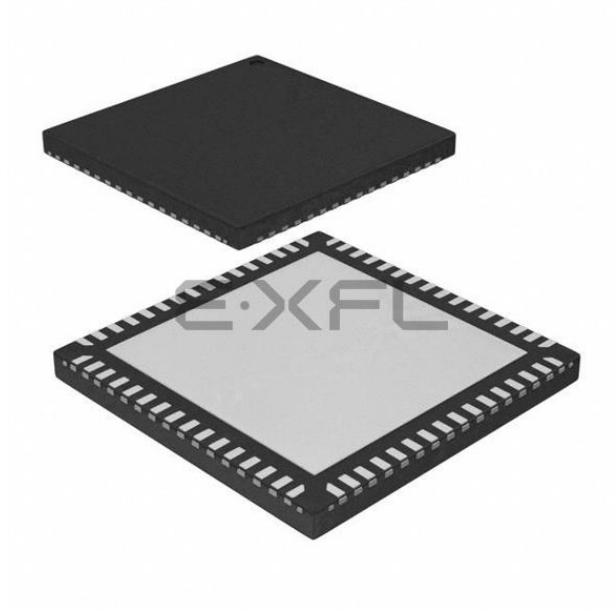

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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "Embedded - Microcontrollers"

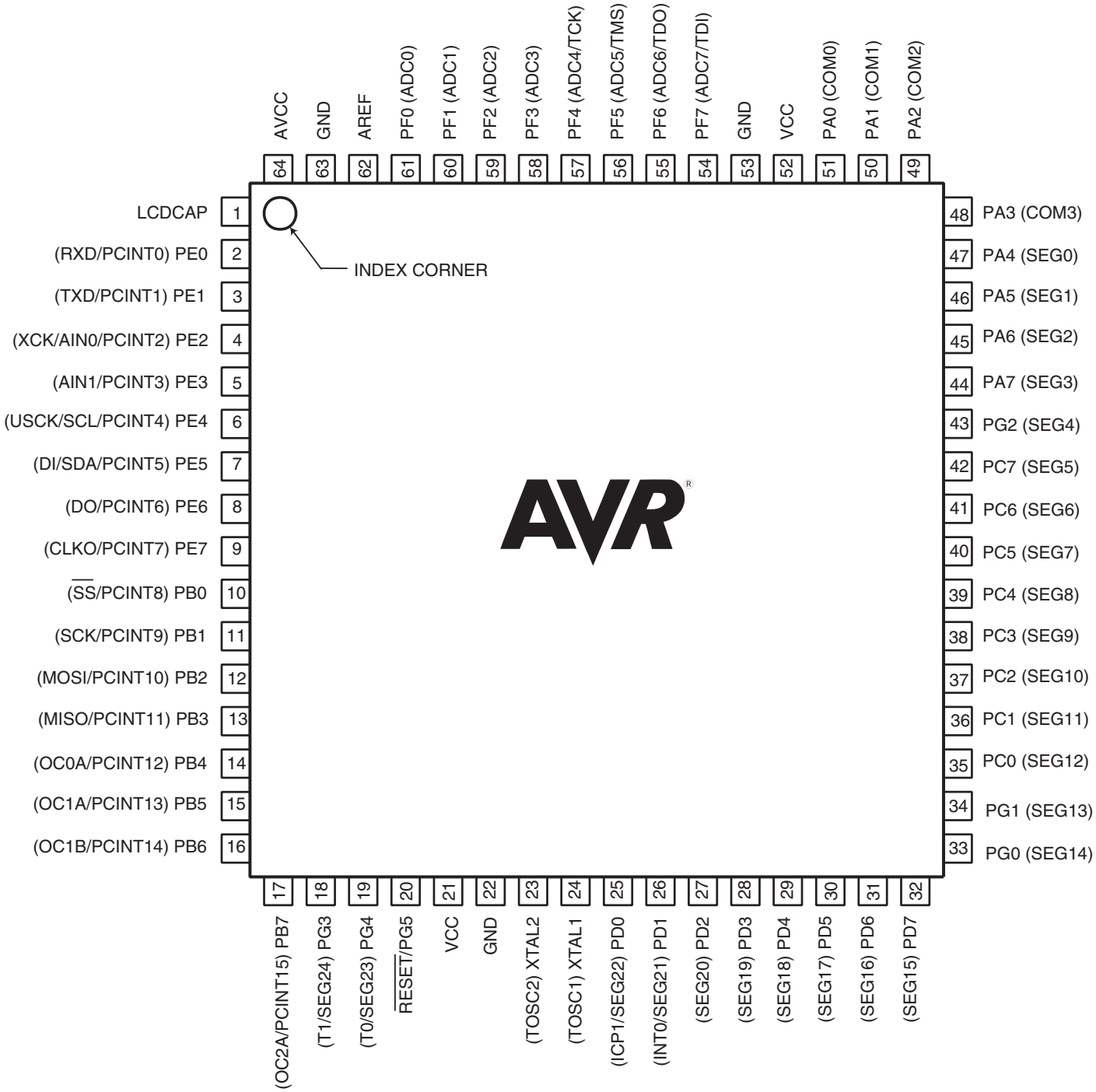
Details	
Product Status	Active
Core Processor	AVR
Core Size	8-Bit
Speed	16MHz
Connectivity	SPI, UART/USART, USI
Peripherals	Brown-out Detect/Reset, LCD, POR, PWM, WDT
Number of I/O	54
Program Memory Size	16KB (8K x 16)
Program Memory Type	FLASH
EEPROM Size	512 x 8
RAM Size	1K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 5.5V
Data Converters	A/D 8x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 105°C (TA)
Mounting Type	Surface Mount
Package / Case	64-VFQFN Exposed Pad
Supplier Device Package	64-QFN (9x9)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/atmega169pa-mn

  - Real Time Counter with separate oscillator
  - Four PWM channels
  - 8-channel, 10-bit ADC
  - Programmable Serial USART
  - Master/Slave SPI Serial Interface
  - Universal Serial Interface with Start Condition Detector
  - Programmable Watchdog Timer with Separate On-chip oscillator
  - On-chip analog comparator
  - Interrupt and Wake-up on pin change
- Special microcontroller features
  - Power-on reset and programmable Brown-out detection
  - Internal calibrated oscillator
  - External and internal interrupt sources
  - Five sleep modes: Idle, ADC Noise Reduction, Power-save, Power-down, and Standby
- I/O and packages
  - 54/69 programmable I/O lines
  - 64/100-lead TQFP, 64-pad QFN/MLF, and 64-pad DRQFN
- Speed Grade:
  - ATmega169A/169PA/649A/649P:
    - 0 - 16MHz @ 1.8 - 5.5V
  - ATmega3290A/3290PA/6490A/6490P:
    - 0 - 20MHz @ 1.8 - 5.5V
- Temperature range:
  - -40°C to 85°C industrial
- Ultra-low power consumption (picoPower® devices)
  - Active mode:
    - 1MHz, 1.8V: 215µA
    - 32kHz, 1.8V: 8µA (including oscillator)
    - 32kHz, 1.8V: 25µA (including oscillator and LCD)
  - Power-down mode:
    - 0.1µA at 1.8V
  - Power-save mode:
    - 0.6µA at 1.8V (Including 32kHz RTC)
    - 750nA at 1.8V

