

Welcome to [E-XFL.COM](#)

What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Obsolete
Core Processor	ARM® Cortex®-M4
Core Size	32-Bit Single-Core
Speed	72MHz
Connectivity	CANbus, EBI/EMI, I²C, IrDA, LINbus, SmartCard, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, LCD, POR, PWM, WDT
Number of I/O	95
Program Memory Size	2MB (2M x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	384K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.8V
Data Converters	A/D 16x12b SAR; D/A 2x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	120-VFBGA
Supplier Device Package	120-BGA (7x7)
Purchase URL	https://www.e-xfl.com/product-detail/silicon-labs/efm32gg11b510f2048il120-a

3.12 Configuration Summary

The features of the EFM32GG11 are a subset of the feature set described in the device reference manual. The table below describes device specific implementation of the features. Remaining modules support full configuration.

Table 3.2. Configuration Summary

Module	Configuration	Pin Connections
USART0	IrDA, SmartCard	US0_TX, US0_RX, US0_CLK, US0_CS
USART1	I ² S, SmartCard	US1_TX, US1_RX, US1_CLK, US1_CS
USART2	IrDA, SmartCard, High-Speed	US2_TX, US2_RX, US2_CLK, US2_CS
USART3	I ² S, SmartCard	US3_TX, US3_RX, US3_CLK, US3_CS
USART4	I ² S, SmartCard	US4_TX, US4_RX, US4_CLK, US4_CS
USART5	SmartCard	US5_TX, US5_RX, US5_CLK, US5_CS
TIMER0	with DTI	TIM0_CC[2:0], TIM0_CDTI[2:0]
TIMER1	-	TIM1_CC[3:0]
TIMER2	with DTI	TIM2_CC[2:0], TIM2_CDTI[2:0]
TIMER3	-	TIM3_CC[2:0]
TIMER4	with DTI	TIM4_CC[2:0], TIM4_CDTI[2:0]
TIMER5	-	TIM5_CC[2:0]
TIMER6	with DTI	TIM6_CC[2:0], TIM6_CDTI[2:0]
WTIMER0	with DTI	WTIM0_CC[2:0], WTIM0_CDTI[2:0]
WTIMER1	-	WTIM1_CC[3:0]
WTIMER2	-	WTIM2_CC[2:0]
WTIMER3	-	WTIM3_CC[2:0]

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Note:						
1.	The minimum voltage required in bypass mode is calculated using R_{BYP} from the DCDC specification table. Requirements for other loads can be calculated as $V_{DVDD_min} + I_{LOAD} * R_{BYP_max}$.					
2.	VREGVDD must be tied to AVDD. Both VREGVDD and AVDD minimum voltages must be satisfied for the part to operate.					
3.	The system designer should consult the characteristic specs of the capacitor used on DECOUPLE to ensure its capacitance value stays within the specified bounds across temperature and DC bias.					
4.	VSCALE0 to VSCALE2 voltage change transitions occur at a rate of 10 mV / usec for approximately 20 usec. During this transition, peak currents will be dependent on the value of the DECOUPLE output capacitor, from 35 mA (with a 1 μ F capacitor) to 70 mA (with a 2.7 μ F capacitor).					
5.	When the CSEN peripheral is used with chopping enabled (CSEN_CTRL_CHOPEN = ENABLE), IOVDD must be equal to AVDD.					
6.	The maximum limit on T_A may be lower due to device self-heating, which depends on the power dissipation of the specific application. T_A (max) = T_J (max) - (θ_{TAJA} x PowerDissipation). Refer to the Absolute Maximum Ratings table and the Thermal Characteristics table for T_J and θ_{TAJA} .					

4.1.3 Thermal Characteristics

Table 4.3. Thermal Characteristics

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Thermal resistance, QFN64 Package	THE _A _J _A _QFN64	4-Layer PCB, Air velocity = 0 m/s	—	17.8	—	°C/W
		4-Layer PCB, Air velocity = 1 m/s	—	15.4	—	°C/W
		4-Layer PCB, Air velocity = 2 m/s	—	13.8	—	°C/W
Thermal resistance, TQFP64 Package	THE _A _J _A _TQFP64	4-Layer PCB, Air velocity = 0 m/s	—	33.9	—	°C/W
		4-Layer PCB, Air velocity = 1 m/s	—	32.1	—	°C/W
		4-Layer PCB, Air velocity = 2 m/s	—	30.1	—	°C/W
Thermal resistance, TQFP100 Package	THE _A _J _A _TQFP100	4-Layer PCB, Air velocity = 0 m/s	—	44.1	—	°C/W
		4-Layer PCB, Air velocity = 1 m/s	—	37.7	—	°C/W
		4-Layer PCB, Air velocity = 2 m/s	—	35.5	—	°C/W
Thermal resistance, BGA112 Package	THE _A _J _A _BGA112	4-Layer PCB, Air velocity = 0 m/s	—	42.0	—	°C/W
		4-Layer PCB, Air velocity = 1 m/s	—	37.0	—	°C/W
		4-Layer PCB, Air velocity = 2 m/s	—	35.3	—	°C/W
Thermal resistance, BGA120 Package	THE _A _J _A _BGA120	4-Layer PCB, Air velocity = 0 m/s	—	47.9	—	°C/W
		4-Layer PCB, Air velocity = 1 m/s	—	41.8	—	°C/W
		4-Layer PCB, Air velocity = 2 m/s	—	39.6	—	°C/W
Thermal resistance, BGA152 Package	THE _A _J _A _BGA152	4-Layer PCB, Air velocity = 0 m/s	—	35.7	—	°C/W
		4-Layer PCB, Air velocity = 1 m/s	—	31.0	—	°C/W
		4-Layer PCB, Air velocity = 2 m/s	—	29.5	—	°C/W
Thermal resistance, BGA192 Package	THE _A _J _A _BGA192	4-Layer PCB, Air velocity = 0 m/s	—	47.9	—	°C/W
		4-Layer PCB, Air velocity = 1 m/s	—	41.8	—	°C/W
		4-Layer PCB, Air velocity = 2 m/s	—	39.6	—	°C/W

4.1.12 General-Purpose I/O (GPIO)

Table 4.20. General-Purpose I/O (GPIO)

