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### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Obsolete
Core Processor	eZ8
Core Size	8-Bit
Speed	20MHz
Connectivity	IrDA, UART/USART
Peripherals	Brown-out Detect/Reset, LED, LVD, POR, PWM, Temp Sensor, WDT
Number of I/O	6
Program Memory Size	8KB (8K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	1K x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 3.6V
Data Converters	A/D 4x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Through Hole
Package / Case	8-DIP (0.300", 7.62mm)
Supplier Device Package	-
Purchase URL	<a href="https://www.e-xfl.com/product-detail/zilog/z8f082apb020ec">https://www.e-xfl.com/product-detail/zilog/z8f082apb020ec</a>

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## Universal Asynchronous Receiver/Transmitter

The full-duplex universal asynchronous receiver/transmitter (UART) is included in all Z8 Encore! XP package types. The UART supports 8- and 9-bit data modes and selectable parity. The UART also supports multi-drop address processing in hardware. The UART baud rate generator (BRG) can be configured and used as a basic 16-bit timer.

## Timers

Two enhanced 16-bit reloadable timers can be used for timing/counting events or for motor control operations. These timers provide a 16-bit programmable reload counter and operate in ONE-SHOT, CONTINUOUS, GATED, CAPTURE, CAPTURE RESTART, COMPARE, CAPTURE and COMPARE, PWM SINGLE OUTPUT and PWM DUAL OUTPUT modes.

## General-Purpose Input/Output

The Z8 Encore! XP F082A Series features 6 to 25 port pins (Ports A–D) for general-purpose input/output (GPIO). The number of GPIO pins available is a function of package, and each pin is individually programmable. 5 V tolerant input pins are available on all I/Os on 8-pin devices and most I/Os on other package types.

## Direct LED Drive

The 20- and 28-pin devices support controlled current sinking output pins capable of driving LEDs without the need for a current limiting resistor. These LED drivers are independently programmable to four different intensity levels.

## Flash Controller

The Flash Controller programs and erases Flash memory. The Flash Controller supports several protection mechanisms against accidental program and erasure, as well as factory serialization and read protection.

## Non-Volatile Data Storage

The non-volatile data storage (NVDS) uses a hybrid hardware/software scheme to implement a byte programmable data memory and is capable of over 100,000 write cycles.

► **Note:** *Devices with 8 KB Flash memory do not include the NVDS feature.*

and as long as four. A reset pulse three clock cycles in duration might trigger a reset; a pulse four cycles in duration always triggers a reset.

While the  $\overline{\text{RESET}}$  input pin is asserted Low, the Z8 Encore! XP<sup>®</sup> F082A Series devices remain in the Reset state. If the  $\overline{\text{RESET}}$  pin is held Low beyond the System Reset time-out, the device exits the Reset state on the system clock rising edge following  $\overline{\text{RESET}}$  pin deassertion. Following a System Reset initiated by the external  $\overline{\text{RESET}}$  pin, the EXT status bit in the Reset Status (RSTSTAT) register is set to 1.

## External Reset Indicator

During System Reset or when enabled by the GPIO logic (see [Port A–D Control Registers](#) on page 46), the  $\overline{\text{RESET}}$  pin functions as an open-drain (active Low) reset mode indicator in addition to the input functionality. This reset output feature allows a Z8 Encore! XP F082A Series device to reset other components to which it is connected, even if that reset is caused by internal sources such as POR, VBO or WDT events.

After an internal reset event occurs, the internal circuitry begins driving the  $\overline{\text{RESET}}$  pin Low. The  $\overline{\text{RESET}}$  pin is held Low by the internal circuitry until the appropriate delay listed in [Table 8](#) has elapsed.

## On-Chip Debugger Initiated Reset

A Power-On Reset can be initiated using the On-Chip Debugger by setting the RST bit in the OCD Control register. The On-Chip Debugger block is not reset but the rest of the chip goes through a normal system reset. The RST bit automatically clears during the system reset. Following the system reset the POR bit in the Reset Status (RSTSTAT) register is set.

