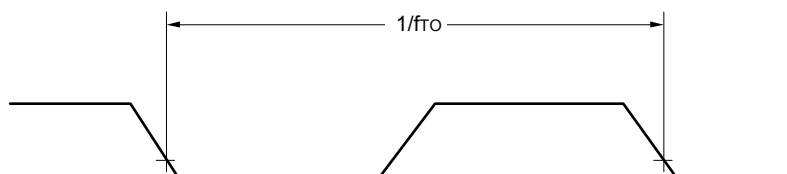
External System Clock Timing



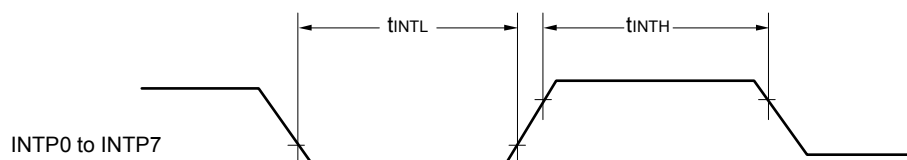
TI/TO Timing



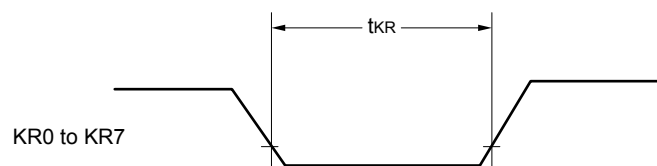
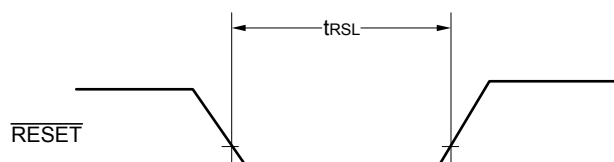
TO00 to TO07



Interrupt Request Input Timing

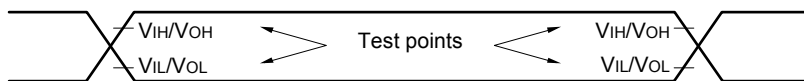


Key Interrupt Input Timing

 $\overline{\text{RESET}}$ Input Timing

2.5 Peripheral Functions Characteristics

AC Timing Test Points



2.5.1 Serial array unit

(1) During communication at same potential (UART mode)

(TA = -40 to +85 °C, 1.8 V ≤ V_{DD} ≤ 3.6 V, V_{SS} = 0 V)

Parameter	Symbol	Conditions	HS (high-speed main) Mode		LS (low-speed main) Mode		Unit
			MIN.	MAX.	MIN.	MAX.	
Transfer rate Note 1		2.7 V ≤ V _{DD} ≤ 3.6 V		f _{MCK} /6 Note 2		f _{MCK} /6	bps
		Theoretical value of the maximum transfer rate f _{MCK} = f _{CLK} Note 3		4.0		1.3	Mbps
		2.4 V ≤ V _{DD} ≤ 3.6 V		f _{MCK} /6 Note 2		f _{MCK} /6	bps
		Theoretical value of the maximum transfer rate f _{MCK} = f _{CLK} Note 3		2.6		1.3	Mbps
		1.8 V ≤ V _{DD} ≤ 3.6 V	—			f _{MCK} /6 Note 2	bps
		Theoretical value of the maximum transfer rate f _{MCK} = f _{CLK} Note 3	—			1.3	Mbps

Note 1. Transfer rate in the SNOOZE mode is 4800 bps only.

Note 2. The following conditions are required for low voltage interface.

2.4 V ≤ V_{DD} < 2.7 V: MAX. 2.6 Mbps

1.8 V ≤ V_{DD} < 2.4 V: MAX. 1.3 Mbps

Note 3. The maximum operating frequencies of the CPU/peripheral hardware clock (f_{CLK}) are:

HS (high-speed main) mode: 24 MHz (2.7 V ≤ V_{DD} ≤ 3.6 V)

16 MHz (2.4 V ≤ V_{DD} ≤ 3.6 V)

LS (low-speed main) mode: 8 MHz (1.8 V ≤ V_{DD} ≤ 3.6 V)

Caution Select the normal input buffer for the RxDq pin and the normal output mode for the TxDq pin by using port input mode register g (PIMg) and port output mode register g (POMg).

