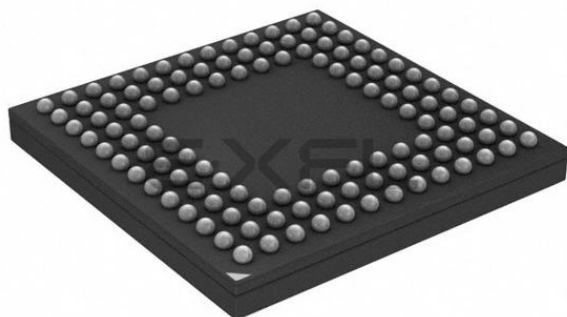




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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

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Details

Product Status	Obsolete
Core Processor	ARM® Cortex®-M4
Core Size	32-Bit Single-Core
Speed	72MHz
Connectivity	CANbus, EBI/EMI, Ethernet, I ² C, IrDA, LINbus, MMC/SD/SDIO, QSPI, SmartCard, SPI, UART/USART, USB
Peripherals	Brown-out Detect/Reset, DMA, LCD, POR, PWM, WDT
Number of I/O	93
Program Memory Size	2MB (2M x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	512K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.8V
Data Converters	A/D 16x12b SAR; D/A 2x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	120-VFBGA
Supplier Device Package	120-BGA (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/silicon-labs/efm32gg11b420f2048il120-a

4. Electrical Specifications

4.1 Electrical Characteristics

All electrical parameters in all tables are specified under the following conditions, unless stated otherwise:

- Typical values are based on $T_{AMB}=25\text{ }^{\circ}\text{C}$ and $V_{DD}=3.3\text{ V}$, by production test and/or technology characterization.
- Minimum and maximum values represent the worst conditions across supply voltage, process variation, and operating temperature, unless stated otherwise.

Refer to [4.1.2.1 General Operating Conditions](#) for more details about operational supply and temperature limits.

4.1.6 Backup Supply Domain

Table 4.6. Backup Supply Domain

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Backup supply voltage range	V _{BU_VIN}		1.8	—	3.8	V
PWRRES resistor	R _{PWRRES}	EMU_BUCTRL_PWRRES = RES0	3400	3900	4400	Ω
		EMU_BUCTRL_PWRRES = RES1	1450	1800	2150	Ω
		EMU_BUCTRL_PWRRES = RES2	1000	1350	1700	Ω
		EMU_BUCTRL_PWRRES = RES3	525	815	1100	Ω
Output impedance between BU_VIN and BU_VOUT ²	R _{BU_VOUT}	EMU_BUCTRL_VOUTRES = STRONG	35	110	185	Ω
		EMU_BUCTRL_VOUTRES = MED	475	775	1075	Ω
		EMU_BUCTRL_VOUTRES = WEAK	5600	6500	7400	Ω
Supply current	I _{BU_VIN}	BU_VIN not powering backup do- main	—	11	TBD	nA
		BU_VIN powering backup do- main ¹	—	550	TBD	nA

Note:

1. Additional current required by backup circuitry when backup is active. Includes supply current of backup switches and backup regulator. Does not include supply current required for backed-up circuitry.

2. BU_VOUT and BU_STAT signals are not available in all package configurations. Check the device pinout for availability.

4.1.14 Analog to Digital Converter (ADC)

Specified at 1 Msps, ADCCLK = 16 MHz, BIASPROG = 0, GPBIASACC = 0, unless otherwise indicated.

Table 4.22. Analog to Digital Converter (ADC)

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Resolution	V _{RESOLUTION}		6	—	12	Bits
Input voltage range ⁵	V _{ADCIN}	Single ended	—	—	V _{FS}	V
		Differential	-V _{FS} /2	—	V _{FS} /2	V
Input range of external reference voltage, single ended and differential	V _{ADCREFIN_P}		1	—	V _{AVDD}	V
Power supply rejection ²	PSRR _{ADC}	At DC	—	80	—	dB
Analog input common mode rejection ratio	CMRR _{ADC}	At DC	—	80	—	dB
Current from all supplies, using internal reference buffer. Continuous operation. WAR-MUPMODE ⁴ = KEEPADC-WARM	I _{ADC_CONTINUOUS_LP}	1 Msps / 16 MHz ADCCLK, BIASPROG = 0, GPBIASACC = 1 ³	—	270	TBD	μA
		250 ksps / 4 MHz ADCCLK, BIASPROG = 6, GPBIASACC = 1 ³	—	125	—	μA
		62.5 ksps / 1 MHz ADCCLK, BIASPROG = 15, GPBIASACC = 1 ³	—	80	—	μA
Current from all supplies, using internal reference buffer. Duty-cycled operation. WAR-MUPMODE ⁴ = NORMAL	I _{ADC_NORMAL_LP}	35 ksps / 16 MHz ADCCLK, BIASPROG = 0, GPBIASACC = 1 ³	—	45	—	μA
		5 ksps / 16 MHz ADCCLK BIASPROG = 0, GPBIASACC = 1 ³	—	8	—	μA
Current from all supplies, using internal reference buffer. Duty-cycled operation. AWARMUPMODE ⁴ = KEEP-INSTANDBY or KEEPIN-SLOWACC	I _{ADC_STANDBY_LP}	125 ksps / 16 MHz ADCCLK, BIASPROG = 0, GPBIASACC = 1 ³	—	105	—	μA
		35 ksps / 16 MHz ADCCLK, BIASPROG = 0, GPBIASACC = 1 ³	—	70	—	μA
Current from all supplies, using internal reference buffer. Continuous operation. WAR-MUPMODE ⁴ = KEEPADC-WARM	I _{ADC_CONTINUOUS_HP}	1 Msps / 16 MHz ADCCLK, BIASPROG = 0, GPBIASACC = 0 ³	—	325	—	μA
		250 ksps / 4 MHz ADCCLK, BIASPROG = 6, GPBIASACC = 0 ³	—	175	—	μA
		62.5 ksps / 1 MHz ADCCLK, BIASPROG = 15, GPBIASACC = 0 ³	—	125	—	μA
Current from all supplies, using internal reference buffer. Duty-cycled operation. WAR-MUPMODE ⁴ = NORMAL	I _{ADC_NORMAL_HP}	35 ksps / 16 MHz ADCCLK, BIASPROG = 0, GPBIASACC = 0 ³	—	85	—	μA
		5 ksps / 16 MHz ADCCLK BIASPROG = 0, GPBIASACC = 0 ³	—	16	—	μA
Current from all supplies, using internal reference buffer. Duty-cycled operation. AWARMUPMODE ⁴ = KEEP-INSTANDBY or KEEPIN-SLOWACC	I _{ADC_STANDBY_HP}	125 ksps / 16 MHz ADCCLK, BIASPROG = 0, GPBIASACC = 0 ³	—	160	—	μA
		35 ksps / 16 MHz ADCCLK, BIASPROG = 0, GPBIASACC = 0 ³	—	125	—	μA
Current from HFPERCLK	I _{ADC_CLK}	HFPERCLK = 16 MHz	—	180	—	μA

