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Understanding Embedded - Microprocessors

Embedded microprocessors are specialized computing chips designed to perform specific tasks within an embedded system. Unlike general-purpose microprocessors found in personal computers, embedded microprocessors are tailored for dedicated functions within larger systems, offering optimized performance, efficiency, and reliability. These microprocessors are integral to the operation of countless electronic devices, providing the computational power necessary for controlling processes, handling data, and managing communications.

Applications of Embedded - Microprocessors

Embedded microprocessors are utilized across a broad spectrum of applications, making them indispensable in

Details	
Product Status	Obsolete
Core Processor	MPC8xx
Number of Cores/Bus Width	1 Core, 32-Bit
Speed	133MHz
Co-Processors/DSP	Communications; CPM, Security; SEC
RAM Controllers	DRAM
Graphics Acceleration	No
Display & Interface Controllers	-
Ethernet	10Mbps (3), 10/100Mbps (2)
SATA	-
USB	USB 2.0 (1)
Voltage - I/O	3.3V
Operating Temperature	-40°C ~ 100°C (TA)
Security Features	Cryptography
Package / Case	357-BBGA
Supplier Device Package	357-PBGA (25x25)
Purchase URL	https://www.e-xfl.com/product-detail/nxp-semiconductors/kmpc885czp133

1 Overview

The MPC885/MPC880 is a versatile single-chip integrated microprocessor and peripheral combination that can be used in a variety of controller applications and communications and networking systems. The MPC885/MPC880 provides enhanced ATM functionality, an additional fast Ethernet controller, a USB, and an encryption block.

Table 1 shows the functionality supported by MPC885/MPC880.

Table 1. MPC885 Family

Part	Cache (Kbytes)		Ethernet		SCC	SMC	USB	ATM Support	Security Engine
	I Cache	D Cache	10BaseT	10/100					
MPC885	8	8	Up to 3	2	3	2	1	Serial ATM and UTOPIA interface	Yes
MPC880	8	8	Up to 2	2	2	2	1	Serial ATM and UTOPIA interface	No

2 Features

The MPC885/MPC880 is comprised of three modules that each use the 32-bit internal bus: a MPC8xx core, a system integration unit (SIU), and a communications processor module (CPM).

The following list summarizes the key MPC885/MPC880 features:

- Embedded MPC8xx core up to 133 MHz
- Maximum frequency operation of the external bus is 80 MHz (in 1:1 mode)
  - The 133-MHz core frequency supports 2:1 mode only.
  - The 66-/80-MHz core frequencies support both the 1:1 and 2:1 modes.
- Single-issue, 32-bit core (compatible with the Power Architecture definition) with thirty-two 32-bit general-purpose registers (GPRs)
  - The core performs branch prediction with conditional prefetch and without conditional execution.
  - 8-Kbyte data cache and 8-Kbyte instruction cache (see Table 1)
    - Instruction cache is two-way, set-associative with 256 sets in 2 blocks
    - Data cache is two-way, set-associative with 256 sets
    - Cache coherency for both instruction and data caches is maintained on 128-bit (4-word) cache blocks.
    - Caches are physically addressed, implement a least recently used (LRU) replacement algorithm, and are lockable on a cache block basis.
  - MMUs with 32-entry TLB, fully associative instruction and data TLBs
  - MMUs support multiple page sizes of 4, 16, and 512 Kbytes, and 8 Mbytes; 16 virtual address spaces and 16 protection groups
  - Advanced on-chip emulation debug mode

If the board temperature is known, an estimate of the junction temperature in the environment can be made using the following equation:

$$T_J = T_B + (R_{\theta JB} \times P_D)$$

where:

$R_{\theta JB}$ = junction-to-board thermal resistance (ºC/W)

T_B = board temperature (ºC)

P_D = power dissipation in package

If the board temperature is known and the heat loss from the package case to the air can be ignored, acceptable predictions of junction temperature can be made. For this method to work, the board and board mounting must be similar to the test board used to determine the junction-to-board thermal resistance, namely a 2s2p (board with a power and a ground plane) and vias attaching the thermal balls to the ground plane.

7.4 Estimation Using Simulation

When the board temperature is not known, a thermal simulation of the application is needed. The simple two resistor model can be used with the thermal simulation of the application [2], or a more accurate and complex model of the package can be used in the thermal simulation.

7.5 Experimental Determination

To determine the junction temperature of the device in the application after prototypes are available, the thermal characterization parameter (Ψ_{JT}) can be used to determine the junction temperature with a measurement of the temperature at the top center of the package case using the following equation:

$$T_J = T_T + (\Psi_{JT} \times P_D)$$

where:

Ψ_{JT} = thermal characterization parameter

T_T = thermocouple temperature on top of package

P_D = power dissipation in package

The thermal characterization parameter is measured per the JESD51-2 specification published by JEDEC using a 40 gauge type T thermocouple epoxied to the top center of the package case. The thermocouple should be positioned so that the thermocouple junction rests on the package. A small amount of epoxy is placed over the thermocouple junction and over about 1 mm of wire extending from the junction. The thermocouple wire is placed flat against the package case to avoid measurement errors caused by the cooling effects of the thermocouple wire.

Table 7. Frequency Ranges for Standard Part Frequencies (1:1 Bus Mode)

Part Frequency	66 MHz		80 MHz	
	Min	Max	Min	Max
Core frequency	40	66.67	40	80
Bus frequency	40	66.67	40	80

Table 8. Frequency Ranges for Standard Part Frequencies (2:1 Bus Mode)

Part Frequency	66 MHz		80 MHz		133 MHz	
	Min	Max	Min	Max	Min	Max
Core frequency	40	66.67	40	80	40	133
Bus frequency	20	33.33	20	40	20	66

Table 9 provides the timings for the MPC885/MPC880 at 33-, 40-, 66-, and 80-MHz bus operation.

The timing for the MPC885/MPC880 bus shown assumes a 50-pF load for maximum delays and a 0-pF load for minimum delays. CLKOUT assumes a 100-pF load for maximum delays and a 50-pF load for minimum delays.

Table 9. Bus Operation Timings

Num	Characteristic	33 MHz		40 MHz		66 MHz		80 MHz		Unit
		Min	Max	Min	Max	Min	Max	Min	Max	
B1	Bus period (CLKOUT), see Table 7	—	—	—	—	—	—	—	—	ns
B1a	EXTCLK to CLKOUT phase skew - If CLKOUT is an integer multiple of EXTCLK, then the rising edge of EXTCLK is aligned with the rising edge of CLKOUT. For a non-integer multiple of EXTCLK, this synchronization is lost, and the rising edges of EXTCLK and CLKOUT have a continuously varying phase skew.	–2	+2	–2	+2	–2	+2	–2	+2	ns
B1b	CLKOUT frequency jitter peak-to-peak	—	1	—	1	—	1	—	1	ns
B1c	Frequency jitter on EXTCLK	—	0.50	—	0.50	—	0.50	—	0.50	%
B1d	CLKOUT phase jitter peak-to-peak for OSCLK ≥ 15 MHz	—	4	—	4	—	4	—	4	ns
	CLKOUT phase jitter peak-to-peak for OSCLK < 15 MHz	—	5	—	5	—	5	—	5	ns
B2	CLKOUT pulse width low (MIN = 0.4 × B1, MAX = 0.6 × B1)	12.1	18.2	10.0	15.0	6.1	9.1	5.0	7.5	ns
B3	CLKOUT pulse width high (MIN = 0.4 × B1, MAX = 0.6 × B1)	12.1	18.2	10.0	15.0	6.1	9.1	5.0	7.5	ns
B4	CLKOUT rise time	—	4.00	—	4.00	—	4.00	—	4.00	ns

Table 9. Bus Operation Timings (continued)

