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### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Obsolete
Core Processor	eZ8
Core Size	8-Bit
Speed	20MHz
Connectivity	IrDA, UART/USART
Peripherals	Brown-out Detect/Reset, LED, LVD, POR, PWM, WDT
Number of I/O	25
Program Memory Size	1KB (1K x 8)
Program Memory Type	FLASH
EEPROM Size	16 x 8
RAM Size	256 x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 3.6V
Data Converters	-
Oscillator Type	Internal
Operating Temperature	0°C ~ 70°C (TA)
Mounting Type	Surface Mount
Package / Case	28-SSOP (0.173", 4.40mm Width)
Supplier Device Package	-
Purchase URL	<a href="https://www.e-xfl.com/product-detail/zilog/z8f011ahj020sc">https://www.e-xfl.com/product-detail/zilog/z8f011ahj020sc</a>

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- Up to thirteen 5 V-tolerant input pins
- Up to 8 ports capable of direct LED drive with no current limit resistor required
- On-Chip Debugger (OCD)
- Voltage Brownout (VBO) protection
- Programmable low battery detection (LVD) (8-pin devices only)
- Bandgap generated precision voltage references available for the ADC, comparator, VBO, and LVD
- Power-On Reset (POR)
- 2.7 V to 3.6 V operating voltage
- 8-, 20-, and 28-pin packages
- 0 °C to +70 °C and -40 °C to +105 °C for operating temperature ranges

## **Part Selection Guide**

[Table 1](#) on page 3 identifies the basic features and package styles available for each device within the Z8 Encore! XP<sup>®</sup> F082A Series product line.

## **Interrupt Controller**

The Z8 Encore! XP<sup>®</sup> F082A Series products support up to 20 interrupts. These interrupts consist of 8 internal peripheral interrupts and 12 general-purpose I/O pin interrupt sources. The interrupts have three levels of programmable interrupt priority.

## **Reset Controller**

The Z8 Encore! XP F082A Series products can be reset using the  $\overline{\text{RESET}}$  pin, Power-On Reset, Watchdog Timer (WDT) time-out, STOP mode exit, or Voltage Brownout (VBO) warning signal. The  $\overline{\text{RESET}}$  pin is bi-directional, that is, it functions as reset source as well as a reset indicator.

**Table 7. Register File Address Map (Continued)**

Address (Hex)	Register Description	Mnemonic	Reset (Hex)	Page No
F91–FBF	Reserved	—	XX	
<b>Interrupt Controller</b>				
FC0	Interrupt Request 0	IRQ0	00	60
FC1	IRQ0 Enable High Bit	IRQ0ENH	00	63
FC2	IRQ0 Enable Low Bit	IRQ0ENL	00	63
FC3	Interrupt Request 1	IRQ1	00	61
FC4	IRQ1 Enable High Bit	IRQ1ENH	00	64
FC5	IRQ1 Enable Low Bit	IRQ1ENL	00	64
FC6	Interrupt Request 2	IRQ2	00	62
FC7	IRQ2 Enable High Bit	IRQ2ENH	00	65
FC8	IRQ2 Enable Low Bit	IRQ2ENL	00	65
FC9–FCC	Reserved	—	XX	
FCD	Interrupt Edge Select	IRQES	00	67
FCE	Shared Interrupt Select	IRQSS	00	67
FCF	Interrupt Control	IRQCTL	00	67
<b>GPIO Port A</b>				
FD0	Port A Address	PAADDR	00	45
FD1	Port A Control	PACTL	00	47
FD2	Port A Input Data	PAIN	XX	47
FD3	Port A Output Data	PAOUT	00	47
<b>GPIO Port B</b>				
FD4	Port B Address	PBADDR	00	45
FD5	Port B Control	PBCTL	00	47
FD6	Port B Input Data	PBIN	XX	47
FD7	Port B Output Data	PBOUT	00	47
<b>GPIO Port C</b>				
FD8	Port C Address	PCADDR	00	45
FD9	Port C Control	PCCTL	00	47
FDA	Port C Input Data	PCIN	XX	47
FDB	Port C Output Data	PCOUT	00	47
<b>GPIO Port D</b>				
FDC	Port D Address	PDADDR	00	45
FDD	Port D Control	PDCTL	00	47
FDE	Reserved	—	XX	
XX=Undefined				

