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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

Details

E·XF

Product Status	Active
Core Processor	ARM® Cortex®-M4
Core Size	32-Bit Single-Core
Speed	72MHz
Connectivity	CANbus, EBI/EMI, I ² C, IrDA, LINbus, SmartCard, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, DMA, LCD, POR, PWM, WDT
Number of I/O	53
Program Memory Size	2MB (2M x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	512K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.8V
Data Converters	A/D 16x12b SAR; D/A 2x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	64-VFQFN Exposed Pad
Supplier Device Package	64-QFN (9x9)
Purchase URL	https://www.e-xfl.com/product-detail/silicon-labs/efm32gg11b520f2048im64-br

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

3.2 Power

The EFM32GG11 has an Energy Management Unit (EMU) and efficient integrated regulators to generate internal supply voltages. Only a single external supply voltage is required, from which all internal voltages are created. A 5 V regulator is available on some OPNs, allowing the device to be powered directly from 5 V power sources, such as USB. An optional integrated DC-DC buck regulator can be utilized to further reduce the current consumption. The DC-DC regulator requires one external inductor and one external capacitor.

The EFM32GG11 device family includes support for internal supply voltage scaling, as well as two different power domain groups for peripherals. These enhancements allow for further supply current reductions and lower overall power consumption.

AVDD and VREGVDD need to be 1.8 V or higher for the MCU to operate across all conditions; however the rest of the system will operate down to 1.62 V, including the digital supply and I/O. This means that the device is fully compatible with 1.8 V components. Running from a sufficiently high supply, the device can use the DC-DC to regulate voltage not only for itself, but also for other PCB components, supplying up to a total of 200 mA.

3.2.1 Energy Management Unit (EMU)

The Energy Management Unit manages transitions of energy modes in the device. Each energy mode defines which peripherals and features are available and the amount of current the device consumes. The EMU can also be used to turn off the power to unused RAM blocks, and it contains control registers for the DC-DC regulator and the Voltage Monitor (VMON). The VMON is used to monitor multiple supply voltages. It has multiple channels which can be programmed individually by the user to determine if a sensed supply has fallen below a chosen threshold.

3.2.2 DC-DC Converter

The DC-DC buck converter covers a wide range of load currents and provides up to 90% efficiency in energy modes EM0, EM1, EM2 and EM3, and can supply up to 200 mA to the device and surrounding PCB components. Protection features include programmable current limiting, short-circuit protection, and dead-time protection. The DC-DC converter may also enter bypass mode when the input voltage is too low for efficient operation. In bypass mode, the DC-DC input supply is internally connected directly to its output through a low resistance switch. Bypass mode also supports in-rush current limiting to prevent input supply voltage droops due to excessive output current transients.

3.2.3 5 V Regulator

A 5 V input regulator is available, allowing the device to be powered directly from 5 V power sources such as the USB VBUS line. The regulator is available in all energy modes, and outputs 3.3 V to be used to power the USB PHY and other 3.3 V systems. Two inputs to the regulator allow for seamless switching between local and external power sources.

4.1.13 Voltage Monitor (VMON)

Parameter	Symbol	Test Condition	Min	Тур	Мах	Unit
Supply current (including I_SENSE)	I _{VMON}	In EM0 or EM1, 1 supply monitored, T \leq 85 °C	_	6.0	TBD	μA
		In EM0 or EM1, 4 supplies monitored, T \leq 85 °C	—	14.9	TBD	μA
		In EM2, EM3 or EM4, 1 supply monitored and above threshold	—	62		nA
		In EM2, EM3 or EM4, 1 supply monitored and below threshold	—	62		nA
		In EM2, EM3 or EM4, 4 supplies monitored and all above threshold	_	99		nA
		In EM2, EM3 or EM4, 4 supplies monitored and all below threshold	—	99	_	nA
Loading of monitored supply	I _{SENSE}	In EM0 or EM1	_	2	_	μA
		In EM2, EM3 or EM4	_	2	_	nA
Threshold range	V _{VMON_RANGE}		1.62	_	3.4	V
Threshold step size	N _{VMON_STESP}	Coarse	_	200		mV
		Fine	_	20	_	mV
Response time	t _{VMON_RES}	Supply drops at 1V/µs rate	—	460	_	ns
Hysteresis	V _{VMON_HYST}		_	26	_	mV

Table 4.21. Voltage Monitor (VMON)

Parameter	Symbol	Test Condition	Min	Тур	Max	Unit
	rrent is the sum of th al drive. egister. RESIS registers.	etting in ACMPn_CTRL_PWRS e contributions from the ACMF				IACMP +

