

Welcome to [E-XFL.COM](#)

#### What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

#### Applications of "[Embedded - Microcontrollers](#)"

##### Details

Product Status	Active
Core Processor	ARM® Cortex®-M4
Core Size	32-Bit Single-Core
Speed	72MHz
Connectivity	CANbus, EBI/EMI, Ethernet, I²C, IrDA, LINbus, MMC/SD/SDIO, QSPI, SmartCard, SPI, UART/USART, USB
Peripherals	Brown-out Detect/Reset, DMA, LCD, POR, PWM, WDT
Number of I/O	121
Program Memory Size	1MB (1M x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	512K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.8V
Data Converters	A/D 16x12b SAR; D/A 2x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	152-VFBGA
Supplier Device Package	152-BGA (8x8)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/silicon-labs/efm32gg11b840f1024il152-br">https://www.e-xfl.com/product-detail/silicon-labs/efm32gg11b840f1024il152-br</a>

## 1. Feature List

The EFM32GG11 highlighted features are listed below.

- **ARM Cortex-M4 CPU platform**
  - High performance 32-bit processor @ up to 72 MHz
  - DSP instruction support and Floating Point Unit
  - Memory Protection Unit
  - Wake-up Interrupt Controller
- **Flexible Energy Management System**
  - 80  $\mu$ A/MHz in Active Mode (EM0)
  - 2.1  $\mu$ A EM2 Deep Sleep current (16 kB RAM retention and RTCC running from LFRCO)
- **Integrated DC-DC buck converter**
- **Up to 2048 kB flash program memory**
  - Dual-bank with read-while-write support
- **Up to 512 kB RAM data memory**
  - 256 kB with ECC (SEC-DED)
- **Octal/Quad-SPI Flash Memory Interface**
  - Supports 3 V and 1.8 V memories
  - 1/2/4/8-bit data bus
  - Quad-SPI Execute In Place (XIP)
- **Communication Interfaces**
  - Low-energy Universal Serial Bus (USB) with Device and Host support
    - Fully USB 2.0 compliant
    - On-chip PHY and embedded 5V to 3.3V regulator
    - Crystal-free Device mode operation
    - Patent-pending Low-Energy Mode (LEM)
  - SD/MMC/SDIO Host Controller
    - SD v3.01, SDIO v3.0 and MMC v4.51
    - 1/4/8-bit bus width
  - 10/100 Ethernet MAC with MII/RMII interface
    - IEEE1588-2008 precision time stamping
    - Energy Efficient Ethernet (802.3az)
  - Up to 2x CAN Bus Controller
    - Version 2.0A and 2.0B up to 1 Mbps
  - 6x Universal Synchronous/Asynchronous Receiver/ Transmitter
    - UART/SPI/SmartCard (ISO 7816)/IrDA/I2S/LIN
    - Triple buffered full/half-duplex operation with flow control
    - Ultra high speed (36 MHz) operation on one instance
  - 2x Universal Asynchronous Receiver/ Transmitter
  - 2x Low Energy UART
    - Autonomous operation with DMA in Deep Sleep Mode
  - 3x I<sup>2</sup>C Interface with SMBus support
    - Address recognition in EM3 Stop Mode
- **Up to 144 General Purpose I/O Pins**
  - Configurable push-pull, open-drain, pull-up/down, input filter, drive strength
  - Configurable peripheral I/O locations
  - 5 V tolerance on select pins
  - Asynchronous external interrupts
  - Output state retention and wake-up from Shutoff Mode
- **Up to 24 Channel DMA Controller**
- **Up to 24 Channel Peripheral Reflex System (PRS) for autonomous inter-peripheral signaling**
- **External Bus Interface for up to 4x256 MB of external memory mapped space**
  - TFT Controller with Direct Drive
  - Per-pixel alpha-blending engine
- **Hardware Cryptography**
  - AES 128/256-bit keys
  - ECC B/K163, B/K233, P192, P224, P256
  - SHA-1 and SHA-2 (SHA-224 and SHA-256)
  - True Random Number Generator (TRNG)
- **Hardware CRC engine**
  - Single-cycle computation with 8/16/32-bit data and 16-bit (programmable)/32-bit (fixed) polynomial
- **Security Management Unit (SMU)**
  - Fine-grained access control for on-chip peripherals
- **Integrated Low-energy LCD Controller with up to 8x36 segments**
  - Voltage boost, contrast and autonomous animation
  - Patented low-energy LCD driver
- **Backup Power Domain**
  - RTCC and retention registers in a separate power domain, available down to energy mode EM4H
  - Operation from backup battery when main power absent/ insufficient
- **Ultra Low-Power Precision Analog Peripherals**
  - 2x 12-bit 1 Msamples/s Analog to Digital Converter (ADC)
    - On-chip temperature sensor
  - 2x 12-bit 500 ksamples/s Digital to Analog Converter (VDAC)
  - Digital to Analog Current Converter (IDAC)
  - Up to 4x Analog Comparator (ACMP)
  - Up to 4x Operational Amplifier (OPAMP)
  - Robust current-based capacitive sensing with up to 64 inputs and wake-on-touch (CSEN)
  - Up to 108 GPIO pins are analog-capable. Flexible analog peripheral-to-pin routing via Analog Port (APORT)
  - Supply Voltage Monitor

