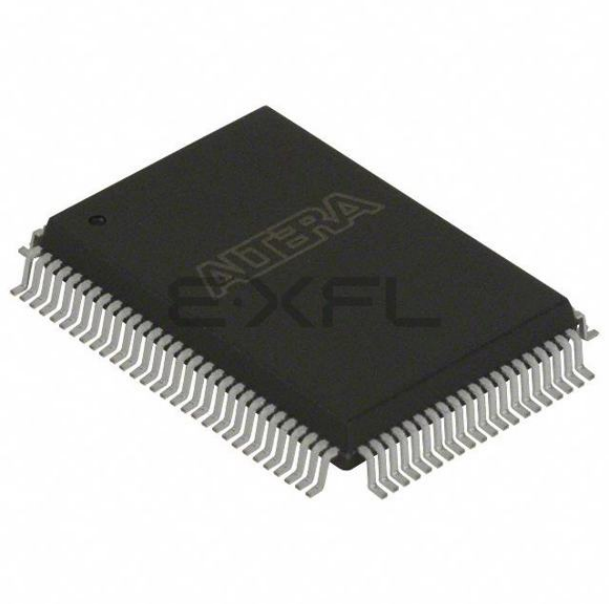

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Understanding Embedded - CPLDs (Complex Programmable Logic Devices)

Embedded - CPLDs, or Complex Programmable Logic Devices, are highly versatile digital logic devices used in electronic systems. These programmable components are designed to perform complex logical operations and can be customized for specific applications. Unlike fixed-function ICs, CPLDs offer the flexibility to reprogram their configuration, making them an ideal choice for various embedded systems. They consist of a set of logic gates and programmable interconnects, allowing designers to implement complex logic circuits without needing custom hardware.

Applications of Embedded - CPLDs

Details	
Product Status	Obsolete
Programmable Type	EE PLD
Delay Time tpd(1) Max	15 ns
Voltage Supply - Internal	4.5V ~ 5.5V
Number of Logic Elements/Blocks	4
Number of Macrocells	64
Number of Gates	1250
Number of I/O	68
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	100-BQFP
Supplier Device Package	100-PQFP (20x14)
Purchase URL	https://www.e-xfl.com/product-detail/intel/epm7064qi100-15

The MAX 7000E devices—including the EPM7128E, EPM7160E, EPM7192E, and EPM7256E devices—have several enhanced features: additional global clocking, additional output enable controls, enhanced interconnect resources, fast input registers, and a programmable slew rate.

In-system programmable MAX 7000 devices—called MAX 7000S devices—include the EPM7032S, EPM7064S, EPM7128S, EPM7160S, EPM7192S, and EPM7256S devices. MAX 7000S devices have the enhanced features of MAX 7000E devices as well as JTAG BST circuitry in devices with 128 or more macrocells, ISP, and an open-drain output option. See Table 4.

Table 4. MAX 7000 Device Features

Feature	EPM7032 EPM7064 EPM7096	All MAX 7000E Devices	All MAX 7000S Devices
ISP via JTAG interface			✓
JTAG BST circuitry			✓ *(1)*
Open-drain output option			✓
Fast input registers		✓	✓
Six global output enables		✓	✓
Two global clocks		✓	✓
Slew-rate control		✓	✓
MultiVolt interface *(2)*	✓	✓	✓
Programmable register	✓	✓	✓
Parallel expanders	✓	✓	✓
Shared expanders	✓	✓	✓
Power-saving mode	✓	✓	✓
Security bit	✓	✓	✓
PCI-compliant devices available	✓	✓	✓

Notes:

(1) Available only in EPM7128S, EPM7160S, EPM7192S, and EPM7256S devices only.

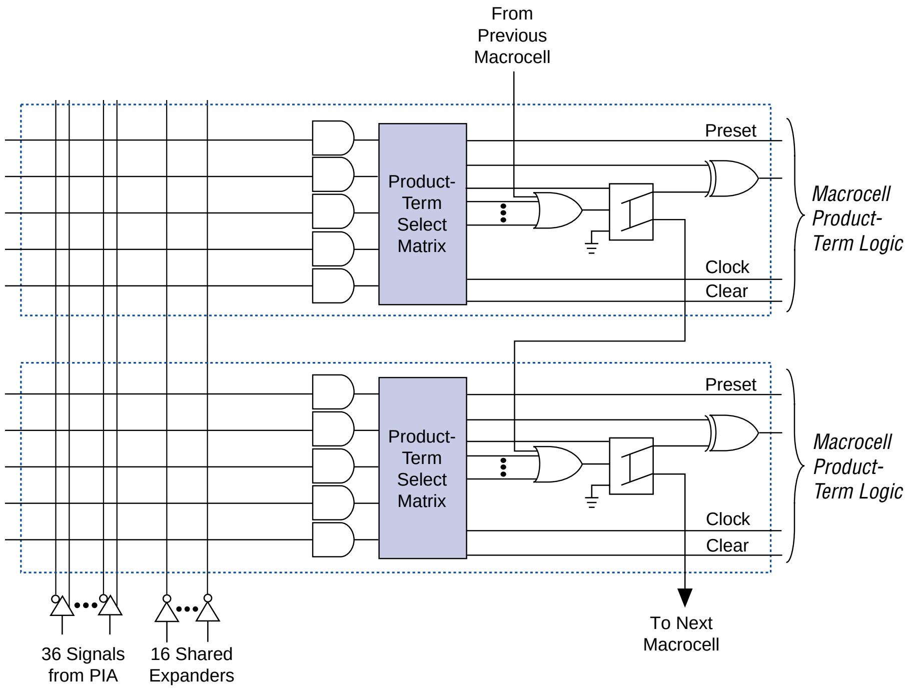
(2) The MultiVolt I/O interface is not available in 44-pin packages.