1. Pin configurations

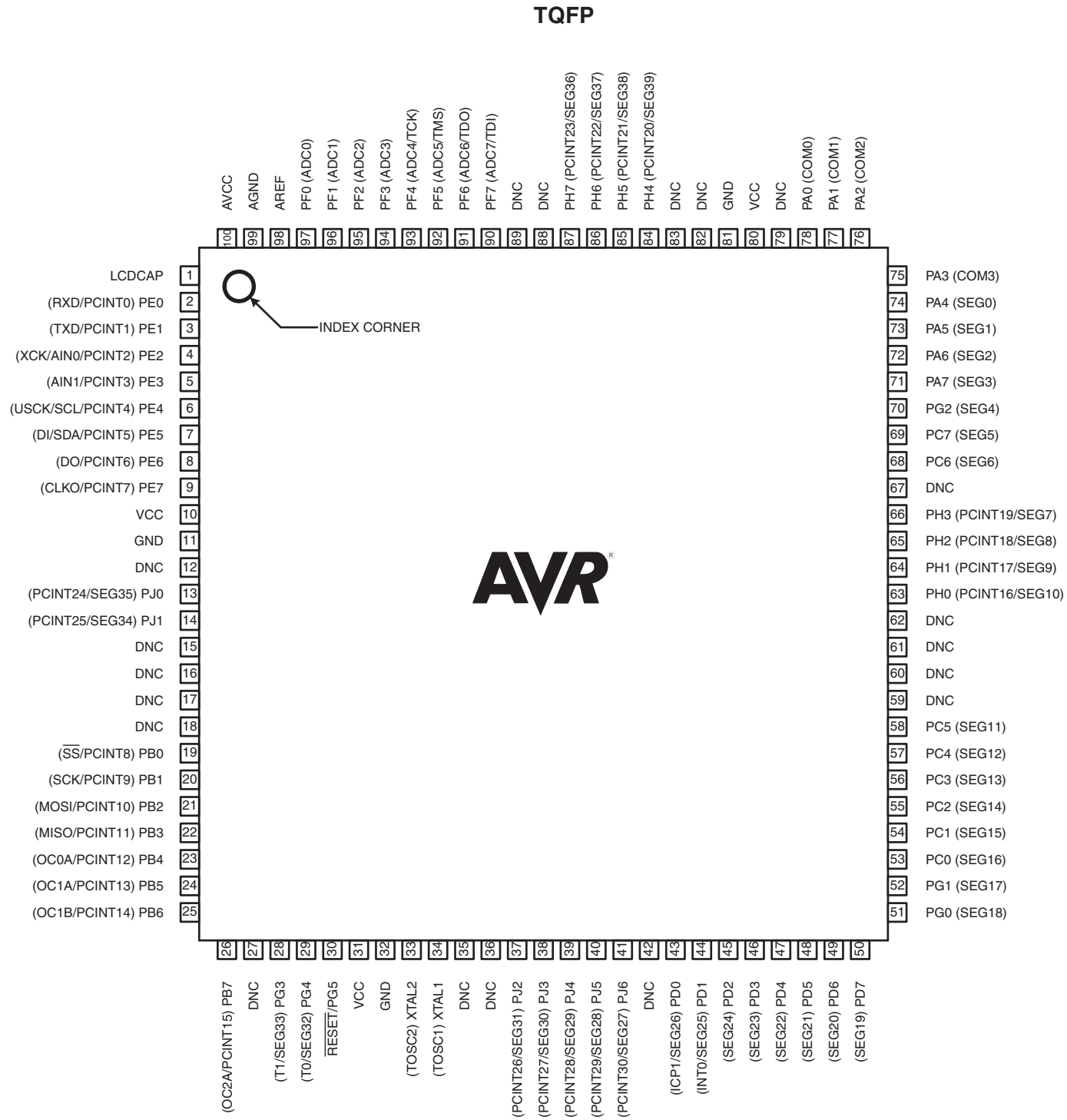
1.1 Pinout - 64A (TQFP) and 64M1 (QFN/MLF)

Figure 1-1. Pinout Atmel ATmega169A/ATmega169PA/ATmega329A/ATmega329PA/ATmega649A/ATmega649P.



1.2 Pinout - 100A (TQFP)

Figure 1-2. Pinout Atmel ATmega3290A/ATmega3290PA/ATmega6490A/ATmega6490P.



Note: The large center pad underneath the QFN/MLF packages is made of metal and internally connected to GND. It should be soldered or glued to the board to ensure good mechanical stability. If the center pad is left unconnected, the package might loosen from the board.

1.3 Pinout - 64MC (DRQFN)

Figure 1-3. Pinout Atmel ATmega169A/ATmega169PA.

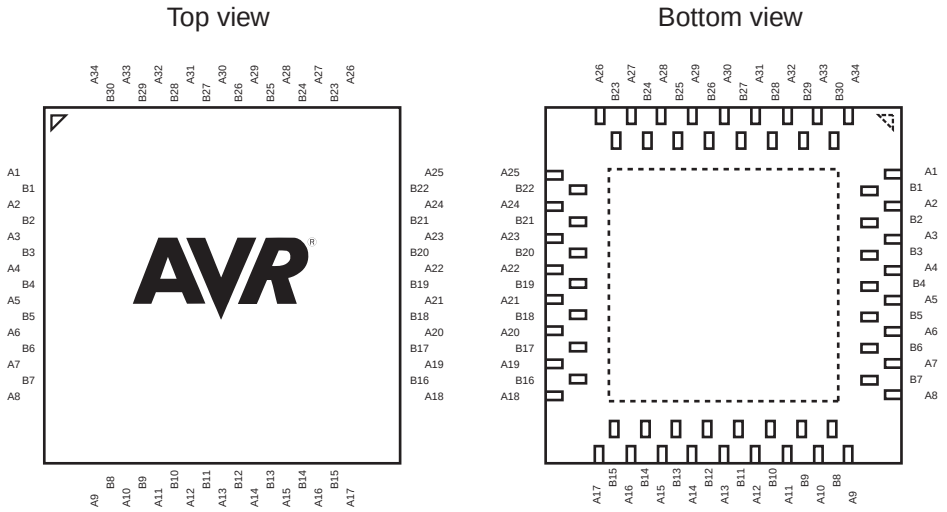


Table 1-1. DRQFN-64 Pinout ATmega169A/ATmega169PA.