## Stop Mode Recovery

STOP mode is entered by execution of a STOP instruction by the eZ8 CPU. See [Low-Power Modes](#) on page 33 for detailed STOP mode information. During Stop Mode Recovery (SMR), the CPU is held in reset for 66 IPO cycles if the crystal oscillator is disabled or 5000 cycles if it is enabled. The SMR delay (see [Table 131](#) on page 229)  $T_{\text{SMR}}$ , also includes the time required to start up the IPO.

Stop Mode Recovery does not affect on-chip registers other than the Watchdog Timer Control register (WDTCTL) and the Oscillator Control register (OSCCTL). After any Stop Mode Recovery, the IPO is enabled and selected as the system clock. If another system clock source is required, the Stop Mode Recovery code must reconfigure the oscillator control block such that the correct system clock source is enabled and selected.

The eZ8 CPU fetches the Reset vector at Program Memory addresses 0002H and 0003H and loads that value into the Program Counter. Program execution begins at the Reset

# Low-Power Modes

The Z8 Encore! XP F082A Series products contain power-saving features. The highest level of power reduction is provided by the STOP mode, in which nearly all device functions are powered down. The next lower level of power reduction is provided by the HALT mode, in which the CPU is powered down.

Further power savings can be implemented by disabling individual peripheral blocks while in Active mode (defined as being in neither STOP nor HALT mode).

## STOP Mode

Executing the eZ8 CPU's STOP instruction places the device into STOP mode, powering down all peripherals except the Voltage Brownout detector, the Low-power Operational Amplifier and the Watchdog Timer. These three blocks may also be disabled for additional power savings. Specifically, the operating characteristics are:

- Primary crystal oscillator and internal precision oscillator are stopped; XIN and XOUT (if previously enabled) are disabled, and PA0/PA1 revert to the states programmed by the GPIO registers.
- System clock is stopped.
- eZ8 CPU is stopped.
- Program counter (PC) stops incrementing.
- Watchdog Timer's internal RC oscillator continues to operate if enabled by the Oscillator Control register.
- If enabled, the Watchdog Timer logic continues to operate.
- If enabled for operation in STOP mode by the associated Flash Option Bit, the Voltage Brownout protection circuit continues to operate.
- Low-power operational amplifier continues to operate if enabled by the Power Control register to do so.
- All other on-chip peripherals are idle.

To minimize current in STOP mode, all GPIO pins that are configured as digital inputs must be driven to one of the supply rails ( $V_{CC}$  or GND). Additionally, any GPIOs configured as outputs must also be driven to one of the supply rails. The device can be brought out of STOP mode using Stop Mode Recovery. For more information on Stop Mode Recovery, see [Reset, Stop Mode Recovery, and Low Voltage Detection](#) on page 23.

**Table 15. Port Alternate Function Mapping (8-Pin Parts)**

Port	Pin	Mnemonic	Alternate Function Description	Alternate Function Select Register AFS1	Alternate Function Select Register AFS2
<b>Port A</b>	PA0	T0IN	Timer 0 Input	AFS1[0]: 0	AFS2[0]: 0
		Reserved		AFS1[0]: 0	AFS2[0]: 1
		Reserved		AFS1[0]: 1	AFS2[0]: 0
		$\overline{T0OUT}$	Timer 0 Output Complement	AFS1[0]: 1	AFS2[0]: 1
	PA1	T0OUT	Timer 0 Output	AFS1[1]: 0	AFS2[1]: 0
		Reserved		AFS1[1]: 0	AFS2[1]: 1
		CLKIN	External Clock Input	AFS1[1]: 1	AFS2[1]: 0
		Analog Functions*	ADC Analog Input/VREF	AFS1[1]: 1	AFS2[1]: 1
	PA2	DE0	UART 0 Driver Enable	AFS1[2]: 0	AFS2[2]: 0
		$\overline{RESET}$	External Reset	AFS1[2]: 0	AFS2[2]: 1
		T1OUT	Timer 1 Output	AFS1[2]: 1	AFS2[2]: 0
		Reserved		AFS1[2]: 1	AFS2[2]: 1
	PA3	$\overline{CTS0}$	UART 0 Clear to Send	AFS1[3]: 0	AFS2[3]: 0
		COUT	Comparator Output	AFS1[3]: 0	AFS2[3]: 1
		T1IN	Timer 1 Input	AFS1[3]: 1	AFS2[3]: 0
		Analog Functions*	ADC Analog Input/LPO Input (P)	AFS1[3]: 1	AFS2[3]: 1
	PA4	RXD0	UART 0 Receive Data	AFS1[4]: 0	AFS2[4]: 0
		Reserved		AFS1[4]: 0	AFS2[4]: 1
		Reserved		AFS1[4]: 1	AFS2[4]: 0
		Analog Functions*	ADC/Comparator Input (N)/LPO Input (N)	AFS1[4]: 1	AFS2[4]: 1
	PA5	TXD0	UART 0 Transmit Data	AFS1[5]: 0	AFS2[5]: 0
		$\overline{T1OUT}$	Timer 1 Output Complement	AFS1[5]: 0	AFS2[5]: 1
		Reserved		AFS1[5]: 1	AFS2[5]: 0
		Analog Functions*	ADC/Comparator Input (P) LPO Output	AFS1[5]: 1	AFS2[5]: 1

