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What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	ARM® Cortex®-M4
Core Size	32-Bit Single-Core
Speed	72MHz
Connectivity	CANbus, EBI/EMI, Ethernet, I²C, IrDA, LINbus, MMC/SD/SDIO, QSPI, SmartCard, SPI, UART/USART, USB
Peripherals	Brown-out Detect/Reset, DMA, LCD, POR, PWM, WDT
Number of I/O	93
Program Memory Size	2MB (2M x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	512K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.8V
Data Converters	A/D 16x12b SAR; D/A 2x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	120-VFBGA
Supplier Device Package	120-BGA (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/silicon-labs/efm32gg11b420f2048gl120-b

• Timers/Counters

- 7× 16-bit Timer/Counter
 - 3 + 4 Compare/Capture/PWM channels (4 + 4 on one timer instance)
 - Dead-Time Insertion on several timer instances
- 4× 32-bit Timer/Counter
- 32-bit Real Time Counter and Calendar (RTCC)
- 24-bit Real Time Counter (RTC)
- 32-bit Ultra Low Energy CRYOTIMER for periodic wakeup from any Energy Mode
- 2× 16-bit Low Energy Timer for waveform generation
- 3× 16-bit Pulse Counter with asynchronous operation
- 2× Watchdog Timer with dedicated RC oscillator

• Low Energy Sensor Interface (LESENSE)

- Autonomous sensor monitoring in Deep Sleep Mode
- Wide range of sensors supported, including LC sensors and capacitive buttons
- Up to 16 inputs

• Ultra efficient Power-on Reset and Brown-Out Detector**• Debug Interface**

- 2-pin Serial Wire Debug interface
- 1-pin Serial Wire Viewer
- 4-pin JTAG interface
- Embedded Trace Macrocell (ETM)

• Pre-Programmed USB/UART Bootloader**• Wide Operating Range**

- 1.8 V to 3.8 V single power supply
- Integrated DC-DC, down to 1.8 V output with up to 200 mA load current for system
- Standard (-40 °C to 85 °C T_{AMB}) and Extended (-40 °C to 125 °C T_J) temperature grades available

• Packages

- QFN64 (9x9 mm)
- TQFP64 (10x10 mm)
- TQFP100 (14x14 mm)
- BGA112 (10x10 mm)
- BGA120 (7x7 mm)
- BGA152 (8x8 mm)
- BGA192 (7x7mm)

3.2.4 EM2 and EM3 Power Domains

The EFM32GG11 has three independent peripheral power domains for use in EM2 and EM3. Two of these domains are dynamic and can be shut down to save energy. Peripherals associated with the two dynamic power domains are listed in [Table 3.1 EM2 and EM3 Peripheral Power Subdomains on page 13](#). If all of the peripherals in a peripheral power domain are unused, the power domain for that group will be powered off in EM2 and EM3, reducing the overall current consumption of the device. Other EM2, EM3, and EM4-capable peripherals and functions not listed in the table below reside on the primary power domain, which is always on in EM2 and EM3.

Table 3.1. EM2 and EM3 Peripheral Power Subdomains

Peripheral Power Domain 1	Peripheral Power Domain 2
ACMP0	ACMP1
PCNT0	PCNT1
ADC0	PCNT2
LETIMER0	CSEN
LESENSE	VDAC0
APORT	LEUART0
-	LEUART1
-	LETIMER1
-	I2C0
-	I2C1
-	I2C2
-	IDAC
-	ADC1
-	ACMP2
-	ACMP3
-	LCD
-	RTC

3.3 General Purpose Input/Output (GPIO)

EFM32GG11 has up to 144 General Purpose Input/Output pins. GPIO are organized on three independent supply rails, allowing for interface to multiple logic levels in the system simultaneously. Each GPIO pin can be individually configured as either an output or input. More advanced configurations including open-drain, open-source, and glitch-filtering can be configured for each individual GPIO pin. The GPIO pins can be overridden by peripheral connections, like SPI communication. Each peripheral connection can be routed to several GPIO pins on the device. The input value of a GPIO pin can be routed through the Peripheral Reflex System to other peripherals. The GPIO subsystem supports asynchronous external pin interrupts.

3.4 Clocking

3.4.1 Clock Management Unit (CMU)

The Clock Management Unit controls oscillators and clocks in the EFM32GG11. Individual enabling and disabling of clocks to all peripheral modules is performed by the CMU. The CMU also controls enabling and configuration of the oscillators. A high degree of flexibility allows software to optimize energy consumption in any specific application by minimizing power dissipation in unused peripherals and oscillators.

4.1.6 Backup Supply Domain

Table 4.6. Backup Supply Domain

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Backup supply voltage range	V _{BU_VIN}		1.8	—	3.8	V
PWRRES resistor	R _{PWRRES}	EMU_BUCTRL_PWRRES = RES0	3400	3900	4400	Ω
		EMU_BUCTRL_PWRRES = RES1	1450	1800	2150	Ω
		EMU_BUCTRL_PWRRES = RES2	1000	1350	1700	Ω
		EMU_BUCTRL_PWRRES = RES3	525	815	1100	Ω
Output impedance between BU_VIN and BU_VOUT ²	R _{BU_VOUT}	EMU_BUCTRL_VOUTRES = STRONG	35	110	185	Ω
		EMU_BUCTRL_VOUTRES = MED	475	775	1075	Ω
		EMU_BUCTRL_VOUTRES = WEAK	5600	6500	7400	Ω
Supply current	I _{BU_VIN}	BU_VIN not powering backup domain	—	11	TBD	nA
		BU_VIN powering backup domain ¹	—	550	TBD	nA

Note:

1. Additional current required by backup circuitry when backup is active. Includes supply current of backup switches and backup regulator. Does not include supply current required for backed-up circuitry.
2. BU_VOUT and BU_STAT signals are not available in all package configurations. Check the device pinout for availability.

