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### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Obsolete
Core Processor	F <sup>2</sup> MC-16FX
Core Size	16-Bit
Speed	32MHz
Connectivity	CANbus, I <sup>2</sup> C, LINbus, SCI, UART/USART
Peripherals	DMA, LVD, POR, PWM, WDT
Number of I/O	81
Program Memory Size	288KB (288K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	24K x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 5.5V
Data Converters	A/D 24x8/10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	100-LQFP
Supplier Device Package	100-LQFP (14x14)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/infineon-technologies/mb96f646rbpmc-gse2">https://www.e-xfl.com/product-detail/infineon-technologies/mb96f646rbpmc-gse2</a>

**■ Hardware Watchdog Timer**

- Hardware watchdog timer is active after reset
- Window function of Watchdog Timer is used to select the lower window limit of the watchdog interval

**■ Reload Timers**

- 16-bit wide
- Prescaler with  $1/2^1$ ,  $1/2^2$ ,  $1/2^3$ ,  $1/2^4$ ,  $1/2^5$ ,  $1/2^6$  of peripheral clock frequency
- Event count function

**■ Free-Running Timers**

- Signals an interrupt on overflow, supports timer clear upon match with Output Compare (0, 4)
- Prescaler with  $1$ ,  $1/2^1$ ,  $1/2^2$ ,  $1/2^3$ ,  $1/2^4$ ,  $1/2^5$ ,  $1/2^6$ ,  $1/2^7$ ,  $1/2^8$  of peripheral clock frequency

**■ Input Capture Units**

- 16-bit wide
- Signals an interrupt upon external event
- Rising edge, Falling edge or Both (rising & falling) edges sensitive

**■ Output Compare Units**

- 16-bit wide
- Signals an interrupt when a match with Free-running Timer occurs
- A pair of compare registers can be used to generate an output signal

**■ Programmable Pulse Generator**

- 16-bit down counter, cycle and duty setting registers
- Can be used as  $2 \times 8$ -bit PPG
- Interrupt at trigger, counter borrow and/or duty match
- PWM operation and one-shot operation
- Internal prescaler allows  $1$ ,  $1/4$ ,  $1/16$ ,  $1/64$  of peripheral clock as counter clock or of selected Reload timer underflow as clock input
- Can be triggered by software or reload timer
- Can trigger ADC conversion
- Timing point capture
- Start delay

**■ Quadrature Position/Revolution Counter (QPRC)**

- Up/down count mode, Phase difference count mode, Count mode with direction
- 16-bit position counter
- 16-bit revolution counter
- Two 16-bit compare registers with interrupt
- Detection edge of the three external event input pins AIN, BIN and ZIN is configurable

**■ Real Time Clock**

- Operational on main oscillation (4MHz), sub oscillation (32kHz) or RC oscillation (100kHz/2MHz)
- Capable to correct oscillation deviation of Sub clock or RC oscillator clock (clock calibration)
- Read/write accessible second/minute/hour registers
- Can signal interrupts every half second/second/minute/hour/day
- Internal clock divider and prescaler provide exact 1s clock

**■ External Interrupts**

- Edge or Level sensitive
- Interrupt mask bit per channel
- Each available CAN channel RX has an external interrupt for wake-up
- Selected USART channels SIN have an external interrupt for wake-up

**■ Non Maskable Interrupt**

- Disabled after reset, can be enabled by Boot-ROM depending on ROM configuration block
- Once enabled, cannot be disabled other than by reset
- High or Low level sensitive
- Pin shared with external interrupt 0

**■ I/O Ports**

- Most of the external pins can be used as general purpose I/O
- All push-pull outputs (except when used as I<sup>2</sup>C SDA/SCL line)
- Bit-wise programmable as input/output or peripheral signal
- Bit-wise programmable input enable
- One input level per GPIO-pin (either Automotive or CMOS hysteresis)
- Bit-wise programmable pull-up resistor

**■ Built-in On Chip Debugger (OCD)**

- One-wire debug tool interface
- Break function:
  - Hardware break: 6 points (shared with code event)
  - Software break: 4096 points
- Event function
  - Code event: 6 points (shared with hardware break)
  - Data event: 6 points
  - Event sequencer: 2 levels + reset
- Execution time measurement function
- Trace function: 42 branches
- Security function

**■ Flash Memory**

- Dual operation flash allowing reading of one Flash bank while programming or erasing the other bank
- Command sequencer for automatic execution of programming algorithm and for supporting DMA for programming of the Flash Memory
- Supports automatic programming, Embedded Algorithm
- Write/Erase/Erase-Suspend/Resume commands
- A flag indicating completion of the automatic algorithm
- Erase can be performed on each sector individually
- Sector protection
- Flash Security feature to protect the content of the Flash
- Low voltage detection during Flash erases or writes