\*Analog Functions include ADC inputs, ADC reference, comparator inputs and LPO ports.

**Note:** Also, alternate function selection as described in [Port A–D Alternate Function Sub-Registers](#) on page 47 must be enabled.

function). (Push-pull output)

1 = The source current for the associated pin is disabled (open-drain mode).

### Port A–D High Drive Enable Sub-Registers

The Port A–D High Drive Enable sub-register (Table 22) is accessed through the Port A–D Control register by writing 04H to the Port A–D Address register. Setting the bits in the Port A–D High Drive Enable sub-registers to 1 configures the specified port pins for high current output drive operation. The Port A–D High Drive Enable sub-register affects the pins directly and, as a result, alternate functions are also affected.

**Table 22. Port A–D High Drive Enable Sub-Registers (PxHDE)**

BITS	7	6	5	4	3	2	1	0
FIELD	PHDE7	PHDE6	PHDE5	PHDE4	PHDE3	PHDE2	PHDE1	PHDE0
RESET	0	0	0	0	0	0	0	0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
ADDR	If 04H in Port A–D Address Register, accessible through the Port A–D Control Register							

PHDE[7:0]—Port High Drive Enabled

0 = The Port pin is configured for standard output current drive.

1 = The Port pin is configured for high output current drive.

### Port A–D Stop Mode Recovery Source Enable Sub-Registers

The Port A–D Stop Mode Recovery Source Enable sub-register (Table 23) is accessed through the Port A–D Control register by writing 05H to the Port A–D Address register. Setting the bits in the Port A–D Stop Mode Recovery Source Enable sub-registers to 1 configures the specified Port pins as a Stop Mode Recovery source. During STOP mode, any logic transition on a Port pin enabled as a Stop Mode Recovery source initiates Stop Mode Recovery.

**Table 23. Port A–D Stop Mode Recovery Source Enable Sub-Registers (PxSMRE)**

BITS	7	6	5	4	3	2	1	0
FIELD	PSMRE7	PSMRE6	PSMRE5	PSMRE4	PSMRE3	PSMRE2	PSMRE1	PSMRE0
RESET	0	0	0	0	0	0	0	0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
ADDR	If 05H in Port A–D Address Register, accessible through the Port A–D Control Register							

PSMRE[7:0]—Port Stop Mode Recovery Source Enabled

0 = The Port pin is not configured as a Stop Mode Recovery source. Transitions on this pin

## Interrupt Request 2 Register

The Interrupt Request 2 (IRQ2) register ([Table 35](#)) stores interrupt requests for both vectored and polled interrupts. When a request is presented to the interrupt controller, the corresponding bit in the IRQ2 register becomes 1. If interrupts are globally enabled (vectored interrupts), the interrupt controller passes an interrupt request to the eZ8 CPU. If interrupts are globally disabled (polled interrupts), the eZ8 CPU can read the Interrupt Request 2 register to determine if any interrupt requests are pending.

**Table 35. Interrupt Request 2 Register (IRQ2)**

BITS	7	6	5	4	3	2	1	0
FIELD	Reserved				PC3I	PC2I	PC1I	PC0I
RESET	0	0	0	0	0	0	0	0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
ADDR	FC6H							

Reserved—Must be 0.

