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### Understanding [Embedded - CPLDs \(Complex Programmable Logic Devices\)](#)

Embedded - CPLDs, or Complex Programmable Logic Devices, are highly versatile digital logic devices used in electronic systems. These programmable components are designed to perform complex logical operations and can be customized for specific applications. Unlike fixed-function ICs, CPLDs offer the flexibility to reprogram their configuration, making them an ideal choice for various embedded systems. They consist of a set of logic gates and programmable interconnects, allowing designers to implement complex logic circuits without needing custom hardware.

### Applications of Embedded - CPLDs

#### Details

|                                 |   |
|---------------------------------|---|
| Product Status                  | Obsolete  |
| Programmable Type               | In System Programmable  |
| Delay Time tpd(1) Max           | 5 ns  |
| Voltage Supply - Internal       | 4.75V ~ 5.25V   |
| Number of Logic Elements/Blocks | 4   |
| Number of Macrocells            | 64  |
| Number of Gates                 | 1250  |
| Number of I/O                   | 36  |
| Operating Temperature           | 0°C ~ 70°C (TA)   |
| Mounting Type                   | Surface Mount   |
| Package / Case                  | 44-LCC (J-Lead)   |
| Supplier Device Package         | 44-PLCC (16.59x16.59)   |
| Purchase URL                    | <a href="https://www.e-xfl.com/product-detail/intel/epm7064slc44-5">https://www.e-xfl.com/product-detail/intel/epm7064slc44-5</a> |

- Additional design entry and simulation support provided by EDIF 2.0.0 and 3.0.0 netlist files, library of parameterized modules (LPM), Verilog HDL, VHDL, and other interfaces to popular EDA tools from manufacturers such as Cadence, Exemplar Logic, Mentor Graphics, OrCAD, Synopsys, and VeriBest
- Programming support
  - Altera's Master Programming Unit (MPU) and programming hardware from third-party manufacturers program all MAX 7000 devices
  - The BitBlaster™ serial download cable, ByteBlasterMV™ parallel port download cable, and MasterBlaster™ serial/universal serial bus (USB) download cable program MAX 7000S devices

## General Description

The MAX 7000 family of high-density, high-performance PLDs is based on Altera's second-generation MAX architecture. Fabricated with advanced CMOS technology, the EEPROM-based MAX 7000 family provides 600 to 5,000 usable gates, ISP, pin-to-pin delays as fast as 5 ns, and counter speeds of up to 175.4 MHz. MAX 7000S devices in the -5, -6, -7, and -10 speed grades as well as MAX 7000 and MAX 7000E devices in -5, -6, -7, -10P, and -12P speed grades comply with the PCI Special Interest Group (PCI SIG) *PCI Local Bus Specification, Revision 2.2*. See [Table 3](#) for available speed grades.

**Table 3. MAX 7000 Speed Grades**

| Device   | Speed Grade |    |    |      |     |      |     |     |      |     |
|----------|-------------|----|----|------|-----|------|-----|-----|------|-----|
|          | -5          | -6 | -7 | -10P | -10 | -12P | -12 | -15 | -15T | -20 |
| EPM7032  |             | ✓  | ✓  |      | ✓   |      | ✓   | ✓   | ✓    |     |
| EPM7032S | ✓           | ✓  | ✓  |      | ✓   |      |     |     |      |     |
| EPM7064  |             | ✓  | ✓  |      | ✓   |      | ✓   | ✓   |      |     |
| EPM7064S | ✓           | ✓  | ✓  |      | ✓   |      |     |     |      |     |
| EPM7096  |             |    | ✓  |      | ✓   |      | ✓   | ✓   |      |     |
| EPM7128E |             |    | ✓  | ✓    | ✓   |      | ✓   | ✓   |      | ✓   |
| EPM7128S |             | ✓  | ✓  |      | ✓   |      |     | ✓   |      |     |
| EPM7160E |             |    |    | ✓    | ✓   |      | ✓   | ✓   |      | ✓   |
| EPM7160S |             | ✓  | ✓  |      | ✓   |      |     | ✓   |      |     |
| EPM7192E |             |    |    |      |     | ✓    | ✓   | ✓   |      | ✓   |
| EPM7192S |             |    | ✓  |      | ✓   |      |     | ✓   |      |     |
| EPM7256E |             |    |    |      |     | ✓    | ✓   | ✓   |      | ✓   |
| EPM7256S |             |    | ✓  |      | ✓   |      |     | ✓   |      |     |

The MAX 7000 architecture supports 100% TTL emulation and high-density integration of SSI, MSI, and LSI logic functions. The MAX 7000 architecture easily integrates multiple devices ranging from PALs, GALs, and 22V10s to MACH and pLSI devices. MAX 7000 devices are available in a wide range of packages, including PLCC, PGA, PQFP, RQFP, and TQFP packages. See [Table 5](#).

**Table 5. MAX 7000 Maximum User I/O Pins** *Note (1)*

| Device   | 44-Pin<br>PLCC | 44-Pin<br>PQFP | 44-Pin<br>TQFP | 68-Pin<br>PLCC | 84-Pin<br>PLCC | 100-Pin<br>PQFP | 100-Pin<br>TQFP | 160-Pin<br>PQFP | 160-Pin<br>PGA | 192-Pin<br>PGA | 208-Pin<br>PQFP | 208-Pin<br>RQFP |
|----------|----------------|----------------|----------------|----------------|----------------|-----------------|-----------------|-----------------|----------------|----------------|-----------------|-----------------|
| EPM7032  | 36             | 36             | 36             |                |                |                 |                 |                 |                |                |                 |                 |
| EPM7032S | 36             |                | 36             |                |                |                 |                 |                 |                |                |                 |                 |
| EPM7064  | 36             |                | 36             | 52             | 68             | 68              |                 |                 |                |                |                 |                 |
| EPM7064S | 36             |                | 36             |                | 68             |                 | 68              |                 |                |                |                 |                 |
| EPM7096  |                |                |                | 52             | 64             | 76              |                 |                 |                |                |                 |                 |
| EPM7128E |                |                |                |                | 68             | 84              |                 | 100             |                |                |                 |                 |
| EPM7128S |                |                |                |                | 68             | 84              | 84 (2)          | 100             |                |                |                 |                 |
| EPM7160E |                |                |                |                | 64             | 84              |                 | 104             |                |                |                 |                 |
| EPM7160S |                |                |                |                | 64             |                 | 84 (2)          | 104             |                |                |                 |                 |
| EPM7192E |                |                |                |                |                |                 |                 | 124             | 124            |                |                 |                 |
| EPM7192S |                |                |                |                |                |                 |                 | 124             |                |                |                 |                 |
| EPM7256E |                |                |                |                |                |                 |                 | 132 (2)         |                | 164            |                 | 164             |
| EPM7256S |                |                |                |                |                |                 |                 |                 |                |                | 164 (2)         | 164             |

**Notes:**

- (1) When the JTAG interface in MAX 7000S devices is used for either boundary-scan testing or for ISP, four I/O pins become JTAG pins.
- (2) Perform a complete thermal analysis before committing a design to this device package. For more information, see the [Operating Requirements for Altera Devices Data Sheet](#).

MAX 7000 devices use CMOS EEPROM cells to implement logic functions. The user-configurable MAX 7000 architecture accommodates a variety of independent combinatorial and sequential logic functions. The devices can be reprogrammed for quick and efficient iterations during design development and debug cycles, and can be programmed and erased up to 100 times.

MAX 7000 devices contain from 32 to 256 macrocells that are combined into groups of 16 macrocells, called logic array blocks (LABs). Each macrocell has a programmable-AND/fixed-OR array and a configurable register with independently programmable clock, clock enable, clear, and preset functions. To build complex logic functions, each macrocell can be supplemented with both shareable expander product terms and high-speed parallel expander product terms to provide up to 32 product terms per macrocell.

The MAX 7000 family provides programmable speed/power optimization. Speed-critical portions of a design can run at high speed/full power, while the remaining portions run at reduced speed/low power. This speed/power optimization feature enables the designer to configure one or more macrocells to operate at 50% or lower power while adding only a nominal timing delay. MAX 7000E and MAX 7000S devices also provide an option that reduces the slew rate of the output buffers, minimizing noise transients when non-speed-critical signals are switching. The output drivers of all MAX 7000 devices (except 44-pin devices) can be set for either 3.3-V or 5.0-V operation, allowing MAX 7000 devices to be used in mixed-voltage systems.

