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Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details

Product Status	Obsolete
Number of LABs/CLBs	19811
Number of Logic Elements/Cells	420000
Total RAM Bits	23625728
Number of I/O	704
Number of Gates	-
Voltage - Supply	1.07V ~ 1.13V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	1517-BBGA
Supplier Device Package	1517-FBGA (40x40)
Purchase URL	https://www.e-xfl.com/product-detail/intel/5agxbb5d6f40c6n

I/O Standard	$V_{IL(DC)} (V)$		$V_{IH(DC)} (V)$		$V_{IL(AC)} (V)$	$V_{IH(AC)} (V)$	$V_{OL} (V)$	$V_{OH} (V)$	$I_{OL}^{(14)} (mA)$	$I_{OH}^{(14)} (mA)$
	Min	Max	Min	Max	Max	Min	Max	Min		
HSTL-15 Class II	—	$V_{REF} - 0.1$	$V_{REF} + 0.1$	—	$V_{REF} - 0.2$	$V_{REF} + 0.2$	0.4	$V_{CCIO} - 0.4$	16	-16
HSTL-12 Class I	-0.15	$V_{REF} - 0.08$	$V_{REF} + 0.08$	$V_{CCIO} + 0.15$	$V_{REF} - 0.15$	$V_{REF} + 0.15$	$0.25 \times V_{CCIO}$	$0.75 \times V_{CCIO}$	8	-8
HSTL-12 Class II	-0.15	$V_{REF} - 0.08$	$V_{REF} + 0.08$	$V_{CCIO} + 0.15$	$V_{REF} - 0.15$	$V_{REF} + 0.15$	$0.25 \times V_{CCIO}$	$0.75 \times V_{CCIO}$	16	-16
HSUL-12	—	$V_{REF} - 0.13$	$V_{REF} + 0.13$	—	$V_{REF} - 0.22$	$V_{REF} + 0.22$	$0.1 \times V_{CCIO}$	$0.9 \times V_{CCIO}$	—	—

Differential SSTL I/O Standards

Table 1-17: Differential SSTL I/O Standards for Arria V Devices

I/O Standard	$V_{CCIO} (V)$			$V_{SWING(DC)} (V)$		$V_{X(AC)} (V)$			$V_{SWING(AC)} (V)$	
	Min	Typ	Max	Min	Max	Min	Typ	Max	Min	Max
SSTL-2 Class I, II	2.375	2.5	2.625	0.3	$V_{CCIO} + 0.6$	$V_{CCIO}/2 - 0.2$	—	$V_{CCIO}/2 + 0.2$	0.62	$V_{CCIO} + 0.6$
SSTL-18 Class I, II	1.71	1.8	1.89	0.25	$V_{CCIO} + 0.6$	$V_{CCIO}/2 - 0.175$	—	$V_{CCIO}/2 + 0.175$	0.5	$V_{CCIO} + 0.6$
SSTL-15 Class I, II	1.425	1.5	1.575	0.2	⁽¹⁵⁾	$V_{CCIO}/2 - 0.15$	—	$V_{CCIO}/2 + 0.15$	$2(V_{IH(AC)} - V_{REF})$	$2(V_{IL(AC)} - V_{REF})$
SSTL-135	1.283	1.35	1.45	0.18	⁽¹⁵⁾	$V_{CCIO}/2 - 0.15$	$V_{CCIO}/2$	$V_{CCIO}/2 + 0.15$	$2(V_{IH(AC)} - V_{REF})$	$2(V_{IL(AC)} - V_{REF})$

⁽¹⁴⁾ To meet the I_{OL} and I_{OH} specifications, you must set the current strength settings accordingly. For example, to meet the SSTL15CI specification (8 mA), you should set the current strength settings to 8 mA. Setting at lower current strength may not meet the I_{OL} and I_{OH} specifications in the datasheet.

⁽¹⁵⁾ The maximum value for $V_{SWING(DC)}$ is not defined. However, each single-ended signal needs to be within the respective single-ended limits ($V_{IH(DC)}$ and $V_{IL(DC)}$).

Symbol/Description	Condition	Transceiver Speed Grade 3			Unit
		Min	Typ	Max	
Differential on-chip termination resistors	85- Ω setting	—	85	—	Ω
	100- Ω setting	—	100	—	Ω
	120- Ω setting	—	120	—	Ω
	150- Ω setting	—	150	—	Ω
Intra-differential pair skew	TX $V_{CM} = 0.65$ V (AC coupled) and slew rate of 15 ps	—	—	15	ps
Intra-transceiver block transmitter channel-to-channel skew	$\times 6$ PMA bonded mode	—	—	180	ps
Inter-transceiver block transmitter channel-to-channel skew ⁽⁵⁵⁾	$\times N$ PMA bonded mode	—	—	500	ps

Table 1-30: CMU PLL Specifications for Arria V GT and ST Devices

Symbol/Description	Transceiver Speed Grade 3		Unit
	Min	Max	
Supported data range	0.611	10.3125	Gbps
fPLL supported data range	611	3125	Mbps

⁽⁵⁵⁾ This specification is only applicable to channels on one side of the device across two transceiver banks.

