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Understanding [Embedded - FPGAs \(Field Programmable Gate Array\)](#)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details

Product Status	Obsolete
Number of LABs/CLBs	7362
Number of Logic Elements/Cells	156000
Total RAM Bits	11746304
Number of I/O	336
Number of Gates	-
Voltage - Supply	1.07V ~ 1.13V
Mounting Type	Surface Mount
Operating Temperature	-40°C ~ 100°C (TJ)
Package / Case	672-BBGA, FCBGA
Supplier Device Package	672-FBGA (27x27)
Purchase URL	https://www.e-xfl.com/product-detail/intel/5agxma3d4f27i5n

I/O Standard	$V_{IL(DC)} (V)$		$V_{IH(DC)} (V)$		$V_{IL(AC)} (V)$	$V_{IH(AC)} (V)$	$V_{OL} (V)$	$V_{OH} (V)$	$I_{OL}^{(14)} (mA)$	$I_{OH}^{(14)} (mA)$
	Min	Max	Min	Max	Max	Min	Max	Min		
HSTL-15 Class II	—	$V_{REF} - 0.1$	$V_{REF} + 0.1$	—	$V_{REF} - 0.2$	$V_{REF} + 0.2$	0.4	$V_{CCIO} - 0.4$	16	-16
HSTL-12 Class I	-0.15	$V_{REF} - 0.08$	$V_{REF} + 0.08$	$V_{CCIO} + 0.15$	$V_{REF} - 0.15$	$V_{REF} + 0.15$	$0.25 \times V_{CCIO}$	$0.75 \times V_{CCIO}$	8	-8
HSTL-12 Class II	-0.15	$V_{REF} - 0.08$	$V_{REF} + 0.08$	$V_{CCIO} + 0.15$	$V_{REF} - 0.15$	$V_{REF} + 0.15$	$0.25 \times V_{CCIO}$	$0.75 \times V_{CCIO}$	16	-16
HSUL-12	—	$V_{REF} - 0.13$	$V_{REF} + 0.13$	—	$V_{REF} - 0.22$	$V_{REF} + 0.22$	$0.1 \times V_{CCIO}$	$0.9 \times V_{CCIO}$	—	—

Differential SSTL I/O Standards

Table 1-17: Differential SSTL I/O Standards for Arria V Devices

I/O Standard	$V_{CCIO} (V)$			$V_{SWING(DC)} (V)$		$V_{X(AC)} (V)$			$V_{SWING(AC)} (V)$	
	Min	Typ	Max	Min	Max	Min	Typ	Max	Min	Max
SSTL-2 Class I, II	2.375	2.5	2.625	0.3	$V_{CCIO} + 0.6$	$V_{CCIO}/2 - 0.2$	—	$V_{CCIO}/2 + 0.2$	0.62	$V_{CCIO} + 0.6$
SSTL-18 Class I, II	1.71	1.8	1.89	0.25	$V_{CCIO} + 0.6$	$V_{CCIO}/2 - 0.175$	—	$V_{CCIO}/2 + 0.175$	0.5	$V_{CCIO} + 0.6$
SSTL-15 Class I, II	1.425	1.5	1.575	0.2	⁽¹⁵⁾	$V_{CCIO}/2 - 0.15$	—	$V_{CCIO}/2 + 0.15$	$2(V_{IH(AC)} - V_{REF})$	$2(V_{IL(AC)} - V_{REF})$
SSTL-135	1.283	1.35	1.45	0.18	⁽¹⁵⁾	$V_{CCIO}/2 - 0.15$	$V_{CCIO}/2$	$V_{CCIO}/2 + 0.15$	$2(V_{IH(AC)} - V_{REF})$	$2(V_{IL(AC)} - V_{REF})$

⁽¹⁴⁾ To meet the I_{OL} and I_{OH} specifications, you must set the current strength settings accordingly. For example, to meet the SSTL15CI specification (8 mA), you should set the current strength settings to 8 mA. Setting at lower current strength may not meet the I_{OL} and I_{OH} specifications in the datasheet.

⁽¹⁵⁾ The maximum value for $V_{SWING(DC)}$ is not defined. However, each single-ended signal needs to be within the respective single-ended limits ($V_{IH(DC)}$ and $V_{IL(DC)}$).

Symbol		Condition	-I3, -C4			-I5, -C5			-C6			Unit
			Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
	TCCS	True Differential I/O Standards	—	—	150	—	—	150	—	—	150	ps
		Emulated Differential I/O Standards	—	—	300	—	—	300	—	—	300	ps
Receiver	True Differential I/O Standards - f_{HSDRDPA} (data rate)	SERDES factor J = 3 to 10 ⁽⁷⁶⁾	150	—	1250	150	—	1250	150	—	1050	Mbps
		SERDES factor J ≥ 8 with DPA ⁽⁷⁶⁾⁽⁷⁸⁾	150	—	1600	150	—	1500	150	—	1250	Mbps
	f_{HSDR} (data rate)	SERDES factor J = 3 to 10	⁽⁷⁷⁾	—	⁽⁸³⁾	⁽⁷⁷⁾	—	⁽⁸³⁾	⁽⁷⁷⁾	—	⁽⁸³⁾	Mbps
		SERDES factor J = 1 to 2, uses DDR registers	⁽⁷⁷⁾	—	⁽⁷⁹⁾	⁽⁷⁷⁾	—	⁽⁷⁹⁾	⁽⁷⁷⁾	—	⁽⁷⁹⁾	Mbps
DPA Mode	DPA run length	—	—	—	10000	—	—	10000	—	—	10000	UI
Soft-CDR Mode	Soft-CDR ppm tolerance	—	—	—	300	—	—	300	—	—	300	±ppm
Non-DPA Mode	Sampling Window	—	—	—	300	—	—	300	—	—	300	ps

⁽⁸³⁾ You can estimate the achievable maximum data rate for non-DPA mode by performing link timing closure analysis. You must consider the board skew margin, transmitter delay margin, and receiver sampling margin to determine the maximum data rate supported.