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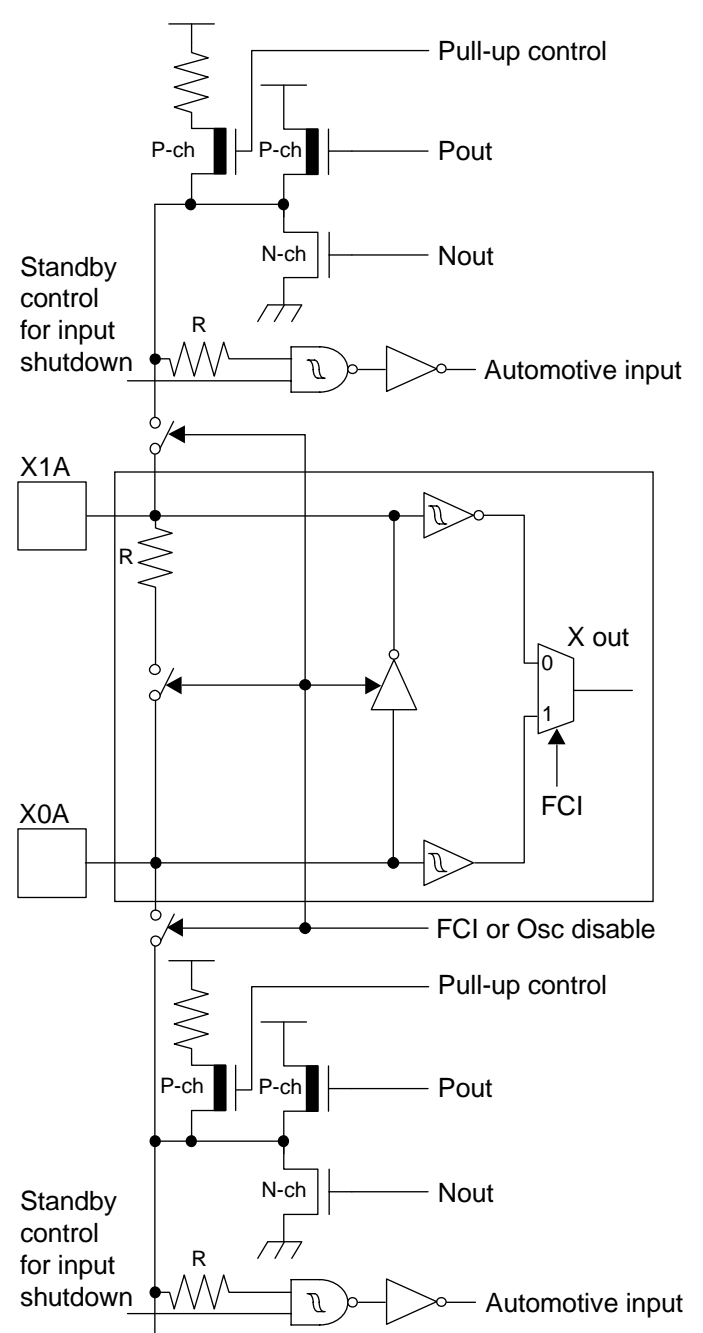
## 5. Pin Circuit Type

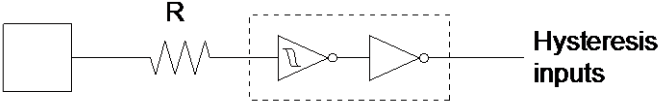
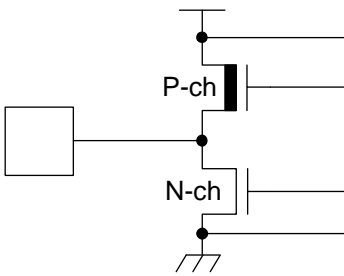
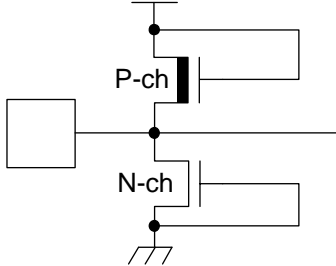
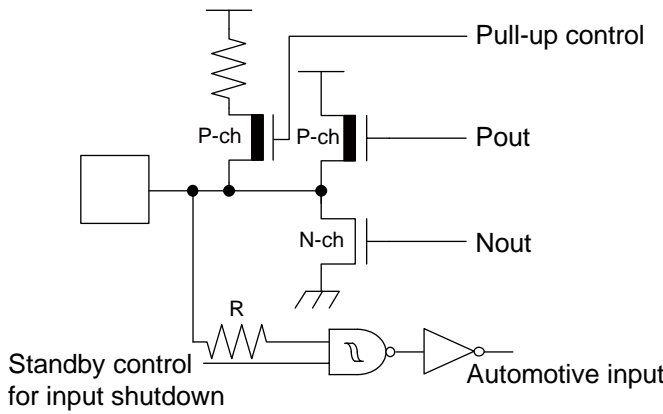
Pin no.	I/O circuit type*	Pin name
1	Supply	Vss
2	F	C
3	M	P03_7 / INT1 / SIN1
4	H	P13_0 / INT2 / SOT1
5	M	P13_1 / INT3 / SCK1
6	H	P13_2 / PPG0 / TIN0 / FRCK1
7	H	P13_3 / PPG1 / TOT0 / WOT
8	M	P13_4 / SIN0 / INT6
9	H	P13_5 / SOT0 / ADTG / INT7
10	M	P13_6 / SCK0 / CKOTX0
11	N	P04_4 / PPG3 / SDA0
12	N	P04_5 / PPG4 / SCL0
13	I	P06_2 / AN2 / INT5 / SIN5
14	K	P06_3 / AN3 / FRCK0
15	K	P06_4 / AN4 / IN0 / TTG0 / TTG4
16	K	P06_6 / AN6 / TIN1 / IN4_R
17	K	P06_7 / AN7 / TOT1 / IN5_R
18	Supply	AVcc
19	G	AVRH
20	G	AVRL
21	Supply	AVss
22	K	P05_0 / AN8
23	K	P05_2 / AN10 / OUT2
24	K	P05_3 / AN11 / OUT3
25	Supply	Vcc
26	Supply	Vss
27	K	P05_4 / AN12 / INT2_R / WOT_R
28	K	P05_6 / AN14 / TIN2
29	K	P05_7 / AN15 / TOT2
30	K	P08_0 / AN16
31	K	P08_1 / AN17
32	K	P08_2 / AN18
33	K	P08_3 / AN19
34	K	P08_4 / AN20 / OUT6
35	N	P04_6 / SDA1
36	N	P04_7 / SCL1
37	K	P08_5 / AN21 / OUT7
38	K	P08_6 / AN22 / PPG6_B

Pin no.	I/O circuit type*	Pin name
39	K	P08_7 / AN23 / PPG7_B
40	K	P09_0 / AN24 / PPG8_R
41	K	P09_1 / AN25 / PPG9_R
42	K	P09_2 / AN26 / PPG10_R
43	K	P09_3 / AN27 / PPG11_R
44	H	P17_1 / PPG12_R
45	H	P17_2 / PPG13_R
46	I	P10_0 / SIN2 / TIN3 / AN28 / INT11
47	H	P10_1 / SOT2 / TOT3
48	M	P10_2 / SCK2 / PPG6
49	H	P10_3 / PPG7
50	Supply	Vcc
51	Supply	Vss
52	O	DEBUG I/F
53	H	P17_0
54	C	MD
55	A	X0
56	A	X1
57	Supply	Vss
58	B	P04_0 / X0A
59	B	P04_1 / X1A
60	C	RSTX
61	H	P11_0
62	H	P11_1 / PPG0_R
63	H	P11_2 / PPG1_R
64	H	P11_3 / PPG2_R
65	H	P11_4 / PPG3_R
66	H	P11_5 / PPG4_R
67	H	P11_6 / FRCK0_R / ZIN1
68	H	P11_7 / IN0_R / AIN1
69	H	P12_0 / IN1_R / BIN1
70	H	P12_3 / OUT2_R
71	H	P12_7 / INT1_R
72	H	P00_0 / INT3_R / FRCK2
73	H	P00_1 / INT4_R
74	H	P00_2 / INT5_R
75	Supply	Vcc
76	Supply	Vss
77	H	P00_3 / INT6_R / PPG8_B

