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Applications of "[Embedded - Microcontrollers](#)"

Details

Product Status	Not For New Designs
Core Processor	M16C/60
Core Size	16-Bit
Speed	16MHz
Connectivity	I ² C, IEBus, UART/USART
Peripherals	DMA, POR, PWM, WDT
Number of I/O	85
Program Memory Size	192KB (192K x 8)
Program Memory Type	FLASH
EEPROM Size	4K x 8
RAM Size	6K x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 5.5V
Data Converters	A/D 18x10b
Oscillator Type	External
Operating Temperature	-20°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	100-LQFP
Supplier Device Package	100-LFQFP (14x14)
Purchase URL	https://www.e-xfl.com/product-detail/renesas-electronics-america/m30302fepgp-u5

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1. Overview

The M16C/30P Group of single-chip microcomputers is built using the high-performance silicon gate CMOS process using a M16C/60 Series CPU core and is packaged in a 100-pin plastic molded QFP.

These single-chip microcomputers operate using sophisticated instructions featuring a high level of instruction efficiency. With 1 Mbyte of address space, they are capable of executing instructions at high speed. In addition, these microcomputers contain a multiplier and DMAC which combined with fast instruction processing capability, make it suitable for control of various OA, communication, and industrial equipment which requires high-speed arithmetic/logic operations.

1.1 Applications

Audio, cameras, TV, home appliance, office/communications/portable/industrial equipment, etc.

1.2 Performance Outline

Table 1.1 lists Performance Outline of M16C/30P Group.

Table 1.1 Performance Outline of M16C/30P Group

Item		Performance
CPU	Number of Basic Instructions	91 instructions
	Minimum Instruction Execution Time	62.5ns(f(XIN)=16MHz, VCC1=VCC2=3.0 to 5.5V, no wait) 100ns(f(XIN)=10MHz, VCC1=VCC2=2.7 to 5.5V, no wait)
	Operation Mode	Single-chip, memory expansion and microprocessor mode
	Memory Space	1 Mbyte
	Memory Capacity	See Table 1.2 Product List
Peripheral Function	Port	Input/Output : 87 pins, Input : 1 pin
	Multifunction Timer	Timer A : 16 bits x 3 channels, Timer B : 16 bits x 3 channels
	Serial Interface	1 channels Clock synchronous, UART, I ² CBus ⁽¹⁾ , IEBus ⁽²⁾ 2 channels Clock synchronous, UART, I ² CBus ⁽¹⁾
	A/D Converter	10-bit A/D converter: 1 circuit, 18 channels
	DMAC	2 channels
	CRC Calculation Circuit	CCITT-CRC
	Watchdog Timer	15 bits x 1 channel (with prescaler)
	Interrupt	Internal: 20 sources, External: 7 sources, Software: 4 sources, Priority level: 7 levels
	Clock Generating Circuit	2 circuits Main clock generation circuit (*), Subclock generation circuit (*), (*)Equipped with a built-in feedback resistor.
Electric Characteristics	Supply Voltage	VCC1=VCC2=3.0 to 5.5 V (f(XIN)=16MHz) VCC1=VCC2=2.7 to 5.5 V (f(XIN)=10MHz, no wait)
	Power Consumption	10 mA (VCC1=VCC2=5V, f(XIN)=16MHz) 8 mA (VCC1=VCC2=3V, f(XIN)=10MHz) 1.8 μ A (VCC1=VCC2=3V, f(XCIN)=32kHz, wait mode) 0.7 μ A (VCC1=VCC2=3V, stop mode)
One time flash version	Program Supply Voltage	3.3 \pm 0.3 V or 5.0 \pm 0.5 V
Flash memory version	Program/Erase Supply Voltage	3.3 \pm 0.3 V or 5.0 \pm 0.5 V
	Program and Erase Endurance	100 times (all area)
Operating Ambient Temperature		-20 to 85°C, -40 to 85°C
Package		100-pin plastic mold QFP, LQFP

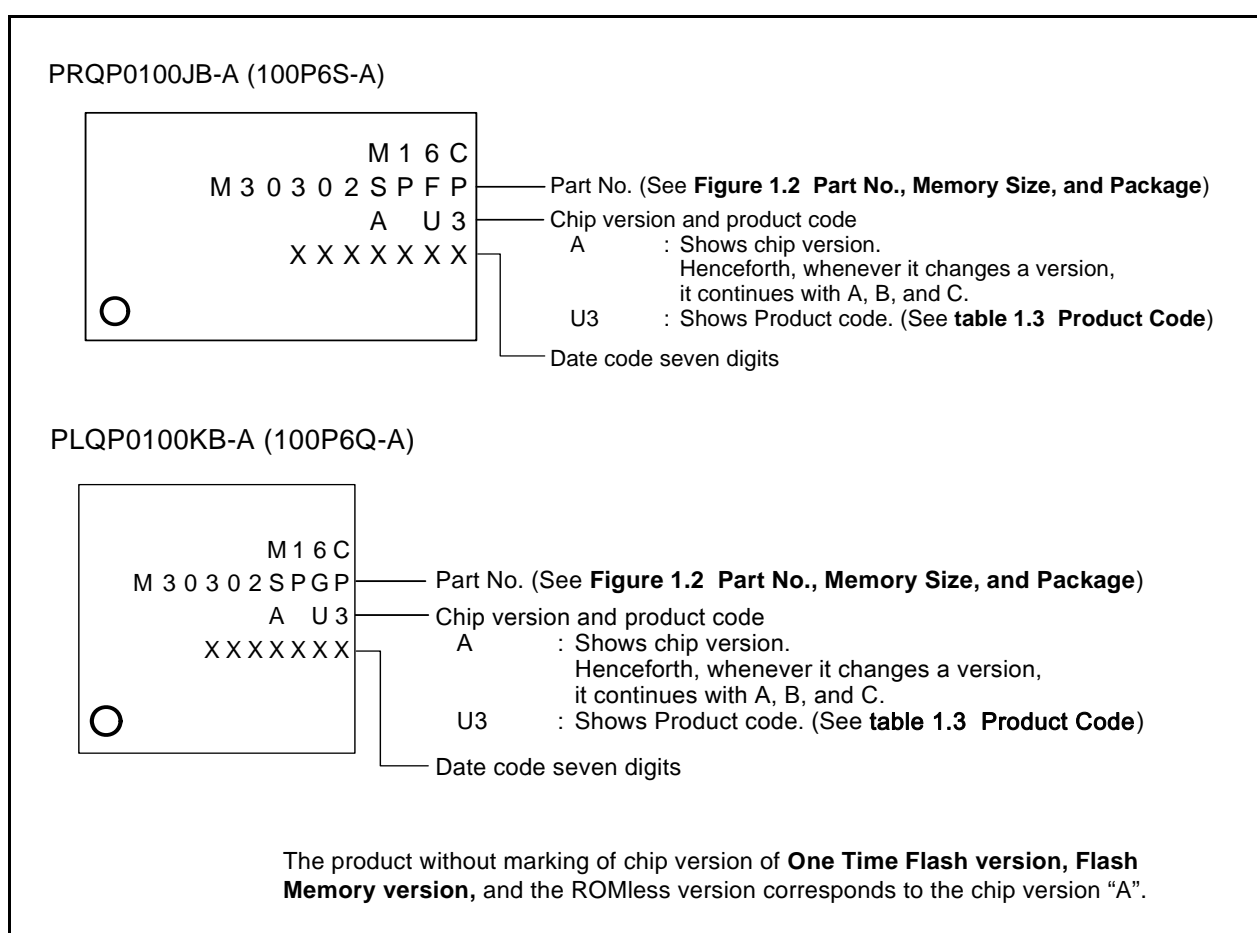
NOTES:

1. I²C bus is a registered trademark of Koninklijke Philips Electronics N. V.
2. IEBus is a registered trademark of NEC Electronics Corporation.
3. Use the M16C/30P on VCC1 = VCC2.

