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#### What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

# Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

## Details

E·XF

Product Status	Active
Core Processor	ARM® Cortex®-M4
Core Size	32-Bit Single-Core
Speed	72MHz
Connectivity	CANbus, EBI/EMI, I <sup>2</sup> C, IrDA, LINbus, SmartCard, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, POR, PWM, WDT
Number of I/O	56
Program Memory Size	2MB (2M x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	384K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.8V
Data Converters	A/D 16x12b SAR; D/A 2x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	64-VFQFN Exposed Pad
Supplier Device Package	64-QFN (9x9)
Purchase URL	https://www.e-xfl.com/product-detail/silicon-labs/efm32gg11b110f2048im64-b

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

### 3.10.2 Memory System Controller (MSC)

The Memory System Controller (MSC) is the program memory unit of the microcontroller. The flash memory is readable and writable from both the Cortex-M and DMA. The flash memory is divided into two blocks; the main block and the information block. Program code is normally written to the main block, whereas the information block is available for special user data and flash lock bits. There is also a read-only page in the information block containing system and device calibration data. Read and write operations are supported in energy modes EM0 Active and EM1 Sleep.

### 3.10.3 Linked Direct Memory Access Controller (LDMA)

The Linked Direct Memory Access (LDMA) controller allows the system to perform memory operations independently of software. This reduces both energy consumption and software workload. The LDMA allows operations to be linked together and staged, enabling so-phisticated operations to be implemented.

### 3.10.4 Bootloader

All devices come pre-programmed with a UART bootloader. This bootloader resides in flash and can be erased if it is not needed. More information about the bootloader protocol and usage can be found in *AN0003: UART Bootloader*. Application notes can be found on the Silicon Labs website (www.silabs.com/32bit-appnotes) or within Simplicity Studio in the [**Documentation**] area.

### 4.1.7 Current Consumption

# 4.1.7.1 Current Consumption 3.3 V without DC-DC Converter

Unless otherwise indicated, typical conditions are: VREGVDD = AVDD = DVDD = 3.3 V. T = 25 °C. DCDC is off. Minimum and maximum values in this table represent the worst conditions across supply voltage and process variation at T = 25 °C.

# Table 4.7. Current Consumption 3.3 V without DC-DC Converter

Parameter	Symbol	Test Condition	Min	Тур	Max	Unit
Current consumption in EM0 mode with all peripherals dis-	I <sub>ACTIVE</sub>	72 MHz HFRCO, CPU running Prime from flash	_	120	_	µA/MHz
abled		72 MHz HFRCO, CPU running while loop from flash	_	120	TBD	µA/MHz
		72 MHz HFRCO, CPU running CoreMark loop from flash	_	140		µA/MHz
		50 MHz crystal, CPU running while loop from flash	_	123	_	µA/MHz
		48 MHz HFRCO, CPU running while loop from flash	_	122	TBD	µA/MHz
		32 MHz HFRCO, CPU running while loop from flash	_	124	_	µA/MHz
		26 MHz HFRCO, CPU running while loop from flash	_	126	TBD	µA/MHz
		16 MHz HFRCO, CPU running while loop from flash	_	131	_	µA/MHz
		1 MHz HFRCO, CPU running while loop from flash	_	319	TBD	µA/MHz
Current consumption in EM0 mode with all peripherals dis-	IACTIVE_VS	19 MHz HFRCO, CPU running while loop from flash	_	107	_	µA/MHz
abled and voltage scaling enabled		1 MHz HFRCO, CPU running while loop from flash	_	262	_	µA/MHz
Current consumption in EM1	I <sub>EM1</sub>	72 MHz HFRCO	—	57	TBD	µA/MHz
mode with all peripherals disabled		50 MHz crystal	_	60	_	µA/MHz
		48 MHz HFRCO	_	59	TBD	µA/MHz
		32 MHz HFRCO	_	61		µA/MHz
		26 MHz HFRCO		63	TBD	µA/MHz
		16 MHz HFRCO		68	_	µA/MHz
		1 MHz HFRCO	_	255	TBD	µA/MHz
Current consumption in EM1	I <sub>EM1_VS</sub>	19 MHz HFRCO	_	55	_	µA/MHz
mode with all peripherals dis- abled and voltage scaling enabled		1 MHz HFRCO	_	210	_	µA/MHz