**Table 7. Register File Address Map (Continued)**

Address (Hex)	Register Description	Mnemonic	Reset (Hex)	Page No
FDF	Port D Output Data	PDOUT	00	<a href="#">47</a>
FE0–FEF	Reserved	—	XX	
<b>Watchdog Timer (WDT)</b>				
FF0	Reset Status (Read-only)	RSTSTAT	X0	<a href="#">30</a>
	Watchdog Timer Control (Write-only)	WDTCTL	N/A	<a href="#">94</a>
FF1	Watchdog Timer Reload Upper Byte	WDTU	00	<a href="#">95</a>
FF2	Watchdog Timer Reload High Byte	WDTH	04	<a href="#">95</a>
FF3	Watchdog Timer Reload Low Byte	WDTL	00	<a href="#">95</a>
FF4–FF5	Reserved	—	XX	
<b>Trim Bit Control</b>				
FF6	Trim Bit Address	TRMADR	00	<a href="#">155</a>
FF7	Trim Bit Data	TRMDR	00	<a href="#">156</a>
<b>Flash Memory Controller</b>				
FF8	Flash Control	FCTL	00	<a href="#">149</a>
FF8	Flash Status	FSTAT	00	<a href="#">150</a>
FF9	Flash Page Select	FPS	00	<a href="#">151</a>
	Flash Sector Protect	FPROT	00	<a href="#">151</a>
FFA	Flash Programming Frequency High Byte	FFREQH	00	<a href="#">152</a>
FFB	Flash Programming Frequency Low Byte	FFREQL	00	<a href="#">152</a>
<b>eZ8 CPU</b>				
FFC	Flags	—	XX	Refer to eZ8 CPU Core User Manual (UM0128)
FFD	Register Pointer	RP	XX	
FFE	Stack Pointer High Byte	SPH	XX	
FFF	Stack Pointer Low Byte	SPL	XX	
XX=Undefined				





**Table 14. Port Alternate Function Mapping (Non 8-Pin Parts) (Continued)**

Port	Pin	Mnemonic	Alternate Function Description	Alternate Function Set Register AFS1
Port B	PB0	Reserved		AFS1[0]: 0
		ANA0/AMPOUT	ADC Analog Input/LPO Output	AFS1[0]: 1
	PB1	Reserved		AFS1[1]: 0
		ANA1/AMPINN	ADC Analog Input/LPO Input (N)	AFS1[1]: 1
	PB2	Reserved		AFS1[2]: 0
		ANA2/AMPINP	ADC Analog Input/LPO Input (P)	AFS1[2]: 1
	PB3	CLKIN	External Clock Input	AFS1[3]: 0
		ANA3	ADC Analog Input	AFS1[3]: 1
	PB4	Reserved		AFS1[4]: 0
		ANA7	ADC Analog Input	AFS1[4]: 1
	PB5	Reserved		AFS1[5]: 0
		VREF*	ADC Voltage Reference	AFS1[5]: 1
	PB6	Reserved		AFS1[6]: 0
		Reserved		AFS1[6]: 1
	PB7	Reserved		AFS1[7]: 0
		Reserved		AFS1[7]: 1

**Note:** Because there are at most two choices of alternate function for any pin of Port B, the Alternate Function Set register AFS2 is not used to select the function. Also, alternate function selection as described in [Port A–D Alternate Function Sub-Registers](#) on page 47 must also be enabled.