PCxI—Port C Pin *x* Interrupt Request

0 = No interrupt request is pending for GPIO Port C pin *x*.

1 = An interrupt request from GPIO Port C pin *x* is awaiting service.

where *x* indicates the specific GPIO Port C pin number (0–3).

## IRQ0 Enable High and Low Bit Registers

[Table 36](#) describes the priority control for IRQ0. The IRQ0 Enable High and Low Bit registers ([Table 37](#) and [Table 38](#)) form a priority encoded enabling for interrupts in the Interrupt Request 0 register.

**Table 36. IRQ0 Enable and Priority Encoding**

IRQ0ENH[x]	IRQ0ENL[x]	Priority	Description
0	0	Disabled	Disabled
0	1	Level 1	Low
1	0	Level 2	Medium
1	1	Level 3	High

where *x* indicates the register bits from 0–7.





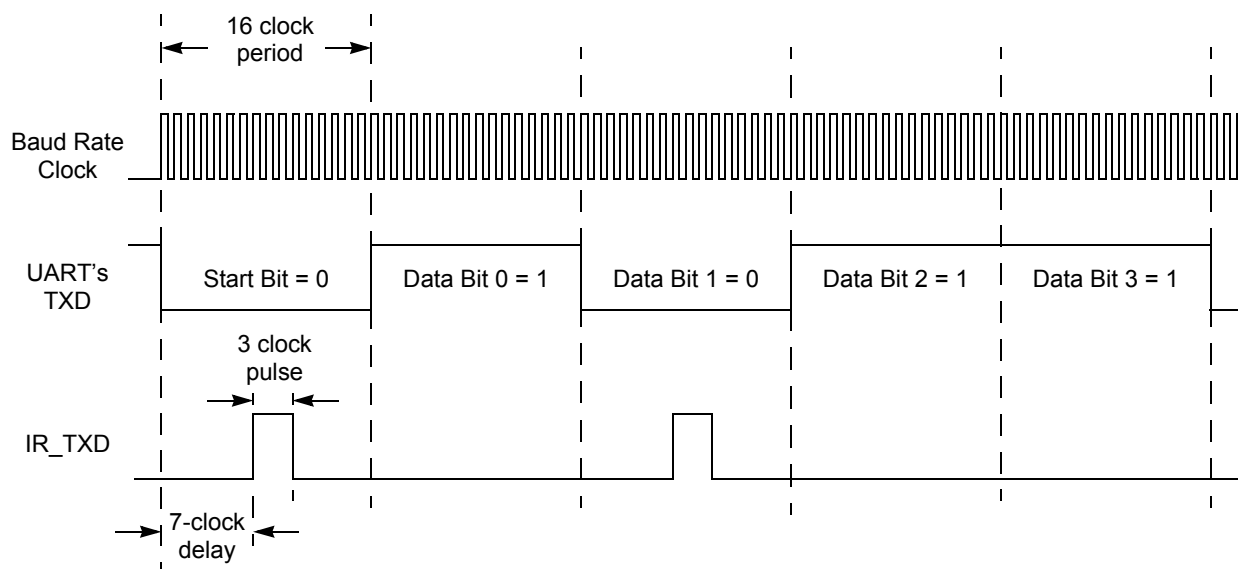
Endec, and passed to the UART. Communication is half-duplex, which means simultaneous data transmission and reception is not allowed.

The baud rate is set by the UART's Baud Rate Generator and supports IrDA standard baud rates from 9600 baud to 115.2 kbaud. Higher baud rates are possible, but do not meet IrDA specifications. The UART must be enabled to use the Infrared Endec. The Infrared Endec data rate is calculated using the following equation:

$$\text{Infrared Data Rate (bits/s)} = \frac{\text{System Clock Frequency (Hz)}}{16 \times \text{UART Baud Rate Divisor Value}}$$