Symbol	Parameter	Condition	Min	Typ	Max	Unit
$f_{\text{OUT_EXT}}$	Output frequency for external clock output	–3 speed grade	—	—	670 ⁽⁶³⁾	MHz
		–4 speed grade	—	—	670 ⁽⁶³⁾	MHz
		–5 speed grade	—	—	622 ⁽⁶³⁾	MHz
		–6 speed grade	—	—	500 ⁽⁶³⁾	MHz
t_{OUTDUTY}	Duty cycle for external clock output (when set to 50%)	—	45	50	55	%
t_{FCOMP}	External feedback clock compensation time	—	—	—	10	ns
$t_{\text{DYCONFIGCLK}}$	Dynamic configuration clock for <code>mgmt_clk</code> and <code>scanclk</code>	—	—	—	100	MHz
t_{LOCK}	Time required to lock from end-of-device configuration or deassertion of <code>areset</code>	—	—	—	1	ms
t_{DLOCK}	Time required to lock dynamically (after switchover or reconfiguring any non-post-scale counters/delays)	—	—	—	1	ms
f_{CLBW}	PLL closed-loop bandwidth	Low	—	0.3	—	MHz
		Medium	—	1.5	—	MHz
		High ⁽⁶⁴⁾	—	4	—	MHz
$t_{\text{PLL_PSERR}}$	Accuracy of PLL phase shift	—	—	—	±50	ps
t_{ARESET}	Minimum pulse width on the <code>areset</code> signal	—	10	—	—	ns
$t_{\text{INCCJ}}^{(65)(66)}$	Input clock cycle-to-cycle jitter	$F_{\text{REF}} \geq 100 \text{ MHz}$	—	—	0.15	UI (p-p)
		$F_{\text{REF}} < 100 \text{ MHz}$	—	—	±750	ps (p-p)

⁽⁶⁴⁾ High bandwidth PLL settings are not supported in external feedback mode.

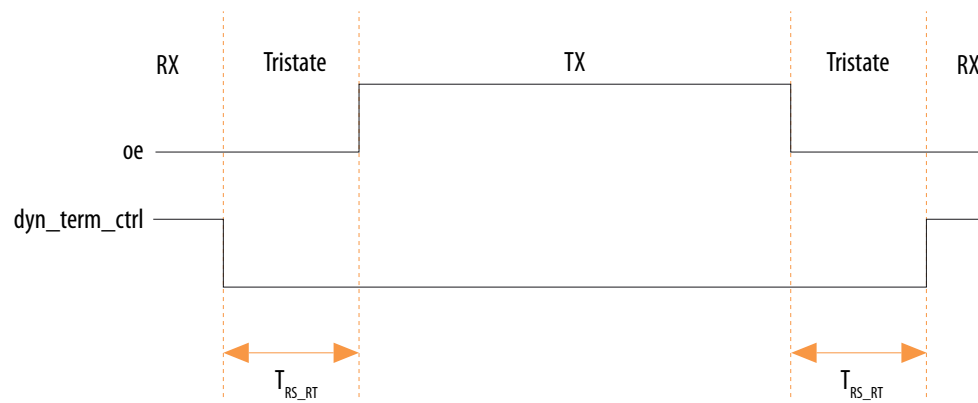
⁽⁶⁵⁾ A high input jitter directly affects the PLL output jitter. To have low PLL output clock jitter, you must provide a clean clock source with jitter < 120 ps.

⁽⁶⁶⁾ F_{REF} is f_{IN}/N , specification applies when $N = 1$.

Symbol		Condition	-I3, -C4			-I5, -C5			-C6			Unit
			Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
	TCCS	True Differential I/O Standards	—	—	150	—	—	150	—	—	150	ps
		Emulated Differential I/O Standards	—	—	300	—	—	300	—	—	300	ps
Receiver	True Differential I/O Standards - f_{HSDRDPA} (data rate)	SERDES factor J = 3 to 10 ⁽⁷⁶⁾	150	—	1250	150	—	1250	150	—	1050	Mbps
		SERDES factor J ≥ 8 with DPA ⁽⁷⁶⁾⁽⁷⁸⁾	150	—	1600	150	—	1500	150	—	1250	Mbps
	f_{HSDR} (data rate)	SERDES factor J = 3 to 10	⁽⁷⁷⁾	—	⁽⁸³⁾	⁽⁷⁷⁾	—	⁽⁸³⁾	⁽⁷⁷⁾	—	⁽⁸³⁾	Mbps
		SERDES factor J = 1 to 2, uses DDR registers	⁽⁷⁷⁾	—	⁽⁷⁹⁾	⁽⁷⁷⁾	—	⁽⁷⁹⁾	⁽⁷⁷⁾	—	⁽⁷⁹⁾	Mbps
DPA Mode	DPA run length	—	—	—	10000	—	—	10000	—	—	10000	UI
Soft-CDR Mode	Soft-CDR ppm tolerance	—	—	—	300	—	—	300	—	—	300	±ppm
Non-DPA Mode	Sampling Window	—	—	—	300	—	—	300	—	—	300	ps

⁽⁸³⁾ You can estimate the achievable maximum data rate for non-DPA mode by performing link timing closure analysis. You must consider the board skew margin, transmitter delay margin, and receiver sampling margin to determine the maximum data rate supported.