(2) During communication at same potential (CSI mode) (master mode, SCKp... internal clock output, corresponding CSI00 only)

(TA = -40 to +85 °C, 2.7 V ≤ VDD ≤ 3.6 V, VSS = 0 V)

Parameter	Symbol	Conditions		HS (high-speed main) Mode		LS (low-speed main) Mode		Unit
				MIN.	MAX.	MIN.	MAX.	
SCKp cycle time	t _{KCY1}	t _{KCY1} ≥ f _{CLK} /2	2.7 V ≤ V _{DD} ≤ 3.6 V	167		250		ns
SCKp high-/low-level width	t _{KL1}	2.7 V ≤ V _{DD} ≤ 3.6 V		t _{KCY1} /2 - 10		t _{KCY1} /2 - 50		ns
Slp setup time (to SCKp↑) Note 1	t _{SIK1}	2.7 V ≤ V _{DD} ≤ 3.6 V		33		110		ns
Slp hold time (from SCKp↑) Note 2	t _{SH1}	2.7 V ≤ V _{DD} ≤ 3.6 V		10		10		ns
Delay time from SCKp↓ to SOp output Note 3	t _{KSO1}	C = 20 pF Note 4			10		10	ns

Note 1. When DAPmn = 0 and CKPmn = 0, or DAPmn = 1 and CKPmn = 1. The Slp setup time becomes “to SCKp↓” when DAPmn = 0 and CKPmn = 1, or DAPmn = 1 and CKPmn = 0.

Note 2. When DAPmn = 0 and CKPmn = 0, or DAPmn = 1 and CKPmn = 1. The Slp hold time becomes “from SCKp↓” when DAPmn = 0 and CKPmn = 1, or DAPmn = 1 and CKPmn = 0.

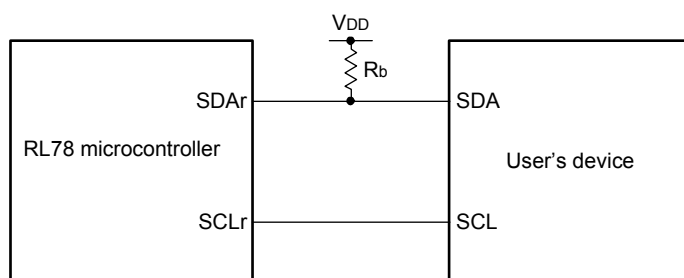
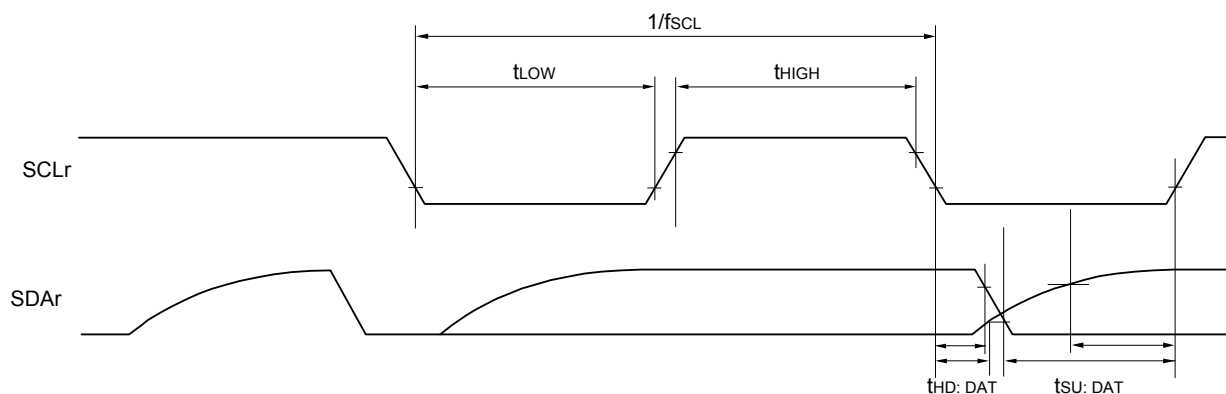
Note 3. When DAPmn = 0 and CKPmn = 0, or DAPmn = 1 and CKPmn = 1. The delay time to SOp output becomes “from SCKp↑” when DAPmn = 0 and CKPmn = 1, or DAPmn = 1 and CKPmn = 0.

