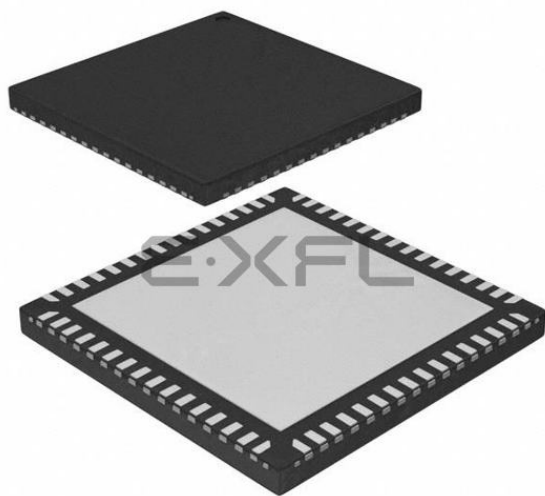




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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

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Details

Product Status	Active
Core Processor	ARM® Cortex®-M4
Core Size	32-Bit Single-Core
Speed	72MHz
Connectivity	CANbus, EBI/EMI, Ethernet, I ² C, IrDA, LINbus, MMC/SD/SDIO, QSPI, SmartCard, SPI, UART/USART, USB
Peripherals	Brown-out Detect/Reset, DMA, LCD, POR, PWM, WDT
Number of I/O	50
Program Memory Size	2MB (2M x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	512K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.8V
Data Converters	A/D 16x12b SAR; D/A 2x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	64-VFQFN Exposed Pad
Supplier Device Package	64-QFN (9x9)
Purchase URL	https://www.e-xfl.com/product-detail/silicon-labs/efm32gg11b820f2048im64-br

- **Timers/Counters**
 - 7× 16-bit Timer/Counter
 - 3 + 4 Compare/Capture/PWM channels (4 + 4 on one timer instance)
 - Dead-Time Insertion on several timer instances
 - 4× 32-bit Timer/Counter
 - 32-bit Real Time Counter and Calendar (RTCC)
 - 24-bit Real Time Counter (RTC)
 - 32-bit Ultra Low Energy CRYOTIMER for periodic wakeup from any Energy Mode
 - 2× 16-bit Low Energy Timer for waveform generation
 - 3× 16-bit Pulse Counter with asynchronous operation
 - 2× Watchdog Timer with dedicated RC oscillator
- **Low Energy Sensor Interface (LESENSE)**
 - Autonomous sensor monitoring in Deep Sleep Mode
 - Wide range of sensors supported, including LC sensors and capacitive buttons
 - Up to 16 inputs
- **Ultra efficient Power-on Reset and Brown-Out Detector**
- **Debug Interface**
 - 2-pin Serial Wire Debug interface
 - 1-pin Serial Wire Viewer
 - 4-pin JTAG interface
 - Embedded Trace Macrocell (ETM)
- **Pre-Programmed USB/UART Bootloader**
- **Wide Operating Range**
 - 1.8 V to 3.8 V single power supply
 - Integrated DC-DC, down to 1.8 V output with up to 200 mA load current for system
 - Standard (-40 °C to 85 °C T_{AMB}) and Extended (-40 °C to 125 °C T_J) temperature grades available
- **Packages**
 - QFN64 (9x9 mm)
 - TQFP64 (10x10 mm)
 - TQFP100 (14x14 mm)
 - BGA112 (10x10 mm)
 - BGA120 (7x7 mm)
 - BGA152 (8x8 mm)
 - BGA192 (7x7mm)

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Current consumption in EM0 mode with all peripherals disabled, DCDC in LP mode ³	I _{ACTIVE_LPM}	32 MHz HFRCO, CPU running while loop from flash	—	82	—	μA/MHz
		26 MHz HFRCO, CPU running while loop from flash	—	83	—	μA/MHz
		16 MHz HFRCO, CPU running while loop from flash	—	88	—	μA/MHz
		1 MHz HFRCO, CPU running while loop from flash	—	257	—	μA/MHz
Current consumption in EM0 mode with all peripherals disabled and voltage scaling enabled, DCDC in Low Noise CCM mode ¹	I _{ACTIVE_CCM_VS}	19 MHz HFRCO, CPU running while loop from flash	—	117	—	μA/MHz
		1 MHz HFRCO, CPU running while loop from flash	—	1231	—	μA/MHz
Current consumption in EM0 mode with all peripherals disabled and voltage scaling enabled, DCDC in LP mode ³	I _{ACTIVE_LPM_VS}	19 MHz HFRCO, CPU running while loop from flash	—	72	—	μA/MHz
		1 MHz HFRCO, CPU running while loop from flash	—	219	—	μA/MHz
Current consumption in EM1 mode with all peripherals disabled, DCDC in Low Noise DCM mode ²	I _{EM1_DCM}	72 MHz HFRCO	—	42	—	μA/MHz
		50 MHz crystal	—	46	—	μA/MHz
		48 MHz HFRCO	—	46	—	μA/MHz
		32 MHz HFRCO	—	53	—	μA/MHz
		26 MHz HFRCO	—	57	—	μA/MHz
		16 MHz HFRCO	—	72	—	μA/MHz
		1 MHz HFRCO	—	663	—	μA/MHz
Current consumption in EM1 mode with all peripherals disabled, DCDC in Low Power mode ³	I _{EM1_LPM}	32 MHz HFRCO	—	42	—	μA/MHz
		26 MHz HFRCO	—	43	—	μA/MHz
		16 MHz HFRCO	—	48	—	μA/MHz
		1 MHz HFRCO	—	219	—	μA/MHz
Current consumption in EM1 mode with all peripherals disabled and voltage scaling enabled, DCDC in Low Noise DCM mode ²	I _{EM1_DCM_VS}	19 MHz HFRCO	—	60	—	μA/MHz
		1 MHz HFRCO	—	637	—	μA/MHz
Current consumption in EM1 mode with all peripherals disabled and voltage scaling enabled. DCDC in LP mode ³	I _{EM1_LPM_VS}	19 MHz HFRCO	—	39	—	μA/MHz
		1 MHz HFRCO	—	190	—	μA/MHz
Current consumption in EM2 mode, with voltage scaling enabled, DCDC in LP mode ³	I _{EM2_VS}	Full 512 kB RAM retention and RTCC running from LFXO	—	2.8	—	μA
		Full 512 kB RAM retention and RTCC running from LFRCO	—	3.1	—	μA
		16 kB (1 bank) RAM retention and RTCC running from LFRCO ⁵	—	2.1	—	μA
Current consumption in EM3 mode, with voltage scaling enabled	I _{EM3_VS}	Full 512 kB RAM retention and CRYOTIMER running from ULFR-CO	—	2.4	—	μA

