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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

Details

Product Status	Active
Core Processor	AVR
Core Size	8-Bit
Speed	16MHz
Connectivity	SPI, UART/USART, USI
Peripherals	Brown-out Detect/Reset, LCD, POR, PWM, WDT
Number of I/O	54
Program Memory Size	16KB (8K x 16)
Program Memory Type	FLASH
EEPROM Size	512 x 8
RAM Size	1K x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 5.5V
Data Converters	A/D 8x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	64-VFQFN Exposed Pad
Supplier Device Package	64-QFN (9x9)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/atmega169pa-mur

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

2. Overview

The Atmel ATmega169A/169PA/329A/329PA/3290A/3290PA/649A/649P/6490A/6490P is a low-power CMOS 8-bit microcontroller based on the Atmel®AVR® enhanced RISC architecture. By executing powerful instructions in a single clock cycle, the ATmega169A/169PA/329A/329PA/3290A/3290PA/649A/649P/6490A/6490P achieves throughputs approaching 1 MIPS per MHz allowing the system designer to optimize power consumption versus processing speed.

2.1 Block diagram

Figure 2-1. Block diagram.



The AVR core combines a rich instruction set with 32 general purpose working registers. All the 32 registers are directly connected to the Arithmetic Logic Unit (ALU), allowing two independent registers to be accessed in one



2.3 Pin descriptions

The following section describes the I/O-pin special functions.

2.3.1 V_{cc}

Digital supply voltage.

2.3.2 GND

Ground.

2.3.3 Port A (PA7...PA0)

Port A is an 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port A output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port A pins that are externally pulled low will source current if the pull-up resistors are activated. The Port A pins are tri-stated when a reset condition becomes active, even if the clock is not running.

Port A also serves the functions of various special features of the Atmel ATmega169A/169PA/329A/329PA/3290A/3290PA/649A/649A/6490P/6490A/6490P as listed on page 72.

2.3.4 Port B (PB7...PB0)

Port B is an 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port B output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port B pins that are externally pulled low will source current if the pull-up resistors are activated. The Port B pins are tri-stated when a reset condition becomes active, even if the clock is not running.

Port B has better driving capabilities than the other ports. Port B also serves the functions of various special features of the ATmega169A/169PA/329A/329PA/3290A/3290PA/649A/649P/6490A/6490P as listed on page 73.

2.3.5 Port C (PC7...PC0)

Port C is an 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port C output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port C pins that are externally pulled low will source current if the pull-up resistors are activated. The Port C pins are tri-stated when a reset condition becomes active, even if the clock is not running.

Port C also serves the functions of special features of the ATmega169A/169PA/329A/329PA/3290A/3290PA/649A/649P/6490A/6490P as listed on page 76.

2.3.6 Port D (PD7...PD0)

Port D is an 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port D output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port D pins that are externally pulled low will source current if the pull-up resistors are activated. The Port D pins are tri-stated when a reset condition becomes active, even if the clock is not running.

Port D also serves the functions of various special features of the ATmega169A/169PA/329A/329PA/3290A/3290PA/649A/649P/6490A/6490P as listed on page 77.

2.3.7 Port E (PE7...PE0)

Port E is an 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port E output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port E pins that



are externally pulled low will source current if the pull-up resistors are activated. The Port E pins are tri-stated when a reset condition becomes active, even if the clock is not running.

Port E also serves the functions of various special features of the ATmega169A/169PA/329A/329PA/3290A/3290PA/649A/649P/6490A/6490P as listed on page 79.

2.3.8 Port F (PF7...PF0)

Port F serves as the analog inputs to the A/D Converter.

Port F also serves as an 8-bit bi-directional I/O port, if the A/D Converter is not used. Port pins can provide internal pull-up resistors (selected for each bit). The Port F output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port F pins that are externally pulled low will source current if the pull-up resistors are activated. The Port F pins are tri-stated when a reset condition becomes active, even if the clock is not running. If the JTAG interface is enabled, the pull-up resistors on pins PF7(TDI), PF5(TMS), and PF4(TCK) will be activated even if a reset occurs.

