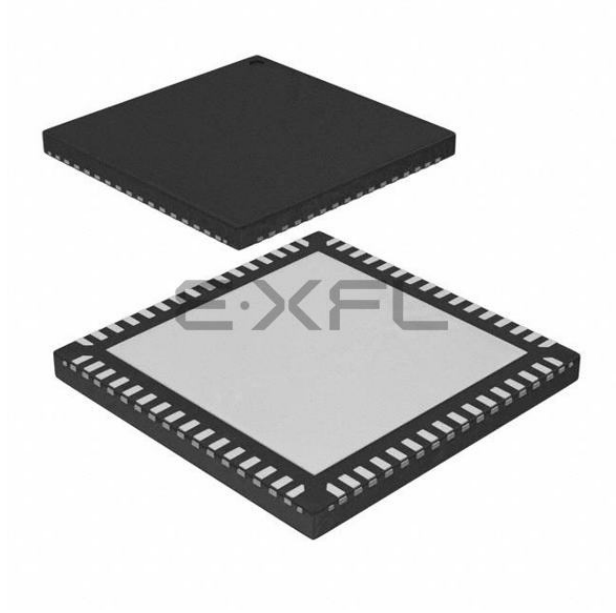
Silicon Labs - EFM32GG11B120F2048GM64-BR Datasheet



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Applications of "Embedded - Microcontrollers"

Details	
Product Status	Active
Core Processor	ARM® Cortex®-M4
Core Size	32-Bit Single-Core
Speed	72MHz
Connectivity	CANbus, EBI/EMI, I²C, IrDA, LINbus, SmartCard, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, POR, PWM, WDT
Number of I/O	56
Program Memory Size	2MB (2M x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	512K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.8V
Data Converters	A/D 16x12b SAR; D/A 2x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-VFQFN Exposed Pad
Supplier Device Package	64-QFN (9x9)
Purchase URL	https://www.e-xfl.com/product-detail/silicon-labs/efm32gg11b120f2048gm64-br

3.11 Memory Map

The EFM32GG11 memory map is shown in the figures below. RAM and flash sizes are for the largest memory configuration.

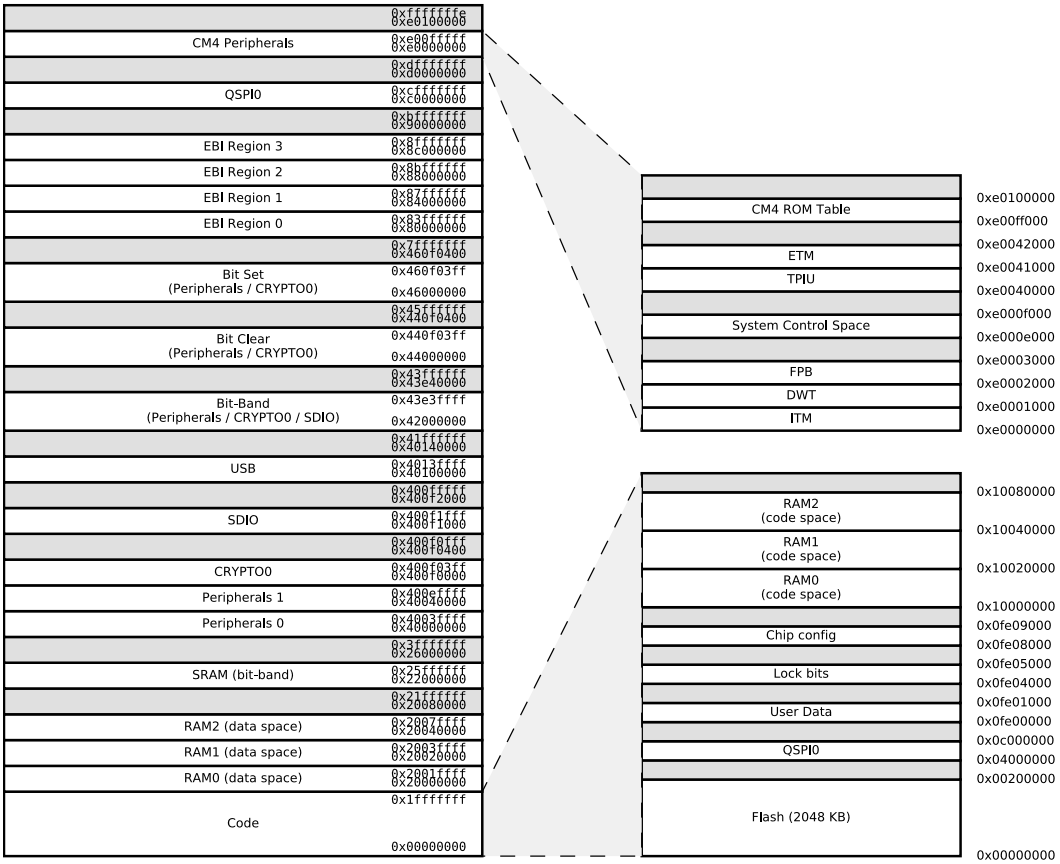

Figure 3.2. EFM32GG11 Memory Map — Core Peripherals and Code Space

4.1.10 Oscillators

4.1.10.1 Low-Frequency Crystal Oscillator (LFXO)

Table 4.12. Low-Frequency Crystal Oscillator (LFXO)

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Crystal frequency	f_{LFXO}		—	32.768	—	kHz
Supported crystal equivalent series resistance (ESR)	ESR_{LFXO}		—	—	70	kΩ
Supported range of crystal load capacitance [1]	C_{LFXO_CL}		6	—	18	pF
On-chip tuning cap range [2]	C_{LFXO_T}	On each of LFXTAL_N and LFXTAL_P pins	8	—	40	pF
On-chip tuning cap step size	SS_{LFXO}		—	0.25	—	pF
Current consumption after startup [3]	I_{LFXO}	ESR = 70 kOhm, C_L = 7 pF, GAIN[4] = 2, AGC[4] = 1	—	273	—	nA
Start- up time	t_{LFXO}	ESR = 70 kOhm, C_L = 7 pF, GAIN[4] = 2	—	308	—	ms

Note:

1. Total load capacitance as seen by the crystal.
2. The effective load capacitance seen by the crystal will be C_{LFXO_T} /2. This is because each XTAL pin has a tuning cap and the two caps will be seen in series by the crystal.
3. Block is supplied by AVDD if ANASW = 0, or DVDD if ANASW=1 in EMU_PWRCTRL register.
4. In CMU_LFXOCTRL register.

