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"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

### Applications of "[Embedded - Microcontrollers](#)"

#### Details

Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	64MHz
Connectivity	I <sup>2</sup> C, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, LVD, POR, PWM, WDT
Number of I/O	25
Program Memory Size	64KB (32K x 16)
Program Memory Type	FLASH
EEPROM Size	1K x 8
RAM Size	3.6K x 8
Voltage - Supply (Vcc/Vdd)	2.3V ~ 5.5V
Data Converters	A/D 24x10b; D/A 1x5b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	28-SOIC (0.295", 7.50mm Width)
Supplier Device Package	28-SOIC
Purchase URL	<a href="https://www.e-xfl.com/product-detail/microchip-technology/pic18f26k40-e-so">https://www.e-xfl.com/product-detail/microchip-technology/pic18f26k40-e-so</a>

# PIC18(L)F26/45/46K40

## REGISTER 4-4: OSCSTAT: OSCILLATOR STATUS REGISTER 1

R-q/q	R-q/q	R-q/q	R-q/q	R-q/q	R-q/q	U-0	R-q/q
EXTOR	HFOR	MFOR	LFOR	SOR	ADOR	—	PLL R
bit 7							bit 0

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

q = Reset value is determined by hardware

bit 7	<b>EXTOR:</b> EXTOSC (external) Oscillator Ready bit 1 = The oscillator is ready to be used 0 = The oscillator is not enabled, or is not yet ready to be used
bit 6	<b>HFOR:</b> HFINTOSC Oscillator Ready bit 1 = The oscillator is ready to be used 0 = The oscillator is not enabled, or is not yet ready to be used
bit 5	<b>MFOR:</b> MFINTOSC Oscillator Ready 1 = The oscillator is ready to be used 0 = The oscillator is not enabled, or is not yet ready to be used
bit 4	<b>LFOR:</b> LFINTOSC Oscillator Ready bit 1 = The oscillator is ready to be used 0 = The oscillator is not enabled, or is not yet ready to be used
bit 3	<b>SOR:</b> Secondary (Timer1) Oscillator Ready bit 1 = The oscillator is ready to be used 0 = The oscillator is not enabled, or is not yet ready to be used
bit 2	<b>ADOR:</b> ADC Oscillator Ready bit 1 = The oscillator is ready to be used 0 = The oscillator is not enabled, or is not yet ready to be used
bit 1	<b>Unimplemented:</b> Read as '0'
bit 0	<b>PLL R:</b> PLL is Ready bit 1 = The PLL is ready to be used 0 = The PLL is not enabled, the required input source is not ready, or the PLL is not locked.

## REGISTER 9-2: WDTCON1: WATCHDOG TIMER CONTROL REGISTER 1

U-0	R/W <sup>(3)</sup> -q/q <sup>(1)</sup>	R/W <sup>(3)</sup> -q/q <sup>(1)</sup>	R/W <sup>(3)</sup> -q/q <sup>(1)</sup>	U-0	R/W <sup>(4)</sup> -q/q <sup>(2)</sup>	R/W <sup>(4)</sup> -q/q <sup>(2)</sup>	R/W <sup>(4)</sup> -q/q <sup>(2)</sup>
—	WDTCS<2:0>			—	WINDOW<2:0>		
bit 7							bit 0

### Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	q = Value depends on condition

bit 7 **Unimplemented:** Read as '0'

bit 6-4 **WDTCS<2:0>:** Watchdog Timer Clock Select bits

111 = Reserved

•  
•  
•

010 = Reserved

001 = MFINTOSC 31.25 kHz

000 = LFINTOSC 31 kHz

bit 3 **Unimplemented:** Read as '0'

bit 2-0 **WINDOW<2:0>:** Watchdog Timer Window Select bits

WINDOW<2:0>	Window delay Percent of time	Window opening Percent of time
111	N/A	100
110	12.5	87.5
101	25	75
100	37.5	62.5
011	50	50
010	62.5	37.5
001	75	25
000	87.5	12.5

- Note 1:** If WDTCCS <2:0> in CONFIG3H = 111, the Reset value of WDTCS<2:0> is 000.
- 2:** The Reset value of WINDOW<2:0> is determined by the value of WDTCCS<2:0> in the CONFIG3H register.
- 3:** If WDTCCS<2:0> in CONFIG3H ≠ 111, these bits are read-only.
- 4:** If WDTCCS<2:0> in CONFIG3H ≠ 111, these bits are read-only.

## 11.1.3 READING THE PROGRAM FLASH MEMORY

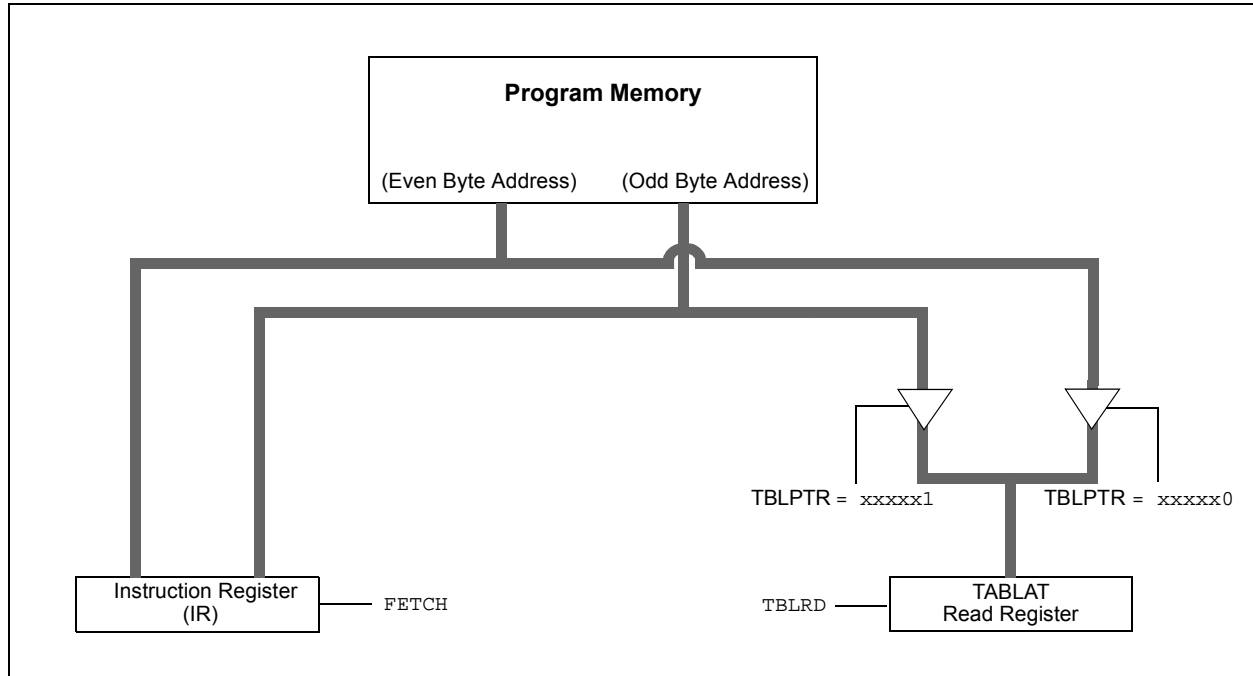
The **TBLRD** instruction retrieves data from program memory and places it into data RAM. Table reads from program memory are performed one byte at a time.

