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### **Understanding Embedded - FPGAs (Field Programmable Gate Array)**

Embedded - FPGAs, or Field Programmable Gate Arrays, are advanced integrated circuits that offer unparalleled flexibility and performance for digital systems. Unlike traditional fixed-function logic devices, FPGAs can be programmed and reprogrammed to execute a wide array of logical operations, enabling customized functionality tailored to specific applications. This reprogrammability allows developers to iterate designs quickly and implement complex functions without the need for custom hardware.

### **Applications of Embedded - FPGAs**

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications,

#### **Details**

Product Status	Obsolete
Number of LABs/CLBs	23780
Number of Logic Elements/Cells	504000
Total RAM Bits	27695104
Number of I/O	704
Number of Gates	-
Voltage - Supply	1.07V ~ 1.13V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	1517-BBGA
Supplier Device Package	1517-FBGA (40x40)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/intel/5agxmb7g4f40c4n">https://www.e-xfl.com/product-detail/intel/5agxmb7g4f40c4n</a>

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Parameter	Symbol	Condition	V <sub>CCIO</sub> (V)												Unit	
			1.2		1.5		1.8		2.5		3.0		3.3			
			Min	Max	Min	Max	Min	Max	Min	Max	Min	Max	Min	Max		
Bus-hold trip point	V <sub>TRIP</sub>	—	0.3	0.9	0.375	1.125	0.68	1.07	0.7	1.7	0.8	2	0.8	2	V	

### OCT Calibration Accuracy Specifications

If you enable on-chip termination (OCT) calibration, calibration is automatically performed at power up for I/Os connected to the calibration block.

**Table 1-8: OCT Calibration Accuracy Specifications for Arria V Devices**

Calibration accuracy for the calibrated on-chip series termination (R<sub>S</sub> OCT) and on-chip parallel termination (R<sub>T</sub> OCT) are applicable at the moment of calibration. When process, voltage, and temperature (PVT) conditions change after calibration, the tolerance may change.

Symbol	Description	Condition (V)	Calibration Accuracy			Unit
			-I3, -C4	-I5, -C5	-C6	
25-Ω R <sub>S</sub>	Internal series termination with calibration (25-Ω setting)	V <sub>CCIO</sub> = 3.0, 2.5, 1.8, 1.5, 1.2	±15	±15	±15	%
50-Ω R <sub>S</sub>	Internal series termination with calibration (50-Ω setting)	V <sub>CCIO</sub> = 3.0, 2.5, 1.8, 1.5, 1.2	±15	±15	±15	%
34-Ω and 40-Ω R <sub>S</sub>	Internal series termination with calibration (34-Ω and 40-Ω setting)	V <sub>CCIO</sub> = 1.5, 1.35, 1.25, 1.2	±15	±15	±15	%
48-Ω, 60-Ω, and 80-Ω R <sub>S</sub>	Internal series termination with calibration (48-Ω, 60-Ω, and 80-Ω setting)	V <sub>CCIO</sub> = 1.2	±15	±15	±15	%
50-Ω R <sub>T</sub>	Internal parallel termination with calibration (50-Ω setting)	V <sub>CCIO</sub> = 2.5, 1.8, 1.5, 1.2	-10 to +40	-10 to +40	-10 to +40	%
20-Ω, 30-Ω, 40-Ω, 60-Ω, and 120-Ω R <sub>T</sub>	Internal parallel termination with calibration (20-Ω, 30-Ω, 40-Ω, 60-Ω, and 120-Ω setting)	V <sub>CCIO</sub> = 1.5, 1.35, 1.25	-10 to +40	-10 to +40	-10 to +40	%

Symbol	Description	V <sub>CCIO</sub> (V)	Value	Unit
dR/dT	OCT variation with temperature without recalibration	3.0	0.189	%/°C
		2.5	0.208	
		1.8	0.266	
		1.5	0.273	
		1.35	0.200	
		1.25	0.200	
		1.2	0.317	

## Pin Capacitance

Table 1-11: Pin Capacitance for Arria V Devices

Symbol	Description	Maximum	Unit
C <sub>IOTB</sub>	Input capacitance on top/bottom I/O pins	6	pF
C <sub>IOLR</sub>	Input capacitance on left/right I/O pins	6	pF
C <sub>OUTFB</sub>	Input capacitance on dual-purpose clock output/feedback pins	6	pF
C <sub>IOVREF</sub>	Input capacitance on V <sub>REF</sub> pins	48	pF