	PE0		PB7		PG1 (SEG13)		PA2 (COM2)
	VLCDCAP		PB6		PG0 (SEG14)		PA3 (COM3)
	PE1		PG3		PC0 (SEG12)		PA1 (COM1)
	PE2		PG4		PC1 (SEG11)		PA0 (COM0)
	PE3		$\overline{\text{RESET}}$		PC2 (SEG10)		VCC
	PE4		VCC		PC3 (SEG9)		GND
	PE5		GND		PC4 (SEG8)		PF7
	PE6		XTAL2 (TOSC2)		PC5 (SEG7)		PF6
	PE7		XTAL1 (TOSC1)		PC6 (SEG6)		PF5
	PB0		PD0 (SEG22)		PC7 (SEG5)		PF4
	PB1		PD1 (SEG21)		PG2 (SEG4)		PF3
	PB2		PD2 (SEG20)		PA7 (SEG3)		PF2
	PB3		PD3 (SEG19)		PA6 (SEG2)		PF1
	PB5		PD4 (SEG18)		PA4 (SEG0)		PF0
	PB4		PD5 (SEG17)		PA5 (SEG1)		AREF
			PD7 (SEG15)				AVCC
			PD6 (SEG16)				GND

2.2 Comparison between Atmel ATmega169A/169PA/329A/329PA/649A/649P/3290A/3290PA/6490A/6490P

Table 2-1. Differences between: ATmega169A/169PA/329A/329PA/649A/649P/3290A/3290PA/6490A/6490P.

ATmega169A	16Kbyte	512Bytes	1Kbyte	4 × 25
ATmega169PA	16Kbyte	512Bytes	1Kbyte	4 × 25
ATmega329A	32Kbyte	1Kbyte	2Kbyte	4 × 25
ATmega329PA	32Kbyte	1Kbyte	2Kbyte	4 × 25
ATmega3290A	32Kbytes	1Kbyte	2Kbyte	4 × 40
ATmega3290PA	32Kbyte	1Kbyte	2Kbyte	4 × 40
ATmega649A	64Kbyte	2Kbyte	4Kbyte	4 × 25
ATmega649P	64Kbyte	2Kbyte	4Kbyte	4 × 25
ATmega6490A	64Kbyte	2Kbyte	4Kbyte	4 × 40
ATmega6490P	64Kbyte	2Kbyte	4Kbyte	4 × 40

2.3 Pin descriptions

The following section describes the I/O-pin special functions.

2.3.1 V_{CC}

Digital supply voltage.

2.3.2 GND

Ground.

2.3.3 Port A (PA7...PA0)

Port A is an 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port A output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port A pins that are externally pulled low will source current if the pull-up resistors are activated. The Port A pins are tri-stated when a reset condition becomes active, even if the clock is not running.

Port A also serves the functions of various special features of the Atmel ATmega169A/169PA/329A/329PA/3290A/3290PA/649A/649P/6490A/6490P as listed on page 72.

2.3.4 Port B (PB7...PB0)

Port B is an 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port B output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port B pins that are externally pulled low will source current if the pull-up resistors are activated. The Port B pins are tri-stated when a reset condition becomes active, even if the clock is not running.

Port B has better driving capabilities than the other ports.
Port B also serves the functions of various special features of the ATmega169A/169PA/329A/329PA/3290A/3290PA/649A/649P/6490A/6490P as listed on page 73.

2.3.5 Port C (PC7...PC0)

Port C is an 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port C output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port C pins that are externally pulled low will source current if the pull-up resistors are activated. The Port C pins are tri-stated when a reset condition becomes active, even if the clock is not running.

Port C also serves the functions of special features of the ATmega169A/169PA/329A/329PA/3290A/3290PA/649A/649P/6490A/6490P as listed on page 76.

2.3.6 Port D (PD7...PD0)

Port D is an 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port D output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port D pins that are externally pulled low will source current if the pull-up resistors are activated. The Port D pins are tri-stated when a reset condition becomes active, even if the clock is not running.

Port D also serves the functions of various special features of the ATmega169A/169PA/329A/329PA/3290A/3290PA/649A/649P/6490A/6490P as listed on page 77.

2.3.7 Port E (PE7...PE0)

Port E is an 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port E output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port E pins that

are externally pulled low will source current if the pull-up resistors are activated. The Port E pins are tri-stated when a reset condition becomes active, even if the clock is not running.

Port E also serves the functions of various special features of the ATmega169A/169PA/329A/329PA/3290A/3290PA/649A/649P/6490A/6490P as listed on page 79.

2.3.8 Port F (PF7...PF0)

Port F serves as the analog inputs to the A/D Converter.

Port F also serves as an 8-bit bi-directional I/O port, if the A/D Converter is not used. Port pins can provide internal pull-up resistors (selected for each bit). The Port F output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port F pins that are externally pulled low will source current if the pull-up resistors are activated. The Port F pins are tri-stated when a reset condition becomes active, even if the clock is not running. If the JTAG interface is enabled, the pull-up resistors on pins PF7(TDI), PF5(TMS), and PF4(TCK) will be activated even if a reset occurs.

Port F also serves the functions of the JTAG interface.

2.3.9 Port G (PG5...PG0)

Port G is a 6-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port G output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port G pins that are externally pulled low will source current if the pull-up resistors are activated. The Port G pins are tri-stated when a reset condition becomes active, even if the clock is not running.

Port G also serves the functions of various special features of the ATmega169A/169PA/329A/329PA/3290A/3290PA/649A/649P/6490A/6490P as listed on page 83.

2.3.10 Port H (PH7...PH0)

Port H is a 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port H output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port H pins that are externally pulled low will source current if the pull-up resistors are activated. The Port H pins are tri-stated when a reset condition becomes active, even if the clock is not running.

Port H also serves the functions of various special features of the ATmega3290PA/6490P as listed on page 85.

2.3.11 Port J (PJ6...PJ0)

Port J is a 7-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port J output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port J pins that are externally pulled low will source current if the pull-up resistors are activated. The Port J pins are tri-stated when a reset condition becomes active, even if the clock is not running.

Port J also serves the functions of various special features of the ATmega3290PA/6490P as listed on page 87.

2.3.12 $\overline{\text{RESET}}$

Reset input. A low level on this pin for longer than the minimum pulse length will generate a reset, even if the clock is not running. The minimum pulse length is given in ”System and reset characteristics” on page 332. Shorter pulses are not guaranteed to generate a reset.