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Hysteresis (V_{CM} = 1.25 V, BIASPROG[4] = 0x10, FULLBIAS[4] = 1)	$V_{ACMPHYST}$	HYSTSEL[5] = HYST0	TBD	0	TBD	mV
		HYSTSEL[5] = HYST1	TBD	18	TBD	mV
		HYSTSEL[5] = HYST2	TBD	33	TBD	mV
		HYSTSEL[5] = HYST3	TBD	46	TBD	mV
		HYSTSEL[5] = HYST4	TBD	57	TBD	mV
		HYSTSEL[5] = HYST5	TBD	68	TBD	mV
		HYSTSEL[5] = HYST6	TBD	79	TBD	mV
		HYSTSEL[5] = HYST7	TBD	90	TBD	mV
		HYSTSEL[5] = HYST8	TBD	0	TBD	mV
		HYSTSEL[5] = HYST9	TBD	-18	TBD	mV
		HYSTSEL[5] = HYST10	TBD	-33	TBD	mV
		HYSTSEL[5] = HYST11	TBD	-45	TBD	mV
		HYSTSEL[5] = HYST12	TBD	-57	TBD	mV
		HYSTSEL[5] = HYST13	TBD	-67	TBD	mV
		HYSTSEL[5] = HYST14	TBD	-78	TBD	mV
		HYSTSEL[5] = HYST15	TBD	-88	TBD	mV
Comparator delay[3]	$t_{ACMPDELAY}$	BIASPROG[4] = 1, FULLBIAS[4] = 0	—	30	—	µs
		BIASPROG[4] = 0x10, FULLBIAS[4] = 0	—	3.7	—	µs
		BIASPROG[4] = 0x02, FULLBIAS[4] = 1	—	360	—	ns
		BIASPROG[4] = 0x20, FULLBIAS[4] = 1	—	35	—	ns
Offset voltage	$V_{ACMPOFFSET}$	BIASPROG[4] =0x10, FULLBIAS[4] = 1	TBD	—	TBD	mV
Reference voltage	$V_{ACMPREF}$	Internal 1.25 V reference	TBD	1.25	TBD	V
		Internal 2.5 V reference	TBD	2.5	TBD	V
Capacitive sense internal resistance	R_{CSRES}	CSRESSEL[6] = 0	—	infinite	—	kΩ
		CSRESSEL[6] = 1	—	15	—	kΩ
		CSRESSEL[6] = 2	—	27	—	kΩ
		CSRESSEL[6] = 3	—	39	—	kΩ
		CSRESSEL[6] = 4	—	51	—	kΩ
		CSRESSEL[6] = 5	—	100	—	kΩ
		CSRESSEL[6] = 6	—	162	—	kΩ
		CSRESSEL[6] = 7	—	235	—	kΩ

4.1.21 Pulse Counter (PCNT)

Table 4.29. Pulse Counter (PCNT)

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Input frequency	F_{IN}	Asynchronous Single and Quadrature Modes	—	—	20	MHz
		Sampled Modes with Debounce filter set to 0.	—	—	8	kHz

4.1.22 Analog Port (APORT)

Table 4.30. Analog Port (APORT)

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Supply current[2] [1]	I_{APORT}	Operation in EM0/EM1	—	7	—	µA
		Operation in EM2/EM3	—	915	—	nA

Note:

1. Specified current is for continuous APORT operation. In applications where the APORT is not requested continuously (e.g. periodic ACMP requests from LESENSE in EM2), the average current requirements can be estimated by mutiplying the duty cycle of the requests by the specified continuous current number.
2. Supply current increase that occurs when an analog peripheral requests access to APORT. This current is not included in reported module currents. Additional peripherals requesting access to APORT do not incur further current.

EBI Read Enable Output Timing

Timing applies to both EBI_REn and EBI_NANDREn for all addressing modes and both polarities. Output timing for EBI_AD applies only to multiplexed addressing modes D8A24ALE and D16A16ALE. All numbers are based on route locations 0,1,2 only (with all EBI alternate functions using the same location at the same time). Timing is specified at 10% and 90% of IOVDD, 25 pF external loading, and slew rate for all GPIO set to 6.