Table 1.5 Product Code of One Time Flash version, Flash Memory version, and ROM-less version for M16C/30P

	Product Code	Package	Internal ROM		Operating Ambient Temperature
			Program and Erase Endurance	Temperature Range	
One Time Flash version	U3	Lead-free	0	0°C to 60°C	-40°C to 85°C
	U5				-20°C to 85°C
Flash Memory version	U3	Lead-free	100	0°C to 60°C	-40°C to 85°C
	U5				-20°C to 85°C
ROM-less version	U3	Lead-free	—	—	-40°C to 85°C
	U5				-20°C to 85°C

NOTES: The one time flash version can be written once only.

**Figure 1.4 Marking Diagram of One Time Flash version, Flash Memory version, and ROM-less Version for M16C/30P (Top View)**

1.5 Pin Configuration

Figures 1.5 to 1.6 show the pin configurations (top view).

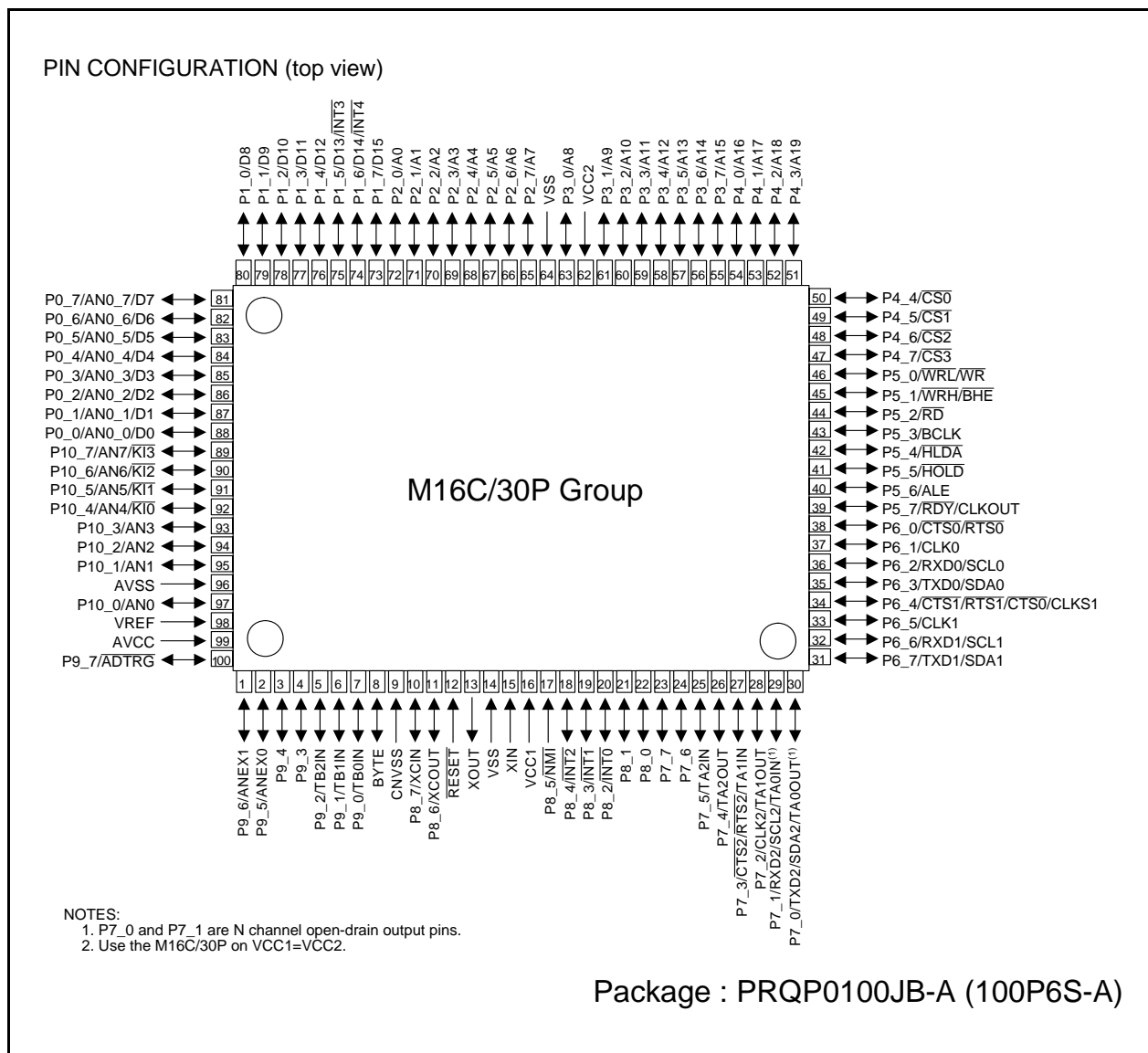


Figure 1.5 Pin Configuration (Top View)

Table 1.7 Pin Characteristics (2)

Pin No.		Control Pin	Port	Interrupt Pin	Timer Pin	UART Pin	Analog Pin	Bus Control Pin
FP	GP							
51	49		P4_3					A19
52	50		P4_2					A18
53	51		P4_1					A17
54	52		P4_0					A16
55	53		P3_7					A15
56	54		P3_6					A14
57	55		P3_5					A13
58	56		P3_4					A12
59	57		P3_3					A11
60	58		P3_2					A10
61	59		P3_1					A9
62	60	VCC2						
63	61		P3_0					A8
64	62	VSS						
65	63		P2_7					A7
66	64		P2_6					A6
67	65		P2_5					A5
68	66		P2_4					A4
69	67		P2_3					A3
70	68		P2_2					A2
71	69		P2_1					A1
72	70		P2_0					A0
73	71		P1_7					D15
74	72		P1_6	INT4				D14
75	73		P1_5	INT3				D13
76	74		P1_4					D12
77	75		P1_3					D11
78	76		P1_2					D10
79	77		P1_1					D9
80	78		P1_0					D8
81	79		P0_7				AN0_7	D7
82	80		P0_6				AN0_6	D6
83	81		P0_5				AN0_5	D5
84	82		P0_4				AN0_4	D4
85	83		P0_3				AN0_3	D3
86	84		P0_2				AN0_2	D2
87	85		P0_1				AN0_1	D1
88	86		P0_0				AN0_0	D0
89	87		P10_7	KI3			AN7	
90	88		P10_6	KI2			AN6	
91	89		P10_5	KI1			AN5	
92	90		P10_4	KI0			AN4	
93	91		P10_3				AN3	
94	92		P10_2				AN2	
95	93		P10_1				AN1	
96	94	AVSS						
97	95		P10_0				AN0	
98	96	VREF						
99	97	AVCC						
100	98		P9_7				ADTRG	