## Hot Socketing

Table 1-12: Hot Socketing Specifications for Arria V Devices

Symbol	Description	Maximum	Unit
I <sub>IOPIN</sub> (DC)	DC current per I/O pin	300	µA
I <sub>IOPIN</sub> (AC)	AC current per I/O pin	8 <sup>(10)</sup>	mA
I <sub>XCVR-TX</sub> (DC)	DC current per transceiver transmitter (TX) pin	100	mA

Symbol/Description	Condition	Transceiver Speed Grade 4			Transceiver Speed Grade 6			Unit
		Min	Typ	Max	Min	Typ	Max	
Minimum differential eye opening at the receiver serial input pins <sup>(30)</sup>	—	100	—	—	100	—	—	mV
V <sub>ICM</sub> (AC coupled)	—	—	0.7/0.75/ 0.8 <sup>(31)</sup>	—	—	0.7/0.75/ 0.8 <sup>(31)</sup>	—	mV
V <sub>ICM</sub> (DC coupled)	≤ 3.2Gbps <sup>(32)</sup>	670	700	730	670	700	730	mV
Differential on-chip termination resistors	85-Ω setting	—	85	—	—	85	—	Ω
	100-Ω setting	—	100	—	—	100	—	Ω
	120-Ω setting	—	120	—	—	120	—	Ω
	150-Ω setting	—	150	—	—	150	—	Ω
t <sub>LTR</sub> <sup>(33)</sup>	—	—	—	10	—	—	10	μs
t <sub>LTD</sub> <sup>(34)</sup>	—	4	—	—	4	—	—	μs
t <sub>LTD_manual</sub> <sup>(35)</sup>	—	4	—	—	4	—	—	μs
t <sub>LTR_LTD_manual</sub> <sup>(36)</sup>	—	15	—	—	15	—	—	μs
Programmable ppm detector <sup>(37)</sup>	—	±62.5, 100, 125, 200, 250, 300, 500, and 1000						ppm

<sup>(30)</sup> The differential eye opening specification at the receiver input pins assumes that you have disabled the **Receiver Equalization** feature. If you enable the **Receiver Equalization** feature, the receiver circuitry can tolerate a lower minimum eye opening, depending on the equalization level.

<sup>(31)</sup> The AC coupled V<sub>ICM</sub> = 700 mV for Arria V GX and SX in PCIe mode only. The AC coupled V<sub>ICM</sub> = 750 mV for Arria V GT and ST in PCIe mode only.

<sup>(32)</sup> For standard protocol compliance, use AC coupling.

<sup>(33)</sup> t<sub>LTR</sub> is the time required for the receive CDR to lock to the input reference clock frequency after coming out of reset.

<sup>(34)</sup> t<sub>LTD</sub> is time required for the receiver CDR to start recovering valid data after the rx\_is\_lockedtodata signal goes high.

<sup>(35)</sup> t<sub>LTD\_manual</sub> is the time required for the receiver CDR to start recovering valid data after the rx\_is\_lockedtodata signal goes high when the CDR is functioning in the manual mode.

<sup>(36)</sup> t<sub>LTR\_LTD\_manual</sub> is the time the receiver CDR must be kept in lock to reference (LTR) mode after the rx\_is\_lockedtoref signal goes high when the CDR is functioning in the manual mode.

For example, when  $V_{OD} = 800$  mV, the corresponding  $V_{OD}$  value setting is 40. The following conditions show that the 1st post tap pre-emphasis setting = 2 is valid:

- $|B| + |C| \leq 60 \rightarrow 40 + 2 = 42$
- $|B| - |C| > 5 \rightarrow 40 - 2 = 38$
- $(V_{MAX}/V_{MIN} - 1)\% < 600\% \rightarrow (42/38 - 1)\% = 10.52\%$

To predict the pre-emphasis level for your specific data rate and pattern, run simulations using the Arria V HSSI HSPICE models.

**Table 1-33: Transmitter Pre-Emphasis Levels for Arria V Devices**

Quartus Prime 1st Post Tap Pre-Emphasis Setting	Quartus Prime $V_{OD}$ Setting							Unit
	10 (200 mV)	20 (400 mV)	30 (600 mV)	35 (700 mV)	40 (800 mV)	45 (900 mV)	50 (1000 mV)	
0	0	0	0	0	0	0	0	dB
1	1.97	0.88	0.43	0.32	0.24	0.19	0.13	dB
2	3.58	1.67	0.95	0.76	0.61	0.5	0.41	dB
3	5.35	2.48	1.49	1.2	1	0.83	0.69	dB
4	7.27	3.31	2	1.63	1.36	1.14	0.96	dB
5	—	4.19	2.55	2.1	1.76	1.49	1.26	dB
6	—	5.08	3.11	2.56	2.17	1.83	1.56	dB
7	—	5.99	3.71	3.06	2.58	2.18	1.87	dB
8	—	6.92	4.22	3.47	2.93	2.48	2.11	dB
9	—	7.92	4.86	4	3.38	2.87	2.46	dB
10	—	9.04	5.46	4.51	3.79	3.23	2.77	dB
11	—	10.2	6.09	5.01	4.23	3.61	—	dB
12	—	11.56	6.74	5.51	4.68	3.97	—	dB
13	—	12.9	7.44	6.1	5.12	4.36	—	dB
14	—	14.44	8.12	6.64	5.57	4.76	—	dB
15	—	—	8.87	7.21	6.06	5.14	—	dB

