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What is "Embedded - Microcontrollers"?

"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

Details

E·XF

Product Status	Active
Core Processor	AVR
Core Size	8-Bit
Speed	20MHz
Connectivity	SPI, UART/USART, USI
Peripherals	Brown-out Detect/Reset, LCD, POR, PWM, WDT
Number of I/O	69
Program Memory Size	32KB (16K x 16)
Program Memory Type	FLASH
EEPROM Size	1K x 8
RAM Size	2K x 8
Voltage - Supply (Vcc/Vdd)	2.7V ~ 5.5V
Data Converters	A/D 8x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	100-TQFP
Supplier Device Package	100-TQFP (14x14)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/atmega3290pa-aur

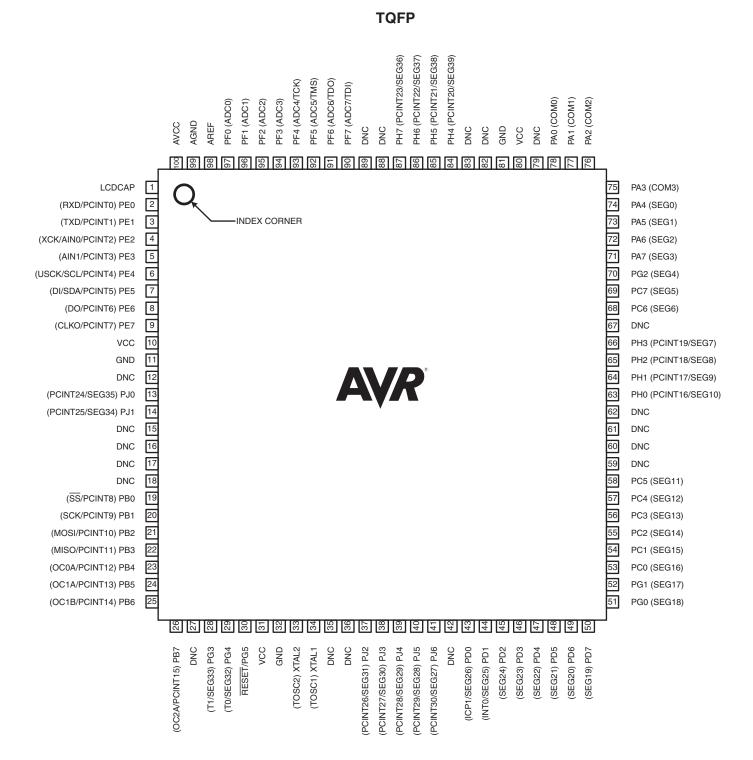
Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong

- Real Time Counter with separate oscillator
- Four PWM channels
- 8-channel, 10-bit ADC
- Programmable Serial USART
- Master/Slave SPI Serial Interface
- Universal Serial Interface with Start Condition Detector
- Programmable Watchdog Timer with Separate On-chip oscillator
- On-chip analog comparator
- Interrupt and Wake-up on pin change
- Special microcontroller features
 - Power-on reset and programmable Brown-out detection
 - Internal calibrated oscillator
 - External and internal interrupt sources
 - Five sleep modes: Idle, ADC Noise Reduction, Power-save, Power-down, and Standby
- I/O and packages
 - 54/69 programmable I/O lines
 - 64/100-lead TQFP, 64-pad QFN/MLF, and 64-pad DRQFN
- Speed Grade:
 - ATmega169A/169PA/649A/649P:
 - 0 16MHz @ 1.8 5.5V
 - ATmega3290A/3290PA/6490A/6490P:
 - 0 20MHz @ 1.8 5.5V
- Temperature range:
 - -40°C to 85°C industrial
- Ultra-low power consumption (picoPower[®] devices)
 - Active mode:
 - 1MHz, 1.8V: 215µA
 - 32kHz, 1.8V: 8µA (including oscillator)
 - 32kHz, 1.8V: 25µA (including oscillator and LCD)
 - Power-down mode:
 - 0.1µA at 1.8V
 - Power-save mode:
 - 0.6µA at 1.8V (Including 32kHz RTC)
 - 750nA at 1.8V

1.2 Pinout - 100A (TQFP)





Note: The large center pad underneath the QFN/MLF packages is made of metal and internally connected to GND. It should be soldered or glued to the board to ensure good mechanical stability. If the center pad is left unconnected, the package might loosen from the board.



1.3 Pinout - 64MC (DRQFN)



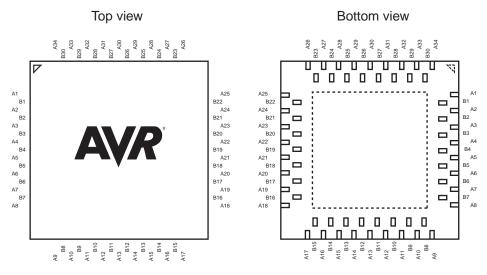


Table 1-1. DRQFN-64 Pinout ATmega169A/ATmega169PA.