2.3.13 XTAL1

Input to the inverting Oscillator amplifier and input to the internal clock operating circuit.

2.3.14 XTAL2

Output from the inverting Oscillator amplifier.

3. Resources

A comprehensive set of development tools, application notes and datasheets are available for download on http://www.atmel.com/avr.

4. Data retention

Reliability Qualification results show that the projected data retention failure rate is much less than 1 PPM over 20 years at 85°C or 100 years at 25°C.

5. About code examples

This documentation contains simple code examples that briefly show how to use various parts of the device. These code examples assume that the part specific header file is included before compilation. Be aware that not all C compiler vendors include bit definitions in the header files and interrupt handling in C is compiler dependent. Please confirm with the C compiler documentation for more details.

For I/O Registers located in extended I/O map, “IN”, “OUT”, “SBIS”, “SBIC”, “CBI”, and “SBI” instructions must be replaced with instructions that allow access to extended I/O. Typically “LDS” and “STS” combined with “SBRS”, “SBRC”, “SBR”, and “CBR”.

6. Capacitive touch sensing

The Atmel® QTouch® Library provides a simple to use solution to realize touch sensitive interfaces on most Atmel AVR® microcontrollers. The QTouch Library includes support for the QTouch and QMatrix® acquisition methods.

Touch sensing can be added to any application by linking the appropriate Atmel QTouch Library for the AVR Microcontroller. This is done by using a simple set of APIs to define the touch channels and sensors, and then calling the touch sensing API’s to retrieve the channel information and determine the touch sensor states.

The QTouch Library is FREE and downloadable from the Atmel website at the following location: www.atmel.com/qtouchlibrary. For implementation details and other information, refer to the Atmel QTouch Library User Guide - also available for download from the Atmel website.

7. Register summary

Note: Registers with bold type only available in Atmel ATmega3290A/3290PA/6490A/6490P.

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Page
(0xFF)	**LCDDR19**	**SEG339**	**SEG338**	**SEG337**	**SEG336**	**SEG335**	**SEG334**	**SEG333**	**SEG332**	236
(0xFE)	LCDDR18	**SEG331**	**SEG330**	**SEG329**	**SEG328**	**SEG327**	**SEG326**	**SEG325**	SEG324	236
(0xFD)	LCDDR17	SEG323	SEG322	SEG321	SEG320	SEG319	SEG318	SEG317	SEG316	236
(0xFC)	LCDDR16	SEG315	SEG314	SEG313	SEG312	SEG311	SEG310	SEG309	SEG308	236
(0xFB)	LCDDR15	SEG307	SEG306	SEG305	SEG304	SEG303	SEG302	SEG301	SEG300	236
(0xFA)	**LCDDR14**	**SEG239**	**SEG238**	**SEG237**	**SEG236**	**SEG235**	**SEG234**	**SEG233**	**SEG232**	236
(0xF9)	LCDDR13	**SEG231**	**SEG230**	**SEG229**	**SEG228**	**SEG227**	**SEG226**	**SEG225**	SEG224	236
(0xF8)	LCDDR12	SEG223	SEG222	SEG221	SEG220	SEG219	SEG218	SEG217	SEG216	236
(0xF7)	LCDDR11	SEG215	SEG214	SEG213	SEG212	SEG211	SEG210	SEG209	SEG208	236
(0xF6)	LCDDR10	SEG207	SEG206	SEG205	SEG204	SEG203	SEG202	SEG201	SEG200	236
(0xF5)	**LCDDR09**	**SEG139**	**SEG138**	**SEG137**	**SEG136**	**SEG135**	**SEG134**	**SEG133**	**SEG132**	236

