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Understanding [Embedded - FPGAs \(Field Programmable Gate Array\)](#)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

Details

Product Status	Obsolete
Number of LABs/CLBs	8962
Number of Logic Elements/Cells	190000
Total RAM Bits	13284352
Number of I/O	544
Number of Gates	-
Voltage - Supply	1.07V ~ 1.13V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	1152-BBGA, FCBGA Exposed Pad
Supplier Device Package	1152-FBGA (35x35)
Purchase URL	https://www.e-xfl.com/product-detail/intel/5agxma5g4f35c5n

Transceiver Power Supply Operating Conditions

Table 1-4: Transceiver Power Supply Operating Conditions for Arria V Devices

Symbol	Description	Minimum ⁽⁵⁾	Typical	Maximum ⁽⁵⁾	Unit
V _{CCA_GXBL}	Transceiver high voltage power (left side)	2.375	2.500	2.625	V
V _{CCA_GXBR}	Transceiver high voltage power (right side)				
V _{CCR_GXBL}	GX and SX speed grades—receiver power (left side)	1.08/1.12	1.1/1.15 ⁽⁶⁾	1.14/1.18	V
V _{CCR_GXBR}	GX and SX speed grades—receiver power (right side)				
V _{CCR_GXBL}	GT and ST speed grades—receiver power (left side)	1.17	1.20	1.23	V
V _{CCR_GXBR}	GT and ST speed grades—receiver power (right side)				
V _{CCT_GXBL}	GX and SX speed grades—transmitter power (left side)	1.08/1.12	1.1/1.15 ⁽⁶⁾	1.14/1.18	V
V _{CCT_GXBR}	GX and SX speed grades—transmitter power (right side)				
V _{CCT_GXBL}	GT and ST speed grades—transmitter power (left side)	1.17	1.20	1.23	V
V _{CCT_GXBR}	GT and ST speed grades—transmitter power (right side)				
V _{CCH_GXBL}	Transmitter output buffer power (left side)	1.425	1.500	1.575	V
V _{CCH_GXBR}	Transmitter output buffer power (right side)				

⁽⁵⁾ The power supply value describes the budget for the DC (static) power supply tolerance and does not include the dynamic tolerance requirements. Refer to the PDN tool for the additional budget for the dynamic tolerance requirements.

⁽⁶⁾ For data rate ≤ 3.2 Gbps, connect V_{CCR_GXBL/R}, V_{CCT_GXBL/R}, or V_{CCL_GXBL/R} to either 1.1-V or 1.15-V power supply. For data rate > 3.2 Gbps, connect V_{CCR_GXBL/R}, V_{CCT_GXBL/R}, or V_{CCL_GXBL/R} to a 1.15-V power supply. For details, refer to the Arria V GT, GX, ST, and SX Device Family Pin Connection Guidelines.

Symbol	Description	Maximum	Unit
$I_{XCVR-RX} (DC)$	DC current per transceiver receiver (RX) pin	50	mA

Internal Weak Pull-Up Resistor

All I/O pins, except configuration, test, and JTAG pins, have an option to enable weak pull-up.

Table 1-13: Internal Weak Pull-Up Resistor Values for Arria V Devices

Symbol	Description	Condition (V) ⁽¹¹⁾	Value ⁽¹²⁾	Unit
R_{PU}	Value of the I/O pin pull-up resistor before and during configuration, as well as user mode if you have enabled the programmable pull-up resistor option.	$V_{CCIO} = 3.3 \pm 5\%$	25	k Ω
		$V_{CCIO} = 3.0 \pm 5\%$	25	k Ω
		$V_{CCIO} = 2.5 \pm 5\%$	25	k Ω
		$V_{CCIO} = 1.8 \pm 5\%$	25	k Ω
		$V_{CCIO} = 1.5 \pm 5\%$	25	k Ω
		$V_{CCIO} = 1.35 \pm 5\%$	25	k Ω
		$V_{CCIO} = 1.25 \pm 5\%$	25	k Ω
		$V_{CCIO} = 1.2 \pm 5\%$	25	k Ω

Related Information

[Arria V GT, GX, ST, and SX Device Family Pin Connection Guidelines](#)

Provides more information about the pins that support internal weak pull-up and internal weak pull-down features.

⁽¹⁰⁾ The I/O ramp rate is 10 ns or more. For ramp rates faster than 10 ns, $|I_{IOPIN}| = C \, dv/dt$, in which C is the I/O pin capacitance and dv/dt is the slew rate.