PE0	PB7	PG1 (SEG13)	PA2 (COM2)
VLCDCAP	PB6	PG0 (SEG14)	PA3 (COM3)
PE1	PG3	PC0 (SEG12)	PA1 (COM1)
PE2	PG4	PC1 (SEG11)	PA0 (COM0)
PE3	RESET	PC2 (SEG10)	VCC
PE4	VCC	PC3 (SEG9)	GND
PE5	GND	PC4 (SEG8)	PF7
PE6	XTAL2 (TOSC2)	PC5 (SEG7)	PF6
PE7	XTAL1 (TOSC1)	PC6 (SEG6)	PF5
PB0	PD0 (SEG22)	PC7 (SEG5)	PF4
PB1	PD1 (SEG21)	PG2 (SEG4)	PF3
PB2	PD2 (SEG20)	PA7 (SEG3)	PF2
PB3	PD3 (SEG19)	PA6 (SEG2)	PF1
PB5	PD4 (SEG18)	PA4 (SEG0)	PF0
PB4	PD5 (SEG17)	PA5 (SEG1)	AREF
	PD7 (SEG15)		AVCC
	PD6 (SEG16)		GND

2.3 Pin descriptions

The following section describes the I/O-pin special functions.

2.3.1 V_{cc}

Digital supply voltage.

2.3.2 GND

Ground.

2.3.3 Port A (PA7...PA0)

Port A is an 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port A output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port A pins that are externally pulled low will source current if the pull-up resistors are activated. The Port A pins are tri-stated when a reset condition becomes active, even if the clock is not running.

Port A also serves the functions of various special features of the Atmel ATmega169A/169PA/329A/329PA/3290A/3290PA/649A/649P/6490A/6490P as listed on page 72.

2.3.4 Port B (PB7...PB0)

Port B is an 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port B output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port B pins that are externally pulled low will source current if the pull-up resistors are activated. The Port B pins are tri-stated when a reset condition becomes active, even if the clock is not running.

Port B has better driving capabilities than the other ports. Port B also serves the functions of various special features of the ATmega169A/169PA/329A/329PA/3290A/3290PA/649A/649P/6490A/6490P as listed on page 73.

2.3.5 Port C (PC7...PC0)

Port C is an 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port C output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port C pins that are externally pulled low will source current if the pull-up resistors are activated. The Port C pins are tri-stated when a reset condition becomes active, even if the clock is not running.

Port C also serves the functions of special features of the ATmega169A/169PA/329A/329PA/3290A/3290PA/649A/649P/6490A/6490P as listed on page 76.

2.3.6 Port D (PD7...PD0)

Port D is an 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port D output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port D pins that are externally pulled low will source current if the pull-up resistors are activated. The Port D pins are tri-stated when a reset condition becomes active, even if the clock is not running.

Port D also serves the functions of various special features of the ATmega169A/169PA/329A/329PA/3290A/3290PA/649A/649P/6490A/6490P as listed on page 77.

2.3.7 Port E (PE7...PE0)

Port E is an 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port E output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port E pins that



are externally pulled low will source current if the pull-up resistors are activated. The Port E pins are tri-stated when a reset condition becomes active, even if the clock is not running.

Port E also serves the functions of various special features of the ATmega169A/169PA/329A/329PA/3290A/3290PA/649A/649P/6490A/6490P as listed on page 79.

2.3.8 Port F (PF7...PF0)

Port F serves as the analog inputs to the A/D Converter.

Port F also serves as an 8-bit bi-directional I/O port, if the A/D Converter is not used. Port pins can provide internal pull-up resistors (selected for each bit). The Port F output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port F pins that are externally pulled low will source current if the pull-up resistors are activated. The Port F pins are tri-stated when a reset condition becomes active, even if the clock is not running. If the JTAG interface is enabled, the pull-up resistors on pins PF7(TDI), PF5(TMS), and PF4(TCK) will be activated even if a reset occurs.

Port F also serves the functions of the JTAG interface.

2.3.9 Port G (PG5...PG0)

Port G is a 6-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port G output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port G pins that are externally pulled low will source current if the pull-up resistors are activated. The Port G pins are tri-stated when a reset condition becomes active, even if the clock is not running.

Port G also serves the functions of various special features of the ATmega169A/169PA/329A/329PA/3290A/3290PA/649A/649P/6490A/6490P as listed on page 83.

2.3.10 Port H (PH7...PH0)

Port H is a 8-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port H output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port H pins that are externally pulled low will source current if the pull-up resistors are activated. The Port H pins are tri-stated when a reset condition becomes active, even if the clock is not running.

Port H also serves the functions of various special features of the ATmega3290PA/6490P as listed on page 85.

2.3.11 Port J (PJ6...PJ0)

Port J is a 7-bit bi-directional I/O port with internal pull-up resistors (selected for each bit). The Port J output buffers have symmetrical drive characteristics with both high sink and source capability. As inputs, Port J pins that are externally pulled low will source current if the pull-up resistors are activated. The Port J pins are tri-stated when a reset condition becomes active, even if the clock is not running.