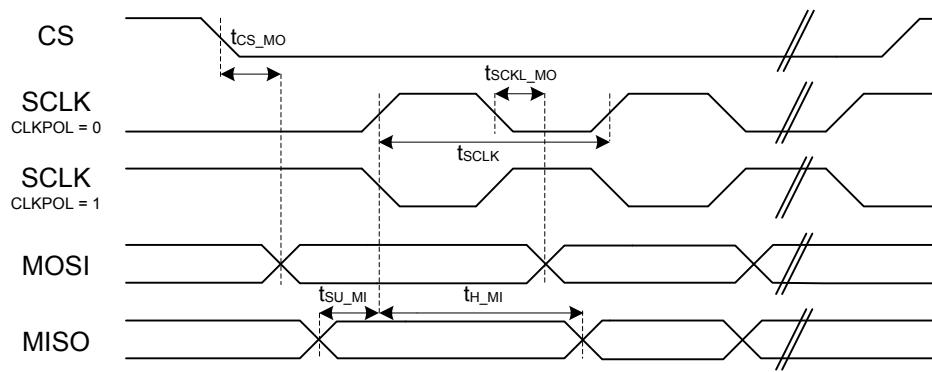
Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Input low voltage	V _{IL}	GPIO pins	—	—	IOVDD*0.3	V
Input high voltage	V _{IH}	GPIO pins	IOVDD*0.7	—	—	V
Output high voltage relative to IOVDD	V _{OH}	Sourcing 3 mA, IOVDD ≥ 3 V, DRIVESTRENGTH ¹ = WEAK	IOVDD*0.8	—	—	V
		Sourcing 1.2 mA, IOVDD ≥ 1.62 V, DRIVESTRENGTH ¹ = WEAK	IOVDD*0.6	—	—	V
		Sourcing 20 mA, IOVDD ≥ 3 V, DRIVESTRENGTH ¹ = STRONG	IOVDD*0.8	—	—	V
		Sourcing 8 mA, IOVDD ≥ 1.62 V, DRIVESTRENGTH ¹ = STRONG	IOVDD*0.6	—	—	V
Output low voltage relative to IOVDD	V _{OL}	Sinking 3 mA, IOVDD ≥ 3 V, DRIVESTRENGTH ¹ = WEAK	—	—	IOVDD*0.2	V
		Sinking 1.2 mA, IOVDD ≥ 1.62 V, DRIVESTRENGTH ¹ = WEAK	—	—	IOVDD*0.4	V
		Sinking 20 mA, IOVDD ≥ 3 V, DRIVESTRENGTH ¹ = STRONG	—	—	IOVDD*0.2	V
		Sinking 8 mA, IOVDD ≥ 1.62 V, DRIVESTRENGTH ¹ = STRONG	—	—	IOVDD*0.4	V
Input leakage current	I _{IOLEAK}	All GPIO except LFXO pins, GPIO ≤ IOVDD, T ≤ 85 °C	—	0.1	TBD	nA
		LFXO Pins, GPIO ≤ IOVDD, T ≤ 85 °C	—	0.1	TBD	nA
		All GPIO except LFXO pins, GPIO ≤ IOVDD, T > 85 °C	—	—	TBD	nA
		LFXO Pins, GPIO ≤ IOVDD, T > 85 °C	—	—	TBD	nA
Input leakage current on 5VTOL pads above IOVDD	I _{5VTOLLEAK}	IOVDD < GPIO ≤ IOVDD + 2 V	—	3.3	TBD	µA
I/O pin pull-up/pull-down resistor	R _{PUD}		TBD	40	TBD	kΩ
Pulse width of pulses removed by the glitch suppression filter	t _{IOGLITCH}		15	25	35	ns

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Hysteresis ($V_{CM} = 1.25$ V, $\text{BIASPROG}^4 = 0x10$, FULL-BIAS ⁴ = 1)	VACMPHYST	HYSTSEL ⁵ = HYST0	TBD	0	TBD	mV
		HYSTSEL ⁵ = HYST1	TBD	18	TBD	mV
		HYSTSEL ⁵ = HYST2	TBD	33	TBD	mV
		HYSTSEL ⁵ = HYST3	TBD	46	TBD	mV
		HYSTSEL ⁵ = HYST4	TBD	57	TBD	mV
		HYSTSEL ⁵ = HYST5	TBD	68	TBD	mV
		HYSTSEL ⁵ = HYST6	TBD	79	TBD	mV
		HYSTSEL ⁵ = HYST7	TBD	90	TBD	mV
		HYSTSEL ⁵ = HYST8	TBD	0	TBD	mV
		HYSTSEL ⁵ = HYST9	TBD	-18	TBD	mV
		HYSTSEL ⁵ = HYST10	TBD	-33	TBD	mV
		HYSTSEL ⁵ = HYST11	TBD	-45	TBD	mV
		HYSTSEL ⁵ = HYST12	TBD	-57	TBD	mV
		HYSTSEL ⁵ = HYST13	TBD	-67	TBD	mV
		HYSTSEL ⁵ = HYST14	TBD	-78	TBD	mV
		HYSTSEL ⁵ = HYST15	TBD	-88	TBD	mV
Comparator delay ³	tACMPDELAY	BIASPROG ⁴ = 1, FULLBIAS ⁴ = 0	—	30	—	μs
		BIASPROG ⁴ = 0x10, FULLBIAS ⁴ = 0	—	3.7	—	μs
		BIASPROG ⁴ = 0x02, FULLBIAS ⁴ = 1	—	360	—	ns
		BIASPROG ⁴ = 0x20, FULLBIAS ⁴ = 1	—	35	—	ns
Offset voltage	VACMPOFFSET	BIASPROG ⁴ = 0x10, FULLBIAS ⁴ = 1	TBD	—	TBD	mV
Reference voltage	VACMPREF	Internal 1.25 V reference	TBD	1.25	TBD	V
		Internal 2.5 V reference	TBD	2.5	TBD	V
Capacitive sense internal resistance	RCSRES	CSRESSEL ⁶ = 0	—	infinite	—	kΩ
		CSRESSEL ⁶ = 1	—	15	—	kΩ
		CSRESSEL ⁶ = 2	—	27	—	kΩ
		CSRESSEL ⁶ = 3	—	39	—	kΩ
		CSRESSEL ⁶ = 4	—	51	—	kΩ
		CSRESSEL ⁶ = 5	—	100	—	kΩ
		CSRESSEL ⁶ = 6	—	162	—	kΩ
		CSRESSEL ⁶ = 7	—	235	—	kΩ

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
MISO hold time ^{1 3}	t_{H_MI}	USART2, location 4, IOVDD = 1.8 V	-11.6	—	—	ns
		USART2, location 4, IOVDD = 3.0 V	-11.6	—	—	ns
		USART2, location 5, IOVDD = 1.8 V	-9.1	—	—	ns
		USART2, location 5, IOVDD = 3.0 V	-9.1	—	—	ns
		All other USARTs and locations, IOVDD = 1.8 V	-8	—	—	ns
		All other USARTs and locations, IOVDD = 3.0 V	-8	—	—	ns

Note:

1. Applies for both CLKPHA = 0 and CLKPHA = 1 (figure only shows CLKPHA = 0).
2. $t_{HPERCLK}$ is one period of the selected HPERCLK.
3. Measurement done with 8 pF output loading at 10% and 90% of V_{DD} (figure shows 50% of V_{DD}).