Num	Characteristic	33 MHz		40 MHz		66 MHz		80 MHz		Unit
		Min	Max	Min	Max	Min	Max	Min	Max	
B5	CLKOUT fall time	—	4.00	—	4.00	—	4.00	—	4.00	ns
B7	CLKOUT to A(0:31), BADDR(28:30), RD/$\overline{WR}$, $\overline{BURST}$, D(0:31) output hold (MIN = 0.25 × B1)	7.60	—	6.30	—	3.80	—	3.13	—	ns
B7a	CLKOUT to TSIZ(0:1), $\overline{REG}$, $\overline{RSV}$, $\overline{BDIP}$, PTR output hold (MIN = 0.25 × B1)	7.60	—	6.30	—	3.80	—	3.13	—	ns
B7b	CLKOUT to $\overline{BR}$, $\overline{BG}$, FRZ, VFLS(0:1), VF(0:2) IWP(0:2), LWP(0:1), $\overline{STS}$ output hold (MIN = 0.25 × B1)	7.60	—	6.30	—	3.80	—	3.13	—	ns
B8	CLKOUT to A(0:31), BADDR(28:30) RD/$\overline{WR}$, $\overline{BURST}$, D(0:31) valid (MAX = 0.25 × B1 + 6.3)	—	13.80	—	12.50	—	10.00	—	9.43	ns
B8a	CLKOUT to TSIZ(0:1), $\overline{REG}$, $\overline{RSV}$, AT(0:3) $\overline{BDIP}$, PTR valid (MAX = 0.25 × B1 + 6.3)	—	13.80	—	12.50	—	10.00	—	9.43	ns
B8b	CLKOUT to $\overline{BR}$, $\overline{BG}$, VFLS(0:1), VF(0:2), IWP(0:2), FRZ, LWP(0:1), $\overline{STS}$ valid [4] (MAX = 0.25 × B1 + 6.3)	—	13.80	—	12.50	—	10.00	—	9.43	ns
B9	CLKOUT to A(0:31), BADDR(28:30), RD/$\overline{WR}$, $\overline{BURST}$, D(0:31), TSIZ(0:1), $\overline{REG}$, $\overline{RSV}$, AT(0:3), PTR High-Z (MAX = 0.25 × B1 + 6.3)	7.60	13.80	6.30	12.50	3.80	10.00	3.13	9.43	ns
B11	CLKOUT to $\overline{TS}$, $\overline{BB}$ assertion (MAX = 0.25 × B1 + 6.0)	7.60	13.60	6.30	12.30	3.80	9.80	3.13	9.13	ns
B11a	CLKOUT to $\overline{TA}$, $\overline{BI}$ assertion (when driven by the memory controller or PCMCIA interface) (MAX = 0.00 × B1 + 9.30[1])	2.50	9.30	2.50	9.30	2.50	9.30	2.50	9.30	ns
B12	CLKOUT to $\overline{TS}$, $\overline{BB}$ negation (MAX = 0.25 × B1 + 4.8)	7.60	12.30	6.30	11.00	3.80	8.50	3.13	7.92	ns
B12a	CLKOUT to $\overline{TA}$, $\overline{BI}$ negation (when driven by the memory controller or PCMCIA interface) (MAX = 0.00 × B1 + 9.00)	2.50	9.00	2.50	9.00	2.50	9.00	2.5	9.00	ns
B13	CLKOUT to $\overline{TS}$, $\overline{BB}$ High-Z (MIN = 0.25 × B1)	7.60	21.60	6.30	20.30	3.80	14.00	3.13	12.93	ns
B13a	CLKOUT to $\overline{TA}$, $\overline{BI}$ High-Z (when driven by the memory controller or PCMCIA interface) (MIN = 0.00 × B1 + 2.5)	2.50	15.00	2.50	15.00	2.50	15.00	2.5	15.00	ns
B14	CLKOUT to $\overline{TEA}$ assertion (MAX = 0.00 × B1 + 9.00)	2.50	9.00	2.50	9.00	2.50	9.00	2.50	9.00	ns
B15	CLKOUT to $\overline{TEA}$ High-Z (MIN = 0.00 × B1 + 2.50)	2.50	15.00	2.50	15.00	2.50	15.00	2.50	15.00	ns
B16	$\overline{TA}$, $\overline{BI}$ valid to CLKOUT (setup time) (MIN = 0.00 × B1 + 6.00)	6.00	—	6.00	—	6.00	—	6	—	ns
B16a	$\overline{TEA}$, $\overline{KR}$, $\overline{RETRY}$, $\overline{CR}$ valid to CLKOUT (setup time) (MIN = 0.00 × B1 + 4.5)	4.50	—	4.50	—	4.50	—	4.50	—	ns

Table 9. Bus Operation Timings (continued)

Num	Characteristic	33 MHz		40 MHz		66 MHz		80 MHz		Unit
		Min	Max	Min	Max	Min	Max	Min	Max	
B16b	$\overline{BB}$, $\overline{BG}$, $\overline{BR}$, valid to CLKOUT (setup time)[2] (4MIN = 0.00 × B1 + 0.00)	4.00	—	4.00	—	4.00	—	4.00	—	ns
B17	CLKOUT to $\overline{TA}$, $\overline{TEA}$, $\overline{BI}$, $\overline{BB}$, $\overline{BG}$, $\overline{BR}$ valid (hold time) (MIN = 0.00 × B1 + 1.00[3])	1.00	—	1.00	—	2.00	—	2.00	—	ns
B17a	CLKOUT to $\overline{KR}$, $\overline{RETRY}$, $\overline{CR}$ valid (hold time) (MIN = 0.00 × B1 + 2.00)	2.00	—	2.00	—	2.00	—	2.00	—	ns
B18	D(0:31) valid to CLKOUT rising edge (setup time)[4] (MIN = 0.00 × B1 + 6.00)	6.00	—	6.00	—	6.00	—	6.00	—	ns
B19	CLKOUT rising edge to D(0:31) valid (hold time)[4] (MIN = 0.00 × B1 + 1.00[5])	1.00	—	1.00	—	2.00	—	2.00	—	ns
B20	D(0:31) valid to CLKOUT falling edge (setup time)[6] (MIN = 0.00 × B1 + 4.00)	4.00	—	4.00	—	4.00	—	4.00	—	ns
B21	CLKOUT falling edge to D(0:31) valid (hold time)[6] (MIN = 0.00 × B1 + 2.00)	2.00	—	2.00	—	2.00	—	2.00	—	ns
B22	CLKOUT rising edge to $\overline{CS}$ asserted GPCM ACS = 00 (MAX = 0.25 × B1 + 6.3)	7.60	13.80	6.30	12.50	3.80	10.00	3.13	9.43	ns
B22a	CLKOUT falling edge to $\overline{CS}$ asserted GPCM ACS = 10, TRLX = [0 or 1] (MAX = 0.00 × B1 + 8.00)	—	8.00	—	8.00	—	8.00	—	8.00	ns
B22b	CLKOUT falling edge to $\overline{CS}$ asserted GPCM ACS = 11, TRLX = [0 or 1], EBDF = 0 (MAX = 0.25 × B1 + 6.3)	7.60	13.80	6.30	12.50	3.80	10.00	3.13	9.43	ns
B22c	CLKOUT falling edge to $\overline{CS}$ asserted GPCM ACS = 11, TRLX = [0 or 1], EBDF = 1 (MAX = 0.375 × B1 + 6.6)	10.90	18.00	10.90	16.00	5.20	12.30	4.69	10.93	ns
B23	CLKOUT rising edge to $\overline{CS}$ negated GPCM read access, GPCM write access ACS = 00 and CSNT = 0 (MAX = 0.00 × B1 + 8.00)	2.00	8.00	2.00	8.00	2.00	8.00	2.00	8.00	ns
B24	A(0:31) and BADDR(28:30) to $\overline{CS}$ asserted GPCM ACS = 10, TRLX = 0 (MIN = 0.25 × B1 – 2.00)	5.60	—	4.30	—	1.80	—	1.13	—	ns
B24a	A(0:31) and BADDR(28:30) to $\overline{CS}$ asserted GPCM ACS = 11 TRLX = 0 (MIN = 0.50 × B1 – 2.00)	13.20	—	10.50	—	5.60	—	4.25	—	ns
B25	CLKOUT rising edge to $\overline{OE}$, $\overline{WE}$(0:3) asserted (MAX = 0.00 × B1 + 9.00)	—	9.00	—	9.00	—	9.00	—	9.00	ns
B26	CLKOUT rising edge to $\overline{OE}$ negated (MAX = 0.00 X B1 + 9.00)	2.00	9.00	2.00	9.00	2.00	9.00	2.00	9.00	ns
B27	A(0:31) and BADDR(28:30) to $\overline{CS}$ asserted GPCM ACS = 10, TRLX = 1 (MIN = 1.25 × B1 – 2.00)	35.90	—	29.30	—	16.90	—	13.60	—	ns

Figure 12 provides the timing for the input data controlled by the UPM for data beats where DLT3 = 1 in the UPM RAM words. (This is only the case where data is latched on the falling edge of CLKOUT.)