Figure 1-7: Timing Diagram for oe and dyn_term_ctrl Signals



Duty Cycle Distortion (DCD) Specifications

Table 1-47: Worst-Case DCD on Arria V I/O Pins

The output DCD cycle only applies to the I/O buffer. It does not cover the system DCD.

Symbol	-I3, -C4		-C5, -I5		-C6		Unit
	Min	Max	Min	Max	Min	Max	
Output Duty Cycle	45	55	45	55	45	55	%

HPS Specifications

This section provides HPS specifications and timing for Arria V devices.

For HPS reset, the minimum reset pulse widths for the HPS cold and warm reset signals (HPS_nRST and HPS_nPOR) are six clock cycles of HPS_CLK1.

HPS PLL Input Jitter

Use the following equation to determine the maximum input jitter (peak-to-peak) the HPS PLLs can tolerate. The divide value (N) is the value programmed into the denominator field of the VCO register for each PLL. The PLL input reference clock is divided by this value. The range of the denominator is 1 to 64.

$$\text{Maximum input jitter} = \text{Input clock period} \times \text{Divide value (N)} \times 0.02$$

Table 1-50: Examples of Maximum Input Jitter

Input Reference Clock Period	Divide Value (N)	Maximum Jitter	Unit
40 ns	1	0.8	ns
40 ns	2	1.6	ns
40 ns	4	3.2	ns

Quad SPI Flash Timing Characteristics

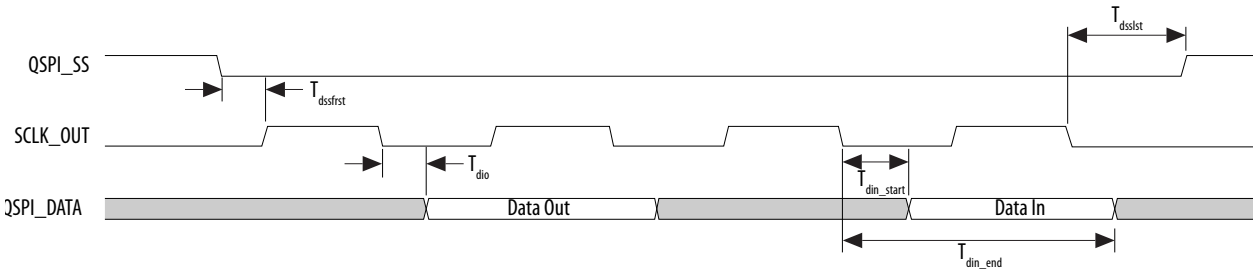
Table 1-51: Quad Serial Peripheral Interface (SPI) Flash Timing Requirements for Arria V Devices

Symbol	Description	Min	Typ	Max	Unit
F_{clk}	SCLK_OUT clock frequency (External clock)	—	—	108	MHz
$T_{\text{qspi_clk}}$	QSPI_CLK clock period (Internal reference clock)	2.32	—	—	ns
$T_{\text{duty_cycle}}$	SCLK_OUT duty cycle	45	—	55	%
T_{dssfrst}	Output delay QSPI_SS valid before first clock edge	—	1/2 cycle of SCLK_OUT	—	ns
T_{dsslst}	Output delay QSPI_SS valid after last clock edge	–1	—	1	ns
T_{dio}	I/O data output delay	–1	—	1	ns
$T_{\text{din_start}}$	Input data valid start	—	—	$(2 + R_{\text{delay}}) \times T_{\text{qspi_clk}} - 7.52^{(85)}$	ns

Symbol	Description	Min	Typ	Max	Unit
T_{din_end}	Input data valid end	$(2 + R_{delay}) \times T_{qspi_clk} - 1.21^{(85)}$	—	—	ns

Figure 1-8: Quad SPI Flash Timing Diagram

This timing diagram illustrates clock polarity mode 0 and clock phase mode 0.



Related Information

[Quad SPI Flash Controller Chapter, Arria V Hard Processor System Technical Reference Manual](#)

Provides more information about Rdelay.

SPI Timing Characteristics

Table 1-52: SPI Master Timing Requirements for Arria V Devices

The setup and hold times can be used for Texas Instruments SSP mode and National Semiconductor Microwire mode.

