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### Understanding [Embedded - CPLDs \(Complex Programmable Logic Devices\)](#)

Embedded - CPLDs, or Complex Programmable Logic Devices, are highly versatile digital logic devices used in electronic systems. These programmable components are designed to perform complex logical operations and can be customized for specific applications. Unlike fixed-function ICs, CPLDs offer the flexibility to reprogram their configuration, making them an ideal choice for various embedded systems. They consist of a set of logic gates and programmable interconnects, allowing designers to implement complex logic circuits without needing custom hardware.

### Applications of Embedded - CPLDs

#### Details

|                                 |   |
|---------------------------------|---|
| Product Status                  | Active  |
| Programmable Type               | EE PLD  |
| Delay Time tpd(1) Max           | 5 ns  |
| Voltage Supply - Internal       | 4.75V ~ 5.25V   |
| Number of Logic Elements/Blocks | 4   |
| Number of Macrocells            | 64  |
| Number of Gates                 | 1250  |
| Number of I/O                   | 68  |
| Operating Temperature           | 0°C ~ 70°C (TA)   |
| Mounting Type                   | Surface Mount   |
| Package / Case                  | 100-TQFP  |
| Supplier Device Package         | 100-TQFP (14x14)  |
| Purchase URL                    | <a href="https://www.e-xfl.com/pro/item?MUrl=&amp;PartUrl=epm7064stc100-5">https://www.e-xfl.com/pro/item?MUrl=&amp;PartUrl=epm7064stc100-5</a> |

Table 2. MAX 7000S Device Features

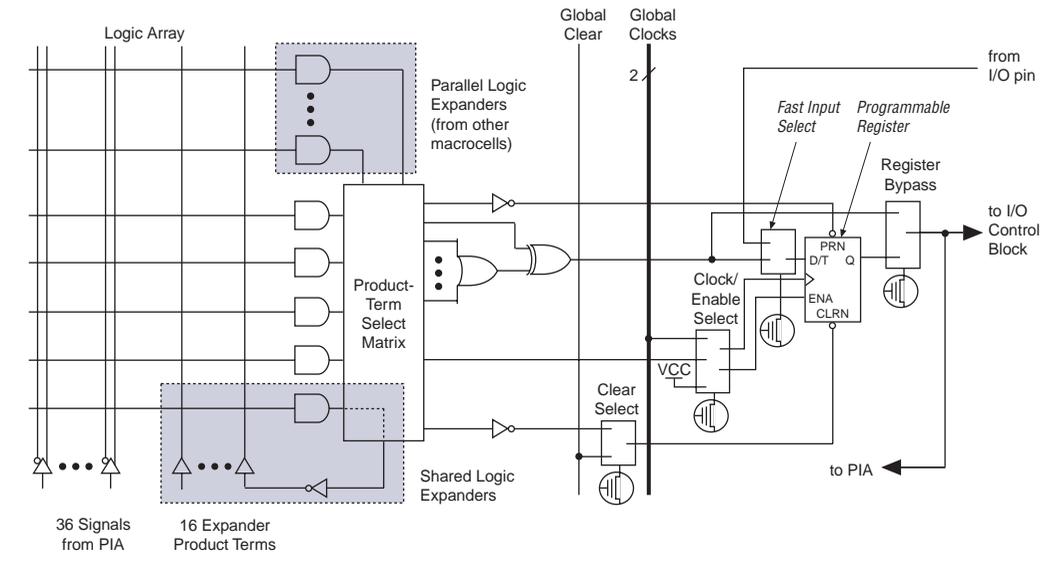
| Feature               | EPM7032S | EPM7064S | EPM7128S | EPM7160S | EPM7192S | EPM7256S |
|-----------------------|----------|----------|----------|----------|----------|----------|
| Usable gates          | 600      | 1,250    | 2,500    | 3,200    | 3,750    | 5,000    |
| Macrocells            | 32       | 64       | 128      | 160      | 192      | 256      |
| Logic array blocks    | 2        | 4        | 8        | 10       | 12       | 16       |
| Maximum user I/O pins | 36       | 68       | 100      | 104      | 124      | 164      |
| $t_{PD}$ (ns)         | 5        | 5        | 6        | 6        | 7.5      | 7.5      |
| $t_{SU}$ (ns)         | 2.9      | 2.9      | 3.4      | 3.4      | 4.1      | 3.9      |
| $t_{FSU}$ (ns)        | 2.5      | 2.5      | 2.5      | 2.5      | 3        | 3        |
| $t_{CO1}$ (ns)        | 3.2      | 3.2      | 4        | 3.9      | 4.7      | 4.7      |
| $f_{CNT}$ (MHz)       | 175.4    | 175.4    | 147.1    | 149.3    | 125.0    | 128.2    |

## ...and More Features

- Open-drain output option in MAX 7000S devices
- Programmable macrocell flipflops with individual clear, preset, clock, and clock enable controls
- Programmable power-saving mode for a reduction of over 50% in each macrocell
- Configurable expander product-term distribution, allowing up to 32 product terms per macrocell
- 44 to 208 pins available in plastic J-lead chip carrier (PLCC), ceramic pin-grid array (PGA), plastic quad flat pack (PQFP), power quad flat pack (RQFP), and 1.0-mm thin quad flat pack (TQFP) packages
- Programmable security bit for protection of proprietary designs
- 3.3-V or 5.0-V operation
  - MultiVolt™ I/O interface operation, allowing devices to interface with 3.3-V or 5.0-V devices (MultiVolt I/O operation is not available in 44-pin packages)
  - Pin compatible with low-voltage MAX 7000A and MAX 7000B devices
- Enhanced features available in MAX 7000E and MAX 7000S devices
  - Six pin- or logic-driven output enable signals
  - Two global clock signals with optional inversion
  - Enhanced interconnect resources for improved routability
  - Fast input setup times provided by a dedicated path from I/O pin to macrocell registers
  - Programmable output slew-rate control
- Software design support and automatic place-and-route provided by Altera's development system for Windows-based PCs and Sun SPARCstation, and HP 9000 Series 700/800 workstations

Figure 4 shows a MAX 7000E and MAX 7000S device macrocell.

Figure 4. MAX 7000E & MAX 7000S Device Macrocell



Combinatorial logic is implemented in the logic array, which provides five product terms per macrocell. The product-term select matrix allocates these product terms for use as either primary logic inputs (to the OR and XOR gates) to implement combinatorial functions, or as secondary inputs to the macrocell's register clear, preset, clock, and clock enable control functions. Two kinds of expander product terms ("expanders") are available to supplement macrocell logic resources:

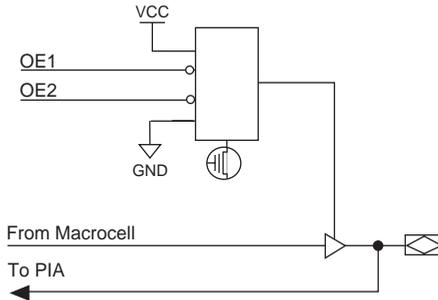
- Shareable expanders, which are inverted product terms that are fed back into the logic array
- Parallel expanders, which are product terms borrowed from adjacent macrocells

The Altera development system automatically optimizes product-term allocation according to the logic requirements of the design.