**Figure 4.1. SPI Master Timing Diagram**

SDIO SDR Mode Timing

Timing is specified for route location 0 at 1.8 V IOVDD with voltage scaling disabled. Slew rate for SD_CLK set to 7, all other GPIO set to 6, DRIVESTRENGTH = STRONG for all pins. SDIO_CTRL_TXDLYMUXSEL = 0. Loading between 5 and 10 pF on all pins or between 10 and 40 pF on all pins.

Table 4.48. SDIO SDR Mode Timing (Location 0)

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Clock frequency during data transfer	FSD_CLK	Using HFRCO, AUXHFRCO, or USHFRCO	—	—	20	MHz
		Using HFXO	—	—	TBD	MHz
Clock low time	tWL	Using HFRCO, AUXHFRCO, or USHFRCO	22.6	—	—	ns
		Using HFXO	TBD	—	—	ns
Clock high time	tWH	Using HFRCO, AUXHFRCO, or USHFRCO	22.6	—	—	ns
		Using HFXO	TBD	—	—	ns
Clock rise time	tR		0.99	4.68	—	ns
Clock fall time	tF		0.90	3.64	—	ns
Input setup time, CMD, DAT[0:3] valid to SD_CLK	tISU		8	—	—	ns
Input hold time, SD_CLK to CMD, DAT[0:3] change	tIH		1.5	—	—	ns
Output delay time, SD_CLK to CMD, DAT[0:3] valid	tODLY		0	—	35	ns
Output hold time, SD_CLK to CMD, DAT[0:3] change	tOH		0.8	—	—	ns

5. Pin Definitions

5.1 EFM32GG11B8xx in BGA192 Device Pinout

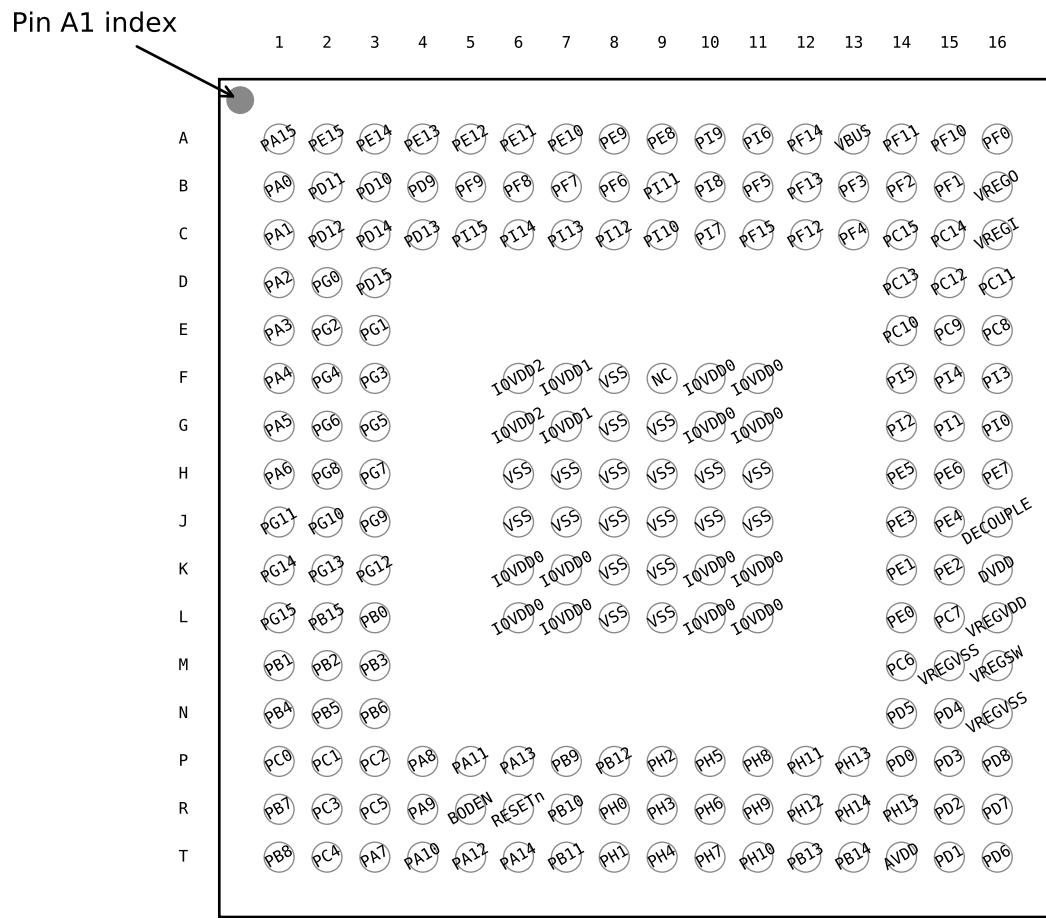


Figure 5.1. EFM32GG11B8xx in BGA192 Device Pinout

The following table provides package pin connections and general descriptions of pin functionality. For detailed information on the supported features for each GPIO pin, see [5.20 GPIO Functionality Table](#) or [5.21 Alternate Functionality Overview](#).