Symbol	Description	Min	Max	Unit
T_{clk}	CLK clock period	16.67	—	ns
T_{su}	SPI Master-in slave-out (MISO) setup time	8.35 ⁽⁸⁶⁾	—	ns

⁽⁸⁵⁾ R_{delay} is set by programming the register `qspiregs.rddatacap`. For the SoC EDS software version 13.1 and later, Altera provides automatic Quad SPI calibration in the preloader. For more information about R_{delay} , refer to the Quad SPI Flash Controller chapter in the Arria V Hard Processor System Technical Reference Manual.

Symbol	Description	Min	Max	Unit
T_h	SPI MISO hold time	1	—	ns
$T_{\text{duty cycle}}$	SPI_CLK duty cycle	45	55	%
T_{dssfrst}	Output delay SPI_SS valid before first clock edge	8	—	ns
T_{dsslst}	Output delay SPI_SS valid after last clock edge	8	—	ns
T_{dio}	Master-out slave-in (MOSI) output delay	–1	1	ns

⁽⁸⁶⁾ This value is based on $\text{rx_sample_dly} = 1$ and $\text{spi_m_clk} = 120$ MHz. spi_m_clk is the internal clock that is used by SPI Master to derive its SCLK_OUT . These timings are based on rx_sample_dly of 1. This delay can be adjusted as needed to accommodate slower response times from the slave. Note that a delay of 0 is not allowed. The setup time can be used as a reference starting point. It is very crucial to do a calibration to get the correct rx_sample_dly value because each SPI slave device may have different output delay and each application board may have different path delay. For more information about rx_sample_delay , refer to the SPI Controller chapter in the Hard Processor System Technical Reference Manual.

POR Delay	Minimum	Maximum	Unit
Standard	100	300	ms

Related Information**MSEL Pin Settings**

Provides more information about POR delay based on MSEL pin settings for each configuration scheme.

FPGA JTAG Configuration Timing

Table 1-64: FPGA JTAG Timing Parameters and Values for Arria V Devices

Symbol	Description	Min	Max	Unit
t_{JCP}	TCK clock period	30, 167 ⁽⁹²⁾	—	ns
t_{JCH}	TCK clock high time	14	—	ns
t_{JCL}	TCK clock low time	14	—	ns
t_{JPSU} (TDI)	TDI JTAG port setup time	2	—	ns
t_{JPSU} (TMS)	TMS JTAG port setup time	3	—	ns
t_{JPH}	JTAG port hold time	5	—	ns
t_{JPCO}	JTAG port clock to output	—	12 ⁽⁹³⁾	ns
t_{JPZX}	JTAG port high impedance to valid output	—	14 ⁽⁹³⁾	ns
t_{JPXZ}	JTAG port valid output to high impedance	—	14 ⁽⁹³⁾	ns

⁽⁹²⁾ The minimum TCK clock period is 167 ns if V_{CCBAT} is within the range 1.2 V – 1.5 V when you perform the volatile key programming.

⁽⁹³⁾ A 1-ns adder is required for each VCCIO voltage step down from 3.0 V. For example, t_{JPCO} = 13 ns if VCCIO of the TDO I/O bank = 2.5 V, or 14 ns if it equals 1.8 V.

Related Information

- [PS Configuration Timing](#) on page 1-81
- [AS Configuration Timing](#)
Provides the AS configuration timing waveform.

DCLK Frequency Specification in the AS Configuration Scheme

Table 1-69: DCLK Frequency Specification in the AS Configuration Scheme

This table lists the internal clock frequency specification for the AS configuration scheme. The DCLK frequency specification applies when you use the internal oscillator as the configuration clock source. The AS multi-device configuration scheme does not support DCLK frequency of 100 MHz.

Parameter	Minimum	Typical	Maximum	Unit
DCLK frequency in AS configuration scheme	5.3	7.9	12.5	MHz
	10.6	15.7	25.0	MHz
	21.3	31.4	50.0	MHz
	42.6	62.9	100.0	MHz

PS Configuration Timing

Table 1-70: PS Timing Parameters for Arria V Devices

Symbol	Parameter	Minimum	Maximum	Unit
t _{CF2CD}	nCONFIG low to CONF_DONE low	—	600	ns
t _{CF2ST0}	nCONFIG low to nSTATUS low	—	600	ns
t _{CFG}	nCONFIG low pulse width	2	—	μs
t _{STATUS}	nSTATUS low pulse width	268	1506 ⁽¹⁰³⁾	μs
t _{CF2ST1}	nCONFIG high to nSTATUS high	—	1506 ⁽¹⁰⁴⁾	μs

⁽¹⁰³⁾ You can obtain this value if you do not delay configuration by extending the nCONFIG or nSTATUS low pulse width.

