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Understanding [Embedded - CPLDs \(Complex Programmable Logic Devices\)](#)

Embedded - CPLDs, or Complex Programmable Logic Devices, are highly versatile digital logic devices used in electronic systems. These programmable components are designed to perform complex logical operations and can be customized for specific applications. Unlike fixed-function ICs, CPLDs offer the flexibility to reprogram their configuration, making them an ideal choice for various embedded systems. They consist of a set of logic gates and programmable interconnects, allowing designers to implement complex logic circuits without needing custom hardware.

Applications of Embedded - CPLDs

Details

| | |
|---------------------------------|---|
| Product Status | Obsolete |
| Programmable Type | EE PLD |
| Delay Time tpd(1) Max | 7.5 ns |
| Voltage Supply - Internal | 4.75V ~ 5.25V |
| Number of Logic Elements/Blocks | 4 |
| Number of Macrocells | 64 |
| Number of Gates | 1250 |
| Number of I/O | 68 |
| Operating Temperature | 0°C ~ 70°C (TA) |
| Mounting Type | Surface Mount |
| Package / Case | 84-LCC (J-Lead) |
| Supplier Device Package | 84-PLCC (29.31x29.31) |
| Purchase URL | https://www.e-xfl.com/product-detail/intel/epm7064lc84-7yy |

Each programmable register can be clocked in three different modes:

- By a global clock signal. This mode achieves the fastest clock-to-output performance.
- By a global clock signal and enabled by an active-high clock enable. This mode provides an enable on each flipflop while still achieving the fast clock-to-output performance of the global clock.
- By an array clock implemented with a product term. In this mode, the flipflop can be clocked by signals from buried macrocells or I/O pins.

In EPM7032, EPM7064, and EPM7096 devices, the global clock signal is available from a dedicated clock pin, GCLK1, as shown in [Figure 1](#). In MAX 7000E and MAX 7000S devices, two global clock signals are available. As shown in [Figure 2](#), these global clock signals can be the true or the complement of either of the global clock pins, GCLK1 or GCLK2.

Each register also supports asynchronous preset and clear functions. As shown in [Figures 3 and 4](#), the product-term select matrix allocates product terms to control these operations. Although the product-term-driven preset and clear of the register are active high, active-low control can be obtained by inverting the signal within the logic array. In addition, each register clear function can be individually driven by the active-low dedicated global clear pin (GCLRn). Upon power-up, each register in the device will be set to a low state.

All MAX 7000E and MAX 7000S I/O pins have a fast input path to a macrocell register. This dedicated path allows a signal to bypass the PIA and combinatorial logic and be driven to an input D flipflop with an extremely fast (2.5 ns) input setup time.

Expander Product Terms

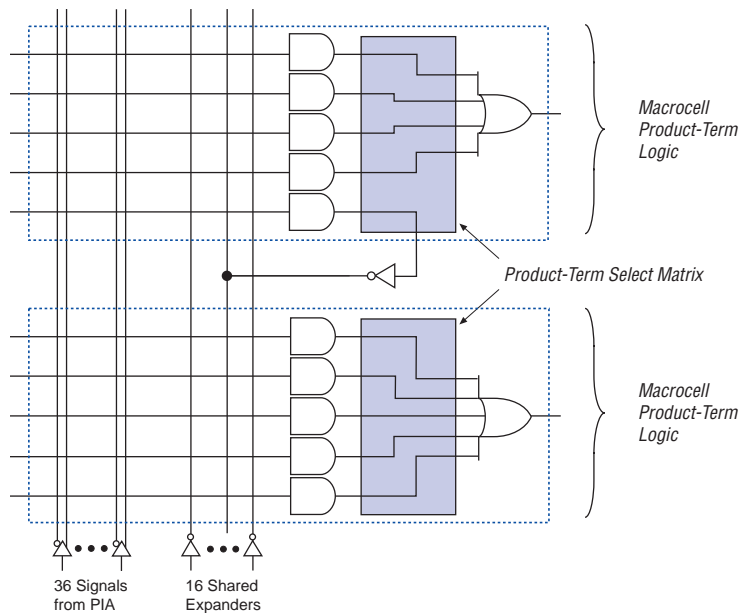
Although most logic functions can be implemented with the five product terms available in each macrocell, the more complex logic functions require additional product terms. Another macrocell can be used to supply the required logic resources; however, the MAX 7000 architecture also allows both shareable and parallel expander product terms (“expanders”) that provide additional product terms directly to any macrocell in the same LAB. These expanders help ensure that logic is synthesized with the fewest possible logic resources to obtain the fastest possible speed.

Shareable Expanders

Each LAB has 16 shareable expanders that can be viewed as a pool of uncommitted single product terms (one from each macrocell) with inverted outputs that feed back into the logic array. Each shareable expander can be used and shared by any or all macrocells in the LAB to build complex logic functions. A small delay (t_{SEXP}) is incurred when shareable expanders are used. Figure 5 shows how shareable expanders can feed multiple macrocells.

Figure 5. Shareable Expanders

Shareable expanders can be shared by any or all macrocells in an LAB.



Parallel Expanders

Parallel expanders are unused product terms that can be allocated to a neighboring macrocell to implement fast, complex logic functions. Parallel expanders allow up to 20 product terms to directly feed the macrocell OR logic, with five product terms provided by the macrocell and 15 parallel expanders provided by neighboring macrocells in the LAB.



For more information on using the Jam language, refer to *AN 122: Using Jam STAPL for ISP & ICR via an Embedded Processor*.

The ISP circuitry in MAX 7000S devices is compatible with IEEE Std. 1532 specification. The IEEE Std. 1532 is a standard developed to allow concurrent ISP between multiple PLD vendors.

Programming Sequence

During in-system programming, instructions, addresses, and data are shifted into the MAX 7000S device through the TDI input pin. Data is shifted out through the TDO output pin and compared against the expected data.

Programming a pattern into the device requires the following six ISP stages. A stand-alone verification of a programmed pattern involves only stages 1, 2, 5, and 6.

1. *Enter ISP.* The enter ISP stage ensures that the I/O pins transition smoothly from user mode to ISP mode. The enter ISP stage requires 1 ms.
2. *Check ID.* Before any program or verify process, the silicon ID is checked. The time required to read this silicon ID is relatively small compared to the overall programming time.
3. *Bulk Erase.* Erasing the device in-system involves shifting in the instructions to erase the device and applying one erase pulse of 100 ms.
4. *Program.* Programming the device in-system involves shifting in the address and data and then applying the programming pulse to program the EEPROM cells. This process is repeated for each EEPROM address.
5. *Verify.* Verifying an Altera device in-system involves shifting in addresses, applying the read pulse to verify the EEPROM cells, and shifting out the data for comparison. This process is repeated for each EEPROM address.
6. *Exit ISP.* An exit ISP stage ensures that the I/O pins transition smoothly from ISP mode to user mode. The exit ISP stage requires 1 ms.