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Current consumption in EM0 mode with all peripherals disabled, DCDC in LP mode <sup>3</sup>	I <sub>ACTIVE_LPM</sub>	32 MHz HFRCO, CPU running while loop from flash	—	82	—	µA/MHz
		26 MHz HFRCO, CPU running while loop from flash	—	83	—	µA/MHz
		16 MHz HFRCO, CPU running while loop from flash	—	88	—	µA/MHz
		1 MHz HFRCO, CPU running while loop from flash	—	257	—	µA/MHz
Current consumption in EM0 mode with all peripherals disabled and voltage scaling enabled, DCDC in Low Noise CCM mode <sup>1</sup>	I <sub>ACTIVE_CCM_VS</sub>	19 MHz HFRCO, CPU running while loop from flash	—	117	—	µA/MHz
		1 MHz HFRCO, CPU running while loop from flash	—	1231	—	µA/MHz
Current consumption in EM0 mode with all peripherals disabled and voltage scaling enabled, DCDC in LP mode <sup>3</sup>	I <sub>ACTIVE_LPM_VS</sub>	19 MHz HFRCO, CPU running while loop from flash	—	72	—	µA/MHz
		1 MHz HFRCO, CPU running while loop from flash	—	219	—	µA/MHz
Current consumption in EM1 mode with all peripherals disabled, DCDC in Low Noise DCM mode <sup>2</sup>	I <sub>EM1_DCM</sub>	72 MHz HFRCO	—	42	—	µA/MHz
		50 MHz crystal	—	46	—	µA/MHz
		48 MHz HFRCO	—	46	—	µA/MHz
		32 MHz HFRCO	—	53	—	µA/MHz
		26 MHz HFRCO	—	57	—	µA/MHz
		16 MHz HFRCO	—	72	—	µA/MHz
		1 MHz HFRCO	—	663	—	µA/MHz
Current consumption in EM1 mode with all peripherals disabled, DCDC in Low Power mode <sup>3</sup>	I <sub>EM1_LPM</sub>	32 MHz HFRCO	—	42	—	µA/MHz
		26 MHz HFRCO	—	43	—	µA/MHz
		16 MHz HFRCO	—	48	—	µA/MHz
		1 MHz HFRCO	—	219	—	µA/MHz
Current consumption in EM1 mode with all peripherals disabled and voltage scaling enabled, DCDC in Low Noise DCM mode <sup>2</sup>	I <sub>EM1_DCM_VS</sub>	19 MHz HFRCO	—	60	—	µA/MHz
		1 MHz HFRCO	—	637	—	µA/MHz
Current consumption in EM1 mode with all peripherals disabled and voltage scaling enabled. DCDC in LP mode <sup>3</sup>	I <sub>EM1_LPM_VS</sub>	19 MHz HFRCO	—	39	—	µA/MHz
		1 MHz HFRCO	—	190	—	µA/MHz
Current consumption in EM2 mode, with voltage scaling enabled, DCDC in LP mode <sup>3</sup>	I <sub>EM2_VS</sub>	Full 512 kB RAM retention and RTCC running from LFXO	—	2.8	—	µA
		Full 512 kB RAM retention and RTCC running from LFRCO	—	3.1	—	µA
		16 kB (1 bank) RAM retention and RTCC running from LFRCO <sup>5</sup>	—	2.1	—	µA
Current consumption in EM3 mode, with voltage scaling enabled	I <sub>EM3_VS</sub>	Full 512 kB RAM retention and CRYOTIMER running from ULFR-CO	—	2.4	—	µA

## 4.1.12 General-Purpose I/O (GPIO)

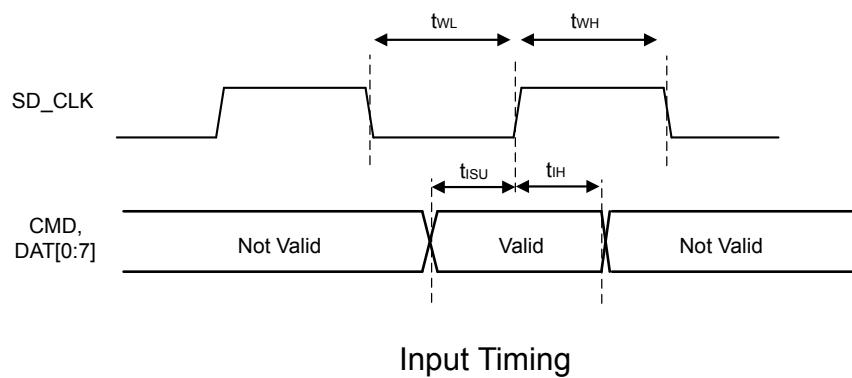
Table 4.20. General-Purpose I/O (GPIO)

Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Input low voltage	V <sub>IL</sub>	GPIO pins	—	—	IOVDD*0.3	V
Input high voltage	V <sub>IH</sub>	GPIO pins	IOVDD*0.7	—	—	V
Output high voltage relative to IOVDD	V <sub>OH</sub>	Sourcing 3 mA, IOVDD ≥ 3 V, DRIVESTRENGTH <sup>1</sup> = WEAK	IOVDD*0.8	—	—	V
		Sourcing 1.2 mA, IOVDD ≥ 1.62 V, DRIVESTRENGTH <sup>1</sup> = WEAK	IOVDD*0.6	—	—	V
		Sourcing 20 mA, IOVDD ≥ 3 V, DRIVESTRENGTH <sup>1</sup> = STRONG	IOVDD*0.8	—	—	V
		Sourcing 8 mA, IOVDD ≥ 1.62 V, DRIVESTRENGTH <sup>1</sup> = STRONG	IOVDD*0.6	—	—	V
Output low voltage relative to IOVDD	V <sub>OL</sub>	Sinking 3 mA, IOVDD ≥ 3 V, DRIVESTRENGTH <sup>1</sup> = WEAK	—	—	IOVDD*0.2	V
		Sinking 1.2 mA, IOVDD ≥ 1.62 V, DRIVESTRENGTH <sup>1</sup> = WEAK	—	—	IOVDD*0.4	V
		Sinking 20 mA, IOVDD ≥ 3 V, DRIVESTRENGTH <sup>1</sup> = STRONG	—	—	IOVDD*0.2	V
		Sinking 8 mA, IOVDD ≥ 1.62 V, DRIVESTRENGTH <sup>1</sup> = STRONG	—	—	IOVDD*0.4	V
Input leakage current	I <sub>IOLEAK</sub>	All GPIO except LFXO pins, GPIO ≤ IOVDD, T ≤ 85 °C	—	0.1	TBD	nA
		LFXO Pins, GPIO ≤ IOVDD, T ≤ 85 °C	—	0.1	TBD	nA
		All GPIO except LFXO pins, GPIO ≤ IOVDD, T > 85 °C	—	—	TBD	nA
		LFXO Pins, GPIO ≤ IOVDD, T > 85 °C	—	—	TBD	nA
Input leakage current on 5VTOL pads above IOVDD	I <sub>5VTOLLEAK</sub>	IOVDD < GPIO ≤ IOVDD + 2 V	—	3.3	TBD	µA
I/O pin pull-up/pull-down resistor	R <sub>PUD</sub>		TBD	40	TBD	kΩ
Pulse width of pulses removed by the glitch suppression filter	t <sub>IOGLITCH</sub>		15	25	35	ns

