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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

#### Applications of "[Embedded - Microcontrollers](#)"

##### Details

Product Status	Active
Core Processor	STM8
Core Size	8-Bit
Speed	24MHz
Connectivity	I <sup>2</sup> C, IrDA, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	38
Program Memory Size	64KB (64K x 8)
Program Memory Type	FLASH
EEPROM Size	1.5K x 8
RAM Size	6K x 8
Voltage - Supply (Vcc/Vdd)	2.95V ~ 5.5V
Data Converters	A/D 10x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	48-LQFP
Supplier Device Package	48-LQFP (7x7)
Purchase URL	<a href="https://www.e-xfl.com/product-detail/stmicroelectronics/stm8s207c8t3">https://www.e-xfl.com/product-detail/stmicroelectronics/stm8s207c8t3</a>

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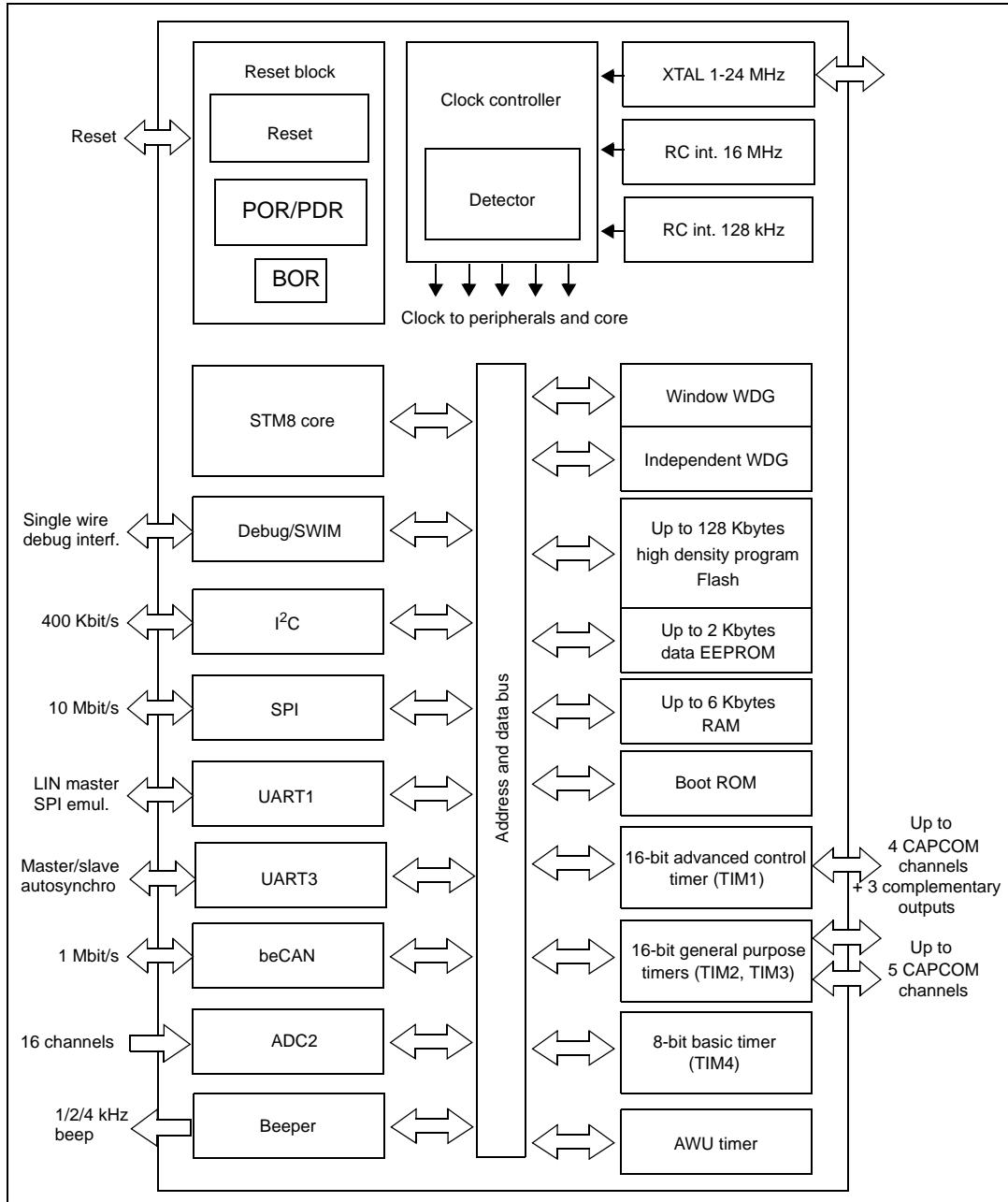
## 1 Introduction

This datasheet contains the description of the STM8S20xxx features, pinout, electrical characteristics, mechanical data and ordering information.