Parameter	Symbol	Test Condition	Min	Тур	Мах	Unit
Current consumption in EM4H mode, with voltage	I <sub>EM4H_VS</sub>	128 byte RAM retention, RTCC running from LFXO	—	0.94		μA
scaling enabled		128 byte RAM retention, CRYO- TIMER running from ULFRCO	—	0.62		μA
		128 byte RAM retention, no RTCC	_	0.62	_	μA
Current consumption in EM4S mode	I <sub>EM4S</sub>	No RAM retention, no RTCC	—	0.13		μA
Current consumption of pe- ripheral power domain 1, with voltage scaling enabled, DCDC in LP mode <sup>3</sup>	IPD1_VS	Additional current consumption in EM2/3 when any peripherals on power domain 1 are enabled <sup>4</sup>		0.68	_	μA
Current consumption of pe- ripheral power domain 2, with voltage scaling enabled, DCDC in LP mode <sup>3</sup>	IPD2_VS	Additional current consumption in EM2/3 when any peripherals on power domain 2 are enabled <sup>4</sup>		0.28	_	μA

### Note:

1. DCDC Low Noise CCM Mode = Light Drive (PFETCNT=NFETCNT=3), F=6.4 MHz (RCOBAND=4), ANASW=DVDD.

2. DCDC Low Noise DCM Mode = Light Drive (PFETCNT=NFETCNT=3), F=3.0 MHz (RCOBAND=0), ANASW=DVDD.

3. DCDC Low Power Mode = Medium Drive (PFETCNT=NFETCNT=7), LPOSCDIV=1, LPCMPBIASEM234H=0, LPCLIMILIM-SEL=1, ANASW=DVDD.

4. Extra current consumed by power domain. Does not include current associated with the enabled peripherals. See 3.2.4 EM2 and EM3 Power Domains for a list of the peripherals in each power domain.

5. CMU\_LFRCOCTRL\_ENVREF = 1, CMU\_LFRCOCTRL\_VREFUPDATE = 1

# 4.1.10.3 Low-Frequency RC Oscillator (LFRCO)

Parameter	Symbol	Test Condition	Min	Тур	Мах	Unit
Oscillation frequency	f <sub>LFRCO</sub>	ENVREF <sup>2</sup> = 1	TBD	32.768	TBD	kHz
		ENVREF <sup>2</sup> = 1, T > 85 °C	TBD	32.768	TBD	kHz
		ENVREF <sup>2</sup> = 0	TBD	32.768	TBD	kHz
Startup time	t <sub>LFRCO</sub>		_	500	_	μs
Current consumption <sup>1</sup>	I <sub>LFRCO</sub>	ENVREF = 1 in CMU_LFRCOCTRL	_	370	_	nA
		ENVREF = 0 in CMU_LFRCOCTRL	-	520		nA
Note:	1	I.	1	1	1	1

# Table 4.14. Low-Frequency RC Oscillator (LFRCO)

1. Block is supplied by AVDD if ANASW = 0, or DVDD if ANASW=1 in EMU\_PWRCTRL register.

2. In CMU\_LFRCOCTRL register.

# 4.1.23.2 I2C Fast-mode (Fm)<sup>1</sup>

Parameter	Symbol	Test Condition	Min	Тур	Max	Unit
SCL clock frequency <sup>2</sup>	f <sub>SCL</sub>		0	_	400	kHz
SCL clock low time	t <sub>LOW</sub>		1.3	_	_	μs
SCL clock high time	t <sub>HIGH</sub>		0.6	_	_	μs
SDA set-up time	t <sub>SU_DAT</sub>		100	_	_	ns
SDA hold time <sup>3</sup>	t <sub>HD_DAT</sub>		100	_	900	ns
Repeated START condition set-up time	t <sub>SU_STA</sub>		0.6	_	_	μs
(Repeated) START condition hold time	t <sub>HD_STA</sub>		0.6	_	_	μs
STOP condition set-up time	t <sub>SU_STO</sub>		0.6	_		μs
Bus free time between a STOP and START condition	t <sub>BUF</sub>		1.3	—	_	μs

# Table 4.32. I2C Fast-mode (Fm)<sup>1</sup>

Note:

1. For CLHR set to 1 in the I2Cn\_CTRL register.

2. For the minimum HFPERCLK frequency required in Fast-mode, refer to the I2C chapter in the reference manual.

3. The maximum SDA hold time (t<sub>HD,DAT</sub>) needs to be met only when the device does not stretch the low time of SCL (t<sub>LOW</sub>).

