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Understanding [Embedded - FPGAs \(Field Programmable Gate Array\)](#)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details

Product Status	Obsolete
Number of LABs/CLBs	3537
Number of Logic Elements/Cells	75000
Total RAM Bits	8666112
Number of I/O	336
Number of Gates	-
Voltage - Supply	1.07V ~ 1.13V
Mounting Type	Surface Mount
Operating Temperature	-40°C ~ 100°C (TJ)
Package / Case	672-BBGA, FCBGA
Supplier Device Package	672-FBGA (27x27)
Purchase URL	https://www.e-xfl.com/product-detail/intel/5agxba1d4f27i5

Symbol	Description	Condition	Minimum ⁽¹⁾	Typical	Maximum ⁽¹⁾	Unit
V_{CC}	Core voltage power supply	–C4, –I5, –C5, –C6	1.07	1.1	1.13	V
		–I3	1.12	1.15	1.18	V
V_{CCP}	Periphery circuitry, PCIe hard IP block, and transceiver PCS power supply	–C4, –I5, –C5, –C6	1.07	1.1	1.13	V
		–I3	1.12	1.15	1.18	V
V_{CCPGM}	Configuration pins power supply	3.3 V	3.135	3.3	3.465	V
		3.0 V	2.85	3.0	3.15	V
		2.5 V	2.375	2.5	2.625	V
		1.8 V	1.71	1.8	1.89	V
V_{CC_AUX}	Auxiliary supply	—	2.375	2.5	2.625	V
$V_{CCBAT}^{(2)}$	Battery back-up power supply (For design security volatile key register)	—	1.2	—	3.0	V
$V_{CCPD}^{(3)}$	I/O pre-driver power supply	3.3 V	3.135	3.3	3.465	V
		3.0 V	2.85	3.0	3.15	V
		2.5 V	2.375	2.5	2.625	V

⁽¹⁾ The power supply value describes the budget for the DC (static) power supply tolerance and does not include the dynamic tolerance requirements. Refer to the PDN tool for the additional budget for the dynamic tolerance requirements.

⁽²⁾ If you do not use the design security feature in Arria V devices, connect V_{CCBAT} to a 1.5-V, 2.5-V, or 3.0-V power supply. Arria V power-on reset (POR) circuitry monitors V_{CCBAT} . Arria V devices do not exit POR if V_{CCBAT} is not powered up.

⁽³⁾ V_{CCPD} must be 2.5 V when V_{CCIO} is 2.5, 1.8, 1.5, 1.35, 1.25, or 1.2 V. V_{CCPD} must be 3.0 V when V_{CCIO} is 3.0 V. V_{CCPD} must be 3.3 V when V_{CCIO} is 3.3 V.

Symbol	Description	Minimum ⁽⁵⁾	Typical	Maximum ⁽⁵⁾	Unit
V _{CCL_GXBL}	GX and SX speed grades—clock network power (left side)	1.08/1.12	1.1/1.15 ⁽⁶⁾	1.14/1.18	V
V _{CCL_GXBR}	GX and SX speed grades—clock network power (right side)				
V _{CCL_GXBL}	GT and ST speed grades—clock network power (left side)	1.17	1.20	1.23	V
V _{CCL_GXBR}	GT and ST speed grades—clock network power (right side)				

Related Information**Arria V GT, GX, ST, and SX Device Family Pin Connection Guidelines**

Provides more information about the power supply connection for different data rates.

HPS Power Supply Operating Conditions**Table 1-5: HPS Power Supply Operating Conditions for Arria V SX and ST Devices**

This table lists the steady-state voltage and current values expected from Arria V system-on-a-chip (SoC) devices with ARM®-based hard processor system (HPS). Power supply ramps must all be strictly monotonic, without plateaus. Refer to Recommended Operating Conditions for Arria V Devices table for the steady-state voltage values expected from the FPGA portion of the Arria V SoC devices.

Symbol	Description	Condition	Minimum ⁽⁷⁾	Typical	Maximum ⁽⁷⁾	Unit
V _{CC_HPS}	HPS core voltage and periphery circuitry power supply	–C4, –I5, –C5, –C6	1.07	1.1	1.13	V
		–I3	1.12	1.15	1.18	V

⁽⁵⁾ The power supply value describes the budget for the DC (static) power supply tolerance and does not include the dynamic tolerance requirements. Refer to the PDN tool for the additional budget for the dynamic tolerance requirements.

⁽⁷⁾ The power supply value describes the budget for the DC (static) power supply tolerance and does not include the dynamic tolerance requirements. Refer to the PDN tool for the additional budget for the dynamic tolerance requirements.

Table 1-21: Transceiver Clocks Specifications for Arria V GX and SX Devices

Symbol/Description	Condition	Transceiver Speed Grade 4			Transceiver Speed Grade 6			Unit
		Min	Typ	Max	Min	Typ	Max	
fixedclk clock frequency	PCIe Receiver Detect	—	125	—	—	125	—	MHz
Transceiver Reconfiguration Controller IP (mgmt_clk_clk) clock frequency	—	75	—	125	75	—	125	MHz

Table 1-22: Receiver Specifications for Arria V GX and SX Devices

Symbol/Description	Condition	Transceiver Speed Grade 4			Transceiver Speed Grade 6			Unit
		Min	Typ	Max	Min	Typ	Max	
Supported I/O standards	1.5 V PCML, 2.5 V PCML, LVPECL, and LVDS							
Data rate ⁽²⁸⁾	—	611	—	6553.6	611	—	3125	Mbps
Absolute V _{MAX} for a receiver pin ⁽²⁹⁾	—	—	—	1.2	—	—	1.2	V
Absolute V _{MIN} for a receiver pin	—	−0.4	—	—	−0.4	—	—	V
Maximum peak-to-peak differential input voltage V _{ID} (diff p-p) before device configuration	—	—	—	1.6	—	—	1.6	V
Maximum peak-to-peak differential input voltage V _{ID} (diff p-p) after device configuration	—	—	—	2.2	—	—	2.2	V

⁽²⁸⁾ To support data rates lower than the minimum specification through oversampling, use the CDR in LTR mode only.⁽²⁹⁾ The device cannot tolerate prolonged operation at this absolute maximum.

