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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Active
Core Processor	ARM® Cortex®-M4
Core Size	32-Bit Single-Core
Speed	72MHz
Connectivity	CANbus, EBI/EMI, Ethernet, I²C, IrDA, LINbus, MMC/SD/SDIO, QSPI, SmartCard, SPI, UART/USART, USB
Peripherals	Brown-out Detect/Reset, DMA, LCD, POR, PWM, WDT
Number of I/O	121
Program Memory Size	1MB (1M x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	512K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.8V
Data Converters	A/D 16x12b SAR; D/A 2x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	152-VFBGA
Supplier Device Package	152-BGA (8x8)
Purchase URL	https://www.e-xfl.com/product-detail/silicon-labs/efm32gg11b840f1024gl152-b

1. Feature List

The EFM32GG11 highlighted features are listed below.

- **ARM Cortex-M4 CPU platform**
 - High performance 32-bit processor @ up to 72 MHz
 - DSP instruction support and Floating Point Unit
 - Memory Protection Unit
 - Wake-up Interrupt Controller
- **Flexible Energy Management System**
 - 80 μ A/MHz in Active Mode (EM0)
 - 2.1 μ A EM2 Deep Sleep current (16 kB RAM retention and RTCC running from LFRCO)
- **Integrated DC-DC buck converter**
- **Up to 2048 kB flash program memory**
 - Dual-bank with read-while-write support
- **Up to 512 kB RAM data memory**
 - 256 kB with ECC (SEC-DED)
- **Octal/Quad-SPI Flash Memory Interface**
 - Supports 3 V and 1.8 V memories
 - 1/2/4/8-bit data bus
 - Quad-SPI Execute In Place (XIP)
- **Communication Interfaces**
 - Low-energy Universal Serial Bus (USB) with Device and Host support
 - Fully USB 2.0 compliant
 - On-chip PHY and embedded 5V to 3.3V regulator
 - Crystal-free Device mode operation
 - Patent-pending Low-Energy Mode (LEM)
 - SD/MMC/SDIO Host Controller
 - SD v3.01, SDIO v3.0 and MMC v4.51
 - 1/4/8-bit bus width
 - 10/100 Ethernet MAC with MII/RMII interface
 - IEEE1588-2008 precision time stamping
 - Energy Efficient Ethernet (802.3az)
 - Up to 2x CAN Bus Controller
 - Version 2.0A and 2.0B up to 1 Mbps
 - 6x Universal Synchronous/Asynchronous Receiver/ Transmitter
 - UART/SPI/SmartCard (ISO 7816)/IrDA/I2S/LIN
 - Triple buffered full/half-duplex operation with flow control
 - Ultra high speed (36 MHz) operation on one instance
 - 2x Universal Asynchronous Receiver/ Transmitter
 - 2x Low Energy UART
 - Autonomous operation with DMA in Deep Sleep Mode
 - 3x I²C Interface with SMBus support
 - Address recognition in EM3 Stop Mode
- **Up to 144 General Purpose I/O Pins**
 - Configurable push-pull, open-drain, pull-up/down, input filter, drive strength
 - Configurable peripheral I/O locations
 - 5 V tolerance on select pins
 - Asynchronous external interrupts
 - Output state retention and wake-up from Shutoff Mode
- **Up to 24 Channel DMA Controller**
- **Up to 24 Channel Peripheral Reflex System (PRS) for autonomous inter-peripheral signaling**
- **External Bus Interface for up to 4x256 MB of external memory mapped space**
 - TFT Controller with Direct Drive
 - Per-pixel alpha-blending engine
- **Hardware Cryptography**
 - AES 128/256-bit keys
 - ECC B/K163, B/K233, P192, P224, P256
 - SHA-1 and SHA-2 (SHA-224 and SHA-256)
 - True Random Number Generator (TRNG)
- **Hardware CRC engine**
 - Single-cycle computation with 8/16/32-bit data and 16-bit (programmable)/32-bit (fixed) polynomial
- **Security Management Unit (SMU)**
 - Fine-grained access control for on-chip peripherals
- **Integrated Low-energy LCD Controller with up to 8x36 segments**
 - Voltage boost, contrast and autonomous animation
 - Patented low-energy LCD driver
- **Backup Power Domain**
 - RTCC and retention registers in a separate power domain, available down to energy mode EM4H
 - Operation from backup battery when main power absent/ insufficient
- **Ultra Low-Power Precision Analog Peripherals**
 - 2x 12-bit 1 Msamples/s Analog to Digital Converter (ADC)
 - On-chip temperature sensor
 - 2x 12-bit 500 ksamples/s Digital to Analog Converter (VDAC)
 - Digital to Analog Current Converter (IDAC)
 - Up to 4x Analog Comparator (ACMP)
 - Up to 4x Operational Amplifier (OPAMP)
 - Robust current-based capacitive sensing with up to 64 inputs and wake-on-touch (CSEN)
 - Up to 108 GPIO pins are analog-capable. Flexible analog peripheral-to-pin routing via Analog Port (APORT)
 - Supply Voltage Monitor

3.12 Configuration Summary

The features of the EFM32GG11 are a subset of the feature set described in the device reference manual. The table below describes device specific implementation of the features. Remaining modules support full configuration.

Table 3.2. Configuration Summary

Module	Configuration	Pin Connections
USART0	IrDA, SmartCard	US0_TX, US0_RX, US0_CLK, US0_CS
USART1	I ² S, SmartCard	US1_TX, US1_RX, US1_CLK, US1_CS
USART2	IrDA, SmartCard, High-Speed	US2_TX, US2_RX, US2_CLK, US2_CS
USART3	I ² S, SmartCard	US3_TX, US3_RX, US3_CLK, US3_CS
USART4	I ² S, SmartCard	US4_TX, US4_RX, US4_CLK, US4_CS
USART5	SmartCard	US5_TX, US5_RX, US5_CLK, US5_CS
TIMER0	with DTI	TIM0_CC[2:0], TIM0_CDTI[2:0]
TIMER1	-	TIM1_CC[3:0]
TIMER2	with DTI	TIM2_CC[2:0], TIM2_CDTI[2:0]
TIMER3	-	TIM3_CC[2:0]
TIMER4	with DTI	TIM4_CC[2:0], TIM4_CDTI[2:0]
TIMER5	-	TIM5_CC[2:0]
TIMER6	with DTI	TIM6_CC[2:0], TIM6_CDTI[2:0]
WTIMER0	with DTI	WTIM0_CC[2:0], WTIM0_CDTI[2:0]
WTIMER1	-	WTIM1_CC[3:0]
WTIMER2	-	WTIM2_CC[2:0]
WTIMER3	-	WTIM3_CC[2:0]