4.1.9 Brown Out Detector (BOD)

Table 4.11. Brown Out Detector (BOD)

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
DVDD BOD threshold	V _{DVddbOD}	DVDD rising	—	—	1.62	V
		DVDD falling (EM0/EM1)	1.35	—	—	V
		DVDD falling (EM2/EM3)	TBD	—	—	V
DVDD BOD hysteresis	V _{DVddbOD_HYST}		—	18	—	mV
DVDD BOD response time	t _{DVddbOD_DELAY}	Supply drops at 0.1V/μs rate	—	2.4	—	μs
AVDD BOD threshold	V _{AVddbOD}	AVDD rising	—	—	1.8	V
		AVDD falling (EM0/EM1)	1.62	—	—	V
		AVDD falling (EM2/EM3)	TBD	—	—	V
AVDD BOD hysteresis	V _{AVddbOD_HYST}		—	20	—	mV
AVDD BOD response time	t _{AVddbOD_DELAY}	Supply drops at 0.1V/μs rate	—	2.4	—	μs
EM4 BOD threshold	V _{EM4dBOD}	AVDD rising	—	—	1.7	V
		AVDD falling	1.45	—	—	V
EM4 BOD hysteresis	V _{EM4BOD_HYST}		—	25	—	mV
EM4 BOD response time	t _{EM4BOD_DELAY}	Supply drops at 0.1V/μs rate	—	300	—	μs

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Frequency limits	f _{HFRCO_BAND}	FREQRANGE = 0, FINETUNING = 0	1	—	10	MHz
		FREQRANGE = 3, FINETUNING = 0	2	—	17	MHz
		FREQRANGE = 6, FINETUNING = 0	4	—	30	MHz
		FREQRANGE = 7, FINETUNING = 0	5	—	34	MHz
		FREQRANGE = 8, FINETUNING = 0	7	—	42	MHz
		FREQRANGE = 10, FINETUNING = 0	12	—	58	MHz
		FREQRANGE = 11, FINETUNING = 0	15	—	68	MHz
		FREQRANGE = 12, FINETUNING = 0	18	—	83	MHz
		FREQRANGE = 13, FINETUNING = 0	24	—	100	MHz
		FREQRANGE = 14, FINETUNING = 0	28	—	119	MHz
		FREQRANGE = 15, FINETUNING = 0	33	—	138	MHz
		FREQRANGE = 16, FINETUNING = 0	43	—	163	MHz
Note: 1. Maximum DPLL lock time ~ = 6 x (M+1) x t _{REF} , where t _{REF} is the reference clock period.						

4.1.10.5 Auxiliary High-Frequency RC Oscillator (AUXHFRCO)

Table 4.16. Auxiliary High-Frequency RC Oscillator (AUXHFRCO)

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Frequency accuracy	$f_{\text{AUXHFRCO_ACC}}$	At production calibrated frequencies, across supply voltage and temperature	TBD	—	TBD	%
Start-up time	t_{AUXHFRCO}	$f_{\text{AUXHFRCO}} \geq 19 \text{ MHz}$	—	400	—	ns
		$4 < f_{\text{AUXHFRCO}} < 19 \text{ MHz}$	—	1.4	—	μs
		$f_{\text{AUXHFRCO}} \leq 4 \text{ MHz}$	—	2.5	—	μs
Current consumption on all supplies	I_{AUXHFRCO}	$f_{\text{AUXHFRCO}} = 50 \text{ MHz}$	—	289	TBD	μA
		$f_{\text{AUXHFRCO}} = 48 \text{ MHz}$	—	276	TBD	μA
		$f_{\text{AUXHFRCO}} = 38 \text{ MHz}$	—	227	TBD	μA
		$f_{\text{AUXHFRCO}} = 32 \text{ MHz}$	—	186	TBD	μA
		$f_{\text{AUXHFRCO}} = 26 \text{ MHz}$	—	158	TBD	μA
		$f_{\text{AUXHFRCO}} = 19 \text{ MHz}$	—	126	TBD	μA
		$f_{\text{AUXHFRCO}} = 16 \text{ MHz}$	—	114	TBD	μA
		$f_{\text{AUXHFRCO}} = 13 \text{ MHz}$	—	88	TBD	μA
		$f_{\text{AUXHFRCO}} = 7 \text{ MHz}$	—	59	TBD	μA
		$f_{\text{AUXHFRCO}} = 4 \text{ MHz}$	—	33	TBD	μA
		$f_{\text{AUXHFRCO}} = 2 \text{ MHz}$	—	28	TBD	μA
		$f_{\text{AUXHFRCO}} = 1 \text{ MHz}$	—	26	TBD	μA
Coarse trim step size (% of period)	$SS_{\text{AUXHFRCO_COARSE}}$		—	0.8	—	%
Fine trim step size (% of period)	$SS_{\text{AUXHFRCO_FINE}}$		—	0.1	—	%
Period jitter	PJ_{AUXHFRCO}		—	0.2	—	% RMS