⁽¹¹⁾ Pin pull-up resistance values may be lower if an external source drives the pin higher than V_{CCIO} .

⁽¹²⁾ Valid with $\pm 10\%$ tolerances to cover changes over PVT.

Symbol/Description	Condition	Transceiver Speed Grade 3			Unit
		Min	Typ	Max	
Differential on-chip termination resistors	85- Ω setting	—	85	—	Ω
	100- Ω setting	—	100	—	Ω
	120- Ω setting	—	120	—	Ω
	150- Ω setting	—	150	—	Ω
Intra-differential pair skew	TX $V_{CM} = 0.65$ V (AC coupled) and slew rate of 15 ps	—	—	15	ps
Intra-transceiver block transmitter channel-to-channel skew	$\times 6$ PMA bonded mode	—	—	180	ps
Inter-transceiver block transmitter channel-to-channel skew ⁽⁵⁵⁾	$\times N$ PMA bonded mode	—	—	500	ps

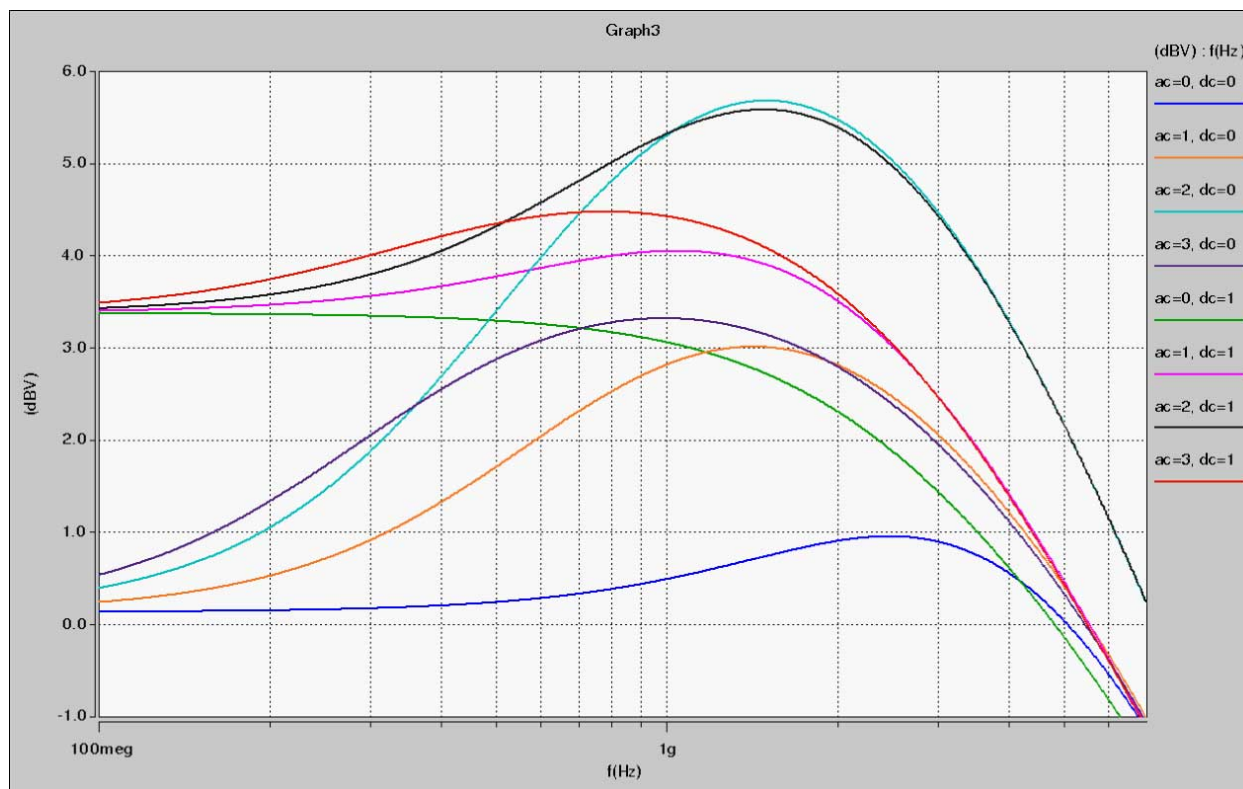
Table 1-30: CMU PLL Specifications for Arria V GT and ST Devices

Symbol/Description	Transceiver Speed Grade 3		Unit
	Min	Max	
Supported data range	0.611	10.3125	Gbps
fPLL supported data range	611	3125	Mbps

⁽⁵⁵⁾ This specification is only applicable to channels on one side of the device across two transceiver banks.