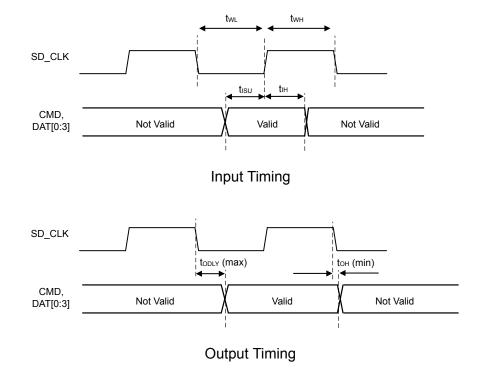
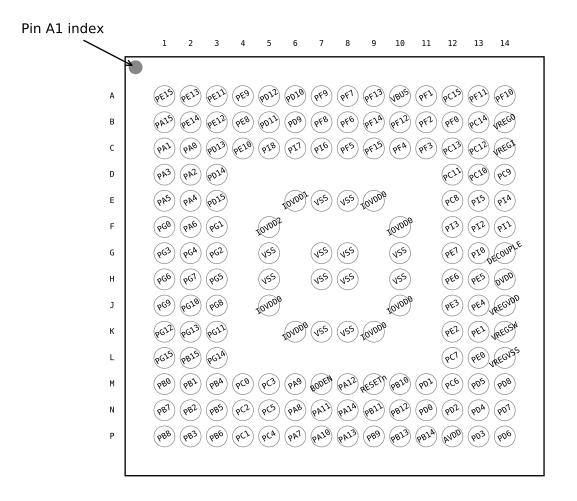


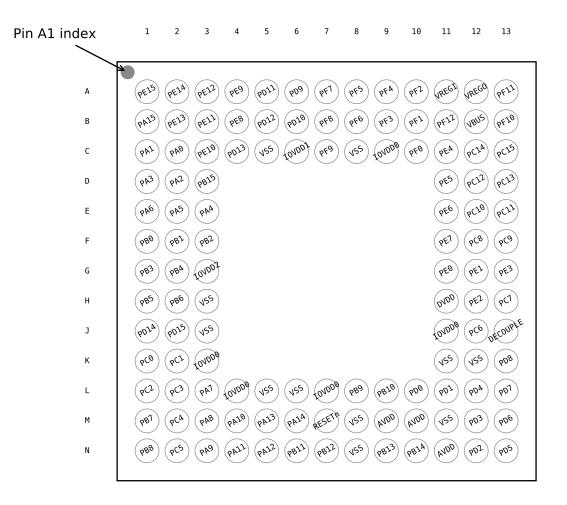
Figure 4.13. SDIO DS Mode Timing



### Figure 5.2. EFM32GG11B8xx in BGA152 Device Pinout

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PE15	A1	GPIO	PE13	A2	GPIO
PE11	A3	GPIO	PE9	A4	GPIO
PD12	A5	GPIO	PD10	A6	GPIO
PF9	A7	GPIO	PF7	A8	GPIO
PF13	A9	GPIO (5V)	VBUS	A10	USB VBUS signal and auxiliary input to 5 V regulator.
PF1	A11	GPIO (5V)	PC15	A12	GPIO (5V)
PF11	A13	GPIO (5V)	PF10	A14	GPIO (5V)