Table 1.9 Pin Description (2)

Signal Name	Pin Name	I/O Type	Description
Main clock input	XIN	I	I/O pins for the main clock generation circuit. Connect a ceramic resonator or crystal oscillator between XIN and XOUT. To use the external clock, input the clock from XIN and leave XOUT open.
Main clock output	XOUT	O	
Sub clock input	XCIN	I	I/O pins for a sub clock oscillation circuit. Connect a crystal oscillator between XCIN and XCOU. To use the external clock, input the clock from XCIN and leave XCOU open.
Sub clock output	XCOU	O	
Clock output	CLKOUT	O	The clock of the same cycle as fC, f8, or f32 is outputted.
INT interrupt input	INT0 to INT4	I	Input pins for the INT interrupt.
NMI interrupt input	NMI	I	Input pin for the NMI interrupt.
Key input interrupt input	KI0 to KI3	I	Input pins for the key input interrupt.
Timer A	TA0OUT to TA2OUT	I/O	These are timer A0 to timer A2 I/O pins. (however, the output of TA0OUT for the N-channel open drain output.)
	TA0IN to TA2IN	I	These are timer A0 to timer A2 input pins.
Timer B	TB0IN to TB2IN	I	These are timer B0 to timer B2 input pins.
Serial interface	CTS0 to CTS2	I	These are send control input pins.
	RTS0 to RTS2	O	These are receive control output pins.
	CLK0 to CLK2	I/O	These are transfer clock I/O pins.
	RXD0 to RXD2	I	These are serial data input pins.
	TXD0 to TXD2	O	These are serial data output pins. (however, TXD2 for the N-channel open drain output.)
	CLKS1	O	This is output pin for transfer clock output from multiple pins function.
I ² C mode	SDA0 to SDA2	I/O	These are serial data I/O pins. (however, SDA2 for the N-channel open drain output.)
	SCL0 to SCL2	I/O	These are transfer clock I/O pins. (however, SCL2 for the N-channel open drain output.)
Reference voltage input	VREF	I	Applies the reference voltage for the A/D converter.
A/D converter	AN0 to AN7, AN0_0 to AN0_7	I	Analog input pins for the A/D converter.
	ADTRG	I	This is an A/D trigger input pin.
	ANEX0	I/O	This is the extended analog input pin for the A/D converter, and is the output in external op-amp connection mode.
	ANEX1	I	This is the extended analog input pin for the A/D converter.
I/O port	P0_0 to P0_7, P1_0 to P1_7, P2_0 to P2_7, P3_0 to P3_7, P4_0 to P4_7, P5_0 to P5_7, P6_0 to P6_7, P7_0 to P7_7, P9_0 to P9_7, P10_0 to P10_7	I/O	8-bit I/O ports in CMOS, having a direction register to select an input or output. Each pin is set as an input port or output port. An input port can be set for a pull-up or for no pull-up in 4-bit unit by program. (however, P7_0 and P7_1 for the N-channel open drain output.)
	P8_0 to P8_4, P8_6, P8_7	I/O	I/O ports having equivalent functions to P0.
Input port	P8_5	I	Input pin for the NMI interrupt. Pin states can be read by the P8_5 bit in the P8 register.

I : Input O : Output I/O : Input and output

2.8.8 Stack Pointer Select Flag (U Flag)

ISP is selected when the U flag is “0”; USP is selected when the U flag is “1”.

The U flag is cleared to “0” when a hardware interrupt request is accepted or an INT instruction for software interrupt Nos. 0 to 31 is executed.

2.8.9 Processor Interrupt Priority Level (IPL)

IPL is configured with three bits, for specification of up to eight processor interrupt priority levels from level 0 to level 7.

If a requested interrupt has priority greater than IPL, the interrupt is enabled.

2.8.10 Reserved Area

When write to this bit, write “0”. When read, its content is indeterminate.

3. Memory

Figure 3.1 is a Memory Map of the M16C/30P group. The address space extends the 1 Mbyte from address 00000h to FFFFFh.

The internal ROM is allocated in a lower address direction beginning with address FFFFFh. For example, a 64-Kbyte internal ROM is allocated to the addresses from F0000h to FFFFFh.

The fixed interrupt vector table is allocated to the addresses from FFFDCh to FFFFFh. Therefore, store the start address of each interrupt routine here.

The internal RAM is allocated in an upper address direction beginning with address 00400h. For example, a 5-Kbyte internal RAM is allocated to the addresses from 00400h to 017FFh. In addition to storing data, the internal RAM also stores the stack used when calling subroutines and when interrupts are generated. The SFR is allocated to the addresses from 00000h to 003FFh. Peripheral function control registers are located here. Of the SFR, any area which has no functions allocated is reserved for future use and cannot be used by users.

The special page vector table is allocated to the addresses from FFE00h to FFFDBh. This vector is used by the JMPS or JSRS instruction. For details, refer to the **M16C/60 and M16C/20 Series Software Manual**.

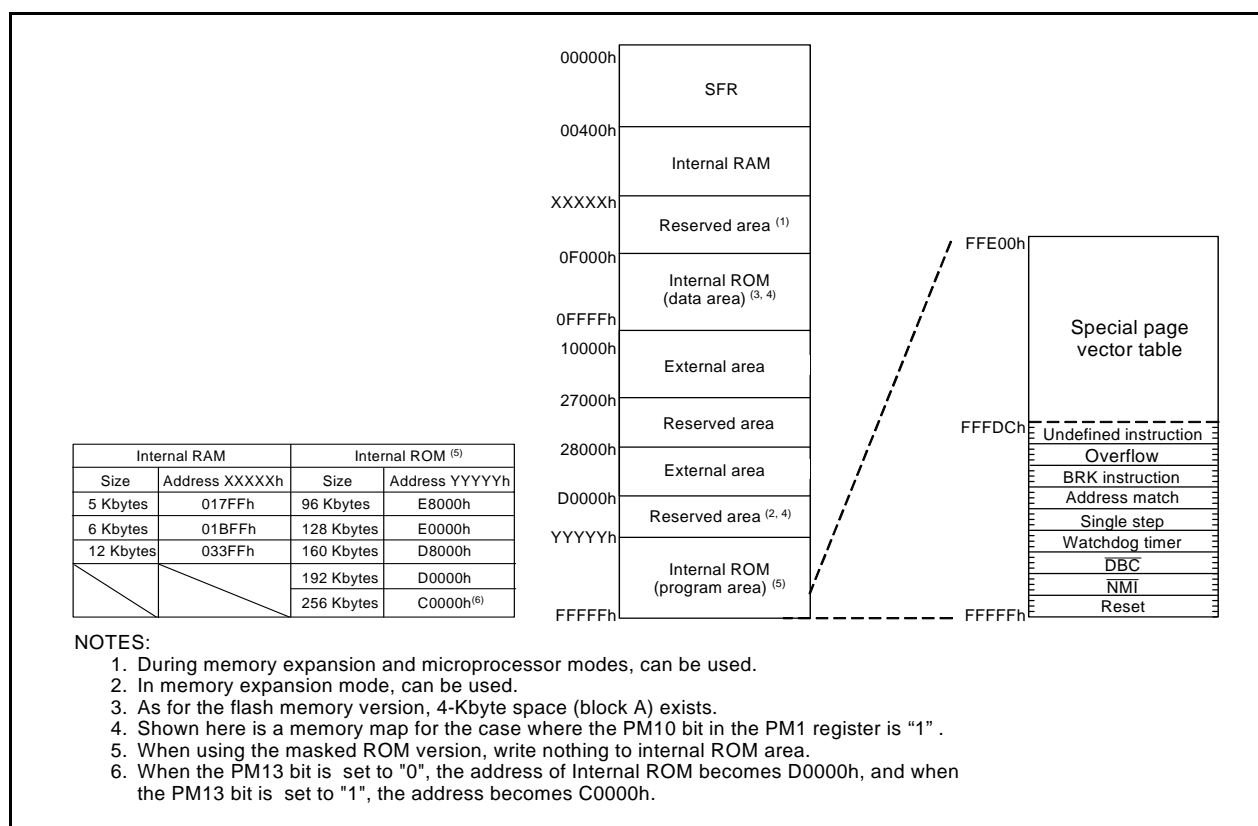


Figure 3.1 Memory Map

Table 5.3 A/D Conversion Characteristics (1)