## Transmitting IrDA Data

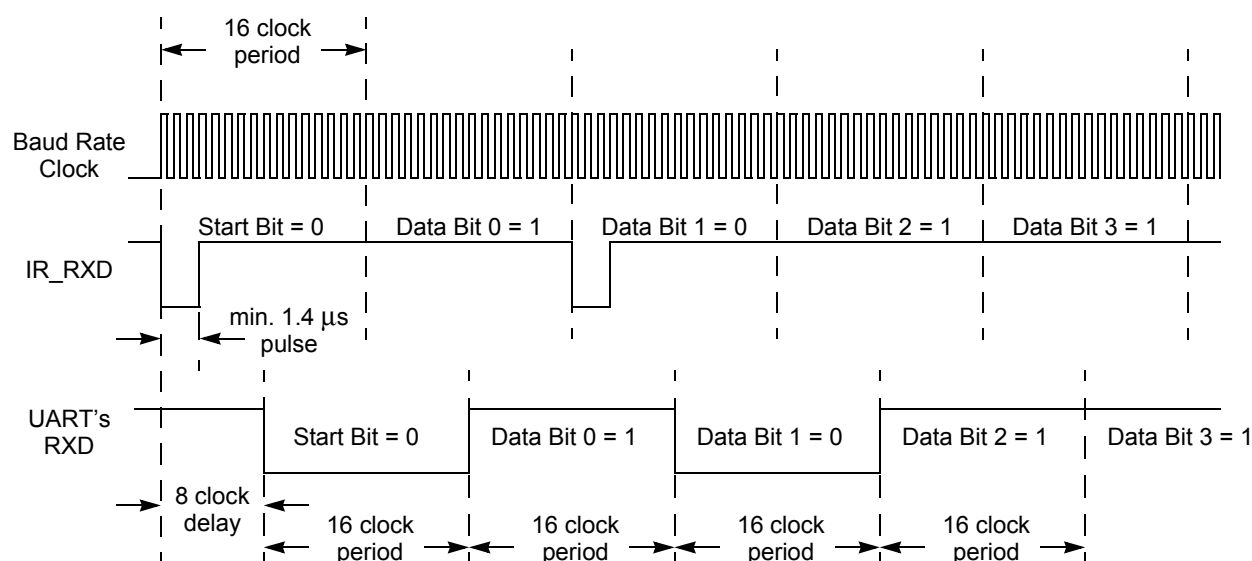
The data to be transmitted using the infrared transceiver is first sent to the UART. The UART's transmit signal (TXD) and baud rate clock are used by the IrDA to generate the modulation signal (IR\_TXD) that drives the infrared transceiver. Each UART/Infrared data bit is 16 clocks wide. If the data to be transmitted is 1, the IR\_TXD signal remains low for the full 16 clock period. If the data to be transmitted is 0, the transmitter first outputs a 7 clock low period, followed by a 3 clock high pulse. Finally, a 6 clock low pulse is output to complete the full 16 clock data period. [Figure 17](#) displays IrDA data transmission. When the Infrared Endec is enabled, the UART's TXD signal is internal to the Z8 Encore! XP<sup>®</sup> F082A Series products while the IR\_TXD signal is output through the TXD pin.



**Figure 17. Infrared Data Transmission**

## Receiving IrDA Data

Data received from the infrared transceiver using the IR\_RXD signal through the RXD pin is decoded by the Infrared Endec and passed to the UART. The UART's baud rate clock is used by the Infrared Endec to generate the demodulated signal (RXD) that drives the UART. Each UART/Infrared data bit is 16-clocks wide. Figure 18 displays data reception. When the Infrared Endec is enabled, the UART's RXD signal is internal to the Z8 Encore! XP<sup>®</sup> F082A Series products while the IR\_RXD signal is received through the RXD pin.



**Figure 18. IrDA Data Reception**

### Infrared Data Reception



**Caution:** The system clock frequency must be at least 1.0 MHz to ensure proper reception of the 1.4 μs minimum width pulses allowed by the IrDA standard.

