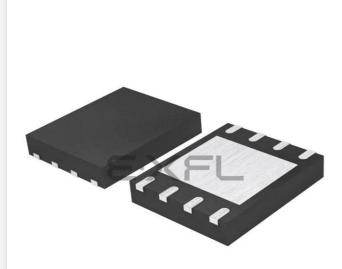
Zilog - Z8F012AQB020EC Datasheet





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Details

20000	
Product Status	Obsolete
Core Processor	eZ8
Core Size	8-Bit
Speed	20MHz
Connectivity	IrDA, UART/USART
Peripherals	Brown-out Detect/Reset, LED, LVD, POR, PWM, Temp Sensor, WDT
Number of I/O	6
Program Memory Size	1KB (1K x 8)
Program Memory Type	FLASH
EEPROM Size	16 × 8
RAM Size	256 x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 3.6V
Data Converters	A/D 4x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	8-VDFN Exposed Pad
Supplier Device Package	8-QFN (5x6)
Purchase URL	https://www.e-xfl.com/product-detail/zilog/z8f012aqb020ec

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

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Table 3. Pin Characteristics (20- and 28-pin Devices) (Continued)

Symbol Mnemonic	Direction	Reset Direction	Active Low or Active High	Tristate Output	Internal Pull- up or Pull-down	Schmitt- Trigger Input	Open Drain Output	5 V Tolerance
PC[7:0]	I/O	I	N/A	Yes	Programmable Pull-up	Yes	Yes, Programmable	PC[7:3] unless pullups enabled
RESET/PD0	I/O	I/O <u>(defaults</u> to RESET)	Low (in Reset mode)	Yes (PD0 only)	Programmable for PD0 <u>; always</u> on for RESET	Yes	Programmable for PD0 <u>; always</u> on for RESET	Yes, unless pullups enabled
VDD	N/A	N/A	N/A	N/A			N/A	N/A
VSS	N/A	N/A	N/A	N/A			N/A	N/A

Note: *PB6 and PB7 are available only in those devices without ADC.*

Table 4. Pin Characteristics (8-Pin Devices)

Symbol Mnemonic	Direction	Reset Direction	Active Low or Active High	Tristate Output	Internal Pull- up or Pull-down	Schmitt- Trigger Input	Open Drain Output	5 V Tolerance
PA0/DBG	I/O	I (but can change during reset if key sequence detected)	N/A	Yes	Programmable Pull-up	Yes	Yes, Programmable	Yes, unless pull-ups enabled
PA1	I/O	I	N/A	Yes	Programmable Pull-up	Yes	Yes, Programmable	Yes, unless pull-ups enabled
RESET/PA2	I/O	I/O <u>(defaults</u> to RESET)	Low (in Reset mode)	Yes	Programmable for PA2; always on for RESET	Yes	Programmable for PA2; always on for RESET	Yes, unless pull-ups enabled
PA[5:3]	I/O	I	N/A	Yes	Programmable Pull-up	Yes	Yes, Programmable	Yes, unless pull-ups enabled
V _{DD}	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A
V _{SS}	N/A	N/A	N/A	N/A	N/A	N/A	N/A	N/A

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Reset, Stop Mode Recovery, and Low Voltage Detection

The Reset Controller within the Z8 Encore! XP[®] F082A Series controls Reset and Stop Mode Recovery operation and provides indication of low supply voltage conditions. In typical operation, the following events cause a Reset:

- Power-On Reset (POR)
- Voltage Brownout (VBO)
- Watchdog Timer time-out (when configured by the WDT_RES Flash Option Bit to initiate a reset)
- External RESET pin assertion (when the alternate RESET function is enabled by the GPIO register)
- On-chip debugger initiated Reset (OCDCTL[0] set to 1)

When the device is in STOP mode, a Stop Mode Recovery is initiated by either of the following:

- Watchdog Timer time-out
- GPIO Port input pin transition on an enabled Stop Mode Recovery source

The low voltage detection circuitry on the device (available on the 8-pin product versions only) performs the following functions:

- Generates the VBO reset when the supply voltage drops below a minimum safe level.
- Generates an interrupt when the supply voltage drops below a user-defined level (8-pin devices only).