4.1.1 Absolute Maximum Ratings

Stresses above those listed below may cause permanent damage to the device. This is a stress rating only and functional operation of the devices at those or any other conditions above those indicated in the operation listings of this specification is not implied. Exposure to maximum rating conditions for extended periods may affect device reliability. For more information on the available quality and reliability data, see the Quality and Reliability Monitor Report at <http://www.silabs.com/support/quality/pages/default.aspx>.

Table 4.1. Absolute Maximum Ratings

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Storage temperature range	T _{STG}		-50	—	150	°C
Voltage on supply pins other than VREGI and VBUS	V _{DDMAX}		-0.3	—	3.8	V
Voltage ramp rate on any supply pin	V _{DDRAMPMAX}		—	—	1	V / μs
DC voltage on any GPIO pin	V _{DIGPIN}	5V tolerant GPIO pins ^{1 2 3}	-0.3	—	Min of 5.25 and IOVDD +2	V
		LCD pins ³	-0.3	—	Min of 3.8 and IOVDD +2	V
		Standard GPIO pins	-0.3	—	IOVDD+0.3	V
Total current into VDD power lines	I _{VDDMAX}	Source	—	—	200	mA
Total current into VSS ground lines	I _{VSSMAX}	Sink	—	—	200	mA
Current per I/O pin	I _{IOMAX}	Sink	—	—	50	mA
		Source	—	—	50	mA
Current for all I/O pins	I _{IOTALLMAX}	Sink	—	—	200	mA
		Source	—	—	200	mA
Junction temperature	T _J	-G grade devices	-40	—	105	°C
		-I grade devices	-40	—	125	°C
Voltage on regulator supply pins VREGI and VBUS	V _{VREGI}		-0.3	—	5.5	V

Note:

- When a GPIO pin is routed to the analog module through the APOR, the maximum voltage = IOVDD.
- Valid for IOVDD in valid operating range or when IOVDD is undriven (high-Z). If IOVDD is connected to a low-impedance source below the valid operating range (e.g. IOVDD shorted to VSS), the pin voltage maximum is IOVDD + 0.3 V, to avoid exceeding the maximum IO current specifications.
- To operate above the IOVDD supply rail, over-voltage tolerance must be enabled according to the GPIO_Px_OVTDIS register. Pins with over-voltage tolerance disabled have the same limits as Standard GPIO.

4.1.7.2 Current Consumption 3.3 V using DC-DC Converter

Unless otherwise indicated, typical conditions are: VREGVDD = AVDD = IOVDD = 3.3 V, DVDD = 1.8 V DC-DC output. T = 25 °C. Minimum and maximum values in this table represent the worst conditions across supply voltage and process variation at T = 25 °C.

Table 4.8. Current Consumption 3.3 V using DC-DC Converter

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Current consumption in EM0 mode with all peripherals disabled, DCDC in Low Noise DCM mode ²	IACTIVE_DCM	72 MHz HFRCO, CPU running Prime from flash	—	80	—	µA/MHz
		72 MHz HFRCO, CPU running while loop from flash	—	80	—	µA/MHz
		72 MHz HFRCO, CPU running CoreMark loop from flash	—	92	—	µA/MHz
		50 MHz crystal, CPU running while loop from flash	—	84	—	µA/MHz
		48 MHz HFRCO, CPU running while loop from flash	—	84	—	µA/MHz
		32 MHz HFRCO, CPU running while loop from flash	—	90	—	µA/MHz
		26 MHz HFRCO, CPU running while loop from flash	—	94	—	µA/MHz
		16 MHz HFRCO, CPU running while loop from flash	—	109	—	µA/MHz
		1 MHz HFRCO, CPU running while loop from flash	—	698	—	µA/MHz
Current consumption in EM0 mode with all peripherals disabled, DCDC in Low Noise CCM mode ¹	IACTIVE_CCM	72 MHz HFRCO, CPU running Prime from flash	—	84	—	µA/MHz
		72 MHz HFRCO, CPU running while loop from flash	—	84	—	µA/MHz
		72 MHz HFRCO, CPU running CoreMark loop from flash	—	95	—	µA/MHz
		50 MHz crystal, CPU running while loop from flash	—	91	—	µA/MHz
		48 MHz HFRCO, CPU running while loop from flash	—	92	—	µA/MHz
		32 MHz HFRCO, CPU running while loop from flash	—	104	—	µA/MHz
		26 MHz HFRCO, CPU running while loop from flash	—	113	—	µA/MHz
		16 MHz HFRCO, CPU running while loop from flash	—	142	—	µA/MHz
		1 MHz HFRCO, CPU running while loop from flash	—	1264	—	µA/MHz

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Frequency limits	f_{HFRCO_BAND}	FREQRANGE = 0, FINETUNIN-GEN = 0	1	—	10	MHz
		FREQRANGE = 3, FINETUNIN-GEN = 0	2	—	17	MHz
		FREQRANGE = 6, FINETUNIN-GEN = 0	4	—	30	MHz
		FREQRANGE = 7, FINETUNIN-GEN = 0	5	—	34	MHz
		FREQRANGE = 8, FINETUNIN-GEN = 0	7	—	42	MHz
		FREQRANGE = 10, FINETUNIN-GEN = 0	12	—	58	MHz
		FREQRANGE = 11, FINETUNIN-GEN = 0	15	—	68	MHz
		FREQRANGE = 12, FINETUNIN-GEN = 0	18	—	83	MHz
		FREQRANGE = 13, FINETUNIN-GEN = 0	24	—	100	MHz
		FREQRANGE = 14, FINETUNIN-GEN = 0	28	—	119	MHz
		FREQRANGE = 15, FINETUNIN-GEN = 0	33	—	138	MHz
		FREQRANGE = 16, FINETUNIN-GEN = 0	43	—	163	MHz