Pin no.	I/O circuit type*	Pin name
78	H	P00_4 / INT7_R / PPG9_B
79	H	P00_5 / IN6 / TTG2 / TTG6 / PPG10_B
80	H	P00_6 / IN7 / TTG3 / TTG7 / PPG11_B
81	H	P00_7 / INT14
82	M	P01_0 / SCK7
83	H	P01_1 / CKOT1 / OUT0 / SOT7
84	M	P01_2 / CKOTX1 / OUT1 / INT15 / SIN7
85	H	P01_3 / PPG5
86	M	P01_4 / SIN4 / INT8
87	H	P01_5 / SOT4
88	M	P01_6 / SCK4 / TTG12
89	M	P01_7 / CKOTX1_R / INT9 / TTG13 / ZIN0 / SCK7_R
90	H	P02_0 / CKOT1_R / INT10 / TTG14 / AIN0 / SOT7_R
91	M	P02_2 / IN7_R / CKOT0_R / INT12 / BIN0 / SIN7_R
92	M	P02_5 / OUT0_R / INT13 / SIN5_R
93	H	P03_0 / PPG4_B
94	H	P03_1 / PPG5_B
95	H	P03_2 / PPG14_B / SOT5_R
96	M	P03_3 / PPG15_B / SCK5_R
97	M	P03_4 / RX0 / INT4
98	H	P03_5 / TX0
99	H	P03_6 / INT0 / NMI
100	Supply	Vcc

\*: See "I/O Circuit Type" for details on the I/O circuit types.

Type	Circuit	Remarks
B	 <p>The circuit diagram illustrates a low-speed oscillation circuit shared with GPIO functionality. It features two identical input/output blocks. Each block includes a pull-up control, P-out, N-out, and automotive input. A standby control for input shutdown is shown. The central part of the diagram shows a feedback loop with resistors R, inverters, and a multiplexer X out controlled by FCI. Labels include X1A, X0A, FCI or Osc disable, and Automotive input.</p>	<p>Low-speed oscillation circuit shared with GPIO functionality:</p> <ul style="list-style-type: none"> <li>• Feedback resistor = approx. <math>5.0\text{M}\Omega</math></li> <li>• GPIO functionality selectable (CMOS level output (<math>I_{OL} = 4\text{mA}</math>, <math>I_{OH} = -4\text{mA}</math>), Automotive input with input shutdown function and programmable pull-up resistor)</li> </ul>

Type	Circuit	Remarks
C		CMOS hysteresis input pin
F		Power supply input protection circuit
G		<ul style="list-style-type: none"> <li>• A/D converter ref+ (AVRH)/ ref- (AVRL) power supply input pin with protection circuit</li> <li>• Without protection circuit against <math>V_{CC}</math> for pins AVRH/AVRL</li> </ul>
H		<ul style="list-style-type: none"> <li>• CMOS level output (<math>I_{OL} = 4mA</math>, <math>I_{OH} = -4mA</math>)</li> <li>• Automotive input with input shutdown function</li> <li>• Programmable pull-up resistor</li> </ul>



Vector number	Offset in vector table	Vector name	Cleared by DMA	Index in ICR to program	Description
40	35C <sub>H</sub>	PPG2	Yes	40	Programmable Pulse Generator 2
41	358 <sub>H</sub>	PPG3	Yes	41	Programmable Pulse Generator 3
42	354 <sub>H</sub>	PPG4	Yes	42	Programmable Pulse Generator 4
43	350 <sub>H</sub>	PPG5	Yes	43	Programmable Pulse Generator 5
44	34C <sub>H</sub>	PPG6	Yes	44	Programmable Pulse Generator 6
45	348 <sub>H</sub>	PPG7	Yes	45	Programmable Pulse Generator 7
46	344 <sub>H</sub>	PPG8	Yes	46	Programmable Pulse Generator 8
47	340 <sub>H</sub>	PPG9	Yes	47	Programmable Pulse Generator 9
48	33C <sub>H</sub>	PPG10	Yes	48	Programmable Pulse Generator 10
49	338 <sub>H</sub>	PPG11	Yes	49	Programmable Pulse Generator 11
50	334 <sub>H</sub>	PPG12	Yes	50	Programmable Pulse Generator 12
51	330 <sub>H</sub>	PPG13	Yes	51	Programmable Pulse Generator 13
52	32C <sub>H</sub>	PPG14	Yes	52	Programmable Pulse Generator 14
53	328 <sub>H</sub>	PPG15	Yes	53	Programmable Pulse Generator 15
54	324 <sub>H</sub>	-	-	54	Reserved
55	320 <sub>H</sub>	-	-	55	Reserved
56	31C <sub>H</sub>	-	-	56	Reserved
57	318 <sub>H</sub>	-	-	57	Reserved
58	314 <sub>H</sub>	RLT0	Yes	58	Reload Timer 0
59	310 <sub>H</sub>	RLT1	Yes	59	Reload Timer 1
60	30C <sub>H</sub>	RLT2	Yes	60	Reload Timer 2
61	308 <sub>H</sub>	RLT3	Yes	61	Reload Timer 3
62	304 <sub>H</sub>	-	-	62	Reserved
63	300 <sub>H</sub>	-	-	63	Reserved
64	2FC <sub>H</sub>	RLT6	Yes	64	Reload Timer 6
65	2F8 <sub>H</sub>	ICU0	Yes	65	Input Capture Unit 0
66	2F4 <sub>H</sub>	ICU1	Yes	66	Input Capture Unit 1
67	2F0 <sub>H</sub>	-	-	67	Reserved
68	2EC <sub>H</sub>	-	-	68	Reserved
69	2E8 <sub>H</sub>	ICU4	Yes	69	Input Capture Unit 4
70	2E4 <sub>H</sub>	ICU5	Yes	70	Input Capture Unit 5
71	2E0 <sub>H</sub>	ICU6	Yes	71	Input Capture Unit 6
72	2DC <sub>H</sub>	ICU7	Yes	72	Input Capture Unit 7
73	2D8 <sub>H</sub>	-	-	73	Reserved
74	2D4 <sub>H</sub>	ICU9	Yes	74	Input Capture Unit 9
75	2D0 <sub>H</sub>	-	-	75	Reserved
76	2CC <sub>H</sub>	-	-	76	Reserved
77	2C8 <sub>H</sub>	OCU0	Yes	77	Output Compare Unit 0
78	2C4 <sub>H</sub>	OCU1	Yes	78	Output Compare Unit 1
79	2C0 <sub>H</sub>	OCU2	Yes	79	Output Compare Unit 2
80	2BC <sub>H</sub>	OCU3	Yes	80	Output Compare Unit 3
81	2B8 <sub>H</sub>	OCU4	Yes	81	Output Compare Unit 4