Reset Types

The Z8 Encore! XP F082A Series provides several different types of Reset operation. Stop Mode Recovery is considered as a form of Reset. Table 8 lists the types of Reset and their operating characteristics. The System Reset is longer if the external crystal oscillator is enabled by the Flash option bits, allowing additional time for oscillator start-up.



Low-Power Modes

The Z8 Encore! XP F082A Series products contain power-saving features. The highest level of power reduction is provided by the STOP mode, in which nearly all device functions are powered down. The next lower level of power reduction is provided by the HALT mode, in which the CPU is powered down.

Further power savings can be implemented by disabling individual peripheral blocks while in Active mode (defined as being in neither STOP nor HALT mode).

STOP Mode

Executing the eZ8 CPU's STOP instruction places the device into STOP mode, powering down all peripherals except the Voltage Brownout detector, the Low-power Operational Amplifier and the Watchdog Timer. These three blocks may also be disabled for additional power savings. Specifically, the operating characteristics are:

- Primary crystal oscillator and internal precision oscillator are stopped; XIN and XOUT (if previously enabled) are disabled, and PA0/PA1 revert to the states programmed by the GPIO registers.
- System clock is stopped.
- eZ8 CPU is stopped.
- Program counter (PC) stops incrementing.
- Watchdog Timer's internal RC oscillator continues to operate if enabled by the Oscillator Control register.
- If enabled, the Watchdog Timer logic continues to operate.
- If enabled for operation in STOP mode by the associated Flash Option Bit, the Voltage Brownout protection circuit continues to operate.
- Low-power operational amplifier continues to operate if enabled by the Power Control register to do so.
- All other on-chip peripherals are idle.

To minimize current in STOP mode, all GPIO pins that are configured as digital inputs must be driven to one of the supply rails (V_{CC} or GND). Additionally, any GPIOs configured as outputs must also be driven to one of the supply rails. The device can be brought out of STOP mode using Stop Mode Recovery. For more information on Stop Mode Recovery, see Reset, Stop Mode Recovery, and Low Voltage Detection on page 23.

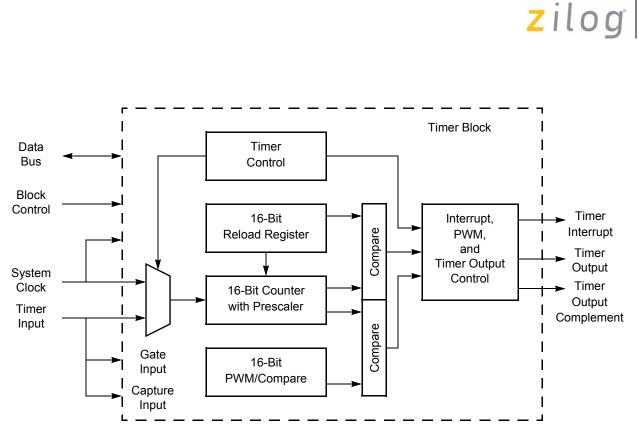


Figure 9. Timer Block Diagram

Operation

The timers are 16-bit up-counters. Minimum time-out delay is set by loading the value 0001H into the Timer Reload High and Low Byte registers and setting the prescale value to 1. Maximum time-out delay is set by loading the value 0000H into the Timer Reload High and Low Byte registers and setting the prescale value to 128. If the Timer reaches FFFFH, the timer rolls over to 0000H and continues counting.

Timer Operating Modes

The timers can be configured to operate in the following modes:

ONE-SHOT Mode

In ONE-SHOT mode, the timer counts up to the 16-bit Reload value stored in the Timer Reload High and Low byte registers. The timer input is the system clock. Upon reaching the Reload value, the timer generates an interrupt and the count value in the Timer High and Low Byte registers is reset to 0001H. The timer is automatically disabled and stops counting.