Note:

1. Maximum DPLL lock time $\approx 6 \times (M+1) \times t_{REF}$, where t_{REF} is the reference clock period.

4.1.23 I²C4.1.23.1 I²C Standard-mode (Sm)¹Table 4.31. I²C Standard-mode (Sm)¹

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
SCL clock frequency ²	f _{SCL}		0	—	100	kHz
SCL clock low time	t _{LOW}		4.7	—	—	μs
SCL clock high time	t _{HIGH}		4	—	—	μs
SDA set-up time	t _{SU_DAT}		250	—	—	ns
SDA hold time ³	t _{HD_DAT}		100	—	3450	ns
Repeated START condition set-up time	t _{SU_STA}		4.7	—	—	μs
(Repeated) START condition hold time	t _{HD_STA}		4	—	—	μs
STOP condition set-up time	t _{SU_STO}		4	—	—	μs
Bus free time between a STOP and START condition	t _{BUF}		4.7	—	—	μs

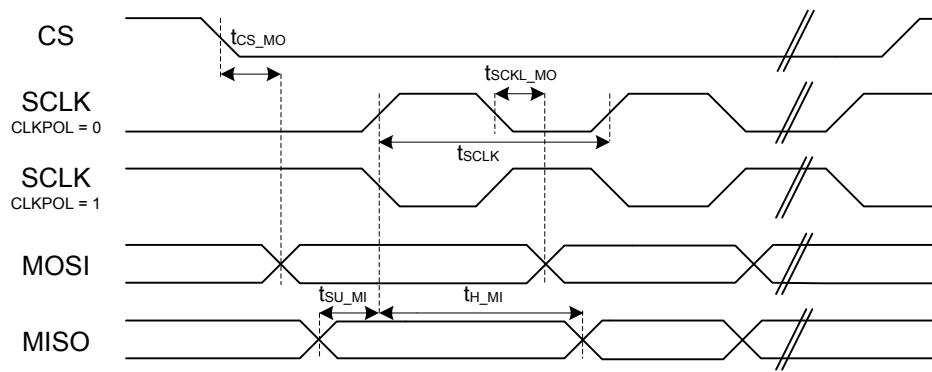
Note:

1. For CLHR set to 0 in the I²Cn_CTRL register.
2. For the minimum HFPERCLK frequency required in Standard-mode, refer to the I²C chapter in the reference manual.
3. The maximum SDA hold time (t_{HD_DAT}) needs to be met only when the device does not stretch the low time of SCL (t_{LOW}).

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
MISO hold time ^{1 3}	t_{H_MI}	USART2, location 4, IOVDD = 1.8 V	-11.6	—	—	ns
		USART2, location 4, IOVDD = 3.0 V	-11.6	—	—	ns
		USART2, location 5, IOVDD = 1.8 V	-9.1	—	—	ns
		USART2, location 5, IOVDD = 3.0 V	-9.1	—	—	ns
		All other USARTs and locations, IOVDD = 1.8 V	-8	—	—	ns
		All other USARTs and locations, IOVDD = 3.0 V	-8	—	—	ns

Note:

1. Applies for both CLKPHA = 0 and CLKPHA = 1 (figure only shows CLKPHA = 0).
2. $t_{HPERCLK}$ is one period of the selected HPERCLK.
3. Measurement done with 8 pF output loading at 10% and 90% of V_{DD} (figure shows 50% of V_{DD}).

**Figure 4.1. SPI Master Timing Diagram**

SDIO SDR Mode Timing

Timing is specified for route location 0 at 1.8 V IOVDD with voltage scaling disabled. Slew rate for SD_CLK set to 7, all other GPIO set to 6, DRIVESTRENGTH = STRONG for all pins. SDIO_CTRL_TXDLYMUXSEL = 0. Loading between 5 and 10 pF on all pins or between 10 and 40 pF on all pins.

Table 4.48. SDIO SDR Mode Timing (Location 0)

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Clock frequency during data transfer	FSD_CLK	Using HFRCO, AUXHFRCO, or USHFRCO	—	—	20	MHz
		Using HFXO	—	—	TBD	MHz
Clock low time	tWL	Using HFRCO, AUXHFRCO, or USHFRCO	22.6	—	—	ns
		Using HFXO	TBD	—	—	ns
Clock high time	tWH	Using HFRCO, AUXHFRCO, or USHFRCO	22.6	—	—	ns
		Using HFXO	TBD	—	—	ns
Clock rise time	tR		0.99	4.68	—	ns
Clock fall time	tF		0.90	3.64	—	ns
Input setup time, CMD, DAT[0:3] valid to SD_CLK	tISU		8	—	—	ns
Input hold time, SD_CLK to CMD, DAT[0:3] change	tIH		1.5	—	—	ns
Output delay time, SD_CLK to CMD, DAT[0:3] valid	tODLY		0	—	35	ns
Output hold time, SD_CLK to CMD, DAT[0:3] change	tOH		0.8	—	—	ns

SDIO DDR Mode Timing

Timing is specified for route location 0 at 1.8 V IOVDD with voltage scaling disabled. Slew rate for SD_CLK set to 6, all other GPIO set to 6, DRIVESTRENGTH = STRONG for all pins. SDIO_CTRL_TXDLYMUXSEL = 1. Loading between 5 and 10 pF on all pins or between 10 and 30 pF on all pins.

