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Applications of "[Embedded - Microcontrollers](#)"

Details

| | |
|----------------------------|-------------------------------------------------------------------------------------------------------------------------------------------|
| Product Status | Obsolete |
| Core Processor | eZ8 |
| Core Size | 8-Bit |
| Speed | 20MHz |
| Connectivity | IrDA, UART/USART |
| Peripherals | Brown-out Detect/Reset, LED, LVD, POR, PWM, Temp Sensor, WDT |
| Number of I/O | 17 |
| Program Memory Size | 1KB (1K x 8) |
| Program Memory Type | FLASH |
| EEPROM Size | 16 x 8 |
| RAM Size | 256 x 8 |
| Voltage - Supply (Vcc/Vdd) | 2.7V ~ 3.6V |
| Data Converters | A/D 7x10b |
| Oscillator Type | Internal |
| Operating Temperature | 0°C ~ 70°C (TA) |
| Mounting Type | Through Hole |
| Package / Case | 20-DIP (0.300", 7.62mm) |
| Supplier Device Package | 20-PDIP |
| Purchase URL | https://www.e-xfl.com/product-detail/zilog/z8f012aph020sc2103 |

| | |
|--------------------------------------------------------------------|------------|
| Watchdog Timer Time-Out Response | 92 |
| Watchdog Timer Reload Unlock Sequence | 93 |
| Watchdog Timer Calibration | 93 |
| Watchdog Timer Control Register Definitions | 94 |
| Watchdog Timer Control Register | 94 |
| Watchdog Timer Reload Upper, High and Low Byte Registers | 94 |
| Universal Asynchronous Receiver/Transmitter | 97 |
| Architecture | 97 |
| Operation | 98 |
| Data Format | 98 |
| Transmitting Data using the Polled Method | 99 |
| Transmitting Data using the Interrupt-Driven Method | 100 |
| Receiving Data using the Polled Method | 101 |
| Receiving Data using the Interrupt-Driven Method | 102 |
| Clear To Send (CTS) Operation | 103 |
| MULTIPROCESSOR (9-bit) Mode | 103 |
| External Driver Enable | 104 |
| UART Interrupts | 105 |
| UART Baud Rate Generator | 107 |
| UART Control Register Definitions | 108 |
| UART Control 0 and Control 1 Registers | 108 |
| UART Status 0 Register | 111 |
| UART Status 1 Register | 112 |
| UART Transmit Data Register | 113 |
| UART Receive Data Register | 113 |
| UART Address Compare Register | 114 |
| UART Baud Rate High and Low Byte Registers | 114 |
| Infrared Encoder/Decoder | 117 |
| Architecture | 117 |
| Operation | 117 |
| Transmitting IrDA Data | 118 |
| Receiving IrDA Data | 119 |
| Infrared Encoder/Decoder Control Register Definitions | 120 |
| Analog-to-Digital Converter | 121 |
| Architecture | 121 |
| Operation | 122 |
| Data Format | 122 |

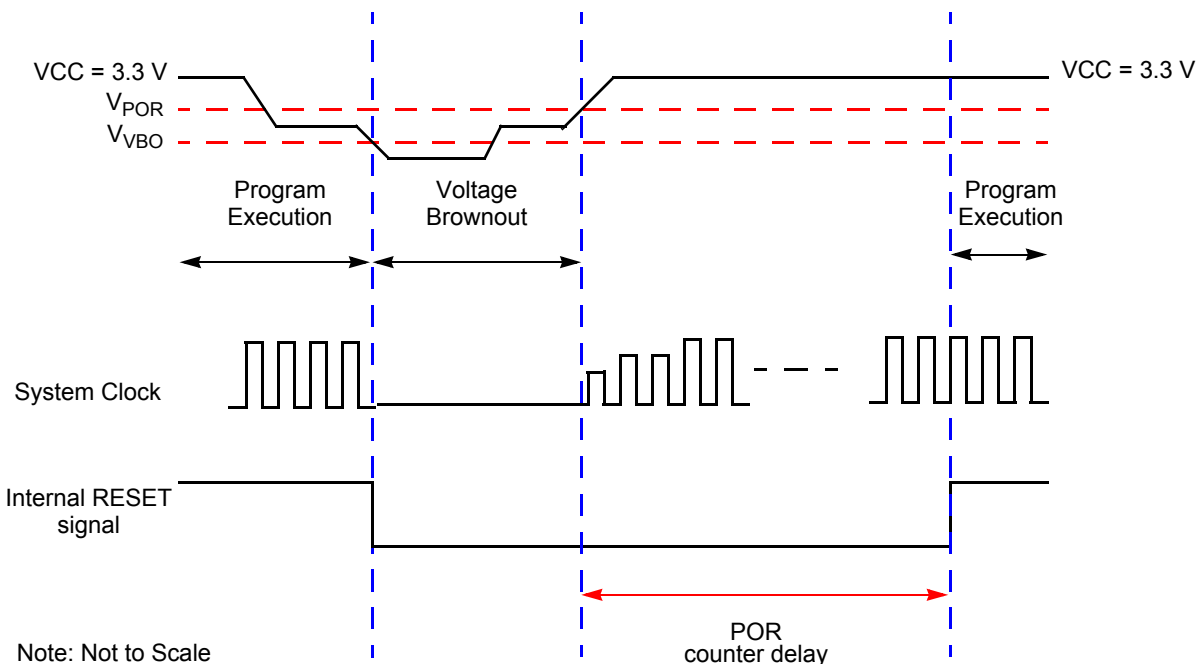


Figure 6. Voltage Brownout Reset Operation

The POR level is greater than the VBO level by the specified hysteresis value. This ensures that the device undergoes a Power-On Reset after recovering from a VBO condition.