Vector number	Offset in vector table	Vector name	Cleared by DMA	Index in ICR to program	Description
82	2B4 <sub>H</sub>	-	-	82	Reserved
83	2B0 <sub>H</sub>	OCU6	Yes	83	Output Compare Unit 6
84	2AC <sub>H</sub>	OCU7	Yes	84	Output Compare Unit 7
85	2A8 <sub>H</sub>	-	-	85	Reserved
86	2A4 <sub>H</sub>	-	-	86	Reserved
87	2A0 <sub>H</sub>	-	-	87	Reserved
88	29C <sub>H</sub>	-	-	88	Reserved
89	298 <sub>H</sub>	FRT0	Yes	89	Free-Running Timer 0
90	294 <sub>H</sub>	FRT1	Yes	90	Free-Running Timer 1
91	290 <sub>H</sub>	FRT2	Yes	91	Free-Running Timer 2
92	28C <sub>H</sub>	-	-	92	Reserved
93	288 <sub>H</sub>	RTC0	No	93	Real Time Clock
94	284 <sub>H</sub>	CAL0	No	94	Clock Calibration Unit
95	280 <sub>H</sub>	-	-	95	Reserved
96	27C <sub>H</sub>	IIC0	Yes	96	I <sup>2</sup> C interface 0
97	278 <sub>H</sub>	IIC1	Yes	97	I <sup>2</sup> C interface 1
98	274 <sub>H</sub>	ADC0	Yes	98	A/D Converter 0
99	270 <sub>H</sub>	-	-	99	Reserved
100	26C <sub>H</sub>	-	-	100	Reserved
101	268 <sub>H</sub>	LINR0	Yes	101	LIN USART 0 RX
102	264 <sub>H</sub>	LINT0	Yes	102	LIN USART 0 TX
103	260 <sub>H</sub>	LINR1	Yes	103	LIN USART 1 RX
104	25C <sub>H</sub>	LINT1	Yes	104	LIN USART 1 TX
105	258 <sub>H</sub>	LINR2	Yes	105	LIN USART 2 RX
106	254 <sub>H</sub>	LINT2	Yes	106	LIN USART 2 TX
107	250 <sub>H</sub>	-	-	107	Reserved
108	24C <sub>H</sub>	-	-	108	Reserved
109	248 <sub>H</sub>	LINR4	Yes	109	LIN USART 4 RX
110	244 <sub>H</sub>	LINT4	Yes	110	LIN USART 4 TX
111	240 <sub>H</sub>	LINR5	Yes	111	LIN USART 5 RX
112	23C <sub>H</sub>	LINT5	Yes	112	LIN USART 5 TX
113	238 <sub>H</sub>	-	-	113	Reserved
114	234 <sub>H</sub>	-	-	114	Reserved
115	230 <sub>H</sub>	LINR7	Yes	115	LIN USART 7 RX
116	22C <sub>H</sub>	LINT7	Yes	116	LIN USART 7 TX
117	228 <sub>H</sub>	-	-	117	Reserved
118	224 <sub>H</sub>	-	-	118	Reserved
119	220 <sub>H</sub>	-	-	119	Reserved
120	21C <sub>H</sub>	-	-	120	Reserved

#### ■ Precautions Related to Usage of Devices

Cypress semiconductor devices are intended for use in standard applications (computers, office automation and other office equipment, industrial, communications, and measurement equipment, personal or household devices, etc.).

CAUTION: Customers considering the use of our products in special applications where failure or abnormal operation may directly affect human lives or cause physical injury or property damage, or where extremely high levels of reliability are demanded (such as aerospace systems, atomic energy controls, sea floor repeaters, vehicle operating controls, medical devices for life support, etc.) are requested to consult with sales representatives before such use. The company will not be responsible for damages arising from such use without prior approval.

### 12.2 Precautions for Package Mounting

Package mounting may be either lead insertion type or surface mount type. In either case, for heat resistance during soldering, you should only mount under Cypress's recommended conditions. For detailed information about mount conditions, contact your sales representative.

#### ■ Lead Insertion Type

Mounting of lead insertion type packages onto printed circuit boards may be done by two methods: direct soldering on the board, or mounting by using a socket.

Direct mounting onto boards normally involves processes for inserting leads into through-holes on the board and using the flow soldering (wave soldering) method of applying liquid solder. In this case, the soldering process usually causes leads to be subjected to thermal stress in excess of the absolute ratings for storage temperature. Mounting processes should conform to Cypress recommended mounting conditions.

If socket mounting is used, differences in surface treatment of the socket contacts and IC lead surfaces can lead to contact deterioration after long periods. For this reason it is recommended that the surface treatment of socket contacts and IC leads be verified before mounting.

#### ■ Surface Mount Type

Surface mount packaging has longer and thinner leads than lead-insertion packaging, and therefore leads are more easily deformed or bent. The use of packages with higher pin counts and narrower pin pitch results in increased susceptibility to open connections caused by deformed pins, or shorting due to solder bridges.