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Page
(0x72)	Reserved	-	-	-	-	-	-	-	-	
(0x71)	Reserved	-	-	-	-	-	-	-	-	
(0x70)	TIMSK2	-	-	-	-	-	-	OCIE2A	TOIE2	154
(0x6F)	TIMSK1	-	-	ICIE1	-	-	OCIE1B	OCIE1A	TOIE1	131
(0x6E)	TIMSK0	-	-	-	-	-	-	OCIE0A	TOIE0	137
(0x6D)	**PCMSK2**	**PCINT23**	**PCINT22**	**PCINT21**	**PCINT20**	**PCINT19**	**PCINT18**	**PCINT17**	**PCINT16**	64
(0x6C)	PCMSK1	PCINT15	PCINT14	PCINT13	PCINT12	PCINT11	PCINT10	PCINT9	PCINT8	64
(0x6B)	PCMSK0	PCINT7	PCINT6	PCINT5	PCINT4	PCINT3	PCINT2	PCINT1	PCINT0	64
(0x6A)	Reserved	-	-	-	-	-	-	-	-	
(0x69)	EICRA	-	-	-	-	-	-	ISC01	ISC00	61
(0x68)	Reserved	-	-	-	-	-	-	-	-	
(0x67)	Reserved	-	-	-	-	-	-	-	-	
(0x66)	OSCCAL	Oscillator Calibration Register [CAL7...0]								38
(0x65)	Reserved	-	-	-	-	-	-	-	-	
(0x64)	PRR	-	-	-	PRLCD	PRTIM1	PRSPI	PSUSART0	PRADC	46
(0x63)	Reserved	-	-	-	-	-	-	-	-	
(0x62)	Reserved	-	-	-	-	-	-	-	-	
(0x61)	CLKPR	CLKPCE	-	-	-	CLKPS3	CLKPS2	CLKPS1	CLKPS0	38
(0x60)	WDTCR	-	-	-	WDCE	WDE	WDP2	WDP1	WDP0	53
0x3F (0x5F)	SREG	I	T	H	S	V	N	Z	C	15
0x3E (0x5E)	SPH	Stack Pointer High								17
0x3D (0x5D)	SPL	Stack Pointer Low								17
0x3C (0x5C)	Reserved	-	-	-	-	-	-	-	-	
0x3B (0x5B)	Reserved	-	-	-	-	-	-	-	-	
0x3A (0x5A)	Reserved	-	-	-	-	-	-	-	-	
0x39 (0x59)	Reserved	-	-	-	-	-	-	-	-	
0x38 (0x58)	Reserved	-	-	-	-	-	-	-	-	
0x37 (0x57)	SPMCSR	SPMIE	RWWSB	-	RWWSRE	BLBSET	PGWRT	PGERS	SPMEN	289
0x36 (0x56)	Reserved									
0x35 (0x55)	MCUCR	JTD	BODS	BODSE	PUD	-	-	IVSEL	IVCE	59/90/275
0x34 (0x54)	MCUSR	-	-	-	JTRF	WDRF	BORF	EXTRF	PORF	53
0x33 (0x53)	SMCR	-	-	-	-	SM2	SM1	SM0	SE	45
0x32 (0x52)	Reserved	-	-	-	-	-	-	-	-	
0x31 (0x51)	OCDR	IDRD/OCDR7	OCDR6	OCDR5	OCDR4	OCDR3	OCDR2	OCDR1	OCDR0	242
0x30 (0x50)	ACSR	ACD	ACBG	ACO	ACI	ACIE	ACIC	ACIS1	ACIS0	202
0x2F (0x4F)	Reserved	-	-	-	-	-	-	-	-	
0x2E (0x4E)	SPDR	SPI Data Register								165
0x2D (0x4D)	SPSR	SPIF	WCOL	-	-	-	-	-	SPI2X	164
0x2C (0x4C)	SPCR	SPIE	SPE	DORD	MSTR	CPOL	CPHA	SPR1	SPR0	163
0x2B (0x4B)	GPIOR2	General Purpose I/O Register								29
0x2A (0x4A)	GPIOR1	General Purpose I/O Register								29
0x29 (0x49)	Reserved	-	-	-	-	-	-	-	-	
0x28 (0x48)	Reserved	-	-	-	-	-	-	-	-	
0x27 (0x47)	OCR0A	Timer/Counter0 Output Compare A								138
0x26 (0x46)	TCNT0	Timer/Counter0								137
0x25 (0x45)	Reserved	-	-	-	-	-	-	-	-	
0x24 (0x44)	TCCR0A	FOC0A	WGM00	COM0A1	COM0A0	WGM01	CS02	CS01	CS00	135
0x23 (0x43)	GTCCR	TSM	-	-	-	-	-	PSR2	PSR10	138/155
0x22 (0x42)	EEARH	-	-	-	-	-	EEPROM Address Register High			28
0x21 (0x41)	EEARL	EEPROM Address Register Low								28
0x20 (0x40)	EEDR	EEPROM Data Register								28
0x1F (0x3F)	EECR	-	-	-	-	EERIE	EEMWE	EEWE	EERE	28
0x1E (0x3E)	GPIOR0	General Purpose I/O Register								29
0x1D (0x3D)	EIMSK	PCIE	PCIE2	PCIE1	PCIE0	-	-	-	INT0	62
0x1C (0x3C)	EIFR	PCIF3	PCIF2	PCIF1	PCIF0	-	-	-	INTF0	63
0x1B (0x3B)	Reserved	-	-	-	-	-	-	-	-	
0x1A (0x3A)	Reserved	-	-	-	-	-	-	-	-	
0x19 (0x39)	Reserved	-	-	-	-	-	-	-	-	
0x18 (0x38)	Reserved	-	-	-	-	-	-	-	-	
0x17 (0x37)	TIFR2	-	-	-	-	-	-	OCF2A	TOV2	154
0x16 (0x36)	TIFR1	-	-	ICF1	-	-	OCF1B	OCF1A	TOV1	131
0x15 (0x35)	TIFR0	-	-	-	-	-	-	OCF0A	TOV0	138
0x14 (0x34)	PORTG	-	-	-	PORTG4	PORTG3	PORTG2	PORTG1	PORTG0	92
0x13 (0x33)	DDRG	-	-	-	DDG4	DDG3	DDG2	DDG1	DDG0	92
0x12 (0x32)	PING	-	-	PING5	PING4	PING3	PING2	PING1	PING0	92

Mnemonics	Operands	Description	Operation	Flags	#Clocks
BRVC	k	Branch if Overflow Flag is Cleared	if (V = 0) then PC ← PC + k + 1	None	1/2
BRIE	k	Branch if Interrupt Enabled	if (I = 1) then PC ← PC + k + 1	None	1/2
BRID	k	Branch if Interrupt Disabled	if (I = 0) then PC ← PC + k + 1	None	1/2
BIT AND BIT-TEST INSTRUCTIONS					
SBI	P,b	Set Bit in I/O Register	I/O(P,b) ← 1	None	2
CBI	P,b	Clear Bit in I/O Register	I/O(P,b) ← 0	None	2
LSL	Rd	Logical Shift Left	Rd(n+1) ← Rd(n), Rd(0) ← 0	Z,C,N,V	1
LSR	Rd	Logical Shift Right	Rd(n) ← Rd(n+1), Rd(7) ← 0	Z,C,N,V	1
ROL	Rd	Rotate Left Through Carry	Rd(0)←C,Rd(n+1)← Rd(n),C←Rd(7)	Z,C,N,V	1
ROR	Rd	Rotate Right Through Carry	Rd(7)←C,Rd(n)← Rd(n+1),C←Rd(0)	Z,C,N,V	1
ASR	Rd	Arithmetic Shift Right	Rd(n) ← Rd(n+1), n=0..6	Z,C,N,V	1
SWAP	Rd	Swap Nibbles	Rd(3..0)←Rd(7..4),Rd(7..4)←Rd(3..0)	None	1
BSET	s	Flag Set	SREG(s) ← 1	SREG(s)	1
BCLR	s	Flag Clear	SREG(s) ← 0	SREG(s)	1
BST	Rr, b	Bit Store from Register to T	T ← Rr(b)	T	1
BLD	Rd, b	Bit load from T to Register	Rd(b) ← T	None	1
SEC		Set Carry	C ← 1	C	1
CLC		Clear Carry	C ← 0	C	1
SEN		Set Negative Flag	N ← 1	N	1
CLN		Clear Negative Flag	N ← 0	N	1
SEZ		Set Zero Flag	Z ← 1	Z	1
CLZ		Clear Zero Flag	Z ← 0	Z	1
SEI		Global Interrupt Enable	I ← 1	I	1
CLI		Global Interrupt Disable	I ← 0	I	1
SES		Set Signed Test Flag	S ← 1	S	1
CLS		Clear Signed Test Flag	S ← 0	S	1
SEV		Set Twos Complement Overflow.	V ← 1	V	1
CLV		Clear Twos Complement Overflow	V ← 0	V	1
SET		Set T in SREG	T ← 1	T	1
CLT		Clear T in SREG	T ← 0	T	1
SEH		Set Half Carry Flag in SREG	H ← 1	H	1
CLH		Clear Half Carry Flag in SREG	H ← 0	H	1
DATA TRANSFER INSTRUCTIONS					
MOV	Rd, Rr	Move Between Registers	Rd ← Rr	None	1
MOVW	Rd, Rr	Copy Register Word	Rd+1:Rd ← Rr+1:Rr	None	1
LDI	Rd, K	Load Immediate	Rd ← K	None	1
LD	Rd, X	Load Indirect	Rd ← (X)	None	2
LD	Rd, X+	Load Indirect and Post-Inc.	Rd ← (X), X ← X + 1	None	2
LD	Rd, - X	Load Indirect and Pre-Dec.	X ← X - 1, Rd ← (X)	None	2
LD	Rd, Y	Load Indirect	Rd ← (Y)	None	2
LD	Rd, Y+	Load Indirect and Post-Inc.	Rd ← (Y), Y ← Y + 1	None	2
LD	Rd, - Y	Load Indirect and Pre-Dec.	Y ← Y - 1, Rd ← (Y)	None	2
LDD	Rd,Y+q	Load Indirect with Displacement	Rd ← (Y + q)	None	2
LD	Rd, Z	Load Indirect	Rd ← (Z)	None	2
LD	Rd, Z+	Load Indirect and Post-Inc.	Rd ← (Z), Z ← Z+1	None	2
LD	Rd, -Z	Load Indirect and Pre-Dec.	Z ← Z - 1, Rd ← (Z)	None	2
LDD	Rd, Z+q	Load Indirect with Displacement	Rd ← (Z + q)	None	2
LDS	Rd, k	Load Direct from SRAM	Rd ← (k)	None	2
ST	X, Rr	Store Indirect	(X) ← Rr	None	2
ST	X+, Rr	Store Indirect and Post-Inc.	(X) ← Rr, X ← X + 1	None	2
ST	- X, Rr	Store Indirect and Pre-Dec.	X ← X - 1, (X) ← Rr	None	2
ST	Y, Rr	Store Indirect	(Y) ← Rr	None	2
ST	Y+, Rr	Store Indirect and Post-Inc.	(Y) ← Rr, Y ← Y + 1	None	2
ST	- Y, Rr	Store Indirect and Pre-Dec.	Y ← Y - 1, (Y) ← Rr	None	2
STD	Y+q,Rr	Store Indirect with Displacement	(Y + q) ← Rr	None	2
ST	Z, Rr	Store Indirect	(Z) ← Rr	None	2
ST	Z+, Rr	Store Indirect and Post-Inc.	(Z) ← Rr, Z ← Z + 1	None	2
ST	-Z, Rr	Store Indirect and Pre-Dec.	Z ← Z - 1, (Z) ← Rr	None	2
STD	Z+q,Rr	Store Indirect with Displacement	(Z + q) ← Rr	None	2
STS	k, Rr	Store Direct to SRAM	(k) ← Rr	None	2
LPM		Load Program Memory	R0 ← (Z)	None	3
LPM	Rd, Z	Load Program Memory	Rd ← (Z)	None	3
LPM	Rd, Z+	Load Program Memory and Post-Inc	Rd ← (Z), Z ← Z+1	None	3
SPM		Store Program Memory	(Z) ← R1:R0	None	-
IN	Rd, P	In Port	Rd ← P	None	1
OUT	P, Rr	Out Port	P ← Rr	None	1
PUSH	Rr	Push Register on Stack	STACK ← Rr	None	2
POP	Rd	Pop Register from Stack	Rd ← STACK	None	2