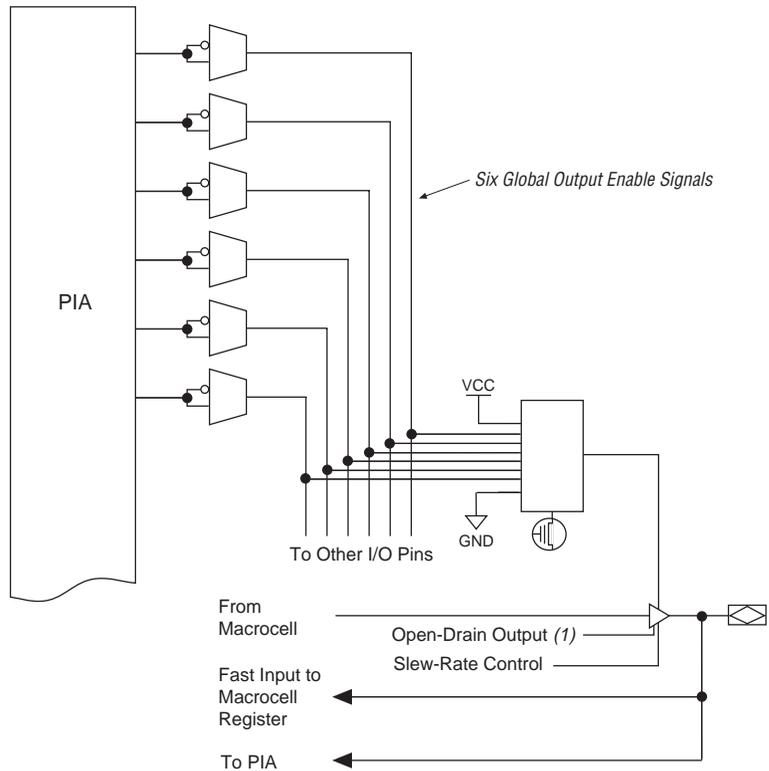
For registered functions, each macrocell flipflop can be individually programmed to implement D, T, JK, or SR operation with programmable clock control. The flipflop can be bypassed for combinatorial operation. During design entry, the designer specifies the desired flipflop type; the Altera development software then selects the most efficient flipflop operation for each registered function to optimize resource utilization.

**Figure 8. I/O Control Block of MAX 7000 Devices**

**EPM7032, EPM7064 & EPM7096 Devices**



**MAX 7000E & MAX 7000S Devices**



**Note:**

(1) The open-drain output option is available only in MAX 7000S devices.

When the tri-state buffer control is connected to ground, the output is tri-stated (high impedance) and the I/O pin can be used as a dedicated input. When the tri-state buffer control is connected to  $V_{CC}$ , the output is enabled.

The MAX 7000 architecture provides dual I/O feedback, in which macrocell and pin feedbacks are independent. When an I/O pin is configured as an input, the associated macrocell can be used for buried logic.

### **In-System Programmability (ISP)**

MAX 7000S devices are in-system programmable via an industry-standard 4-pin Joint Test Action Group (JTAG) interface (IEEE Std. 1149.1-1990). ISP allows quick, efficient iterations during design development and debugging cycles. The MAX 7000S architecture internally generates the high programming voltage required to program EEPROM cells, allowing in-system programming with only a single 5.0 V power supply. During in-system programming, the I/O pins are tri-stated and pulled-up to eliminate board conflicts. The pull-up value is nominally 50 k $\Omega$ .

ISP simplifies the manufacturing flow by allowing devices to be mounted on a printed circuit board with standard in-circuit test equipment before they are programmed. MAX 7000S devices can be programmed by downloading the information via in-circuit testers (ICT), embedded processors, or the Altera MasterBlaster, ByteBlasterMV, ByteBlaster, BitBlaster download cables. (The ByteBlaster cable is obsolete and is replaced by the ByteBlasterMV cable, which can program and configure 2.5-V, 3.3-V, and 5.0-V devices.) Programming the devices after they are placed on the board eliminates lead damage on high-pin-count packages (e.g., QFP packages) due to device handling and allows devices to be reprogrammed after a system has already shipped to the field. For example, product upgrades can be performed in the field via software or modem.

In-system programming can be accomplished with either an adaptive or constant algorithm. An adaptive algorithm reads information from the unit and adapts subsequent programming steps to achieve the fastest possible programming time for that unit. Because some in-circuit testers cannot support an adaptive algorithm, Altera offers devices tested with a constant algorithm. Devices tested to the constant algorithm have an "F" suffix in the ordering code.

The Jam™ Standard Test and Programming Language (STAPL) can be used to program MAX 7000S devices with in-circuit testers, PCs, or embedded processor.

## Programmable Speed/Power Control

MAX 7000 devices offer a power-saving mode that supports low-power operation across user-defined signal paths or the entire device. This feature allows total power dissipation to be reduced by 50% or more, because most logic applications require only a small fraction of all gates to operate at maximum frequency.

The designer can program each individual macrocell in a MAX 7000 device for either high-speed (i.e., with the Turbo Bit™ option turned on) or low-power (i.e., with the Turbo Bit option turned off) operation. As a result, speed-critical paths in the design can run at high speed, while the remaining paths can operate at reduced power. Macrocells that run at low power incur a nominal timing delay adder ( $t_{LPA}$ ) for the  $t_{LAD}$ ,  $t_{LAC}$ ,  $t_{IC}$ ,  $t_{EN}$ , and  $t_{SEXP}$ ,  $t_{ACL}$ , and  $t_{CPPW}$  parameters.

## Output Configuration

MAX 7000 device outputs can be programmed to meet a variety of system-level requirements.

### MultiVolt I/O Interface

MAX 7000 devices—except 44-pin devices—support the MultiVolt I/O interface feature, which allows MAX 7000 devices to interface with systems that have differing supply voltages. The 5.0-V devices in all packages can be set for 3.3-V or 5.0-V I/O pin operation. These devices have one set of VCC pins for internal operation and input buffers (VCCINT), and another set for I/O output drivers (VCCIO).

The VCCINT pins must always be connected to a 5.0-V power supply. With a 5.0-V VCCINT level, input voltage thresholds are at TTL levels, and are therefore compatible with both 3.3-V and 5.0-V inputs.

The VCCIO pins can be connected to either a 3.3-V or a 5.0-V power supply, depending on the output requirements. When the VCCIO pins are connected to a 5.0-V supply, the output levels are compatible with 5.0-V systems. When VCCIO is connected to a 3.3-V supply, the output high is 3.3 V and is therefore compatible with 3.3-V or 5.0-V systems. Devices operating with VCCIO levels lower than 4.75 V incur a nominally greater timing delay of  $t_{OD2}$  instead of  $t_{OD1}$ .

### Open-Drain Output Option (MAX 7000S Devices Only)

MAX 7000S devices provide an optional open-drain (functionally equivalent to open-collector) output for each I/O pin. This open-drain output enables the device to provide system-level control signals (e.g., interrupt and write enable signals) that can be asserted by any of several devices. It can also provide an additional wired-OR plane.

By using an external 5.0-V pull-up resistor, output pins on MAX 7000S devices can be set to meet 5.0-V CMOS input voltages. When  $V_{CCIO}$  is 3.3 V, setting the open drain option will turn off the output pull-up transistor, allowing the external pull-up resistor to pull the output high enough to meet 5.0-V CMOS input voltages. When  $V_{CCIO}$  is 5.0 V, setting the output drain option is not necessary because the pull-up transistor will already turn off when the pin exceeds approximately 3.8 V, allowing the external pull-up resistor to pull the output high enough to meet 5.0-V CMOS input voltages.