CTLE Response at Data Rates ≤ 3.25 Gbps across Supported AC Gain and DC Gain

Figure 1-3: CTLE Response at Data Rates ≤ 3.25 Gbps across Supported AC Gain and DC Gain for Arria V GX, GT, SX, and ST Devices



Typical TX V_{OD} Setting for Arria V Transceiver Channels with termination of 100 Ω Table 1-32: Typical TX V_{OD} Setting for Arria V Transceiver Channels with termination of 100 Ω

Symbol	V_{OD} Setting ⁽⁵⁸⁾	V_{OD} Value (mV)	V_{OD} Setting ⁽⁵⁸⁾	V_{OD} Value (mV)
V_{OD} differential peak-to-peak typical	6 ⁽⁵⁹⁾	120	34	680
	7 ⁽⁵⁹⁾	140	35	700
	8 ⁽⁵⁹⁾	160	36	720
	9	180	37	740
	10	200	38	760
	11	220	39	780
	12	240	40	800
	13	260	41	820
	14	280	42	840
	15	300	43	860
	16	320	44	880
	17	340	45	900
	18	360	46	920
	19	380	47	940
	20	400	48	960
	21	420	49	980
	22	440	50	1000
	23	460	51	1020
	24	480	52	1040

⁽⁵⁸⁾ Convert these values to their binary equivalent form if you are using the dynamic reconfiguration mode for PMA analog controls.⁽⁵⁹⁾ Only valid for data rates ≤ 5 Gbps.

Table 1-34: Transceiver Compliance Specification for All Supported Protocol for Arria V GX, GT, SX, and ST Devices

Protocol	Sub-protocol	Data Rate (Mbps)
PCIe	PCIe Gen1	2,500
	PCIe Gen2	5,000
	PCIe Cable	2,500
XAUI	XAUI 2135	3,125
Serial RapidIO® (SRIO)	SRIO 1250 SR	1,250
	SRIO 1250 LR	1,250
	SRIO 2500 SR	2,500
	SRIO 2500 LR	2,500
	SRIO 3125 SR	3,125
	SRIO 3125 LR	3,125
	SRIO 5000 SR	5,000
	SRIO 5000 MR	5,000
	SRIO 5000 LR	5,000
	SRIO_6250_SR	6,250
	SRIO_6250_MR	6,250
	SRIO_6250_LR	6,250

Symbol	Condition	-I3, -C4			-I5, -C5			-C6			Unit
		Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
	SERDES factor $J \geq 8^{(76)(78)}$, LVDS TX with RX DPA	⁽⁷⁷⁾	—	1600	⁽⁷⁷⁾	—	1500	⁽⁷⁷⁾	—	1250	Mbps
	SERDES factor $J = 1$ to 2, Uses DDR Registers	⁽⁷⁷⁾	—	⁽⁷⁹⁾	⁽⁷⁷⁾	—	⁽⁷⁹⁾	⁽⁷⁷⁾	—	⁽⁷⁹⁾	Mbps
Emulated Differential I/O Standards with Three External Output Resistor Network - f_{HSDR} (data rate) ⁽⁸⁰⁾	SERDES factor $J = 4$ to $10^{(81)}$	⁽⁷⁷⁾	—	945	⁽⁷⁷⁾	—	945	⁽⁷⁷⁾	—	945	Mbps
Emulated Differential I/O Standards with One External Output Resistor Network - f_{HSDR} (data rate) ⁽⁸⁰⁾	SERDES factor $J = 4$ to $10^{(81)}$	⁽⁷⁷⁾	—	200	⁽⁷⁷⁾	—	200	⁽⁷⁷⁾	—	200	Mbps
$t_{x \text{ Jitter}}$ - True Differential I/O Standards	Total Jitter for Data Rate 600 Mbps – 1.25 Gbps	—	—	160	—	—	160	—	—	160	ps
	Total Jitter for Data Rate < 600 Mbps	—	—	0.1	—	—	0.1	—	—	0.1	UI

⁽⁷⁸⁾ The V_{CC} and V_{CCP} must be on a separate power layer and a maximum load of 5 pF for chip-to-chip interface.

⁽⁷⁹⁾ The maximum ideal data rate is the SERDES factor (J) x the PLL maximum output frequency (f_{OUT}), provided you can close the design timing and the signal integrity simulation is clean.

