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Understanding [Embedded - FPGAs \(Field Programmable Gate Array\)](#)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details

| | |
|--------------------------------|-------------------------------------------------------------------------------------------------------------------------------------|
| Product Status | Active |
| Number of LABs/CLBs | 17110 |
| Number of Logic Elements/Cells | 362000 |
| Total RAM Bits | 19822592 |
| Number of I/O | 544 |
| Number of Gates | - |
| Voltage - Supply | 1.07V ~ 1.13V |
| Mounting Type | Surface Mount |
| Operating Temperature | -40°C ~ 100°C (TJ) |
| Package / Case | 1152-BBGA, FCBGA Exposed Pad |
| Supplier Device Package | 1152-FBGA (35x35) |
| Purchase URL | https://www.e-xfl.com/product-detail/intel/5agxfb3h4f35i5g |

| Symbol | Description | Condition | Minimum ⁽¹⁾ | Typical | Maximum ⁽¹⁾ | Unit |
|----------------------------------|--------------------------------------------|--------------|------------------------|---------|------------------------|------|
| V _{CCIO} | I/O buffers power supply | 3.3 V | 3.135 | 3.3 | 3.465 | V |
| | | 3.0 V | 2.85 | 3.0 | 3.15 | V |
| | | 2.5 V | 2.375 | 2.5 | 2.625 | V |
| | | 1.8 V | 1.71 | 1.8 | 1.89 | V |
| | | 1.5 V | 1.425 | 1.5 | 1.575 | V |
| | | 1.35 V | 1.283 | 1.35 | 1.418 | V |
| | | 1.25 V | 1.19 | 1.25 | 1.31 | V |
| | | 1.2 V | 1.14 | 1.2 | 1.26 | V |
| V _{CCD_FPLL} | PLL digital voltage regulator power supply | — | 1.425 | 1.5 | 1.575 | V |
| V _{CCA_FPLL} | PLL analog voltage regulator power supply | — | 2.375 | 2.5 | 2.625 | V |
| V _I | DC input voltage | — | −0.5 | — | 3.6 | V |
| V _O | Output voltage | — | 0 | — | V _{CCIO} | V |
| T _J | Operating junction temperature | Commercial | 0 | — | 85 | °C |
| | | Industrial | −40 | — | 100 | °C |
| t _{RAMP} ⁽⁴⁾ | Power supply ramp time | Standard POR | 200 μs | — | 100 ms | — |
| | | Fast POR | 200 μs | — | 4 ms | — |

⁽¹⁾ The power supply value describes the budget for the DC (static) power supply tolerance and does not include the dynamic tolerance requirements. Refer to the PDN tool for the additional budget for the dynamic tolerance requirements.

⁽⁴⁾ This is also applicable to HPS power supply. For HPS power supply, refer to t_{RAMP} specifications for standard POR when HPS_PORSEL = 0 and t_{RAMP} specifications for fast POR when HPS_PORSEL = 1.

| Symbol | Description | Condition (V) | Calibration Accuracy | | | Unit |
|--------------------------------------|-----------------------------------------------------------------------------------------------------|--------------------------------------|----------------------|------------|------------|------|
| | | | -I3, -C4 | -I5, -C5 | -C6 | |
| 60- Ω and 120- Ω R_T | Internal parallel termination with calibration (60- Ω and 120- Ω setting) | $V_{CCIO} = 1.2$ | -10 to +40 | -10 to +40 | -10 to +40 | % |
| 25- Ω $R_{S_left_shift}$ | Internal left shift series termination with calibration (25- Ω $R_{S_left_shift}$ setting) | $V_{CCIO} = 3.0, 2.5, 1.8, 1.5, 1.2$ | ± 15 | ± 15 | ± 15 | % |

OCT Without Calibration Resistance Tolerance Specifications

Table 1-9: OCT Without Calibration Resistance Tolerance Specifications for Arria V Devices

This table lists the Arria V OCT without calibration resistance tolerance to PVT changes.

| Symbol | Description | Condition (V) | ResistanceTolerance | | | Unit |
|---------------------|------------------------------------------------------------------------|-----------------------|---------------------|----------|----------|------|
| | | | -I3, -C4 | -I5, -C5 | -C6 | |
| 25- Ω R_S | Internal series termination without calibration (25- Ω setting) | $V_{CCIO} = 3.0, 2.5$ | ± 30 | ± 40 | ± 40 | % |
| 25- Ω R_S | Internal series termination without calibration (25- Ω setting) | $V_{CCIO} = 1.8, 1.5$ | ± 30 | ± 40 | ± 40 | % |
| 25- Ω R_S | Internal series termination without calibration (25- Ω setting) | $V_{CCIO} = 1.2$ | ± 35 | ± 50 | ± 50 | % |
| 50- Ω R_S | Internal series termination without calibration (50- Ω setting) | $V_{CCIO} = 3.0, 2.5$ | ± 30 | ± 40 | ± 40 | % |
| 50- Ω R_S | Internal series termination without calibration (50- Ω setting) | $V_{CCIO} = 1.8, 1.5$ | ± 30 | ± 40 | ± 40 | % |
| 50- Ω R_S | Internal series termination without calibration (50- Ω setting) | $V_{CCIO} = 1.2$ | ± 35 | ± 50 | ± 50 | % |
| 100- Ω R_D | Internal differential termination (100- Ω setting) | $V_{CCIO} = 2.5$ | ± 25 | ± 40 | ± 40 | % |

| Symbol/Description | Condition | Transceiver Speed Grade 4 | | | Transceiver Speed Grade 6 | | | Unit |
|-----------------------------------------------------------------------------|--------------------|---------------------------|-----|-----|---------------------------|-----|-----|------|
| | | Min | Typ | Max | Min | Typ | Max | |
| Inter-transceiver block transmitter channel-to-channel skew ⁽³⁹⁾ | ×N PMA bonded mode | — | — | 500 | — | — | 500 | ps |