Symbol	Parameter		Measuring Condition	Standard			Unit
				Min.	Typ.	Max.	
—	Resolution		VREF=VCC			10	Bits
INL	Integral Non-Linearity Error	10bit	VREF=VCC=5V AN0 to AN7 input, AN0_0 to AN0_7 input, ANEX0, ANEX1 input			±5	LSB
			VREF=VCC=3.3V AN0 to AN7 input, AN0_0 to AN0_7 input, ANEX0, ANEX1 input			±7	LSB
		8bit	VREF=VCC=5V, 3.3V			±2	LSB
—	Absolute Accuracy	10bit	VREF=VCC=5V AN0 to AN7 input, AN0_0 to AN0_7 input, ANEX0, ANEX1 input			±5	LSB
			VREF=VCC=3.3V AN0 to AN7 input, AN0_0 to AN0_7 input, ANEX0, ANEX1 input			±7	LSB
		8bit	VREF=VCC=5V, 3.3V			±2	LSB
—	Tolerance Level Impedance				3		kΩ
DNL	Differential Non-Linearity Error					±2	LSB
—	Offset Error					±5	LSB
—	Gain Error					±5	LSB
RLADDER	Ladder Resistance		VREF=VCC	10		40	kΩ
tCONV	10-bit Conversion Time, Sample & Hold Function Available		VREF=VCC=5V, φAD=10MHz	3.3			μs
tCONV	8-bit Conversion Time, Sample & Hold Function Available		VREF=VCC=5V, φAD=10MHz	2.8			μs
tsAMP	Sampling Time			0.3			μs
VREF	Reference Voltage			3.0		VCC	V
VIA	Analog Input Voltage			0		VREF	V

NOTES:

1. Referenced to VCC=AVCC=VREF=3.3 to 5.5V, VSS=AVSS=0V at T_{opr} = -20 to 85°C / -40 to 85°C unless otherwise specified.
2. φAD frequency must be 10 MHz or less.
3. When sample & hold function is disabled, φAD frequency must be 250 kHz or more, in addition to the limitation in Note 2.
4. When sample & hold function is enabled, φAD frequency must be 1MHz or more, in addition to the limitation in Note 2.

Table 5.4 Flash Memory Version Electrical Characteristics ⁽¹⁾

Symbol	Parameter		Standard			Unit
			Min.	Typ.	Max.	
—	Program and Erase Endurance ⁽²⁾		100 ⁽³⁾			cycle
—	Word Program Time (V _{CC1} =5.0V)			25	200	μs
—	Lock Bit Program Time			25	200	μs
—	Block Erase Time (V _{CC1} =5.0V)	4-Kbyte block		0.3	4	s
—		8-Kbyte block		0.3	4	s
—		32-Kbyte block		0.5	4	s
—		64-Kbyte block		0.8	4	s
t _{PS}	Flash Memory Circuit Stabilization Wait Time				15	μs
—	Data Hold Time ⁽⁴⁾		10			year

NOTES:

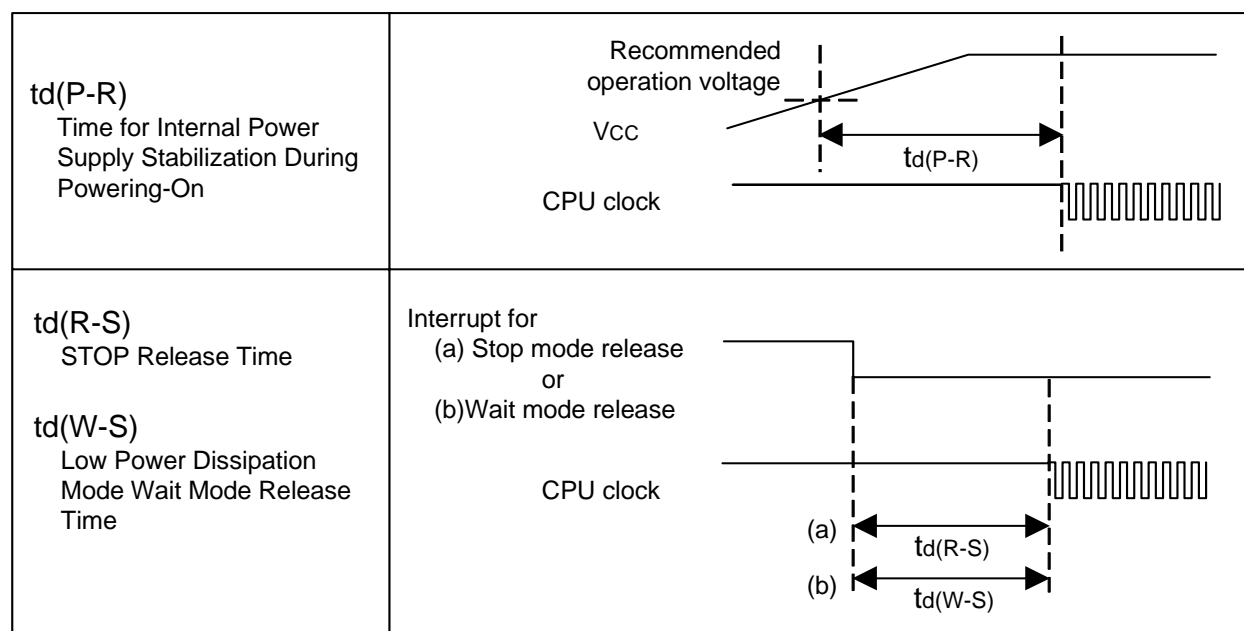
1. Referenced to V_{CC1}=4.5 to 5.5V, 3.0 to 3.6V at T_{opr} = 0 to 60 °C (U3, U5) unless otherwise specified.
2. Program and Erase Endurance refers to the number of times a block erase can be performed.
If the program and erase endurance is 100, each block can be erased 100 times.
For example, if a 4 Kbytes block A is erased after writing 1 word data 2,048 times, each to a different address, this counts as one program and erase endurance. Data cannot be written to the same address more than once without erasing the block.
(Rewrite prohibited)
3. Maximum number of E/W cycles for which operation is guaranteed.
4. T_{opr} = -40 to 85 °C (U3) / -20 to 85 °C (U5).

