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Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

Details

Product Status	Obsolete
Core Processor	eZ8
Core Size	8-Bit
Speed	20MHz
Connectivity	IrDA, UART/USART
Peripherals	Brown-out Detect/Reset, LED, LVD, POR, PWM, Temp Sensor, WDT
Number of I/O	6
Program Memory Size	2KB (2K x 8)
Program Memory Type	FLASH
EEPROM Size	64 x 8
RAM Size	512 x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 3.6V
Data Converters	A/D 4x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	8-SOIC (0.154", 3.90mm Width)
Supplier Device Package	-
Purchase URL	https://www.e-xfl.com/product-detail/zilog/z8f022asb020ec

Email: info@E-XFL.COM

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Interrupt Controller

The Z8 Encore! XP[®] F082A Series products support up to 20 interrupts. These interrupts consist of 8 internal peripheral interrupts and 12 general-purpose I/O pin interrupt sources. The interrupts have three levels of programmable interrupt priority.

Reset Controller

The Z8 Encore! XP F082A Series products can be reset using the $\overline{\text{RESET}}$ pin, Power-On Reset, Watchdog Timer (WDT) time-out, STOP mode exit, or Voltage Brownout (VBO) warning signal. The $\overline{\text{RESET}}$ pin is bi-directional, that is, it functions as reset source as well as a reset indicator.



Table 39. IRQ1 Enable and Priority Encoding

IRQ1ENH[x]	IRQ1ENL[x]	Priority	Description
0	0	Disabled	Disabled
0	1	Level 1	Low
1	0	Level 2	Medium
1	1	Level 3	High

where x indicates the register bits from 0–7.

Table 40. IRQ1 Enable High Bit Register (IRQ1ENH)

BITS	7	6	5	4	3	2	1	0				
FIELD	PA7VENH	PA6CENH	PA5ENH	PA4ENH	PA3ENH	PA2ENH	PA1ENH	PA0ENH				
RESET	0	0	0	0	0	0	0 0					
R/W	R/W	V R/W R/W R/W R/W R/W										
ADDR		FC4H										

PA7VENH—Port A Bit[7] or LVD Interrupt Request Enable High Bit PA6CENH—Port A Bit[7] or Comparator Interrupt Request Enable High Bit PAxENH—Port A Bit[x] Interrupt Request Enable High Bit

See Shared Interrupt Select (IRQSS) register for selection of either the LVD or the comparator as the interrupt source.

Table 41. IRQ1 Enable Low Bit Register (IRQ1ENL)

BITS	7	6	5	4	3	2	1	0
FIELD	PA7VENL	PA6CENL	PA5ENL	PA4ENL	PA3ENL	PA2ENL PA1ENL		PA0ENL
RESET	0	0	0	0	0	0 0		0
R/W	R/W	/ R/W R/W R/W R/W R/W						R/W
ADDR				FC	5H			

PA7VENL—Port A Bit[7] or LVD Interrupt Request Enable Low Bit PA6CENL—Port A Bit[6] or Comparator Interrupt Request Enable Low Bit PAxENL—Port A Bit[x] Interrupt Request Enable Low Bit



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PWM DUAL OUTPUT Mode

In PWM DUAL OUTPUT mode, the timer outputs a Pulse-Width Modulated (PWM) output signal pair (basic PWM signal and its complement) through two GPIO Port pins. The timer input is the system clock. The timer first counts up to the 16-bit PWM match value stored in the Timer PWM High and Low Byte registers. When the timer count value matches the PWM value, the Timer Output toggles. The timer continues counting until it reaches the Reload value stored in the Timer Reload High and Low Byte registers. Upon reaching the Reload value, the timer generates an interrupt, the count value in the Timer High and Low Byte registers is reset to 0001H and counting resumes.

If the TPOL bit in the Timer Control register is set to 1, the Timer Output signal begins as a High (1) and transitions to a Low (0) when the timer value matches the PWM value. The Timer Output signal returns to a High (1) after the timer reaches the Reload value and is reset to 0001H.

If the TPOL bit in the Timer Control register is set to 0, the Timer Output signal begins as a Low (0) and transitions to a High (1) when the timer value matches the PWM value. The Timer Output signal returns to a Low (0) after the timer reaches the Reload value and is reset to 0001H.

The timer also generates a second PWM output signal Timer Output Complement. The Timer Output Complement is the complement of the Timer Output PWM signal. A programmable deadband delay can be configured to time delay (0 to 128 system clock cycles) PWM output transitions on these two pins from a low to a high (inactive to active). This ensures a time gap between the deassertion of one PWM output to the assertion of its complement.