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
MISO hold time ^{1 3}	t_{H_MI}	USART2, location 4, IOVDD = 1.8 V	-11.6	—	—	ns
		USART2, location 4, IOVDD = 3.0 V	-11.6	—	—	ns
		USART2, location 5, IOVDD = 1.8 V	-9.1	—	—	ns
		USART2, location 5, IOVDD = 3.0 V	-9.1	—	—	ns
		All other USARTs and locations, IOVDD = 1.8 V	-8	—	—	ns
		All other USARTs and locations, IOVDD = 3.0 V	-8	—	—	ns

Note:

1. Applies for both CLKPHA = 0 and CLKPHA = 1 (figure only shows CLKPHA = 0).
2. t_{H_PERCLK} is one period of the selected HPERCLK.
3. Measurement done with 8 pF output loading at 10% and 90% of V_{DD} (figure shows 50% of V_{DD}).

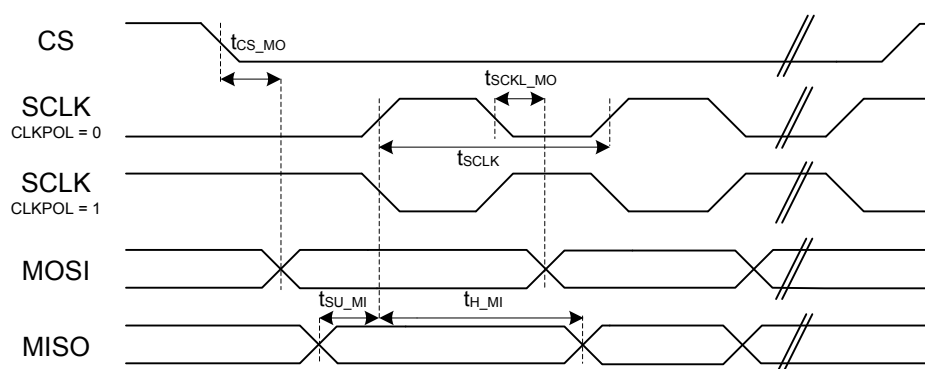


Figure 4.1. SPI Master Timing Diagram

RMII Receive Timing

Timing is specified with $3.0\text{ V} \leq \text{IOVDD} \leq 3.8\text{ V}$, 25 pF external loading, and slew rate for all GPIO set to 6 unless otherwise indicated.

Table 4.45. Ethernet RMII Receive Timing

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
REF_CLK frequency	$F_{\text{REF_CLK}}$	Output slew rate set to 7	—	50	—	MHz
REF_CLK duty cycle	$DC_{\text{REF_CLK}}$		35	—	65	%
Setup time, RXD[1:0], CRS_DV, RX_ER valid to REF_CLK	t_{SU}		4	—	—	ns
Hold time, REF_CLK to RXD[1:0], CRS_DV, RX_ER change	t_{HD}		2	—	—	ns

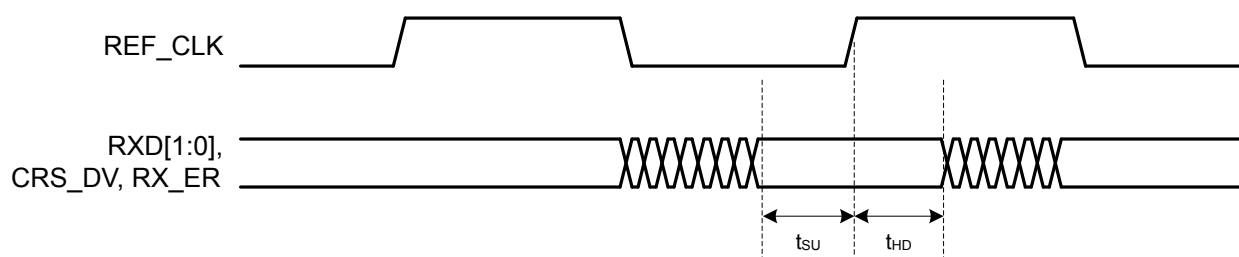
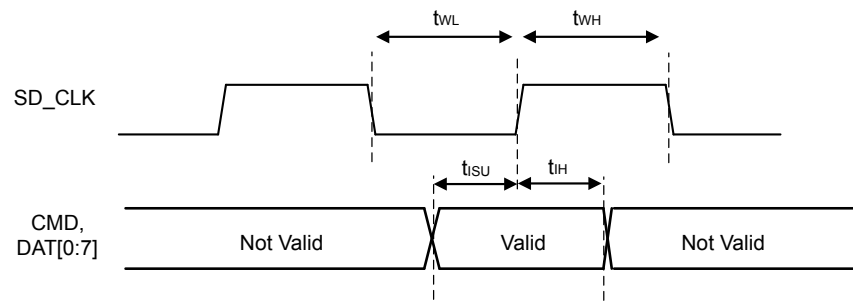
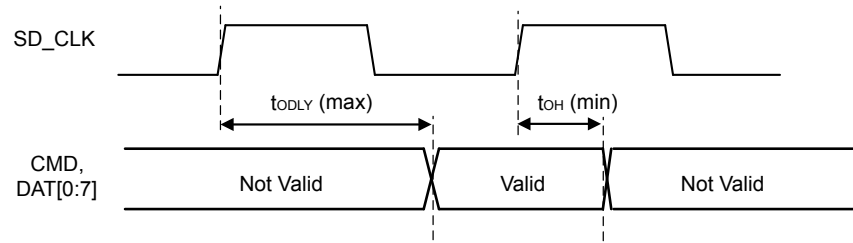


