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What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Obsolete
Core Processor	F ² MC-16FX
Core Size	16-Bit
Speed	32MHz
Connectivity	CANbus, I ² C, LINbus, SCI, UART/USART
Peripherals	DMA, LVD, POR, PWM, WDT
Number of I/O	81
Program Memory Size	288KB (288K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	24K x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 5.5V
Data Converters	A/D 24x8/10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	100-LQFP
Supplier Device Package	100-LQFP (14x14)
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/mb96f646rbpmc-gse1

■ Hardware Watchdog Timer

- Hardware watchdog timer is active after reset
- Window function of Watchdog Timer is used to select the lower window limit of the watchdog interval

■ Reload Timers

- 16-bit wide
- Prescaler with $1/2^1$, $1/2^2$, $1/2^3$, $1/2^4$, $1/2^5$, $1/2^6$ of peripheral clock frequency
- Event count function

■ Free-Running Timers

- Signals an interrupt on overflow, supports timer clear upon match with Output Compare (0, 4)
- Prescaler with 1 , $1/2^1$, $1/2^2$, $1/2^3$, $1/2^4$, $1/2^5$, $1/2^6$, $1/2^7$, $1/2^8$ of peripheral clock frequency

■ Input Capture Units

- 16-bit wide
- Signals an interrupt upon external event
- Rising edge, Falling edge or Both (rising & falling) edges sensitive

■ Output Compare Units

- 16-bit wide
- Signals an interrupt when a match with Free-running Timer occurs
- A pair of compare registers can be used to generate an output signal

■ Programmable Pulse Generator

- 16-bit down counter, cycle and duty setting registers
- Can be used as 2×8 -bit PPG
- Interrupt at trigger, counter borrow and/or duty match
- PWM operation and one-shot operation
- Internal prescaler allows 1 , $1/4$, $1/16$, $1/64$ of peripheral clock as counter clock or of selected Reload timer underflow as clock input
- Can be triggered by software or reload timer
- Can trigger ADC conversion
- Timing point capture
- Start delay

■ Quadrature Position/Revolution Counter (QPRC)

- Up/down count mode, Phase difference count mode, Count mode with direction
- 16-bit position counter
- 16-bit revolution counter
- Two 16-bit compare registers with interrupt
- Detection edge of the three external event input pins AIN, BIN and ZIN is configurable

■ Real Time Clock

- Operational on main oscillation (4MHz), sub oscillation (32kHz) or RC oscillation (100kHz/2MHz)
- Capable to correct oscillation deviation of Sub clock or RC oscillator clock (clock calibration)
- Read/write accessible second/minute/hour registers
- Can signal interrupts every half second/second/minute/hour/day
- Internal clock divider and prescaler provide exact 1s clock

■ External Interrupts

- Edge or Level sensitive
- Interrupt mask bit per channel
- Each available CAN channel RX has an external interrupt for wake-up
- Selected USART channels SIN have an external interrupt for wake-up

■ Non Maskable Interrupt

- Disabled after reset, can be enabled by Boot-ROM depending on ROM configuration block
- Once enabled, cannot be disabled other than by reset
- High or Low level sensitive
- Pin shared with external interrupt 0

■ I/O Ports

- Most of the external pins can be used as general purpose I/O
- All push-pull outputs (except when used as I²C SDA/SCL line)
- Bit-wise programmable as input/output or peripheral signal
- Bit-wise programmable input enable
- One input level per GPIO-pin (either Automotive or CMOS hysteresis)
- Bit-wise programmable pull-up resistor

■ Built-in On Chip Debugger (OCD)

- One-wire debug tool interface
- Break function:
 - Hardware break: 6 points (shared with code event)
 - Software break: 4096 points
- Event function
 - Code event: 6 points (shared with hardware break)
 - Data event: 6 points
 - Event sequencer: 2 levels + reset
- Execution time measurement function
- Trace function: 42 branches
- Security function

■ Flash Memory

- Dual operation flash allowing reading of one Flash bank while programming or erasing the other bank
- Command sequencer for automatic execution of programming algorithm and for supporting DMA for programming of the Flash Memory
- Supports automatic programming, Embedded Algorithm
- Write/Erase/Erase-Suspend/Resume commands
- A flag indicating completion of the automatic algorithm
- Erase can be performed on each sector individually
- Sector protection
- Flash Security feature to protect the content of the Flash
- Low voltage detection during Flash erases or writes

1. Product Lineup

Features		MB96640	Remark
Product Type		Flash Memory Product	
Subclock		Subclock can be set by software	
Dual Operation Flash Memory	RAM	-	
64.5KB + 32KB	10KB	MB96F643R, MB96F643A	Product Options R: MCU with CAN A: MCU without CAN
128.5KB + 32KB	16KB	MB96F645R, MB96F645A	
256.5KB + 32KB	24KB	MB96F646R	
384.5KB + 32KB	28KB	MB96F647R	
Package		LQFP-100 FPT-100P-M20	
DMA		4ch	
USART		6ch	LIN-USART 0 to 2/4/5/7
	with automatic LIN-Header transmission/reception	Yes (only 1ch)	LIN-USART 0
	with 16 byte RX- and TX-FIFO	No	
I ² C		2ch	I ² C 0/1
8/10-bit A/D Converter		24ch	AN 2 to 4/6 to 8/10 to 12/14 to 28
	with Data Buffer	No	
	with Range Comparator	Yes	
	with Scan Disable	Yes	
	with ADC Pulse Detection	No	
16-bit Reload Timer (RLT)		5ch	RLT 0 to 3/6
16-bit Free-Running Timer (FRT)		3ch	FRT 0 to 2
16-bit Input Capture Unit (ICU)		7ch (1 channel for LIN-USART)	ICU 0/1/4 to 7/9 (ICU 9 for LIN-USART)
16-bit Output Compare Unit (OCU)		7ch	OCU 0 to 4/6/7 (OCU 4 for FRT clear)
8/16-bit Programmable Pulse Generator (PPG)		16ch (16-bit) / 24ch (8-bit)	PPG 0 to 15
	with Timing point capture	Yes	
	with Start delay	Yes	
	with Ramp	No	
Quadrature Position/Revolution Counter (QPRC)		2ch	QPRC 0/1
CAN Interface		1ch	CAN 0 32 Message Buffers
External Interrupts (INT)		16ch	INT 0 to 15
Non-Maskable Interrupt (NMI)		1ch	
Real Time Clock (RTC)		1ch	
I/O Ports		79 (Dual clock mode) 81 (Single clock mode)	
Clock Calibration Unit (CAL)		1ch	
Clock Output Function		2ch	
Low Voltage Detection Function		Yes	Low voltage detection function can be disabled by software
Hardware Watchdog Timer		Yes	
On-chip RC-oscillator		Yes	
On-chip Debugger		Yes	

Note:

All signals of the peripheral function in each product cannot be allocated by limiting the pins of package. It is necessary to use the port relocate function of the general I/O port according to your function use.