Typical TX V_{OD} Setting for Arria V Transceiver Channels with termination of 100 Ω Table 1-32: Typical TX V_{OD} Setting for Arria V Transceiver Channels with termination of 100 Ω

Symbol	V_{OD} Setting ⁽⁵⁸⁾	V_{OD} Value (mV)	V_{OD} Setting ⁽⁵⁸⁾	V_{OD} Value (mV)
V_{OD} differential peak-to-peak typical	6 ⁽⁵⁹⁾	120	34	680
	7 ⁽⁵⁹⁾	140	35	700
	8 ⁽⁵⁹⁾	160	36	720
	9	180	37	740
	10	200	38	760
	11	220	39	780
	12	240	40	800
	13	260	41	820
	14	280	42	840
	15	300	43	860
	16	320	44	880
	17	340	45	900
	18	360	46	920
	19	380	47	940
	20	400	48	960
	21	420	49	980
	22	440	50	1000
	23	460	51	1020
	24	480	52	1040

⁽⁵⁸⁾ Convert these values to their binary equivalent form if you are using the dynamic reconfiguration mode for PMA analog controls.⁽⁵⁹⁾ Only valid for data rates ≤ 5 Gbps.

Table 1-34: Transceiver Compliance Specification for All Supported Protocol for Arria V GX, GT, SX, and ST Devices

Protocol	Sub-protocol	Data Rate (Mbps)
PCIe	PCIe Gen1	2,500
	PCIe Gen2	5,000
	PCIe Cable	2,500
XAUI	XAUI 2135	3,125
Serial RapidIO® (SRIO)	SRIO 1250 SR	1,250
	SRIO 1250 LR	1,250
	SRIO 2500 SR	2,500
	SRIO 2500 LR	2,500
	SRIO 3125 SR	3,125
	SRIO 3125 LR	3,125
	SRIO 5000 SR	5,000
	SRIO 5000 MR	5,000
	SRIO 5000 LR	5,000
	SRIO_6250_SR	6,250
	SRIO_6250_MR	6,250
	SRIO_6250_LR	6,250

Symbol	Condition	-I3, -C4			-I5, -C5			-C6			Unit
		Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
	SERDES factor $J \geq 8^{(76)(78)}$, LVDS TX with RX DPA	⁽⁷⁷⁾	—	1600	⁽⁷⁷⁾	—	1500	⁽⁷⁷⁾	—	1250	Mbps
	SERDES factor $J = 1$ to 2, Uses DDR Registers	⁽⁷⁷⁾	—	⁽⁷⁹⁾	⁽⁷⁷⁾	—	⁽⁷⁹⁾	⁽⁷⁷⁾	—	⁽⁷⁹⁾	Mbps
Emulated Differential I/O Standards with Three External Output Resistor Network - f_{HSDR} (data rate) ⁽⁸⁰⁾	SERDES factor $J = 4$ to $10^{(81)}$	⁽⁷⁷⁾	—	945	⁽⁷⁷⁾	—	945	⁽⁷⁷⁾	—	945	Mbps
Emulated Differential I/O Standards with One External Output Resistor Network - f_{HSDR} (data rate) ⁽⁸⁰⁾	SERDES factor $J = 4$ to $10^{(81)}$	⁽⁷⁷⁾	—	200	⁽⁷⁷⁾	—	200	⁽⁷⁷⁾	—	200	Mbps
$t_{\text{x jitter}}$ - True Differential I/O Standards	Total Jitter for Data Rate 600 Mbps – 1.25 Gbps	—	—	160	—	—	160	—	—	160	ps
	Total Jitter for Data Rate < 600 Mbps	—	—	0.1	—	—	0.1	—	—	0.1	UI

⁽⁷⁸⁾ The V_{CC} and V_{CCP} must be on a separate power layer and a maximum load of 5 pF for chip-to-chip interface.

⁽⁷⁹⁾ The maximum ideal data rate is the SERDES factor (J) x the PLL maximum output frequency (f_{OUT}), provided you can close the design timing and the signal integrity simulation is clean.

⁽⁸⁰⁾ You must calculate the leftover timing margin in the receiver by performing link timing closure analysis. You must consider the board skew margin, transmitter channel-to-channel skew, and receiver sampling margin to determine the leftover timing margin.

⁽⁸¹⁾ When using True LVDS RX channels for emulated LVDS TX channel, only serialization factors 1 and 2 are supported.

Symbol	Condition	-I3, -C4			-I5, -C5			-C6			Unit
		Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
$t_{x \text{ Jitter}}$ -Emulated Differential I/O Standards with Three External Output Resistor Network	Total Jitter for Data Rate 600 Mbps – 1.25 Gbps	—	—	260	—	—	300	—	—	350	ps
	Total Jitter for Data Rate < 600 Mbps	—	—	0.16	—	—	0.18	—	—	0.21	UI
$t_{x \text{ Jitter}}$ -Emulated Differential I/O Standards with One External Output Resistor Network	—	—	—	0.15	—	—	0.15	—	—	0.15	UI
t_{DUTY}	TX output clock duty cycle for both True and Emulated Differential I/O Standards	45	50	55	45	50	55	45	50	55	%
t_{RISE} and t_{FALL}	True Differential I/O Standards ⁽⁸²⁾	—	—	160	—	—	180	—	—	200	ps
	Emulated Differential I/O Standards with Three External Output Resistor Network	—	—	250	—	—	250	—	—	300	ps
	Emulated Differential I/O Standards with One External Output Resistor Network	—	—	500	—	—	500	—	—	500	ps

⁽⁸²⁾ This applies to default pre-emphasis and V_{OD} settings only.