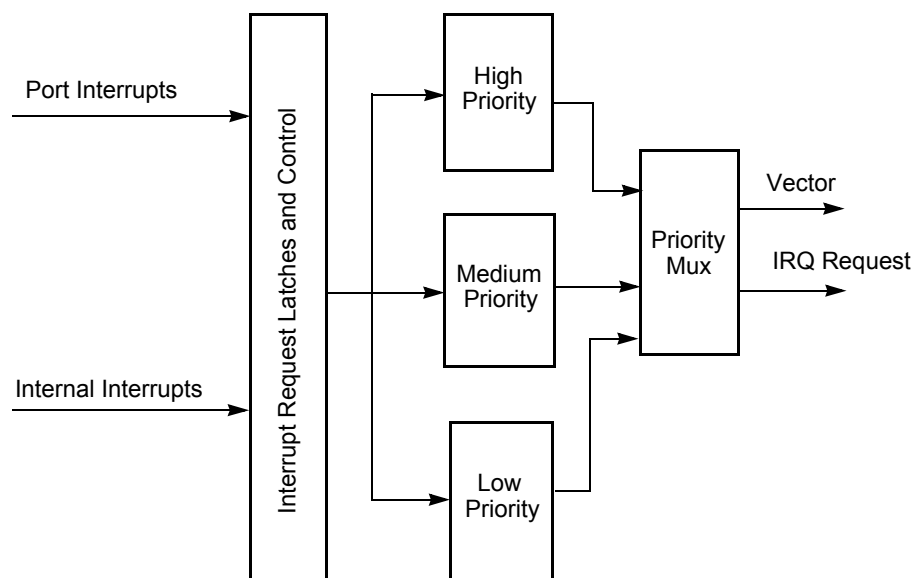
\* VREF is available on PB5 in 28-pin products only.

**Table 32. Trap and Interrupt Vectors in Order of Priority (Continued)**

	Program Memory	
Priority	Vector Address	Interrupt or Trap Source
	0034H	Port C Pin 1, both input edges
Lowest	0036H	Port C Pin 0, both input edges
	0038H	Reserved

## Architecture

Figure 8 displays the interrupt controller block diagram.



**Figure 8. Interrupt Controller Block Diagram**

## Operation

### Master Interrupt Enable

The master interrupt enable bit (IRQE) in the Interrupt Control register globally enables and disables interrupts.

## Watchdog Timer Refresh

When first enabled, the Watchdog Timer is loaded with the value in the Watchdog Timer Reload registers. The Watchdog Timer counts down to 000000H unless a WDT instruction is executed by the eZ8 CPU. Execution of the WDT instruction causes the downcounter to be reloaded with the WDT Reload value stored in the Watchdog Timer Reload registers. Counting resumes following the reload operation.

When the Z8 Encore! XP<sup>®</sup> F082A Series devices are operating in DEBUG mode (using the on-chip debugger), the Watchdog Timer is continuously refreshed to prevent any Watchdog Timer time-outs.

## Watchdog Timer Time-Out Response

The Watchdog Timer times out when the counter reaches 000000H. A time-out of the Watchdog Timer generates either an interrupt or a system reset. The WDT\_RES Flash Option Bit determines the time-out response of the Watchdog Timer. For information on programming the WDT\_RES Flash Option Bit, see [Flash Option Bits](#) on page 153.

### WDT Interrupt in Normal Operation

If configured to generate an interrupt when a time-out occurs, the Watchdog Timer issues an interrupt request to the interrupt controller and sets the WDT status bit in the Reset Status (RSTSTAT) register (see [Reset Status Register](#) on page 30). If interrupts are enabled, the eZ8 CPU responds to the interrupt request by fetching the Watchdog Timer interrupt vector and executing code from the vector address. After time-out and interrupt generation, the Watchdog Timer counter rolls over to its maximum value of FFFFFH and continues counting. The Watchdog Timer counter is not automatically returned to its Reload Value.

The Reset Status (RSTSTAT) register must be read before clearing the WDT interrupt. This read clears the WDT timeout Flag and prevents further WDT interrupts from immediately occurring.

### WDT Interrupt in STOP Mode

If configured to generate an interrupt when a time-out occurs and the Z8 Encore! XP F082A Series devices are in STOP mode, the Watchdog Timer automatically initiates a Stop Mode Recovery and generates an interrupt request. Both the WDT status bit and the STOP bit in the Reset Status (RSTSTAT) register are set to 1 following a WDT time-out in STOP mode. For more information on Stop Mode Recovery, see [Reset, Stop Mode Recovery, and Low Voltage Detection](#) on page 23.

If interrupts are enabled, following completion of the Stop Mode Recovery the eZ8 CPU responds to the interrupt request by fetching the Watchdog Timer interrupt vector and executing code from the vector address.