Table 5.5 Flash Memory Version Program / Erase Voltage and Read Operation Voltage Characteristics

Flash Program, Erase Voltage	Flash Read Operation Voltage
V _{CC1} = 3.3 ± 0.3 V or 5.0 ± 0.5 (T _{opr} = 0°C to 60°C)	V _{CC1} =2.7 to 5.5 V (T _{opr} = -40°C to 85°C (U3) -20°C to 85°C (U5))

Table 5.8 Power Supply Circuit Timing Characteristics

Symbol	Parameter	Measuring Condition	Standard			Unit
			Min.	Typ.	Max.	
$t_d(P-R)$	Time for Internal Power Supply Stabilization During Powering-On	$V_{CC}=2.7V$ to $5.5V$			2	ms
$t_d(R-S)$	STOP Release Time				1500	μs
$t_d(W-S)$	Low Power Dissipation Mode Wait Mode Release Time				1500	μs

**Figure 5.1 Power Supply Circuit Timing Diagram**

$$V_{CC1}=V_{CC2}=5V$$

Table 5.9 Electrical Characteristics(1) (1)

Symbol	Parameter		Measuring Condition	Standard			Unit
				Min.	Typ.	Max.	
VOH	HIGH Output Voltage	P0_0 to P0_7, P1_0 to P1_7, P2_0 to P2_7, P3_0 to P3_7, P4_0 to P4_7, P5_0 to P5_7, P6_0 to P6_7, P7_2 to P7_7, P8_0 to P8_4, P8_6, P8_7, P9_0 to P9_7, P10_0 to P10_7	IOH=−5mA	V _{CC} −2.0		V _{CC}	V
VOH	HIGH Output Voltage	P0_0 to P0_7, P1_0 to P1_7, P2_0 to P2_7, P3_0 to P3_7, P4_0 to P4_7, P5_0 to P5_7, P6_0 to P6_7, P7_2 to P7_7, P8_0 to P8_4, P8_6, P8_7, P9_0 to P9_7, P10_0 to P10_7	IOH=−200μA	V _{CC} −0.3		V _{CC}	V
VOH	HIGH Output Voltage XOUT	HIGHPOWER	IOH=−1mA	V _{CC} −2.0		V _{CC}	V
		LOWPOWER	IOH=−0.5mA	V _{CC} −2.0		V _{CC}	
	HIGH Output Voltage XCOUT	HIGHPOWER	With no load applied		2.5		V
		LOWPOWER	With no load applied		1.6		
VOL	LOW Output Voltage	P0_0 to P0_7, P1_0 to P1_7, P2_0 to P2_7, P3_0 to P3_7, P4_0 to P4_7, P5_0 to P5_7, P6_0 to P6_7, P7_0 to P7_7, P8_0 to P8_4, P8_6, P8_7, P9_0 to P9_7, P10_0 to P10_7	IOL=5mA			2.0	V
VOL	LOW Output Voltage	P0_0 to P0_7, P1_0 to P1_7, P2_0 to P2_7, P3_0 to P3_7, P4_0 to P4_7, P5_0 to P5_7, P6_0 to P6_7, P7_0 to P7_7, P8_0 to P8_4, P8_6, P8_7, P9_0 to P9_7, P10_0 to P10_7	IOL=200μA			0.45	V
VOL	LOW Output Voltage XOUT	HIGHPOWER	IOL=1mA			2.0	V
		LOWPOWER	IOL=0.5mA			2.0	
	LOW Output Voltage XCOUT	HIGHPOWER	With no load applied		0		V
		LOWPOWER	With no load applied		0		
VT+−VT−	Hysteresis	TA0IN to TA2IN, TB0IN to TB2IN, INT0 to INT4, NMI, ADTRG, CTS0 to CTS2, CLK0 to CLK2, TA0OUT to TA2OUT, KI0 to KI3, RXD0 to RXD2, SCL0 to SCL2, SDA0 to SDA2		0.2		1.0	V
VT+−VT−	Hysteresis	RESET		0.2		2.5	V
I _{IH}	HIGH Input Current	P0_0 to P0_7, P1_0 to P1_7, P2_0 to P2_7, P3_0 to P3_7, P4_0 to P4_7, P5_0 to P5_7, P6_0 to P6_7, P7_0 to P7_7, P8_0 to P8_7, P9_0 to P9_7, P10_0 to P10_7, XIN, RESET, CNVSS, BYTE	V _I =5V			5.0	μA
I _{IL}	LOW Input Current	P0_0 to P0_7, P1_0 to P1_7, P2_0 to P2_7, P3_0 to P3_7, P4_0 to P4_7, P5_0 to P5_7, P6_0 to P6_7, P7_0 to P7_7, P8_0 to P8_7, P9_0 to P9_7, P10_0 to P10_7, XIN, RESET, CNVSS, BYTE	V _I =0V			−5.0	μA
R _{PULLUP}	Pull-Up Resistance	P0_0 to P0_7, P1_0 to P1_7, P2_0 to P2_7, P3_0 to P3_7, P4_0 to P4_7, P5_0 to P5_7, P6_0 to P6_7, P7_0 to P7_7, P8_0 to P8_4, P8_6, P8_7, P9_0 to P9_7, P10_0 to P10_7	V _I =0V	30	50	170	kΩ
R _{FXIN}	Feedback Resistance	XIN			1.5		MΩ
R _{FXCIN}	Feedback Resistance	XCIN			15		MΩ
V _{RAM}	RAM Retention Voltage		At stop mode	2.0			V

NOTES:

1. Referenced to V_{CC1}=V_{CC2}=4.2 to 5.5V, V_{SS} = 0V at T_{opr} = −20 to 85°C / −40 to 85°C, f(XIN) = 16MHz unless otherwise specified.

$$V_{CC1}=V_{CC2}=5V$$

Timing Requirements

($V_{CC1} = V_{CC2} = 5V$, $V_{SS} = 0V$, at $T_{opr} = -20$ to $85^{\circ}C$ / -40 to $85^{\circ}C$ unless otherwise specified)

Table 5.13 Timer A Input (Counter Input in Event Counter Mode)

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(TA)}$	TAiN Input Cycle Time	100		ns
$t_{w(TAH)}$	TAiN Input HIGH Pulse Width	40		ns
$t_{w(TAL)}$	TAiN Input LOW Pulse Width	40		ns

Table 5.14 Timer A Input (Gating Input in Timer Mode)

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(TA)}$	TAiN Input Cycle Time	400		ns
$t_{w(TAH)}$	TAiN Input HIGH Pulse Width	200		ns
$t_{w(TAL)}$	TAiN Input LOW Pulse Width	200		ns

Table 5.15 Timer A Input (External Trigger Input in One-shot Timer Mode)

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(TA)}$	TAiN Input Cycle Time	200		ns
$t_{w(TAH)}$	TAiN Input HIGH Pulse Width	100		ns
$t_{w(TAL)}$	TAiN Input LOW Pulse Width	100		ns

Table 5.16 Timer A Input (External Trigger Input in Pulse Width Modulation Mode)

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{w(TAH)}$	TAiN Input HIGH Pulse Width	100		ns
$t_{w(TAL)}$	TAiN Input LOW Pulse Width	100		ns

Table 5.17 Timer A Input (Counter Increment/Decrement Input in Event Counter Mode)