Watchdog Timer Reset

If the device is in NORMAL or HALT mode, the Watchdog Timer can initiate a System Reset at time-out if the WDT_RES Flash Option Bit is programmed to 1. This is the unprogrammed state of the WDT_RES Flash Option Bit. If the bit is programmed to 0, it configures the Watchdog Timer to cause an interrupt, not a System Reset, at time-out.

The WDT bit in the Reset Status (RSTSTAT) register is set to signify that the reset was initiated by the Watchdog Timer.

External Reset Input

The RESET pin has a Schmitt-Triggered input and an internal pull-up resistor. Once the RESET pin is asserted for a minimum of four system clock cycles, the device progresses through the System Reset sequence. Because of the possible asynchronicity of the system clock and reset signals, the required reset duration may be as short as three clock periods

Table 18. Port A–D Control Registers (PxCTL)

| BITS | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|------------------------|-----|-----|-----|-----|-----|-----|-----|
| FIELD | PCTL | | | | | | | |
| RESET | 00H | | | | | | | |
| R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| ADDR | FD1H, FD5H, FD9H, FDDH | | | | | | | |

PCTL[7:0]—Port Control

The Port Control register provides access to all sub-registers that configure the GPIO Port operation.

Port A–D Data Direction Sub-Registers

The Port A–D Data Direction sub-register is accessed through the Port A–D Control register by writing 01H to the Port A–D Address register ([Table 19](#)).

Table 19. Port A–D Data Direction Sub-Registers (PxDD)

| BITS | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|---------------------------------------------------------------------------------------|-----|-----|-----|-----|-----|-----|-----|
| FIELD | DD7 | DD6 | DD5 | DD4 | DD3 | DD2 | DD1 | DD0 |
| RESET | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| ADDR | If 01H in Port A–D Address Register, accessible through the Port A–D Control Register | | | | | | | |

DD[7:0]—Data Direction

These bits control the direction of the associated port pin. Port Alternate Function operation overrides the Data Direction register setting.

0 = Output. Data in the Port A–D Output Data register is driven onto the port pin.

1 = Input. The port pin is sampled and the value written into the Port A–D Input Data Register. The output driver is tristated.

Port A–D Alternate Function Sub-Registers

The Port A–D Alternate Function sub-register ([Table 20](#)) is accessed through the Port A–D Control register by writing 02H to the Port A–D Address register. The Port A–D Alternate Function sub-registers enable the alternate function selection on pins. If disabled, pins functions as GPIO. If enabled, select one of four alternate functions using alternate function set subregisters 1 and 2 as described in the [Port A–D Alternate Function](#)

PAFS1[7:0]—Port Alternate Function Set 1

0 = Port Alternate Function selected as defined in [Table 14](#) and [Table 15](#) on page 44.

1 = Port Alternate Function selected as defined in [Table 14](#) and [Table 15](#) on page 44.

Port A–D Alternate Function Set 2 Sub-Registers

The Port A–D Alternate Function Set 2 sub-register ([Table 26](#)) is accessed through the Port A–D Control register by writing 08H to the Port A–D Address register. The Alternate Function Set 2 sub-registers selects the alternate function available at a port pin. Alternate Functions selected by setting or clearing bits of this register is defined in [Table 15](#).

► **Note:** *Alternate function selection on port pins must also be enabled as described in [Port A–D Alternate Function Sub-Registers](#) on page 47.*

Table 26. Port A–D Alternate Function Set 2 Sub-Registers (PxAFS2)

| BITS | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|---------------------------------------------------------------------------------------|--------|--------|--------|--------|--------|--------|--------|
| FIELD | PAFS27 | PAFS26 | PAFS25 | PAFS24 | PAFS23 | PAFS22 | PAFS21 | PAFS20 |
| RESET | 00H (all ports of 20/28 pin devices); 04H (Port A of 8-pin device) | | | | | | | |
| R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| ADDR | If 08H in Port A–D Address Register, accessible through the Port A–D Control Register | | | | | | | |

PAFS2[7:0]—Port Alternate Function Set 2

0 = Port Alternate Function selected as defined in [Table 15](#).

1 = Port Alternate Function selected as defined in [Table 15](#).

Port A–C Input Data Registers

Reading from the Port A–C Input Data registers ([Table 27](#)) returns the sampled values from the corresponding port pins. The Port A–C Input Data registers are read-only. The value returned for any unused ports is 0. Unused ports include those missing on the 8- and 28-pin packages, as well as those missing on the ADC-enabled 28-pin packages.