Figure 4.12. Ethernet RMII Receive Timing

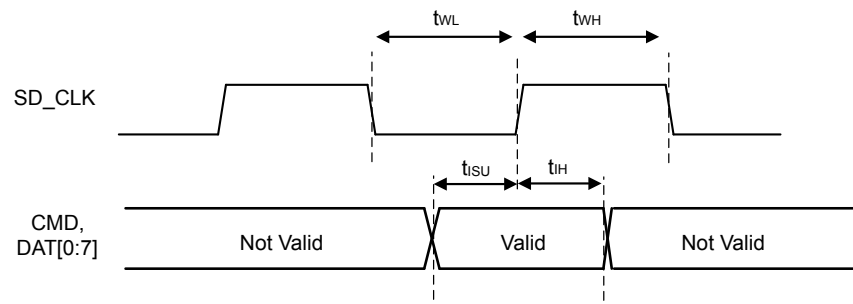


Input Timing

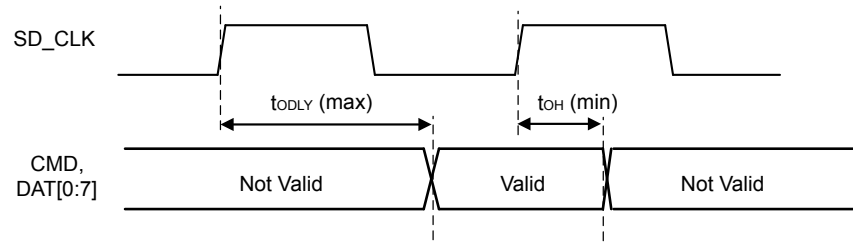


Output Timing

Figure 4.14. SDIO HS Mode Timing



Input Timing



Output Timing

Figure 4.15. SDIO SDR Mode Timing

SDIO MMC SDR Mode Timing at 1.8 V

Timing is specified for route location 0 at 1.8 V IOVDD with voltage scaling disabled. Slew rate for SD_CLK set to 7, all other GPIO set to 6, DRIVESTRENGTH = STRONG for all pins. SDIO_CTRL_TXDLYMUXSEL = 1. Loading between 5 and 10 pF on all pins or between 10 and 20 pF on all pins.

Table 4.50. SDIO MMC SDR Mode Timing (Location 0, 1.8V I/O)

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Clock frequency during data transfer	F _{SD_CLK}	Using HFRCO, AUXHFRCO, or USHFRCO	—	—	25	MHz
		Using HFXO	—	—	TBD	MHz
Clock low time	t _{WL}	Using HFRCO, AUXHFRCO, or USHFRCO	18.1	—	—	ns
		Using HFXO	TBD	—	—	ns
Clock high time	t _{WH}	Using HFRCO, AUXHFRCO, or USHFRCO	18.1	—	—	ns
		Using HFXO	TBD	—	—	ns
Clock rise time	t _R		1.96	8.27	—	ns
Clock fall time	t _F		1.67	6.90	—	ns
Input setup time, CMD, DAT[0:7] valid to SD_CLK	t _{ISU}		5.3	—	—	ns
Input hold time, SD_CLK to CMD, DAT[0:7] change	t _{IH}		2.5	—	—	ns
Output delay time, SD_CLK to CMD, DAT[0:7] valid	t _{ODLY}		0	—	16	ns
Output hold time, SD_CLK to CMD, DAT[0:7] change	t _{OH}		3	—	—	ns