The programming times described in [Tables 6 through 8](#) are associated with the worst-case method using the enhanced ISP algorithm.

Table 6. MAX 7000S t_{PULSE} & $Cycle_{TCK}$ Values

| Device | Programming | | Stand-Alone Verification | |
|----------|------------------|----------------|--------------------------|----------------|
| | t_{PPULSE} (s) | $Cycle_{PTCK}$ | t_{VPULSE} (s) | $Cycle_{VTCK}$ |
| EPM7032S | 4.02 | 342,000 | 0.03 | 200,000 |
| EPM7064S | 4.50 | 504,000 | 0.03 | 308,000 |
| EPM7128S | 5.11 | 832,000 | 0.03 | 528,000 |
| EPM7160S | 5.35 | 1,001,000 | 0.03 | 640,000 |
| EPM7192S | 5.71 | 1,192,000 | 0.03 | 764,000 |
| EPM7256S | 6.43 | 1,603,000 | 0.03 | 1,024,000 |

[Tables 7](#) and [8](#) show the in-system programming and stand alone verification times for several common test clock frequencies.

Table 7. MAX 7000S In-System Programming Times for Different Test Clock Frequencies

| Device | f_{TCK} | | | | | | | | Units |
|----------|-----------|-------|-------|-------|---------|---------|---------|--------|-------|
| | 10 MHz | 5 MHz | 2 MHz | 1 MHz | 500 kHz | 200 kHz | 100 kHz | 50 kHz | |
| EPM7032S | 4.06 | 4.09 | 4.19 | 4.36 | 4.71 | 5.73 | 7.44 | 10.86 | s |
| EPM7064S | 4.55 | 4.60 | 4.76 | 5.01 | 5.51 | 7.02 | 9.54 | 14.58 | s |
| EPM7128S | 5.19 | 5.27 | 5.52 | 5.94 | 6.77 | 9.27 | 13.43 | 21.75 | s |
| EPM7160S | 5.45 | 5.55 | 5.85 | 6.35 | 7.35 | 10.35 | 15.36 | 25.37 | s |
| EPM7192S | 5.83 | 5.95 | 6.30 | 6.90 | 8.09 | 11.67 | 17.63 | 29.55 | s |
| EPM7256S | 6.59 | 6.75 | 7.23 | 8.03 | 9.64 | 14.45 | 22.46 | 38.49 | s |

Table 8. MAX 7000S Stand-Alone Verification Times for Different Test Clock Frequencies

| Device | f_{TCK} | | | | | | | | Units |
|----------|-----------|-------|-------|-------|---------|---------|---------|--------|-------|
| | 10 MHz | 5 MHz | 2 MHz | 1 MHz | 500 kHz | 200 kHz | 100 kHz | 50 kHz | |
| EPM7032S | 0.05 | 0.07 | 0.13 | 0.23 | 0.43 | 1.03 | 2.03 | 4.03 | s |
| EPM7064S | 0.06 | 0.09 | 0.18 | 0.34 | 0.64 | 1.57 | 3.11 | 6.19 | s |
| EPM7128S | 0.08 | 0.14 | 0.29 | 0.56 | 1.09 | 2.67 | 5.31 | 10.59 | s |
| EPM7160S | 0.09 | 0.16 | 0.35 | 0.67 | 1.31 | 3.23 | 6.43 | 12.83 | s |
| EPM7192S | 0.11 | 0.18 | 0.41 | 0.79 | 1.56 | 3.85 | 7.67 | 15.31 | s |
| EPM7256S | 0.13 | 0.24 | 0.54 | 1.06 | 2.08 | 5.15 | 10.27 | 20.51 | s |

Programmable Speed/Power Control

MAX 7000 devices offer a power-saving mode that supports low-power operation across user-defined signal paths or the entire device. This feature allows total power dissipation to be reduced by 50% or more, because most logic applications require only a small fraction of all gates to operate at maximum frequency.

The designer can program each individual macrocell in a MAX 7000 device for either high-speed (i.e., with the Turbo Bit™ option turned on) or low-power (i.e., with the Turbo Bit option turned off) operation. As a result, speed-critical paths in the design can run at high speed, while the remaining paths can operate at reduced power. Macrocells that run at low power incur a nominal timing delay adder (t_{LPA}) for the t_{LAD} , t_{LAC} , t_{IC} , t_{EN} , and t_{SEXP} , t_{ACL} , and t_{CPPW} parameters.

Output Configuration

MAX 7000 device outputs can be programmed to meet a variety of system-level requirements.

MultiVolt I/O Interface

MAX 7000 devices—except 44-pin devices—support the MultiVolt I/O interface feature, which allows MAX 7000 devices to interface with systems that have differing supply voltages. The 5.0-V devices in all packages can be set for 3.3-V or 5.0-V I/O pin operation. These devices have one set of VCC pins for internal operation and input buffers (VCCINT), and another set for I/O output drivers (VCCIO).

The VCCINT pins must always be connected to a 5.0-V power supply. With a 5.0-V VCCINT level, input voltage thresholds are at TTL levels, and are therefore compatible with both 3.3-V and 5.0-V inputs.

The VCCIO pins can be connected to either a 3.3-V or a 5.0-V power supply, depending on the output requirements. When the VCCIO pins are connected to a 5.0-V supply, the output levels are compatible with 5.0-V systems. When VCCIO is connected to a 3.3-V supply, the output high is 3.3 V and is therefore compatible with 3.3-V or 5.0-V systems. Devices operating with VCCIO levels lower than 4.75 V incur a nominally greater timing delay of t_{OD2} instead of t_{OD1} .

Open-Drain Output Option (MAX 7000S Devices Only)

MAX 7000S devices provide an optional open-drain (functionally equivalent to open-collector) output for each I/O pin. This open-drain output enables the device to provide system-level control signals (e.g., interrupt and write enable signals) that can be asserted by any of several devices. It can also provide an additional wired-OR plane.

IEEE Std. 1149.1 (JTAG) Boundary-Scan Support

MAX 7000 devices support JTAG BST circuitry as specified by IEEE Std. 1149.1-1990. [Table 9](#) describes the JTAG instructions supported by the MAX 7000 family. The pin-out tables (see the Altera web site (<http://www.altera.com>) or the *Altera Digital Library* for pin-out information) show the location of the JTAG control pins for each device. If the JTAG interface is not required, the JTAG pins are available as user I/O pins.