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Z8 Encore! XP[®] F082A Series

Product Specification



Follow the steps below for configuring a timer for COUNTER mode and initiating the count:

- 1. Write to the Timer Control register to:
 - Disable the timer.
 - Configure the timer for COUNTER mode.
 - Select either the rising edge or falling edge of the Timer Input signal for the count. This selection also sets the initial logic level (High or Low) for the Timer Output alternate function. However, the Timer Output function is not required to be enabled.
- 2. Write to the Timer High and Low Byte registers to set the starting count value. This only affects the first pass in COUNTER mode. After the first timer Reload in COUNTER mode, counting always begins at the reset value of 0001H. In COUNTER mode the Timer High and Low Byte registers must be written with the value 0001H.
- 3. Write to the Timer Reload High and Low Byte registers to set the Reload value.
- 4. If appropriate, enable the timer interrupt and set the timer interrupt priority by writing to the relevant interrupt registers.
- 5. Configure the associated GPIO port pin for the Timer Input alternate function.
- 6. If using the Timer Output function, configure the associated GPIO port pin for the Timer Output alternate function.
- 7. Write to the Timer Control register to enable the timer.

In COUNTER mode, the number of Timer Input transitions since the timer start is given by the following equation:

COUNTER Mode Timer Input Transitions = Current Count Value-Start Value

COMPARATOR COUNTER Mode

In COMPARATOR COUNTER mode, the timer counts input transitions from the analog comparator output. The TPOL bit in the Timer Control Register selects whether the count occurs on the rising edge or the falling edge of the comparator output signal. In COMPAR-ATOR COUNTER mode, the prescaler is disabled.

Caution: The frequency of the comparator output signal must not exceed one-fourth the system clock frequency. Further, the high or low state of the comparator output signal pulse must be no less than twice the system clock period. A shorter pulse may not be captured.

After reaching the Reload value stored in the Timer Reload High and Low Byte registers, the timer generates an interrupt, the count value in the Timer High and Low Byte registers is reset to 0001H and counting resumes. Also, if the Timer Output alternate function is enabled, the Timer Output pin changes state (from Low to High or from High to Low) at timer Reload.



Follow the steps below for configuring a timer for COMPARATOR COUNTER mode and initiating the count:

- 1. Write to the Timer Control register to:
 - Disable the timer.
 - Configure the timer for COMPARATOR COUNTER mode.
 - Select either the rising edge or falling edge of the comparator output signal for the count. This also sets the initial logic level (High or Low) for the Timer Output alternate function. However, the Timer Output function is not required to be enabled.
- 2. Write to the Timer High and Low Byte registers to set the starting count value. This action only affects the first pass in COMPARATOR COUNTER mode. After the first timer Reload in COMPARATOR COUNTER mode, counting always begins at the reset value of 0001H. Generally, in COMPARATOR COUNTER mode the Timer High and Low Byte registers must be written with the value 0001H.
- 3. Write to the Timer Reload High and Low Byte registers to set the Reload value.
- 4. If appropriate, enable the timer interrupt and set the timer interrupt priority by writing to the relevant interrupt registers.
- 5. If using the Timer Output function, configure the associated GPIO port pin for the Timer Output alternate function.
- 6. Write to the Timer Control register to enable the timer.

In COMPARATOR COUNTER mode, the number of comparator output transitions since the timer start is given by the following equation:

Comparator Output Transitions = Current Count Value – Start Value

PWM SINGLE OUTPUT Mode

In PWM SINGLE OUTPUT mode, the timer outputs a Pulse-Width Modulator (PWM) output signal through a GPIO Port pin. The timer input is the system clock. The timer first counts up to the 16-bit PWM match value stored in the Timer PWM High and Low Byte registers. When the timer count value matches the PWM value, the Timer Output toggles. The timer continues counting until it reaches the Reload value stored in the Timer Reload High and Low Byte registers. Upon reaching the Reload value, the timer generates an interrupt, the count value in the Timer High and Low Byte registers is reset to 0001H and counting resumes.