4.2.1 Supply Current

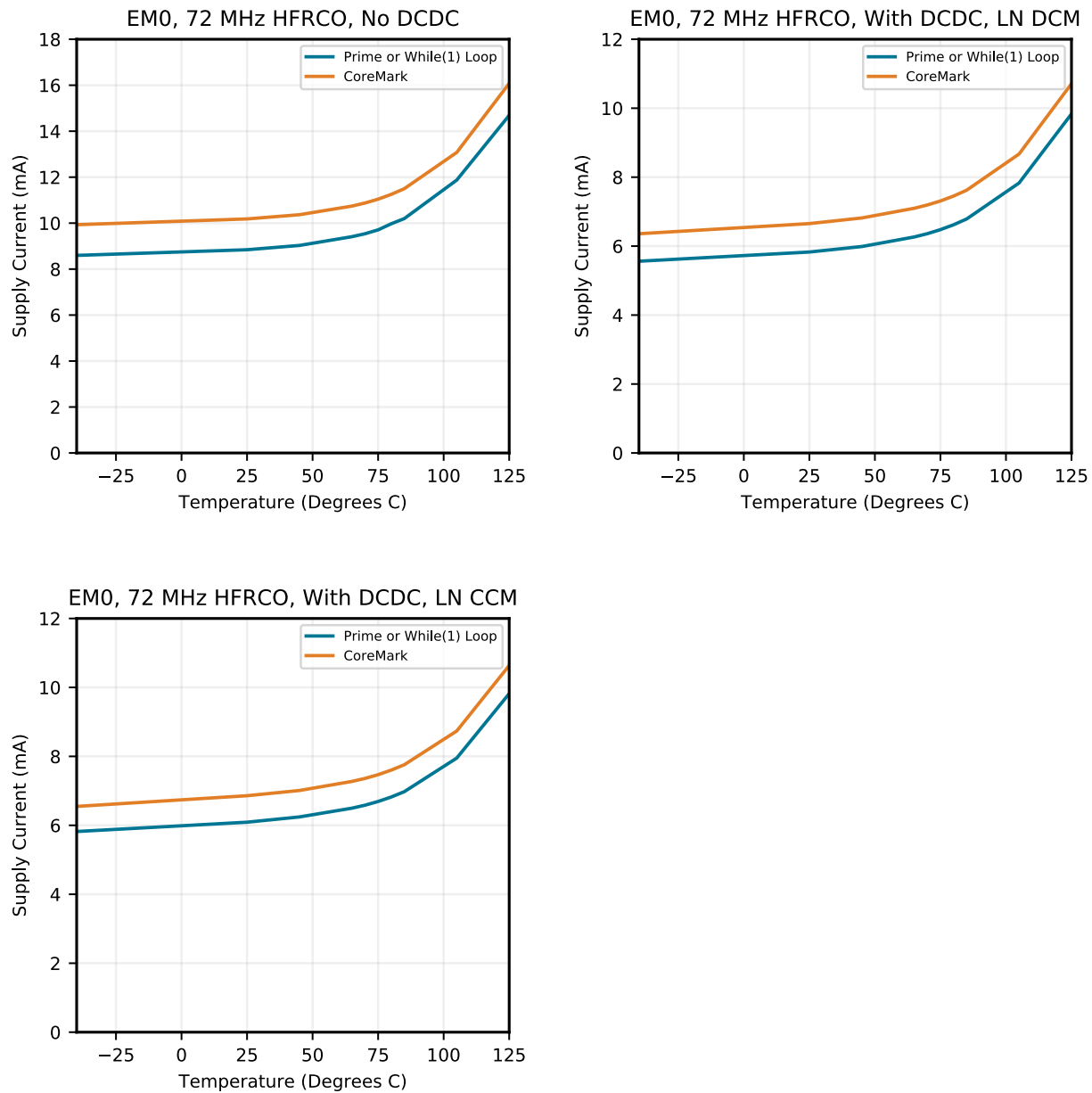


Figure 4.23. EM0 Full Speed Active Mode Typical Supply Current vs. Temperature

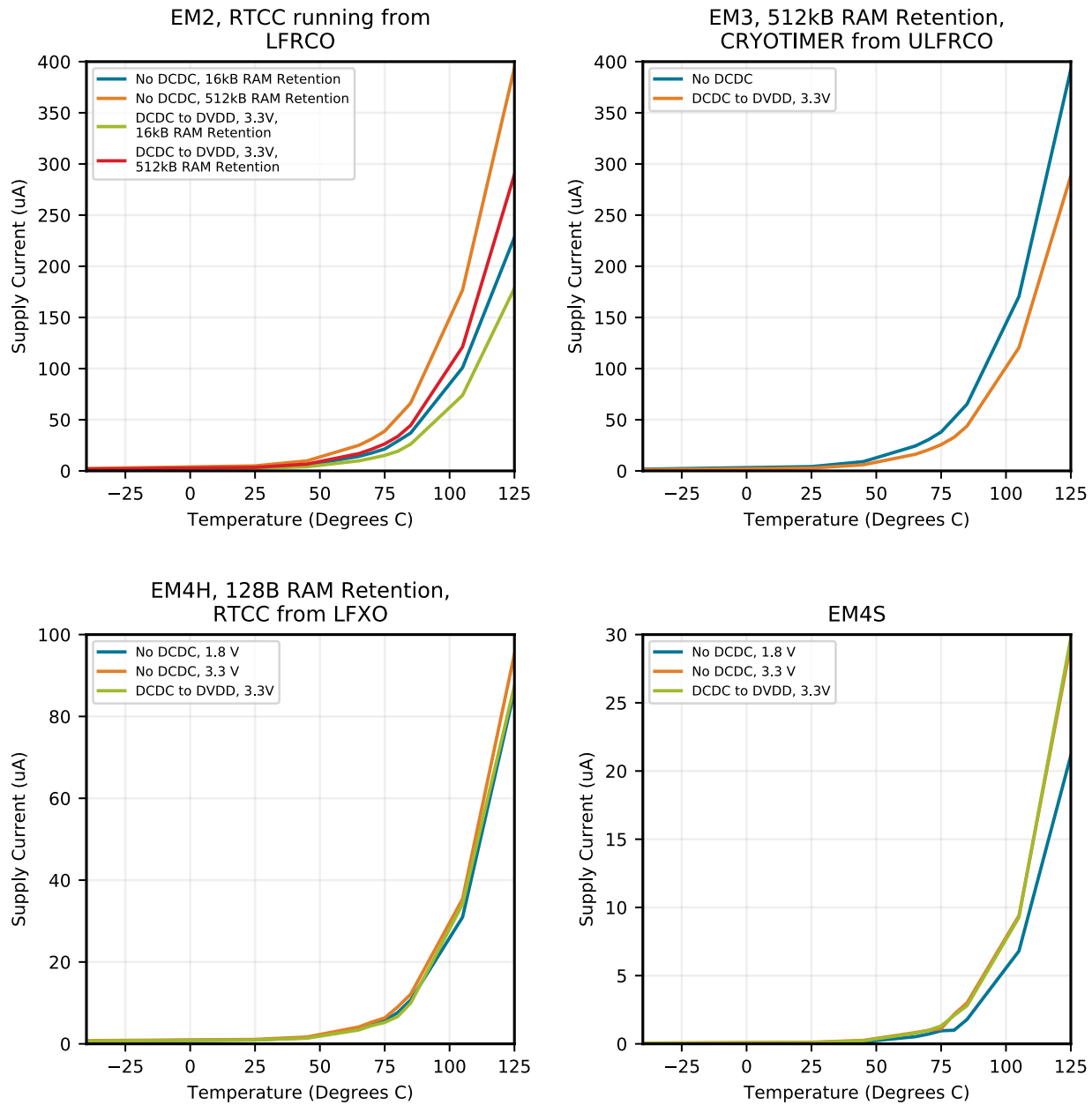


Figure 4.26. EM2, EM3, EM4H and EM4S Typical Supply Current vs. Temperature

5.3 EFM32GG11B8xx in BGA120 Device Pinout

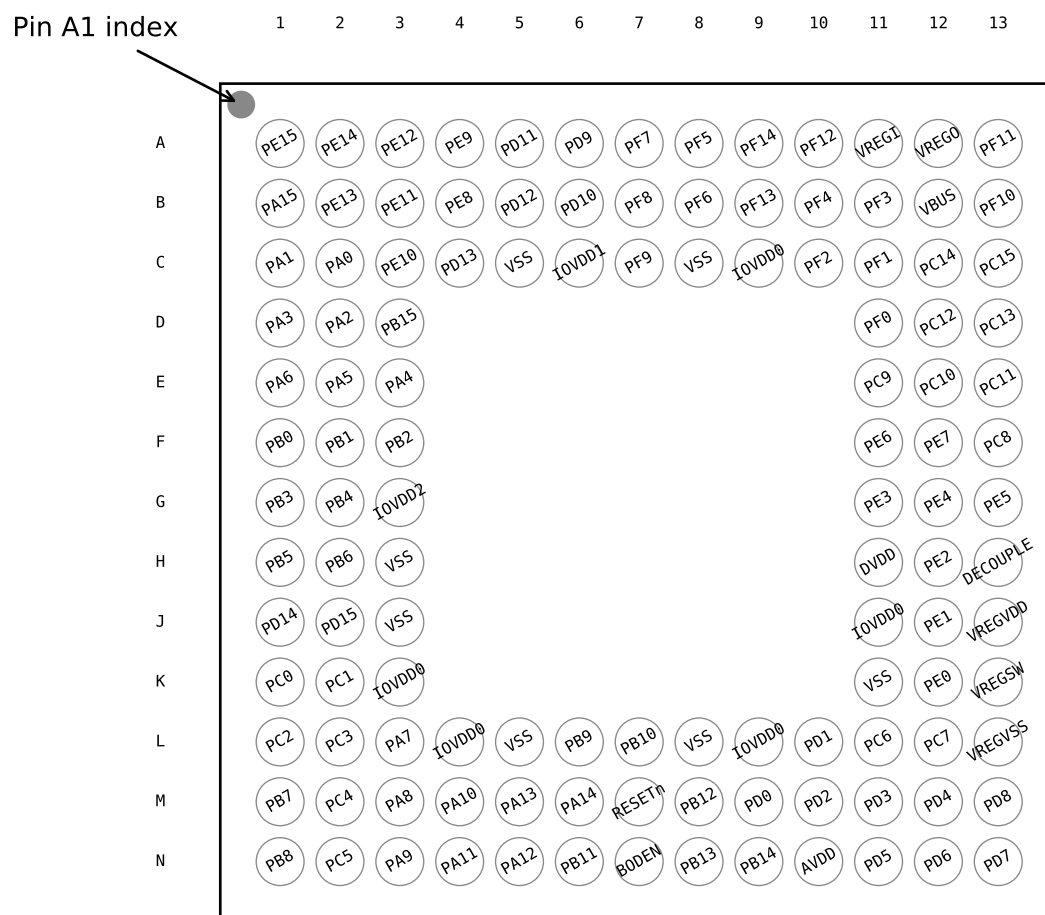


Figure 5.3. EFM32GG11B8xx in BGA120 Device Pinout

The following table provides package pin connections and general descriptions of pin functionality. For detailed information on the supported features for each GPIO pin, see [5.20 GPIO Functionality Table](#) or [5.21 Alternate Functionality Overview](#).

Table 5.3. EFM32GG11B8xx in BGA120 Device Pinout

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PE15	A1	GPIO	PE14	A2	GPIO
PE12	A3	GPIO	PE9	A4	GPIO
PD11	A5	GPIO	PD9	A6	GPIO
PF7	A7	GPIO	PF5	A8	GPIO
PF14	A9	GPIO (5V)	PF12	A10	GPIO
VREGI	A11	Input to 5 V regulator.	VREGO	A12	Decoupling for 5 V regulator and regulator output. Power for USB PHY in USB-enabled OPNs

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PC1	K2	GPIO (5V)	PE0	K12	GPIO (5V)
VREGSW	K13	DCDC regulator switching node	PC2	L1	GPIO (5V)
PC3	L2	GPIO (5V)	PA7	L3	GPIO
PB9	L13	GPIO (5V)	PB10	L14	GPIO (5V)
PD1	L17	GPIO	PC6	L18	GPIO
PC7	L19	GPIO	VREGVSS	L20	Voltage regulator VSS
PB7	M1	GPIO	PC4	M2	GPIO
PA8	M3	GPIO	PA10	M4	GPIO
PA13	M5	GPIO (5V)	PA14	M6	GPIO
RESETn	M7	Reset input, active low. To apply an external reset source to this pin, it is required to only drive this pin low during reset, and let the internal pull-up ensure that reset is released.	PB12	M8	GPIO