Table 1-24: CMU PLL Specifications for Arria V GX and SX Devices

| Symbol/Description | Transceiver Speed Grade 4 | | Transceiver Speed Grade 6 | | Unit |
|---------------------------|---------------------------|--------|---------------------------|------|------|
| | Min | Max | Min | Max | |
| Supported data range | 611 | 6553.6 | 611 | 3125 | Mbps |
| fPLL supported data range | 611 | 3125 | 611 | 3125 | Mbps |

Table 1-25: Transceiver-FPGA Fabric Interface Specifications for Arria V GX and SX Devices

| Symbol/Description | Transceiver Speed Grade 4 and 6 | | Unit |
|-------------------------------------|---------------------------------|--------|------|
| | Min | Max | |
| Interface speed (single-width mode) | 25 | 187.5 | MHz |
| Interface speed (double-width mode) | 25 | 163.84 | MHz |

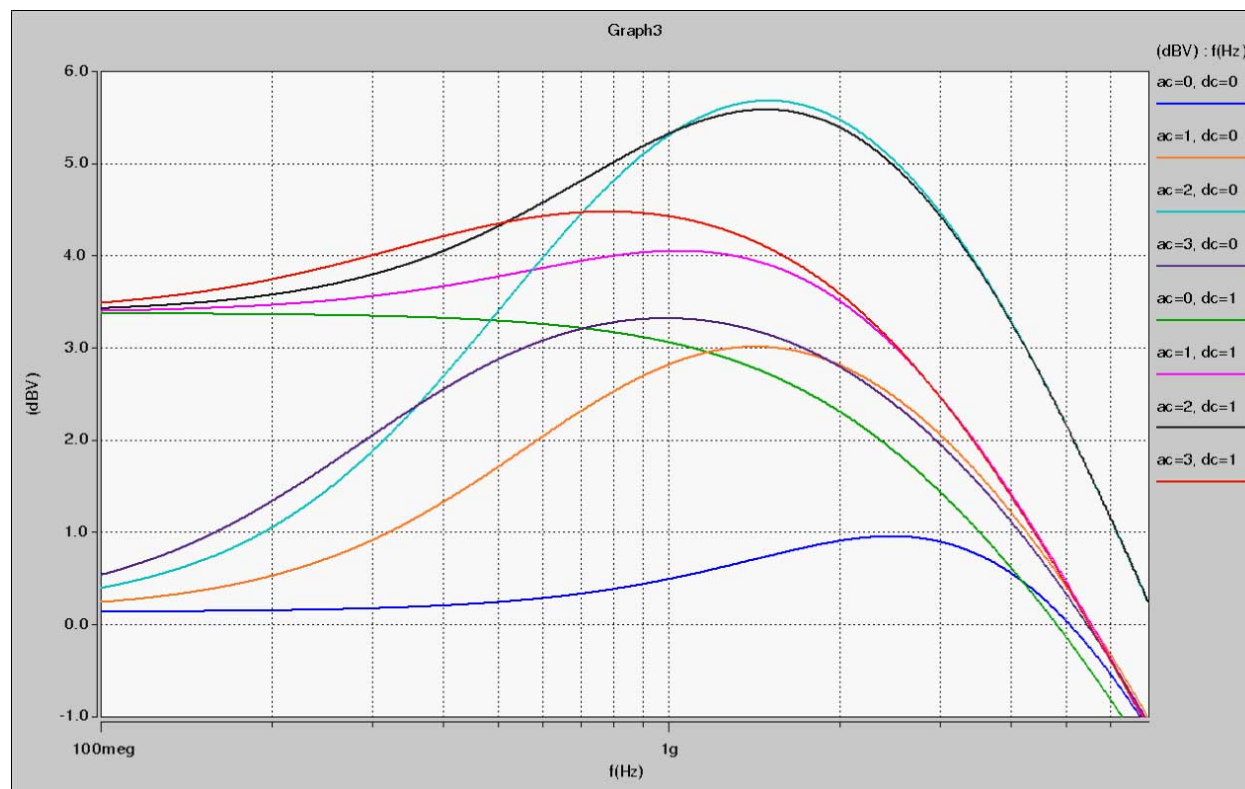
Related Information

- [CTLE Response at Data Rates > 3.25 Gbps across Supported AC Gain and DC Gain](#) on page 1-35
- [CTLE Response at Data Rates ≤ 3.25 Gbps across Supported AC Gain and DC Gain](#) on page 1-36
- [Arria V GT, GX, ST, and SX Device Family Pin Connection Guidelines](#)
Provides more information about the power supply connection for different data rates.

⁽³⁹⁾ This specification is only applicable to channels on one side of the device across two transceiver banks.

CTLE Response at Data Rates ≤ 3.25 Gbps across Supported AC Gain and DC Gain

Figure 1-3: CTLE Response at Data Rates ≤ 3.25 Gbps across Supported AC Gain and DC Gain for Arria V GX, GT, SX, and ST Devices



For example, when $V_{OD} = 800$ mV, the corresponding V_{OD} value setting is 40. The following conditions show that the 1st post tap pre-emphasis setting = 2 is valid:

- $|B| + |C| \leq 60 \rightarrow 40 + 2 = 42$
- $|B| - |C| > 5 \rightarrow 40 - 2 = 38$
- $(V_{MAX}/V_{MIN} - 1)\% < 600\% \rightarrow (42/38 - 1)\% = 10.52\%$

To predict the pre-emphasis level for your specific data rate and pattern, run simulations using the Arria V HSSI HSPICE models.