**TBLPTR** points to a byte address in program space. Executing **TBLRD** places the byte pointed to into **TABLAT**. In addition, **TBLPTR** can be modified automatically for the next table read operation.

The CPU operation is suspended during the read, and it resumes immediately after. From the user point of view, **TABLAT** is valid in the next instruction cycle.

The internal program memory is typically organized by words. The Least Significant bit of the address selects between the high and low bytes of the word. Figure 11-4 shows the interface between the internal program memory and the **TABLAT**.

**FIGURE 11-4: READS FROM PROGRAM FLASH MEMORY**



**EXAMPLE 11-1: READING A PROGRAM FLASH MEMORY WORD**

```

MOV LW    CODE_ADDR_UPPER    ; Load TBLPTR with the base
MOV WF    TBLPTRU             ; address of the word
MOV LW    CODE_ADDR_HIGH
MOV WF    TBLPTRH
MOV LW    CODE_ADDR_LOW
MOV WF    TBLPTRL

READ_WORD
TBLRD*+           ; read into TABLAT and increment
MOV F    TABLAT, W    ; get data
MOV WF    WORD_EVEN
TBLRD*+           ; read into TABLAT and increment
MOV FW    TABLAT, W    ; get data
MOV F    WORD_ODD
    
```

## 11.3 Data EEPROM Memory

The data EEPROM is a nonvolatile memory array, separate from the data RAM and program memory, which is used for long-term storage of program data. It is not directly mapped in either the register file or program memory space but is indirectly addressed through the Special Function Registers (SFRs). The EEPROM is readable and writable during normal operation over the entire VDD range.

Four SFRs are used to read and write to the data EEPROM as well as the program memory. They are:

- NVMCON1
- NVMCON2
- NVMDAT
- NVMADRL
- NVMADRH(1)

**Note 1:** NVMADRH register is not implemented on PIC18(L)F45K40.

The data EEPROM allows byte read and write. When interfacing to the data memory block, NVMDAT holds the 8-bit data for read/write and the NVMADRH:NVMADRL register pair hold the address of the EEPROM location being accessed.

The EEPROM data memory is rated for high erase/write cycle endurance. A byte write automatically erases the location and writes the new data (erase-before-write). The write time is controlled by an internal programming timer; it will vary with voltage and temperature as well as from chip-to-chip. Please refer to the Data EEPROM Memory parameters in **Section 37.0 “Electrical Specifications”** for limits.

### 11.3.1 NVMADRL AND NVMADRH REGISTERS

The NVMADRH:NVMADRL registers are used to address the data EEPROM for read and write operations.

### 11.3.2 NVMCON1 AND NVMCON2 REGISTERS

Access to the data EEPROM is controlled by two registers: NVMCON1 and NVMCON2. These are the same registers which control access to the program memory and are used in a similar manner for the data EEPROM.

The NVMCON1 register (Register 11-1) is the control register for data and program memory access. Control bits NVMREG<1:0> determine if the access will be to program, Data EEPROM Memory or the User IDs, Configuration bits, Revision ID and Device ID.

The WREN bit, when set, will allow a write operation. On power-up, the WREN bit is clear.

The WRERR bit is set by hardware when the WR bit is set and cleared when the internal programming timer expires and the write operation is complete.