Table 5.1. EFM32GG11B8xx in BGA192 Device Pinout

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PA15	A1	GPIO	PE15	A2	GPIO
PE14	A3	GPIO	PE13	A4	GPIO
PE12	A5	GPIO	PE11	A6	GPIO
PE10	A7	GPIO	PE9	A8	GPIO
PE8	A9	GPIO	PI9	A10	GPIO (5V)
PI6	A11	GPIO (5V)	PF14	A12	GPIO (5V)

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PB2	M2	GPIO	PB3	M3	GPIO
PC6	M14	GPIO	VREGVSS	M15 N16	Voltage regulator VSS
VREGSW	M16	DCDC regulator switching node	PB4	N1	GPIO
PB5	N2	GPIO	PB6	N3	GPIO
PD5	N14	GPIO	PD4	N15	GPIO
PC0	P1	GPIO (5V)	PC1	P2	GPIO (5V)
PC2	P3	GPIO (5V)	PA8	P4	GPIO
PA11	P5	GPIO	PA13	P6	GPIO (5V)
PB9	P7	GPIO (5V)	PB12	P8	GPIO
PH2	P9	GPIO (5V)	PH5	P10	GPIO
PH8	P11	GPIO (5V)	PH11	P12	GPIO (5V)
PH13	P13	GPIO (5V)	PD0	P14	GPIO (5V)
PD3	P15	GPIO	PD8	P16	GPIO
PB7	R1	GPIO	PC3	R2	GPIO (5V)
PC5	R3	GPIO	PA9	R4	GPIO
BODEN	R5	Brown-Out Detector Enable. This pin may be left disconnected or tied to AVDD.	RESETn	R6	Reset input, active low. To apply an external reset source to this pin, it is required to only drive this pin low during reset, and let the internal pull-up ensure that reset is released.
PB10	R7	GPIO (5V)	PH0	R8	GPIO (5V)
PH3	R9	GPIO (5V)	PH6	R10	GPIO
PH9	R11	GPIO (5V)	PH12	R12	GPIO (5V)
PH14	R13	GPIO (5V)	PH15	R14	GPIO (5V)
PD2	R15	GPIO (5V)	PD7	R16	GPIO
PB8	T1	GPIO	PC4	T2	GPIO
PA7	T3	GPIO	PA10	T4	GPIO
PA12	T5	GPIO (5V)	PA14	T6	GPIO
PB11	T7	GPIO	PH1	T8	GPIO (5V)
PH4	T9	GPIO	PH7	T10	GPIO (5V)
PH10	T11	GPIO (5V)	PB13	T12	GPIO
PB14	T13	GPIO	AVDD	T14	Analog power supply.
PD1	T15	GPIO	PD6	T16	GPIO

Note:

1. GPIO with 5V tolerance are indicated by (5V).
2. The pins PD13, PD14, and PD15 will not be 5V tolerant on all future devices. In order to preserve upgrade options with full hardware compatibility, do not use these pins with 5V domains.

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
VREGVDD	J13	Voltage regulator VDD input	PC0	K1	GPIO (5V)
PC1	K2	GPIO (5V)	PE0	K12	GPIO (5V)
VREGSW	K13	DCDC regulator switching node	PC2	L1	GPIO (5V)
PC3	L2	GPIO (5V)	PA7	L3	GPIO
PB9	L13	GPIO (5V)	PB10	L14	GPIO (5V)
PD1	L17	GPIO	PC6	L18	GPIO
PC7	L19	GPIO	VREGVSS	L20	Voltage regulator VSS
PB7	M1	GPIO	PC4	M2	GPIO
PA8	M3	GPIO	PA10	M4	GPIO
PA13	M5	GPIO (5V)	PA14	M6	GPIO
RESETn	M7	Reset input, active low. To apply an external reset source to this pin, it is required to only drive this pin low during reset, and let the internal pull-up ensure that reset is released.	PB12	M8	GPIO
PD0	M9	GPIO (5V)	PD2	M10	GPIO (5V)
PD3	M11	GPIO	PD4	M12	GPIO
PD8	M13	GPIO	PB8	N1	GPIO
PC5	N2	GPIO	PA9	N3	GPIO
PA11	N4	GPIO	PA12	N5	GPIO (5V)
PB11	N6	GPIO	BODEN	N7	Brown-Out Detector Enable. This pin may be left disconnected or tied to AVDD.
PB13	N8	GPIO	PB14	N9	GPIO
AVDD	N10	Analog power supply.	PD5	N11	GPIO
PD6	N12	GPIO	PD7	N13	GPIO

Note:

1. GPIO with 5V tolerance are indicated by (5V).
2. The pins PD13, PD14, and PD15 will not be 5V tolerant on all future devices. In order to preserve upgrade options with full hardware compatibility, do not use these pins with 5V domains.

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PB2	11	GPIO	PB3	12	GPIO
PB4	13	GPIO	PB5	14	GPIO
PB6	15	GPIO	VSS	16 32 59 83	Ground
PC0	18	GPIO (5V)	PC1	19	GPIO (5V)
PC2	20	GPIO (5V)	PC3	21	GPIO (5V)
PC4	22	GPIO	PC5	23	GPIO
PB7	24	GPIO	PB8	25	GPIO
PA7	26	GPIO	PA8	27	GPIO
PA9	28	GPIO	PA10	29	GPIO
PA11	30	GPIO	PA12	33	GPIO (5V)
PA13	34	GPIO (5V)	PA14	35	GPIO
RESETn	36	Reset input, active low. To apply an external reset source to this pin, it is required to only drive this pin low during reset, and let the internal pull-up ensure that reset is released.	PB9	37	GPIO (5V)
PB10	38	GPIO (5V)	PB11	39	GPIO
PB12	40	GPIO	AVDD	41	Analog power supply.
PB13	42	GPIO	PB14	43	GPIO
PD0	45	GPIO (5V)	PD1	46	GPIO
PD2	47	GPIO (5V)	PD3	48	GPIO
PD4	49	GPIO	PD5	50	GPIO
PD6	51	GPIO	PD7	52	GPIO
PD8	53	GPIO	PC7	54	GPIO
VREGVSS	55	Voltage regulator VSS	VREGSW	56	DCDC regulator switching node
VREGVDD	57	Voltage regulator VDD input	DVDD	58	Digital power supply.
DECOUPLE	60	Decouple output for on-chip voltage regulator. An external decoupling capacitor is required at this pin.	PE1	61	GPIO (5V)
PE2	62	GPIO	PE3	63	GPIO
PE4	64	GPIO	PE5	65	GPIO
PE6	66	GPIO	PE7	67	GPIO
PC8	68	GPIO (5V)	PC9	69	GPIO (5V)
PC10	70	GPIO (5V)	PC11	71	GPIO (5V)
VREGI	72	Input to 5 V regulator.	VREGO	73	Decoupling for 5 V regulator and regulator output. Power for USB PHY in USB-enabled OPNs
PF10	74	GPIO (5V)	PF11	75	GPIO (5V)
PF0	76	GPIO (5V)	PF1	77	GPIO (5V)