Table 4.49. SDIO DS Mode Timing (Location 0)

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Clock frequency during data transfer	FSD_CLK	Using HFRCO, AUXHFRCO, or USHFRCO	—	—	20	MHz
		Using HFXO	—	—	TBD	MHz
Clock low time	tWL	Using HFRCO, AUXHFRCO, or USHFRCO	22.6	—	—	ns
		Using HFXO	TBD	—	—	ns
Clock high time	tWH	Using HFRCO, AUXHFRCO, or USHFRCO	22.6	—	—	ns
		Using HFXO	TBD	—	—	ns
Clock rise time	tR		1.69	6.52	—	ns
Clock fall time	tF		1.42	4.96	—	ns
Input setup time, CMD valid to SD_CLK	tISU		6	—	—	ns
Input hold time, SD_CLK to CMD change	tIH		1.8	—	—	ns
Output delay time, SD_CLK to CMD valid	tODLY		0	—	16	ns
Output hold time, SD_CLK to CMD change	tOH		0.8	—	—	ns
Input setup time, DAT[0:3] valid to SD_CLK	tISU2X		6	—	—	ns
Input hold time, SD_CLK to DAT[0:3] change	tIH2X		1.5	—	—	ns
Output delay time, SD_CLK to DAT[0:3] valid	tODLY2X		0	—	16	ns
Output hold time, SD_CLK to DAT[0:3] change	tOH2X		0.8	—	—	ns

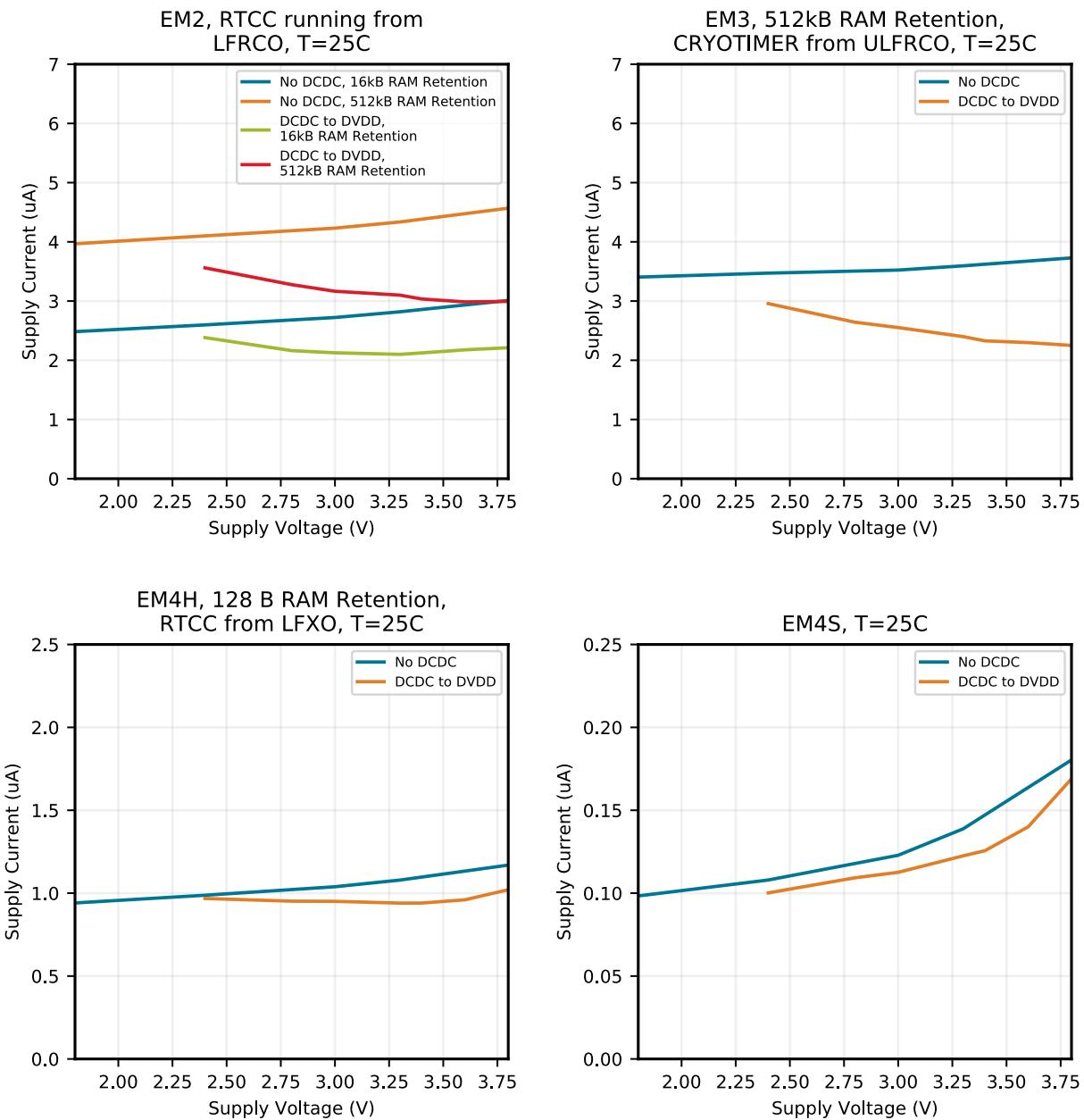


Figure 4.28. EM2, EM3, EM4H and EM4S Typical Supply Current vs. Supply

4.2.2 DC-DC Converter

Default test conditions: CCM mode, LDCDC = 4.7 μ H, CDCDC = 4.7 μ F, VDCDC_I = 3.3 V, VDCDC_O = 1.8 V, FDCDC_LN = 7 MHz