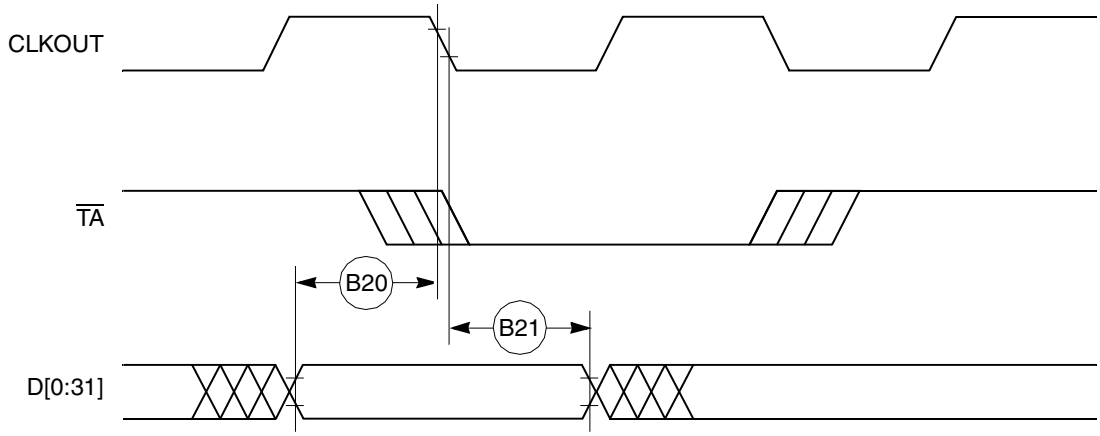


Figure 12. Input Data Timing when Controlled by UPM in the Memory Controller and DLT3 = 1

Figure 13 through Figure 16 provide the timing for the external bus read controlled by various GPCM factors.

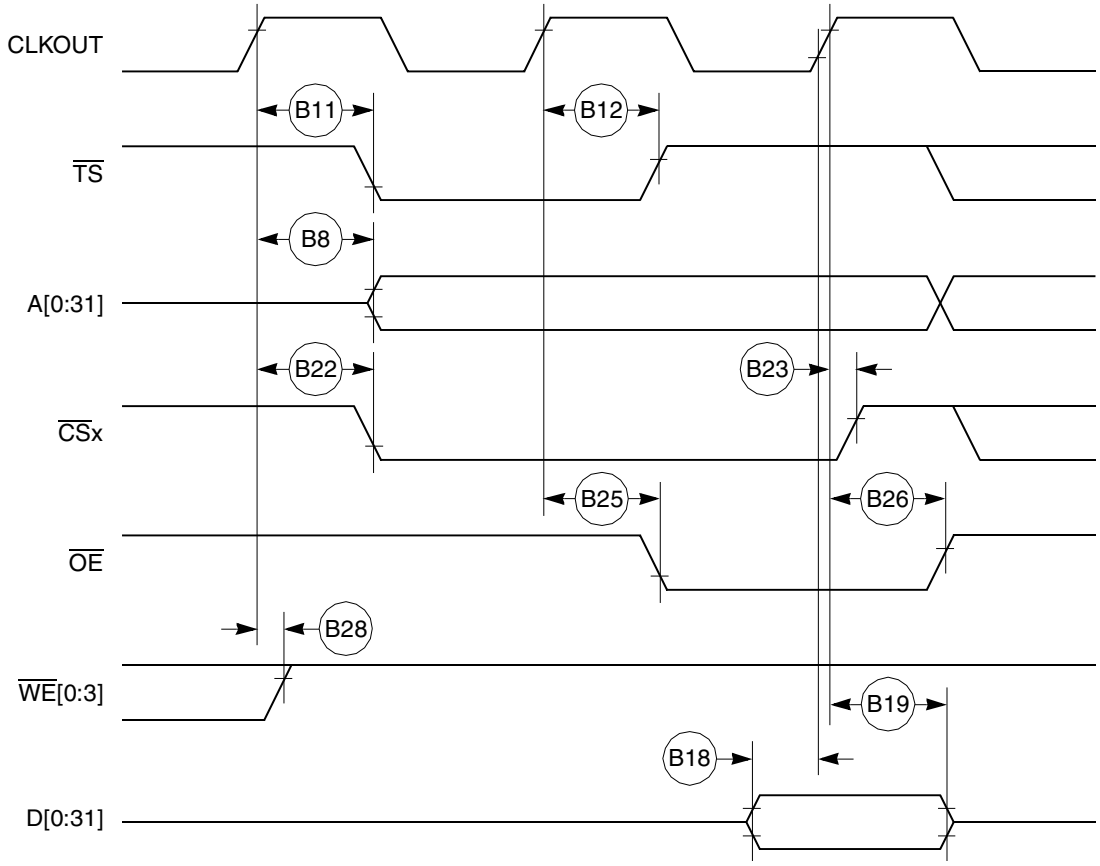


Figure 13. External Bus Read Timing (GPCM Controlled—ACS = 00)

Table 11 shows the PCMCIA timing for the MPC885/MPC880.

Table 11. PCMCIA Timing

Num	Characteristic	33 MHz		40 MHz		66 MHz		80 MHz		Unit
		Min	Max	Min	Max	Min	Max	Min	Max	
P44	A(0:31), $\overline{\text{REG}}$ valid to PCMCIA strobe asserted[1] (MIN = 0.75 × B1 – 2.00)	20.70	—	16.70	—	9.40	—	7.40	—	ns
P45	A(0:31), $\overline{\text{REG}}$ valid to ALE negation[1] (MIN = 1.00 × B1 – 2.00)	28.30	—	23.00	—	13.20	—	10.50	—	ns
P46	CLKOUT to $\overline{\text{REG}}$ valid (MAX = 0.25 × B1 + 8.00)	7.60	15.60	6.30	14.30	3.80	11.80	3.13	11.13	ns
P47	CLKOUT to $\overline{\text{REG}}$ invalid (MIN = 0.25 – B1 + 1.00)	8.60	—	7.30	—	4.80	—	4.13	—	ns
P48	CLKOUT to $\overline{\text{CE1}}$, $\overline{\text{CE2}}$ asserted (MAX = 0.25 × B1 + 8.00)	7.60	15.60	6.30	14.30	3.80	11.80	3.13	11.13	ns
P49	CLKOUT to $\overline{\text{CE1}}$, $\overline{\text{CE2}}$ negated (MAX = 0.25 × B1 + 8.00)	7.60	15.60	6.30	14.30	3.80	11.80	3.13	11.13	ns
P50	CLKOUT to $\overline{\text{PCOE}}$, $\overline{\text{IORD}}$, $\overline{\text{PCWE}}$, $\overline{\text{IOWR}}$ assert time (MAX = 0.00 × B1 + 11.00)	—	11.00	—	11.00	—	11.00	—	11.00	ns
P51	CLKOUT to $\overline{\text{PCOE}}$, $\overline{\text{IORD}}$, $\overline{\text{PCWE}}$, $\overline{\text{IOWR}}$ negate time (MAX = 0.00 × B1 + 11.00)	2.00	11.00	2.00	11.00	2.00	11.00	2.00	11.00	ns
P52	CLKOUT to ALE assert time (MAX = 0.25 × B1 + 6.30)	7.60	13.80	6.30	12.50	3.80	10.00	3.13	9.40	ns
P53	CLKOUT to ALE negate time (MAX = 0.25 × B1 + 8.00)	—	15.60	—	14.30	—	11.80	—	11.13	ns
P54	$\overline{\text{PCWE}}$, $\overline{\text{IOWR}}$ negated to D(0:31) invalid [1] (MIN = 0.25 × B1 – 2.00)	5.60	—	4.30	—	1.80	—	1.13	—	ns
P55	$\overline{\text{WAITA}}$ and $\overline{\text{WAITB}}$ valid to CLKOUT rising edge[1] (MIN = 0.00 × B1 + 8.00)	8.00	—	8.00	—	8.00	—	8.00	—	ns
P56	CLKOUT rising edge to $\overline{\text{WAITA}}$ and $\overline{\text{WAITB}}$ invalid[1] (MIN = 0.00 × B1 + 2.00)	2.00	—	2.00	—	2.00	—	2.00	—	ns

[1] PSST = 1. Otherwise add PSST times cycle time.
PSHT = 0. Otherwise add PSHT times cycle time.

These synchronous timings define when the $\overline{\text{WAITx}}$ signals are detected in order to freeze (or relieve) the PCMCIA current cycle. The $\overline{\text{WAITx}}$ assertion will be effective only if it is detected 2 cycles before the PSL timer expiration. See Chapter 16, “PCMCIA Interface,” in the *MPC885 PowerQUICC™ Family Reference Manual*.