Table 27. Port A–C Input Data Registers (PxIN)

| BITS | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|----------------|------------------|------|------|------|------|------|------|------|
| FIELD | PIN7 | PIN6 | PIN5 | PIN4 | PIN3 | PIN2 | PIN1 | PIN0 |
| RESET | X | X | X | X | X | X | X | X |
| R/W | R | R | R | R | R | R | R | R |
| ADDR | FD2H, FD6H, FDAH | | | | | | | |
| X = Undefined. | | | | | | | | |

Driver Enable is an active High signal that envelopes the entire transmitted data frame including parity and Stop bits as displayed in Figure 14. The Driver Enable signal asserts when a byte is written to the UART Transmit Data register. The Driver Enable signal asserts at least one UART bit period and no greater than two UART bit periods before the Start bit is transmitted. This allows a setup time to enable the transceiver. The Driver Enable signal deasserts one system clock period after the final Stop bit is transmitted. This one system clock delay allows both time for data to clear the transceiver before disabling it, as well as the ability to determine if another character follows the current character. In the event of back to back characters (new data must be written to the Transmit Data Register before the previous character is completely transmitted) the DE signal is not deasserted between characters. The DEPOL bit in the UART Control Register 1 sets the polarity of the Driver Enable signal.

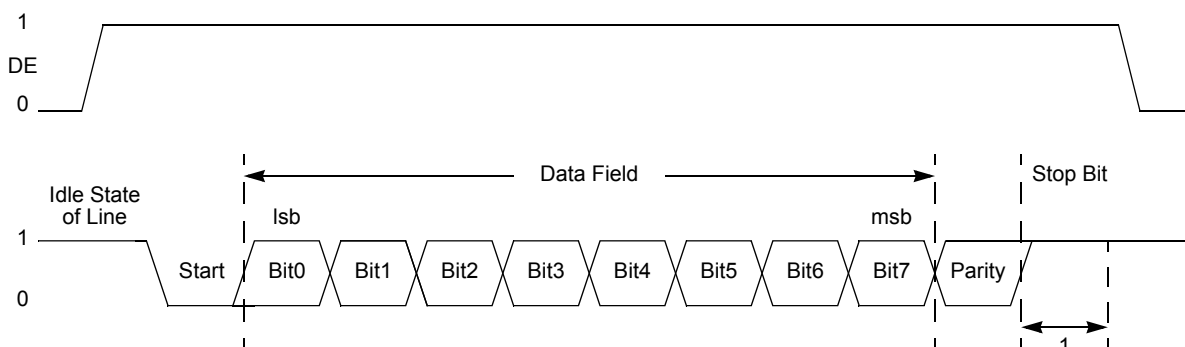


Figure 14. UART Driver Enable Signal Timing (shown with 1 Stop Bit and Parity)

The Driver Enable to Start bit setup time is calculated as follows:

$$\left(\frac{1}{\text{Baud Rate (Hz)}} \right) \leq \text{DE to Start Bit Setup Time (s)} \leq \left(\frac{2}{\text{Baud Rate (Hz)}} \right)$$

UART Interrupts

The UART features separate interrupts for the transmitter and the receiver. In addition, when the UART primary functionality is disabled, the Baud Rate Generator can also function as a basic timer with interrupt capability.

Transmitter Interrupts

The transmitter generates a single interrupt when the Transmit Data Register Empty bit (TDRE) is set to 1. This indicates that the transmitter is ready to accept new data for transmission. The TDRE interrupt occurs after the Transmit shift register has shifted the first bit of data out. The Transmit Data register can now be written with the next character to

MPRX—Multiprocessor Receive

Returns the value of the most recent multiprocessor bit received. Reading from the UART Receive Data register resets this bit to 0.

UART Transmit Data Register

Data bytes written to the UART Transmit Data (UxTXD) register ([Table 65](#)) are shifted out on the TXD_x pin. The Write-only UART Transmit Data register shares a Register File address with the read-only UART Receive Data register.

Table 65. UART Transmit Data Register (U0TXD)

| BITS | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|------|---|---|---|---|---|---|---|
| FIELD | TXD | | | | | | | |
| RESET | X | X | X | X | X | X | X | X |
| R/W | W | W | W | W | W | W | W | W |
| ADDR | F40H | | | | | | | |

TXD—Transmit Data

UART transmitter data byte to be shifted out through the TXD_x pin.

UART Receive Data Register

Data bytes received through the RXD_x pin are stored in the UART Receive Data (UxRXD) register ([Table 66](#)). The read-only UART Receive Data register shares a Register File address with the Write-only UART Transmit Data register.

Table 66. UART Receive Data Register (U0RXD)

| BITS | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|----------------|------|---|---|---|---|---|---|---|
| FIELD | RXD | | | | | | | |
| RESET | X | X | X | X | X | X | X | X |
| R/W | R | R | R | R | R | R | R | R |
| ADDR | F40H | | | | | | | |
| X = Undefined. | | | | | | | | |

RXD—Receive Data

UART receiver data byte from the RXD_x pin

UART Address Compare Register

The UART Address Compare (UxADDR) register stores the multi-node network address of the UART (see [Table 67](#)). When the MPMD[1] bit of UART Control Register 0 is set, all incoming address bytes are compared to the value stored in the Address Compare register. Receive interrupts and RDA assertions only occur in the event of a match.