- For complete information on the STM8S microcontroller memory, registers and peripherals, please refer to the STM8S microcontroller family reference manual (RM0016).
- For information on programming, erasing and protection of the internal Flash memory please refer to the STM8S Flash programming manual (PM0051).
- For information on the debug and SWIM (single wire interface module) refer to the STM8 SWIM communication protocol and debug module user manual (UM0470).
- For information on the STM8 core, please refer to the STM8 CPU programming manual (PM0044).

### 3 Block diagram

Figure 1. STM8S20xxx block diagram



- Legend:
  - ADC: Analog-to-digital converter
  - beCAN: Controller area network
  - BOR: Brownout reset
  - I<sup>2</sup>C: Inter-integrated circuit multimaster interface
  - Independent WDG: Independent watchdog
  - POR/PDR: Power on reset / power down reset
  - SPI: Serial peripheral interface
  - SWIM: Single wire interface module
  - UART: Universal asynchronous receiver transmitter
  - Window WDG: Window watchdog

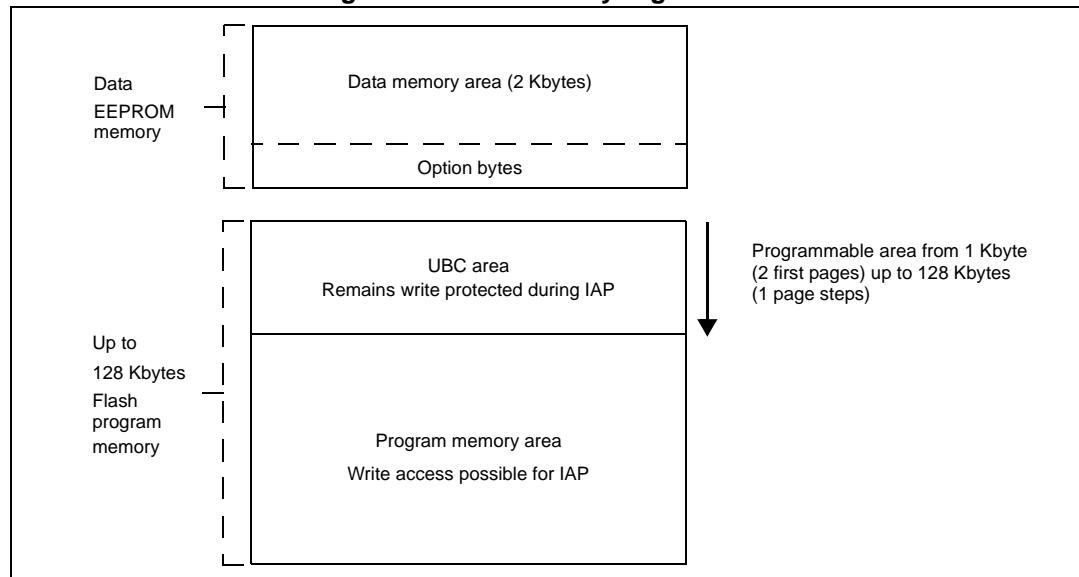
The size of the UBC is programmable through the UBC option byte ([Table 13](#)), in increments of 1 page (512 bytes) by programming the UBC option byte in ICP mode.

This divides the program memory into two areas:

- Main program memory: Up to 128 Kbytes minus UBC
- User-specific boot code (UBC): Configurable up to 128 Kbytes

The UBC area remains write-protected during in-application programming. This means that the MASS keys do not unlock the UBC area. It protects the memory used to store the boot program, specific code libraries, reset and interrupt vectors, the reset routine and usually the IAP and communication routines.

**Figure 2. Flash memory organization**



### Read-out protection (ROP)

The read-out protection blocks reading and writing the Flash program memory and data EEPROM memory in ICP mode (and debug mode). Once the read-out protection is activated, any attempt to toggle its status triggers a global erase of the program and data memory. Even if no protection can be considered as totally unbreakable, the feature provides a very high level of protection for a general purpose microcontroller.

## 4.6 Power management

For efficient power management, the application can be put in one of four different low-power modes. You can configure each mode to obtain the best compromise between lowest power consumption, fastest start-up time and available wakeup sources.