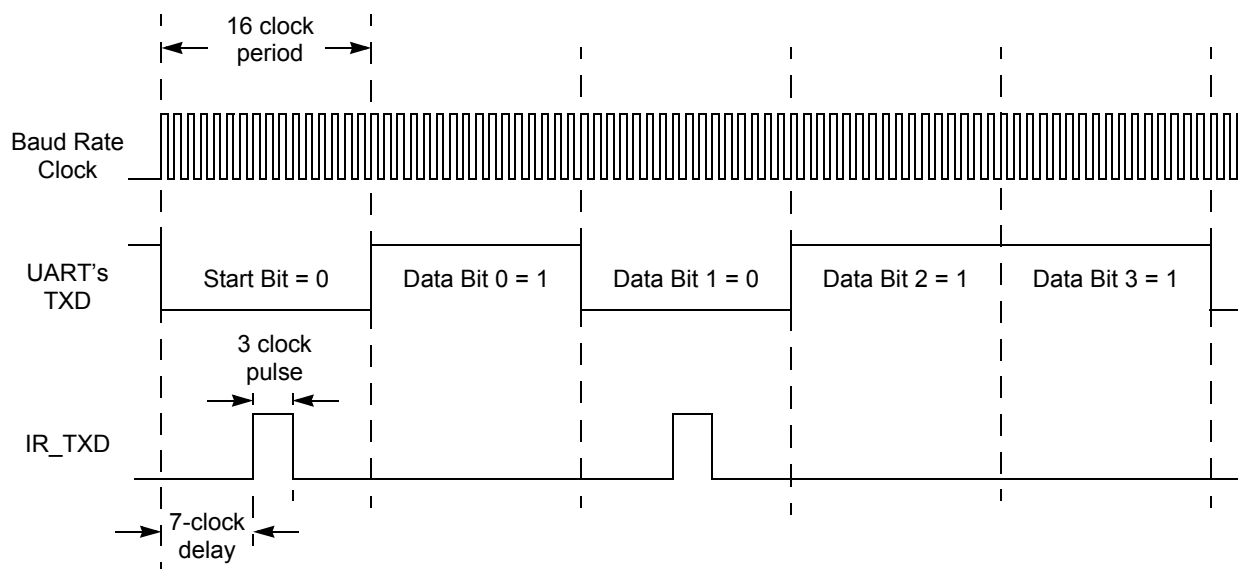
Endec, and passed to the UART. Communication is half-duplex, which means simultaneous data transmission and reception is not allowed.

The baud rate is set by the UART's Baud Rate Generator and supports IrDA standard baud rates from 9600 baud to 115.2 kbaud. Higher baud rates are possible, but do not meet IrDA specifications. The UART must be enabled to use the Infrared Endec. The Infrared Endec data rate is calculated using the following equation:

$$\text{Infrared Data Rate (bits/s)} = \frac{\text{System Clock Frequency (Hz)}}{16 \times \text{UART Baud Rate Divisor Value}}$$

## Transmitting IrDA Data

The data to be transmitted using the infrared transceiver is first sent to the UART. The UART's transmit signal (TXD) and baud rate clock are used by the IrDA to generate the modulation signal (IR\_TXD) that drives the infrared transceiver. Each UART/Infrared data bit is 16 clocks wide. If the data to be transmitted is 1, the IR\_TXD signal remains low for the full 16 clock period. If the data to be transmitted is 0, the transmitter first outputs a 7 clock low period, followed by a 3 clock high pulse. Finally, a 6 clock low pulse is output to complete the full 16 clock data period. [Figure 17](#) displays IrDA data transmission. When the Infrared Endec is enabled, the UART's TXD signal is internal to the Z8 Encore! XP<sup>®</sup> F082A Series products while the IR\_TXD signal is output through the TXD pin.



**Figure 17. Infrared Data Transmission**

### Randomized Lot Identification Bits

As an optional feature, Zilog is able to provide a factory-programmed random lot identifier. With this feature, all devices in a given production lot are programmed with the same random number. This random number is uniquely regenerated for each successive production lot and is not likely to be repeated.

The randomized lot identifier is a 32 byte binary value, stored in the Flash information page (see [Reading the Flash Information Page](#) on page 155 and [Randomized Lot Identifier](#) on page 166 for more details) and is unaffected by mass erasure of the device's Flash memory.

### Reading the Flash Information Page

The following code example shows how to read data from the Flash information area.

```
; get value at info address 60 (FE60h)

ldx FPS, #%80 ; enable access to flash info page

ld R0, #%FE
ld R1, #%60
ldc R2, @RR0 ; R2 now contains the calibration value
```

## Flash Option Bit Control Register Definitions

### Trim Bit Address Register

The Trim Bit Address (TRMADR) register contains the target address for an access to the trim option bits ([Table 84](#)).