LVDS Soft-CDR/DPA Sinusoidal Jitter Tolerance Specifications

Figure 1-5: LVDS Soft-Clock Data Recovery (CDR)/DPA Sinusoidal Jitter Tolerance Specification for a Data Rate Equal to 1.25 Gbps

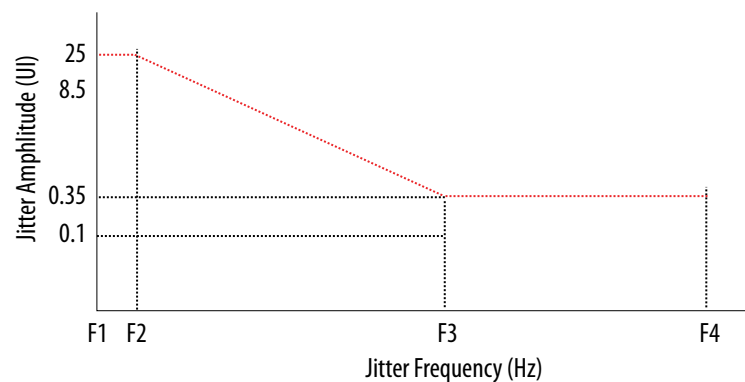
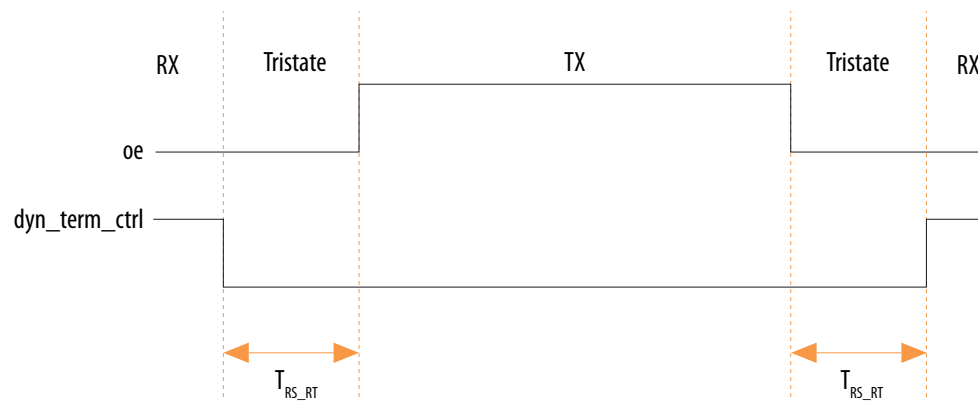


Table 1-42: LVDS Soft-CDR/DPA Sinusoidal Jitter Mask Values for a Data Rate Equal to 1.25 Gbps

Jitter Frequency (Hz)		Sinusoidal Jitter (UI)
F1	10,000	25.000
F2	17,565	25.000
F3	1,493,000	0.350
F4	50,000,000	0.350

Figure 1-7: Timing Diagram for oe and dyn_term_ctrl Signals



Duty Cycle Distortion (DCD) Specifications

Table 1-47: Worst-Case DCD on Arria V I/O Pins

The output DCD cycle only applies to the I/O buffer. It does not cover the system DCD.

Symbol	-I3, -C4		-C5, -I5		-C6		Unit
	Min	Max	Min	Max	Min	Max	
Output Duty Cycle	45	55	45	55	45	55	%

HPS Specifications

This section provides HPS specifications and timing for Arria V devices.

For HPS reset, the minimum reset pulse widths for the HPS cold and warm reset signals (HPS_nRST and HPS_nPOR) are six clock cycles of HPS_CLK1.