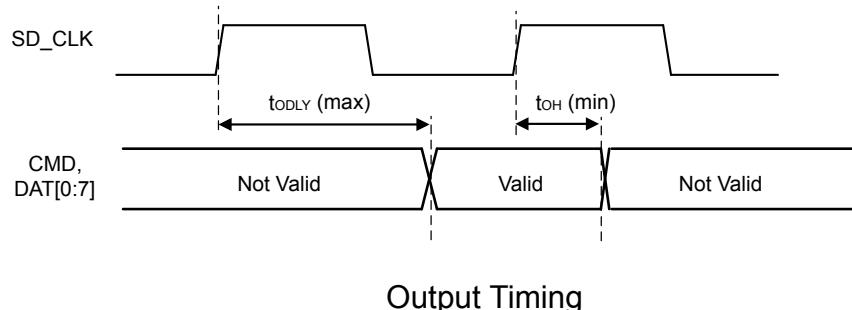
Parameter	Symbol	Test Condition	Min	Typ	Max	Unit
Start up time	t <sub>IDAC_SU</sub>	Output within 1% of steady state value	—	5	—	μs
Settling time, (output settled within 1% of steady state value),	t <sub>IDAC_SETTLE</sub>	Range setting is changed	—	5	—	μs
		Step value is changed	—	1	—	μs
Current consumption <sup>2</sup>	I <sub>IDAC</sub>	EM0 or EM1 Source mode, excluding output current, Across operating temperature range	—	11	TBD	μA
		EM0 or EM1 Sink mode, excluding output current, Across operating temperature range	—	13	TBD	μA
		EM2 or EM3 Source mode, excluding output current, T = 25 °C	—	0.05	—	μA
		EM2 or EM3 Sink mode, excluding output current, T = 25 °C	—	0.07	—	μA
		EM2 or EM3 Source mode, excluding output current, T ≥ 85 °C	—	11	—	μA
		EM2 or EM3 Sink mode, excluding output current, T ≥ 85 °C	—	13	—	μA
Output voltage compliance in source mode, source current change relative to current sourced at 0 V	I <sub>COMP_SRC</sub>	RANGESEL1=0, output voltage = min(V <sub>IOVDD</sub> , V <sub>AVDD</sub> <sup>2</sup> -100 mV)	—	0.11	—	%
		RANGESEL1=1, output voltage = min(V <sub>IOVDD</sub> , V <sub>AVDD</sub> <sup>2</sup> -100 mV)	—	0.06	—	%
		RANGESEL1=2, output voltage = min(V <sub>IOVDD</sub> , V <sub>AVDD</sub> <sup>2</sup> -150 mV)	—	0.04	—	%
		RANGESEL1=3, output voltage = min(V <sub>IOVDD</sub> , V <sub>AVDD</sub> <sup>2</sup> -250 mV)	—	0.03	—	%
Output voltage compliance in sink mode, sink current change relative to current sunk at IOVDD	I <sub>COMP_SINK</sub>	RANGESEL1=0, output voltage = 100 mV	—	0.29	—	%
		RANGESEL1=1, output voltage = 100 mV	—	0.27	—	%
		RANGESEL1=2, output voltage = 150 mV	—	0.12	—	%
		RANGESEL1=3, output voltage = 250 mV	—	0.03	—	%

**Note:**

1. In IDAC\_CURPROG register.
2. The IDAC is supplied by either AVDD, DVDD, or IOVDD based on the setting of ANASW in the EMU\_PWRCTRL register and PWRSEL in the IDAC\_CTRL register. Setting PWRSEL to 1 selects IOVDD. With PWRSEL cleared to 0, ANASW selects between AVDD (0) and DVDD (1).