**Table 84. Trim Bit Address Register (TRMADR)**

BITS	7	6	5	4	3	2	1	0
FIELD	TRMADR - Trim Bit Address (00H to 1FH)							
RESET	0	0	0	0	0	0	0	0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
ADDR	FF6H							

read operations to illegal addresses. Also, the user code must pop the address byte off the stack.

The read routine uses 9 bytes of stack space in addition to the one byte of address pushed by the user. Sufficient memory must be available for this stack usage.

Because of the Flash memory architecture, NVDS reads exhibit a non-uniform execution time. A read operation takes between 44  $\mu$ s and 489  $\mu$ s (assuming a 20 MHz system clock). Slower system clock speeds result in proportionally higher execution times.

NVDS byte reads from invalid addresses (those exceeding the NVDS array size) return 0xff. Illegal read operations have a 2  $\mu$ s execution time.

The status byte returned by the NVDS read routine is zero for successful read, as determined by a CRC check. If the status byte is non-zero, there was a corrupted value in the NVDS array at the location being read. In this case, the value returned in R0 is the byte most recently written to the array that does not have a CRC error.

## Power Failure Protection

The NVDS routines employ error checking mechanisms to ensure a power failure endangers only the most recently written byte. Bytes previously written to the array are not perturbed.

A system reset (such as a pin reset or Watchdog Timer reset) that occurs during a write operation also perturbs the byte currently being written. All other bytes in the array are unperturbed.

## Optimizing NVDS Memory Usage for Execution Speed

The NVDS read time varies drastically, this discrepancy being a trade-off for minimizing the frequency of writes that require post-write page erases (see [Table 104](#)). The NVDS read time of address N is a function of the number of writes to addresses other than N since the most recent write to address N, as well as the number of writes since the most recent page erase. Neglecting effects caused by page erases and results caused by the initial condition in which the NVDS is blank, a rule of thumb is that every write since the most recent page erase causes read times of unwritten addresses to increase by 1  $\mu$ s, up to a maximum of (511-NVDS\_SIZE)  $\mu$ s.

**Table 104. NVDS Read Time**

Operation	Minimum Latency	Maximum Latency
Read (16 byte array)	875	9961
Read (64 byte array)	876	8952

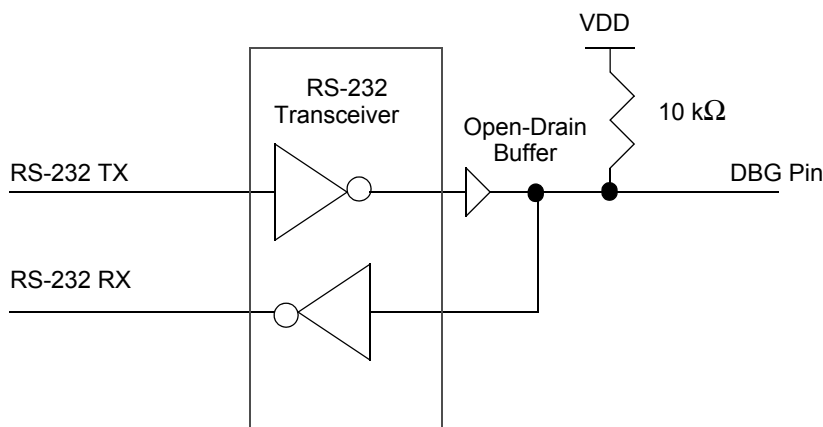


Figure 25. Interfacing the On-Chip Debugger's DBG Pin with an RS-232 Interface (2)

## DEBUG Mode

The operating characteristics of the devices in DEBUG mode are:

- The eZ8 CPU fetch unit stops, idling the eZ8 CPU, unless directed by the OCD to execute specific instructions.
- The system clock operates unless in STOP mode.
- All enabled on-chip peripherals operate unless in STOP mode.
- Automatically exits HALT mode.
- Constantly refreshes the Watchdog Timer, if enabled.

## Entering DEBUG Mode

The operating characteristics of the devices entering DEBUG mode are:

- The device enters DEBUG mode after the eZ8 CPU executes a BRK (Breakpoint) instruction.
- If the DBG pin is held Low during the final clock cycle of system reset, the part enters DEBUG mode immediately (20-/28-pin products only).