4.1.14 Analog to Digital Converter (ADC)

Specified at 1 Msps, ADCCLK = 16 MHz, BIASPROG = 0, GPBIASACC = 0, unless otherwise indicated.

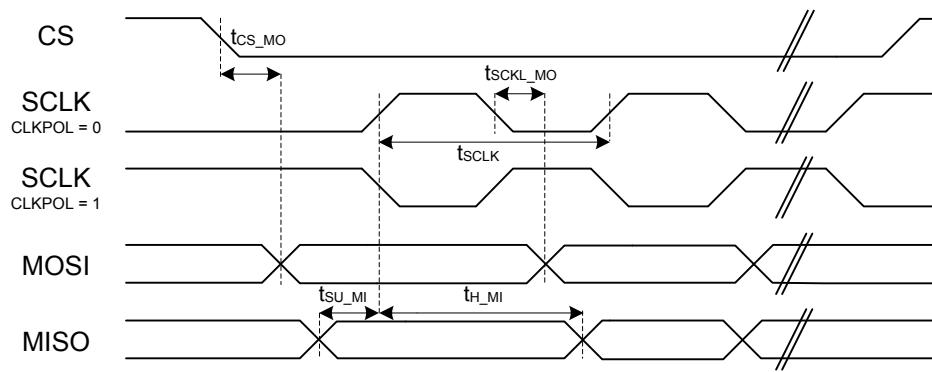
Table 4.22. Analog to Digital Converter (ADC)

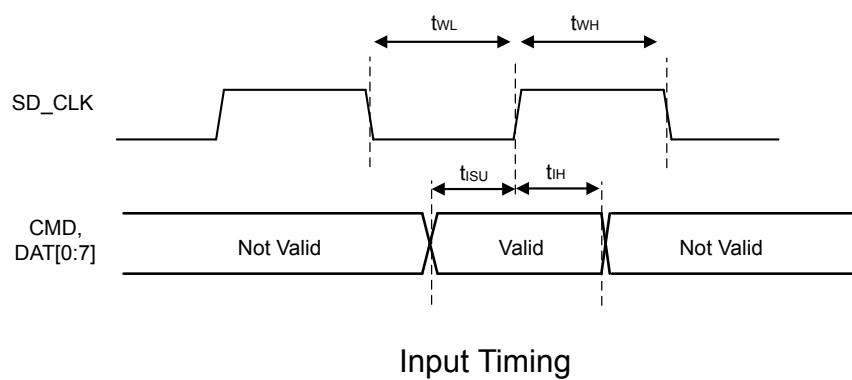
Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Resolution	V _{RESOLUTION}		6	—	12	Bits
Input voltage range ⁵	V _{ADCIN}	Single ended	—	—	V _{FS}	V
		Differential	-V _{FS} /2	—	V _{FS} /2	V
Input range of external reference voltage, single ended and differential	V _{ADCREFIN_P}		1	—	V _{AVDD}	V
Power supply rejection ²	PSRR _{ADC}	At DC	—	80	—	dB
Analog input common mode rejection ratio	CMRR _{ADC}	At DC	—	80	—	dB
Current from all supplies, using internal reference buffer. Continous operation. WAR-MUPMODE ⁴ = KEEPADC-WARM	I _{ADC_CONTINUOUS_LP}	1 Msps / 16 MHz ADCCLK, BIASPROG = 0, GPBIASACC = 1 ³	—	270	TBD	µA
		250 ksps / 4 MHz ADCCLK, BIASPROG = 6, GPBIASACC = 1 ³	—	125	—	µA
		62.5 ksps / 1 MHz ADCCLK, BIASPROG = 15, GPBIASACC = 1 ³	—	80	—	µA
Current from all supplies, using internal reference buffer. Duty-cycled operation. WAR-MUPMODE ⁴ = NORMAL	I _{ADC_NORMAL_LP}	35 ksps / 16 MHz ADCCLK, BIASPROG = 0, GPBIASACC = 1 ³	—	45	—	µA
		5 ksps / 16 MHz ADCCLK BIASPROG = 0, GPBIASACC = 1 ³	—	8	—	µA
Current from all supplies, using internal reference buffer. Duty-cycled operation. AWARMUPMODE ⁴ = KEEPINSTANDBY or KEEPIN-SLOWACC	I _{ADC_STANDBY_LP}	125 ksps / 16 MHz ADCCLK, BIASPROG = 0, GPBIASACC = 1 ³	—	105	—	µA
		35 ksps / 16 MHz ADCCLK, BIASPROG = 0, GPBIASACC = 1 ³	—	70	—	µA
Current from all supplies, using internal reference buffer. Continous operation. WAR-MUPMODE ⁴ = KEEPADC-WARM	I _{ADC_CONTINUOUS_HP}	1 Msps / 16 MHz ADCCLK, BIASPROG = 0, GPBIASACC = 0 ³	—	325	—	µA
		250 ksps / 4 MHz ADCCLK, BIASPROG = 6, GPBIASACC = 0 ³	—	175	—	µA
		62.5 ksps / 1 MHz ADCCLK, BIASPROG = 15, GPBIASACC = 0 ³	—	125	—	µA
Current from all supplies, using internal reference buffer. Duty-cycled operation. WAR-MUPMODE ⁴ = NORMAL	I _{ADC_NORMAL_HP}	35 ksps / 16 MHz ADCCLK, BIASPROG = 0, GPBIASACC = 0 ³	—	85	—	µA
		5 ksps / 16 MHz ADCCLK BIASPROG = 0, GPBIASACC = 0 ³	—	16	—	µA
Current from all supplies, using internal reference buffer. Duty-cycled operation. AWARMUPMODE ⁴ = KEEPINSTANDBY or KEEPIN-SLOWACC	I _{ADC_STANDBY_HP}	125 ksps / 16 MHz ADCCLK, BIASPROG = 0, GPBIASACC = 0 ³	—	160	—	µA
		35 ksps / 16 MHz ADCCLK, BIASPROG = 0, GPBIASACC = 0 ³	—	125	—	µA
Current from HPERCLK	I _{ADC_CLK}	HPERCLK = 16 MHz	—	180	—	µA