Figure 29 provides the PCMCIA access cycle timing for the external bus write.

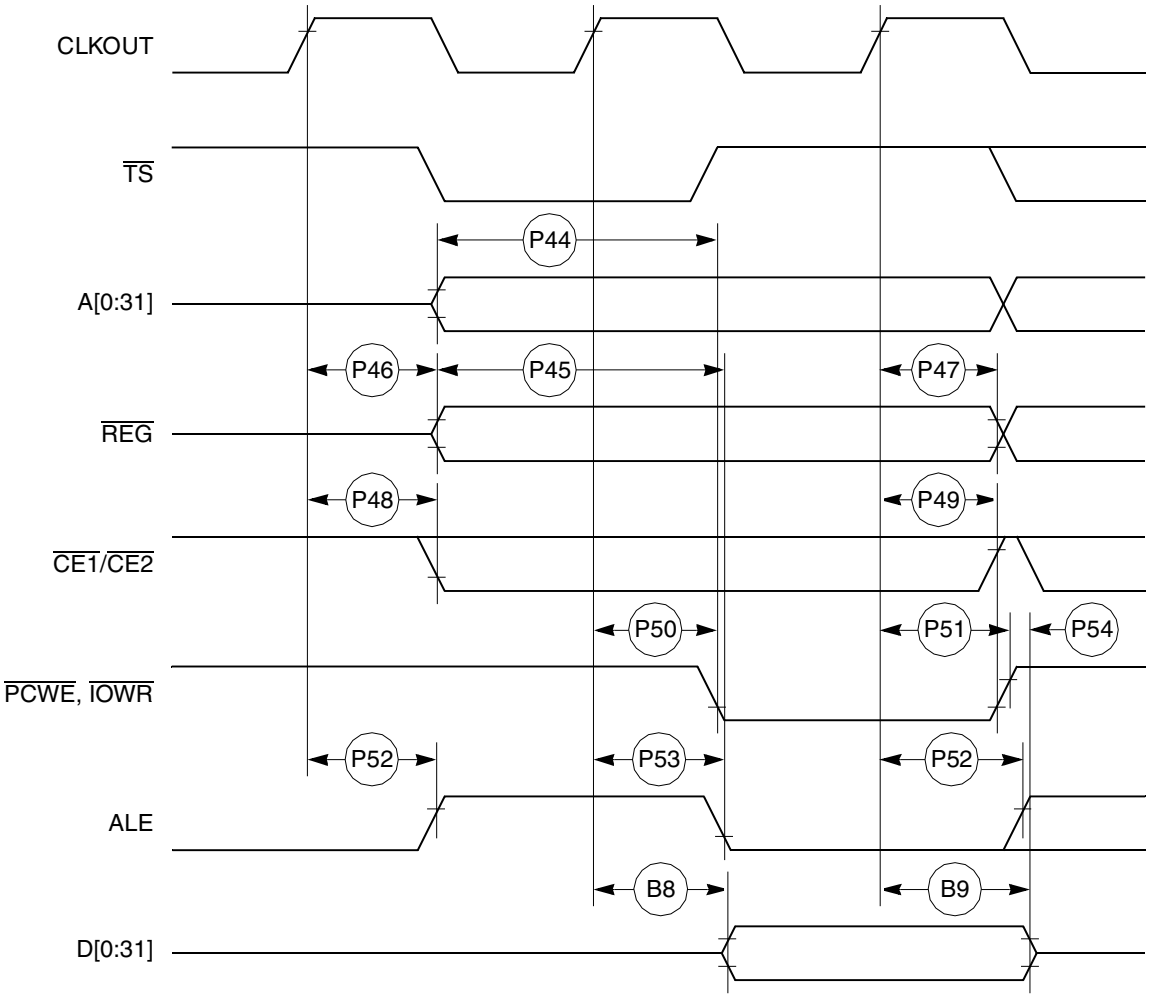


Figure 29. PCMCIA Access Cycles Timing External Bus Write

Figure 30 provides the PCMCIA WAIT signals detection timing.

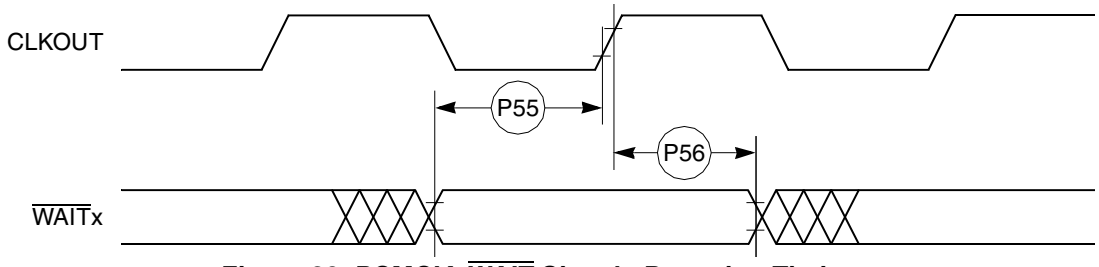


Figure 30. PCMCIA WAIT Signals Detection Timing

Table 13 shows the debug port timing for the MPC885/MPC880.

Table 13. Debug Port Timing

Num	Characteristic	All Frequencies		Unit
		Min	Max	
D61	DSCK cycle time	$3 \times T_{CLOCKOUT}$	—	—
D62	DSCK clock pulse width	$1.25 \times T_{CLOCKOUT}$	—	—
D63	DSCK rise and fall times	0.00	3.00	ns
D64	DSDI input data setup time	8.00	—	ns
D65	DSDI data hold time	5.00	—	ns
D66	DSCK low to DSDO data valid	0.00	15.00	ns
D67	DSCK low to DSDO invalid	0.00	2.00	ns

Figure 33 provides the input timing for the debug port clock.

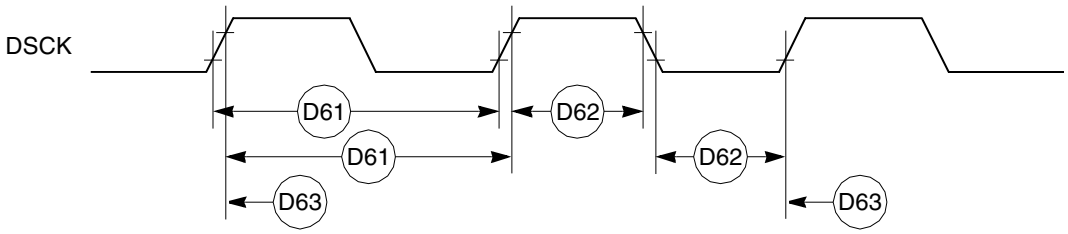


Figure 33. Debug Port Clock Input Timing

Figure 34 provides the timing for the debug port.

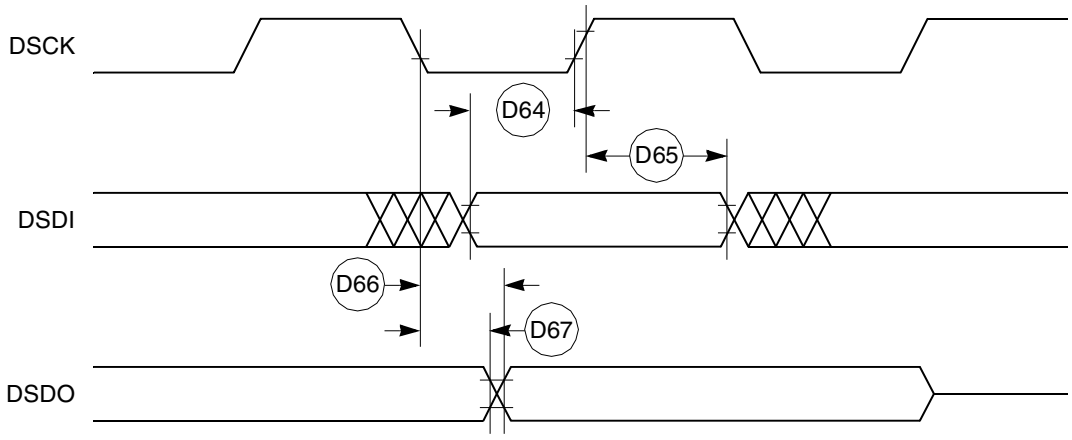


Figure 34. Debug Port Timings

Figure 35 shows the reset timing for the data bus configuration.