After the Boot ROM code exits and control is passed to the preloader, software can adjust the value of `drvsel` and `smp1sel` via the system manager. `drvsel` can be set from 1 to 7 and `smp1sel` can be set from 0 to 7. While the preloader is executing, the values for `SDMMC_CLK` and `SDMMC_CLK_OUT` increase to a maximum of 200 MHz and 50 MHz respectively.

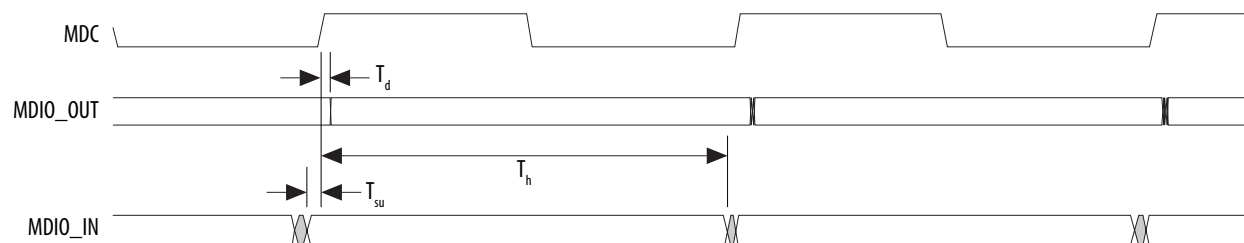
The SD/MMC interface calibration support will be available in a future release of the preloader through the SoC EDS software update.

Symbol	Description	Min	Max	Unit
$T_{\text{sdmmc_clk}}$ (internal reference clock)	SDMMC_CLK clock period (Identification mode)	20	—	ns
	SDMMC_CLK clock period (Default speed mode)	5	—	ns
	SDMMC_CLK clock period (High speed mode)	5	—	ns
$T_{\text{sdmmc_clk_out}}$ (interface output clock)	SDMMC_CLK_OUT clock period (Identification mode)	2500	—	ns
	SDMMC_CLK_OUT clock period (Default speed mode)	40	—	ns
	SDMMC_CLK_OUT clock period (High speed mode)	20	—	ns
$T_{\text{duty cycle}}$	SDMMC_CLK_OUT duty cycle	45	55	%
T_d	SDMMC_CMD/SDMMC_D output delay	$(T_{\text{sdmmc_clk}} \times \text{drvsel})/2 - 1.23^{(87)}$	$(T_{\text{sdmmc_clk}} \times \text{drvsel})/2 + 1.69^{(87)}$	ns
T_{su}	Input setup time	$1.05 - (T_{\text{sdmmc_clk}} \times \text{smp1sel})/2^{(88)}$	—	ns
T_h	Input hold time	$(T_{\text{sdmmc_clk}} \times \text{smp1sel})/2^{(88)}$	—	ns

⁽⁸⁷⁾ `drvsel` is the drive clock phase shift select value.

⁽⁸⁸⁾ `smp1sel` is the sample clock phase shift select value.

Figure 1-15: MDIO Timing Diagram



I²C Timing Characteristics

Table 1-59: I²C Timing Requirements for Arria V Devices

Symbol	Description	Standard Mode		Fast Mode		Unit
		Min	Max	Min	Max	
T_{clk}	Serial clock (SCL) clock period	10	—	2.5	—	μs
$T_{clkhigh}$	SCL high time	4.7	—	0.6	—	μs
T_{clklow}	SCL low time	4	—	1.3	—	μs
T_s	Setup time for serial data line (SDA) data to SCL	0.25	—	0.1	—	μs
T_h	Hold time for SCL to SDA data	0	3.45	0	0.9	μs
T_d	SCL to SDA output data delay	—	0.2	—	0.2	μs
T_{su_start}	Setup time for a repeated start condition	4.7	—	0.6	—	μs
T_{hd_start}	Hold time for a repeated start condition	4	—	0.6	—	μs
T_{su_stop}	Setup time for a stop condition	4	—	0.6	—	μs

Variant	Member Code	Configuration .rbf Size (bits)	IOCSR .rbf Size (bits)
Arria V GX	A1	71,015,712	439,960
	A3	71,015,712	439,960
	A5	101,740,800	446,360
	A7	101,740,800	446,360
	B1	137,785,088	457,368
	B3	137,785,088	457,368
	B5	185,915,808	463,128
	B7	185,915,808	463,128
Arria V GT	C3	71,015,712	439,960
	C7	101,740,800	446,360
	D3	137,785,088	457,368
	D7	185,915,808	463,128
Arria V SX	B3	185,903,680	450,968
	B5	185,903,680	450,968
Arria V ST	D3	185,903,680	450,968
	D5	185,903,680	450,968

Minimum Configuration Time Estimation

Table 1-73: Minimum Configuration Time Estimation for Arria V Devices

The estimated values are based on the configuration .rbf sizes in Uncompressed .rbf Sizes for Arria V Devices table.

