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### Understanding [Embedded - FPGAs \(Field Programmable Gate Array\)](#)

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

### Applications of Embedded - FPGAs

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

#### Details

Product Status	Obsolete
Number of LABs/CLBs	8962
Number of Logic Elements/Cells	190000
Total RAM Bits	13284352
Number of I/O	544
Number of Gates	-
Voltage - Supply	1.07V ~ 1.13V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	1152-BBGA, FCBGA Exposed Pad
Supplier Device Package	1152-FBGA (35x35)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/intel/5agxma5g6f35c6n">https://www.e-xfl.com/product-detail/intel/5agxma5g6f35c6n</a>

## I/O Standard Specifications

Tables in this section list the input voltage ( $V_{IH}$  and  $V_{IL}$ ), output voltage ( $V_{OH}$  and  $V_{OL}$ ), and current drive characteristics ( $I_{OH}$  and  $I_{OL}$ ) for various I/O standards supported by Arria V devices.

You must perform timing closure analysis to determine the maximum achievable frequency for general purpose I/O standards.

### Single-Ended I/O Standards

**Table 1-14: Single-Ended I/O Standards for Arria V Devices**

I/O Standard	$V_{CCIO}$ (V)			$V_{IL}$ (V)		$V_{IH}$ (V)		$V_{OL}$ (V)	$V_{OH}$ (V)	$I_{OL}^{(13)}$ (mA)	$I_{OH}^{(13)}$ (mA)
	Min	Typ	Max	Min	Max	Min	Max	Max	Min		
3.3-V LVTTL	3.135	3.3	3.465	-0.3	0.8	1.7	3.6	0.45	2.4	4	-4
3.3-V LVCMOS	3.135	3.3	3.465	-0.3	0.8	1.7	3.6	0.2	$V_{CCIO} - 0.2$	2	-2
3.0-V LVTTL	2.85	3	3.15	-0.3	0.8	1.7	3.6	0.4	2.4	2	-2
3.0-V LVCMOS	2.85	3	3.15	-0.3	0.8	1.7	3.6	0.2	$V_{CCIO} - 0.2$	0.1	-0.1
3.0-V PCI	2.85	3	3.15	—	$0.3 \times V_{CCIO}$	$0.5 \times V_{CCIO}$	$V_{CCIO} + 0.3$	$0.1 \times V_{CCIO}$	$0.9 \times V_{CCIO}$	1.5	-0.5
3.0-V PCI-X	2.85	3	3.15	—	$0.35 \times V_{CCIO}$	$0.5 \times V_{CCIO}$	$V_{CCIO} + 0.3$	$0.1 \times V_{CCIO}$	$0.9 \times V_{CCIO}$	1.5	-0.5
2.5 V	2.375	2.5	2.625	-0.3	0.7	1.7	3.6	0.4	2	1	-1
1.8 V	1.71	1.8	1.89	-0.3	$0.35 \times V_{CCIO}$	$0.65 \times V_{CCIO}$	$V_{CCIO} + 0.3$	0.45	$V_{CCIO} - 0.45$	2	-2
1.5 V	1.425	1.5	1.575	-0.3	$0.35 \times V_{CCIO}$	$0.65 \times V_{CCIO}$	$V_{CCIO} + 0.3$	$0.25 \times V_{CCIO}$	$0.75 \times V_{CCIO}$	2	-2
1.2 V	1.14	1.2	1.26	-0.3	$0.35 \times V_{CCIO}$	$0.65 \times V_{CCIO}$	$V_{CCIO} + 0.3$	$0.25 \times V_{CCIO}$	$0.75 \times V_{CCIO}$	2	-2

<sup>(13)</sup> To meet the  $I_{OL}$  and  $I_{OH}$  specifications, you must set the current strength settings accordingly. For example, to meet the 3.3-V LVTTL specification (4 mA), you should set the current strength settings to 4 mA. Setting at lower current strength may not meet the  $I_{OL}$  and  $I_{OH}$  specifications in the datasheet.

I/O Standard	$V_{CCIO}$ (V)			$V_{SWING(DC)}$ (V)		$V_{X(AC)}$ (V)			$V_{SWING(AC)}$ (V)	
	Min	Typ	Max	Min	Max	Min	Typ	Max	Min	Max
SSTL-125	1.19	1.25	1.31	0.18	<sup>(15)</sup>	$V_{CCIO}/2 - 0.15$	$V_{CCIO}/2$	$V_{CCIO}/2 + 0.15$	$2(V_{IH(AC)} - V_{REF})$	$2(V_{IL(AC)} - V_{REF})$