Port J also serves the functions of various special features of the ATmega3290PA/6490P as listed on page 87.

2.3.12 RESET

Reset input. A low level on this pin for longer than the minimum pulse length will generate a reset, even if the clock is not running. The minimum pulse length is given in "System and reset characteristics" on page 332. Shorter pulses are not guaranteed to generate a reset.

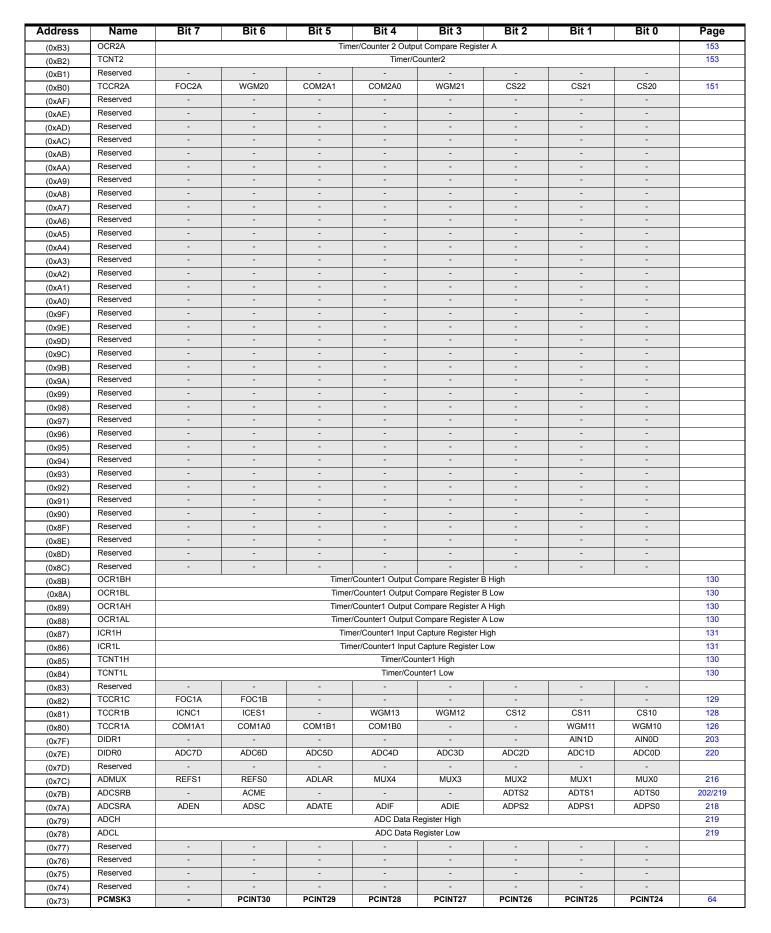
2.3.13 XTAL1

Input to the inverting Oscillator amplifier and input to the internal clock operating circuit.

2.3.14 XTAL2

Output from the inverting Oscillator amplifier.







Address	Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Page
0x11 (0x31)	PORTF	PORTF7	PORTF6	PORTF5	PORTF4	PORTF3	PORTF2	PORTF1	PORTF0	92
0x10 (0x30)	DDRF	DDF7	DDF6	DDF5	DDF4	DDF3	DDF2	DDF1	DDF0	92
0x0F (0x2F)	PINF	PINF7	PINF6	PINF5	PINF4	PINF3	PINF2	PINF1	PINF0	92
0x0E (0x2E)	PORTE	PORTE7	PORTE6	PORTE5	PORTE4	PORTE3	PORTE2	PORTE1	PORTE0	91
0x0D (0x2D)	DDRE	DDE7	DDE6	DDE5	DDE4	DDE3	DDE2	DDE1	DDE0	92
0x0C (0x2C)	PINE	PINE7	PINE6	PINE5	PINE4	PINE3	PINE2	PINE1	PINE0	92
0x0B (0x2B)	PORTD	PORTD7	PORTD6	PORTD5	PORTD4	PORTD3	PORTD2	PORTD1	PORTD0	91
0x0A (0x2A)	DDRD	DDD7	DDD6	DDD5	DDD4	DDD3	DDD2	DDD1	DDD0	91
0x09 (0x29)	PIND	PIND7	PIND6	PIND5	PIND4	PIND3	PIND2	PIND1	PIND0	91
0x08 (0x28)	PORTC	PORTC7	PORTC6	PORTC5	PORTC4	PORTC3	PORTC2	PORTC1	PORTC0	91
0x07 (0x27)	DDRC	DDC7	DDC6	DDC5	DDC4	DDC3	DDC2	DDC1	DDC0	91
0x06 (0x26)	PINC	PINC7	PINC6	PINC5	PINC4	PINC3	PINC2	PINC1	PINC0	91
0x05 (0x25)	PORTB	PORTB7	PORTB6	PORTB5	PORTB4	PORTB3	PORTB2	PORTB1	PORTB0	90
0x04 (0x24)	DDRB	DDB7	DDB6	DDB5	DDB4	DDB3	DDB2	DDB1	DDB0	90
0x03 (0x23)	PINB	PINB7	PINB6	PINB5	PINB4	PINB3	PINB2	PINB1	PINB0	91
0x02 (0x22)	PORTA	PORTA7	PORTA6	PORTA5	PORTA4	PORTA3	PORTA2	PORTA1	PORTA0	90
0x01 (0x21)	DDRA	DDA7	DDA6	DDA5	DDA4	DDA3	DDA2	DDA1	DDA0	90
0x00 (0x20)	PINA	PINA7	PINA6	PINA5	PINA4	PINA3	PINA2	PINA1	PINA0	90