Table 4.38. EBI Read Enable Output Timing

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Output hold time, from trailing EBI_REn / EBI_NANDREn edge to EBI_AD, EBI_A, EBI_CSn, EBI_BLn invalid	t_{OH_REn}	IOVDD ≥ 1.62 V	-23 + (RDHOLD * $t_{HFCORECLK}$)	—	—	ns
		IOVDD ≥ 3.0 V	-13 + (RDHOLD * $t_{HFCORECLK}$)	—	—	ns
Output setup time, from EBI_AD, EBI_A, EBI_CSn, EBI_BLn valid to leading EBI_REn / EBI_NANDREn edge [1]	t_{OSU_REn}	IOVDD ≥ 1.62 V	-12 + (RDSETUP * $t_{HFCORECLK}$)	—	—	ns
		IOVDD ≥ 3.0 V	-11 + (RDSETUP * $t_{HFCORECLK}$)	—	—	ns
EBI_REn pulse width[1] [2]	t_{WIDTH_REn}	IOVDD ≥ 1.62 V	-6 + (MAX(1, RDSTRB) * $t_{HFCORECLK}$)	—	—	ns
		IOVDD ≥ 3.0 V	-4 + (MAX(1, RDSTRB) * $t_{HFCORECLK}$)	—	—	ns

Note:

1. The figure shows the timing for the case that the half strobe length functionality is not used, i.e. HALFRE=0. The leading edge of EBI_REn can be moved to the right by setting HALFRE=1. This decreases the length of t_{WIDTH_REn} and increases the length of t_{OSU_REn} by 1/2 * $t_{HFCLKNODIV}$.
2. When page mode is used, RDSTRB is replaced by RDPA for page hits.

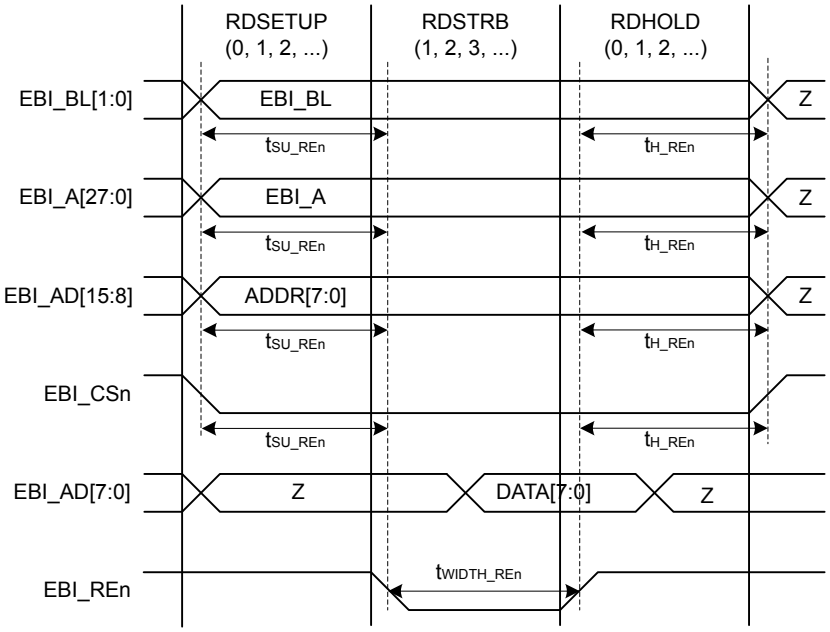

Figure 4.5. EBI Read Enable Output Timing Diagram

MII Receive Timing

Timing is specified with 3.0 V ≤ IOVDD ≤ 3.8 V, 25 pF external loading, and slew rate for all GPIO set to 6 unless otherwise indicated.

Table 4.43. Ethernet MII Receive Timing

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
RX_CLK frequency	F_{RX_CLK}		—	25	—	MHz
RX_CLK duty cycle	DC_{RX_CLK}		35	—	65	%
Setup time, RXD[3:0], RX_DV, RX_ER valid to RX_CLK	t_{SU}		6	—	—	ns
Hold time, RX_CLK to RXD[3:0], RX_DV, RX_ER change	t_{HD}		5	—	—	ns

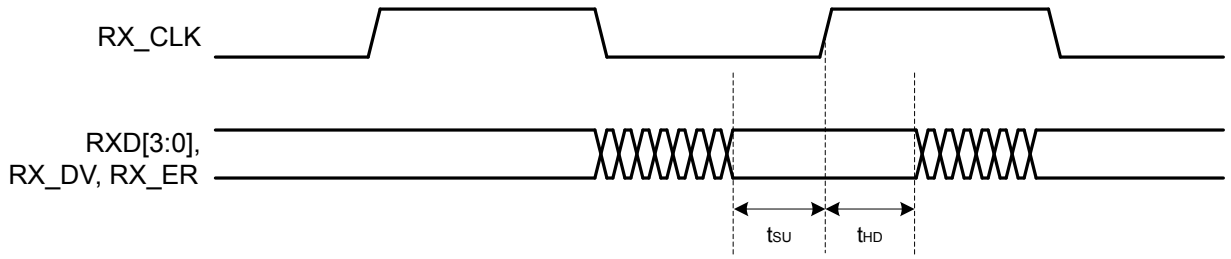

Figure 4.10. Ethernet MII Receive Timing

RMII Transmit Timing

Timing is specified with 3.0 V ≤ IOVDD ≤ 3.8 V, 25 pF external loading, and slew rate for all GPIO set to 6 unless otherwise indicated.

Table 4.44. Ethernet RMII Transmit Timing

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
REF_CLK frequency	F_{REF_CLK}	Output slew rate set to 7	—	50	—	MHz
REF_CLK duty cycle	DC_{REF_CLK}		35	—	65	%
Output delay, REF_CLK to TXD[1:0], TX_EN	t_{OUT}		2.3	—	14.1	ns