4. Pin Description

Pin name	Feature	Description
ADTG	ADC	A/D converter trigger input pin
AINn	QPRC	Quadrature Position/Revolution Counter Unit n input pin
ANn	ADC	A/D converter channel n input pin
AVcc	Supply	Analog circuits power supply pin
AVRH	ADC	A/D converter high reference voltage input pin
AVRL	ADC	A/D converter low reference voltage input pin
AVss	Supply	Analog circuits power supply pin
BINn	QPRC	Quadrature Position/Revolution Counter Unit n input pin
C	Voltage regulator	Internally regulated power supply stabilization capacitor pin
CKOTn	Clock Output function	Clock Output function n output pin
CKOTn_R	Clock Output function	Relocated Clock Output function n output pin
CKOTXn	Clock Output function	Clock Output function n inverted output pin
CKOTXn_R	Clock Output function	Relocated Clock Output function n inverted output pin
DEBUG I/F	OCD	On Chip Debugger input/output pin
FRCKn	Free-Running Timer	Free-Running Timer n input pin
FRCKn_R	Free-Running Timer	Relocated Free-Running Timer n input pin
INn	ICU	Input Capture Unit n input pin
INn_R	ICU	Relocated Input Capture Unit n input pin
INTn	External Interrupt	External Interrupt n input pin
INTn_R	External Interrupt	Relocated External Interrupt n input pin
MD	Core	Input pin for specifying the operating mode
NMI	External Interrupt	Non-Maskable Interrupt input pin
OUTn	OCU	Output Compare Unit n waveform output pin
OUTn_R	OCU	Relocated Output Compare Unit n waveform output pin
Pnn_m	GPIO	General purpose I/O pin
PPGn	PPG	Programmable Pulse Generator n output pin (16bit/8bit)
PPGn_R	PPG	Relocated Programmable Pulse Generator n output pin (16bit/8bit)
PPGn_B	PPG	Programmable Pulse Generator n output pin (16bit/8bit)
RSTX	Core	Reset input pin
RXn	CAN	CAN interface n RX input pin
SCKn	USART	USART n serial clock input/output pin
SCKn_R	USART	Relocated USART n serial clock input/output pin
SCLn	I ² C	I ² C interface n clock I/O input/output pin
SDAn	I ² C	I ² C interface n serial data I/O input/output pin
SINn	USART	USART n serial data input pin
SINn_R	USART	Relocated USART n serial data input pin
SOTn	USART	USART n serial data output pin
SOTn_R	USART	Relocated USART n serial data output pin
TINn	Reload Timer	Reload Timer n event input pin
TOTn	Reload Timer	Reload Timer n output pin

Pin no.	I/O circuit type*	Pin name
39	K	P08_7 / AN23 / PPG7_B
40	K	P09_0 / AN24 / PPG8_R
41	K	P09_1 / AN25 / PPG9_R
42	K	P09_2 / AN26 / PPG10_R
43	K	P09_3 / AN27 / PPG11_R
44	H	P17_1 / PPG12_R
45	H	P17_2 / PPG13_R
46	I	P10_0 / SIN2 / TIN3 / AN28 / INT11
47	H	P10_1 / SOT2 / TOT3
48	M	P10_2 / SCK2 / PPG6
49	H	P10_3 / PPG7
50	Supply	Vcc
51	Supply	Vss
52	O	DEBUG I/F
53	H	P17_0
54	C	MD
55	A	X0
56	A	X1
57	Supply	Vss
58	B	P04_0 / X0A
59	B	P04_1 / X1A
60	C	RSTX
61	H	P11_0
62	H	P11_1 / PPG0_R
63	H	P11_2 / PPG1_R
64	H	P11_3 / PPG2_R
65	H	P11_4 / PPG3_R
66	H	P11_5 / PPG4_R
67	H	P11_6 / FRCK0_R / ZIN1
68	H	P11_7 / IN0_R / AIN1
69	H	P12_0 / IN1_R / BIN1
70	H	P12_3 / OUT2_R
71	H	P12_7 / INT1_R
72	H	P00_0 / INT3_R / FRCK2
73	H	P00_1 / INT4_R
74	H	P00_2 / INT5_R
75	Supply	Vcc
76	Supply	Vss
77	H	P00_3 / INT6_R / PPG8_B

Pin no.	I/O circuit type*	Pin name
78	H	P00_4 / INT7_R / PPG9_B
79	H	P00_5 / IN6 / TTG2 / TTG6 / PPG10_B
80	H	P00_6 / IN7 / TTG3 / TTG7 / PPG11_B
81	H	P00_7 / INT14
82	M	P01_0 / SCK7
83	H	P01_1 / CKOT1 / OUT0 / SOT7
84	M	P01_2 / CKOTX1 / OUT1 / INT15 / SIN7
85	H	P01_3 / PPG5
86	M	P01_4 / SIN4 / INT8
87	H	P01_5 / SOT4
88	M	P01_6 / SCK4 / TTG12
89	M	P01_7 / CKOTX1_R / INT9 / TTG13 / ZIN0 / SCK7_R
90	H	P02_0 / CKOT1_R / INT10 / TTG14 / AIN0 / SOT7_R
91	M	P02_2 / IN7_R / CKOT0_R / INT12 / BIN0 / SIN7_R
92	M	P02_5 / OUT0_R / INT13 / SIN5_R
93	H	P03_0 / PPG4_B
94	H	P03_1 / PPG5_B
95	H	P03_2 / PPG14_B / SOT5_R
96	M	P03_3 / PPG15_B / SCK5_R
97	M	P03_4 / RX0 / INT4
98	H	P03_5 / TX0
99	H	P03_6 / INT0 / NMI
100	Supply	Vcc

*: See "I/O Circuit Type" for details on the I/O circuit types.