Note 4. C is the load capacitance of the SCKp and SOp output lines.

Caution Select the normal input buffer for the SIp pin and the normal output mode for the SOp pin and SCKp pin by using port input mode register g (PIMg) and port output mode register g (POMg).

Remark 1. p: CSI number (p = 00), m: Unit number (m = 0), n: Channel number (n = 0), g: PIM and POM number (g = 4)

Remark 2. f_{MCK}: Serial array unit operation clock frequency
(Operation clock to be set by the CKSmn bit of serial mode register mn (SMRmn). m: Unit number, n: Channel number (mn = 00))

Simplified I²C mode connection diagram (during communication at same potential)**Simplified I²C mode serial transfer timing (during communication at same potential)**

Remark 1. $R_b[\Omega]$: Communication line (SDAr) pull-up resistance, $C_b[F]$: Communication line (SCLr, SDAr) load capacitance

Remark 2. r: IIC number (r = 00, 10, 20, 30), g: PIM number (g = 0, 1, 3, 4, 8),
h: POM number (h = 0 to 3)

Remark 3. f_{MCK} : Serial array unit operation clock frequency
(Operation clock to be set by the CKSmn bit of serial mode register mn (SMRmn). m: Unit number (m = 0, 1),
n: Channel number (n = 0, 2), mn = 00 to 03, 10 to 13)

(8) Communication at different potential (1.8 V, 2.5 V) (CSI mode) (master mode, SCKp... internal clock output)**(TA = -40 to +85 °C, 1.8 V ≤ VDD ≤ 3.6 V, VSS = 0 V)(2/2)**

Parameter	Symbol	Conditions	HS (high-speed main) Mode		LS (low-speed main) Mode		Unit
			MIN.	MAX.	MIN.	MAX.	
Slp setup time (to SCKp↑) Note 1	tSIK1	2.7 V ≤ VDD ≤ 3.6 V, 2.3 V ≤ Vb ≤ 2.7 V, Cb = 30 pF, Rb = 2.7 kΩ	177		479		ns
		1.8 V ≤ VDD < 3.3 V, 1.6 V ≤ Vb ≤ 2.0 V Note 3, Cb = 30 pF, Rb = 5.5 kΩ	479		479		ns
Slp hold time (from SCKp↑) Note 1	tKSI1	2.7 V ≤ VDD ≤ 3.6 V, 2.3 V ≤ Vb ≤ 2.7 V, Cb = 30 pF, Rb = 2.7 kΩ	19		19		ns
		1.8 V ≤ VDD < 3.3 V, 1.6 V ≤ Vb ≤ 2.0 V Note 3, Cb = 30 pF, Rb = 5.5 kΩ	19		19		ns
Delay time from SCKp↓ to SOp output Note 1	tKSO1	2.7 V ≤ VDD ≤ 3.6 V, 2.3 V ≤ Vb ≤ 2.7 V, Cb = 30 pF, Rb = 2.7 kΩ		195		195	ns
		1.8 V ≤ VDD < 3.3 V, 1.6 V ≤ Vb ≤ 2.0 V Note 3, Cb = 30 pF, Rb = 5.5 kΩ		483		483	ns
Slp setup time (to SCKp↓) Note 2	tSIK1	2.7 V ≤ VDD ≤ 3.6 V, 2.3 V ≤ Vb ≤ 2.7 V, Cb = 30 pF, Rb = 2.7 kΩ	44		110		ns
		1.8 V ≤ VDD < 3.3 V, 1.6 V ≤ Vb ≤ 2.0 V Note 3, Cb = 30 pF, Rb = 5.5 kΩ	110		110		ns
Slp hold time (from SCKp↓) Note 2	tKSI1	2.7 V ≤ VDD ≤ 3.6 V, 2.3 V ≤ Vb ≤ 2.7 V, Cb = 30 pF, Rb = 2.7 kΩ	19		19		ns
		1.8 V ≤ VDD < 3.3 V, 1.6 V ≤ Vb ≤ 2.0 V Note 3, Cb = 30 pF, Rb = 5.5 kΩ	19		19		ns
Delay time from SCKp↑ to SOp output Note 2	tKSO1	2.7 V ≤ VDD ≤ 3.6 V, 2.3 V ≤ Vb ≤ 2.7 V, Cb = 30 pF, Rb = 2.7 kΩ		25		25	ns
		1.8 V ≤ VDD < 3.3 V, 1.6 V ≤ Vb ≤ 2.0 V Note 3, Cb = 30 pF, Rb = 5.5 kΩ		25		25	ns