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
MISO hold time ^{1 3}	t_{H_MI}	USART2, location 4, IOVDD = 1.8 V	-11.6	—	—	ns
		USART2, location 4, IOVDD = 3.0 V	-11.6	—	—	ns
		USART2, location 5, IOVDD = 1.8 V	-9.1	—	—	ns
		USART2, location 5, IOVDD = 3.0 V	-9.1	—	—	ns
		All other USARTs and locations, IOVDD = 1.8 V	-8	—	—	ns
		All other USARTs and locations, IOVDD = 3.0 V	-8	—	—	ns

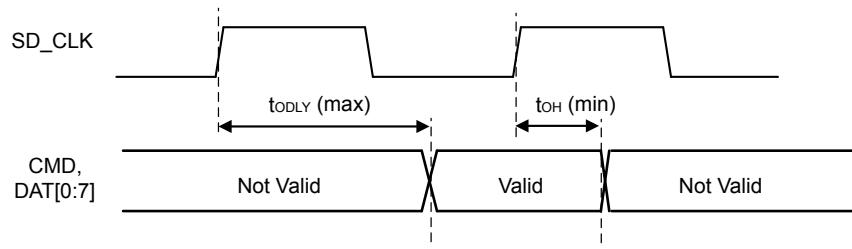
Note:

1. Applies for both CLKPHA = 0 and CLKPHA = 1 (figure only shows CLKPHA = 0).
2. $t_{HPERCLK}$ is one period of the selected HPERCLK.
3. Measurement done with 8 pF output loading at 10% and 90% of V_{DD} (figure shows 50% of V_{DD}).

**Figure 4.1. SPI Master Timing Diagram**

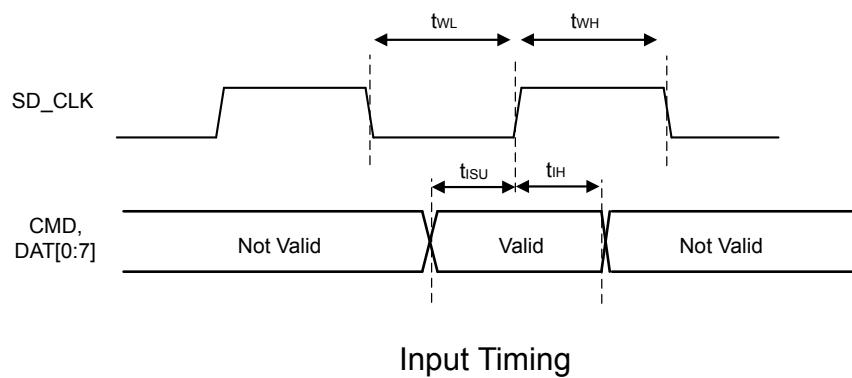


Input Timing

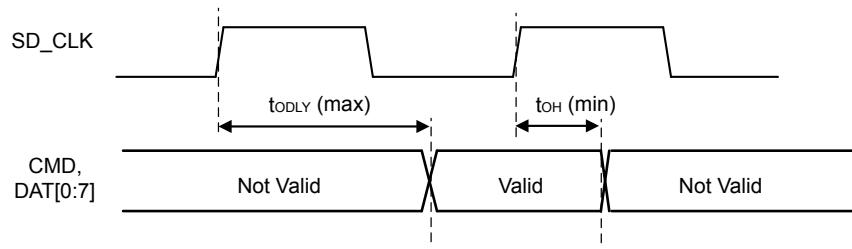


Output Timing

Figure 4.15. SDIO SDR Mode Timing



Input Timing



Output Timing

Figure 4.18. SDIO MMC SDR Mode Timing

4.2.2 DC-DC Converter

Default test conditions: CCM mode, LDCDC = 4.7 μ H, CDCDC = 4.7 μ F, VDCDC_I = 3.3 V, VDCDC_O = 1.8 V, FDCDC_LN = 7 MHz