Related Information

- [PowerPlay Early Power Estimator User Guide](#)
For more information about the EPE tool.
- [PowerPlay Power Analysis](#)
For more information about PowerPlay power analysis.

Power Consumption

Altera offers two ways to estimate power consumption for a design—the Excel-based Early Power Estimator and the Quartus II PowerPlay Power Analyzer feature.

Note: You typically use the interactive Excel-based Early Power Estimator before designing the FPGA to get a magnitude estimate of the device power. The Quartus II PowerPlay Power Analyzer provides better quality estimates based on the specifics of the design after you complete place-and-route. The PowerPlay Power Analyzer can apply a combination of user-entered, simulation-derived, and estimated signal activities that, when combined with detailed circuit models, yields very accurate power estimates.

Related Information

- [PowerPlay Early Power Estimator User Guide](#)
For more information about the EPE tool.
- [PowerPlay Power Analysis](#)
For more information about PowerPlay power analysis.

I/O Pin Leakage Current**Table 2-8: I/O Pin Leakage Current for Arria V GZ Devices**

If $V_O = V_{CCIO}$ to $V_{CCIO_{MAX}}$, 100 μA of leakage current per I/O is expected.

Symbol	Description	Conditions	Min	Typ	Max	Unit
I_I	Input pin	$V_I = 0\text{ V to }V_{CCIO_{MAX}}$	-30	—	30	μA
I_{OZ}	Tri-stated I/O pin	$V_O = 0\text{ V to }V_{CCIO_{MAX}}$	-30	—	30	μA

Table 2-19: Differential SSTL I/O Standards for Arria V GZ Devices

I/O Standard	V_{CCIO} (V)			$V_{SWING(DC)}$ (V)		$V_{X(AC)}$ (V)			$V_{SWING(AC)}$ (V)	
	Min	Typ	Max	Min	Max	Min	Typ	Max	Min	Max
SSTL-2 Class I, II	2.375	2.5	2.625	0.3	$V_{CCIO} + 0.6$	$V_{CCIO}/2 - 0.2$	—	$V_{CCIO}/2 + 0.2$	0.62	$V_{CCIO} + 0.6$
SSTL-18 Class I, II	1.71	1.8	1.89	0.25	$V_{CCIO} + 0.6$	$V_{CCIO}/2 - 0.175$	—	$V_{CCIO}/2 + 0.175$	0.5	$V_{CCIO} + 0.6$
SSTL-15 Class I, II	1.425	1.5	1.575	0.2	⁽¹²⁷⁾	$V_{CCIO}/2 - 0.15$	—	$V_{CCIO}/2 + 0.15$	0.35	—
SSTL-135 Class I, II	1.283	1.35	1.45	0.2	⁽¹²⁷⁾	$V_{CCIO}/2 - 0.15$	$V_{CCIO}/2$	$V_{CCIO}/2 + 0.15$	$2(V_{IH(AC)} - V_{REF})$	$2(V_{IL(AC)} - V_{REF})$
SSTL-125 Class I, II	1.19	1.25	1.31	0.18	⁽¹²⁷⁾	$V_{CCIO}/2 - 0.15$	$V_{CCIO}/2$	$V_{CCIO}/2 + 0.15$	$2(V_{IH(AC)} - V_{REF})$	—
SSTL-12 Class I, II	1.14	1.2	1.26	0.18	—	$V_{REF} - 0.15$	$V_{CCIO}/2$	$V_{REF} + 0.15$	-0.30	0.30

Table 2-20: Differential HSTL and HSUL I/O Standards for Arria V GZ Devices

I/O Standard	V_{CCIO} (V)			$V_{DIF(DC)}$ (V)		$V_{X(AC)}$ (V)			$V_{CM(DC)}$ (V)			$V_{DIF(AC)}$ (V)	
	Min	Typ	Max	Min	Max	Min	Typ	Max	Min	Typ	Max	Min	Max
HSTL-18 Class I, II	1.71	1.8	1.89	0.2	—	0.78	—	1.12	0.78	—	1.12	0.4	—
HSTL-15 Class I, II	1.425	1.5	1.575	0.2	—	0.68	—	0.9	0.68	—	0.9	0.4	—

⁽¹²⁷⁾ The maximum value for $V_{SWING(DC)}$ is not defined. However, each single-ended signal needs to be within the respective single-ended limits ($V_{IH(DC)}$ and $V_{IL(DC)}$).

Switching Characteristics

Transceiver Performance Specifications

Reference Clock

Table 2-22: Reference Clock Specifications for Arria V GZ Devices

Speed grades shown refer to the PMA Speed Grade in the device ordering code. The maximum data rate could be restricted by the Core/PCS speed grade. Contact your Altera Sales Representative for the maximum data rate specifications in each speed grade combination offered. For more information about device ordering codes, refer to the *Arria V Device Overview*.

