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Details

Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	64MHz
Connectivity	I ² C, LINbus, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, LVD, POR, PWM, WDT
Number of I/O	36
Program Memory Size	64KB (32K x 16)
Program Memory Type	FLASH
EEPROM Size	1K x 8
RAM Size	3.6K x 8
Voltage - Supply (Vcc/Vdd)	2.3V ~ 5.5V
Data Converters	A/D 35x10b; D/A 1x5b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	44-VQFN Exposed Pad
Supplier Device Package	44-QFN (8x8)
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic18f46k40-i-ml

8.13 Determining the Cause of a Reset

Upon any Reset, multiple bits in the STATUS and PCON0 registers are updated to indicate the cause of the Reset. Table 8-3 shows the Reset conditions of these registers.

TABLE 8-3: RESET CONDITION FOR SPECIAL REGISTERS

Condition	Program Counter	STATUS Register ^(2,3)	PCON0 Register
Power-on Reset	0	-110 0000	0011 110x
Brown-out Reset	0	-110 0000	0011 11u0
MCLR Reset during normal operation	0	-uuu uuuu	uuuu 0uuu
MCLR Reset during Sleep	0	-10u uuuu	uuuu 0uuu
WDT Time-out Reset	0	-0uu uuuu	uuu0 uuuu
WDT Wake-up from Sleep	PC + 2	-00u uuuu	uuuu uuuu
WWDT Window Violation Reset	0	-uuu uuuu	uu0u uuuu
Interrupt Wake-up from Sleep	PC + 2 ⁽¹⁾	-10u 0uuu	uuuu uuuu
RESET Instruction Executed	0	-uuu uuuu	uuuu u0uu
Stack Overflow Reset (STVREN = 1)	0	-uuu uuuu	1uuu uuuu
Stack Underflow Reset (STVREN = 1)	0	-uuu uuuu	u1uu uuuu

Legend: u = unchanged, x = unknown, – = unimplemented bit, reads as '0'.

Note 1: When the wake-up is due to an interrupt and Global Interrupt Enable bit (GIE) is set the return address is pushed on the stack and PC is loaded with the corresponding interrupt vector (depending on source, high or low priority) after execution of PC + 2.

2: If a Status bit is not implemented, that bit will be read as '0'.

3: Status bits Z, C, DC are reset by POR/BOR (Register 10-2).

8.14 Power Control (PCON0) Register

The Power Control (PCON0) register contains flag bits to differentiate between a:

- Brown-out Reset ($\overline{\text{BOR}}$)
- Power-on Reset ($\overline{\text{POR}}$)
- Reset Instruction Reset ($\overline{\text{RI}}$)
- MCLR Reset ($\overline{\text{RMCLR}}$)
- Watchdog Timer Reset ($\overline{\text{RWDI}}$)
- Watchdog Window Violation ($\overline{\text{WDTWV}}$)
- Stack Underflow Reset (STKUNF)
- Stack Overflow Reset (STKOVF)

The PCON0 register bits are shown in Register 8-2.

Hardware will change the corresponding register bit during the Reset process; if the Reset was not caused by the condition, the bit remains unchanged (Table 8-3).

Software should reset the bit to the inactive state after restart (hardware will not reset the bit).

Software may also set any PCON0 bit to the active state, so that user code may be tested, but no Reset action will be generated.

TABLE 8-4: SUMMARY OF REGISTERS ASSOCIATED WITH RESETS

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on Page
BORCON	SBOREN	—	—	—	—	—	—	BORRDY	75
PCON0	STKOVF	STKUNF	$\overline{\text{WDTWV}}$	$\overline{\text{RWDI}}$	$\overline{\text{RMCLR}}$	$\overline{\text{RI}}$	$\overline{\text{POR}}$	$\overline{\text{BOR}}$	76
STATUS	—	$\overline{\text{TO}}$	$\overline{\text{PD}}$	N	OV	Z	DC	C	118
WDTCON0	—	—	WDTPS<4:0>					SEN	85
WDTCON1	—	WDTCS<2:0>			—	WINDOW<2:0>			86

Legend: — = unimplemented location, read as '0'. Shaded cells are not used by Resets.