You must use appropriate mounting techniques. Cypress recommends the solder reflow method, and has established a ranking of mounting conditions for each product. Users are advised to mount packages in accordance with Cypress ranking of recommended conditions.

#### ■ Lead-Free Packaging

CAUTION: When ball grid array (BGA) packages with Sn-Ag-Cu balls are mounted using Sn-Pb eutectic soldering, junction strength may be reduced under some conditions of use.

#### ■ Storage of Semiconductor Devices

Because plastic chip packages are formed from plastic resins, exposure to natural environmental conditions will cause absorption of moisture. During mounting, the application of heat to a package that has absorbed moisture can cause surfaces to peel, reducing moisture resistance and causing packages to crack. To prevent, do the following:

1. Avoid exposure to rapid temperature changes, which cause moisture to condense inside the product. Store products in locations where temperature changes are slight.
2. Use dry boxes for product storage. Products should be stored below 70% relative humidity, and at temperatures between 5°C and 30°C.  
When you open Dry Package that recommends humidity 40% to 70% relative humidity.
3. When necessary, Cypress packages semiconductor devices in highly moisture-resistant aluminum laminate bags, with a silica gel desiccant. Devices should be sealed in their aluminum laminate bags for storage.
4. Avoid storing packages where they are exposed to corrosive gases or high levels of dust.

#### ■ Baking

Packages that have absorbed moisture may be de-moisturized by baking (heat drying). Follow the Cypress recommended conditions for baking.

Condition: 125°C/24 h

### 13.8 Pin handling when not using the A/D converter

If the A/D converter is not used, the power supply pins for A/D converter should be connected such as  $AV_{CC} = V_{CC}$ ,  $AV_{SS} = AVRH = V_{SS}$ .

### 13.9 Notes on Power-on

To prevent malfunction of the internal voltage regulator, supply voltage profile while turning the power supply on should be slower than 50 $\mu$ s from 0.2V to 2.7V.

### 13.10 Stabilization of power supply voltage

If the power supply voltage varies acutely even within the operation safety range of the  $V_{CC}$  power supply voltage, a malfunction may occur. The  $V_{CC}$  power supply voltage must therefore be stabilized. As stabilization guidelines, the power supply voltage must be stabilized in such a way that  $V_{CC}$  ripple fluctuations (peak to peak value) in the commercial frequencies (50Hz to 60Hz) fall within 10% of the standard  $V_{CC}$  power supply voltage and the transient fluctuation rate becomes 0.1V/ $\mu$ s or less in instantaneous fluctuation for power supply switching.

### 13.11 Serial communication

There is a possibility to receive wrong data due to noise or other causes on the serial communication.

Therefore, design a printed circuit board so as to avoid noise.

Consider receiving of wrong data when designing the system. For example apply a checksum and retransmit the data if an error occurs.

### 13.12 Mode Pin (MD)

Connect the mode pin directly to  $V_{CC}$  or  $V_{SS}$  pin. To prevent the device unintentionally entering test mode due to noise, lay out the printed circuit board so as to minimize the distance from the mode pin to  $V_{CC}$  or  $V_{SS}$  pin and provide a low-impedance connection.

## 14.2 Recommended Operating Conditions

(V<sub>SS</sub> = AV<sub>SS</sub> = 0V)

Parameter	Symbol	Value			Unit	Remarks
		Min	Typ	Max		
Power supply voltage	V <sub>CC</sub> , AV <sub>CC</sub>	2.7	-	5.5	V	
		2.0	-	5.5	V	Maintains RAM data in stop mode
Smoothing capacitor at C pin	C <sub>S</sub>	0.5	1.0 to 3.9	4.7	μF	1.0μF (Allowance within ± 50%) 3.9μF (Allowance within ± 20%) Please use the ceramic capacitor or the capacitor of the frequency response of this level. The smoothing capacitor at V <sub>CC</sub> must use the one of a capacity value that is larger than C <sub>S</sub> .

### WARNING

The recommended operating conditions are required in order to ensure the normal operation of the semiconductor device. All of the device's electrical characteristics are warranted when the device is operated within these ranges. Always use semiconductor devices within their recommended operating condition ranges. Operation outside these ranges may adversely affect reliability and could result in device failure. No warranty is made with respect to uses, operating conditions, or combinations not represented on the data sheet. Users considering application outside the listed conditions are advised to contact their representatives beforehand.

Parameter	Symbol	Pin name	Conditions	Value			Unit	Remarks
				Min	Typ	Max		
Power supply current in Sleep modes <sup>1</sup>	I <sub>CCSPLL</sub>	V <sub>CC</sub>	PLL Sleep mode with CLKS1/2 = CLKP1/2 = 32MHz (CLKRC and CLKSC stopped)	-	8.5	-	mA	T <sub>A</sub> = +25°C
				-	-	14	mA	T <sub>A</sub> = +105°C
				-	-	15.5	mA	T <sub>A</sub> = +125°C
	I <sub>CCSMAIN</sub>		Main Sleep mode with CLKS1/2 = CLKP1/2 = 4MHz, SMCR:LPMSS = 0 (CLKPLL, CLKRC and CLKSC stopped)	-	1	-	mA	T <sub>A</sub> = +25°C
				-	-	4.5	mA	T <sub>A</sub> = +105°C
				-	-	6	mA	T <sub>A</sub> = +125°C
	I <sub>CCSRCH</sub>		RC Sleep mode with CLKS1/2 = CLKP1/2 = CLKRC = 2MHz, SMCR:LPMSS = 0 (CLKMC, CLKPLL and CLKSC stopped)	-	0.6	-	mA	T <sub>A</sub> = +25°C
				-	-	3.8	mA	T <sub>A</sub> = +105°C
				-	-	5.3	mA	T <sub>A</sub> = +125°C
	I <sub>CCSRCL</sub>		RC Sleep mode with CLKS1/2 = CLKP1/2 = CLKRC = 100kHz (CLKMC, CLKPLL and CLKSC stopped)	-	0.07	-	mA	T <sub>A</sub> = +25°C
				-	-	2.8	mA	T <sub>A</sub> = +105°C
				-	-	4.3	mA	T <sub>A</sub> = +125°C
	I <sub>CCSSUB</sub>		Sub Sleep mode with CLKS1/2 = CLKP1/2 = 32kHz, (CLKMC, CLKPLL and CLKRC stopped)	-	0.04	-	mA	T <sub>A</sub> = +25°C
				-	-	2.5	mA	T <sub>A</sub> = +105°C
				-	-	4	mA	T <sub>A</sub> = +125°C