### Slew-Rate Control

The output buffer for each MAX 7000E and MAX 7000S I/O pin has an adjustable output slew rate that can be configured for low-noise or high-speed performance. A faster slew rate provides high-speed transitions for high-performance systems. However, these fast transitions may introduce noise transients into the system. A slow slew rate reduces system noise, but adds a nominal delay of 4 to 5 ns. In MAX 7000E devices, when the Turbo Bit is turned off, the slew rate is set for low noise performance. For MAX 7000S devices, each I/O pin has an individual EEPROM bit that controls the slew rate, allowing designers to specify the slew rate on a pin-by-pin basis.

## Programming with External Hardware

MAX 7000 devices can be programmed on Windows-based PCs with the Altera Logic Programmer card, the Master Programming Unit (MPU), and the appropriate device adapter. The MPU performs a continuity check to ensure adequate electrical contact between the adapter and the device.



For more information, see the [Altera Programming Hardware Data Sheet](#).

The Altera development system can use text- or waveform-format test vectors created with the Text Editor or Waveform Editor to test the programmed device. For added design verification, designers can perform functional testing to compare the functional behavior of a MAX 7000 device with the results of simulation. Moreover, Data I/O, BP Microsystems, and other programming hardware manufacturers also provide programming support for Altera devices.



For more information, see the [Programming Hardware Manufacturers](#).

Figure 9 shows the timing requirements for the JTAG signals.

**Figure 9. MAX 7000 JTAG Waveforms**

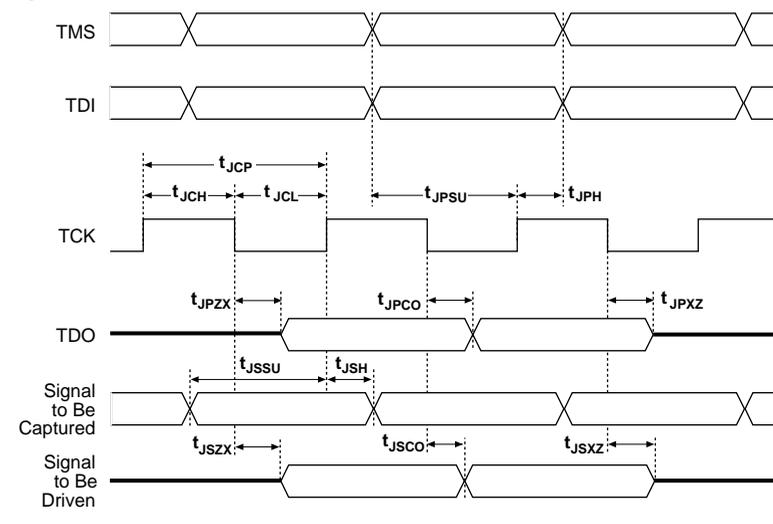


Table 12 shows the JTAG timing parameters and values for MAX 7000S devices.

| Symbol     | Parameter                                      | Min | Max | Unit |
|------------|--|-----|-----|------|
| $t_{JCP}$  | TCK clock period                               | 100 |     | ns   |
| $t_{JCH}$  | TCK clock high time                            | 50  |     | ns   |
| $t_{JCL}$  | TCK clock low time                             | 50  |     | ns   |
| $t_{JPSU}$ | JTAG port setup time                           | 20  |     | ns   |
| $t_{JPH}$  | JTAG port hold time                            | 45  |     | ns   |
| $t_{JPCO}$ | JTAG port clock to output                      |     | 25  | ns   |
| $t_{JPZX}$ | JTAG port high impedance to valid output       |     | 25  | ns   |
| $t_{JPXZ}$ | JTAG port valid output to high impedance       |     | 25  | ns   |
| $t_{JSSU}$ | Capture register setup time                    | 20  |     | ns   |
| $t_{JSH}$  | Capture register hold time                     | 45  |     | ns   |
| $t_{JSco}$ | Update register clock to output                |     | 25  | ns   |
| $t_{JSZX}$ | Update register high impedance to valid output |     | 25  | ns   |
| $t_{JSXZ}$ | Update register valid output to high impedance |     | 25  | ns   |



For more information, see [Application Note 39 \(IEEE 1149.1 \(JTAG\) Boundary-Scan Testing in Altera Devices\)](#).

## Design Security

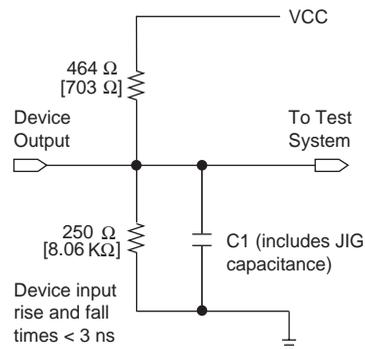
All MAX 7000 devices contain a programmable security bit that controls access to the data programmed into the device. When this bit is programmed, a proprietary design implemented in the device cannot be copied or retrieved. This feature provides a high level of design security because programmed data within EEPROM cells is invisible. The security bit that controls this function, as well as all other programmed data, is reset only when the device is reprogrammed.

## Generic Testing

Each MAX 7000 device is functionally tested. Complete testing of each programmable EEPROM bit and all internal logic elements ensures 100% programming yield. AC test measurements are taken under conditions equivalent to those shown in [Figure 10](#). Test patterns can be used and then erased during early stages of the production flow.

**Figure 10. MAX 7000 AC Test Conditions**

*Power supply transients can affect AC measurements. Simultaneous transitions of multiple outputs should be avoided for accurate measurement. Threshold tests must not be performed under AC conditions. Large-amplitude, fast ground-current transients normally occur as the device outputs discharge the load capacitances. When these transients flow through the parasitic inductance between the device ground pin and the test system ground, significant reductions in observable noise immunity can result. Numbers in brackets are for 2.5-V devices and outputs. Numbers without brackets are for 3.3-V devices and outputs.*



## QFP Carrier & Development Socket

MAX 7000 and MAX 7000E devices in QFP packages with 100 or more pins are shipped in special plastic carriers to protect the QFP leads. The carrier is used with a prototype development socket and special programming hardware available from Altera. This carrier technology makes it possible to program, test, erase, and reprogram a device without exposing the leads to mechanical stress.



For detailed information and carrier dimensions, refer to the [QFP Carrier & Development Socket Data Sheet](#).



MAX 7000S devices are not shipped in carriers.