Figure 1-9: SPI Master Timing Diagram

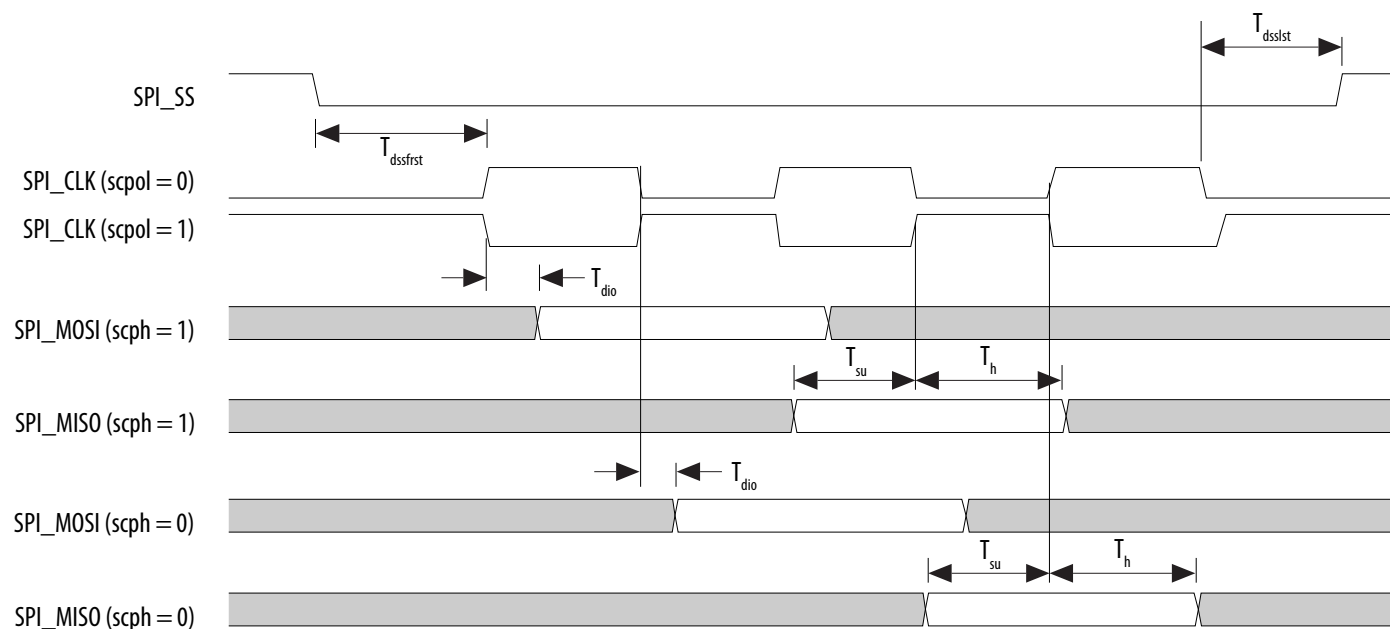


Table 1-53: SPI Slave Timing Requirements for Arria V Devices

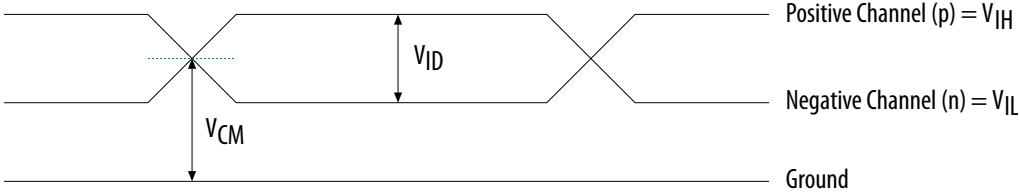
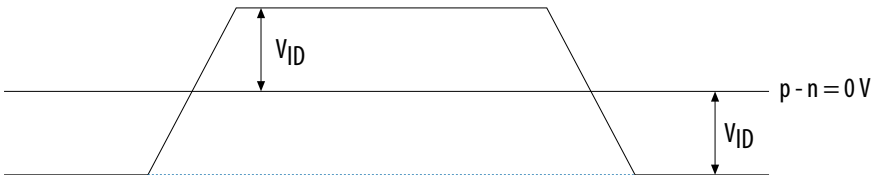
The setup and hold times can be used for Texas Instruments SSP mode and National Semiconductor Microwire mode.

Symbol	Description	Min	Max	Unit
T_{clk}	CLK clock period	20	—	ns
T_s	MOSI Setup time	5	—	ns
T_h	MOSI Hold time	5	—	ns
T_{suss}	Setup time SPI_SS valid before first clock edge	8	—	ns
T_{hss}	Hold time SPI_SS valid after last clock edge	8	—	ns
T_d	MISO output delay	—	6	ns

Symbol	Parameter	Typical	Unit
D_{OUTBUF}	Rising and/or falling edge delay	0 (default)	ps
		50	ps
		100	ps
		150	ps

Glossary

Table 1-78: Glossary

Term	Definition
Differential I/O standards	<p>Receiver Input Waveforms</p> <p>Single-Ended Waveform</p>  <p>Positive Channel (p) = V_{IH}</p> <p>Negative Channel (n) = V_{IL}</p> <p>Ground</p> <p>Differential Waveform</p>  <p>$p - n = 0\text{ V}$</p>

Symbol	Description	Minimum	Maximum	Unit
V_I	DC input voltage	-0.5	3.8	V
T_J	Operating junction temperature	-55	125	°C
T_{STG}	Storage temperature (No bias)	-65	150	°C
I_{OUT}	DC output current per pin	-25	40	mA

Table 2-3: Transceiver Power Supply Absolute Conditions for Arria V GZ Devices

Symbol	Description	Minimum	Maximum	Unit
V_{CCA_GXBL}	Transceiver channel PLL power supply (left side)	-0.5	3.75	V
V_{CCA_GXBR}	Transceiver channel PLL power supply (right side)	-0.5	3.75	V
V_{CCHIP_L}	Transceiver hard IP power supply (left side)	-0.5	1.35	V
V_{CCHSSI_L}	Transceiver PCS power supply (left side)	-0.5	1.35	V
V_{CCHSSI_R}	Transceiver PCS power supply (right side)	-0.5	1.35	V
V_{CCR_GXBL}	Receiver analog power supply (left side)	-0.5	1.35	V
V_{CCR_GXBR}	Receiver analog power supply (right side)	-0.5	1.35	V
V_{CCT_GXBL}	Transmitter analog power supply (left side)	-0.5	1.35	V
V_{CCT_GXBR}	Transmitter analog power supply (right side)	-0.5	1.35	V
V_{CCH_GXBL}	Transmitter output buffer power supply (left side)	-0.5	1.8	V
V_{CCH_GXBR}	Transmitter output buffer power supply (right side)	-0.5	1.8	V

Maximum Allowed Overshoot and Undershoot Voltage

During transitions, input signals may overshoot to the voltage shown in the following table. They may also undershoot to -2.0 V for input currents less than 100 mA and periods shorter than 20 ns.