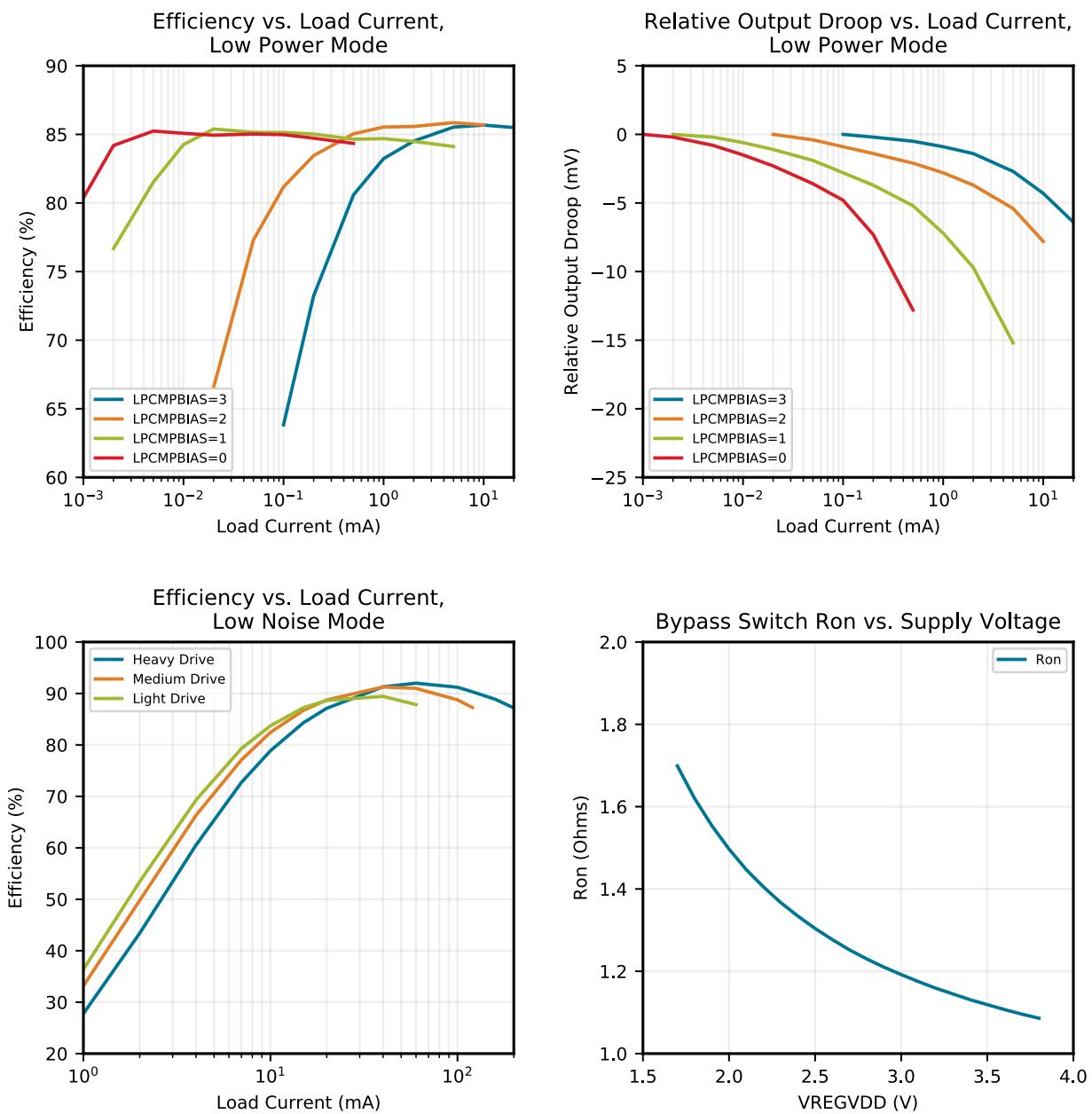


Figure 4.29. DC-DC Converter Typical Performance Characteristics

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PG6	H1	GPIO (5V)	PG7	H2	GPIO (5V)
PG5	H3	GPIO (5V)	PE6	H12	GPIO
PE5	H13	GPIO	DVDD	H14	Digital power supply.
PG9	J1	GPIO (5V)	PG10	J2	GPIO (5V)
PG8	J3	GPIO (5V)	PE3	J12	GPIO
PE4	J13	GPIO	VREGVDD	J14	Voltage regulator VDD input
PG12	K1	GPIO	PG13	K2	GPIO
PG11	K3	GPIO (5V)	PE2	K12	GPIO
PE1	K13	GPIO (5V)	VREGSW	K14	DCDC regulator switching node
PG15	L1	GPIO (5V)	PB15	L2	GPIO (5V)
PG14	L3	GPIO	PC7	L12	GPIO
PE0	L13	GPIO (5V)	VREGVSS	L14	Voltage regulator VSS
PB0	M1	GPIO	PB1	M2	GPIO
PB4	M3	GPIO	PC0	M4	GPIO (5V)
PC3	M5	GPIO (5V)	PA9	M6	GPIO
BODEN	M7	Brown-Out Detector Enable. This pin may be left disconnected or tied to AVDD.	PA12	M8	GPIO (5V)
RESETn	M9	Reset input, active low. To apply an external reset source to this pin, it is required to only drive this pin low during reset, and let the internal pull-up ensure that reset is released.	PB10	M10	GPIO (5V)
PD1	M11	GPIO	PC6	M12	GPIO
PD5	M13	GPIO	PD8	M14	GPIO
PB7	N1	GPIO	PB2	N2	GPIO
PB5	N3	GPIO	PC2	N4	GPIO (5V)
PC5	N5	GPIO	PA8	N6	GPIO
PA11	N7	GPIO	PA14	N8	GPIO
PB11	N9	GPIO	PB12	N10	GPIO
PD0	N11	GPIO (5V)	PD2	N12	GPIO (5V)
PD4	N13	GPIO	PD7	N14	GPIO
PB8	P1	GPIO	PB3	P2	GPIO
PB6	P3	GPIO	PC1	P4	GPIO (5V)
PC4	P5	GPIO	PA7	P6	GPIO
PA10	P7	GPIO	PA13	P8	GPIO (5V)
PB9	P9	GPIO (5V)	PB13	P10	GPIO
PB14	P11	GPIO	AVDD	P12	Analog power supply.
PD3	P13	GPIO	PD6	P14	GPIO

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PF2	78	GPIO	VBUS	79	USB VBUS signal and auxiliary input to 5 V regulator.
PF12	80	GPIO	PF5	81	GPIO
PF6	84	GPIO	PF7	85	GPIO
PF8	86	GPIO	PF9	87	GPIO
PD9	88	GPIO	PD10	89	GPIO
PD11	90	GPIO	PD12	91	GPIO
PE8	92	GPIO	PE9	93	GPIO
PE10	94	GPIO	PE11	95	GPIO
PE12	96	GPIO	PE13	97	GPIO
PE14	98	GPIO	PE15	99	GPIO
PA15	100	GPIO			

Note:

1. GPIO with 5V tolerance are indicated by (5V).

5.11 EFM32GG11B3xx in QFP100 Device Pinout

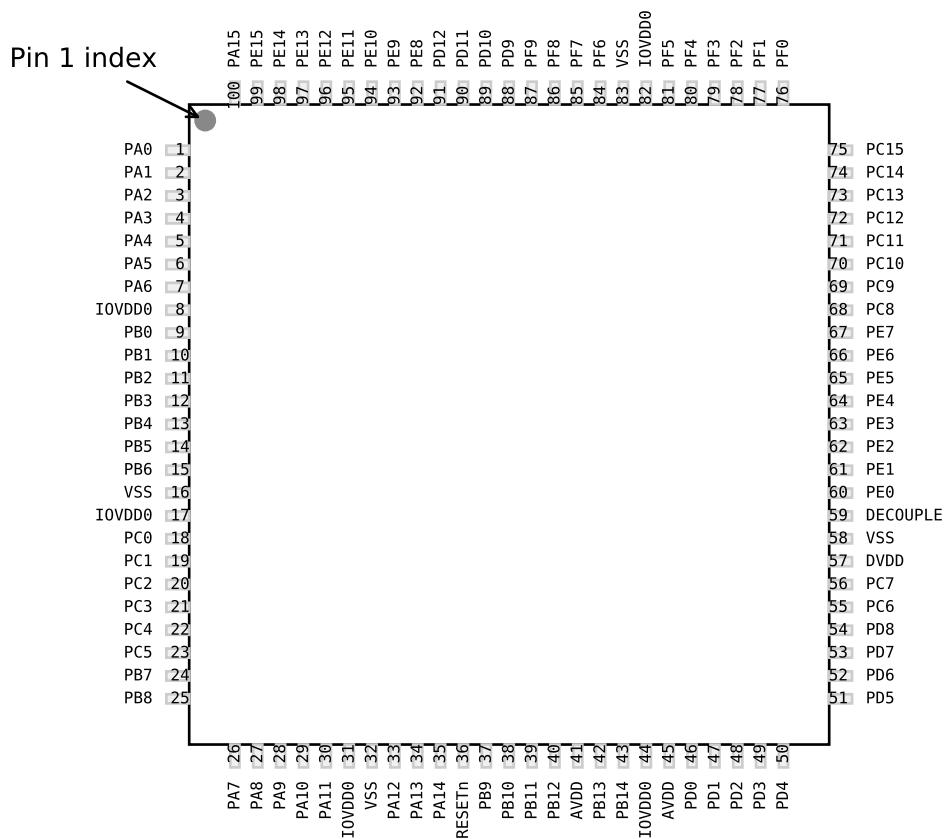


Figure 5.11. EFM32GG11B3xx in QFP100 Device Pinout

The following table provides package pin connections and general descriptions of pin functionality. For detailed information on the supported features for each GPIO pin, see [5.20 GPIO Functionality Table](#) or [5.21 Alternate Functionality Overview](#).

Table 5.11. EFM32GG11B3xx in QFP100 Device Pinout

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PA0	1	GPIO	PA1	2	GPIO
PA2	3	GPIO	PA3	4	GPIO
PA4	5	GPIO	PA5	6	GPIO
PA6	7	GPIO	IOVDD0	8 17 31 44 82	Digital IO power supply 0.
PB0	9	GPIO	PB1	10	GPIO

5.15 EFM32GG11B1xx in QFP64 Device Pinout

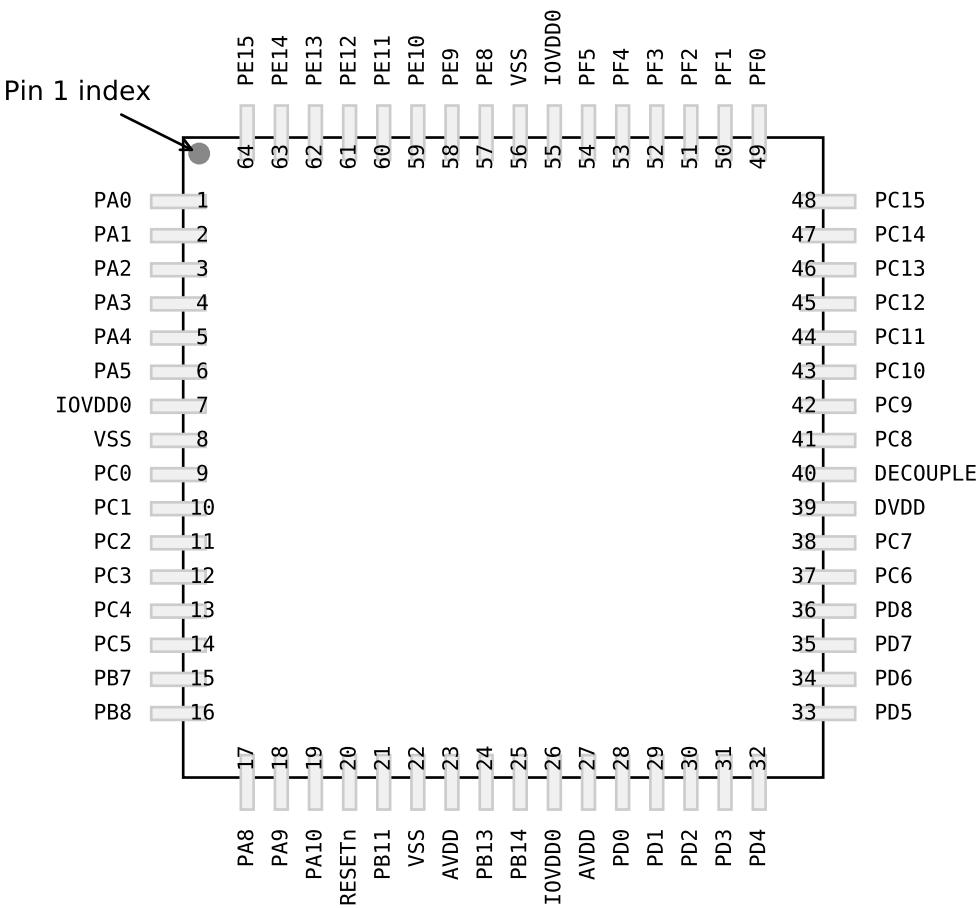


Figure 5.15. EFM32GG11B1xx in QFP64 Device Pinout

The following table provides package pin connections and general descriptions of pin functionality. For detailed information on the supported features for each GPIO pin, see [5.20 GPIO Functionality Table](#) or [5.21 Alternate Functionality Overview](#).