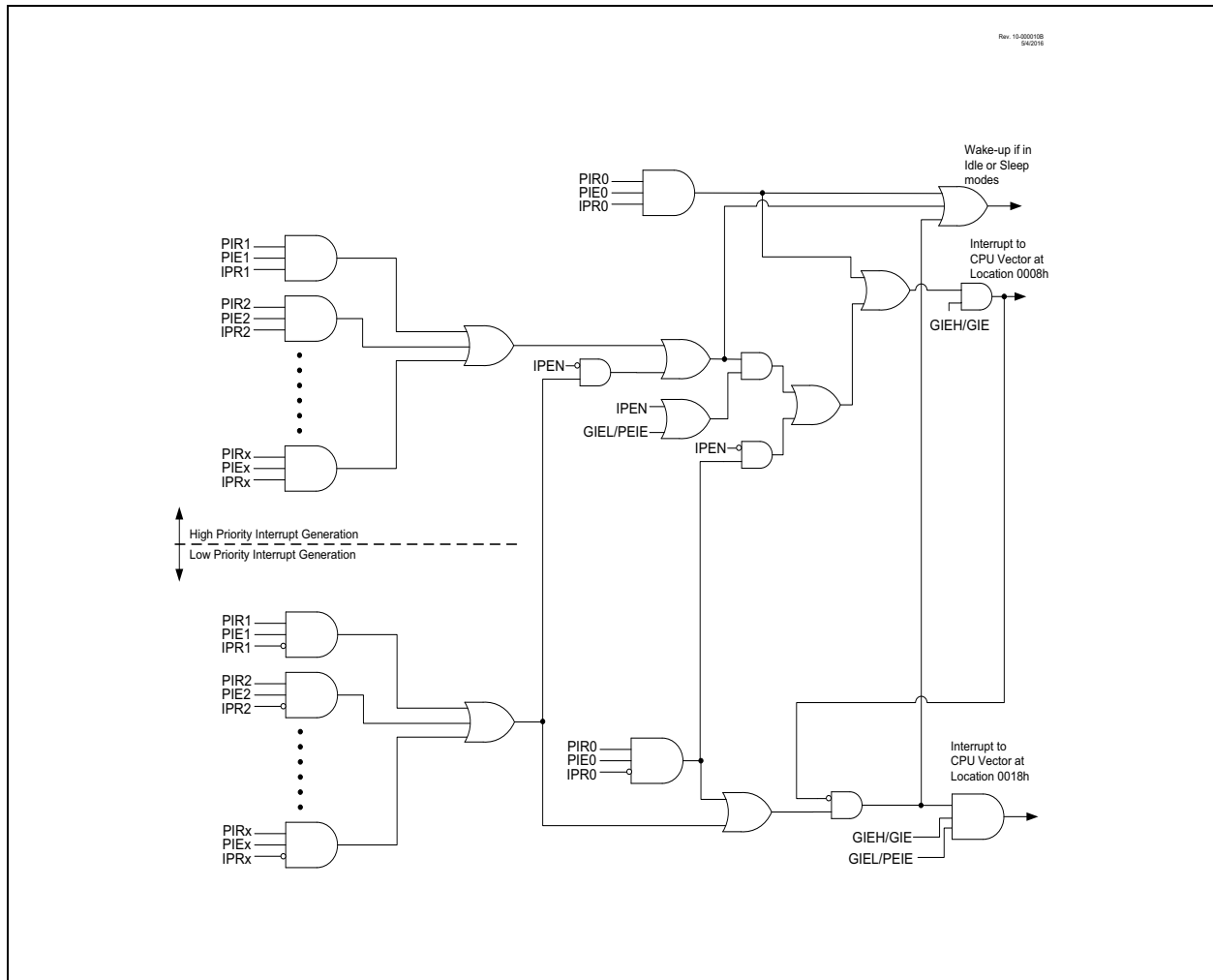
The WR control bit initiates write operations. The bit can be set but not cleared by software. It is cleared only by hardware at the completion of the write operation.

The NVMIF interrupt flag bit of the PIR7 register is set when the write is complete. It must be cleared by software.

Control bits, RD and WR, start read and erase/write operations, respectively. These bits are set by firmware and cleared by hardware at the completion of the operation.

The RD bit cannot be set when accessing program memory (NVMREG<1:0> = 0x10). Program memory is read using table read instructions. See **Section 11.1.1 “Table Reads and Table Writes”** regarding table reads.

**FIGURE 14-1: PIC18 INTERRUPT LOGIC**



## 16.6 Register Definitions: Interrupt-on-Change Control

### REGISTER 16-1: IOCxP: INTERRUPT-ON-CHANGE POSITIVE EDGE REGISTER EXAMPLE

R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
IOCxP7	IOCxP6	IOCxP5	IOCxP4	IOCxP3	IOCxP2	IOCxP1	IOCxP0
bit 7							bit 0

#### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

bit 7-0

**IOCxP<7:0>:** Interrupt-on-Change Positive Edge Enable bits

1 = Interrupt-on-Change enabled on the IOCx pin for a positive-going edge. Associated Status bit and interrupt flag will be set upon detecting an edge.

0 = Interrupt-on-Change disabled for the associated pin.

### REGISTER 16-2: IOCxN: INTERRUPT-ON-CHANGE NEGATIVE EDGE REGISTER EXAMPLE

R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
IOCxN7	IOCxN6	IOCxN5	IOCxN4	IOCxN3	IOCxN2	IOCxN1	IOCxN0
bit 7							bit 0

#### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

bit 7-0

**IOCxN<7:0>:** Interrupt-on-Change Negative Edge Enable bits

1 = Interrupt-on-Change enabled on the IOCx pin for a negative-going edge. Associated Status bit and interrupt flag will be set upon detecting an edge.

0 = Interrupt-on-Change disabled for the associated pin

### REGISTER 16-3: IOCxF: INTERRUPT-ON-CHANGE FLAG REGISTER EXAMPLE

R/W/HS-0/0	R/W/HS-0/0	R/W/HS-0/0	R/W/HS-0/0	R/W/HS-0/0	R/W/HS-0/0	R/W/HS-0/0	R/W/HS-0/0
IOCxF7	IOCxF6	IOCxF5	IOCxF4	IOCxF3	IOCxF2	IOCxF1	IOCxF0
bit 7							bit 0

#### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

HS - Bit is set in hardware

bit 7-0

**IOCxF<7:0>:** Interrupt-on-Change Flag bits

1 = A enabled change was detected on the associated pin. Set when IOCxP[n] = 1 and a positive edge was detected on the IOCn pin, or when IOCxN[n] = 1 and a negative edge was detected on the IOCn pin

0 = No change was detected, or the user cleared the detected change

# PIC18(L)F26/45/46K40

**REGISTER 18-3: TMR0L: TIMER0 COUNT REGISTER**

R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
TMR0<7:0>							
bit 7				bit 0			

**Legend:**

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7-0      **TMR0<7:0>**:TMR0 Counter bits <7:0>

**REGISTER 18-4: TMR0H: TIMER0 PERIOD REGISTER**

R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1	R/W-1/1
TMR0<15:8>							
bit 7				bit 0			

**Legend:**

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7-0      When T016BIT = 0  
**PR0<7:0>**:TMR0 Period Register Bits <7:0>  
When T016BIT = 1  
**TMR0<15:8>**: TMR0 Counter bits <15:8>

**TABLE 18-1: SUMMARY OF REGISTERS ASSOCIATED WITH TIMER0**

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on Page
TMR0L	TMR0<7:0>								226
TMR0H	TMR0<15:8>								226
T0CON0	T0EN	—	T0OUT	T016BIT	T0OUTPS<3:0>				224
T0CON1	T0CS<2:0>			T0ASYNC	T0CKPS<3:0>				225
T0CKIPPS	—	—	—	T0CKIPPS<4:0>				216	
TMR0PPS	—	—	—	TMR0PPS<4:0>				216	
INTCON	GIE/GIEH	PEIE/GIEL	IPEN	—	—	INT2EDG	INT1EDG	INT0EDG	170
PIR0	—	—	TMR0IF	IOCIF	—	INT2IF	INT1IF	INT0IF	171
PIE0	—	—	TMR0IE	IOCIE	—	INT2IE	INT1IE	INT0IE	179
IPR0	—	—	TMR0IP	IOCIP	—	INT2IP	INT1IP	INT0IP	187
PMD1	—	TMR6MD	TMR5MD	TMR4MD	TMR3MD	TMR2MD	TMR1MD	TMR0MD	69