► **Note:** *Holding the DBG pin Low for an additional 5000 (minimum) clock cycles after reset (making sure to account for any specified frequency error if using an internal oscillator) prevents a false interpretation of an Autobaud sequence (see [OCD Auto-Baud Detector/Generator](#) on page 176).*

High. Because of the open-drain nature of the DBG pin, the host can send a Serial Break to the OCD even if the OCD is transmitting a character.

## OCD Unlock Sequence (8-Pin Devices Only)

Because of pin-sharing on the 8-pin device, an unlock sequence must be performed to access the DBG pin. If this sequence is not completed during a system reset, then the PA0/DBG pin functions only as a GPIO pin.

The following sequence unlocks the DBG pin:

1. Hold PA2/ $\overline{\text{RESET}}$  Low.
2. Wait 5ms for the internal reset sequence to complete.
3. Send the following bytes serially to the debug pin:  
DBG  $\leftarrow$  80H (autobaud)  
DBG  $\leftarrow$  EBH  
DBG  $\leftarrow$  5AH  
DBG  $\leftarrow$  70H  
DBG  $\leftarrow$  CDH (32-bit unlock key)
4. Release PA2/ $\overline{\text{RESET}}$ . The PA0/DBG pin is now identical in function to that of the DBG pin on the 20-/28-pin device. To enter DEBUG mode, re-autobaud and write 80H to the OCD control register (see [On-Chip Debugger Commands](#) on page 179).



**Caution:** *Between [Step 3](#) and [Step 4](#), there is an interval during which the 8-pin device is neither in RESET nor DEBUG mode. If a device has been erased or has not yet been programmed, all program memory bytes contain FFH. The CPU interprets this as an illegal instruction, so some irregular behavior can occur before entering DEBUG mode, and the register values after entering DEBUG mode differs from their specified reset values. However, none of these irregularities prevent programming the Flash memory. Before beginning system debug, it is recommended that some legal code be programmed into the 8-pin device, and that a RESET occurs.*

## Breakpoints

Execution Breakpoints are generated using the BRK instruction (opcode 00H). When the eZ8 CPU decodes a BRK instruction, it signals the On-Chip Debugger. If Breakpoints are enabled, the OCD enters DEBUG mode and idles the eZ8 CPU. If Breakpoints are not enabled, the OCD ignores the BRK signal and the BRK instruction operates as an NOP instruction.



Debug Command	Command Byte	Enabled when NOT in DEBUG mode?	Disabled by Flash Read Protect Option Bit
Write Register	08H	—	Only writes of the Flash Memory Control registers are allowed. Additionally, only the Mass Erase command is allowed to be written to the Flash Control register.
Read Register	09H	—	Disabled
Write Program Memory	0AH	—	Disabled
Read Program Memory	0BH	—	Disabled
Write Data Memory	0CH	—	Yes
Read Data Memory	0DH	—	—
Read Program Memory CRC	0EH	—	—
Reserved	0FH	—	—
Step Instruction	10H	—	Disabled
Stuff Instruction	11H	—	Disabled
Execute Instruction	12H	—	Disabled
Reserved	13H–FFH	—	—

In the following bulleted list of OCD Commands, data and commands sent from the host to the On-Chip Debugger are identified by 'DBG ← Command/Data'. Data sent from the On-Chip Debugger back to the host is identified by 'DBG → Data'.

- Read OCD Revision (00H)**—The Read OCD Revision command determines the version of the On-Chip Debugger. If OCD commands are added, removed, or changed, this revision number changes.
 

DBG ← 00H

DBG → OCDRev[15:8] (Major revision number)

DBG → OCDRev[7:0] (Minor revision number)
- Read OCD Status Register (02H)**—The Read OCD Status Register command reads the OCDSTAT register.
 

DBG ← 02H

DBG → OCDSTAT[7:0]
- Read Runtime Counter (03H)**—The Runtime Counter counts system clock cycles in between Breakpoints. The 16-bit Runtime Counter counts up from 0000H and stops at the maximum count of FFFFH. The Runtime Counter is overwritten during the



**Caution:** *It is possible to disable the clock failure detection circuitry as well as all functioning clock sources. In this case, the Z8 Encore! XP F082A Series device ceases functioning and can only be recovered by Power-On-Reset.*

## Oscillator Control Register Definitions

### Oscillator Control Register

The Oscillator Control Register (OSCCTL) enables/disables the various oscillator circuits, enables/disables the failure detection/recovery circuitry and selects the primary oscillator, which becomes the system clock.