Table 9. MAX 7000 JTAG Instructions

| JTAG Instruction | Devices | Description |
|------------------|--|---|
| SAMPLE/PRELOAD | EPM7128S EPM7160S EPM7192S EPM7256S | Allows a snapshot of signals at the device pins to be captured and examined during normal device operation, and permits an initial data pattern output at the device pins. |
| EXTEST | EPM7128S EPM7160S EPM7192S EPM7256S | Allows the external circuitry and board-level interconnections to be tested by forcing a test pattern at the output pins and capturing test results at the input pins. |
| BYPASS | EPM7032S EPM7064S EPM7128S EPM7160S EPM7192S EPM7256S | Places the 1-bit bypass register between the TDI and TDO pins, which allows the BST data to pass synchronously through a selected device to adjacent devices during normal device operation. |
| IDCODE | EPM7032S EPM7064S EPM7128S EPM7160S EPM7192S EPM7256S | Selects the IDCODE register and places it between TDI and TDO, allowing the IDCODE to be serially shifted out of TDO. |
| ISP Instructions | EPM7032S EPM7064S EPM7128S EPM7160S EPM7192S EPM7256S | These instructions are used when programming MAX 7000S devices via the JTAG ports with the MasterBlaster, ByteBlasterMV, BitBlaster download cable, or using a Jam File (.jam), Jam Byte-Code file (.jbc), or Serial Vector Format file (.svf) via an embedded processor or test equipment. |

The instruction register length of MAX 7000S devices is 10 bits. Tables 10 and 11 show the boundary-scan register length and device IDCODE information for MAX 7000S devices.

Table 10. MAX 7000S Boundary-Scan Register Length

| Device | Boundary-Scan Register Length |
|----------|-------------------------------|
| EPM7032S | 1 (1) |
| EPM7064S | 1 (1) |
| EPM7128S | 288 |
| EPM7160S | 312 |
| EPM7192S | 360 |
| EPM7256S | 480 |

Note:

- (1) This device does not support JTAG boundary-scan testing. Selecting either the EXTEST or SAMPLE/PRELOAD instruction will select the one-bit bypass register.

Table 11. 32-Bit MAX 7000 Device IDCODE Note (1)

| Device | IDCODE (32 Bits) | | | |
|----------|------------------|-----------------------|-----------------------------------|---------------|
| | Version (4 Bits) | Part Number (16 Bits) | Manufacturer's Identity (11 Bits) | 1 (1 Bit) (2) |
| EPM7032S | 0000 | 0111 0000 0011 0010 | 00001101110 | 1 |
| EPM7064S | 0000 | 0111 0000 0110 0100 | 00001101110 | 1 |
| EPM7128S | 0000 | 0111 0001 0010 1000 | 00001101110 | 1 |
| EPM7160S | 0000 | 0111 0001 0110 0000 | 00001101110 | 1 |
| EPM7192S | 0000 | 0111 0001 1001 0010 | 00001101110 | 1 |
| EPM7256S | 0000 | 0111 0010 0101 0110 | 00001101110 | 1 |

Notes:

- (1) The most significant bit (MSB) is on the left.
 (2) The least significant bit (LSB) for all JTAG IDCODEs is 1.

Operating Conditions

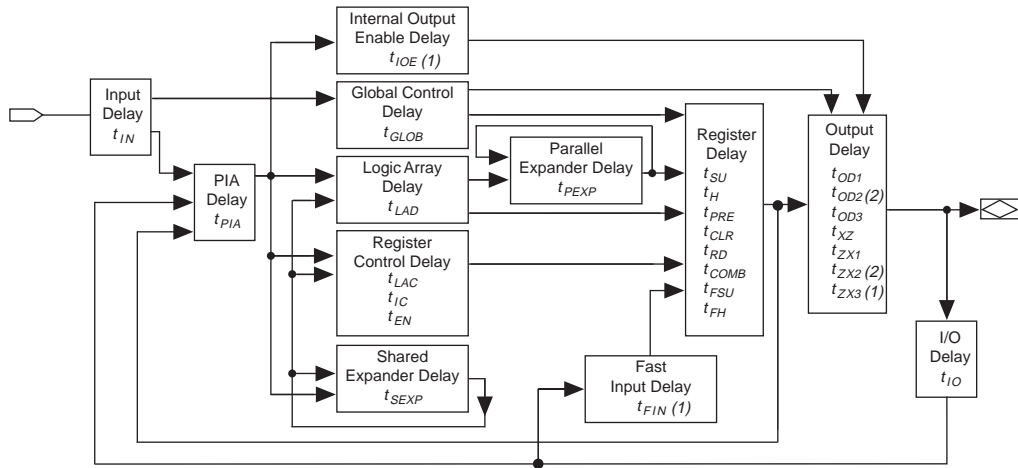
Tables 13 through 18 provide information about absolute maximum ratings, recommended operating conditions, operating conditions, and capacitance for 5.0-V MAX 7000 devices.

Table 13. MAX 7000 5.0-V Device Absolute Maximum Ratings *Note (1)*

| Symbol | Parameter | Conditions | Min | Max | Unit |
|-----------|----------------------------|------------------------------------|------|-----|------|
| V_{CC} | Supply voltage | With respect to ground (2) | –2.0 | 7.0 | V |
| V_I | DC input voltage | | –2.0 | 7.0 | V |
| I_{OUT} | DC output current, per pin | | –25 | 25 | mA |
| T_{STG} | Storage temperature | No bias | –65 | 150 | °C |
| T_{AMB} | Ambient temperature | Under bias | –65 | 135 | °C |
| T_J | Junction temperature | Ceramic packages, under bias | | 150 | °C |
| | | PQFP and RQFP packages, under bias | | 135 | °C |

Table 14. MAX 7000 5.0-V Device Recommended Operating Conditions

| Symbol | Parameter | Conditions | Min | Max | Unit |
|-------------|---|--------------------|----------------|-------------------|------|
| V_{CCINT} | Supply voltage for internal logic and input buffers | (3), (4), (5) | 4.75 (4.50) | 5.25 (5.50) | V |
| V_{CCIO} | Supply voltage for output drivers, 5.0-V operation | (3), (4) | 4.75 (4.50) | 5.25 (5.50) | V |
| | Supply voltage for output drivers, 3.3-V operation | (3), (4), (6) | 3.00 (3.00) | 3.60 (3.60) | V |
| V_{CCISP} | Supply voltage during ISP | (7) | 4.75 | 5.25 | V |
| V_I | Input voltage | | –0.5 (8) | $V_{CCINT} + 0.5$ | V |
| V_O | Output voltage | | 0 | V_{CCIO} | V |
| T_A | Ambient temperature | For commercial use | 0 | 70 | °C |
| | | For industrial use | –40 | 85 | °C |
| T_J | Junction temperature | For commercial use | 0 | 90 | °C |
| | | For industrial use | –40 | 105 | °C |
| t_R | Input rise time | | | 40 | ns |
| t_F | Input fall time | | | 40 | ns |

Figure 12. MAX 7000 Timing Model**Notes:**

- (1) Only available in MAX 7000E and MAX 7000S devices.
- (2) Not available in 44-pin devices.