⁽¹⁰⁴⁾ You can obtain this value if you do not delay configuration by externally holding nSTATUS low.

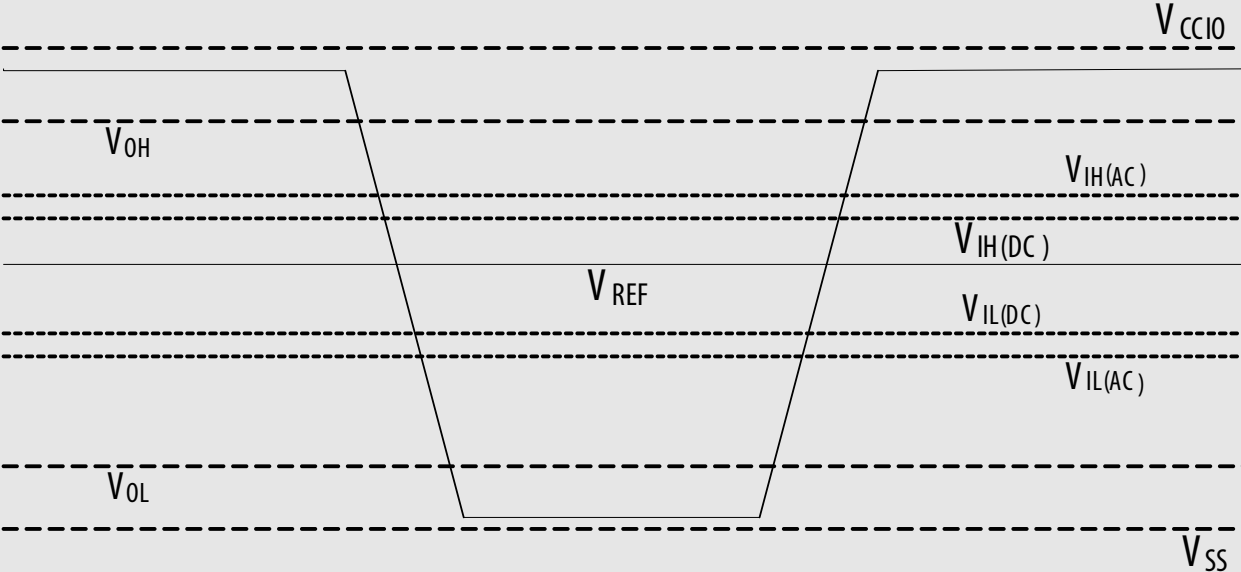
Symbol	Parameter	Minimum	Maximum	Unit
$t_{CF2CK}^{(105)}$	nCONFIG high to first rising edge on DCLK	1506	—	μs
$t_{ST2CK}^{(105)}$	nSTATUS high to first rising edge of DCLK	2	—	μs
t_{DSU}	DATA[] setup time before rising edge on DCLK	5.5	—	ns
t_{DH}	DATA[] hold time after rising edge on DCLK	0	—	ns
t_{CH}	DCLK high time	$0.45 \times 1/f_{MAX}$	—	s
t_{CL}	DCLK low time	$0.45 \times 1/f_{MAX}$	—	s
t_{CLK}	DCLK period	$1/f_{MAX}$	—	s
f_{MAX}	DCLK frequency	—	125	MHz
t_{CD2UM}	CONF_DONE high to user mode ⁽¹⁰⁶⁾	175	437	μs
t_{CD2CU}	CONF_DONE high to CLKUSR enabled	$4 \times \text{maximum DCLK period}$	—	—
t_{CD2UMC}	CONF_DONE high to user mode with CLKUSR option on	$t_{CD2CU} + (T_{init} \times \text{CLKUSR period})$	—	—
T_{init}	Number of clock cycles required for device initialization	8,576	—	Cycles

Related Information**PS Configuration Timing**

Provides the PS configuration timing waveform.

⁽¹⁰⁵⁾ If nSTATUS is monitored, follow the t_{ST2CK} specification. If nSTATUS is not monitored, follow the t_{CF2CK} specification.

⁽¹⁰⁶⁾ The minimum and maximum numbers apply only if you chose the internal oscillator as the clock source for initializing the device.

Term	Definition
Single-ended voltage referenced I/O standard	<p>The JEDEC standard for the SSTL and HSTL I/O defines both the AC and DC input signal values. The AC values indicate the voltage levels at which the receiver must meet its timing specifications. The DC values indicate the voltage levels at which the final logic state of the receiver is unambiguously defined. After the receiver input has crossed the AC value, the receiver changes to the new logic state.</p> <p>The new logic state is then maintained as long as the input stays beyond the DC threshold. This approach is intended to provide predictable receiver timing in the presence of input waveform ringing.</p> <p>Single-Ended Voltage Referenced I/O Standard</p> 
t_C	High-speed receiver/transmitter input and output clock period.
TCCS (channel-to-channel-skew)	The timing difference between the fastest and slowest output edges, including the t_{CO} variation and clock skew, across channels driven by the same PLL. The clock is included in the TCCS measurement (refer to the Timing Diagram figure under SW in this table).
t_{DUTY}	High-speed I/O block—Duty cycle on high-speed transmitter output clock.