Protocol	Sub-protocol	Data Rate (Mbps)
Common Public Radio Interface (CPRI)	CPRI E6LV	614.4
	CPRI E6HV	614.4
	CPRI E6LVII	614.4
	CPRI E12LV	1,228.8
	CPRI E12HV	1,228.8
	CPRI E12LVII	1,228.8
	CPRI E24LV	2,457.6
	CPRI E24LVII	2,457.6
	CPRI E30LV	3,072
	CPRI E30LVII	3,072
	CPRI E48LVII	4,915.2
	CPRI E60LVII	6,144
Gbps Ethernet (GbE)	CPRI E96LVIII <sup>(60)</sup>	9,830.4
	GbE 1250	1,250
OBSAI	OBSAI 768	768
	OBSAI 1536	1,536
	OBSAI 3072	3,072
	OBSAI 6144	6,144
	SDI 270 SD	270
Serial digital interface (SDI)	SDI 1485 HD	1,485
	SDI 2970 3G	2,970

<sup>(60)</sup> You can achieve compliance with TX channel restriction of one HSSI channel per six-channel transceiver bank.

## HPS Clock Performance

**Table 1-48: HPS Clock Performance for Arria V Devices**

Symbol/Description	-I3	-C4	-C5, -I5	-C6	Unit
mpu_base_clk (microprocessor unit clock)	1050	925	800	700	MHz
main_base_clk (L3/L4 interconnect clock)	400	400	400	350	MHz
h2f_user0_clk	100	100	100	100	MHz
h2f_user1_clk	100	100	100	100	MHz
h2f_user2_clk	200	200	200	160	MHz

## HPS PLL Specifications

### HPS PLL VCO Frequency Range

**Table 1-49: HPS PLL VCO Frequency Range for Arria V Devices**

Description	Speed Grade	Minimum	Maximum	Unit
VCO range	-C5, -I5, -C6	320	1,600	MHz
	-C4	320	1,850	MHz
	-I3	320	2,100	MHz

### HPS PLL Input Clock Range

The HPS PLL input clock range is 10 – 50 MHz. This clock range applies to both HPS\_CLK1 and HPS\_CLK2 inputs.

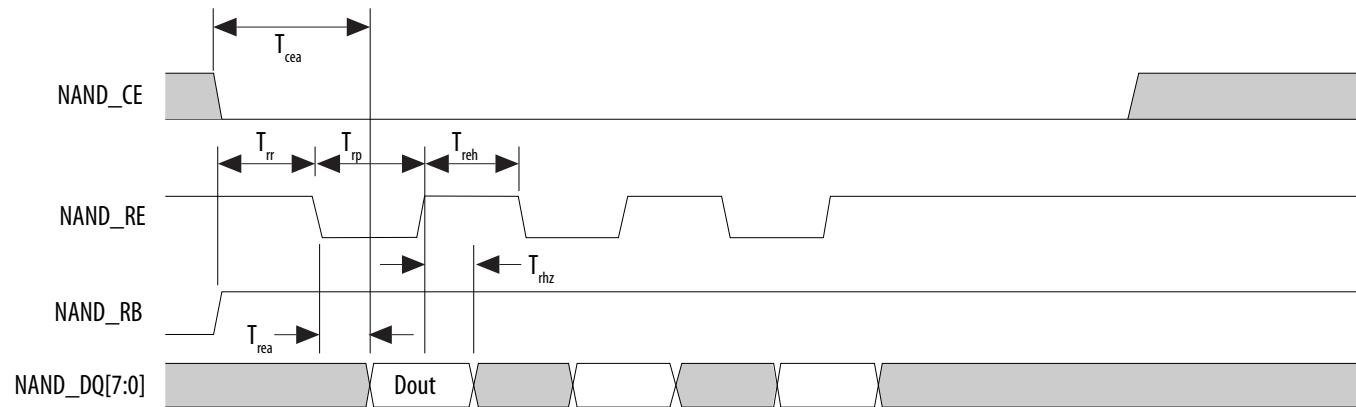
#### Related Information

##### [Clock Select, Booting and Configuration chapter](#)

Provides more information about the clock range for different values of clock select (CSEL).