Table 67. UART Address Compare Register (U0ADDR)

| BITS | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|-----------|-----|-----|-----|-----|-----|-----|-----|
| FIELD | COMP_ADDR | | | | | | | |
| RESET | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| ADDR | F45H | | | | | | | |

COMP_ADDR—Compare Address
This 8-bit value is compared to incoming address bytes.

UART Baud Rate High and Low Byte Registers

The UART Baud Rate High (UxBRH) and Low Byte (UxBRL) registers ([Table 68](#) and [Table 69](#)) combine to create a 16-bit baud rate divisor value (BRG[15:0]) that sets the data transmission rate (baud rate) of the UART.

Table 68. UART Baud Rate High Byte Register (U0BRH)

| BITS | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|------|-----|-----|-----|-----|-----|-----|-----|
| FIELD | BRH | | | | | | | |
| RESET | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| ADDR | F46H | | | | | | | |

Table 69. UART Baud Rate Low Byte Register (U0BRL)

| BITS | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|------|-----|-----|-----|-----|-----|-----|-----|
| FIELD | BRL | | | | | | | |
| RESET | 1 | 1 | 1 | 1 | 1 | 1 | 1 | 1 |
| R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| ADDR | F47H | | | | | | | |

Receiving IrDA Data

Data received from the infrared transceiver using the IR_RXD signal through the RXD pin is decoded by the Infrared Endec and passed to the UART. The UART's baud rate clock is used by the Infrared Endec to generate the demodulated signal (RXD) that drives the UART. Each UART/Infrared data bit is 16-clocks wide. Figure 18 displays data reception. When the Infrared Endec is enabled, the UART's RXD signal is internal to the Z8 Encore! XP[®] F082A Series products while the IR_RXD signal is received through the RXD pin.

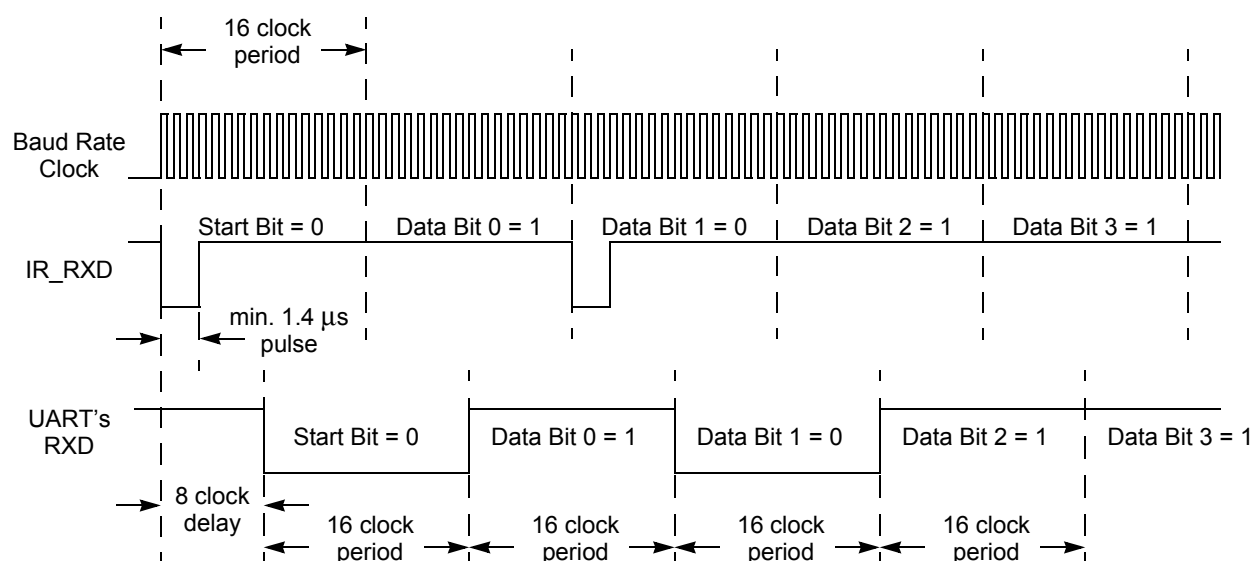


Figure 18. IrDA Data Reception

Infrared Data Reception



Caution: The system clock frequency must be at least 1.0 MHz to ensure proper reception of the 1.4 μs minimum width pulses allowed by the IrDA standard.

Endec Receiver Synchronization

The IrDA receiver uses a local baud rate clock counter (0 to 15 clock periods) to generate an input stream for the UART and to create a sampling window for detection of incoming pulses. The generated UART input (UART RXD) is delayed by 8 baud rate clock periods with respect to the incoming IrDA data stream. When a falling edge in the input data stream is detected, the Endec counter is reset. When the count reaches a value of 8, the UART RXD value is updated to reflect the value of the decoded data. When the count reaches 12 baud clock periods, the sampling window for the next incoming pulse opens. The window remains open until the count again reaches 8 (that is, 24 baud clock periods since the previous pulse was detected), giving the Endec a sampling window of minus four

ADC Control Register Definitions

ADC Control Register 0

The ADC Control Register 0 (ADCCTL0) selects the analog input channel and initiates the analog-to-digital conversion. It also selects the voltage reference configuration.