Port F also serves the functions of the JTAG interface.

2.3.9 Port G (PG5...PG0)

Port G is a 6-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port G output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port G pins that are externally pulled low will source current if the pull-up resistors are activated. The Port G pins are tri-stated when a reset condition becomes active, even if the clock is not running.

Port G also serves the functions of various special features of the ATmega169A/169PA/329A/329PA/3290A/3290PA/649A/649P/6490A/6490P as listed on page 83.

2.3.10 Port H (PH7...PH0)

Port H is a 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port H output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port H pins that are externally pulled low will source current if the pull-up resistors are activated. The Port H pins are tri-stated when a reset condition becomes active, even if the clock is not running.

Port H also serves the functions of various special features of the ATmega3290PA/6490P as listed on page 85.

2.3.11 Port J (PJ6...PJ0)

Port J is a 7-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port J output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port J pins that are externally pulled low will source current if the pull-up resistors are activated. The Port J pins are tri-stated when a reset condition becomes active, even if the clock is not running.

Port J also serves the functions of various special features of the ATmega3290PA/6490P as listed on page 87.

2.3.12 RESET

Reset input. A low level on this pin for longer than the minimum pulse length will generate a reset, even if the clock is not running. The minimum pulse length is given in "System and reset characteristics" on page 332. Shorter pulses are not guaranteed to generate a reset.

2.3.13 XTAL1

Input to the inverting Oscillator amplifier and input to the internal clock operating circuit.

2.3.14 XTAL2

Output from the inverting Oscillator amplifier.



2.3.15 AVCC

AVCC is the supply voltage pin for Port F and the A/D Converter. It should be externally connected to V_{CC} , even if the ADC is not used. If the ADC is used, it should be connected to V_{CC} through a low-pass filter.

2.3.16 AREF

This is the analog reference pin for the A/D Converter.

2.3.17 LCDCAP

An external capacitor (typical > 470 nF) must be connected to the LCDCAP pin as shown in Figure 24-2, if the LCD module is enabled and configured to use internal power. This capacitor acts as a reservoir for LCD power (V_{LCD}). A large capacitance reduces ripple on V_{LCD} but increases the time until V_{LCD} reaches its target value.



3. Resources

A comprehensive set of development tools, application notes and datasheets are available for download on http://www.atmel.com/avr.

4. Data retention

Reliability Qualification results show that the projected data retention failure rate is much less than 1 PPM over 20 years at 85°C or 100 years at 25°C.

5. About code examples

This documentation contains simple code examples that briefly show how to use various parts of the device. These code examples assume that the part specific header file is included before compilation. Be aware that not all C compiler vendors include bit definitions in the header files and interrupt handling in C is compiler dependent. Please confirm with the C compiler documentation for more details.

For I/O Registers located in extended I/O map, "IN", "OUT", "SBIS", "SBIC", "CBI", and "SBI" instructions must be replaced with instructions that allow access to extended I/O. Typically "LDS" and "STS" combined with "SBRS", "SBRC", "SBR", and "CBR".

6. Capacitive touch sensing

The Atmel[®] QTouch[®] Library provides a simple to use solution to realize touch sensitive interfaces on most Atmel AVR[®] microcontrollers. The QTouch Library includes support for the QTouch and QMatrix[®] acquisition methods.

Touch sensing can be added to any application by linking the appropriate Atmel QTouch Library for the AVR Microcontroller. This is done by using a simple set of APIs to define the touch channels and sensors, and then calling the touch sensing API's to retrieve the channel information and determine the touch sensor states.

The QTouch Library is FREE and downloadable from the Atmel website at the following location: www.atmel.com/qtouchlibrary. For implementation details and other information, refer to the Atmel QTouch Library User Guide - also available for download from the Atmel website.