## Differential HSTL and HSUL I/O Standards

Table 1-18: Differential HSTL and HSUL I/O Standards for Arria V Devices

I/O Standard	$V_{CCIO}$ (V)			$V_{DIF(DC)}$ (V)		$V_{X(AC)}$ (V)			$V_{CM(DC)}$ (V)			$V_{DIF(AC)}$ (V)	
	Min	Typ	Max	Min	Max	Min	Typ	Max	Min	Typ	Max	Min	Max
HSTL-18 Class I, II	1.71	1.8	1.89	0.2	—	0.78	—	1.12	0.78	—	1.12	0.4	—
HSTL-15 Class I, II	1.425	1.5	1.575	0.2	—	0.68	—	0.9	0.68	—	0.9	0.4	—
HSTL-12 Class I, II	1.14	1.2	1.26	0.16	$V_{CCIO} + 0.3$	—	$0.5 \times V_{CCIO}$	—	$0.4 \times V_{CCIO}$	$0.5 \times V_{CCIO}$	$0.6 \times V_{CCIO}$	0.3	$V_{CCIO} + 0.48$
HSUL-12	1.14	1.2	1.3	0.26	0.26	$0.5 \times V_{CCIO} - 0.12$	$0.5 \times V_{CCIO}$	$0.5 \times V_{CCIO} + 0.12$	$0.4 \times V_{CCIO}$	$0.5 \times V_{CCIO}$	$0.6 \times V_{CCIO}$	0.44	0.44

## Differential I/O Standard Specifications

Table 1-19: Differential I/O Standard Specifications for Arria V Devices

Differential inputs are powered by  $V_{CCPD}$  which requires 2.5 V.

Symbol/Description	Condition	Transceiver Speed Grade 4			Transceiver Speed Grade 6			Unit
		Min	Typ	Max	Min	Typ	Max	
Run length	—	—	—	200	—	—	200	UI
Programmable equalization AC and DC gain	AC gain setting = 0 to 3 <sup>(38)</sup> DC gain setting = 0 to 1	Refer to CTLE Response at Data Rates > 3.25 Gbps across Supported AC Gain and DC Gain for Arria V GX, GT, SX, and ST Devices and CTLE Response at Data Rates ≤ 3.25 Gbps across Supported AC Gain and DC Gain for Arria V GX, GT, SX, and ST Devices diagrams.						dB

Table 1-23: Transmitter Specifications for Arria V GX and SX Devices

Symbol/Description	Condition	Transceiver Speed Grade 4			Transceiver Speed Grade 6			Unit
		Min	Typ	Max	Min	Typ	Max	
Supported I/O standards	1.5 V PCML							
Data rate	—	611	—	6553.6	611	—	3125	Mbps
V <sub>OCM</sub> (AC coupled)	—	—	650	—	—	650	—	mV
V <sub>OCM</sub> (DC coupled)	≤ 3.2Gbps <sup>(32)</sup>	670	700	730	670	700	730	mV
Differential on-chip termination resistors	85-Ω setting	—	85	—	—	85	—	Ω
	100-Ω setting	—	100	—	—	100	—	Ω
	120-Ω setting	—	120	—	—	120	—	Ω
	150-Ω setting	—	150	—	—	150	—	Ω
Intra-differential pair skew	TX V <sub>CM</sub> = 0.65 V (AC coupled) and slew rate of 15 ps	—	—	15	—	—	15	ps
Intra-transceiver block transmitter channel-to-channel skew	×6 PMA bonded mode	—	—	180	—	—	180	ps

<sup>(37)</sup> The rate match FIFO supports only up to ±300 parts per million (ppm).<sup>(38)</sup> The Quartus Prime software allows AC gain setting = 3 for design with data rate between 611 Mbps and 1.25 Gbps only.

## Transceiver Specifications for Arria V GT and ST Devices

Table 1-26: Reference Clock Specifications for Arria V GT and ST Devices

Symbol/Description	Condition	Transceiver Speed Grade 3			Unit
		Min	Typ	Max	
Supported I/O standards	1.2 V PCML, 1.4 VPCML, 1.5 V PCML, 2.5 V PCML, Differential LVPECL <sup>(40)</sup> , HCSL, and LVDS				
Input frequency from REFCLK input pins	—	27	—	710	MHz
Rise time	Measure at ±60 mV of differential signal <sup>(41)</sup>	—	—	400	ps
Fall time	Measure at ±60 mV of differential signal <sup>(41)</sup>	—	—	400	ps
Duty cycle	—	45	—	55	%
Peak-to-peak differential input voltage	—	200	—	300 <sup>(42)</sup> /2000	mV
Spread-spectrum modulating clock frequency	PCI Express (PCIe)	30	—	33	kHz
Spread-spectrum downspread	PCIe	—	0 to –0.5%	—	—
On-chip termination resistors	—	—	100	—	Ω
V <sub>ICM</sub> (AC coupled)	—	—	1.2	—	V
V <sub>ICM</sub> (DC coupled)	HCSL I/O standard for the PCIe reference clock	250	—	550	mV

<sup>(40)</sup> Differential LVPECL signal levels must comply to the minimum and maximum peak-to-peak differential input voltage specified in this table.<sup>(41)</sup> REFCLK performance requires to meet transmitter REFCLK phase noise specification.<sup>(42)</sup> The maximum peak-to peak differential input voltage of 300 mV is allowed for DC coupled link.