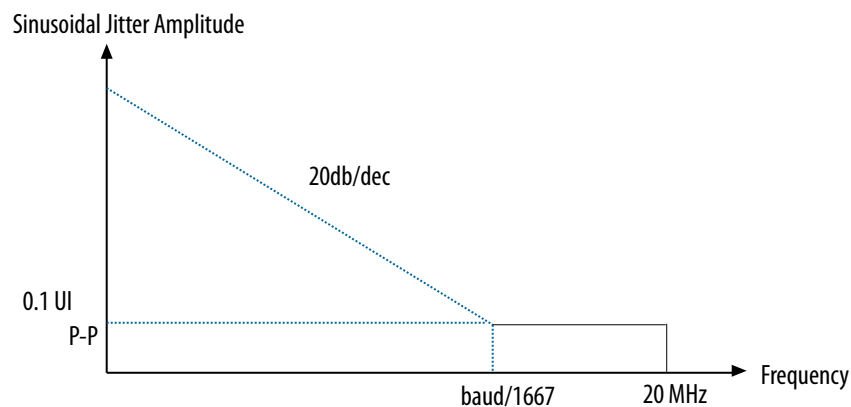
⁽⁸⁰⁾ You must calculate the leftover timing margin in the receiver by performing link timing closure analysis. You must consider the board skew margin, transmitter channel-to-channel skew, and receiver sampling margin to determine the leftover timing margin.

⁽⁸¹⁾ When using True LVDS RX channels for emulated LVDS TX channel, only serialization factors 1 and 2 are supported.

Symbol	Condition	-I3, -C4			-I5, -C5			-C6			Unit
		Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	
$t_{x \text{ Jitter}}$ -Emulated Differential I/O Standards with Three External Output Resistor Network	Total Jitter for Data Rate 600 Mbps – 1.25 Gbps	—	—	260	—	—	300	—	—	350	ps
	Total Jitter for Data Rate < 600 Mbps	—	—	0.16	—	—	0.18	—	—	0.21	UI
$t_{x \text{ Jitter}}$ -Emulated Differential I/O Standards with One External Output Resistor Network	—	—	—	0.15	—	—	0.15	—	—	0.15	UI
t_{DUTY}	TX output clock duty cycle for both True and Emulated Differential I/O Standards	45	50	55	45	50	55	45	50	55	%
t_{RISE} and t_{FALL}	True Differential I/O Standards ⁽⁸²⁾	—	—	160	—	—	180	—	—	200	ps
	Emulated Differential I/O Standards with Three External Output Resistor Network	—	—	250	—	—	250	—	—	300	ps
	Emulated Differential I/O Standards with One External Output Resistor Network	—	—	500	—	—	500	—	—	500	ps

⁽⁸²⁾ This applies to default pre-emphasis and V_{OD} settings only.

Figure 1-6: LVDS Soft-CDR/DPA Sinusoidal Jitter Tolerance Specification for a Data Rate Less than 1.25 Gbps



DLL Frequency Range Specifications

Table 1-43: DLL Frequency Range Specifications for Arria V Devices

Parameter	-I3, -C4	-I5, -C5	-C6	Unit
DLL operating frequency range	200 – 667	200 – 667	200 – 667	MHz

DQS Logic Block Specifications

Table 1-44: DQS Phase Shift Error Specifications for DLL-Delayed Clock ($t_{\text{DQS_PSERR}}$) for Arria V Devices

This error specification is the absolute maximum and minimum error.