The compiler can allocate up to three sets of up to five parallel expanders automatically to the macrocells that require additional product terms. Each set of five parallel expanders incurs a small, incremental timing delay (t_{PEXP}). For example, if a macrocell requires 14 product terms, the Compiler uses the five dedicated product terms within the macrocell and allocates two sets of parallel expanders; the first set includes five product terms and the second set includes four product terms, increasing the total delay by $2 \times t_{PEXP}$.

Two groups of 8 macrocells within each LAB (e.g., macrocells 1 through 8 and 9 through 16) form two chains to lend or borrow parallel expanders. A macrocell borrows parallel expanders from lower-numbered macrocells. For example, macrocell 8 can borrow parallel expanders from macrocell 7, from macrocells 7 and 6, or from macrocells 7, 6, and 5. Within each group of 8, the lowest-numbered macrocell can only lend parallel expanders and the highest-numbered macrocell can only borrow them. Figure 6 shows how parallel expanders can be borrowed from a neighboring macrocell.

Figure 6. Parallel Expanders

Unused product terms in a macrocell can be allocated to a neighboring macrocell.



When the tri-state buffer control is connected to ground, the output is tri-stated (high impedance) and the I/O pin can be used as a dedicated input. When the tri-state buffer control is connected to V_{CC}, the output is enabled.

The MAX 7000 architecture provides dual I/O feedback, in which macrocell and pin feedbacks are independent. When an I/O pin is configured as an input, the associated macrocell can be used for buried logic.

In-System Programmability (ISP)

MAX 7000S devices are in-system programmable via an industry-standard 4-pin Joint Test Action Group (JTAG) interface (IEEE Std. 1149.1-1990). ISP allows quick, efficient iterations during design development and debugging cycles. The MAX 7000S architecture internally generates the high programming voltage required to program EEPROM cells, allowing in-system programming with only a single 5.0 V power supply. During in-system programming, the I/O pins are tri-stated and pulled-up to eliminate board conflicts. The pull-up value is nominally 50 k¾.

ISP simplifies the manufacturing flow by allowing devices to be mounted on a printed circuit board with standard in-circuit test equipment before they are programmed. MAX 7000S devices can be programmed by downloading the information via in-circuit testers (ICT), embedded processors, or the Altera MasterBlaster, ByteBlasterMV, ByteBlaster, BitBlaster download cables. (The ByteBlaster cable is obsolete and is replaced by the ByteBlasterMV cable, which can program and configure 2.5-V, 3.3-V, and 5.0-V devices.) Programming the devices after they are placed on the board eliminates lead damage on high-pin-count packages (e.g., QFP packages) due to device handling and allows devices to be reprogrammed after a system has already shipped to the field. For example, product upgrades can be performed in the field via software or modem.

In-system programming can be accomplished with either an adaptive or constant algorithm. An adaptive algorithm reads information from the unit and adapts subsequent programming steps to achieve the fastest possible programming time for that unit. Because some in-circuit testers cannot support an adaptive algorithm, Altera offers devices tested with a constant algorithm. Devices tested to the constant algorithm have an "F" suffix in the ordering code.

The Jam™ Standard Test and Programming Language (STAPL) can be used to program MAX 7000S devices with in-circuit testers, PCs, or embedded processor.

For more information on using the Jam language, refer to *AN 122: Using Jam STAPL for ISP & ICR via an Embedded Processor*.

The ISP circuitry in MAX 7000S devices is compatible with IEEE Std. 1532 specification. The IEEE Std. 1532 is a standard developed to allow concurrent ISP between multiple PLD vendors.

Programming Sequence

During in-system programming, instructions, addresses, and data are shifted into the MAX 7000S device through the `TDI` input pin. Data is shifted out through the `TDO` output pin and compared against the expected data.

Programming a pattern into the device requires the following six ISP stages. A stand-alone verification of a programmed pattern involves only stages 1, 2, 5, and 6.

1. *Enter ISP*. The enter ISP stage ensures that the I/O pins transition smoothly from user mode to ISP mode. The enter ISP stage requires 1 ms.

2. *Check ID*. Before any program or verify process, the silicon ID is checked. The time required to read this silicon ID is relatively small compared to the overall programming time.

3. *Bulk Erase*. Erasing the device in-system involves shifting in the instructions to erase the device and applying one erase pulse of 100 ms.

4. *Program*. Programming the device in-system involves shifting in the address and data and then applying the programming pulse to program the EEPROM cells. This process is repeated for each EEPROM address.

5. *Verify*. Verifying an Altera device in-system involves shifting in addresses, applying the read pulse to verify the EEPROM cells, and shifting out the data for comparison. This process is repeated for each EEPROM address.

6. *Exit ISP*. An exit ISP stage ensures that the I/O pins transition smoothly from ISP mode to user mode. The exit ISP stage requires 1 ms.

Programming Times

The time required to implement each of the six programming stages can be broken into the following two elements:

- A pulse time to erase, program, or read the EEPROM cells.
- A shifting time based on the test clock (TCK) frequency and the number of TCK cycles to shift instructions, address, and data into the device.

By combining the pulse and shift times for each of the programming stages, the program or verify time can be derived as a function of the TCK frequency, the number of devices, and specific target device(s). Because different ISP-capable devices have a different number of EEPROM cells, both the total fixed and total variable times are unique for a single device.