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PF11	A13	GPIO (5V)	PA15	B1	GPIO
PE13	B2	GPIO	PE11	B3	GPIO
PE8	B4	GPIO	PD12	B5	GPIO
PD10	B6	GPIO	PF8	B7	GPIO
PF6	B8	GPIO	PF13	B9	GPIO (5V)
PF4	B10	GPIO	PF3	B11	GPIO
NC	B12	No Connect.	PF10	B13	GPIO (5V)
PA1	C1	GPIO	PA0	C2	GPIO
PE10	C3	GPIO	PD13	C4	GPIO (5V)
VSS	C5 C8 H3 J3 K11 L12 L15	Ground	IOVDD1	C6	Digital IO power supply 1.
PF9	C7	GPIO	IOVDD0	C9 J11 K3 L11 L16	Digital IO power supply 0.
PF2	C10	GPIO	PF1	C11	GPIO (5V)
PC14	C12	GPIO (5V)	PC15	C13	GPIO (5V)
PA3	D1	GPIO	PA2	D2	GPIO
PB15	D3	GPIO (5V)	PF0	D11	GPIO (5V)
PC12	D12	GPIO (5V)	PC13	D13	GPIO (5V)
PA6	E1	GPIO	PA5	E2	GPIO
PA4	E3	GPIO	PC9	E11	GPIO (5V)
PC10	E12	GPIO (5V)	PC11	E13	GPIO (5V)
PB0	F1	GPIO	PB1	F2	GPIO
PB2	F3	GPIO	PE6	F11	GPIO
PE7	F12	GPIO	PC8	F13	GPIO (5V)
PB3	G1	GPIO	PB4	G2	GPIO
IOVDD2	G3	Digital IO power supply 2.	PE3	G11	GPIO
PE4	G12	GPIO	PE5	G13	GPIO
PB5	H1	GPIO	PB6	H2	GPIO
DVDD	H11	Digital power supply.	PE2	H12	GPIO
DECOUPLE	H13	Decouple output for on-chip voltage regulator. An external decoupling ca- pacitor is required at this pin.	PD14	J1	GPIO (5V)
PD15	J2	GPIO (5V)	PE1	J12	GPIO (5V)
VREGVDD	J13	Voltage regulator VDD input	PC0	K1	GPIO (5V)



### Figure 5.5. EFM32GG11B4xx in BGA120 Device Pinout

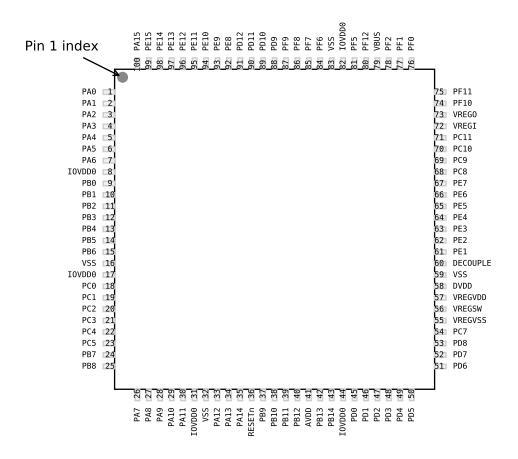
Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PE15	A1	GPIO	PE14	A2	GPIO
PE12	A3	GPIO	PE9	A4	GPIO
PD11	A5	GPIO	PD9	A6	GPIO
PF7	A7	GPIO	PF5	A8	GPIO
PF4	A9	GPIO	PF2	A10	GPIO
VREGI	A11	Input to 5 V regulator.	VREGO	A12	Decoupling for 5 V regulator and regu- lator output. Power for USB PHY in USB-enabled OPNs

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PD8	H8	GPIO	PD5	H9	GPIO
PD6	H10	GPIO	PD7	H11	GPIO
PC1	J1	GPIO (5V)	PC3	J2	GPIO (5V)
PD15	J3	GPIO (5V)	PA12	J4	GPIO (5V)
PA9	J5	GPIO	PA10	J6	GPIO
PB9	J7	GPIO (5V)	PB10	J8	GPIO (5V)
PD2	J9	GPIO (5V)	PD3	J10	GPIO
PD4	J11	GPIO	PB7	K1	GPIO
PC4	K2	GPIO	PA13	K3	GPIO (5V)
PA11	K5	GPIO	RESETn	K6	Reset input, active low. To apply an ex- ternal reset source to this pin, it is re- quired to only drive this pin low during reset, and let the internal pull-up ensure that reset is released.
AVDD	K8 K9 L10	Analog power supply.	PD1	K11	GPIO
PB8	L1	GPIO	PC5	L2	GPIO
PA14	L3	GPIO	PB11	L5	GPIO
PB12	L6	GPIO	PB13	L8	GPIO
PB14	L9	GPIO	PD0	L11	GPIO (5V)