**Legend:** — = Unimplemented location, read as '0'. Shaded cells are not used by the Timer0 module.



## REGISTER 19-5: TMRxL: TIMERx LOW BYTE REGISTER

R/W-x/x	R/W-x/x	R/W-x/x	R/W-x/x	R/W-x/x	R/W-x/x	R/W-x/x	R/W-x/x
TMRxL<7:0>							
bit 7				bit 0			

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

bit 7-0      **TMRxL<7:0>**:Timerx Low Byte bits

## REGISTER 19-6: TMRxH: TIMERx HIGH BYTE REGISTER

R/W-x/x	R/W-x/x	R/W-x/x	R/W-x/x	R/W-x/x	R/W-x/x	R/W-x/x	R/W-x/x
TMRxH<7:0>							
bit 7				bit 0			

### Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

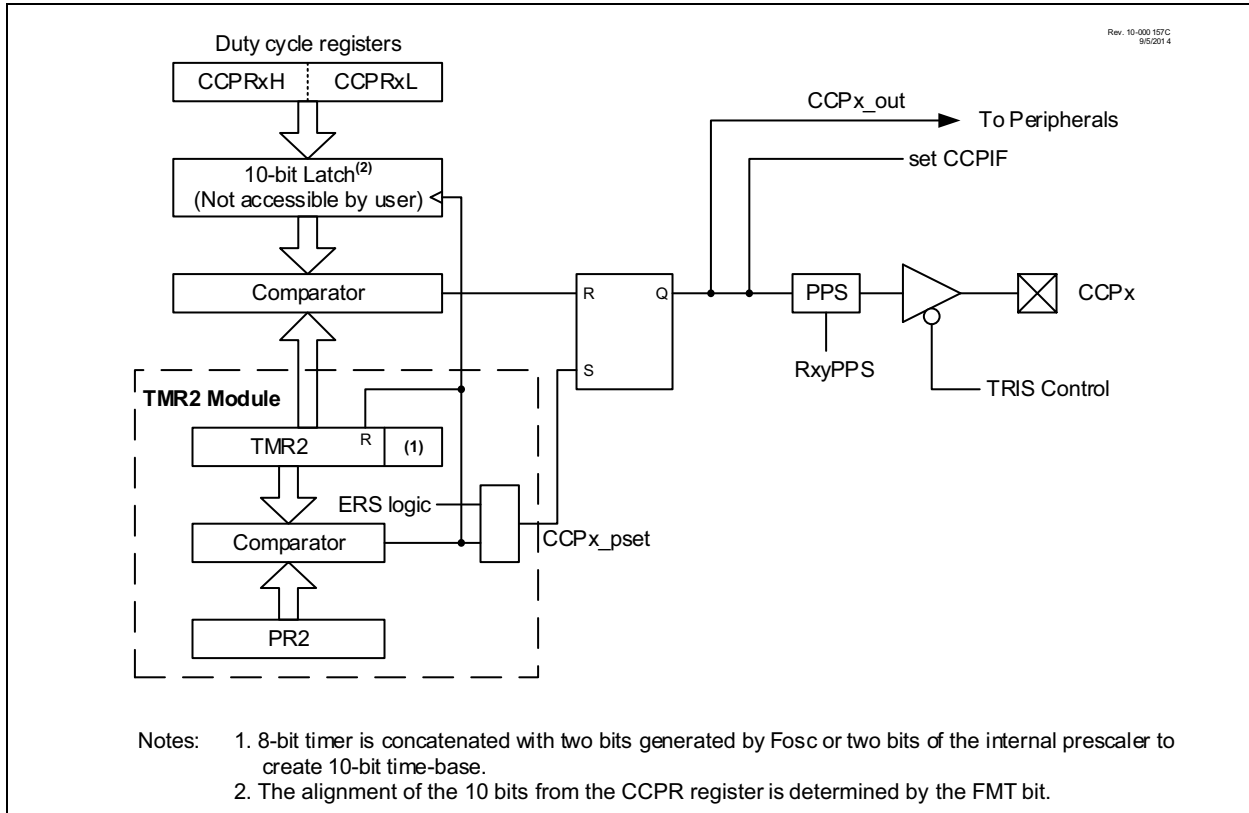
-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

bit 7-0      **TMRxH<7:0>**:Timerx High Byte bits

**FIGURE 21-4: SIMPLIFIED PWM BLOCK DIAGRAM**



**TABLE 21-3: EXAMPLE PWM FREQUENCIES AND RESOLUTIONS (Fosc = 20 MHz)**

PWM Frequency	1.22 kHz	4.88 kHz	19.53 kHz	78.12 kHz	156.3 kHz	208.3 kHz
Timer Prescale	16	4	1	1	1	1
PR2 Value	0xFF	0xFF	0xFF	0x3F	0x1F	0x17
Maximum Resolution (bits)	10	10	10	8	7	6.6

**TABLE 21-4: EXAMPLE PWM FREQUENCIES AND RESOLUTIONS (Fosc = 8 MHz)**

PWM Frequency	1.22 kHz	4.90 kHz	19.61 kHz	76.92 kHz	153.85 kHz	200.0 kHz
Timer Prescale	16	4	1	1	1	1
PR2 Value	0x65	0x65	0x65	0x19	0x0C	0x09
Maximum Resolution (bits)	8	8	8	6	5	5

## 21.5.7 OPERATION IN SLEEP MODE

In Sleep mode, the TMR2 register will not increment and the state of the module will not change. If the CCPx pin is driving a value, it will continue to drive that value. When the device wakes up, TMR2 will continue from its previous state.