Symbol	Description	Min	Max	Unit
$T_h$	SPI MISO hold time	1	—	ns
$T_{dutycycle}$	SPI_CLK duty cycle	45	55	%
$T_{dssfrst}$	Output delay SPI_SS valid before first clock edge	8	—	ns
$T_{dsslst}$	Output delay SPI_SS valid after last clock edge	8	—	ns
$T_{dio}$	Master-out slave-in (MOSI) output delay	-1	1	ns

<sup>(86)</sup> This value is based on `rx_sample_dly` = 1 and `spi_m_clk` = 120 MHz. `spi_m_clk` is the internal clock that is used by SPI Master to derive its `SCLK_OUT`. These timings are based on `rx_sample_dly` of 1. This delay can be adjusted as needed to accommodate slower response times from the slave. Note that a delay of 0 is not allowed. The setup time can be used as a reference starting point. It is very crucial to do a calibration to get the correct `rx_sample_dly` value because each SPI slave device may have different output delay and each application board may have different path delay. For more information about `rx_sample_delay`, refer to the SPI Controller chapter in the Hard Processor System Technical Reference Manual.

**Figure 1-20: NAND Data Read Timing Diagram**

## ARM Trace Timing Characteristics

**Table 1-61: ARM Trace Timing Requirements for Arria V Devices**

Most debugging tools have a mechanism to adjust the capture point of trace data.

Description	Min	Max	Unit
CLK clock period	12.5	—	ns
CLK maximum duty cycle	45	55	%
CLK to D0 –D7 output data delay	-1	1	ns

## UART Interface

The maximum UART baud rate is 6.25 megasymbols per second.

## GPIO Interface

The minimum detectable general-purpose I/O (GPIO) pulse width is 2  $\mu$ s. The pulse width is based on a debounce clock frequency of 1 MHz.

Date	Version	Changes
December 2015	2015.12.16	<ul style="list-style-type: none"><li>• Updated Quad Serial Peripheral Interface (SPI) Flash Timing Requirements for Arria V Devices table.<ul style="list-style-type: none"><li>• Updated <math>F_{clk}</math>, <math>T_{dutycycle}</math>, and <math>T_{dssfrst}</math> specifications.</li><li>• Added <math>T_{qspi_clk}</math>, <math>T_{din_start}</math>, and <math>T_{din_end}</math> specifications.</li><li>• Removed <math>T_{dinmax}</math> specifications.</li></ul></li><li>• Updated the minimum specification for <math>T_{clk}</math> to 16.67 ns and removed the maximum specification in SPI Master Timing Requirements for Arria V Devices table.</li><li>• Updated Secure Digital (SD)/MultiMediaCard (MMC) Timing Requirements for Arria V Devices table.<ul style="list-style-type: none"><li>• Updated <math>T_{clk}</math> to <math>T_{sdmmc_clk\_out}</math> symbol.</li><li>• Updated <math>T_{sdmmc_clk\_out}</math> and <math>T_d</math> specifications.</li><li>• Added <math>T_{sdmmc_clk}</math>, <math>T_{su}</math>, and <math>T_h</math> specifications.</li><li>• Removed <math>T_{dinmax}</math> specifications.</li></ul></li><li>• Updated the following diagrams:<ul style="list-style-type: none"><li>• Quad SPI Flash Timing Diagram</li><li>• SD/MMC Timing Diagram</li></ul></li><li>• Updated configuration .rbf sizes for Arria V devices.</li><li>• Changed instances of <i>Quartus II</i> to <i>Quartus Prime</i>.</li></ul>

Symbol	Description	Condition	Minimum <sup>(114)</sup>	Typical	Maximum <sup>(114)</sup>	Unit
V <sub>I</sub>	DC input voltage	—	-0.5	—	3.6	V
V <sub>O</sub>	Output voltage	—	0	—	V <sub>CCIO</sub>	V
T <sub>J</sub>	Operating junction temperature	Commercial	0	—	85	°C
		Industrial	-40	—	100	°C
t <sub>RAMP</sub>	Power supply ramp time	Standard POR	200 µs	—	100 ms	—
		Fast POR	200 µs	—	4 ms	—

### Recommended Transceiver Power Supply Operating Conditions

**Table 2-6: Recommended Transceiver Power Supply Operating Conditions for Arria V GZ Devices**

Symbol	Description	Minimum <sup>(118)</sup>	Typical	Maximum <sup>(118)</sup>	Unit
V <sub>CCA_GXBL</sub> <sup>(119), (120)</sup>	Transceiver channel PLL power supply (left side)	2.85	3.0	3.15	V
		2.375	2.5	2.625	
V <sub>CCA_GXBR</sub> <sup>(119), (120)</sup>	Transceiver channel PLL power supply (right side)	2.85	3.0	3.15	V
		2.375	2.5	2.625	
V <sub>CCHIP_L</sub>	Transceiver hard IP power supply (left side)	0.82	0.85	0.88	V
V <sub>CCHSSI_L</sub>	Transceiver PCS power supply (left side)	0.82	0.85	0.88	V
V <sub>CCHSSI_R</sub>	Transceiver PCS power supply (right side)	0.82	0.85	0.88	V

<sup>(114)</sup> The power supply value describes the budget for the DC (static) power supply tolerance and does not include the dynamic tolerance requirements. Refer to the PDN tool for the additional budget for the dynamic tolerance requirements.

<sup>(118)</sup> This value describes the budget for the DC (static) power supply tolerance and does not include the dynamic tolerance requirements. Refer to the PDN tool for the additional budget for the dynamic tolerance requirements.

<sup>(119)</sup> This supply must be connected to 3.0 V if the CMU PLL, receiver CDR, or both, are configured at a base data rate > 6.5 Gbps. Up to 6.5 Gbps, you can connect this supply to either 3.0 V or 2.5 V.

<sup>(120)</sup> When using ATX PLLs, the supply must be 3.0 V.

### Related Information

- [PowerPlay Early Power Estimator User Guide](#)

For more information about the EPE tool.

- [PowerPlay Power Analysis](#)

For more information about PowerPlay power analysis.

### Power Consumption

Altera offers two ways to estimate power consumption for a design—the Excel-based Early Power Estimator and the Quartus II PowerPlay Power Analyzer feature.

**Note:** You typically use the interactive Excel-based Early Power Estimator before designing the FPGA to get a magnitude estimate of the device power. The Quartus II PowerPlay Power Analyzer provides better quality estimates based on the specifics of the design after you complete place-and-route. The PowerPlay Power Analyzer can apply a combination of user-entered, simulation-derived, and estimated signal activities that, when combined with detailed circuit models, yields very accurate power estimates.

### Related Information

- [PowerPlay Early Power Estimator User Guide](#)

For more information about the EPE tool.

- [PowerPlay Power Analysis](#)

For more information about PowerPlay power analysis.

### I/O Pin Leakage Current

**Table 2-8: I/O Pin Leakage Current for Arria V GZ Devices**

If  $V_O = V_{CCIO}$  to  $V_{CCIOMax}$ , 100  $\mu A$  of leakage current per I/O is expected.

Symbol	Description	Conditions	Min	Typ	Max	Unit
$I_I$	Input pin	$V_I = 0 \text{ V to } V_{CCIOMAX}$	-30	—	30	$\mu A$
$I_{OZ}$	Tri-stated I/O pin	$V_O = 0 \text{ V to } V_{CCIOMAX}$	-30	—	30	$\mu A$

Symbol	Description	Conditions	Calibration Accuracy		Unit
			C3, I3L	C4, I4	
25- $\Omega$ R <sub>S</sub>	Internal series termination with calibration (25- $\Omega$ setting)	V <sub>CCIO</sub> = 3.0, 2.5, 1.8, 1.5, 1.2 V	$\pm 15$	$\pm 15$	%
50- $\Omega$ R <sub>S</sub>	Internal series termination with calibration (50- $\Omega$ setting)	V <sub>CCIO</sub> = 3.0, 2.5, 1.8, 1.5, 1.2 V	$\pm 15$	$\pm 15$	%
34- $\Omega$ and 40- $\Omega$ R <sub>S</sub>	Internal series termination with calibration (34- $\Omega$ and 40- $\Omega$ setting)	V <sub>CCIO</sub> = 1.5, 1.35, 1.25, 1.2 V	$\pm 15$	$\pm 15$	%
48- $\Omega$ , 60- $\Omega$ , 80- $\Omega$ , and 240- $\Omega$ R <sub>S</sub>	Internal series termination with calibration (48- $\Omega$ , 60- $\Omega$ , 80- $\Omega$ , and 240- $\Omega$ setting)	V <sub>CCIO</sub> = 1.2 V	$\pm 15$	$\pm 15$	%
50- $\Omega$ R <sub>T</sub>	Internal parallel termination with calibration (50- $\Omega$ setting)	V <sub>CCIO</sub> = 2.5, 1.8, 1.5, 1.2 V	-10 to +40	-10 to +40	%
20- $\Omega$ , 30- $\Omega$ , 40- $\Omega$ , 60- $\Omega$ , and 120- $\Omega$ R <sub>T</sub>	Internal parallel termination with calibration (20- $\Omega$ , 30- $\Omega$ , 40- $\Omega$ , 60- $\Omega$ , and 120- $\Omega$ setting)	V <sub>CCIO</sub> = 1.5, 1.35, 1.25 V	-10 to +40	-10 to +40	%
60- $\Omega$ and 120- $\Omega$ R <sub>T</sub>	Internal parallel termination with calibration (60- $\Omega$ and 120- $\Omega$ setting)	V <sub>CCIO</sub> = 1.2	-10 to +40	-10 to +40	%
25- $\Omega$ R <sub>S_left_shift</sub>	Internal left shift series termination with calibration (25- $\Omega$ R <sub>S_left_shift</sub> setting)	V <sub>CCIO</sub> = 3.0, 2.5, 1.8, 1.5, 1.2 V	$\pm 15$	$\pm 15$	%

Table 2-11: OCT Without Calibration Resistance Tolerance Specifications for Arria V GZ Devices

Symbol	Description	Conditions	Resistance Tolerance		Unit
			C3, I3L	C4, I4	
25- $\Omega$ R, 50- $\Omega$ R <sub>S</sub>	Internal series termination without calibration (25- $\Omega$ setting)	V <sub>CCIO</sub> = 3.0 and 2.5 V	$\pm 40$	$\pm 40$	%

Clock Network	ATX PLL			CMU PLL <sup>(161)</sup>			fPLL		
	Non-bonded Mode (Gbps)	Bonded Mode (Gbps)	Channel Span	Non-bonded Mode (Gbps)	Bonded Mode (Gbps)	Channel Span	Non-bonded Mode (Gbps)	Bonded Mode (Gbps)	Channel Span
xN (PCIe)	—	8.0	8	—	5.0	8	—	—	—
xN (Native PHY IP)	8.0	8.0	Up to 13 channels above and below PLL	7.99	7.99	Up to 13 channels above and below PLL	3.125	3.125	Up to 13 channels above and below PLL
	—	8.01 to 9.8304	Up to 7 channels above and below PLL						

## Standard PCS Data Rate

**Table 2-30: Standard PCS Approximate Maximum Date Rate (Gbps) for Arria V GZ Devices**

The maximum data rate is also constrained by the transceiver speed grade. Refer to the “Commercial and Industrial Speed Grade Offering for Arria V GZ Devices” table for the transceiver speed grade.

Mode <sup>(164)</sup>	Transceiver Speed Grade	PMA Width	20	20	16	16	10	10	8	8
		PCS/Core Width	40	20	32	16	20	10	16	8
FIFO	2	C3, I3L core speed grade	9.9	9	7.84	7.2	5.3	4.7	4.24	3.76
	3	C4, I4 core speed grade	8.8	8.2	7.2	6.56	4.8	4.3	3.84	3.44

<sup>(161)</sup> ATX PLL is recommended at 8 Gbps and above data rates for improved jitter performance.

<sup>(164)</sup> The Phase Compensation FIFO can be configured in FIFO mode or register mode. In the FIFO mode, the pointers are not fixed, and the latency can vary. In the register mode the pointers are fixed for low latency.

Symbol	Parameter	Min	Typ	Max	Unit
$f_{OUT}^{(169)}$	Output frequency for an internal global or regional clock (C3, I3L speed grade)	—	—	650	MHz
	Output frequency for an internal global or regional clock (C4, I4 speed grade)	—	—	580	MHz
$f_{OUT\_EXT}^{(169)}$	Output frequency for an external clock output (C3, I3L speed grade)	—	—	667	MHz
	Output frequency for an external clock output (C4, I4 speed grade)	—	—	533	MHz
$t_{OUTDUTY}$	Duty cycle for a dedicated external clock output (when set to 50%)	45	50	55	%
$t_{FCOMP}$	External feedback clock compensation time	—	—	10	ns
$f_{DYCONFIGCLK}$	Dynamic configuration clock for <code>mgmt_clk</code> and <code>scanclk</code>	—	—	100	MHz
$t_{LOCK}$	Time required to lock from the end-of-device configuration or deassertion of <code>areset</code>	—	—	1	ms
$t_{DLOCK}$	Time required to lock dynamically (after switchover or reconfiguring any non-post-scale counters/delays)	—	—	1	ms
$f_{CLBW}$	PLL closed-loop low bandwidth	—	0.3	—	MHz
	PLL closed-loop medium bandwidth	—	1.5	—	MHz
	PLL closed-loop high bandwidth <sup>(170)</sup>	—	4	—	MHz
$t_{PLL\_PSERR}$	Accuracy of PLL phase shift	—	—	$\pm 50$	ps
$t_{ARESET}$	Minimum pulse width on the <code>areset</code> signal	10	—	—	ns

<sup>(169)</sup> This specification is limited by the lower of the two: I/O  $f_{MAX}$  or  $f_{OUT}$  of the PLL.

<sup>(170)</sup> High bandwidth PLL settings are not supported in external feedback mode.

Memory	Mode	Resources Used		Performance				Unit
		ALUTs	Memory	C3	C4	I3L	I4	
M20K Block	Single-port, all supported widths	0	1	650	550	500	450	MHz
	Simple dual-port, all supported widths	0	1	650	550	500	450	MHz
	Simple dual-port with the read-during-write option set to <b>Old Data</b> , all supported widths	0	1	455	400	455	400	MHz
	Simple dual-port with ECC enabled, $512 \times 32$	0	1	400	350	400	350	MHz
	Simple dual-port with ECC and optional pipeline registers enabled, $512 \times 32$	0	1	500	450	500	450	MHz
	True dual port, all supported widths	0	1	650	550	500	450	MHz
	ROM, all supported widths	0	1	650	550	500	450	MHz

## Temperature Sensing Diode Specifications

Table 2-37: Internal Temperature Sensing Diode Specification

Temperature Range	Accuracy	Offset Calibrated Option	Sampling Rate	Conversion Time	Resolution	Minimum Resolution with no Missing Codes
-40°C to 100°C	±8°C	No	1 MHz, 500 kHz	< 100 ms	8 bits	8 bits

Table 2-38: External Temperature Sensing Diode Specifications for Arria V GZ Devices

Description	Min	Typ	Max	Unit
$I_{bias}$ , diode source current	8	—	200	µA
$V_{bias}$ , voltage across diode	0.3	—	0.9	V
Series resistance	—	—	< 1	Ω

## JTAG Configuration Specifications

**Table 2-54: JTAG Timing Parameters and Values for Arria V GZ Devices**

Symbol	Description	Min	Max	Unit
$t_{JCP}$	TCK clock period	30	—	ns
$t_{JCP}$	TCK clock period	167 <sup>(203)</sup>	—	ns
$t_{JCH}$	TCK clock high time	14	—	ns
$t_{JCL}$	TCK clock low time	14	—	ns
$t_{JPSU}$ (TDI)	TDI JTAG port setup time	2	—	ns
$t_{JPSU}$ (TMS)	TMS JTAG port setup time	3	—	ns
$t_{JPXH}$	JTAG port hold time	5	—	ns
$t_{JPXO}$	JTAG port clock to output	—	11 <sup>(204)</sup>	ns
$t_{JPZX}$	JTAG port high impedance to valid output	—	14 <sup>(204)</sup>	ns
$t_{JPXZ}$	JTAG port valid output to high impedance	—	14 <sup>(204)</sup>	ns

## Fast Passive Parallel (FPP) Configuration Timing

### DCLK-to-DATA[] Ratio (r) for FPP Configuration

FPP configuration requires a different DCLK-to-DATA[ ] ratio when you turn on encryption or the compression feature.

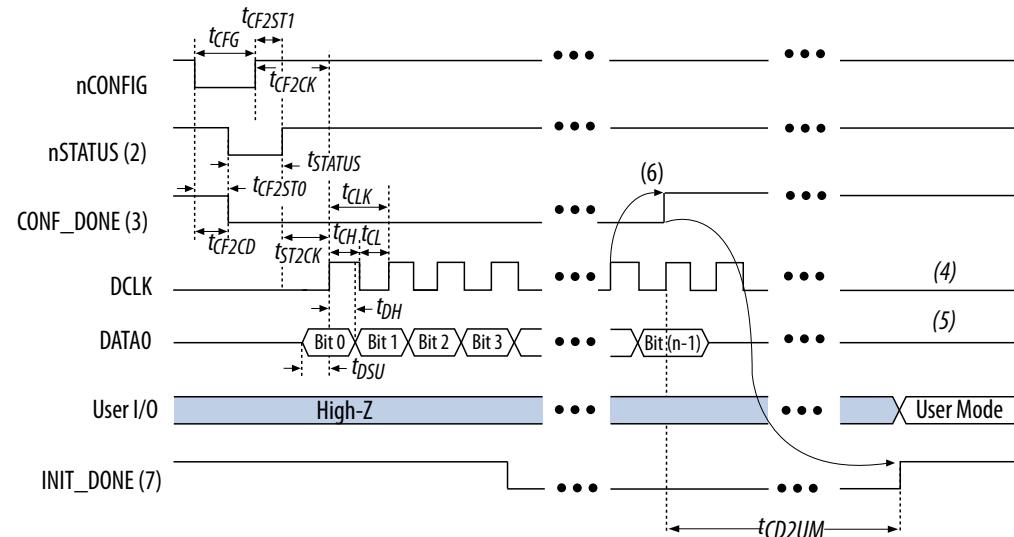
<sup>(203)</sup> The minimum TCK clock period is 167 ns if VCCBAT is within the range 1.2V-1.5V when you perform the volatile key programming.

<sup>(204)</sup> A 1-ns adder is required for each V<sub>CCIO</sub> voltage step down from 3.0 V. For example,  $t_{JPXO} = 12$  ns if V<sub>CCIO</sub> of the TDO I/O bank = 2.5 V, or 13 ns if it equals 1.8 V.

## Passive Serial Configuration Timing

Figure 2-10: PS Configuration Timing Waveform

Timing waveform for a passive serial (PS) configuration when using a MAX II device, MAX V device, or microprocessor as an external host.



### Notes:

1. The beginning of this waveform shows the device in user mode. In user mode, nCONFIG, nSTATUS, and CONF\_DONE are at logic high levels. When nCONFIG is pulled low, a reconfiguration cycle begins.
2. After power-up, the Arria V GZ device holds nSTATUS low for the time of the POR delay.
3. After power-up, before and during configuration, CONF\_DONE is low.
4. Do not leave DCLK floating after configuration. DCLK is ignored after configuration is complete.  
It can toggle high or low if required.
5. DATA0 is available as a user I/O pin after configuration. The state of this pin depends on the dual-purpose pin settings in the Device and Pins Option.
6. To ensure a successful configuration, send the entire configuration data to the Arria V GZ device. CONF\_DONE is released high after the Arria V GZ device receives all the configuration data successfully. After CONF\_DONE goes high, send two additional falling edges on DCLK to begin initialization and enter user mode.
7. After the option bit to enable the INIT\_DONE pin is configured into the device, the INIT\_DONE goes low.

# Glossary

Table 2-68: Glossary

Term	Definition
Differential I/O Standards	<p>Receiver Input Waveforms</p> <p><b>Single-Ended Waveform</b></p> <p>Positive Channel (p) = <math>V_{IH}</math></p> <p>Negative Channel (n) = <math>V_{IL}</math></p> <p>Ground</p> <p><b>Differential Waveform</b></p> <p><math>V_{ID}</math></p> <p><math>p - n = 0 V</math></p>
	<p>Transmitter Output Waveforms</p>

Term	Definition
$t_C$	High-speed receiver and transmitter input and output clock period.
TCCS (channel-to-channel-skew)	The timing difference between the fastest and slowest output edges, including $t_{CO}$ variation and clock skew, across channels driven by the same PLL. The clock is included in the TCCS measurement (refer to the Timing Diagram figure under SW in this table).
$t_{DUTY}$	High-speed I/O block—Duty cycle on the high-speed transmitter output clock.
$t_{FALL}$	Signal high-to-low transition time (80-20%)
$t_{INCCJ}$	Cycle-to-cycle jitter tolerance on the PLL clock input.
$t_{OUTPJ\_IO}$	Period jitter on the general purpose I/O driven by a PLL.
$t_{OUTPJ\_DC}$	Period jitter on the dedicated clock output driven by a PLL.
$t_{RISE}$	Signal low-to-high transition time (20-80%)
Timing Unit Interval (TUI)	The timing budget allowed for skew, propagation delays, and the data sampling window. ( $TUI = 1/(receiver\ input\ clock\ frequency\ multiplication\ factor) = t_C/w$ )
$V_{CM(DC)}$	DC common mode input voltage.
$V_{ICM}$	Input common mode voltage—The common mode of the differential signal at the receiver.
$V_{ID}$	Input differential voltage swing—The difference in voltage between the positive and complementary conductors of a differential transmission at the receiver.
$V_{DIF(AC)}$	AC differential input voltage—Minimum AC input differential voltage required for switching.
$V_{DIF(DC)}$	DC differential input voltage— Minimum DC input differential voltage required for switching.
$V_{IH}$	Voltage input high—The minimum positive voltage applied to the input which is accepted by the device as a logic high.
$V_{IH(AC)}$	High-level AC input voltage
$V_{IH(DC)}$	High-level DC input voltage
$V_{IL}$	Voltage input low—The maximum positive voltage applied to the input which is accepted by the device as a logic low.
$V_{IL(AC)}$	Low-level AC input voltage
$V_{IL(DC)}$	Low-level DC input voltage