Number of DQS Delay Buffer	-I3, -C4	-I5, -C5	-C6	Unit
2	40	80	80	ps

Figure 1-9: SPI Master Timing Diagram

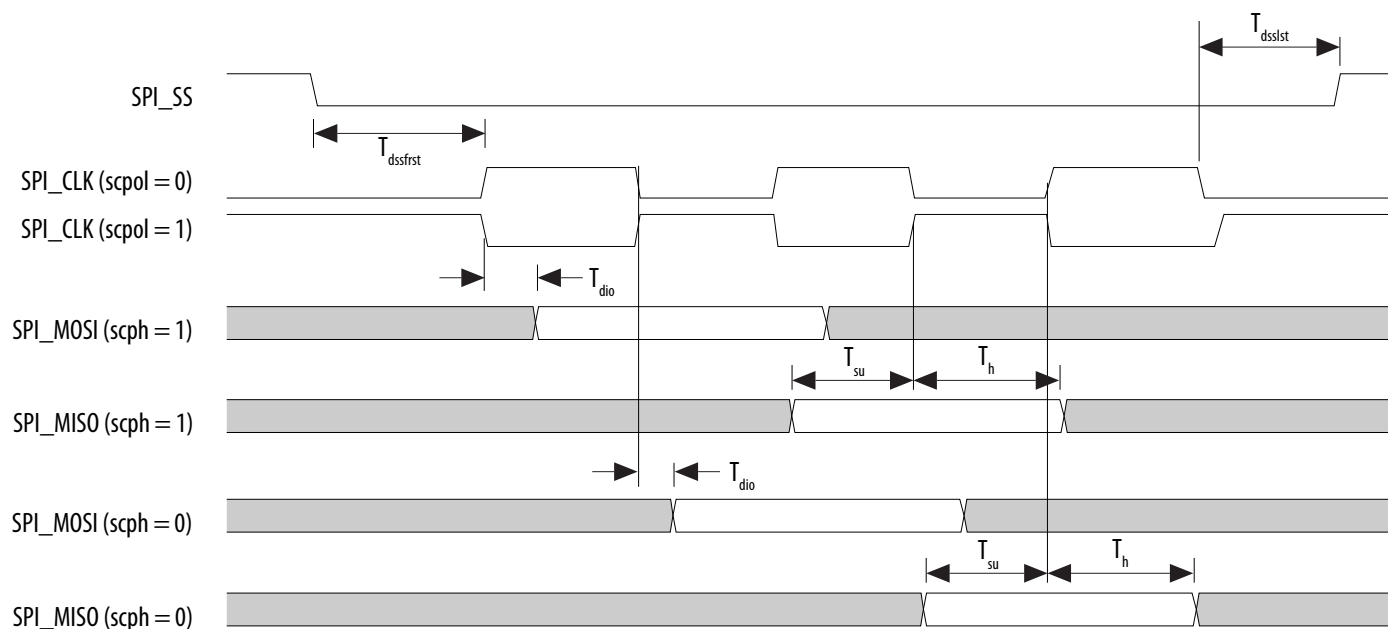
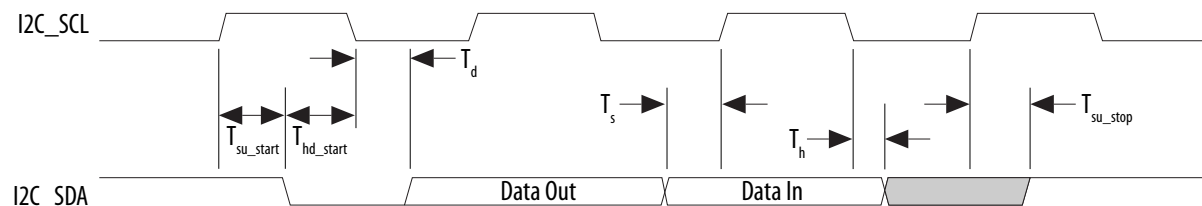


Table 1-53: SPI Slave Timing Requirements for Arria V Devices

The setup and hold times can be used for Texas Instruments SSP mode and National Semiconductor Microwire mode.

Symbol	Description	Min	Max	Unit
T_{clk}	CLK clock period	20	—	ns
T_s	MOSI Setup time	5	—	ns
T_h	MOSI Hold time	5	—	ns
T_{suss}	Setup time SPI_SS valid before first clock edge	8	—	ns
T_{hss}	Hold time SPI_SS valid after last clock edge	8	—	ns
T_d	MISO output delay	—	6	ns

Figure 1-16: I²C Timing Diagram

NAND Timing Characteristics

Table 1-60: NAND ONFI 1.0 Timing Requirements for Arria V Devices

The NAND controller supports Open NAND FLASH Interface (ONFI) 1.0 Mode 5 timing as well as legacy NAND devices. This table lists the requirements for ONFI 1.0 mode 5 timing. The HPS NAND controller can meet this timing by programming the c4 output of the main HPS PLL and timing registers provided in the NAND controller.

Symbol	Description	Min	Max	Unit
$T_{wp}^{(89)}$	Write enable pulse width	10	—	ns
$T_{wh}^{(89)}$	Write enable hold time	7	—	ns
$T_{rp}^{(89)}$	Read enable pulse width	10	—	ns
$T_{reh}^{(89)}$	Read enable hold time	7	—	ns
$T_{clesu}^{(89)}$	Command latch enable to write enable setup time	10	—	ns
$T_{cleh}^{(89)}$	Command latch enable to write enable hold time	5	—	ns
$T_{cesu}^{(89)}$	Chip enable to write enable setup time	15	—	ns
$T_{ceh}^{(89)}$	Chip enable to write enable hold time	5	—	ns
$T_{alesu}^{(89)}$	Address latch enable to write enable setup time	10	—	ns
$T_{aleh}^{(89)}$	Address latch enable to write enable hold time	5	—	ns
$T_{dsu}^{(89)}$	Data to write enable setup time	10	—	ns

⁽⁸⁹⁾ Timing of the NAND interface is controlled through the NAND configuration registers.