The Oscillator Control Register must be unlocked before writing. Writing the two step sequence E7H followed by 18H to the Oscillator Control Register unlocks it. The register is locked at successful completion of a register write to the OSCCTL.

**Table 109. Oscillator Control Register (OSCCTL)**

BITS	7	6	5	4	3	2	1	0
FIELD	INTEN	XTLEN	WDTEN	SOFEN	WDFEN	SCKSEL		
RESET	1	0	1	0	0	0	0	0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
ADDR	F86H							

INTEN—Internal Precision Oscillator Enable

1 = Internal precision oscillator is enabled

0 = Internal precision oscillator is disabled

XTLEN—Crystal Oscillator Enable; this setting overrides the GPIO register control for PA0 and PA1

1 = Crystal oscillator is enabled

0 = Crystal oscillator is disabled

WDTEN—Watchdog Timer Oscillator Enable

1 = Watchdog Timer oscillator is enabled

0 = Watchdog Timer oscillator is disabled

SOFEN—System Clock Oscillator Failure Detection Enable

1 = Failure detection and recovery of system clock oscillator is enabled

0 = Failure detection and recovery of system clock oscillator is disabled

WDFEN—Watchdog Timer Oscillator Failure Detection Enable

1 = Failure detection of Watchdog Timer oscillator is enabled

0 = Failure detection of Watchdog Timer oscillator is disabled

SCKSEL—System Clock Oscillator Select

000 = Internal precision oscillator functions as system clock at 5.53 MHz

001 = Internal precision oscillator functions as system clock at 32 kHz

010 = Crystal oscillator or external RC oscillator functions as system clock

011 = Watchdog Timer oscillator functions as system

100 = External clock signal on PB3 functions as system clock

101 = Reserved

110 = Reserved

111 = Reserved

Table 116 through Table 123 lists the instructions belonging to each group and the number of operands required for each instruction. Some instructions appear in more than one table as these instruction can be considered as a subset of more than one category. Within these tables, the source operand is identified as ‘src’, the destination operand is ‘dst’ and a condition code is ‘cc’.

**Table 116. Arithmetic Instructions**

Mnemonic	Operands	Instruction
ADC	dst, src	Add with Carry
ADCX	dst, src	Add with Carry using Extended Addressing
ADD	dst, src	Add
ADDX	dst, src	Add using Extended Addressing
CP	dst, src	Compare
CPC	dst, src	Compare with Carry
CPCX	dst, src	Compare with Carry using Extended Addressing
CPX	dst, src	Compare using Extended Addressing
DA	dst	Decimal Adjust
DEC	dst	Decrement
DECW	dst	Decrement Word
INC	dst	Increment
INCW	dst	Increment Word
MULT	dst	Multiply
SBC	dst, src	Subtract with Carry
SBCX	dst, src	Subtract with Carry using Extended Addressing
SUB	dst, src	Subtract
SUBX	dst, src	Subtract using Extended Addressing

**Table 130. Internal Precision Oscillator Electrical Characteristics**

		$V_{DD} = 2.7 \text{ V to } 3.6 \text{ V}$ $T_A = -40 \text{ }^{\circ}\text{C to } +105 \text{ }^{\circ}\text{C}$ (unless otherwise stated)				
Symbol	Parameter	Minimum	Typical	Maximum	Units	Conditions
$F_{IPO}$	Internal Precision Oscillator Frequency (High Speed)		5.53		MHz	$V_{DD} = 3.3 \text{ V}$ $T_A = 30 \text{ }^{\circ}\text{C}$
$F_{IPO}$	Internal Precision Oscillator Frequency (Low Speed)		32.7		kHz	$V_{DD} = 3.3 \text{ V}$ $T_A = 30 \text{ }^{\circ}\text{C}$
$F_{IPO}$	Internal Precision Oscillator Error		$\pm 1$	$\pm 4$	%	
$T_{IPOST}$	Internal Precision Oscillator Startup Time		3		$\mu\text{s}$	