### Endec Receiver Synchronization

The IrDA receiver uses a local baud rate clock counter (0 to 15 clock periods) to generate an input stream for the UART and to create a sampling window for detection of incoming pulses. The generated UART input (UART RXD) is delayed by 8 baud rate clock periods with respect to the incoming IrDA data stream. When a falling edge in the input data stream is detected, the Endec counter is reset. When the count reaches a value of 8, the UART RXD value is updated to reflect the value of the decoded data. When the count reaches 12 baud clock periods, the sampling window for the next incoming pulse opens. The window remains open until the count again reaches 8 (that is, 24 baud clock periods since the previous pulse was detected), giving the Endec a sampling window of minus four

Debug Command	Command Byte	Enabled when NOT in DEBUG mode?	Disabled by Flash Read Protect Option Bit
Write Register	08H	—	Only writes of the Flash Memory Control registers are allowed. Additionally, only the Mass Erase command is allowed to be written to the Flash Control register.
Read Register	09H	—	Disabled
Write Program Memory	0AH	—	Disabled
Read Program Memory	0BH	—	Disabled
Write Data Memory	0CH	—	Yes
Read Data Memory	0DH	—	—
Read Program Memory CRC	0EH	—	—
Reserved	0FH	—	—
Step Instruction	10H	—	Disabled
Stuff Instruction	11H	—	Disabled
Execute Instruction	12H	—	Disabled
Reserved	13H–FFH	—	—

In the following bulleted list of OCD Commands, data and commands sent from the host to the On-Chip Debugger are identified by 'DBG ← Command/Data'. Data sent from the On-Chip Debugger back to the host is identified by 'DBG → Data'.

- Read OCD Revision (00H)**—The Read OCD Revision command determines the version of the On-Chip Debugger. If OCD commands are added, removed, or changed, this revision number changes.
   
DBG ← 00H
   
DBG → OCDRev[15:8] (Major revision number)
   
DBG → OCDRev[7:0] (Minor revision number)
- Read OCD Status Register (02H)**—The Read OCD Status Register command reads the OCDSTAT register.
   
DBG ← 02H
   
DBG → OCDSTAT[7:0]
- Read Runtime Counter (03H)**—The Runtime Counter counts system clock cycles in between Breakpoints. The 16-bit Runtime Counter counts up from 0000H and stops at the maximum count of FFFFH. The Runtime Counter is overwritten during the



**Caution:** *It is possible to disable the clock failure detection circuitry as well as all functioning clock sources. In this case, the Z8 Encore! XP F082A Series device ceases functioning and can only be recovered by Power-On-Reset.*

## Oscillator Control Register Definitions

### Oscillator Control Register

The Oscillator Control Register (OSCCTL) enables/disables the various oscillator circuits, enables/disables the failure detection/recovery circuitry and selects the primary oscillator, which becomes the system clock.

The Oscillator Control Register must be unlocked before writing. Writing the two step sequence E7H followed by 18H to the Oscillator Control Register unlocks it. The register is locked at successful completion of a register write to the OSCCTL.

**Table 109. Oscillator Control Register (OSCCTL)**

BITS	7	6	5	4	3	2	1	0
FIELD	INTEN	XTLEN	WDTEN	SOFEN	WDFEN	SCKSEL		
RESET	1	0	1	0	0	0	0	0
R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
ADDR	F86H							

INTEN—Internal Precision Oscillator Enable

1 = Internal precision oscillator is enabled

0 = Internal precision oscillator is disabled

XTLEN—Crystal Oscillator Enable; this setting overrides the GPIO register control for PA0 and PA1

1 = Crystal oscillator is enabled

0 = Crystal oscillator is disabled

WDTEN—Watchdog Timer Oscillator Enable

1 = Watchdog Timer oscillator is enabled

0 = Watchdog Timer oscillator is disabled

SOFEN—System Clock Oscillator Failure Detection Enable

1 = Failure detection and recovery of system clock oscillator is enabled

0 = Failure detection and recovery of system clock oscillator is disabled



**Table 117. Bit Manipulation Instructions**

<b>Mnemonic</b>	<b>Operands</b>	<b>Instruction</b>
BCLR	bit, dst	Bit Clear
BIT	p, bit, dst	Bit Set or Clear
BSET	bit, dst	Bit Set
BSWAP	dst	Bit Swap
CCF	—	Complement Carry Flag
RCF	—	Reset Carry Flag
SCF	—	Set Carry Flag
TCM	dst, src	Test Complement Under Mask
TCMX	dst, src	Test Complement Under Mask using Extended Addressing
TM	dst, src	Test Under Mask
TMX	dst, src	Test Under Mask using Extended Addressing