PD0	M9	GPIO (5V)	PD2	M10	GPIO (5V)
PD3	M11	GPIO	PD4	M12	GPIO
PD8	M13	GPIO	PB8	N1	GPIO
PC5	N2	GPIO	PA9	N3	GPIO
PA11	N4	GPIO	PA12	N5	GPIO (5V)
PB11	N6	GPIO	BODEN	N7	Brown-Out Detector Enable. This pin may be left disconnected or tied to AVDD.
PB13	N8	GPIO	PB14	N9	GPIO
AVDD	N10	Analog power supply.	PD5	N11	GPIO
PD6	N12	GPIO	PD7	N13	GPIO

Note:

1. GPIO with 5V tolerance are indicated by (5V).
2. The pins PD13, PD14, and PD15 will not be 5V tolerant on all future devices. In order to preserve upgrade options with full hardware compatibility, do not use these pins with 5V domains.

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PF11	A13	GPIO (5V)	PA15	B1	GPIO
PE13	B2	GPIO	PE11	B3	GPIO
PE8	B4	GPIO	PD12	B5	GPIO
PD10	B6	GPIO	PF8	B7	GPIO
PF6	B8	GPIO	PF3	B9	GPIO
PF1	B10	GPIO (5V)	PF12	B11	GPIO
VBUS	B12	USB VBUS signal and auxiliary input to 5 V regulator.	PF10	B13	GPIO (5V)
PA1	C1	GPIO	PA0	C2	GPIO
PE10	C3	GPIO	PD13	C4	GPIO (5V)
VSS	C5 C8 H3 J3 K11 K12 L12 L13 M8 M11 N8	Ground	IOVDD1	C6	Digital IO power supply 1.
PF9	C7	GPIO	IOVDD0	C9 J11 K3 L11 L14	Digital IO power supply 0.
PF0	C10	GPIO (5V)	PE4	C11	GPIO
PC14	C12	GPIO (5V)	PC15	C13	GPIO (5V)
PA3	D1	GPIO	PA2	D2	GPIO
PB15	D3	GPIO (5V)	PE5	D11	GPIO
PC12	D12	GPIO (5V)	PC13	D13	GPIO (5V)
PA6	E1	GPIO	PA5	E2	GPIO
PA4	E3	GPIO	PE6	E11	GPIO
PC10	E12	GPIO (5V)	PC11	E13	GPIO (5V)
PB0	F1	GPIO	PB1	F2	GPIO
PB2	F3	GPIO	PE7	F11	GPIO
PC8	F12	GPIO (5V)	PC9	F13	GPIO (5V)
PB3	G1	GPIO	PB4	G2	GPIO
IOVDD2	G3	Digital IO power supply 2.	PE0	G11	GPIO (5V)
PE1	G12	GPIO (5V)	PE3	G13	GPIO
PB5	H1	GPIO	PB6	H2	GPIO
DVDD	H11	Digital power supply.	PE2	H12	GPIO
PC7	H13	GPIO	PD14	J1	GPIO (5V)