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(UP)}$	TAiOUT Input Cycle Time	2000		ns
$t_{w(UPH)}$	TAiOUT Input HIGH Pulse Width	1000		ns
$t_{w(UPL)}$	TAiOUT Input LOW Pulse Width	1000		ns
$t_{su(UP-TIN)}$	TAiOUT Input Setup Time	400		ns
$t_{h(TIN-UP)}$	TAiOUT Input Hold Time	400		ns

Table 5.18 Timer A Input (Two-phase Pulse Input in Event Counter Mode)

Symbol	Parameter	Standard		Unit
		Min.	Max.	
$t_{c(TA)}$	TAiN Input Cycle Time	800		ns
$t_{su(TAIN-TAOUT)}$	TAiOUT Input Setup Time	200		ns
$t_{su(TAOUT-TAIN)}$	TAiN Input Setup Time	200		ns

$$V_{CC1}=V_{CC2}=5V$$

Switching Characteristics

($V_{CC1} = V_{CC2} = 5V$, $V_{SS} = 0V$, at $T_{opr} = -20$ to $85^{\circ}C$ / -40 to $85^{\circ}C$ unless otherwise specified)

Table 5.25 Memory Expansion and Microprocessor Modes (for setting with no wait)

Symbol	Parameter		Standard		Unit
			Min.	Max.	
$t_d(BCLK-AD)$	Address Output Delay Time	See Figure 5.2		25	ns
$t_h(BCLK-AD)$	Address Output Hold Time (in relation to BCLK)		-3		ns
$t_h(RD-AD)$	Address Output Hold Time (in relation to RD)		0		ns
$t_h(WR-AD)$	Address Output Hold Time (in relation to WR)		(NOTE 2)		ns
$t_d(BCLK-CS)$	Chip Select Output Delay Time			25	ns
$t_h(BCLK-CS)$	Chip Select Output Hold Time (in relation to BCLK)		-3		ns
$t_d(BCLK-ALE)$	ALE Signal Output Delay Time			15	ns
$t_h(BCLK-ALE)$	ALE Signal Output Hold Time		-4		ns
$t_d(BCLK-RD)$	RD Signal Output Delay Time			25	ns
$t_h(BCLK-RD)$	RD Signal Output Hold Time		0		ns
$t_d(BCLK-WR)$	WR Signal Output Delay Time			25	ns
$t_h(BCLK-WR)$	WR Signal Output Hold Time		0		ns
$t_d(BCLK-DB)$	Data Output Delay Time (in relation to BCLK)			40	ns
$t_h(BCLK-DB)$	Data Output Hold Time (in relation to BCLK) ⁽³⁾		4		ns
$t_d(DB-WR)$	Data Output Delay Time (in relation to WR)		(NOTE 1)		ns
$t_h(WR-DB)$	Data Output Hold Time (in relation to WR) ⁽³⁾		(NOTE 2)		ns
$t_d(BCLK-HLDA)$	HLDA Output Delay Time			40	ns

NOTES:

1. Calculated according to the BCLK frequency as follows:

$$\frac{0.5 \times 10^9}{f(BCLK)} - 40 [ns] \quad f(BCLK) \text{ is } 12.5MHz \text{ or less.}$$

2. Calculated according to the BCLK frequency as follows:

$$\frac{0.5 \times 10^9}{f(BCLK)} - 10 [ns]$$

3. This standard value shows the timing when the output is off, and does not show hold time of data bus.

Hold time of data bus varies with capacitor volume and pull-up (pull-down) resistance value.

Hold time of data bus is expressed in

$$t = -CR \times \ln(1 - V_{OL} / V_{CC1})$$

by a circuit of the right figure.

For example, when $V_{OL} = 0.2V_{CC1}$, $C = 30pF$, $R = 1k\Omega$, hold time of output "L" level is

$$t = -30pF \times 1k\Omega \times \ln(1 - 0.2V_{CC1} / V_{CC1}) = 6.7ns.$$

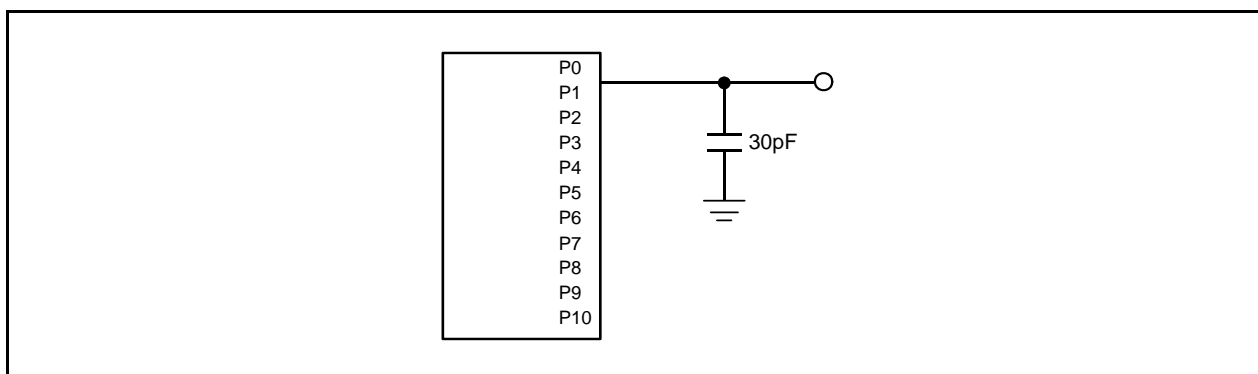
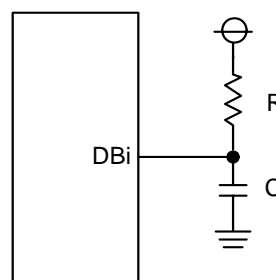


Figure 5.2 Ports P0 to P10 Measurement Circuit

$$V_{CC1}=V_{CC2}=5V$$

Switching Characteristics

($V_{CC1} = V_{CC2} = 5V$, $V_{SS} = 0V$, at $T_{opr} = -20$ to $85^{\circ}C$ / -40 to $85^{\circ}C$ unless otherwise specified)

Table 5.26 Memory Expansion and Microprocessor Modes (for 1 wait setting and external area access)

Symbol	Parameter		Standard		Unit
			Min.	Max.	
$t_d(BCLK-AD)$	Address Output Delay Time	See Figure 5.2		25	ns
$t_h(BCLK-AD)$	Address Output Hold Time (in relation to BCLK)		-3		ns
$t_h(RD-AD)$	Address Output Hold Time (in relation to RD)		0		ns
$t_h(WR-AD)$	Address Output Hold Time (in relation to WR)		(NOTE 2)		ns
$t_d(BCLK-CS)$	Chip Select Output Delay Time			25	ns
$t_h(BCLK-CS)$	Chip Select Output Hold Time (in relation to BCLK)		-3		ns
$t_d(BCLK-ALE)$	ALE Signal Output Delay Time			15	ns
$t_h(BCLK-ALE)$	ALE Signal Output Hold Time		-4		ns
$t_d(BCLK-RD)$	RD Signal Output Delay Time			25	ns
$t_h(BCLK-RD)$	RD Signal Output Hold Time		0		ns
$t_d(BCLK-WR)$	WR Signal Output Delay Time			25	ns
$t_h(BCLK-WR)$	WR Signal Output Hold Time		0		ns
$t_d(BCLK-DB)$	Data Output Delay Time (in relation to BCLK)			40	ns
$t_h(BCLK-DB)$	Data Output Hold Time (in relation to BCLK) ⁽³⁾		4		ns
$t_d(DB-WR)$	Data Output Delay Time (in relation to WR)		(NOTE 1)		ns
$t_h(WR-DB)$	Data Output Hold Time (in relation to WR) ⁽³⁾		(NOTE 2)		ns
$t_d(BCLK-HLDA)$	HLDA Output Delay Time			40	ns