Table 71. ADC Control Register 0 (ADCCTL0)

| BITS | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|------|---------|--------|------|------------|-----|-----|-----|
| FIELD | CEN | REFSELL | REFOUT | CONT | ANAIN[3:0] | | | |
| RESET | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| ADDR | F70H | | | | | | | |

CEN—Conversion Enable

0 = Conversion is complete. Writing a 0 produces no effect. The ADC automatically clears this bit to 0 when a conversion is complete.

1 = Begin conversion. Writing a 1 to this bit starts a conversion. If a conversion is already in progress, the conversion restarts. This bit remains 1 until the conversion is complete.

REFSELL—Voltage Reference Level Select Low Bit; in conjunction with the High bit (REFSELH) in [ADC Control/Status Register 1](#), this determines the level of the internal voltage reference; the following details the effects of {REFSELH, REFSELL}; note that this reference is independent of the Comparator reference.

00= Internal Reference Disabled, reference comes from external pin

01= Internal Reference set to 1.0 V

10= Internal Reference set to 2.0 V (default)

11= Reserved

REFOUT—Internal Reference Output Enable

0 = Reference buffer is disabled; Vref pin is available for GPIO or analog functions

1 = The internal ADC reference is buffered and driven out to the Vref pin



Warning: When the ADC is used with an external reference ({REFSELH, REFSELL}=00), the REFOUT bit must be set to 0.

CONT

0 = Single-shot conversion. ADC data is output once at completion of the 5129 system clock cycles (measurements of the internal temperature sensor take twice as long)

1 = Continuous conversion. ADC data updated every 256 system clock cycles after an initial 5129 clock conversion (measurements of the internal temperature sensor take twice as long)

Trim Bit Data Register

The Trim Bid Data (TRMDR) register contains the read or write data for access to the trim option bits (Table 85).

Table 85. Trim Bit Data Register (TRMDR)

| BITS | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------|-----------------------|-----|-----|-----|-----|-----|-----|-----|
| FIELD | TRMDR - Trim Bit Data | | | | | | | |
| RESET | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |
| R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| ADDR | FF7H | | | | | | | |

Flash Option Bit Address Space

The first two bytes of Flash program memory at addresses 0000H and 0001H are reserved for the user-programmable Flash option bits.

Flash Program Memory Address 0000H

Table 86. Flash Option Bits at Program Memory Address 0000H

| BITS | 7 | 6 | 5 | 4 | 3 | 2 | 1 | 0 |
|-------------------------------------------------|----------------------|--------|--------------|-----|--------|-----|----------|-----|
| FIELD | WDT_RES | WDT_AO | OSC_SEL[1:0] | | VBO_AO | FRP | Reserved | FWP |
| RESET | U | U | U | U | U | U | U | U |
| R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W | R/W |
| ADDR | Program Memory 0000H | | | | | | | |
| Note: U = Unchanged by Reset. R/W = Read/Write. | | | | | | | | |

WDT_RES—Watchdog Timer Reset

0 = Watchdog Timer time-out generates an interrupt request. Interrupts must be globally enabled for the eZ8 CPU to acknowledge the interrupt request.

1 = Watchdog Timer time-out causes a system reset. This setting is the default for unprogrammed (erased) Flash.

WDT_AO—Watchdog Timer Always On

0 = Watchdog Timer is automatically enabled upon application of system power. Watchdog Timer can not be disabled.

Figure 27 displays a recommended configuration for connection with an external fundamental-mode, parallel-resonant crystal operating at 20 MHz. Recommended 20 MHz crystal specifications are provided in Table 110. Printed circuit board layout must add no more than 4 pF of stray capacitance to either the X_{IN} or X_{OUT} pins. If oscillation does not occur, reduce the values of capacitors C₁ and C₂ to decrease loading.