Note 1. When DAPmn = 0 and CKPmn = 0, or DAPmn = 1 and CKPmn = 1.**Note 2.** When DAPmn = 0 and CKPmn = 1, or DAPmn = 1 and CKPmn = 0.**Note 3.** Use it with VDD ≥ Vb.

Caution Select the TTL input buffer for the Slp pin and the N-ch open drain output (VDD tolerance) mode for the SOp pin and SCKp pin by using port input mode register g (PIMg) and port output mode register g (POMg). For VIH and VIL, see the DC characteristics with TTL input buffer selected.

(Remarks are listed on the next page.)

2.5.2 Serial interface IICA

(1) I²C standard mode

(TA = -40 to +85 °C, 1.8 V ≤ V_{DD} ≤ 3.6 V, V_{SS} = 0 V)

Parameter	Symbol	Conditions	HS (high-speed main) Mode		LS (low-speed main) Mode		Unit
			MIN.	MAX.	MIN.	MAX.	
SCLA0 clock frequency	f _{SCL}	Standard mode: 2.7 V ≤ V _{DD} ≤ 3.6 V	0	100	0	100	kHz
		f _{CLK} ≥ 1 MHz 1.8 V ≤ V _{DD} ≤ 3.6 V	—	—	0	100	kHz
Setup time of restart condition	t _{SU: STA}	2.7 V ≤ V _{DD} ≤ 3.6 V	4.7		4.7		μs
		1.8 V ≤ V _{DD} ≤ 3.6 V	—		4.7		μs
Hold time ^{Note 1}	t _{HD: STA}	2.7 V ≤ V _{DD} ≤ 3.6 V	4.0		4.0		μs
		1.8 V ≤ V _{DD} ≤ 3.6 V	—		4.0		μs
Hold time when SCLA0 = "L"	t _{LOW}	2.7 V ≤ V _{DD} ≤ 3.6 V	4.7		4.7		μs
		1.8 V ≤ V _{DD} ≤ 3.6 V	—		4.7		μs
Hold time when SCLA0 = "H"	t _{HIGH}	2.7 V ≤ V _{DD} ≤ 3.6 V	4.0		4.0		μs
		1.8 V ≤ V _{DD} ≤ 3.6 V	—		4.0		μs
Data setup time (reception)	t _{SU: DAT}	2.7 V ≤ V _{DD} ≤ 3.6 V	250		250		ns
		1.8 V ≤ V _{DD} ≤ 3.6 V	—		250		ns
Data hold time (transmission) ^{Note 2}	t _{HD: DAT}	2.7 V ≤ V _{DD} ≤ 3.6 V	0	3.45	0	3.45	μs
		1.8 V ≤ V _{DD} ≤ 3.6 V	—		0	3.45	μs
Setup time of stop condition	t _{SU: STO}	2.7 V ≤ V _{DD} ≤ 3.6 V	4.0		4.0		μs
		1.8 V ≤ V _{DD} ≤ 3.6 V	—		4.0		μs
Bus-free time	t _{BUF}	2.7 V ≤ V _{DD} ≤ 3.6 V	4.7		4.7		μs
		1.8 V ≤ V _{DD} ≤ 3.6 V	—		4.7		μs

Note 1. The first clock pulse is generated after this period when the start/restart condition is detected.