Vector number	Offset in vector table	Vector name	Cleared by DMA	Index in ICR to program	Description
40	35C _H	PPG2	Yes	40	Programmable Pulse Generator 2
41	358 _H	PPG3	Yes	41	Programmable Pulse Generator 3
42	354 _H	PPG4	Yes	42	Programmable Pulse Generator 4
43	350 _H	PPG5	Yes	43	Programmable Pulse Generator 5
44	34C _H	PPG6	Yes	44	Programmable Pulse Generator 6
45	348 _H	PPG7	Yes	45	Programmable Pulse Generator 7
46	344 _H	PPG8	Yes	46	Programmable Pulse Generator 8
47	340 _H	PPG9	Yes	47	Programmable Pulse Generator 9
48	33C _H	PPG10	Yes	48	Programmable Pulse Generator 10
49	338 _H	PPG11	Yes	49	Programmable Pulse Generator 11
50	334 _H	PPG12	Yes	50	Programmable Pulse Generator 12
51	330 _H	PPG13	Yes	51	Programmable Pulse Generator 13
52	32C _H	PPG14	Yes	52	Programmable Pulse Generator 14
53	328 _H	PPG15	Yes	53	Programmable Pulse Generator 15
54	324 _H	-	-	54	Reserved
55	320 _H	-	-	55	Reserved
56	31C _H	-	-	56	Reserved
57	318 _H	-	-	57	Reserved
58	314 _H	RLT0	Yes	58	Reload Timer 0
59	310 _H	RLT1	Yes	59	Reload Timer 1
60	30C _H	RLT2	Yes	60	Reload Timer 2
61	308 _H	RLT3	Yes	61	Reload Timer 3
62	304 _H	-	-	62	Reserved
63	300 _H	-	-	63	Reserved
64	2FC _H	RLT6	Yes	64	Reload Timer 6
65	2F8 _H	ICU0	Yes	65	Input Capture Unit 0
66	2F4 _H	ICU1	Yes	66	Input Capture Unit 1
67	2F0 _H	-	-	67	Reserved
68	2EC _H	-	-	68	Reserved
69	2E8 _H	ICU4	Yes	69	Input Capture Unit 4
70	2E4 _H	ICU5	Yes	70	Input Capture Unit 5
71	2E0 _H	ICU6	Yes	71	Input Capture Unit 6
72	2DC _H	ICU7	Yes	72	Input Capture Unit 7
73	2D8 _H	-	-	73	Reserved
74	2D4 _H	ICU9	Yes	74	Input Capture Unit 9
75	2D0 _H	-	-	75	Reserved
76	2CC _H	-	-	76	Reserved
77	2C8 _H	OCU0	Yes	77	Output Compare Unit 0
78	2C4 _H	OCU1	Yes	78	Output Compare Unit 1
79	2C0 _H	OCU2	Yes	79	Output Compare Unit 2
80	2BC _H	OCU3	Yes	80	Output Compare Unit 3
81	2B8 _H	OCU4	Yes	81	Output Compare Unit 4

Vector number	Offset in vector table	Vector name	Cleared by DMA	Index in ICR to program	Description
82	2B4 _H	-	-	82	Reserved
83	2B0 _H	OCU6	Yes	83	Output Compare Unit 6
84	2AC _H	OCU7	Yes	84	Output Compare Unit 7
85	2A8 _H	-	-	85	Reserved
86	2A4 _H	-	-	86	Reserved
87	2A0 _H	-	-	87	Reserved
88	29C _H	-	-	88	Reserved
89	298 _H	FRT0	Yes	89	Free-Running Timer 0
90	294 _H	FRT1	Yes	90	Free-Running Timer 1
91	290 _H	FRT2	Yes	91	Free-Running Timer 2
92	28C _H	-	-	92	Reserved
93	288 _H	RTC0	No	93	Real Time Clock
94	284 _H	CAL0	No	94	Clock Calibration Unit
95	280 _H	-	-	95	Reserved
96	27C _H	IIC0	Yes	96	I ² C interface 0
97	278 _H	IIC1	Yes	97	I ² C interface 1
98	274 _H	ADC0	Yes	98	A/D Converter 0
99	270 _H	-	-	99	Reserved
100	26C _H	-	-	100	Reserved
101	268 _H	LINR0	Yes	101	LIN USART 0 RX
102	264 _H	LINT0	Yes	102	LIN USART 0 TX
103	260 _H	LINR1	Yes	103	LIN USART 1 RX
104	25C _H	LINT1	Yes	104	LIN USART 1 TX
105	258 _H	LINR2	Yes	105	LIN USART 2 RX
106	254 _H	LINT2	Yes	106	LIN USART 2 TX
107	250 _H	-	-	107	Reserved
108	24C _H	-	-	108	Reserved
109	248 _H	LINR4	Yes	109	LIN USART 4 RX
110	244 _H	LINT4	Yes	110	LIN USART 4 TX
111	240 _H	LINR5	Yes	111	LIN USART 5 RX
112	23C _H	LINT5	Yes	112	LIN USART 5 TX
113	238 _H	-	-	113	Reserved
114	234 _H	-	-	114	Reserved
115	230 _H	LINR7	Yes	115	LIN USART 7 RX
116	22C _H	LINT7	Yes	116	LIN USART 7 TX
117	228 _H	-	-	117	Reserved
118	224 _H	-	-	118	Reserved
119	220 _H	-	-	119	Reserved
120	21C _H	-	-	120	Reserved

Vector number	Offset in vector table	Vector name	Cleared by DMA	Index in ICR to program	Description
121	218 _H	-	-	121	Reserved
122	214 _H	-	-	122	Reserved
123	210 _H	-	-	123	Reserved
124	20C _H	-	-	124	Reserved
125	208 _H	-	-	125	Reserved
126	204 _H	-	-	126	Reserved
127	200 _H	-	-	127	Reserved
128	1FC _H	-	-	128	Reserved
129	1F8 _H	-	-	129	Reserved
130	1F4 _H	-	-	130	Reserved
131	1F0 _H	-	-	131	Reserved
132	1EC _H	-	-	132	Reserved
133	1E8 _H	FLASHA	Yes	133	Flash memory A interrupt
134	1E4 _H	-	-	134	Reserved
135	1E0 _H	-	-	135	Reserved
136	1DC _H	-	-	136	Reserved
137	1D8 _H	QPRC0	Yes	137	Quad Position/Revolution counter 0
138	1D4 _H	QPRC1	Yes	138	Quad Position/Revolution counter 1
139	1D0 _H	ADCRC0	No	139	A/D Converter 0 - Range Comparator
140	1CC _H	-	-	140	Reserved
141	1C8 _H	-	-	141	Reserved
142	1C4 _H	-	-	142	Reserved
143	1C0 _H	-	-	143	Reserved

13. Handling Devices

Special care is required for the following when handling the device:

- Latch-up prevention
- Unused pins handling
- External clock usage
- Notes on PLL clock mode operation
- Power supply pins (V_{CC}/V_{SS})
- Crystal oscillator and ceramic resonator circuit
- Turn on sequence of power supply to A/D converter and analog inputs
- Pin handling when not using the A/D converter
- Notes on Power-on
- Stabilization of power supply voltage
- SMC power supply pins
- Serial communication
- Mode Pin (MD)

13.1 Latch-up prevention

CMOS IC chips may suffer latch-up under the following conditions:

- A voltage higher than V_{CC} or lower than V_{SS} is applied to an input or output pin.
- A voltage higher than the rated voltage is applied between V_{CC} pins and V_{SS} pins.
- The AV_{CC} power supply is applied before the V_{CC} voltage.