Follow the steps below for configuring a timer for PWM DUAL OUTPUT mode and initiating the PWM operation:

- 1. Write to the Timer Control register to:
 - Disable the timer.
 - Configure the timer for PWM DUAL OUTPUT mode by writing the TMODE bits in the TxCTL1 register and the TMODEHI bit in TxCTL0 register.
 - Set the prescale value.
 - Set the initial logic level (High or Low) and PWM High/Low transition for the Timer Output alternate function.
- 2. Write to the Timer High and Low Byte registers to set the starting count value (typically 0001H). This only affects the first pass in PWM mode. After the first timer reset in PWM mode, counting always begins at the reset value of 0001H.
- 3. Write to the PWM High and Low Byte registers to set the PWM value.
- 4. Write to the PWM Control register to set the PWM dead band delay value. The deadband delay must be less than the duration of the positive phase of the PWM signal (as defined by the PWM high and low byte registers). It must also be less than the

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Timer Reload Low Byte register occurs, the temporary holding register value is written to the Timer High Byte register. This operation allows simultaneous updates of the 16-bit Timer Reload value.

In COMPARE mode, the Timer Reload High and Low Byte registers store the 16-bit Compare value.

Table 52. Timer 0–1 Reload High Byte Register (TxRH)

BITS	7	6	5	4	3	2	1	0				
FIELD		TRH										
RESET	1	1	1	1	1	1	1					
R/W	R/W R/W R/W R/W R/W R/W R											
ADDR				F02H,	F0AH							

Table 53. Timer 0–1 Reload Low Byte Register (TxRL)

BITS	7	6	5	4	3	2	2 1					
FIELD		TRL										
RESET	1	1	1	1	1	1	1					
R/W	R/W R/W R/W R/W R/W R/W R											
ADDR				F03H,	F0BH							

TRH and TRL—Timer Reload Register High and Low

These two bytes form the 16-bit Reload value, {TRH[7:0], TRL[7:0]}. This value sets the maximum count value which initiates a timer reload to 0001H. In COMPARE mode, these two bytes form the 16-bit Compare value.

Timer 0-1 PWM High and Low Byte Registers

The Timer 0-1 PWM High and Low Byte (TxPWMH and TxPWML) registers (Table 54 and Table 55) control Pulse-Width Modulator (PWM) operations. These registers also store the Capture values for the CAPTURE and CAPTURE/COMPARE modes.

Table 54. Timer 0–1 PWM High Byte Register (TxPWMH)

BITS	7	6	5	4	3	2	1	0		
FIELD	PWMH									
RESET	0	0	0	0	0	0	0	0		
R/W	R/W	R/W	R/W	R/W	R/W	R/W R/W		R/W		
ADDR				F04H,	F0CH					



WDT Reset in Normal Operation

If configured to generate a Reset when a time-out occurs, the Watchdog Timer forces the device into the System Reset state. The WDT status bit in the Reset Status (RSTSTAT) register is set to 1. For more information on system reset, see Reset, Stop Mode Recovery, and Low Voltage Detection on page 23.

WDT Reset in STOP Mode

If configured to generate a Reset when a time-out occurs and the device is in STOP mode, the Watchdog Timer initiates a Stop Mode Recovery. Both the WDT status bit and the STOP bit in the Reset Status (RSTSTAT) register are set to 1 following WDT time-out in STOP mode.

Watchdog Timer Reload Unlock Sequence

Writing the unlock sequence to the Watchdog Timer (WDTCTL) Control register address unlocks the three Watchdog Timer Reload Byte registers (WDTU, WDTH, and WDTL) to allow changes to the time-out period. These write operations to the WDTCTL register address produce no effect on the bits in the WDTCTL register. The locking mechanism prevents spurious writes to the Reload registers. Follow the steps below to unlock the Watchdog Timer Reload Byte registers (WDTU, WDTH, and WDTL) for write access.

- 1. Write 55H to the Watchdog Timer Control register (WDTCTL).
- 2. Write AAH to the Watchdog Timer Control register (WDTCTL).
- 3. Write the Watchdog Timer Reload Upper Byte register (WDTU) with the desired time-out value.
- 4. Write the Watchdog Timer Reload High Byte register (WDTH) with the desired time-out value.
- 5. Write the Watchdog Timer Reload Low Byte register (WDTL) with the desired time-out value.