Symbol/Description	Conditions	Transceiver Speed Grade 2			Transceiver Speed Grade 3			Unit
		Min	Typ	Max	Min	Typ	Max	
Reference Clock								
Supported I/O Standards	Dedicated reference clock pin	1.2-V PCML, 1.4-V PCML, 1.5-V PCML, 2.5-V PCML, Differential LVPECL, LVDS, and HCSL						
	RX reference clock pin	1.4-V PCML, 1.5-V PCML, 2.5-V PCML, LVPECL, and LVDS						
Input Reference Clock Frequency (CMU PLL) ⁽¹³⁷⁾	—	40	—	710	40	—	710	MHz
Input Reference Clock Frequency (ATX PLL) ⁽¹³⁷⁾	—	100	—	710	100	—	710	MHz

⁽¹³⁷⁾ The input reference clock frequency options depend on the data rate and the device speed grade.

Symbol/Description	Conditions	Transceiver Speed Grade 2			Transceiver Speed Grade 3			Unit
		Min	Typ	Max	Min	Typ	Max	
fixedclk clock frequency	PCIe Receiver Detect	—	100 or 125	—	—	100 or 125	—	MHz
Reconfiguration clock (mgmt_clk_clk) frequency	—	100	—	125	100	—	125	MHz

Related Information[Arria V Device Overview](#)

For more information about device ordering codes.

Receiver**Table 2-24: Receiver Specifications for Arria V GZ Devices**

Speed grades shown refer to the PMA Speed Grade in the device ordering code. The maximum data rate could be restricted by the Core/PCS speed grade. Contact your Altera Sales Representative for the maximum data rate specifications in each speed grade combination offered. For more information about device ordering codes, refer to the *Arria V Device Overview*.

Symbol/Description	Conditions	Transceiver Speed Grade 2			Transceiver Speed Grade 3			Unit
		Min	Typ	Max	Min	Typ	Max	
Supported I/O Standards	1.4-V PCML, 1.5-V PCML, 2.5-V PCML, LVPECL, and LVDS							
Data rate (Standard PCS) ⁽¹⁴³⁾ , ⁽¹⁴⁴⁾	—	600	—	9900	600	—	8800	Mbps
Data rate (10G PCS) ⁽¹⁴³⁾ , ⁽¹⁴⁴⁾	—	600	—	12500	600	—	10312.5	Mbps
Absolute V _{MAX} for a receiver pin ⁽¹⁴⁵⁾	—	—	—	1.2	—	—	1.2	V
Absolute V _{MIN} for a receiver pin	—	−0.4	—	—	−0.4	—	—	V

⁽¹⁴³⁾ The line data rate may be limited by PCS-FPGA interface speed grade.

⁽¹⁴⁴⁾ To support data rates lower than the minimum specification through oversampling, use the CDR in LTR mode only.

⁽¹⁴⁵⁾ The device cannot tolerate prolonged operation at this absolute maximum.

Symbol/Description	Conditions	Transceiver Speed Grade 2			Transceiver Speed Grade 3			Unit
		Min	Typ	Max	Min	Typ	Max	
V_{ICM} (AC and DC coupled)	$V_{CCR_GXB} = 0.85\text{ V}$ full bandwidth	—	600	—	—	600	—	mV
	$V_{CCR_GXB} = 0.85\text{ V}$ half bandwidth	—	600	—	—	600	—	mV
	$V_{CCR_GXB} = 1.0\text{ V}$ full bandwidth	—	700	—	—	700	—	mV
	$V_{CCR_GXB} = 1.0\text{ V}$ half bandwidth	—	700	—	—	700	—	mV
$t_{LTR}^{(149)}$	—	—	—	10	—	—	10	μs
$t_{LTD}^{(150)}$	—	4	—	—	4	—	—	μs
$t_{LTD_manual}^{(151)}$	—	4	—	—	4	—	—	μs
$t_{LTR_LTD_manual}^{(152)}$	—	15	—	—	15	—	—	μs
Programmable equalization (AC Gain)	Full bandwidth (6.25 GHz) Half bandwidth (3.125 GHz)	—	—	16	—	—	16	dB

⁽¹⁴⁹⁾ t_{LTR} is the time required for the receive CDR to lock to the input reference clock frequency after coming out of reset.

⁽¹⁵⁰⁾ t_{LTD} is time required for the receiver CDR to start recovering valid data after the `rx_is_lockedto data` signal goes high.

⁽¹⁵¹⁾ t_{LTD_manual} is the time required for the receiver CDR to start recovering valid data after the `rx_is_lockedto data` signal goes high when the CDR is functioning in the manual mode.

⁽¹⁵²⁾ $t_{LTR_LTD_manual}$ is the time the receiver CDR must be kept in lock to reference (LTR) mode after the `rx_is_lockedto ref` signal goes high when the CDR is functioning in the manual mode.