Latch-up may increase the power supply current dramatically, causing thermal damages to the device.

For the same reason, extra care is required to not let the analog power-supply voltage (AV_{CC} , $AVRH$) exceed the digital power-supply voltage.

13.2 Unused pins handling

Unused input pins can be left open when the input is disabled (corresponding bit of Port Input Enable register $PIER = 0$).

Leaving unused input pins open when the input is enabled may result in misbehavior and possible permanent damage of the device. To prevent latch-up, they must therefore be pulled up or pulled down through resistors which should be more than $2k\Omega$.

Unused bidirectional pins can be set either to the output state and be then left open, or to the input state with either input disabled or external pull-up/pull-down resistor as described above.

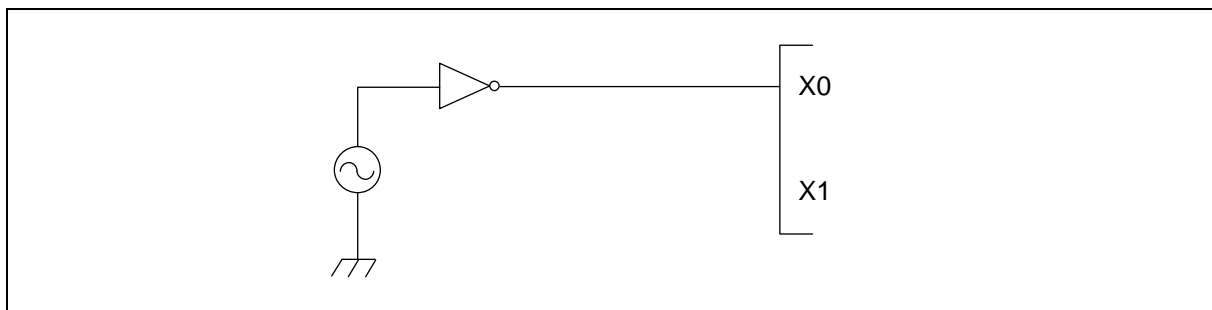
13.3 External clock usage

The permitted frequency range of an external clock depends on the oscillator type and configuration.

See AC Characteristics for detailed modes and frequency limits. Single and opposite phase external clocks must be connected as follows:

13.3.1 Single phase external clock for Main oscillator

When using a single phase external clock for the Main oscillator, X0 pin must be driven and X1 pin left open. And supply 1.8V power to the external clock.



14. Electrical Characteristics

14.1 Absolute Maximum Ratings

Parameter	Symbol	Condition	Rating		Unit	Remarks
			Min	Max		
Power supply voltage* ¹	V _{CC}	-	V _{SS} - 0.3	V _{SS} + 6.0	V	
Analog power supply voltage* ¹	AV _{CC}	-	V _{SS} - 0.3	V _{SS} + 6.0	V	V _{CC} = AV _{CC} * ²
Analog reference voltage* ¹	AVRH, AVRL	-	V _{SS} - 0.3	V _{SS} + 6.0	V	AV _{CC} ≥ AVRH, AV _{CC} ≥ AVRL, AVRH > AVRL, AVRL ≥ AV _{SS}
Input voltage* ¹	V _I	-	V _{SS} - 0.3	V _{SS} + 6.0	V	V _I ≤ V _{CC} + 0.3V* ³
Output voltage* ¹	V _O	-	V _{SS} - 0.3	V _{SS} + 6.0	V	V _O ≤ V _{CC} + 0.3V* ³
Maximum Clamp Current	I _{CLAMP}	-	-4.0	+4.0	mA	Applicable to general purpose I/O pins * ⁴
Total Maximum Clamp Current	Σ I _{CLAMP}	-	-	26	mA	Applicable to general purpose I/O pins * ⁴
"L" level maximum output current	I _{OL}	-	-	15	mA	
"L" level average output current	I _{OLAV}	-	-	4	mA	
"L" level maximum overall output current	ΣI _{OL}	-	-	66	mA	
"L" level average overall output current	ΣI _{OLAV}	-	-	33	mA	
"H" level maximum output current	I _{OH}	-	-	-15	mA	
"H" level average output current	I _{OHAV}	-	-	-4	mA	
"H" level maximum overall output current	ΣI _{OH}	-	-	-66	mA	
"H" level average overall output current	ΣI _{OHAV}	-	-	-33	mA	
Power consumption* ⁵	P _D	T _A = +125°C	-	416* ⁶	mW	
Operating ambient temperature	T _A	-	-40	+125* ⁷	°C	
Storage temperature	T _{STG}	-	-55	+150	°C	

*1: This parameter is based on V_{SS} = AV_{SS} = 0V.

*2: AV_{CC} and V_{CC} must be set to the same voltage. It is required that AV_{CC} does not exceed V_{CC} and that the voltage at the analog inputs does not exceed AV_{CC} when the power is switched on.

*3: V_I and V_O should not exceed V_{CC} + 0.3V. V_I should also not exceed the specified ratings. However if the maximum current to/from an input is limited by some means with external components, the I_{CLAMP} rating supersedes the V_I rating. Input/Output voltages of standard ports depend on V_{CC}.

*4: Applicable to all general purpose I/O pins (Pnn_m).

- Use within recommended operating conditions.
- Use at DC voltage (current).
- The +B signal should always be applied a limiting resistance placed between the +B signal and the microcontroller.
- The value of the limiting resistance should be set so that when the +B signal is applied the input current to the microcontroller pin does not exceed rated values, either instantaneously or for prolonged periods.
- Note that when the microcontroller drive current is low, such as in the power saving modes, the +B input potential may pass through the protective diode and increase the potential at the VCC pin, and this may affect other devices.
- Note that if a +B signal is input when the microcontroller power supply is off (not fixed at 0V), the power supply is provided from the pins, so that incomplete operation may result.

Parameter	Symbol	Pin name	Conditions	Value			Unit	Remarks
				Min	Typ	Max		
Power supply current in Stop mode*3	I _{CCCH}	V _{CC}	-	-	20	60	μA	T _A = +25°C
				-	-	880	μA	T _A = +105°C
				-	-	1845	μA	T _A = +125°C
Flash Power Down current	I _{CCFLASHPD}		-	-	36	70	μA	
Power supply current for active Low Voltage detector*4	I _{CCLVD}		Low voltage detector enabled	-	5	-	μA	T _A = +25°C
				-	-	12.5	μA	T _A = +125°C
Flash Write/ Erase current*5	I _{CCFLASH}		-	-	12.5	-	mA	T _A = +25°C
				-	-	20	mA	T _A = +125°C

*1: The power supply current is measured with a 4MHz external clock connected to the Main oscillator and a 32 kHz external clock connected to the Sub oscillator. See chapter "Standby mode and voltage regulator control circuit" of the Hardware Manual for further details about voltage regulator control. Current for "On Chip Debugger" part is not included. Power supply current in Run mode does not include Flash Write / Erase current.