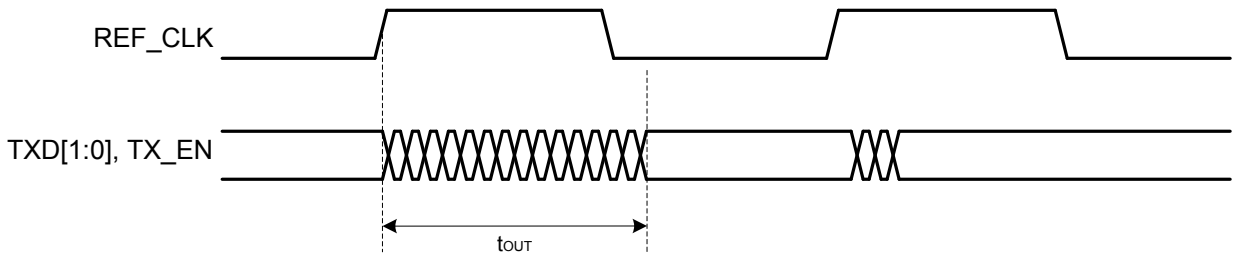

Figure 4.11. Ethernet RMII Transmit Timing

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
VBUS	A13	USB VBUS signal and auxiliary input to 5 V regulator.	PF11	A14	GPIO (5V)
PF10	A15	GPIO (5V)	PF0	A16	GPIO (5V)
PA0	B1	GPIO	PD11	B2	GPIO
PD10	B3	GPIO	PD9	B4	GPIO
PF9	B5	GPIO	PF8	B6	GPIO
PF7	B7	GPIO	PF6	B8	GPIO
PI11	B9	GPIO (5V)	PI8	B10	GPIO (5V)
PF5	B11	GPIO	PF13	B12	GPIO (5V)
PF3	B13	GPIO	PF2	B14	GPIO
PF1	B15	GPIO (5V)	VREGO	B16	Decoupling for 5 V regulator and regulator output. Power for USB PHY in USB-enabled OPNs
PA1	C1	GPIO	PD12	C2	GPIO
PD14	C3	GPIO (5V)	PD13	C4	GPIO (5V)
PI15	C5	GPIO (5V)	PI14	C6	GPIO (5V)
PI13	C7	GPIO (5V)	PI12	C8	GPIO (5V)
PI10	C9	GPIO (5V)	PI7	C10	GPIO (5V)
PF15	C11	GPIO (5V)	PF12	C12	GPIO
PF4	C13	GPIO	PC15	C14	GPIO (5V)
PC14	C15	GPIO (5V)	VREGI	C16	Input to 5 V regulator.
PA2	D1	GPIO	PG0	D2	GPIO (5V)
PD15	D3	GPIO (5V)	PC13	D14	GPIO (5V)
PC12	D15	GPIO (5V)	PC11	D16	GPIO (5V)
PA3	E1	GPIO	PG2	E2	GPIO (5V)
PG1	E3	GPIO (5V)	PC10	E14	GPIO (5V)
PC9	E15	GPIO (5V)	PC8	E16	GPIO (5V)
PA4	F1	GPIO	PG4	F2	GPIO (5V)
PG3	F3	GPIO (5V)	IOVDD2	F6 G6	Digital IO power supply 2.

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PG6	H1	GPIO (5V)	PG7	H2	GPIO (5V)
PG5	H3	GPIO (5V)	PE6	H12	GPIO
PE5	H13	GPIO	DVDD	H14	Digital power supply.
PG9	J1	GPIO (5V)	PG10	J2	GPIO (5V)
PG8	J3	GPIO (5V)	PE3	J12	GPIO
PE4	J13	GPIO	VREGVDD	J14	Voltage regulator VDD input
PG12	K1	GPIO	PG13	K2	GPIO
PG11	K3	GPIO (5V)	PE2	K12	GPIO
PE1	K13	GPIO (5V)	VREGSW	K14	DCDC regulator switching node
PG15	L1	GPIO (5V)	PB15	L2	GPIO (5V)
PG14	L3	GPIO	PC7	L12	GPIO
PE0	L13	GPIO (5V)	VREGVSS	L14	Voltage regulator VSS
PB0	M1	GPIO	PB1	M2	GPIO
PB4	M3	GPIO	PC0	M4	GPIO (5V)
PC3	M5	GPIO (5V)	PA9	M6	GPIO
BODEN	M7	Brown-Out Detector Enable. This pin may be left disconnected or tied to AVDD.	PA12	M8	GPIO (5V)
RESETn	M9	Reset input, active low. To apply an external reset source to this pin, it is required to only drive this pin low during reset, and let the internal pull-up ensure that reset is released.	PB10	M10	GPIO (5V)
PD1	M11	GPIO	PC6	M12	GPIO
PD5	M13	GPIO	PD8	M14	GPIO
PB7	N1	GPIO	PB2	N2	GPIO
PB5	N3	GPIO	PC2	N4	GPIO (5V)
PC5	N5	GPIO	PA8	N6	GPIO
PA11	N7	GPIO	PA14	N8	GPIO
PB11	N9	GPIO	PB12	N10	GPIO
PD0	N11	GPIO (5V)	PD2	N12	GPIO (5V)
PD4	N13	GPIO	PD7	N14	GPIO
PB8	P1	GPIO	PB3	P2	GPIO
PB6	P3	GPIO	PC1	P4	GPIO (5V)
PC4	P5	GPIO	PA7	P6	GPIO
PA10	P7	GPIO	PA13	P8	GPIO (5V)
PB9	P9	GPIO (5V)	PB13	P10	GPIO
PB14	P11	GPIO	AVDD	P12	Analog power supply.
PD3	P13	GPIO	PD6	P14	GPIO

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description

Note:

1. GPIO with 5V tolerance are indicated by (5V).
2. The pins PD13, PD14, and PD15 will not be 5V tolerant on all future devices. In order to preserve upgrade options with full hardware compatibility, do not use these pins with 5V domains.