Table 5.15. EFM32GG11B1xx in QFP64 Device Pinout

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PA0	1	GPIO	PA1	2	GPIO
PA2	3	GPIO	PA3	4	GPIO
PA4	5	GPIO	PA5	6	GPIO
IOVDD0	7 26 55	Digital IO power supply 0.	VSS	8 22 56	Ground
PC0	9	GPIO (5V)	PC1	10	GPIO (5V)
PC2	11	GPIO (5V)	PC3	12	GPIO (5V)

5.21 Alternate Functionality Overview

A wide selection of alternate functionality is available for multiplexing to various pins. The following table shows the name of the alternate functionality in the first column, followed by columns showing the possible LOCATION bitfield settings and the associated GPIO pin. Refer to [5.20 GPIO Functionality Table](#) for a list of functions available on each GPIO pin.

Note: Some functionality, such as analog interfaces, do not have alternate settings or a LOCATION bitfield. In these cases, the pinout is shown in the column corresponding to LOCATION 0.

Table 5.21. Alternate Functionality Overview

Alternate	LOCATION		
Functionality	0 - 3	4 - 7	Description
ACMP0_O	0: PE13 1: PE2 2: PD6 3: PB11	4: PA6 5: PB0 6: PB2 7: PB3	Analog comparator ACMP0, digital output.
ACMP1_O	0: PF2 1: PE3 2: PD7 3: PA12	4: PA14 5: PB9 6: PB10 7: PA5	Analog comparator ACMP1, digital output.
ACMP2_O	0: PD8 1: PE0 2: PE1 3: PI0	4: PI1 5: PI2	Analog comparator ACMP2, digital output.
ACMP3_O	0: PF0 1: PC15 2: PC14 3: PC13	4: PI4 5: PI5	Analog comparator ACMP3, digital output.
ADC0_EXTN	0: PD7		Analog to digital converter ADC0 external reference input negative pin.
ADC0_EXTP	0: PD6		Analog to digital converter ADC0 external reference input positive pin.
ADC1_EXTN	0: PD7		Analog to digital converter ADC1 external reference input negative pin.
ADC1_EXTP	0: PD6		Analog to digital converter ADC1 external reference input positive pin.
BOOT_RX	0: PF1		Bootloader RX.
BOOT_TX	0: PF0		Bootloader TX.

Alternate	LOCATION		
Functionality	0 - 3	4 - 7	Description
PCNT0_S0IN	0: PC13 1: PE0 2: PC0 3: PD6	4: PA0 5: PB0 6: PB5 7: PB12	Pulse Counter PCNT0 input number 0.
PCNT0_S1IN	0: PC14 1: PE1 2: PC1 3: PD7	4: PA1 5: PB1 6: PB6 7: PB11	Pulse Counter PCNT0 input number 1.
PCNT1_S0IN	0: PA5 1: PB3 2: PD15 3: PC4	4: PA7 5: PA12 6: PB11 7: PG14	Pulse Counter PCNT1 input number 0.
PCNT1_S1IN	0: PA6 1: PB4 2: PB0 3: PC5	4: PA8 5: PA13 6: PB12 7: PG15	Pulse Counter PCNT1 input number 1.
PCNT2_S0IN	0: PD0 1: PE8 2: PB13 3: PF10	4: PC12 5: PI2 6: PI0 7: PH14	Pulse Counter PCNT2 input number 0.
PCNT2_S1IN	0: PD1 1: PE9 2: PB14 3: PF11	4: PC13 5: PI1 6: PH15 7: PH13	Pulse Counter PCNT2 input number 1.
PRS_CH0	0: PA0 1: PF3 2: PC14 3: PF2		Peripheral Reflex System PRS, channel 0.
PRS_CH1	0: PA1 1: PF4 2: PC15 3: PE12		Peripheral Reflex System PRS, channel 1.
PRS_CH2	0: PC0 1: PF5 2: PE10 3: PE13		Peripheral Reflex System PRS, channel 2.
PRS_CH3	0: PC1 1: PE8 2: PE11 3: PA0		Peripheral Reflex System PRS, channel 3.
PRS_CH4	0: PC8 1: PB0 2: PF1		Peripheral Reflex System PRS, channel 4.
PRS_CH5	0: PC9 1: PB1 2: PD6		Peripheral Reflex System PRS, channel 5.
PRS_CH6	0: PA6 1: PB14 2: PE6		Peripheral Reflex System PRS, channel 6.