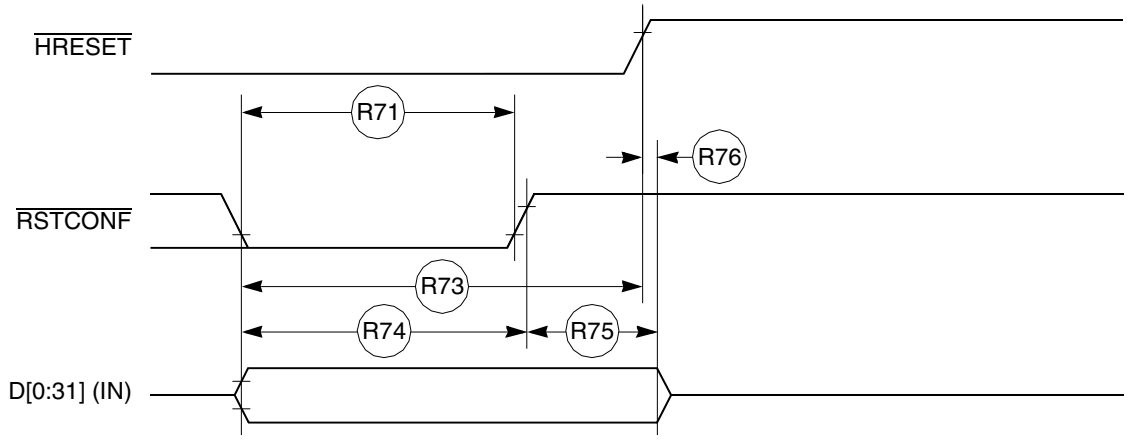


Figure 35. Reset Timing—Configuration from Data Bus

Figure 36 provides the reset timing for the data bus weak drive during configuration.

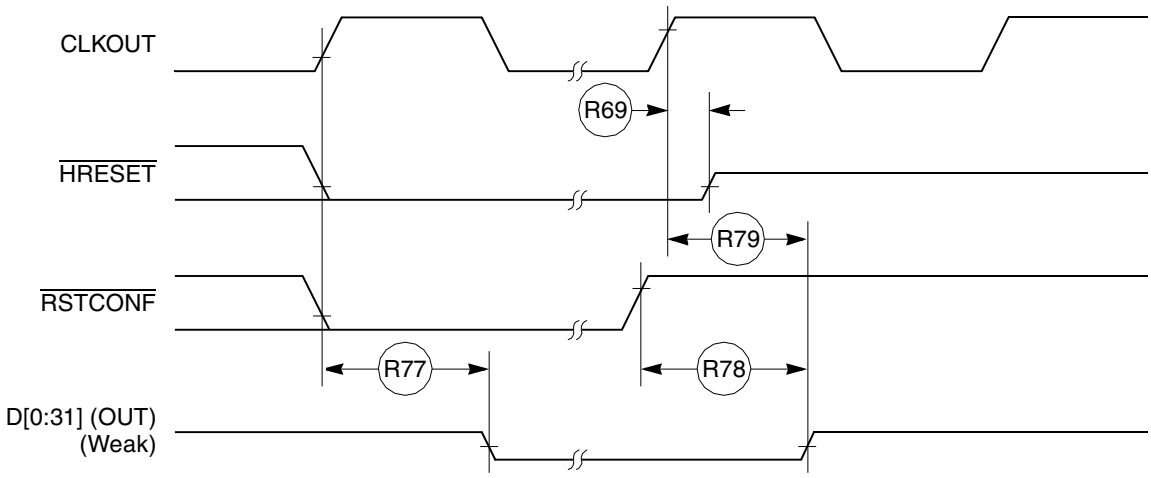


Figure 36. Reset Timing—Data Bus Weak Drive During Configuration

Figure 37 provides the reset timing for the debug port configuration.

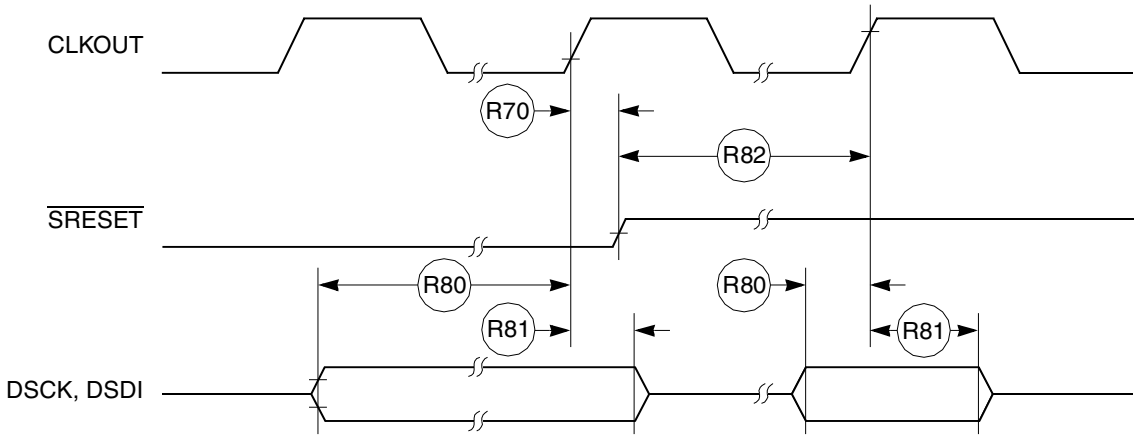


Figure 37. Reset Timing—Debug Port Configuration

11 IEEE 1149.1 Electrical Specifications

Table 15 provides the JTAG timings for the MPC885/MPC880 shown in Figure 38 through Figure 41.

Table 15. JTAG Timing

Num	Characteristic	All Frequencies		Unit
		Min	Max	
J82	TCK cycle time	100.00	—	ns
J83	TCK clock pulse width measured at 1.5 V	40.00	—	ns
J84	TCK rise and fall times	0.00	10.00	ns
J85	TMS, TDI data setup time	5.00	—	ns
J86	TMS, TDI data hold time	25.00	—	ns
J87	TCK low to TDO data valid	—	27.00	ns
J88	TCK low to TDO data invalid	0.00	—	ns
J89	TCK low to TDO high impedance	—	20.00	ns
J90	$\overline{\text{TRST}}$ assert time	100.00	—	ns
J91	$\overline{\text{TRST}}$ setup time to TCK low	40.00	—	ns
J92	TCK falling edge to output valid	—	50.00	ns
J93	TCK falling edge to output valid out of high impedance	—	50.00	ns
J94	TCK falling edge to output high impedance	—	50.00	ns
J95	Boundary scan input valid to TCK rising edge	50.00	—	ns
J96	TCK rising edge to boundary scan input invalid	50.00	—	ns