## Note:

1. GPIO with 5V tolerance are indicated by (5V).

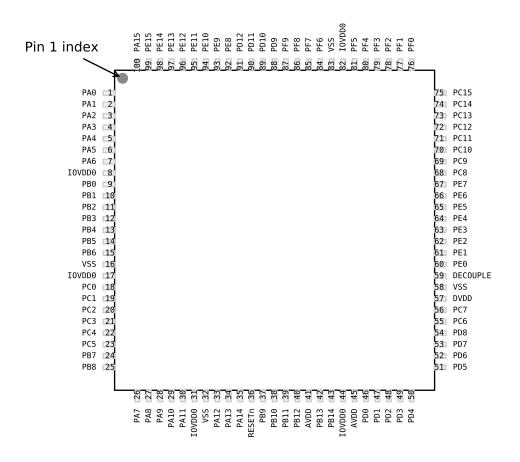
2. The pins PD13, PD14, and PD15 will not be 5V tolerant on all future devices. In order to preserve upgrade options with full hardware compatibility, do not use these pins with 5V domains.



### Figure 5.8. EFM32GG11B8xx in QFP100 Device Pinout

Table 5.8.	EFM32GG11B8xx in QFP100 Device Pinout
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Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PA0	1	GPIO	PA1	2	GPIO
PA2	3	GPIO	PA3	4	GPIO
PA4	5	GPIO	PA5	6	GPIO
PA6	7	GPIO	IOVDD0	8 17 31 44 82	Digital IO power supply 0.
PB0	9	GPIO	PB1	10	GPIO

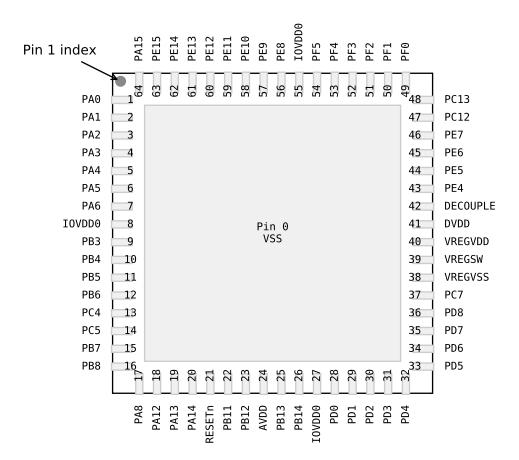


### Figure 5.11. EFM32GG11B3xx in QFP100 Device Pinout

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PA0	1	GPIO	PA1	2	GPIO
PA2	3	GPIO	PA3	4	GPIO
PA4	5	GPIO	PA5	6	GPIO
PA6	7	GPIO	IOVDD0	8 17 31 44 82	Digital IO power supply 0.
PB0	9	GPIO	PB1	10	GPIO

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PC4	13	GPIO	PC5	14	GPIO
PB7	15	GPIO	PB8	16	GPIO
PA12	17	GPIO (5V)	PA13	18	GPIO (5V)
PA14	19	GPIO	RESETn	20	Reset input, active low. To apply an ex- ternal reset source to this pin, it is re- quired to only drive this pin low during reset, and let the internal pull-up ensure that reset is released.
PB11	21	GPIO	AVDD	23 27	Analog power supply.
PB13	24	GPIO	PB14	25	GPIO
PD0	28	GPIO (5V)	PD1	29	GPIO
PD2	30	GPIO (5V)	PD3	31	GPIO
PD4	32	GPIO	PD5	33	GPIO
PD6	34	GPIO	PD7	35	GPIO
PD8	36	GPIO	PC6	37	GPIO
PC7	38	GPIO	DVDD	39	Digital power supply.
DECOUPLE	40	Decouple output for on-chip voltage regulator. An external decoupling capacitor is required at this pin.	PE4	41	GPIO
PE5	42	GPIO	PE6	43	GPIO
PE7	44	GPIO	VREGI	45	Input to 5 V regulator.
VREGO	46	Decoupling for 5 V regulator and regu- lator output. Power for USB PHY in USB-enabled OPNs	PF10	47	GPIO (5V)
PF11	48	GPIO (5V)	PF0	49	GPIO (5V)
PF1	50	GPIO (5V)	PF2	51	GPIO
VBUS	52	USB VBUS signal and auxiliary input to 5 V regulator.	PF12	53	GPIO
PF5	54	GPIO	PE8	57	GPIO
PE9	58	GPIO	PE10	59	GPIO
PE11	60	GPIO	PE12	61	GPIO
PE13	62	GPIO	PE14	63	GPIO
PE15	64	GPIO			