4.1.17 Current Digital to Analog Converter (IDAC)

Parameter	Symbol	Test Condition	Min	Тур	Max	Unit
Number of ranges	N _{IDAC_RANGES}		_	4	_	ranges
Output current	I _{IDAC_OUT}	RANGSEL ¹ = RANGE0	0.05	_	1.6	μA
		RANGSEL ¹ = RANGE1	1.6	_	4.7	μA
		RANGSEL ¹ = RANGE2	0.5	_	16	μA
		RANGSEL ¹ = RANGE3	2	_	64	μA
Linear steps within each range	N _{IDAC_STEPS}		_	32	_	steps
Step size	SS _{IDAC}	RANGSEL ¹ = RANGE0	_	50	_	nA
		RANGSEL ¹ = RANGE1	_	100	_	nA
		RANGSEL ¹ = RANGE2	_	500	_	nA
		RANGSEL ¹ = RANGE3	_	2	_	μA
Total accuracy, STEPSEL ¹ = 0x10	PSEL ¹ = ACC _{IDAC}	EM0 or EM1, AVDD=3.3 V, T = 25 °C	TBD	_	TBD	%
		EM0 or EM1, Across operating temperature range	TBD	_	TBD	%
		EM2 or EM3, Source mode, RANGSEL ¹ = RANGE0, AVDD=3.3 V, T = 25 °C	_	-2.7	_	%
		EM2 or EM3, Source mode, RANGSEL ¹ = RANGE1, AVDD=3.3 V, T = 25 °C	_	-2.5	_	%
		EM2 or EM3, Source mode, RANGSEL ¹ = RANGE2, AVDD=3.3 V, T = 25 °C	_	-1.5	_	%
		EM2 or EM3, Source mode, RANGSEL ¹ = RANGE3, AVDD=3.3 V, T = 25 °C	_	-1.0	_	%
		EM2 or EM3, Sink mode, RANG- SEL ¹ = RANGE0, AVDD=3.3 V, T = 25 °C	_	-1.1	_	%
		EM2 or EM3, Sink mode, RANG- SEL ¹ = RANGE1, AVDD=3.3 V, T = 25 °C	_	-1.1	_	%
		EM2 or EM3, Sink mode, RANG- SEL ¹ = RANGE2, AVDD=3.3 V, T = 25 °C	_	-0.9	_	%
		EM2 or EM3, Sink mode, RANG- SEL ¹ = RANGE3, AVDD=3.3 V, T = 25 °C	_	-0.9	-	%

Table 4.25. Current Digital to Analog Converter (IDAC)

4.1.18 Capacitive Sense (CSEN)

Parameter	Symbol	Test Condition	Min	Тур	Max	Unit
Single conversion time (1x	t _{CNV}	12-bit SAR Conversions	_	20.2	_	μs
accumulation)		16-bit SAR Conversions	_	26.4	_	μs
		Delta Modulation Conversion (sin- gle comparison)	_	1.55	-	μs
Maximum external capacitive load	C _{EXTMAX}	CS0CG=7 (Gain = 1x), including routing parasitics	_	68	-	pF
		CS0CG=0 (Gain = 10x), including routing parasitics	—	680	_	pF
Maximum external series impedance	R _{EXTMAX}		—	1	-	kΩ
Supply current, EM2 bonded conversions, WARMUP- MODE=NORMAL, WAR- MUPCNT=0	ICSEN_BOND	12-bit SAR conversions, 20 ms conversion rate, CS0CG=7 (Gain = 1x), 10 channels bonded (total capacitance of 330 pF) ¹	_	326	_	nA
		Delta Modulation conversions, 20 ms conversion rate, CS0CG=7 (Gain = 1x), 10 channels bonded (total capacitance of 330 pF) ¹	_	226	_	nA
		12-bit SAR conversions, 200 ms conversion rate, CS0CG=7 (Gain = 1x), 10 channels bonded (total capacitance of 330 pF) ¹	—	33	_	nA
		Delta Modulation conversions, 200 ms conversion rate, CS0CG=7 (Gain = 1x), 10 chan- nels bonded (total capacitance of 330 pF) ¹	_	25	_	nA
Supply current, EM2 scan conversions, WARMUP- MODE=NORMAL, WAR-	ICSEN_EM2	12-bit SAR conversions, 20 ms scan rate, CS0CG=0 (Gain = 10x), 8 samples per scan ¹	_	690	_	nA
MUPCNT=0		Delta Modulation conversions, 20 ms scan rate, 8 comparisons per sample (DMCR = 1, DMR = 2), CS0CG=0 (Gain = 10x), 8 sam- ples per scan ¹	_	515	_	nA
		12-bit SAR conversions, 200 ms scan rate, CS0CG=0 (Gain = 10x), 8 samples per scan ¹	_	79	_	nA
		Delta Modulation conversions, 200 ms scan rate, 8 comparisons per sample (DMCR = 1, DMR = 2), CS0CG=0 (Gain = 10x), 8 samples per scan ¹	_	57	_	nA

Table 4.26. Capacitive Sense (CSEN)

EBI Ready/Wait Timing Requirements

Timing applies to both EBI_REn and EBI_WEn for all addressing modes and both polarities. All numbers are based on route locations 0,1,2 only (with all EBI alternate functions using the same location at the same time). Timing is specified at 10% and 90% of IOVDD, 25 pF external loading, and slew rate for all GPIO set to 6.