- **Wait mode:** In this mode, the CPU is stopped, but peripherals are kept running. The wakeup is performed by an internal or external interrupt or reset.
- **Active halt mode with regulator on:** In this mode, the CPU and peripheral clocks are stopped. An internal wakeup is generated at programmable intervals by the auto wake up unit (AWU). The main voltage regulator is kept powered on, so current consumption is higher than in active halt mode with regulator off, but the wakeup time is faster. Wakeup is triggered by the internal AWU interrupt, external interrupt or reset.
- **Active halt mode with regulator off:** This mode is the same as active halt with regulator on, except that the main voltage regulator is powered off, so the wake up time is slower.
- **Halt mode:** In this mode the microcontroller uses the least power. The CPU and peripheral clocks are stopped, the main voltage regulator is powered off. Wakeup is triggered by external event or reset.

## 4.7 Watchdog timers

The watchdog system is based on two independent timers providing maximum security to the applications.

Activation of the watchdog timers is controlled by option bytes or by software. Once activated, the watchdogs cannot be disabled by the user program without performing a reset.

### Window watchdog timer

The window watchdog is used to detect the occurrence of a software fault, usually generated by external interferences or by unexpected logical conditions, which cause the application program to abandon its normal sequence.

The window function can be used to trim the watchdog behavior to match the application perfectly.

The application software must refresh the counter before time-out and during a limited time window.

A reset is generated in two situations:

1. Timeout: At 16 MHz CPU clock the time-out period can be adjusted between 75 µs up to 64 ms.
2. Refresh out of window: The downcounter is refreshed before its value is lower than the one stored in the window register.

#### 4.14.4 I<sup>2</sup>C

- I<sup>2</sup>C master features:
  - Clock generation
  - Start and stop generation
- I<sup>2</sup>C slave features:
  - Programmable I<sup>2</sup>C address detection
  - Stop bit detection
- Generation and detection of 7-bit/10-bit addressing and general call
- Supports different communication speeds:
  - Standard speed (up to 100 kHz)
  - Fast speed (up to 400 kHz)

#### 4.14.5 beCAN

The beCAN controller (basic enhanced CAN), interfaces the CAN network and supports the CAN protocol version 2.0A and B. It has been designed to manage a high number of incoming messages efficiently with a minimum CPU load.

For safety-critical applications the beCAN controller provides all hardware functions to support the CAN time triggered communication option (TTCAN).

The maximum transmission speed is 1 Mbit.

##### Transmission

- Three transmit mailboxes
- Configurable transmit priority by identifier or order request
- Time stamp on SOF transmission

##### Reception

- 8-, 11- and 29-bit ID
- One receive FIFO (3 messages deep)
- Software-efficient mailbox mapping at a unique address space
- FMI (filter match index) stored with message
- Configurable FIFO overrun
- Time stamp on SOF reception
- Six filter banks, 2 x 32 bytes (scalable to 4 x 16-bit) each, enabling various masking configurations, such as 12 filters for 29-bit ID or 48 filters for 11-bit ID
- Filtering modes:
  - Mask mode permitting ID range filtering
  - ID list mode
- Time triggered communication option
  - Disable automatic retransmission mode
  - 16-bit free running timer
  - Configurable timer resolution
  - Time stamp sent in last two data bytes

Table 9. General hardware register map (continued)

Address	Block	Register label	Register name	Reset status
0x00 50CC	CLK	CLK_HSITRIMR	HSI clock calibration trimming register	0x00
0x00 50CD		CLK_SWIMCCR	SWIM clock control register	0bXXXX XXX0
0x00 50CE to 0x00 50D0	Reserved area (3 bytes)			
0x00 50D1	WWDG	WWDG_CR	WWDG control register	0x7F
0x00 50D2		WWDG_WR	WWDR window register	0x7F
0x00 50D3 to 0x00 50DF	Reserved area (13 bytes)			
0x00 50E0	IWDG	IWDG_KR	IWDG key register	0xXX <sup>(2)</sup>
0x00 50E1		IWDG_PR	IWDG prescaler register	0x00
0x00 50E2		IWDG_RLR	IWDG reload register	0xFF
0x00 50E3 to 0x00 50EF	Reserved area (13 bytes)			
0x00 50F0	AWU	AWU_CSR1	AWU control/status register 1	0x00
0x00 50F1		AWU_APR	AWU asynchronous prescaler buffer register	0x3F
0x00 50F2		AWU_TBR	AWU timebase selection register	0x00
0x00 50F3	BEEP	BEEP_CSR	BEEP control/status register	0x1F
0x00 50F4 to 0x00 50FF	Reserved area (12 bytes)			
0x00 5200	SPI	SPI_CR1	SPI control register 1	0x00
0x00 5201		SPI_CR2	SPI control register 2	0x00
0x00 5202		SPI_ICR	SPI interrupt control register	0x00
0x00 5203		SPI_SR	SPI status register	0x02
0x00 5204		SPI_DR	SPI data register	0x00
0x00 5205		SPI_CRCPR	SPI CRC polynomial register	0x07
0x00 5206		SPI_RXCRCR	SPI Rx CRC register	0xFF
0x00 5207		SPI_TXCRCR	SPI Tx CRC register	0xFF
0x00 5208 to 0x00 520F	Reserved area (8 bytes)			
0x00 5210	I <sup>2</sup> C	I <sup>2</sup> C_CR1	I <sup>2</sup> C control register 1	0x00
0x00 5211		I <sup>2</sup> C_CR2	I <sup>2</sup> C control register 2	0x00
0x00 5212		I <sup>2</sup> C_FREQR	I <sup>2</sup> C frequency register	0x00
0x00 5213		I <sup>2</sup> C_OARL	I <sup>2</sup> C own address register low	0x00
0x00 5214		I <sup>2</sup> C_OARH	I <sup>2</sup> C own address register high	0x00
0x00 5215		Reserved		