7. Register summary

Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Page
(0xFF)	LCDDR19	SEG339	SEG338	SEG337	SEG336	SEG335	SEG334	SEG333	SEG332	236
(0xFE)	LCDDR18	SEG331	SEG330	SEG329	SEG328	SEG327	SEG326	SEG325	SEG324	236
(0xFD)	LCDDR17	SEG323	SEG322	SEG321	SEG320	SEG319	SEG318	SEG317	SEG316	236
(0xFC)	LCDDR16	SEG315	SEG314	SEG313	SEG312	SEG311	SEG310	SEG309	SEG308	236
(0xFB)	LCDDR15	SEG307	SEG306	SEG305	SEG304	SEG303	SEG302	SEG301	SEG300	236
(0xFA)	LCDDR14	SEG239	SEG238	SEG237	SEG236	SEG235	SEG234	SEG233	SEG232	236
(0xF9)	LCDDR13	SEG231	SEG230	SEG229	SEG228	SEG227	SEG226	SEG225	SEG224	236
(0xF8)	LCDDR12	SEG223	SEG222	SEG221	SEG220	SEG219	SEG218	SEG217	SEG216	236
(0xF7)	LCDDR11	SEG215	SEG214	SEG213	SEG212	SEG211	SEG210	SEG209	SEG208	236
(0xF6)	LCDDR10	SEG207	SEG206	SEG205	SEG204	SEG203	SEG202	SEG201	SEG200	236
(0xE5)	LCDDR09	SEG139	SEG138	SEG137	SEG136	SEG135	SEG134	SEG133	SEG132	236

Note: Registers with bold type only available in Atmel ATmega3290A/3290PA/6490A/6490P.







Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Page
0x11 (0x31)	PORTF	PORTF7	PORTF6	PORTF5	PORTF4	PORTF3	PORTF2	PORTF1	PORTF0	92
0x10 (0x30)	DDRF	DDF7	DDF6	DDF5	DDF4	DDF3	DDF2	DDF1	DDF0	92
0x0F (0x2F)	PINF	PINF7	PINF6	PINF5	PINF4	PINF3	PINF2	PINF1	PINF0	92
0x0E (0x2E)	PORTE	PORTE7	PORTE6	PORTE5	PORTE4	PORTE3	PORTE2	PORTE1	PORTE0	91
0x0D (0x2D)	DDRE	DDE7	DDE6	DDE5	DDE4	DDE3	DDE2	DDE1	DDE0	92
0x0C (0x2C)	PINE	PINE7	PINE6	PINE5	PINE4	PINE3	PINE2	PINE1	PINE0	92
0x0B (0x2B)	PORTD	PORTD7	PORTD6	PORTD5	PORTD4	PORTD3	PORTD2	PORTD1	PORTD0	91
0x0A (0x2A)	DDRD	DDD7	DDD6	DDD5	DDD4	DDD3	DDD2	DDD1	DDD0	91
0x09 (0x29)	PIND	PIND7	PIND6	PIND5	PIND4	PIND3	PIND2	PIND1	PIND0	91
0x08 (0x28)	PORTC	PORTC7	PORTC6	PORTC5	PORTC4	PORTC3	PORTC2	PORTC1	PORTC0	91
0x07 (0x27)	DDRC	DDC7	DDC6	DDC5	DDC4	DDC3	DDC2	DDC1	DDC0	91
0x06 (0x26)	PINC	PINC7	PINC6	PINC5	PINC4	PINC3	PINC2	PINC1	PINC0	91
0x05 (0x25)	PORTB	PORTB7	PORTB6	PORTB5	PORTB4	PORTB3	PORTB2	PORTB1	PORTB0	90
0x04 (0x24)	DDRB	DDB7	DDB6	DDB5	DDB4	DDB3	DDB2	DDB1	DDB0	90
0x03 (0x23)	PINB	PINB7	PINB6	PINB5	PINB4	PINB3	PINB2	PINB1	PINB0	91
0x02 (0x22)	PORTA	PORTA7	PORTA6	PORTA5	PORTA4	PORTA3	PORTA2	PORTA1	PORTA0	90
0x01 (0x21)	DDRA	DDA7	DDA6	DDA5	DDA4	DDA3	DDA2	DDA1	DDA0	90
0x00 (0x20)	PINA	PINA7	PINA6	PINA5	PINA4	PINA3	PINA2	PINA1	PINA0	90

Notes: 1. For compatibility with future devices, reserved bits should be written to zero if accessed. Reserved I/O memory addresses should never be written.