Symbol/Description	Condition	Transceiver Speed Grade 3			Unit
		Min	Typ	Max	
Differential on-chip termination resistors	85- $\Omega$ setting	—	85	—	$\Omega$
	100- $\Omega$ setting	—	100	—	$\Omega$
	120- $\Omega$ setting	—	120	—	$\Omega$
	150- $\Omega$ setting	—	150	—	$\Omega$
Intra-differential pair skew	TX $V_{CM} = 0.65$ V (AC coupled) and slew rate of 15 ps	—	—	15	ps
Intra-transceiver block transmitter channel-to-channel skew	$\times 6$ PMA bonded mode	—	—	180	ps
Inter-transceiver block transmitter channel-to-channel skew <sup>(55)</sup>	$\times N$ PMA bonded mode	—	—	500	ps

Table 1-30: CMU PLL Specifications for Arria V GT and ST Devices

Symbol/Description	Transceiver Speed Grade 3		Unit
	Min	Max	
Supported data range	0.611	10.3125	Gbps
fPLL supported data range	611	3125	Mbps

<sup>(55)</sup> This specification is only applicable to channels on one side of the device across two transceiver banks.

Protocol	Sub-protocol	Data Rate (Mbps)
SONET	SONET 155	155.52
	SONET 622	622.08
	SONET 2488	2,488.32
Gigabit-capable passive optical network (GPON)	GPON 155	155.52
	GPON 622	622.08
	GPON 1244	1,244.16
	GPON 2488	2,488.32
QSGMII	QSGMII 5000	5,000

## Core Performance Specifications

### Clock Tree Specifications

Table 1-35: Clock Tree Specifications for Arria V Devices

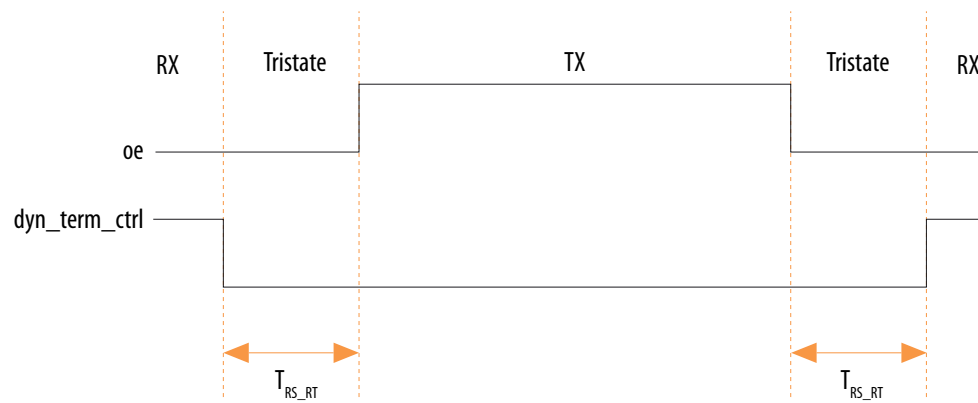
Parameter	Performance			Unit
	-I3, -C4	-I5, -C5	-C6	
Global clock and Regional clock	625	625	525	MHz
Peripheral clock	450	400	350	MHz

### PLL Specifications

Table 1-36: PLL Specifications for Arria V Devices

This table lists the Arria V PLL block specifications. Arria V PLL block does not include HPS PLL.

Figure 1-7: Timing Diagram for oe and dyn\_term\_ctrl Signals



## Duty Cycle Distortion (DCD) Specifications

Table 1-47: Worst-Case DCD on Arria V I/O Pins

The output DCD cycle only applies to the I/O buffer. It does not cover the system DCD.

Symbol	-I3, -C4		-C5, -I5		-C6		Unit
	Min	Max	Min	Max	Min	Max	
Output Duty Cycle	45	55	45	55	45	55	%

## HPS Specifications

This section provides HPS specifications and timing for Arria V devices.

For HPS reset, the minimum reset pulse widths for the HPS cold and warm reset signals (HPS\_nRST and HPS\_nPOR) are six clock cycles of HPS\_CLK1.



## HPS PLL Input Jitter

Use the following equation to determine the maximum input jitter (peak-to-peak) the HPS PLLs can tolerate. The divide value (N) is the value programmed into the denominator field of the VCO register for each PLL. The PLL input reference clock is divided by this value. The range of the denominator is 1 to 64.

$$\text{Maximum input jitter} = \text{Input clock period} \times \text{Divide value (N)} \times 0.02$$

**Table 1-50: Examples of Maximum Input Jitter**

Input Reference Clock Period	Divide Value (N)	Maximum Jitter	Unit
40 ns	1	0.8	ns
40 ns	2	1.6	ns
40 ns	4	3.2	ns