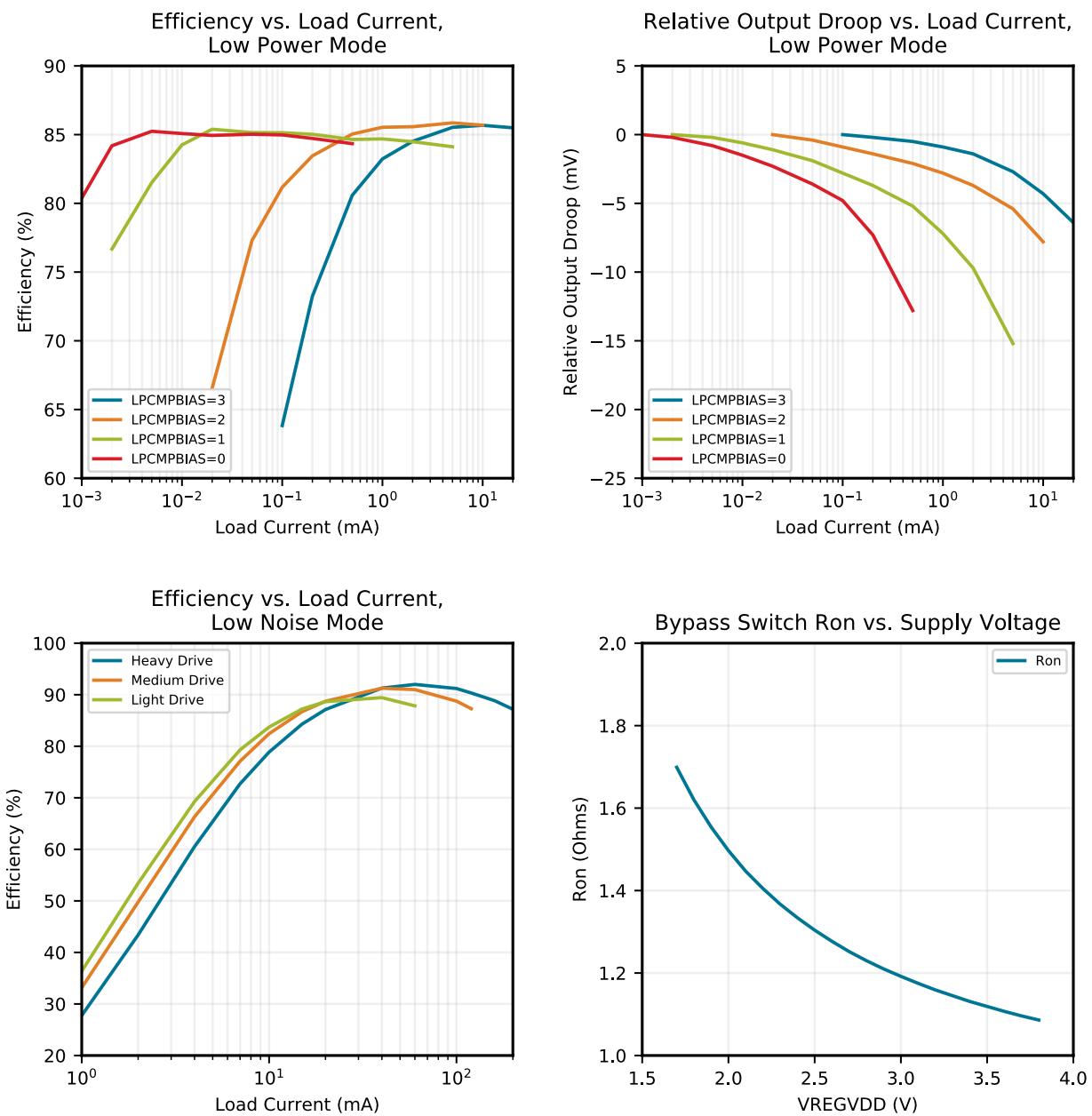


Figure 4.29. DC-DC Converter Typical Performance Characteristics

5. Pin Definitions

5.1 EFM32GG11B8xx in BGA192 Device Pinout

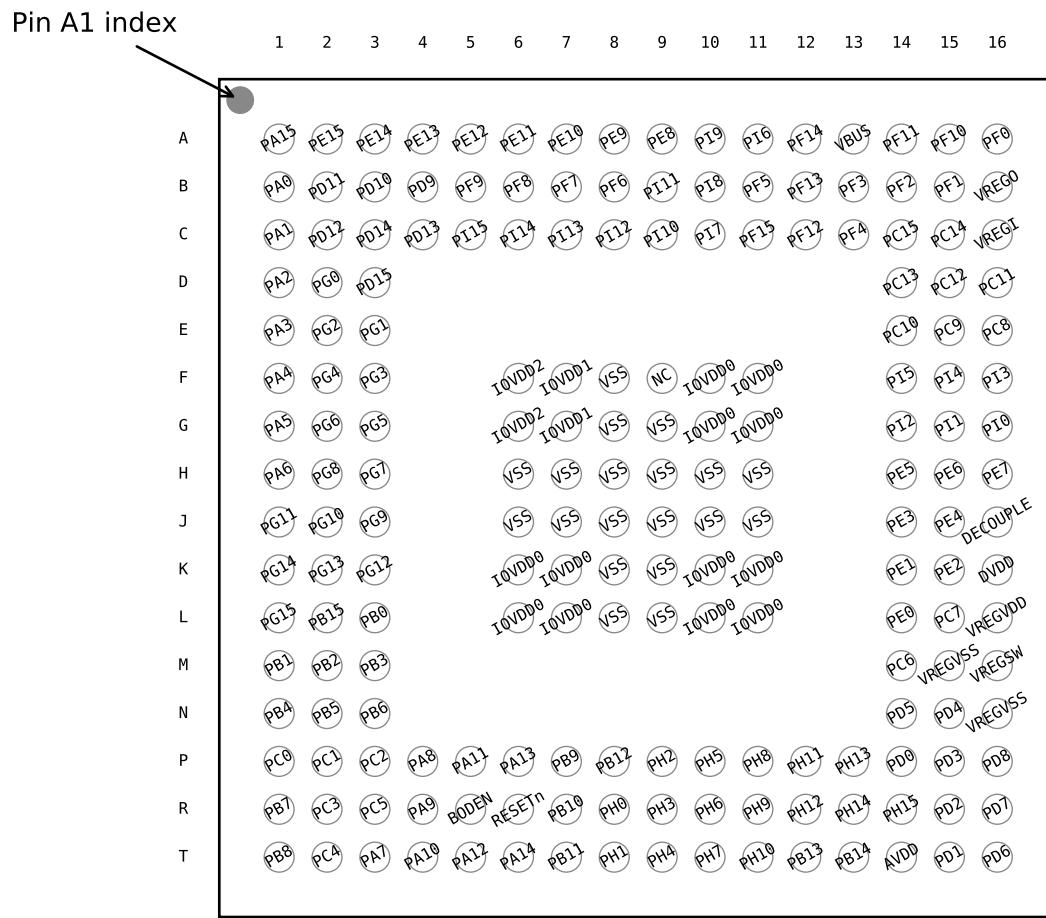


Figure 5.1. EFM32GG11B8xx in BGA192 Device Pinout

The following table provides package pin connections and general descriptions of pin functionality. For detailed information on the supported features for each GPIO pin, see [5.20 GPIO Functionality Table](#) or [5.21 Alternate Functionality Overview](#).