Table 4.41.	EBI Ready/Wait	Timing Re	equirements
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Parameter	Symbol	Test Condition	Min	Тур	Max	Unit
Setup time, from EBI_ARDY valid to trailing EBI_REn, EBI_WEn edge	tsu_ardy	IOVDD ≥ 1.62 V	55 + (3 * t _{HFCOR-} ЕСLК)	_	_	ns
		IOVDD ≥ 3.0 V	36 + (3 * t _{HFCOR-} _{ECLK})	_	_	ns
Hold time, from trailing EBI_REn, EBI_WEn edge to EBI_ARDY invalid	th_ardy	IOVDD ≥ 1.62 V	-9	_	_	ns

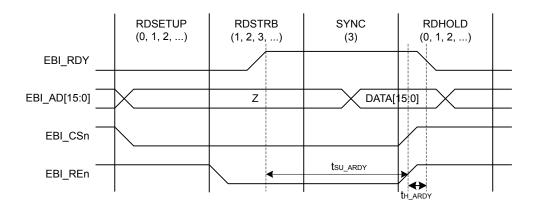


Figure 4.8. EBI Ready/Wait Timing Requirements

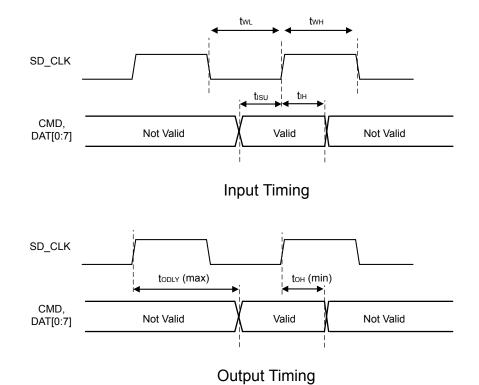


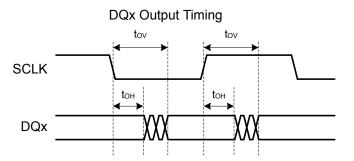
Figure 4.15. SDIO SDR Mode Timing

QSPI DDR Mode Timing (Locations 1, 2)

Timing is specified with voltage scaling disabled, PHY-mode, route locations other than 0, TX DLL = 53, RX DLL = 88, 20-25 pF loading per GPIO, and slew rate for all GPIO set to 6, DRIVESTRENGTH = STRONG.

Table 4.57.	QSPI DDR	R Mode	Timing	(Locations	1, 2)
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Parameter	Symbol	Test Condition	Min	Тур	Max	Unit
Half SCLK period	T/2	HFXO	(1/F _{SCLK}) * 0.4 - 0.4	_	_	ns
		HFRCO, AUXHFRCO, USHFRCO	(1/F _{SCLK}) * 0.44	_		ns
Output valid	t _{OV}		_	_	T/2 - 6.6	ns
Output hold	t _{OH}		T/2 - 52.2	—	_	ns
Input setup	t _{SU}		44.8	_	_	ns
Input hold	t _H		-2.4	_	_	ns



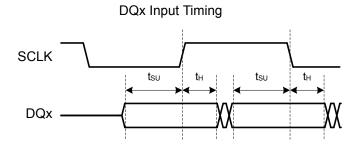


Figure 4.22. QSPI DDR Timing Diagrams

QSPI DDR Flash Timing Example

This example uses timing values for location 0 (DDR mode) to demonstrate the calculation of allowable flash timing using the QSPI in DDR mode.

- Using a configured SCLK frequency (F_{SCLK}) of 8 MHz from the HFXO clock source:
- The resulting minimum half-period, T/2(min) = (1/F_{SCLK}) * 0.4 0.4 = 49.6 ns.
- Flash will see a minimum setup time of $T/2 t_{OV} = T/2 (T/2 5.0) = 5.0$ ns.
- Flash will see a minimum hold time of $t_{OH} = T/2 39.4 = 49.6 39.4 = 10.2$ ns.
- Flash can have a maximum output valid time of $T/2 t_{SU} = T/2 33.1 = 49.6 33.1 = 16.5$ ns.
- Flash can have a minimum output hold time of t_H = 0.9 ns.