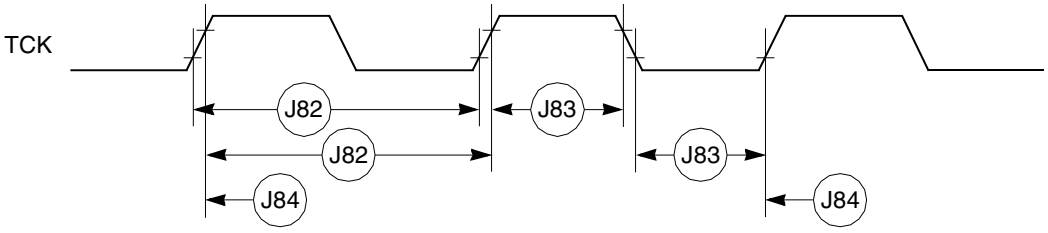


Figure 38. JTAG Test Clock Input Timing

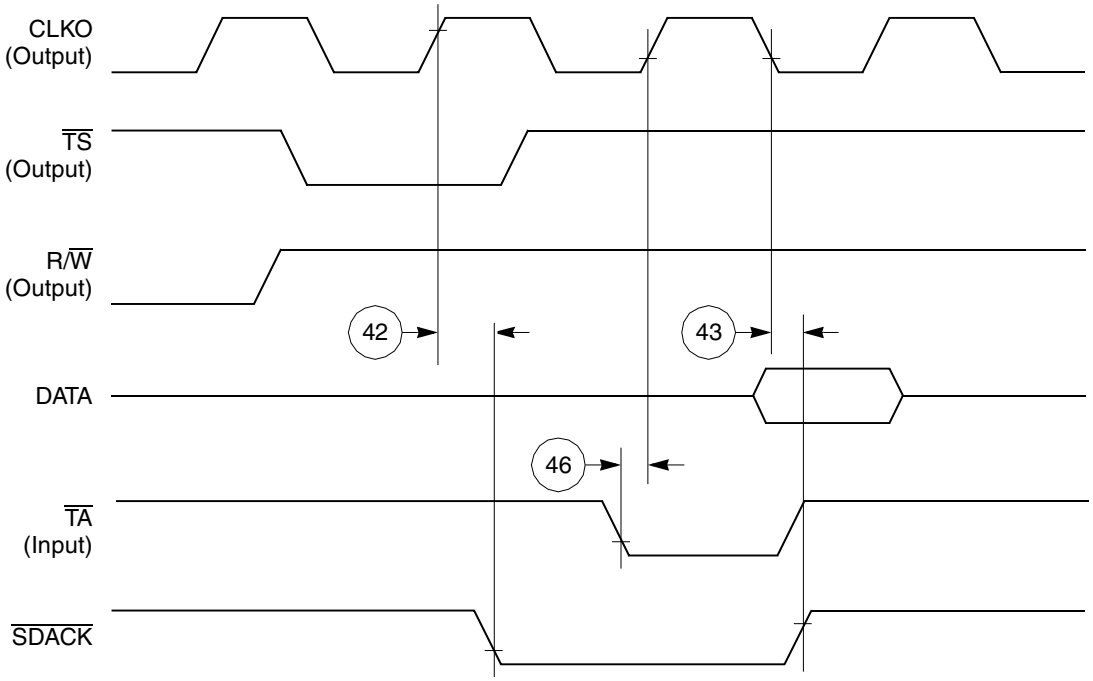


Figure 49. SDACK Timing Diagram—Peripheral Write, Externally-Generated TA

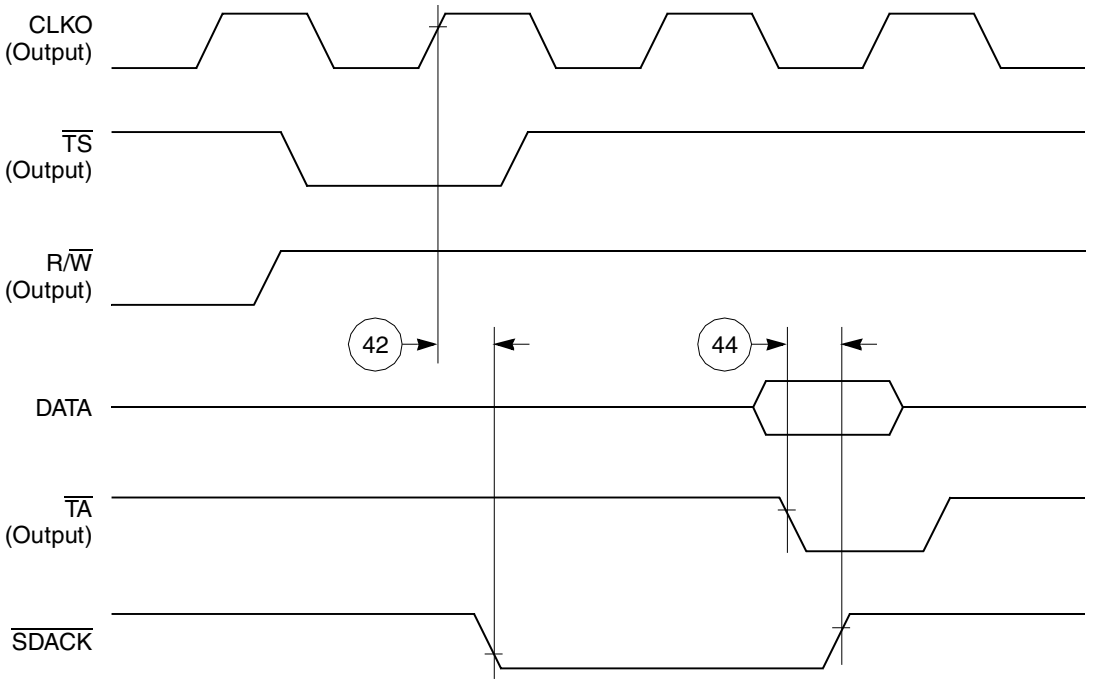


Figure 50. SDACK Timing Diagram—Peripheral Write, Internally-Generated TA

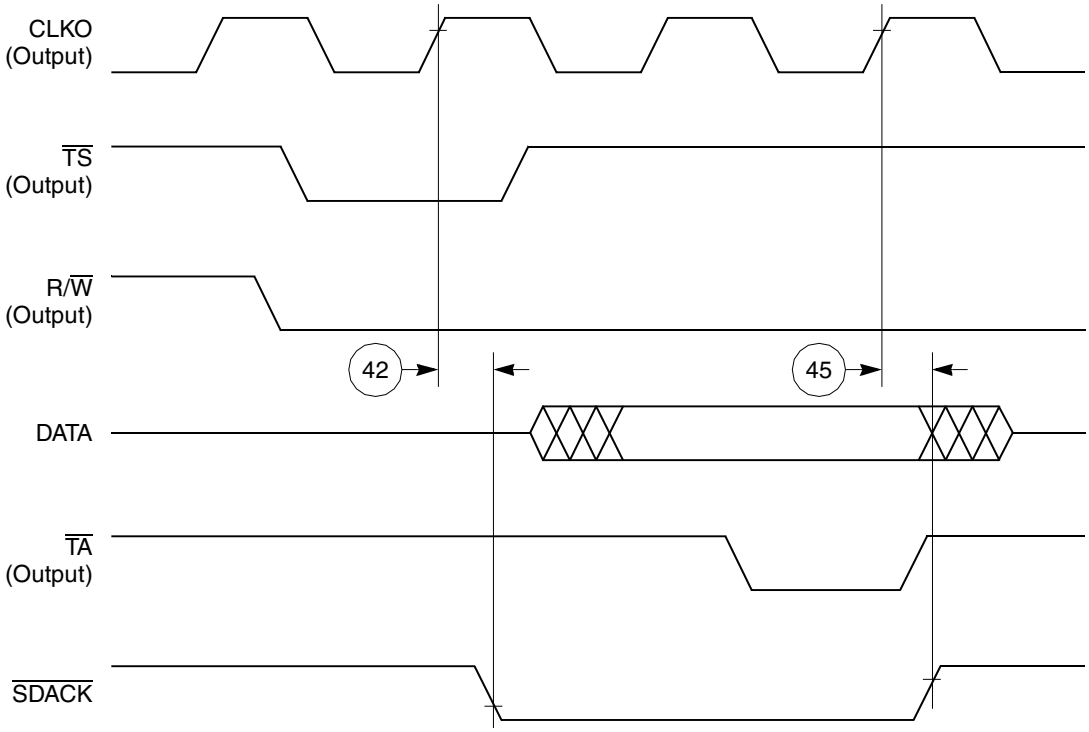


Figure 51. SDACK Timing Diagram—Peripheral Read, Internally-Generated TA

12.4 Baud Rate Generator AC Electrical Specifications

Table 19 provides the baud rate generator timings as shown in Figure 52.

Table 19. Baud Rate Generator Timing

Num	Characteristic	All Frequencies		Unit
		Min	Max	
50	BRGO rise and fall time	—	10	ns
51	BRGO duty cycle	40	60	%
52	BRGO cycle	40	—	ns