Date	Version	Changes
December 2015	2015.12.16	<ul style="list-style-type: none">Updated Quad Serial Peripheral Interface (SPI) Flash Timing Requirements for Arria V Devices table.<ul style="list-style-type: none">Updated F_{clk}, $T_{duty\ cycle}$, and $T_{dss\ first}$ specifications.Added T_{qspi_clk}, T_{din_start}, and T_{din_end} specifications.Removed $T_{din\ max}$ specifications.Updated the minimum specification for T_{clk} to 16.67 ns and removed the maximum specification in SPI Master Timing Requirements for Arria V Devices table.Updated Secure Digital (SD)/MultiMediaCard (MMC) Timing Requirements for Arria V Devices table.<ul style="list-style-type: none">Updated T_{clk} to $T_{sdmmc_clk_out}$ symbol.Updated $T_{sdmmc_clk_out}$ and T_d specifications.Added T_{sdmmc_clk}, T_{su}, and T_h specifications.Removed $T_{din\ max}$ specifications.Updated the following diagrams:<ul style="list-style-type: none">Quad SPI Flash Timing DiagramSD/MMC Timing DiagramUpdated configuration .rbf sizes for Arria V devices.Changed instances of <i>Quartus II</i> to <i>Quartus Prime</i>.

Date	Version	Changes
November 2012	3.0	<ul style="list-style-type: none"> Updated Table 2, Table 4, Table 9, Table 14, Table 16, Table 17, Table 20, Table 21, Table 25, Table 29, Table 36, Table 56, Table 57, and Table 60. Removed table: Transceiver Block Jitter Specifications for Arria V Devices. Added HPS information: <ul style="list-style-type: none"> Added “HPS Specifications” section. Added Table 38, Table 39, Table 40, Table 41, Table 42, Table 43, Table 44, Table 45, Table 46, Table 47, Table 48, Table 49, and Table 50. Added Figure 7, Figure 8, Figure 9, Figure 10, Figure 11, Figure 12, Figure 13, Figure 14, Figure 15, Figure 16, Figure 17, Figure 18, and Figure 19. Updated Table 3 and Table 5.
October 2012	2.4	<ul style="list-style-type: none"> Updated Arria V GX $V_{CCR_GXBL/R}$, $V_{CCT_GXBL/R}$, and $V_{CCL_GXBL/R}$ minimum and maximum values, and data rate in Table 4. Added receiver V_{ICM} (AC coupled) and V_{ICM} (DC coupled) values, and transmitter V_{OCM} (AC coupled) and V_{OCM} (DC coupled) values in Table 20 and Table 21.
August 2012	2.3	Updated the SERDES factor condition in Table 30.
July 2012	2.2	<ul style="list-style-type: none"> Updated the maximum voltage for V_I (DC input voltage) in Table 1. Updated Table 20 to include the Arria V GX -I3 speed grade. Updated the minimum value of the fixedclk clock frequency in Table 20 and Table 21. Updated the SERDES factor condition in Table 30. Updated Table 50 to include the IOE programmable delay settings for the Arria V GX -I3 speed grade.
June 2012	2.1	Updated $V_{CCR_GXBL/R}$, $V_{CCT_GXBL/R}$, and $V_{CCL_GXBL/R}$ values in Table 4.

Transceiver Power Supply Requirements

Table 2-7: Transceiver Power Supply Voltage Requirements for Arria V GZ Devices

Conditions	VCCR_GXB and VCCT_GXB ⁽¹²²⁾	VCCA_GXB	VCCH_GXB	Unit
If BOTH of the following conditions are true: <ul style="list-style-type: none"> Data rate > 10.3 Gbps. DFE is used. 	1.05	3.0	1.5	V
If ANY of the following conditions are true ⁽¹²³⁾ : <ul style="list-style-type: none"> ATX PLL is used. Data rate > 6.5Gbps. DFE (data rate ≤ 10.3 Gbps), AEQ, or EyeQ feature is used. 	1.0			
If ALL of the following conditions are true: <ul style="list-style-type: none"> ATX PLL is not used. Data rate ≤ 6.5Gbps. DFE, AEQ, and EyeQ are not used. 	0.85	2.5		

DC Characteristics

Supply Current

Standby current is the current drawn from the respective power rails used for power budgeting.

Use the Excel-based Early Power Estimator (EPE) to get supply current estimates for your design because these currents vary greatly with the resources you use.

⁽¹²²⁾ If the VCCR_GXB and VCCT_GXB supplies are set to 1.0 V or 1.05 V, they cannot be shared with the VCC core supply. If the VCCR_GXB and VCCT_GXB are set to 0.85 V, they can be shared with the VCC core supply.