If the TPOL bit in the Timer Control register is set to 1, the Timer Output signal begins as a High (1) and transitions to a Low (0) when the timer value matches the PWM value. The Timer Output signal returns to a High (1) after the timer reaches the Reload value and is reset to 0001H.



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BITS	7	6	5	4	3	2	1	0	
FIELD		PWML							
RESET	0	0	0	0	0	0	0	0	
R/W	R/W	R/W R/W R/W R/W R/W R/W R/W							
ADDR		F05H, F0DH							

Table 55. Timer 0–1 PWM Low Byte Register (TxPWML)

PWMH and PWML—Pulse-Width Modulator High and Low Bytes These two bytes, {PWMH[7:0], PWML[7:0]}, form a 16-bit value that is compared to the current 16-bit timer count. When a match occurs, the PWM output changes state. The PWM output value is set by the TPOL bit in the Timer Control Register (TxCTL1) register.

The TxPWMH and TxPWML registers also store the 16-bit captured timer value when operating in CAPTURE or CAPTURE/COMPARE modes.



Watchdog Timer Reload Registers results in a one-second timeout at room temperature and 3.3 V supply voltage.

Timeouts other than one second may be obtained by scaling the calibration values up or down as required.

Note: *The Watchdog Timer accuracy still degrades as temperature and supply voltage vary. See* Table 133 on page 230 *for* details.

Watchdog Timer Control Register Definitions

Watchdog Timer Control Register

The Watchdog Timer Control (WDTCTL) register is a write-only control register. Writing the 55H, AAH unlock sequence to the WDTCTL register address unlocks the three Watchdog Timer Reload Byte registers (WDTU, WDTH, and WDTL) to allow changes to the time-out period. These write operations to the WDTCTL register address produce no effect on the bits in the WDTCTL register. The locking mechanism prevents spurious writes to the Reload registers.

This register address is shared with the read-only Reset Status register.

BITS	7	6	5	4	3	2	1	0	
FIELD		WDTUNLK							
RESET	Х	Х	Х	Х	Х	Х	Х	Х	
R/W	W	W	W	W	W	W	W	W	
ADDR	FFOH								
X = Undef	X = Undefined.								

Table 57. Watchdog Timer Control Register (WDTCTL)

WDTUNLK—Watchdog Timer Unlock

The software must write the correct unlocking sequence to this register before it is allowed to modify the contents of the Watchdog Timer reload registers.

Watchdog Timer Reload Upper, High and Low Byte Registers

The Watchdog Timer Reload Upper, High and Low Byte (WDTU, WDTH, WDTL) registers (Table 58 through Table 60) form the 24-bit reload value that is loaded into the Watchdog Timer when a WDT instruction executes. The 24-bit reload value is {WDTU[7:0], WDTH[7:0]}. Writing to these registers sets the appropriate Reload Value. Reading from these registers returns the current Watchdog Timer count value.

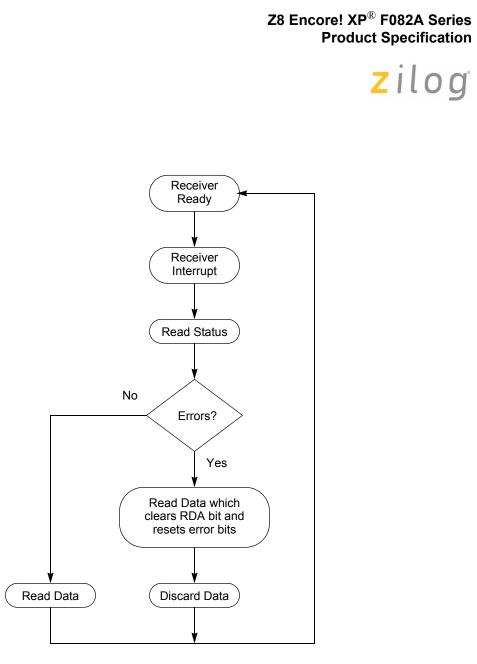


Figure 15. UART Receiver Interrupt Service Routine Flow

Baud Rate Generator Interrupts

If the baud rate generator (BRG) interrupt enable is set, the UART Receiver interrupt asserts when the UART Baud Rate Generator reloads. This condition allows the Baud Rate Generator to function as an additional counter if the UART functionality is not employed.