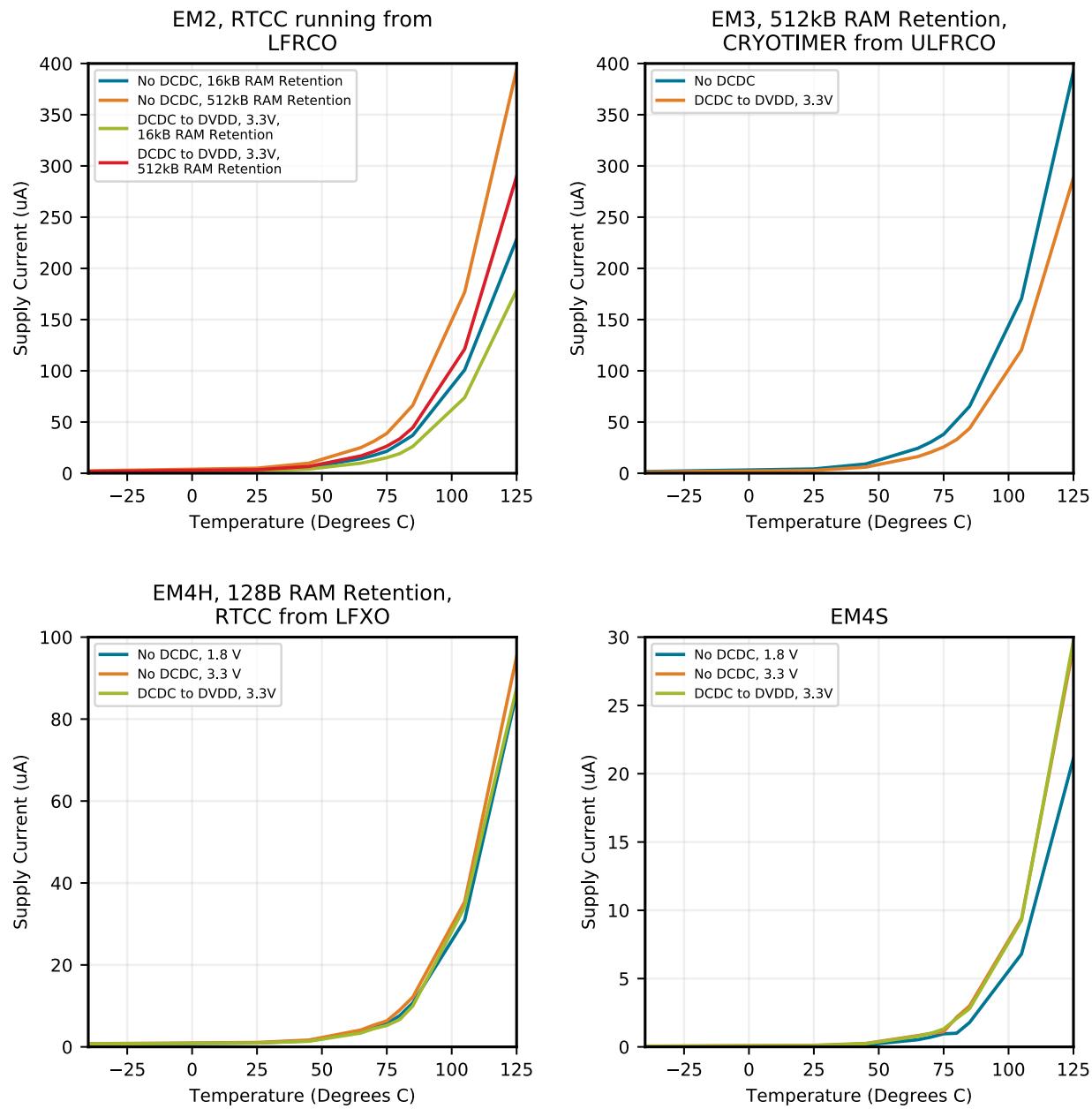


Input Timing



Output Timing

Figure 4.14. SDIO HS Mode Timing



**Figure 4.26. EM2, EM3, EM4H and EM4S Typical Supply Current vs. Temperature**

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PE8	B4	GPIO	PD11	B5	GPIO
PF8	B6	GPIO	PF6	B7	GPIO
VBUS	B8	USB VBUS signal and auxiliary input to 5 V regulator.	PE5	B9	GPIO
VREGI	B10	Input to 5 V regulator.	VREGO	B11	Decoupling for 5 V regulator and regulator output. Power for USB PHY in USB-enabled OPNs
PA1	C1	GPIO	PA0	C2	GPIO
PE10	C3	GPIO	PD13	C4	GPIO (5V)
PD12	C5	GPIO	PF9	C6	GPIO
VSS	C7 D4 F9 G3 G9 H6 K4 K7 K10 L7	Ground	PF2	C8	GPIO
PE6	C9	GPIO	PC10	C10	GPIO (5V)
PC11	C11	GPIO (5V)	PA3	D1	GPIO
PA2	D2	GPIO	PB15	D3	GPIO (5V)
IOVDD1	D5	Digital IO power supply 1.	PD9	D6	GPIO
IOVDD0	D7 G8 H7 L4	Digital IO power supply 0.	PF1	D8	GPIO (5V)
PE7	D9	GPIO	PC8	D10	GPIO (5V)
PC9	D11	GPIO (5V)	PA6	E1	GPIO
PA5	E2	GPIO	PA4	E3	GPIO
PB0	E4	GPIO	PF0	E8	GPIO (5V)
PE0	E9	GPIO (5V)	PE1	E10	GPIO (5V)
PE3	E11	GPIO	PB1	F1	GPIO
PB2	F2	GPIO	PB3	F3	GPIO
PB4	F4	GPIO	DVDD	F8	Digital power supply.
PE2	F10	GPIO	DECOPPLE	F11	Decouple output for on-chip voltage regulator. An external decoupling capacitor is required at this pin.
PB5	G1	GPIO	PB6	G2	GPIO
IOVDD2	G4	Digital IO power supply 2.	PC6	G10	GPIO
PC7	G11	GPIO	PC0	H1	GPIO (5V)
PC2	H2	GPIO (5V)	PD14	H3	GPIO (5V)
PA7	H4	GPIO	PA8	H5	GPIO

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PE8	B4	GPIO	PD11	B5	GPIO
PF8	B6	GPIO	PF6	B7	GPIO
PF3	B8	GPIO	PE5	B9	GPIO
PC12	B10	GPIO (5V)	PC13	B11	GPIO (5V)
PA1	C1	GPIO	PA0	C2	GPIO
PE10	C3	GPIO	PD13	C4	GPIO (5V)
PD12	C5	GPIO	PF9	C6	GPIO
VSS	C7 D4 F9 G3 G9 H6 K4 K7 K10 L7	Ground	PF2	C8	GPIO
PE6	C9	GPIO	PC10	C10	GPIO (5V)
PC11	C11	GPIO (5V)	PA3	D1	GPIO
PA2	D2	GPIO	PB15	D3	GPIO (5V)
IOVDD1	D5	Digital IO power supply 1.	PD9	D6	GPIO
IOVDD0	D7 G8 H7 L4	Digital IO power supply 0.	PF1	D8	GPIO (5V)
PE7	D9	GPIO	PC8	D10	GPIO (5V)
PC9	D11	GPIO (5V)	PA6	E1	GPIO
PA5	E2	GPIO	PA4	E3	GPIO
PB0	E4	GPIO	PF0	E8	GPIO (5V)
PE0	E9	GPIO (5V)	PE1	E10	GPIO (5V)
PE3	E11	GPIO	PB1	F1	GPIO
PB2	F2	GPIO	PB3	F3	GPIO
PB4	F4	GPIO	DVDD	F8	Digital power supply.
PE2	F10	GPIO	DECOPPLE	F11	Decouple output for on-chip voltage regulator. An external decoupling capacitor is required at this pin.
PB5	G1	GPIO	PB6	G2	GPIO
IOVDD2	G4	Digital IO power supply 2.	PC6	G10	GPIO
PC7	G11	GPIO	PC0	H1	GPIO (5V)
PC2	H2	GPIO (5V)	PD14	H3	GPIO (5V)
PA7	H4	GPIO	PA8	H5	GPIO
PD8	H8	GPIO	PD5	H9	GPIO
PD6	H10	GPIO	PD7	H11	GPIO