All three Watchdog Timer Reload registers must be written in the order just listed. There must be no other register writes between each of these operations. If a register write occurs, the lock state machine resets and no further writes can occur unless the sequence is restarted. The value in the Watchdog Timer Reload registers is loaded into the counter when the Watchdog Timer is first enabled and every time a WDT instruction is executed.

Watchdog Timer Calibration

Due to its extremely low operating current, the Watchdog Timer oscillator is somewhat inaccurate. This variation can be corrected using the calibration data stored in the Flash Information Page (see Table 97 and Table 98 on page 165). Loading these values into the





Figure 19. Analog-to-Digital Converter Block Diagram

Operation

Data Format

In both SINGLE-ENDED and DIFFERENTIAL modes, the effective output of the ADC is an 11-bit, signed, two's complement digital value. In DIFFERENTIAL mode, the ADC

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ANAIN[3:0]—Analog Input Select

These bits select the analog input for conversion. Not all Port pins in this list are available in all packages for the Z8 Encore! XP[®] F082A Series. For information on port pins available with each package style, see Pin Description on page 9. Do not enable unavailable analog inputs. Usage of these bits changes depending on the buffer mode selected in ADC Control/Status Register 1.

For the reserved values, all input switches are disabled to avoid leakage or other undesirable operation. ADC samples taken with reserved bit settings are undefined.

SINGLE-ENDED:

- 0000 = ANA0 (transimpedance amp output when enabled)
- 0001 = ANA1 (transimpedance amp inverting input)
- 0010 = ANA2 (transimpedance amp non-inverting input)
- 0011 = ANA3
- 0100 = ANA4
- 0101 = ANA5
- 0110 = ANA6
- 0111 = ANA7
- 1000 = Reserved
- 1001 = Reserved
- 1010 = Reserved
- 1011 = Reserved
- 1100 = Hold transimpedance input nodes (ANA1 and ANA2) to ground.
- 1101 = Reserved
- 1110 = Temperature Sensor.
- 1111 = Reserved.

DIFFERENTIAL (non-inverting input and inverting input respectively):

- 0000 = ANA0 and ANA1 0001 = ANA2 and ANA3 0010 = ANA4 and ANA5 0011 = ANA1 and ANA0 0100 = ANA3 and ANA2 0101 = ANA5 and ANA4 0110 = ANA6 and ANA5 0111 = ANA0 and ANA5 1011 = ANA0 and ANA3 1001 = ANA0 and ANA3 1001 = ANA0 and ANA4 1010 = ANA0 and ANA5 1011 = Reserved 1100 = Reserved 1101 = Reserved1101 = Reserved
- 1111 = Manual Offset Calibration Mode



Assuming a compensated ADC measurement, the following equation defines the relationship between the ADC reading and the die temperature:

 $T = (25/128) \times (ADC - TSCAL[11:2]) + 30$

where, T is the temperature in C; ADC is the 10-bit compensated ADC value; and TSCAL is the temperature sensor calibration value, ignoring the two least significant bits of the 12-bit value.

See Temperature Sensor Calibration Data on page 164 for the location of TSCAL.

Calibration

The temperature sensor undergoes calibration during the manufacturing process and is maximally accurate at 30 °C. Accuracy decreases as measured temperatures move further from the calibration point.



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Trim Bit Address 0001H

Table 89. Trim Option Bits at 0001H

BITS	7	6	5	4	3	2	1	0					
FIELD		Reserved											
RESET	U	U	U	U	U	U	U						
R/W	R/W R/W R/W R/W R/W R/W R/W												
ADDR		Information Page Memory 0021H											
Note: U =	ote: U = Unchanged by Reset. R/W = Read/Write.												

Reserved—Altering this register may result in incorrect device operation.

Trim Bit Address 0002H

Table 90. Trim Option Bits at 0002H (TIPO)

BITS	7	6	5	4	3	2	1	0					
FIELD		IPO_TRIM											
RESET	U												
R/W	R/W												
ADDR	Information Page Memory 0022H												
Note: U =	Unchanged b	v Reset. R/W	= Read/Write	2									

IPO_TRIM—Internal Precision Oscillator Trim Byte Contains trimming bits for Internal Precision Oscillator.