Note 2. The maximum value (MAX.) of t_{HD:DAT} is during normal transfer and a wait state is inserted in the ACK (acknowledge) timing.

Remark The maximum value of C_b (communication line capacitance) and the value of R_b (communication line pull-up resistor) at that time in each mode are as follows.

Standard mode: C_b = 400 pF, R_b = 2.7 kΩ

2.6.3 D/A converter characteristics

(1) When reference voltage = AVREFP, AVREFM

(TA = -40 to +85 °C, 1.8 V ≤ AVREFP ≤ AVDD ≤ VDD ≤ 3.6 V, VSS = AVSS = 0 V)

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Resolution	RES				12	bit
Load resistance	RO		30			kΩ
Load capacitance	CO				50	pF
Output voltage range	Tout		0.35		AVDD - 0.47	V
Differential linearity error	DNL			±0.5	±1.0	LSB
Integral linearity error	AINL			±0.4	±8.0	LSB
Zero-scale error	Ezs				±20	mV
Full-scale error	EFS				±20	mV
Output resistance	RO			5		Ω
Conversion time	tcon				30	μs

(2) When reference voltage = AVDD, AVSS

(TA = -40 to +85 °C, 1.8 V ≤ AVDD ≤ VDD ≤ 3.6 V, VSS = AVSS = 0 V)

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
Resolution	RES				12	bit
Load resistance	RO		30			kΩ
Load capacitance	CO				50	pF
Output voltage range	Tout		0.35		AVDD - 0.47	V
Differential linearity error	DNL			±0.5	±2.0	LSB
Integral linearity error	AINL			±0.4	±8.0	LSB
Zero-scale error	Ezs				±30	mV
Full-scale error	EFS				±30	mV
Output resistance	RO			5		Ω
Conversion time	tcon				30	μs

2.6.4 Comparator

(TA = -40 to +85 °C, 1.8 V ≤ VDD ≤ 3.6 V, VSS = 0 V)

Parameter	Symbol	Conditions		MIN.	TYP.	MAX.	Unit
Input voltage range	Ivref			0		VDD - 1.4	V
	Ivcmp			-0.3		VDD + 0.3	V
Output delay	td	VDD = 3.0 V Input slew rate > 50 mV/μs	High-speed comparator mode, standard mode			1.2	μs
			High-speed comparator mode, window mode			2.0	μs
			Low-speed comparator mode, standard mode		3	5.0	μs
High-electric-potential judgment voltage	VTW+	High-speed comparator mode, window mode			0.76 VDD		V
Low-electric-potential judgment voltage	VTW-	High-speed comparator mode, window mode			0.24 VDD		V
Operation stabilization wait time	tcMP			100			μs
Internal reference voltage <small>Note</small>	VBGR			1.38	1.45	1.50	V

Note Not usable in LS (low-speed main) mode, sub-clock operation, or STOP mode.

2.6.5 Rail to rail Operational amplifier characteristics

(TA = -40 to +85 °C, 2.2 V ≤ AVDD ≤ VDD ≤ 3.6 V, AVSS = VSS = 0 V)