Table 5.1. EFM32GG11B8xx in BGA192 Device Pinout

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PA15	A1	GPIO	PE15	A2	GPIO
PE14	A3	GPIO	PE13	A4	GPIO
PE12	A5	GPIO	PE11	A6	GPIO
PE10	A7	GPIO	PE9	A8	GPIO
PE8	A9	GPIO	PI9	A10	GPIO (5V)
PI6	A11	GPIO (5V)	PF14	A12	GPIO (5V)

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PD15	J2	GPIO (5V)	PC6	J12	GPIO
DECOPULE	J13	Decouple output for on-chip voltage regulator. An external decoupling capacitor is required at this pin.	PC0	K1	GPIO (5V)
PC1	K2	GPIO (5V)	PD8	K13	GPIO
PC2	L1	GPIO (5V)	PC3	L2	GPIO (5V)
PA7	L3	GPIO	PB9	L15	GPIO (5V)
PB10	L16	GPIO (5V)	PD0	L17	GPIO (5V)
PD1	L18	GPIO	PD4	L19	GPIO
PD7	L20	GPIO	PB7	M1	GPIO
PC4	M2	GPIO	PA8	M3	GPIO
PA10	M4	GPIO	PA13	M5	GPIO (5V)
PA14	M6	GPIO	RESETn	M7	Reset input, active low. To apply an external reset source to this pin, it is required to only drive this pin low during reset, and let the internal pull-up ensure that reset is released.
AVDD	M9 M10 N11	Analog power supply.	PD3	M12	GPIO
PD6	M13	GPIO	PB8	N1	GPIO
PC5	N2	GPIO	PA9	N3	GPIO
PA11	N4	GPIO	PA12	N5	GPIO (5V)
PB11	N6	GPIO	PB12	N7	GPIO
PB13	N9	GPIO	PB14	N10	GPIO
PD2	N12	GPIO (5V)	PD5	N13	GPIO

Note:

1. GPIO with 5V tolerance are indicated by (5V).
2. The pins PD13, PD14, and PD15 will not be 5V tolerant on all future devices. In order to preserve upgrade options with full hardware compatibility, do not use these pins with 5V domains.

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PB2	11	GPIO	PB3	12	GPIO
PB4	13	GPIO	PB5	14	GPIO
PB6	15	GPIO	VSS	16 32 59 83	Ground
PC0	18	GPIO (5V)	PC1	19	GPIO (5V)
PC2	20	GPIO (5V)	PC3	21	GPIO (5V)
PC4	22	GPIO	PC5	23	GPIO
PB7	24	GPIO	PB8	25	GPIO
PA7	26	GPIO	PA8	27	GPIO
PA9	28	GPIO	PA10	29	GPIO
PA11	30	GPIO	PA12	33	GPIO (5V)
PA13	34	GPIO (5V)	PA14	35	GPIO
RESETn	36	Reset input, active low. To apply an external reset source to this pin, it is required to only drive this pin low during reset, and let the internal pull-up ensure that reset is released.	PB9	37	GPIO (5V)
PB10	38	GPIO (5V)	PB11	39	GPIO
PB12	40	GPIO	AVDD	41	Analog power supply.
PB13	42	GPIO	PB14	43	GPIO
PD0	45	GPIO (5V)	PD1	46	GPIO
PD2	47	GPIO (5V)	PD3	48	GPIO
PD4	49	GPIO	PD5	50	GPIO
PD6	51	GPIO	PD7	52	GPIO
PD8	53	GPIO	PC7	54	GPIO
VREGVSS	55	Voltage regulator VSS	VREGSW	56	DCDC regulator switching node
VREGVDD	57	Voltage regulator VDD input	DVDD	58	Digital power supply.
DECOUPLE	60	Decouple output for on-chip voltage regulator. An external decoupling capacitor is required at this pin.	PE1	61	GPIO (5V)
PE2	62	GPIO	PE3	63	GPIO
PE4	64	GPIO	PE5	65	GPIO
PE6	66	GPIO	PE7	67	GPIO
PC8	68	GPIO (5V)	PC9	69	GPIO (5V)
PC10	70	GPIO (5V)	PC11	71	GPIO (5V)
VREGI	72	Input to 5 V regulator.	VREGO	73	Decoupling for 5 V regulator and regulator output. Power for USB PHY in USB-enabled OPNs
PF10	74	GPIO (5V)	PF11	75	GPIO (5V)
PF0	76	GPIO (5V)	PF1	77	GPIO (5V)

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PC4	13	GPIO	PC5	14	GPIO
PB7	15	GPIO	PB8	16	GPIO
PA8	17	GPIO	PA12	18	GPIO (5V)
PA14	19	GPIO	RESETn	20	Reset input, active low. To apply an external reset source to this pin, it is required to only drive this pin low during reset, and let the internal pull-up ensure that reset is released.
PB11	21	GPIO	PB12	22	GPIO
AVDD	24	Analog power supply.	PB13	25	GPIO
PB14	26	GPIO	PD0	28	GPIO (5V)
PD1	29	GPIO	PD2	30	GPIO (5V)
PD3	31	GPIO	PD4	32	GPIO
PD5	33	GPIO	PD6	34	GPIO
PD8	35	GPIO	VREGVSS	36	Voltage regulator VSS
VREGSW	37	DCDC regulator switching node	VREGVDD	38	Voltage regulator VDD input
DVDD	39	Digital power supply.	DECOPPLE	40	Decouple output for on-chip voltage regulator. An external decoupling capacitor is required at this pin.
PE4	41	GPIO	PE5	42	GPIO
PE6	43	GPIO	PE7	44	GPIO
VREGI	45	Input to 5 V regulator.	VREGO	46	Decoupling for 5 V regulator and regulator output. Power for USB PHY in USB-enabled OPNs
PF10	47	GPIO (5V)	PF11	48	GPIO (5V)
PF0	49	GPIO (5V)	PF1	50	GPIO (5V)
PF2	51	GPIO	VBUS	52	USB VBUS signal and auxiliary input to 5 V regulator.
PF12	53	GPIO	PF5	54	GPIO
PE8	57	GPIO	PE9	58	GPIO
PE10	59	GPIO	PE11	60	GPIO
PE12	61	GPIO	PE13	62	GPIO
PE14	63	GPIO	PE15	64	GPIO