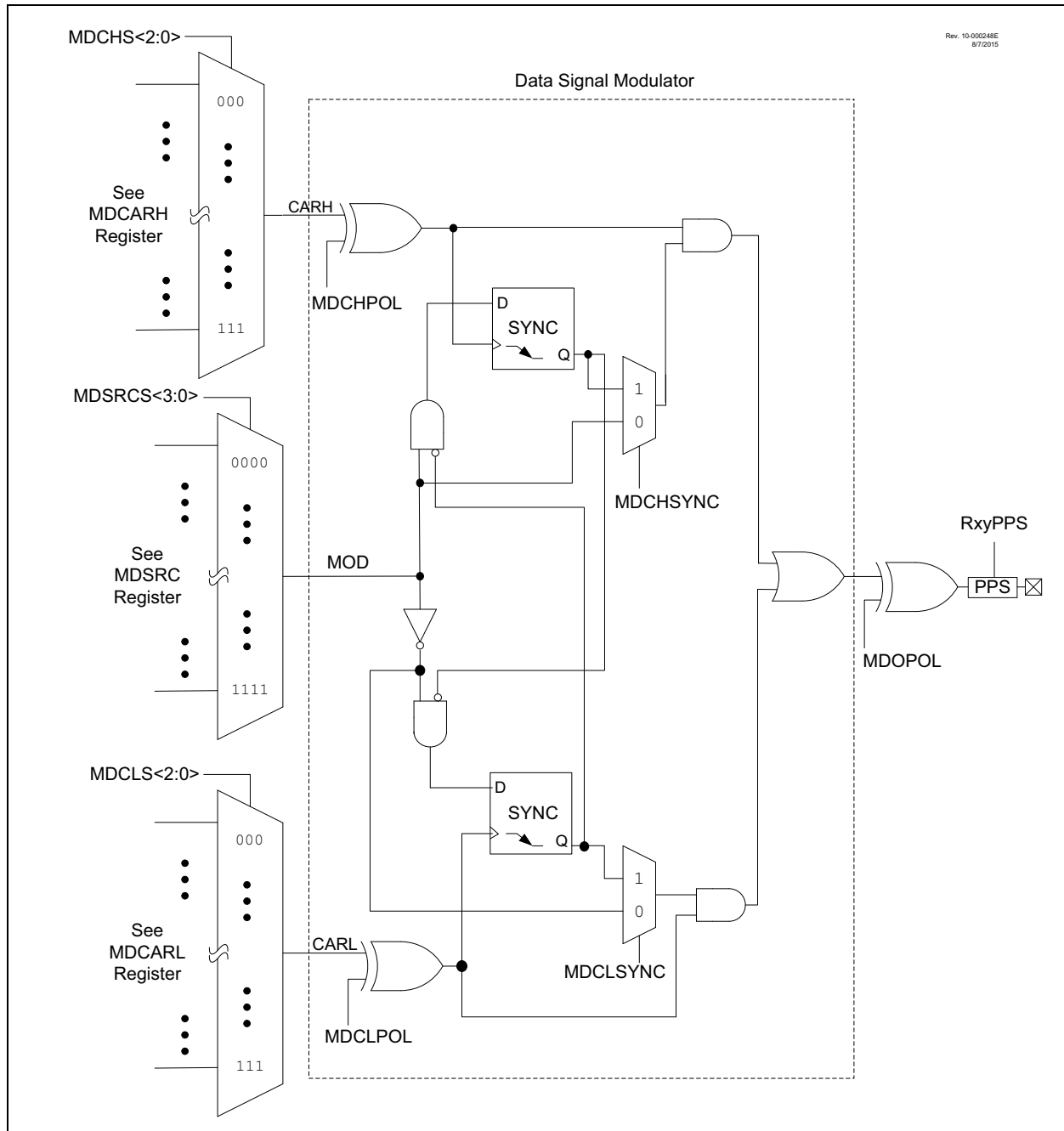
## 21.5.8 CHANGES IN SYSTEM CLOCK FREQUENCY

The PWM frequency is derived from the system clock frequency. Any changes in the system clock frequency will result in changes to the PWM frequency. See **Section 4.0 “Oscillator Module (with Fail-Safe Clock Monitor)”** for additional details.

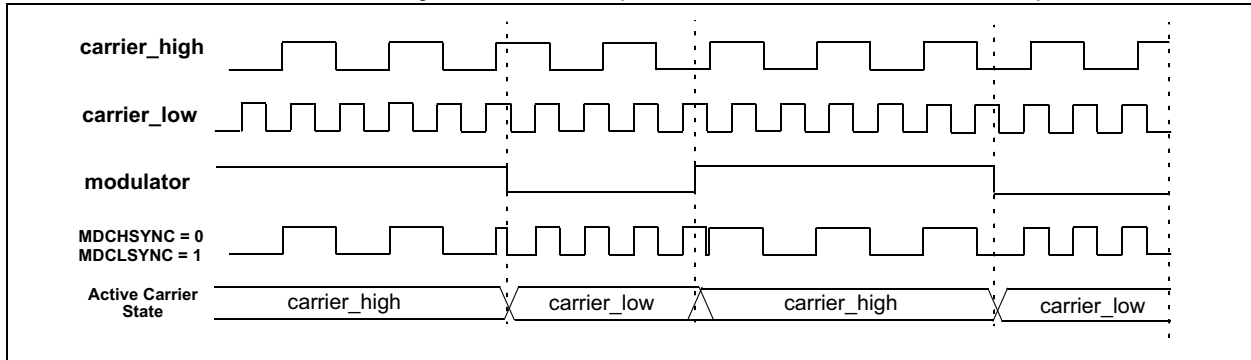
## 21.5.9 EFFECTS OF RESET

Any Reset will force all ports to Input mode and the CCP registers to their Reset states.