Table 21. MAX 7000 & MAX 7000E External Timing Parameters *Note (1)*

| Symbol     | Parameter                                | Conditions     | Speed Grade      |      |                                   |      | Unit |
|------------|--|----------------|------------------|------|-----------------------------------|------|------|
|            |  |                | MAX 7000E (-10P) |      | MAX 7000 (-10)<br>MAX 7000E (-10) |      |      |
|            |  |                | Min              | Max  | Min                               | Max  |      |
| $t_{PD1}$  | Input to non-registered output           | C1 = 35 pF     |                  | 10.0 |                                   | 10.0 | ns   |
| $t_{PD2}$  | I/O input to non-registered output       | C1 = 35 pF     |                  | 10.0 |                                   | 10.0 | ns   |
| $t_{SU}$   | Global clock setup time                  |                | 7.0              |      | 8.0                               |      | ns   |
| $t_H$      | Global clock hold time                   |                | 0.0              |      | 0.0                               |      | ns   |
| $t_{FSU}$  | Global clock setup time of fast input    | (2)            | 3.0              |      | 3.0                               |      | ns   |
| $t_{FH}$   | Global clock hold time of fast input     | (2)            | 0.5              |      | 0.5                               |      | ns   |
| $t_{CO1}$  | Global clock to output delay             | C1 = 35 pF     |                  | 5.0  |                                   | 5    | ns   |
| $t_{CH}$   | Global clock high time                   |                | 4.0              |      | 4.0                               |      | ns   |
| $t_{CL}$   | Global clock low time                    |                | 4.0              |      | 4.0                               |      | ns   |
| $t_{ASU}$  | Array clock setup time                   |                | 2.0              |      | 3.0                               |      | ns   |
| $t_{AH}$   | Array clock hold time                    |                | 3.0              |      | 3.0                               |      | ns   |
| $t_{ACO1}$ | Array clock to output delay              | C1 = 35 pF     |                  | 10.0 |                                   | 10.0 | ns   |
| $t_{ACH}$  | Array clock high time                    |                | 4.0              |      | 4.0                               |      | ns   |
| $t_{ACL}$  | Array clock low time                     |                | 4.0              |      | 4.0                               |      | ns   |
| $t_{CPPW}$ | Minimum pulse width for clear and preset | (3)            | 4.0              |      | 4.0                               |      | ns   |
| $t_{ODH}$  | Output data hold time after clock        | C1 = 35 pF (4) | 1.0              |      | 1.0                               |      | ns   |
| $t_{CNT}$  | Minimum global clock period              |                |                  | 10.0 |                                   | 10.0 | ns   |
| $f_{CNT}$  | Maximum internal global clock frequency  | (5)            | 100.0            |      | 100.0                             |      | MHz  |
| $t_{ACNT}$ | Minimum array clock period               |                |                  | 10.0 |                                   | 10.0 | ns   |
| $f_{ACNT}$ | Maximum internal array clock frequency   | (5)            | 100.0            |      | 100.0                             |      | MHz  |
| $f_{MAX}$  | Maximum clock frequency                  | (6)            | 125.0            |      | 125.0                             |      | MHz  |

Table 22. MAX 7000 & MAX 7000E Internal Timing Parameters *Note (1)*

| Symbol     | Parameter   | Conditions              | Speed Grade      |      |                                   |      | Unit |
|------------|---|-------------------------|------------------|------|-----------------------------------|------|------|
|            |   |                         | MAX 7000E (-10P) |      | MAX 7000 (-10)<br>MAX 7000E (-10) |      |      |
|            |   |                         | Min              | Max  | Min                               | Max  |      |
| $t_{IN}$   | Input pad and buffer delay  |                         |                  | 0.5  |                                   | 1.0  | ns   |
| $t_{IO}$   | I/O input pad and buffer delay  |                         |                  | 0.5  |                                   | 1.0  | ns   |
| $t_{FIN}$  | Fast input delay  | (2)                     |                  | 1.0  |                                   | 1.0  | ns   |
| $t_{SEXP}$ | Shared expander delay   |                         |                  | 5.0  |                                   | 5.0  | ns   |
| $t_{PEXP}$ | Parallel expander delay   |                         |                  | 0.8  |                                   | 0.8  | ns   |
| $t_{LAD}$  | Logic array delay   |                         |                  | 5.0  |                                   | 5.0  | ns   |
| $t_{LAC}$  | Logic control array delay   |                         |                  | 5.0  |                                   | 5.0  | ns   |
| $t_{IOE}$  | Internal output enable delay  | (2)                     |                  | 2.0  |                                   | 2.0  | ns   |
| $t_{OD1}$  | Output buffer and pad delay<br>Slow slew rate = off<br>$V_{CCIO} = 5.0\text{ V}$                  | $C1 = 35\text{ pF}$     |                  | 1.5  |                                   | 2.0  | ns   |
| $t_{OD2}$  | Output buffer and pad delay<br>Slow slew rate = off<br>$V_{CCIO} = 3.3\text{ V}$                  | $C1 = 35\text{ pF}$ (7) |                  | 2.0  |                                   | 2.5  | ns   |
| $t_{OD3}$  | Output buffer and pad delay<br>Slow slew rate = on<br>$V_{CCIO} = 5.0\text{ V}$ or $3.3\text{ V}$ | $C1 = 35\text{ pF}$ (2) |                  | 5.5  |                                   | 6.0  | ns   |
| $t_{ZX1}$  | Output buffer enable delay<br>Slow slew rate = off<br>$V_{CCIO} = 5.0\text{ V}$                   | $C1 = 35\text{ pF}$     |                  | 5.0  |                                   | 5.0  | ns   |
| $t_{ZX2}$  | Output buffer enable delay<br>Slow slew rate = off<br>$V_{CCIO} = 3.3\text{ V}$                   | $C1 = 35\text{ pF}$ (7) |                  | 5.5  |                                   | 5.5  | ns   |
| $t_{ZX3}$  | Output buffer enable delay<br>Slow slew rate = on<br>$V_{CCIO} = 5.0\text{ V}$ or $3.3\text{ V}$  | $C1 = 35\text{ pF}$ (2) |                  | 9.0  |                                   | 9.0  | ns   |
| $t_{XZ}$   | Output buffer disable delay   | $C1 = 5\text{ pF}$      |                  | 5.0  |                                   | 5.0  | ns   |
| $t_{SU}$   | Register setup time   |                         | 2.0              |      | 3.0                               |      | ns   |
| $t_H$      | Register hold time  |                         | 3.0              |      | 3.0                               |      | ns   |
| $t_{FSU}$  | Register setup time of fast input   | (2)                     | 3.0              |      | 3.0                               |      | ns   |
| $t_{FH}$   | Register hold time of fast input  | (2)                     | 0.5              |      | 0.5                               |      | ns   |
| $t_{RD}$   | Register delay  |                         |                  | 2.0  |                                   | 1.0  | ns   |
| $t_{COMB}$ | Combinatorial delay   |                         |                  | 2.0  |                                   | 1.0  | ns   |
| $t_{IC}$   | Array clock delay   |                         |                  | 5.0  |                                   | 5.0  | ns   |
| $t_{EN}$   | Register enable time  |                         |                  | 5.0  |                                   | 5.0  | ns   |
| $t_{GLOB}$ | Global control delay  |                         |                  | 1.0  |                                   | 1.0  | ns   |
| $t_{PRE}$  | Register preset time  |                         |                  | 3.0  |                                   | 3.0  | ns   |
| $t_{CLR}$  | Register clear time   |                         |                  | 3.0  |                                   | 3.0  | ns   |
| $t_{PIA}$  | PIA delay   |                         |                  | 1.0  |                                   | 1.0  | ns   |
| $t_{LPA}$  | Low-power adder   | (8)                     |                  | 11.0 |                                   | 11.0 | ns   |