Mnemonics	Operands	Description	Operation	Flags	#Clocks
MCU CONTROL INSTRUCTIONS					
NOP		No Operation		None	1
SLEEP		Sleep	(see specific descr. for Sleep function)	None	1
WDR		Watchdog Reset	(see specific descr. for WDR/timer)	None	1
BREAK		Break	For On-chip Debug Only	None	N/A

9. Ordering information

9.1 Atmel ATmega169A

Speed [MHz] (3)	Power supply	Ordering code (2)	Package type (1)	Operational range
16	1.8 - 5.5V	ATmega169A-AU ATmega169A-AUR (4) ATmega169A-MU ATmega169A-MUR (4) ATmega169A-MCH ATmega169A-MCHR (4)	64A 64A 64M1 64M1 64MC 64MC	Industrial (-40°C to 85°C)
		ATmega169A-AN ATmega169A-ANR (4) ATmega169A-MN ATmega169A-MNR (4)	64A 64A 64M1 64M1	Extended (-40°C to 105°C)

Notes:
1. This device can also be supplied in wafer form. Please contact your local Atmel sales office for detailed ordering information and minimum quantities.
2. Pb-free packaging, complies to the European Directive for Restriction of Hazardous Substances (RoHS directive). Also Halide free and fully Green.
3. For Speed vs. V_{CC}, see Figure 29-1 on page 330.
4. Tape & Reel.

Package type	
	64-lead, thin (1.0mm) plastic Gull Wing Quad Flat Package (TQFP)
	64-pad, 9 × 9 × 1.0mm body, lead pitch 0.50mm, Quad Flat No-Lead/Micro Lead Frame Package (QFN/MLF)
	64-lead (2-row Staggered), 7 × 7 × 1.0mm body, 4.0 × 4.0 mm Exposed Pad, Quad Flat No-Lead Package (QFN)

9.3 Atmel ATmega329A

Speed [MHz] (3)	Power supply	Ordering code (2)	Package type (1)	Operational range
20	1.8 - 5.5V	ATmega329A-AU ATmega329A-AUR (4) ATmega329A-MU ATmega329A-MUR (4)	64A 64A 64M1 64M1	Industrial (-40°C to 85°C)
		ATmega329A-AN ATmega329A-ANR (4) ATmega329A-MN ATmega329A-MNR (4)	64A 64A 64M1 64M1	Extended (-40°C to 105°C)(5)

Notes:
1. This device can also be supplied in wafer form. Please contact your local Atmel sales office for detailed ordering information and minimum quantities.
2. Pb-free packaging complies to the European Directive for Restriction of Hazardous Substances (RoHS directive). Also Halide free and fully Green.
3. For Speed vs. V_{CC} see Figure 29-2 on page 330.
4. Tape & Reel.
5. See characterization specifications at 105°C.

Package type	
	64-lead, 14 × 14 × 1.0mm, thin profile plastic Quad Flat Package (TQFP)
	64-pad, 9 × 9 × 1.0mm, Quad Flat No-Lead/Micro Lead Frame Package (QFN/MLF)

9.4 Atmel ATmega329PA

Speed [MHz] (3)	Power supply	Ordering code (2)	Package type (1)	Operational range
20	1.8 - 5.5V	ATmega329PA-AU ATmega329PA-AUR(4) ATmega329PA-MU ATmega329PA-MUR(4)	64A 64A 64M1 64M1	Industrial (-40°C to 85°C)
		ATmega329PA-AN ATmega329PA-ANR(4) ATmega329PA-MN ATmega329PA-MNR(4)	64A 64A 64M1 64M1	Extended (-40°C to 105°C)(5)

Notes:
1. This device can also be supplied in wafer form. Please contact your local Atmel sales office for detailed ordering information and minimum quantities.
2. Pb-free packaging complies to the European Directive for Restriction of Hazardous Substances (RoHS directive). Also Halide free and fully Green.
3. For Speed vs. V_{CC} see Figure 29-2 on page 330.
4. Tape &Reel.
5. See characterization specification at 105°C.