⁽¹²³⁾ Choose this power supply voltage requirement option if you plan to upgrade your design later with any of the listed conditions.

Symbol/Description	Conditions	Transceiver Speed Grade 2			Transceiver Speed Grade 3			Unit
		Min	Typ	Max	Min	Typ	Max	
Transmitter REFCLK Phase Noise (622 MHz) ⁽¹⁴¹⁾	100 Hz	—	—	-70	—	—	-70	dBc/Hz
	1 kHz	—	—	-90	—	—	-90	dBc/Hz
	10 kHz	—	—	-100	—	—	-100	dBc/Hz
	100 kHz	—	—	-110	—	—	-110	dBc/Hz
	≥1 MHz	—	—	-120	—	—	-120	dBc/Hz
Transmitter REFCLK Phase Jitter (100 MHz) ⁽¹⁴²⁾	10 kHz to 1.5 MHz (PCIe)	—	—	3	—	—	3	ps (rms)
R _{REF}	—	—	1800 ±1%	—	—	1800 ±1%	—	Ω

Related Information[Arria V Device Overview](#)

For more information about device ordering codes.

Transceiver Clocks**Table 2-23: Transceiver Clocks Specifications for Arria V GZ Devices**

Speed grades shown refer to the PMA Speed Grade in the device ordering code. The maximum data rate could be restricted by the Core/PCS speed grade. Contact your Altera Sales Representative for the maximum data rate specifications in each speed grade combination offered. For more information about device ordering codes, refer to the *Arria V Device Overview*.

⁽¹⁴¹⁾ To calculate the REFCLK phase noise requirement at frequencies other than 622 MHz, use the following formula: REFCLK phase noise at f(MHz) = REFCLK phase noise at 622 MHz + 20*log(f/622).

⁽¹⁴²⁾ To calculate the REFCLK rms phase jitter requirement for PCIe at reference clock frequencies other than 100 MHz, use the following formula: REFCLK rms phase jitter at f(MHz) = REFCLK rms phase jitter at 100 MHz × 100/f.

Symbol	Parameter	Min	Typ	Max	Unit
$t_{\text{INCCJ}}^{(171), (172)}$	Input clock cycle-to-cycle jitter ($f_{\text{REF}} \geq 100$ MHz)	—	—	0.15	UI (p-p)
	Input clock cycle-to-cycle jitter ($f_{\text{REF}} < 100$ MHz)	-750	—	+750	ps (p-p)
$t_{\text{OUTPJ_DC}}^{(173)}$	Period Jitter for dedicated clock output in integer PLL ($f_{\text{OUT}} \geq 100$ MHz)	—	—	175	ps (p-p)
	Period Jitter for dedicated clock output in integer PLL ($f_{\text{OUT}} < 100$ MHz)	—	—	17.5	mUI (p-p)
$t_{\text{FOUTPJ_DC}}^{(173)}$	Period Jitter for dedicated clock output in fractional PLL ($f_{\text{OUT}} \geq 100$ MHz)	—	—	250 ⁽¹⁷⁶⁾ , 175 ⁽¹⁷⁴⁾	ps (p-p)
	Period Jitter for dedicated clock output in fractional PLL ($f_{\text{OUT}} < 100$ MHz)	—	—	25 ⁽¹⁷⁶⁾ , 17.5 ⁽¹⁷⁴⁾	mUI (p-p)
$t_{\text{OUTCCJ_DC}}^{(173)}$	Cycle-to-cycle Jitter for a dedicated clock output in integer PLL ($f_{\text{OUT}} \geq 100$ MHz)	—	—	175	ps (p-p)
	Cycle-to-cycle Jitter for a dedicated clock output in integer PLL ($f_{\text{OUT}} < 100$ MHz)	—	—	17.5	mUI (p-p)
$t_{\text{FOUTCCJ_DC}}^{(173)}$	Cycle-to-cycle Jitter for a dedicated clock output in fractional PLL ($f_{\text{OUT}} \geq 100$ MHz)	—	—	250 ⁽¹⁷⁶⁾ , 175 ⁽¹⁷⁴⁾	ps (p-p)
	Cycle-to-cycle Jitter for a dedicated clock output in fractional PLL ($f_{\text{OUT}} < 100$ MHz)	—	—	25 ⁽¹⁷⁶⁾ , 17.5 ⁽¹⁷⁴⁾	mUI (p-p)

⁽¹⁷¹⁾ A high input jitter directly affects the PLL output jitter. To have low PLL output clock jitter, you must provide a clean clock source with jitter < 120 ps.

⁽¹⁷²⁾ The f_{REF} is f_{IN}/N specification applies when $N = 1$.