Alternate	LOCATION		
Functionality	0 - 3	4 - 7	Description
SDIO_DAT7	0: PD9 1: PB4		SDIO Data 7.
SDIO_WP	0: PF9 1: PC5 2: PB15 3: PB9		SDIO Write Protect.
TIM0_CC0	0: PA0 1: PF6 2: PD1 3: PB6	4: PF0 5: PC4 6: PA8 7: PA1	Timer 0 Capture Compare input / output channel 0.
TIM0_CC1	0: PA1 1: PF7 2: PD2 3: PC0	4: PF1 5: PC5 6: PA9 7: PA0	Timer 0 Capture Compare input / output channel 1.
TIM0_CC2	0: PA2 1: PF8 2: PD3 3: PC1	4: PF2 5: PA7 6: PA10 7: PA13	Timer 0 Capture Compare input / output channel 2.
TIM0_CDTI0	0: PA3 1: PC13 2: PF3 3: PC2	4: PB7	Timer 0 Complimentary Dead Time Insertion channel 0.
TIM0_CDTI1	0: PA4 1: PC14 2: PF4 3: PC3	4: PB8	Timer 0 Complimentary Dead Time Insertion channel 1.
TIM0_CDTI2	0: PA5 1: PC15 2: PF5 3: PC4	4: PB11	Timer 0 Complimentary Dead Time Insertion channel 2.
TIM1_CC0	0: PC13 1: PE10 2: PB0 3: PB7	4: PD6 5: PF2 6: PF13 7: PI6	Timer 1 Capture Compare input / output channel 0.
TIM1_CC1	0: PC14 1: PE11 2: PB1 3: PB8	4: PD7 5: PF3 6: PF14 7: PI7	Timer 1 Capture Compare input / output channel 1.
TIM1_CC2	0: PC15 1: PE12 2: PB2 3: PB11	4: PC13 5: PF4 6: PF15 7: PI8	Timer 1 Capture Compare input / output channel 2.
TIM1_CC3	0: PC12 1: PE13 2: PB3 3: PB12	4: PC14 5: PF12 6: PF5 7: PI9	Timer 1 Capture Compare input / output channel 3.
TIM2_CC0	0: PA8 1: PA12 2: PC8 3: PF2	4: PB6 5: PC2 6: PG8 7: PG5	Timer 2 Capture Compare input / output channel 0.

Table 5.23. ACMP0 Bus and Pin Mapping

APORT4Y	APORT4X	APORT3Y	APORT3X	APORT2Y	APORT2X	APORT1Y	APORT1X	APORT0Y	APORT0X	Port
BUSDY	BUSDX	BUSCY	BUSCX	BUSBY	BUSBX	BUSAY	BUSAX	BUSACMP0Y	BUSACMP0X	Bus
PF15	PF15			PB15						CH31
PF14		PF14		PB14		PB14				CH30
PF13	PF13			PB13	PB13					CH29
PF12		PF12		PB12		PB12				CH28
PF11	PF11			PB11	PB11					CH27
PF10		PF10		PB10		PB10				CH26
PF9	PF9			PB9	PB9					CH25
PF8		PF8								CH24
PF7	PF7									CH23
PF6		PF6		PB6	PB6					CH22
PF5	PF5			PB5	PB5	PB5	PB4			CH21
PF4		PF4		PB4	PB4	PB3	PB3			CH20
PF3	PF3			PB2	PB2	PB1	PB1			CH19
PF2		PF2		PB0	PB0		PB0			CH18
PF1	PF1									CH17
PF0		PF0								CH16
PE15	PE15			PA15	PA15	PA15	PA14			CH15
PE14		PE14		PA14	PA14	PA13	PA13			CH14
PE13	PE13			PA12	PA12		PA12			CH13
PE12		PE12		PA11	PA11	PA11				CH12
PE11	PE11			PA10	PA10		PA10			CH11
PE10		PE10		PA9	PA9	PA9	PA9			CH10
PE9	PE9			PA8	PA8		PA8			CH9
PE8		PE8								CH8
PE7	PE7									CH7
PE6		PE6		PA6	PA6		PA6	PC6	PC6	CH6
PE5	PE5			PA5	PA5		PA5	PC5	PC5	CH5
PE4		PE4		PA4	PA4		PA4	PC4	PC4	CH4
				PA3	PA3		PA3	PC3	PC3	CH3
				PA2	PA2		PA2	PC2	PC2	CH2
PE1	PE1			PA1	PA1	PA1	PA1	PC1	PC1	CH1
PE0		PE0		PA0	PA0		PA0	PC0	PC0	CH0

Table 5.24. ACMP1 Bus and Pin Mapping

	APORT4Y	APORT4X	APORT3Y	APORT3X	APORT2Y	APORT2X	APORT1Y	APORT1X	APORT0Y	APORT0X	Port
BUSDY	BUSDX	BUSCY	BUSCX	BUSBY	BUSBX	BUSAY	BUSAX	BUSACMP1Y	BUSACMP1X	BUS	CH31
PF15	PF15			PB15		PB15					CH30
PF14		PF14		PB14			PB14				CH29
PF12		PF12		PB12		PB13	PB13				CH28
PF10		PF10		PB10		PB11	PB11				CH27
PF8		PF9	PF9		PB9	PB9	PB9	PB10			CH26
PF7		PF7	PF8								CH25
PF6		PF5	PF6	PB6	PB6	PB5	PB5	PB6			CH24
PF4		PF4	PF4	PB4	PB4	PB3	PB3	PB4			CH23
PF2		PF2	PF2	PB2	PB2	PB1	PB1	PB2			CH22
PF0		PF1	PF1	PB0	PB0	PA15	PA15	PB0			CH21
PE15	PE15	PE15	PE14	PA14	PA14	PA13	PA13	PA14			CH20
PE14	PE13	PE13	PE12	PA12	PA12	PA11	PA11	PA12			CH19
PE12	PE11	PE11	PE10	PA10	PA10	PA9	PA9	PA10			CH18
PE10	PE9	PE9	PE8	PA8	PA8	PA7	PA7	PA8			CH17
PE8		PE7	PE7	PA6	PA6	PA5	PA5	PA6			CH16
PE6		PE5	PE5	PA4	PA4	PA3	PA3	PA4			CH15
PE4				PA2		PA2		PA2			CH14
PE1		PE1		PA1	PA1	PA0	PA0	PA1	PA0	PA0	CH13
PE0			PE0	PA0							CH12