Notes: 1. For compatibility with future devices, reserved bits should be written to zero if accessed. Reserved I/O memory addresses should never be written.

- 2. I/O Registers within the address range 0x00 0x1F are directly bit-accessible using the SBI and CBI instructions. In these registers, the value of single bits can be checked by using the SBIS and SBIC instructions.
- Some of the Status Flags are cleared by writing a logical one to them. Note that, unlike most other AVRs, the CBI and SBI instructions will only operate on the specified bit, and can therefore be used on registers containing such Status Flags. The CBI and SBI instructions work with registers 0x00 to 0x1F only.
- 4. When using the I/O specific commands IN and OUT, the I/O addresses 0x00 0x3F must be used. When addressing I/O Registers as data space using LD and ST instructions, 0x20 must be added to these addresses. The Atmel ATmega169A/169PA/329A/329PA/3290A/3290PA/649A/649P/6490A/6490P is a complex microcontroller with more peripheral units than can be supported within the 64 location reserved in Opcode for the IN and OUT instructions. For the Extended I/O space from 0x60 0xFF in SRAM, only the ST/STS/STD and LD/LDS/LDD instructions can be used.



Mnemonics	Operands	Description	Operation	Flags	#Clocks
BRVC	k	Branch if Overflow Flag is Cleared	if (V = 0) then PC \leftarrow PC + k + 1	None	1/2
BRIE	k	Branch if Interrupt Enabled	if (I = 1) then PC \leftarrow PC + k + 1	None	1/2
BRID	k	Branch if Interrupt Disabled	if (I = 0) then PC \leftarrow PC + k + 1	None	1/2
BIT AND BIT-TEST	INSTRUCTIONS				
SBI	P,b	Set Bit in I/O Register	I/O(P,b) ← 1	None	2
CBI	P,b	Clear Bit in I/O Register	I/O(P,b) ← 0	None	2
LSL	Rd	Logical Shift Left	$Rd(n+1) \leftarrow Rd(n), Rd(0) \leftarrow 0$	Z,C,N,V	1
LSR	Rd	Logical Shift Right	$Rd(n) \leftarrow Rd(n+1), Rd(7) \leftarrow 0$	Z,C,N,V	1
ROL	Rd	Rotate Left Through Carry	$Rd(0) \leftarrow C, Rd(n+1) \leftarrow Rd(n), C \leftarrow Rd(7)$	Z,C,N,V	1
ROR	Rd	Rotate Right Through Carry	$Rd(7) \leftarrow C, Rd(n) \leftarrow Rd(n+1), C \leftarrow Rd(0)$	Z,C,N,V	1
ASR	Rd	Arithmetic Shift Right	Rd(n) ← Rd(n+1), n=06	Z,C,N,V	1
SWAP	Rd	Swap Nibbles	Rd(30)←Rd(74),Rd(74)←Rd(30)	None	1
BSET	s	Flag Set	$SREG(s) \leftarrow 1$	SREG(s)	1
BCLR	S	Flag Clear	$SREG(s) \leftarrow 0$	SREG(s)	1
BST	Rr, b	Bit Store from Register to T	$T \leftarrow Rr(b)$	Т	1
BLD	Rd, b	Bit load from T to Register	$Rd(b) \leftarrow T$	None	1
SEC		Set Carry	C ← 1	С	1
CLC		Clear Carry	C ← 0	С	1
SEN		Set Negative Flag	N ← 1	N	1
CLN		Clear Negative Flag	N ← 0	N	1
SEZ		Set Zero Flag	Z ← 1	Z	1
CLZ		Clear Zero Flag	Z ← 0	Z	1
SEI		Global Interrupt Enable	1 ← 1	1	1
CLI		Global Interrupt Disable	←0	1	1
SES		Set Signed Test Flag	S ← 1	S	1
CLS		Clear Signed Test Flag	S ← 0	S	1
SEV		Set Twos Complement Overflow.	V ← 1	V	1
CLV		Clear Twos Complement Overflow	V ← 0	v	1
SET		Set T in SREG	T ← 1	T	1
CLT		Clear T in SREG	$T \leftarrow 0$	T	1
SEH		Set Half Carry Flag in SREG	$H \leftarrow 1$	Н	1