Table 9. General hardware register map (continued)

Address	Block	Register label	Register name	Reset status
0x00 5216	I <sup>2</sup> C	I2C_DR	I <sup>2</sup> C data register	0x00
0x00 5217		I2C_SR1	I <sup>2</sup> C status register 1	0x00
0x00 5218		I2C_SR2	I <sup>2</sup> C status register 2	0x00
0x00 5219		I2C_SR3	I <sup>2</sup> C status register 3	0x00
0x00 521A		I2C_ITR	I <sup>2</sup> C interrupt control register	0x00
0x00 521B		I2C_CCRL	I <sup>2</sup> C clock control register low	0x00
0x00 521C		I2C_CCRH	I <sup>2</sup> C clock control register high	0x00
0x00 521D		I2C_TRISER	I <sup>2</sup> C TRISE register	0x02
0x00 521E to 0x00 522F		Reserved area (18 bytes)		
0x00 5230	UART1	UART1_SR	UART1 status register	0xC0
0x00 5231		UART1_DR	UART1 data register	0XX
0x00 5232		UART1_BRR1	UART1 baud rate register 1	0x00
0x00 5233		UART1_BRR2	UART1 baud rate register 2	0x00
0x00 5234		UART1_CR1	UART1 control register 1	0x00
0x00 5235		UART1_CR2	UART1 control register 2	0x00
0x00 5236		UART1_CR3	UART1 control register 3	0x00
0x00 5237		UART1_CR4	UART1 control register 4	0x00
0x00 5238		UART1_CR5	UART1 control register 5	0x00
0x00 5239		UART1_GTR	UART1 guard time register	0x00
0x00 523A		UART1_PSCR	UART1 prescaler register	0x00
0x00 523B to 0x00 523F		Reserved area (5 bytes)		
0x00 5240	UART3	UART3_SR	UART3 status register	C0h
0x00 5241		UART3_DR	UART3 data register	0XX
0x00 5242		UART3_BRR1	UART3 baud rate register 1	0x00
0x00 5243		UART3_BRR2	UART3 baud rate register 2	0x00
0x00 5244		UART3_CR1	UART3 control register 1	0x00
0x00 5245		UART3_CR2	UART3 control register 2	0x00
0x00 5246		UART3_CR3	UART3 control register 3	0x00
0x00 5247		UART3_CR4	UART3 control register 4	0x00
0x00 5248		Reserved		
0x00 5249		UART3_CR6	UART3 control register 6	0x00
0x00 524A to 0x00 524F	Reserved area (6 bytes)			

### Total current consumption in active halt mode

**Table 24. Total current consumption in active halt mode at  $V_{DD} = 5\text{ V}$ ,  $T_A = -40\text{ to }85^\circ\text{C}$**

Symbol	Parameter	Conditions			Typ	Max <sup>(1)</sup>	Unit
		Main voltage regulator (MVR) <sup>(2)</sup>	Flash mode <sup>(3)</sup>	Clock source			
$I_{DD(AH)}$	Supply current in active halt mode	On	Operating mode	HSE crystal oscillator (16 MHz)	1000		$\mu\text{A}$
				LSI RC oscillator (128 kHz)	200	260	
			Power-down mode	HSE crystal oscillator (16 MHz)	940		
				LSI RC oscillator (128 kHz)	140		
		Off	Operating mode	LSI RC oscillator (128 kHz)	68		
			Power-down mode		11	45	