Pin Name	Pin(s)	Description	Pin Name	Pin(s)	Description
PF1	77	GPIO (5V)	PF2	78	GPIO
VBUS	79	USB VBUS signal and auxiliary input to 5 V regulator.	PF12	80	GPIO
PF5	81	GPIO	PF6	84	GPIO
PF7	85	GPIO	PF8	86	GPIO
PF9	87	GPIO	PD9	88	GPIO
PD10	89	GPIO	PD11	90	GPIO
PD12	91	GPIO	PE8	92	GPIO
PE9	93	GPIO	PE10	94	GPIO
PE11	95	GPIO	PE12	96	GPIO
PE13	97	GPIO	PE14	98	GPIO
PE15	99	GPIO	PA15	100	GPIO
<b>Note:</b>					
1. GPIO with 5V tolerance are indicated by (5V).					

GPIO Name	Pin Alternate Functionality / Description				
	Analog	EBI	Timers	Communication	Other
PB0	BUSBY BUSAX LCD_SEG32	EBI_AD00 #1 EBI_CS0 #3 EBI_A16 #0	TIM2_CDTI0 #0 TIM1_CC0 #2 TIM3_CC2 #7 WTIMO_CC0 #5 PCNT0_S0IN #5 PCNT1_S1IN #2	LEU1_TX #3	PRS_CH4 #1 ACMP0_O #5
PE0	BUSDY BUSCX	EBI_A00 #2 EBI_A07 #0	TIM3_CC0 #1 WTIM1_CC1 #3 PCNT0_S0IN #1	CAN0_RX #6 U0_TX #1 I2C1_SDA #2	PRS_CH22 #1 ACMP2_O #1
PC7	BUSACMP0Y BU-SACMP0X OPA3_N	EBI_A06 #0 EBI_A13 #1 EBI_A21 #3	WTIM1_CC0 #3	US0_CTS #2 US1_RTS #3 LEU1_RX #0 I2C0_SCL #2	LES_CH7 PRS_CH15 #1 ETM_TD0 #2
PB1	BUSAY BUSBX LCD_SEG33	EBI_AD01 #1 EBI_CS1 #3 EBI_A17 #0	TIM2_CDTI1 #0 TIM1_CC1 #2 WTIM0_CC1 #5 LETIM1_OUT1 #5 PCNT0_S1IN #5	ETH_MIICRS #0 US5_RX #2 LEU1_RX #3	PRS_CH5 #1
PB2	BUSBY BUSAX LCD_SEG34	EBI_AD02 #1 EBI_CS2 #3 EBI_A18 #0	TIM2_CDTI2 #0 TIM1_CC2 #2 WTIM0_CC2 #5 LETIM1_OUT0 #5	ETH_MIICOL #0 US1_CS #6	PRS_CH18 #0 ACMP0_O #6
PB3	BUSAY BUSBX LCD_SEG20 / LCD_COM4	EBI_AD03 #1 EBI_CS3 #3 EBI_A19 #0	TIM1_CC3 #2 WTIM0_CC0 #6 PCNT1_S0IN #1	ETH_MIICRS #2 ETH_MDIO #0 SDIO_DAT6 #1 US2_TX #1 US3_TX #2 QSPI0_DQ4 #1	PRS_CH19 #0 ACMP0_O #7
PC6	BUSACMP0Y BU-SACMP0X OPA3_P	EBI_A05 #0	WTIM1_CC3 #2	US0_RTS #2 US1_CTS #3 LEU1_TX #0 I2C0_SDA #2	LES_CH6 PRS_CH14 #1 ETM_TCLK #2
PB4	BUSBY BUSAX LCD_SEG21 / LCD_COM5	EBI_AD04 #1 EBI_ARDY #3 EBI_A20 #0	WTIM0_CC1 #6 PCNT1_S1IN #1	ETH_MIICOL #2 ETH_MDC #0 SDIO_DAT7 #1 US2_RX #1 QSPI0_DQ5 #1 LEU1_TX #4	PRS_CH20 #0
PB5	BUSAY BUSBX LCD_SEG22 / LCD_COM6	EBI_AD05 #1 EBI_ALE #3 EBI_A21 #0	WTIM0_CC2 #6 LETIM1_OUT0 #4 PCNT0_S0IN #6	ETH_TSUEXTCLK #0 US0_RTS #4 US2_CLK #1 QSPI0_DQ6 #1 LEU1_RX #4	PRS_CH21 #0
PB6	BUSBY BUSAX LCD_SEG23 / LCD_COM7	EBI_AD06 #1 EBI_WEn #3 EBI_A22 #0	TIM0_CC0 #3 TIM2_CC0 #4 WTIM3_CC0 #6 LETIM1_OUT1 #4 PCNT0_S1IN #6	ETH_TSUTMRTOG #0 US0_CTS #4 US2_CS #1 QSPI0_DQ7 #1	PRS_CH12 #1
PD5	BUSADC0Y BU-SADC0X OPA2_OUT	EBI_A09 #1 EBI_A18 #3	TIM6_CC1 #7 WTIM0_CDTI1 #4 WTIM1_CC3 #1 WTIM2_CC2 #5	US1_RTS #1 U0_CTS #5 LEU0_RX #0 I2C1_SCL #3	PRS_CH11 #2 ETM_TD3 #0 ETM_TD3 #2