| Symbol     | Parameter   | Conditions              | Speed Grade      |      |                                   |      | Unit |
|------------|---|-------------------------|------------------|------|-----------------------------------|------|------|
|            |   |                         | MAX 7000E (-12P) |      | MAX 7000 (-12)<br>MAX 7000E (-12) |      |      |
|            |   |                         | Min              | Max  | Min                               | Max  |      |
| $t_{IN}$   | Input pad and buffer delay  |                         |                  | 1.0  |                                   | 2.0  | ns   |
| $t_{IO}$   | I/O input pad and buffer delay  |                         |                  | 1.0  |                                   | 2.0  | ns   |
| $t_{FIN}$  | Fast input delay  | (2)                     |                  | 1.0  |                                   | 1.0  | ns   |
| $t_{SEXP}$ | Shared expander delay   |                         |                  | 7.0  |                                   | 7.0  | ns   |
| $t_{PEXP}$ | Parallel expander delay   |                         |                  | 1.0  |                                   | 1.0  | ns   |
| $t_{LAD}$  | Logic array delay   |                         |                  | 7.0  |                                   | 5.0  | ns   |
| $t_{LAC}$  | Logic control array delay   |                         |                  | 5.0  |                                   | 5.0  | ns   |
| $t_{IOE}$  | Internal output enable delay  | (2)                     |                  | 2.0  |                                   | 2.0  | ns   |
| $t_{OD1}$  | Output buffer and pad delay<br>Slow slew rate = off<br>$V_{CCIO} = 5.0\text{ V}$                  | $C1 = 35\text{ pF}$     |                  | 1.0  |                                   | 3.0  | ns   |
| $t_{OD2}$  | Output buffer and pad delay<br>Slow slew rate = off<br>$V_{CCIO} = 3.3\text{ V}$                  | $C1 = 35\text{ pF}$ (7) |                  | 2.0  |                                   | 4.0  | ns   |
| $t_{OD3}$  | Output buffer and pad delay<br>Slow slew rate = on<br>$V_{CCIO} = 5.0\text{ V}$ or $3.3\text{ V}$ | $C1 = 35\text{ pF}$ (2) |                  | 5.0  |                                   | 7.0  | ns   |
| $t_{ZX1}$  | Output buffer enable delay<br>Slow slew rate = off<br>$V_{CCIO} = 5.0\text{ V}$                   | $C1 = 35\text{ pF}$     |                  | 6.0  |                                   | 6.0  | ns   |
| $t_{ZX2}$  | Output buffer enable delay<br>Slow slew rate = off<br>$V_{CCIO} = 3.3\text{ V}$                   | $C1 = 35\text{ pF}$ (7) |                  | 7.0  |                                   | 7.0  | ns   |
| $t_{ZX3}$  | Output buffer enable delay<br>Slow slew rate = on<br>$V_{CCIO} = 5.0\text{ V}$ or $3.3\text{ V}$  | $C1 = 35\text{ pF}$ (2) |                  | 10.0 |                                   | 10.0 | ns   |
| $t_{XZ}$   | Output buffer disable delay   | $C1 = 5\text{ pF}$      |                  | 6.0  |                                   | 6.0  | ns   |
| $t_{SU}$   | Register setup time   |                         | 1.0              |      | 4.0                               |      | ns   |
| $t_H$      | Register hold time  |                         | 6.0              |      | 4.0                               |      | ns   |
| $t_{FSU}$  | Register setup time of fast input   | (2)                     | 4.0              |      | 2.0                               |      | ns   |
| $t_{FH}$   | Register hold time of fast input  | (2)                     | 0.0              |      | 2.0                               |      | ns   |
| $t_{RD}$   | Register delay  |                         |                  | 2.0  |                                   | 1.0  | ns   |
| $t_{COMB}$ | Combinatorial delay   |                         |                  | 2.0  |                                   | 1.0  | ns   |
| $t_{IC}$   | Array clock delay   |                         |                  | 5.0  |                                   | 5.0  | ns   |
| $t_{EN}$   | Register enable time  |                         |                  | 7.0  |                                   | 5.0  | ns   |
| $t_{GLOB}$ | Global control delay  |                         |                  | 2.0  |                                   | 0.0  | ns   |
| $t_{PRE}$  | Register preset time  |                         |                  | 4.0  |                                   | 3.0  | ns   |
| $t_{CLR}$  | Register clear time   |                         |                  | 4.0  |                                   | 3.0  | ns   |
| $t_{PIA}$  | PIA delay   |                         |                  | 1.0  |                                   | 1.0  | ns   |
| $t_{LPA}$  | Low-power adder   | (8)                     |                  | 12.0 |                                   | 12.0 | ns   |

Table 32. EPM7128S Internal Timing Parameters *Note (1)*

| Symbol     | Parameter                         | Conditions     | Speed Grade |      |     |      |     |      |     |      | Unit |
|------------|-----------------------------------|----------------|-------------|------|-----|------|-----|------|-----|------|------|
|            |                                   |                | -6          |      | -7  |      | -10 |      | -15 |      |      |
|            |                                   |                | Min         | Max  | Min | Max  | Min | Max  | Min | Max  |      |
| $t_{IN}$   | Input pad and buffer delay        |                |             | 0.2  |     | 0.5  |     | 0.5  |     | 2.0  | ns   |
| $t_{IO}$   | I/O input pad and buffer delay    |                |             | 0.2  |     | 0.5  |     | 0.5  |     | 2.0  | ns   |
| $t_{FIN}$  | Fast input delay                  |                |             | 2.6  |     | 1.0  |     | 1.0  |     | 2.0  | ns   |
| $t_{SEXP}$ | Shared expander delay             |                |             | 3.7  |     | 4.0  |     | 5.0  |     | 8.0  | ns   |
| $t_{PEXP}$ | Parallel expander delay           |                |             | 1.1  |     | 0.8  |     | 0.8  |     | 1.0  | ns   |
| $t_{LAD}$  | Logic array delay                 |                |             | 3.0  |     | 3.0  |     | 5.0  |     | 6.0  | ns   |
| $t_{LAC}$  | Logic control array delay         |                |             | 3.0  |     | 3.0  |     | 5.0  |     | 6.0  | ns   |
| $t_{IOE}$  | Internal output enable delay      |                |             | 0.7  |     | 2.0  |     | 2.0  |     | 3.0  | ns   |
| $t_{OD1}$  | Output buffer and pad delay       | C1 = 35 pF     |             | 0.4  |     | 2.0  |     | 1.5  |     | 4.0  | ns   |
| $t_{OD2}$  | Output buffer and pad delay       | C1 = 35 pF (6) |             | 0.9  |     | 2.5  |     | 2.0  |     | 5.0  | ns   |
| $t_{OD3}$  | Output buffer and pad delay       | C1 = 35 pF     |             | 5.4  |     | 7.0  |     | 5.5  |     | 8.0  | ns   |
| $t_{ZX1}$  | Output buffer enable delay        | C1 = 35 pF     |             | 4.0  |     | 4.0  |     | 5.0  |     | 6.0  | ns   |
| $t_{ZX2}$  | Output buffer enable delay        | C1 = 35 pF (6) |             | 4.5  |     | 4.5  |     | 5.5  |     | 7.0  | ns   |
| $t_{ZX3}$  | Output buffer enable delay        | C1 = 35 pF     |             | 9.0  |     | 9.0  |     | 9.0  |     | 10.0 | ns   |
| $t_{XZ}$   | Output buffer disable delay       | C1 = 5 pF      |             | 4.0  |     | 4.0  |     | 5.0  |     | 6.0  | ns   |
| $t_{SU}$   | Register setup time               |                |             | 1.0  |     | 3.0  |     | 2.0  |     | 4.0  | ns   |
| $t_H$      | Register hold time                |                |             | 1.7  |     | 2.0  |     | 5.0  |     | 4.0  | ns   |
| $t_{FSU}$  | Register setup time of fast input |                |             | 1.9  |     | 3.0  |     | 3.0  |     | 2.0  | ns   |
| $t_{FH}$   | Register hold time of fast input  |                |             | 0.6  |     | 0.5  |     | 0.5  |     | 1.0  | ns   |
| $t_{RD}$   | Register delay                    |                |             | 1.4  |     | 1.0  |     | 2.0  |     | 1.0  | ns   |
| $t_{COMB}$ | Combinatorial delay               |                |             | 1.0  |     | 1.0  |     | 2.0  |     | 1.0  | ns   |
| $t_{IC}$   | Array clock delay                 |                |             | 3.1  |     | 3.0  |     | 5.0  |     | 6.0  | ns   |
| $t_{EN}$   | Register enable time              |                |             | 3.0  |     | 3.0  |     | 5.0  |     | 6.0  | ns   |
| $t_{GLOB}$ | Global control delay              |                |             | 2.0  |     | 1.0  |     | 1.0  |     | 1.0  | ns   |
| $t_{PRE}$  | Register preset time              |                |             | 2.4  |     | 2.0  |     | 3.0  |     | 4.0  | ns   |
| $t_{CLR}$  | Register clear time               |                |             | 2.4  |     | 2.0  |     | 3.0  |     | 4.0  | ns   |
| $t_{PIA}$  | PIA delay                         | (7)            |             | 1.4  |     | 1.0  |     | 1.0  |     | 2.0  | ns   |
| $t_{LPA}$  | Low-power adder                   | (8)            |             | 11.0 |     | 10.0 |     | 11.0 |     | 13.0 | ns   |