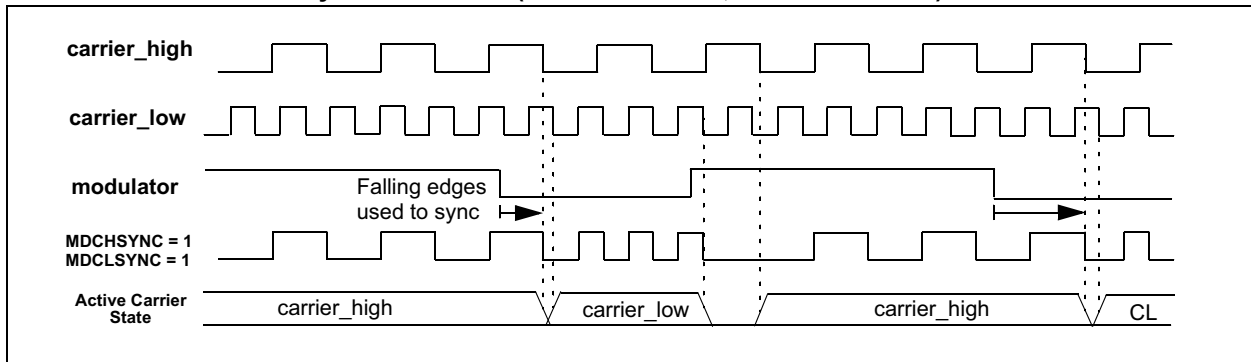
**FIGURE 25-1: SIMPLIFIED BLOCK DIAGRAM OF THE DATA SIGNAL MODULATOR**



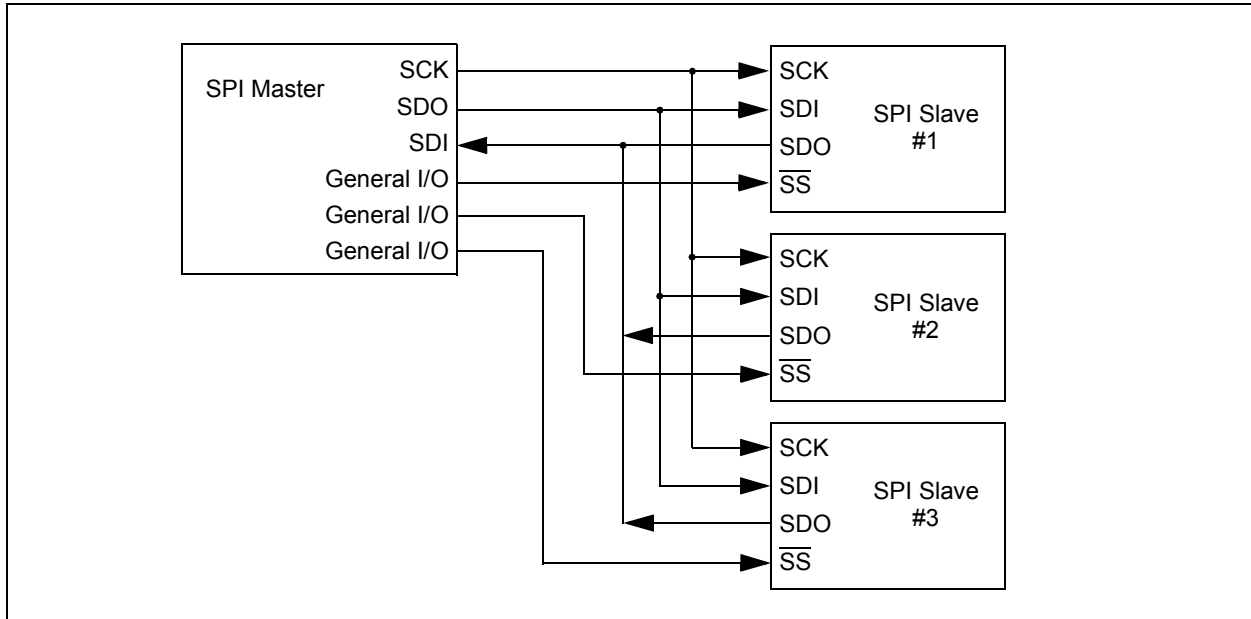
**FIGURE 25-5: Carrier Low Synchronization (MDSHSYNC = 0, MDCLSYNC = 1)**



**FIGURE 25-6: Full Synchronization (MDSHSYNC = 1, MDCLSYNC = 1)**



**FIGURE 26-2: SPI MASTER AND MULTIPLE SLAVE CONNECTION**



## 26.3 SPI Mode Registers

The MSSP module has five registers for SPI mode operation. These are:

- MSSP STATUS register (SSPxSTAT)
- MSSP Control register 1 (SSPxCON1)
- MSSP Control register 3 (SSPxCON3)
- MSSP Data Buffer register (SSPxBUF)
- MSSP Address register (SSPxADD)
- MSSP Shift register (SSPSR)  
(Not directly accessible)

SSPxCON1 and SSPxSTAT are the control and STATUS registers in SPI mode operation. The SSPxCON1 register is readable and writable. The lower six bits of the SSPxSTAT are read-only. The upper two bits of the SSPxSTAT are read/write.

In one SPI master mode, SSPxADD can be loaded with a value used in the Baud Rate Generator. More information on the Baud Rate Generator is available in **Section 26.11 “Baud Rate Generator”**.

SSPSR is the shift register used for shifting data in and out. SSPxBUF provides indirect access to the SSPSR register. SSPxBUF is the buffer register to which data bytes are written, and from which data bytes are read.

In receive operations, SSPSR and SSPxBUF together create a buffered receiver. When SSPSR receives a complete byte, it is transferred to SSPxBUF and the SSPxIF interrupt is set.

During transmission, the SSPxBUF is not buffered. A write to SSPxBUF will write to both SSPxBUF and SSPSR.

## 27.5.2 SYNCHRONOUS SLAVE MODE

The following bits are used to configure the EUSART for synchronous slave operation:

- SYNC = 1
- CSRC = 0
- SREN = 0 (for transmit); SREN = 1 (for receive)
- CREN = 0 (for transmit); CREN = 1 (for receive)
- SPEN = 1

Setting the SYNC bit of the TXxSTA register configures the device for synchronous operation. Clearing the CSRC bit of the TXxSTA register configures the device as a slave. Clearing the SREN and CREN bits of the RCxSTA register ensures that the device is in the Transmit mode, otherwise the device will be configured to receive. Setting the SPEN bit of the RCxSTA register enables the EUSART.

### 27.5.2.1 EUSART Synchronous Slave Transmit

The operation of the Synchronous Master and Slave modes are identical (see **Section 27.5.1.3 “Synchronous Master Transmission”**), except in the case of the Sleep mode.