Symbol/Description	Conditions	Transceiver Speed Grade 2			Transceiver Speed Grade 3			Unit
		Min	Typ	Max	Min	Typ	Max	
Differential on-chip termination resistors	85- Ω setting	—	85 \pm 20%	—	—	85 \pm 20%	—	Ω
	100- Ω setting	—	100 \pm 20%	—	—	100 \pm 20%	—	Ω
	120- Ω setting	—	120 \pm 20%	—	—	120 \pm 20%	—	Ω
	150- Ω setting	—	150 \pm 20%	—	—	150 \pm 20%	—	Ω
V _{OCM} (AC coupled)	0.65-V setting	—	650	—	—	650	—	mV
V _{OCM} (DC coupled)	—	—	650	—	—	650	—	mV
Intra-differential pair skew	Tx V _{CM} = 0.5 V and slew rate of 15 ps	—	—	15	—	—	15	ps
Intra-transceiver block transmitter channel-to-channel skew	x6 PMA bonded mode	—	—	120	—	—	120	ps
Inter-transceiver block transmitter channel-to-channel skew	xN PMA bonded mode	—	—	500	—	—	500	ps

Related Information**[Arria V Device Overview](#)**

For more information about device ordering codes.

Mode ⁽¹⁶⁴⁾	Transceiver Speed Grade	PMA Width	20	20	16	16	10	10	8	8
		PCS/Core Width	40	20	32	16	20	10	16	8
Register	2	C3, I3L core speed grade	9.9	9	7.92	7.2	4.9	4.5	3.92	3.6
	3	C4, I4 core speed grade	8.8	8.2	7.04	6.56	4.4	4.1	3.52	3.28

Related Information[Operating Conditions](#) on page 2-1**10G PCS Data Rate****Table 2-31: 10G PCS Approximate Maximum Data Rate (Gbps) for Arria V GZ Devices**

Mode ⁽¹⁶⁵⁾	Transceiver Speed Grade	PMA Width	64	40	40	40	32	32
		PCS Width	64	66/67	50	40	64/66/67	32
FIFO	2	C3, I3L core speed grade	12.5	12.5	10.69	12.5	10.88	10.88
	3	C4, I4 core speed grade	10.3125	10.3125	10.69	10.3125	9.92	9.92
Register	2	C3, I3L core speed grade	12.5	12.5	10.69	12.5	10.88	10.88
	3	C4, I4 core speed grade	10.3125	10.3125	10.69	10.3125	9.92	9.92

⁽¹⁶⁴⁾ The Phase Compensation FIFO can be configured in FIFO mode or register mode. In the FIFO mode, the pointers are not fixed, and the latency can vary. In the register mode the pointers are fixed for low latency.

⁽¹⁶⁵⁾ The Phase Compensation FIFO can be configured in FIFO mode or register mode. In the FIFO mode, the pointers are not fixed, and the latency can vary. In the register mode the pointers are fixed for low latency.

Memory	Mode	Resources Used		Performance				Unit
		ALUTs	Memory	C3	C4	I3L	I4	
M20K Block	Single-port, all supported widths	0	1	650	550	500	450	MHz
	Simple dual-port, all supported widths	0	1	650	550	500	450	MHz
	Simple dual-port with the read-during-write option set to Old Data , all supported widths	0	1	455	400	455	400	MHz
	Simple dual-port with ECC enabled, 512×32	0	1	400	350	400	350	MHz
	Simple dual-port with ECC and optional pipeline registers enabled, 512×32	0	1	500	450	500	450	MHz
	True dual port, all supported widths	0	1	650	550	500	450	MHz
	ROM, all supported widths	0	1	650	550	500	450	MHz

Temperature Sensing Diode Specifications

Table 2-37: Internal Temperature Sensing Diode Specification

Temperature Range	Accuracy	Offset Calibrated Option	Sampling Rate	Conversion Time	Resolution	Minimum Resolution with no Missing Codes
-40°C to 100°C	±8°C	No	1 MHz, 500 kHz	< 100 ms	8 bits	8 bits

Table 2-38: External Temperature Sensing Diode Specifications for Arria V GZ Devices

Description	Min	Typ	Max	Unit
I_{bias} , diode source current	8	—	200	μA
V_{bias} , voltage across diode	0.3	—	0.9	V
Series resistance	—	—	< 1	Ω

Symbol	Conditions	C3, I3L			C4, I4			Unit
		Min	Typ	Max	Min	Typ	Max	
$t_{x \text{ Jitter}}$ - True Differential I/O Standards	Total Jitter for Data Rate 600 Mbps - 1.25 Gbps	—	—	160	—	—	160	ps
	Total Jitter for Data Rate < 600 Mbps	—	—	0.1	—	—	0.1	UI
$t_{x \text{ Jitter}}$ - Emulated Differential I/O Standards with Three External Output Resistor Network	Total Jitter for Data Rate 600 Mbps - 1.25 Gbps	—	—	300	—	—	325	ps
	Total Jitter for Data Rate < 600 Mbps	—	—	0.2	—	—	0.25	UI
t_{DUTY}	Transmitter output clock duty cycle for both True and Emulated Differential I/O Standards	45	50	55	45	50	55	%
$t_{\text{RISE}} \& t_{\text{FALL}}$	True Differential I/O Standards	—	—	200	—	—	200	ps
	Emulated Differential I/O Standards with three external output resistor networks	—	—	250	—	—	300	ps
TCCS	True Differential I/O Standards	—	—	150	—	—	150	ps
	Emulated Differential I/O Standards	—	—	300	—	—	300	ps

Receiver High-Speed I/O Specifications

Table 2-41: Receiver High-Speed I/O Specifications for Arria V GZ Devices

When J = 3 to 10, use the serializer/deserializer (SERDES) block.