The timing characteristics of any signal path can be derived from the timing model and parameters of a particular device. External timing parameters, which represent pin-to-pin timing delays, can be calculated as the sum of internal parameters. Figure 13 shows the internal timing relationship of internal and external delay parameters.



For more information, see *Application Note 94 (Understanding MAX 7000 Timing)*.

Table 24. MAX 7000 & MAX 7000E Internal Timing Parameters *Note (1)*

| Symbol | Parameter | Conditions | Speed Grade | | | | Unit |
|------------|---|------------------|------------------|------|-----------------------------------|------|------|
| | | | MAX 7000E (-12P) | | MAX 7000 (-12) MAX 7000E (-12) | | |
| | | | Min | Max | Min | Max | |
| t_{IN} | Input pad and buffer delay | | | 1.0 | | 2.0 | ns |
| t_{IO} | I/O input pad and buffer delay | | | 1.0 | | 2.0 | ns |
| t_{FIN} | Fast input delay | (2) | | 1.0 | | 1.0 | ns |
| t_{SEXP} | Shared expander delay | | | 7.0 | | 7.0 | ns |
| t_{PEXP} | Parallel expander delay | | | 1.0 | | 1.0 | ns |
| t_{LAD} | Logic array delay | | | 7.0 | | 5.0 | ns |
| t_{LAC} | Logic control array delay | | | 5.0 | | 5.0 | ns |
| t_{IOE} | Internal output enable delay | (2) | | 2.0 | | 2.0 | ns |
| t_{OD1} | Output buffer and pad delay Slow slew rate = off $V_{CCIO} = 5.0$ V | $C1 = 35$ pF | | 1.0 | | 3.0 | ns |
| t_{OD2} | Output buffer and pad delay Slow slew rate = off $V_{CCIO} = 3.3$ V | $C1 = 35$ pF (7) | | 2.0 | | 4.0 | ns |
| t_{OD3} | Output buffer and pad delay Slow slew rate = on $V_{CCIO} = 5.0$ V or 3.3 V | $C1 = 35$ pF (2) | | 5.0 | | 7.0 | ns |
| t_{ZX1} | Output buffer enable delay Slow slew rate = off $V_{CCIO} = 5.0$ V | $C1 = 35$ pF | | 6.0 | | 6.0 | ns |
| t_{ZX2} | Output buffer enable delay Slow slew rate = off $V_{CCIO} = 3.3$ V | $C1 = 35$ pF (7) | | 7.0 | | 7.0 | ns |
| t_{ZX3} | Output buffer enable delay Slow slew rate = on $V_{CCIO} = 5.0$ V or 3.3 V | $C1 = 35$ pF (2) | | 10.0 | | 10.0 | ns |
| t_{XZ} | Output buffer disable delay | $C1 = 5$ pF | | 6.0 | | 6.0 | ns |
| t_{SU} | Register setup time | | 1.0 | | 4.0 | | ns |
| t_H | Register hold time | | 6.0 | | 4.0 | | ns |
| t_{FSU} | Register setup time of fast input | (2) | 4.0 | | 2.0 | | ns |
| t_{FH} | Register hold time of fast input | (2) | 0.0 | | 2.0 | | ns |
| t_{RD} | Register delay | | | 2.0 | | 1.0 | ns |
| t_{COMB} | Combinatorial delay | | | 2.0 | | 1.0 | ns |
| t_{IC} | Array clock delay | | | 5.0 | | 5.0 | ns |
| t_{EN} | Register enable time | | | 7.0 | | 5.0 | ns |
| t_{GLOB} | Global control delay | | | 2.0 | | 0.0 | ns |
| t_{PRE} | Register preset time | | | 4.0 | | 3.0 | ns |
| t_{CLR} | Register clear time | | | 4.0 | | 3.0 | ns |
| t_{PIA} | PIA delay | | | 1.0 | | 1.0 | ns |
| t_{LPA} | Low-power adder | (8) | | 12.0 | | 12.0 | ns |

Table 26. MAX 7000 & MAX 7000E Internal Timing Parameters *Note (1)*

| Symbol | Parameter | Conditions | Speed Grade | | | | | | Unit |
|------------|---|-------------------------|-------------|------|------|------|-----|------|------|
| | | | -15 | | -15T | | -20 | | |
| | | | Min | Max | Min | Max | Min | Max | |
| t_{IN} | Input pad and buffer delay | | | 2.0 | | 2.0 | | 3.0 | ns |
| t_{IO} | I/O input pad and buffer delay | | | 2.0 | | 2.0 | | 3.0 | ns |
| t_{FIN} | Fast input delay | (2) | | 2.0 | | — | | 4.0 | ns |
| t_{SEXP} | Shared expander delay | | | 8.0 | | 10.0 | | 9.0 | ns |
| t_{PEXP} | Parallel expander delay | | | 1.0 | | 1.0 | | 2.0 | ns |
| t_{LAD} | Logic array delay | | | 6.0 | | 6.0 | | 8.0 | ns |
| t_{LAC} | Logic control array delay | | | 6.0 | | 6.0 | | 8.0 | ns |
| t_{IOE} | Internal output enable delay | (2) | | 3.0 | | — | | 4.0 | ns |
| t_{OD1} | Output buffer and pad delay Slow slew rate = off $V_{CCIO} = 5.0\text{ V}$ | $C1 = 35\text{ pF}$ | | 4.0 | | 4.0 | | 5.0 | ns |
| t_{OD2} | Output buffer and pad delay Slow slew rate = off $V_{CCIO} = 3.3\text{ V}$ | $C1 = 35\text{ pF}$ (7) | | 5.0 | | — | | 6.0 | ns |
| t_{OD3} | Output buffer and pad delay Slow slew rate = on $V_{CCIO} = 5.0\text{ V}$ or 3.3 V | $C1 = 35\text{ pF}$ (2) | | 8.0 | | — | | 9.0 | ns |
| t_{ZX1} | Output buffer enable delay Slow slew rate = off $V_{CCIO} = 5.0\text{ V}$ | $C1 = 35\text{ pF}$ | | 6.0 | | 6.0 | | 10.0 | ns |
| t_{ZX2} | Output buffer enable delay Slow slew rate = off $V_{CCIO} = 3.3\text{ V}$ | $C1 = 35\text{ pF}$ (7) | | 7.0 | | — | | 11.0 | ns |
| t_{ZX3} | Output buffer enable delay Slow slew rate = on $V_{CCIO} = 5.0\text{ V}$ or 3.3 V | $C1 = 35\text{ pF}$ (2) | | 10.0 | | — | | 14.0 | ns |
| t_{XZ} | Output buffer disable delay | $C1 = 5\text{ pF}$ | | 6.0 | | 6.0 | | 10.0 | ns |
| t_{SU} | Register setup time | | 4.0 | | 4.0 | | 4.0 | | ns |
| t_H | Register hold time | | 4.0 | | 4.0 | | 5.0 | | ns |
| t_{FSU} | Register setup time of fast input | (2) | 2.0 | | — | | 4.0 | | ns |
| t_{FH} | Register hold time of fast input | (2) | 2.0 | | — | | 3.0 | | ns |
| t_{RD} | Register delay | | | 1.0 | | 1.0 | | 1.0 | ns |
| t_{COMB} | Combinatorial delay | | | 1.0 | | 1.0 | | 1.0 | ns |
| t_{IC} | Array clock delay | | | 6.0 | | 6.0 | | 8.0 | ns |
| t_{EN} | Register enable time | | | 6.0 | | 6.0 | | 8.0 | ns |
| t_{GLOB} | Global control delay | | | 1.0 | | 1.0 | | 3.0 | ns |
| t_{PRE} | Register preset time | | | 4.0 | | 4.0 | | 4.0 | ns |
| t_{CLR} | Register clear time | | | 4.0 | | 4.0 | | 4.0 | ns |
| t_{PIA} | PIA delay | | | 2.0 | | 2.0 | | 3.0 | ns |
| t_{LPA} | Low-power adder | (8) | | 13.0 | | 15.0 | | 15.0 | ns |