Programming a Single MAX 7000S Device

The time required to program a single MAX 7000S device in-system can be calculated from the following formula:

$$t_{PROG} = t_{PPULSE} + \frac{Cycle_{PTCK}}{f_{TCK}}$$

where: t_{PROG} = Programming time
t_{PPULSE} = Sum of the fixed times to erase, program, and verify the EEPROM cells
$Cycle_{PTCK}$ = Number of TCK cycles to program a device
f_{TCK} = TCK frequency

The ISP times for a stand-alone verification of a single MAX 7000S device can be calculated from the following formula:

$$t_{VER} = t_{VPULSE} + \frac{Cycle_{VTCK}}{f_{TCK}}$$

where: t_{VER} = Verify time
t_{VPULSE} = Sum of the fixed times to verify the EEPROM cells
$Cycle_{VTCK}$ = Number of TCK cycles to verify a device

By using an external 5.0-V pull-up resistor, output pins on MAX 7000S devices can be set to meet 5.0-V CMOS input voltages. When V_{CCIO} is 3.3 V, setting the open drain option will turn off the output pull-up transistor, allowing the external pull-up resistor to pull the output high enough to meet 5.0-V CMOS input voltages. When V_{CCIO} is 5.0 V, setting the output drain option is not necessary because the pull-up transistor will already turn off when the pin exceeds approximately 3.8 V, allowing the external pull-up resistor to pull the output high enough to meet 5.0-V CMOS input voltages.

Slew-Rate Control

The output buffer for each MAX 7000E and MAX 7000S I/O pin has an adjustable output slew rate that can be configured for low-noise or high-speed performance. A faster slew rate provides high-speed transitions for high-performance systems. However, these fast transitions may introduce noise transients into the system. A slow slew rate reduces system noise, but adds a nominal delay of 4 to 5 ns. In MAX 7000E devices, when the Turbo Bit is turned off, the slew rate is set for low noise performance. For MAX 7000S devices, each I/O pin has an individual EEPROM bit that controls the slew rate, allowing designers to specify the slew rate on a pin-by-pin basis.

Programming with External Hardware

MAX 7000 devices can be programmed on Windows-based PCs with the Altera Logic Programmer card, the Master Programming Unit (MPU), and the appropriate device adapter. The MPU performs a continuity check to ensure adequate electrical contact between the adapter and the device.

For more information, see the *Altera Programming Hardware Data Sheet*.

The Altera development system can use text- or waveform-format test vectors created with the Text Editor or Waveform Editor to test the programmed device. For added design verification, designers can perform functional testing to compare the functional behavior of a MAX 7000 device with the results of simulation. Moreover, Data I/O, BP Microsystems, and other programming hardware manufacturers also provide programming support for Altera devices.

For more information, see the *Programming Hardware Manufacturers*.

Figure 9 shows the timing requirements for the JTAG signals.

Figure 9. MAX 7000 JTAG Waveforms

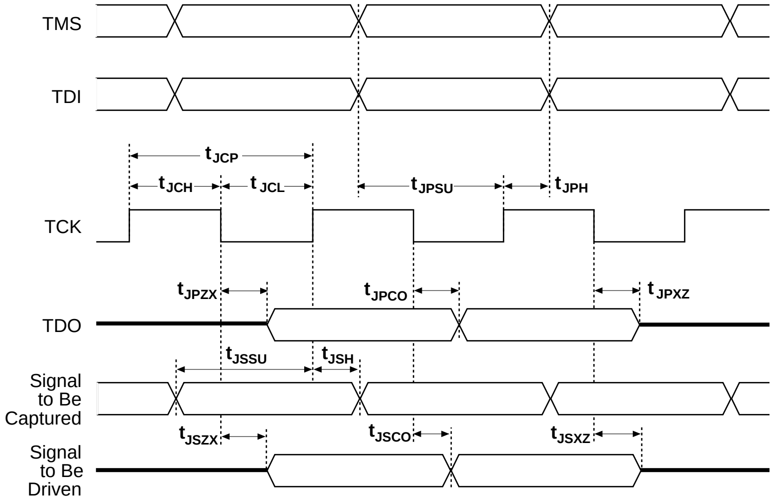


Table 12 shows the JTAG timing parameters and values for MAX 7000S devices.

Table 12. JTAG Timing Parameters & Values for MAX 7000S Devices

Symbol	Parameter	Min	Max	Unit
t_{JCP}	TCK clock period	100		ns
t_{JCH}	TCK clock high time	50		ns
t_{JCL}	TCK clock low time	50		ns
t_{JPSU}	JTAG port setup time	20		ns
t_{JPH}	JTAG port hold time	45		ns
t_{JPCO}	JTAG port clock to output		25	ns
t_{JPZX}	JTAG port high impedance to valid output		25	ns
t_{JPXZ}	JTAG port valid output to high impedance		25	ns
t_{JSSU}	Capture register setup time	20		ns
t_{JSH}	Capture register hold time	45		ns
t_{JSCO}	Update register clock to output		25	ns
t_{JSZX}	Update register high impedance to valid output		25	ns
t_{JSXZ}	Update register valid output to high impedance		25	ns

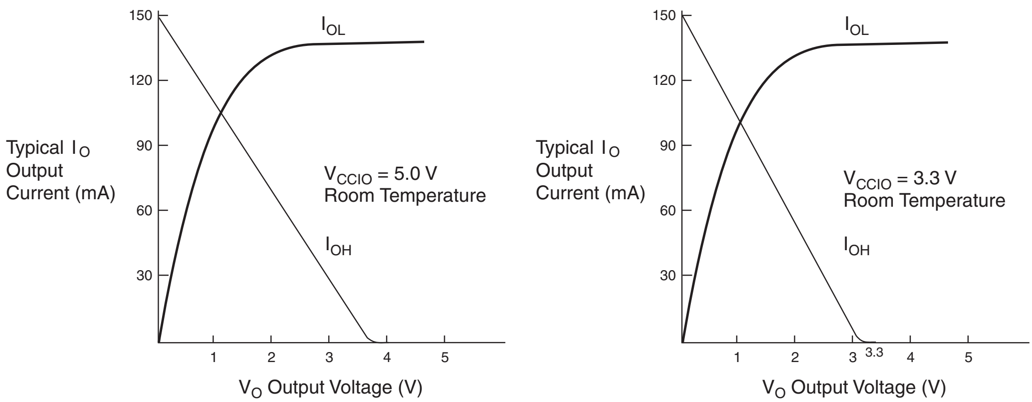
For more information, see *Application Note 39 (IEEE 1149.1 (JTAG) Boundary-Scan Testing in Altera Devices)*.