When J = 1 or 2, bypass the SERDES block.

Symbol	Conditions	C3, I3L			C4, I4			Unit
		Min	Typ	Max	Min	Typ	Max	
True Differential I/O Standards - f_{HSDRDPA} (data rate)	SERDES factor J = 3 to 10 (192), (193), (194), (195), (196), (197)	150	—	1250	150	—	1050	Mbps
	SERDES factor J ≥ 4 LVDS RX with DPA (193), (195), (196), (197)	150	—	1600	150	—	1250	Mbps
	SERDES factor J = 2, uses DDR Registers	(198)	—	(199)	(198)	—	(199)	Mbps
	SERDES factor J = 1, uses SDR Register	(198)	—	(199)	(198)	—	(199)	Mbps
f_{HSDR} (data rate)	SERDES factor J = 3 to 10	(198)	—	(200)	(198)	—	(200)	Mbps
	SERDES factor J = 2, uses DDR Registers	(198)	—	(199)	(198)	—	(199)	Mbps
	SERDES factor J = 1, uses SDR Register	(198)	—	(199)	(198)	—	(199)	Mbps

(192) The F_{MAX} specification is based on the fast clock used for serial data. The interface F_{MAX} is also dependent on the parallel clock domain which is design dependent and requires timing analysis.

(193) Arria V GZ RX LVDS will need DPA. For Arria V GZ TX LVDS, the receiver side component must have DPA.

(194) Arria V GZ LVDS serialization and de-serialization factor needs to be x4 and above.

(195) Requires package skew compensation with PCB trace length.

(196) Do not mix single-ended I/O buffer within LVDS I/O bank.

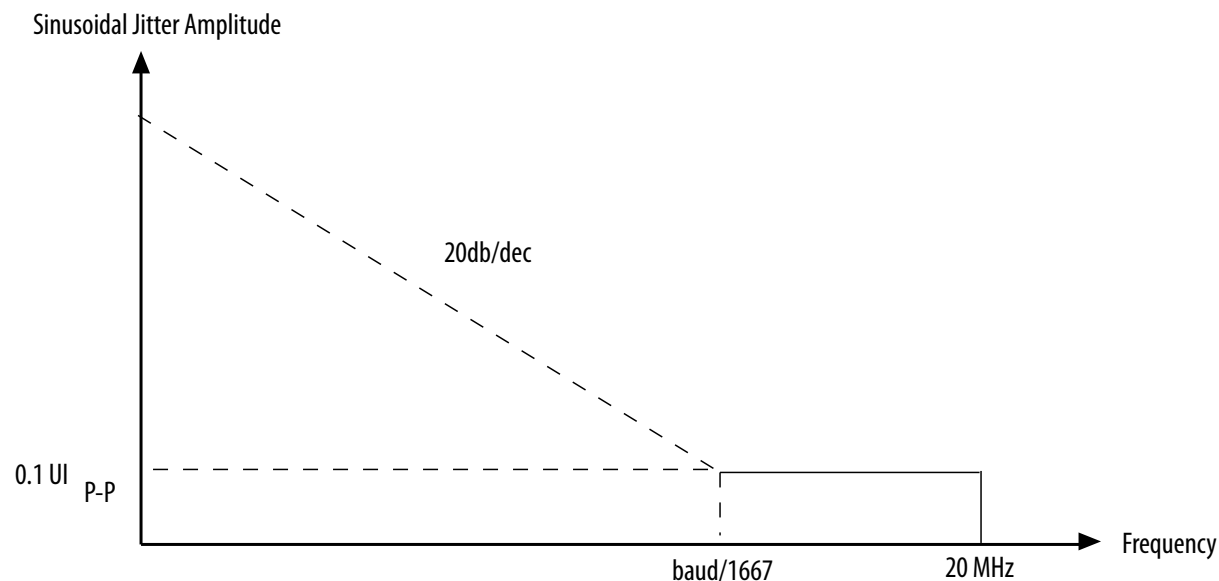
(197) Chip-to-chip communication only with a maximum load of 5 pF.

(198) The minimum specification depends on the clock source (for example, the PLL and clock pin) and the clock routing resource (global, regional, or local) that you use. The I/O differential buffer and input register do not have a minimum toggle rate.

(199) The maximum ideal data rate is the SERDES factor (J) x the PLL maximum output frequency (f_{OUT}) provided you can close the design timing and the signal integrity simulation is clean.

(200) You can estimate the achievable maximum data rate for non-DPA mode by performing link timing closure analysis. You must consider the board skew margin, transmitter delay margin, and receiver sampling margin to determine the maximum data rate supported.

Figure 2-5: LVDS Soft-CDR/DPA Sinusoidal Jitter Tolerance Specification for a Data Rate < 1.25 Gbps



Non DPA Mode High-Speed I/O Specifications

Table 2-46: High-Speed I/O Specifications for Arria V GZ Devices

When J = 3 to 10, use the serializer/deserializer (SERDES) block.