Table 29. EPM7064S External Timing Parameters (Part 2 of 2) *Note (1)*

| Symbol | Parameter | Conditions | Speed Grade | | | | | | | | Unit |
|-------------------|--|----------------|-------------|-----|-------|-----|-------|-----|-------|------|------|
| | | | -5 | | -6 | | -7 | | -10 | | |
| | | | Min | Max | Min | Max | Min | Max | Min | Max | |
| t _{ACO1} | Array clock to output delay | C1 = 35 pF | | 5.4 | | 6.7 | | 7.5 | | 10.0 | ns |
| t _{ACH} | Array clock high time | | 2.5 | | 2.5 | | 3.0 | | 4.0 | | ns |
| t _{ACL} | Array clock low time | | 2.5 | | 2.5 | | 3.0 | | 4.0 | | ns |
| t _{CPPW} | Minimum pulse width for clear and preset | (2) | 2.5 | | 2.5 | | 3.0 | | 4.0 | | ns |
| t _{ODH} | Output data hold time after clock | C1 = 35 pF (3) | 1.0 | | 1.0 | | 1.0 | | 1.0 | | ns |
| t _{CNT} | Minimum global clock period | | | 5.7 | | 7.1 | | 8.0 | | 10.0 | ns |
| f _{CNT} | Maximum internal global clock frequency | (4) | 175.4 | | 140.8 | | 125.0 | | 100.0 | | MHz |
| t _{ACNT} | Minimum array clock period | | | 5.7 | | 7.1 | | 8.0 | | 10.0 | ns |
| f _{ACNT} | Maximum internal array clock frequency | (4) | 175.4 | | 140.8 | | 125.0 | | 100.0 | | MHz |
| f _{MAX} | Maximum clock frequency | (5) | 250.0 | | 200.0 | | 166.7 | | 125.0 | | MHz |

Table 30. EPM7064S Internal Timing Parameters (Part 1 of 2) *Note (1)*

| Symbol | Parameter | Conditions | Speed Grade | | | | | | | | Unit |
|------------|--------------------------------|----------------|-------------|-----|-----|-----|-----|-----|-----|-----|------|
| | | | -5 | | -6 | | -7 | | -10 | | |
| | | | Min | Max | Min | Max | Min | Max | Min | Max | |
| t_{IN} | Input pad and buffer delay | | | 0.2 | | 0.2 | | 0.5 | | 0.5 | ns |
| t_{IO} | I/O input pad and buffer delay | | | 0.2 | | 0.2 | | 0.5 | | 0.5 | ns |
| t_{FIN} | Fast input delay | | | 2.2 | | 2.6 | | 1.0 | | 1.0 | ns |
| t_{SEXP} | Shared expander delay | | | 3.1 | | 3.8 | | 4.0 | | 5.0 | ns |
| t_{PEXP} | Parallel expander delay | | | 0.9 | | 1.1 | | 0.8 | | 0.8 | ns |
| t_{LAD} | Logic array delay | | | 2.6 | | 3.2 | | 3.0 | | 5.0 | ns |
| t_{LAC} | Logic control array delay | | | 2.5 | | 3.2 | | 3.0 | | 5.0 | ns |
| t_{IOE} | Internal output enable delay | | | 0.7 | | 0.8 | | 2.0 | | 2.0 | ns |
| t_{OD1} | Output buffer and pad delay | C1 = 35 pF | | 0.2 | | 0.3 | | 2.0 | | 1.5 | ns |
| t_{OD2} | Output buffer and pad delay | C1 = 35 pF (6) | | 0.7 | | 0.8 | | 2.5 | | 2.0 | ns |
| t_{OD3} | Output buffer and pad delay | C1 = 35 pF | | 5.2 | | 5.3 | | 7.0 | | 5.5 | ns |
| t_{ZX1} | Output buffer enable delay | C1 = 35 pF | | 4.0 | | 4.0 | | 4.0 | | 5.0 | ns |
| t_{ZX2} | Output buffer enable delay | C1 = 35 pF (6) | | 4.5 | | 4.5 | | 4.5 | | 5.5 | ns |
| t_{ZX3} | Output buffer enable delay | C1 = 35 pF | | 9.0 | | 9.0 | | 9.0 | | 9.0 | ns |
| t_{XZ} | Output buffer disable delay | C1 = 5 pF | | 4.0 | | 4.0 | | 4.0 | | 5.0 | ns |
| t_{SU} | Register setup time | | 0.8 | | 1.0 | | 3.0 | | 2.0 | | ns |
| t_H | Register hold time | | 1.7 | | 2.0 | | 2.0 | | 3.0 | | ns |