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Note: 1. Supply current specifications are for VDAC circuitry operating with static output only and do not include current required to drive the load. 2. In differential mode, the output is defined as the difference between two single-ended outputs. Absolute voltage on each output is limited to the single-ended range. 3. Entire range is monotonic and has no missing codes. 4. Current from HUPERCLK is dependent on HUPERCLK frequency. This current contributes to the total supply current used when the clock to the DAC module is enabled in the CMU. 5. Gain is calculated by measuring the slope from 10% to 90% of full scale. Offset is calculated by comparing actual VDAC output at 10% of full scale to ideal VDAC output at 10% of full scale with the measured gain. 6. PSRR calculated as $20 * \log_{10}(\Delta V_{DD} / \Delta V_{OUT})$, VDAC output at 90% of full scale						

4.1.28.2 QSPI DDR Mode

QSPI DDR Mode Timing (Location 0)

Timing is specified with voltage scaling disabled, PHY-mode, route location 0 only, TX DLL = 35, RX DLL = 70, 20-25 pF loading per GPIO, and slew rate for all GPIO set to 6, DRIVESTRENGTH = STRONG.

Table 4.56. QSPI DDR Mode Timing (Location 0)

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Half SCLK period	T/2	HFXO	$(1/F_{SCLK})^*$ 0.4 - 0.4	—	—	ns
		HFRCO, AUXHFRCO, USHFRCO	$(1/F_{SCLK})^*$ 0.44	—	—	ns
Output valid	t _{OV}		—	—	T/2 - 5.0	ns
Output hold	t _{OH}		T/2 - 39.4	—	—	ns
Input setup	t _{SU}		33.1	—	—	ns
Input hold	t _H		-0.9	—	—	ns

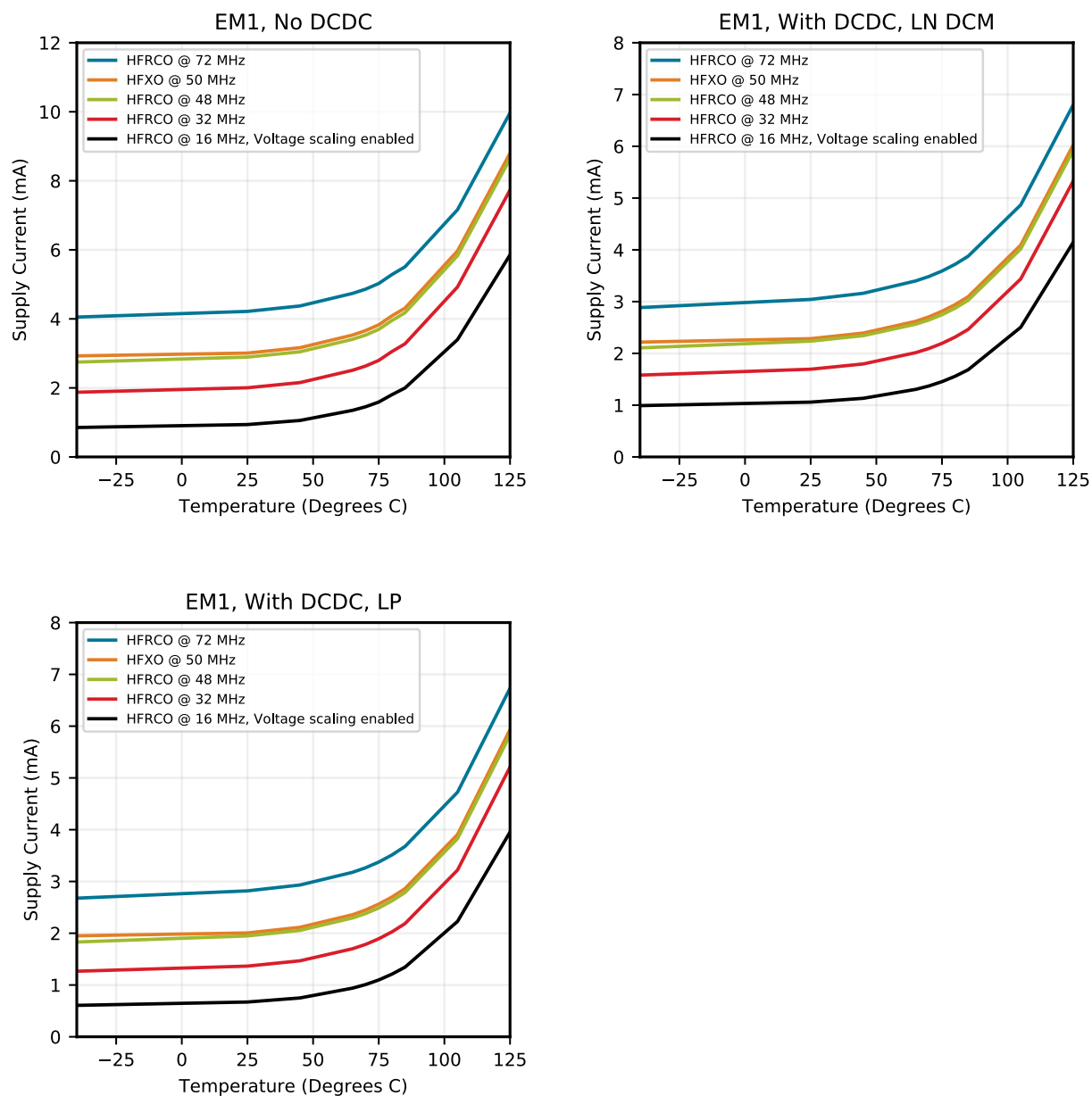


Figure 4.25. EM1 Sleep Mode Typical Supply Current vs. Temperature

Typical supply current for EM2, EM3 and EM4H using standard software libraries from Silicon Laboratories.