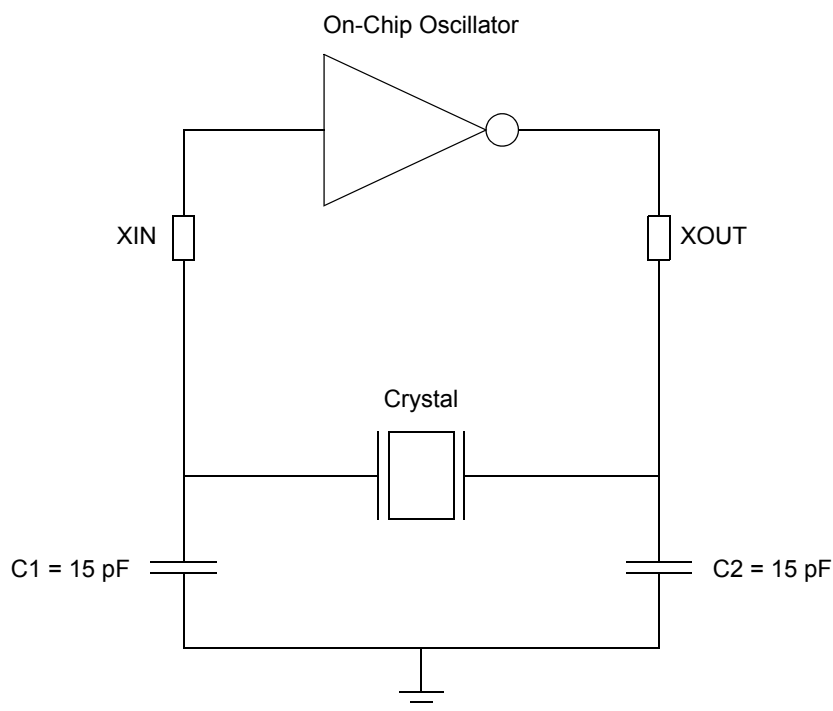


Figure 27. Recommended 20 MHz Crystal Oscillator Configuration

Table 110. Recommended Crystal Oscillator Specifications

| Parameter | Value | Units | Comments |
|-------------------------------------|-------------|-------|----------|
| Frequency | 20 | MHz | |
| Resonance | Parallel | | |
| Mode | Fundamental | | |
| Series Resistance (R _S) | 60 | Ω | Maximum |
| Load Capacitance (C _L) | 30 | pF | Maximum |
| Shunt Capacitance (C ₀) | 7 | pF | Maximum |
| Drive Level | 1 | mW | Maximum |

Table 116 through Table 123 lists the instructions belonging to each group and the number of operands required for each instruction. Some instructions appear in more than one table as these instruction can be considered as a subset of more than one category. Within these tables, the source operand is identified as ‘src’, the destination operand is ‘dst’ and a condition code is ‘cc’.

Table 116. Arithmetic Instructions

| Mnemonic | Operands | Instruction |
|----------|----------|-----------------------------------------------|
| ADC | dst, src | Add with Carry |
| ADCX | dst, src | Add with Carry using Extended Addressing |
| ADD | dst, src | Add |
| ADDX | dst, src | Add using Extended Addressing |
| CP | dst, src | Compare |
| CPC | dst, src | Compare with Carry |
| CPCX | dst, src | Compare with Carry using Extended Addressing |
| CPX | dst, src | Compare using Extended Addressing |
| DA | dst | Decimal Adjust |
| DEC | dst | Decrement |
| DECW | dst | Decrement Word |
| INC | dst | Increment |
| INCW | dst | Increment Word |
| MULT | dst | Multiply |
| SBC | dst, src | Subtract with Carry |
| SBCX | dst, src | Subtract with Carry using Extended Addressing |
| SUB | dst, src | Subtract |
| SUBX | dst, src | Subtract using Extended Addressing |

Table 117. Bit Manipulation Instructions

| Mnemonic | Operands | Instruction |
|-----------------|-----------------|------------------------------------------------------|
| BCLR | bit, dst | Bit Clear |
| BIT | p, bit, dst | Bit Set or Clear |
| BSET | bit, dst | Bit Set |
| BSWAP | dst | Bit Swap |
| CCF | — | Complement Carry Flag |
| RCF | — | Reset Carry Flag |
| SCF | — | Set Carry Flag |
| TCM | dst, src | Test Complement Under Mask |
| TCMX | dst, src | Test Complement Under Mask using Extended Addressing |
| TM | dst, src | Test Under Mask |
| TMX | dst, src | Test Under Mask using Extended Addressing |

Table 118. Block Transfer Instructions

| Mnemonic | Operands | Instruction |
|-----------------|-----------------|---------------------------------------------------------------------|
| LDCI | dst, src | Load Constant to/from Program Memory and Auto-Increment Addresses |
| LDEI | dst, src | Load External Data to/from Data Memory and Auto-Increment Addresses |

Table 119. CPU Control Instructions

| Mnemonic | Operands | Instruction |
|-----------------|-----------------|-----------------------|
| ATM | — | Atomic Execution |
| CCF | — | Complement Carry Flag |
| DI | — | Disable Interrupts |
| EI | — | Enable Interrupts |
| HALT | — | Halt Mode |
| NOP | — | No Operation |
| RCF | — | Reset Carry Flag |

Table 136. Low Power Operational Amplifier Electrical Characteristics

| $V_{DD} = 2.7 \text{ V to } 3.6 \text{ V}$ $T_A = -40 \text{ }^{\circ}\text{C to } +105 \text{ }^{\circ}\text{C}$ | | | | | | |
|----------------------------------------------------------------------------------------------------------------------|------------------------------------------|---------|---------|--------------|--------------------------------|---------------------------------|
| Symbol | Parameter | Minimum | Typical | Maximum | Units | Conditions |
| A_v | Open loop voltage gain | | 80 | | dB | |
| GBW | Gain/Bandwidth product | | 500 | | kHz | |
| PM | Phase Margin | | 50 | | deg | Assuming 13 pF load capacitance |
| V_{OSLPO} | Input Offset Voltage | | ± 1 | ± 4 | mV | |
| V_{OSLPO} | Input Offset Voltage (Temperature Drift) | | 1 | 10 | $\mu\text{V}/^{\circ}\text{C}$ | |
| V_{IN} | Input Voltage Range | 0.3 | | $V_{DD} - 1$ | V | |
| V_{OUT} | Output Voltage Range | 0.3 | | $V_{DD} - 1$ | V | $I_{OUT} = 45 \mu\text{A}$ |