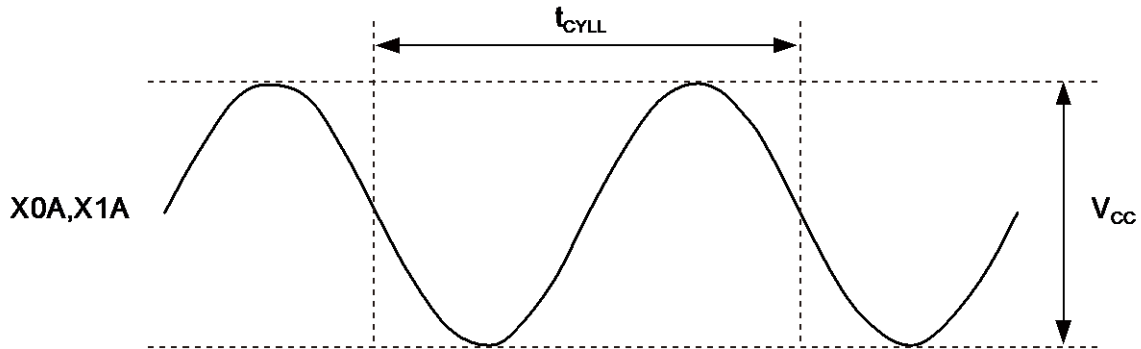
Parameter	Symbol	Pin name	Conditions	Value			Unit	Remarks
				Min	Typ	Max		
"H" level output voltage	V <sub>OH4</sub>	4mA type	4.5V ≤ V <sub>CC</sub> ≤ 5.5V I <sub>OH</sub> = -4mA	V <sub>CC</sub> - 0.5	-	V <sub>CC</sub>	V	
			2.7V ≤ V <sub>CC</sub> < 4.5V I <sub>OH</sub> = -1.5mA					
	V <sub>OH3</sub>	3mA type	4.5V ≤ V <sub>CC</sub> ≤ 5.5V I <sub>OH</sub> = -3mA	V <sub>CC</sub> - 0.5	-	V <sub>CC</sub>	V	
			2.7V ≤ V <sub>CC</sub> < 4.5V I <sub>OH</sub> = -1.5mA					
"L" level output voltage	V <sub>OL4</sub>	4mA type	4.5V ≤ V <sub>CC</sub> ≤ 5.5V I <sub>OL</sub> = +4mA	-	-	0.4	V	
			2.7V ≤ V <sub>CC</sub> < 4.5V I <sub>OL</sub> = +1.7mA					
	V <sub>OL3</sub>	3mA type	2.7V ≤ V <sub>CC</sub> < 5.5V I <sub>OL</sub> = +3mA	-	-	0.4	V	
	V <sub>OLD</sub>	DEBUG I/F	V <sub>CC</sub> = 2.7V I <sub>OL</sub> = +25mA	0	-	0.25	V	
Input leak current	I <sub>IL</sub>	Pnn_m	V <sub>SS</sub> < V <sub>I</sub> < V <sub>CC</sub> AV <sub>SS</sub> , AV <sub>RL</sub> < V <sub>I</sub> < AV <sub>CC</sub> , AV <sub>RH</sub>	- 1	-	+ 1	μA	
Pull-up resistance value	R <sub>PU</sub>	Pnn_m	V <sub>CC</sub> = 5.0V ±10%	25	50	100	kΩ	
Input capacitance	C <sub>IN</sub>	Other than C, V <sub>CC</sub> , V <sub>SS</sub> , AV <sub>CC</sub> , AV <sub>SS</sub> , AV <sub>RH</sub> , AV <sub>RL</sub>	-	-	5	15	pF	

#### 14.4.2 Sub Clock Input Characteristics

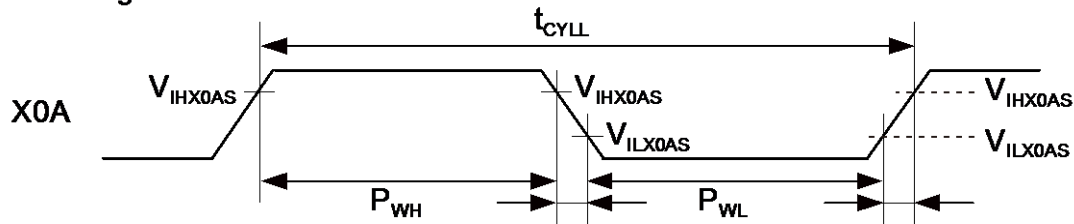
( $V_{CC} = AV_{CC} = 2.7V$  to  $5.5V$ ,  $V_{SS} = AV_{SS} = 0V$ ,  $T_A = -40^{\circ}C$  to  $+125^{\circ}C$ )

Parameter	Symbol	Pin name	Conditions	Value			Unit	Remarks
				Min	Typ	Max		
Input frequency	$f_{CL}$	X0A, X1A	-	-	32.768	-	kHz	When using an oscillation circuit
			-	-	-	100	kHz	When using an opposite phase external clock
		X0A	-	-	-	50	kHz	When using a single phase external clock
Input clock cycle	$t_{CYLL}$	-	-	10	-	-	$\mu s$	
Input clock pulse width	-	-	$P_{WH}/t_{CYLL}$ , $P_{WL}/t_{CYLL}$	30	-	70	%	