Symbol	Description	Condition	Minimum ⁽¹¹⁴⁾	Typical	Maximum ⁽¹¹⁴⁾	Unit
V _I	DC input voltage	—	−0.5	—	3.6	V
V _O	Output voltage	—	0	—	V _{CCIO}	V
T _J	Operating junction temperature	Commercial	0	—	85	°C
		Industrial	−40	—	100	°C
t _{RAMP}	Power supply ramp time	Standard POR	200 μs	—	100 ms	—
		Fast POR	200 μs	—	4 ms	—

Recommended Transceiver Power Supply Operating Conditions

Table 2-6: Recommended Transceiver Power Supply Operating Conditions for Arria V GZ Devices

Symbol	Description	Minimum ⁽¹¹⁸⁾	Typical	Maximum ⁽¹¹⁸⁾	Unit
V _{CCA_GXBL} (119), (120)	Transceiver channel PLL power supply (left side)	2.85	3.0	3.15	V
		2.375	2.5	2.625	
V _{CCA_GXBR} (119), (120)	Transceiver channel PLL power supply (right side)	2.85	3.0	3.15	V
		2.375	2.5	2.625	
V _{CCHIP_L}	Transceiver hard IP power supply (left side)	0.82	0.85	0.88	V
V _{CCHSSI_L}	Transceiver PCS power supply (left side)	0.82	0.85	0.88	V
V _{CCHSSI_R}	Transceiver PCS power supply (right side)	0.82	0.85	0.88	V

⁽¹¹⁴⁾ The power supply value describes the budget for the DC (static) power supply tolerance and does not include the dynamic tolerance requirements. Refer to the PDN tool for the additional budget for the dynamic tolerance requirements.

⁽¹¹⁸⁾ This value describes the budget for the DC (static) power supply tolerance and does not include the dynamic tolerance requirements. Refer to the PDN tool for the additional budget for the dynamic tolerance requirements.

⁽¹¹⁹⁾ This supply must be connected to 3.0 V if the CMU PLL, receiver CDR, or both, are configured at a base data rate > 6.5 Gbps. Up to 6.5 Gbps, you can connect this supply to either 3.0 V or 2.5 V.

⁽¹²⁰⁾ When using ATX PLLs, the supply must be 3.0 V.

Symbol/Description	Conditions	Transceiver Speed Grade 2			Transceiver Speed Grade 3			Unit
		Min	Typ	Max	Min	Typ	Max	
Transmitter REFCLK Phase Noise (622 MHz) ⁽¹⁴¹⁾	100 Hz	—	—	-70	—	—	-70	dBc/Hz
	1 kHz	—	—	-90	—	—	-90	dBc/Hz
	10 kHz	—	—	-100	—	—	-100	dBc/Hz
	100 kHz	—	—	-110	—	—	-110	dBc/Hz
	≥1 MHz	—	—	-120	—	—	-120	dBc/Hz
Transmitter REFCLK Phase Jitter (100 MHz) ⁽¹⁴²⁾	10 kHz to 1.5 MHz (PCIe)	—	—	3	—	—	3	ps (rms)
R _{REF}	—	—	1800 ±1%	—	—	1800 ±1%	—	Ω

Related Information[Arria V Device Overview](#)

For more information about device ordering codes.

Transceiver Clocks**Table 2-23: Transceiver Clocks Specifications for Arria V GZ Devices**

Speed grades shown refer to the PMA Speed Grade in the device ordering code. The maximum data rate could be restricted by the Core/PCS speed grade. Contact your Altera Sales Representative for the maximum data rate specifications in each speed grade combination offered. For more information about device ordering codes, refer to the *Arria V Device Overview*.

⁽¹⁴¹⁾ To calculate the REFCLK phase noise requirement at frequencies other than 622 MHz, use the following formula: REFCLK phase noise at f(MHz) = REFCLK phase noise at 622 MHz + 20*log(f/622).

⁽¹⁴²⁾ To calculate the REFCLK rms phase jitter requirement for PCIe at reference clock frequencies other than 100 MHz, use the following formula: REFCLK rms phase jitter at f(MHz) = REFCLK rms phase jitter at 100 MHz × 100/f.

Symbol/Description	Conditions	Transceiver Speed Grade 2			Transceiver Speed Grade 3			Unit
		Min	Typ	Max	Min	Typ	Max	
V_{ICM} (AC and DC coupled)	$V_{CCR_GXB} = 0.85\text{ V}$ full bandwidth	—	600	—	—	600	—	mV
	$V_{CCR_GXB} = 0.85\text{ V}$ half bandwidth	—	600	—	—	600	—	mV
	$V_{CCR_GXB} = 1.0\text{ V}$ full bandwidth	—	700	—	—	700	—	mV
	$V_{CCR_GXB} = 1.0\text{ V}$ half bandwidth	—	700	—	—	700	—	mV
$t_{LTR}^{(149)}$	—	—	—	10	—	—	10	μs
$t_{LTD}^{(150)}$	—	4	—	—	4	—	—	μs
$t_{LTD_manual}^{(151)}$	—	4	—	—	4	—	—	μs
$t_{LTR_LTD_manual}^{(152)}$	—	15	—	—	15	—	—	μs
Programmable equalization (AC Gain)	Full bandwidth (6.25 GHz) Half bandwidth (3.125 GHz)	—	—	16	—	—	16	dB