- 2. I/O Registers within the address range 0x00 0x1F are directly bit-accessible using the SBI and CBI instructions. In these registers, the value of single bits can be checked by using the SBIS and SBIC instructions.
- Some of the Status Flags are cleared by writing a logical one to them. Note that, unlike most other AVRs, the CBI and SBI instructions will only operate on the specified bit, and can therefore be used on registers containing such Status Flags. The CBI and SBI instructions work with registers 0x00 to 0x1F only.
- 4. When using the I/O specific commands IN and OUT, the I/O addresses 0x00 0x3F must be used. When addressing I/O Registers as data space using LD and ST instructions, 0x20 must be added to these addresses. The Atmel ATmega169A/169PA/329A/329PA/3290A/3290PA/649A/649P/6490A/6490P is a complex microcontroller with more peripheral units than can be supported within the 64 location reserved in Opcode for the IN and OUT instructions. For the Extended I/O space from 0x60 0xFF in SRAM, only the ST/STS/STD and LD/LDS/LDD instructions can be used.



Mnemonics	Operands	Description	Operation	Flags	#Clocks
BRVC	k	Branch if Overflow Flag is Cleared	if (V = 0) then PC \leftarrow PC + k + 1	None	1/2
BRIE	k	Branch if Interrupt Enabled	if (I = 1) then PC \leftarrow PC + k + 1	None	1/2
BRID	k	Branch if Interrupt Disabled	if (I = 0) then PC \leftarrow PC + k + 1	None	1/2
BIT AND BIT-TEST I	NSTRUCTIONS		1		
SBI	P,b	Set Bit in I/O Register	I/O(P,b) ← 1	None	2
CBI	P,b	Clear Bit in I/O Register	$I/O(P,b) \leftarrow 0$	None	2
LSL	Rd	Logical Shift Left	$Rd(n+1) \leftarrow Rd(n), Rd(0) \leftarrow 0$	Z,C,N,V	1
ROI	Ru	Logical Shill Right	$Rd(II) \leftarrow Rd(II+I), Rd(I) \leftarrow 0$ $Rd(0) \leftarrow C Rd(n+1), Rd(n) \leftarrow 0$		1
ROR	Rd	Rotate Right Through Carry	$Rd(7) \leftarrow C Rd(n) \leftarrow Rd(n+1) C \leftarrow Rd(0)$	ZCNV	1
ASR	Rd	Arithmetic Shift Right	$Rd(n) \leftarrow Rd(n+1), n=06$	Z,C,N,V	1
SWAP	Rd	Swap Nibbles	Rd(30)←Rd(74),Rd(74)←Rd(30)	None	1
BSET	s	Flag Set	$SREG(s) \leftarrow 1$	SREG(s)	1
BCLR	s	Flag Clear	$SREG(s) \leftarrow 0$	SREG(s)	1
BST	Rr, b	Bit Store from Register to T	$T \leftarrow Rr(b)$	Т	1
BLD	Rd, b	Bit load from T to Register	$Rd(b) \leftarrow T$	None	1
SEC		Set Carry	C ← 1	С	1
CLC		Clear Carry	C ← 0	C	1
SEN		Set Negative Flag	N ← 1	N	1
CLN		Clear Negative Flag		N 7	1
SEZ		Set Zero Flag		Z 7	1
SEL		Global Interrupt Enable		1	1
CLI		Global Interrupt Disable			1
SES		Set Signed Test Flag	S ← 1	S	1
CLS		Clear Signed Test Flag	S ← 0	S	1