Trim Bit Address 0003H

Note: *The LVD is available on 8-pin devices only.*

Table 91. Trim Option Bits at Address 0003H (TLVD)

BITS	7	6	5	4	3	0						
FIELD		Reserved		LVD_TRIM								
RESET	U	U	U									
R/W	R/W	R/W	R/W	R/W R/W R/W R/W								
ADDR		Information Page Memory 0023H										
Note: U =	Unchanged b	y Reset. R/W	= Read/Write									

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WDFEN-Watchdog Timer Oscillator Failure Detection Enable

1 = Failure detection of Watchdog Timer oscillator is enabled

0 = Failure detection of Watchdog Timer oscillator is disabled

SCKSEL—System Clock Oscillator Select

000 = Internal precision oscillator functions as system clock at 5.53 MHz

001 = Internal precision oscillator functions as system clock at 32 kHz

010 = Crystal oscillator or external RC oscillator functions as system clock

011 = Watchdog Timer oscillator functions as system

100 = External clock signal on PB3 functions as system clock

101 = Reserved

110 = Reserved

111 = Reserved

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Crystal Oscillator

The products in the Z8 Encore! XP[®] F082A Series contain an on-chip crystal oscillator for use with external crystals with 32 kHz to 20 MHz frequencies. In addition, the oscillator supports external RC networks with oscillation frequencies up to 4 MHz or ceramic resonators with frequencies up to 8 MHz. The on-chip crystal oscillator can be used to generate the primary system clock for the internal eZ8 CPU and the majority of the on-chip peripherals. Alternatively, the X_{IN} input pin can also accept a CMOS-level clock input signal (32 kHz–20 MHz). If an external clock generator is used, the X_{OUT} pin must be left unconnected. The Z8 Encore! XP F082A Series products do not contain an internal clock divider. The frequency of the signal on the X_{IN} input pin determines the frequency of the system clock.

Note:

Although the XIN pin can be used as an input for an external clock generator, the CLKIN pin is better suited for such use (see System Clock Selection on page 187).

Operating Modes

The Z8 Encore! XP F082A Series products support four oscillator modes:

- Minimum power for use with very low frequency crystals (32 kHz–1 MHz).
- Medium power for use with medium frequency crystals or ceramic resonators (0.5 MHz to 8 MHz).
- Maximum power for use with high frequency crystals (8 MHz to 20 MHz).
- On-chip oscillator configured for use with external RC networks (<4 MHz).

The oscillator mode is selected using user-programmable Flash Option Bits. See Flash Option Bits on page 153 for information.

Crystal Oscillator Operation

The Flash Option bit XTLDIS controls whether the crystal oscillator is enabled during reset. The crystal may later be disabled after reset if a new oscillator has been selected as the system clock. If the crystal is manually enabled after reset through the OSCCTL register, the user code must wait at least 1000 crystal oscillator cycles for the crystal to stabilize. After this, the crystal oscillator may be selected as the system clock.

• Note: The stabilization time varies depending on the crystal or resonator used, as well as on the feedback network. See Table 111 for transconductance values to compute oscillator stabilization times.

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Table 116 through Table 123 lists the instructions belonging to each group and the number of operands required for each instruction. Some instructions appear in more than one table as these instruction can be considered as a subset of more than one category. Within these tables, the source operand is identified as 'src', the destination operand is 'dst' and a condition code is 'cc'.

Mnemonic	Operands	Instruction
ADC	dst, src	Add with Carry
ADCX	dst, src	Add with Carry using Extended Addressing
ADD	dst, src	Add
ADDX	dst, src	Add using Extended Addressing
СР	dst, src	Compare
CPC	dst, src	Compare with Carry
CPCX	dst, src	Compare with Carry using Extended Addressing
СРХ	dst, src	Compare using Extended Addressing
DA	dst	Decimal Adjust
DEC	dst	Decrement
DECW	dst	Decrement Word
INC	dst	Increment
INCW	dst	Increment Word
MULT	dst	Multiply
SBC	dst, src	Subtract with Carry
SBCX	dst, src	Subtract with Carry using Extended Addressing
SUB	dst, src	Subtract
SUBX	dst, src	Subtract using Extended Addressing