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PB2	11	GPIO	PB3	12	GPIO
PB4	13	GPIO	PB5	14	GPIO
PB6	15	GPIO	VSS	16 32 59 83	Ground
PC0	18	GPIO (5V)	PC1	19	GPIO (5V)
PC2	20	GPIO (5V)	PC3	21	GPIO (5V)
PC4	22	GPIO	PC5	23	GPIO
PB7	24	GPIO	PB8	25	GPIO
PA7	26	GPIO	PA8	27	GPIO
PA9	28	GPIO	PA10	29	GPIO
PA11	30	GPIO	PA12	33	GPIO (5V)
PA13	34	GPIO (5V)	PA14	35	GPIO
RESETn	36	Reset input, active low. To apply an external reset source to this pin, it is required to only drive this pin low during reset, and let the internal pull-up ensure that reset is released.	PB9	37	GPIO (5V)
PB10	38	GPIO (5V)	PB11	39	GPIO
PB12	40	GPIO	AVDD	41	Analog power supply.
PB13	42	GPIO	PB14	43	GPIO
PD0	45	GPIO (5V)	PD1	46	GPIO
PD2	47	GPIO (5V)	PD3	48	GPIO
PD4	49	GPIO	PD5	50	GPIO
PD6	51	GPIO	PD7	52	GPIO
PD8	53	GPIO	PC7	54	GPIO
VREGVSS	55	Voltage regulator VSS	VREGSW	56	DCDC regulator switching node
VREGVDD	57	Voltage regulator VDD input	DVDD	58	Digital power supply.
DECOUPLE	60	Decouple output for on-chip voltage regulator. An external decoupling capacitor is required at this pin.	PE1	61	GPIO (5V)
PE2	62	GPIO	PE3	63	GPIO
PE4	64	GPIO	PE5	65	GPIO
PE6	66	GPIO	PE7	67	GPIO
PC8	68	GPIO (5V)	PC9	69	GPIO (5V)
PC10	70	GPIO (5V)	PC11	71	GPIO (5V)
VREGI	72	Input to 5 V regulator.	VREGO	73	Decoupling for 5 V regulator and regulator output. Power for USB PHY in USB-enabled OPNs
PF10	74	GPIO (5V)	PF11	75	GPIO (5V)
PF0	76	GPIO (5V)	PF1	77	GPIO (5V)

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PF3	79	GPIO	PF4	80	GPIO
PF5	81	GPIO	PF6	84	GPIO
PF7	85	GPIO	PF8	86	GPIO
PF9	87	GPIO	PD9	88	GPIO
PD10	89	GPIO	PD11	90	GPIO
PD12	91	GPIO	PE8	92	GPIO
PE9	93	GPIO	PE10	94	GPIO
PE11	95	GPIO	PE12	96	GPIO
PE13	97	GPIO	PE14	98	GPIO
PE15	99	GPIO	PA15	100	GPIO

Note:

1. GPIO with 5V tolerance are indicated by (5V).

GPIO Name	Pin Alternate Functionality / Description				
	Analog	EBI	Timers	Communication	Other
PF14	BUSDY BUSCX		TIM1_CC1 #6 TIM4_CC1 #1 TIM5_CC2 #7 WTIM3_CC1 #7	I2C2_SCL #4	
PF11	BUSCY BUSDX	EBI_NANDWE _n #5	TIM5_CC2 #6 WTIM3_CC2 #3 PCNT2_S1IN #3	US5_CTS #2 U1_RX #1 I2C2_SCL #2 USB_DP	
PF10	BUSDY BUSCX	EBI_ARDY #5	TIM5_CC1 #6 WTIM3_CC1 #3 PCNT2_S0IN #3	US5_RTS #2 U1_TX #1 I2C2_SDA #2 USB_DM	
PF0	BUSDY BUSCX	EBI_A24 #1	TIM0_CC0 #4 WTIM0_CC1 #4 LE-TIM0_OUT0 #2	US2_TX #5 CAN0_RX #1 US1_CLK #2 LEU0_TX #3 I2C0_SDA #5	PRS_CH15 #2 ACMP3_O #0 DBG_SWCLKTCK BOOT_TX
PA0	BUSBY BUSAX LCD_SEG13	EBI_AD09 #0 EBI_CSTFT #3	TIM0_CC0 #0 TIM0_CC1 #7 TIM3_CC0 #4 PCNT0_S0IN #4	ETH_RMIITXEN #0 ETH_MIIITXCLK #0 SDIO_DAT0 #1 US1_RX #5 US3_TX #0 QSPI0_CS0 #1 LEU0_RX #4 I2C0_SDA #0	CMU_CLK2 #0 PRS_CH0 #0 PRS_CH3 #3 GPIO_EM4WU0
PD11	LCD_SEG30	EBI_CS2 #0 EBI_HSNC #1	TIM4_CC0 #6 WTIM3_CC2 #0	ETH_RMIICRSDV #1 SDIO_DAT5 #0 QSPI0_DQ2 #0 ETH_MIIRXD3 #2 US4_CLK #1	
PD10	LCD_SEG29	EBI_CS1 #0 EBI_VSNC #1	TIM4_CC2 #5 WTIM3_CC1 #0	ETH_RMIIREFCLK #1 SDIO_DAT6 #0 QSPI0_DQ1 #0 ETH_MIIRXD2 #2 US4_RX #1	CMU_CLK2 #5 CMU_CLKI0 #5
PD9	LCD_SEG28	EBI_CS0 #0 EBI_DTEN #1	TIM4_CC1 #5 WTIM3_CC0 #0	ETH_RMIIRXD0 #1 SDIO_DAT7 #0 QSPI0_DQ0 #0 ETH_MIIRXD1 #2 US4_TX #1	
PF9	BUSCY BUSDX LCD_SEG27	EBI_REn #4 EBI_BL1 #1	TIM4_CC0 #5	ETH_RMIIRXD1 #1 US2_CS #4 QSPI0_DQS #0 ETH_MIIRXD0 #2 ETH_TSUTMRTOG #3 SDIO_WP #0 U0_RTS #0 U1_CTS #1	ETM_TD0 #1
PF8	BUSDY BUSCX LCD_SEG26	EBI_WEn #4 EBI_BL0 #1	TIM0_CC2 #1 TIM4_CC2 #4	ETH_RMIITXEN #1 US2_CLK #4 QSPI0_CS1 #0 ETH_MIIRXDV #2 ETH_TSUEXTCLK #3 SDIO_CD #0 U0_CTS #0 U1_RTS #1	ETM_TCLK #1 GPIO_EM4WU8