CLH		Clear Half Carry Flag in SREG	$H \leftarrow 0$	Н	1
DATA TRANSFER I	NSTRUCTIONS		11 ~ 0		1
MOV	Rd, Rr	Move Between Registers	Rd ← Rr	None	1
MOVW	Rd, Rr	Copy Register Word	$Rd \leftarrow Rr+1:Rr$	None	1
					1
LDI	Rd, K	Load Immediate	$Rd \leftarrow K$	None	2
LD	Rd, X	Load Indirect	$Rd \leftarrow (X)$	None	
LD	Rd, X+	Load Indirect and Post-Inc.	$Rd \leftarrow (X), X \leftarrow X + 1$	None	2
LD	Rd, - X	Load Indirect and Pre-Dec.	$X \leftarrow X - 1, Rd \leftarrow (X)$	None	2
LD	Rd, Y	Load Indirect	$Rd \leftarrow (Y)$	None	2
LD	Rd, Y+	Load Indirect and Post-Inc.	$Rd \leftarrow (Y), Y \leftarrow Y + 1$	None	2
LD	Rd, - Y	Load Indirect and Pre-Dec.	$Y \leftarrow Y - 1, Rd \leftarrow (Y)$	None	2
LDD	Rd,Y+q	Load Indirect with Displacement	$Rd \leftarrow (Y + q)$	None	2
LD	Rd, Z	Load Indirect	$Rd \leftarrow (Z)$	None	2
LD	Rd, Z+	Load Indirect and Post-Inc.	$Rd \leftarrow (Z), Z \leftarrow Z+1$	None	2
LD	Rd, -Z	Load Indirect and Pre-Dec.	$Z \leftarrow Z - 1, Rd \leftarrow (Z)$	None	2
LDD	Rd, Z+q	Load Indirect with Displacement	$Rd \leftarrow (Z + q)$	None	2
LDS	Rd, k	Load Direct from SRAM	$Rd \leftarrow (k)$	None	2
ST	X, Rr	Store Indirect	$(X) \leftarrow Rr$	None	2
ST	X+, Rr	Store Indirect and Post-Inc.	$(X) \leftarrow \operatorname{Rr}, X \leftarrow X + 1$	None	2
ST	- X, Rr	Store Indirect and Pre-Dec.	$X \leftarrow X - 1$, (X) $\leftarrow Rr$	None	2
ST	Y, Rr	Store Indirect	$(Y) \leftarrow Rr$	None	2
ST	Y+, Rr	Store Indirect and Post-Inc.	$(Y) \leftarrow Rr, Y \leftarrow Y + 1$	None	2
ST	- Y, Rr	Store Indirect and Pre-Dec.	$Y \leftarrow Y - 1, (Y) \leftarrow Rr$	None	2
STD	Y+q,Rr	Store Indirect with Displacement	(Y + q) ← Rr	None	2
ST	Z, Rr	Store Indirect	$(Z) \leftarrow Rr$	None	2
ST	Z+, Rr	Store Indirect and Post-Inc.	$(Z) \leftarrow Rr, Z \leftarrow Z + 1$	None	2
ST	-Z, Rr	Store Indirect and Pre-Dec.	$Z \leftarrow Z - 1$, (Z) $\leftarrow Rr$	None	2
STD	Z+q,Rr	Store Indirect with Displacement	$(Z + q) \leftarrow Rr$	None	2
STS	k, Rr	Store Direct to SRAM	(k) ← Rr	None	2
LPM		Load Program Memory	$R0 \leftarrow (Z)$	None	3
LPM	Rd, Z	Load Program Memory	$Rd \leftarrow (Z)$	None	3
LPM	Rd, Z+	Load Program Memory and Post-Inc	$Rd \leftarrow (Z), Z \leftarrow Z+1$	None	3
SPM		Store Program Memory	$(Z) \leftarrow R1:R0$	None	-
	Rd, P	In Port	$Rd \leftarrow P$	None	1
IN	· ·, ·				-
	P Rr	Out Port	P ← Rr	None	1
OUT PUSH	P, Rr Rr	Out Port Push Register on Stack	$P \leftarrow Rr$ STACK $\leftarrow Rr$	None None	1 2



9.3 Atmel ATmega329A

Speed [MHz] ⁽³⁾	Power supply	Ordering code ⁽²⁾	Package type ⁽¹⁾	Operational range
20	20 1.8 - 5.5V	ATmega329A-AU ATmega329A-AUR ⁽⁴⁾ ATmega329A-MU ATmega329A-MUR ⁽⁴⁾	64A 64A 64M1 64M1	Industrial (-40°C to 85°C)
20		ATmega329A-AN ATmega329A-ANR ⁽⁴⁾ ATmega329A-MN ATmega329A-MNR ⁽⁴⁾	64A 64A 64M1 64M1	Extended (-40°C to 105°C) ⁽⁵⁾

Notes: 1. This device can also be supplied in wafer form. Please contact your local Atmel sales office for detailed ordering information and minimum quantities.