## Quad SPI Flash Timing Characteristics

**Table 1-51: Quad Serial Peripheral Interface (SPI) Flash Timing Requirements for Arria V Devices**

Symbol	Description	Min	Typ	Max	Unit
F <sub>clk</sub>	SCLK_OUT clock frequency (External clock)	—	—	108	MHz
T <sub>qspi_clk</sub>	QSPI_CLK clock period (Internal reference clock)	2.32	—	—	ns
T <sub>dutycycle</sub>	SCLK_OUT duty cycle	45	—	55	%
T <sub>dssfrst</sub>	Output delay QSPI_SS valid before first clock edge	—	1/2 cycle of SCLK_OUT	—	ns
T <sub>dsslst</sub>	Output delay QSPI_SS valid after last clock edge	–1	—	1	ns
T <sub>dio</sub>	I/O data output delay	–1	—	1	ns
T <sub>din_start</sub>	Input data valid start	—	—	$(2 + R_{\text{delay}}) \times T_{\text{qspi\_clk}} - 7.52^{(85)}$	ns

Symbol	Description	Min	Max	Unit
$T_h$	SPI MISO hold time	1	—	ns
$T_{\text{duty cycle}}$	SPI_CLK duty cycle	45	55	%
$T_{\text{dssfrst}}$	Output delay SPI_SS valid before first clock edge	8	—	ns
$T_{\text{dsslst}}$	Output delay SPI_SS valid after last clock edge	8	—	ns
$T_{\text{dio}}$	Master-out slave-in (MOSI) output delay	–1	1	ns

<sup>(86)</sup> This value is based on  $\text{rx\_sample\_dly} = 1$  and  $\text{spi\_m\_clk} = 120$  MHz.  $\text{spi\_m\_clk}$  is the internal clock that is used by SPI Master to derive its  $\text{SCLK\_OUT}$ . These timings are based on  $\text{rx\_sample\_dly}$  of 1. This delay can be adjusted as needed to accommodate slower response times from the slave. Note that a delay of 0 is not allowed. The setup time can be used as a reference starting point. It is very crucial to do a calibration to get the correct  $\text{rx\_sample\_dly}$  value because each SPI slave device may have different output delay and each application board may have different path delay. For more information about  $\text{rx\_sample\_delay}$ , refer to the SPI Controller chapter in the Hard Processor System Technical Reference Manual.

Symbol	Description	Min	Max	Unit
$T_{dh}^{(89)}$	Data to write enable hold time	5	—	ns
$T_{cea}$	Chip enable to data access time	—	25	ns
$T_{rea}$	Read enable to data access time	—	16	ns
$T_{rhz}$	Read enable to data high impedance	—	100	ns
$T_{rr}$	Ready to read enable low	20	—	ns