**Table 34. EPM7160S Internal Timing Parameters (Part 2 of 2)** *Note (1)*

| Symbol    | Parameter           | Conditions | Speed Grade |      |     |      |     |      |     |      | Unit |
|-----------|---------------------|------------|-------------|------|-----|------|-----|------|-----|------|------|
|           |                     |            | -6          |      | -7  |      | -10 |      | -15 |      |      |
|           |                     |            | Min         | Max  | Min | Max  | Min | Max  | Min | Max  |      |
| $t_{CLR}$ | Register clear time |            |             | 2.4  |     | 3.0  |     | 3.0  |     | 4.0  | ns   |
| $t_{PIA}$ | PIA delay           | (7)        |             | 1.6  |     | 2.0  |     | 1.0  |     | 2.0  | ns   |
| $t_{LPA}$ | Low-power adder     | (8)        |             | 11.0 |     | 10.0 |     | 11.0 |     | 13.0 | ns   |

**Notes to tables:**

- (1) These values are specified under the recommended operating conditions shown in Table 14. See Figure 13 for more information on switching waveforms.
- (2) This minimum pulse width for preset and clear applies for both global clear and array controls. The  $t_{LPA}$  parameter must be added to this minimum width if the clear or reset signal incorporates the  $t_{LAD}$  parameter into the signal path.
- (3) This parameter is a guideline that is sample-tested only and is based on extensive device characterization. This parameter applies for both global and array clocking.
- (4) These parameters are measured with a 16-bit loadable, enabled, up/down counter programmed into each LAB.
- (5) The  $f_{MAX}$  values represent the highest frequency for pipelined data.
- (6) Operating conditions:  $V_{CCIO} = 3.3 V \pm 10\%$  for commercial and industrial use.
- (7) For EPM7064S-5, EPM7064S-6, EPM7128S-6, EPM7160S-6, EPM7160S-7, EPM7192S-7, and EPM7256S-7 devices, these values are specified for a PIA fan-out of one LAB (16 macrocells). For each additional LAB fan-out in these devices, add an additional 0.1 ns to the PIA timing value.
- (8) The  $t_{LPA}$  parameter must be added to the  $t_{LAD}$ ,  $t_{LAC}$ ,  $t_{IC}$ ,  $t_{EN}$ ,  $t_{SEXP}$ ,  $t_{ACL}$  and  $t_{CPPW}$  parameters for macrocells running in the low-power mode.

Tables 35 and 36 show the EPM7192S AC operating conditions.

**Table 35. EPM7192S External Timing Parameters (Part 1 of 2)** *Note (1)*

| Symbol    | Parameter                             | Conditions | Speed Grade |     |     |      |      |      | Unit |
|-----------|---------------------------------------|------------|-------------|-----|-----|------|------|------|------|
|           |                                       |            | -7          |     | -10 |      | -15  |      |      |
|           |                                       |            | Min         | Max | Min | Max  | Min  | Max  |      |
| $t_{PD1}$ | Input to non-registered output        | C1 = 35 pF |             | 7.5 |     | 10.0 |      | 15.0 | ns   |
| $t_{PD2}$ | I/O input to non-registered output    | C1 = 35 pF |             | 7.5 |     | 10.0 |      | 15.0 | ns   |
| $t_{SU}$  | Global clock setup time               |            | 4.1         |     | 7.0 |      | 11.0 |      | ns   |
| $t_H$     | Global clock hold time                |            | 0.0         |     | 0.0 |      | 0.0  |      | ns   |
| $t_{FSU}$ | Global clock setup time of fast input |            | 3.0         |     | 3.0 |      | 3.0  |      | ns   |
| $t_{FH}$  | Global clock hold time of fast input  |            | 0.0         |     | 0.5 |      | 0.0  |      | ns   |
| $t_{CO1}$ | Global clock to output delay          | C1 = 35 pF |             | 4.7 |     | 5.0  |      | 8.0  | ns   |
| $t_{CH}$  | Global clock high time                |            | 3.0         |     | 4.0 |      | 5.0  |      | ns   |
| $t_{CL}$  | Global clock low time                 |            | 3.0         |     | 4.0 |      | 5.0  |      | ns   |
| $t_{ASU}$ | Array clock setup time                |            | 1.0         |     | 2.0 |      | 4.0  |      | ns   |

Table 35. EPM7192S External Timing Parameters (Part 2 of 2) *Note (1)*

| Symbol     | Parameter                                | Conditions     | Speed Grade |     |       |      |       |      | Unit |
|------------|--|----------------|-------------|-----|-------|------|-------|------|------|
|            |  |                | -7          |     | -10   |      | -15   |      |      |
|            |  |                | Min         | Max | Min   | Max  | Min   | Max  |      |
| $t_{AH}$   | Array clock hold time                    |                | 1.8         |     | 3.0   |      | 4.0   |      | ns   |
| $t_{ACO1}$ | Array clock to output delay              | C1 = 35 pF     |             | 7.8 |       | 10.0 |       | 15.0 | ns   |
| $t_{ACH}$  | Array clock high time                    |                | 3.0         |     | 4.0   |      | 6.0   |      | ns   |
| $t_{ACL}$  | Array clock low time                     |                | 3.0         |     | 4.0   |      | 6.0   |      | ns   |
| $t_{CPPW}$ | Minimum pulse width for clear and preset | (2)            | 3.0         |     | 4.0   |      | 6.0   |      | ns   |
| $t_{ODH}$  | Output data hold time after clock        | C1 = 35 pF (3) | 1.0         |     | 1.0   |      | 1.0   |      | ns   |
| $t_{CNT}$  | Minimum global clock period              |                |             | 8.0 |       | 10.0 |       | 13.0 | ns   |
| $f_{CNT}$  | Maximum internal global clock frequency  | (4)            | 125.0       |     | 100.0 |      | 76.9  |      | MHz  |
| $t_{ACNT}$ | Minimum array clock period               |                |             | 8.0 |       | 10.0 |       | 13.0 | ns   |
| $f_{ACNT}$ | Maximum internal array clock frequency   | (4)            | 125.0       |     | 100.0 |      | 76.9  |      | MHz  |
| $f_{MAX}$  | Maximum clock frequency                  | (5)            | 166.7       |     | 125.0 |      | 100.0 |      | MHz  |