HPS JTAG Timing Specifications

Table 1-62: HPS JTAG Timing Parameters and Values for Arria V Devices

Symbol	Description	Min	Max	Unit
t_{JCP}	TCK clock period	30	—	ns
t_{JCH}	TCK clock high time	14	—	ns
t_{JCL}	TCK clock low time	14	—	ns
t_{JPSU} (TDI)	TDI JTAG port setup time	2	—	ns
t_{JPSU} (TMS)	TMS JTAG port setup time	3	—	ns
t_{JPH}	JTAG port hold time	5	—	ns
t_{JPCO}	JTAG port clock to output	—	12 ⁽⁹⁰⁾	ns
t_{JPZX}	JTAG port high impedance to valid output	—	14 ⁽⁹⁰⁾	ns
t_{JPXZ}	JTAG port valid output to high impedance	—	14 ⁽⁹⁰⁾	ns

Configuration Specifications

This section provides configuration specifications and timing for Arria V devices.

POR Specifications

Table 1-63: Fast and Standard POR Delay Specification for Arria V Devices

POR Delay	Minimum	Maximum	Unit
Fast	4	12 ⁽⁹¹⁾	ms

⁽⁹⁰⁾ A 1-ns adder is required for each V_{CCIO_HPS} voltage step down from 3.0 V. For example, t_{JPCO} = 13 ns if V_{CCIO_HPS} of the TDO I/O bank = 2.5 V, or 14 ns if it equals 1.8 V.

⁽⁹¹⁾ The maximum pulse width of the fast POR delay is 12 ms, providing enough time for the PCIe hard IP to initialize after the POR trip.

Remote System Upgrades

Table 1-74: Remote System Upgrade Circuitry Timing Specifications for Arria V Devices

Parameter	Minimum	Unit
$t_{RU_nCONFIG}^{(110)}$	250	ns
$t_{RU_nRSTIMER}^{(111)}$	250	ns

Related Information

- [Remote System Upgrade State Machine](#)
Provides more information about configuration reset (RU_CONFIG) signal.
- [User Watchdog Timer](#)
Provides more information about reset_timer (RU_nRSTIMER) signal.

User Watchdog Internal Oscillator Frequency Specifications

Table 1-75: User Watchdog Internal Oscillator Frequency Specifications for Arria V Devices

Parameter	Minimum	Typical	Maximum	Unit
User watchdog internal oscillator frequency	5.3	7.9	12.5	MHz

I/O Timing

Altera offers two ways to determine I/O timing—the Excel-based I/O timing and the Quartus Prime Timing Analyzer.

Excel-based I/O timing provides pin timing performance for each device density and speed grade. The data is typically used prior to designing the FPGA to get an estimate of the timing budget as part of the link timing analysis.

⁽¹¹⁰⁾ This is equivalent to strobing the reconfiguration input of the ALTREMOTE_UPDATE IP core high for the minimum timing specification.

⁽¹¹¹⁾ This is equivalent to strobing the reset timer input of the ALTREMOTE_UPDATE IP core high for the minimum timing specification.

Symbol	Description	V _{CCIO} (V)	Typical	Unit
dR/dV	OCT variation with voltage without re-calibration	3.0	0.0297	%/mV
		2.5	0.0344	
		1.8	0.0499	
		1.5	0.0744	
		1.2	0.1241	
dR/dT	OCT variation with temperature without re-calibration	3.0	0.189	%/°C
		2.5	0.208	
		1.8	0.266	
		1.5	0.273	
		1.2	0.317	

Pin Capacitance

Table 2-13: Pin Capacitance for Arria V GZ Devices

Symbol	Description	Maximum	Unit
C _{IOTB}	Input capacitance on the top and bottom I/O pins	6	pF
C _{IOLR}	Input capacitance on the left and right I/O pins	6	pF
C _{OUTFB}	Input capacitance on dual-purpose clock output and feedback pins	6	pF

Switching Characteristics

Transceiver Performance Specifications

Reference Clock

Table 2-22: Reference Clock Specifications for Arria V GZ Devices

Speed grades shown refer to the PMA Speed Grade in the device ordering code. The maximum data rate could be restricted by the Core/PCS speed grade. Contact your Altera Sales Representative for the maximum data rate specifications in each speed grade combination offered. For more information about device ordering codes, refer to the *Arria V Device Overview*.