Table 30. EPM7064S Internal Timing Parameters (Part 2 of 2) *Note (1)*

| Symbol | Parameter | Conditions | Speed Grade | | | | | | | | Unit |
|------------|-----------------------------------|------------|-------------|------|-----|------|-----|------|-----|------|------|
| | | | -5 | | -6 | | -7 | | -10 | | |
| | | | Min | Max | Min | Max | Min | Max | Min | Max | |
| t_{FSU} | Register setup time of fast input | | 1.9 | | 1.8 | | 3.0 | | 3.0 | | ns |
| t_{FH} | Register hold time of fast input | | 0.6 | | 0.7 | | 0.5 | | 0.5 | | ns |
| t_{RD} | Register delay | | | 1.2 | | 1.6 | | 1.0 | | 2.0 | ns |
| t_{COMB} | Combinatorial delay | | | 0.9 | | 1.0 | | 1.0 | | 2.0 | ns |
| t_{IC} | Array clock delay | | | 2.7 | | 3.3 | | 3.0 | | 5.0 | ns |
| t_{EN} | Register enable time | | | 2.6 | | 3.2 | | 3.0 | | 5.0 | ns |
| t_{GLOB} | Global control delay | | | 1.6 | | 1.9 | | 1.0 | | 1.0 | ns |
| t_{PRE} | Register preset time | | | 2.0 | | 2.4 | | 2.0 | | 3.0 | ns |
| t_{CLR} | Register clear time | | | 2.0 | | 2.4 | | 2.0 | | 3.0 | ns |
| t_{PIA} | PIA delay | (7) | | 1.1 | | 1.3 | | 1.0 | | 1.0 | ns |
| t_{LPA} | Low-power adder | (8) | | 12.0 | | 11.0 | | 10.0 | | 11.0 | ns |

Notes to tables:

- (1) These values are specified under the recommended operating conditions shown in Table 14. See Figure 13 for more information on switching waveforms.
- (2) This minimum pulse width for preset and clear applies for both global clear and array controls. The t_{LPA} parameter must be added to this minimum width if the clear or reset signal incorporates the t_{LAD} parameter into the signal path.
- (3) This parameter is a guideline that is sample-tested only and is based on extensive device characterization. This parameter applies for both global and array clocking.
- (4) These parameters are measured with a 16-bit loadable, enabled, up/down counter programmed into each LAB.
- (5) The f_{MAX} values represent the highest frequency for pipelined data.
- (6) Operating conditions: $V_{CCIO} = 3.3\text{ V} \pm 10\%$ for commercial and industrial use.
- (7) For EPM7064S-5, EPM7064S-6, EPM7128S-6, EPM7160S-6, EPM7160S-7, EPM7192S-7, and EPM7256S-7 devices, these values are specified for a PIA fan-out of one LAB (16 macrocells). For each additional LAB fan-out in these devices, add an additional 0.1 ns to the PIA timing value.
- (8) The t_{LPA} parameter must be added to the t_{LAD} , t_{LAC} , t_{IC} , t_{EN} , t_{SEXP} , t_{ACL} and t_{CPW} parameters for macrocells running in the low-power mode.

Notes to tables:

- (1) These values are specified under the recommended operating conditions shown in Table 14. See Figure 13 for more information on switching waveforms.
- (2) This minimum pulse width for preset and clear applies for both global clear and array controls. The t_{LPA} parameter must be added to this minimum width if the clear or reset signal incorporates the t_{LAD} parameter into the signal path.
- (3) This parameter is a guideline that is sample-tested only and is based on extensive device characterization. This parameter applies for both global and array clocking.
- (4) These parameters are measured with a 16-bit loadable, enabled, up/down counter programmed into each LAB.
- (5) The f_{MAX} values represent the highest frequency for pipelined data.
- (6) Operating conditions: $V_{CCIO} = 3.3 \text{ V} \pm 10\%$ for commercial and industrial use.
- (7) For EPM7064S-5, EPM7064S-6, EPM7128S-6, EPM7160S-6, EPM7160S-7, EPM7192S-7, and EPM7256S-7 devices, these values are specified for a PIA fan-out of one LAB (16 macrocells). For each additional LAB fan-out in these devices, add an additional 0.1 ns to the PIA timing value.
- (8) The t_{LPA} parameter must be added to the t_{LAD} , t_{LAC} , t_{IC} , t_{EN} , t_{SEXP} , t_{ACL} , and t_{CPPW} parameters for macrocells running in the low-power mode.

Tables 33 and 34 show the EPM7160S AC operating conditions.

Table 33. EPM7160S External Timing Parameters (Part 1 of 2) *Note (1)*

| Symbol | Parameter | Conditions | Speed Grade | | | | | | | | Unit |
|-------------------|--|----------------|-------------|-----|-------|-----|-------|------|------|------|------|
| | | | -6 | | -7 | | -10 | | -15 | | |
| | | | Min | Max | Min | Max | Min | Max | Min | Max | |
| t _{PD1} | Input to non-registered output | C1 = 35 pF | | 6.0 | | 7.5 | | 10.0 | | 15.0 | ns |
| t _{PD2} | I/O input to non-registered output | C1 = 35 pF | | 6.0 | | 7.5 | | 10.0 | | 15.0 | ns |
| t _{SU} | Global clock setup time | | 3.4 | | 4.2 | | 7.0 | | 11.0 | | ns |
| t _H | Global clock hold time | | 0.0 | | 0.0 | | 0.0 | | 0.0 | | ns |
| t _{FSU} | Global clock setup time of fast input | | 2.5 | | 3.0 | | 3.0 | | 3.0 | | ns |
| t _{FH} | Global clock hold time of fast input | | 0.0 | | 0.0 | | 0.5 | | 0.0 | | ns |
| t _{CO1} | Global clock to output delay | C1 = 35 pF | | 3.9 | | 4.8 | | 5 | | 8 | ns |
| t _{CH} | Global clock high time | | 3.0 | | 3.0 | | 4.0 | | 5.0 | | ns |
| t _{CL} | Global clock low time | | 3.0 | | 3.0 | | 4.0 | | 5.0 | | ns |
| t _{ASU} | Array clock setup time | | 0.9 | | 1.1 | | 2.0 | | 4.0 | | ns |
| t _{AH} | Array clock hold time | | 1.7 | | 2.1 | | 3.0 | | 4.0 | | ns |
| t _{ACO1} | Array clock to output delay | C1 = 35 pF | | 6.4 | | 7.9 | | 10.0 | | 15.0 | ns |
| t _{ACH} | Array clock high time | | 3.0 | | 3.0 | | 4.0 | | 6.0 | | ns |
| t _{ACL} | Array clock low time | | 3.0 | | 3.0 | | 4.0 | | 6.0 | | ns |
| t _{CPPW} | Minimum pulse width for clear and preset | (2) | 2.5 | | 3.0 | | 4.0 | | 6.0 | | ns |
| t _{ODH} | Output data hold time after clock | C1 = 35 pF (3) | 1.0 | | 1.0 | | 1.0 | | 1.0 | | ns |
| t _{CNT} | Minimum global clock period | | | 6.7 | | 8.2 | | 10.0 | | 13.0 | ns |
| f _{CNT} | Maximum internal global clock frequency | (4) | 149.3 | | 122.0 | | 100.0 | | 76.9 | | MHz |