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
IOVDD1	F7 G7	Digital IO power supply 1.	VSS	F8 G8 G9 H6 H7 H8 H9 H10 H11 J6 J7 J8 J9 J10 J11 K8 K9 L8 L9	Ground
NC	F9	No Connect.	IOVDD0	F10 F11 G10 G11 K6 K7 K10 K11 L6 L7 L10 L11	Digital IO power supply 0.
PI5	F14	GPIO (5V)	PI4	F15	GPIO (5V)
PI3	F16	GPIO (5V)	PA5	G1	GPIO
PG6	G2	GPIO (5V)	PG5	G3	GPIO (5V)
PI2	G14	GPIO (5V)	PI1	G15	GPIO (5V)
PI0	G16	GPIO (5V)	PA6	H1	GPIO
PG8	H2	GPIO (5V)	PG7	H3	GPIO (5V)
PE5	H14	GPIO	PE6	H15	GPIO
PE7	H16	GPIO	PG11	J1	GPIO (5V)
PG10	J2	GPIO (5V)	PG9	J3	GPIO (5V)
PE3	J14	GPIO	PE4	J15	GPIO
DECOUPLE	J16	Decouple output for on-chip voltage regulator. An external decoupling capacitor is required at this pin.	PG14	K1	GPIO
PG13	K2	GPIO	PG12	K3	GPIO
PE1	K14	GPIO (5V)	PE2	K15	GPIO
DVDD	K16	Digital power supply.	PG15	L1	GPIO (5V)
PB15	L2	GPIO (5V)	PB0	L3	GPIO
PE0	L14	GPIO (5V)	PC7	L15	GPIO
VREGVDD	L16	Voltage regulator VDD input	PB1	M1	GPIO

5.7 EFM32GG11B3xx in BGA112 Device Pinout

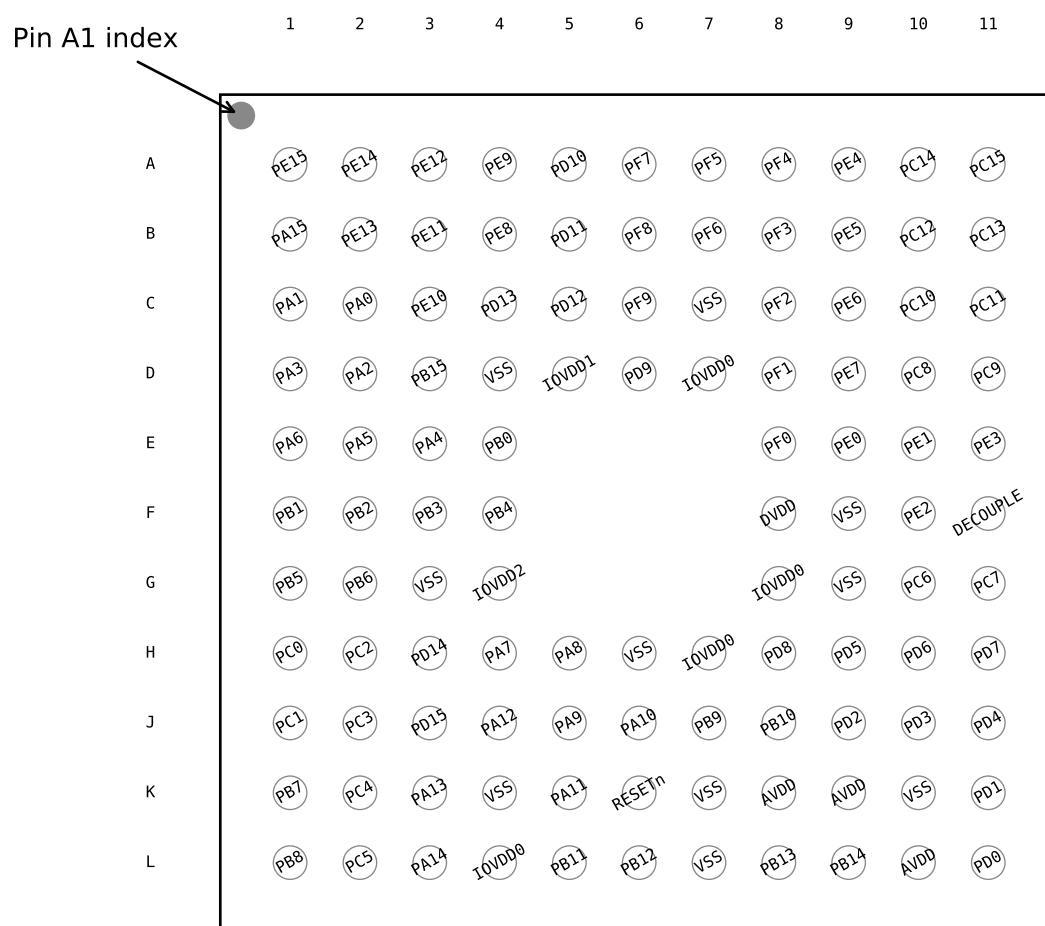


Figure 5.7. EFM32GG11B3xx in BGA112 Device Pinout

The following table provides package pin connections and general descriptions of pin functionality. For detailed information on the supported features for each GPIO pin, see [5.20 GPIO Functionality Table](#) or [5.21 Alternate Functionality Overview](#).