4.2.1 Supply Current

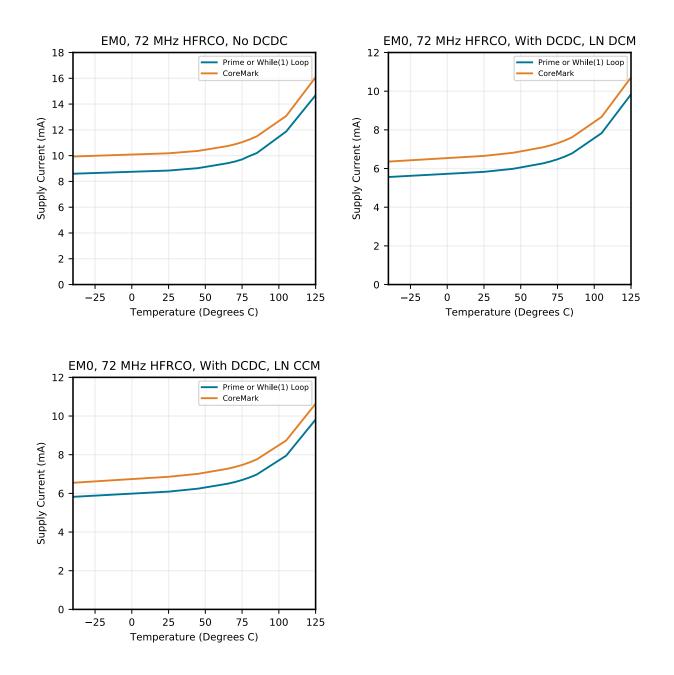


Figure 4.23. EM0 Full Speed Active Mode Typical Supply Current vs. Temperature

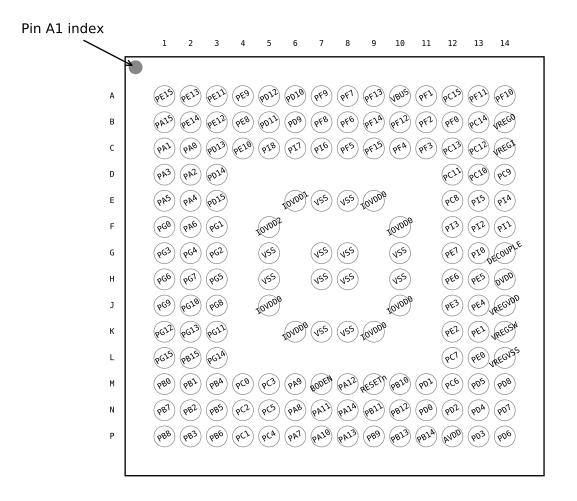


Figure 5.2. EFM32GG11B8xx in BGA152 Device Pinout

The following table provides package pin connections and general descriptions of pin functionality. For detailed information on the supported features for each GPIO pin, see 5.20 GPIO Functionality Table or 5.21 Alternate Functionality Overview.

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PE15	A1	GPIO	PE13	A2	GPIO
PE11	A3	GPIO	PE9	A4	GPIO
PD12	A5	GPIO	PD10	A6	GPIO
PF9	A7	GPIO	PF7	A8	GPIO
PF13	A9	GPIO (5V)	VBUS	A10	USB VBUS signal and auxiliary input to 5 V regulator.
PF1	A11	GPIO (5V)	PC15	A12	GPIO (5V)
PF11	A13	GPIO (5V)	PF10	A14	GPIO (5V)

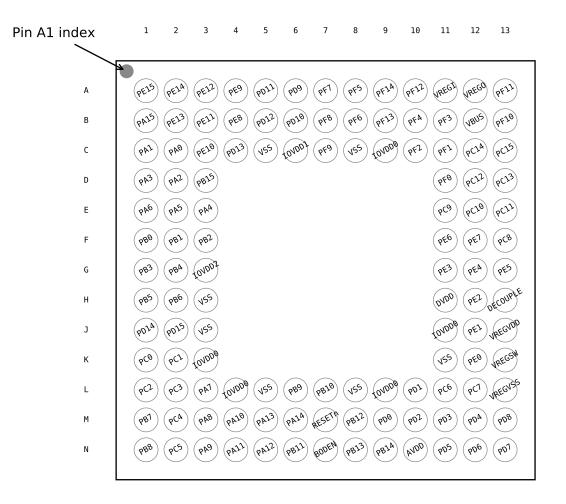


Figure 5.3. EFM32GG11B8xx in BGA120 Device Pinout

The following table provides package pin connections and general descriptions of pin functionality. For detailed information on the supported features for each GPIO pin, see 5.20 GPIO Functionality Table or 5.21 Alternate Functionality Overview.

Table 5.3. EFM32GG11B8xx in BGA120 Device Pinout
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Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PE15	A1	GPIO	PE14	A2	GPIO
PE12	A3	GPIO	PE9	A4	GPIO
PD11	A5	GPIO	PD9	A6	GPIO
PF7	A7	GPIO	PF5	A8	GPIO
PF14	A9	GPIO (5V)	PF12	A10	GPIO
VREGI	A11	Input to 5 V regulator.	VREGO	A12	Decoupling for 5 V regulator and regu- lator output. Power for USB PHY in USB-enabled OPNs