Package type	
	64-lead, 14 × 14 × 1.0mm, thin profile Plastic Quad Flat Package (TQFP)
	64-pad, 9 × 9 × 1.0mm, Quad Flat No-Lead/Micro Lead Frame Package (QFN/MLF)

9.6 Atmel ATmega3290PA

Speed [MHz] (3)	Power supply	Ordering code (2)	Package type (1)	Operational range
20	1.8 - 5.5V	ATmega3290PA-AU ATmega3290PA-AUR(4)	100A 100A	Industrial (-40°C to 85°C)
		ATmega3290PA-AN ATmega3290PA-ANR(4)	100A 100A	Industrial (-40°C to 105°C)(5)

Notes:
1. This device can also be supplied in wafer form. Please contact your local Atmel sales office for detailed ordering information and minimum quantities.
2. Pb-free packaging complies to the European Directive for Restriction of Hazardous Substances (RoHS directive). Also Halide free and fully Green.
3. For Speed vs. V_{CC} see Figure 29-2 on page 330.
4. Tape & Reel.
5. See characterization specification at 105°C.

	Package type
	100-lead, 14 × 14 × 1.0mm, 0.5mm Lead Pitch, Thin Profile Plastic Quad Flat Package (TQFP)

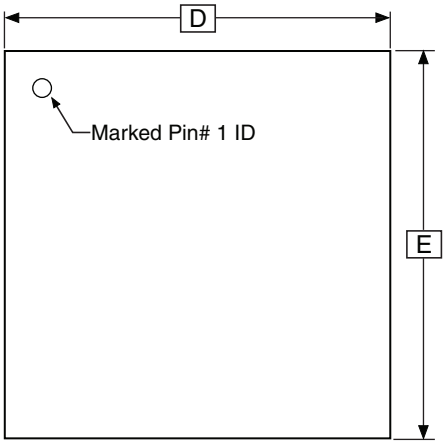
9.8 Atmel ATmega649P

Speed [MHz] (3)	Power supply	Ordering code (2)	Package type (1)	Operational range
16	1.8 - 5.5 V	ATmega649P-AU ATmega649P-AUR (4) ATmega649P-MU ATmega649P-MUR (4)	64A 64A 64M1 64M1	Industrial (-40°C to 85°C)

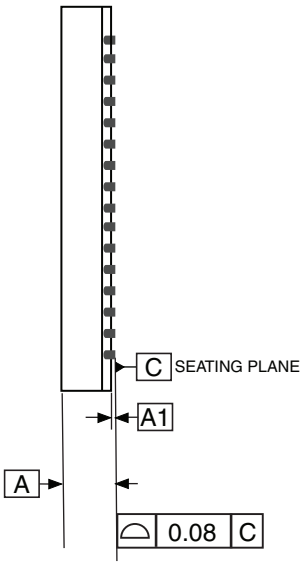
Notes:
1. This device can also be supplied in wafer form. Please contact your local Atmel sales office for detailed ordering information and minimum quantities.
2. Pb-free packaging complies to the European Directive for Restriction of Hazardous Substances (RoHS directive). Also Halide free and fully Green.
3. For Speed vs. V_{CC} see Figure 29-1 on page 330.
4. Tape & Reel.

Package type	
	64-lead, 14 × 14 × 1.0mm, Thin Profile Plastic Quad Flat Package (TQFP)
	64-pad, 9 × 9 × 1.0mm, Quad Flat No-Lead/Micro Lead Frame Package (QFN/MLF)

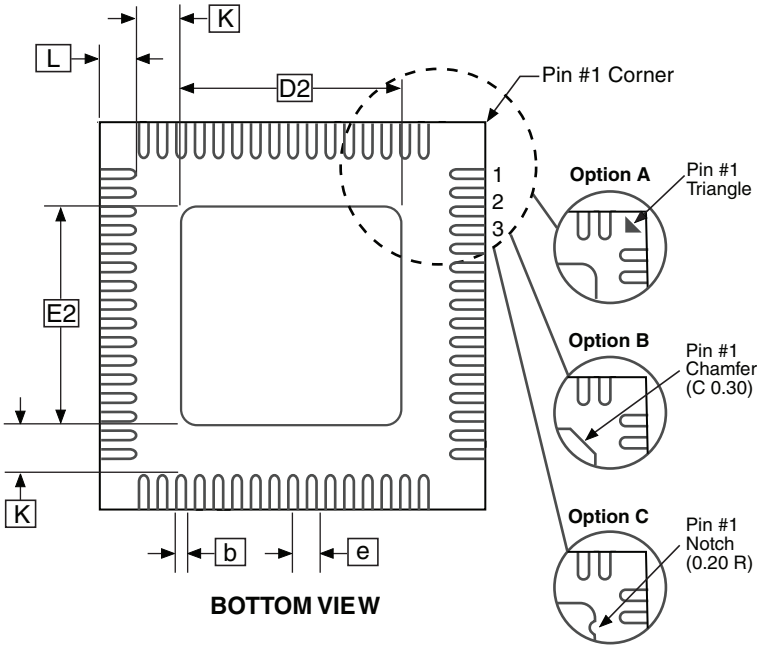
10.2 64M1



TOP VIEW



SIDE VIEW



BOTTOM VIEW

COMMON DIMENSIONS
(Unit of Measure = mm)