1. Data based on characterization results, not tested in production.

2. Configured by the REGAH bit in the CLK\_ICKR register.

3. Configured by the AHALT bit in the FLASH\_CR1 register.

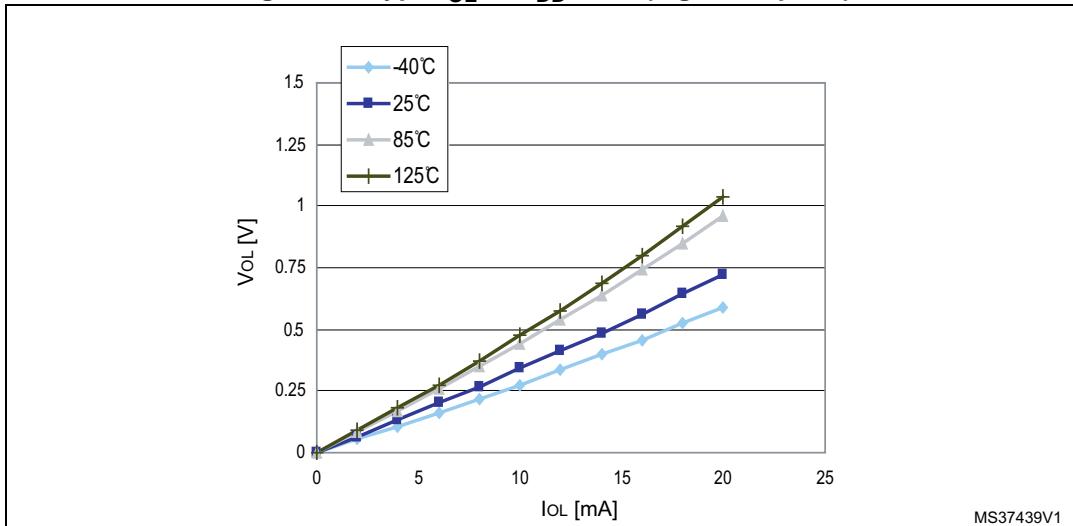
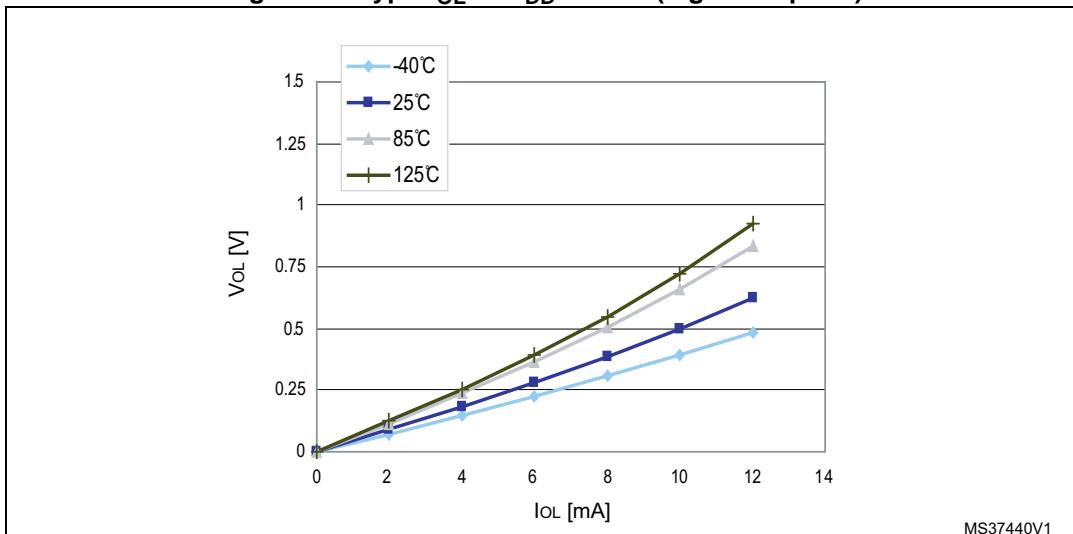
**Table 25. Total current consumption in active halt mode at  $V_{DD} = 3.3\text{ V}$**