SEV		Set Twos Complement Overflow.	V ← 1	V	1
CLV		Clear Twos Complement Overflow	V ← 0	V	1
SET		Set T in SREG	T ← 1	Т	1
CLT		Clear T in SREG	T ← 0	Т	1
SEH		Set Half Carry Flag in SREG	H ← 1	Н	1
CLH		Clear Half Carry Flag in SREG	H ← 0	Н	1
DATA TRANSFER IN	NSTRUCTIONS			1	
MOV	Rd, Rr	Move Between Registers	Rd ← Rr	None	1
MOVW	Rd, Rr	Copy Register Word	$Rd+1:Rd \leftarrow Rr+1:Rr$	None	1
LDI	Ra, K Rd Y		$Rd \leftarrow K$	None	1
	Rd X+	Load Indirect and Post-Inc	$Rd \leftarrow (X) X \leftarrow X + 1$	None	2
LD	Rd X	Load Indirect and Pre-Dec.	$X \leftarrow X - 1$, $Bd \leftarrow (X)$	None	2
LD	Rd, Y	Load Indirect	$Rd \leftarrow (Y)$	None	2
LD	Rd, Y+	Load Indirect and Post-Inc.	$Rd \leftarrow (Y), Y \leftarrow Y + 1$	None	2
LD	Rd, - Y	Load Indirect and Pre-Dec.	$Y \leftarrow Y - 1$, Rd $\leftarrow (Y)$	None	2
LDD	Rd,Y+q	Load Indirect with Displacement	$Rd \leftarrow (Y + q)$	None	2
LD	Rd, Z	Load Indirect	$Rd \leftarrow (Z)$	None	2
LD	Rd, Z+	Load Indirect and Post-Inc.	$Rd \leftarrow (Z), Z \leftarrow Z+1$	None	2
LD	Rd, -Z	Load Indirect and Pre-Dec.	$Z \leftarrow Z - 1, Rd \leftarrow (Z)$	None	2
LDD	Rd, Z+q	Load Indirect with Displacement	$Rd \leftarrow (Z + q)$	None	2
LDS	Ra, K	Load Direct from SRAM	$Rd \leftarrow (K)$	None	2
ST	X+ Br	Store Indirect and Post-Inc	$(X) \leftarrow Ri$	None	2
ST	- X. Rr	Store Indirect and Pre-Dec	$X \leftarrow X - 1$, $(X) \leftarrow Rr$	None	2
ST	Y. Rr	Store Indirect	$(Y) \leftarrow Rr$	None	2
ST	Y+, Rr	Store Indirect and Post-Inc.	$(Y) \leftarrow Rr, Y \leftarrow Y + 1$	None	2
ST	- Y, Rr	Store Indirect and Pre-Dec.	$Y \leftarrow Y - 1, (Y) \leftarrow Rr$	None	2
STD	Y+q,Rr	Store Indirect with Displacement	$(Y + q) \leftarrow Rr$	None	2
ST	Z, Rr	Store Indirect	$(Z) \leftarrow Rr$	None	2
ST	Z+, Rr	Store Indirect and Post-Inc.	$(Z) \leftarrow Rr, Z \leftarrow Z + 1$	None	2
ST	-Z, Rr	Store Indirect and Pre-Dec.	$Z \leftarrow Z - 1$, (Z) $\leftarrow Rr$	None	2
STD	Z+q,Rr	Store Indirect with Displacement	$(Z + q) \leftarrow Rr$	None	2
STS	k, Rr	Store Direct to SRAM	$(k) \leftarrow Rr$	None	2
		Load Program Memory	$KU \leftarrow (Z)$	None	3
	rku, Z		$Ru \leftarrow (\mathcal{L})$ $Pd_{\mathcal{L}}(7) = 7 \cdot 7 \cdot 1$	None	ు ా
SPM	rtu, ∠†	Store Program Memory	$1 \land u \leftarrow (Z), Z \leftarrow Z^+ I$ $(Z) \leftarrow P1 \cdot P0$	None	3
IN	Rd P		$Rd \leftarrow P$	None	- 1
OUT	P. Rr	Out Port	P ← Rr	None	1
PUSH	Rr	Push Register on Stack	STACK ← Rr	None	2
POP	Rd	Pop Register from Stack	$Rd \leftarrow STACK$	None	2