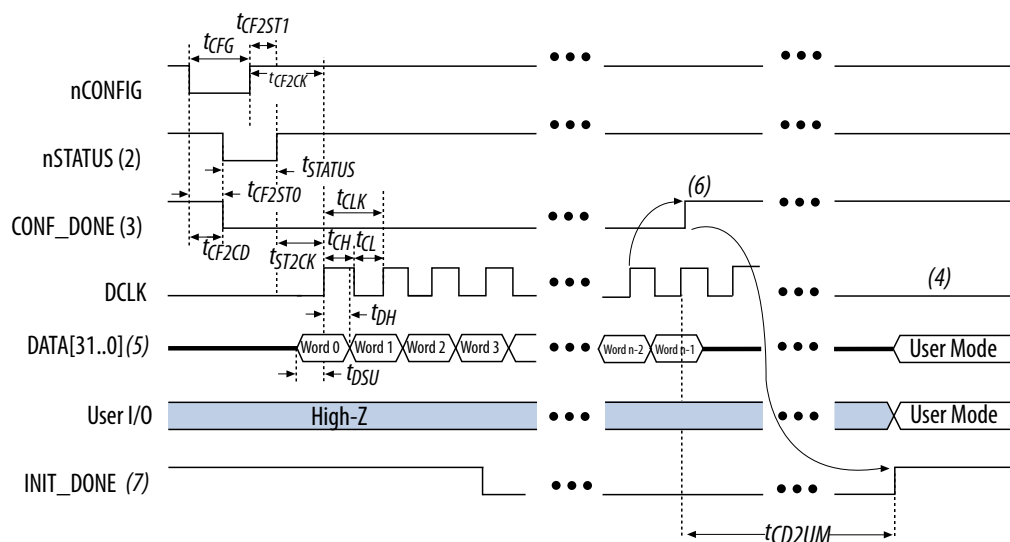
When J = 1 or 2, bypass the SERDES block.

Symbol	Conditions	C3, I3L			C4, I4			Unit
		Min	Typ	Max	Min	Typ	Max	
Sampling Window	—	—	—	300	—	—	300	ps

FPP Configuration Timing when DCLK to DATA[] = 1

Figure 2-7: FPP Configuration Timing Waveform When the DCLK-to-DATA[] Ratio is 1

Timing waveform for FPP configuration when using a MAX[®] II or MAX V device as an external host.



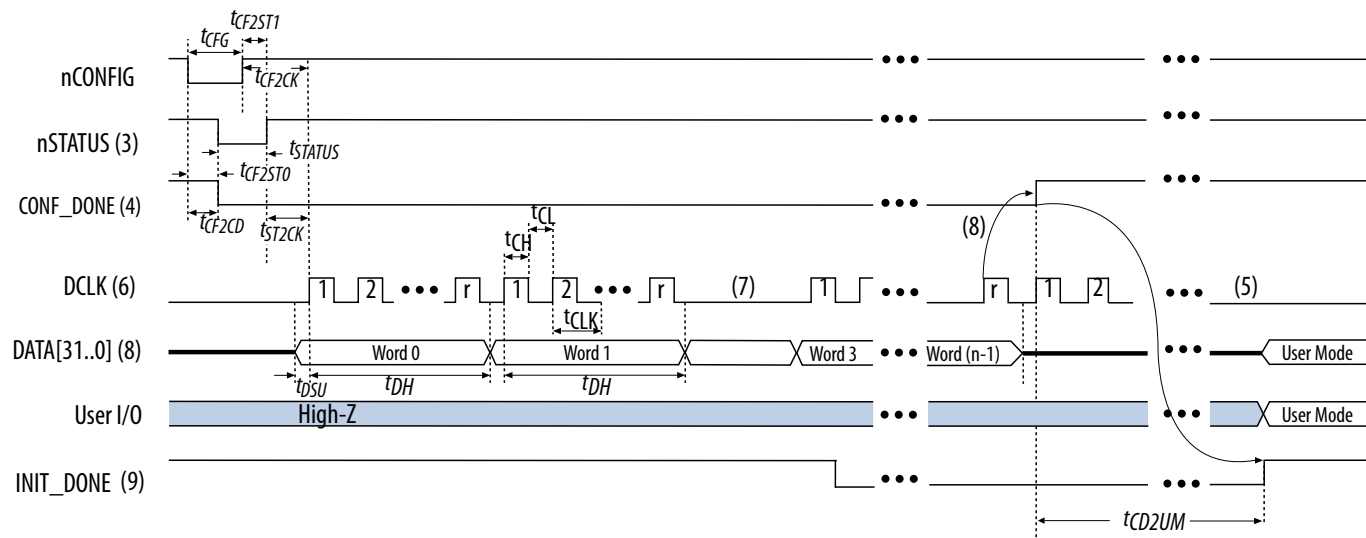
Notes:

1. The beginning of this waveform shows the device in user mode. In user mode, nCONFIG, nSTATUS, and CONF_DONE are at logic-high levels. When nCONFIG is pulled low, a reconfiguration cycle begins.
2. After power-up, the Arria V GZ device holds nSTATUS low for the time of the POR delay.
3. After power-up, before and during configuration, CONF_DONE is low.
4. Do not leave DCLK floating after configuration. DCLK is ignored after configuration is complete. It can toggle high or low if required.
5. For FPP $\times 16$, use DATA[15..0]. For FPP $\times 8$, use DATA[7..0]. DATA[31..0] are available as a user I/O pin after configuration. The state of this pin depends on the dual-purpose pin settings.
6. To ensure a successful configuration, send the entire configuration data to the Arria V GZ device. CONF_DONE is released high when the Arria V GZ device receives all the configuration data successfully. After CONF_DONE goes high, send two additional falling edges on DCLK to begin initialization and enter user mode.
7. After the option bit to enable the INIT_DONE pin is configured into the device, the INIT_DONE goes low.