Note:

1. GPIO with 5V tolerance are indicated by (5V).

Alternate	LOCATION		
Functionality	0 - 3	4 - 7	Description
EBI_CS1	0: PD10 1: PA11 2: PC1 3: PB1	4: PE9	External Bus Interface (EBI) Chip Select output 1.
EBI_CS2	0: PD11 1: PA12 2: PC2 3: PB2	4: PE10	External Bus Interface (EBI) Chip Select output 2.
EBI_CS3	0: PD12 1: PB15 2: PC3 3: PB3	4: PE11	External Bus Interface (EBI) Chip Select output 3.
EBI_CSTFT	0: PA7 1: PF6 2: PB12 3: PA0		External Bus Interface (EBI) Chip Select output TFT.
EBI_DCLK	0: PA8 1: PF7 2: PH0 3: PA1		External Bus Interface (EBI) TFT Dot Clock pin.
EBI_DTEN	0: PA9 1: PD9 2: PH1 3: PA2		External Bus Interface (EBI) TFT Data Enable pin.
EBI_HSNC	0: PA11 1: PD11 2: PH3 3: PA4		External Bus Interface (EBI) TFT Horizontal Synchronization pin.
EBI_NANDREn	0: PC3 1: PD15 2: PB9 3: PC4	4: PC15 5: PF12	External Bus Interface (EBI) NAND Read Enable output.
EBI_NANDWEn	0: PC5 1: PD14 2: PA13 3: PC2	4: PC14 5: PF11	External Bus Interface (EBI) NAND Write Enable output.
EBI_REn	0: PF5 1: PA14 2: PA12 3: PC0	4: PF9 5: PF5	External Bus Interface (EBI) Read Enable output.
EBI_VSNC	0: PA10 1: PD10 2: PH2 3: PA3		External Bus Interface (EBI) TFT Vertical Synchronization pin.
EBI_WEn	0: PF4 1: PA13 2: PC5 3: PB6	4: PF8 5: PF4	External Bus Interface (EBI) Write Enable output.
ETH_MDC	0: PB4 1: PD14 2: PC1 3: PA6		Ethernet Management Data Clock.

Table 5.24. ACMP1 Bus and Pin Mapping

	APORT4Y	APORT4X	APORT3Y	APORT3X	APORT2Y	APORT2X	APORT1Y	APORT1X	APORT0Y	APORT0X	Port
BUSDY	BUSDX	BUSCY	BUSCX	BUSBY	BUSBX	BUSAY	BUSAX	BUSACMP1Y	BUSACMP1X	BUS	CH31
PF15	PF15			PB15		PB15					CH30
PF14		PF14		PB14			PB14				CH29
PF12		PF12		PB12		PB13	PB13				CH28
PF10		PF11	PF13	PB10	PB11	PB11	PB12				CH27
PF8		PF9	PF9	PB9	PB9	PB9	PB10				CH26
PF6		PF7	PF7	PB6	PB6	PB6	PB6				CH25
PF4		PF5	PF5	PB4	PB4	PB5	PB5	PB4			CH24
PF2		PF3	PF3	PB2	PB2	PB3	PB3	PB2			CH23
PF0		PF1	PF1	PB0	PB0	PB1	PB1	PB0			CH22
PE14		PE15	PE15	PA14	PA14	PA15	PA15	PA14			CH20
PE12		PE13	PE13	PA12	PA12	PA13	PA13	PA12			CH19
PE10		PE11	PE11	PA10	PA10	PA11	PA11	PA10			CH18
PE8		PE9	PE9	PA8	PA8	PA9	PA9	PA8			CH17
PE6		PE7	PE7	PA6	PA6	PA5	PA5	PA6	PC14	PC14	CH16
PE4		PE5	PE5	PA4	PA4	PA3	PA3	PA4	PC13	PC13	CH15
				PA2		PA2		PA2	PC12	PC12	CH14
				PA1	PA1	PA1		PA1	PC11	PC11	CH13
				PA0	PA0			PA0	PC10	PC10	CH12
									PC9	PC9	CH11
									PC8	PC8	CH10

Table 5.27. ADC0 Bus and Pin Mapping

APORT4Y	APORT4X	APORT3Y	APORT3X	APORT2Y	APORT2X	APORT1Y	APORT1X	APORT0Y	APORT0X	Port
BUSDY	BUSDX	BUSCY	BUSCX	BUSBY	BUSBX	BUSA Y	BUSA X	BUSA DC0 Y	BUSA DC0 X	Bus
PF15	PF15			PF14	PB14	PB15	PB15			CH31
PF14	PF13	PF13		PF12	PB12	PB13	PB13	PB14		CH30
PF12	PF11	PF11		PF10	PB10	PF11	PB11	PB12		CH29
PF10	PF9	PF9		PF8	PB9	PF10	PB10	PB11		CH28
PF8	PF7	PF7		PF6	PB6	PF9	PB9	PB10		CH27
PF6	PF5	PF5		PF4	PB4	PF6	PB5	PB6		CH26
PF4	PF3	PF3		PF2	PB2	PF4	PB4	PB5		CH25
PF2	PF1	PF1		PF0	PB0	PF3	PB3	PB4		CH24
PF0	PE15	PE15		PE14	PA14	PF2	PB1	PB2		CH23
PE14	PE13	PE13		PE12	PA12	PE14	PA13	PA14		CH22
PE12	PE11	PE11		PE10	PA10	PE12	PA11	PA12		CH21
PE10	PE9	PE9		PE8	PA9	PE10	PA10	PA11		CH20
PE8	PE7	PE7		PE6	PA8	PE8	PA9	PA10		CH19
PE6	PE5	PE5		PE4	PA6	PE6	PA7	PA8		CH18
PE4					PA5	PE4	PA5	PA6		CH17
					PA4	PA4	PA4	PD6		CH16
					PA3	PA3	PA3	PD5		CH15
					PA2	PA2	PA2	PD4		CH14
					PA1	PA1	PA1	PD3		CH13
					PA0	PA0	PA0	PD2		CH12
								PD1		CH11
								PD0		CH10
										CH9
										CH8
										CH7
										CH6
										CH5
										CH4
										CH3
										CH2
										CH1
										CH0