Table 1-33: Transmitter Pre-Emphasis Levels for Arria V Devices

| Quartus Prime 1st Post Tap Pre-Emphasis Setting | Quartus Prime V_{OD} Setting | | | | | | | Unit |
|-------------------------------------------------|--------------------------------|-------------|-------------|-------------|-------------|-------------|--------------|------|
| | 10 (200 mV) | 20 (400 mV) | 30 (600 mV) | 35 (700 mV) | 40 (800 mV) | 45 (900 mV) | 50 (1000 mV) | |
| 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 | dB |
| 1 | 1.97 | 0.88 | 0.43 | 0.32 | 0.24 | 0.19 | 0.13 | dB |
| 2 | 3.58 | 1.67 | 0.95 | 0.76 | 0.61 | 0.5 | 0.41 | dB |
| 3 | 5.35 | 2.48 | 1.49 | 1.2 | 1 | 0.83 | 0.69 | dB |
| 4 | 7.27 | 3.31 | 2 | 1.63 | 1.36 | 1.14 | 0.96 | dB |
| 5 | — | 4.19 | 2.55 | 2.1 | 1.76 | 1.49 | 1.26 | dB |
| 6 | — | 5.08 | 3.11 | 2.56 | 2.17 | 1.83 | 1.56 | dB |
| 7 | — | 5.99 | 3.71 | 3.06 | 2.58 | 2.18 | 1.87 | dB |
| 8 | — | 6.92 | 4.22 | 3.47 | 2.93 | 2.48 | 2.11 | dB |
| 9 | — | 7.92 | 4.86 | 4 | 3.38 | 2.87 | 2.46 | dB |
| 10 | — | 9.04 | 5.46 | 4.51 | 3.79 | 3.23 | 2.77 | dB |
| 11 | — | 10.2 | 6.09 | 5.01 | 4.23 | 3.61 | — | dB |
| 12 | — | 11.56 | 6.74 | 5.51 | 4.68 | 3.97 | — | dB |
| 13 | — | 12.9 | 7.44 | 6.1 | 5.12 | 4.36 | — | dB |
| 14 | — | 14.44 | 8.12 | 6.64 | 5.57 | 4.76 | — | dB |
| 15 | — | — | 8.87 | 7.21 | 6.06 | 5.14 | — | dB |

DSP Block Performance Specifications

Table 1-37: DSP Block Performance Specifications for Arria V Devices

| Mode | | Performance | | | Unit |
|----------------------------|----------------------------------------------------------|-------------|----------|-----|------|
| | | -I3, -C4 | -I5, -C5 | -C6 | |
| Modes using One DSP Block | Independent 9×9 multiplication | 370 | 310 | 220 | MHz |
| | Independent 18×19 multiplication | 370 | 310 | 220 | MHz |
| | Independent 18×25 multiplication | 370 | 310 | 220 | MHz |
| | Independent 20×24 multiplication | 370 | 310 | 220 | MHz |
| | Independent 27×27 multiplication | 310 | 250 | 200 | MHz |
| | Two 18×19 multiplier adder mode | 370 | 310 | 220 | MHz |
| | 18×18 multiplier added summed with 36-bit input | 370 | 310 | 220 | MHz |
| Modes using Two DSP Blocks | Complex 18×19 multiplication | 370 | 310 | 220 | MHz |

Memory Block Performance Specifications

To achieve the maximum memory block performance, use a memory block clock that comes through global clock routing from an on-chip PLL and set to 50% output duty cycle. Use the Quartus Prime software to report timing for the memory block clocking schemes.

When you use the error detection cyclical redundancy check (CRC) feature, there is no degradation in f_{MAX} .

High-Speed I/O Specifications

Table 1-40: High-Speed I/O Specifications for Arria V Devices

When $J = 3$ to 10, use the serializer/deserializer (SERDES) block. When $J = 1$ or 2, bypass the SERDES block.

For LVDS applications, you must use the PLLs in integer PLL mode.

The Arria V devices support the following output standards using true LVDS output buffer types on all I/O banks.

- True RSDS output standard with data rates of up to 360 Mbps
- True mini-LVDS output standard with data rates of up to 400 Mbps

| Symbol | | Condition | -I3, -C4 | | | -I5, -C5 | | | -C6 | | | Unit |
|------------------------------------------------------------------------------------------|-----------------------------------------------------------------|-------------------------------------------|-----------------|-----|--------------|-----------------|-----|--------------|-----------------|-----|--------------|------|
| | | | Min | Typ | Max | Min | Typ | Max | Min | Typ | Max | |
| $f_{\text{HCLK_in}}$ (input clock frequency) True Differential I/O Standards | | Clock boost factor $W = 1$ to $40^{(72)}$ | 5 | — | 800 | 5 | — | 750 | 5 | — | 625 | MHz |
| $f_{\text{HCLK_in}}$ (input clock frequency) Single-Ended I/O Standards ⁽⁷³⁾ | | Clock boost factor $W = 1$ to $40^{(72)}$ | 5 | — | 625 | 5 | — | 625 | 5 | — | 500 | MHz |
| $f_{\text{HCLK_in}}$ (input clock frequency) Single-Ended I/O Standards ⁽⁷⁴⁾ | | Clock boost factor $W = 1$ to $40^{(72)}$ | 5 | — | 420 | 5 | — | 420 | 5 | — | 420 | MHz |
| $f_{\text{HCLK_OUT}}$ (output clock frequency) | | — | 5 | — | $625^{(75)}$ | 5 | — | $625^{(75)}$ | 5 | — | $500^{(75)}$ | MHz |
| Transmitter | True Differential I/O Standards - f_{HSDR} (data rate) | SERDES factor $J = 3$ to $10^{(76)}$ | ⁽⁷⁷⁾ | — | 1250 | ⁽⁷⁷⁾ | — | 1250 | ⁽⁷⁷⁾ | — | 1050 | Mbps |

⁽⁷²⁾ Clock boost factor (W) is the ratio between the input data rate and the input clock rate.

⁽⁷³⁾ This applies to DPA and soft-CDR modes only.

⁽⁷⁴⁾ This applies to non-DPA mode only.