The MAX 7000 family is supported by Altera development systems, which are integrated packages that offer schematic, text—including VHDL, Verilog HDL, and the Altera Hardware Description Language (AHDL)—and waveform design entry, compilation and logic synthesis, simulation and timing analysis, and device programming. The software provides EDIF 2.0.0 and 3.0.0, LPM, VHDL, Verilog HDL, and other interfaces for additional design entry and simulation support from other industry-standard PC- and UNIX-workstation-based EDA tools. The software runs on Windows-based PCs, as well as Sun SPARCstation, and HP 9000 Series 700/800 workstations.



For more information on development tools, see the *MAX+PLUS II Programmable Logic Development System & Software Data Sheet* and the *Quartus Programmable Logic Development System & Software Data Sheet*.

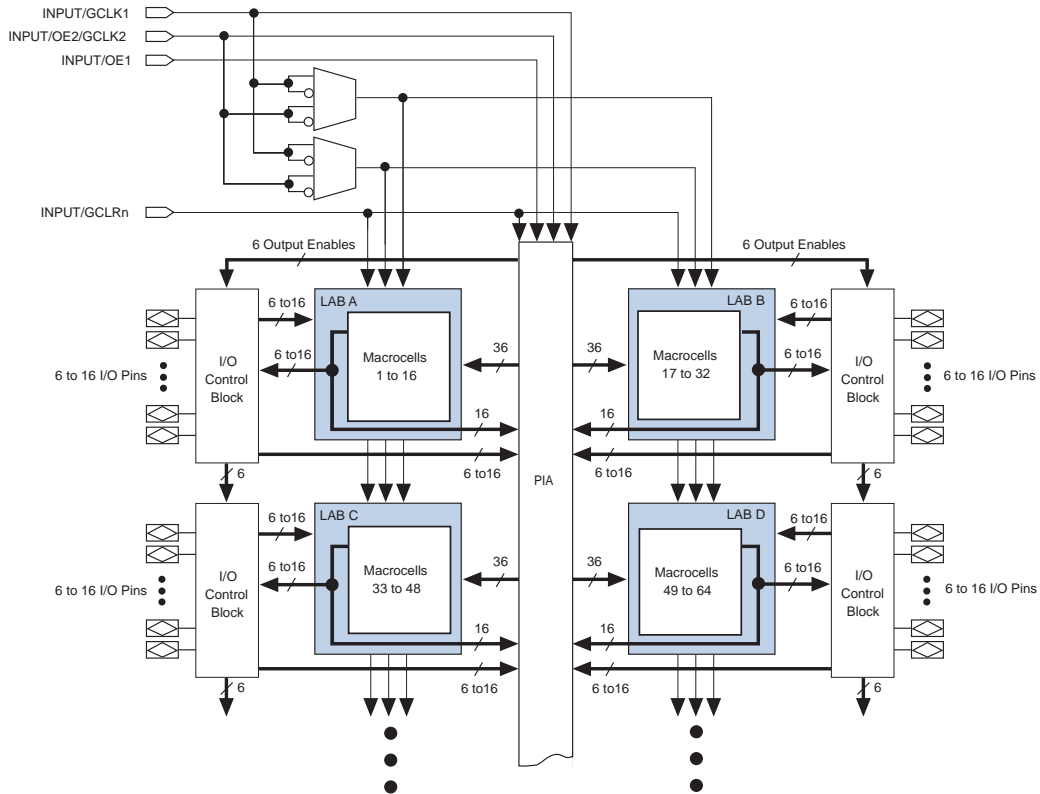
## Functional Description

The MAX 7000 architecture includes the following elements:

- Logic array blocks
- Macrocells
- Expander product terms (shareable and parallel)
- Programmable interconnect array
- I/O control blocks

Figure 2 shows the architecture of MAX 7000E and MAX 7000S devices.

**Figure 2. MAX 7000E & MAX 7000S Device Block Diagram**



## Logic Array Blocks

The MAX 7000 device architecture is based on the linking of high-performance, flexible, logic array modules called logic array blocks (LABs). LABs consist of 16-macrocell arrays, as shown in Figures 1 and 2. Multiple LABs are linked together via the programmable interconnect array (PIA), a global bus that is fed by all dedicated inputs, I/O pins, and macrocells.

## Design Security

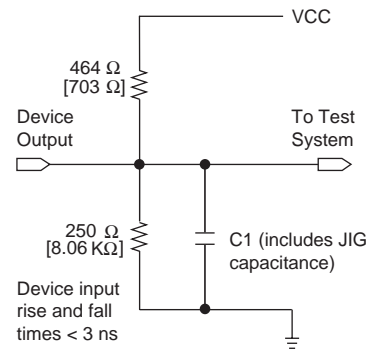
All MAX 7000 devices contain a programmable security bit that controls access to the data programmed into the device. When this bit is programmed, a proprietary design implemented in the device cannot be copied or retrieved. This feature provides a high level of design security because programmed data within EEPROM cells is invisible. The security bit that controls this function, as well as all other programmed data, is reset only when the device is reprogrammed.

## Generic Testing

Each MAX 7000 device is functionally tested. Complete testing of each programmable EEPROM bit and all internal logic elements ensures 100% programming yield. AC test measurements are taken under conditions equivalent to those shown in [Figure 10](#). Test patterns can be used and then erased during early stages of the production flow.

**Figure 10. MAX 7000 AC Test Conditions**

*Power supply transients can affect AC measurements. Simultaneous transitions of multiple outputs should be avoided for accurate measurement. Threshold tests must not be performed under AC conditions. Large-amplitude, fast ground-current transients normally occur as the device outputs discharge the load capacitances. When these transients flow through the parasitic inductance between the device ground pin and the test system ground, significant reductions in observable noise immunity can result. Numbers in brackets are for 2.5-V devices and outputs. Numbers without brackets are for 3.3-V devices and outputs.*



## QFP Carrier & Development Socket

MAX 7000 and MAX 7000E devices in QFP packages with 100 or more pins are shipped in special plastic carriers to protect the QFP leads. The carrier is used with a prototype development socket and special programming hardware available from Altera. This carrier technology makes it possible to program, test, erase, and reprogram a device without exposing the leads to mechanical stress.



For detailed information and carrier dimensions, refer to the [QFP Carrier & Development Socket Data Sheet](#).



MAX 7000S devices are not shipped in carriers.