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PD15	J2	GPIO (5V)	PC6	J12	GPIO
DECOUPLE	J13	Decouple output for on-chip voltage regulator. An external decoupling capacitor is required at this pin.	PC0	K1	GPIO (5V)
PC1	K2	GPIO (5V)	PD8	K13	GPIO
PC2	L1	GPIO (5V)	PC3	L2	GPIO (5V)
PA7	L3	GPIO	PB9	L15	GPIO (5V)
PB10	L16	GPIO (5V)	PD0	L17	GPIO (5V)
PD1	L18	GPIO	PD4	L19	GPIO
PD7	L20	GPIO	PB7	M1	GPIO
PC4	M2	GPIO	PA8	M3	GPIO
PA10	M4	GPIO	PA13	M5	GPIO (5V)
PA14	M6	GPIO	RESETn	M7	Reset input, active low. To apply an external reset source to this pin, it is required to only drive this pin low during reset, and let the internal pull-up ensure that reset is released.
AVDD	M9 M10 N11	Analog power supply.	PD3	M12	GPIO
PD6	M13	GPIO	PB8	N1	GPIO
PC5	N2	GPIO	PA9	N3	GPIO
PA11	N4	GPIO	PA12	N5	GPIO (5V)
PB11	N6	GPIO	PB12	N7	GPIO
PB13	N9	GPIO	PB14	N10	GPIO
PD2	N12	GPIO (5V)	PD5	N13	GPIO

Note:

1. GPIO with 5V tolerance are indicated by (5V).
2. The pins PD13, PD14, and PD15 will not be 5V tolerant on all future devices. In order to preserve upgrade options with full hardware compatibility, do not use these pins with 5V domains.

5.9 EFM32GG11B5xx in QFP100 Device Pinout

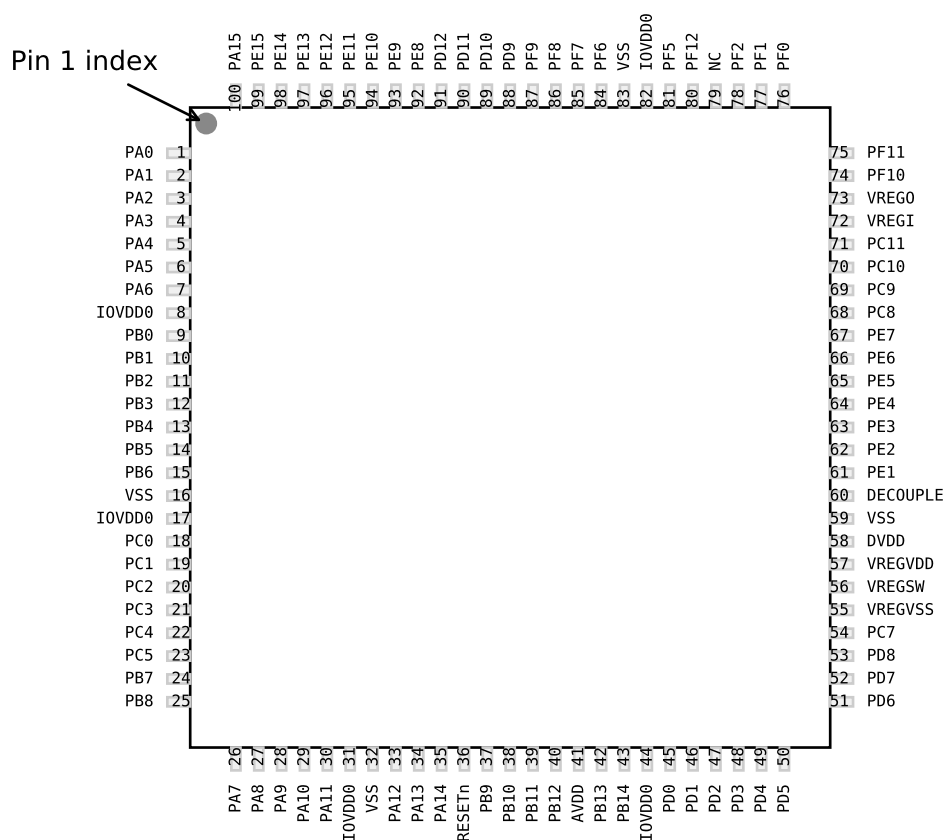


Figure 5.9. EFM32GG11B5xx in QFP100 Device Pinout

The following table provides package pin connections and general descriptions of pin functionality. For detailed information on the supported features for each GPIO pin, see [5.20 GPIO Functionality Table](#) or [5.21 Alternate Functionality Overview](#).

Table 5.9. EFM32GG11B5xx in QFP100 Device Pinout

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PA0	1	GPIO	PA1	2	GPIO
PA2	3	GPIO	PA3	4	GPIO
PA4	5	GPIO	PA5	6	GPIO
PA6	7	GPIO	IOVDD0	8, 17, 31, 44, 82	Digital IO power supply 0.
PB0	9	GPIO	PB1	10	GPIO