*2: The power supply current in Timer mode is the value when Flash is in Power-down / reset mode.

When Flash is not in Power-down / reset mode, I_{CCFLASHPD} must be added to the Power supply current.

The power supply current is measured with a 4MHz external clock connected to the Main oscillator and a 32 kHz external clock connected to the Sub oscillator. The current for "On Chip Debugger" part is not included.

*3: The power supply current in Stop mode is the value when Flash is in Power-down / reset mode.

When Flash is not in Power-down / reset mode, I_{CCFLASHPD} must be added to the Power supply current.

*4: When low voltage detector is enabled, I_{CCLVD} must be added to Power supply current.

*5: When Flash Write / Erase program is executed, I_{CCFLASH} must be added to Power supply current.

Parameter	Symbol	Pin name	Conditions	Value			Unit	Remarks
				Min	Typ	Max		
"H" level output voltage	V _{OH4}	4mA type	4.5V ≤ V _{CC} ≤ 5.5V I _{OH} = -4mA	V _{CC} - 0.5	-	V _{CC}	V	
			2.7V ≤ V _{CC} < 4.5V I _{OH} = -1.5mA					
	V _{OH3}	3mA type	4.5V ≤ V _{CC} ≤ 5.5V I _{OH} = -3mA	V _{CC} - 0.5	-	V _{CC}	V	
			2.7V ≤ V _{CC} < 4.5V I _{OH} = -1.5mA					
"L" level output voltage	V _{OL4}	4mA type	4.5V ≤ V _{CC} ≤ 5.5V I _{OL} = +4mA	-	-	0.4	V	
			2.7V ≤ V _{CC} < 4.5V I _{OL} = +1.7mA					
	V _{OL3}	3mA type	2.7V ≤ V _{CC} < 5.5V I _{OL} = +3mA	-	-	0.4	V	
	V _{OLD}	DEBUG I/F	V _{CC} = 2.7V I _{OL} = +25mA	0	-	0.25	V	
Input leak current	I _{IL}	Pnn_m	V _{SS} < V _I < V _{CC} AV _{SS} , AV _{RL} < V _I < AV _{CC} , AV _{RH}	- 1	-	+ 1	μA	
Pull-up resistance value	R _{PU}	Pnn_m	V _{CC} = 5.0V ±10%	25	50	100	kΩ	
Input capacitance	C _{IN}	Other than C, V _{CC} , V _{SS} , AV _{CC} , AV _{SS} , AV _{RH} , AV _{RL}	-	-	5	15	pF	

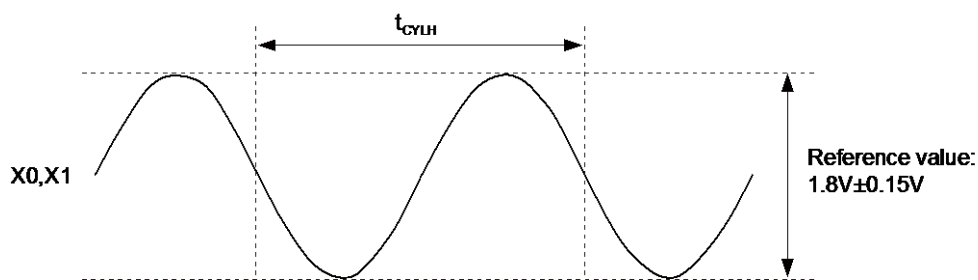
14.4 AC Characteristics

14.4.1 Main Clock Input Characteristics

($V_{CC} = AV_{CC} = 2.7V$ to $5.5V$, $V_D = 1.8V \pm 0.15V$, $V_{SS} = AV_{SS} = 0V$, $T_A = -40^\circ C$ to $+125^\circ C$)

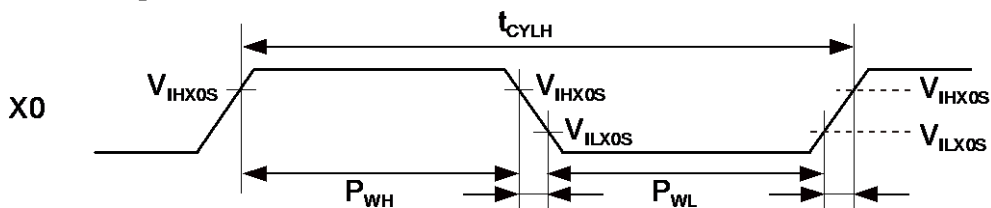
Parameter	Symbol	Pin name	Value			Unit	Remarks
			Min	Typ	Max		
Input frequency	f_C	X0, X1	4	-	8	MHz	When using a crystal oscillator, PLL off
			-	-	8	MHz	When using an opposite phase external clock, PLL off
			4	-	8	MHz	When using a crystal oscillator or opposite phase external clock, PLL on
Input frequency	f_{FCI}	X0	-	-	8	MHz	When using a single phase external clock in "Fast Clock Input mode", PLL off
			4	-	8	MHz	When using a single phase external clock in "Fast Clock Input mode", PLL on
Input clock cycle	t_{CYLH}	-	125	-	-	ns	
Input clock pulse width	P_{WH}, P_{WL}	-	55	-	-	ns	

When using the crystal oscillator



The amplitude changes by resistance, capacity which added outside or the difference of the device.

When using the external clock



14.4.8 USART Timing

($V_{CC} = AV_{CC} = 2.7V$ to $5.5V$, $V_{SS} = AV_{SS} = 0V$, $T_A = -40^{\circ}C$ to $+125^{\circ}C$, $C_L = 50pF$)