NOTES:

1. Calculated according to the BCLK frequency as follows:

$$\frac{(n-0.5) \times 10^9}{f(BCLK)} - 40[ns] \quad n \text{ is "1" for 1-wait setting, } f(BCLK) \text{ is 12.5MHz or less.}$$

2. Calculated according to the BCLK frequency as follows:

$$\frac{0.5 \times 10^9}{f(BCLK)} - 10[ns]$$

3. This standard value shows the timing when the output is off, and does not show hold time of data bus.

Hold time of data bus varies with capacitor volume and pull-up (pull-down) resistance value.

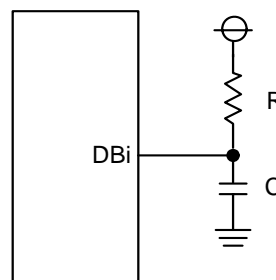
Hold time of data bus is expressed in

$$t = -CR \times \ln(1 - V_{OL} / V_{CC1})$$

by a circuit of the right figure.

For example, when $V_{OL} = 0.2V_{CC1}$, $C = 30pF$, $R = 1k\Omega$, hold time of output "L" level is

$$t = -30pF \times 1k\Omega \times \ln(1 - 0.2V_{CC1} / V_{CC1}) = 6.7ns.$$



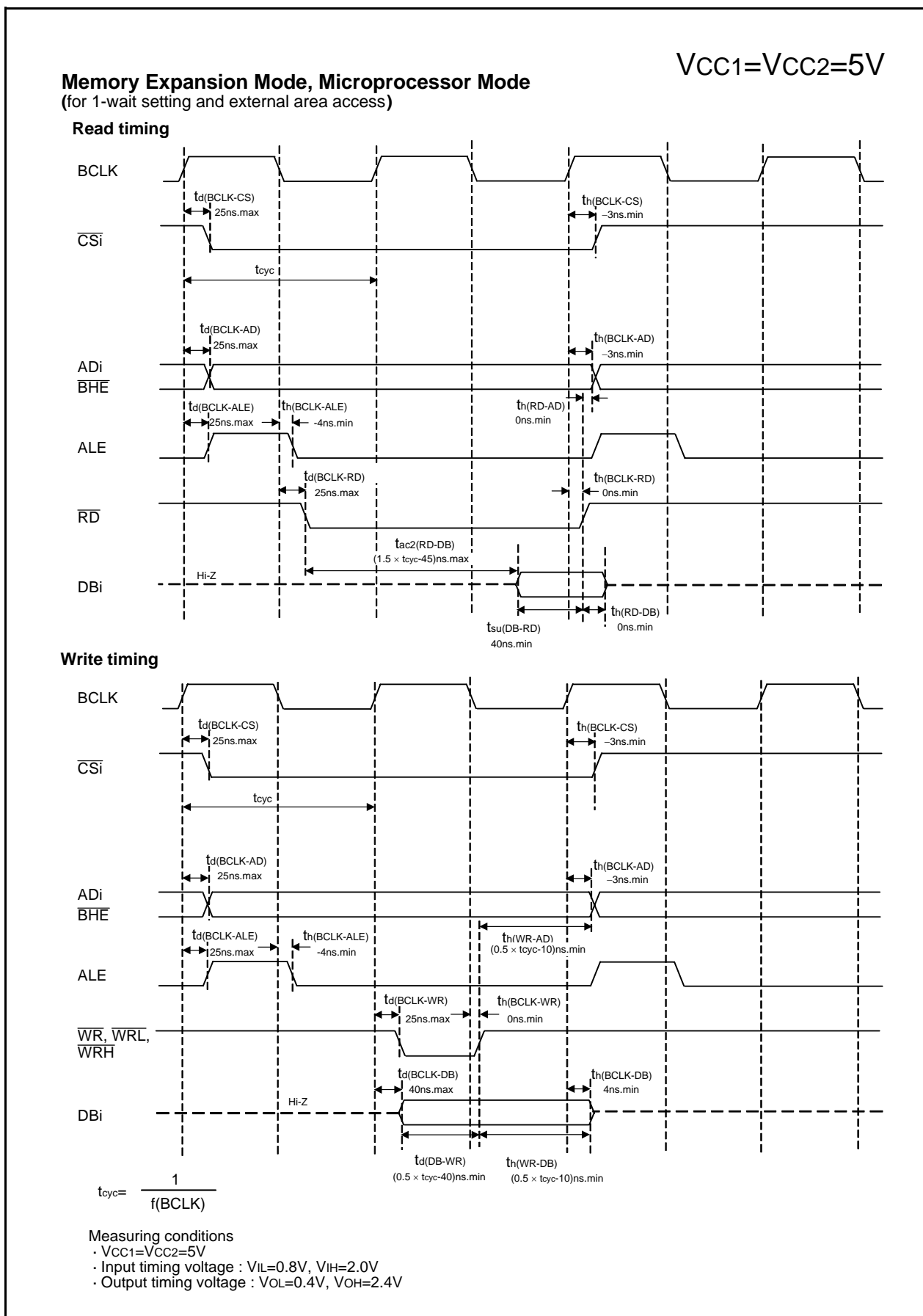


Figure 5.7 Timing Diagram (5)

$$V_{CC1}=V_{CC2}=3V$$

Switching Characteristics

($V_{CC1} = V_{CC2} = 3V$, $V_{SS} = 0V$, at $T_{opr} = -20$ to $85^{\circ}C$ / -40 to $85^{\circ}C$ unless otherwise specified)

Table 5.43 Memory Expansion and Microprocessor Modes (for setting with no wait)

Symbol	Parameter		Standard		Unit
			Min.	Max.	
$t_d(BCLK-AD)$	Address Output Delay Time	See Figure 5.8		30	ns
$t_h(BCLK-AD)$	Address Output Hold Time (in relation to BCLK)		0		ns
$t_h(RD-AD)$	Address Output Hold Time (in relation to RD)		0		ns
$t_h(WR-AD)$	Address Output Hold Time (in relation to WR)		(NOTE 2)		ns
$t_d(BCLK-CS)$	Chip Select Output Delay Time			30	ns
$t_h(BCLK-CS)$	Chip Select Output Hold Time (in relation to BCLK)		0		ns
$t_d(BCLK-ALE)$	ALE Signal Output Delay Time			25	ns
$t_h(BCLK-ALE)$	ALE Signal Output Hold Time		-4		ns
$t_d(BCLK-RD)$	RD Signal Output Delay Time			30	ns
$t_h(BCLK-RD)$	RD Signal Output Hold Time		0		ns
$t_d(BCLK-WR)$	WR Signal Output Delay Time			30	ns
$t_h(BCLK-WR)$	WR Signal Output Hold Time		0		ns
$t_d(BCLK-DB)$	Data Output Delay Time (in relation to BCLK)			40	ns
$t_h(BCLK-DB)$	Data Output Hold Time (in relation to BCLK) ⁽³⁾		4		ns
$t_d(DB-WR)$	Data Output Delay Time (in relation to WR)		(NOTE 1)		ns
$t_h(WR-DB)$	Data Output Hold Time (in relation to WR) ⁽³⁾		(NOTE 2)		ns
$t_d(BCLK-HLDA)$	HLDA Output Delay Time			40	ns

NOTES:

1. Calculated according to the BCLK frequency as follows:

$$\frac{0.5 \times 10^9}{f(BCLK)} - 40 [ns] \quad f(BCLK) \text{ is } 12.5MHz \text{ or less.}$$

2. Calculated according to the BCLK frequency as follows:

$$\frac{0.5 \times 10^9}{f(BCLK)} - 10 [ns]$$

3. This standard value shows the timing when the output is off, and does not show hold time of data bus.

Hold time of data bus varies with capacitor volume and pull-up (pull-down) resistance value.