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PC4	13	GPIO	PC5	14	GPIO
PB7	15	GPIO	PB8	16	GPIO
PA8	17	GPIO	PA12	18	GPIO (5V)
PA14	19	GPIO	RESETn	20	Reset input, active low. To apply an external reset source to this pin, it is required to only drive this pin low during reset, and let the internal pull-up ensure that reset is released.
PB11	21	GPIO	PB12	22	GPIO
AVDD	24	Analog power supply.	PB13	25	GPIO
PB14	26	GPIO	PD0	28	GPIO (5V)
PD1	29	GPIO	PD2	30	GPIO (5V)
PD3	31	GPIO	PD4	32	GPIO
PD5	33	GPIO	PD6	34	GPIO
PD8	35	GPIO	VREGVSS	36	Voltage regulator VSS
VREGSW	37	DCDC regulator switching node	VREGVDD	38	Voltage regulator VDD input
DVDD	39	Digital power supply.	DECOUPLE	40	Decouple output for on-chip voltage regulator. An external decoupling capacitor is required at this pin.
PE4	41	GPIO	PE5	42	GPIO
PE6	43	GPIO	PE7	44	GPIO
VREGI	45	Input to 5 V regulator.	VREGO	46	Decoupling for 5 V regulator and regulator output. Power for USB PHY in USB-enabled OPNs
PF10	47	GPIO (5V)	PF11	48	GPIO (5V)
PF0	49	GPIO (5V)	PF1	50	GPIO (5V)
PF2	51	GPIO	VBUS	52	USB VBUS signal and auxiliary input to 5 V regulator.
PF12	53	GPIO	PF5	54	GPIO
PE8	57	GPIO	PE9	58	GPIO
PE10	59	GPIO	PE11	60	GPIO
PE12	61	GPIO	PE13	62	GPIO
PE14	63	GPIO	PE15	64	GPIO

Note:

1. GPIO with 5V tolerance are indicated by (5V).

GPIO Name	Pin Alternate Functionality / Description				
	Analog	EBI	Timers	Communication	Other
PD13		EBI_ARDY #1	TIM2_CDTI0 #1 TIM3_CC1 #6 WTIM0_CC1 #1	ETH_MDIO #1 US4_CTS #1 US5_CLK #1	ETM_TD1 #1
PI15				CAN1_TX #7 US3_CS #5	
PI14				CAN1_RX #7 US3_CLK #5	
PI13				CAN0_TX #7 US3_RX #5	
PI12				CAN0_RX #7 US3_TX #5	
PI10		EBI_A15 #2	TIM4_CC2 #3	US4_CTS #3	
PI7		EBI_A12 #2	TIM1_CC1 #7 TIM4_CC2 #2 WTIM3_CC1 #5	US4_RX #3	
PF15	BUSCY BUSDX		TIM1_CC2 #6 TIM4_CC2 #1 WTIM3_CC2 #7	US5_TX #2 I2C2_SDA #5	
PF12	BUSDY BUSCX	EBI_NANDREn #5	TIM4_CC2 #0 TIM1_CC3 #5 TIM5_CC0 #7 WTIM3_CC2 #6	US5_CS #2 I2C2_SCL #3 USB_ID	
PF4	BUSDY BUSCX LCD_SEG2	EBI_WEn #0 EBI_WEn #5	TIM4_CC1 #0 TIM0_CDTI1 #2 TIM1_CC2 #5 WTIM3_CC1 #6	US1_RTS #2 I2C2_SDA #3	PRS_CH1 #1
PC15	VDAC0_OUT1ALT / OPA1_OUTALT #3 BUSACMP1Y BUSACMP1X	EBI_NANDREn #4	TIM0_CDTI2 #1 TIM1_CC2 #0 WTIM0_CC0 #4 LETIM0_OUT1 #5	US0_CLK #3 US1_CLK #3 US3_RTS #3 U0_RX #3 U1_RTS #0 LEU0_RX #5 I2C2_SCL #1	LES_CH15 PRS_CH1 #2 ACMP3_O #1 DBG_SWO #1
PC14	VDAC0_OUT1ALT / OPA1_OUTALT #2 BUSACMP1Y BUSACMP1X	EBI_NANDWEn #4	TIM0_CDTI1 #1 TIM1_CC1 #0 TIM1_CC3 #4 TIM5_CC0 #6 WTIM3_CC0 #3 LETIM0_OUT0 #5 PCNT0_S1IN #0	US0_CS #3 US1_CS #3 US2_RTS #3 US3_CS #2 U0_TX #3 U1_CTS #0 LEU0_TX #5 I2C2_SDA #1	LES_CH14 PRS_CH0 #2 ACMP3_O #2
PA2	BUSBY BUSAX LCD_SEG15	EBI_AD11 #0 EBI_DTEN #3	TIM0_CC2 #0 TIM3_CC2 #4	ETH_RMIIRXD0 #0 ETH_MIITXD2 #0 SDIO_DAT2 #1 US1_RX #6 US3_CLK #0 QSPI0_DQ0 #1	CMU_CLK0 #0 PRS_CH8 #1 ETM_TD0 #3
PG0	BUSACMP2Y BUSACMP2X	EBI_AD00 #2	TIM6_CC0 #0 TIM2_CDTI0 #3 WTIM0_CDTI1 #1 LETIM1_OUT0 #6	ETH_MIITXCLK #1 US3_TX #4 QSPI0_SCLK #2	CMU_CLK2 #3