Figure 1-17: NAND Command Latch Timing Diagram

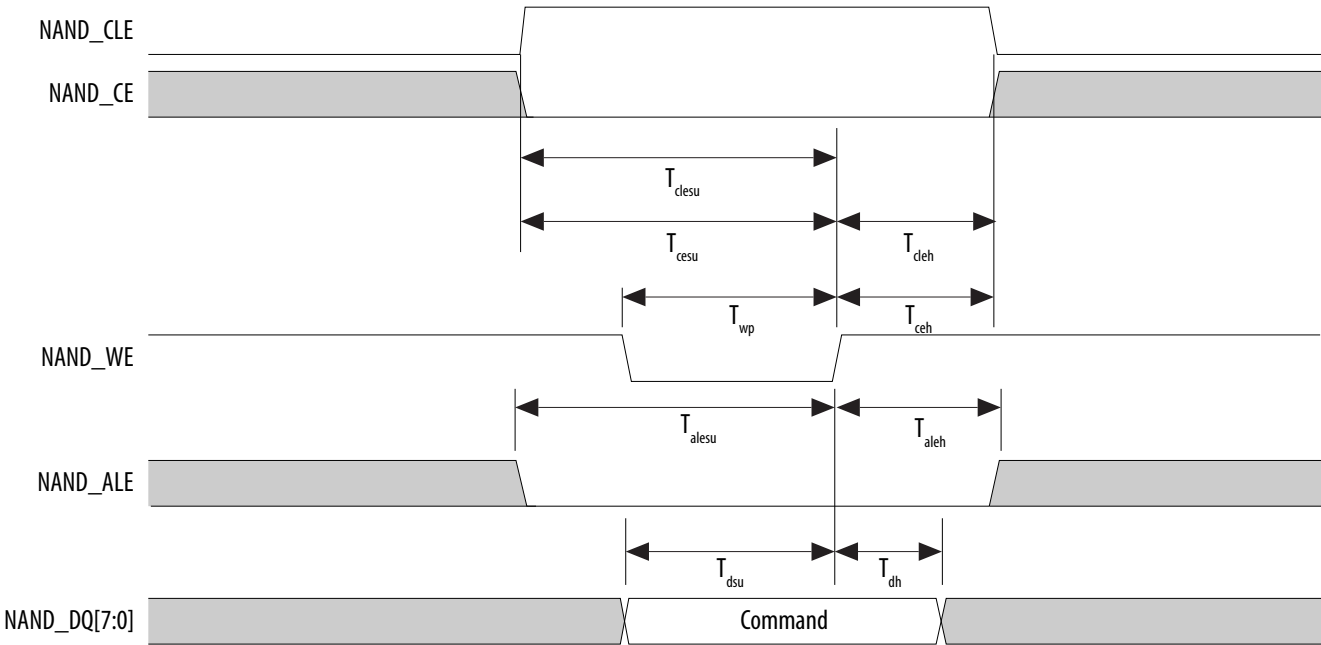
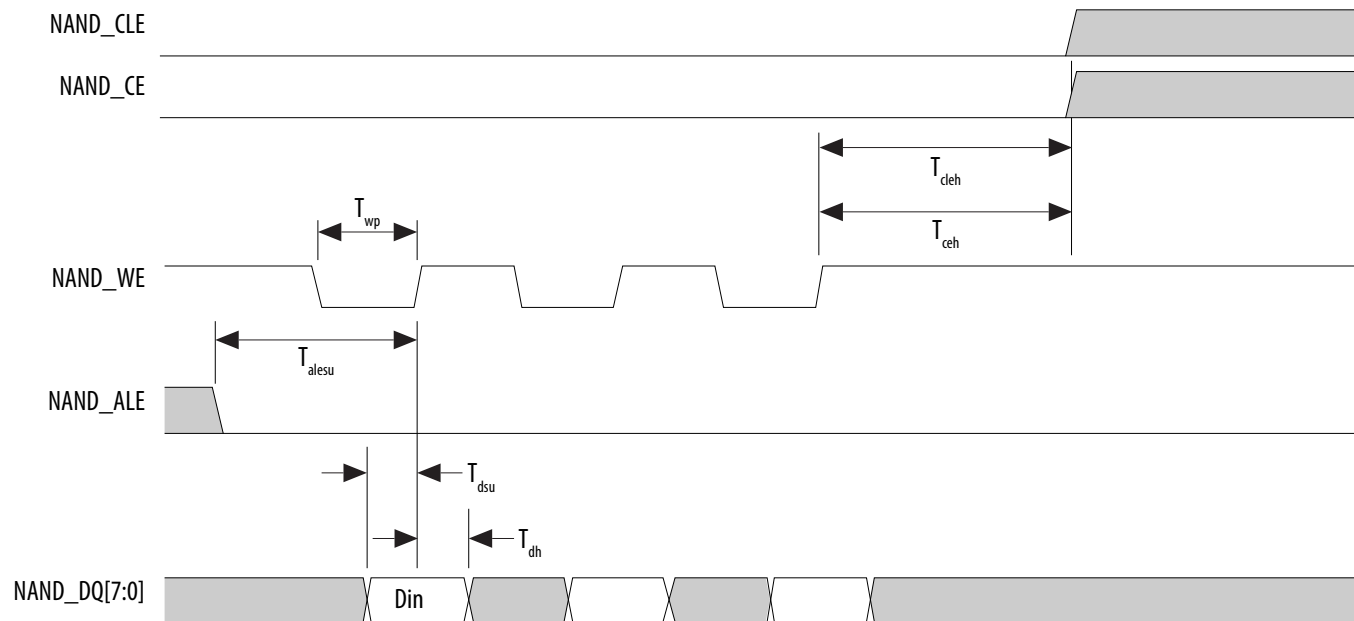


Figure 1-19: NAND Data Write Timing Diagram



## FPP Configuration Timing

### DCLK-to-DATA[] Ratio (r) for FPP Configuration

Fast passive parallel (FPP) configuration requires a different DCLK-to-DATA[] ratio when you turn on encryption or the compression feature.

Depending on the DCLK-to-DATA[] ratio, the host must send a DCLK frequency that is  $r$  times the DATA[] rate in byte per second (Bps) or word per second (Wps). For example, in FPP  $\times 16$  where the  $r$  is 2, the DCLK frequency must be 2 times the DATA[] rate in Wps.

**Table 1-65: DCLK-to-DATA[] Ratio for Arria V Devices**

Configuration Scheme	Encryption	Compression	DCLK-to-DATA[] Ratio (r)
FPP (8-bit wide)	Off	Off	1
	On	Off	1
	Off	On	2
	On	On	2
FPP (16-bit wide)	Off	Off	1
	On	Off	2
	Off	On	4
	On	On	4

### FPP Configuration Timing when DCLK-to-DATA[] = 1

When you enable decompression or the design security feature, the DCLK-to-DATA[] ratio varies for FPP  $\times 8$  and FPP  $\times 16$ . For the respective DCLK-to-DATA[] ratio, refer to the DCLK-to-DATA[] Ratio for Arria V Devices table.