Alternate	LOCATION		
Functionality	0 - 3	4 - 7	Description
BU_STAT	0: PE3		Backup Power Domain status, whether or not the system is in backup mode.
BU_VIN	0: PD8		Battery input for Backup Power Domain.
BU_VOUT	0: PE2		Power output for Backup Power Domain.
CAN0_RX	0: PC0 1: PF0 2: PD0 3: PB9	4: PG8 5: PD14 6: PE0 7: PI12	CAN0 RX.
CAN0_TX	0: PC1 1: PF2 2: PD1 3: PB10	4: PG9 5: PD15 6: PE1 7: PI13	CAN0 TX.
CAN1_RX	0: PC2 1: PF1 2: PD3 3: PC9	4: PC12 5: PA12 6: PG10 7: PI14	CAN1 RX.
CAN1_TX	0: PC3 1: PF3 2: PD4 3: PC10	4: PC11 5: PA13 6: PG11 7: PI15	CAN1 TX.
CMU_CLK0	0: PA2 1: PC12 2: PD7 3: PG2	4: PF2 5: PA12	Clock Management Unit, clock output number 0.
CMU_CLK1	0: PA1 1: PD8 2: PE12 3: PG1	4: PF3 5: PB11	Clock Management Unit, clock output number 1.
CMU_CLK2	0: PA0 1: PA3 2: PD6 3: PG0	4: PA3 5: PD10	Clock Management Unit, clock output number 2.
CMU_CLKIO	0: PD4 1: PA3 2: PB8 3: PB13	4: PE1 5: PD10 6: PE12 7: PB11	Clock Management Unit, clock input number 0.
DBG_SWCLKTCK	0: PF0		Debug-interface Serial Wire clock input and JTAG Test Clock. Note that this function is enabled to the pin out of reset, and has a built-in pull down.
DBG_SWDIOTMS	0: PF1		Debug-interface Serial Wire data input / output and JTAG Test Mode Select. Note that this function is enabled to the pin out of reset, and has a built-in pull up.

Alternate	LOCATION		
Functionality	0 - 3	4 - 7	Description
LES_CH11	0: PC11		LESENSE channel 11.
LES_CH12	0: PC12		LESENSE channel 12.
LES_CH13	0: PC13		LESENSE channel 13.
LES_CH14	0: PC14		LESENSE channel 14.
LES_CH15	0: PC15		LESENSE channel 15.
LETIM0_OUT0	0: PD6 1: PB11 2: PF0 3: PC4	4: PE12 5: PC14 6: PA8 7: PB9	Low Energy Timer LETIM0, output channel 0.
LETIM0_OUT1	0: PD7 1: PB12 2: PF1 3: PC5	4: PE13 5: PC15 6: PA9 7: PB10	Low Energy Timer LETIM0, output channel 1.
LETIM1_OUT0	0: PA7 1: PA11 2: PA12 3: PC2	4: PB5 5: PB2 6: PG0 7: PG2	Low Energy Timer LETIM1, output channel 0.
LETIM1_OUT1	0: PA6 1: PA13 2: PA14 3: PC3	4: PB6 5: PB1 6: PG1 7: PG3	Low Energy Timer LETIM1, output channel 1.
LEU0_RX	0: PD5 1: PB14 2: PE15 3: PF1	4: PA0 5: PC15	LEUART0 Receive input.
LEU0_TX	0: PD4 1: PB13 2: PE14 3: PF0	4: PF2 5: PC14	LEUART0 Transmit output. Also used as receive input in half duplex communication.
LEU1_RX	0: PC7 1: PA6 2: PD3 3: PB1	4: PB5 5: PH1	LEUART1 Receive input.
LEU1_TX	0: PC6 1: PA5 2: PD2 3: PB0	4: PB4 5: PH0	LEUART1 Transmit output. Also used as receive input in half duplex communication.

Alternate	LOCATION		
Functionality	0 - 3	4 - 7	Description
PCNT0_S0IN	0: PC13 1: PE0 2: PC0 3: PD6	4: PA0 5: PB0 6: PB5 7: PB12	Pulse Counter PCNT0 input number 0.
PCNT0_S1IN	0: PC14 1: PE1 2: PC1 3: PD7	4: PA1 5: PB1 6: PB6 7: PB11	Pulse Counter PCNT0 input number 1.
PCNT1_S0IN	0: PA5 1: PB3 2: PD15 3: PC4	4: PA7 5: PA12 6: PB11 7: PG14	Pulse Counter PCNT1 input number 0.
PCNT1_S1IN	0: PA6 1: PB4 2: PB0 3: PC5	4: PA8 5: PA13 6: PB12 7: PG15	Pulse Counter PCNT1 input number 1.
PCNT2_S0IN	0: PD0 1: PE8 2: PB13 3: PF10	4: PC12 5: PI2 6: PI0 7: PH14	Pulse Counter PCNT2 input number 0.
PCNT2_S1IN	0: PD1 1: PE9 2: PB14 3: PF11	4: PC13 5: PI1 6: PH15 7: PH13	Pulse Counter PCNT2 input number 1.
PRS_CH0	0: PA0 1: PF3 2: PC14 3: PF2		Peripheral Reflex System PRS, channel 0.
PRS_CH1	0: PA1 1: PF4 2: PC15 3: PE12		Peripheral Reflex System PRS, channel 1.
PRS_CH2	0: PC0 1: PF5 2: PE10 3: PE13		Peripheral Reflex System PRS, channel 2.
PRS_CH3	0: PC1 1: PE8 2: PE11 3: PA0		Peripheral Reflex System PRS, channel 3.
PRS_CH4	0: PC8 1: PB0 2: PF1		Peripheral Reflex System PRS, channel 4.
PRS_CH5	0: PC9 1: PB1 2: PD6		Peripheral Reflex System PRS, channel 5.
PRS_CH6	0: PA6 1: PB14 2: PE6		Peripheral Reflex System PRS, channel 6.