GPIO Name	Pin Alternate Functionality / Description				
	Analog	EBI	Timers	Communication	Other
PD15		EBI_NANDREn #1	TIM2_CDTI2 #1 TIM3_CC0 #7 WTIM0_CDTI0 #1 PCNT1_S0IN #2	ETH_TSUEXTCLK #1 CAN0_TX #5 US5_CTS #1 I2C0_SCL #3	
PC13	VDAC0_OUT1ALT / OPA1_OUTALT #1 BUSACMP1Y BUSACMP1X	EBI_ARDY #4	TIM0_CDTI0 #1 TIM1_CC0 #0 TIM1_CC2 #4 TIM5_CC2 #5 WTIM3_CC2 #2 PCNT0_S0IN #0 PCNT2_S1IN #4	US0_CTS #3 US1_RTS #4 US2_RTS #4 U0_CTS #3 U1_RX #0 I2C2_SCL #6	LES_CH13 PRS_CH21 #1 ACMP3_O #3
PC12	VDAC0_OUT1ALT / OPA1_OUTALT #0 BUSACMP1Y BUSACMP1X		TIM1_CC3 #0 TIM5_CC1 #5 WTIM3_CC1 #2 PCNT2_S0IN #4	CAN1_RX #4 US0_RTS #3 US1_CTS #4 US2_CTS #4 U0_RTS #3 U1_TX #0 I2C2_SDA #6	CMU_CLK0 #1 LES_CH12 PRS_CH20 #1
PC11	BUSACMP1Y BUSACMP1X	EBI_ALE #4 EBI_ALE #5 EBI_A23 #1	TIM5_CC0 #5 WTIM3_CC0 #2	CAN1_TX #4 US0_TX #2 I2C1_SDA #4	LES_CH11 PRS_CH19 #1
PA3	BUSAY BUSBX LCD_SEG16	EBI_AD12 #0 EBI_VSNC #3	TIM0_CDTI0 #0 TIM3_CC0 #5	ETH_RMIIREFCLK #0 ETH_MIITXD1 #0 SDIO_DAT3 #1 US3_CS #0 U0_TX #2 QSPI0_DQ1 #1	CMU_CLK2 #1 CMU_CLKI0 #1 CMU_CLK2 #4 LES_ALTEX2 PRS_CH9 #1 ETM_TD1 #3
PG2	BUSACMP2Y BUSACMP2X	EBI_AD02 #2	TIM6_CC2 #0 TIM2_CDTI2 #3 WTIM0_CC0 #2 LETIM1_OUT0 #7	ETH_MIITXD2 #1 US3_CLK #4 QSPI0_DQ1 #2	CMU_CLK0 #3
PG1	BUSACMP2Y BUSACMP2X	EBI_AD01 #2	TIM6_CC1 #0 TIM2_CDTI1 #3 WTIM0_CDTI2 #1 LETIM1_OUT1 #6	ETH_MIITXD3 #1 US3_RX #4 QSPI0_DQ0 #2	CMU_CLK1 #3
PC10	BUSACMP1Y BUSACMP1X	EBI_A10 #2 EBI_A22 #1	TIM2_CC2 #2 TIM5_CC2 #4 WTIM3_CC2 #1	CAN1_TX #3 US0_RX #2	LES_CH10 PRS_CH18 #1
PC9	BUSACMP1Y BUSACMP1X	EBI_A09 #2 EBI_A21 #1 EBI_A27 #3	TIM2_CC1 #2 TIM5_CC1 #4 WTIM3_CC1 #1	CAN1_RX #3 US0_CLK #2	LES_CH9 PRS_CH5 #0 GPIO_EM4WU2
PC8	BUSACMP1Y BUSACMP1X	EBI_A08 #2 EBI_A15 #0 EBI_A20 #1 EBI_A26 #3	TIM2_CC0 #2 TIM5_CC0 #4 WTIM3_CC0 #1	US0_CS #2	LES_CH8 PRS_CH4 #0
PA4	BUSBY BUSAX LCD_SEG17	EBI_AD13 #0 EBI_HSNC #3	TIM0_CDTI1 #0 TIM3_CC1 #5	ETH_RMIICRSDV #0 ETH_MIITXD0 #0 SDIO_DAT4 #1 US3_CTS #0 U0_RX #2 QSPI0_DQ2 #1	LES_ALTEX3 PRS_CH16 #0 ETM_TD2 #3
PG4	BUSACMP2Y BUSACMP2X	EBI_AD04 #2	TIM6_CDTI1 #0 WTIM0_CC2 #2	ETH_MIITXD0 #1 US3_CTS #4 QSPI0_DQ3 #2	

Alternate	LOCATION		
Functionality	0 - 3	4 - 7	Description
EBI_AD08	0: PA15 1: PC1 2: PG8		External Bus Interface (EBI) address and data input / output pin 08.
EBI_AD09	0: PA0 1: PC2 2: PG9		External Bus Interface (EBI) address and data input / output pin 09.
EBI_AD10	0: PA1 1: PC3 2: PG10		External Bus Interface (EBI) address and data input / output pin 10.
EBI_AD11	0: PA2 1: PC4 2: PG11		External Bus Interface (EBI) address and data input / output pin 11.
EBI_AD12	0: PA3 1: PC5 2: PG12		External Bus Interface (EBI) address and data input / output pin 12.
EBI_AD13	0: PA4 1: PA7 2: PG13		External Bus Interface (EBI) address and data input / output pin 13.
EBI_AD14	0: PA5 1: PA8 2: PG14		External Bus Interface (EBI) address and data input / output pin 14.
EBI_AD15	0: PA6 1: PA9 2: PG15		External Bus Interface (EBI) address and data input / output pin 15.
EBI_ALE	0: PF3 1: PB9 2: PC4 3: PB5	4: PC11 5: PC11	External Bus Interface (EBI) Address Latch Enable output.
EBI_ARDY	0: PF2 1: PD13 2: PB15 3: PB4	4: PC13 5: PF10	External Bus Interface (EBI) Hardware Ready Control input.
EBI_BL0	0: PF6 1: PF8 2: PB10 3: PC1	4: PF6 5: PF6	External Bus Interface (EBI) Byte Lane/Enable pin 0.
EBI_BL1	0: PF7 1: PF9 2: PB11 3: PC3	4: PF7 5: PF7	External Bus Interface (EBI) Byte Lane/Enable pin 1.
EBI_CS0	0: PD9 1: PA10 2: PC0 3: PB0	4: PE8	External Bus Interface (EBI) Chip Select output 0.