Table 137. Comparator Electrical Characteristics

| $V_{DD} = 2.7 \text{ V to } 3.6 \text{ V}$ $T_A = -40 \text{ }^{\circ}\text{C to } +105 \text{ }^{\circ}\text{C}$ | | | | | | |
|----------------------------------------------------------------------------------------------------------------------|-----------------------------------------|----------|---------|--------------|-------|--------------------|
| Symbol | Parameter | Minimum | Typical | Maximum | Units | Conditions |
| V_{OS} | Input DC Offset | | 5 | | mV | |
| V_{CREF} | Programmable Internal Reference Voltage | | ± 5 | | % | 20-/28-pin devices |
| | | | ± 3 | | % | 8-pin devices |
| T_{PROP} | Propagation Delay | | 200 | | ns | |
| V_{HYS} | Input Hysteresis | | 4 | | mV | |
| V_{IN} | Input Voltage Range | V_{SS} | | $V_{DD} - 1$ | V | |

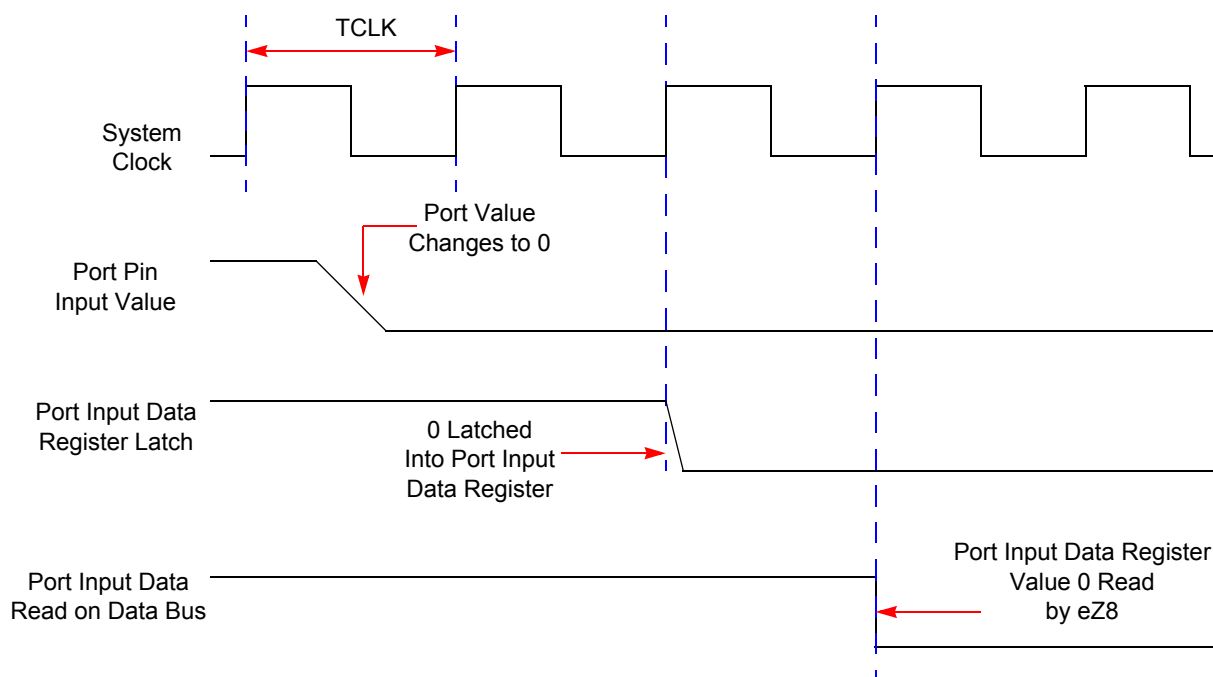


Figure 34. Port Input Sample Timing

Table 139. GPIO Port Input Timing

| Parameter | Abbreviation | Delay (ns) | |
|---------------------|----------------------------------------------------------------------------------------------------------|------------|---------|
| | | Minimum | Maximum |
| T _{S_PORT} | Port Input Transition to XIN Rise Setup Time (Not pictured) | 5 | – |
| T _{H_PORT} | XIN Rise to Port Input Transition Hold Time (Not pictured) | 0 | – |
| T _{SMR} | GPIO Port Pin Pulse Width to ensure Stop Mode Recovery (for GPIO Port Pins enabled as SMR sources) | 1 μs | |

Figure 47 displays the 28-pin Small Shrink Outline Package (SSOP) available for the Z8 Encore! XP F082A Series devices.