If two words are written to the TXxREG and then the SLEEP instruction is executed, the following will occur:

1. The first character will immediately transfer to the TSR register and transmit.
2. The second word will remain in the TXxREG register.
3. The TXxIF bit will not be set.
4. After the first character has been shifted out of TSR, the TXxREG register will transfer the second character to the TSR and the TXxIF bit will now be set.
5. If the PEIE and TXxIE bits are set, the interrupt will wake the device from Sleep and execute the next instruction. If the GIE bit is also set, the program will call the Interrupt Service Routine.

### 27.5.2.2 Synchronous Slave Transmission Setup

1. Set the SYNC and SPEN bits and clear the CSRC bit.
2. Clear the ANSEL bit for the CKx pin (if applicable).
3. Clear the CREN and SREN bits.
4. If interrupts are desired, set the TXxIE bit of the PIE3 register and the GIE and PEIE bits of the INTCON register.
5. If 9-bit transmission is desired, set the TX9 bit.
6. Enable transmission by setting the TXEN bit.
7. If 9-bit transmission is selected, insert the Most Significant bit into the TX9D bit.
8. Start transmission by writing the Least Significant eight bits to the TXxREG register.

## 31.1 ADC Configuration

When configuring and using the ADC the following functions must be considered:

- Port configuration
- Channel selection
- ADC voltage reference selection
- ADC conversion clock source
- Interrupt control
- Result formatting
- Conversion Trigger Selection
- ADC Acquisition Time
- ADC Precharge Time
- Additional Sample and Hold Capacitor
- Single/Double Sample Conversion
- Guard Ring Outputs

Refer to Section 31.2 “ADC Operation” for more information.

**Note:** It is recommended that when switching from an ADC channel of a higher voltage to a channel of a lower voltage, the software selects the Vss channel before switching. If the ADC does not have a dedicated Vss input channel, the Vss selection (DAC1R<4:0> = b'00000') through the DAC output channel can be used. If the DAC is in use, a free input channel can be connected to Vss, and can be used in place of the DAC.

### 31.1.1 PORT CONFIGURATION

The ADC can be used to convert both analog and digital signals. When converting analog signals, the I/O pin should be configured for analog by setting the associated TRIS and ANSEL bits. Refer to **Section 15.0 “I/O Ports”** for more information.

**Note:** Analog voltages on any pin that is defined as a digital input may cause the input buffer to conduct excess current.

### 31.1.2 CHANNEL SELECTION

There are several channel selections available:

- Eight PORTA pins (RA<7:0>)
- Eight PORTB pins (RB<7:0>)
- Eight PORTC pins (RC<7:0>)
- Eight PORTD pins (RD<7:0>), PIC18(L)F45/46K40 only)
- Three PORTE pins (RE<2:0>), PIC18(L)F45/46K40 only)
- Temperature Indicator
- DAC output
- Fixed Voltage Reference (FVR)
- AVss (ground)

The ADPCH register determines which channel is connected to the sample and hold circuit.

When changing channels, a delay is required before starting the next conversion. 0



# PIC18(L)F26/45/46K40

## REGISTER 31-2: ADCON1: ADC CONTROL REGISTER 1

R/W-0/0	R/W-0/0	R/W-0/0	U-0	U-0	U-0	U-0	R/W-0/0
ADPPOL	ADIPEN	ADGPOL	—	—	—	—	ADDSEN
bit 7							bit 0

### Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7

**ADPPOL:** Precharge Polarity bit

If ADPRE>0x00:

ADPPOL	Action During 1st Precharge Stage	
	External (selected analog I/O pin)	Internal (AD sampling capacitor)
1	Shorted to AVDD	C <sub>HOLD</sub> shorted to VSS
0	Shorted to VSS	C <sub>HOLD</sub> shorted to AVDD

Otherwise:

The bit is ignored

bit 6

**ADIPEN:** A/D Inverted Precharge Enable bit

If ADDSEN = 1

1 = The precharge and guard signals in the second conversion cycle are the opposite polarity of the first cycle

0 = Both Conversion cycles use the precharge and guards specified by ADPPOL and ADGPOL

Otherwise:

The bit is ignored

bit 5

**ADGPOL:** Guard Ring Polarity Selection bit

1 = ADC guard Ring outputs start as digital high during Precharge stage

0 = ADC guard Ring outputs start as digital low during Precharge stage

bit 4-1

**Unimplemented:** Read as '0'

bit 0

**ADDSEN:** Double-sample enable bit

1 = Two conversions are performed on each trigger. Data from the first conversion appears in ADPREV

0 = One conversion is performed for each trigger

## REGISTER 31-19: ADRESL: ADC RESULT REGISTER LOW, ADFM = 1

R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u	R/W-x/u
ADRES<7:0>							
bit 7				bit 0			

### Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7-0 **ADRES<7:0>**: ADC Result Register bits. Lower eight bits of 10-bit conversion result.

## REGISTER 31-20: ADPREVH: ADC PREVIOUS RESULT REGISTER

R-x	R-x	R-x	R-x	R-x	R-x	R-x	R-x
ADPREV<15:8>							
bit 7				bit 0			

### Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7-0 **ADPREV<15:8>**: Previous ADC Results bits  
 If ADPSIS = 1:  
 Upper byte of ADFLTR at the start of current ADC conversion  
 If ADPSIS = 0:  
 Upper bits of ADRES at the start of current ADC conversion<sup>(1)</sup>

**Note 1:** If ADPSIS = 0, ADPREVH and ADPREVL are formatted the same way as ADRES is, depending on the ADFM bit.

# PIC18(L)F26/45/46K40

## ANDWF

## AND W with f

Syntax: ANDWF f {,d {,a}}

Operands:  $0 \leq f \leq 255$   
 $d \in [0,1]$   
 $a \in [0,1]$

Operation: (W) .AND. (f) → dest

Status Affected: N, Z

Encoding: 

0001	01da	ffff	ffff
------	------	------	------

Description: The contents of W are AND'ed with register 'f'. If 'd' is '0', the result is stored in W. If 'd' is '1', the result is stored back in register 'f' (default).  
 If 'a' is '0', the Access Bank is selected. If 'a' is '1', the BSR is used to select the GPR bank.  
 If 'a' is '0' and the extended instruction set is enabled, this instruction operates in Indexed Literal Offset Addressing mode whenever  $f \leq 95$  (5Fh). See **Section 35.2.3 "Byte-Oriented and Bit-Oriented Instructions in Indexed Literal Offset Mode"** for details.