UART Baud Rate Generator

The UART Baud Rate Generator creates a lower frequency baud rate clock for data transmission. The input to the Baud Rate Generator is the system clock. The UART Baud Rate High and Low Byte registers combine to create a 16-bit baud rate divisor value

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3.579545 MHz System Clock							
Acceptable Rate (kHz)	BRG Divisor (Decimal)	Actual Rate (kHz)	Error (%)				
1250.0	N/A	N/A	N/A				
625.0	N/A	N/A	N/A				
250.0	1	223.72	-10.51				
115.2	2	111.9	-2.90				
57.6	4	55.9	-2.90				
38.4	6	37.3	-2.90				
19.2	12	18.6	-2.90				
9.60	23	9.73	1.32				
4.80	47	4.76	-0.83				
2.40	93	2.41	0.23				
1.20	186	1.20	0.23				
0.60	373	0.60	-0.04				
0.30	746	0.30	-0.04				

Table 70. UART Baud Rates (Continued)

1.8432 MHz \$	System Clock			
Acceptable Rate (kHz)	BRG Divisor (Decimal)	Actual Rate (kHz)	Error (%)	
1250.0	N/A	N/A	N/A	
625.0	N/A	N/A	N/A	
250.0	N/A	N/A	N/A	
115.2	1	115.2	0.00	
57.6	2	57.6	0.00	
38.4	3	38.4	0.00	
19.2	6	19.2	0.00	
9.60	12	9.60	0.00	
4.80	24	4.80	0.00	
2.40	48	2.40	0.00	
1.20	96	1.20	0.00	
0.60	192	0.60	0.00	
0.30	384	0.30	0.00	

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- If the internal voltage reference must be output to a pin, set the REFEXT bit to 1. The internal voltage reference must be enabled in this case.
- Write the REFSELL bit of the pair {REFSELH, REFSELL} to select the internal voltage reference level or to disable the internal reference. The REFSELH bit is contained in the ADC Control/Status Register 1.
- Set CEN to 1 to start the conversion.
- 4. CEN remains 1 while the conversion is in progress. A single-shot conversion requires 5129 system clock cycles to complete. If a single-shot conversion is requested from an ADC powered-down state, the ADC uses 40 additional clock cycles to power up before beginning the 5129 cycle conversion.
- 5. When the conversion is complete, the ADC control logic performs the following operations:
 - 13-bit two's-complement result written to {ADCD_H[7:0], ADCD_L[7:3]}.
 - Sends an interrupt request to the Interrupt Controller denoting conversion complete.
 - CEN resets to 0 to indicate the conversion is complete.
- 6. If the ADC remains idle for 160 consecutive system clock cycles, it is automatically powered-down.

Continuous Conversion

When configured for continuous conversion, the ADC continuously performs an analog-to-digital conversion on the selected analog input. Each new data value over-writes the previous value stored in the ADC Data registers. An interrupt is generated after each conversion.

Caution: In CONTINUOUS mode, ADC updates are limited by the input signal bandwidth of the ADC and the latency of the ADC and its digital filter. Step changes at the input are not immediately detected at the next output from the ADC. The response of the ADC (in all modes) is limited by the input signal bandwidth and the latency.

Follow the steps below for setting up the ADC and initiating continuous conversion:

- 1. Enable the desired analog input by configuring the general-purpose I/O pins for alternate function. This action disables the digital input and output driver.
- 2. Write the ADC Control/Status Register 1 to configure the ADC.
 - Write to BUFMODE[2:0] to select SINGLE-ENDED or DIFFERENTIAL mode, as well as unbuffered or buffered mode.
 - Write the REFSELH bit of the pair {REFSELH, REFSELL} to select the internal voltage reference level or to disable the internal reference. The REFSELL bit is contained in the ADC Control Register 0.