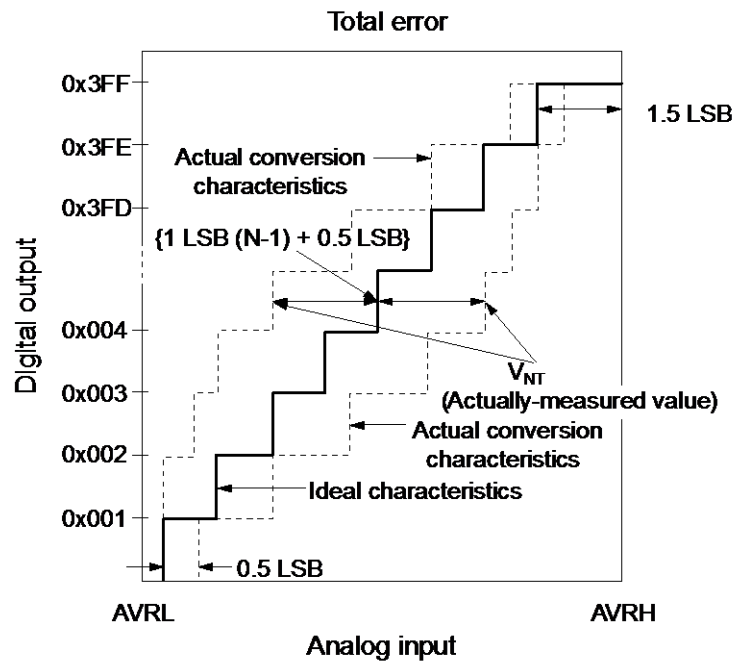
Parameter	Symbol	Pin name	Conditions	$4.5V \leq V_{CC} < 5.5V$		$2.7V \leq V_{CC} < 4.5V$		Unit
				Min	Max	Min	Max	
Serial clock cycle time	t_{SCYC}	SCKn	Internal shift clock mode	$4t_{CLKP1}$	-	$4t_{CLKP1}$	-	ns
SCK $\downarrow \rightarrow$ SOT delay time	t_{SLOVI}	SCKn, SOTn		- 20	+ 20	- 30	+ 30	ns
SOT \rightarrow SCK \uparrow delay time	t_{OVSHI}	SCKn, SOTn		$N \times t_{CLKP1} - 20$	-	$N \times t_{CLKP1} - 30$	-	ns
SIN \rightarrow SCK \uparrow setup time	t_{IVSHI}	SCKn, SINn		$t_{CLKP1} + 45$	-	$t_{CLKP1} + 55$	-	ns
SCK $\uparrow \rightarrow$ SIN hold time	t_{SHIXI}	SCKn, SINn		0	-	0	-	ns
Serial clock "L" pulse width	t_{SLSH}	SCKn	External shift clock mode	$t_{CLKP1} + 10$	-	$t_{CLKP1} + 10$	-	ns
Serial clock "H" pulse width	t_{SHSL}	SCKn		$t_{CLKP1} + 10$	-	$t_{CLKP1} + 10$	-	ns
SCK $\downarrow \rightarrow$ SOT delay time	t_{SLOVE}	SCKn, SOTn		-	$2t_{CLKP1} + 45$	-	$2t_{CLKP1} + 55$	ns
SIN \rightarrow SCK \uparrow setup time	t_{IVSHE}	SCKn, SINn		$t_{CLKP1}/2 + 10$	-	$t_{CLKP1}/2 + 10$	-	ns
SCK $\uparrow \rightarrow$ SIN hold time	t_{SHIXE}	SCKn, SINn		$t_{CLKP1} + 10$	-	$t_{CLKP1} + 10$	-	ns
SCK fall time	t_F	SCKn		-	20	-	20	ns
SCK rise time	t_R	SCKn		-	20	-	20	ns

Notes:

- AC characteristic in CLK synchronized mode.
- C_L is the load capacity value of pins when testing.
- Depending on the used machine clock frequency, the maximum possible baud rate can be limited by some parameters. These parameters are shown in "MB96600 series HARDWARE MANUAL".
- t_{CLKP1} indicates the peripheral clock 1 (CLKP1), Unit: ns
- These characteristics only guarantee the same relocate port number.
For example, the combination of SCKn and SOTn_R is not guaranteed.

*: Parameter N depends on t_{SCYC} and can be calculated as follows:

- If $t_{SCYC} = 2 \times k \times t_{CLKP1}$, then $N = k$, where k is an integer > 2
- If $t_{SCYC} = (2 \times k + 1) \times t_{CLKP1}$, then $N = k + 1$, where k is an integer > 1



$$1\text{LSB (Ideal value)} = \frac{\text{AVRH} - \text{AVRL}}{1024} \text{ [V]}$$

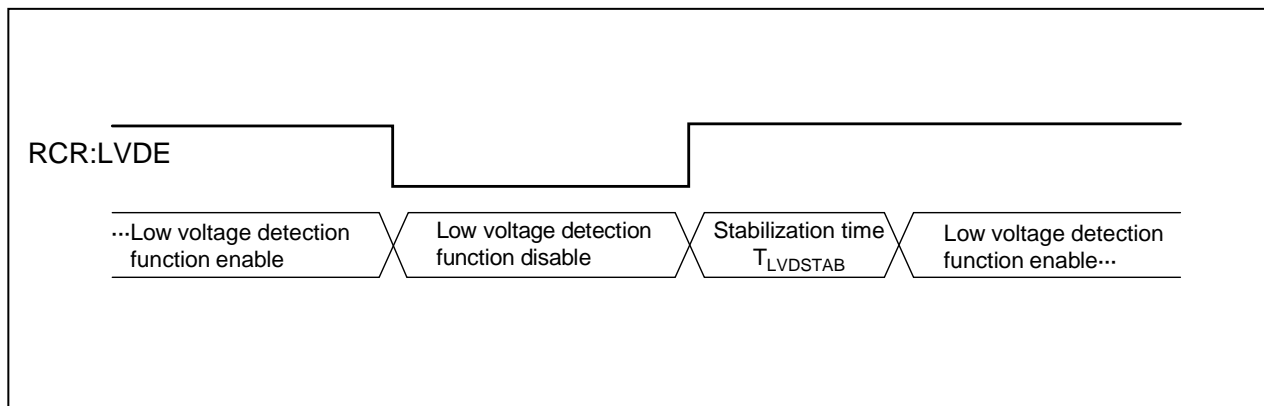
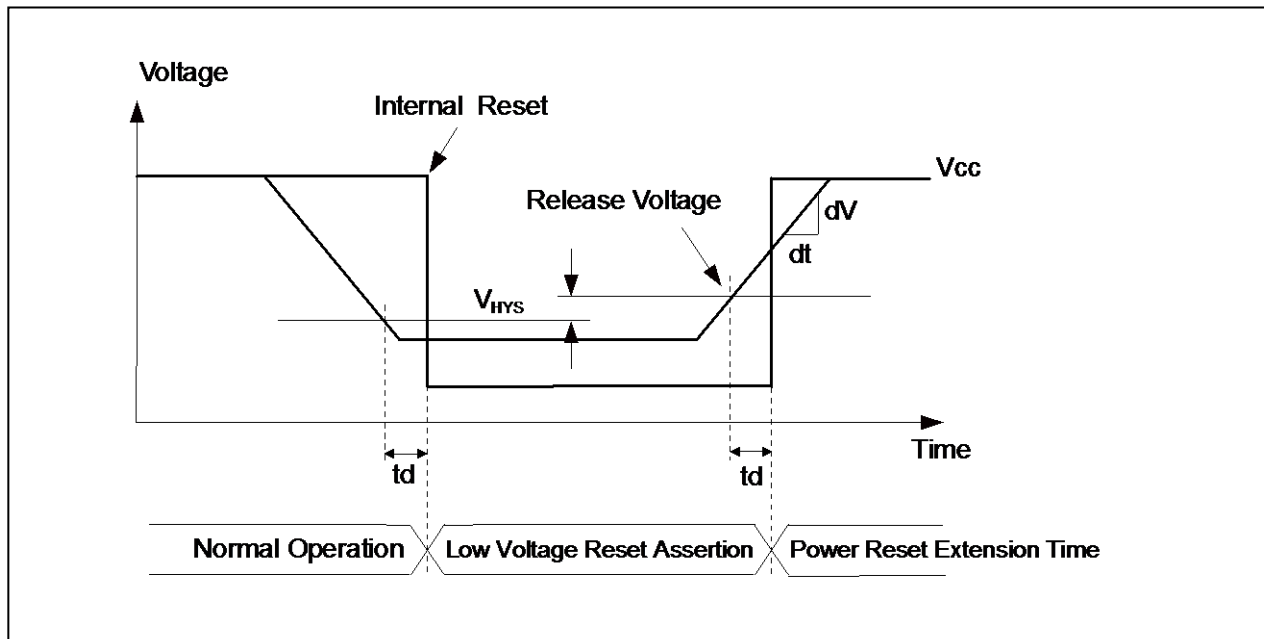
$$\text{Total error of digital output N} = \frac{V_{\text{NT}} - \{1\text{LSB} \times (\text{N} - 1) + 0.5\text{LSB}\}}{1\text{LSB}}$$