2. Pb-free packaging complies to the European Directive for Restriction of Hazardous Substances (RoHS directive). Also Halide free and fully Green.

- 3. For Speed vs. V_{CC} see Figure 29-2 on page 330.
- 4. Tape & Reel.
- 5. See characterization specifications at 105°C.

Package type		
64-lead, 14 × 14 × 1.0mm, thin profile plastic Quad Flat Package (TQFP)		
64-pad, 9 × 9 × 1.0mm, Quad Flat No-Lead/Micro Lead Frame Package (QFN/MLF)		

9.4 Atmel ATmega329PA

Speed [MHz] ⁽³⁾	Power supply	Ordering code ⁽²⁾	Package type ⁽¹⁾	Operational range
20	1.8 - 5.5V	ATmega329PA-AU ATmega329PA-AUR ⁽⁴⁾ ATmega329PA-MU ATmega329PA-MUR ⁽⁴⁾	64A 64A 64M1 64M1	Industrial (-40°C to 85°C)
20		ATmega329PA-AN ATmega329PA-ANR ⁽⁴⁾ ATmega329PA-MN ATmega329PA-MNR ⁽⁴⁾	64A 64A 64M1 64M1	Extended (-40°C to 105°C) ⁽⁵⁾

Notes: 1. This device can also be supplied in wafer form. Please contact your local Atmel sales office for detailed ordering information and minimum quantities.

2. Pb-free packaging complies to the European Directive for Restriction of Hazardous Substances (RoHS directive). Also Halide free and fully Green.

3. For Speed vs. V_{CC} see Figure 29-2 on page 330.

4. Tape &Reel.

5. See characterization specification at 105°C.

Package type			
64-lead, 14 × 14 × 1.0mm, thin profile Plastic Quad Flat Package (TQFP)			
64-pad, 9 × 9 × 1.0mm, Quad Flat No-Lead/Micro Lead Frame Package (QFN/MLF)			



9.5 Atmel ATmega3290A

Speed [MHz] ⁽³⁾	Power supply	Ordering code ⁽²⁾	Package type ⁽¹⁾	Operational range
20	1.8 - 5.5V	ATmega3290A-AU ATmega3290A-AUR ⁽⁴⁾	100A 100A	Industrial (-40°C to 85°C)
20	1.0 - 5.5V	ATmega3290A-AN ATmega3290A-ANR ⁽⁴⁾	100A 100A	Extended (-40°C to 105°C) ⁽⁵⁾

Notes: 1. This device can also be supplied in wafer form. Please contact your local Atmel sales office for detailed ordering information and minimum quantities.

2. Pb-free packaging complies to the European Directive for Restriction of Hazardous Substances (RoHS directive). Also Halide free and fully Green.

3. For Speed vs. V_{CC} see Figure 29-2 on page 330.

4. Tape & Reel.

5. See characterization specification at 105°C.

Package type

100-lead, 14 × 14 × 1.0mm, 0.5mm Lead Pitch, Thin Profile Plastic Quad Flat Package (TQFP)



9.6 Atmel ATmega3290PA

Speed [MHz] ⁽³⁾	Power supply	Ordering code ⁽²⁾	Package type ⁽¹⁾	Operational range
20	1.8 - 5.5V	ATmega3290PA-AU ATmega3290PA-AUR ⁽⁴⁾	100A 100A	Industrial (-40°C to 85°C)
20	1.0 - 5.5V	ATmega3290PA-AN ATmega3290PA-ANR ⁽⁴⁾	100A 100A	Industrial (-40°C to 105°C) ⁽⁵⁾

Notes: 1. This device can also be supplied in wafer form. Please contact your local Atmel sales office for detailed ordering information and minimum quantities.

2. Pb-free packaging complies to the European Directive for Restriction of Hazardous Substances (RoHS directive). Also Halide free and fully Green.

3. For Speed vs. V_{CC} see Figure 29-2 on page 330.

4. Tape & Reel.

5. See characterization specification at 105°C.

Package type

100-lead, 14 × 14 × 1.0mm, 0.5mm Lead Pitch, Thin Profile Plastic Quad Flat Package (TQFP)



9.7 Atmel ATmega649A

Speed [MHz] ⁽³⁾	Power supply	Ordering code ⁽²⁾	Package type ⁽¹⁾	Operational range
16	1.8 - 5.5V	ATmega649A-AU ATmega649A-AUR ⁽⁴⁾ ATmega649A-MU ATmega649A-MUR ⁽⁴⁾	64A 64A 64M1 64M1	Industrial (-40°C to 85°C)

Notes: 1. This device can also be supplied in wafer form. Please contact your local Atmel sales office for detailed ordering information and minimum quantities.