Symbol/Description	Conditions	Transceiver Speed Grade 2			Transceiver Speed Grade 3			Unit
		Min	Typ	Max	Min	Typ	Max	
Reference Clock								
Supported I/O Standards	Dedicated reference clock pin	1.2-V PCML, 1.4-V PCML, 1.5-V PCML, 2.5-V PCML, Differential LVPECL, LVDS, and HCSL						
	RX reference clock pin	1.4-V PCML, 1.5-V PCML, 2.5-V PCML, LVPECL, and LVDS						
Input Reference Clock Frequency (CMU PLL) ⁽¹³⁷⁾	—	40	—	710	40	—	710	MHz
Input Reference Clock Frequency (ATX PLL) ⁽¹³⁷⁾	—	100	—	710	100	—	710	MHz

⁽¹³⁷⁾ The input reference clock frequency options depend on the data rate and the device speed grade.

CMU PLL

Table 2-26: CMU PLL Specifications for Arria V GZ Devices

Speed grades shown refer to the PMA Speed Grade in the device ordering code. The maximum data rate could be restricted by the Core/PCS speed grade. Contact your Altera Sales Representative for the maximum data rate specifications in each speed grade combination offered. For more information about device ordering codes, refer to the *Arria V Device Overview*.

Symbol/Description	Conditions	Transceiver Speed Grade 2			Transceiver Speed Grade 3			Unit
		Min	Typ	Max	Min	Typ	Max	
Supported data range	—	600	—	12500	600	—	10312.5	Mbps
$t_{\text{pll_powerdown}}$ ⁽¹⁵³⁾	—	1	—	—	1	—	—	μs
$t_{\text{pll_lock}}$ ⁽¹⁵⁴⁾	—		—	10	—	—	10	μs

Related Information

[Arria V Device Overview](#)

For more information about device ordering codes.

ATX PLL

Table 2-27: ATX PLL Specifications for Arria V GZ Devices

Speed grades shown refer to the PMA Speed Grade in the device ordering code. The maximum data rate could be restricted by the Core/PCS speed grade. Contact your Altera Sales Representative for the maximum data rate specifications in each speed grade combination offered. For more information about device ordering codes, refer to the *Arria V Device Overview*.

⁽¹⁵³⁾ $t_{\text{pll_powerdown}}$ is the PLL powerdown minimum pulse width.

⁽¹⁵⁴⁾ $t_{\text{pll_lock}}$ is the time required for the transmitter CMU/ATX PLL to lock to the input reference clock frequency after coming out of reset.

Duty Cycle Distortion (DCD) Specifications

Table 2-52: Worst-Case DCD on Arria V GZ I/O Pins

The DCD numbers do not cover the core clock network.

Symbol	C3, I3L		C4, I4		Unit
	Min	Max	Min	Max	
Output Duty Cycle	45	55	45	55	%

Configuration Specification

POR Specifications

Table 2-53: Fast and Standard POR Delay Specification for Arria V GZ Devices

Select the POR delay based on the MSEL setting as described in the “Configuration Schemes for Arria V Devices” table in the *Configuration, Design Security, and Remote System Upgrades in Arria V Devices* chapter.

POR Delay	Minimum (ms)	Maximum (ms)
Fast	4	12 ⁽²⁰²⁾
Standard	100	300

Related Information

[Configuration, Design Security, and Remote System Upgrades in Arria V Devices](#)

⁽²⁰²⁾ The maximum pulse width of the fast POR delay is 12 ms, providing enough time for the PCIe hard IP to initialize after the POR trip.

Related Information

- [Configuration, Design Security, and Remote System Upgrades in Arria V Devices](#)
For more information about the reconfiguration input for the ALTREMOTE_UPDATE IP core, refer to the “User Watchdog Timer” section.
- [Configuration, Design Security, and Remote System Upgrades in Arria V Devices](#)
For more information about the `reset_timer` input for the ALTREMOTE_UPDATE IP core, refer to the “Remote System Upgrade State Machine” section.

User Watchdog Internal Oscillator Frequency Specification

Table 2-65: User Watchdog Internal Oscillator Frequency Specifications

Minimum	Typical	Maximum	Unit
5.3	7.9	12.5	MHz

I/O Timing

Altera offers two ways to determine I/O timing—the Excel-based I/O Timing and the Quartus II Timing Analyzer.

Excel-based I/O timing provides pin timing performance for each device density and speed grade. The data is typically used prior to designing the FPGA to get an estimate of the timing budget as part of the link timing analysis.