**Table 118. Block Transfer Instructions**

<b>Mnemonic</b>	<b>Operands</b>	<b>Instruction</b>
LDCI	dst, src	Load Constant to/from Program Memory and Auto-Increment Addresses
LDEI	dst, src	Load External Data to/from Data Memory and Auto-Increment Addresses

**Table 119. CPU Control Instructions**

<b>Mnemonic</b>	<b>Operands</b>	<b>Instruction</b>
ATM	—	Atomic Execution
CCF	—	Complement Carry Flag
DI	—	Disable Interrupts
EI	—	Enable Interrupts
HALT	—	Halt Mode
NOP	—	No Operation
RCF	—	Reset Carry Flag

**Table 123. Rotate and Shift Instructions (Continued)**

Mnemonic	Operands	Instruction
SRA	dst	Shift Right Arithmetic
SRL	dst	Shift Right Logical
SWAP	dst	Swap Nibbles

## eZ8 CPU Instruction Summary

Table 124 summarizes the eZ8 CPU instructions. The table identifies the addressing modes employed by the instruction, the effect upon the Flags register, the number of CPU clock cycles required for the instruction fetch, and the number of CPU clock cycles required for the instruction execution.

**Table 124. eZ8 CPU Instruction Summary**

Assembly Mnemonic	Symbolic Operation	Address Mode		Opcode(s) (Hex)	Flags						Fetch Cycles	Instr. Cycles
		dst	src		C	Z	S	V	D	H		
ADC dst, src	$\text{dst} \leftarrow \text{dst} + \text{src} + \text{C}$	r	r	12	*	*	*	*	0	*	2	3
		r	lr	13							2	4
		R	R	14							3	3
		R	IR	15							3	4
		R	IM	16							3	3
		IR	IM	17							3	4
ADCX dst, src	$\text{dst} \leftarrow \text{dst} + \text{src} + \text{C}$	ER	ER	18	*	*	*	*	0	*	4	3
		ER	IM	19							4	3
ADD dst, src	$\text{dst} \leftarrow \text{dst} + \text{src}$	r	r	02	*	*	*	*	0	*	2	3
		r	lr	03							2	4
		R	R	04							3	3
		R	IR	05							3	4
		R	IM	06							3	3
		IR	IM	07							3	4
ADDX dst, src	$\text{dst} \leftarrow \text{dst} + \text{src}$	ER	ER	08	*	*	*	*	0	*	4	3
		ER	IM	09							4	3
Flags Notation:	* = Value is a function of the result of the operation. – = Unaffected X = Undefined				0 = Reset to 0 1 = Set to 1							



**Table 125. Opcode Map Abbreviations**

<b>Abbreviation</b>	<b>Description</b>	<b>Abbreviation</b>	<b>Description</b>
b	Bit position	IRR	Indirect Register Pair
cc	Condition code	p	Polarity (0 or 1)
X	8-bit signed index or displacement	r	4-bit Working Register
DA	Destination address	R	8-bit register
ER	Extended Addressing register	r1, R1, Ir1, Irr1, IR1, rr1, RR1, IRR1, ER1	Destination address
IM	Immediate data value	r2, R2, Ir2, Irr2, IR2, rr2, RR2, IRR2, ER2	Source address
Ir	Indirect Working Register	RA	Relative
IR	Indirect register	rr	Working Register Pair
Irr	Indirect Working Register Pair	RR	Register Pair

## AC Characteristics

The section provides information about the AC characteristics and timing. All AC timing information assumes a standard load of 50 pF on all outputs.