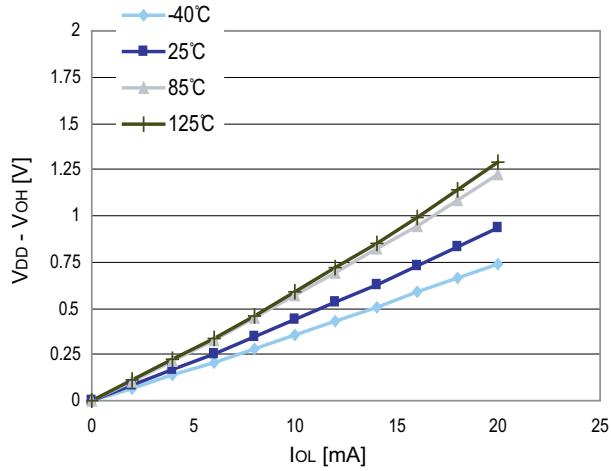
Symbol	Parameter	Conditions			Typ <sup>(1)</sup>	Unit
		Main voltage regulator (MVR) <sup>(2)</sup>	Flash mode <sup>(3)</sup>	Clock source		
$I_{DD(AH)}$	Supply current in active halt mode	On	Operating mode	HSE crystal osc. (16 MHz)	600	$\mu\text{A}$
				LSI RC osc. (128 kHz)	200	
			Power-down mode	HSE crystal osc. (16 MHz)	540	
				LSI RC osc. (128 kHz)	140	
		Off	Operating mode	LSI RC osc. (128 kHz)	66	
			Power-down mode		9	

1. Data based on characterization results, not tested in production.

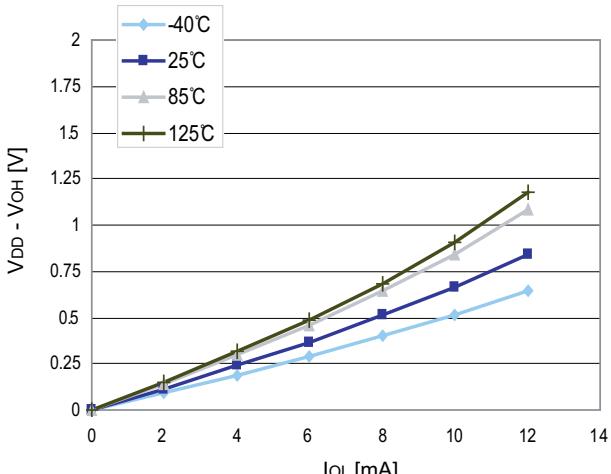
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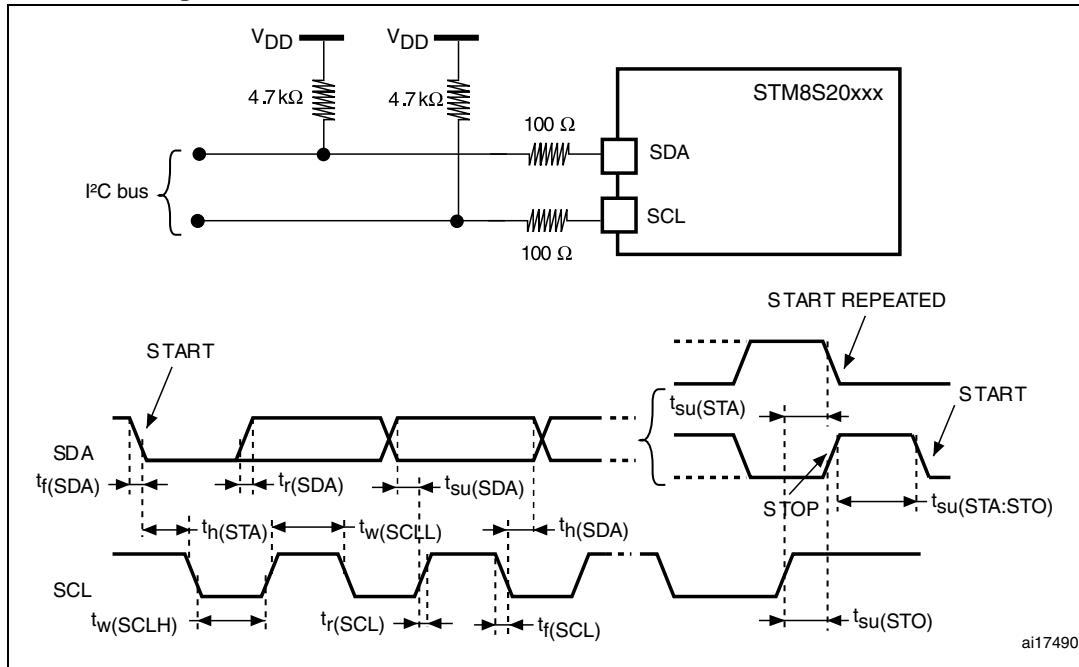
**Figure 27. Typ.  $V_{OL}$  @  $V_{DD} = 5$  V (high sink ports)****Figure 28. Typ.  $V_{OL}$  @  $V_{DD} = 3.3$  V (high sink ports)**