Table 5.7. EFM32GG11B3xx in BGA112 Device Pinout

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PE15	A1	GPIO	PE14	A2	GPIO
PE12	A3	GPIO	PE9	A4	GPIO
PD10	A5	GPIO	PF7	A6	GPIO
PF5	A7	GPIO	PF4	A8	GPIO
PE4	A9	GPIO	PC14	A10	GPIO (5V)
PC15	A11	GPIO (5V)	PA15	B1	GPIO
PE13	B2	GPIO	PE11	B3	GPIO

5.8 EFM32GG11B8xx in QFP100 Device Pinout

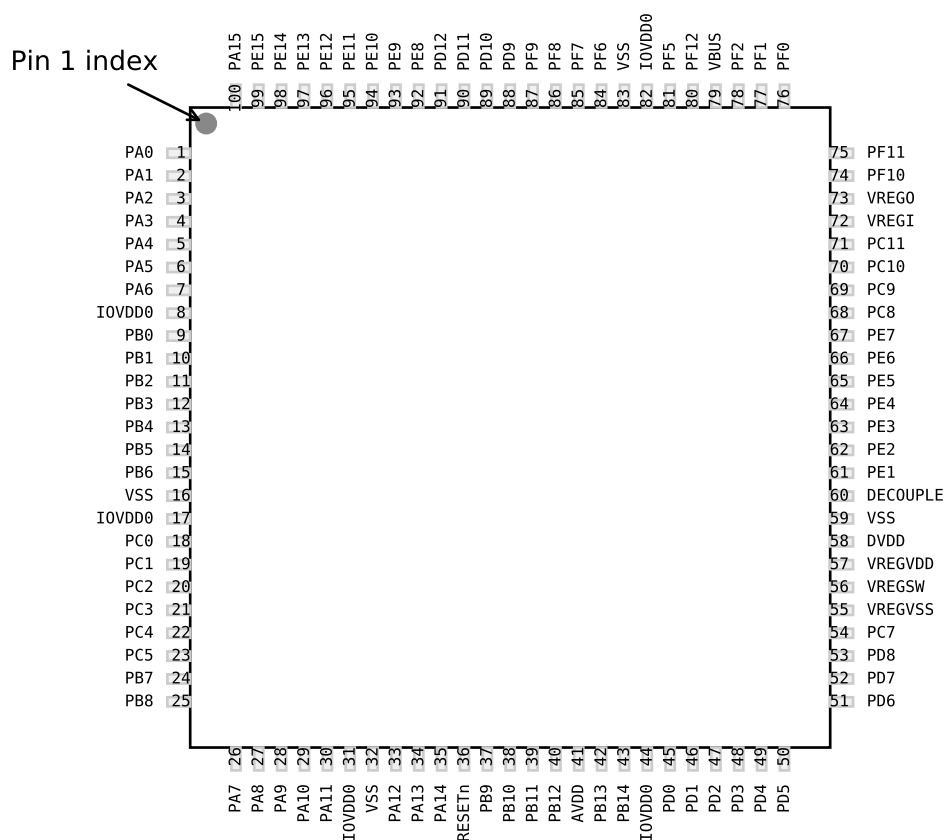


Figure 5.8. EFM32GG11B8xx in QFP100 Device Pinout

The following table provides package pin connections and general descriptions of pin functionality. For detailed information on the supported features for each GPIO pin, see [5.20 GPIO Functionality Table](#) or [5.21 Alternate Functionality Overview](#).

Table 5.8. EFM32GG11B8xx in QFP100 Device Pinout

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PA0	1	GPIO	PA1	2	GPIO
PA2	3	GPIO	PA3	4	GPIO
PA4	5	GPIO	PA5	6	GPIO
PA6	7	GPIO	IOVDD0	8, 17, 31, 44, 82	Digital IO power supply 0.
PB0	9	GPIO	PB1	10	GPIO

GPIO Name	Pin Alternate Functionality / Description				
	Analog	EBI	Timers	Communication	Other
PH11	BUSACMP3Y BU-SACMP3X	EBI_A23 #2	TIM5_CC1 #1 WTIM1_CC3 #6	US5_RX #3 U1_TX #5 I2C1_SDA #5	
PH13	BUSACMP3Y BU-SACMP3X	EBI_A25 #2	TIM5_CC0 #2 WTIM1_CC1 #7 PCNT2_S1IN #7	US5_CS #3 U1_CTS #5 I2C1_SDA #6	
PD0	VDAC0_OUT0ALT / OPA0_OUTALT #4 OPA2_OUTALT BU-SADC0Y BUSADC0X	EBI_A04 #1 EBI_A13 #3	TIM4_CDTI0 TIM6_CC2 #5 WTIM1_CC2 #0 PCNT2_S0IN #0	CAN0_RX #2 US1_TX #1	
PD3	BUSADC0Y BU-SADC0X OPA2_N	EBI_A07 #1 EBI_A16 #3	TIM4_CDTI2 TIM0_CC2 #2 TIM6_CC2 #6 WTIM1_CC1 #1 WTIM2_CC0 #5	CAN1_RX #2 US1_CS #1 LEU1_RX #2	ETM_TD1 #0 ETM_TD1 #2
PD8	BU_VIN	EBI_A12 #1	WTIM1_CC2 #2	US2_RTS #5	CMU_CLK1 #1 PRS_CH12 #2 ACMP2_O #0
PB7	LFXTAL_P		TIM0_CDTI0 #4 TIM1_CC0 #3	US0_TX #4 US1_CLK #0 US3_RX #2 US4_TX #0 U0_CTS #4	PRS_CH22 #0
PC3	VDAC0_OUT0ALT / OPA0_OUTALT #3 BUSACMP0Y BU-SACMP0X	EBI_AD10 #1 EBI_CS3 #2 EBI_BL1 #3 EBI_NANDREN #0	TIM0_CDTI1 #3 TIM2_CC1 #5 WTIM0_CC2 #7 LE-TIM1_OUT1 #3	ETH_TSUTMRTOG #2 CAN1_TX #0 US1_CLK #4 US2_RX #0	LES_CH3 PRS_CH11 #1
PC5	BUSACMP0Y BU-SACMP0X OPA0_N	EBI_AD12 #1 EBI_WEN #2 EBI_NANDWEN #0 EBI_A00 #3	TIM0_CC1 #5 LE-TIM0_OUT1 #3 PCNT1_S1IN #3	SDIO_WP #1 US2_CS #0 US4_CS #0 U0_RX #4 U1_RTS #4 I2C1_SCL #0	LES_CH5 PRS_CH19 #2
PA9	BUSAY BUSBX LCD_SEG37	EBI_AD15 #1 EBI_A03 #3 EBI_DTEN #0	TIM2_CC1 #0 TIM0_CC1 #6 WTIM2_CC0 #0 LE-TIM0_OUT1 #6	US2_CLK #2	PRS_CH9 #0
PB10	BUSBY BUSAX	EBI_BL0 #2 EBI_A01 #1 EBI_A04 #0 EBI_A10 #3	WTIM2_CC1 #2 LE-TIM0_OUT1 #7	SDIO_CD #3 CAN0_TX #3 US1_RTS #0 US2_CTS #3 U1_RX #2	PRS_CH9 #2 ACMP1_O #6
PH0	BUSADC1Y BU-SADC1X	EBI_DCLK #2	WTIM2_CC2 #4	US0_CTS #6 LEU1_TX #5	
PH3	BUSADC1Y BU-SADC1X	EBI_HSNC #2	TIM6_CC1 #3	US1_RTS #6	
PH6	BUSADC1Y BU-SADC1X	EBI_A18 #2	TIM6_CDTI1 #3 WTIM2_CC2 #6	US4_CLK #4	
PH9	BUSACMP3Y BU-SACMP3X	EBI_A21 #2	TIM6_CC1 #4 WTIM1_CC1 #6 WTIM2_CC2 #7	US4_RTS #4	
PH12	BUSACMP3Y BU-SACMP3X	EBI_A24 #2	TIM5_CC2 #1 WTIM1_CC0 #7	US5_CLK #3 U1_RX #5 I2C1_SCL #5	