Alternate	LOCATION		
Functionality	0 - 3	4 - 7	Description
US3_RTS	0: PA5 1: PC1 2: PA14 3: PC15	4: PG5 5: PG11	USART3 Request To Send hardware flow control output.
US3_RX	0: PA1 1: PE7 2: PB7 3: PG7	4: PG1 5: PI13	USART3 Asynchronous Receive. USART3 Synchronous mode Master Input / Slave Output (MISO).
US3_TX	0: PA0 1: PE6 2: PB3 3: PG6	4: PG0 5: PI12	USART3 Asynchronous Transmit. Also used as receive input in half duplex communication. USART3 Synchronous mode Master Output / Slave Input (MOSI).
US4_CLK	0: PC4 1: PD11 2: PI2 3: PI8	4: PH6	USART4 clock input / output.
US4_CS	0: PC5 1: PD12 2: PI3 3: PI9	4: PH7	USART4 chip select input / output.
US4_CTS	0: PA7 1: PD13 2: PI4 3: PI10	4: PH8	USART4 Clear To Send hardware flow control input.
US4_RTS	0: PA8 1: PD14 2: PI5 3: PI11	4: PH9	USART4 Request To Send hardware flow control output.
US4_RX	0: PB8 1: PD10 2: PI1 3: PI7	4: PH5	USART4 Asynchronous Receive. USART4 Synchronous mode Master Input / Slave Output (MISO).
US4_TX	0: PB7 1: PD9 2: PI0 3: PI6	4: PH4	USART4 Asynchronous Transmit. Also used as receive input in half duplex communication. USART4 Synchronous mode Master Output / Slave Input (MOSI).
US5_CLK	0: PB11 1: PD13 2: PF13 3: PH12		USART5 clock input / output.
US5_CS	0: PB13 1: PD14 2: PF12 3: PH13		USART5 chip select input / output.
US5_CTS	0: PB14 1: PD15 2: PF11 3: PH14		USART5 Clear To Send hardware flow control input.
US5_RTS	0: PB12 1: PB15 2: PF10 3: PH15		USART5 Request To Send hardware flow control output.