**Table 1-66: FPP Timing Parameters When DCLK-to-DATA[] Ratio is 1 for Arria V Devices**

Symbol	Parameter	Minimum	Maximum	Unit
$t_{CF2CD}$	nCONFIG low to CONF_DONE low	—	600	ns
$t_{CF2ST0}$	nCONFIG low to nSTATUS low	—	600	ns
$t_{CFG}$	nCONFIG low pulse width	2	—	$\mu$ s

Symbol	Description	Minimum	Maximum	Unit
$V_I$	DC input voltage	-0.5	3.8	V
$T_J$	Operating junction temperature	-55	125	°C
$T_{STG}$	Storage temperature (No bias)	-65	150	°C
$I_{OUT}$	DC output current per pin	-25	40	mA

**Table 2-3: Transceiver Power Supply Absolute Conditions for Arria V GZ Devices**

Symbol	Description	Minimum	Maximum	Unit
$V_{CCA\_GXBL}$	Transceiver channel PLL power supply (left side)	-0.5	3.75	V
$V_{CCA\_GXBR}$	Transceiver channel PLL power supply (right side)	-0.5	3.75	V
$V_{CCHIP\_L}$	Transceiver hard IP power supply (left side)	-0.5	1.35	V
$V_{CCHSSI\_L}$	Transceiver PCS power supply (left side)	-0.5	1.35	V
$V_{CCHSSI\_R}$	Transceiver PCS power supply (right side)	-0.5	1.35	V
$V_{CCR\_GXBL}$	Receiver analog power supply (left side)	-0.5	1.35	V
$V_{CCR\_GXBR}$	Receiver analog power supply (right side)	-0.5	1.35	V
$V_{CCT\_GXBL}$	Transmitter analog power supply (left side)	-0.5	1.35	V
$V_{CCT\_GXBR}$	Transmitter analog power supply (right side)	-0.5	1.35	V
$V_{CCH\_GXBL}$	Transmitter output buffer power supply (left side)	-0.5	1.8	V
$V_{CCH\_GXBR}$	Transmitter output buffer power supply (right side)	-0.5	1.8	V

**Maximum Allowed Overshoot and Undershoot Voltage**

During transitions, input signals may overshoot to the voltage shown in the following table. They may also undershoot to -2.0 V for input currents less than 100 mA and periods shorter than 20 ns.

Clock Network	ATX PLL			CMU PLL <sup>(161)</sup>			fPLL		
	Non-bonded Mode (Gbps)	Bonded Mode (Gbps)	Channel Span	Non-bonded Mode (Gbps)	Bonded Mode (Gbps)	Channel Span	Non-bonded Mode (Gbps)	Bonded Mode (Gbps)	Channel Span
xN (PCIe)	—	8.0	8	—	5.0	8	—	—	—
xN (Native PHY IP)	8.0	8.0	Up to 13 channels above and below PLL	7.99	7.99	Up to 13 channels above and below PLL	3.125	3.125	Up to 13 channels above and below PLL
	—	8.01 to 9.8304	Up to 7 channels above and below PLL						

## Standard PCS Data Rate

**Table 2-30: Standard PCS Approximate Maximum Date Rate (Gbps) for Arria V GZ Devices**

The maximum data rate is also constrained by the transceiver speed grade. Refer to the “Commercial and Industrial Speed Grade Offering for Arria V GZ Devices” table for the transceiver speed grade.

Mode <sup>(164)</sup>	Transceiver Speed Grade	PMA Width	20	20	16	16	10	10	8	8
		PCS/Core Width	40	20	32	16	20	10	16	8
FIFO	2	C3, I3L core speed grade	9.9	9	7.84	7.2	5.3	4.7	4.24	3.76
	3	C4, I4 core speed grade	8.8	8.2	7.2	6.56	4.8	4.3	3.84	3.44

<sup>(161)</sup> ATX PLL is recommended at 8 Gbps and above data rates for improved jitter performance.

<sup>(164)</sup> The Phase Compensation FIFO can be configured in FIFO mode or register mode. In the FIFO mode, the pointers are not fixed, and the latency can vary. In the register mode the pointers are fixed for low latency.

Symbol	Parameter	Min	Typ	Max	Unit
$f_{OUT}^{(169)}$	Output frequency for an internal global or regional clock (C3, I3L speed grade)	—	—	650	MHz
	Output frequency for an internal global or regional clock (C4, I4 speed grade)	—	—	580	MHz
$f_{OUT\_EXT}^{(169)}$	Output frequency for an external clock output (C3, I3L speed grade)	—	—	667	MHz
	Output frequency for an external clock output (C4, I4 speed grade)	—	—	533	MHz
$t_{OUTDUTY}$	Duty cycle for a dedicated external clock output (when set to 50%)	45	50	55	%
$t_{FCOMP}$	External feedback clock compensation time	—	—	10	ns
$f_{DYCONFIGCLK}$	Dynamic configuration clock for <code>mgmt_clk</code> and <code>scanclk</code>	—	—	100	MHz
$t_{LOCK}$	Time required to lock from the end-of-device configuration or deassertion of <code>areset</code>	—	—	1	ms
$t_{DLOCK}$	Time required to lock dynamically (after switchover or reconfiguring any non-post-scale counters/ delays)	—	—	1	ms
$f_{CLBW}$	PLL closed-loop low bandwidth	—	0.3	—	MHz
	PLL closed-loop medium bandwidth	—	1.5	—	MHz
	PLL closed-loop high bandwidth <sup>(170)</sup>	—	4	—	MHz
$t_{PLL\_PSERR}$	Accuracy of PLL phase shift	—	—	±50	ps
$t_{ARESET}$	Minimum pulse width on the <code>areset</code> signal	10	—	—	ns

<sup>(169)</sup> This specification is limited by the lower of the two: I/O  $f_{MAX}$  or  $f_{OUT}$  of the PLL.