Table 116. Arithmetic Instructions

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Assembly	Symbolic	Addres	s Mode	Opcode(s)			Fla	ags			Fetch	Instr.
Mnemonic	Operation	dst	src	(Hex)	С	Ζ	S	۷	D	Н	Cycles	Cycles
HALT	Halt Mode			7F	_	_	_	_	-	_	1	2
INC dst	$dst \gets dst + 1$	R		20	-	*	*	_	-	_	2	2
		IR		21	-						2	3
		r		0E-FE	-						1	2
INCW dst	$dst \gets dst + 1$	RR		A0	-	*	*	*	-	-	2	5
		IRR		A1	-						2	6
IRET	$\begin{array}{l} FLAGS \leftarrow @SP \\ SP \leftarrow SP + 1 \\ PC \leftarrow @SP \\ SP \leftarrow SP + 2 \\ IRQCTL[7] \leftarrow 1 \end{array}$			BF	*	*	*	*	*	*	1	5
JP dst	$PC \gets dst$	DA		8D	-	_	-	-	-	-	3	2
		IRR		C4	-						2	3
JP cc, dst	if cc is true PC \leftarrow dst	DA		0D-FD	_	_	-	-	-	-	3	2
JR dst	$PC \gets PC + X$	DA		8B	_	_	_	_	-	_	2	2
JR cc, dst	if cc is true PC \leftarrow PC + X	DA		0B-FB	-	-	-	_	-	-	2	2
LD dst, rc	$dst \gets src$	r	IM	0C-FC	-	-	-	-	-	-	2	2
		r	X(r)	C7	-						3	3
		X(r)	r	D7	-						3	4
		r	lr	E3	-						2	3
		R	R	E4	-						3	2
		R	IR	E5	-						3	4
		R	IM	E6	-						3	2
		IR	IM	E7	-						3	3
		lr	r	F3	-						2	3
		IR	R	F5	-						3	3
Flags Notation:	* = Value is a functior – = Unaffected X = Undefined	of the result	of the o	peration.	0 = 1 =	Re Se	set t to	to (1)			

Table 124. eZ8 CPU Instruction Summary (Continued)

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Assembly	Symbolic	Addres	s Mode	Opcode(s)	Flags						Fetch	Instr.
Mnemonic	Operation	dst	src	src (Hex)		Ζ	S	۷	D	Н	Cycles	Cycles
RR dst		R		E0	*	*	*	*	-	-	2	2
	► D7 D6 D5 D4 D3 D2 D1 D0 ► C	IR		E1							2	3
RRC dst		R		C0	*	*	*	*	-	-	2	2
	► D7 D6 D5 D4 D3 D2 D1 D0 ► C	IR		C1							2	3
SBC dst, src	$dst \gets dst - src - C$	r	r	32	*	*	*	*	1	*	2	3
		r	lr	33							2	4
		R	R	34							3	3
		R	IR	35							3	4
		R	IM	36							3	3
		IR	IM	37							3	4
SBCX dst, src	$dst \gets dst - src - C$	ER	ER	38	*	*	*	*	1	*	4	3
		ER	IM	39	_						4	3
SCF	$C \leftarrow 1$			DF	1	-	-	-	-	-	1	2
SRA dst	T V	R		D0	*	*	*	0	_	-	2	2
	D7 D6 D5 D4 D3 D2 D1 D0 C dst	IR		D1							2	3
SRL dst	0 - ▶ D7 D6 D5 D4 D3 D2 D1 D0 ▶ C	R		1F C0	*	*	0	*	-	-	3	2
	dst	IR		1F C1	•						3	3
SRP src	$RP \gets src$		IM	01	_	_	_	_	_	_	2	2
STOP	STOP Mode			6F	_	_	_	_	_	-	1	2
SUB dst, src	$dst \gets dst - src$	r	r	22	*	*	*	*	1	*	2	3
		r	lr	23	•						2	4
		R	R	24	•						3	3
		R	IR	25	•						3	4
		R	IM	26							3	3
		IR	IM	27	•						3	4
Flags Notation:	* = Value is a function of th – = Unaffected X = Undefined	ne result	of the o	peration.	0 = 1 =	Re Se	set t to	to (1)			

Table 124. eZ8 CPU Instruction Summary (Continued)



On-Chip Debugger Timing

Figure 36 and Table 141 provide timing information for the DBG pin. The DBG pin timing specifications assume a 4 ns maximum rise and fall time.



Figure 36. On-Chip Debugger Timing

		Delay (ns)					
Parameter	Abbreviation	Minimum	Maximum				
DBG							
T ₁	XIN Rise to DBG Valid Delay	-	15				
T ₂	XIN Rise to DBG Output Hold Time	2	-				
T ₃	DBG to XIN Rise Input Setup Time	5	-				
T ₄	DBG to XIN Rise Input Hold Time	5	-				

Table 141. On-Chip Debugger Timing

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Figure 43 displays the 20-pin Small Outline Integrated Circuit Package (SOIC) available for the Z8 Encore! XP F082A Series devices.