5.16 EFM32GG11B8xx in QFN64 Device Pinout

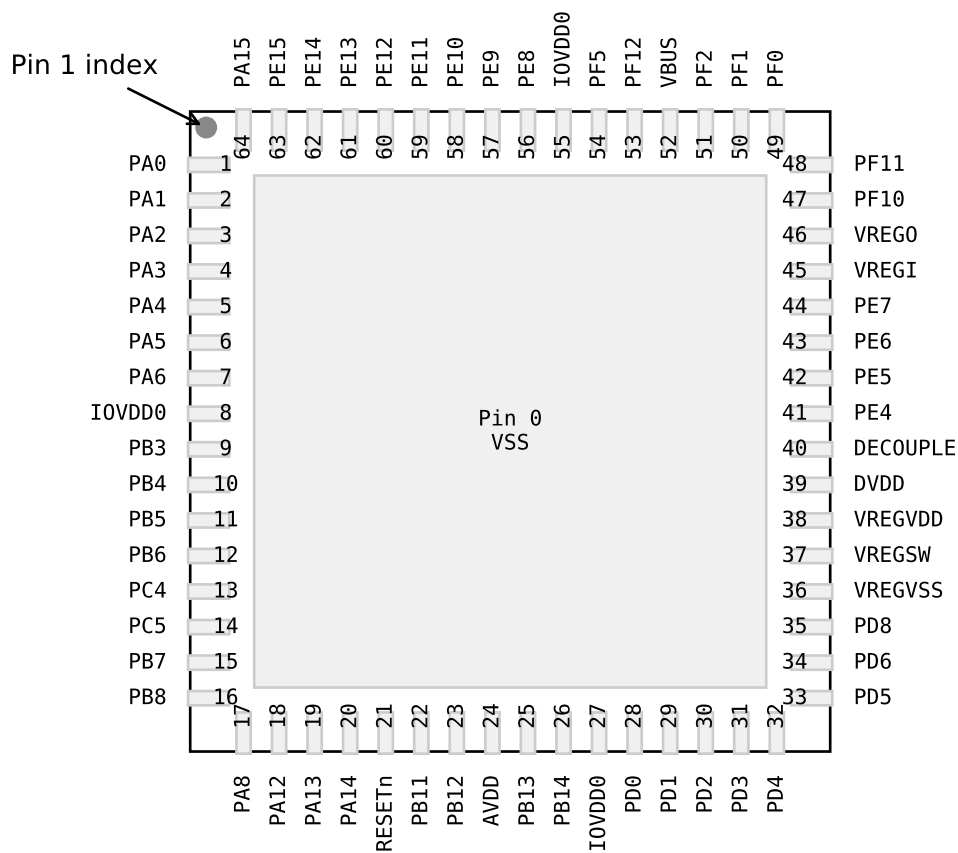


Figure 5.16. EFM32GG11B8xx in QFN64 Device Pinout

The following table provides package pin connections and general descriptions of pin functionality. For detailed information on the supported features for each GPIO pin, see [5.20 GPIO Functionality Table](#) or [5.21 Alternate Functionality Overview](#).

Table 5.16. EFM32GG11B8xx in QFN64 Device Pinout

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
VSS	0	Ground	PA0	1	GPIO
PA1	2	GPIO	PA2	3	GPIO
PA3	4	GPIO	PA4	5	GPIO
PA5	6	GPIO	PA6	7	GPIO
IOVDD0	8 27 55	Digital IO power supply 0.	PB3	9	GPIO
PB4	10	GPIO	PB5	11	GPIO

GPIO Name	Pin Alternate Functionality / Description				
	Analog	EBI	Timers	Communication	Other
PD4	BUSADC0Y BU-SADC0X OPA2_P	EBI_A08 #1 EBI_A17 #3	TIM6_CC0 #7 WTIM0_CDTI0 #4 WTIM1_CC2 #1 WTIM2_CC1 #5	CAN1_TX #2 US1_CTS #1 US3_CLK #2 LEU0_TX #0 I2C1_SDA #3	CMU_CLKI0 #0 PRS_CH10 #2 ETM_TD2 #0 ETM_TD2 #2
PC0	VDAC0_OUT0ALT / OPA0_OUTALT #0 BUSACMP0Y BU-SACMP0X	EBI_AD07 #1 EBI_CS0 #2 EBI_REn #3 EBI_A23 #0	TIM0_CC1 #3 TIM2_CC1 #4 PCNT0_S0IN #2	ETH_MDIO #2 CAN0_RX #0 US0_TX #5 US1_TX #0 US1_CS #4 US2_RTS #0 US3_CS #3 I2C0_SDA #4	LES_CH0 PRS_CH2 #0
PC1	VDAC0_OUT0ALT / OPA0_OUTALT #1 BUSACMP0Y BU-SACMP0X	EBI_AD08 #1 EBI_CS1 #2 EBI_BL0 #3 EBI_A24 #0	TIM0_CC2 #3 TIM2_CC2 #4 WTIM0_CC0 #7 PCNT0_S1IN #2	ETH_MDC #2 CAN0_TX #0 US0_RX #5 US1_TX #4 US1_RX #0 US2_CTS #0 US3_RTS #1 I2C0_SCL #4	LES_CH1 PRS_CH3 #0
PC2	VDAC0_OUT0ALT / OPA0_OUTALT #2 BUSACMP0Y BU-SACMP0X	EBI_AD09 #1 EBI_CS2 #2 EBI_NANDWEEn #3 EBI_A25 #0	TIM0_CDTI0 #3 TIM2_CC0 #5 WTIM0_CC1 #7 LE-TIM1_OUT0 #3	ETH_TSUEXTCLK #2 CAN1_RX #0 US1_RX #4 US2_TX #0	LES_CH2 PRS_CH10 #1
PA8	BUSBY BUSAX LCD_SEG36	EBI_AD14 #1 EBI_A02 #3 EBI_DCLK #0	TIM2_CC0 #0 TIM0_CC0 #6 LE-TIM0_OUT0 #6 PCNT1_S1IN #4	US2_RX #2 US4_RTS #0	PRS_CH8 #0
PA11	BUSAY BUSBX LCD_SEG39	EBI_CS1 #1 EBI_A05 #3 EBI_HSNC #0	WTIM2_CC2 #0 LE-TIM1_OUT0 #1	US2_CTS #2	PRS_CH11 #0
PA13	BUSAY BUSBX	EBI_WEn #1 EBI_NANDWEEn #2 EBI_A01 #0 EBI_A07 #3	TIM0_CC2 #7 TIM2_CC1 #1 WTIM0_CDTI1 #2 WTIM2_CC1 #1 LE-TIM1_OUT1 #1 PCNT1_S1IN #5	CAN1_TX #5 US0_CS #5 US2_TX #3	PRS_CH13 #0
PB9	BUSAY BUSBX	EBI_ALE #1 EBI_NANDREn #2 EBI_A00 #1 EBI_A03 #0 EBI_A09 #3	WTIM2_CC0 #2 LE-TIM0_OUT0 #7	SDIO_WP #3 CAN0_RX #3 US1_CTS #0 U1_TX #2	PRS_CH13 #1 ACMP1_O #5
PB12	BUSBY BUSAX VDAC0_OUT1 / OPA1_OUT	EBI_A03 #1 EBI_A12 #3 EBI_CSTFT #2	TIM1_CC3 #3 WTIM2_CC0 #3 LE-TIM0_OUT1 #1 PCNT0_S0IN #7 PCNT1_S1IN #6	US2_CTS #1 US5_RTS #0 U1_RTS #2 I2C1_SCL #1	PRS_CH16 #1
PH2	BUSADC1Y BU-SADC1X	EBI_VSNC #2	TIM6_CC0 #3	US1_CTS #6	
PH5	BUSADC1Y BU-SADC1X	EBI_A17 #2	TIM6_CDTI0 #3 WTIM2_CC1 #6	US4_RX #4	
PH8	BUSACMP3Y BU-SACMP3X	EBI_A20 #2	TIM6_CC0 #4 WTIM1_CC0 #6 WTIM2_CC1 #7	US4_CTS #4	