<sup>(170)</sup> High bandwidth PLL settings are not supported in external feedback mode.



Symbol	Conditions	C3, I3L			C4, I4			Unit
		Min	Typ	Max	Min	Typ	Max	
$f_{\text{HCLK\_in}}$ (input clock frequency) True Differential I/O Standards <sup>(179)</sup>	Clock boost factor $W = 1$ to $40$ <sup>(180)</sup>	5	—	625	5	—	525	MHz
$f_{\text{HCLK\_in}}$ (input clock frequency) Single Ended I/O Standards	Clock boost factor $W = 1$ to $40$ <sup>(180)</sup>	5	—	625	5	—	525	MHz
$f_{\text{HCLK\_in}}$ (input clock frequency) Single Ended I/O Standards	Clock boost factor $W = 1$ to $40$ <sup>(180)</sup>	5	—	420	5	—	420	MHz
$f_{\text{HCLK\_OUT}}$ (output clock frequency)	—	5	—	625 <sup>(181)</sup>	5	—	525 <sup>(181)</sup>	MHz

### Transmitter High-Speed I/O Specifications

**Table 2-40: Transmitter High-Speed I/O Specifications for Arria V GZ Devices**

When  $J = 3$  to  $10$ , use the serializer/deserializer (SERDES) block.

When  $J = 1$  or  $2$ , bypass the SERDES block.

<sup>(179)</sup> This only applies to DPA and soft-CDR modes.

<sup>(180)</sup> Clock Boost Factor ( $W$ ) is the ratio between the input data rate to the input clock rate.

<sup>(181)</sup> This is achieved by using the LVDS clock network.

Number of DQS Delay Buffers	C3, I3L	C4, I4	Unit
4	120	128	ps

## Memory Output Clock Jitter Specifications

**Table 2-50: Memory Output Clock Jitter Specification for Arria V GZ Devices**

The clock jitter specification applies to the memory output clock pins generated using differential signal-splitter and DDIO circuits clocked by a PLL output routed on a PHY, regional, or global clock network as specified. Altera recommends using PHY clock networks whenever possible.

The clock jitter specification applies to the memory output clock pins clocked by an integer PLL.

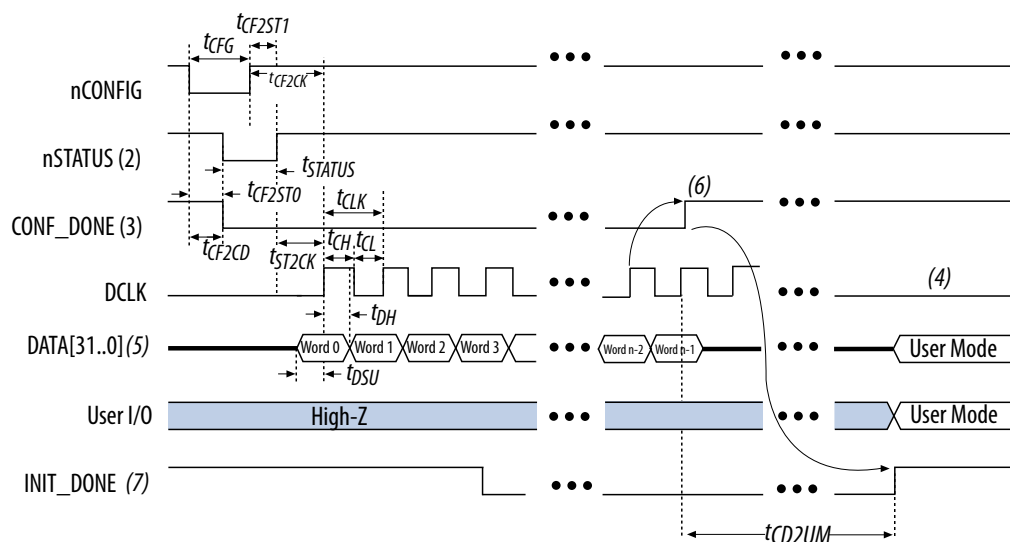
The memory output clock jitter is applicable when an input jitter of 30 ps peak-to-peak is applied with bit error rate (BER) -12, equivalent to 14 sigma.