**Table 20. MAX 7000 & MAX 7000E Internal Timing Parameters** *Note (1)*

| Symbol     | Parameter  | Conditions       | Speed Grade -6 |      | Speed Grade -7 |      | Unit |
|------------|--|------------------|----------------|------|----------------|------|------|
|            |  |                  | Min            | Max  | Min            | Max  |      |
| $t_{IN}$   | Input pad and buffer delay   |                  |                | 0.4  |                | 0.5  | ns   |
| $t_{IO}$   | I/O input pad and buffer delay   |                  |                | 0.4  |                | 0.5  | ns   |
| $t_{FIN}$  | Fast input delay   | (2)              |                | 0.8  |                | 1.0  | ns   |
| $t_{SEXP}$ | Shared expander delay  |                  |                | 3.5  |                | 4.0  | ns   |
| $t_{PEXP}$ | Parallel expander delay  |                  |                | 0.8  |                | 0.8  | ns   |
| $t_{LAD}$  | Logic array delay  |                  |                | 2.0  |                | 3.0  | ns   |
| $t_{LAC}$  | Logic control array delay  |                  |                | 2.0  |                | 3.0  | ns   |
| $t_{OE}$   | Internal output enable delay   | (2)              |                |      |                | 2.0  | ns   |
| $t_{OD1}$  | Output buffer and pad delay<br>Slow slew rate = off, $V_{CCIO} = 5.0$ V            | $C1 = 35$ pF     |                | 2.0  |                | 2.0  | ns   |
| $t_{OD2}$  | Output buffer and pad delay<br>Slow slew rate = off, $V_{CCIO} = 3.3$ V            | $C1 = 35$ pF (7) |                | 2.5  |                | 2.5  | ns   |
| $t_{OD3}$  | Output buffer and pad delay<br>Slow slew rate = on,<br>$V_{CCIO} = 5.0$ V or 3.3 V | $C1 = 35$ pF (2) |                | 7.0  |                | 7.0  | ns   |
| $t_{ZX1}$  | Output buffer enable delay<br>Slow slew rate = off, $V_{CCIO} = 5.0$ V             | $C1 = 35$ pF     |                | 4.0  |                | 4.0  | ns   |
| $t_{ZX2}$  | Output buffer enable delay<br>Slow slew rate = off, $V_{CCIO} = 3.3$ V             | $C1 = 35$ pF (7) |                | 4.5  |                | 4.5  | ns   |
| $t_{ZX3}$  | Output buffer enable delay<br>Slow slew rate = on<br>$V_{CCIO} = 5.0$ V or 3.3 V   | $C1 = 35$ pF (2) |                | 9.0  |                | 9.0  | ns   |
| $t_{XZ}$   | Output buffer disable delay  | $C1 = 5$ pF      |                | 4.0  |                | 4.0  | ns   |
| $t_{SU}$   | Register setup time  |                  | 3.0            |      | 3.0            |      | ns   |
| $t_H$      | Register hold time   |                  | 1.5            |      | 2.0            |      | ns   |
| $t_{FSU}$  | Register setup time of fast input  | (2)              | 2.5            |      | 3.0            |      | ns   |
| $t_{FH}$   | Register hold time of fast input   | (2)              | 0.5            |      | 0.5            |      | ns   |
| $t_{RD}$   | Register delay   |                  |                | 0.8  |                | 1.0  | ns   |
| $t_{COMB}$ | Combinatorial delay  |                  |                | 0.8  |                | 1.0  | ns   |
| $t_{JC}$   | Array clock delay  |                  |                | 2.5  |                | 3.0  | ns   |
| $t_{EN}$   | Register enable time   |                  |                | 2.0  |                | 3.0  | ns   |
| $t_{GLOB}$ | Global control delay   |                  |                | 0.8  |                | 1.0  | ns   |
| $t_{PRE}$  | Register preset time   |                  |                | 2.0  |                | 2.0  | ns   |
| $t_{CLR}$  | Register clear time  |                  |                | 2.0  |                | 2.0  | ns   |
| $t_{PIA}$  | PIA delay  |                  |                | 0.8  |                | 1.0  | ns   |
| $t_{LPA}$  | Low-power adder  | (8)              |                | 10.0 |                | 10.0 | ns   |

**Table 26. MAX 7000 & MAX 7000E Internal Timing Parameters** *Note (1)*

| Symbol     | Parameter   | Conditions              | Speed Grade |      |      |      |     |      | Unit |
|------------|---|-------------------------|-------------|------|------|------|-----|------|------|
|            |   |                         | -15         |      | -15T |      | -20 |      |      |
|            |   |                         | Min         | Max  | Min  | Max  | Min | Max  |      |
| $t_{IN}$   | Input pad and buffer delay  |                         |             | 2.0  |      | 2.0  |     | 3.0  | ns   |
| $t_{IO}$   | I/O input pad and buffer delay  |                         |             | 2.0  |      | 2.0  |     | 3.0  | ns   |
| $t_{FIN}$  | Fast input delay  | (2)                     |             | 2.0  |      | —    |     | 4.0  | ns   |
| $t_{SEXP}$ | Shared expander delay   |                         |             | 8.0  |      | 10.0 |     | 9.0  | ns   |
| $t_{PEXP}$ | Parallel expander delay   |                         |             | 1.0  |      | 1.0  |     | 2.0  | ns   |
| $t_{LAD}$  | Logic array delay   |                         |             | 6.0  |      | 6.0  |     | 8.0  | ns   |
| $t_{LAC}$  | Logic control array delay   |                         |             | 6.0  |      | 6.0  |     | 8.0  | ns   |
| $t_{IOE}$  | Internal output enable delay  | (2)                     |             | 3.0  |      | —    |     | 4.0  | ns   |
| $t_{OD1}$  | Output buffer and pad delay<br>Slow slew rate = off<br>$V_{CCIO} = 5.0\text{ V}$                  | $C1 = 35\text{ pF}$     |             | 4.0  |      | 4.0  |     | 5.0  | ns   |
| $t_{OD2}$  | Output buffer and pad delay<br>Slow slew rate = off<br>$V_{CCIO} = 3.3\text{ V}$                  | $C1 = 35\text{ pF}$ (7) |             | 5.0  |      | —    |     | 6.0  | ns   |
| $t_{OD3}$  | Output buffer and pad delay<br>Slow slew rate = on<br>$V_{CCIO} = 5.0\text{ V}$ or $3.3\text{ V}$ | $C1 = 35\text{ pF}$ (2) |             | 8.0  |      | —    |     | 9.0  | ns   |
| $t_{ZX1}$  | Output buffer enable delay<br>Slow slew rate = off<br>$V_{CCIO} = 5.0\text{ V}$                   | $C1 = 35\text{ pF}$     |             | 6.0  |      | 6.0  |     | 10.0 | ns   |
| $t_{ZX2}$  | Output buffer enable delay<br>Slow slew rate = off<br>$V_{CCIO} = 3.3\text{ V}$                   | $C1 = 35\text{ pF}$ (7) |             | 7.0  |      | —    |     | 11.0 | ns   |
| $t_{ZX3}$  | Output buffer enable delay<br>Slow slew rate = on<br>$V_{CCIO} = 5.0\text{ V}$ or $3.3\text{ V}$  | $C1 = 35\text{ pF}$ (2) |             | 10.0 |      | —    |     | 14.0 | ns   |
| $t_{XZ}$   | Output buffer disable delay   | $C1 = 5\text{ pF}$      |             | 6.0  |      | 6.0  |     | 10.0 | ns   |
| $t_{SU}$   | Register setup time   |                         | 4.0         |      | 4.0  |      | 4.0 |      | ns   |
| $t_H$      | Register hold time  |                         | 4.0         |      | 4.0  |      | 5.0 |      | ns   |
| $t_{FSU}$  | Register setup time of fast input   | (2)                     | 2.0         |      | —    |      | 4.0 |      | ns   |
| $t_{FH}$   | Register hold time of fast input  | (2)                     | 2.0         |      | —    |      | 3.0 |      | ns   |
| $t_{RD}$   | Register delay  |                         |             | 1.0  |      | 1.0  |     | 1.0  | ns   |
| $t_{COMB}$ | Combinatorial delay   |                         |             | 1.0  |      | 1.0  |     | 1.0  | ns   |
| $t_{IC}$   | Array clock delay   |                         |             | 6.0  |      | 6.0  |     | 8.0  | ns   |
| $t_{EN}$   | Register enable time  |                         |             | 6.0  |      | 6.0  |     | 8.0  | ns   |
| $t_{GLOB}$ | Global control delay  |                         |             | 1.0  |      | 1.0  |     | 3.0  | ns   |
| $t_{PRE}$  | Register preset time  |                         |             | 4.0  |      | 4.0  |     | 4.0  | ns   |
| $t_{CLR}$  | Register clear time   |                         |             | 4.0  |      | 4.0  |     | 4.0  | ns   |
| $t_{PIA}$  | PIA delay   |                         |             | 2.0  |      | 2.0  |     | 3.0  | ns   |
| $t_{LPA}$  | Low-power adder   | (8)                     |             | 13.0 |      | 15.0 |     | 15.0 | ns   |



**Table 28. EPM7032S Internal Timing Parameters** *Note (1)*

| Symbol    | Parameter       | Conditions | Speed Grade |      |     |      |     |      |     |      | Unit |
|-----------|-----------------|------------|-------------|------|-----|------|-----|------|-----|------|------|
|           |                 |            | -5          |      | -6  |      | -7  |      | -10 |      |      |
|           |                 |            | Min         | Max  | Min | Max  | Min | Max  | Min | Max  |      |
| $t_{PIA}$ | PIA delay       | (7)        |             | 1.1  |     | 1.1  |     | 1.4  |     | 1.0  | ns   |
| $t_{LPA}$ | Low-power adder | (8)        |             | 12.0 |     | 10.0 |     | 10.0 |     | 11.0 | ns   |

**Notes to tables:**

- (1) These values are specified under the recommended operating conditions shown in Table 14. See Figure 13 for more information on switching waveforms.
- (2) This minimum pulse width for preset and clear applies for both global clear and array controls. The  $t_{LPA}$  parameter must be added to this minimum width if the clear or reset signal incorporates the  $t_{LAD}$  parameter into the signal path.
- (3) This parameter is a guideline that is sample-tested only and is based on extensive device characterization. This parameter applies for both global and array clocking.
- (4) These parameters are measured with a 16-bit loadable, enabled, up/down counter programmed into each LAB.
- (5) The  $f_{MAX}$  values represent the highest frequency for pipelined data.
- (6) Operating conditions:  $V_{CCIO} = 3.3\text{ V} \pm 10\%$  for commercial and industrial use.
- (7) For EPM7064S-5, EPM7064S-6, EPM7128S-6, EPM7160S-6, EPM7160S-7, EPM7192S-7, and EPM7256S-7 devices, these values are specified for a PIA fan-out of one LAB (16 macrocells). For each additional LAB fan-out in these devices, add an additional 0.1 ns to the PIA timing value.
- (8) The  $t_{LPA}$  parameter must be added to the  $t_{LAD}$ ,  $t_{LAC}$ ,  $t_{IC}$ ,  $t_{EN}$ ,  $t_{SEXP}$ ,  $t_{ACL}$ , and  $t_{CPPW}$  parameters for macrocells running in the low-power mode.