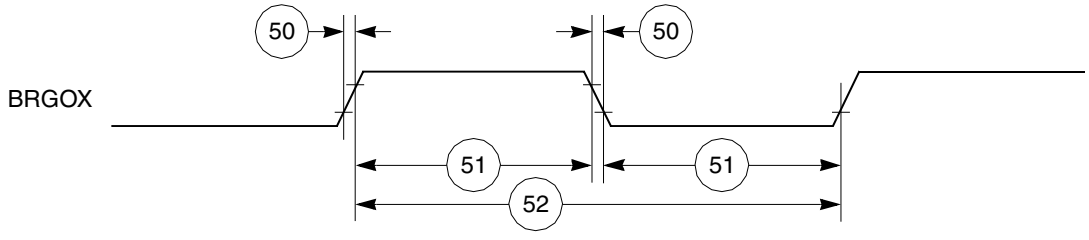


Figure 52. Baud Rate Generator Timing Diagram

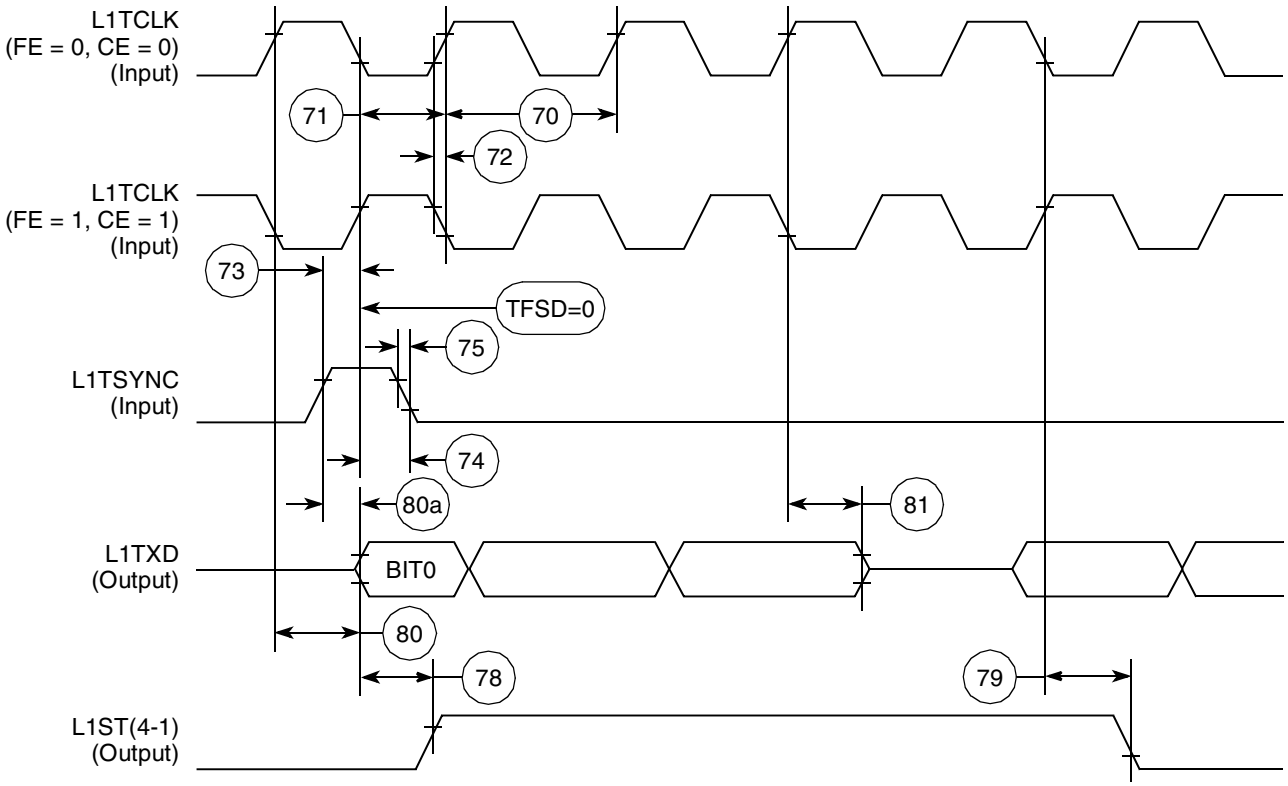


Figure 56. SI Transmit Timing Diagram (DSC = 0)

12.7 SCC in NMSI Mode Electrical Specifications

Table 22 provides the NMSI external clock timing.

Table 22. NMSI External Clock Timing

Num	Characteristic	All Frequencies		Unit
		Min	Max	
100	RCLK1 and TCLK1 width high[1]	1/SYNCCLK	—	ns
101	RCLK1 and TCLK1 width low	1/SYNCCLK + 5	—	ns
102	RCLK1 and TCLK1 rise/fall time	—	15.00	ns
103	TXD1 active delay (from TCLK1 falling edge)	0.00	50.00	ns
104	$\overline{\text{RTS1}}$ active/inactive delay (from TCLK1 falling edge)	0.00	50.00	ns
105	$\overline{\text{CTS1}}$ setup time to TCLK1 rising edge	5.00	—	ns
106	RXD1 setup time to RCLK1 rising edge	5.00	—	ns
107	RXD1 hold time from RCLK1 rising edge[2]	5.00	—	ns
108	$\overline{\text{CD1}}$ setup time to RCLK1 rising edge	5.00	—	ns

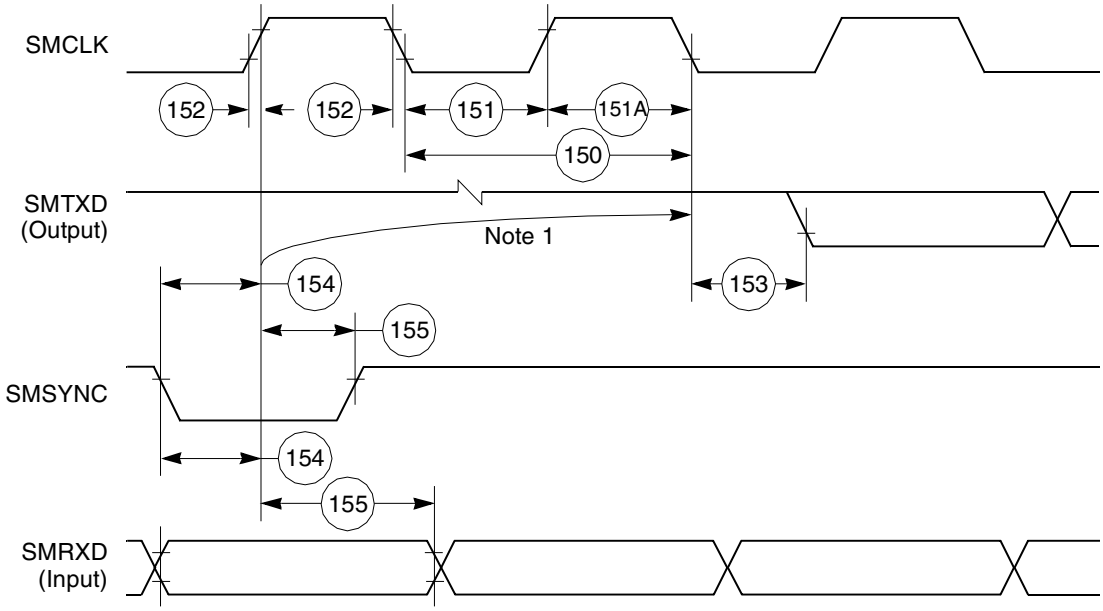
1 The ratios SyncCLK/RCLK1 and SyncCLK/TCLK1 must be greater than or equal to 2.25/1.
2 Also applies to $\overline{\text{CD}}$ and $\overline{\text{CTS}}$ hold time when they are used as external sync signals.

Table 23 provides the NMSI internal clock timing.

Table 23. NMSI Internal Clock Timing

Num	Characteristic	All Frequencies		Unit
		Min	Max	
100	RCLK1 and TCLK1 frequency[1]	0.00	SYNCCLK/3	MHz
102	RCLK1 and TCLK1 rise/fall time	—	—	ns
103	TXD1 active delay (from TCLK1 falling edge)	0.00	30.00	ns
104	$\overline{\text{RTS1}}$ active/inactive delay (from TCLK1 falling edge)	0.00	30.00	ns
105	$\overline{\text{CTS1}}$ setup time to TCLK1 rising edge	40.00	—	ns
106	RXD1 setup time to RCLK1 rising edge	40.00	—	ns
107	RXD1 hold time from RCLK1 rising edge[2]	0.00	—	ns
108	$\overline{\text{CD1}}$ setup time to RCLK1 rising edge	40.00	—	ns

1 The ratios SyncCLK/RCLK1 and SyncCLK/TCLK1 must be greater than or equal to 3/1.
2 Also applies to $\overline{\text{CD}}$ and $\overline{\text{CTS}}$ hold time when they are used as external sync signals



Note:
1. This delay is equal to an integer number of character-length clocks.

Figure 65. SMC Transparent Timing Diagram

12.10 SPI Master AC Electrical Specifications

Table 26 provides the SPI master timings as shown in Figure 66 and Figure 67.