Hold time of data bus is expressed in

$$t = -CR \times \ln(1 - V_{OL} / V_{CC1})$$

by a circuit of the right figure.

For example, when $V_{OL} = 0.2V_{CC1}$, $C = 30pF$, $R = 1k\Omega$, hold time of output "L" level is

$$t = -30pF \times 1k\Omega \times \ln(1 - 0.2V_{CC1} / V_{CC1}) = 6.7ns.$$

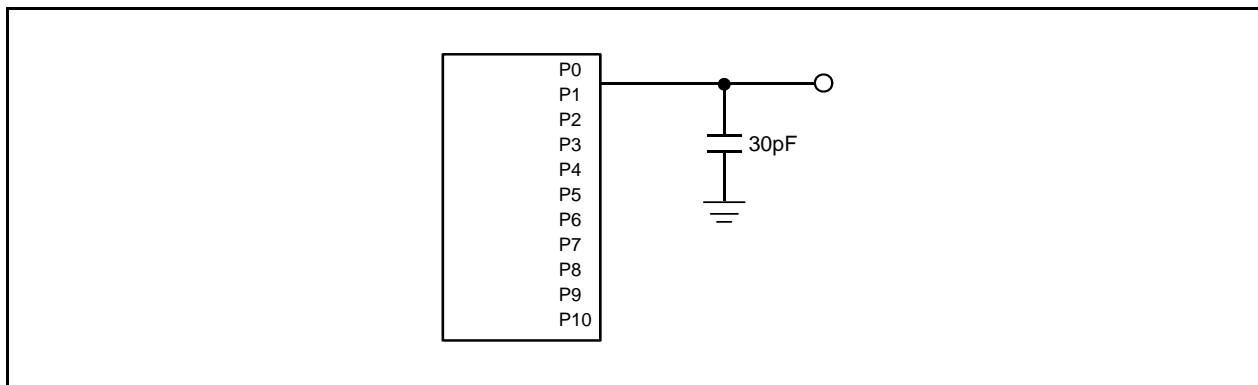
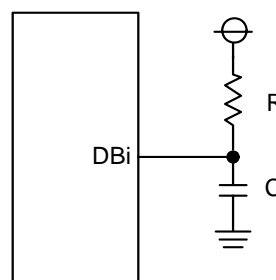


Figure 5.8 Ports P0 to P10 Measurement Circuit

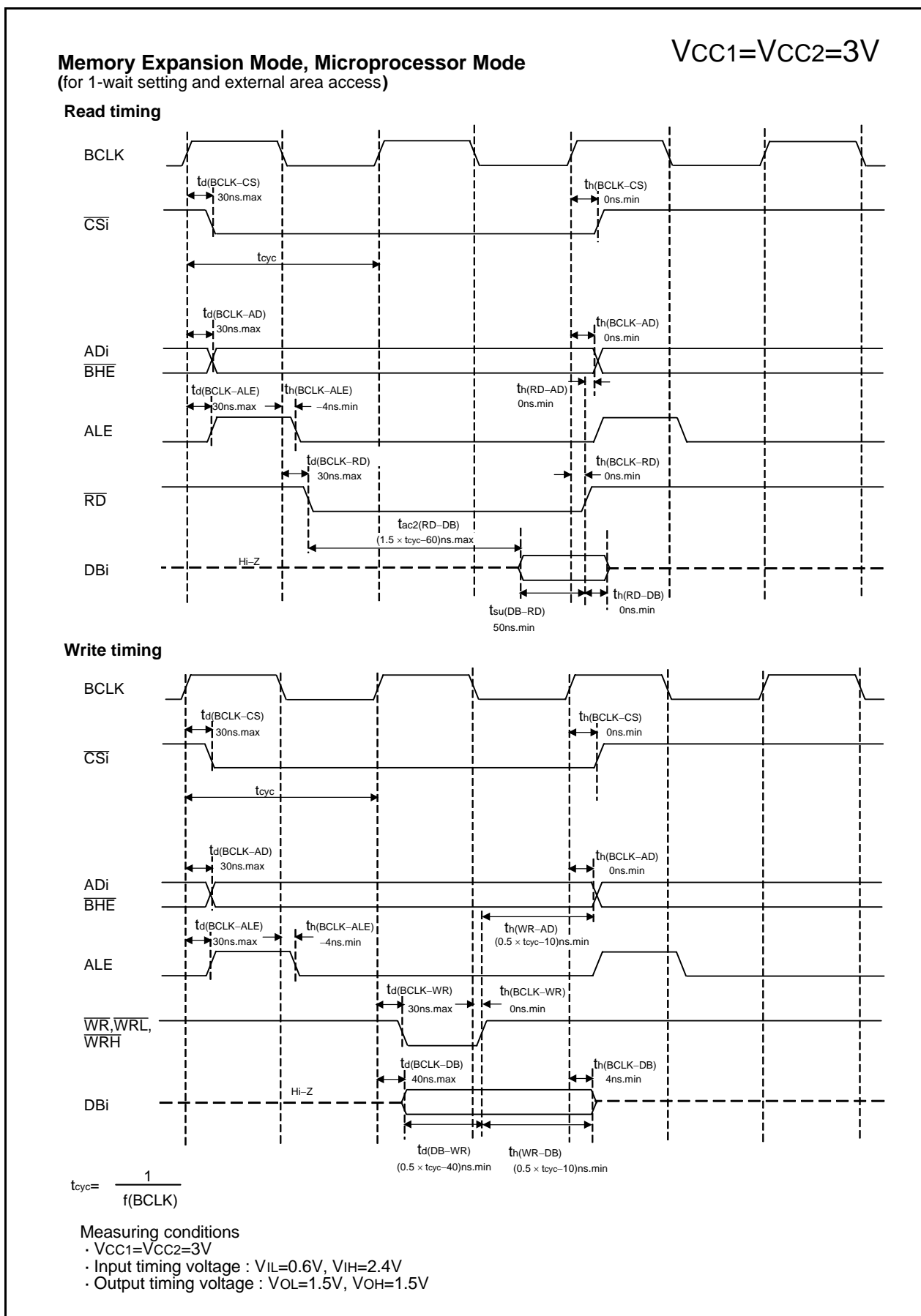


Figure 5.13 Timing Diagram (5)

Notes:

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