Tables 29 and 30 show the EPM7064S AC operating conditions.

**Table 29. EPM7064S External Timing Parameters (Part 1 of 2)** *Note (1)*

| Symbol           | Parameter                             | Conditions | Speed Grade |     |     |     |     |     |     |      | Unit |
|------------------|---------------------------------------|------------|-------------|-----|-----|-----|-----|-----|-----|------|------|
|                  |                                       |            | -5          |     | -6  |     | -7  |     | -10 |      |      |
|                  |                                       |            | Min         | Max | Min | Max | Min | Max | Min | Max  |      |
| t <sub>PD1</sub> | Input to non-registered output        | C1 = 35 pF |             | 5.0 |     | 6.0 |     | 7.5 |     | 10.0 | ns   |
| t <sub>PD2</sub> | I/O input to non-registered output    | C1 = 35 pF |             | 5.0 |     | 6.0 |     | 7.5 |     | 10.0 | ns   |
| t <sub>SU</sub>  | Global clock setup time               |            | 2.9         |     | 3.6 |     | 6.0 |     | 7.0 |      | ns   |
| t <sub>H</sub>   | Global clock hold time                |            | 0.0         |     | 0.0 |     | 0.0 |     | 0.0 |      | ns   |
| t <sub>FSU</sub> | Global clock setup time of fast input |            | 2.5         |     | 2.5 |     | 3.0 |     | 3.0 |      | ns   |
| t <sub>FH</sub>  | Global clock hold time of fast input  |            | 0.0         |     | 0.0 |     | 0.5 |     | 0.5 |      | ns   |
| t <sub>CO1</sub> | Global clock to output delay          | C1 = 35 pF |             | 3.2 |     | 4.0 |     | 4.5 |     | 5.0  | ns   |
| t <sub>CH</sub>  | Global clock high time                |            | 2.0         |     | 2.5 |     | 3.0 |     | 4.0 |      | ns   |
| t <sub>CL</sub>  | Global clock low time                 |            | 2.0         |     | 2.5 |     | 3.0 |     | 4.0 |      | ns   |
| t <sub>ASU</sub> | Array clock setup time                |            | 0.7         |     | 0.9 |     | 3.0 |     | 2.0 |      | ns   |
| t <sub>AH</sub>  | Array clock hold time                 |            | 1.8         |     | 2.1 |     | 2.0 |     | 3.0 |      | ns   |

**Table 29. EPM7064S External Timing Parameters (Part 2 of 2)** *Note (1)*

| Symbol            | Parameter                                | Conditions     | Speed Grade |     |       |     |       |     |       |      | Unit |
|-------------------|--|----------------|-------------|-----|-------|-----|-------|-----|-------|------|------|
|                   |  |                | -5          |     | -6    |     | -7    |     | -10   |      |      |
|                   |  |                | Min         | Max | Min   | Max | Min   | Max | Min   | Max  |      |
| t <sub>ACO1</sub> | Array clock to output delay              | C1 = 35 pF     |             | 5.4 |       | 6.7 |       | 7.5 |       | 10.0 | ns   |
| t <sub>ACH</sub>  | Array clock high time                    |                | 2.5         |     | 2.5   |     | 3.0   |     | 4.0   |      | ns   |
| t <sub>ACL</sub>  | Array clock low time                     |                | 2.5         |     | 2.5   |     | 3.0   |     | 4.0   |      | ns   |
| t <sub>CPPW</sub> | Minimum pulse width for clear and preset | (2)            | 2.5         |     | 2.5   |     | 3.0   |     | 4.0   |      | ns   |
| t <sub>ODH</sub>  | Output data hold time after clock        | C1 = 35 pF (3) | 1.0         |     | 1.0   |     | 1.0   |     | 1.0   |      | ns   |
| t <sub>CNT</sub>  | Minimum global clock period              |                |             | 5.7 |       | 7.1 |       | 8.0 |       | 10.0 | ns   |
| f <sub>CNT</sub>  | Maximum internal global clock frequency  | (4)            | 175.4       |     | 140.8 |     | 125.0 |     | 100.0 |      | MHz  |
| t <sub>ACNT</sub> | Minimum array clock period               |                |             | 5.7 |       | 7.1 |       | 8.0 |       | 10.0 | ns   |
| f <sub>ACNT</sub> | Maximum internal array clock frequency   | (4)            | 175.4       |     | 140.8 |     | 125.0 |     | 100.0 |      | MHz  |
| f <sub>MAX</sub>  | Maximum clock frequency                  | (5)            | 250.0       |     | 200.0 |     | 166.7 |     | 125.0 |      | MHz  |

**Table 30. EPM7064S Internal Timing Parameters (Part 1 of 2)** *Note (1)*

| Symbol     | Parameter                      | Conditions     | Speed Grade |     |     |     |     |     |     |     | Unit |
|------------|--------------------------------|----------------|-------------|-----|-----|-----|-----|-----|-----|-----|------|
|            |                                |                | -5          |     | -6  |     | -7  |     | -10 |     |      |
|            |                                |                | Min         | Max | Min | Max | Min | Max | Min | Max |      |
| $t_{IN}$   | Input pad and buffer delay     |                |             | 0.2 |     | 0.2 |     | 0.5 |     | 0.5 | ns   |
| $t_{IO}$   | I/O input pad and buffer delay |                |             | 0.2 |     | 0.2 |     | 0.5 |     | 0.5 | ns   |
| $t_{FIN}$  | Fast input delay               |                |             | 2.2 |     | 2.6 |     | 1.0 |     | 1.0 | ns   |
| $t_{SEXP}$ | Shared expander delay          |                |             | 3.1 |     | 3.8 |     | 4.0 |     | 5.0 | ns   |
| $t_{PEXP}$ | Parallel expander delay        |                |             | 0.9 |     | 1.1 |     | 0.8 |     | 0.8 | ns   |
| $t_{LAD}$  | Logic array delay              |                |             | 2.6 |     | 3.2 |     | 3.0 |     | 5.0 | ns   |
| $t_{LAC}$  | Logic control array delay      |                |             | 2.5 |     | 3.2 |     | 3.0 |     | 5.0 | ns   |
| $t_{IOE}$  | Internal output enable delay   |                |             | 0.7 |     | 0.8 |     | 2.0 |     | 2.0 | ns   |
| $t_{OD1}$  | Output buffer and pad delay    | C1 = 35 pF     |             | 0.2 |     | 0.3 |     | 2.0 |     | 1.5 | ns   |
| $t_{OD2}$  | Output buffer and pad delay    | C1 = 35 pF (6) |             | 0.7 |     | 0.8 |     | 2.5 |     | 2.0 | ns   |
| $t_{OD3}$  | Output buffer and pad delay    | C1 = 35 pF     |             | 5.2 |     | 5.3 |     | 7.0 |     | 5.5 | ns   |
| $t_{ZX1}$  | Output buffer enable delay     | C1 = 35 pF     |             | 4.0 |     | 4.0 |     | 4.0 |     | 5.0 | ns   |
| $t_{ZX2}$  | Output buffer enable delay     | C1 = 35 pF (6) |             | 4.5 |     | 4.5 |     | 4.5 |     | 5.5 | ns   |
| $t_{ZX3}$  | Output buffer enable delay     | C1 = 35 pF     |             | 9.0 |     | 9.0 |     | 9.0 |     | 9.0 | ns   |
| $t_{XZ}$   | Output buffer disable delay    | C1 = 5 pF      |             | 4.0 |     | 4.0 |     | 4.0 |     | 5.0 | ns   |
| $t_{SU}$   | Register setup time            |                | 0.8         |     | 1.0 |     | 3.0 |     | 2.0 |     | ns   |
| $t_H$      | Register hold time             |                | 1.7         |     | 2.0 |     | 2.0 |     | 3.0 |     | ns   |