**Figure 31. Typ.  $V_{DD} - V_{OH}$  @  $V_{DD} = 5$  V (high sink ports)**

MS37443V1

**Figure 32. Typ.  $V_{DD} - V_{OH}$  @  $V_{DD} = 3.3$  V (high sink ports)**

MS37444V1

Figure 40. Typical application with I<sup>2</sup>C bus and timing diagram

1. Measurement points are made at CMOS levels:  $0.3 \times V_{DD}$  and  $0.7 \times V_{DD}$

### Static latch-up

Two complementary static tests are required on 10 parts to assess the latch-up performance:

- A supply overvoltage (applied to each power supply pin)
- A current injection (applied to each input, output and configurable I/O pin) is performed on each sample.

This test conforms to the EIA/JESD 78 IC latch-up standard. For more details, refer to the application note AN1181.

**Table 50. Electrical sensitivities**

Symbol	Parameter	Conditions	Class <sup>(1)</sup>
LU	Static latch-up class	$T_A = 25 \text{ }^\circ\text{C}$	A
		$T_A = 85 \text{ }^\circ\text{C}$	A
		$T_A = 125 \text{ }^\circ\text{C}$	A

1. Class description: A Class is an STMicroelectronics internal specification. All its limits are higher than the JEDEC specifications, that means when a device belongs to class A it exceeds the JEDEC standard. B class strictly covers all the JEDEC criteria (international standard).