Table 36. EPM7192S Internal Timing Parameters (Part 1 of 2) *Note (1)*

| Symbol     | Parameter                      | Conditions     | Speed Grade |     |     |     |     |      | Unit |
|------------|--------------------------------|----------------|-------------|-----|-----|-----|-----|------|------|
|            |                                |                | -7          |     | -10 |     | -15 |      |      |
|            |                                |                | Min         | Max | Min | Max | Min | Max  |      |
| $t_{IN}$   | Input pad and buffer delay     |                |             | 0.3 |     | 0.5 |     | 2.0  | ns   |
| $t_{IO}$   | I/O input pad and buffer delay |                |             | 0.3 |     | 0.5 |     | 2.0  | ns   |
| $t_{FIN}$  | Fast input delay               |                |             | 3.2 |     | 1.0 |     | 2.0  | ns   |
| $t_{SEXP}$ | Shared expander delay          |                |             | 4.2 |     | 5.0 |     | 8.0  | ns   |
| $t_{PEXP}$ | Parallel expander delay        |                |             | 1.2 |     | 0.8 |     | 1.0  | ns   |
| $t_{LAD}$  | Logic array delay              |                |             | 3.1 |     | 5.0 |     | 6.0  | ns   |
| $t_{LAC}$  | Logic control array delay      |                |             | 3.1 |     | 5.0 |     | 6.0  | ns   |
| $t_{IOE}$  | Internal output enable delay   |                |             | 0.9 |     | 2.0 |     | 3.0  | ns   |
| $t_{OD1}$  | Output buffer and pad delay    | C1 = 35 pF     |             | 0.5 |     | 1.5 |     | 4.0  | ns   |
| $t_{OD2}$  | Output buffer and pad delay    | C1 = 35 pF (6) |             | 1.0 |     | 2.0 |     | 5.0  | ns   |
| $t_{OD3}$  | Output buffer and pad delay    | C1 = 35 pF     |             | 5.5 |     | 5.5 |     | 7.0  | ns   |
| $t_{ZX1}$  | Output buffer enable delay     | C1 = 35 pF     |             | 4.0 |     | 5.0 |     | 6.0  | ns   |
| $t_{ZX2}$  | Output buffer enable delay     | C1 = 35 pF (6) |             | 4.5 |     | 5.5 |     | 7.0  | ns   |
| $t_{ZX3}$  | Output buffer enable delay     | C1 = 35 pF     |             | 9.0 |     | 9.0 |     | 10.0 | ns   |
| $t_{XZ}$   | Output buffer disable delay    | C1 = 5 pF      |             | 4.0 |     | 5.0 |     | 6.0  | ns   |
| $t_{SU}$   | Register setup time            |                | 1.1         |     | 2.0 |     | 4.0 |      | ns   |

Tables 37 and 38 show the EPM7256S AC operating conditions.

| Symbol     | Parameter                                | Conditions     | Speed Grade |     |       |      |       |      | Unit |
|------------|--|----------------|-------------|-----|-------|------|-------|------|------|
|            |  |                | -7          |     | -10   |      | -15   |      |      |
|            |  |                | Min         | Max | Min   | Max  | Min   | Max  |      |
| $t_{PD1}$  | Input to non-registered output           | C1 = 35 pF     |             | 7.5 |       | 10.0 |       | 15.0 | ns   |
| $t_{PD2}$  | I/O input to non-registered output       | C1 = 35 pF     |             | 7.5 |       | 10.0 |       | 15.0 | ns   |
| $t_{SU}$   | Global clock setup time                  |                | 3.9         |     | 7.0   |      | 11.0  |      | ns   |
| $t_H$      | Global clock hold time                   |                | 0.0         |     | 0.0   |      | 0.0   |      | ns   |
| $t_{FSU}$  | Global clock setup time of fast input    |                | 3.0         |     | 3.0   |      | 3.0   |      | ns   |
| $t_{FH}$   | Global clock hold time of fast input     |                | 0.0         |     | 0.5   |      | 0.0   |      | ns   |
| $t_{CO1}$  | Global clock to output delay             | C1 = 35 pF     |             | 4.7 |       | 5.0  |       | 8.0  | ns   |
| $t_{CH}$   | Global clock high time                   |                | 3.0         |     | 4.0   |      | 5.0   |      | ns   |
| $t_{CL}$   | Global clock low time                    |                | 3.0         |     | 4.0   |      | 5.0   |      | ns   |
| $t_{ASU}$  | Array clock setup time                   |                | 0.8         |     | 2.0   |      | 4.0   |      | ns   |
| $t_{AH}$   | Array clock hold time                    |                | 1.9         |     | 3.0   |      | 4.0   |      | ns   |
| $t_{ACO1}$ | Array clock to output delay              | C1 = 35 pF     |             | 7.8 |       | 10.0 |       | 15.0 | ns   |
| $t_{ACH}$  | Array clock high time                    |                | 3.0         |     | 4.0   |      | 6.0   |      | ns   |
| $t_{ACL}$  | Array clock low time                     |                | 3.0         |     | 4.0   |      | 6.0   |      | ns   |
| $t_{CPW}$  | Minimum pulse width for clear and preset | (2)            | 3.0         |     | 4.0   |      | 6.0   |      | ns   |
| $t_{ODH}$  | Output data hold time after clock        | C1 = 35 pF (3) | 1.0         |     | 1.0   |      | 1.0   |      | ns   |
| $t_{CNT}$  | Minimum global clock period              |                |             | 7.8 |       | 10.0 |       | 13.0 | ns   |
| $f_{CNT}$  | Maximum internal global clock frequency  | (4)            | 128.2       |     | 100.0 |      | 76.9  |      | MHz  |
| $t_{ACNT}$ | Minimum array clock period               |                |             | 7.8 |       | 10.0 |       | 13.0 | ns   |
| $f_{ACNT}$ | Maximum internal array clock frequency   | (4)            | 128.2       |     | 100.0 |      | 76.9  |      | MHz  |
| $f_{MAX}$  | Maximum clock frequency                  | (5)            | 166.7       |     | 125.0 |      | 100.0 |      | MHz  |