Tables 31 and 32 show the EPM7128S AC operating conditions.

| Table 31. EPM7128S External Timing Parameters      Note (1) |  |                |             |     |       |     |       |      |       |      |      |
|---|--|----------------|-------------|-----|-------|-----|-------|------|-------|------|------|
| Symbol  | Parameter                                | Conditions     | Speed Grade |     |       |     |       |      |       |      | Unit |
|   |  |                | -6          |     | -7    |     | -10   |      | -15   |      |      |
|   |  |                | Min         | Max | Min   | Max | Min   | Max  | Min   | Max  |      |
| t <sub>PD1</sub>  | Input to non-registered output           | C1 = 35 pF     |             | 6.0 |       | 7.5 |       | 10.0 |       | 15.0 | ns   |
| t <sub>PD2</sub>  | I/O input to non-registered output       | C1 = 35 pF     |             | 6.0 |       | 7.5 |       | 10.0 |       | 15.0 | ns   |
| t <sub>SU</sub>   | Global clock setup time                  |                | 3.4         |     | 6.0   |     | 7.0   |      | 11.0  |      | ns   |
| t <sub>H</sub>  | Global clock hold time                   |                | 0.0         |     | 0.0   |     | 0.0   |      | 0.0   |      | ns   |
| t <sub>FSU</sub>  | Global clock setup time of fast input    |                | 2.5         |     | 3.0   |     | 3.0   |      | 3.0   |      | ns   |
| t <sub>FH</sub>   | Global clock hold time of fast input     |                | 0.0         |     | 0.5   |     | 0.5   |      | 0.0   |      | ns   |
| t <sub>CO1</sub>  | Global clock to output delay             | C1 = 35 pF     |             | 4.0 |       | 4.5 |       | 5.0  |       | 8.0  | ns   |
| t <sub>CH</sub>   | Global clock high time                   |                | 3.0         |     | 3.0   |     | 4.0   |      | 5.0   |      | ns   |
| t <sub>CL</sub>   | Global clock low time                    |                | 3.0         |     | 3.0   |     | 4.0   |      | 5.0   |      | ns   |
| t <sub>ASU</sub>  | Array clock setup time                   |                | 0.9         |     | 3.0   |     | 2.0   |      | 4.0   |      | ns   |
| t <sub>AH</sub>   | Array clock hold time                    |                | 1.8         |     | 2.0   |     | 5.0   |      | 4.0   |      | ns   |
| t <sub>ACO1</sub>   | Array clock to output delay              | C1 = 35 pF     |             | 6.5 |       | 7.5 |       | 10.0 |       | 15.0 | ns   |
| t <sub>ACH</sub>  | Array clock high time                    |                | 3.0         |     | 3.0   |     | 4.0   |      | 6.0   |      | ns   |
| t <sub>ACL</sub>  | Array clock low time                     |                | 3.0         |     | 3.0   |     | 4.0   |      | 6.0   |      | ns   |
| t <sub>CPPW</sub>   | Minimum pulse width for clear and preset | (2)            | 3.0         |     | 3.0   |     | 4.0   |      | 6.0   |      | ns   |
| t <sub>ODH</sub>  | Output data hold time after clock        | C1 = 35 pF (3) | 1.0         |     | 1.0   |     | 1.0   |      | 1.0   |      | ns   |
| t <sub>CNT</sub>  | Minimum global clock period              |                |             | 6.8 |       | 8.0 |       | 10.0 |       | 13.0 | ns   |
| f <sub>CNT</sub>  | Maximum internal global clock frequency  | (4)            | 147.1       |     | 125.0 |     | 100.0 |      | 76.9  |      | MHz  |
| t <sub>ACNT</sub>   | Minimum array clock period               |                |             | 6.8 |       | 8.0 |       | 10.0 |       | 13.0 | ns   |
| f <sub>ACNT</sub>   | Maximum internal array clock frequency   | (4)            | 147.1       |     | 125.0 |     | 100.0 |      | 76.9  |      | MHz  |
| f <sub>MAX</sub>  | Maximum clock frequency                  | (5)            | 166.7       |     | 166.7 |     | 125.0 |      | 100.0 |      | MHz  |

**Notes to tables:**

- (1) These values are specified under the recommended operating conditions shown in Table 14. See Figure 13 for more information on switching waveforms.
- (2) This minimum pulse width for preset and clear applies for both global clear and array controls. The  $t_{LPA}$  parameter must be added to this minimum width if the clear or reset signal incorporates the  $t_{LAD}$  parameter into the signal path.
- (3) This parameter is a guideline that is sample-tested only and is based on extensive device characterization. This parameter applies for both global and array clocking.
- (4) These parameters are measured with a 16-bit loadable, enabled, up/down counter programmed into each LAB.
- (5) The  $f_{MAX}$  values represent the highest frequency for pipelined data.
- (6) Operating conditions:  $V_{CCIO} = 3.3 \text{ V} \pm 10\%$  for commercial and industrial use.
- (7) For EPM7064S-5, EPM7064S-6, EPM7128S-6, EPM7160S-6, EPM7160S-7, EPM7192S-7, and EPM7256S-7 devices, these values are specified for a PIA fan-out of one LAB (16 macrocells). For each additional LAB fan-out in these devices, add an additional 0.1 ns to the PIA timing value.
- (8) The  $t_{LPA}$  parameter must be added to the  $t_{LAD}$ ,  $t_{LAC}$ ,  $t_{IC}$ ,  $t_{EN}$ ,  $t_{SEXP}$ ,  $t_{ACL}$ , and  $t_{CPPW}$  parameters for macrocells running in the low-power mode.

Tables 33 and 34 show the EPM7160S AC operating conditions.

**Table 33. EPM7160S External Timing Parameters (Part 1 of 2)** *Note (1)*

| Symbol            | Parameter                                | Conditions     | Speed Grade |     |       |     |       |      |      |      | Unit |
|-------------------|--|----------------|-------------|-----|-------|-----|-------|------|------|------|------|
|                   |  |                | -6          |     | -7    |     | -10   |      | -15  |      |      |
|                   |  |                | Min         | Max | Min   | Max | Min   | Max  | Min  | Max  |      |
| t <sub>PD1</sub>  | Input to non-registered output           | C1 = 35 pF     |             | 6.0 |       | 7.5 |       | 10.0 |      | 15.0 | ns   |
| t <sub>PD2</sub>  | I/O input to non-registered output       | C1 = 35 pF     |             | 6.0 |       | 7.5 |       | 10.0 |      | 15.0 | ns   |
| t <sub>SU</sub>   | Global clock setup time                  |                | 3.4         |     | 4.2   |     | 7.0   |      | 11.0 |      | ns   |
| t <sub>H</sub>    | Global clock hold time                   |                | 0.0         |     | 0.0   |     | 0.0   |      | 0.0  |      | ns   |
| t <sub>FSU</sub>  | Global clock setup time of fast input    |                | 2.5         |     | 3.0   |     | 3.0   |      | 3.0  |      | ns   |
| t <sub>FH</sub>   | Global clock hold time of fast input     |                | 0.0         |     | 0.0   |     | 0.5   |      | 0.0  |      | ns   |
| t <sub>CO1</sub>  | Global clock to output delay             | C1 = 35 pF     |             | 3.9 |       | 4.8 |       | 5    |      | 8    | ns   |
| t <sub>CH</sub>   | Global clock high time                   |                | 3.0         |     | 3.0   |     | 4.0   |      | 5.0  |      | ns   |
| t <sub>CL</sub>   | Global clock low time                    |                | 3.0         |     | 3.0   |     | 4.0   |      | 5.0  |      | ns   |
| t <sub>ASU</sub>  | Array clock setup time                   |                | 0.9         |     | 1.1   |     | 2.0   |      | 4.0  |      | ns   |
| t <sub>AH</sub>   | Array clock hold time                    |                | 1.7         |     | 2.1   |     | 3.0   |      | 4.0  |      | ns   |
| t <sub>ACO1</sub> | Array clock to output delay              | C1 = 35 pF     |             | 6.4 |       | 7.9 |       | 10.0 |      | 15.0 | ns   |
| t <sub>ACH</sub>  | Array clock high time                    |                | 3.0         |     | 3.0   |     | 4.0   |      | 6.0  |      | ns   |
| t <sub>ACL</sub>  | Array clock low time                     |                | 3.0         |     | 3.0   |     | 4.0   |      | 6.0  |      | ns   |
| t <sub>CPPW</sub> | Minimum pulse width for clear and preset | (2)            | 2.5         |     | 3.0   |     | 4.0   |      | 6.0  |      | ns   |
| t <sub>ODH</sub>  | Output data hold time after clock        | C1 = 35 pF (3) | 1.0         |     | 1.0   |     | 1.0   |      | 1.0  |      | ns   |
| t <sub>CNT</sub>  | Minimum global clock period              |                |             | 6.7 |       | 8.2 |       | 10.0 |      | 13.0 | ns   |
| f <sub>CNT</sub>  | Maximum internal global clock frequency  | (4)            | 149.3       |     | 122.0 |     | 100.0 |      | 76.9 |      | MHz  |