Alternate	LOCATION		
Functionality	0 - 3	4 - 7	Description
EBI_A10	0: PE3 1: PD6 2: PC10 3: PB10		External Bus Interface (EBI) address output pin 10.
EBI_A11	0: PE4 1: PD7 2: PI6 3: PB11		External Bus Interface (EBI) address output pin 11.
EBI_A12	0: PE5 1: PD8 2: PI7 3: PB12		External Bus Interface (EBI) address output pin 12.
EBI_A13	0: PE6 1: PC7 2: PI8 3: PD0		External Bus Interface (EBI) address output pin 13.
EBI_A14	0: PE7 1: PE2 2: PI9 3: PD1		External Bus Interface (EBI) address output pin 14.
EBI_A15	0: PC8 1: PE3 2: PI10 3: PD2		External Bus Interface (EBI) address output pin 15.
EBI_A16	0: PB0 1: PE4 2: PH4 3: PD3		External Bus Interface (EBI) address output pin 16.
EBI_A17	0: PB1 1: PE5 2: PH5 3: PD4		External Bus Interface (EBI) address output pin 17.
EBI_A18	0: PB2 1: PE6 2: PH6 3: PD5		External Bus Interface (EBI) address output pin 18.
EBI_A19	0: PB3 1: PE7 2: PH7 3: PD6		External Bus Interface (EBI) address output pin 19.
EBI_A20	0: PB4 1: PC8 2: PH8 3: PD7		External Bus Interface (EBI) address output pin 20.
EBI_A21	0: PB5 1: PC9 2: PH9 3: PC7		External Bus Interface (EBI) address output pin 21.
EBI_A22	0: PB6 1: PC10 2: PH10 3: PE4		External Bus Interface (EBI) address output pin 22.

Alternate Functionality	Location	Priority
US2_CLK	4: PF8 5: PF2	High Speed High Speed
US2_CS	4: PF9 5: PF5	High Speed High Speed
US2_RX	4: PF7 5: PF1	High Speed High Speed
US2_TX	4: PF6 5: PF0	High Speed High Speed

## 5.22 Analog Port (APORT) Client Maps

The Analog Port (APORT) is an infrastructure used to connect chip pins with on-chip analog clients such as analog comparators, ADCs, DACs, etc. The APORT consists of a set of shared buses, switches, and control logic needed to configurally implement the signal routing. [Figure 5.20 APORT Connection Diagram on page 211](#) shows the APORT routing for this device family (note that available features may vary by part number). A complete description of APORT functionality can be found in the Reference Manual.

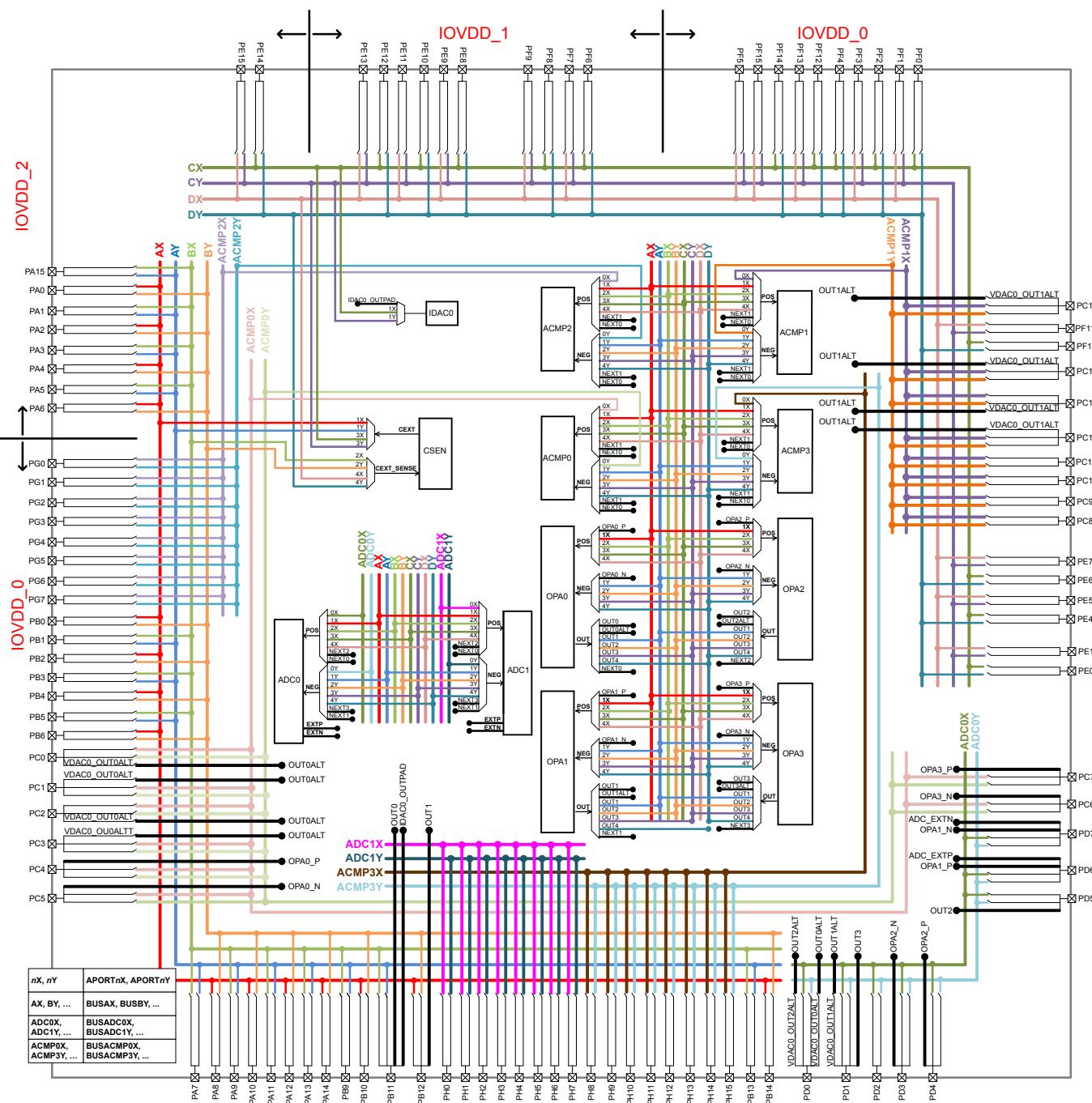


Figure 5.20. APORT Connection Diagram

Client maps for each analog circuit using the APORT are shown in the following tables. The maps are organized by bus, and show the peripheral's port connection, the shared bus, and the connection from specific bus channel numbers to GPIO pins.