7.2 BGA152 PCB Land Pattern

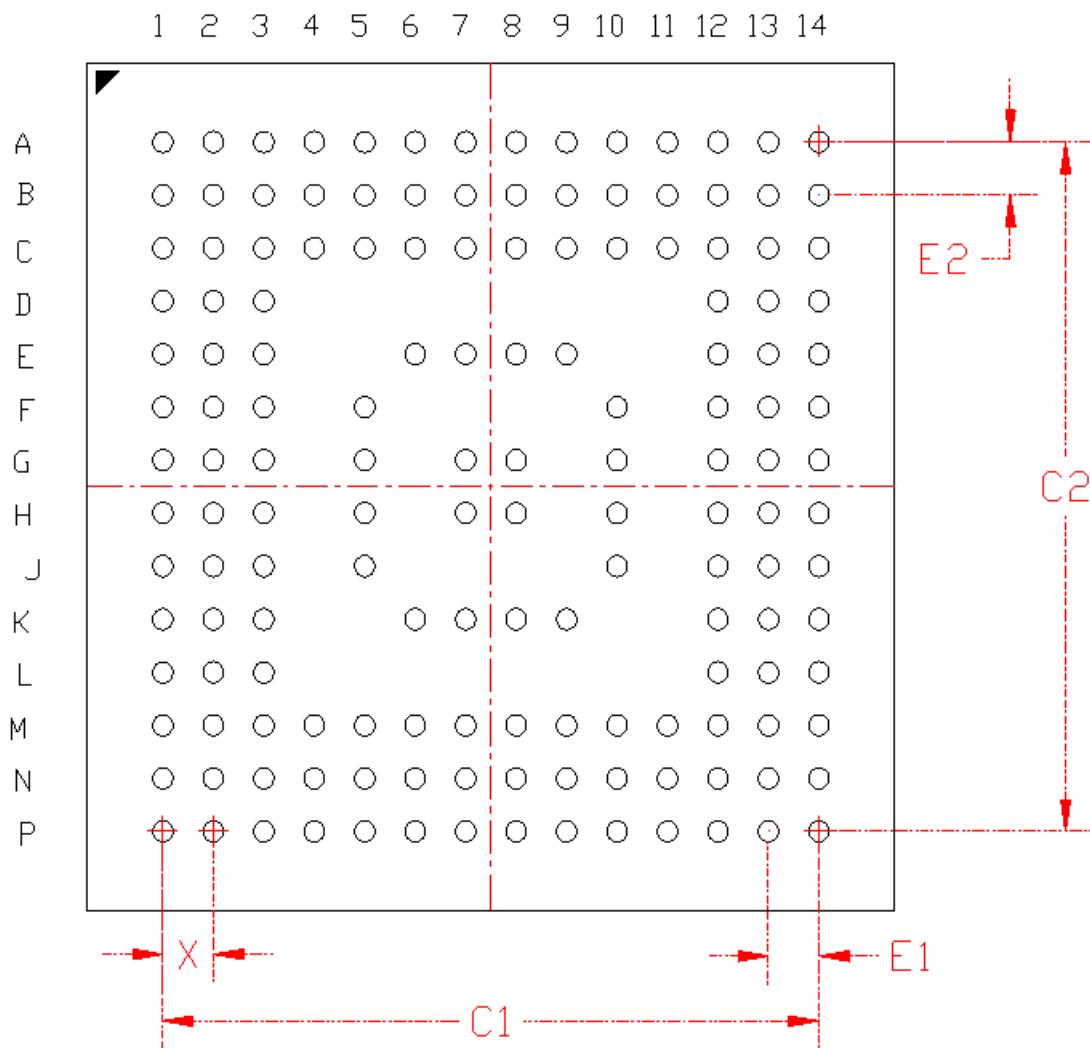


Figure 7.2. BGA152 PCB Land Pattern Drawing

11.2 TQFP64 PCB Land Pattern

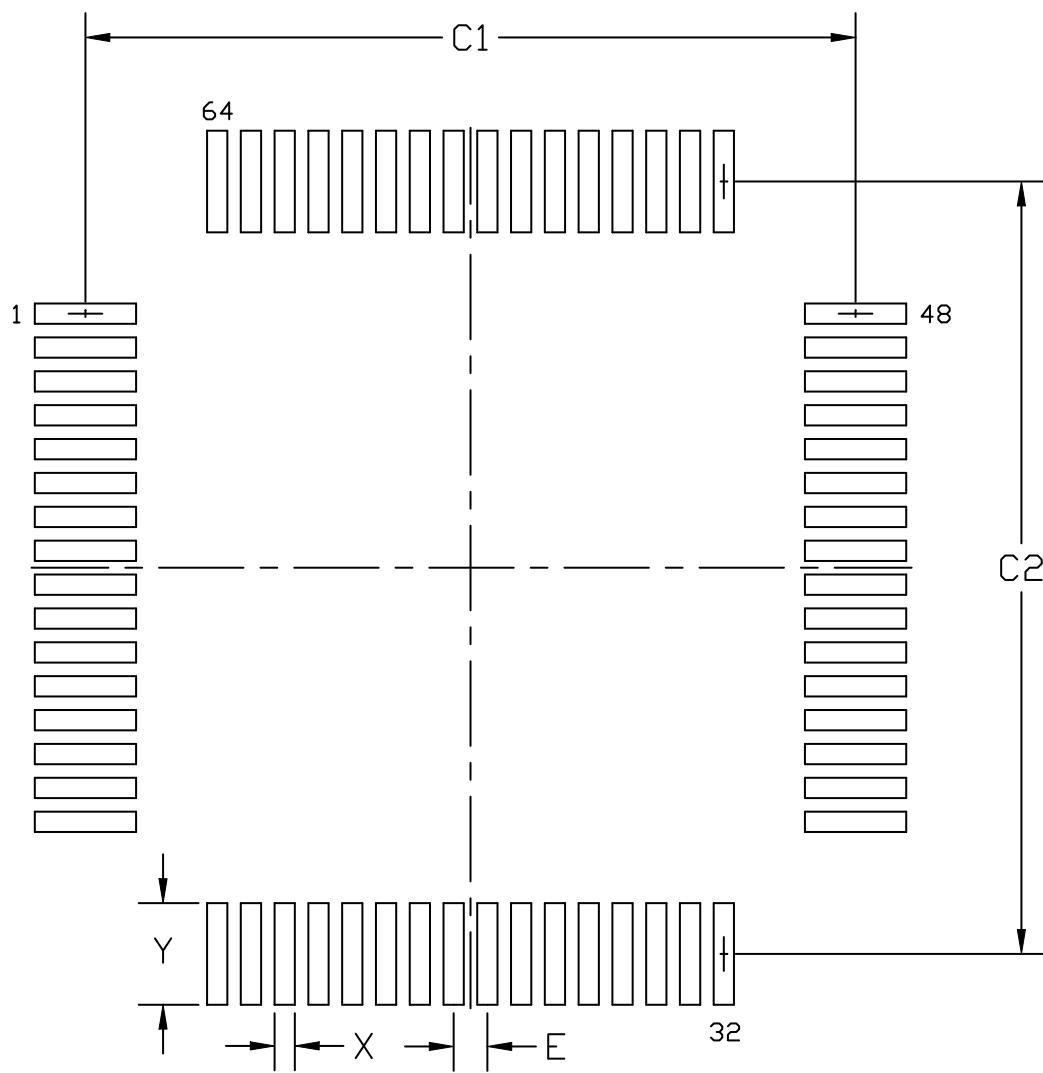


Figure 11.2. TQFP64 PCB Land Pattern Drawing

12.2 QFN64 PCB Land Pattern

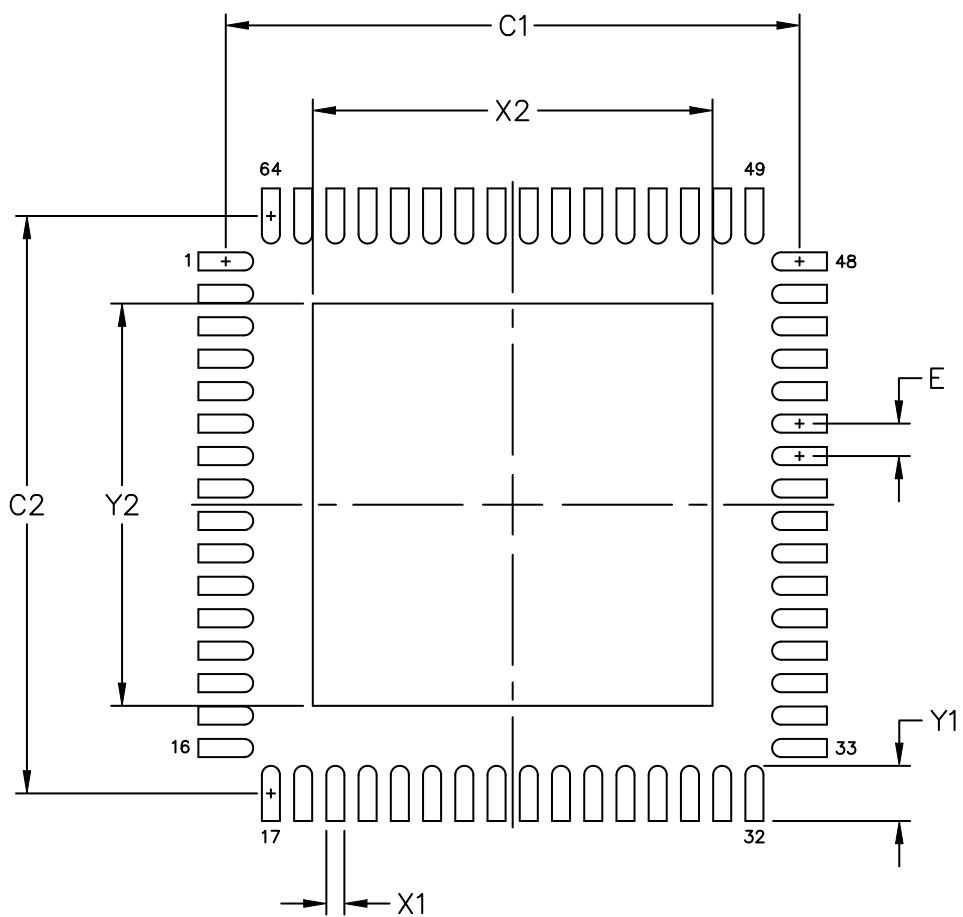


Figure 12.2. QFN64 PCB Land Pattern Drawing