Alternate	LOCATION		
Functionality	0 - 3	4 - 7	Description
LES_ALTEX6	0: PE12		LESENSE alternate excite output 6.
LES_ALTEX7	0: PE13		LESENSE alternate excite output 7.
LES_CH0	0: PC0		LESENSE channel 0.
LES_CH1	0: PC1		LESENSE channel 1.
LES_CH2	0: PC2		LESENSE channel 2.
LES_CH3	0: PC3		LESENSE channel 3.
LES_CH4	0: PC4		LESENSE channel 4.
LES_CH5	0: PC5		LESENSE channel 5.
LES_CH6	0: PC6		LESENSE channel 6.
LES_CH7	0: PC7		LESENSE channel 7.
LES_CH8	0: PC8		LESENSE channel 8.
LES_CH9	0: PC9		LESENSE channel 9.
LES_CH10	0: PC10		LESENSE channel 10.

Alternate	LOCATION		
Functionality	0 - 3	4 - 7	Description
LFXTAL_N	0: PB8		Low Frequency Crystal (typically 32.768 kHz) negative pin. Also used as an optional external clock input pin.
LFXTAL_P	0: PB7		Low Frequency Crystal (typically 32.768 kHz) positive pin.
OPA0_N	0: PC5		Operational Amplifier 0 external negative input.
OPA0_P	0: PC4		Operational Amplifier 0 external positive input.
OPA1_N	0: PD7		Operational Amplifier 1 external negative input.
OPA1_P	0: PD6		Operational Amplifier 1 external positive input.
OPA2_N	0: PD3		Operational Amplifier 2 external negative input.
OPA2_OUT	0: PD5		Operational Amplifier 2 output.
OPA2_OUTALT	0: PD0		Operational Amplifier 2 alternative output.
OPA2_P	0: PD4		Operational Amplifier 2 external positive input.
OPA3_N	0: PC7		Operational Amplifier 3 external negative input.
OPA3_OUT	0: PD1		Operational Amplifier 3 output.
OPA3_P	0: PC6		Operational Amplifier 3 external positive input.

Alternate	LOCATION		
Functionality	0 - 3	4 - 7	Description
PCNT0_S0IN	0: PC13 1: PE0 2: PC0 3: PD6	4: PA0 5: PB0 6: PB5 7: PB12	Pulse Counter PCNT0 input number 0.
PCNT0_S1IN	0: PC14 1: PE1 2: PC1 3: PD7	4: PA1 5: PB1 6: PB6 7: PB11	Pulse Counter PCNT0 input number 1.
PCNT1_S0IN	0: PA5 1: PB3 2: PD15 3: PC4	4: PA7 5: PA12 6: PB11 7: PG14	Pulse Counter PCNT1 input number 0.
PCNT1_S1IN	0: PA6 1: PB4 2: PB0 3: PC5	4: PA8 5: PA13 6: PB12 7: PG15	Pulse Counter PCNT1 input number 1.
PCNT2_S0IN	0: PD0 1: PE8 2: PB13 3: PF10	4: PC12 5: PI2 6: PI0 7: PH14	Pulse Counter PCNT2 input number 0.
PCNT2_S1IN	0: PD1 1: PE9 2: PB14 3: PF11	4: PC13 5: PI1 6: PH15 7: PH13	Pulse Counter PCNT2 input number 1.
PRS_CH0	0: PA0 1: PF3 2: PC14 3: PF2		Peripheral Reflex System PRS, channel 0.
PRS_CH1	0: PA1 1: PF4 2: PC15 3: PE12		Peripheral Reflex System PRS, channel 1.
PRS_CH2	0: PC0 1: PF5 2: PE10 3: PE13		Peripheral Reflex System PRS, channel 2.
PRS_CH3	0: PC1 1: PE8 2: PE11 3: PA0		Peripheral Reflex System PRS, channel 3.
PRS_CH4	0: PC8 1: PB0 2: PF1		Peripheral Reflex System PRS, channel 4.
PRS_CH5	0: PC9 1: PB1 2: PD6		Peripheral Reflex System PRS, channel 5.
PRS_CH6	0: PA6 1: PB14 2: PE6		Peripheral Reflex System PRS, channel 6.