Parameter	Symbol	Conditions		MIN	TYP	MAX	Unit
Circuit current	Icc1	Low-power consumption mode		—	10	16	μA
	Icc2	High-speed mode		—	210	350	μA
Common mode input range	Vicm1	Low-power consumption mode		0.1	—	AVDD-0.1	V
	Vicm2	High-speed mode		0.1	—	AVDD-0.1	V
Output voltage range	Vo1	Low-power consumption mode		0.1	—	AVDD-0.1	V
	Vo2	High-speed mode		0.1	—	AVDD-0.1	V
Input offset voltage	Fioff	Low-power consumption mode		-10	—	10	mV
		High-speed mode		-5	—	5	mV
Open gain	Av			—	120	—	dB
Gain-bandwidth (GB) product	GBW1	Low-power consumption mode		—	0.06	—	MHz
	GBW2	High-speed mode		—	1	—	MHz
Phase margin	PM	CL = 22 pF		50	—	—	deg
Gain margin	GM	CL = 20 pF		10	—	—	dB
Equivalent input noise	Vnoise1	f = 1 kHz	Low-power consumption mode	—	900	—	nV/√Hz
	Vnoise2	f = 10 kHz		—	450	—	nV/√Hz
	Vnoise3	f = 1 kHz	High-speed mode	—	80	—	nV/√Hz
	Vnoise4	f = 2 kHz		—	50	—	nV/√Hz
Power supply reduction ratio	PSRR			—	90	—	dB
Common mode signal reduction ratio	CMPR			—	90	—	dB
Operation stabilization wait time	Tturn1	CL = 20 pF	Low-power consumption mode	—	110	300	μs
	Tturn2	CL = 20 pF	High-speed mode	—	5	14	μs
Settling time	Tset1	CL = 20 pF	Low-power consumption mode	—	100	300	μs
	Tset2	CL = 20 pF	High-speed mode	—	4	14	μs
Slew rate	Tselw1	CL = 20 pF	Low-power consumption mode	0.01	0.04	—	V/μs
	Tselw2	CL = 20 pF	High-speed mode	0.3	0.7	—	V/μs
Load current	Iload1	Low-power consumption mode		-110	—	110	μA
	Iload2	High-speed mode		-110	—	110	μA
Load capacitance	CL			—	—	22	pF
Analog MUX ON resistance	Ron	One channel		—	—	1	kΩ

2.7 Power supply voltage rising slope characteristics

(TA = -40 to +85 °C, Vss = 0 V)

Parameter	Conditions	MIN.	TYP.	MAX.	Unit
Power supply voltage rising slope	SVDD			54	V/ms

Caution Make sure to keep the internal reset state by the LVD circuit or an external reset until VDD reaches the operating voltage range shown in 2.4 AC Characteristics.

2.8.3 Capacitor split method

(1) 1/3 bias method

(TA = -40 to +85 °C, 2.2 V ≤ VDD ≤ 3.6 V, VSS = 0 V)

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
VL4 voltage	VL4	C1 to C4 = 0.47 μF Note 2		VDD		V
VL2 voltage	VL2	C1 to C4 = 0.47 μF Note 2	2/3 VL4 - 0.1	2/3 VL4	2/3 VL4 + 0.1	V
VL1 voltage	VL1	C1 to C4 = 0.47 μF Note 2	1/3 VL4 - 0.1	1/3 VL4	1/3 VL4 + 0.1	V
Capacitor split wait time Note 1	tvWAIT		100			ms

Note 1. This is the wait time from when voltage bucking is started (VLCON = 1) until display is enabled (LCDON = 1).

Note 2. This is a capacitor that is connected between voltage pins used to drive the LCD.

C1: A capacitor connected between CAPH and CAPL

C2: A capacitor connected between VL1 and GND

C3: A capacitor connected between VL2 and GND

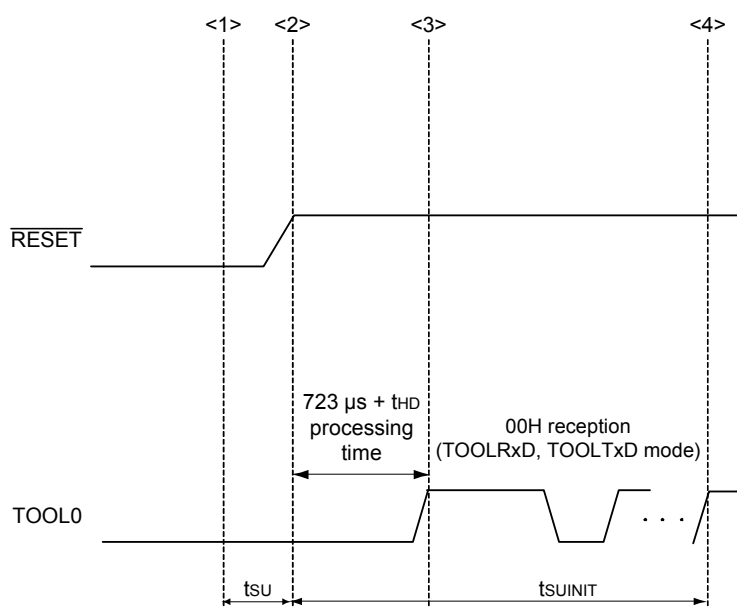
C4: A capacitor connected between VL4 and GND