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PC1	K2	GPIO (5V)	PE0	K12	GPIO (5V)
VREGSW	K13	DCDC regulator switching node	PC2	L1	GPIO (5V)
PC3	L2	GPIO (5V)	PA7	L3	GPIO
PB9	L13	GPIO (5V)	PB10	L14	GPIO (5V)
PD1	L17	GPIO	PC6	L18	GPIO
PC7	L19	GPIO	VREGVSS	L20	Voltage regulator VSS
PB7	M1	GPIO	PC4	M2	GPIO
PA8	M3	GPIO	PA10	M4	GPIO
PA13	M5	GPIO (5V)	PA14	M6	GPIO
RESETn	M7	Reset input, active low. To apply an ex- ternal reset source to this pin, it is re- quired to only drive this pin low during reset, and let the internal pull-up ensure that reset is released.	PB12	M8	GPIO
PD0	M9	GPIO (5V)	PD2	M10	GPIO (5V)
PD3	M11	GPIO	PD4	M12	GPIO
PD8	M13	GPIO	PB8	N1	GPIO
PC5	N2	GPIO	PA9	N3	GPIO
PA11	N4	GPIO	PA12	N5	GPIO (5V)
PB11	N6	GPIO	BODEN	N7	Brown-Out Detector Enable. This pin may be left disconnected or tied to AVDD.
PB13	N8	GPIO	PB14	N9	GPIO
AVDD	N10	Analog power supply.	PD5	N11	GPIO
PD6	N12	GPIO	PD7	N13	GPIO

Note:

1. GPIO with 5V tolerance are indicated by (5V).

2. The pins PD13, PD14, and PD15 will not be 5V tolerant on all future devices. In order to preserve upgrade options with full hardware compatibility, do not use these pins with 5V domains.

5.6 EFM32GG11B4xx in BGA112 Device Pinout

Pin A1 index	1	2	3	4	5	6	7	8	9	10	11
A	PELS	PE14	PELZ	(PE9)	2010	(PFT)	PF5	PFIZ	(PEA)	PF10	pF1
В	PALS	PEL3	PEL	PE8	6017	PF8	(PF6)	BUS	PE5	VREGI	REGD
C	(LAG)	PAO	PEIO	6013	6013	PF9	455	PF2	PEO	6C10	6C1-)
D	(PA3)	PAZ	PB1 ⁵	N55	TONDI	(PD9)	101000	PFI	PET	PC8	(⁶)9
E	PAG	PAS	PAA	<i>680</i>				PEO	PEO	PEL	PE3
F	PBI	(PB2)	PB3	(PBA)				pupp	155	PE2	DECOUPLE
G	PB5	(PB6)	155	101002				TONDO	155	<i>(0)</i>	(PC1)
Н	(PC)	PC2	6014	(TA9)	849	(155)	TONODO	(P08)	P05	<i>609</i>	(<i>TO</i> 9)
J	PCJ	PC3	015	PAIZ	PA9	PLAG	PB9	6810	605	(PD3)	(A09)
К	PB1	PCA	E149	(155)	eA1	RESETIN	155	AVOD	AVOD	155	(09)
L	PB8	PC5	PALA	10000	6811	0813	155	6813	PB14	AVOD	<i>(00</i> 9

Figure 5.6. EFM32GG11B4xx in BGA112 Device Pinout

The following table provides package pin connections and general descriptions of pin functionality. For detailed information on the supported features for each GPIO pin, see 5.20 GPIO Functionality Table or 5.21 Alternate Functionality Overview.

Table 5.6. EFM32GG11B4xx in BGA112 Device Pinc	ut
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Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PE15	A1	GPIO	PE14	A2	GPIO
PE12	A3	GPIO	PE9	A4	GPIO
PD10	A5	GPIO	PF7	A6	GPIO
PF5	A7	GPIO	PF12	A8	GPIO
PE4	A9	GPIO	PF10	A10	GPIO (5V)
PF11	A11	GPIO (5V)	PA15	B1	GPIO
PE13	B2	GPIO	PE11	В3	GPIO

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PB2	11	GPIO	PB3	12	GPIO
PB4	13	GPIO	PB5	14	GPIO
PB6	15	GPIO	VSS	16 32 58 83	Ground
PC0	18	GPIO (5V)	PC1	19	GPIO (5V)
PC2	20	GPIO (5V)	PC3	21	GPIO (5V)
PC4	22	GPIO	PC5	23	GPIO
PB7	24	GPIO	PB8	25	GPIO
PA7	26	GPIO	PA8	27	GPIO
PA9	28	GPIO	PA10	29	GPIO
PA11	30	GPIO	PA12	33	GPIO (5V)
PA13	34	GPIO (5V)	PA14	35	GPIO
RESETn	36	Reset input, active low. To apply an ex- ternal reset source to this pin, it is re- quired to only drive this pin low during reset, and let the internal pull-up ensure that reset is released.	PB9	37	GPIO (5V)
PB10	38	GPIO (5V)	PB11	39	GPIO
PB12	40	GPIO	AVDD	41 45	Analog power supply.
PB13	42	GPIO	PB14	43	GPIO
PD0	46	GPIO (5V)	PD1	47	GPIO
PD2	48	GPIO (5V)	PD3	49	GPIO
PD4	50	GPIO	PD5	51	GPIO
PD6	52	GPIO	PD7	53	GPIO
PD8	54	GPIO	PC6	55	GPIO
PC7	56	GPIO	DVDD	57	Digital power supply.
DECOUPLE	59	Decouple output for on-chip voltage regulator. An external decoupling ca- pacitor is required at this pin.	PE0	60	GPIO (5V)
PE1	61	GPIO (5V)	PE2	62	GPIO
PE3	63	GPIO	PE4	64	GPIO
PE5	65	GPIO	PE6	66	GPIO
PE7	67	GPIO	PC8	68	GPIO (5V)
PC9	69	GPIO (5V)	PC10	70	GPIO (5V)
PC11	71	GPIO (5V)	VREGI	72	Input to 5 V regulator.
VREGO	73	Decoupling for 5 V regulator and regu- lator output. Power for USB PHY in USB-enabled OPNs	PF10	74	GPIO (5V)
PF11	75	GPIO (5V)	PF0	76	GPIO (5V)