Figure 43. 20-Pin Small Outline Integrated Circuit Package (SOIC)

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art Number	lash	ŁAM	NDS	O Lines	nterrupts	6-Bit Timers w/PWM	0-Bit A/D Channels	JART with IrDA	comparator	emperature Sensor	lescription
Z8 Encore! XP [®] F082A	Serie	s with 1	KB Fla	 Ish, 1	 0-Bit	Ana	log-t	o-Dig	ital C	onv	verter
Standard Temperature: 0 °C to 70 °C											
Z8F012APB020SC	1 KB	256 B	16 B	6	14	2	4	1	1	1	PDIP 8-pin package
Z8F012AQB020SC	1 KB	256 B	16 B	6	14	2	4	1	1	1	QFN 8-pin package
Z8F012ASB020SC	1 KB	256 B	16 B	6	14	2	4	1	1	1	SOIC 8-pin package
Z8F012ASH020SC	1 KB	256 B	16 B	17	20	2	7	1	1	1	SOIC 20-pin package
Z8F012AHH020SC	1 KB	256 B	16 B	17	20	2	7	1	1	1	SSOP 20-pin package
Z8F012APH020SC	1 KB	256 B	16 B	17	20	2	7	1	1	1	PDIP 20-pin package
Z8F012ASJ020SC	1 KB	256 B	16 B	23	20	2	8	1	1	1	SOIC 28-pin package
Z8F012AHJ020SC	1 KB	256 B	16 B	23	20	2	8	1	1	1	SSOP 28-pin package
Z8F012APJ020SC	1 KB	256 B	16 B	23	20	2	8	1	1	1	PDIP 28-pin package
Extended Temperature	e: -40 °	°C to 10	5 °C								
Z8F012APB020EC	1 KB	256 B	16 B	6	14	2	4	1	1	1	PDIP 8-pin package
Z8F012AQB020EC	1 KB	256 B	16 B	6	14	2	4	1	1	1	QFN 8-pin package
Z8F012ASB020EC	1 KB	256 B	16 B	6	14	2	4	1	1	1	SOIC 8-pin package
Z8F012ASH020EC	1 KB	256 B	16 B	17	20	2	7	1	1	1	SOIC 20-pin package
Z8F012AHH020EC	1 KB	256 B	16 B	17	20	2	7	1	1	1	SSOP 20-pin package
Z8F012APH020EC	1 KB	256 B	16 B	17	20	2	7	1	1	1	PDIP 20-pin package
Z8F012ASJ020EC	1 KB	256 B	16 B	23	20	2	8	1	1	1	SOIC 28-pin package
Z8F012AHJ020EC	1 KB	256 B	16 B	23	20	2	8	1	1	1	SSOP 28-pin package
Z8F012APJ020EC	1 KB	256 B	16 B	23	20	2	8	1	1	1	PDIP 28-pin package
Replace C with G for Lead	I-Free F	ackaging									



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DJNZ 206 EI 204 **HALT 204 INC 203 INCW 203 IRET 206** JP 206 LD 205 LDC 205 LDCI 204, 205 LDE 205 LDEI 204 LDX 205 LEA 205 logical 205 **MULT 203** NOP 204 OR 205 **ORX 206** POP 205 **POPX 205** program control 206 **PUSH 205** PUSHX 205 **RCF 204 RET 206** RL 206 **RLC 206** rotate and shift 206 RR 206 **RRC 206** SBC 203 SCF 204, 205 SRA 207 SRL 207 **SRP 205 STOP 205** SUB 203 SUBX 203 **SWAP 207** TCM 204 **TCMX 204** TM 204 TMX 204

TRAP 206 Watchdog Timer refresh 205 XOR 206 **XORX 206** instructions, eZ8 classes of 202 interrupt control register 67 interrupt controller 55 architecture 55 interrupt assertion types 58 interrupt vectors and priority 58 operation 57 register definitions 60 software interrupt assertion 59 interrupt edge select register 66 interrupt request 0 register 60 interrupt request 1 register 61 interrupt request 2 register 62 interrupt return 206 interrupt vector listing 55 interrupts **UART 105** IR 201 lr 201 IrDA architecture 117 block diagram 117 control register definitions 120 operation 117 receiving data 119 transmitting data 118 **IRET 206** IRQ0 enable high and low bit registers 62 IRQ1 enable high and low bit registers 63 IRQ2 enable high and low bit registers 65 **IRR 201** Irr 201

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JP 206 jump, conditional, relative, and relative conditional 206