N : A/D converter digital output value.

V_{NT} : Voltage at which the digital output changes from 0x (N + 1) to 0xN.

V_{OT} (Ideal value) = AVRL + 0.5LSB[V]

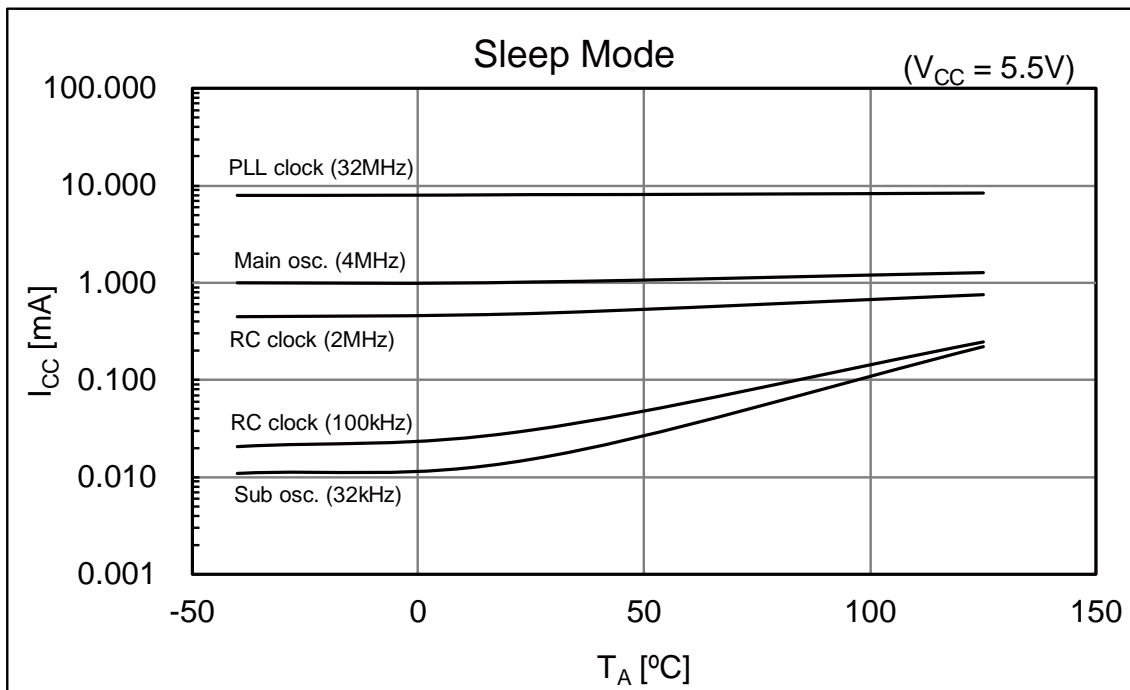
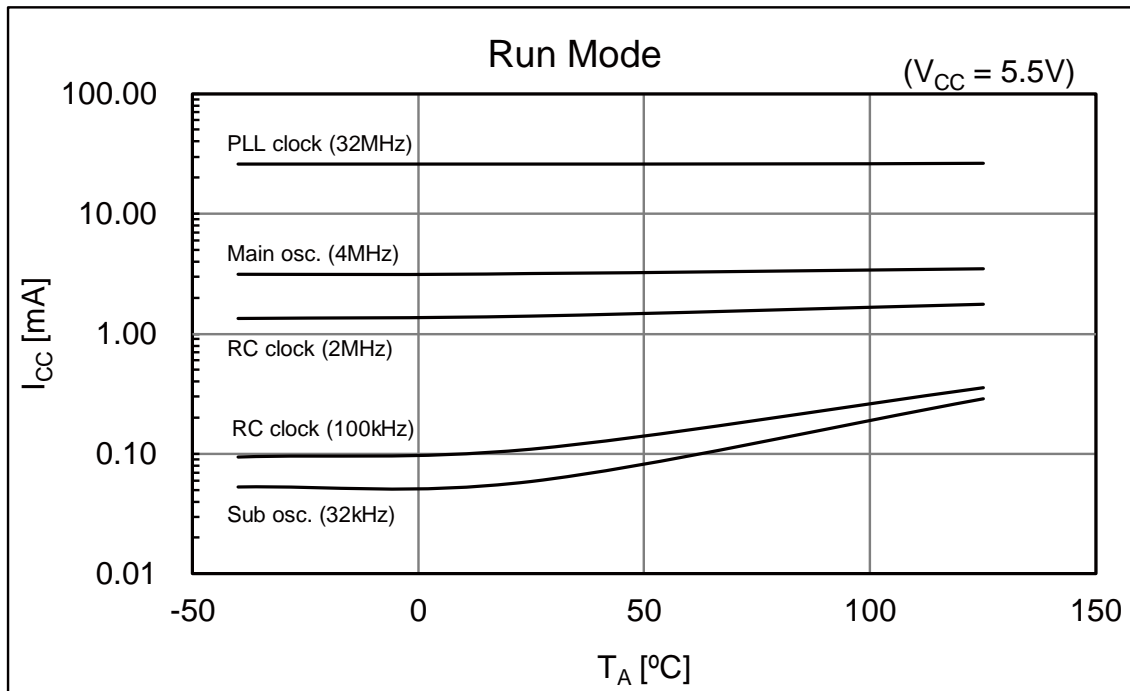
V_{FST} (Ideal value) = AVRH - 1.5LSB[V]