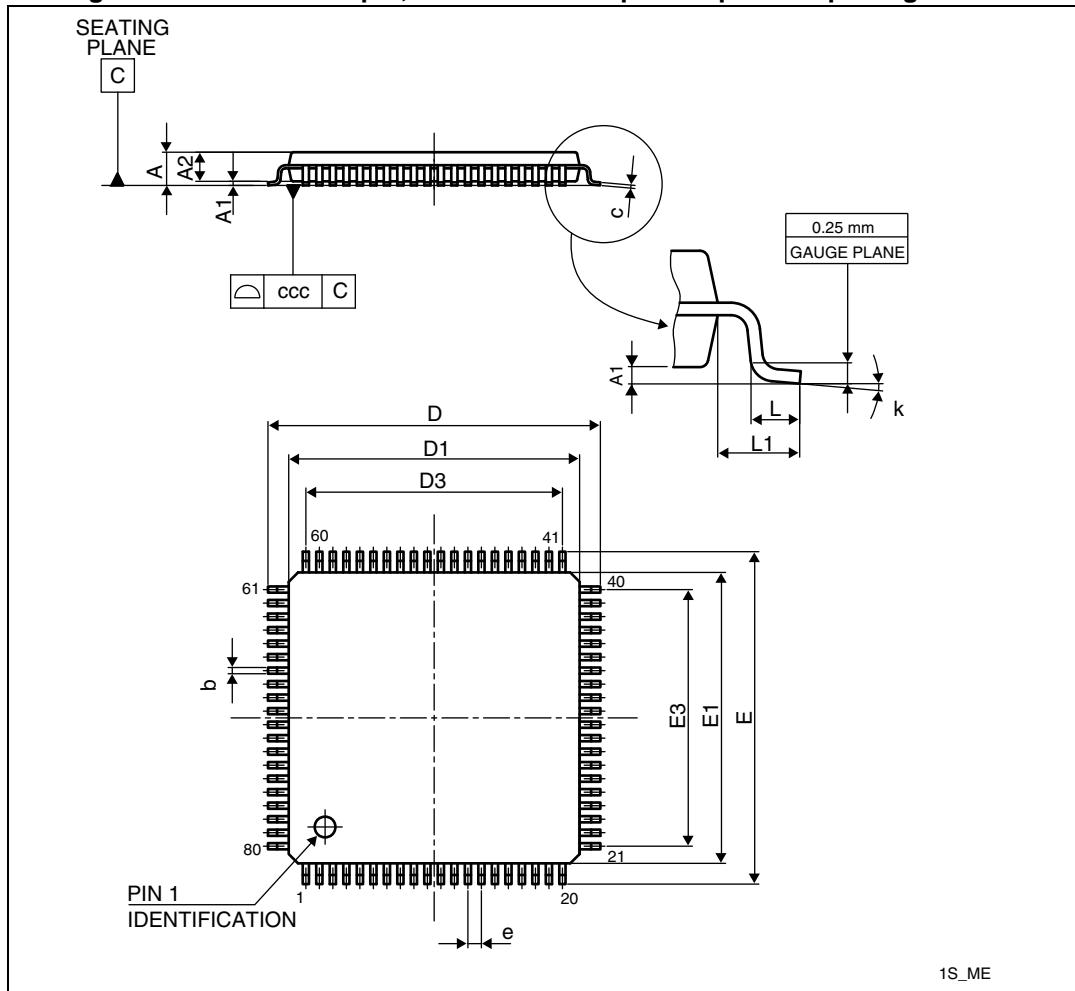
## 11 Package characteristics

To meet environmental requirements, ST offers these devices in different grades of ECOPACK® packages, depending on their level of environmental compliance. ECOPACK® specifications, grade definitions and product status are available at [www.st.com](http://www.st.com).  
ECOPACK® is an ST trademark.

## 11.1 Package information

### 11.1.1 LQFP80 package information

**Figure 43. LQFP80 - 80-pin, 14 x 14 mm low-profile quad flat package outline**



1. Drawing is not to scale.

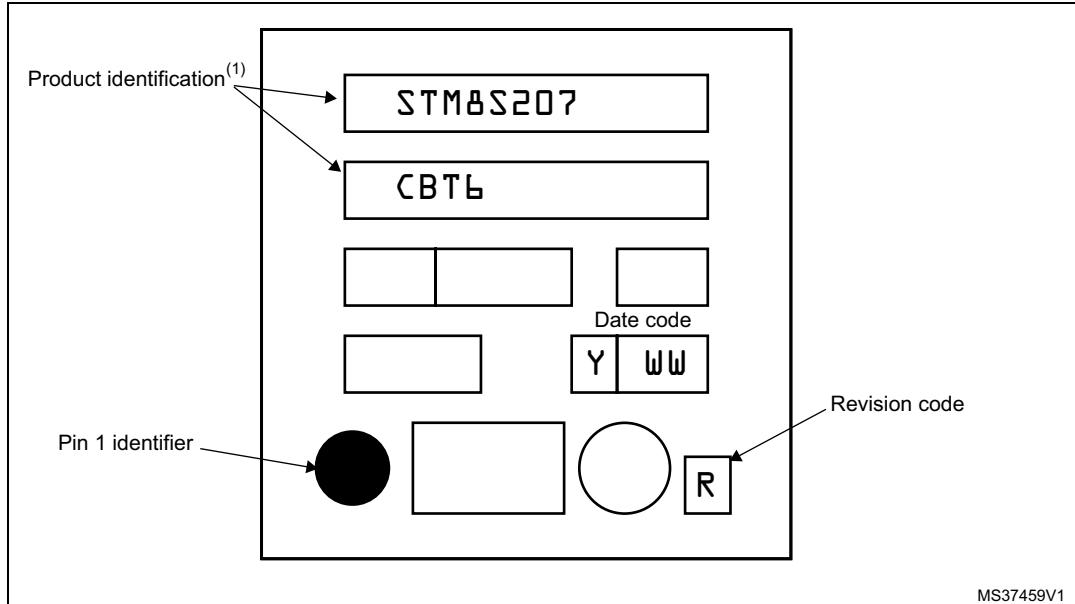
**Table 51. LQFP80 - 80-pin, 14 x 14 mm low-profile quad flat package mechanical data<sup>(1)</sup>**

Symbol	millimeters			inches		
	Min	Typ	Max	Min	Typ	Max
A	-	-	1.600	-	-	0.0630
A1	0.050	-	0.150	0.0020	-	0.0059
A2	1.350	1.400	1.450	0.0531	0.0551	0.0571
b	0.220	0.320	0.380	0.0087	0.0126	0.0150
c	0.090	-	0.200	0.0035	-	0.0079

## Device marking

The following figure shows the marking for the LQFP48 package.

Figure 52. LQFP48 marking example (package top view)



1. Parts marked as "ES", "E" or accompanied by an Engineering Sample notification letter, are not yet qualified and therefore not yet ready to be used in production and any consequences deriving from such usage will not be at ST charge. In no event, ST will be liable for any customer usage of these engineering samples in production. ST Quality has to be contacted prior to any decision to use these Engineering samples to run qualification activity.

### 11.1.4 LQFP44 package information

Figure 53. LQFP44 - 44-pin, 10 x 10 mm low-profile quad flat package outline