Notes to tables:

(1) See the *Operating Requirements for Altera Devices Data Sheet*.
(2) Minimum DC input voltage on I/O pins is –0.5 V and on 4 dedicated input pins is –0.3 V. During transitions, the inputs may undershoot to –2.0 V or overshoot to 7.0 V for input currents less than 100 mA and periods shorter than 20 ns.
(3) Numbers in parentheses are for industrial-temperature-range devices.
(4) V_{CC} must rise monotonically.
(5) The POR time for all 7000S devices does not exceed 300 μs. The sufficient V_{CCINT} voltage level for POR is 4.5 V. The device is fully initialized within the POR time after V_{CCINT} reaches the sufficient POR voltage level.
(6) 3.3-V I/O operation is not available for 44-pin packages.
(7) The V_{CCISP} parameter applies only to MAX 7000S devices.
(8) During in-system programming, the minimum DC input voltage is –0.3 V.
(9) These values are specified under the MAX 7000 recommended operating conditions in Table 14 on page 26.
(10) The parameter is measured with 50% of the outputs each sourcing the specified current. The I_{OH} parameter refers to high-level TTL or CMOS output current.
(11) The parameter is measured with 50% of the outputs each sinking the specified current. The I_{OL} parameter refers to low-level TTL, PCI, or CMOS output current.
(12) When the JTAG interface is enabled in MAX 7000S devices, the input leakage current on the JTAG pins is typically –60 μA.
(13) Capacitance is measured at 25° C and is sample-tested only. The `OE1` pin has a maximum capacitance of 20 pF.

Figure 11 shows the typical output drive characteristics of MAX 7000 devices.

Figure 11. Output Drive Characteristics of 5.0-V MAX 7000 Devices

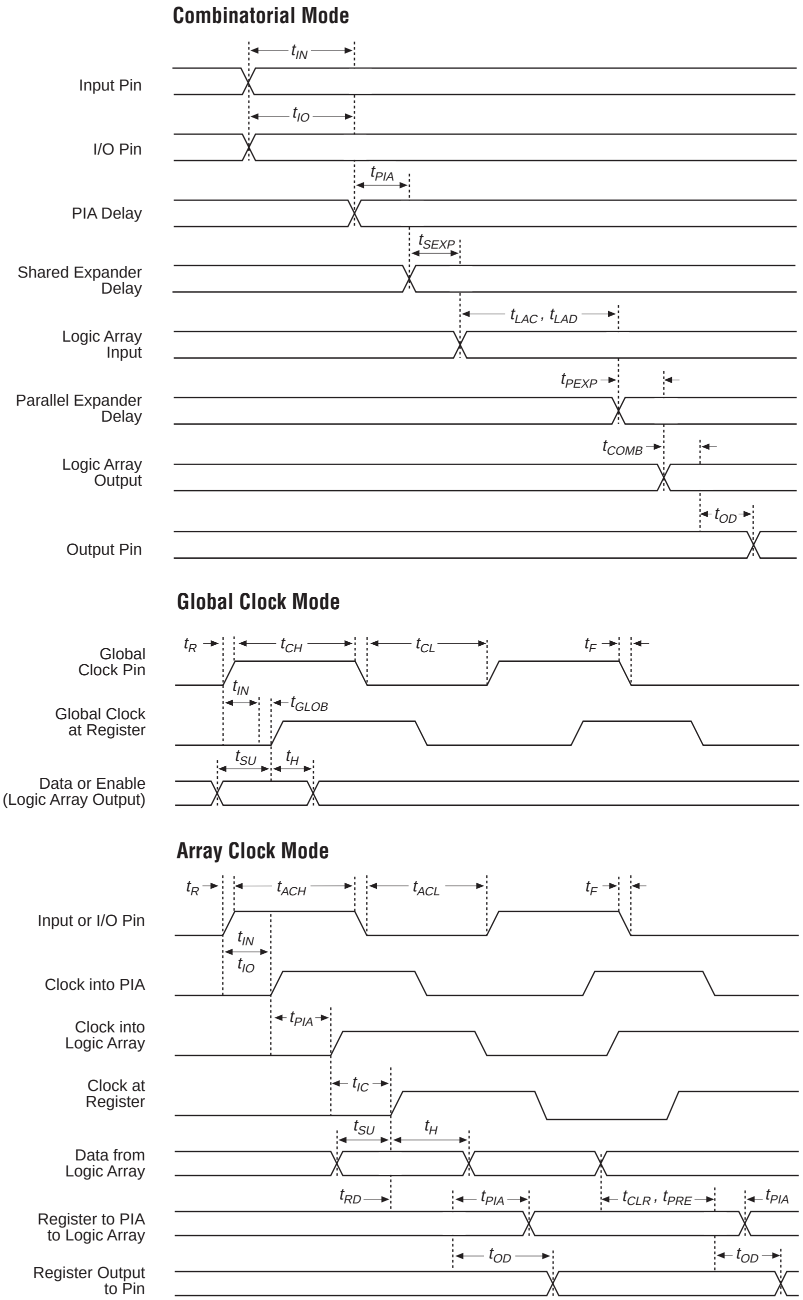


Timing Model

MAX 7000 device timing can be analyzed with the Altera software, with a variety of popular industry-standard EDA simulators and timing analyzers, or with the timing model shown in Figure 12. MAX 7000 devices have fixed internal delays that enable the designer to determine the worst-case timing of any design. The Altera software provides timing simulation, point-to-point delay prediction, and detailed timing analysis for a device-wide performance evaluation.