Alternate	LOCATION		
Functionality	0 - 3	4 - 7	Description
ETH_MDIO	0: PB3 1: PD13 2: PC0 3: PA15		Ethernet Management Data I/O.
ETH_MIICOL	0: PB2 1: PG15 2: PB4		Ethernet MII Collision Detect.
ETH_MIICRS	0: PB1 1: PG14 2: PB3		Ethernet MII Carrier Sense.
ETH_MIIRXCLK	0: PA15 1: PG7 2: PD12		Ethernet MII Receive Clock.
ETH_MIIRXD0	0: PE12 1: PG11 2: PF9		Ethernet MII Receive Data Bit 0.
ETH_MIIRXD1	0: PE13 1: PG10 2: PD9		Ethernet MII Receive Data Bit 1.
ETH_MIIRXD2	0: PE14 1: PG9 2: PD10		Ethernet MII Receive Data Bit 2.
ETH_MIIRXD3	0: PE15 1: PG8 2: PD11		Ethernet MII Receive Data Bit 3.
ETH_MIIRXDV	0: PE11 1: PG12 2: PF8		Ethernet MII Receive Data Valid.
ETH_MIIRXER	0: PE10 1: PG13 2: PF7		Ethernet MII Receive Error.
ETH_MIITXCLK	0: PA0 1: PG0		Ethernet MII Transmit Clock.
ETH_MIITXD0	0: PA4 1: PG4		Ethernet MII Transmit Data Bit 0.
ETH_MIITXD1	0: PA3 1: PG3		Ethernet MII Transmit Data Bit 1.

Alternate	LOCATION		
Functionality	0 - 3	4 - 7	Description
PRS_CH7	0: PB13 1: PA7 2: PE7		Peripheral Reflex System PRS, channel 7.
PRS_CH8	0: PA8 1: PA2 2: PE9		Peripheral Reflex System PRS, channel 8.
PRS_CH9	0: PA9 1: PA3 2: PB10		Peripheral Reflex System PRS, channel 9.
PRS_CH10	0: PA10 1: PC2 2: PD4		Peripheral Reflex System PRS, channel 10.
PRS_CH11	0: PA11 1: PC3 2: PD5		Peripheral Reflex System PRS, channel 11.
PRS_CH12	0: PA12 1: PB6 2: PD8		Peripheral Reflex System PRS, channel 12.
PRS_CH13	0: PA13 1: PB9 2: PE14		Peripheral Reflex System PRS, channel 13.
PRS_CH14	0: PA14 1: PC6 2: PE15		Peripheral Reflex System PRS, channel 14.
PRS_CH15	0: PA15 1: PC7 2: PF0		Peripheral Reflex System PRS, channel 15.
PRS_CH16	0: PA4 1: PB12 2: PE4		Peripheral Reflex System PRS, channel 16.
PRS_CH17	0: PA5 1: PB15 2: PE5		Peripheral Reflex System PRS, channel 17.
PRS_CH18	0: PB2 1: PC10 2: PC4		Peripheral Reflex System PRS, channel 18.
PRS_CH19	0: PB3 1: PC11 2: PC5		Peripheral Reflex System PRS, channel 19.

Alternate	LOCATION		
Functionality	0 - 3	4 - 7	Description
TIM2_CC1	0: PA9 1: PA13 2: PC9 3: PE12	4: PC0 5: PC3 6: PG9 7: PG6	Timer 2 Capture Compare input / output channel 1.
TIM2_CC2	0: PA10 1: PA14 2: PC10 3: PE13	4: PC1 5: PC4 6: PG10 7: PG7	Timer 2 Capture Compare input / output channel 2.
TIM2_CDTI0	0: PB0 1: PD13 2: PE8 3: PG0		Timer 2 Complimentary Dead Time Insertion channel 0.
TIM2_CDTI1	0: PB1 1: PD14 2: PE14 3: PG1		Timer 2 Complimentary Dead Time Insertion channel 1.
TIM2_CDTI2	0: PB2 1: PD15 2: PE15 3: PG2		Timer 2 Complimentary Dead Time Insertion channel 2.
TIM3_CC0	0: PE14 1: PE0 2: PE3 3: PE5	4: PA0 5: PA3 6: PA6 7: PD15	Timer 3 Capture Compare input / output channel 0.
TIM3_CC1	0: PE15 1: PE1 2: PE4 3: PE6	4: PA1 5: PA4 6: PD13 7: PB15	Timer 3 Capture Compare input / output channel 1.
TIM3_CC2	0: PA15 1: PE2 2: PE5 3: PE7	4: PA2 5: PA5 6: PD14 7: PB0	Timer 3 Capture Compare input / output channel 2.
TIM4_CC0	0: PF3 1: PF13 2: PF5 3: PI8	4: PF6 5: PF9 6: PD11 7: PE9	Timer 4 Capture Compare input / output channel 0.
TIM4_CC1	0: PF4 1: PF14 2: PI6 3: PI9	4: PF7 5: PD9 6: PD12 7: PE10	Timer 4 Capture Compare input / output channel 1.
TIM4_CC2	0: PF12 1: PF15 2: PI7 3: PI10	4: PF8 5: PD10 6: PE8 7: PE11	Timer 4 Capture Compare input / output channel 2.
TIM4_CDTI0	0: PD0		Timer 4 Complimentary Dead Time Insertion channel 0.
TIM4_CDTI1	0: PD1		Timer 4 Complimentary Dead Time Insertion channel 1.