Alternate	LOCATION		
Functionality	0 - 3	4 - 7	Description
TIM2_CC1	0: PA9 1: PA13 2: PC9 3: PE12	4: PC0 5: PC3 6: PG9 7: PG6	Timer 2 Capture Compare input / output channel 1.
TIM2_CC2	0: PA10 1: PA14 2: PC10 3: PE13	4: PC1 5: PC4 6: PG10 7: PG7	Timer 2 Capture Compare input / output channel 2.
TIM2_CDT10	0: PB0 1: PD13 2: PE8 3: PG0		Timer 2 Complimentary Dead Time Insertion channel 0.
TIM2_CDT11	0: PB1 1: PD14 2: PE14 3: PG1		Timer 2 Complimentary Dead Time Insertion channel 1.
TIM2_CDT12	0: PB2 1: PD15 2: PE15 3: PG2		Timer 2 Complimentary Dead Time Insertion channel 2.
TIM3_CC0	0: PE14 1: PE0 2: PE3 3: PE5	4: PA0 5: PA3 6: PA6 7: PD15	Timer 3 Capture Compare input / output channel 0.
TIM3_CC1	0: PE15 1: PE1 2: PE4 3: PE6	4: PA1 5: PA4 6: PD13 7: PB15	Timer 3 Capture Compare input / output channel 1.
TIM3_CC2	0: PA15 1: PE2 2: PE5 3: PE7	4: PA2 5: PA5 6: PD14 7: PB0	Timer 3 Capture Compare input / output channel 2.
TIM4_CC0	0: PF3 1: PF13 2: PF5 3: PI8	4: PF6 5: PF9 6: PD11 7: PE9	Timer 4 Capture Compare input / output channel 0.
TIM4_CC1	0: PF4 1: PF14 2: PI6 3: PI9	4: PF7 5: PD9 6: PD12 7: PE10	Timer 4 Capture Compare input / output channel 1.
TIM4_CC2	0: PF12 1: PF15 2: PI7 3: PI10	4: PF8 5: PD10 6: PE8 7: PE11	Timer 4 Capture Compare input / output channel 2.
TIM4_CDT10	0: PD0		Timer 4 Complimentary Dead Time Insertion channel 0.
TIM4_CDT11	0: PD1		Timer 4 Complimentary Dead Time Insertion channel 1.

Alternate	LOCATION		
Functionality	0 - 3	4 - 7	Description
TIM4_CDTI2	0: PD3		Timer 4 Complimentary Dead Time Insertion channel 2.
TIM5_CC0	0: PE4 1: PE7 2: PH13 3: PI0	4: PC8 5: PC11 6: PC14 7: PF12	Timer 5 Capture Compare input / output channel 0.
TIM5_CC1	0: PE5 1: PH11 2: PH14 3: PI1	4: PC9 5: PC12 6: PF10 7: PF13	Timer 5 Capture Compare input / output channel 1.
TIM5_CC2	0: PE6 1: PH12 2: PH15 3: PI2	4: PC10 5: PC13 6: PF11 7: PF14	Timer 5 Capture Compare input / output channel 2.
TIM6_CC0	0: PG0 1: PG6 2: PG12 3: PH2	4: PH8 5: PB13 6: PD1 7: PD4	Timer 6 Capture Compare input / output channel 0.
TIM6_CC1	0: PG1 1: PG7 2: PG13 3: PH3	4: PH9 5: PB14 6: PD2 7: PD5	Timer 6 Capture Compare input / output channel 1.
TIM6_CC2	0: PG2 1: PG8 2: PG14 3: PH4	4: PH10 5: PD0 6: PD3 7: PD6	Timer 6 Capture Compare input / output channel 2.
TIM6_CDTI0	0: PG3 1: PG9 2: PE4 3: PH5		Timer 6 Complimentary Dead Time Insertion channel 0.
TIM6_CDTI1	0: PG4 1: PG10 2: PE5 3: PH6		Timer 6 Complimentary Dead Time Insertion channel 1.
TIM6_CDTI2	0: PG5 1: PG11 2: PE6 3: PH7		Timer 6 Complimentary Dead Time Insertion channel 2.
U0_CTS	0: PF8 1: PE2 2: PA5 3: PC13	4: PB7 5: PD5	UART0 Clear To Send hardware flow control input.
U0_RTS	0: PF9 1: PE3 2: PA6 3: PC12	4: PB8 5: PD6	UART0 Request To Send hardware flow control output.
U0_RX	0: PF7 1: PE1 2: PA4 3: PC15	4: PC5 5: PF2 6: PE4	UART0 Receive input.