Operation

The Flash Controller programs and erases Flash memory. The Flash Controller provides the proper Flash controls and timing for Byte Programming, Page Erase, and Mass Erase of Flash memory.

The Flash Controller contains several protection mechanisms to prevent accidental programming or erasure. These mechanism operate on the page, sector and full-memory levels.

The Flow Chart in Figure 22 displays basic Flash Controller operation. The following subsections provide details about the various operations (Lock, Unlock, Byte Programming, Page Protect, Page Unprotect, Page Select, Page Erase, and Mass Erase) displayed in Figure 22.

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WDTCALH—Watchdog Timer Calibration High Byte The WDTCALH and WDTCALL bytes, when loaded into the Watchdog Timer reload registers result in a one second timeout at room temperature and 3.3 V supply voltage. To use the Watchdog Timer calibration, user code must load WDTU with 0x00, WDTH with WDTCALH and WDTL with WDTCALL.

Table 98. Watchdog Calibration Low Byte at 007FH (WDTCALL)

BITS	7	6	5	4	3	2	1	0	
FIELD		WDTCALL							
RESET	U	U	U	U	U	U	U	U	
R/W	R/W	N R/W R/W R/W R/W R/W R/W R/						R/W	
ADDR	Information Page Memory 007FH								
Note: U =	Unchanged b	y Reset. R/W	= Read/Write						

WDTCALL—Watchdog Timer Calibration Low Byte

The WDTCALH and WDTCALL bytes, when loaded into the Watchdog Timer reload registers result in a one second timeout at room temperature and 3.3 V supply voltage. To use the Watchdog Timer calibration, user code must load WDTU with 0x00, WDTH with WDTCALH and WDTL with WDTCALL.

Serialization Data

Table 99. Serial Number at 001C - 001F (S_NUM)

BITS	7	6	5	4	3	2	1	0	
FIELD		S_NUM							
RESET	U	U	U	U	U	U	U	U	
R/W	R/W	R/W R/W R/W R/W R/W R/W R/W						R/W	
ADDR	Information Page Memory 001C-001F								
Note: U =	Unchanged by	y Reset. R/W	= Read/Write	e.					

S NUM—Serial Number Byte

The serial number is a unique four-byte binary value.



If the device is not in DEBUG mode or the Flash Read Protect Option bit is enabled, this command reads and discards one byte.

DBG \leftarrow 12H DBG \leftarrow 1-5 byte opcode

On-Chip Debugger Control Register Definitions

OCD Control Register

The OCD Control register controls the state of the On-Chip Debugger. This register is used to enter or exit DEBUG mode and to enable the BRK instruction. It can also reset the Z8 Encore! XP[®] F082A Series device.

A reset and stop function can be achieved by writing \$1H to this register. A reset and go function can be achieved by writing \$1H to this register. If the device is in DEBUG mode, a run function can be implemented by writing \$0H to this register.

Table 106. OCD Control Register (OCDCTL)

BITS	7	6	5	4	3	2	1	0
FIELD	DBGMODE	BRKEN	DBGACK		Rese	erved		RST
RESET	0	0	0	0	0	0	0	0
R/W	R/W	R/W	R/W	R	R	R	R	R/W

DBGMODE—DEBUG Mode

The device enters DEBUG mode when this bit is 1. When in DEBUG mode, the eZ8 CPU stops fetching new instructions. Clearing this bit causes the eZ8 CPU to restart. This bit is automatically set when a BRK instruction is decoded and Breakpoints are enabled. If the Flash Read Protect Option Bit is enabled, this bit can only be cleared by resetting the device. It cannot be written to 0.

0 = The Z8 Encore! XP F082A Series device is operating in NORMAL mode.

1 = The Z8 Encore! XP F082A Series device is in DEBUG mode.