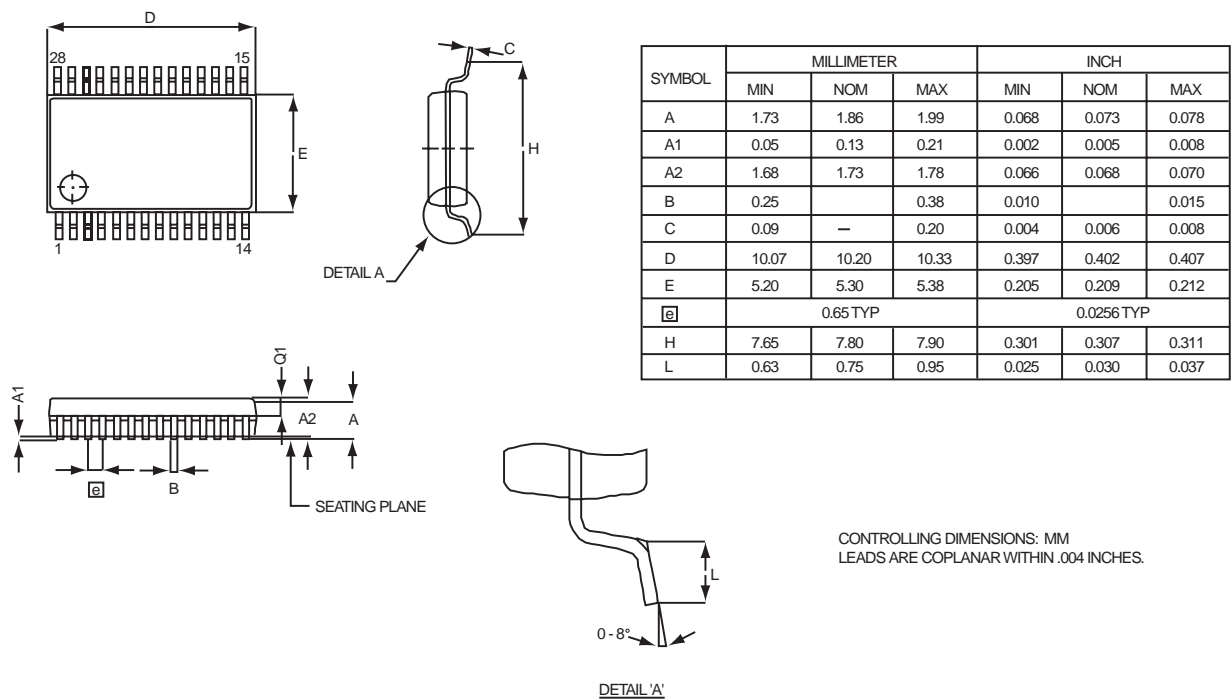


Figure 47. 28-Pin Small Shrink Outline Package (SSOP)

- timing 237
- OCD commands
 - execute instruction (12H) 183
 - read data memory (0DH) 183
 - read OCD control register (05H) 181
 - read OCD revision (00H) 180
 - read OCD status register (02H) 180
 - read program counter (07H) 181
 - read program memory (0BH) 182
 - read program memory CRC (0EH) 183
 - read register (09H) 182
 - read runtime counter (03H) 180
 - step instruction (10H) 183
 - stuff instruction (11H) 183
 - write data memory (0CH) 182
 - write OCD control register (04H) 181
 - write program counter (06H) 181
 - write program memory (0AH) 182
 - write register (08H) 181
- on-chip debugger (OCD) 173
- on-chip debugger signals 12
- on-chip oscillator 193
- ONE-SHOT mode 84
- opcode map
 - abbreviations 217
 - cell description 216
 - first 218
 - second after 1FH 219
- Operational Description 23, 33, 37, 55, 69, 91, 97, 117, 121, 134, 135, 139, 141, 153, 169, 173, 187, 193, 197
- OR 205
- ordering information 251
- ORX 206
- oscillator signals 12

P

- p 201
- packaging
 - 20-pin PDIP 244, 245
 - 20-pin SSOP 246, 249
 - 28-pin PDIP 247
 - 28-pin SOIC 248

- 8-pin PDIP 241
- 8-pin SOIC 242
- PDIP 248, 249
- part selection guide 2
- PC 202
- PDIP 248, 249
- peripheral AC and DC electrical characteristics 229
- pin characteristics 13
- Pin Descriptions 9
- polarity 201
- POP 205
- pop using extended addressing 205
- POPX 205
- port availability, device 37
- port input timing (GPIO) 235
- port output timing, GPIO 236
- power supply signals 13
- power-down, automatic (ADC) 122
- Power-on and Voltage Brownout electrical characteristics and timing 229
- Power-On Reset (POR) 25
- program control instructions 206
- program counter 202
- program memory 15
- PUSH 205
- push using extended addressing 205
- PUSHX 205
- PWM mode 85
- PxADDR register 46
- PxCTL register 47

R

- R 201
- r 201
- RA
 - register address 201
- RCF 204
- receive
 - IrDA data 119
- receiving UART data-interrupt-driven method 102
- receiving UART data-pollled method 101

- electrical characteristics and timing 230, 233
- interrupt in normal operation 92
- interrupt in STOP mode 92
- operation 135
- refresh 92, 205
- reload unlock sequence 93
- reload upper, high and low registers 94
- reset 27
- reset in normal operation 93
- reset in STOP mode 93
- time-out response 92
- WDTCTL register 31, 94, 136, 190
- WDTH register 95
- WDTL register 95
- working register 201
- working register pair 201
- WTDU register 95

X

- X 201
- XOR 206
- XORX 206

Z

- Z8 Encore!
 - block diagram 4
 - features 1
 - part selection guide 2