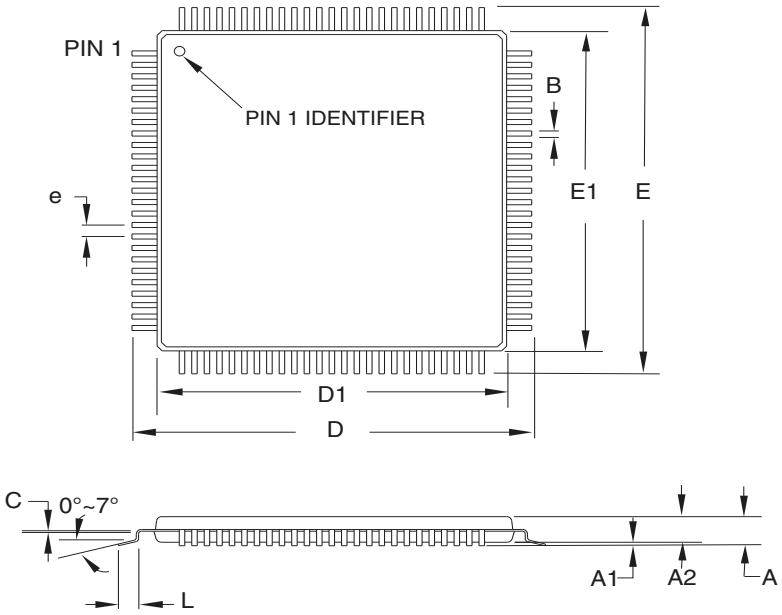
SYMBOL	MIN	NOM	MAX	NOTE
A	0.80	0.90	1.00	
A1	–	0.02	0.05	
b	0.18	0.25	0.30	
D	8.90	9.00	9.10	
D2	5.20	5.40	5.60	
E	8.90	9.00	9.10	
E2	5.20	5.40	5.60	
e	0.50 BSC			
L	0.35	0.40	0.45	
K	1.25	1.40	1.55	

Notes:
1. JEDEC Standard MO-220, (SAW Singulation) Fig. 1, VMMD.
2. Dimension and tolerance conform to ASMEY14.5M-1994.

2010-10-19

Atmel 2325 Orchard Parkway San Jose, CA 95131	**TITLE** **64M1**, 64-pad, 9 x 9 x 1.0 mm Body, Lead Pitch 0.50 mm, 5.40 mm Exposed Pad, Micro Lead Frame Package (MLF)	**DRAWING NO.** 64M1	**REV.** H

10.4 100A



COMMON DIMENSIONS
(Unit of Measure = mm)

SYMBOL	MIN	NOM	MAX	NOTE
A	–	–	1.20	
A1	0.05	–	0.15	
A2	0.95	1.00	1.05	
D	15.75	16.00	16.25	
D1	13.90	14.00	14.10	Note 2
E	15.75	16.00	16.25	
E1	13.90	14.00	14.10	Note 2
B	0.17	–	0.27	
C	0.09	–	0.20	
L	0.45	–	0.75	
e	0.50 TYP			

Notes:
1. This package conforms to JEDEC reference MS-026, Variation AED.
2. Dimensions D1 and E1 do not include mold protrusion. Allowable protrusion is 0.25mm per side. Dimensions D1 and E1 are maximum plastic body size dimensions including mold mismatch.
3. Lead coplanarity is 0.08mm maximum.

2014-02-05

Atmel Package Drawing Contact: packagedrawings@atmel.com	TITLE	DRAWING NO.	REV.
	100A, 100-lead, 14 x 14mm Body Size, 1.0mm Body Thickness, 0.5mm Lead Pitch, Thin Profile Plastic Quad Flat Package (TQFP)	100A	E

11. Errata

11.1 Atmel ATmega169A

No known errata

11.2 Atmel ATmega169A/169PA Rev. A to F

Not sampled.

11.3 Atmel ATmega169PA Rev. G

No known errata.

11.4 Atmel ATmega329A/329PA rev. A

- **Interrupts may be lost when writing the timer registers in the asynchronous timer**
- **Using BOD disable will make the chip reset**

1. **Interrupts may be lost when writing the timer registers in the asynchronous timer**

   The interrupt will be lost if a timer register that is synchronous timer clock is written when the asynchronous Timer/Counter register (TCNTx) is 0x00.

   Problem Fix/ Workaround

   Always check that the asynchronous Timer/Counter register neither have the value 0xFF nor 0x00 before writing to the asynchronous Timer Control Register (TCCRx), asynchronous Timer Counter Register (TCNTx), or asynchronous Output Compare Register (OCRx).

2. **Using BOD disable will make the chip reset**

   If the part enters sleep with the BOD turned off with the BOD disable option

   enabled, a BOD reset will be generated at wakeup and the chip will reset.

   Problem Fix/Workaround

   Do not use BOD disable

11.5 Atmel ATmega329A/329PA rev. B

- **Interrupts may be lost when writing the timer registers in the asynchronous timer**

1. **Interrupts may be lost when writing the timer registers in the asynchronous timer**

   The interrupt will be lost if a timer register that is synchronous timer clock is written when the asynchronous Timer/Counter register (TCNTx) is 0x00.

   Problem Fix/ Workaround

   Always check that the asynchronous Timer/Counter register neither have the value 0xFF nor 0x00 before writing to the asynchronous Timer Control Register (TCCRx), asynchronous Timer Counter Register (TCNTx), or asynchronous Output Compare Register (OCRx).

11.6 Atmel ATmega329A/329PA rev. C

- **Interrupts may be lost when writing the timer registers in the asynchronous timer**

1. **Interrupts may be lost when writing the timer registers in the asynchronous timer**

   The interrupt will be lost if a timer register that is synchronous timer clock is written when the asynchronous Timer/Counter register (TCNTx) is 0x00.

   Problem Fix/ Workaround

   Always check that the asynchronous Timer/Counter register neither have the value 0xFF nor 0x00 before writing to the asynchronous Timer Control Register (TCCRx), asynchronous Timer Counter Register (TCNTx), or asynchronous Output Compare Register (OCRx).

11.7 Atmel ATmega3290A/3290PA rev. A

- **Interrupts may be lost when writing the timer registers in the asynchronous timer**
- **Using BOD disable will make the chip reset**

1. **Interrupts may be lost when writing the timer registers in the asynchronous timer**

   The interrupt will be lost if a timer register that is synchronous timer clock is written when the asynchronous Timer/Counter register (TCNTx) is 0x00.

   Problem Fix/ Workaround

   Always check that the asynchronous Timer/Counter register neither have the value 0xFF nor 0x00 before writing to the asynchronous Timer Control Register (TCCRx), asynchronous Timer Counter Register (TCNTx), or asynchronous Output Compare Register (OCRx).

2. **Using BOD disable will make the chip reset**

   If the part enters sleep with the BOD turned off with the BOD disable option

   enabled, a BOD reset will be generated at wakeup and the chip will reset.

   Problem Fix/Workaround

   Do not use BOD disable

11.8 Atmel ATmega3290A/3290PA rev. B

- **Interrupts may be lost when writing the timer registers in the asynchronous timer**

1. **Interrupts may be lost when writing the timer registers in the asynchronous timer**

   The interrupt will be lost if a timer register that is synchronous timer clock is written when the asynchronous Timer/Counter register (TCNTx) is 0x00.

   Problem Fix/ Workaround

   Always check that the asynchronous Timer/Counter register neither have the value 0xFF nor 0x00 before writing to the asynchronous Timer Control Register (TCCRx), asynchronous Timer Counter Register (TCNTx), or asynchronous Output Compare Register (OCRx).