Mnemonics	Operands	Description	Operation	Flags	#Clocks
MCU CONTROL INS	TRUCTIONS				
NOP		No Operation		None	1
SLEEP		Sleep	(see specific descr. for Sleep function)	None	1
WDR		Watchdog Reset	(see specific descr. for WDR/timer)	None	1
BREAK		Break	For On-chip Debug Only	None	N/A

9.2 Atmel ATmega169PA

Speed [MHz] ⁽³⁾	Power supply	Ordering code ⁽²⁾	Package type ⁽¹⁾	Operational range
16	1.8 - 5.5V	ATmega169PA-AU ATmega169PA-AUR ⁽⁴⁾ ATmega169PA-MU ATmega169PA-MUR ⁽⁴⁾ ATmega169PA-MCH ATmega169PA-MCHR ⁽⁴⁾	64A 64A 64M1 64M1 64MC 64MC	Industrial (-40°C to 85°C)
		ATmega169PA-AN ATmega169PA-ANR ⁽⁴⁾ ATmega169PA-MN ATmega169PA-MNR ⁽⁴⁾	64A 64A 64M1 64M1	Extended (-40°C to 105°C) ⁽⁵⁾

Notes: 1. This device can also be supplied in wafer form. Please contact your local Atmel sales office for detailed ordering information and minimum quantities.

2. Pb-free packaging, complies to the European Directive for Restriction of Hazardous Substances (RoHS directive). Also Halide free and fully Green.

3. For Speed vs. V_{CC} , see Figure 29-1 on page 330.

- 4. Tape & Reel.
- 5. See characterization specification at 105°C.

Package type				
	64-lead, thin (1.0mm) plastic Gull Wing Quad Flat Package (TQFP)			
	64-pad, 9 × 9 × 1.0mm body, lead pitch 0.50mm, Quad Flat No-Lead/Micro Lead Frame Package (QFN/MLF)			
	64-lead (2-row Staggered), 7 × 7 × 1.0mm body, 4.0 × 4.0mm Exposed Pad, Quad Flat No-Lead Package (QFN)			

9.3 Atmel ATmega329A

Speed [MHz] ⁽³⁾	Power supply	Ordering code ⁽²⁾	Package type ⁽¹⁾	Operational range
20	18 551/	ATmega329A-AU ATmega329A-AUR ⁽⁴⁾ ATmega329A-MU ATmega329A-MUR ⁽⁴⁾	64A 64A 64M1 64M1	Industrial (-40°C to 85°C)
20	1.0 - 5.5 V	ATmega329A-AN ATmega329A-ANR ⁽⁴⁾ ATmega329A-MN ATmega329A-MNR ⁽⁴⁾	64A 64A 64M1 64M1	Extended (-40°C to 105°C) ⁽⁵⁾

Notes: 1. This device can also be supplied in wafer form. Please contact your local Atmel sales office for detailed ordering information and minimum quantities.

2. Pb-free packaging complies to the European Directive for Restriction of Hazardous Substances (RoHS directive). Also Halide free and fully Green.

- 3. For Speed vs. V_{CC} see Figure 29-2 on page 330.
- 4. Tape & Reel.
- 5. See characterization specifications at 105°C.

Package type				
	64-lead, 14 × 14 × 1.0mm, thin profile plastic Quad Flat Package (TQFP)			
	64-pad, 9 × 9 × 1.0mm, Quad Flat No-Lead/Micro Lead Frame Package (QFN/MLF)			

9.5 Atmel ATmega3290A

Speed [MHz] ⁽³⁾	Power supply	Ordering code ⁽²⁾	Package type ⁽¹⁾	Operational range
20	18 551	ATmega3290A-AU ATmega3290A-AUR ⁽⁴⁾	100A 100A	Industrial (-40°C to 85°C)
20	1.0 - 5.5V	ATmega3290A-AN ATmega3290A-ANR ⁽⁴⁾	100A 100A	Extended (-40°C to 105°C) ⁽⁵⁾

Notes: 1. This device can also be supplied in wafer form. Please contact your local Atmel sales office for detailed ordering information and minimum quantities.

2. Pb-free packaging complies to the European Directive for Restriction of Hazardous Substances (RoHS directive). Also Halide free and fully Green.