Table 34. EPM7160S Internal Timing Parameters (Part 2 of 2) *Note (1)*

| Symbol | Parameter | Conditions | Speed Grade | | | | | | | | Unit |
|-----------|---------------------|------------|-------------|------|-----|------|-----|------|-----|------|------|
| | | | -6 | | -7 | | -10 | | -15 | | |
| | | | Min | Max | Min | Max | Min | Max | Min | Max | |
| t_{CLR} | Register clear time | | | 2.4 | | 3.0 | | 3.0 | | 4.0 | ns |
| t_{PIA} | PIA delay | (7) | | 1.6 | | 2.0 | | 1.0 | | 2.0 | ns |
| t_{LPA} | Low-power adder | (8) | | 11.0 | | 10.0 | | 11.0 | | 13.0 | ns |

Notes to tables:

- (1) These values are specified under the recommended operating conditions shown in Table 14. See Figure 13 for more information on switching waveforms.
- (2) This minimum pulse width for preset and clear applies for both global clear and array controls. The t_{LPA} parameter must be added to this minimum width if the clear or reset signal incorporates the t_{LAD} parameter into the signal path.
- (3) This parameter is a guideline that is sample-tested only and is based on extensive device characterization. This parameter applies for both global and array clocking.
- (4) These parameters are measured with a 16-bit loadable, enabled, up/down counter programmed into each LAB.
- (5) The f_{MAX} values represent the highest frequency for pipelined data.
- (6) Operating conditions: $V_{CCIO} = 3.3\text{ V} \pm 10\%$ for commercial and industrial use.
- (7) For EPM7064S-5, EPM7064S-6, EPM7128S-6, EPM7160S-6, EPM7160S-7, EPM7192S-7, and EPM7256S-7 devices, these values are specified for a PIA fan-out of one LAB (16 macrocells). For each additional LAB fan-out in these devices, add an additional 0.1 ns to the PIA timing value.
- (8) The t_{LPA} parameter must be added to the t_{LAD} , t_{LAC} , t_{IC} , t_{EN} , t_{SEXP} , t_{ACL} , and t_{CPPW} parameters for macrocells running in the low-power mode.

Tables 35 and 36 show the EPM7192S AC operating conditions.

Table 35. EPM7192S External Timing Parameters (Part 1 of 2) *Note (1)*

| Symbol | Parameter | Conditions | Speed Grade | | | | | | Unit |
|------------------|---------------------------------------|------------|-------------|-----|-----|------|------|------|------|
| | | | -7 | | -10 | | -15 | | |
| | | | Min | Max | Min | Max | Min | Max | |
| t _{PD1} | Input to non-registered output | C1 = 35 pF | | 7.5 | | 10.0 | | 15.0 | ns |
| t _{PD2} | I/O input to non-registered output | C1 = 35 pF | | 7.5 | | 10.0 | | 15.0 | ns |
| t _{SU} | Global clock setup time | | 4.1 | | 7.0 | | 11.0 | | ns |
| t _H | Global clock hold time | | 0.0 | | 0.0 | | 0.0 | | ns |
| t _{FSU} | Global clock setup time of fast input | | 3.0 | | 3.0 | | 3.0 | | ns |
| t _{FH} | Global clock hold time of fast input | | 0.0 | | 0.5 | | 0.0 | | ns |
| t _{CO1} | Global clock to output delay | C1 = 35 pF | | 4.7 | | 5.0 | | 8.0 | ns |
| t _{CH} | Global clock high time | | 3.0 | | 4.0 | | 5.0 | | ns |
| t _{CL} | Global clock low time | | 3.0 | | 4.0 | | 5.0 | | ns |
| t _{ASU} | Array clock setup time | | 1.0 | | 2.0 | | 4.0 | | ns |

Tables 37 and 38 show the EPM7256S AC operating conditions.

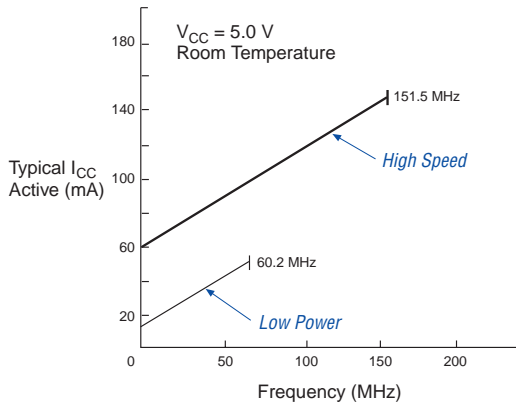
Table 37. EPM7256S External Timing Parameters *Note (1)*

| Symbol | Parameter | Conditions | Speed Grade | | | | | | Unit |
|-------------------|--|----------------|-------------|-----|-------|------|-------|------|------|
| | | | -7 | | -10 | | -15 | | |
| | | | Min | Max | Min | Max | Min | Max | |
| t _{PD1} | Input to non-registered output | C1 = 35 pF | | 7.5 | | 10.0 | | 15.0 | ns |
| t _{PD2} | I/O input to non-registered output | C1 = 35 pF | | 7.5 | | 10.0 | | 15.0 | ns |
| t _{SU} | Global clock setup time | | 3.9 | | 7.0 | | 11.0 | | ns |
| t _H | Global clock hold time | | 0.0 | | 0.0 | | 0.0 | | ns |
| t _{FSU} | Global clock setup time of fast input | | 3.0 | | 3.0 | | 3.0 | | ns |
| t _{FH} | Global clock hold time of fast input | | 0.0 | | 0.5 | | 0.0 | | ns |
| t _{CO1} | Global clock to output delay | C1 = 35 pF | | 4.7 | | 5.0 | | 8.0 | ns |
| t _{CH} | Global clock high time | | 3.0 | | 4.0 | | 5.0 | | ns |
| t _{CL} | Global clock low time | | 3.0 | | 4.0 | | 5.0 | | ns |
| t _{ASU} | Array clock setup time | | 0.8 | | 2.0 | | 4.0 | | ns |
| t _{AH} | Array clock hold time | | 1.9 | | 3.0 | | 4.0 | | ns |
| t _{ACO1} | Array clock to output delay | C1 = 35 pF | | 7.8 | | 10.0 | | 15.0 | ns |
| t _{ACH} | Array clock high time | | 3.0 | | 4.0 | | 6.0 | | ns |
| t _{ACL} | Array clock low time | | 3.0 | | 4.0 | | 6.0 | | ns |
| t _{CPPW} | Minimum pulse width for clear and preset | (2) | 3.0 | | 4.0 | | 6.0 | | ns |
| t _{ODH} | Output data hold time after clock | C1 = 35 pF (3) | 1.0 | | 1.0 | | 1.0 | | ns |
| t _{CNT} | Minimum global clock period | | | 7.8 | | 10.0 | | 13.0 | ns |
| f _{CNT} | Maximum internal global clock frequency | (4) | 128.2 | | 100.0 | | 76.9 | | MHz |
| t _{ACNT} | Minimum array clock period | | | 7.8 | | 10.0 | | 13.0 | ns |
| f _{ACNT} | Maximum internal array clock frequency | (4) | 128.2 | | 100.0 | | 76.9 | | MHz |
| f _{MAX} | Maximum clock frequency | (5) | 166.7 | | 125.0 | | 100.0 | | MHz |