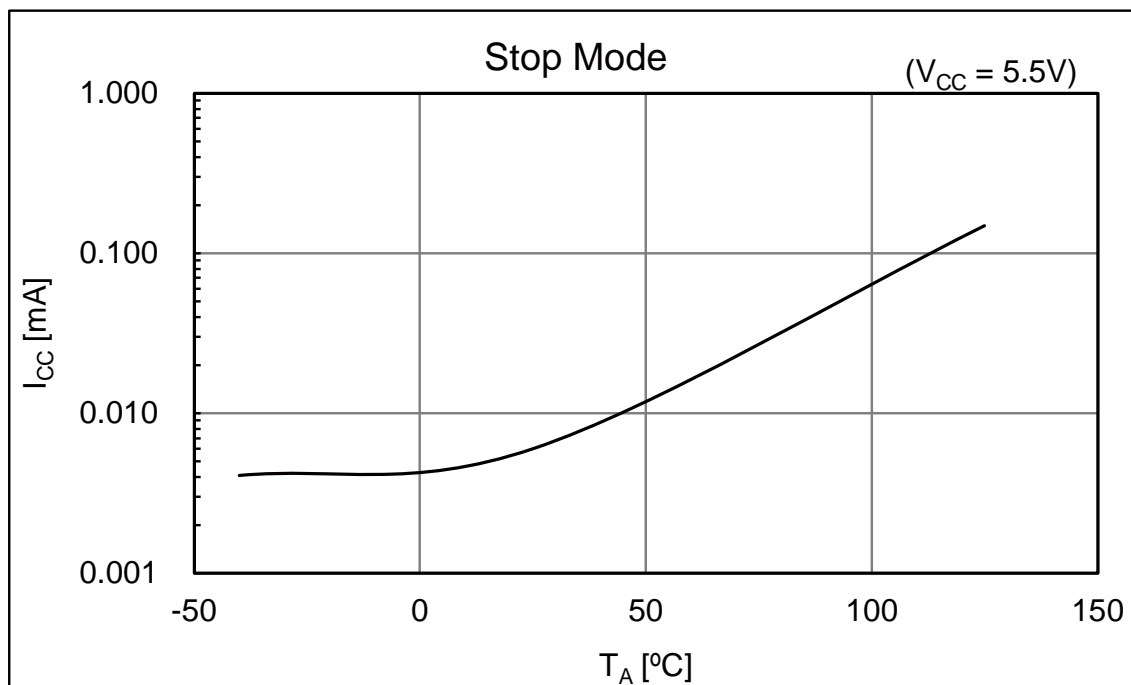
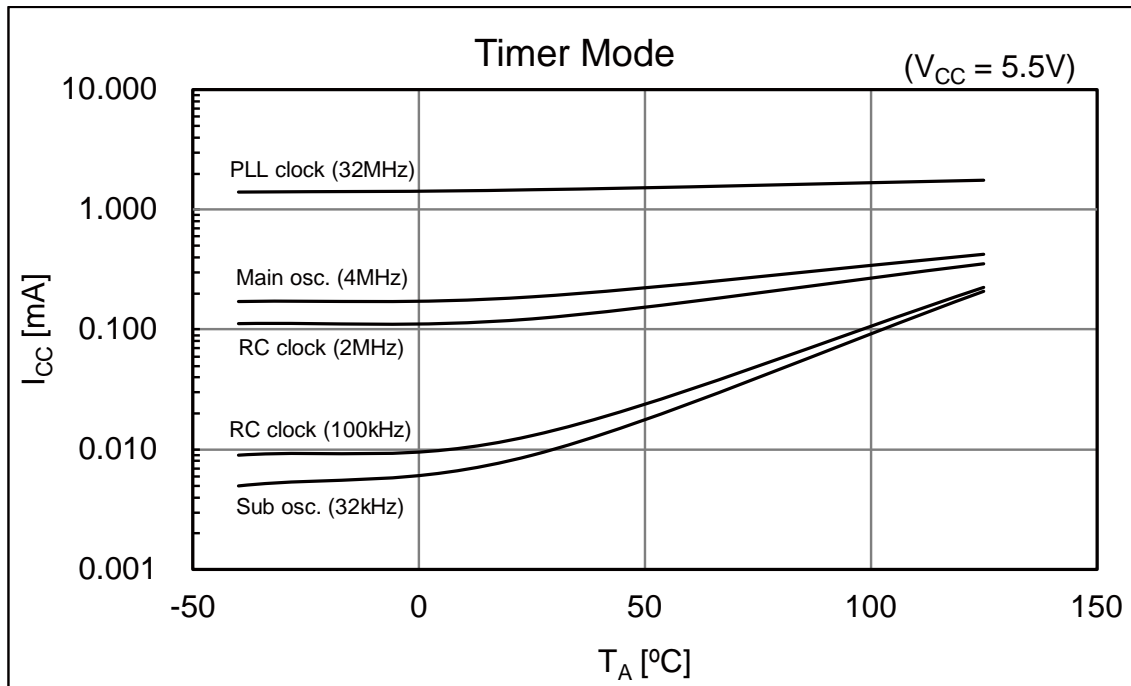
15. Example Characteristics

This characteristic is an actual value of the arbitrary sample. It is not the guaranteed value.

■ MB96F647



■ MB96F647



16. Ordering Information

MCU with CAN controller

Part number	Flash memory	Package*
MB96F643RBPMC-GSE1	Flash A (96.5KB)	100-pin plastic LQFP (FPT-100P-M20)
MB96F643RBPMC-GSE2		
MB96F645RBPMC-GSE1	Flash A (160.5KB)	100-pin plastic LQFP (FPT-100P-M20)
MB96F645RBPMC-GSE2		
MB96F646RBPMC-GSE1	Flash A (288.5KB)	100-pin plastic LQFP (FPT-100P-M20)
MB96F646RBPMC-GSE2		
MB96F647RBPMC-GSE1	Flash A (416.5KB)	100-pin plastic LQFP (FPT-100P-M20)
MB96F647RBPMC-GSE2		

*: For details about package, see "Package Dimension".

MCU without CAN controller

Part number	Flash memory	Package*
MB96F643ABPMC-GSE1	Flash A (96.5KB)	100-pin plastic LQFP (FPT-100P-M20)
MB96F643ABPMC-GSE2		
MB96F645ABPMC-GSE1	Flash A (160.5KB)	100-pin plastic LQFP (FPT-100P-M20)
MB96F645ABPMC-GSE2		

*: For details about package, see "Package Dimension".

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