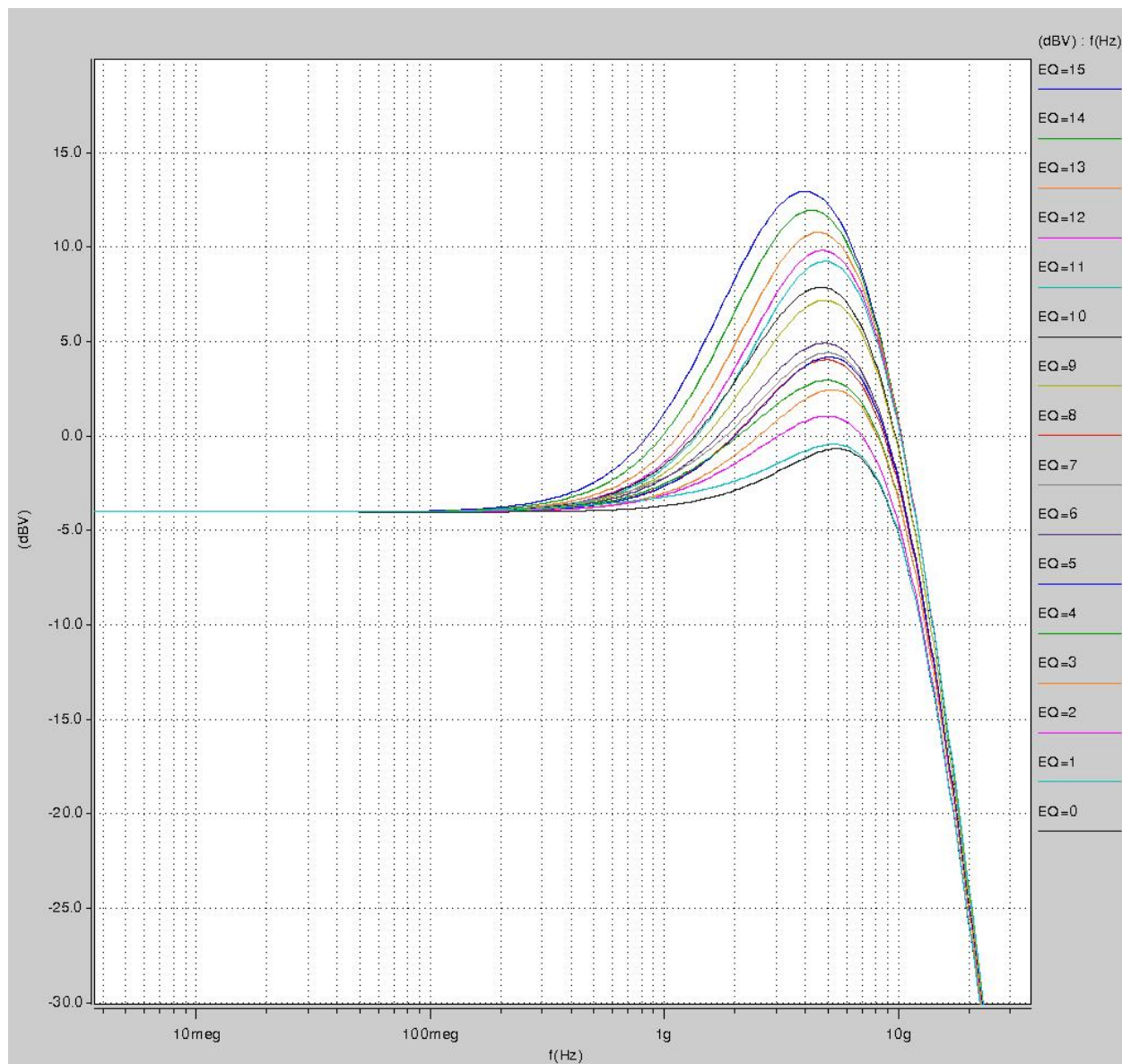
⁽¹⁴⁹⁾ t_{LTR} is the time required for the receive CDR to lock to the input reference clock frequency after coming out of reset.

⁽¹⁵⁰⁾ t_{LTD} is time required for the receiver CDR to start recovering valid data after the `rx_is_lockedto data` signal goes high.

⁽¹⁵¹⁾ t_{LTD_manual} is the time required for the receiver CDR to start recovering valid data after the `rx_is_lockedto data` signal goes high when the CDR is functioning in the manual mode.

⁽¹⁵²⁾ $t_{LTR_LTD_manual}$ is the time the receiver CDR must be kept in lock to reference (LTR) mode after the `rx_is_lockedto ref` signal goes high when the CDR is functioning in the manual mode.

Figure 2-2: AC Gain Curves for Arria V GZ Channels (full bandwidth)



Symbol	Parameter	Min	Typ	Max	Unit
$t_{\text{INCCJ}}^{(171), (172)}$	Input clock cycle-to-cycle jitter ($f_{\text{REF}} \geq 100$ MHz)	—	—	0.15	UI (p-p)
	Input clock cycle-to-cycle jitter ($f_{\text{REF}} < 100$ MHz)	-750	—	+750	ps (p-p)
$t_{\text{OUTPJ_DC}}^{(173)}$	Period Jitter for dedicated clock output in integer PLL ($f_{\text{OUT}} \geq 100$ MHz)	—	—	175	ps (p-p)
	Period Jitter for dedicated clock output in integer PLL ($f_{\text{OUT}} < 100$ MHz)	—	—	17.5	mUI (p-p)
$t_{\text{FOUTPJ_DC}}^{(173)}$	Period Jitter for dedicated clock output in fractional PLL ($f_{\text{OUT}} \geq 100$ MHz)	—	—	250 ⁽¹⁷⁶⁾ , 175 ⁽¹⁷⁴⁾	ps (p-p)
	Period Jitter for dedicated clock output in fractional PLL ($f_{\text{OUT}} < 100$ MHz)	—	—	25 ⁽¹⁷⁶⁾ , 17.5 ⁽¹⁷⁴⁾	mUI (p-p)
$t_{\text{OUTCCJ_DC}}^{(173)}$	Cycle-to-cycle Jitter for a dedicated clock output in integer PLL ($f_{\text{OUT}} \geq 100$ MHz)	—	—	175	ps (p-p)
	Cycle-to-cycle Jitter for a dedicated clock output in integer PLL ($f_{\text{OUT}} < 100$ MHz)	—	—	17.5	mUI (p-p)
$t_{\text{FOUTCCJ_DC}}^{(173)}$	Cycle-to-cycle Jitter for a dedicated clock output in fractional PLL ($f_{\text{OUT}} \geq 100$ MHz)	—	—	250 ⁽¹⁷⁶⁾ , 175 ⁽¹⁷⁴⁾	ps (p-p)
	Cycle-to-cycle Jitter for a dedicated clock output in fractional PLL ($f_{\text{OUT}} < 100$ MHz)	—	—	25 ⁽¹⁷⁶⁾ , 17.5 ⁽¹⁷⁴⁾	mUI (p-p)