1. GPIO with 5V tolerance are indicated by (5V).



# Figure 5.17. EFM32GG11B5xx in QFN64 Device Pinout

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
VSS	0	Ground	PA0	1	GPIO
PA1	2	GPIO	PA2	3	GPIO
PA3	4	GPIO	PA4	5	GPIO
PA5	6	GPIO	PA6	7	GPIO
IOVDD0	8 27 55	Digital IO power supply 0.	PB3	9	GPIO
PB4	10	GPIO	PB5	11	GPIO

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PB6	12	GPIO	PC4	13	GPIO
PC5	14	GPIO	PB7	15	GPIO
PB8	16	GPIO	PA12	17	GPIO (5V)
PA13	18	GPIO (5V)	PA14	19	GPIO
RESETn	20	Reset input, active low. To apply an ex- ternal reset source to this pin, it is re- quired to only drive this pin low during reset, and let the internal pull-up ensure that reset is released.	PB11	21	GPIO
PB12	22	GPIO	AVDD	23 27	Analog power supply.
PB13	24	GPIO	PB14	25	GPIO
PD0	28	GPIO (5V)	PD1	29	GPIO
PD2	30	GPIO (5V)	PD3	31	GPIO
PD4	32	GPIO	PD5	33	GPIO
PD6	34	GPIO	PD7	35	GPIO
PD8	36	GPIO	PC6	37	GPIO
PC7	38	GPIO	DVDD	39	Digital power supply.
DECOUPLE	40	Decouple output for on-chip voltage regulator. An external decoupling capacitor is required at this pin.	PE4	41	GPIO
PE5	42	GPIO	PE6	43	GPIO
PE7	44	GPIO	VREGI	45	Input to 5 V regulator.
VREGO	46	Decoupling for 5 V regulator and regu- lator output. Power for USB PHY in USB-enabled OPNs	PF10	47	GPIO (5V)
PF11	48	GPIO (5V)	PF0	49	GPIO (5V)
PF1	50	GPIO (5V)	PF2	51	GPIO
VBUS	52	USB VBUS signal and auxiliary input to 5 V regulator.	PF12	53	GPIO
PF5	54	GPIO	PE8	56	GPIO
PE9	57	GPIO	PE10	58	GPIO
PE11	59	GPIO	PE12	60	GPIO
PE13	61	GPIO	PE14	62	GPIO
PE15	63	GPIO	PA15	64	GPIO

1. GPIO with 5V tolerance are indicated by (5V).

GPIO Name		Pin Alternate Functionality / Description					
	Analog	EBI	Timers	Communication	Other		
PB13	BUSAY BUSBX HFXTAL_P		TIM6_CC0 #5 WTIM1_CC0 #0 PCNT2_S0IN #2	US0_CLK #4 US1_CTS #5 US5_CS #0 LEU0_TX #1	CMU_CLKI0 #3 PRS_CH7 #0		
PB14	BUSBY BUSAX HFXTAL_N		TIM6_CC1 #5 WTIM1_CC1 #0 PCNT2_S1IN #2	US0_CS #4 US1_RTS #5 US5_CTS #0 LEU0_RX #1	PRS_CH6 #1		
PD1	VDAC0_OUT1ALT / OPA1_OUTALT #4 BUSADC0Y BU- SADC0X OPA3_OUT	EBI_A05 #1 EBI_A14 #3	TIM4_CDTI1 TIM0_CC0 #2 TIM6_CC0 #6 WTIM1_CC3 #0 PCNT2_S1IN #0	CAN0_TX #2 US1_RX #1	DBG_SWO #2		
PD6	BUSADC0Y BU- SADC0X ADC0_EXTP VDAC0_EXT ADC1_EXTP OPA1_P	EBI_A10 #1 EBI_A19 #3	TIM1_CC0 #4 TIM6_CC2 #7 WTIM0_CDTI2 #4 WTIM1_CC0 #2 LE- TIM0_OUT0 #0 PCNT0_S0IN #3	US0_RTS #5 US1_RX #2 US2_CTS #5 US3_CTS #2 U0_RTS #5 I2C0_SDA #1	CMU_CLK2 #2 LES_ALTEX0 PRS_CH5 #2 ACMP0_O #2 ETM_TD0 #0		