⁽¹⁷³⁾ Peak-to-peak jitter with a probability level of 10^{-12} (14 sigma, 99.9999999974404% confidence level). The output jitter specification applies to the intrinsic jitter of the PLL, when an input jitter of 30 ps is applied. The external memory interface clock output jitter specifications use a different measurement method and are available in the "Worst-Case DCD on Arria V GZ I/O Pins" table.

⁽¹⁷⁴⁾ This specification only covered fractional PLL for low bandwidth. The f_{VCO} for fractional value range 0.20–0.80 must be ≥ 1200 MHz.

Symbol	Conditions	C3, I3L			C4, I4			Unit
		Min	Typ	Max	Min	Typ	Max	
$f_{\text{HCLK_in}}$ (input clock frequency) True Differential I/O Standards ⁽¹⁷⁹⁾	Clock boost factor $W = 1$ to 40 ⁽¹⁸⁰⁾	5	—	625	5	—	525	MHz
$f_{\text{HCLK_in}}$ (input clock frequency) Single Ended I/O Standards	Clock boost factor $W = 1$ to 40 ⁽¹⁸⁰⁾	5	—	625	5	—	525	MHz
$f_{\text{HCLK_in}}$ (input clock frequency) Single Ended I/O Standards	Clock boost factor $W = 1$ to 40 ⁽¹⁸⁰⁾	5	—	420	5	—	420	MHz
$f_{\text{HCLK_OUT}}$ (output clock frequency)	—	5	—	625 ⁽¹⁸¹⁾	5	—	525 ⁽¹⁸¹⁾	MHz

Transmitter High-Speed I/O Specifications

Table 2-40: Transmitter High-Speed I/O Specifications for Arria V GZ Devices

When $J = 3$ to 10 , use the serializer/deserializer (SERDES) block.

When $J = 1$ or 2 , bypass the SERDES block.

⁽¹⁷⁹⁾ This only applies to DPA and soft-CDR modes.

⁽¹⁸⁰⁾ Clock Boost Factor (W) is the ratio between the input data rate to the input clock rate.

⁽¹⁸¹⁾ This is achieved by using the LVDS clock network.

Symbol	Parameter	Minimum	Maximum	Unit
t_{CD2CU}	CONF_DONE high to CLKUSR enabled	$4 \times \text{maximum DCLK period}$	—	—
t_{CD2UMC}	CONF_DONE high to user mode with CLKUSR option on	$t_{CD2CU} + (8576 \times \text{CLKUSR period})$ (209)	—	—

Related Information

- [DCLK-to-DATA\[\] Ratio \(r\) for FPP Configuration](#) on page 2-57
- [Configuration, Design Security, and Remote System Upgrades in Arria V Devices](#)

(208) The minimum and maximum numbers apply only if you chose the internal oscillator as the clock source for initializing the device.

(209) To enable the CLKUSR pin as the initialization clock source and to obtain the maximum frequency specification on these pins, refer to the “Initialization” section of the *Configuration, Design Security, and Remote System Upgrades in Arria V Devices* chapter.

Term	Definition
t_C	High-speed receiver and transmitter input and output clock period.
TCCS (channel-to-channel-skew)	The timing difference between the fastest and slowest output edges, including t_{CO} variation and clock skew, across channels driven by the same PLL. The clock is included in the TCCS measurement (refer to the Timing Diagram figure under SW in this table).
t_{DUTY}	High-speed I/O block—Duty cycle on the high-speed transmitter output clock.
t_{FALL}	Signal high-to-low transition time (80-20%)
t_{INCCJ}	Cycle-to-cycle jitter tolerance on the PLL clock input.
t_{OUTPJ_IO}	Period jitter on the general purpose I/O driven by a PLL.
t_{OUTPJ_DC}	Period jitter on the dedicated clock output driven by a PLL.
t_{RISE}	Signal low-to-high transition time (20-80%)
Timing Unit Interval (TUI)	The timing budget allowed for skew, propagation delays, and the data sampling window. ($TUI = 1/(\text{receiver input clock frequency multiplication factor}) = t_C/w$)
$V_{CM(DC)}$	DC common mode input voltage.
V_{ICM}	Input common mode voltage—The common mode of the differential signal at the receiver.
V_{ID}	Input differential voltage swing—The difference in voltage between the positive and complementary conductors of a differential transmission at the receiver.
$V_{DIF(AC)}$	AC differential input voltage—Minimum AC input differential voltage required for switching.
$V_{DIF(DC)}$	DC differential input voltage— Minimum DC input differential voltage required for switching.
V_{IH}	Voltage input high—The minimum positive voltage applied to the input which is accepted by the device as a logic high.
$V_{IH(AC)}$	High-level AC input voltage
$V_{IH(DC)}$	High-level DC input voltage
V_{IL}	Voltage input low—The maximum positive voltage applied to the input which is accepted by the device as a logic low.
$V_{IL(AC)}$	Low-level AC input voltage
$V_{IL(DC)}$	Low-level DC input voltage