**When using the crystal oscillator**



**When using the external clock**

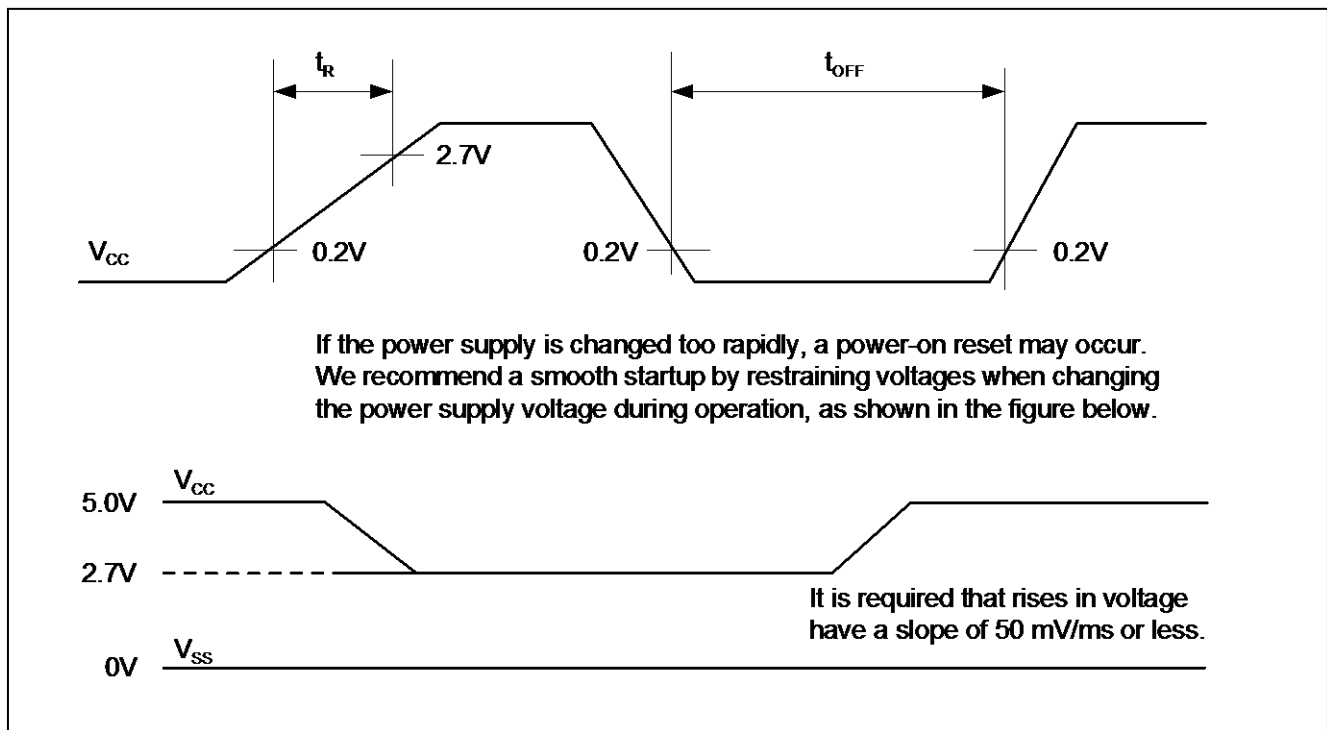




#### 14.4.7 Power-on Reset Timing

( $V_{CC} = AV_{CC} = 2.7V$  to  $5.5V$ ,  $V_{SS} = AV_{SS} = 0V$ ,  $T_A = -40^{\circ}C$  to  $+125^{\circ}C$ )

Parameter	Symbol	Pin name	Value			Unit
			Min	Typ	Max	
Power on rise time	$t_R$	Vcc	0.05	-	30	ms
Power off time	$t_{OFF}$	Vcc	1	-	-	ms



## 14.5 A/D Converter

### 14.5.1 Electrical Characteristics for the A/D Converter

( $V_{CC} = AV_{CC} = 2.7V$  to  $5.5V$ ,  $V_{SS} = AV_{SS} = 0V$ ,  $T_A = -40^{\circ}C$  to  $+125^{\circ}C$ )

Parameter	Symbol	Pin name	Value			Unit	Remarks
			Min	Typ	Max		
Resolution	-	-	-	-	10	bit	
Total error	-	-	- 3.0	-	+ 3.0	LSB	
Nonlinearity error	-	-	- 2.5	-	+ 2.5	LSB	
Differential Nonlinearity error	-	-	- 1.9	-	+ 1.9	LSB	
Zero transition voltage	$V_{OT}$	ANn	Typ - 20	AVRL + 0.5LSB	Typ + 20	mV	
Full scale transition voltage	$V_{FST}$	ANn	Typ - 20	AVRH - 1.5LSB	Typ + 20	mV	
Compare time *	-	-	1.0	-	5.0	$\mu s$	$4.5V \leq AV_{CC} \leq 5.5V$
			2.2	-	8.0	$\mu s$	$2.7V \leq AV_{CC} < 4.5V$
Sampling time *	-	-	0.5	-	-	$\mu s$	$4.5V \leq AV_{CC} \leq 5.5V$
			1.2	-	-	$\mu s$	$2.7V \leq AV_{CC} < 4.5V$
Power supply current	$I_A$	$AV_{CC}$	-	2.0	3.1	mA	A/D Converter active
	$I_{AH}$		-	-	3.3	$\mu A$	A/D Converter not operated
Reference power supply current (between AVRH and AVRL)	$I_R$	AVRH	-	520	810	$\mu A$	A/D Converter active
	$I_{RH}$		-	-	1.0	$\mu A$	A/D Converter not operated
Analog input capacity	$C_{VIN}$	ANn	-	-	15.9	pF	
Analog impedance	$R_{VIN}$	ANn	-	-	2050	$\Omega$	$4.5V \leq AV_{CC} \leq 5.5V$
			-	-	3600	$\Omega$	$2.7V \leq AV_{CC} < 4.5V$
Analog port input current (during conversion)	$I_{AIN}$	ANn	- 0.3	-	+ 0.3	$\mu A$	$AV_{SS}, AVRL < V_{AIN} < AV_{CC}, AVRH$
Analog input voltage	$V_{AIN}$	ANn	AVRL	-	AVRH	V	
Reference voltage range	-	AVRH	$AV_{CC} - 0.1$	-	$AV_{CC}$	V	
	-	AVRL	$AV_{SS}$	-	$AV_{SS} + 0.1$	V	
Variation between channels	-	ANn	-	-	4.0	LSB	

\*: Time for each channel.