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PC4	13	GPIO	PC5	14	GPIO
PB7	15	GPIO	PB8	16	GPIO
PA8	17	GPIO	PA12	18	GPIO (5V)
PA14	19	GPIO	RESETn	20	Reset input, active low. To apply an ex- ternal reset source to this pin, it is re- quired to only drive this pin low during reset, and let the internal pull-up ensure that reset is released.
PB11	21	GPIO	PB12	22	GPIO
AVDD	24	Analog power supply.	PB13	25	GPIO
PB14	26	GPIO	PD0	28	GPIO (5V)
PD1	29	GPIO	PD2	30	GPIO (5V)
PD3	31	GPIO	PD4	32	GPIO
PD5	33	GPIO	PD6	34	GPIO
PD7	35	GPIO	PD8	36	GPIO
PC7	37	GPIO	VREGVSS	38	Voltage regulator VSS
VREGSW	39	DCDC regulator switching node	VREGVDD	40	Voltage regulator VDD input
DVDD	41	Digital power supply.	DECOUPLE	42	Decouple output for on-chip voltage regulator. An external decoupling capacitor is required at this pin.
PE4	43	GPIO	PE5	44	GPIO
PE6	45	GPIO	PE7	46	GPIO
PC12	47	GPIO (5V)	PC13	48	GPIO (5V)
PF0	49	GPIO (5V)	PF1	50	GPIO (5V)
PF2	51	GPIO	PF3	52	GPIO
PF4	53	GPIO	PF5	54	GPIO
PE8	57	GPIO	PE9	58	GPIO
PE10	59	GPIO	PE11	60	GPIO
PE12	61	GPIO	PE13	62	GPIO
PE14	63	GPIO	PE15	64	GPIO

1. GPIO with 5V tolerance are indicated by (5V).

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PC3	12	GPIO (5V)	PC4	13	GPIO
PC5	14	GPIO	PB7	15	GPIO
PB8	16	GPIO	PA8	17	GPIO
PA9	18	GPIO	PA10	19	GPIO
RESETn	20	Reset input, active low. To apply an ex- ternal reset source to this pin, it is re- quired to only drive this pin low during reset, and let the internal pull-up ensure that reset is released.	PB11	21	GPIO
PB12	22	GPIO	AVDD	23 27	Analog power supply.
PB13	24	GPIO	PB14	25	GPIO
PD0	28	GPIO (5V)	PD1	29	GPIO
PD2	30	GPIO (5V)	PD3	31	GPIO
PD4	32	GPIO	PD5	33	GPIO
PD6	34	GPIO	PD7	35	GPIO
PD8	36	GPIO	PC6	37	GPIO
PC7	38	GPIO	DVDD	39	Digital power supply.
DECOUPLE	40	Decouple output for on-chip voltage regulator. An external decoupling capacitor is required at this pin.	PC8	41	GPIO (5V)
PC9	42	GPIO (5V)	PC10	43	GPIO (5V)
PC11	44	GPIO (5V)	PC12	45	GPIO (5V)
PC13	46	GPIO (5V)	PC14	47	GPIO (5V)
PC15	48	GPIO (5V)	PF0	49	GPIO (5V)
PF1	50	GPIO (5V)	PF2	51	GPIO
PF3	52	GPIO	PF4	53	GPIO
PF5	54	GPIO	PE8	56	GPIO
PE9	57	GPIO	PE10	58	GPIO
PE11	59	GPIO	PE12	60	GPIO
PE13	61	GPIO	PE14	62	GPIO
PE15	63	GPIO	PA15	64	GPIO

1. GPIO with 5V tolerance are indicated by (5V).

5.20 GPIO Functionality Table

A wide selection of alternate functionality is available for multiplexing to various pins. The following table shows the name of each GPIO pin, followed by the functionality available on that pin. Refer to 5.21 Alternate Functionality Overview for a list of GPIO locations available for each function.