**Table 33. EPM7160S External Timing Parameters (Part 2 of 2)** *Note (1)*

| Symbol            | Parameter                              | Conditions | Speed Grade |     |       |     |       |      |       |      | Unit |
|-------------------|--|------------|-------------|-----|-------|-----|-------|------|-------|------|------|
|                   |  |            | -6          |     | -7    |     | -10   |      | -15   |      |      |
|                   |  |            | Min         | Max | Min   | Max | Min   | Max  | Min   | Max  |      |
| t <sub>ACNT</sub> | Minimum array clock period             |            |             | 6.7 |       | 8.2 |       | 10.0 |       | 13.0 | ns   |
| f <sub>ACNT</sub> | Maximum internal array clock frequency | (4)        | 149.3       |     | 122.0 |     | 100.0 |      | 76.9  |      | MHz  |
| f <sub>MAX</sub>  | Maximum clock frequency                | (5)        | 166.7       |     | 166.7 |     | 125.0 |      | 100.0 |      | MHz  |

**Table 34. EPM7160S Internal Timing Parameters (Part 1 of 2)** *Note (1)*

| Symbol     | Parameter                         | Conditions     | Speed Grade |     |     |     |     |     |     |      | Unit |
|------------|-----------------------------------|----------------|-------------|-----|-----|-----|-----|-----|-----|------|------|
|            |                                   |                | -6          |     | -7  |     | -10 |     | -15 |      |      |
|            |                                   |                | Min         | Max | Min | Max | Min | Max | Min | Max  |      |
| $t_{IN}$   | Input pad and buffer delay        |                |             | 0.2 |     | 0.3 |     | 0.5 |     | 2.0  | ns   |
| $t_{IO}$   | I/O input pad and buffer delay    |                |             | 0.2 |     | 0.3 |     | 0.5 |     | 2.0  | ns   |
| $t_{FIN}$  | Fast input delay                  |                |             | 2.6 |     | 3.2 |     | 1.0 |     | 2.0  | ns   |
| $t_{SEXP}$ | Shared expander delay             |                |             | 3.6 |     | 4.3 |     | 5.0 |     | 8.0  | ns   |
| $t_{PEXP}$ | Parallel expander delay           |                |             | 1.0 |     | 1.3 |     | 0.8 |     | 1.0  | ns   |
| $t_{LAD}$  | Logic array delay                 |                |             | 2.8 |     | 3.4 |     | 5.0 |     | 6.0  | ns   |
| $t_{LAC}$  | Logic control array delay         |                |             | 2.8 |     | 3.4 |     | 5.0 |     | 6.0  | ns   |
| $t_{IOE}$  | Internal output enable delay      |                |             | 0.7 |     | 0.9 |     | 2.0 |     | 3.0  | ns   |
| $t_{OD1}$  | Output buffer and pad delay       | C1 = 35 pF     |             | 0.4 |     | 0.5 |     | 1.5 |     | 4.0  | ns   |
| $t_{OD2}$  | Output buffer and pad delay       | C1 = 35 pF (6) |             | 0.9 |     | 1.0 |     | 2.0 |     | 5.0  | ns   |
| $t_{OD3}$  | Output buffer and pad delay       | C1 = 35 pF     |             | 5.4 |     | 5.5 |     | 5.5 |     | 8.0  | ns   |
| $t_{ZX1}$  | Output buffer enable delay        | C1 = 35 pF     |             | 4.0 |     | 4.0 |     | 5.0 |     | 6.0  | ns   |
| $t_{ZX2}$  | Output buffer enable delay        | C1 = 35 pF (6) |             | 4.5 |     | 4.5 |     | 5.5 |     | 7.0  | ns   |
| $t_{ZX3}$  | Output buffer enable delay        | C1 = 35 pF     |             | 9.0 |     | 9.0 |     | 9.0 |     | 10.0 | ns   |
| $t_{XZ}$   | Output buffer disable delay       | C1 = 5 pF      |             | 4.0 |     | 4.0 |     | 5.0 |     | 6.0  | ns   |
| $t_{SU}$   | Register setup time               |                | 1.0         |     | 1.2 |     | 2.0 |     | 4.0 |      | ns   |
| $t_H$      | Register hold time                |                | 1.6         |     | 2.0 |     | 3.0 |     | 4.0 |      | ns   |
| $t_{FSU}$  | Register setup time of fast input |                | 1.9         |     | 2.2 |     | 3.0 |     | 2.0 |      | ns   |
| $t_{FH}$   | Register hold time of fast input  |                | 0.6         |     | 0.8 |     | 0.5 |     | 1.0 |      | ns   |
| $t_{RD}$   | Register delay                    |                |             | 1.3 |     | 1.6 |     | 2.0 |     | 1.0  | ns   |
| $t_{COMB}$ | Combinatorial delay               |                |             | 1.0 |     | 1.3 |     | 2.0 |     | 1.0  | ns   |
| $t_{IC}$   | Array clock delay                 |                |             | 2.9 |     | 3.5 |     | 5.0 |     | 6.0  | ns   |
| $t_{EN}$   | Register enable time              |                |             | 2.8 |     | 3.4 |     | 5.0 |     | 6.0  | ns   |
| $t_{GLOB}$ | Global control delay              |                |             | 2.0 |     | 2.4 |     | 1.0 |     | 1.0  | ns   |
| $t_{PRE}$  | Register preset time              |                |             | 2.4 |     | 3.0 |     | 3.0 |     | 4.0  | ns   |