Alternate	LOCA	TION	
Functionality	0 - 3	4 - 7	Description
LFXTAL_N	0: PB8		Low Frequency Crystal (typically 32.768 kHz) negative pin. Also used as an optional ex- ternal clock input pin.
LFXTAL_P	0: PB7		Low Frequency Crystal (typically 32.768 kHz) positive pin.
OPA0_N	0: PC5		Operational Amplifier 0 external negative input.
OPA0_P	0: PC4		Operational Amplifier 0 external positive input.
OPA1_N	0: PD7		Operational Amplifier 1 external negative input.
OPA1_P	0: PD6		Operational Amplifier 1 external positive input.
OPA2_N	0: PD3		Operational Amplifier 2 external negative input.
OPA2_OUT	0: PD5		Operational Amplifier 2 output.
OPA2_OUTALT	0: PD0		Operational Amplifier 2 alternative output.
OPA2_P	0: PD4		Operational Amplifier 2 external positive input.
OPA3_N	0: PC7		Operational Amplifier 3 external negative input.
OPA3_OUT	0: PD1		Operational Amplifier 3 output.
OPA3_P	0: PC6		Operational Amplifier 3 external positive input.

Alternate	LOC	ATION	
Functionality	0 - 3	4 - 7	Description
SDIO_DAT7	0: PD9 1: PB4		SDIO Data 7.
SDIO_WP	0: PF9 1: PC5 2: PB15 3: PB9		SDIO Write Protect.
ТІМ0_ССО	0: PA0 1: PF6 2: PD1 3: PB6	4: PF0 5: PC4 6: PA8 7: PA1	Timer 0 Capture Compare input / output channel 0.
TIM0_CC1	0: PA1 1: PF7 2: PD2 3: PC0	4: PF1 5: PC5 6: PA9 7: PA0	Timer 0 Capture Compare input / output channel 1.
TIM0_CC2	0: PA2 1: PF8 2: PD3 3: PC1	4: PF2 5: PA7 6: PA10 7: PA13	Timer 0 Capture Compare input / output channel 2.
TIM0_CDTI0	0: PA3 1: PC13 2: PF3 3: PC2	4: PB7	Timer 0 Complimentary Dead Time Insertion channel 0.
TIM0_CDTI1	0: PA4 1: PC14 2: PF4 3: PC3	4: PB8	Timer 0 Complimentary Dead Time Insertion channel 1.
TIM0_CDTI2	0: PA5 1: PC15 2: PF5 3: PC4	4: PB11	Timer 0 Complimentary Dead Time Insertion channel 2.
TIM1_CC0	0: PC13 1: PE10 2: PB0 3: PB7	4: PD6 5: PF2 6: PF13 7: PI6	Timer 1 Capture Compare input / output channel 0.
TIM1_CC1	0: PC14 1: PE11 2: PB1 3: PB8	4: PD7 5: PF3 6: PF14 7: PI7	Timer 1 Capture Compare input / output channel 1.
TIM1_CC2	0: PC15 1: PE12 2: PB2 3: PB11	4: PC13 5: PF4 6: PF15 7: PI8	Timer 1 Capture Compare input / output channel 2.
TIM1_CC3	0: PC12 1: PE13 2: PB3 3: PB12	4: PC14 5: PF12 6: PF5 7: PI9	Timer 1 Capture Compare input / output channel 3.
TIM2_CC0	0: PA8 1: PA12 2: PC8 3: PF2	4: PB6 5: PC2 6: PG8 7: PG5	Timer 2 Capture Compare input / output channel 0.

### Table 7.2. BGA152 PCB Land Pattern Dimensions

Min	Nom	Мах		
	0.20			
6.50				
6.50				
	0.5			
	0.5			
	Min	0.20 6.50 6.50 0.5		

# Note:

1. All dimensions shown are in millimeters (mm) unless otherwise noted.

2. Dimensioning and Tolerancing is per the ANSI Y14.5M-1994 specification.

3. This Land Pattern Design is based on the IPC-7351 guidelines.

4. All metal pads are to be non-solder mask defined (NSMD). Clearance between the solder mask and the metal pad is to be 60 μm minimum, all the way around the pad.

5. A stainless steel, laser-cut and electro-polished stencil with trapezoidal walls should be used to assure good solder paste release.

6. The stencil thickness should be 0.125 mm (5 mils).

7. The ratio of stencil aperture to land pad size should be 1:1.

8. A No-Clean, Type-3 solder paste is recommended.

9. The recommended card reflow profile is per the JEDEC/IPC J-STD-020C specification for Small Body Components.





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