3. For Speed vs. V_{CC} see Figure 29-2 on page 330.

4. Tape & Reel.

5. See characterization specification at 105°C.

Package type

100-lead, 14 × 14 × 1.0mm, 0.5mm Lead Pitch, Thin Profile Plastic Quad Flat Package (TQFP)



9.7 Atmel ATmega649A

Speed [MHz] ⁽³⁾	Power supply	Ordering code ⁽²⁾	Package type ⁽¹⁾	Operational range
16	1.8 - 5.5V	ATmega649A-AU ATmega649A-AUR ⁽⁴⁾ ATmega649A-MU ATmega649A-MUR ⁽⁴⁾	64A 64A 64M1 64M1	Industrial (-40°C to 85°C)

Notes: 1. This device can also be supplied in wafer form. Please contact your local Atmel sales office for detailed ordering information and minimum quantities.

2. Pb-free packaging complies to the European Directive for Restriction of Hazardous Substances (RoHS directive). Also Halide free and fully Green.

3. For Speed vs. V_{CC} see Figure 29-1 on page 330.

4. Tape & Reel.

Package type				
	64-lead, 14 × 14 × 1.0mm, Thin Profile Plastic Quad Flat Package (TQFP)			
	64-pad, 9 × 9 × 1.0mm, Quad Flat No-Lead/Micro Lead Frame Package (QFN/MLF)			

9.8 Atmel ATmega649P

Speed [MHz] ⁽³⁾	Power supply	Ordering code ⁽²⁾	Package type ⁽¹⁾	Operational range
16	1.8 - 5.5 V	ATmega649P-AU ATmega649P-AUR ⁽⁴⁾ ATmega649P-MU ATmega649P-MUR ⁽⁴⁾	64A 64A 64M1 64M1	Industrial (-40°C to 85°C)

Notes: 1. This device can also be supplied in wafer form. Please contact your local Atmel sales office for detailed ordering information and minimum quantities.

2. Pb-free packaging complies to the European Directive for Restriction of Hazardous Substances (RoHS directive). Also Halide free and fully Green.

3. For Speed vs. V_{CC} see Figure 29-1 on page 330.

4. Tape & Reel.

Package type				
	64-lead, 14 × 14 × 1.0mm, Thin Profile Plastic Quad Flat Package (TQFP)			
	64-pad, 9 × 9 × 1.0mm, Quad Flat No-Lead/Micro Lead Frame Package (QFN/MLF)			

9.9 Atmel ATmega6490A

Speed [MHz] ⁽³⁾	Power supply	Ordering code ⁽²⁾	Package type ⁽¹⁾	Operational range
20	1.8 - 5.5V	ATmega6490A-AU ATmega6490A-AUR ⁽⁴⁾	100A 100A	Industrial (-40°C to 85°C)

Notes: 1. This device can also be supplied in wafer form. Please contact your local Atmel sales office for detailed ordering information and minimum quantities.

2. Pb-free packaging complies to the European Directive for Restriction of Hazardous Substances (RoHS directive). Also Halide free and fully Green.

3. For Speed vs. V_{CC} see Figure 29-2 on page 330.

4. Tape & Reel.

Package type

100-lead, 14 × 14 × 1.0mm, 0.5mm Lead Pitch, Thin Profile Plastic Quad Flat Package (TQFP)



9.10 Atmel ATmega6490P

Speed [MHz] ⁽³⁾	Power supply	Ordering code ⁽²⁾	Package type ⁽¹⁾	Operational range
20	1.8 - 5.5V	ATmega6490P-AU ATmega6490P-AUR ⁽⁴⁾	100A 100A	Industrial (-40°C to 85°C)

Notes: 1. This device can also be supplied in wafer form. Please contact your local Atmel sales office for detailed ordering information and minimum quantities.

2. Pb-free packaging complies to the European Directive for Restriction of Hazardous Substances (RoHS directive). Also Halide free and fully Green.