The Quartus II Timing Analyzer provides a more accurate and precise I/O timing data based on the specifics of the design after you complete place-and-route.

Related Information

[Arria V Devices Documentation page](#)

For the Excel-based I/O Timing spreadsheet

⁽²²⁶⁾ This is equivalent to strobing the reconfiguration input of the ALTREMOTE_UPDATE IP core high for the minimum timing specification. For more information, refer to the “Remote System Upgrade State Machine” section in the *Configuration, Design Security, and Remote System Upgrades in Arria V Devices* chapter.

⁽²²⁷⁾ This is equivalent to strobing the `reset_timer` input of the ALTREMOTE_UPDATE IP core high for the minimum timing specification. For more information, refer to the “User Watchdog Timer” section in the *Configuration, Design Security, and Remote System Upgrades in Arria V Devices* chapter.

Term	Definition
t_C	High-speed receiver and transmitter input and output clock period.
TCCS (channel-to-channel-skew)	The timing difference between the fastest and slowest output edges, including t_{CO} variation and clock skew, across channels driven by the same PLL. The clock is included in the TCCS measurement (refer to the Timing Diagram figure under SW in this table).
t_{DUTY}	High-speed I/O block—Duty cycle on the high-speed transmitter output clock.
t_{FALL}	Signal high-to-low transition time (80-20%)
t_{INCCJ}	Cycle-to-cycle jitter tolerance on the PLL clock input.
t_{OUTPJ_IO}	Period jitter on the general purpose I/O driven by a PLL.
t_{OUTPJ_DC}	Period jitter on the dedicated clock output driven by a PLL.
t_{RISE}	Signal low-to-high transition time (20-80%)
Timing Unit Interval (TUI)	The timing budget allowed for skew, propagation delays, and the data sampling window. ($TUI = 1/(\text{receiver input clock frequency multiplication factor}) = t_C/w$)
$V_{CM(DC)}$	DC common mode input voltage.
V_{ICM}	Input common mode voltage—The common mode of the differential signal at the receiver.
V_{ID}	Input differential voltage swing—The difference in voltage between the positive and complementary conductors of a differential transmission at the receiver.
$V_{DIF(AC)}$	AC differential input voltage—Minimum AC input differential voltage required for switching.
$V_{DIF(DC)}$	DC differential input voltage— Minimum DC input differential voltage required for switching.
V_{IH}	Voltage input high—The minimum positive voltage applied to the input which is accepted by the device as a logic high.
$V_{IH(AC)}$	High-level AC input voltage
$V_{IH(DC)}$	High-level DC input voltage
V_{IL}	Voltage input low—The maximum positive voltage applied to the input which is accepted by the device as a logic low.
$V_{IL(AC)}$	Low-level AC input voltage
$V_{IL(DC)}$	Low-level DC input voltage

Date	Version	Changes
July 2014	3.8	<ul style="list-style-type: none"> Updated Table 21. Updated Table 22 V_{OCM} (DC Coupled) condition. Updated the DCLK note to Figure 6, Figure 7, and Figure 9. Added note to Table 5 and Table 6. Added the DCLK specification to Table 50. Added note to Table 51. Updated the list of parameters in Table 53.
February 2014	3.7	Updated Table 28.
December 2013	3.6	<ul style="list-style-type: none"> Updated Table 2, Table 13, Table 18, Table 19, Table 22, Table 30, Table 33, Table 37, Table 38, Table 45, Table 46, Table 47, Table 56, Table 49. Updated “PLL Specifications”.
August 2013	3.5	Updated Table 28.
August 2013	3.4	<ul style="list-style-type: none"> Removed Preliminary tags for Table 2, Table 4, Table 5, Table 14, Table 27, Table 28, Table 29, Table 31, Table 32, Table 43, Table 45, Table 46, Table 47, Table 48, Table 49, Table 50, and Table 54. Updated Table 2 and Table 28.
June 2013	3.3	Updated Table 23, Table 28, Table 51, and Table 55.
May 2013	3.2	<ul style="list-style-type: none"> Added Table 23. Updated Table 5, Table 22, Table 26, and Table 57. Updated Figure 6, Figure 7, Figure 8, and Figure 9.
March 2013	3.1	<ul style="list-style-type: none"> Updated Table 2, Table 6, Table 7, Table 8, Table 19, Table 22, Table 26, Table 29, Table 52. Updated “Maximum Allowed Overshoot and Undershoot Voltage”.
December 2012	3.0	Initial release.