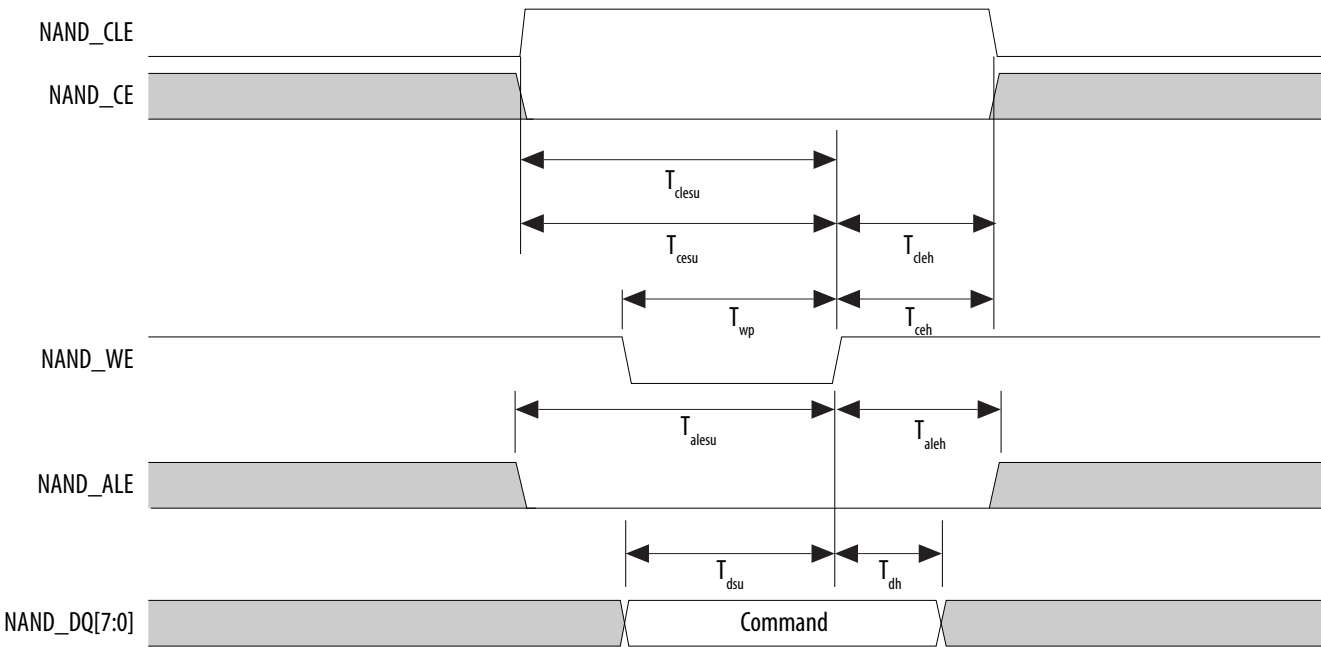
⁽⁷⁵⁾ This is achieved by using the LVDS clock network.

⁽⁷⁶⁾ The F_{max} specification is based on the fast clock used for serial data. The interface F_{max} is also dependent on the parallel clock domain which is design dependent and requires timing analysis.

⁽⁷⁷⁾ The minimum specification depends on the clock source (for example, the PLL and clock pin) and the clock routing resource (global, regional, or local) that you use. The I/O differential buffer and input register do not have a minimum toggle rate.

| Symbol | Description | Min | Max | Unit |
|-----------------|------------------------------------|-----|-----|------|
| $T_{dh}^{(89)}$ | Data to write enable hold time | 5 | — | ns |
| T_{cea} | Chip enable to data access time | — | 25 | ns |
| T_{rea} | Read enable to data access time | — | 16 | ns |
| T_{rhz} | Read enable to data high impedance | — | 100 | ns |
| T_{rr} | Ready to read enable low | 20 | — | ns |

Figure 1-17: NAND Command Latch Timing Diagram



| Date | Version | Changes |
|-------------|---------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| August 2013 | 3.5 | <ul style="list-style-type: none">Removed “Pending silicon characterization” note in Table 29.Updated Table 25. |
| August 2013 | 3.4 | <ul style="list-style-type: none">Removed Preliminary tags for Table 1, Table 2, Table 3, Table 4, Table 5, Table 6, Table 7, Table 9, Table 12, Table 13, Table 14, Table 15, Table 16, Table 17, Table 18, Table 19, Table 20, Table 21, Table 22, Table 23, Table 24, Table 25, Table 26, Table 27, Table 28, Table 29, Table 30, Table 31, Table 35, Table 36, Table 51, Table 53, Table 54, Table 55, Table 56, Table 57, Table 60, Table 62, and Table 64.Updated Table 1, Table 3, Table 11, Table 19, Table 20, Table 21, Table 22, Table 25, and Table 29. |
| June 2013 | 3.3 | Updated Table 20, Table 21, Table 25, and Table 38. |
| May 2013 | 3.2 | <ul style="list-style-type: none">Added Table 37.Updated Figure 8, Figure 9, Figure 20, Figure 22, and Figure 23.Updated Table 1, Table 5, Table 10, Table 13, Table 19, Table 20, Table 21, Table 23, Table 29, Table 39, Table 40, Table 46, Table 56, Table 57, Table 60, and Table 64.Updated industrial junction temperature range for –I3 speed grade in “PLL Specifications” section. |
| March 2013 | 3.1 | <ul style="list-style-type: none">Added HPS reset information in the “HPS Specifications” section.Added Table 60.Updated Table 1, Table 3, Table 17, Table 20, Table 29, and Table 59.Updated Figure 21. |

| Symbol | Description | Minimum | Maximum | Unit |
|-----------|--------------------------------|---------|---------|------|
| V_I | DC input voltage | -0.5 | 3.8 | V |
| T_J | Operating junction temperature | -55 | 125 | °C |
| T_{STG} | Storage temperature (No bias) | -65 | 150 | °C |
| I_{OUT} | DC output current per pin | -25 | 40 | mA |