In general, enumerations for the pin selection field in an analog peripheral's register can be determined by finding the desired pin connection in the table and then combining the value in the Port column (APORT<sub>\_\_</sub>), and the channel identifier (CH<sub>\_\_</sub>). For example, if pin PF7 is available on port APOR2X as CH23, the register field enumeration to connect to PF7 would be APOR2XCH23. The shared bus used by this connection is indicated in the Bus column.

Table 5.25. ACMP2 Bus and Pin Mapping

	APORT4Y	APORT4X	APORT3Y	APORT3X	APORT2Y	APORT2X	APORT1Y	APORT1X	APORT0Y	APORT0X	Port
BUSDY	BUSDX	BUSCY	BUSCX	BUSBY	BUSBX	BUSAY	BUSAX	BUSACMP2Y	BUSACMP2X	BUS	CH31
PF15	PF15			PB15		PB15					CH30
PF14		PF14		PB14			PB14				CH29
PF12		PF12		PB12		PB13	PB13				CH28
PF10		PF10		PB10		PB11	PB11				CH27
PF8		PF9	PF9		PB9	PB9	PB9				CH26
PF7		PF7	PF8								CH25
PF6		PF5	PF6	PB6	PB6	PB5	PB5	PB6			CH24
PF4		PF4	PF4	PB4	PB4	PB3	PB3	PB4			CH23
PF2		PF2	PF2	PB2	PB2	PB1	PB1	PB2			CH22
PF0		PF1	PF1	PB0	PB0	PA15	PA15	PB0			CH21
PE15	PE15	PE15	PE14	PA14	PA14	PA13	PA13	PA14			CH20
PE14	PE13	PE13	PE12	PA12	PA12	PA11	PA11	PA12			CH19
PE12	PE11	PE11	PE10	PA10	PA10	PA9	PA9	PA10			CH18
PE10	PE9	PE9	PE8	PA8	PA8	PA7	PA7	PA8			CH17
PE8		PE7	PE7								CH16
PE6		PE6	PE6	PA6	PA6	PA5	PA5	PA6	PG6	PG6	CH14
PE5		PE5				PA4	PA4	PA4	PG5	PG5	CH13
PE4			PE4			PA3	PA3	PA4	PG4	PG4	CH12
						PA2	PA2	PA2	PG3	PG3	CH11
PE1		PE1				PA1	PA1	PA1	PG2	PG2	CH10
PE0			PE0	PA0	PA0			PA0	PG1	PG1	CH9
									PG0	PG0	CH8
											CH7

					Port
<b>VDAC0_OUT1 / OPA1_OUT</b>					
APORT4Y	APORT3Y	APORT2Y	APORT1Y		Bus
BUSDY	BUSCY	BUSBY	BUSAY		CH31
	PF15		PB15		CH30
PF14		PB14			CH29
PF12	PF13		PB13		CH28
	PF11		PB11		CH27
PF10		PB10			CH26
	PF9		PB9		CH25
PF8					CH24
	PF7				CH23
PF6		PB6			CH22
	PF5		PB5		CH21
PF4		PB4			CH20
	PF3		PB3		CH19
PF2		PB2			CH18
	PF1		PB1		CH17
PF0		PB0			CH16
	PE15		PA15		CH15
PE14		PA14			CH14
	PE13		PA13		CH13
PE12		PA12			CH12
	PE11		PA11		CH11
PE10		PA10			CH10
	PE9		PA9		CH9
PE8		PA8			CH8
	PE7		PA7		CH7
PE6		PA6			CH6
	PE5		PA5		CH5
PE4		PA4			CH4
			PA3		CH3
			PA2		CH2
	PE1		PA1		CH1
PE0		PA0			CH0