**Table 129. AC Characteristics**

		$V_{DD} = 2.7 \text{ V to } 3.6 \text{ V}$ $T_A = -40 \text{ }^{\circ}\text{C to } +105 \text{ }^{\circ}\text{C}$ (unless otherwise stated)			
Symbol	Parameter	Minimum	Maximum	Units	Conditions
F <sub>SYSCLK</sub>	System Clock Frequency	–	20.0	MHz	Read-only from Flash memory
		0.032768	20.0	MHz	Program or erasure of the Flash memory
F <sub>XTAL</sub>	Crystal Oscillator Frequency	–	20.0	MHz	System clock frequencies below the crystal oscillator minimum require an external clock driver
T <sub>XIN</sub>	System Clock Period	50	–	ns	$T_{CLK} = 1/F_{sysclk}$
T <sub>XINH</sub>	System Clock High Time	20	30	ns	$T_{CLK} = 50 \text{ ns}$
T <sub>XINL</sub>	System Clock Low Time	20	30	ns	$T_{CLK} = 50 \text{ ns}$
T <sub>XINR</sub>	System Clock Rise Time	–	3	ns	$T_{CLK} = 50 \text{ ns}$
T <sub>XINF</sub>	System Clock Fall Time	–	3	ns	$T_{CLK} = 50 \text{ ns}$

## Packaging

Figure 39 displays the 8-pin Plastic Dual Inline Package (PDIP) available for Z8 Encore! XP<sup>®</sup> F082A Series devices.

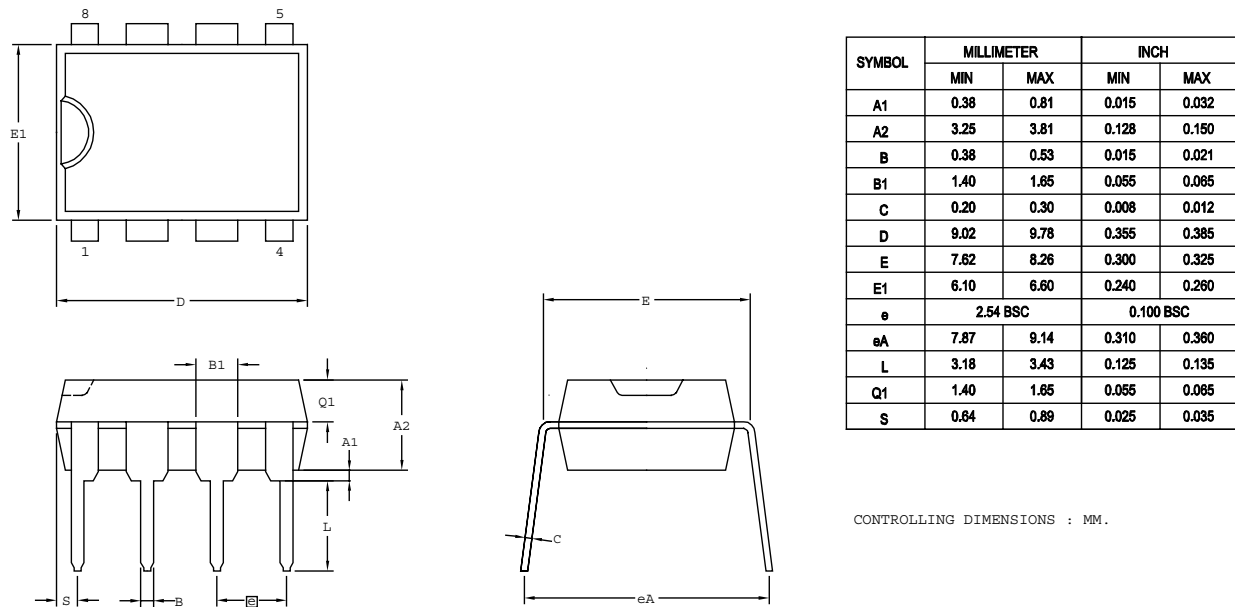


Figure 39. 8-Pin Plastic Dual Inline Package (PDIP)

DJNZ 206  
EI 204  
HALT 204  
INC 203  
INCW 203  
IRET 206  
JP 206  
LD 205  
LDC 205  
LDCI 204, 205  
LDE 205  
LDEI 204  
LDX 205  
LEA 205  
logical 205  
MULT 203  
NOP 204  
OR 205  
ORX 206  
POP 205  
POPX 205  
program control 206  
PUSH 205  
PUSHX 205  
RCF 204  
RET 206  
RL 206  
RLC 206  
rotate and shift 206  
RR 206  
RRC 206  
SBC 203  
SCF 204, 205  
SRA 207  
SRL 207  
SRP 205  
STOP 205  
SUB 203  
SUBX 203  
SWAP 207  
TCM 204  
TCMX 204  
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