Table 2-3: Transceiver Power Supply Absolute Conditions for Arria V GZ Devices

| Symbol | Description | Minimum | Maximum | Unit |
|-----------------|-----------------------------------------------------|---------|---------|------|
| V_{CCA_GXBL} | Transceiver channel PLL power supply (left side) | -0.5 | 3.75 | V |
| V_{CCA_GXBR} | Transceiver channel PLL power supply (right side) | -0.5 | 3.75 | V |
| V_{CCHIP_L} | Transceiver hard IP power supply (left side) | -0.5 | 1.35 | V |
| V_{CCHSSI_L} | Transceiver PCS power supply (left side) | -0.5 | 1.35 | V |
| V_{CCHSSI_R} | Transceiver PCS power supply (right side) | -0.5 | 1.35 | V |
| V_{CCR_GXBL} | Receiver analog power supply (left side) | -0.5 | 1.35 | V |
| V_{CCR_GXBR} | Receiver analog power supply (right side) | -0.5 | 1.35 | V |
| V_{CCT_GXBL} | Transmitter analog power supply (left side) | -0.5 | 1.35 | V |
| V_{CCT_GXBR} | Transmitter analog power supply (right side) | -0.5 | 1.35 | V |
| V_{CCH_GXBL} | Transmitter output buffer power supply (left side) | -0.5 | 1.8 | V |
| V_{CCH_GXBR} | Transmitter output buffer power supply (right side) | -0.5 | 1.8 | V |

Maximum Allowed Overshoot and Undershoot Voltage

During transitions, input signals may overshoot to the voltage shown in the following table. They may also undershoot to -2.0 V for input currents less than 100 mA and periods shorter than 20 ns.

Transceiver Power Supply Requirements

Table 2-7: Transceiver Power Supply Voltage Requirements for Arria V GZ Devices

| Conditions | VCCR_GXB and VCCT_GXB ⁽¹²²⁾ | VCCA_GXB | VCCH_GXB | Unit |
|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|----------------------------------------|----------|----------|------|
| If BOTH of the following conditions are true: <ul style="list-style-type: none"> Data rate > 10.3 Gbps. DFE is used. | 1.05 | 3.0 | 1.5 | V |
| If ANY of the following conditions are true ⁽¹²³⁾ : <ul style="list-style-type: none"> ATX PLL is used. Data rate > 6.5Gbps. DFE (data rate ≤ 10.3 Gbps), AEQ, or EyeQ feature is used. | 1.0 | | | |
| If ALL of the following conditions are true: <ul style="list-style-type: none"> ATX PLL is not used. Data rate ≤ 6.5Gbps. DFE, AEQ, and EyeQ are not used. | 0.85 | 2.5 | | |

DC Characteristics

Supply Current

Standby current is the current drawn from the respective power rails used for power budgeting.

Use the Excel-based Early Power Estimator (EPE) to get supply current estimates for your design because these currents vary greatly with the resources you use.

⁽¹²²⁾ If the VCCR_GXB and VCCT_GXB supplies are set to 1.0 V or 1.05 V, they cannot be shared with the VCC core supply. If the VCCR_GXB and VCCT_GXB are set to 0.85 V, they can be shared with the VCC core supply.

⁽¹²³⁾ Choose this power supply voltage requirement option if you plan to upgrade your design later with any of the listed conditions.

Table 2-19: Differential SSTL I/O Standards for Arria V GZ Devices

| I/O Standard | V_{CCIO} (V) | | | $V_{SWING(DC)}$ (V) | | $V_{X(AC)}$ (V) | | | $V_{SWING(AC)}$ (V) | |
|----------------------|----------------|------|-------|---------------------|------------------|----------------------|--------------|----------------------|---------------------------|---------------------------|
| | Min | Typ | Max | Min | Max | Min | Typ | Max | Min | Max |
| SSTL-2 Class I, II | 2.375 | 2.5 | 2.625 | 0.3 | $V_{CCIO} + 0.6$ | $V_{CCIO}/2 - 0.2$ | — | $V_{CCIO}/2 + 0.2$ | 0.62 | $V_{CCIO} + 0.6$ |
| SSTL-18 Class I, II | 1.71 | 1.8 | 1.89 | 0.25 | $V_{CCIO} + 0.6$ | $V_{CCIO}/2 - 0.175$ | — | $V_{CCIO}/2 + 0.175$ | 0.5 | $V_{CCIO} + 0.6$ |
| SSTL-15 Class I, II | 1.425 | 1.5 | 1.575 | 0.2 | ⁽¹²⁷⁾ | $V_{CCIO}/2 - 0.15$ | — | $V_{CCIO}/2 + 0.15$ | 0.35 | — |
| SSTL-135 Class I, II | 1.283 | 1.35 | 1.45 | 0.2 | ⁽¹²⁷⁾ | $V_{CCIO}/2 - 0.15$ | $V_{CCIO}/2$ | $V_{CCIO}/2 + 0.15$ | $2(V_{IH(AC)} - V_{REF})$ | $2(V_{IL(AC)} - V_{REF})$ |
| SSTL-125 Class I, II | 1.19 | 1.25 | 1.31 | 0.18 | ⁽¹²⁷⁾ | $V_{CCIO}/2 - 0.15$ | $V_{CCIO}/2$ | $V_{CCIO}/2 + 0.15$ | $2(V_{IH(AC)} - V_{REF})$ | — |
| SSTL-12 Class I, II | 1.14 | 1.2 | 1.26 | 0.18 | — | $V_{REF} - 0.15$ | $V_{CCIO}/2$ | $V_{REF} + 0.15$ | -0.30 | 0.30 |

Table 2-20: Differential HSTL and HSUL I/O Standards for Arria V GZ Devices

| I/O Standard | V_{CCIO} (V) | | | $V_{DIF(DC)}$ (V) | | $V_{X(AC)}$ (V) | | | $V_{CM(DC)}$ (V) | | | $V_{DIF(AC)}$ (V) | |
|---------------------|----------------|-----|-------|-------------------|-----|-----------------|-----|------|------------------|-----|------|-------------------|-----|
| | Min | Typ | Max | Min | Max | Min | Typ | Max | Min | Typ | Max | Min | Max |
| HSTL-18 Class I, II | 1.71 | 1.8 | 1.89 | 0.2 | — | 0.78 | — | 1.12 | 0.78 | — | 1.12 | 0.4 | — |
| HSTL-15 Class I, II | 1.425 | 1.5 | 1.575 | 0.2 | — | 0.68 | — | 0.9 | 0.68 | — | 0.9 | 0.4 | — |

⁽¹²⁷⁾ The maximum value for $V_{SWING(DC)}$ is not defined. However, each single-ended signal needs to be within the respective single-ended limits ($V_{IH(DC)}$ and $V_{IL(DC)}$).