Table 5.26. ACMP3 Bus and Pin Mapping

	APORT4Y	APORT4X	APORT3Y	APORT3X	APORT2Y	APORT2X	APORT1Y	APORT1X	APORT0Y	APORT0X	Port
BUSDY	BUSDX	BUSCY	BUSCX	BUSBY	BUSBX	BUSAY	BUSAX	BUSACMP3Y	BUSACMP3X	BUS	CH31
PF15	PF15			PB15		PB15					CH30
PF14		PF14		PB14			PB14				CH29
PF13	PF13			PB13	PB13	PB13					CH28
PF12		PF12		PB12		PB12					CH27
PF11	PF11			PB11	PB11	PB11					CH26
PF10		PF10		PB10		PB10	PB10				CH25
PF9	PF9			PB9	PB9	PB9	PB9				CH24
PF8		PF8									CH23
PF7	PF7			PB6	PB6	PB6	PB6				CH22
PF6	PF5	PF5		PB4	PB4	PB5	PB5	PB4			CH21
PF4	PF3	PF3		PB2	PB2	PB3	PB3	PB2			CH20
PF2		PF1		PB1	PB1	PB1	PB1	PB0			CH19
PF0		PE15	PE15	PB0	PB0	PA15	PA15	PA14			CH18
PE14	PE13	PE13	PE14	PA14	PA14	PA13	PA13	PA12			CH17
PE12	PE11	PE11	PE12	PA12	PA12	PA11	PA11	PA10			CH16
PE10		PE10	PE10	PA10	PA10	PA9	PA9	PA8			CH15
PE8		PE9	PE8	PA8	PA8	PA7	PA7	PA6	PH15	PH15	CH9
PE6		PE7	PE7	PA6	PA6	PA5	PA5	PA4	PH14	PH14	CH8
PE5		PE5		PA4	PA4	PA3	PA3	PA2	PH13	PH13	CH7
PE4						PA1	PA1	PA1	PH12	PH12	CH6
PE1		PE1							PH11	PH11	CH5
PE0			PE0	PA0	PA0				PH10	PH10	CH4
									PH9	PH9	CH3
									PH8	PH8	CH2
											CH1
											CH0

8. BGA120 Package Specifications

8.1 BGA120 Package Dimensions

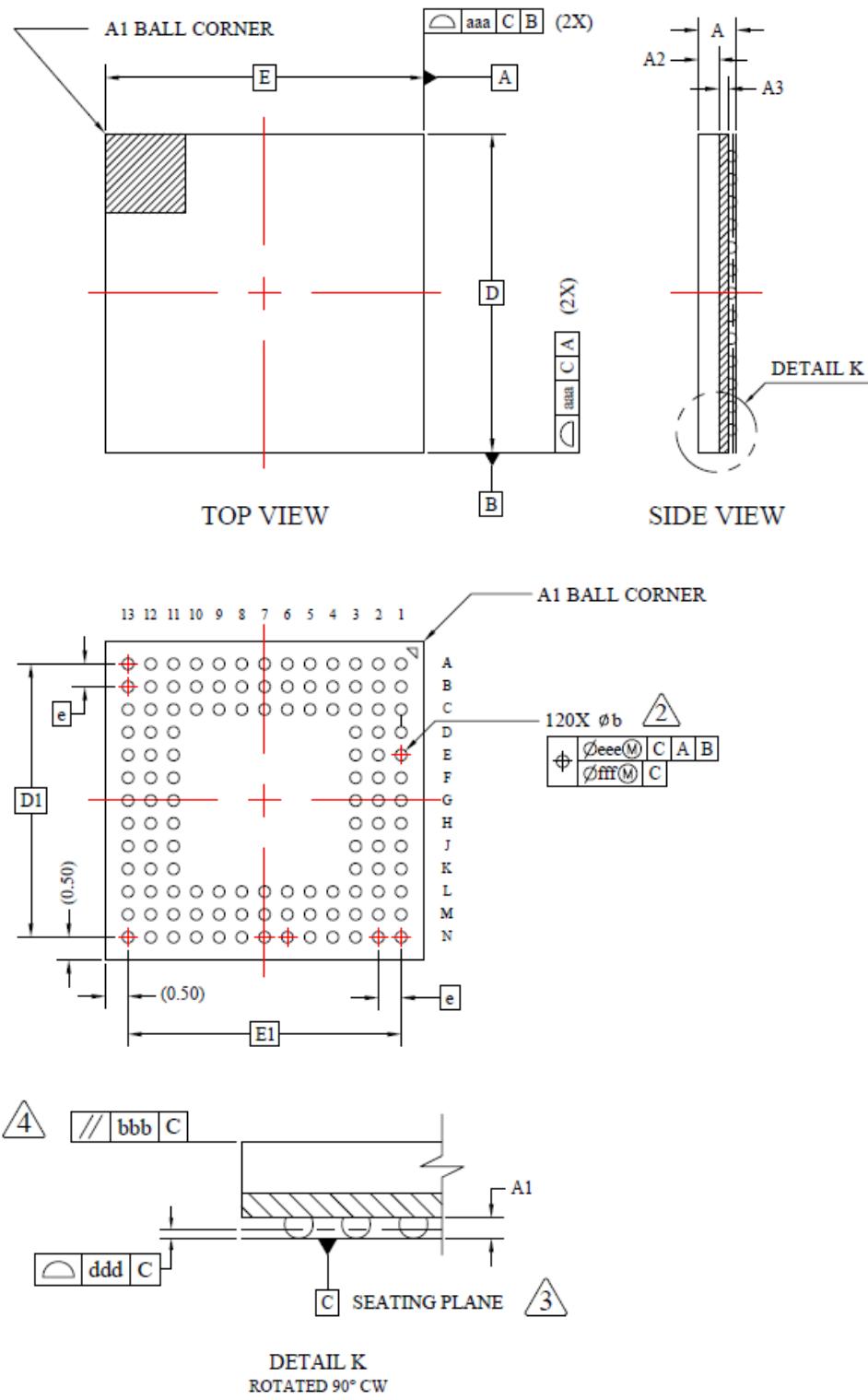


Figure 8.1. BGA120 Package Drawing