BRKEN—Breakpoint Enable

This bit controls the behavior of the BRK instruction (opcode 00H). By default, Breakpoints are disabled and the BRK instruction behaves similar to an NOP instruction. If this bit is 1, when a BRK instruction is decoded, the DBGMODE bit of the OCDCTL register is automatically set to 1.

0 = Breakpoints are disabled.

1 = Breakpoints are enabled.

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WDFEN-Watchdog Timer Oscillator Failure Detection Enable

1 = Failure detection of Watchdog Timer oscillator is enabled

0 = Failure detection of Watchdog Timer oscillator is disabled

SCKSEL—System Clock Oscillator Select

000 = Internal precision oscillator functions as system clock at 5.53 MHz

001 = Internal precision oscillator functions as system clock at 32 kHz

010 = Crystal oscillator or external RC oscillator functions as system clock

011 = Watchdog Timer oscillator functions as system

100 = External clock signal on PB3 functions as system clock

101 = Reserved

110 = Reserved

111 = Reserved

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Mode	Crystal Frequency Range	Function	Use	sconduo (mA/V) this ran alculatio	ge for
Low Gain*	32 kHz–1 MHz	Low Power/Frequency Applications	0.02	0.04	0.09
Medium Gain*	0.5 MHz–10 MHz	Medium Power/Frequency Applications	0.84	1.7	3.1
High Gain*	8 MHz–20 MHz	High Power/Frequency Applications	1.1	2.3	4.2

Table 111. Transconductance Values for Low, Medium, and High Gain Operating Modes

Note: *Printed circuit board layout must not add more than 4 pF of stray capacitance to either XIN or XOUT pins. if no Oscillation occurs, reduce the values of the capacitors C1 and C2 to decrease the loading.

Oscillator Operation with an External RC Network

Figure 28 displays a recommended configuration for connection with an external resistor-capacitor (RC) network.

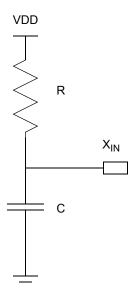


Figure 28. Connecting the On-Chip Oscillator to an External RC Network

An external resistance value of 45 k Ω is recommended for oscillator operation with an external RC network. The minimum resistance value to ensure operation is 40 k Ω . The typical oscillator frequency can be estimated from the values of the resistor (*R* in k Ω) and capacitor (*C* in pF) elements using the following equation:

Oscillator Frequency (kHz) =
$$\frac{1 \times 10^{6}}{(0.4 \times R \times C) + (4 \times C)}$$

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Table 123. Rotate and Shift Instructions (Continued)

Mnemonic	Operands	Instruction
SRA	dst	Shift Right Arithmetic
SRL	dst	Shift Right Logical
SWAP	dst	Swap Nibbles

eZ8 CPU Instruction Summary

Table 124 summarizes the eZ8 CPU instructions. The table identifies the addressing modes employed by the instruction, the effect upon the Flags register, the number of CPU clock cycles required for the instruction fetch, and the number of CPU clock cycles required for the instruction.

Assembly Mnemonic	Symbolic Operation	Addres	s Mode	Opcode(s) (Hex)			FI	ags	Fetch	Instr.		
		dst	src		С	Ζ	S	۷	D	Н		Cycles
ADC dst, src	$dst \gets dst + src + C$	r	r	12	*	*	*	*	0	*	2	3
		r	lr	13	-						2	4
		R	R	14	-						3	3
		R	IR	15	-						3	4
		R	IM	16	-						3	3
		IR	IM	17	-						3	4
ADCX dst, src	$dst \gets dst + src + C$	ER	ER	18	*	*	*	*	0	*	4	3
		ER	IM	19	-						4	3
ADD dst, src	$dst \gets dst + src$	r	r	02	*	*	*	*	0	*	2	3
		r	lr	03	-						2	4
		R	R	04	-						3	3
		R	IR	05	-						3	4
		R	IM	06	-						3	3
		IR	IM	07	-						3	4
ADDX dst, src	$dst \gets dst + src$	ER	ER	08	*	*	*	*	0	*	4	3
		ER	IM	09	-						4	3
Flags Notation:	* = Value is a function – = Unaffected X = Undefined	peration.	0 = Reset to 0 1 = Set to 1									