Figure 13. Switching Waveforms

t_R & t_F < 3 ns. Inputs are driven at 3 V for a logic high and 0 V for a logic low. All timing characteristics are measured at 1.5 V.



Tables 19 through 26 show the MAX 7000 and MAX 7000E AC operating conditions.

Table 19. MAX 7000 & MAX 7000E External Timing Parameters *Note (1)*

Symbol	Parameter	Conditions	-6 Speed Grade		-7 Speed Grade		Unit
			Min	Max	Min	Max	
t_{PD1}	Input to non-registered output	C1 = 35 pF		6.0		7.5	ns
t_{PD2}	I/O input to non-registered output	C1 = 35 pF		6.0		7.5	ns
t_{SU}	Global clock setup time		5.0		6.0		ns
t_{H}	Global clock hold time		0.0		0.0		ns
t_{FSU}	Global clock setup time of fast input	*(2)*	2.5		3.0		ns
t_{FH}	Global clock hold time of fast input	*(2)*	0.5		0.5		ns
t_{CO1}	Global clock to output delay	C1 = 35 pF		4.0		4.5	ns
t_{CH}	Global clock high time		2.5		3.0		ns
t_{CL}	Global clock low time		2.5		3.0		ns
t_{ASU}	Array clock setup time		2.5		3.0		ns
t_{AH}	Array clock hold time		2.0		2.0		ns
t_{ACO1}	Array clock to output delay	C1 = 35 pF		6.5		7.5	ns
t_{ACH}	Array clock high time		3.0		3.0		ns
t_{ACL}	Array clock low time		3.0		3.0		ns
t_{CPPW}	Minimum pulse width for clear and preset	*(3)*	3.0		3.0		ns
t_{ODH}	Output data hold time after clock	C1 = 35 pF *(4)*	1.0		1.0		ns
t_{CNT}	Minimum global clock period			6.6		8.0	ns
f_{CNT}	Maximum internal global clock frequency	*(5)*	151.5		125.0		MHz
t_{ACNT}	Minimum array clock period			6.6		8.0	ns
f_{ACNT}	Maximum internal array clock frequency	*(5)*	151.5		125.0		MHz
f_{MAX}	Maximum clock frequency	*(6)*	200		166.7		MHz

Table 22. MAX 7000 & MAX 7000E Internal Timing Parameters *Note (1)*							
Symbol	**Parameter**	**Conditions**	**Speed Grade**				**Unit**
			MAX 7000E (-10P)		**MAX 7000 (-10) MAX 7000E (-10)**		
			Min	**Max**	**Min**	**Max**	
t_{IN}	Input pad and buffer delay			0.5		1.0	ns
t_{IO}	I/O input pad and buffer delay			0.5		1.0	ns
t_{FIN}	Fast input delay	*(2)*		1.0		1.0	ns
t_{SEXP}	Shared expander delay			5.0		5.0	ns
t_{PEXP}	Parallel expander delay			0.8		0.8	ns
t_{LAD}	Logic array delay			5.0		5.0	ns
t_{LAC}	Logic control array delay			5.0		5.0	ns
t_{IOE}	Internal output enable delay	*(2)*		2.0		2.0	ns
t_{OD1}	Output buffer and pad delay Slow slew rate = off V_{CCIO} = 5.0 V	C1 = 35 pF		1.5		2.0	ns
t_{OD2}	Output buffer and pad delay Slow slew rate = off V_{CCIO} = 3.3 V	C1 = 35 pF *(7)*		2.0		2.5	ns
t_{OD3}	Output buffer and pad delay Slow slew rate = on V_{CCIO} = 5.0 V or 3.3 V	C1 = 35 pF *(2)*		5.5		6.0	ns
t_{ZX1}	Output buffer enable delay Slow slew rate = off V_{CCIO} = 5.0 V	C1 = 35 pF		5.0		5.0	ns
t_{ZX2}	Output buffer enable delay Slow slew rate = off V_{CCIO} = 3.3 V	C1 = 35 pF *(7)*		5.5		5.5	ns
t_{ZX3}	Output buffer enable delay Slow slew rate = on V_{CCIO} = 5.0 V or 3.3 V	C1 = 35 pF *(2)*		9.0		9.0	ns
t_{XZ}	Output buffer disable delay	C1 = 5 pF		5.0		5.0	ns
t_{SU}	Register setup time		2.0		3.0		ns
t_H	Register hold time		3.0		3.0		ns
t_{FSU}	Register setup time of fast input	*(2)*	3.0		3.0		ns
t_{FH}	Register hold time of fast input	*(2)*	0.5		0.5		ns
t_{RD}	Register delay			2.0		1.0	ns
t_{COMB}	Combinatorial delay			2.0		1.0	ns
t_{IC}	Array clock delay			5.0		5.0	ns
t_{EN}	Register enable time			5.0		5.0	ns
t_{GLOB}	Global control delay			1.0		1.0	ns
t_{PRE}	Register preset time			3.0		3.0	ns
t_{CLR}	Register clear time			3.0		3.0	ns
t_{PIA}	PIA delay			1.0		1.0	ns
t_{LPA}	Low-power adder	*(8)*		11.0		11.0	ns

Notes to tables:

(1) These values are specified under the recommended operating conditions shown in Table 14. See Figure 13 for more information on switching waveforms.
(2) This parameter applies to MAX 7000E devices only.
(3) This minimum pulse width for preset and clear applies for both global clear and array controls. The t_{LPA} parameter must be added to this minimum width if the clear or reset signal incorporates the t_{LAD} parameter into the signal path.
(4) This parameter is a guideline that is sample-tested only and is based on extensive device characterization. This parameter applies for both global and array clocking.
(5) These parameters are measured with a 16-bit loadable, enabled, up/down counter programmed into each LAB.
(6) The f_{MAX} values represent the highest frequency for pipelined data.
(7) Operating conditions: V_{CCIO} = 3.3 V ± 10% for commercial and industrial use.
(8) The t_{LPA} parameter must be added to the t_{LAD}, t_{LAC}, t_{IC}, t_{EN}, t_{SEXP}, t_{ACL}, and t_{CPPW} parameters for macrocells running in the low-power mode.