Table 26. SPI Master Timing

Num	Characteristic	All Frequencies		Unit
		Min	Max	
160	MASTER cycle time	4	1024	t_{cyc}
161	MASTER clock (SCK) high or low time	2	512	t_{cyc}
162	MASTER data setup time (inputs)	15	—	ns
163	Master data hold time (inputs)	0	—	ns
164	Master data valid (after SCK edge)	—	10	ns
165	Master data hold time (outputs)	0	—	ns
166	Rise time output	—	15	ns
167	Fall time output	—	15	ns

Table 39. Pin Assignments (continued)

Name	Pin Number	Type
WE0, BS_B0, IORD	B18	Output
WE1, BS_B1, IOWR	E16	Output
WE2, BS_B2, PCOE	C17	Output
WE3, BS_B3, PCWE	B19	Output
BS_A[0:3]	D17, C18, C19, F16	Output
GPL_A0, GPL_B0	B17	Output
OE, GPL_A1, GPL_B1	A18	Output
GPL_A[2:3], GPL_B[2:3], CS[2:3]	D16, A17	Output
UPWAITA, GPL_A4	B13	Bidirectional
UPWAITB, GPL_B4	A14	Bidirectional
GPL_A5	C13	Output
PORESET	B3	Input
RSTCONF	D4	Input
HRESET	B4	Open-drain
SRESET	A3	Open-drain
XTAL	A4	Analog output
EXTAL	D5	Analog input (3.3 V only)
CLKOUT	G4	Output
EXTCLK	A5	Input (3.3 V only)
TEXP	C4	Output
ALE_A	B7	Output
CE1_A	B15	Output
CE2_A	C15	Output
WAIT_A, SOC_Split[1]	A2	Input
WAIT_B	C3	Input
IP_A0, UTPB_Split0[1]	B1	Input
IP_A1, UTPB_Split1[1]	C1	Input
IP_A2, IOIS16_A, UTPB_Split2[1]	F4	Input
IP_A3, UTPB_Split3[1]	E3	Input
IP_A4, UTPB_Split4[1]	D2	Input
IP_A5, UTPB_Split5[1]	D1	Input
IP_A6, UTPB_Split6[1]	E2	Input
IP_A7, UTPB_Split7[1]	D3	Input

Table 39. Pin Assignments (continued)

Name	Pin Number	Type
ALE_B, DSCK/AT1	D8	Bidirectional Three-state
IP_B[0:1], IWP[0:1], VFLS[0:1]	A9, D9	Bidirectional
IP_B2, $\overline{\text{IOIS16\_B}}$, AT2	C8	Bidirectional Three-state
IP_B3, IWP2, VF2	C9	Bidirectional
IP_B4, LWP0, VF0	B9	Bidirectional
IP_B5, LWP1, VF1	A10	Bidirectional
IP_B6, DSDI, AT0	A8	Bidirectional Three-state
IP_B7, $\overline{\text{PTR}}$, AT3	B8	Bidirectional Three-state
OP0, UtpClk_Split[1]	B6	Bidirectional
OP1	C6	Output
OP2, MODCK1, $\overline{\text{STS}}$	D6	Bidirectional
OP3, MODCK2, DSDO	A6	Bidirectional
BADDR30, $\overline{\text{REG}}$	A7	Output
BADDR[28:29]	C5, B5	Output
$\overline{\text{AS}}$	D7	Input
PA15, USBRXD	N16	Bidirectional
PA14, $\overline{\text{USBOE}}$	P17	Bidirectional (Optional: open-drain)
PA13, RXD2	W11	Bidirectional
PA12, TXD2	P16	Bidirectional (Optional: open-drain)
PA11, RXD4, MII1-TXD0, RMII1-TXD0	W9	Bidirectional (Optional: open-drain)
PA10, MII1-TXER, TIN4, CLK7	W17	Bidirectional (Optional: open-drain)
PA9, L1TXDA, RXD3	T15	Bidirectional (Optional: open-drain)
PA8, L1RXDA, TXD3	W15	Bidirectional (Optional: open-drain)
PA7, CLK1, L1RCLKA, BRGO1, TIN1	V14	Bidirectional
PA6, CLK2, $\overline{\text{TOUT1}}$	U13	Bidirectional
PA5, CLK3, L1TCLKA, BRGO2, TIN2	W13	Bidirectional

Table 39. Pin Assignments (continued)

Name	Pin Number	Type
PE14, RXD3, MII2-TXD0, RMII2-TXD0	V7	Bidirectional
TMS	V18	Input
TDI, DSDI	T16	Input
TCK, DSCK	U17	Input
$\overline{\text{TRST}}$	W18	Input
TDO, DSDO	T17	Output
MII1_CRS	T11	Input
MII_MDIO	P19	Bidirectional
MII1_TXEN, RMII1_TXEN	T5	Output
MII1_COL	U12	Input
V_{SSSYN1}	C2	PLL analog V_{DD} and GND
V_{SSSYN}	E4	Power
V_{DDLSYN}	B2	Power
GND	G6, G7, G8, G9, G10, G11, G12, G13, H7, H8, H9, H10, H11, H12, H13, H14, J7, J8, J9, J10, J11, J12, J13, K7, K8, K9, K10, K11, K12, K13, L7, L8, L9, L10, L11, L12, L13, M7, M8, M9, M10, M11, M12, M13, N7, N8, N9, N10, N11, N12, N13, N14, P7, P13, R16	Power
V_{DDL}	E5, E6, E9, E11, E14, G15, H5, J5, J15, K15, L5, M15, N5, R6, R9, R10, R12, R15	Power
V_{DDH}	E7, E8, E10, E12, E13, E15, F5, F6, F7, F8, F9, F10, F11, F12, F13, F14, F15, G5, G14, H6, H15, J6, J14, K5, K6, K14, L6, L14, L15, M5, M6, M14, N6, N15, P5, P6, P8, P9, P10, P11, P12, P14, P15, R5, R7, R8, R11, R13, R14	Power
N/C	N17	No connect

[1] ESAR mode only.

17 Document Revision History

Table 40 lists significant changes between revisions of this hardware specification.

Table 40. Document Revision History

Revision Number	Date	Changes
7	07/2010	In Table 9, "Bus Operation Timings," changed the following: • Updated TRLX condition value for B22a/b/c to "TRLX = [0 or 1]" • Removed TRLX condition for B23 • Updated condition and equation for B30 to "Invalid GPCM read/write access (MIN = 0.25 × B1 – 2.00)" • Updated note 8 to "The timing B30 refers to $\overline{CS}$ when ACS = 00 and to $\overline{CS}$ and $\overline{WE}$(0:3) when CSNT = 0."
6	05/2010	Added minimum load for CLKOUT in Section 10, "Bus Signal Timing."
5	03/2009	Updated formatting of Table 12 , "PCMCIA Port Timing," Table 13, "Debug Port Timing," Table 14, "Reset Timing," and Table 15, "JTAG Timing."
4	08/2007	• On page 1, updated first paragraph and added a second paragraph. • After Table 2, inserted a new figure showing the undershoot/overshoot voltage (Figure 3) and renumbered the rest of the figures. • In Table 9, for reset timings B29f and B29g added footnote indicating that the formula only applies to bus operation up to 50 MHz. • In Figure 6, changed all reference voltage measurement points from 0.2 and 0.8 V to 50% level. • In Table 18, changed num 46 description to read, "$\overline{TA}$ assertion to rising edge ..." • In Figure 49, changed $\overline{TA}$ to reflect the rising edge of the clock.
3.0	7/22/2004	• Added sentence to Spec B1A about EXTCLK and CLKOUT being in Alignment for Integer Values • Added a footnote to Spec 41 specifying that EDM = 1 • Added RMII1_EN under M1II_EN in Table 36 Pin Assignments • Added a tablefootnote to Table 6 DC Electrical Specifications about meeting the VIL Max of the I2C Standard • Put the new part numbers in the Ordering Information Section
2.0	12/2003	• Changed the maximum operating frequency to 133 MHz. • Put in the orderable part numbers that are orderable. • Put the timing in the 80 MHz column. • Rounded the timings to hundredths in the 80 MHz column. • Put the pin numbers in footnotes by the maximum currents in Table 6. • Changed 22 and 41 in the Timing. • Put in the Thermal numbers.
1.0	9/2003	• Added the DSP information in the Features list • Fixed table formatting. • Nontechnical edits. • Released to the external web.
0.9	8/2003	Changed the USB description to full-/low-speed compatible.
0.8	8/2003	Added the Reference to USB 2.0 to the Features list and removed 1.1 from USB on the block diagrams.
0.7	7/2003	Added the RxClav and TxClav signals to PC15.
0.6	6/2003	Changed the pin descriptions per the June 22 spec.
0.5	5/2003	Changed some more typos, put in the phsel and phreq pins. Corrected the USB timing.