Table 5.27. ADC0 Bus and Pin Mapping

APORT4Y	APORT4X	APORT3Y	APORT3X	APORT2Y	APORT2X	APORT1Y	APORT1X	APORT0Y	APORT0X	Port
BUSDY	BUSDY	BUSCY	BUSCX	BUSBY	BUSBX	BUSAY	BUSAX	BUSADC0Y	BUSADC0X	Bus
	PF15	PF15			PB15	PB15				CH31
PF14			PF14	PB14			PB14			CH30
	PF13	PF13			PB13	PB13				CH29
PF12			PF12	PB12			PB12			CH28
	PF11	PF11			PB11	PB11				CH27
PF10			PF10	PB10			PB10			CH26
	PF9	PF9			PB9	PB9				CH25
PF8			PF8							CH24
	PF7	PF7								CH23
PF6			PF6	PB6			PB6			CH22
	PF5	PF5			PB5	PB5				CH21
PF4			PF4	PB4			PB4			CH20
	PF3	PF3			PB3	PB3				CH19
PF2			PF2	PB2			PB2			CH18
	PF1	PF1			PB1	PB1				CH17
PF0			PF0	PB0			PB0			CH16
	PE15	PE15			PA15	PA15				CH15
PE14			PE14	PA14			PA14			CH14
	PE13	PE13			PA13	PA13				CH13
PE12			PE12	PA12			PA12			CH12
	PE11	PE11			PA11	PA11				CH11
PE10			PE10	PA10			PA10			CH10
	PE9	PE9			PA9	PA9				CH9
PE8			PE8	PA8			PA8			CH8
	PE7	PE7			PA7	PA7		PD7	PD7	CH7
PE6			PE6	PA6			PA6	PD6	PD6	CH6
	PE5	PE5			PA5	PA5		PD5	PD5	CH5
PE4			PE4	PA4			PA4	PD4	PD4	CH4
					PA3	PA3		PD3	PD3	CH3
				PA2			PA2	PD2	PD2	CH2
	PE1	PE1			PA1	PA1		PD1	PD1	CH1
PE0			PE0	PA0			PA0	PD0	PD0	CH0

Table 6.2. BGA192 PCB Land Pattern Dimensions

Dimension	Min	Nom	Max
X		0.20	
C1		6.00	
C2		6.00	
E1		0.4	
E2		0.4	

Note:

1. All dimensions shown are in millimeters (mm) unless otherwise noted.
2. Dimensioning and Tolerancing is per the ANSI Y14.5M-1994 specification.
3. This Land Pattern Design is based on the IPC-7351 guidelines.
4. All metal pads are to be non-solder mask defined (NSMD). Clearance between the solder mask and the metal pad is to be 60 μm minimum, all the way around the pad.
5. A stainless steel, laser-cut and electro-polished stencil with trapezoidal walls should be used to assure good solder paste release.
6. The stencil thickness should be 0.125 mm (5 mils).
7. The ratio of stencil aperture to land pad size should be 1:1.
8. A No-Clean, Type-3 solder paste is recommended.
9. The recommended card reflow profile is per the JEDEC/IPC J-STD-020C specification for Small Body Components.

11. TQFP64 Package Specifications

11.1 TQFP64 Package Dimensions

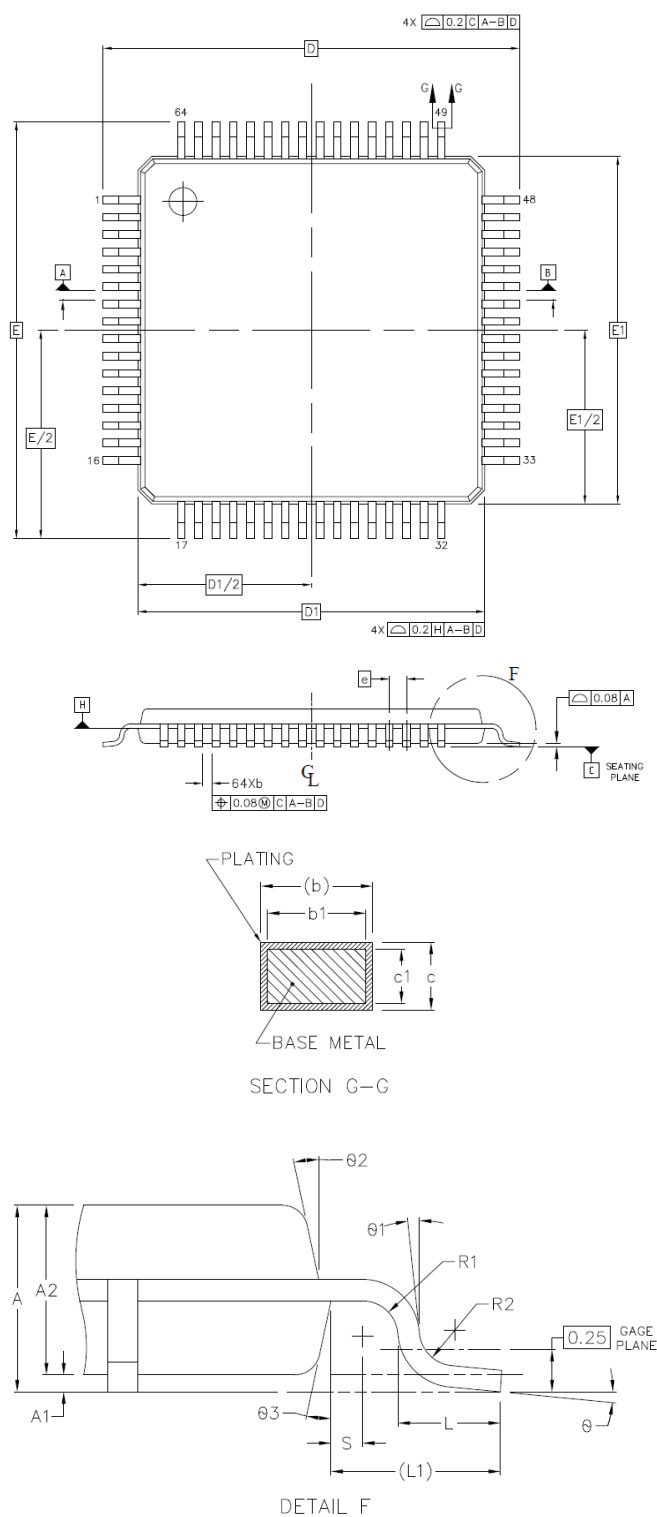


Figure 11.1. TQFP64 Package Drawing