Port	Bus	CH31	CH30	CH29	CH28	CH27	CH26	CH25	CH24	CH23	CH22	CH21	CH20	CH19	CH18	CH17	CH16	CH15	CH14	CH13	CH12	CH11	CH10	CH9	CH8	CH7	CH6	CH5	CH4	CH3	CH2	CH1	CH0
VDAC0_OUT1 / OPA1_OUT																																	
APORT4Y	APORT3Y	APORT2Y	APORT1Y																														
BUSDY	BUSCY	BUSBY	BUSAY																														
	PF15		PB15																														
PF14		PB14																															
	PF13		PB13																														
PF12		PB12																															
	PF11		PB11																														
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	PF5		PB5																														
PF4		PB4																															
	PF3		PB3																														
PF2		PB2																															
	PF1		PB1																														
PF0		PB0																															
	PE15		PA15																														
PE14		PA14																															
	PE13		PA13																														
PE12		PA12																															
	PE11		PA11																														
PE10		PA10																															
	PE9		PA9																														
PE8		PA8																															
	PE7		PA7																														
PE6		PA6																															
	PE5		PA5																														
PE4		PA4																															
			PA3																														
		PA2																															
	PE1		PA1																														
PE0		PA0																															

10. TQFP100 Package Specifications

10.1 TQFP100 Package Dimensions

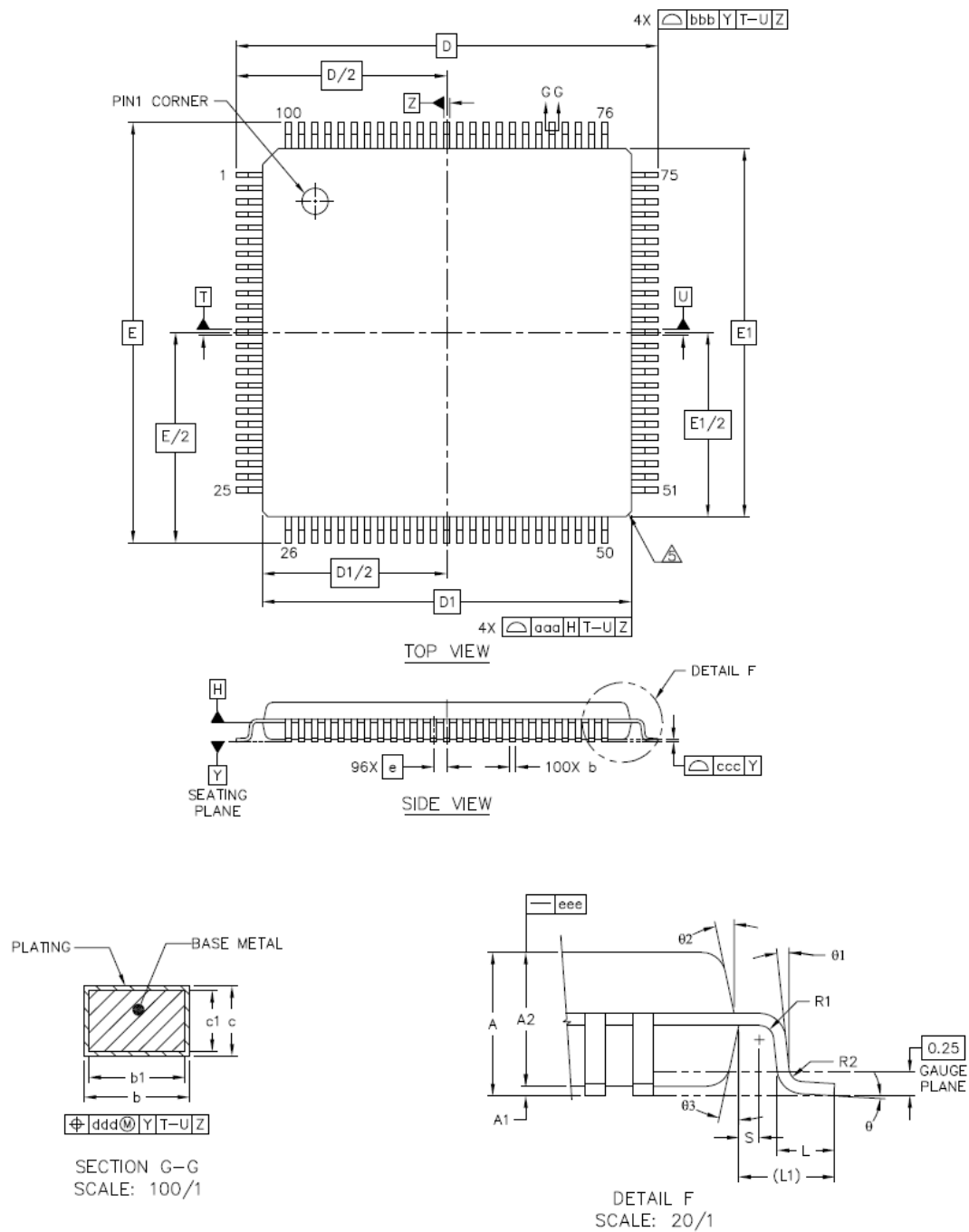


Figure 10.1. TQFP100 Package Drawing

Table 12.1. QFN64 Package Dimensions

Dimension	Min	Typ	Max
A	0.70	0.75	0.80
A1	0.00	—	0.05
b	0.20	0.25	0.30
A3	0.203 REF		
D	9.00 BSC		
e	0.50 BSC		
E	9.00 BSC		
D2	7.10	7.20	7.30
E2	7.10	7.20	7.30
L	0.40	0.45	0.50
L1	0.00	—	0.10
aaa	0.10		
bbb	0.10		
ccc	0.10		
ddd	0.05		
eee	0.08		

Note:

1. All dimensions shown are in millimeters (mm) unless otherwise noted.
2. Dimensioning and Tolerancing per ANSI Y14.5M-1994.
3. Recommended card reflow profile is per the JEDEC/IPC J-STD-020 specification for Small Body Components.