⁽¹⁷¹⁾ A high input jitter directly affects the PLL output jitter. To have low PLL output clock jitter, you must provide a clean clock source with jitter < 120 ps.

⁽¹⁷²⁾ The f_{REF} is f_{IN}/N specification applies when $N = 1$.

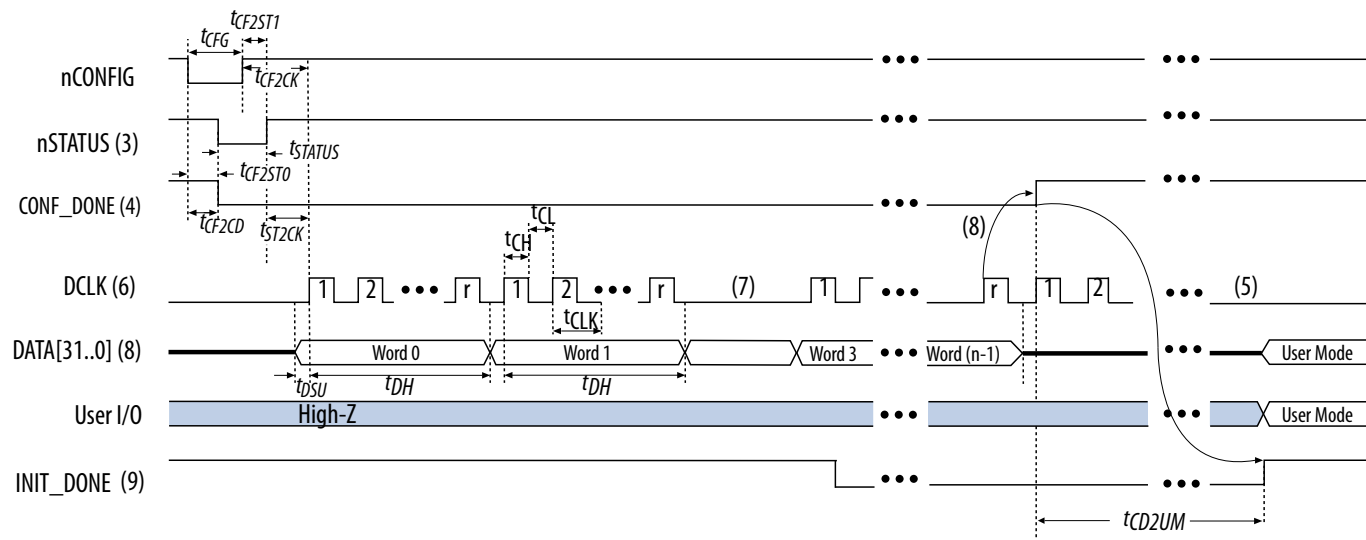
⁽¹⁷³⁾ Peak-to-peak jitter with a probability level of 10^{-12} (14 sigma, 99.9999999974404% confidence level). The output jitter specification applies to the intrinsic jitter of the PLL, when an input jitter of 30 ps is applied. The external memory interface clock output jitter specifications use a different measurement method and are available in the "Worst-Case DCD on Arria V GZ I/O Pins" table.

⁽¹⁷⁴⁾ This specification only covered fractional PLL for low bandwidth. The f_{VCO} for fractional value range 0.20–0.80 must be ≥ 1200 MHz.

FPP Configuration Timing when DCLK to DATA[] > 1

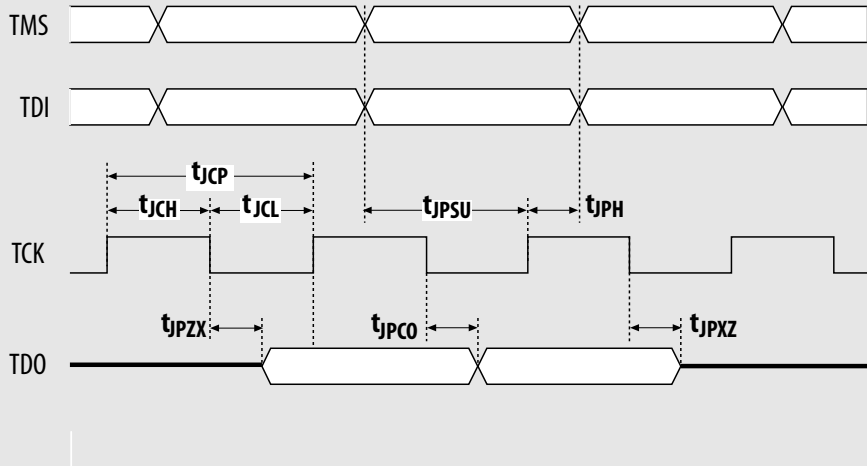
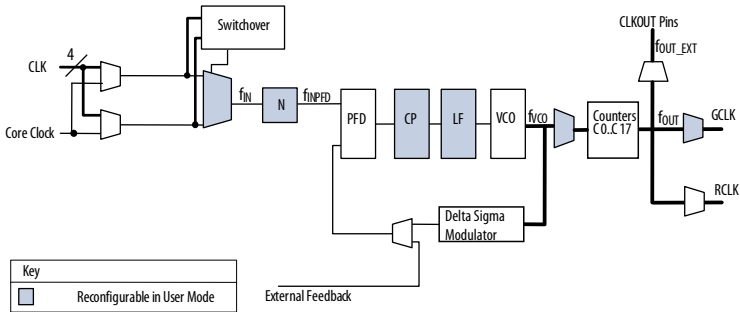
Figure 2-8: FPP Configuration Timing Waveform When the DCLK-to-DATA[] Ratio is >1 ,

Timing when using a MAX II device, MAX V device, or microprocessor as an external host.