C1 = C2 = C3 = C4 = 0.47 μF±30%

2.12 Timing Specs for Switching Modes

(TA = -40 to +85 °C, 1.8 V ≤ VDD ≤ 3.6 V, VSS = 0 V)

Parameter	Symbol	Conditions	MIN.	TYP.	MAX.	Unit
How long from when an external reset ends until the initial communication settings are specified	tsuINIT	POR and LVD reset must end before the external reset ends.			100	ms
How long from when the TOOL0 pin is placed at the low level until an external reset ends	tsu	POR and LVD reset must end before the external reset ends.	10			μs
Time to hold the TOOL0 pin at the low level after an external reset is released (excluding the processing time of the firmware to control the flash memory)	tHD	POR and LVD reset must end before the external reset ends.	1			ms



<1> The low level is input to the TOOL0 pin.

<2> The external reset ends (POR and LVD reset must end before the external reset ends.).

<3> The TOOL0 pin is set to the high level.

<4> Setting of the flash memory programming mode by UART reception and complete the baud rate setting.

Remark tsuINIT: The segment shows that it is necessary to finish specifying the initial communication settings within 100 ms from when the resets end.

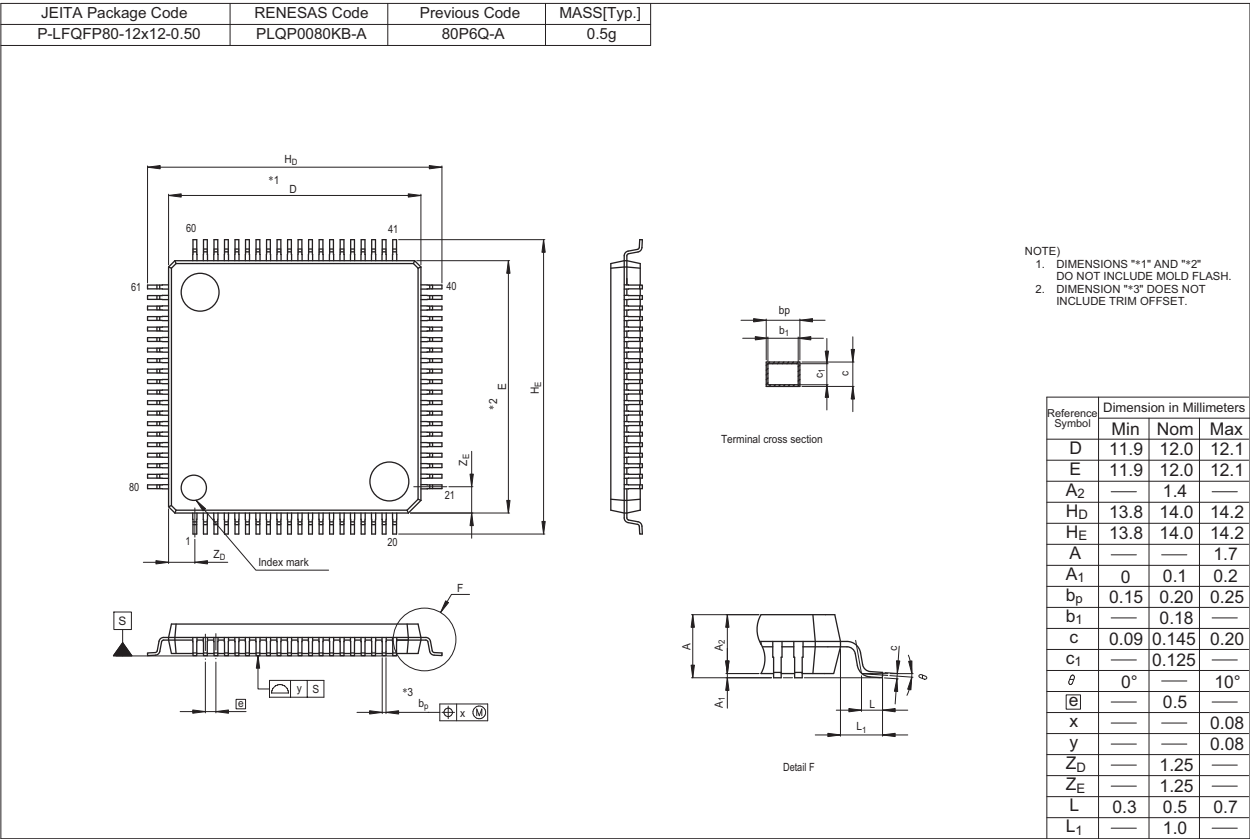
tsu: How long from when the TOOL0 pin is placed at the low level until an external reset ends