| Symbol/Description | Conditions | Transceiver Speed Grade 2 | | | Transceiver Speed Grade 3 | | | Unit |
|------------------------------------------------------------|--------------------------|---------------------------|----------|------|---------------------------|----------|------|----------|
| | | Min | Typ | Max | Min | Typ | Max | |
| Transmitter REFCLK Phase Noise (622 MHz) ⁽¹⁴¹⁾ | 100 Hz | — | — | -70 | — | — | -70 | dBc/Hz |
| | 1 kHz | — | — | -90 | — | — | -90 | dBc/Hz |
| | 10 kHz | — | — | -100 | — | — | -100 | dBc/Hz |
| | 100 kHz | — | — | -110 | — | — | -110 | dBc/Hz |
| | ≥1 MHz | — | — | -120 | — | — | -120 | dBc/Hz |
| Transmitter REFCLK Phase Jitter (100 MHz) ⁽¹⁴²⁾ | 10 kHz to 1.5 MHz (PCIe) | — | — | 3 | — | — | 3 | ps (rms) |
| R _{REF} | — | — | 1800 ±1% | — | — | 1800 ±1% | — | Ω |

Related Information**[Arria V Device Overview](#)**

For more information about device ordering codes.

Transceiver Clocks**Table 2-23: Transceiver Clocks Specifications for Arria V GZ Devices**

Speed grades shown refer to the PMA Speed Grade in the device ordering code. The maximum data rate could be restricted by the Core/PCS speed grade. Contact your Altera Sales Representative for the maximum data rate specifications in each speed grade combination offered. For more information about device ordering codes, refer to the *Arria V Device Overview*.

⁽¹⁴¹⁾ To calculate the REFCLK phase noise requirement at frequencies other than 622 MHz, use the following formula: REFCLK phase noise at f(MHz) = REFCLK phase noise at 622 MHz + 20*log(f/622).

⁽¹⁴²⁾ To calculate the REFCLK rms phase jitter requirement for PCIe at reference clock frequencies other than 100 MHz, use the following formula: REFCLK rms phase jitter at f(MHz) = REFCLK rms phase jitter at 100 MHz × 100/f.

| Symbol/Description | Conditions | Transceiver Speed Grade 2 | | | Transceiver Speed Grade 3 | | | Unit |
|----------------------------------------|---------------------------------------------------------|---------------------------|-----|-----|---------------------------|-----|-----|---------------|
| | | Min | Typ | Max | Min | Typ | Max | |
| V_{ICM} (AC and DC coupled) | $V_{CCR_GXB} = 0.85\text{ V}$ full bandwidth | — | 600 | — | — | 600 | — | mV |
| | $V_{CCR_GXB} = 0.85\text{ V}$ half bandwidth | — | 600 | — | — | 600 | — | mV |
| | $V_{CCR_GXB} = 1.0\text{ V}$ full bandwidth | — | 700 | — | — | 700 | — | mV |
| | $V_{CCR_GXB} = 1.0\text{ V}$ half bandwidth | — | 700 | — | — | 700 | — | mV |
| $t_{LTR}^{(149)}$ | — | — | — | 10 | — | — | 10 | μs |
| $t_{LTD}^{(150)}$ | — | 4 | — | — | 4 | — | — | μs |
| $t_{LTD_manual}^{(151)}$ | — | 4 | — | — | 4 | — | — | μs |
| $t_{LTR_LTD_manual}^{(152)}$ | — | 15 | — | — | 15 | — | — | μs |
| Programmable equalization (AC Gain) | Full bandwidth (6.25 GHz) Half bandwidth (3.125 GHz) | — | — | 16 | — | — | 16 | dB |

⁽¹⁴⁹⁾ t_{LTR} is the time required for the receive CDR to lock to the input reference clock frequency after coming out of reset.

⁽¹⁵⁰⁾ t_{LTD} is time required for the receiver CDR to start recovering valid data after the `rx_is_lockedto data` signal goes high.

⁽¹⁵¹⁾ t_{LTD_manual} is the time required for the receiver CDR to start recovering valid data after the `rx_is_lockedto data` signal goes high when the CDR is functioning in the manual mode.

⁽¹⁵²⁾ $t_{LTR_LTD_manual}$ is the time the receiver CDR must be kept in lock to reference (LTR) mode after the `rx_is_lockedto ref` signal goes high when the CDR is functioning in the manual mode.

| Symbol | Parameter | Min | Typ | Max | Unit |
|------------------------------------------------|--------------------------------------------------------------------------------------------------------------|-----|-----|------|-----------|
| $t_{\text{OUTPJ_IO}}^{(173), (175)}$ | Period Jitter for a clock output on a regular I/O in integer PLL ($f_{\text{OUT}} \geq 100$ MHz) | — | — | 600 | ps (p-p) |
| | Period Jitter for a clock output on a regular I/O in integer PLL ($f_{\text{OUT}} < 100$ MHz) | — | — | 60 | mUI (p-p) |
| $t_{\text{FOUTPJ_IO}}^{(173), (175), (176)}$ | Period Jitter for a clock output on a regular I/O in fractional PLL ($f_{\text{OUT}} \geq 100$ MHz) | — | — | 600 | ps (p-p) |
| | Period Jitter for a clock output on a regular I/O in fractional PLL ($f_{\text{OUT}} < 100$ MHz) | — | — | 60 | mUI (p-p) |
| $t_{\text{OUTCCJ_IO}}^{(173), (175)}$ | Cycle-to-cycle Jitter for a clock output on a regular I/O in integer PLL ($f_{\text{OUT}} \geq 100$ MHz) | — | — | 600 | ps (p-p) |
| | Cycle-to-cycle Jitter for a clock output on a regular I/O in integer PLL ($f_{\text{OUT}} < 100$ MHz) | — | — | 60 | mUI (p-p) |
| $t_{\text{FOUTCCJ_IO}}^{(173), (175), (176)}$ | Cycle-to-cycle Jitter for a clock output on a regular I/O in fractional PLL ($f_{\text{OUT}} \geq 100$ MHz) | — | — | 600 | ps (p-p) |
| | Cycle-to-cycle Jitter for a clock output on a regular I/O in fractional PLL ($f_{\text{OUT}} < 100$ MHz) | — | — | 60 | mUI (p-p) |
| $t_{\text{CASC_OUTPJ_DC}}^{(173), (177)}$ | Period Jitter for a dedicated clock output in cascaded PLLs ($f_{\text{OUT}} \geq 100$ MHz) | — | — | 175 | ps (p-p) |
| | Period Jitter for a dedicated clock output in cascaded PLLs ($f_{\text{OUT}} < 100$ MHz) | — | — | 17.5 | mUI (p-p) |
| dK_{BIT} | Bit number of Delta Sigma Modulator (DSM) | 8 | 24 | 32 | Bits |