## 6. BGA192 Package Specifications

### 6.1 BGA192 Package Dimensions

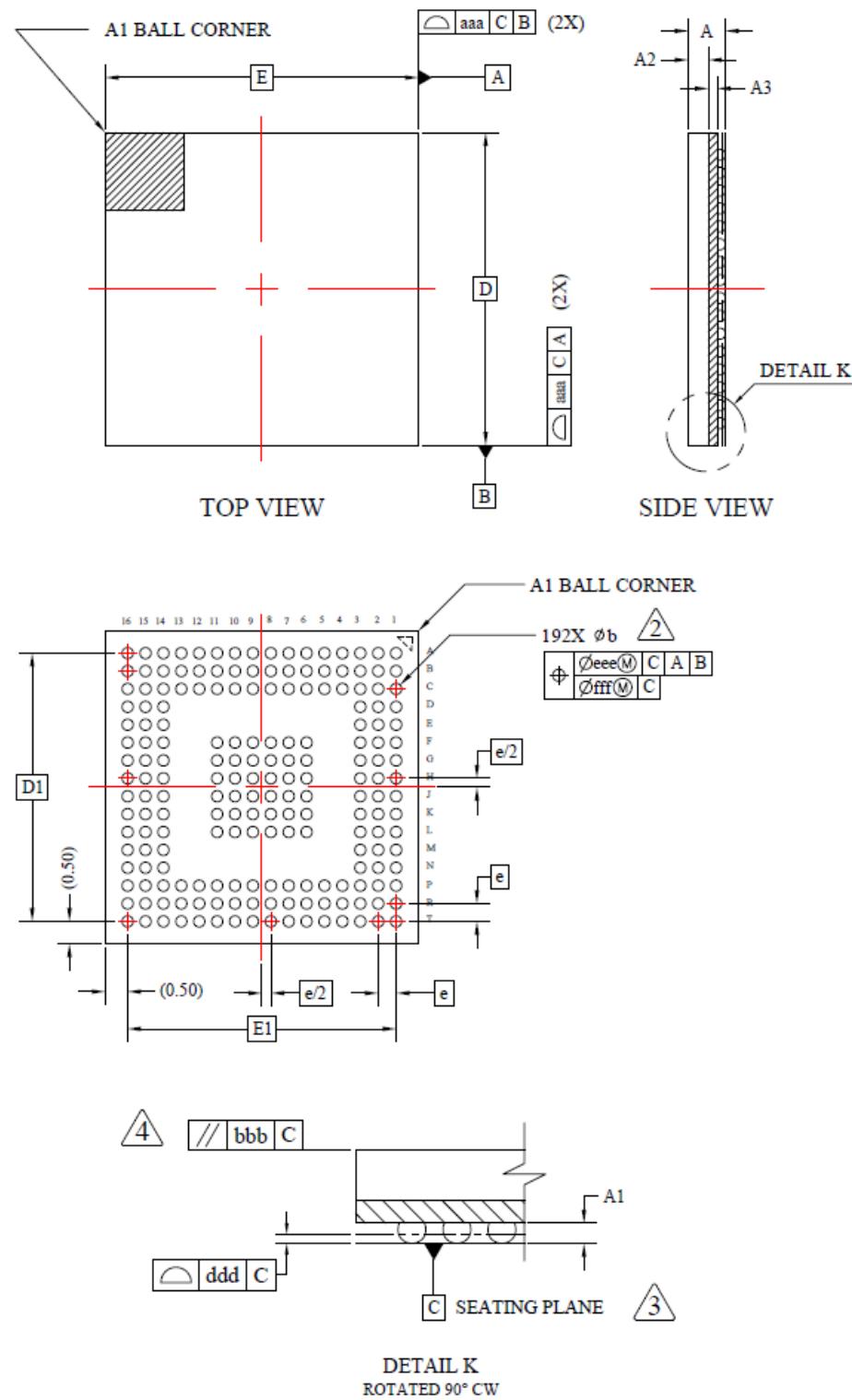


Figure 6.1. BGA192 Package Drawing

**Table 6.1. BGA192 Package Dimensions**

<b>Dimension</b>	<b>Min</b>	<b>Typ</b>	<b>Max</b>
A	0.77	0.83	0.89
A1	0.13	0.18	0.23
A3	0.16	0.20	0.24
A2		0.45 REF	
D		7.00 BSC	
e		0.40 BSC	
E		7.00 BSC	
D1		6.00 BSC	
E1		6.00 BSC	
b	0.20	0.25	0.30
aaa		0.10	
bbb		0.10	
ddd		0.08	
eee		0.15	
fff		0.05	
<b>Note:</b>			
1. All dimensions shown are in millimeters (mm) unless otherwise noted.			
2. Dimensioning and Tolerancing per ANSI Y14.5M-1994.			
3. Recommended card reflow profile is per the JEDEC/IPC J-STD-020 specification for Small Body Components.			

**Table 7.1. BGA152 Package Dimensions**

Dimension	Min	Typ	Max
A	0.78	0.84	0.90
A1	0.13	0.18	0.23
A3	0.16	0.20	0.24
A2		0.45 REF	
D		8.00 BSC	
e		0.50 BSC	
E		8.00 BSC	
D1		6.50 BSC	
E1		6.50 BSC	
b	0.20	0.25	0.30
aaa		0.10	
bbb		0.10	
ddd		0.08	
eee		0.15	
fff		0.05	

**Note:**

1. All dimensions shown are in millimeters (mm) unless otherwise noted.
2. Dimensioning and Tolerancing per ANSI Y14.5M-1994.
3. Recommended card reflow profile is per the JEDEC/IPC J-STD-020 specification for Small Body Components.

**Table 10.2. TQFP100 PCB Land Pattern Dimensions**

Dimension	Min	Nom	Max
C1		15.4	
C2		15.4	
E		0.50 BSC	
X		0.30	
Y		1.50	

**Note:**

1. All dimensions shown are in millimeters (mm) unless otherwise noted.
2. This Land Pattern Design is based on the IPC-7351 guidelines.
3. All metal pads are to be non-solder mask defined (NSMD). Clearance between the solder mask and the metal pad is to be 60 µm minimum, all the way around the pad.
4. A stainless steel, laser-cut and electro-polished stencil with trapezoidal walls should be used to assure good solder paste release.
5. The stencil thickness should be 0.125 mm (5 mils).
6. The ratio of stencil aperture to land pad size should be 1:1 for all perimeter pads.
7. A No-Clean, Type-3 solder paste is recommended.
8. The recommended card reflow profile is per the JEDEC/IPC J-STD-020C specification for Small Body Components.

**10.3 TQFP100 Package Marking****Figure 10.3. TQFP100 Package Marking**

The package marking consists of:

- PPPPPPPP – The part number designation.
- TTTTTT – A trace or manufacturing code. The first letter is the device revision.
- YY – The last 2 digits of the assembly year.
- WW – The 2-digit workweek when the device was assembled.

**Table 12.1. QFN64 Package Dimensions**

Dimension	Min	Typ	Max
A	0.70	0.75	0.80
A1	0.00	—	0.05
b	0.20	0.25	0.30
A3		0.203 REF	
D		9.00 BSC	
e		0.50 BSC	
E		9.00 BSC	
D2	7.10	7.20	7.30
E2	7.10	7.20	7.30
L	0.40	0.45	0.50
L1	0.00	—	0.10
aaa		0.10	
bbb		0.10	
ccc		0.10	
ddd		0.05	
eee		0.08	

**Note:**

1. All dimensions shown are in millimeters (mm) unless otherwise noted.
2. Dimensioning and Tolerancing per ANSI Y14.5M-1994.
3. Recommended card reflow profile is per the JEDEC/IPC J-STD-020 specification for Small Body Components.