GPIO Name		Pin Alter	nate Functionality / De	escription	
	Analog	EBI	Timers	Communication	Other
PA15	BUSAY BUSBX LCD_SEG12	EBI_AD08 #0	TIM3_CC2 #0	ETH_MIIRXCLK #0 ETH_MDIO #3 US2_CLK #3	PRS_CH15 #0
PE15	BUSCY BUSDX LCD_SEG11	EBI_AD07 #0	TIM2_CDTI2 #2 TIM3_CC1 #0	ETH_RMIITXD0 #0 ETH_MIIRXD3 #0 SDIO_CMD #1 US0_RTS #0 QSPI0_DQS #1 LEU0_RX #2	PRS_CH14 #2 ETM_TD3 #4
PE14	BUSDY BUSCX LCD_SEG10	EBI_AD06 #0	TIM2_CDTI1 #2 TIM3_CC0 #0	ETH_RMIITXD1 #0 ETH_MIIRXD2 #0 SDIO_CLK #1 US0_CTS #0 QSPI0_SCLK #1 LEU0_TX #2	PRS_CH13 #2 ETM_TD2 #4
PE13	BUSCY BUSDX LCD_SEG9	EBI_AD05 #0	TIM1_CC3 #1 TIM2_CC2 #3 LE- TIM0_OUT1 #4	SDIO_CLK #0 ETH_MIIRXD1 #0 US0_TX #3 US0_CS #0 U1_RX #4 I2C0_SCL #6	LES_ALTEX7 PRS_CH2 #3 ACMP0_O #0 ETM_TD1 #4 GPIO_EM4WU5
PE12	BUSDY BUSCX LCD_SEG8	EBI_AD04 #0	TIM1_CC2 #1 TIM2_CC1 #3 WTIM0_CDTI2 #0 LETIM0_OUT0 #4	SDIO_CMD #0 ETH_MIIRXD0 #0 US0_RX #3 US0_CLK #0 U1_TX #4 I2C0_SDA #6	CMU_CLK1 #2 CMU_CLKI0 #6 LES_ALTEX6 PRS_CH1 #3 ETM_TD0 #4
PE11	BUSCY BUSDX LCD_SEG7	EBI_AD03 #0 EBI_CS3 #4	TIM1_CC1 #1 TIM4_CC2 #7 WTIM0_CDTI1 #0	SDIO_DAT0 #0 QSPI0_DQ7 #0 ETH_MIIRXDV #0 US0_RX #0	LES_ALTEX5 PRS_CH3 #2 ETM_TCLK #4
PE10	BUSDY BUSCX LCD_SEG6	EBI_AD02 #0 EBI_CS2 #4	TIM1_CC0 #1 TIM4_CC1 #7 WTIM0_CDTI0 #0	SDIO_DAT1 #0 QSPI0_DQ6 #0 ETH_MIIRXER #0 US0_TX #0	PRS_CH2 #2 GPIO_EM4WU9
PE9	BUSCY BUSDX LCD_SEG5	EBI_AD01 #0 EBI_CS1 #4	TIM4_CC0 #7 PCNT2_S1IN #1	SDIO_DAT2 #0 QSPI0_DQ5 #0 US5_RX #0	PRS_CH8 #2
PE8	BUSDY BUSCX LCD_SEG4	EBI_AD00 #0 EBI_CS0 #4	TIM2_CDTI0 #2 TIM4_CC2 #6 PCNT2_S0IN #1	SDIO_DAT3 #0 QSPI0_DQ4 #0 US5_TX #0 I2C2_SDA #0	PRS_CH3 #1
PI9		EBI_A14 #2	TIM1_CC3 #7 TIM4_CC1 #3	US4_CS #3	
PI6		EBI_A11 #2	TIM1_CC0 #7 TIM4_CC1 #2 WTIM3_CC0 #5	US4_TX #3	