⁽¹⁷⁵⁾ The external memory interface clock output jitter specifications use a different measurement method, which is available in the "Memory Output Clock Jitter Specification for Arria V GZ Devices" table.

⁽¹⁷⁶⁾ This specification only covered fractional PLL for low bandwidth. The f_{VCO} for fractional value range 0.05–0.95 must be ≥ 1000 MHz.

⁽¹⁷⁷⁾ The cascaded PLL specification is only applicable with the following condition:

- Upstream PLL: $0.59\text{MHz} \leq \text{Upstream PLL BW} < 1$ MHz
- Downstream PLL: $\text{Downstream PLL BW} > 2$ MHz

| Symbol | Parameter | Min | Typ | Max | Unit |
|--------------------|----------------------------------------------------------------------|--------|---------|------------|------|
| k_{VALUE} | Numerator of Fraction | 128 | 8388608 | 2147483648 | — |
| f_{RES} | Resolution of VCO frequency ($f_{\text{INPFD}} = 100 \text{ MHz}$) | 390625 | 5.96 | 0.023 | Hz |

Related Information

- [Duty Cycle Distortion \(DCD\) Specifications](#) on page 2-56
- [DLL Range Specifications](#) on page 2-53

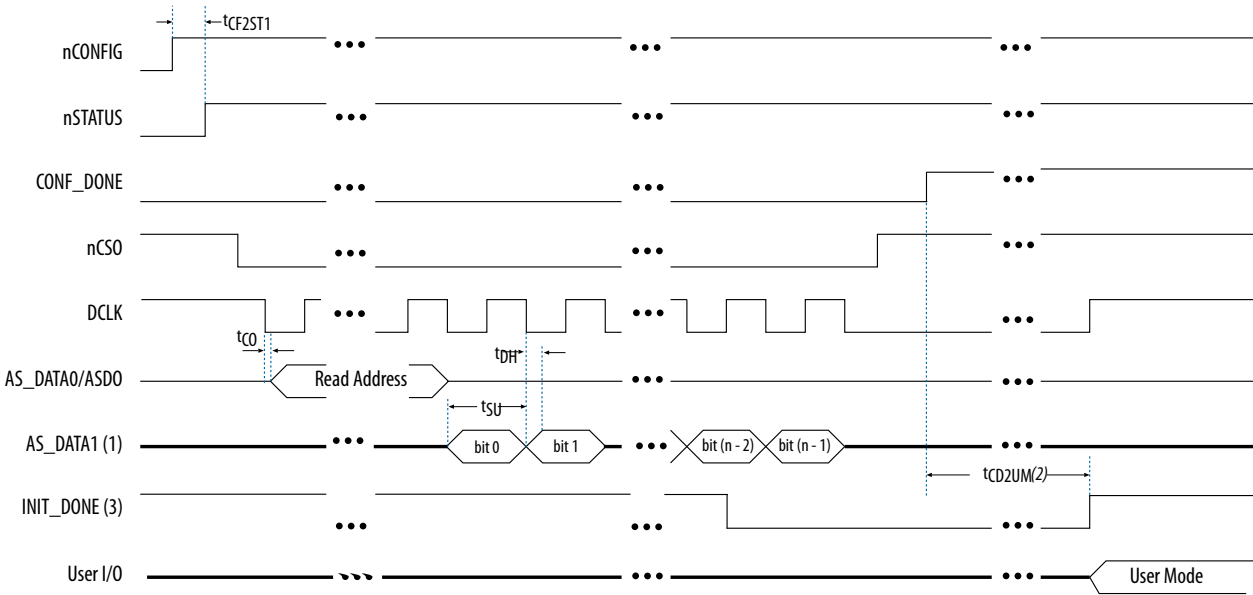
DSP Block Specifications**Table 2-35: DSP Block Performance Specifications for Arria V GZ Devices**

| Mode | Performance | | | Unit |
|----------------------------------------------------------------|-------------|-----|-----|------|
| | C3, I3L | C4 | I4 | |
| Modes using One DSP Block | | | | |
| Three 9×9 | 480 | 420 | | MHz |
| One 18×18 | 480 | 420 | 400 | MHz |
| Two partial 18×18 (or 16×16) | 480 | 420 | 400 | MHz |
| One 27×27 | 400 | 350 | | MHz |
| One 36×18 | 400 | 350 | | MHz |
| One sum of two 18×18 (One sum of two 16×16) | 400 | 350 | | MHz |
| One sum of square | 400 | 350 | | MHz |
| One 18×18 plus $36(a \times b) + c$ | 400 | 350 | | MHz |
| Modes using Two DSP Blocks | | | | |
| Three 18×18 | 400 | 350 | | MHz |
| One sum of four 18×18 | 380 | 300 | | MHz |

Active Serial Configuration Timing

Figure 2-9: AS Configuration Timing

Timing waveform for the active serial (AS) x1 mode and AS x4 mode configuration timing.



- Notes:
1. If you are using AS x4 mode, this signal represents the AS_DATA[3:0] and ERQ sends in 4-bits of data for each DCLK cycle.
 2. The initialization clock can be from internal oscillator or CLKUSR pin.
 3. After the option bit to enable the INIT_DONE pin is configured into the device, the INIT_DONE goes low.