**Table 38. EPM7256S Internal Timing Parameters** *Note (1)*

| Symbol     | Parameter                         | Conditions     | Speed Grade |      |     |      |     |      | Unit |
|------------|-----------------------------------|----------------|-------------|------|-----|------|-----|------|------|
|            |                                   |                | -7          |      | -10 |      | -15 |      |      |
|            |                                   |                | Min         | Max  | Min | Max  | Min | Max  |      |
| $t_{IN}$   | Input pad and buffer delay        |                |             | 0.3  |     | 0.5  |     | 2.0  | ns   |
| $t_{IO}$   | I/O input pad and buffer delay    |                |             | 0.3  |     | 0.5  |     | 2.0  | ns   |
| $t_{FIN}$  | Fast input delay                  |                |             | 3.4  |     | 1.0  |     | 2.0  | ns   |
| $t_{SEXP}$ | Shared expander delay             |                |             | 3.9  |     | 5.0  |     | 8.0  | ns   |
| $t_{PEXP}$ | Parallel expander delay           |                |             | 1.1  |     | 0.8  |     | 1.0  | ns   |
| $t_{LAD}$  | Logic array delay                 |                |             | 2.6  |     | 5.0  |     | 6.0  | ns   |
| $t_{LAC}$  | Logic control array delay         |                |             | 2.6  |     | 5.0  |     | 6.0  | ns   |
| $t_{IOE}$  | Internal output enable delay      |                |             | 0.8  |     | 2.0  |     | 3.0  | ns   |
| $t_{OD1}$  | Output buffer and pad delay       | C1 = 35 pF     |             | 0.5  |     | 1.5  |     | 4.0  | ns   |
| $t_{OD2}$  | Output buffer and pad delay       | C1 = 35 pF (6) |             | 1.0  |     | 2.0  |     | 5.0  | ns   |
| $t_{OD3}$  | Output buffer and pad delay       | C1 = 35 pF     |             | 5.5  |     | 5.5  |     | 8.0  | ns   |
| $t_{ZX1}$  | Output buffer enable delay        | C1 = 35 pF     |             | 4.0  |     | 5.0  |     | 6.0  | ns   |
| $t_{ZX2}$  | Output buffer enable delay        | C1 = 35 pF (6) |             | 4.5  |     | 5.5  |     | 7.0  | ns   |
| $t_{ZX3}$  | Output buffer enable delay        | C1 = 35 pF     |             | 9.0  |     | 9.0  |     | 10.0 | ns   |
| $t_{XZ}$   | Output buffer disable delay       | C1 = 5 pF      |             | 4.0  |     | 5.0  |     | 6.0  | ns   |
| $t_{SU}$   | Register setup time               |                | 1.1         |      | 2.0 |      | 4.0 |      | ns   |
| $t_H$      | Register hold time                |                | 1.6         |      | 3.0 |      | 4.0 |      | ns   |
| $t_{FSU}$  | Register setup time of fast input |                | 2.4         |      | 3.0 |      | 2.0 |      | ns   |
| $t_{FH}$   | Register hold time of fast input  |                | 0.6         |      | 0.5 |      | 1.0 |      | ns   |
| $t_{RD}$   | Register delay                    |                |             | 1.1  |     | 2.0  |     | 1.0  | ns   |
| $t_{COMB}$ | Combinatorial delay               |                |             | 1.1  |     | 2.0  |     | 1.0  | ns   |
| $t_{IC}$   | Array clock delay                 |                |             | 2.9  |     | 5.0  |     | 6.0  | ns   |
| $t_{EN}$   | Register enable time              |                |             | 2.6  |     | 5.0  |     | 6.0  | ns   |
| $t_{GLOB}$ | Global control delay              |                |             | 2.8  |     | 1.0  |     | 1.0  | ns   |
| $t_{PRE}$  | Register preset time              |                |             | 2.7  |     | 3.0  |     | 4.0  | ns   |
| $t_{CLR}$  | Register clear time               |                |             | 2.7  |     | 3.0  |     | 4.0  | ns   |
| $t_{PIA}$  | PIA delay                         | (7)            |             | 3.0  |     | 1.0  |     | 2.0  | ns   |
| $t_{LPA}$  | Low-power adder                   | (8)            |             | 10.0 |     | 11.0 |     | 13.0 | ns   |

**Notes to tables:**

- (1) These values are specified under the recommended operating conditions shown in [Table 14](#). See [Figure 13](#) for more information on switching waveforms.
- (2) This minimum pulse width for preset and clear applies for both global clear and array controls. The  $t_{LPA}$  parameter must be added to this minimum width if the clear or reset signal incorporates the  $t_{LAD}$  parameter into the signal path.
- (3) This parameter is a guideline that is sample-tested only and is based on extensive device characterization. This parameter applies for both global and array clocking.
- (4) These parameters are measured with a 16-bit loadable, enabled, up/down counter programmed into each LAB.
- (5) The  $f_{MAX}$  values represent the highest frequency for pipelined data.
- (6) Operating conditions:  $V_{CCIO} = 3.3 \text{ V} \pm 10\%$  for commercial and industrial use.
- (7) For EPM7064S-5, EPM7064S-6, EPM7128S-6, EPM7160S-6, EPM7160S-7, EPM7192S-7, and EPM7256S-7 devices, these values are specified for a PIA fan-out of one LAB (16 macrocells). For each additional LAB fan-out in these devices, add an additional 0.1 ns to the PIA timing value.
- (8) The  $t_{LPA}$  parameter must be added to the  $t_{LAD}$ ,  $t_{LAC}$ ,  $t_{IC}$ ,  $t_{EN}$ ,  $t_{SEXP}$ ,  $t_{ACL}$ , and  $t_{CPTW}$  parameters for macrocells running in the low-power mode.

## Power Consumption

Supply power (P) versus frequency ( $f_{MAX}$  in MHz) for MAX 7000 devices is calculated with the following equation:

$$P = P_{INT} + P_{IO} = I_{CCINT} \times V_{CC} + P_{IO}$$

The  $P_{IO}$  value, which depends on the device output load characteristics and switching frequency, can be calculated using the guidelines given in [Application Note 74 \(Evaluating Power for Altera Devices\)](#).

The  $I_{CCINT}$  value, which depends on the switching frequency and the application logic, is calculated with the following equation:

$$I_{CCINT} =$$

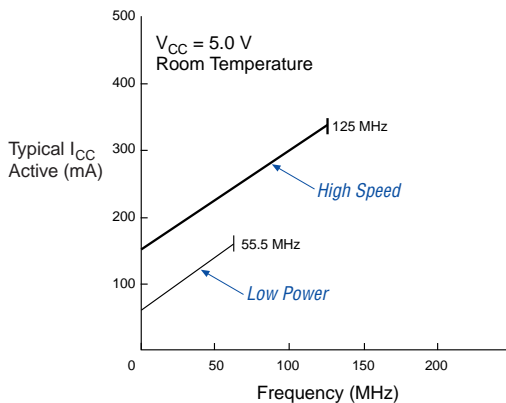
$$A \times MC_{TON} + B \times (MC_{DEV} - MC_{TON}) + C \times MC_{USED} \times f_{MAX} \times \text{tog}_{LC}$$

The parameters in this equation are shown below:

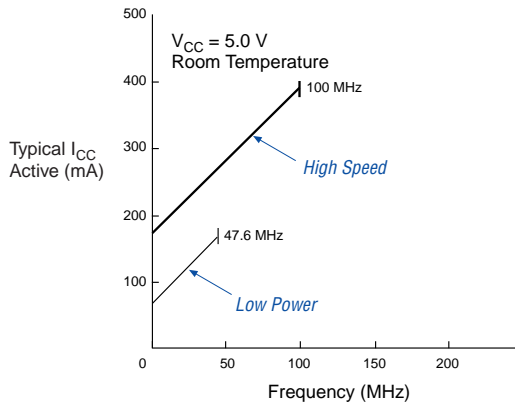
|                   |   |   |
|-------------------|---|---|
| $MC_{TON}$        | = | Number of macrocells with the Turbo Bit option turned on, as reported in the MAX+PLUS II Report File (.rpt) |
| $MC_{DEV}$        | = | Number of macrocells in the device  |
| $MC_{USED}$       | = | Total number of macrocells in the design, as reported in the MAX+PLUS II Report File (.rpt)                 |
| $f_{MAX}$         | = | Highest clock frequency to the device   |
| $\text{tog}_{LC}$ | = | Average ratio of logic cells toggling at each clock (typically 0.125)                                       |
| A, B, C           | = | Constants, shown in <a href="#">Table 39</a>  |

Figure 14.  $I_{CC}$  vs. Frequency for MAX 7000 Devices (Part 2 of 2)