tHD: Time to hold the TOOL0 pin at the low level after an external reset is released (excluding the processing time of the firmware to control the flash memory)

3. PACKAGE DRAWINGS

3.1 80-pin products

R5F11MMDAFB, R5F11MMEAFA, R5F11MMFAFB



REVISION HISTORY	RL78/L1A Datasheet
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Rev.	Date	Description	
		Page	Summary
1.00	Aug 12, 2016	—	First Edition issued

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NOTES FOR CMOS DEVICES

- (1) **VOLTAGE APPLICATION WAVEFORM AT INPUT PIN:** Waveform distortion due to input noise or a reflected wave may cause malfunction. If the input of the CMOS device stays in the area between V_{IL} (MAX) and V_{IH} (MIN) due to noise, etc., the device may malfunction. Take care to prevent chattering noise from entering the device when the input level is fixed, and also in the transition period when the input level passes through the area between V_{IL} (MAX) and V_{IH} (MIN).
- (2) **HANDLING OF UNUSED INPUT PINS:** Unconnected CMOS device inputs can be cause of malfunction. If an input pin is unconnected, it is possible that an internal input level may be generated due to noise, etc., causing malfunction. CMOS devices behave differently than Bipolar or NMOS devices. Input levels of CMOS devices must be fixed high or low by using pull-up or pull-down circuitry. Each unused pin should be connected to VDD or GND via a resistor if there is a possibility that it will be an output pin. All handling related to unused pins must be judged separately for each device and according to related specifications governing the device.
- (3) **PRECAUTION AGAINST ESD:** A strong electric field, when exposed to a MOS device, can cause destruction of the gate oxide and ultimately degrade the device operation. Steps must be taken to stop generation of static electricity as much as possible, and quickly dissipate it when it has occurred. Environmental control must be adequate. When it is dry, a humidifier should be used. It is recommended to avoid using insulators that easily build up static electricity. Semiconductor devices must be stored and transported in an anti-static container, static shielding bag or conductive material. All test and measurement tools including work benches and floors should be grounded. The operator should be grounded using a wrist strap. Semiconductor devices must not be touched with bare hands. Similar precautions need to be taken for PW boards with mounted semiconductor devices.
- (4) **STATUS BEFORE INITIALIZATION:** Power-on does not necessarily define the initial status of a MOS device. Immediately after the power source is turned ON, devices with reset functions have not yet been initialized. Hence, power-on does not guarantee output pin levels, I/O settings or contents of registers. A device is not initialized until the reset signal is received. A reset operation must be executed immediately after power-on for devices with reset functions.
- (5) **POWER ON/OFF SEQUENCE:** In the case of a device that uses different power supplies for the internal operation and external interface, as a rule, switch on the external power supply after switching on the internal power supply. When switching the power supply off, as a rule, switch off the external power supply and then the internal power supply. Use of the reverse power on/off sequences may result in the application of an overvoltage to the internal elements of the device, causing malfunction and degradation of internal elements due to the passage of an abnormal current. The correct power on/off sequence must be judged separately for each device and according to related specifications governing the device.
- (6) **INPUT OF SIGNAL DURING POWER OFF STATE :** Do not input signals or an I/O pull-up power supply while the device is not powered. The current injection that results from input of such a signal or I/O pull-up power supply may cause malfunction and the abnormal current that passes in the device at this time may cause degradation of internal elements. Input of signals during the power off state must be judged separately for each device and according to related specifications governing the device.

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