FPP Configuration Timing when DCLK to DATA[] > 1

Figure 2-8: FPP Configuration Timing Waveform When the DCLK-to-DATA[] Ratio is >1 ,

Timing when using a MAX II device, MAX V device, or microprocessor as an external host.



Notes:

1. To find out the DCLK-to-DATA[] ratio for your system, refer to the "DCLK-to-DATA[] Ratio for Arria V GZ Devices" table.
2. The beginning of this waveform shows the device in user mode. In user mode, nCONFIG, nSTATUS, and CONF_DONE are at logic high levels. When nCONFIG is pulled low, a reconfiguration cycle begins.
3. After power-up, the Arria V GZ device holds nSTATUS low for the time as specified by the POR delay.
4. After power-up, before and during configuration, CONF_DONE is low.
5. Do not leave DCLK floating after configuration is complete. DCLK is ignored after configuration is complete. It can toggle high or low if required.
6. "r" denotes the DCLK-to-DATA[] ratio. For the DCLK-to-DATA[] ratio based on the decompression and the design security feature enable settings, refer to the "DCLK-to-DATA[] Ratio for Arria V GZ Devices" table.
7. If needed, pause DCLK by holding it low. When DCLK restarts, the external host must provide data on the DATA[31..0] pins prior to sending the first DCLK rising edge.
8. To ensure a successful configuration, send the entire configuration data to the Arria V GZ device. CONF_DONE is released high after the Arria V GZ device receives all the configuration data successfully. After CONF_DONE goes high, send two additional falling edges on DCLK to begin initialization and enter user mode.
9. After the option bit to enable the INIT_DONE pin is configured into the device, the INIT_DONE goes low.

Related Information

- [Configuration, Design Security, and Remote System Upgrades in Arria V Devices](#)
For more information about the reconfiguration input for the ALTREMOTE_UPDATE IP core, refer to the “User Watchdog Timer” section.
- [Configuration, Design Security, and Remote System Upgrades in Arria V Devices](#)
For more information about the `reset_timer` input for the ALTREMOTE_UPDATE IP core, refer to the “Remote System Upgrade State Machine” section.

User Watchdog Internal Oscillator Frequency Specification

Table 2-65: User Watchdog Internal Oscillator Frequency Specifications

Minimum	Typical	Maximum	Unit
5.3	7.9	12.5	MHz

I/O Timing

Altera offers two ways to determine I/O timing—the Excel-based I/O Timing and the Quartus II Timing Analyzer.

Excel-based I/O timing provides pin timing performance for each device density and speed grade. The data is typically used prior to designing the FPGA to get an estimate of the timing budget as part of the link timing analysis.

The Quartus II Timing Analyzer provides a more accurate and precise I/O timing data based on the specifics of the design after you complete place-and-route.

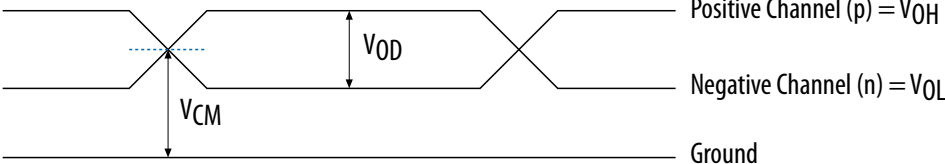

Related Information

[Arria V Devices Documentation page](#)

For the Excel-based I/O Timing spreadsheet

⁽²²⁶⁾ This is equivalent to strobing the reconfiguration input of the ALTREMOTE_UPDATE IP core high for the minimum timing specification. For more information, refer to the “Remote System Upgrade State Machine” section in the *Configuration, Design Security, and Remote System Upgrades in Arria V Devices* chapter.

⁽²²⁷⁾ This is equivalent to strobing the `reset_timer` input of the ALTREMOTE_UPDATE IP core high for the minimum timing specification. For more information, refer to the “User Watchdog Timer” section in the *Configuration, Design Security, and Remote System Upgrades in Arria V Devices* chapter.

Term	Definition
	<p>Single-Ended Waveform</p>  <p>Positive Channel (p) = V_{OH} Negative Channel (n) = V_{OL} Ground</p> <p>Differential Waveform</p>  <p>$p - n = 0V$</p>
f_{HCLK}	Left and right PLL input clock frequency.
f_{HSDR}	High-speed I/O block—Maximum and minimum LVDS data transfer rate ($f_{HSDR} = 1/T_{UI}$), non-DPA.
$f_{HSDR_{DPA}}$	High-speed I/O block—Maximum and minimum LVDS data transfer rate ($f_{HSDR_{DPA}} = 1/T_{UI}$), DPA.
J	High-speed I/O block—Deserialization factor (width of parallel data bus).