Table 124. eZ8 CPU Instruction Summary

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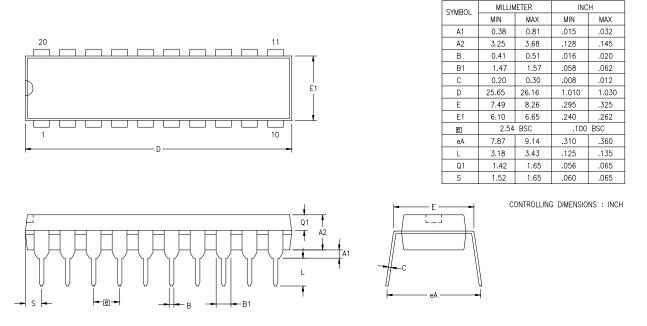


Figure 42 displays the 20-pin Plastic Dual Inline Package (PDIP) available for the Z8 Encore! XP F082A Series devices.

Figure 42. 20-Pin Plastic Dual Inline Package (PDIP)

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Part Number	Flash	RAM	SUVN	I/O Lines	Interrupts	16-Bit Timers w/PWM	10-Bit A/D Channels	UART with IrDA	Comparator	Temperature Sensor	Description
Z8 Encore! XP [®] F082	A Serie	s with 1	KB Fla	ish, 1	0-Bit	Ana	log-t	o-Dig	jital C	Conv	verter
Standard Temperatu	re: 0 °C	to 70 °C	;								
Z8F012APB020SC	1 KB	256 B	16 B	6	14	2	4	1	1	1	PDIP 8-pin package
Z8F012AQB020SC	1 KB	256 B	16 B	6	14	2	4	1	1	1	QFN 8-pin package
Z8F012ASB020SC	1 KB	256 B	16 B	6	14	2	4	1	1	1	SOIC 8-pin package
Z8F012ASH020SC	1 KB	256 B	16 B	17	20	2	7	1	1	1	SOIC 20-pin package
Z8F012AHH020SC	1 KB	256 B	16 B	17	20	2	7	1	1	1	SSOP 20-pin package
Z8F012APH020SC	1 KB	256 B	16 B	17	20	2	7	1	1	1	PDIP 20-pin package
Z8F012ASJ020SC	1 KB	256 B	16 B	23	20	2	8	1	1	1	SOIC 28-pin package
Z8F012AHJ020SC	1 KB	256 B	16 B	23	20	2	8	1	1	1	SSOP 28-pin package
Z8F012APJ020SC	1 KB	256 B	16 B	23	20	2	8	1	1	1	PDIP 28-pin package
Extended Temperatu	re: -40 °	C to 10	5 °C								
Z8F012APB020EC	1 KB	256 B	16 B	6	14	2	4	1	1	1	PDIP 8-pin package
Z8F012AQB020EC	1 KB	256 B	16 B	6	14	2	4	1	1	1	QFN 8-pin package
Z8F012ASB020EC	1 KB	256 B	16 B	6	14	2	4	1	1	1	SOIC 8-pin package
Z8F012ASH020EC	1 KB	256 B	16 B	17	20	2	7	1	1	1	SOIC 20-pin package
Z8F012AHH020EC	1 KB	256 B	16 B	17	20	2	7	1	1	1	SSOP 20-pin package
Z8F012APH020EC	1 KB	256 B	16 B	17	20	2	7	1	1	1	PDIP 20-pin package
Z8F012ASJ020EC	1 KB	256 B	16 B	23	20	2	8	1	1	1	SOIC 28-pin package
Z8F012AHJ020EC	1 KB	256 B	16 B	23	20	2	8	1	1	1	SSOP 28-pin package
Z8F012APJ020EC	1 KB	256 B	16 B	23	20	2	8	1	1	1	PDIP 28-pin package



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Part Number Suffix Designations