Notes:

1. To find out the DCLK-to-DATA[] ratio for your system, refer to the "DCLK-to-DATA[] Ratio for Arria V GZ Devices" table.
2. The beginning of this waveform shows the device in user mode. In user mode, nCONFIG, nSTATUS, and CONF_DONE are at logic high levels. When nCONFIG is pulled low, a reconfiguration cycle begins.
3. After power-up, the Arria V GZ device holds nSTATUS low for the time as specified by the POR delay.
4. After power-up, before and during configuration, CONF_DONE is low.
5. Do not leave DCLK floating after configuration is complete. DCLK is ignored after configuration is complete. It can toggle high or low if required.
6. "r" denotes the DCLK-to-DATA[] ratio. For the DCLK-to-DATA[] ratio based on the decompression and the design security feature enable settings, refer to the "DCLK-to-DATA[] Ratio for Arria V GZ Devices" table.
7. If needed, pause DCLK by holding it low. When DCLK restarts, the external host must provide data on the DATA[31..0] pins prior to sending the first DCLK rising edge.
8. To ensure a successful configuration, send the entire configuration data to the Arria V GZ device. CONF_DONE is released high after the Arria V GZ device receives all the configuration data successfully. After CONF_DONE goes high, send two additional falling edges on DCLK to begin initialization and enter user mode.
9. After the option bit to enable the INIT_DONE pin is configured into the device, the INIT_DONE goes low.

Term	Definition
JTAG Timing Specifications	<p>JTAG Timing Specifications:</p>  <p>The diagram illustrates the timing relationships for JTAG signals. TMS and TDI are shown as high-impedance signals during certain phases. TCK is the clock signal. TDO is the data output signal. The timing parameters are defined as follows:</p> <ul style="list-style-type: none">t_{JCP}: JTAG Capture Periodt_{JCH}: JTAG Capture High Pulse Widtht_{JCL}: JTAG Capture Low Pulse Widtht_{JPSU}: JTAG Programming Setup Timet_{JPH}: JTAG Programming High Pulse Widtht_{JPZX}: JTAG Programming Z-bus Hold Timet_{JPCO}: JTAG Programming Clock Output Delayt_{JPXZ}: JTAG Programming Z-bus Delay
PLL Specifications	<p>Diagram of PLL Specifications</p>  <p>The diagram shows the internal structure of a PLL. It starts with a Core Clock input, which is divided by 4 and then passes through a Switchover block. The output of the Switchover block is fed into a PFD (Phase-Frequency Detector), which is also fed back from the VCO output. The PFD output goes through a CP (Charge Pump) and an LF (Loop Filter) to the VCO (Voltage-Controlled Oscillator). The VCO output is divided by N to provide feedback to the PFD. The VCO output also goes through a Delta Sigma Modulator and a Counters block (CO, C 17) to produce the final output. The output is then divided by 4 to produce the final output. The output is also fed back to the PFD. The output is also fed back to the PFD. The output is also fed back to the PFD.</p> <p>Key</p> <ul style="list-style-type: none">Reconfigurable in User Mode <p>Note:</p> <ol style="list-style-type: none">Core Clock can only be fed by dedicated clock input pins or PLL outputs.

Date	Version	Changes
June 2016	2016.06.20	<ul style="list-style-type: none">• Changed column heading from "Value" to "Maximum" in the "Pin Capacitance for Arria V GZ Devices" table.• Changed the minimum supported data rate range values from "1000" to "2000" in the "ATX PLL Specifications for Arria V GZ Devices" table.• Added the supported data rates for the following output standards using true LVDS output buffer types in the "High-Speed Clock Specifications for Arria V GZ Devices" table:<ul style="list-style-type: none">• True RSDS output standard: data rates of up to 230 Mbps• True mini-LVDS output standard: data rates of up to 340 Mbps
December 2015	2015.12.16	<ul style="list-style-type: none">• Removed the CDR ppm tolerance specification from the "Receiver Specifications for Arria V GZ Devices" table.• Removed transmitter rise and fall time specifications from the "Transmitter Specifications for Arria V GZ Devices" table.• Changed the .rbf sizes in the "Uncompressed .rbf Sizes for Arria V GZ Devices" table.• Added a footnote to the "Transmitter High-Speed I/O Specifications for Arria V GZ Devices" table.
June 2015	2015.06.16	<ul style="list-style-type: none">• Changed the conditions for the reference clock rise and fall time and added a note to the condition in the "Reference Clock Specifications for Arria V GZ Devices" table.• Added a note to the "Minimum differential eye opening at receiver serial input pins" specification in the "Receiver Specifications for Arria V GZ Devices" table.
January 2015	2015.01.30	<ul style="list-style-type: none">• Added 240-Ω to the "OCT Calibration Accuracy Specifications for Arria V GZ Devices" table.• Changed the CDR PPM tolerance spec in the "Receiver Specifications for Arria V GZ Devices" table.• Added additional max data rate for fPLL in the "Fractional PLL Specifications for Arria V GZ Devices" table.