Clock Network	Parameter	Symbol	C3, I3L		C4, I4		Unit
			Min	Max	Min	Max	
Regional	Clock period jitter	$t_{JIT(per)}$	-55	55	-55	55	ps
	Cycle-to-cycle period jitter	$t_{JIT(cc)}$	-110	110	-110	110	ps
	Duty cycle jitter	$t_{JIT(duty)}$	-82.5	82.5	-82.5	82.5	ps
Global	Clock period jitter	$t_{JIT(per)}$	-82.5	82.5	-82.5	82.5	ps
	Cycle-to-cycle period jitter	$t_{JIT(cc)}$	-165	165	-165	165	ps
	Duty cycle jitter	$t_{JIT(duty)}$	-90	90	-90	90	ps
PHY Clock	Clock period jitter	$t_{JIT(per)}$	-30	30	-35	35	ps
	Cycle-to-cycle period jitter	$t_{JIT(cc)}$	-60	60	-70	70	ps
	Duty cycle jitter	$t_{JIT(duty)}$	-45	45	-56	56	ps

## FPP Configuration Timing when DCLK to DATA[] = 1

Figure 2-7: FPP Configuration Timing Waveform When the DCLK-to-DATA[] Ratio is 1

Timing waveform for FPP configuration when using a MAX<sup>®</sup> II or MAX V device as an external host.

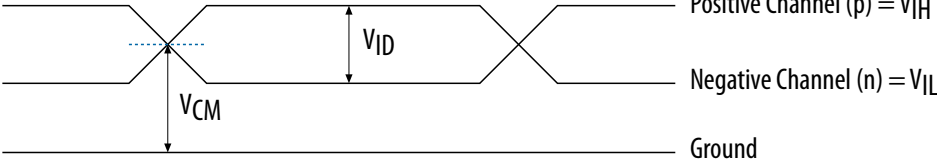



### Notes:

1. The beginning of this waveform shows the device in user mode. In user mode, nCONFIG, nSTATUS, and CONF\_DONE are at logic-high levels. When nCONFIG is pulled low, a reconfiguration cycle begins.
2. After power-up, the Arria V GZ device holds nSTATUS low for the time of the POR delay.
3. After power-up, before and during configuration, CONF\_DONE is low.
4. Do not leave DCLK floating after configuration. DCLK is ignored after configuration is complete. It can toggle high or low if required.
5. For FPP  $\times 16$ , use DATA[15..0]. For FPP  $\times 8$ , use DATA[7..0]. DATA[31..0] are available as a user I/O pin after configuration. The state of this pin depends on the dual-purpose pin settings.
6. To ensure a successful configuration, send the entire configuration data to the Arria V GZ device. CONF\_DONE is released high when the Arria V GZ device receives all the configuration data successfully. After CONF\_DONE goes high, send two additional falling edges on DCLK to begin initialization and enter user mode.
7. After the option bit to enable the INIT\_DONE pin is configured into the device, the INIT\_DONE goes low.

# Glossary

Table 2-68: Glossary

Term	Definition
Differential I/O Standards	<div>Receiver Input Waveforms</div> <div><div>Single-Ended Waveform</div><p>Positive Channel (p) = <math>V_{IH}</math></p><p>Negative Channel (n) = <math>V_{IL}</math></p><p>Ground</p></div> <div><div>Differential Waveform</div><p><math>p - n = 0V</math></p></div> <div>Transmitter Output Waveforms</div>

Term	Definition
$t_C$	High-speed receiver and transmitter input and output clock period.
TCCS (channel-to-channel-skew)	The timing difference between the fastest and slowest output edges, including $t_{CO}$ variation and clock skew, across channels driven by the same PLL. The clock is included in the TCCS measurement (refer to the Timing Diagram figure under SW in this table).
$t_{DUTY}$	High-speed I/O block—Duty cycle on the high-speed transmitter output clock.
$t_{FALL}$	Signal high-to-low transition time (80-20%)
$t_{INCCJ}$	Cycle-to-cycle jitter tolerance on the PLL clock input.
$t_{OUTPJ\_IO}$	Period jitter on the general purpose I/O driven by a PLL.
$t_{OUTPJ\_DC}$	Period jitter on the dedicated clock output driven by a PLL.
$t_{RISE}$	Signal low-to-high transition time (20-80%)
Timing Unit Interval (TUI)	The timing budget allowed for skew, propagation delays, and the data sampling window. ( $TUI = 1/(\text{receiver input clock frequency multiplication factor}) = t_C/w$ )
$V_{CM(DC)}$	DC common mode input voltage.
$V_{ICM}$	Input common mode voltage—The common mode of the differential signal at the receiver.
$V_{ID}$	Input differential voltage swing—The difference in voltage between the positive and complementary conductors of a differential transmission at the receiver.
$V_{DIF(AC)}$	AC differential input voltage—Minimum AC input differential voltage required for switching.
$V_{DIF(DC)}$	DC differential input voltage— Minimum DC input differential voltage required for switching.
$V_{IH}$	Voltage input high—The minimum positive voltage applied to the input which is accepted by the device as a logic high.
$V_{IH(AC)}$	High-level AC input voltage
$V_{IH(DC)}$	High-level DC input voltage
$V_{IL}$	Voltage input low—The maximum positive voltage applied to the input which is accepted by the device as a logic low.
$V_{IL(AC)}$	Low-level AC input voltage
$V_{IL(DC)}$	Low-level DC input voltage