Table 5.31. VDAC0 / OPA Bus and Pin Mapping

												Port
APORT4X	APORT3X	APORT2X	APORT1X	APORT4Y	APORT3Y	APORT2Y	APORT1Y					
OPA0_N												
OPA0_P												
BUSDX	BUSCX	BUSBX	BUSAX	BUSDY	BUSCY	BUSBY	BUSAY					
PF15		PB15		PF15				CH31				
PF13		PB13		PF14		PB14		CH30				
PF11		PB11		PF12		PB12		CH29				
PF10		PB10		PF10		PB10		CH28				
PF9		PB9		PF9		PB9		CH27				
PF8				PF8				CH26				
PF7				PF7				CH25				
PF6		PB6		PF6		PB6		CH24				
PF5		PF5		PF5		PF5		CH23				
PF4		PF4		PF4		PF4		CH22				
PF3		PF3		PF3		PF3		CH21				
PF2		PF2		PF2		PF2		CH20				
PF1		PF1		PF1		PF1		CH19				
PE0		PE0		PE0		PE0		CH18				
PE15		PA15		PE15		PE15		CH17				
PE13		PA13		PE14		PE14		CH16				
PE12		PA12		PE12		PE12		CH15				
PE11		PA11		PE11		PE11		CH14				
PE10		PA10		PE10		PE10		CH13				
PE9		PA9		PE9		PE9		CH12				
PE8		PA8		PE8		PE8		CH11				
PE7		PA7		PE7		PE7		CH10				
PE6		PA6		PE6		PE6		CH9				
PE5		PA5		PE5		PE5		CH8				
PE4		PA4		PE4		PE4		CH7				
PE3		PA3		PA3		PA3		CH6				
PE2		PA2		PA2		PA2		CH5				
PE1		PA1		PE1		PE1		CH4				
PE0		PA0		PE0		PE0		CH3				
								CH2				
								CH1				
								CH0				

7. BGA152 Package Specifications

7.1 BGA152 Package Dimensions

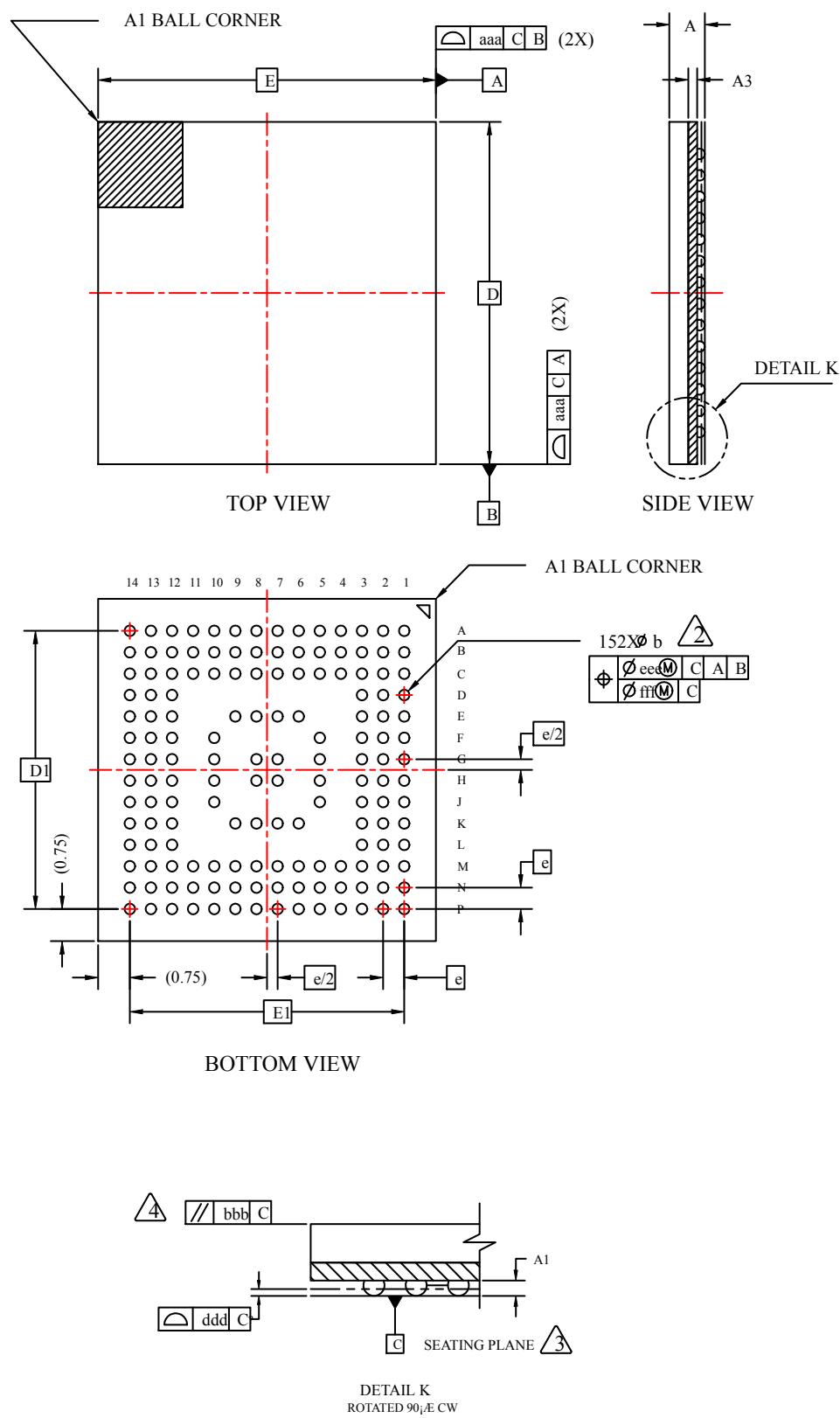


Figure 7.1. BGA152 Package Drawing