2. Pb-free packaging complies to the European Directive for Restriction of Hazardous Substances (RoHS directive). Also Halide free and fully Green.

3. For Speed vs. V_{CC} see Figure 29-1 on page 330.

4. Tape & Reel.

Package type		
64-lead, 14 × 14 × 1.0mm, Thin Profile Plastic Quad Flat Package (TQFP)		
64-pad, 9 × 9 × 1.0mm, Quad Flat No-Lead/Micro Lead Frame Package (QFN/MLF)		

9.10 Atmel ATmega6490P

Speed [MHz] ⁽³⁾	Power supply	Ordering code ⁽²⁾	Package type ⁽¹⁾	Operational range
20	1.8 - 5.5V	ATmega6490P-AU ATmega6490P-AUR ⁽⁴⁾	100A 100A	Industrial (-40°C to 85°C)

Notes: 1. This device can also be supplied in wafer form. Please contact your local Atmel sales office for detailed ordering information and minimum quantities.

2. Pb-free packaging complies to the European Directive for Restriction of Hazardous Substances (RoHS directive). Also Halide free and fully Green.

3. For Speed vs. V_{CC} see Figure 29-2 on page 330.

4. Tape & Reel.

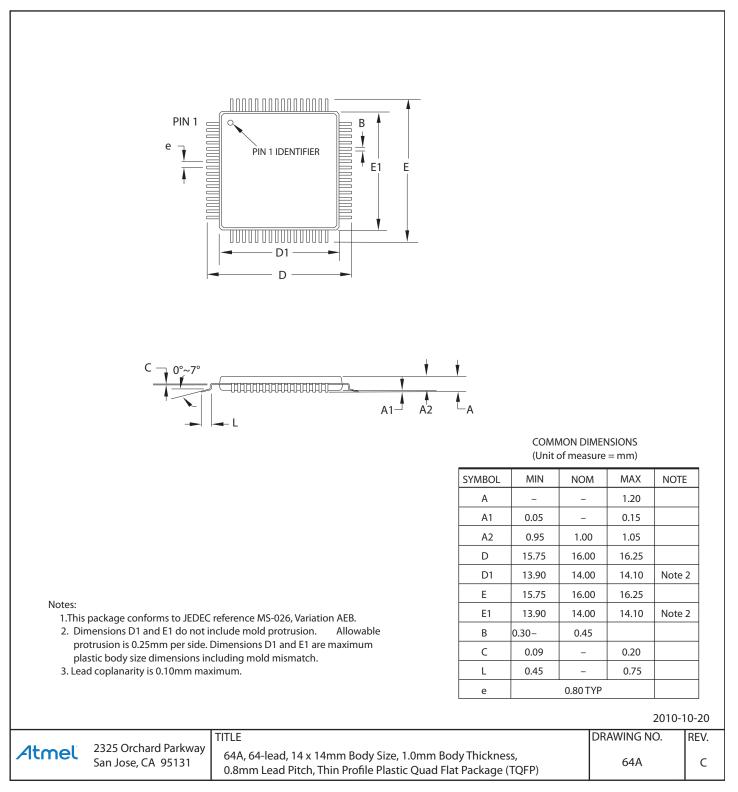
Package Type

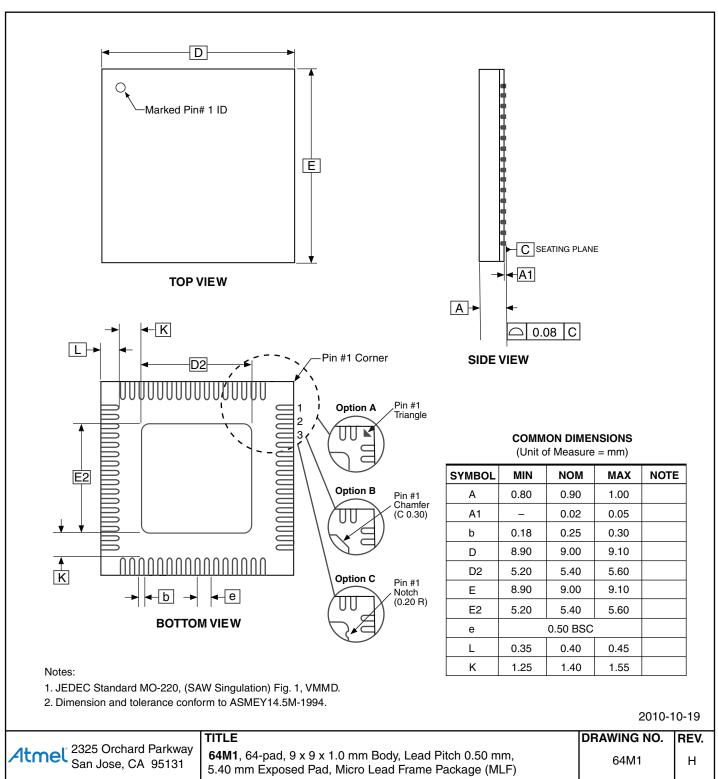
100-lead, 14 × 14 × 1.0mm, 0.5mm Lead Pitch, Thin Profile Plastic Quad Flat Package (TQFP)



10. Packaging Information

10.1 64A





11.6 Atmel ATmega329A/329PA rev. C

· Interrupts may be lost when writing the timer registers in the asynchronous timer

1. Interrupts may be lost when writing the timer registers in the asynchronous timer

The interrupt will be lost if a timer register that is synchronous timer clock is written when the asynchronous Timer/Counter register (TCNTx) is 0x00.