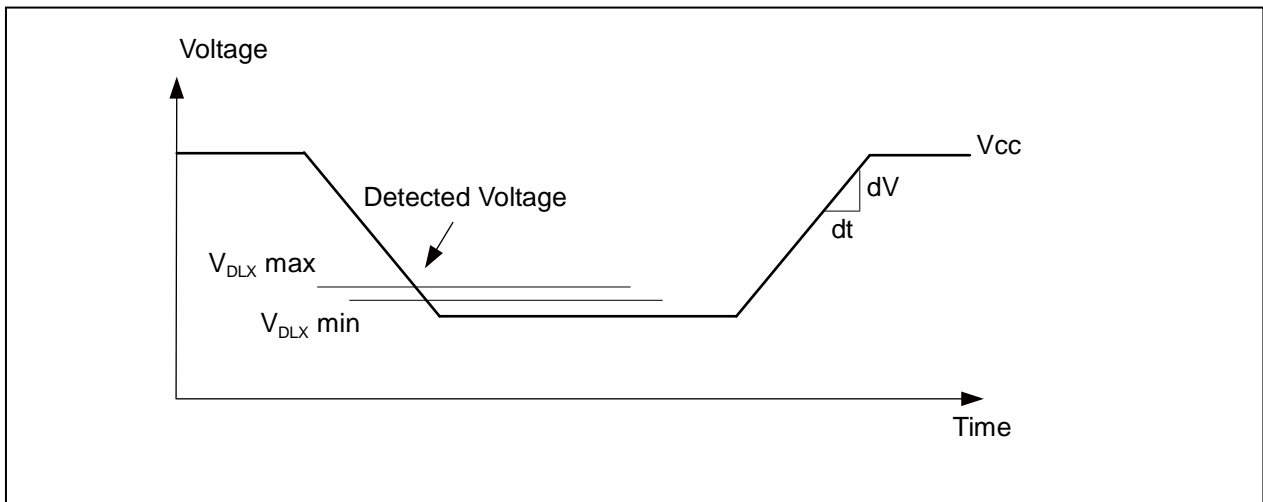
## 14.6 Low Voltage Detection Function Characteristics

( $V_{CC} = AV_{CC} = 2.7V$  to  $5.5V$ ,  $V_{SS} = AV_{SS} = 0V$ ,  $T_A = -40^{\circ}C$  to  $+125^{\circ}C$ )

Parameter	Symbol	Conditions	Value			Unit
			Min	Typ	Max	
Detected voltage <sup>*1</sup>	$V_{DL0}$	CILCR:LVL = 0000 <sub>B</sub>	2.70	2.90	3.10	V
	$V_{DL1}$	CILCR:LVL = 0001 <sub>B</sub>	2.79	3.00	3.21	V
	$V_{DL2}$	CILCR:LVL = 0010 <sub>B</sub>	2.98	3.20	3.42	V
	$V_{DL3}$	CILCR:LVL = 0011 <sub>B</sub>	3.26	3.50	3.74	V
	$V_{DL4}$	CILCR:LVL = 0100 <sub>B</sub>	3.45	3.70	3.95	V
	$V_{DL5}$	CILCR:LVL = 0111 <sub>B</sub>	3.73	4.00	4.27	V
	$V_{DL6}$	CILCR:LVL = 1001 <sub>B</sub>	3.91	4.20	4.49	V
Power supply voltage change rate <sup>*2</sup>	dV/dt	-	- 0.004	-	+ 0.004	V/ $\mu$ s
Hysteresis width	$V_{HYS}$	CILCR:LVHYS=0	-	-	50	mV
		CILCR:LVHYS=1	80	100	120	mV
Stabilization time	$T_{LVDSTAB}$	-	-	-	75	$\mu$ s
Detection delay time	$t_d$	-	-	-	30	$\mu$ s

\*1: If the power supply voltage fluctuates within the time less than the detection delay time ( $t_d$ ), there is a possibility that the low voltage detection will occur or stop after the power supply voltage passes the detection range.

\*2: In order to perform the low voltage detection at the detection voltage ( $V_{DLX}$ ), be sure to suppress fluctuation of the power supply voltage within the limits of the change ration of power supply voltage.



## 16. Ordering Information

MCU with CAN controller

Part number	Flash memory	Package*
MB96F643RBPMC-GSE1	Flash A (96.5KB)	100-pin plastic LQFP (FPT-100P-M20)
MB96F643RBPMC-GSE2		
MB96F645RBPMC-GSE1	Flash A (160.5KB)	100-pin plastic LQFP (FPT-100P-M20)
MB96F645RBPMC-GSE2		
MB96F646RBPMC-GSE1	Flash A (288.5KB)	100-pin plastic LQFP (FPT-100P-M20)
MB96F646RBPMC-GSE2		
MB96F647RBPMC-GSE1	Flash A (416.5KB)	100-pin plastic LQFP (FPT-100P-M20)
MB96F647RBPMC-GSE2		

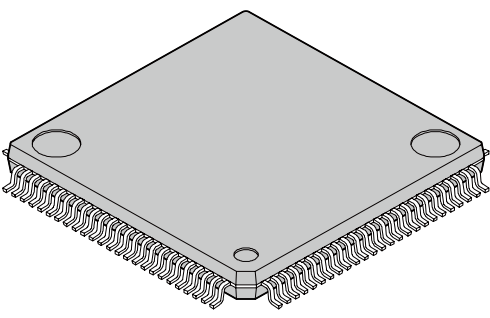
\*: For details about package, see "Package Dimension".

MCU without CAN controller

Part number	Flash memory	Package*
MB96F643ABPMC-GSE1	Flash A (96.5KB)	100-pin plastic LQFP (FPT-100P-M20)
MB96F643ABPMC-GSE2		
MB96F645ABPMC-GSE1	Flash A (160.5KB)	100-pin plastic LQFP (FPT-100P-M20)
MB96F645ABPMC-GSE2		

\*: For details about package, see "Package Dimension".

## 17. Package Dimension

 <p>100-pin plastic LQFP</p> <p>(FPT-100P-M20)</p>	Lead pitch	0.50 mm
	Package width × package length	14.0 mm × 14.0 mm
	Lead shape	Gullwing
	Sealing method	Plastic mold
	Mounting height	1.70 mm Max
	Weight	0.65 g
	Code (Reference)	P-LFQFP100-14×14-0.50