Tables 27 and 28 show the EPM7032S AC operating conditions.

Table 27. EPM7032S External Timing Parameters (Part 1 of 2) *Note (1)*

Symbol	Parameter	Conditions	Speed Grade								Unit
			-5		-6		-7		-10		
			Min	Max	Min	Max	Min	Max	Min	Max	
t_{PD1}	Input to non-registered output	C1 = 35 pF		5.0		6.0		7.5		10.0	ns
t_{PD2}	I/O input to non-registered output	C1 = 35 pF		5.0		6.0		7.5		10.0	ns
t_{SU}	Global clock setup time		2.9		4.0		5.0		7.0		ns
t_H	Global clock hold time		0.0		0.0		0.0		0.0		ns
t_{FSU}	Global clock setup time of fast input		2.5		2.5		2.5		3.0		ns
t_{FH}	Global clock hold time of fast input		0.0		0.0		0.0		0.5		ns
t_{CO1}	Global clock to output delay	C1 = 35 pF		3.2		3.5		4.3		5.0	ns
t_{CH}	Global clock high time		2.0		2.5		3.0		4.0		ns
t_{CL}	Global clock low time		2.0		2.5		3.0		4.0		ns
t_{ASU}	Array clock setup time		0.7		0.9		1.1		2.0		ns
t_{AH}	Array clock hold time		1.8		2.1		2.7		3.0		ns
t_{ACO1}	Array clock to output delay	C1 = 35 pF		5.4		6.6		8.2		10.0	ns
t_{ACH}	Array clock high time		2.5		2.5		3.0		4.0		ns
t_{ACL}	Array clock low time		2.5		2.5		3.0		4.0		ns
t_{CPPW}	Minimum pulse width for clear and preset	*(2)*	2.5		2.5		3.0		4.0		ns
t_{ODH}	Output data hold time after clock	C1 = 35 pF *(3)*	1.0		1.0		1.0		1.0		ns
t_{CNT}	Minimum global clock period			5.7		7.0		8.6		10.0	ns
f_{CNT}	Maximum internal global clock frequency	*(4)*	175.4		142.9		116.3		100.0		MHz
t_{ACNT}	Minimum array clock period			5.7		7.0		8.6		10.0	ns

Tables 31 and 32 show the EPM7128S AC operating conditions.

Table 31. EPM7128S External Timing Parameters *Note (1)*

Symbol	Parameter	Conditions	Speed Grade								Unit
			-6		-7		-10		-15		
			Min	Max	Min	Max	Min	Max	Min	Max	
t_{PD1}	Input to non-registered output	C1 = 35 pF		6.0		7.5		10.0		15.0	ns
t_{PD2}	I/O input to non-registered output	C1 = 35 pF		6.0		7.5		10.0		15.0	ns
t_{SU}	Global clock setup time		3.4		6.0		7.0		11.0		ns
t_H	Global clock hold time		0.0		0.0		0.0		0.0		ns
t_{FSU}	Global clock setup time of fast input		2.5		3.0		3.0		3.0		ns
t_{FH}	Global clock hold time of fast input		0.0		0.5		0.5		0.0		ns
t_{CO1}	Global clock to output delay	C1 = 35 pF		4.0		4.5		5.0		8.0	ns
t_{CH}	Global clock high time		3.0		3.0		4.0		5.0		ns
t_{CL}	Global clock low time		3.0		3.0		4.0		5.0		ns
t_{ASU}	Array clock setup time		0.9		3.0		2.0		4.0		ns
t_{AH}	Array clock hold time		1.8		2.0		5.0		4.0		ns
t_{ACO1}	Array clock to output delay	C1 = 35 pF		6.5		7.5		10.0		15.0	ns
t_{ACH}	Array clock high time		3.0		3.0		4.0		6.0		ns
t_{ACL}	Array clock low time		3.0		3.0		4.0		6.0		ns
t_{CPPW}	Minimum pulse width for clear and preset	*(2)*	3.0		3.0		4.0		6.0		ns
t_{ODH}	Output data hold time after clock	C1 = 35 pF *(3)*	1.0		1.0		1.0		1.0		ns
t_{CNT}	Minimum global clock period			6.8		8.0		10.0		13.0	ns
f_{CNT}	Maximum internal global clock frequency	*(4)*	147.1		125.0		100.0		76.9		MHz
t_{ACNT}	Minimum array clock period			6.8		8.0		10.0		13.0	ns
f_{ACNT}	Maximum internal array clock frequency	*(4)*	147.1		125.0		100.0		76.9		MHz
f_{MAX}	Maximum clock frequency	*(5)*	166.7		166.7		125.0		100.0		MHz