Alternate	LOCATION		
Functionality	0 - 3	4 - 7	Description
US1_CTS	0: PB9 1: PD4 2: PF3 3: PC6	4: PC12 5: PB13 6: PH2	USART1 Clear To Send hardware flow control input.
US1_RTS	0: PB10 1: PD5 2: PF4 3: PC7	4: PC13 5: PB14 6: PH3	USART1 Request To Send hardware flow control output.
US1_RX	0: PC1 1: PD1 2: PD6 3: PF7	4: PC2 5: PA0 6: PA2	USART1 Asynchronous Receive. USART1 Synchronous mode Master Input / Slave Output (MISO).
US1_TX	0: PC0 1: PD0 2: PD7 3: PF6	4: PC1 5: PF2 6: PA14	USART1 Asynchronous Transmit. Also used as receive input in half duplex communication. USART1 Synchronous mode Master Output / Slave Input (MOSI).
US2_CLK	0: PC4 1: PB5 2: PA9 3: PA15	4: PF8 5: PF2	USART2 clock input / output.
US2_CS	0: PC5 1: PB6 2: PA10 3: PB11	4: PF9 5: PF5	USART2 chip select input / output.
US2_CTS	0: PC1 1: PB12 2: PA11 3: PB10	4: PC12 5: PD6	USART2 Clear To Send hardware flow control input.
US2_RTS	0: PC0 1: PB15 2: PA12 3: PC14	4: PC13 5: PD8	USART2 Request To Send hardware flow control output.
US2_RX	0: PC3 1: PB4 2: PA8 3: PA14	4: PF7 5: PF1	USART2 Asynchronous Receive. USART2 Synchronous mode Master Input / Slave Output (MISO).
US2_TX	0: PC2 1: PB3 2: PA7 3: PA13	4: PF6 5: PF0	USART2 Asynchronous Transmit. Also used as receive input in half duplex communication. USART2 Synchronous mode Master Output / Slave Input (MOSI).
US3_CLK	0: PA2 1: PD7 2: PD4 3: PG8	4: PG2 5: PI14	USART3 clock input / output.
US3_CS	0: PA3 1: PE4 2: PC14 3: PC0	4: PG3 5: PI15	USART3 chip select input / output.
US3_CTS	0: PA4 1: PE5 2: PD6 3: PG10	4: PG4 5: PG9	USART3 Clear To Send hardware flow control input.

Alternate Functionality	Location	Priority
QSPI0_DQS	0: PF9	High Speed
QSPI0_SCLK	0: PF6	High Speed
SDIO_CLK	0: PE13	High Speed
SDIO_CMD	0: PE12	High Speed
SDIO_DAT0	0: PE11	High Speed
SDIO_DAT1	0: PE10	High Speed
SDIO_DAT2	0: PE9	High Speed
SDIO_DAT3	0: PE8	High Speed
SDIO_DAT4	0: PD12	High Speed
SDIO_DAT5	0: PD11	High Speed
SDIO_DAT6	0: PD10	High Speed
SDIO_DAT7	0: PD9	High Speed
TIM0_CC0	3: PB6	Non-interference
TIM0_CC1	3: PC0	Non-interference
TIM0_CC2	3: PC1	Non-interference
TIM0_CDTI0	1: PC13	Non-interference
TIM0_CDTI1	1: PC14	Non-interference
TIM0_CDTI2	1: PC15	Non-interference
TIM2_CC0	0: PA8	Non-interference
TIM2_CC1	0: PA9	Non-interference
TIM2_CC2	0: PA10	Non-interference
TIM2_CDTI0	0: PB0	Non-interference
TIM2_CDTI1	0: PB1	Non-interference
TIM2_CDTI2	0: PB2	Non-interference
TIM4_CC0	0: PF3	Non-interference
TIM4_CC1	0: PF4	Non-interference
TIM4_CC2	0: PF12	Non-interference
TIM4_CDTI0	0: PD0	Non-interference
TIM4_CDTI1	0: PD1	Non-interference
TIM4_CDTI2	0: PD3	Non-interference
TIM6_CC0	0: PG0	Non-interference
TIM6_CC1	0: PG1	Non-interference
TIM6_CC2	0: PG2	Non-interference
TIM6_CDTI0	0: PG3	Non-interference
TIM6_CDTI1	0: PG4	Non-interference
TIM6_CDTI2	0: PG5	Non-interference

Table 11.2. TQFP64 PCB Land Pattern Dimensions

Dimension	Min	Max
C1	11.30	11.40
C2	11.30	11.40
E	0.50 BSC	
X	0.20	0.30
Y	1.40	1.50

Note:

1. All dimensions shown are in millimeters (mm) unless otherwise noted.
2. This Land Pattern Design is based on the IPC-7351 guidelines.
3. All metal pads are to be non-solder mask defined (NSMD). Clearance between the solder mask and the metal pad is to be 60 µm minimum, all the way around the pad.
4. A stainless steel, laser-cut and electro-polished stencil with trapezoidal walls should be used to assure good solder paste release.
5. The stencil thickness should be 0.125 mm (5 mils).
6. The ratio of stencil aperture to land pad size can be 1:1 for all pads.
7. A No-Clean, Type-3 solder paste is recommended.
8. The recommended card reflow profile is per the JEDEC/IPC J-STD-020 specification for Small Body Components.

11.3 TQFP64 Package Marking

Figure 11.3. TQFP64 Package Marking

The package marking consists of:

- PPPPPPPPPP – The part number designation.
- TTTTTT – A trace or manufacturing code. The first letter is the device revision.
- YY – The last 2 digits of the assembly year.
- WW – The 2-digit workweek when the device was assembled.