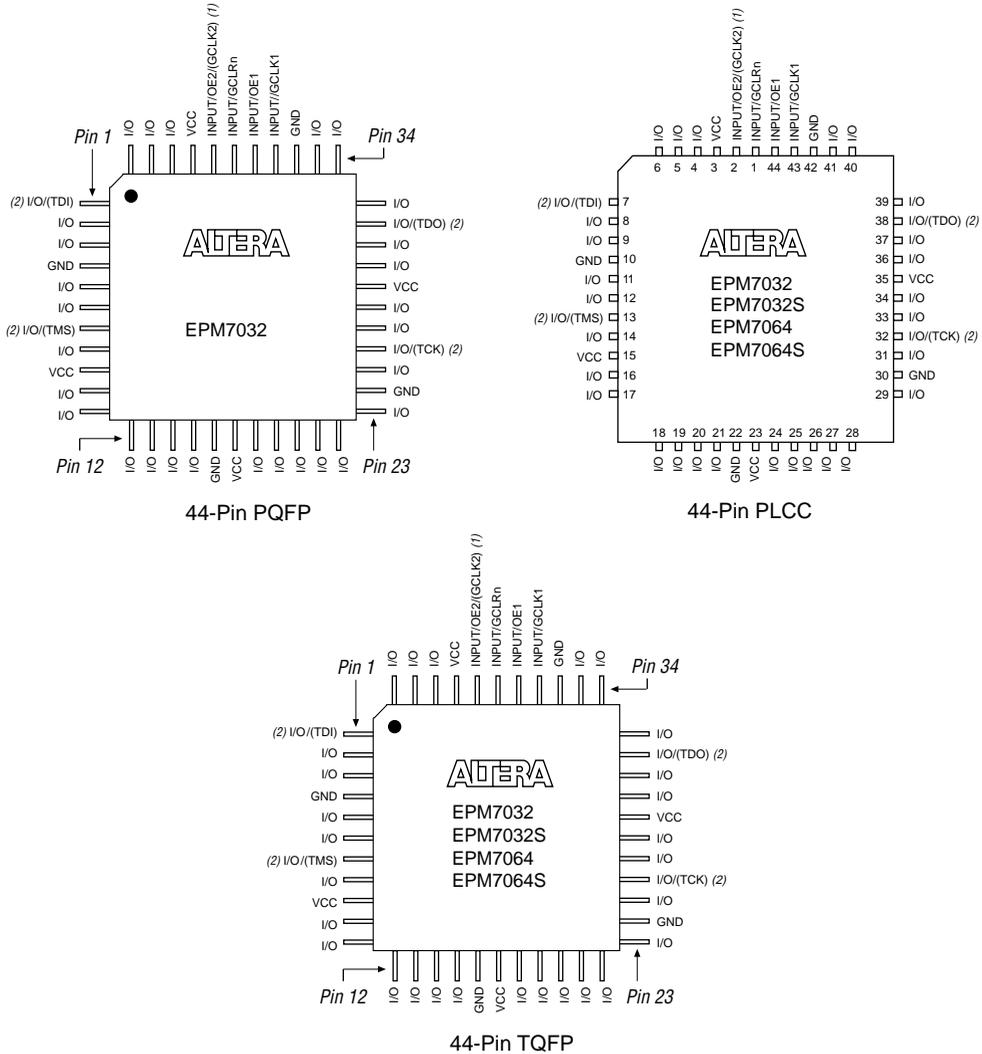
| <b>Device</b> | <b>A</b> | <b>B</b> | <b>C</b> |
|---------------|----------|----------|----------|
| EPM7032       | 1.87     | 0.52     | 0.144    |
| EPM7064       | 1.63     | 0.74     | 0.144    |
| EPM7096       | 1.63     | 0.74     | 0.144    |
| EPM7128E      | 1.17     | 0.54     | 0.096    |
| EPM7160E      | 1.17     | 0.54     | 0.096    |
| EPM7192E      | 1.17     | 0.54     | 0.096    |
| EPM7256E      | 1.17     | 0.54     | 0.096    |
| EPM7032S      | 0.93     | 0.40     | 0.040    |
| EPM7064S      | 0.93     | 0.40     | 0.040    |
| EPM7128S      | 0.93     | 0.40     | 0.040    |
| EPM7160S      | 0.93     | 0.40     | 0.040    |
| EPM7192S      | 0.93     | 0.40     | 0.040    |
| EPM7256S      | 0.93     | 0.40     | 0.040    |

This calculation provides an  $I_{CC}$  estimate based on typical conditions using a pattern of a 16-bit, loadable, enabled, up/down counter in each LAB with no output load. Actual  $I_{CC}$  values should be verified during operation because this measurement is sensitive to the actual pattern in the device and the environmental operating conditions.

Figures 16 through 22 show the package pin-out diagrams for MAX 7000 devices.

**Figure 16. 44-Pin Package Pin-Out Diagram**

Package outlines not drawn to scale.

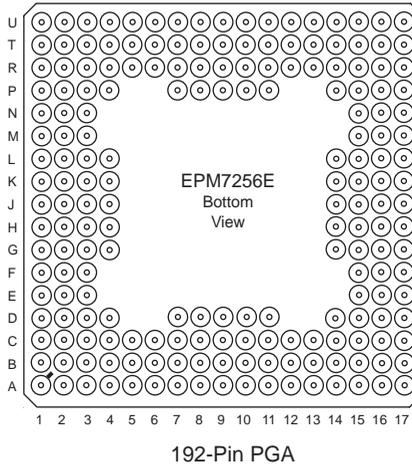


**Notes:**

- (1) The pin functions shown in parenthesis are only available in MAX 7000E and MAX 7000S devices.
- (2) JTAG ports are available in MAX 7000S devices only.

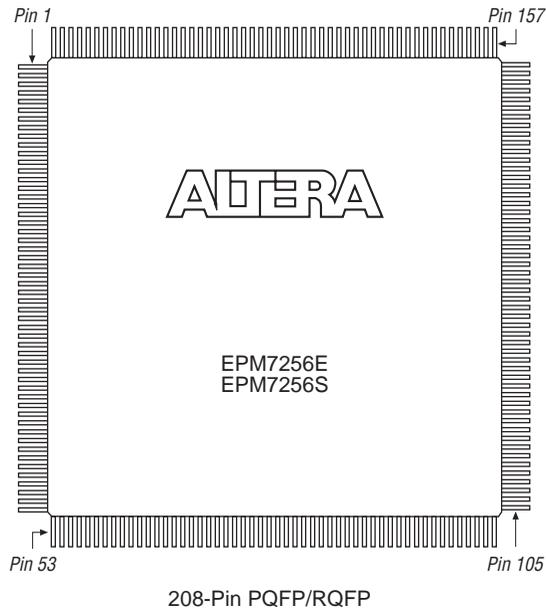
**Figure 21. 192-Pin Package Pin-Out Diagram**

Package outline not drawn to scale.



**Figure 22. 208-Pin Package Pin-Out Diagram**

Package outline not drawn to scale.



## Revision History

The information contained in the *MAX 7000 Programmable Logic Device Family Data Sheet* version 6.7 supersedes information published in previous versions. The following changes were made in the *MAX 7000 Programmable Logic Device Family Data Sheet* version 6.7:

### Version 6.7

The following changes were made in the *MAX 7000 Programmable Logic Device Family Data Sheet* version 6.7:

- Reference to *AN 88: Using the Jam Language for ISP & ICR via an Embedded Processor* has been replaced by *AN 122: Using Jam STAPL for ISP & ICR via an Embedded Processor*.

### Version 6.6

The following changes were made in the *MAX 7000 Programmable Logic Device Family Data Sheet* version 6.6:

- Added [Tables 6 through 8](#).
- Added [“Programming Sequence” section on page 17](#) and [“Programming Times” section on page 18](#).

### Version 6.5

The following changes were made in the *MAX 7000 Programmable Logic Device Family Data Sheet* version 6.5:

- Updated text on [page 16](#).

### Version 6.4

The following changes were made in the *MAX 7000 Programmable Logic Device Family Data Sheet* version 6.4:

- Added [Note \(5\) on page 28](#).

### Version 6.3

The following changes were made in the *MAX 7000 Programmable Logic Device Family Data Sheet* version 6.3:

- Updated the [“Open-Drain Output Option \(MAX 7000S Devices Only\)” section on page 20](#).



*Notes:*