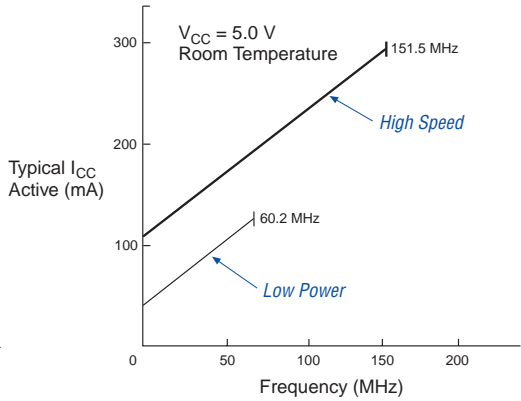
Figure 14 shows typical supply current versus frequency for MAX 7000 devices.

Figure 14. I_{CC} vs. Frequency for MAX 7000 Devices (Part 1 of 2)

EPM7032



EPM7064



EPM7096

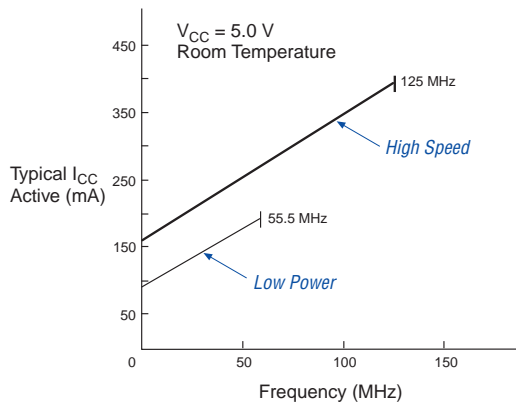
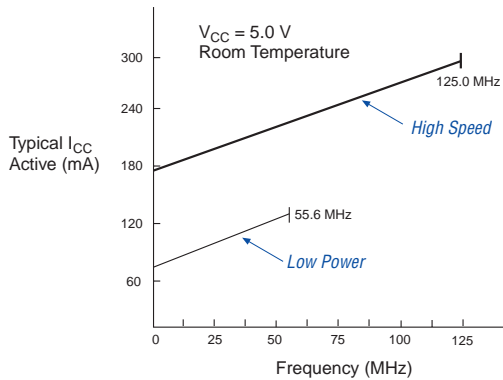
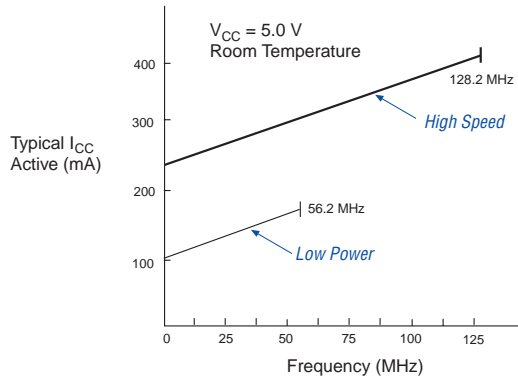


Figure 15. I_{CC} vs. Frequency for MAX 7000S Devices (Part 2 of 2)

EPM7192S



EPM7256S



Device Pin-Outs

See the Altera web site (<http://www.altera.com>) or the *Altera Digital Library* for pin-out information.

Figure 19. 100-Pin Package Pin-Out Diagram

Package outline not drawn to scale.

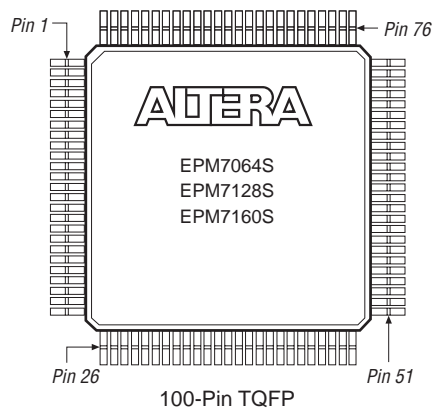
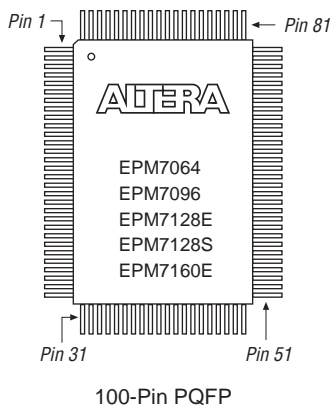
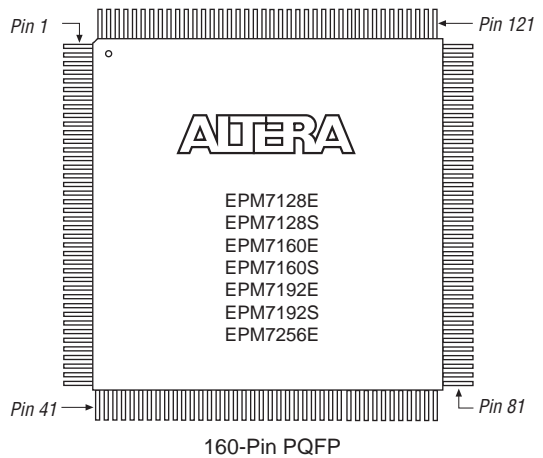
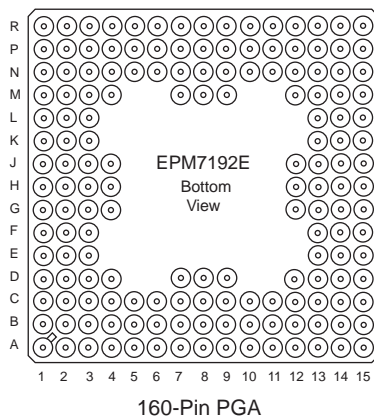


Figure 20. 160-Pin Package Pin-Out Diagram

Package outline not drawn to scale.





Notes: