# E: Lattice Semiconductor Corporation - LFE3-150EA-6FN672C Datasheet



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#### **Applications of Embedded - FPGAs**

The versatility of Embedded - FPGAs makes them indispensable in numerous fields. In telecommunications.

#### Details

Product Status	Active
Number of LABs/CLBs	18625
Number of Logic Elements/Cells	149000
Total RAM Bits	7014400
Number of I/O	380
Number of Gates	-
Voltage - Supply	1.14V ~ 1.26V
Mounting Type	Surface Mount
Operating Temperature	0°C ~ 85°C (TJ)
Package / Case	672-BBGA
Supplier Device Package	672-FPBGA (27x27)
Purchase URL	https://www.e-xfl.com/product-detail/lattice-semiconductor/lfe3-150ea-6fn672c

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#### Table 2-6. Secondary Clock Regions

Device	Number of Secondary Clock Regions
ECP3-17	16
ECP3-35	16
ECP3-70	20
ECP3-95	20
ECP3-150	36





Spine Repeaters



#### Figure 2-31. MULTADDSUBSUM Slice 1



# Advanced sysDSP Slice Features

#### Cascading

The LatticeECP3 sysDSP slice has been enhanced to allow cascading. Adder trees are implemented fully in sys-DSP slices, improving the performance. Cascading of slices uses the signals CIN, COUT and C Mux of the slice.

## Addition

The LatticeECP3 sysDSP slice allows for the bypassing of multipliers and cascading of adder logic. High performance adder functions are implemented without the use of LUTs. The maximum width adders that can be implemented are 54-bit.

## Rounding

The rounding operation is implemented in the ALU and is done by adding a constant followed by a truncation operation. The rounding methods supported are:

- Rounding to zero (RTZ)
- Rounding to infinity (RTI)
- Dynamic rounding
- Random rounding
- Convergent rounding



Two adjacent PIOs can be joined to provide a differential I/O pair (labeled as "T" and "C") as shown in Figure 2-32. The PAD Labels "T" and "C" distinguish the two PIOs. Approximately 50% of the PIO pairs on the left and right edges of the device can be configured as true LVDS outputs. All I/O pairs can operate as LVDS inputs.

#### Table 2-11. PIO Signal List

Name	Туре	Description
INDD	Input Data	Register bypassed input. This is not the same port as INCK.
IPA, INA, IPB, INB	Input Data	Ports to core for input data
OPOSA, ONEGA <sup>1</sup> , OPOSB, ONEGB <sup>1</sup>	Output Data	Output signals from core. An exception is the ONEGB port, used for tristate logic at the DQS pad.
CE	PIO Control	Clock enables for input and output block flip-flops.
SCLK	PIO Control	System Clock (PCLK) for input and output/TS blocks. Connected from clock ISB.
LSR	PIO Control	Local Set/Reset
ECLK1, ECLK2	PIO Control	Edge clock sources. Entire PIO selects one of two sources using mux.
ECLKDQSR <sup>1</sup>	Read Control	From DQS_STROBE, shifted strobe for memory interfaces only.
DDRCLKPOL <sup>1</sup>	Read Control	Ensures transfer from DQS domain to SCLK domain.
DDRLAT <sup>1</sup>	Read Control	Used to guarantee INDDRX2 gearing by selectively enabling a D-Flip-Flop in dat- apath.
DEL[3:0]	Read Control	Dynamic input delay control bits.
INCK	To Clock Distribution and PLL	PIO treated as clock PIO, path to distribute to primary clocks and PLL.
TS	Tristate Data	Tristate signal from core (SDR)
DQCLK0 <sup>1</sup> , DQCLK1 <sup>1</sup>	Write Control	Two clocks edges, 90 degrees out of phase, used in output gearing.
DQSW <sup>2</sup>	Write Control	Used for output and tristate logic at DQS only.
DYNDEL[7:0]	Write Control	Shifting of write clocks for specific DQS group, using 6:0 each step is approxi- mately 25ps, 128 steps. Bit 7 is an invert (timing depends on input frequency). There is also a static control for this 8-bit setting, enabled with a memory cell.
DCNTL[6:0]	PIO Control	Original delay code from DDR DLL
DATAVALID <sup>1</sup>	Output Data	Status flag from DATAVALID logic, used to indicate when input data is captured in IOLOGIC and valid to core.
READ	For DQS_Strobe	Read signal for DDR memory interface
DQSI	For DQS_Strobe	Unshifted DQS strobe from input pad
PRMBDET	For DQS_Strobe	DQSI biased to go high when DQSI is tristate, goes to input logic block as well as core logic.
GSRN	Control from routing	Global Set/Reset

1. Signals available on left/right/top edges only.

2. Selected PIO.

# PIO

The PIO contains four blocks: an input register block, output register block, tristate register block and a control logic block. These blocks contain registers for operating in a variety of modes along with the necessary clock and selection logic.

## Input Register Block

The input register blocks for the PIOs, in the left, right and top edges, contain delay elements and registers that can be used to condition high-speed interface signals, such as DDR memory interfaces and source synchronous interfaces, before they are passed to the device core. Figure 2-33 shows the input register block for the left, right and top edges. The input register block for the bottom edge contains one element to register the input signal and no DDR registers. The following description applies to the input register block for PIOs in the left, right and top edges only.



#### SCI (SERDES Client Interface) Bus

The SERDES Client Interface (SCI) is an IP interface that allows the SERDES/PCS Quad block to be controlled by registers rather than the configuration memory cells. It is a simple register configuration interface that allows SERDES/PCS configuration without power cycling the device.

The Diamond and ispLEVER design tools support all modes of the PCS. Most modes are dedicated to applications associated with a specific industry standard data protocol. Other more general purpose modes allow users to define their own operation. With these tools, the user can define the mode for each quad in a design.

Popular standards such as 10Gb Ethernet, x4 PCI Express and 4x Serial RapidIO can be implemented using IP (available through Lattice), a single quad (Four SERDES channels and PCS) and some additional logic from the core.

The LatticeECP3 family also supports a wide range of primary and secondary protocols. Within the same quad, the LatticeECP3 family can support mixed protocols with semi-independent clocking as long as the required clock frequencies are integer x1, x2, or x11 multiples of each other. Table 2-15 lists the allowable combination of primary and secondary protocol combinations.

# Flexible Quad SERDES Architecture

The LatticeECP3 family SERDES architecture is a quad-based architecture. For most SERDES settings and standards, the whole quad (consisting of four SERDES) is treated as a unit. This helps in silicon area savings, better utilization and overall lower cost.

However, for some specific standards, the LatticeECP3 quad architecture provides flexibility; more than one standard can be supported within the same quad.

Table 2-15 shows the standards can be mixed and matched within the same quad. In general, the SERDES standards whose nominal data rates are either the same or a defined subset of each other, can be supported within the same quad. In Table 2-15, the Primary Protocol column refers to the standard that determines the reference clock and PLL settings. The Secondary Protocol column shows the other standard that can be supported within the same quad.

Furthermore, Table 2-15 also implies that more than two standards in the same quad can be supported, as long as they conform to the data rate and reference clock requirements. For example, a quad may contain PCI Express 1.1, SGMII, Serial RapidIO Type I and Serial RapidIO Type II, all in the same quad.

#### Table 2-15. LatticeECP3 Primary and Secondary Protocol Support

Primary Protocol	Secondary Protocol
PCI Express 1.1	SGMII
PCI Express 1.1	Gigabit Ethernet
PCI Express 1.1	Serial RapidIO Type I
PCI Express 1.1	Serial RapidIO Type II
Serial RapidIO Type I	SGMII
Serial RapidIO Type I	Gigabit Ethernet
Serial RapidIO Type II	SGMII
Serial RapidIO Type II	Gigabit Ethernet
Serial RapidIO Type II	Serial RapidIO Type I
CPRI-3	CPRI-2 and CPRI-1
3G-SDI	HD-SDI and SD-SDI



## **Enhanced Configuration Options**

LatticeECP3 devices have enhanced configuration features such as: decryption support, TransFR™ I/O and dualboot image support.

#### 1. TransFR (Transparent Field Reconfiguration)

TransFR I/O (TFR) is a unique Lattice technology that allows users to update their logic in the field without interrupting system operation using a single ispVM command. TransFR I/O allows I/O states to be frozen during device configuration. This allows the device to be field updated with a minimum of system disruption and downtime. See TN1087, Minimizing System Interruption During Configuration Using TransFR Technology for details.

#### 2. Dual-Boot Image Support

Dual-boot images are supported for applications requiring reliable remote updates of configuration data for the system FPGA. After the system is running with a basic configuration, a new boot image can be downloaded remotely and stored in a separate location in the configuration storage device. Any time after the update the LatticeECP3 can be re-booted from this new configuration file. If there is a problem, such as corrupt data during download or incorrect version number with this new boot image, the LatticeECP3 device can revert back to the original backup golden configuration and try again. This all can be done without power cycling the system. For more information, please see TN1169, LatticeECP3 sysCONFIG Usage Guide.

## Soft Error Detect (SED) Support

LatticeECP3 devices have dedicated logic to perform Cycle Redundancy Code (CRC) checks. During configuration, the configuration data bitstream can be checked with the CRC logic block. In addition, the LatticeECP3 device can also be programmed to utilize a Soft Error Detect (SED) mode that checks for soft errors in configuration SRAM. The SED operation can be run in the background during user mode. If a soft error occurs, during user mode (normal operation) the device can be programmed to generate an error signal.

For further information on SED support, please see TN1184, LatticeECP3 Soft Error Detection (SED) Usage Guide.

#### **External Resistor**

LatticeECP3 devices require a single external, 10 kOhm  $\pm$ 1% value between the XRES pin and ground. Device configuration will not be completed if this resistor is missing. There is no boundary scan register on the external resistor pad.

## **On-Chip Oscillator**

Every LatticeECP3 device has an internal CMOS oscillator which is used to derive a Master Clock (MCCLK) for configuration. The oscillator and the MCCLK run continuously and are available to user logic after configuration is completed. The software default value of the MCCLK is nominally 2.5 MHz. Table 2-16 lists all the available MCCLK frequencies. When a different Master Clock is selected during the design process, the following sequence takes place:

- 1. Device powers up with a nominal Master Clock frequency of 3.1 MHz.
- 2. During configuration, users select a different master clock frequency.
- 3. The Master Clock frequency changes to the selected frequency once the clock configuration bits are received.
- 4. If the user does not select a master clock frequency, then the configuration bitstream defaults to the MCCLK frequency of 2.5 MHz.

This internal 130 MHz +/- 15% CMOS oscillator is available to the user by routing it as an input clock to the clock tree. For further information on the use of this oscillator for configuration or user mode, please see TN1169, LatticeECP3 sysCONFIG Usage Guide.



# SERDES Power Supply Requirements<sup>1, 2, 3</sup>

Symbol	Description	Тур.	Max.	Units
Standby (Power Do	own)	•		1
I <sub>CCA-SB</sub>	V <sub>CCA</sub> current (per channel)	3	5	mA
I <sub>CCIB-SB</sub>	Input buffer current (per channel)		—	mA
I <sub>CCOB-SB</sub>	Output buffer current (per channel)	—	_	mA
Operating (Data Ra	ite = 3.2 Gbps)		•	•
I <sub>CCA-OP</sub>	V <sub>CCA</sub> current (per channel)	68	77	mA
I <sub>CCIB-OP</sub>	Input buffer current (per channel)	5	7	mA
I <sub>CCOB-OP</sub>	Output buffer current (per channel)	19	25	mA
Operating (Data Ra	ite = 2.5 Gbps)	·		·
I <sub>CCA-OP</sub>	V <sub>CCA</sub> current (per channel)	66	76	mA
I <sub>CCIB-OP</sub>	Input buffer current (per channel)	4	5	mA
I <sub>CCOB-OP</sub>	Output buffer current (per channel)	15	18	mA
Operating (Data Ra	ite = 1.25 Gbps)			·
I <sub>CCA-OP</sub>	V <sub>CCA</sub> current (per channel)	62	72	mA
I <sub>CCIB-OP</sub>	Input buffer current (per channel)	4	5	mA
I <sub>CCOB-OP</sub>	Output buffer current (per channel)	15	18	mA
Operating (Data Ra	ite = 250 Mbps)	·		·
I <sub>CCA-OP</sub>	V <sub>CCA</sub> current (per channel)	55	65	mA
I <sub>CCIB-OP</sub>	Input buffer current (per channel)	4	5	mA
I <sub>CCOB-OP</sub>	Output buffer current (per channel)	14	17	mA
Operating (Data Ra	ite = 150 Mbps)	·		·
I <sub>CCA-OP</sub>	V <sub>CCA</sub> current (per channel)	55	65	mA
I <sub>CCIB-OP</sub>	Input buffer current (per channel)	4	5	mA
I <sub>CCOB-OP</sub>	Output buffer current (per channel)	14	17	mA

1. Equalization enabled, pre-emphasis disabled.

2. One quarter of the total quad power (includes contribution from common circuits, all channels in the quad operating, pre-emphasis disabled, equalization enabled).

3. Pre-emphasis adds 20 mA to ICCA-OP data.



#### Figure 3-8. Generic DDRX1/DDRX2 (With Clock Center on Data Window)





# LatticeECP3 Internal Switching Characteristics<sup>1, 2, 5</sup>

		-8 -7		7	-6			
Parameter	Description	Min.	Max.	Min.	Max.	Min.	Max.	Units.
PFU/PFF Logi	c Mode Timing							
t <sub>LUT4_PFU</sub>	LUT4 delay (A to D inputs to F output)	—	0.147	_	0.163	_	0.179	ns
t <sub>LUT6_PFU</sub>	LUT6 delay (A to D inputs to OFX output)	—	0.281		0.335	_	0.379	ns
t <sub>LSR_PFU</sub>	Set/Reset to output of PFU (Asynchronous)	—	0.593	—	0.674	—	0.756	ns
t <sub>LSRREC_PFU</sub>	Asynchronous Set/Reset recovery time for PFU Logic		0.298		0.345		0.391	ns
t <sub>SUM_PFU</sub>	Clock to Mux (M0,M1) Input Setup Time	0.134	_	0.144	_	0.153		ns
t <sub>HM_PFU</sub>	Clock to Mux (M0,M1) Input Hold Time	-0.097	_	-0.103	_	-0.109	_	ns
t <sub>SUD_PFU</sub>	Clock to D input setup time	0.061	_	0.068	_	0.075		ns
t <sub>HD_PFU</sub>	Clock to D input hold time	0.019	_	0.013	_	0.015		ns
t <sub>CK2Q_PFU</sub>	Clock to Q delay, (D-type Register Configuration)	_	0.243	_	0.273	_	0.303	ns
PFU Dual Port	Memory Mode Timing							
t <sub>CORAM_PFU</sub>	Clock to Output (F Port)	—	0.710	—	0.803	—	0.897	ns
t <sub>SUDATA_PFU</sub>	Data Setup Time	-0.137	_	-0.155	_	-0.174		ns
t <sub>HDATA_PFU</sub>	Data Hold Time	0.188	_	0.217	_	0.246	_	ns
t <sub>SUADDR_PFU</sub>	Address Setup Time	-0.227	_	-0.257	_	-0.286		ns
t <sub>HADDR_PFU</sub>	Address Hold Time	0.240	_	0.275	_	0.310	_	ns
t <sub>SUWREN_PFU</sub>	Write/Read Enable Setup Time	-0.055		-0.055	-	-0.063	_	ns
t <sub>HWREN_</sub> PFU	Write/Read Enable Hold Time	0.059	_	0.059	_	0.071	_	ns
PIC Timing								
PIO Input/Out	out Buffer Timing							
t <sub>IN_PIO</sub>	Input Buffer Delay (LVCMOS25)		0.423		0.466		0.508	ns
t <sub>OUT_PIO</sub>	Output Buffer Delay (LVCMOS25)	—	1.241	_	1.301	_	1.361	ns
IOLOGIC Inpu	IOLOGIC Input/Output Timing							
t <sub>SUI_PIO</sub>	Input Register Setup Time (Data Before Clock)	0.956		1.124		1.293		ns
t <sub>HI_PIO</sub>	Input Register Hold Time (Data after Clock)	0.225		0.184		0.240		ns
t <sub>COO_PIO</sub>	Output Register Clock to Output Delay <sup>4</sup>	-	1.09	-	1.16	-	1.23	ns
t <sub>SUCE_PIO</sub>	Input Register Clock Enable Setup Time	0.220	_	0.185	_	0.150	_	ns
t <sub>HCE_PIO</sub>	Input Register Clock Enable Hold Time	-0.085		-0.072		-0.058		ns
t <sub>SULSR_PIO</sub>	Set/Reset Setup Time	0.117	_	0.103	_	0.088	_	ns
t <sub>HLSR_PIO</sub>	Set/Reset Hold Time	-0.107	_	-0.094	_	-0.081	_	ns
EBR Timing								
t <sub>CO_EBR</sub>	Clock (Read) to output from Address or Data	—	2.78	—	2.89	—	2.99	ns
t <sub>COO_EBR</sub>	Clock (Write) to output from EBR output Register	—	0.31	—	0.32	—	0.33	ns
t <sub>SUDATA_EBR</sub>	Setup Data to EBR Memory	-0.218	_	-0.227	_	-0.237	_	ns
t <sub>HDATA_EBR</sub>	Hold Data to EBR Memory	0.249		0.257		0.265	—	ns
t <sub>SUADDR_EBR</sub>	Setup Address to EBR Memory	-0.071		-0.070		-0.068		ns
t <sub>HADDR_EBR</sub>	Hold Address to EBR Memory	0.118		0.098		0.077		ns
t <sub>SUWREN_EBR</sub>	Setup Write/Read Enable to EBR Memory	-0.107	_	-0.106	_	-0.106	—	ns

## **Over Recommended Commercial Operating Conditions**



# LatticeECP3 Maximum I/O Buffer Speed <sup>1, 2, 3, 4, 5, 6</sup>

#### **Over Recommended Operating Conditions**

Buffer	Description	Max.	Units
Maximum Input Frequency		·	
LVDS25	LVDS, $V_{CCIO} = 2.5 V$	400	MHz
MLVDS25	MLVDS, Emulated, V <sub>CCIO</sub> = 2.5 V	400	MHz
BLVDS25	BLVDS, Emulated, V <sub>CCIO</sub> = 2.5 V	400	MHz
PPLVDS	Point-to-Point LVDS	400	MHz
TRLVDS	Transition-Reduced LVDS	612	MHz
Mini LVDS	Mini LVDS	400	MHz
LVPECL33	LVPECL, Emulated, V <sub>CCIO</sub> = 3.3 V	400	MHz
HSTL18 (all supported classes)	HSTL_18 class I, II, V <sub>CCIO</sub> = 1.8 V	400	MHz
HSTL15	HSTL_15 class I, V <sub>CCIO</sub> = 1.5 V	400	MHz
SSTL33 (all supported classes)	SSTL_3 class I, II, V <sub>CCIO</sub> = 3.3 V	400	MHz
SSTL25 (all supported classes)	SSTL_2 class I, II, V <sub>CCIO</sub> = 2.5 V	400	MHz
SSTL18 (all supported classes)	SSTL_18 class I, II, V <sub>CCIO</sub> = 1.8 V	400	MHz
LVTTL33	LVTTL, V <sub>CCIO</sub> = 3.3 V	166	MHz
LVCMOS33	LVCMOS, V <sub>CCIO</sub> = 3.3 V	166	MHz
LVCMOS25	LVCMOS, V <sub>CCIO</sub> = 2.5 V	166	MHz
LVCMOS18	LVCMOS, V <sub>CCIO</sub> = 1.8 V	166	MHz
LVCMOS15	LVCMOS 1.5, V <sub>CCIO</sub> = 1.5 V	166	MHz
LVCMOS12	LVCMOS 1.2, V <sub>CCIO</sub> = 1.2 V	166	MHz
PCI33	PCI, V <sub>CCIO</sub> = 3.3 V	66	MHz
Maximum Output Frequency			
LVDS25E	LVDS, Emulated, V <sub>CCIO</sub> = 2.5 V	300	MHz
LVDS25	LVDS, $V_{CCIO} = 2.5 V$	612	MHz
MLVDS25	MLVDS, Emulated, V <sub>CCIO</sub> = 2.5 V	300	MHz
RSDS25	RSDS, Emulated, V <sub>CCIO</sub> = 2.5 V	612	MHz
BLVDS25	BLVDS, Emulated, V <sub>CCIO</sub> = 2.5 V	300	MHz
PPLVDS	Point-to-point LVDS	612	MHz
LVPECL33	LVPECL, Emulated, V <sub>CCIO</sub> = 3.3 V	612	MHz
Mini-LVDS	Mini LVDS	612	MHz
HSTL18 (all supported classes)	HSTL_18 class I, II, V <sub>CCIO</sub> = 1.8 V	200	MHz
HSTL15 (all supported classes)	HSTL_15 class I, V <sub>CCIO</sub> = 1.5 V	200	MHz
SSTL33 (all supported classes)	SSTL_3 class I, II, V <sub>CCIO</sub> = 3.3 V	233	MHz
SSTL25 (all supported classes)	SSTL_2 class I, II, V <sub>CCIO</sub> = 2.5 V	233	MHz
SSTL18 (all supported classes)	SSTL_18 class I, II, V <sub>CCIO</sub> = 1.8 V	266	MHz
LVTTL33	LVTTL, V <sub>CCIO</sub> = 3.3 V	166	MHz
LVCMOS33 (For all drives)	LVCMOS, 3.3 V	166	MHz
LVCMOS25 (For all drives)	LVCMOS, 2.5 V	166	MHz
LVCMOS18 (For all drives)	LVCMOS, 1.8 V	166	MHz
LVCMOS15 (For all drives)	LVCMOS, 1.5 V	166	MHz
LVCMOS12 (For all drives except 2 mA)	LVCMOS, V <sub>CCIO</sub> = 1.2 V	166	MHz
LVCMOS12 (2 mA drive)	LVCMOS, V <sub>CCIO</sub> = 1.2 V	100	MHz



#### Table 3-7. Channel Output Jitter

Description	Frequency	Min.	Тур.	Max.	Units
Deterministic	3.125 Gbps	—	—	0.17	UI, p-p
Random	3.125 Gbps	—	—	0.25	UI, p-p
Total	3.125 Gbps	—	—	0.35	UI, p-p
Deterministic	2.5 Gbps	—	—	0.17	UI, p-p
Random	2.5 Gbps	—	—	0.20	UI, p-p
Total	2.5 Gbps	—	—	0.35	UI, p-p
Deterministic	1.25 Gbps	—	—	0.10	UI, p-p
Random	1.25 Gbps	—	—	0.22	UI, p-p
Total	1.25 Gbps	—	—	0.24	UI, p-p
Deterministic	622 Mbps	—	—	0.10	UI, p-p
Random	622 Mbps	—	—	0.20	UI, p-p
Total	622 Mbps	—	—	0.24	UI, p-p
Deterministic	250 Mbps	—	—	0.10	UI, p-p
Random	250 Mbps	—	—	0.18	UI, p-p
Total	250 Mbps	—	—	0.24	UI, p-p
Deterministic	150 Mbps	—	—	0.10	UI, p-p
Random	150 Mbps	—	—	0.18	UI, p-p
Total	150 Mbps	—		0.24	UI, p-p

Note: Values are measured with PRBS 2<sup>7</sup>-1, all channels operating, FPGA logic active, I/Os around SERDES pins quiet, reference clock @ 10X mode.



# **SERDES High Speed Data Receiver**

#### Table 3-9. Serial Input Data Specifications

Symbol	Description	Min.	Тур.	Max.	Units	
		3.125 G	—	_	136	
	D <sub>S</sub> Stream of nontransitions <sup>1</sup> (CID = Consecutive Identical Digits) @ 10 <sup>-12</sup> BER	2.5 G	—	_	144	Dite
		1.485 G	—		160	
		622 M	—	_	204	Dits
		270 M	—		228	
		150 M	—		296	
V <sub>RX-DIFF-S</sub>	Differential input sensitivity	·	150	_	1760	mV, p-p
V <sub>RX-IN</sub>	Input levels		0	_	V <sub>CCA</sub> +0.5 <sup>4</sup>	V
V <sub>RX-CM-DC</sub>	Input common mode range (DC coupled)		0.6	_	V <sub>CCA</sub>	V
V <sub>RX-CM-AC</sub>	Input common mode range (AC coupled) <sup>3</sup>		0.1		V <sub>CCA</sub> +0.2	V
T <sub>RX-RELOCK</sub>	SCDR re-lock time <sup>2</sup>		—	1000	—	Bits
Z <sub>RX-TERM</sub>	Input termination 50/75 Ohm/High Z		-20%	50/75/HiZ	+20%	Ohms
RL <sub>RX-RL</sub>	Return loss (without package)		10	_	—	dB

1. This is the number of bits allowed without a transition on the incoming data stream when using DC coupling.

2. This is the typical number of bit times to re-lock to a new phase or frequency within +/- 300 ppm, assuming 8b10b encoded data.

3. AC coupling is used to interface to LVPECL and LVDS. LVDS interfaces are found in laser drivers and Fibre Channel equipment. LVDS interfaces are generally found in 622 Mbps SERDES devices.

4. Up to 1.76 V.

## Input Data Jitter Tolerance

A receiver's ability to tolerate incoming signal jitter is very dependent on jitter type. High speed serial interface standards have recognized the dependency on jitter type and have specifications to indicate tolerance levels for different jitter types as they relate to specific protocols. Sinusoidal jitter is considered to be a worst case jitter type.

Description	Frequency	Condition	Min.	Тур.	Max.	Units
Deterministic		600 mV differential eye	_	_	0.47	UI, p-p
Random	3.125 Gbps	600 mV differential eye	_	_	0.18	UI, p-p
Total		600 mV differential eye	_		0.65	UI, p-p
Deterministic		600 mV differential eye	_	_	0.47	UI, p-p
Random	2.5 Gbps	600 mV differential eye	_	_	0.18	UI, p-p
Total		600 mV differential eye	_		0.65	UI, p-p
Deterministic		600 mV differential eye	_	_	0.47	UI, p-p
Random	1.25 Gbps	600 mV differential eye	_	_	0.18	UI, p-p
Total		600 mV differential eye	_	_	0.65	UI, p-p
Deterministic		600 mV differential eye	_	_	0.47	UI, p-p
Random	622 Mbps	600 mV differential eye	_	_	0.18	UI, p-p
Total	]	600 mV differential eye		—	0.65	UI, p-p

Table 3-10. Receiver Total Jitter Tolerance Specification

Note: Values are measured with CJPAT, all channels operating, FPGA Logic active, I/Os around SERDES pins quiet, voltages are nominal, room temperature.



# Serial Rapid I/O Type 2/CPRI LV E.24 Electrical and Timing Characteristics

## **AC and DC Characteristics**

#### Table 3-15. Transmit

Symbol	Description	Test Conditions	Min.	Тур.	Max.	Units
T <sub>RF</sub> <sup>1</sup>	Differential rise/fall time	20%-80%	—	80	—	ps
Z <sub>TX_DIFF_DC</sub>	Differential impedance		80	100	120	Ohms
J <sub>TX_DDJ</sub> <sup>3, 4, 5</sup>	Output data deterministic jitter			_	0.17	UI
J <sub>TX_TJ</sub> <sup>2, 3, 4, 5</sup>	Total output data jitter			_	0.35	UI

1. Rise and Fall times measured with board trace, connector and approximately 2.5pf load.

2. Total jitter includes both deterministic jitter and random jitter. The random jitter is the total jitter minus the actual deterministic jitter.

3. Jitter values are measured with each CML output AC coupled into a 50-Ohm impedance (100-Ohm differential impedance).

4. Jitter and skew are specified between differential crossings of the 50% threshold of the reference signal.

5. Values are measured at 2.5 Gbps.

#### Table 3-16. Receive and Jitter Tolerance

Symbol	Description	Test Conditions	Min.	Тур.	Max.	Units
RL <sub>RX_DIFF</sub>	Differential return loss	From 100 MHz to 2.5 GHz	10	_	_	dB
RL <sub>RX_CM</sub>	Common mode return loss	From 100 MHz to 2.5 GHz	6	—	—	dB
Z <sub>RX_DIFF</sub>	Differential termination resistance		80	100	120	Ohms
J <sub>RX_DJ</sub> <sup>2, 3, 4, 5</sup>	Deterministic jitter tolerance (peak-to-peak)		_	—	0.37	UI
J <sub>RX_RJ</sub> <sup>2, 3, 4, 5</sup>	Random jitter tolerance (peak-to-peak)		_	_	0.18	UI
J <sub>RX_SJ</sub> <sup>2, 3, 4, 5</sup>	Sinusoidal jitter tolerance (peak-to-peak)		_	_	0.10	UI
J <sub>RX_TJ</sub> <sup>1, 2, 3, 4, 5</sup>	Total jitter tolerance (peak-to-peak)		_	_	0.65	UI
T <sub>RX_EYE</sub>	Receiver eye opening		0.35	—	—	UI

1. Total jitter includes deterministic jitter, random jitter and sinusoidal jitter. The sinusoidal jitter tolerance mask is shown in Figure 3-18.

2. Jitter values are measured with each high-speed input AC coupled into a 50-Ohm impedance.

3. Jitter and skew are specified between differential crossings of the 50% threshold of the reference signal.

4. Jitter tolerance, Differential Input Sensitivity and Receiver Eye Opening parameters are characterized when Full Rx Equalization is enabled.

5. Values are measured at 2.5 Gbps.



# HDMI (High-Definition Multimedia Interface) Electrical and Timing Characteristics

## AC and DC Characteristics

#### Table 3-22. Transmit and Receive<sup>1, 2</sup>

		Spec. Co		
Symbol	Description	Min. Spec.	Max. Spec.	Units
Transmit		•		
Intra-pair Skew		—	75	ps
Inter-pair Skew		—	800	ps
TMDS Differential Clock Jitter		—	0.25	UI
Receive		•		
R <sub>T</sub>	Termination Resistance	40	60	Ohms
V <sub>ICM</sub>	Input AC Common Mode Voltage (50-Ohm Set- ting)	—	50	mV
TMDS Clock Jitter	Clock Jitter Tolerance	—	0.25	UI

1. Output buffers must drive a translation device. Max. speed is 2 Gbps. If translation device does not modify rise/fall time, the maximum speed is 1.5 Gbps.

2. Input buffers must be AC coupled in order to support the 3.3 V common mode. Generally, HDMI inputs are terminated by an external cable equalizer before data/clock is forwarded to the LatticeECP3 device.



# LatticeECP3 sysCONFIG Port Timing Specifications

Parameter	Description	Min.	Max.	Units				
POR, Confi	guration Initialization, and Wakeup				1			
	Time from the Application of $V_{CC}$ , $V_{CCAUX}$ or $V_{CCIO8}^{*}$ (Whichever	Master mode		23	ms			
t <sub>ICFG</sub>	is the Last to Cross the POR Trip Point) to the Rising Edge of INITN	Slave mode	—	6	ms			
t <sub>VMC</sub>	Time from t <sub>ICFG</sub> to the Valid Master MCLK		—	5	μs			
t <sub>PRGM</sub>	PROGRAMN Low Time to Start Configuration		25	—	ns			
t <sub>PRGMRJ</sub>	PROGRAMN Pin Pulse Rejection		_	10	ns			
t <sub>DPPINIT</sub>	Delay Time from PROGRAMN Low to INITN Low		—	37	ns			
t <sub>DPPDONE</sub>	Delay Time from PROGRAMN Low to DONE Low		_	37	ns			
t <sub>DINIT</sub> 1	PROGRAMN High to INITN High Delay		—	1	ms			
t <sub>MWC</sub>	Additional Wake Master Clock Signals After DONE Pin is High		100	500	cycles			
t <sub>CZ</sub>	MCLK From Active To Low To High-Z		—	300	ns			
t <sub>IODISS</sub>	User I/O Disable from PROGRAMN Low			100	ns			
t <sub>IOENSS</sub>	User I/O Enabled Time from CCLK Edge During Wake-up Sequer	nce		100	ns			
All Configu	ration Modes							
t <sub>SUCDI</sub>	Data Setup Time to CCLK/MCLK		5	—	ns			
t <sub>HCDI</sub>	Data Hold Time to CCLK/MCLK		1	—	ns			
t <sub>CODO</sub>	CCLK/MCLK to DOUT in Flowthrough Mode		-0.2	12	ns			
Slave Seria	Slave Serial							
t <sub>SSCH</sub>	CCLK Minimum High Pulse	5	—	ns				
t <sub>SSCL</sub>	CCLK Minimum Low Pulse	5	_	ns				
	Without encryption			33	MHz			
ICCLK	CCLK Frequency	With encryption		20	MHz			
Master and	Slave Parallel	1						
t <sub>SUCS</sub>	CSN[1:0] Setup Time to CCLK/MCLK		7	—	ns			
t <sub>HCS</sub>	CSN[1:0] Hold Time to CCLK/MCLK		1	—	ns			
t <sub>SUWD</sub>	WRITEN Setup Time to CCLK/MCLK		7	_	ns			
t <sub>HWD</sub>	WRITEN Hold Time to CCLK/MCLK		1	_	ns			
t <sub>DCB</sub>	CCLK/MCLK to BUSY Delay Time		_	12	ns			
t <sub>CORD</sub>	CCLK to Out for Read Data		_	12	ns			
t <sub>BSCH</sub>	CCLK Minimum High Pulse		6	_	ns			
t <sub>BSCL</sub>	CCLK Minimum Low Pulse		6	—	ns			
t <sub>BSCYC</sub>	Byte Slave Cycle Time		30	_	ns			
		Without encryption	_	33	MHz			
ICCLK	CCLK/MCLK Frequency	With encryption	—	20	MHz			
Master and	Slave SPI	1						
t <sub>CFGX</sub>	INITN High to MCLK Low		_	80	ns			
t <sub>CSSPI</sub>	INITN High to CSSPIN Low	0.2	2	μs				
t <sub>SOCDO</sub>	MCLK Low to Output Valid		15	ns				
t <sub>CSPID</sub>	CSSPIN[0:1] Low to First MCLK Edge Setup Time		0.3		μs			
	001// 5	Without encryption	—	33	MHz			
ICCLK	CCLK Frequency	With encryption	—	20	MHz			
t <sub>SSCH</sub>	CCLK Minimum High Pulse	5		ns				

#### **Over Recommended Operating Conditions**



#### Figure 3-21. sysCONFIG Parallel Port Write Cycle



1. In Master Parallel Mode the FPGA provides CCLK (MCLK). In Slave Parallel Mode the external device provides CCLK.

#### Figure 3-22. sysCONFIG Master Serial Port Timing









# Signal Descriptions (Cont.)

Signal Name I		Description
[LOC]DQS[num]	I/O	DQ input/output pads: T (top), R (right), B (bottom), L (left), DQS, num = ball function number.
[LOC]DQ[num]	I/O	DQ input/output pads: T (top), R (right), B (bottom), L (left), DQ, associated DQS number.
Test and Programming (Dedicated Pi	ns)	
TMS	I	Test Mode Select input, used to control the 1149.1 state machine. Pull-up is enabled during configuration.
тск	I	Test Clock input pin, used to clock the 1149.1 state machine. No pull-up enabled.
TDI	I	Test Data in pin. Used to load data into device using 1149.1 state machine. After power-up, this TAP port can be activated for configuration by sending appropriate command. (Note: once a configuration port is selected it is locked. Another configuration port cannot be selected until the power-up sequence). Pull-up is enabled during configuration.
TDO	0	Output pin. Test Data Out pin used to shift data out of a device using 1149.1.
VCCJ	—	Power supply pin for JTAG Test Access Port.
Configuration Pads (Used During sys	CONFIG	G)
CFG[2:0]	I	Mode pins used to specify configuration mode values latched on rising edge of INITN. During configuration, a pull-up is enabled. These are dedicated pins.
INITN	I/O	Open Drain pin. Indicates the FPGA is ready to be configured. During configuration, a pull-up is enabled. It is a dedicated pin.
PROGRAMN	Ι	Initiates configuration sequence when asserted low. This pin always has an active pull-up. It is a dedicated pin.
DONE	I/O	Open Drain pin. Indicates that the configuration sequence is complete, and the startup sequence is in progress. It is a dedicated pin.
ССГК	Ι	Input Configuration Clock for configuring an FPGA in Slave SPI, Serial, and CPU modes. It is a dedicated pin.
MCLK	I/O	Output Configuration Clock for configuring an FPGA in SPI, SPIm, and Master configuration modes.
BUSY/SISPI	0	Parallel configuration mode busy indicator. SPI/SPIm mode data output.
CSN/SN/OEN	I/O	Parallel configuration mode active-low chip select. Slave SPI chip select. Parallel burst Flash output enable.
CS1N/HOLDN/RDY	I	Parallel configuration mode active-low chip select. Slave SPI hold input.
WRITEN	Ι	Write enable for parallel configuration modes.
DOUT/CSON/CSSPI1N	0	Serial data output. Chip select output. SPI/SPIm mode chip select.
		sysCONFIG Port Data I/O for Parallel mode. Open drain during configuration.
D[0]/SPIFASTN	I/O	sysCONFIG Port Data I/O for SPI or SPIm. When using the SPI or SPIm mode, this pin should either be tied high or low, must not be left floating. Open drain during configuration.
D1	I/O	Parallel configuration I/O. Open drain during configuration.
D2	I/O	Parallel configuration I/O. Open drain during configuration.
D3/SI	I/O	Parallel configuration I/O. Slave SPI data input. Open drain during configura- tion.
D4/SO	I/O	Parallel configuration I/O. Slave SPI data output. Open drain during configura- tion.
D5	I/O	Parallel configuration I/O. Open drain during configuration.
D6/SPID1	I/O	Parallel configuration I/O. SPI/SPIm data input. Open drain during configura- tion.



# Pin Information Summary (Cont.)

Pin Information Sun		ECP3-17EA		ECP3-35EA			
Pin Type		256 ftBGA	328 csBGA	484 fpBGA	256 ftBGA	484 fpBGA	672 fpBGA
	Bank 0	13	10	18	13	21	24
	Bank 1	7	5	12	7	18	18
	Bank 2	2	2	4	1	8	8
Emulated Differential I/O per	Bank 3	4	2	13	5	20	19
Dank	Bank 6	5	1	13	6	22	20
	Bank 7	6	9	10	6	11	13
	Bank 8	12	12	12	12	12	12
	Bank 0	0	0	0	0	0	0
	Bank 1	0	0	0	0	0	0
	Bank 2	2	2	3	3	6	6
Highspeed Differential I/O per	Bank 3	5	4	9	4	9	12
Dank	Bank 6	5	4	9	4	11	12
	Bank 7	5	6	8	5	9	10
	Bank 8	0	0	0	0	0	0
	Bank 0	26/13	20/10	36/18	26/13	42/21	48/24
	Bank 1	14/7	10/5	24/12	14/7	36/18	36/18
	Bank 2	8/4	9/4	14/7	8/4	28/14	28/14
Differential I/O per Bank	Bank 3	18/9	12/6	44/22	18/9	58/29	63/31
	Bank 6	20/10	11/5	44/22	20/10	67/33	65/32
	Bank 7	23/11	30/15	36/18	23/11	40/20	46/23
	Bank 8	24/12	24/12	24/12	24/12	24/12	24/12
	Bank 0	2	1	3	2	3	4
	Bank 1	1	0	2	1	3	3
	Bank 2	0	0	1	0	2	2
DDR Groups Bonded per	Bank 3	1	0	3	1	3	4
Bank <sup>∠</sup>	Bank 6	1	0	3	1	4	4
	Bank 7	1	2	2	1	3	3
	Configuration Bank 8	0	0	0	0	0	0
SERDES Quads	1	1	1	1	1	1	

These pins must remain floating on the board.
Some DQS groups may not support DQS-12. Refer to the device pinout (.csv) file.



## LatticeECP3 Devices, Green and Lead-Free Packaging

The following devices may have associated errata. Specific devices with associated errata will be notated with a footnote.

Part Number	Voltage	Grade	Power	Package <sup>1</sup>	Pins	Temp.	LUTs (K)
LFE3-17EA-6FTN256C	1.2 V	-6	STD	Lead-Free ftBGA	256	COM	17
LFE3-17EA-7FTN256C	1.2 V	-7	STD	Lead-Free ftBGA	256	COM	17
LFE3-17EA-8FTN256C	1.2 V	-8	STD	Lead-Free ftBGA	256	COM	17
LFE3-17EA-6LFTN256C	1.2 V	-6	LOW	Lead-Free ftBGA	256	COM	17
LFE3-17EA-7LFTN256C	1.2 V	-7	LOW	Lead-Free ftBGA	256	COM	17
LFE3-17EA-8LFTN256C	1.2 V	-8	LOW	Lead-Free ftBGA	256	COM	17
LFE3-17EA-6MG328C	1.2 V	-6	STD	Green csBGA	328	COM	17
LFE3-17EA-7MG328C	1.2 V	-7	STD	Green csBGA	328	COM	17
LFE3-17EA-8MG328C	1.2 V	-8	STD	Green csBGA	328	COM	17
LFE3-17EA-6LMG328C	1.2 V	-6	LOW	Green csBGA	328	COM	17
LFE3-17EA-7LMG328C	1.2 V	-7	LOW	Green csBGA	328	COM	17
LFE3-17EA-8LMG328C	1.2 V	-8	LOW	Green csBGA	328	COM	17
LFE3-17EA-6FN484C	1.2 V	-6	STD	Lead-Free fpBGA	484	COM	17
LFE3-17EA-7FN484C	1.2 V	-7	STD	Lead-Free fpBGA	484	COM	17
LFE3-17EA-8FN484C	1.2 V	-8	STD	Lead-Free fpBGA	484	COM	17
LFE3-17EA-6LFN484C	1.2 V	-6	LOW	Lead-Free fpBGA	484	COM	17
LFE3-17EA-7LFN484C	1.2 V	-7	LOW	Lead-Free fpBGA	484	COM	17
LFE3-17EA-8LFN484C	1.2 V	-8	LOW	Lead-Free fpBGA	484	COM	17

Commercial

1. Green = Halogen free and lead free.

Part Number	Voltage	Grade <sup>1</sup>	Power	Package	Pins	Temp.	LUTs (K)
LFE3-35EA-6FTN256C	1.2 V	-6	STD	Lead-Free ftBGA	256	COM	33
LFE3-35EA-7FTN256C	1.2 V	-7	STD	Lead-Free ftBGA	256	COM	33
LFE3-35EA-8FTN256C	1.2 V	-8	STD	Lead-Free ftBGA	256	COM	33
LFE3-35EA-6LFTN256C	1.2 V	-6	LOW	Lead-Free ftBGA	256	COM	33
LFE3-35EA-7LFTN256C	1.2 V	-7	LOW	Lead-Free ftBGA	256	COM	33
LFE3-35EA-8LFTN256C	1.2 V	-8	LOW	Lead-Free ftBGA	256	COM	33
LFE3-35EA-6FN484C	1.2 V	-6	STD	Lead-Free fpBGA	484	COM	33
LFE3-35EA-7FN484C	1.2 V	-7	STD	Lead-Free fpBGA	484	COM	33
LFE3-35EA-8FN484C	1.2 V	-8	STD	Lead-Free fpBGA	484	COM	33
LFE3-35EA-6LFN484C	1.2 V	-6	LOW	Lead-Free fpBGA	484	COM	33
LFE3-35EA-7LFN484C	1.2 V	-7	LOW	Lead-Free fpBGA	484	COM	33
LFE3-35EA-8LFN484C	1.2 V	-8	LOW	Lead-Free fpBGA	484	COM	33
LFE3-35EA-6FN672C	1.2 V	-6	STD	Lead-Free fpBGA	672	COM	33
LFE3-35EA-7FN672C	1.2 V	-7	STD	Lead-Free fpBGA	672	COM	33
LFE3-35EA-8FN672C	1.2 V	-8	STD	Lead-Free fpBGA	672	COM	33
LFE3-35EA-6LFN672C	1.2 V	-6	LOW	Lead-Free fpBGA	672	COM	33
LFE3-35EA-7LFN672C	1.2 V	-7	LOW	Lead-Free fpBGA	672	COM	33
LFE3-35EA-8LFN672C	1.2 V	-8	LOW	Lead-Free fpBGA	672	COM	33

1. For ordering information on -9 speed grade devices, please contact your Lattice Sales Representative.



Part Number	Voltage	Grade <sup>1</sup>	Power	Package	Pins	Temp.	LUTs (K)
LFE3-70EA-6FN484C	1.2 V	-6	STD	Lead-Free fpBGA	484	COM	67
LFE3-70EA-7FN484C	1.2 V	-7	STD	Lead-Free fpBGA	484	COM	67
LFE3-70EA-8FN484C	1.2 V	-8	STD	Lead-Free fpBGA	484	COM	67
LFE3-70EA-6LFN484C	1.2 V	-6	LOW	Lead-Free fpBGA	484	COM	67
LFE3-70EA-7LFN484C	1.2 V	-7	LOW	Lead-Free fpBGA	484	COM	67
LFE3-70EA-8LFN484C	1.2 V	-8	LOW	Lead-Free fpBGA	484	COM	67
LFE3-70EA-6FN672C	1.2 V	-6	STD	Lead-Free fpBGA	672	COM	67
LFE3-70EA-7FN672C	1.2 V	-7	STD	Lead-Free fpBGA	672	COM	67
LFE3-70EA-8FN672C	1.2 V	-8	STD	Lead-Free fpBGA	672	COM	67
LFE3-70EA-6LFN672C	1.2 V	-6	LOW	Lead-Free fpBGA	672	COM	67
LFE3-70EA-7LFN672C	1.2 V	-7	LOW	Lead-Free fpBGA	672	COM	67
LFE3-70EA-8LFN672C	1.2 V	-8	LOW	Lead-Free fpBGA	672	COM	67
LFE3-70EA-6FN1156C	1.2 V	-6	STD	Lead-Free fpBGA	1156	COM	67
LFE3-70EA-7FN1156C	1.2 V	-7	STD	Lead-Free fpBGA	1156	COM	67
LFE3-70EA-8FN1156C	1.2 V	-8	STD	Lead-Free fpBGA	1156	COM	67
LFE3-70EA-6LFN1156C	1.2 V	-6	LOW	Lead-Free fpBGA	1156	COM	67
LFE3-70EA-7LFN1156C	1.2 V	-7	LOW	Lead-Free fpBGA	1156	COM	67
LFE3-70EA-8LFN1156C	1.2 V	-8	LOW	Lead-Free fpBGA	1156	COM	67

1. For ordering information on -9 speed grade devices, please contact your Lattice Sales Representative.

Part Number	Voltage	Grade <sup>1</sup>	Power	Package	Pins	Temp.	LUTs (K)
LFE3-95EA-6FN484C	1.2 V	-6	STD	Lead-Free fpBGA	484	COM	92
LFE3-95EA-7FN484C	1.2 V	-7	STD	Lead-Free fpBGA	484	COM	92
LFE3-95EA-8FN484C	1.2 V	-8	STD	Lead-Free fpBGA	484	COM	92
LFE3-95EA-6LFN484C	1.2 V	-6	LOW	Lead-Free fpBGA	484	COM	92
LFE3-95EA-7LFN484C	1.2 V	-7	LOW	Lead-Free fpBGA	484	COM	92
LFE3-95EA-8LFN484C	1.2 V	-8	LOW	Lead-Free fpBGA	484	COM	92
LFE3-95EA-6FN672C	1.2 V	-6	STD	Lead-Free fpBGA	672	COM	92
LFE3-95EA-7FN672C	1.2 V	-7	STD	Lead-Free fpBGA	672	COM	92
LFE3-95EA-8FN672C	1.2 V	-8	STD	Lead-Free fpBGA	672	COM	92
LFE3-95EA-6LFN672C	1.2 V	-6	LOW	Lead-Free fpBGA	672	COM	92
LFE3-95EA-7LFN672C	1.2 V	-7	LOW	Lead-Free fpBGA	672	COM	92
LFE3-95EA-8LFN672C	1.2 V	-8	LOW	Lead-Free fpBGA	672	COM	92
LFE3-95EA-6FN1156C	1.2 V	-6	STD	Lead-Free fpBGA	1156	COM	92
LFE3-95EA-7FN1156C	1.2 V	-7	STD	Lead-Free fpBGA	1156	COM	92
LFE3-95EA-8FN1156C	1.2 V	-8	STD	Lead-Free fpBGA	1156	COM	92
LFE3-95EA-6LFN1156C	1.2 V	-6	LOW	Lead-Free fpBGA	1156	COM	92
LFE3-95EA-7LFN1156C	1.2 V	-7	LOW	Lead-Free fpBGA	1156	COM	92
LFE3-95EA-8LFN1156C	1.2 V	-8	LOW	Lead-Free fpBGA	1156	COM	92

1. For ordering information on -9 speed grade devices, please contact your Lattice Sales Representative.



Date	Version	Section	Change Summary
March 2010	01.6	Architecture	Added Read-Before-Write information.
		DC and Switching	Added footnote #6 to Maximum I/O Buffer Speed table.
		Characteristics	Corrected minimum operating conditions for input and output differential voltages in the Point-to-Point LVDS table.
		Pinout Information	Added pin information for the LatticeECP3-70EA and LatticeECP3- 95EA devices.
		Ordering Information	Added ordering part numbers for the LatticeECP3-70EA and LatticeECP3-95EA devices.
			Removed dual mark information.
November 2009	01.5	Introduction	Updated Embedded SERDES features.
			Added SONET/SDH to Embedded SERDES protocols.
		Architecture	Updated Figure 2-4, General Purpose PLL Diagram.
			Updated SONET/SDH to SERDES and PCS protocols.
			Updated Table 2-13, SERDES Standard Support to include SONET/ SDH and updated footnote 2.
		DC and Switching Characterisitcs	Added footnote to ESD Performance table.
			Updated SERDES Power Supply Requirements table and footnotes.
			Updated Maximum I/O Buffer Speed table.
			Updated Pin-to-Pin Peformance table.
			Updated sysCLOCK PLL Timing table.
			Updated DLL timing table.
			Updated High-Speed Data Transmitter tables.
			Updated High-Speed Data Receiver table.
			Updated footnote for Receiver Total Jitter Tolerance Specification table.
			Updated Periodic Receiver Jitter Tolerance Specification table.
			Updated SERDES External Reference Clock Specification table.
			Updated PCI Express Electrical and Timing AC and DC Characteristics.
			Deleted Reference Clock table for PCI Express Electrical and Timing AC and DC Characteristics.
			Updated SMPTE AC/DC Characteristics Transmit table.
			Updated Mini LVDS table.
			Updated RSDS table.
			Added Supply Current (Standby) table for EA devices.
			Updated Internal Switching Characteristics table.
			Updated Register-to-Register Performance table.
			Added HDMI Electrical and Timing Characteristics data.
			Updated Family Timing Adders table.
			Updated sysCONFIG Port Timing Specifications table.
			Updated Recommended Operating Conditions table.
			Updated Hot Socket Specifications table.
			Updated Single-Ended DC table.
			Updated TRLVDS table and figure.
			Updated Serial Data Input Specifications table.
			Updated HDMI Transmit and Receive table.
		Ordering Information	Added LFE3-150EA "TW" devices and footnotes to the Commercial and Industrial tables.