Words: 1

Cycles: 1

Q Cycle Activity:

Q1	Q2	Q3	Q4
Decode	Read register 'f'	Process Data	Write to destination

**Example:** ANDWF REG, 0, 0

Before Instruction

W = 17h  
 REG = C2h

After Instruction

W = 02h  
 REG = C2h

## BC

## Branch if Carry

Syntax: BC n

Operands:  $-128 \leq n \leq 127$

Operation: if CARRY bit is '1'  
 $(PC) + 2 + 2n \rightarrow PC$

Status Affected: None

Encoding: 

1110	0010	nnnn	nnnn
------	------	------	------

Description: If the CARRY bit is '1', then the program will branch.

The 2's complement number '2n' is added to the PC. Since the PC will have incremented to fetch the next instruction, the new address will be  $PC + 2 + 2n$ . This instruction is then a 2-cycle instruction.

Words: 1

Cycles: 1(2)

Q Cycle Activity:

If Jump:

Q1	Q2	Q3	Q4
Decode	Read literal 'n'	Process Data	Write to PC
No operation	No operation	No operation	No operation

If No Jump:

Q1	Q2	Q3	Q4
Decode	Read literal 'n'	Process Data	No operation

**Example:** HERE BC 5

Before Instruction

PC = address (HERE)

After Instruction

If CARRY = 1;  
 PC = address (HERE + 12)  
 If CARRY = 0;  
 PC = address (HERE + 2)

# PIC18(L)F26/45/46K40

<b>GOTO</b>	<b>Unconditional Branch</b>
Syntax:	GOTO k
Operands:	$0 \leq k \leq 1048575$
Operation:	$k \rightarrow PC<20:1>$
Status Affected:	None
Encoding:	
1st word ( $k<7:0>$ )	1110 1111 $k_{19}kkk$ $kkkk_0$
2nd word ( $k<19:8>$ )	1111 $k_{19}kkk$ $kkkk$ $kkkk_8$
Description:	GOTO allows an unconditional branch anywhere within entire 2-Mbyte memory range. The 20-bit value 'k' is loaded into PC<20:1>. GOTO is always a 2-cycle instruction.
Words:	2
Cycles:	2
Q Cycle Activity:	
	Q1 Q2 Q3 Q4
	Decode Read literal 'k'<7:0>, No operation Read literal 'k'<19:8>, Write to PC
	No operation No operation No operation No operation

**Example:** GOTO THERE  
 After Instruction  
 PC = Address (THERE)

<b>INCF</b>	<b>Increment f</b>
Syntax:	INCF f{,d{,a}}
Operands:	$0 \leq f \leq 255$ $d \in [0,1]$ $a \in [0,1]$
Operation:	$(f) + 1 \rightarrow \text{dest}$
Status Affected:	C, DC, N, OV, Z
Encoding:	0010 10da ffff ffff
Description:	The contents of register 'f' are incremented. If 'd' is '0', the result is placed in W. If 'd' is '1', the result is placed back in register 'f' (default). If 'a' is '0', the Access Bank is selected. If 'a' is '1', the BSR is used to select the GPR bank. If 'a' is '0' and the extended instruction set is enabled, this instruction operates in Indexed Literal Offset Addressing mode whenever $f \leq 95$ (5Fh). See <b>Section 35.2.3 "Byte-Oriented and Bit-Oriented Instructions in Indexed Literal Offset Mode"</b> for details.
Words:	1
Cycles:	1
Q Cycle Activity:	
	Q1 Q2 Q3 Q4
	Decode Read register 'f' Process Data Write to destination

**Example:** INCF CNT, 1, 0

Before Instruction  
 CNT = FFh  
 Z = 0  
 C = ?  
 DC = ?  
 After Instruction  
 CNT = 00h  
 Z = 1  
 C = 1  
 DC = 1

# PIC18(L)F26/45/46K40

## RETFIE Return from Interrupt

**Syntax:** RETFIE {s}

**Operands:**  $s \in [0,1]$

**Operation:** (TOS) → PC,  
 $1 \rightarrow \text{GIE/GIEH or PEIE/GIEL}$ ,  
 if  $s = 1$   
 (WS) → W,  
 (STATUS) → Status,  
 (BSRS) → BSR,  
 PCLATU, PCLATH are unchanged.

**Status Affected:** GIE/GIEH, PEIE/GIEL.

**Encoding:**

0000	0000	0001	000s
------	------	------	------

**Description:** Return from interrupt. Stack is popped and Top-of-Stack (TOS) is loaded into the PC. Interrupts are enabled by setting either the high or low priority global interrupt enable bit. If 's' = 1, the contents of the shadow registers, WS, STATUS and BSR, are loaded into their corresponding registers, W, Status and BSR. If 's' = 0, no update of these registers occurs (default).

**Words:** 1

**Cycles:** 2

**Q Cycle Activity:**

Q1	Q2	Q3	Q4
Decode	No operation	No operation	POP PC from stack Set GIEH or GIEL
No operation	No operation	No operation	No operation

**Example:** RETFIE 1

After Interrupt

PC	=	TOS
W	=	WS
BSR	=	BSRS
Status	=	STATUS
GIE/GIEH, PEIE/GIEL	=	1

## RETLW Return literal to W

**Syntax:** RETLW k

**Operands:**  $0 \leq k \leq 255$

**Operation:**  $k \rightarrow W$ ,  
 (TOS) → PC,  
 PCLATU, PCLATH are unchanged

**Status Affected:** None

**Encoding:**

0000	1100	kkkk	kkkk
------	------	------	------

**Description:** W is loaded with the 8-bit literal 'k'. The program counter is loaded from the top of the stack (the return address). The high address latch (PCLATH) remains unchanged.

**Words:** 1

**Cycles:** 2

**Q Cycle Activity:**

Q1	Q2	Q3	Q4
Decode	Read literal 'k'	Process Data	POP PC from stack, Write to W
No operation	No operation	No operation	No operation

### Example:

```
CALL TABLE ; W contains table
              ; offset value
              ; W now has
              ; table value

:
TABLE
  ADDWF PCL ; W = offset
  RETLW k0 ; Begin table
  RETLW k1 ;
:
  RETLW kn ; End of table
```

Before Instruction  
 W = 07h

After Instruction  
 W = value of kn