Table 38. EPM7256S Internal Timing Parameters *Note (1)*

Symbol	Parameter	Conditions	Speed Grade						Unit
			-7		-10		-15		
			Min	Max	Min	Max	Min	Max	
t_{IN}	Input pad and buffer delay			0.3		0.5		2.0	ns
t_{IO}	I/O input pad and buffer delay			0.3		0.5		2.0	ns
t_{FIN}	Fast input delay			3.4		1.0		2.0	ns
t_{SEXP}	Shared expander delay			3.9		5.0		8.0	ns
t_{PEXP}	Parallel expander delay			1.1		0.8		1.0	ns
t_{LAD}	Logic array delay			2.6		5.0		6.0	ns
t_{LAC}	Logic control array delay			2.6		5.0		6.0	ns
t_{IOE}	Internal output enable delay			0.8		2.0		3.0	ns
t_{OD1}	Output buffer and pad delay	C1 = 35 pF		0.5		1.5		4.0	ns
t_{OD2}	Output buffer and pad delay	C1 = 35 pF *(6)*		1.0		2.0		5.0	ns
t_{OD3}	Output buffer and pad delay	C1 = 35 pF		5.5		5.5		8.0	ns
t_{ZX1}	Output buffer enable delay	C1 = 35 pF		4.0		5.0		6.0	ns
t_{ZX2}	Output buffer enable delay	C1 = 35 pF *(6)*		4.5		5.5		7.0	ns
t_{ZX3}	Output buffer enable delay	C1 = 35 pF		9.0		9.0		10.0	ns
t_{XZ}	Output buffer disable delay	C1 = 5 pF		4.0		5.0		6.0	ns
t_{SU}	Register setup time		1.1		2.0		4.0		ns
t_{H}	Register hold time		1.6		3.0		4.0		ns
t_{FSU}	Register setup time of fast input		2.4		3.0		2.0		ns
t_{FH}	Register hold time of fast input		0.6		0.5		1.0		ns
t_{RD}	Register delay			1.1		2.0		1.0	ns
t_{COMB}	Combinatorial delay			1.1		2.0		1.0	ns
t_{IC}	Array clock delay			2.9		5.0		6.0	ns
t_{EN}	Register enable time			2.6		5.0		6.0	ns
t_{GLOB}	Global control delay			2.8		1.0		1.0	ns
t_{PRE}	Register preset time			2.7		3.0		4.0	ns
t_{CLR}	Register clear time			2.7		3.0		4.0	ns
t_{PIA}	PIA delay	*(7)*		3.0		1.0		2.0	ns
t_{LPA}	Low-power adder	*(8)*		10.0		11.0		13.0	ns

Notes to tables:

(1) These values are specified under the recommended operating conditions shown in Table 14. See Figure 13 for more information on switching waveforms.

(2) This minimum pulse width for preset and clear applies for both global clear and array controls. The t_{LPA} parameter must be added to this minimum width if the clear or reset signal incorporates the t_{LAD} parameter into the signal path.

(3) This parameter is a guideline that is sample-tested only and is based on extensive device characterization. This parameter applies for both global and array clocking.

(4) These parameters are measured with a 16-bit loadable, enabled, up/down counter programmed into each LAB.

(5) The $\mathbf{f_{MAX}}$ values represent the highest frequency for pipelined data.

(6) Operating conditions: V_{CCIO} = 3.3 V ± 10% for commercial and industrial use.

(7) For EPM7064S-5, EPM7064S-6, EPM7128S-6, EPM7160S-6, EPM7160S-7, EPM7192S-7, and EPM7256S-7 devices, these values are specified for a PIA fan-out of one LAB (16 macrocells). For each additional LAB fan-out in these devices, add an additional 0.1 ns to the PIA timing value.

(8) The t_{LPA} parameter must be added to the t_{LAD}, t_{LAC}, t_{IC}, t_{EN}, t_{SEXP}, $\mathbf{t_{ACL}}$, and $\mathbf{t_{CPPW}}$ parameters for macrocells running in the low-power mode.

Power Consumption

Supply power (P) versus frequency ($\mathbf{f_{MAX}}$ in MHz) for MAX 7000 devices is calculated with the following equation:

$$P = P_{INT} + P_{IO} = I_{CCINT} \times V_{CC} + P_{IO}$$

The P_{IO} value, which depends on the device output load characteristics and switching frequency, can be calculated using the guidelines given in *Application Note 74 (Evaluating Power for Altera Devices)*.

The I_{CCINT} value, which depends on the switching frequency and the application logic, is calculated with the following equation:

$$I_{CCINT} =$$

$$A \times MC_{TON} + B \times (MC_{DEV} - MC_{TON}) + C \times MC_{USED} \times \mathbf{f_{MAX}} \times \mathbf{tog_{LC}}$$

The parameters in this equation are shown below:

MC_{TON}	=	Number of macrocells with the Turbo Bit option turned on, as reported in the MAX+PLUS II Report File (**.rpt**)
MC_{DEV}	=	Number of macrocells in the device
MC_{USED}	=	Total number of macrocells in the design, as reported in the MAX+PLUS II Report File (**.rpt**)
$\mathbf{f_{MAX}}$	=	Highest clock frequency to the device
$\mathbf{tog_{LC}}$	=	Average ratio of logic cells toggling at each clock (typically 0.125)
A, B, C	=	Constants, shown in Table 39

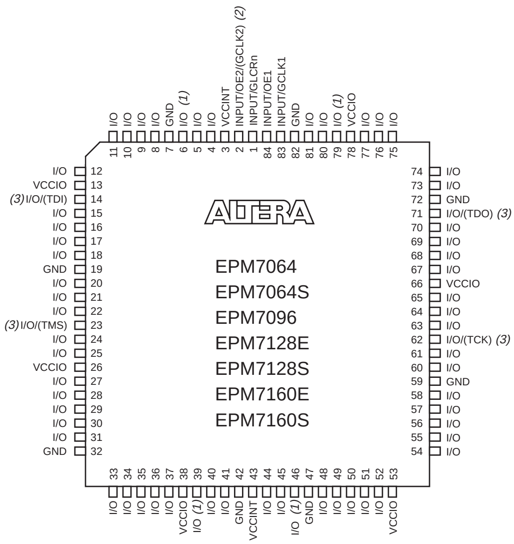
Table 39. MAX 7000 I_{CC} Equation Constants