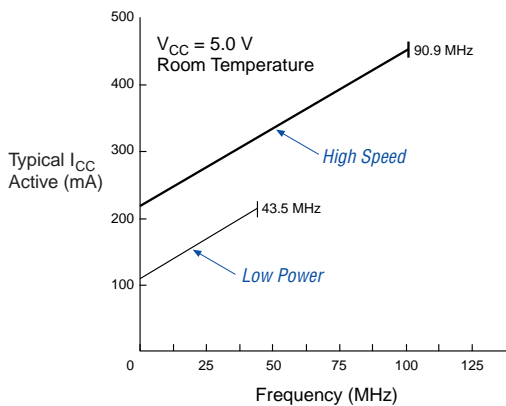
EPM7128E



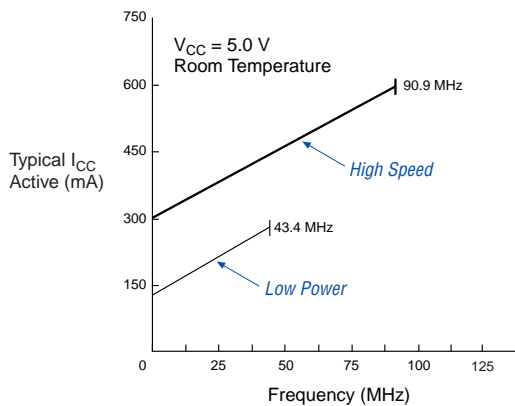
EPM7160E



EPM7192E



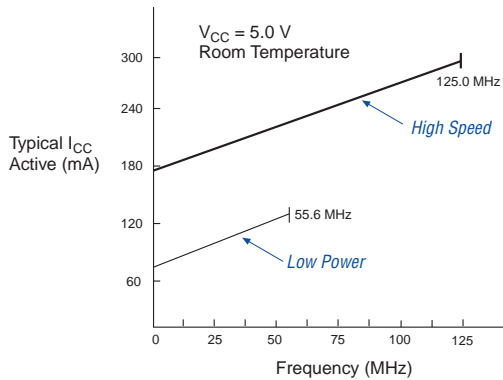
EPM7256E



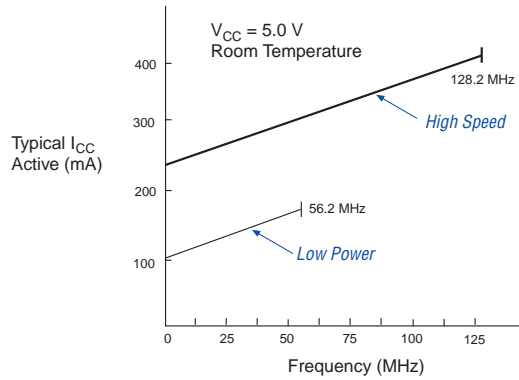


**Figure 15.  $I_{CC}$  vs. Frequency for MAX 7000S Devices (Part 2 of 2)**

EPM7192S



EPM7256S



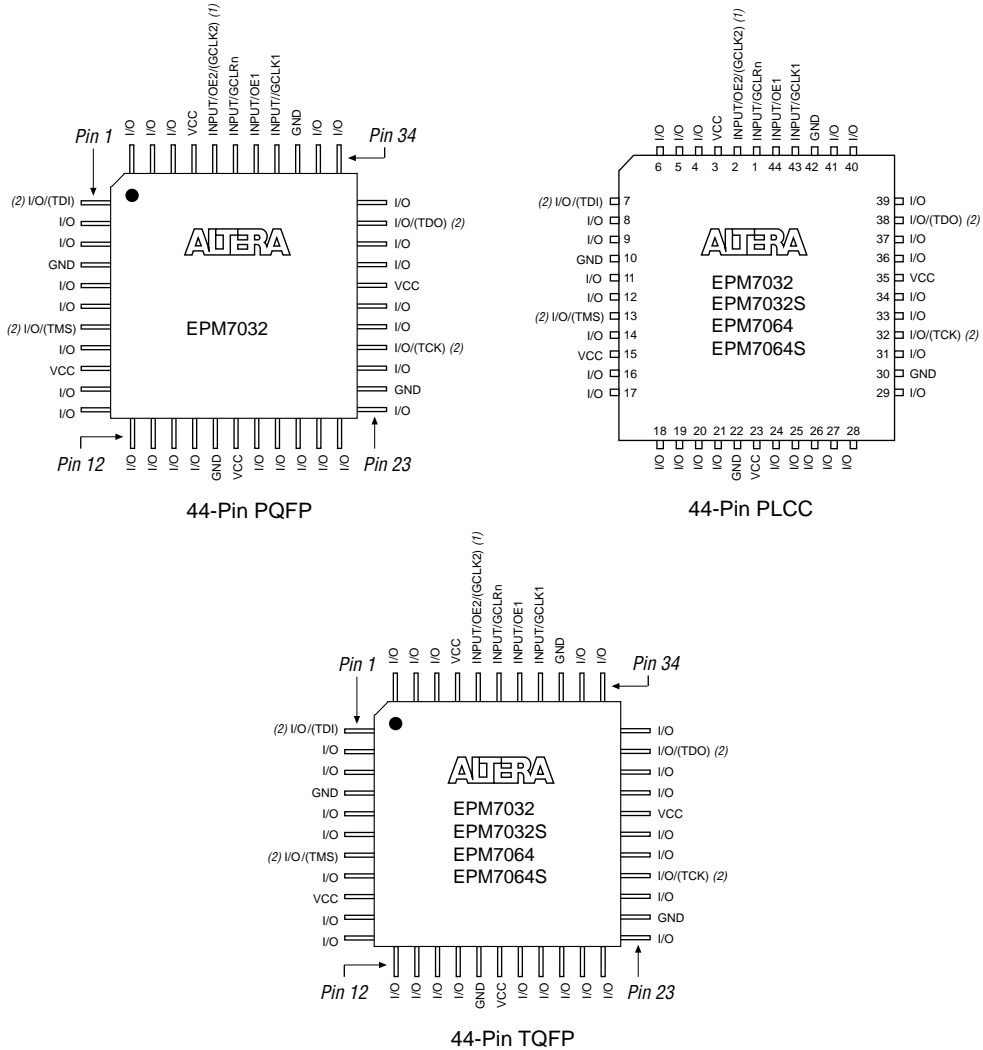
## Device Pin-Outs

See the Altera web site (<http://www.altera.com>) or the *Altera Digital Library* for pin-out information.

Figures 16 through 22 show the package pin-out diagrams for MAX 7000 devices.

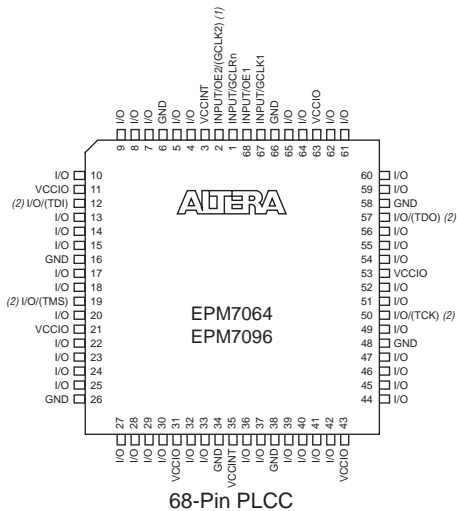
**Figure 16. 44-Pin Package Pin-Out Diagram**

Package outlines not drawn to scale.



**Notes:**

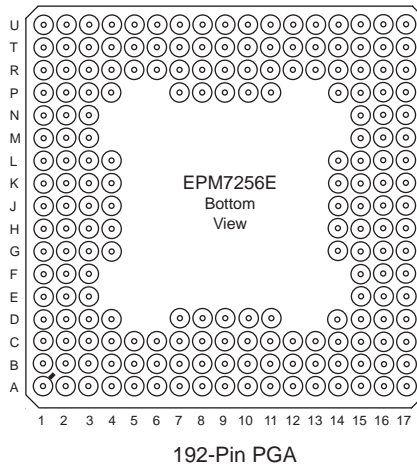
- (1) The pin functions shown in parenthesis are only available in MAX 7000E and MAX 7000S devices.
- (2) JTAG ports are available in MAX 7000S devices only.

**Figure 17. 68-Pin Package Pin-Out Diagram***Package outlines not drawn to scale.***Notes:**

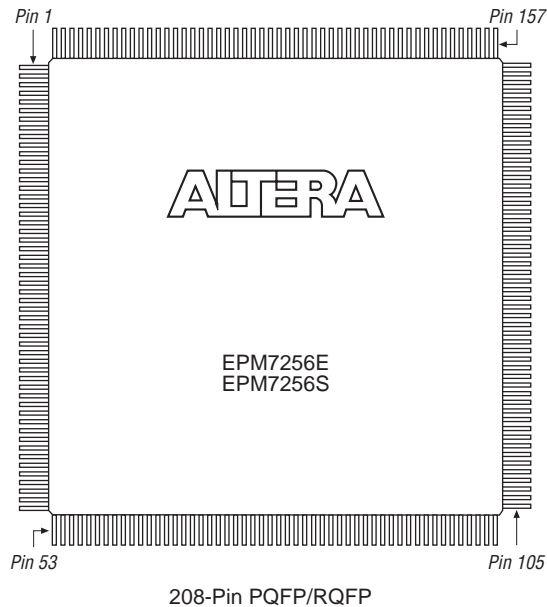
- (1) The pin functions shown in parenthesis are only available in MAX 7000E and MAX 7000S devices.
- (2) JTAG ports are available in MAX 7000S devices only.

**Figure 21. 192-Pin Package Pin-Out Diagram**

Package outline not drawn to scale.

**Figure 22. 208-Pin Package Pin-Out Diagram**

Package outline not drawn to scale.





101 Innovation Drive  
San Jose, CA 95134  
(408) 544-7000  
[www.altera.com](http://www.altera.com)  
[Applications Hotline:](tel:800800EPLD)  
(800) 800-EPLD  
[Literature Services:](mailto:literature@altera.com)  
[literature@altera.com](mailto:literature@altera.com)

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