Table 2-58: AS Timing Parameters for AS x1 and AS x4 Configurations in Arria V GZ Devices

The minimum and maximum numbers apply only if you choose the internal oscillator as the clock source for initializing the device.

t_{CF2CD} , t_{CF2ST0} , t_{CFG} , t_{STATUS} , and t_{CF2ST1} timing parameters are identical to the timing parameters for PS mode listed in the "PS Timing Parameters for Arria V GZ Devices" table.

Table 2-60: PS Timing Parameters for Arria V GZ Devices

| Symbol | Parameter | Minimum | Maximum | Unit |
|------------------------------|---------------------------------------------------|-------------------------------------------------------------------|------------------------|---------|
| t_{CF2CD} | nCONFIG low to CONF_DONE low | — | 600 | ns |
| t_{CF2ST0} | nCONFIG low to nSTATUS low | — | 600 | ns |
| t_{CFG} | nCONFIG low pulse width | 2 | — | μ s |
| t_{STATUS} | nSTATUS low pulse width | 268 | 1,506 ⁽²¹⁷⁾ | μ s |
| t_{CF2ST1} | nCONFIG high to nSTATUS high | — | 1,506 ⁽²¹⁸⁾ | μ s |
| t_{CF2CK} (219) | nCONFIG high to first rising edge on DCLK | 1,506 | — | μ s |
| t_{ST2CK} ⁽²¹⁹⁾ | nSTATUS high to first rising edge of DCLK | 2 | — | μ s |
| t_{DSU} | DATA[] setup time before rising edge on DCLK | 5.5 | — | ns |
| t_{DH} | DATA[] hold time after rising edge on DCLK | 0 | — | ns |
| t_{CH} | DCLK high time | $0.45 \times 1/f_{MAX}$ | — | s |
| t_{CL} | DCLK low time | $0.45 \times 1/f_{MAX}$ | — | s |
| t_{CLK} | DCLK period | $1/f_{MAX}$ | — | s |
| f_{MAX} | DCLK frequency | — | 125 | MHz |
| t_{CD2UM} | CONF_DONE high to user mode ⁽²²⁰⁾ | 175 | 437 | μ s |
| t_{CD2CU} | CONF_DONE high to CLKUSR enabled | $4 \times$ maximum DCLK period | — | — |
| t_{CD2UMC} | CONF_DONE high to user mode with CLKUSR option on | $t_{CD2CU} + (8576 \times \text{CLKUSR period})$ ⁽²²¹⁾ | — | — |

⁽²¹⁷⁾ This value is applicable if you do not delay configuration by extending the nCONFIG or nSTATUS low pulse width.

⁽²¹⁸⁾ This value is applicable if you do not delay configuration by externally holding the nSTATUS low.

⁽²¹⁹⁾ If nSTATUS is monitored, follow the t_{ST2CK} specification. If nSTATUS is not monitored, follow the t_{CF2CK} specification.

⁽²²⁰⁾ The minimum and maximum numbers apply only if you choose the internal oscillator as the clock source for initializing the device.

Programmable IOE Delay

Table 2-66: IOE Programmable Delay for Arria V GZ Devices

| Parameter ⁽²²⁸⁾ | Available Settings | Min Offset ⁽²²⁹⁾ | Fast Model | | Slow Model | | | | Unit |
|----------------------------|--------------------|-----------------------------|------------|------------|------------|-------|-------|-------|------|
| | | | Industrial | Commercial | C3 | C4 | I3L | I4 | |
| D1 | 64 | 0 | 0.464 | 0.493 | 0.924 | 1.011 | 0.921 | 1.006 | ns |
| D2 | 32 | 0 | 0.230 | 0.244 | 0.459 | 0.503 | 0.456 | 0.500 | ns |
| D3 | 8 | 0 | 1.587 | 1.699 | 2.992 | 3.192 | 3.047 | 3.257 | ns |
| D4 | 64 | 0 | 0.464 | 0.492 | 0.924 | 1.011 | 0.920 | 1.006 | ns |
| D5 | 64 | 0 | 0.464 | 0.493 | 0.924 | 1.011 | 0.921 | 1.006 | ns |
| D6 | 32 | 0 | 0.229 | 0.244 | 0.458 | 0.503 | 0.456 | 0.499 | ns |

Programmable Output Buffer Delay

Table 2-67: Programmable Output Buffer Delay for Arria V GZ Devices

You can set the programmable output buffer delay in the Quartus II software by setting the **Output Buffer Delay Control** assignment to either positive, negative, or both edges, with the specific values stated here (in ps) for the **Output Buffer Delay** assignment.

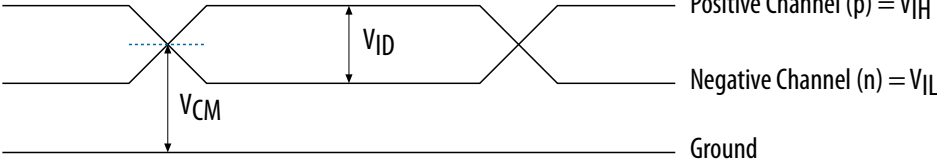

| Symbol | Parameter | Typical | Unit |
|---------------------|----------------------------------|-------------|------|
| D _{OUTBUF} | Rising and/or falling edge delay | 0 (default) | ps |
| | | 50 | ps |
| | | 100 | ps |
| | | 150 | ps |

⁽²²⁸⁾ You can set this value in the Quartus II software by selecting **D1**, **D2**, **D3**, **D4**, **D5**, and **D6** in the **Assignment Name** column of **Assignment Editor**.

⁽²²⁹⁾ Minimum offset does not include the intrinsic delay.

Glossary

Table 2-68: Glossary

| Term | Definition |
|----------------------------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Differential I/O Standards | <div>Receiver Input Waveforms</div> <div><div>Single-Ended Waveform</div><p>Positive Channel (p) = V_{IH}</p><p>Negative Channel (n) = V_{IL}</p><p>Ground</p></div> <div><div>Differential Waveform</div><p>$p - n = 0V$</p></div> <div>Transmitter Output Waveforms</div> |