Device	A	B	C
EPM7032	1.87	0.52	0.144
EPM7064	1.63	0.74	0.144
EPM7096	1.63	0.74	0.144
EPM7128E	1.17	0.54	0.096
EPM7160E	1.17	0.54	0.096
EPM7192E	1.17	0.54	0.096
EPM7256E	1.17	0.54	0.096
EPM7032S	0.93	0.40	0.040
EPM7064S	0.93	0.40	0.040
EPM7128S	0.93	0.40	0.040
EPM7160S	0.93	0.40	0.040
EPM7192S	0.93	0.40	0.040
EPM7256S	0.93	0.40	0.040

This calculation provides an I_{CC} estimate based on typical conditions using a pattern of a 16-bit, loadable, enabled, up/down counter in each LAB with no output load. Actual I_{CC} values should be verified during operation because this measurement is sensitive to the actual pattern in the device and the environmental operating conditions.

Figure 18. 84-Pin Package Pin-Out Diagram

Package outline not drawn to scale.



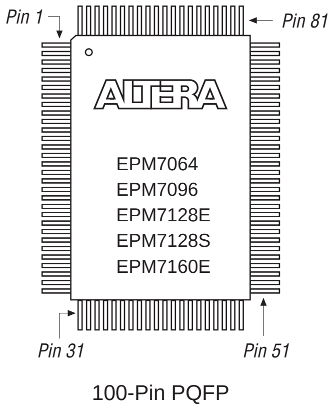
84-Pin PLCC

Notes:

(1) Pins 6, 39, 46, and 79 are no-connect (N.C.) pins on EPM7096, EPM7160E, and EPM7160S devices.
(2) The pin functions shown in parenthesis are only available in MAX 7000E and MAX 7000S devices.
(3) JTAG ports are available in MAX 7000S devices only.

Figure 19. 100-Pin Package Pin-Out Diagram

Package outline not drawn to scale.



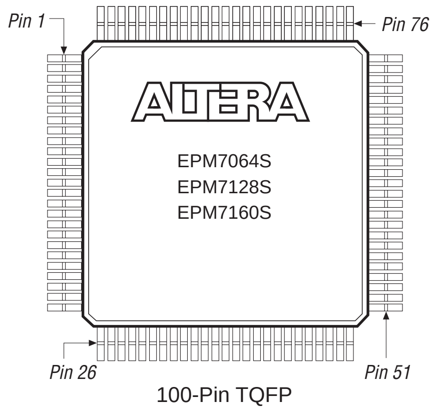
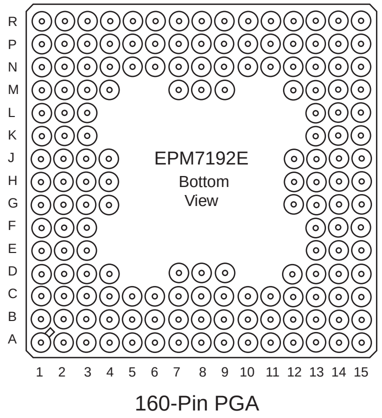
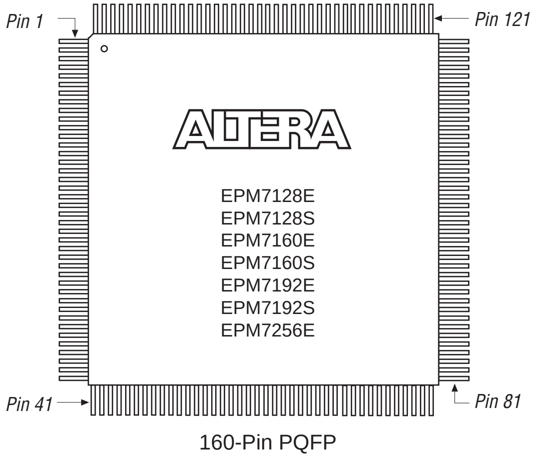


Figure 20. 160-Pin Package Pin-Out Diagram

Package outline not drawn to scale.





Revision History

The information contained in the *MAX 7000 Programmable Logic Device Family Data Sheet* version 6.7 supersedes information published in previous versions. The following changes were made in the *MAX 7000 Programmable Logic Device Family Data Sheet* version 6.7:

Version 6.7

The following changes were made in the *MAX 7000 Programmable Logic Device Family Data Sheet* version 6.7:

- Reference to *AN 88: Using the Jam Language for ISP & ICR via an Embedded Processor* has been replaced by *AN 122: Using Jam STAPL for ISP & ICR via an Embedded Processor*.

Version 6.6

The following changes were made in the *MAX 7000 Programmable Logic Device Family Data Sheet* version 6.6:

- Added Tables 6 through 8.
- Added "Programming Sequence" section on page 17 and "Programming Times" section on page 18.

Version 6.5

The following changes were made in the *MAX 7000 Programmable Logic Device Family Data Sheet* version 6.5:

- Updated text on page 16.

Version 6.4

The following changes were made in the *MAX 7000 Programmable Logic Device Family Data Sheet* version 6.4:

- Added *Note (5)* on page 28.

Version 6.3

The following changes were made in the *MAX 7000 Programmable Logic Device Family Data Sheet* version 6.3:

- Updated the "Open-Drain Output Option (MAX 7000S Devices Only)" section on page 20.

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