3. For Speed vs. V_{CC} see Figure 29-2 on page 330.

4. Tape & Reel.

Package Type

100-lead, 14 × 14 × 1.0mm, 0.5mm Lead Pitch, Thin Profile Plastic Quad Flat Package (TQFP)





Atmel

11. Errata

11.1 Atmel ATmega169A

No known errata

11.2 Atmel ATmega169A/169PA Rev. A to F

Not sampled.

11.3 Atmel ATmega169PA Rev. G

No known errata.

11.4 Atmel ATmega329A/329PA rev. A

- · Interrupts may be lost when writing the timer registers in the asynchronous timer
- Using BOD disable will make the chip reset

1. Interrupts may be lost when writing the timer registers in the asynchronous timer

The interrupt will be lost if a timer register that is synchronous timer clock is written when the asynchronous Timer/Counter register (TCNTx) is 0x00.

Problem Fix/ Workaround

Always check that the asynchronous Timer/Counter register neither have the value 0xFF nor 0x00 before writing to the asynchronous Timer Control Register (TCCRx), asynchronous Timer Counter Register (TCNTx), or asynchronous Output Compare Register (OCRx).

2. Using BOD disable will make the chip reset

If the part enters sleep with the BOD turned off with the BOD disable option enabled, a BOD reset will be generated at wakeup and the chip will reset.

Problem Fix/Workaround

Do not use BOD disable

11.5 Atmel ATmega329A/329PA rev. B

Interrupts may be lost when writing the timer registers in the asynchronous timer

1. Interrupts may be lost when writing the timer registers in the asynchronous timer

The interrupt will be lost if a timer register that is synchronous timer clock is written when the asynchronous Timer/Counter register (TCNTx) is 0x00.

Problem Fix/ Workaround

Always check that the asynchronous Timer/Counter register neither have the value 0xFF nor 0x00 before writing to the asynchronous Timer Control Register (TCCRx), asynchronous Timer Counter Register (TCNTx), or asynchronous Output Compare Register (OCRx).



11.6 Atmel ATmega329A/329PA rev. C

· Interrupts may be lost when writing the timer registers in the asynchronous timer

1. Interrupts may be lost when writing the timer registers in the asynchronous timer

The interrupt will be lost if a timer register that is synchronous timer clock is written when the asynchronous Timer/Counter register (TCNTx) is 0x00.

Problem Fix/ Workaround

Always check that the asynchronous Timer/Counter register neither have the value 0xFF nor 0x00 before writing to the asynchronous Timer Control Register (TCCRx), asynchronous Timer Counter Register (TCNTx), or asynchronous Output Compare Register (OCRx).

11.7 Atmel ATmega3290A/3290PA rev. A

- · Interrupts may be lost when writing the timer registers in the asynchronous timer
- Using BOD disable will make the chip reset

1. Interrupts may be lost when writing the timer registers in the asynchronous timer

The interrupt will be lost if a timer register that is synchronous timer clock is written when the asynchronous Timer/Counter register (TCNTx) is 0x00.

Problem Fix/ Workaround

Always check that the asynchronous Timer/Counter register neither have the value 0xFF nor 0x00 before writing to the asynchronous Timer Control Register (TCCRx), asynchronous Timer Counter Register (TCNTx), or asynchronous Output Compare Register (OCRx).

2. Using BOD disable will make the chip reset

If the part enters sleep with the BOD turned off with the BOD disable option enabled, a BOD reset will be generated at wakeup and the chip will reset.

Problem Fix/Workaround

Do not use BOD disable

11.8 Atmel ATmega3290A/3290PA rev. B

• Interrupts may be lost when writing the timer registers in the asynchronous timer

1. Interrupts may be lost when writing the timer registers in the asynchronous timer

The interrupt will be lost if a timer register that is synchronous timer clock is written when the asynchronous Timer/Counter register (TCNTx) is 0x00.

Problem Fix/ Workaround

Always check that the asynchronous Timer/Counter register neither have the value 0xFF nor 0x00 before writing to the asynchronous Timer Control Register (TCCRx), asynchronous Timer Counter Register (TCNTx), or asynchronous Output Compare Register (OCRx).



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