Problem Fix/ Workaround

Always check that the asynchronous Timer/Counter register neither have the value 0xFF nor 0x00 before writing to the asynchronous Timer Control Register (TCCRx), asynchronous Timer Counter Register (TCNTx), or asynchronous Output Compare Register (OCRx).

11.7 Atmel ATmega3290A/3290PA rev. A

- · Interrupts may be lost when writing the timer registers in the asynchronous timer
- Using BOD disable will make the chip reset

1. Interrupts may be lost when writing the timer registers in the asynchronous timer

The interrupt will be lost if a timer register that is synchronous timer clock is written when the asynchronous Timer/Counter register (TCNTx) is 0x00.

Problem Fix/ Workaround

Always check that the asynchronous Timer/Counter register neither have the value 0xFF nor 0x00 before writing to the asynchronous Timer Control Register (TCCRx), asynchronous Timer Counter Register (TCNTx), or asynchronous Output Compare Register (OCRx).

2. Using BOD disable will make the chip reset

If the part enters sleep with the BOD turned off with the BOD disable option enabled, a BOD reset will be generated at wakeup and the chip will reset.

Problem Fix/Workaround

Do not use BOD disable

11.8 Atmel ATmega3290A/3290PA rev. B

• Interrupts may be lost when writing the timer registers in the asynchronous timer

1. Interrupts may be lost when writing the timer registers in the asynchronous timer

The interrupt will be lost if a timer register that is synchronous timer clock is written when the asynchronous Timer/Counter register (TCNTx) is 0x00.

Problem Fix/ Workaround

Always check that the asynchronous Timer/Counter register neither have the value 0xFF nor 0x00 before writing to the asynchronous Timer Control Register (TCCRx), asynchronous Timer Counter Register (TCNTx), or asynchronous Output Compare Register (OCRx).



11.9 Atmel ATmega3290A/3290PA rev. C

· Interrupts may be lost when writing the timer registers in the asynchronous timer

1. Interrupts may be lost when writing the timer registers in the asynchronous timer

The interrupt will be lost if a timer register that is synchronous timer clock is written when the asynchronous Timer/Counter register (TCNTx) is 0x00.

Problem Fix/ Workaround

Always check that the asynchronous Timer/Counter register neither have the value 0xFF nor 0x00 before writing to the asynchronous Timer Control Register (TCCRx), asynchronous Timer Counter Register (TCNTx), or asynchronous Output Compare Register (OCRx).

11.10 Atmel ATmega649A/649P/ATmega6490A/6490P

No known errata.



12. Datasheet revision history

Please note that the referring page numbers in this section are referring to this document. The referring revision in this section are referring to the document revision.

12.1 Rev. 8284F - 08/2014

- 1. New back page
- 2. Changed chip references in the text in Section 9.6 "Low-frequency XTAL oscillator" on page 34.

12.2 Rev. 8284E - 02/2013

- 1. New template
- 2. Countless, small corrections made throughout the whole document
- 3. In Section "System and reset characteristics" on page 332 the sentence "The following chara apply only to..." has been deleted
 - Former Section 29.6 on page 332 ("Power-on reset"), subsection 29.6.1
- 4. ("ATmega169A/169PA/329A/329PA/3290A/3290PA/649A/649P/6490A/6490PA revision C and later") and subsection 29.6.2 ("ATmega329A/329PA/3290A/3290PA/649A/649P/6490A/6490PA revision A and B") have been deleted
- 5. The maximum limits for "Power Supply Current" in Table 29-9 on page 328 have been corrected
- 6. The maximum limits for "Power Supply Current" in Table 29-11 on page 329 have been corrected
- 7. Added "Electrical Characteristics $TA = -40^{\circ}C$ to $105^{\circ}C$ " on page 337.
- 8. Added "Typical Characteristics $-TA = -40^{\circ}C$ to $105^{\circ}C$ " on page 658.
- 9. Updated "Ordering information" on page 20

12.3 Rev. 8284D - 06/11

- 1. Removed "Preliminary" from the front page
- 2. Updated the Table 29-16 on page 344. V_{POT} falling / Min. is 0.05V, not 0.5V

12.4 Rev. 8284C - 06/11

- 1. Updated "Signature Bytes" on page 294. A, P, and PA devices have different signature (0x002) bytes.
- 2. Updated all "DC Characteristics" on page 323.



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