Table 5.20. GPIO Functionality Table

Alternate	LOC	ATION	
Functionality	0 - 3	4 - 7	Description
U0_TX	0: PF6 1: PE0 2: PA3 3: PC14	4: PC4 5: PF1 6: PD7	UART0 Transmit output. Also used as receive input in half duplex communication.
U1_CTS	0: PC14 1: PF9 2: PB11 3: PE4	4: PC4 5: PH13	UART1 Clear To Send hardware flow control input.
U1_RTS	0: PC15 1: PF8 2: PB12 3: PE5	4: PC5 5: PH14	UART1 Request To Send hardware flow control output.
U1_RX	0: PC13 1: PF11 2: PB10 3: PE3	4: PE13 5: PH12	UART1 Receive input.
U1_TX	0: PC12 1: PF10 2: PB9 3: PE2	4: PE12 5: PH11	UART1 Transmit output. Also used as receive input in half duplex communication.
US0_CLK	0: PE12 1: PE5 2: PC9 3: PC15	4: PB13 5: PA12 6: PG14	USART0 clock input / output.
US0_CS	0: PE13 1: PE4 2: PC8 3: PC14	4: PB14 5: PA13 6: PG15	USART0 chip select input / output.
US0_CTS	0: PE14 1: PE3 2: PC7 3: PC13	4: PB6 5: PB11 6: PH0	USART0 Clear To Send hardware flow control input.
US0_RTS	0: PE15 1: PE2 2: PC6 3: PC12	4: PB5 5: PD6 6: PH1	USART0 Request To Send hardware flow control output.
US0_RX	0: PE11 1: PE6 2: PC10 3: PE12	4: PB8 5: PC1 6: PG13	USART0 Asynchronous Receive. USART0 Synchronous mode Master Input / Slave Output (MISO).
US0_TX	0: PE10 1: PE7 2: PC11 3: PE13	4: PB7 5: PC0 6: PG12	USART0 Asynchronous Transmit. Also used as receive input in half duplex communica- tion. USART0 Synchronous mode Master Output / Slave Input (MOSI).
US1_CLK	0: PB7 1: PD2 2: PF0 3: PC15	4: PC3 5: PB11 6: PE5	USART1 clock input / output.
US1_CS	0: PB8 1: PD3 2: PF1 3: PC14	4: PC0 5: PE4 6: PB2	USART1 chip select input / output.

EFM32GG11 Family Data Sheet Pin Definitions

		_												_									_		_				_		_		
Port	Bus	CH31	CH30	CH29	CH28	CH27	CH26	CH25	CH24	CH23	CH22	CH21	CH20	CH19	CH18	CH17	CH16	CH15	CH14	CH13	CH12	CH11	CH10	СН9	CH8	CH7	CH6	CH5	CH4	СНЗ	CH2	CH1	СНО
OP	A2_	<u>0</u> 0	Г																														
APORT1Y	BUSAY	PB15		PB13		PB11		PB9				PB5		PB3		PB1		PA15		PA13		PA11		PA9		PA7		PA5		PA3		PA1	
APORT2Y	BUSBY		PB14		PB12		PB10				PB6		PB4		PB2		PB0		PA14		PA12		PA10		PA8		PA6		PA4		PA2		PA0
APORT3Y	BUSCY	PF15		PF13		PF11		PF9		PF7		PF5		PF3		PF1		PE15		PE13		PE11		63d		PE7		PE5				PE1	
APORT4Y	BUSDY		PF14		PF12		PF10		PF8		PF6		PF4		PF2		PF0		PE14		PE12		PE10		PE8		PE6		PE4				PEO
OP	A2_	P																															
APORT1X	BUSAX		PB14		PB12		PB10				PB6		PB4		PB2		PBO		PA14		PA12		PA10		PA8		PA6		PA4		PA2		PA0
APORT2X	BUSBX	PB15		PB13		PB11		PB9				PB5		PB3		PB1		PA15		PA13		PA11		PA9		PA7		PA5		PA3		PA1	
APORT3X	BUSCX		PF14		PF12		PF10		PF8		PF6		PF4		PF2		PF0		PE14		PE12		PE10		PE8		PE6		PE4				PEO
APORT4X	BUSDX	PF15		PF13		PF11		PF9		PF7		PF5		PF3		PF1		PE15		PE13		PE11		PE9		PE7		PE5				PE1	
OP	A3_	N																											•				
APORT1Y	BUSAY	PB15		PB13		PB11		PB9				PB5		PB3		PB1		PA15		PA13		PA11		6A9		PA7		PA5		PA3		PA1	
APORT2Y	BUSBY		PB14		PB12		PB10				PB6		PB4		PB2		PB0		PA14		PA12		PA10		PA8		PA6		PA4		PA2		PA0
APORT3Y	BUSCY	PF15		PF13		PF11		PF9		PF7		PF5		PF3		PF1		PE15		PE13		PE11		63d		PE7		PE5				PE1	
APORT4Y	BUSDY		PF14		PF12		PF10		PF8		PF6		PF4		PF2		PF0		PE14		PE12		PE10		PE8		PE6		PE4				PEO

Dimension	Min	Тур	Мах						
A	0.77	0.83	0.89						
A1	0.13	0.18	0.23						
A3	0.16	0.20	0.24						
A2		0.45 REF							
D		7.00 BSC							
е		0.40 BSC							
E		7.00 BSC							
D1		6.00 BSC							
E1		6.00 BSC							
b	0.20	0.25	0.30						
ааа		0.10							
bbb		0.10							
ddd		0.08							
eee	0.15								
fff	0.05								
Noto									

Table 6.1. BGA192 Package Dimensions

Note:

1. All dimensions shown are in millimeters (mm) unless otherwise noted.

2. Dimensioning and Tolerancing per ANSI Y14.5M-1994.

3. Recommended card reflow profile is per the JEDEC/IPC J-STD-020 specification for Small Body Components.