TABLE 10-4: SPECIAL FUNCTION REGISTER MAP FOR PIC18(L)F26/45/46K40 DEVICES

Address	Name	Address	Name	Address	Name	Address	Name	Address	Name
F5Fh	ADPCH	F31h	FVRCON	F03h	RD4PPS ⁽¹⁾	ED5h	WDTPSH	EA7h	T3CKIPPS
F5Eh	ADPRE	F30h	HLVDCON1	F02h	RD3PPS ⁽¹⁾	ED4h	WDTPSL	EA6h	T1GPPS
F5Dh	ADCAP	F2Fh	HLVDCON0	F01h	RD2PPS ⁽¹⁾	ED3h	WDTCN1	EA5h	T1CKIPPS
F5Ch	ADACQ	F2Eh	ANSELE ⁽²⁾	F00h	RD1PPS ⁽²⁾	ED2h	WDTCN0	EA4h	T0CKIPPS
F5Bh	ADCON3	F2Dh	WPUE	EFFh	RD0PPS ⁽²⁾	ED1h	PIR7	EA3h	INT2PPS
F5Ah	ADCON2	F2Ch	ODCONE ⁽²⁾	EFeh	RC7PPS	ED0h	PIR6	EA2h	INT1PPS
F59h	ADCON1	F2Bh	SLRCONE ⁽²⁾	EFdh	RC6PPS	ECFh	PIR5	EA1h	INT0PPS
F58h	ADREF	F2Ah	INLVLE	EFCh	RC5PPS	ECEh	PIR4	EA0h	PPSLOCK
F57h	ADCLK	F29h	IOCEP	EFBh	RC4PPS	ECDh	PIR3	E9Fh	BAUD2CON
F56h	ADACT	F28h	IOCEN	EFAh	RC3PPS	ECCh	PIR2	E9Eh	TX2STA
F55h	MDCARH	F27h	IOCEF	EF9h	RC2PPS	ECBh	PIR1	E9Dh	RC2STA
F54h	MDCARL	F26h	ANSELD ⁽²⁾	EF8h	RC1PPS	ECAh	PIR0	E9Ch	SP2BRGH
F53h	MDSRC	F25h	WPUD ⁽²⁾	EF7h	RC0PPS	EC9h	PIE7	E9Bh	SP2BRGL
F52h	MDCON1	F24h	ODCOND ⁽²⁾	EF6h	RB7PPS	EC8h	PIE6	E9Ah	TX2REG
F51h	MDCON0	F23h	SLRCOND ⁽²⁾	EF5h	RB6PPS	EC7h	PIE5	E99h	RC2REG
F50h	SCANDTRIG	F22h	INLVLD ⁽²⁾	EF4h	RB5PPS	EC6h	PIE4	E98h	SSP2CON3
F4Fh	SCANCON0	F21h	ANSELC	EF3h	RB4PPS	EC5h	PIE3	E97h	SSP2CON2
F4Eh	SCANHADRU	F20h	WPUC	EF2h	RB3PPS	EC4h	PIE2	E96h	SSP2CON1
F4Dh	SCANHADRH	F1Fh	ODCONC	EF1h	RB2PPS	EC3h	PIE1	E95h	SSP2STAT
F4Ch	SCANHADRL	F1Eh	SLRCONC	EF0h	RB1PPS	EC2h	PIE0	E94h	SSP2MSK
F4Bh	SCANLADRU	F1Dh	INLVLC	EEFh	RB0PPS	EC1h	IPR7	E93h	SSP2ADD
F4Ah	SCANLADRH	F1Ch	IOCCP	EEeh	RA7PPS	EC0h	IPR6	E92h	SSP2BUF
F49h	SCANLADRL	F1Bh	IOCCN	EEDh	RA6PPS	EBFh	IPR5	E91h	SSP2SSPPS
F48h	CWG1STR	F1Ah	IOCCF	EECh	RA5PPS	EBEh	IPR4	E90h	SSP2DATPPS
F47h	CWG1AS1	F19h	ANSELB	EEBh	RA4PPS	EBDh	IPR3	E8Fh	SSP2CLKPPS
F46h	CWG1AS0	F18h	WPUB	EEAh	RA3PPS	EBCh	IPR2	E8Eh	TX2PPS
F45h	CWG1CON1	F17h	ODCONB	EE9h	RA2PPS	EBBh	IPR1	E8Dh	RX2PPS
F44h	CWG1CON0	F16h	SLRCONB	EE8h	RA1PPS	EBAh	IPR0		
F43h	CWG1DBF	F15h	INLVLB	EE7h	RA0PPS	EB9h	SSP1SSPPS		
F42h	CWG1DBR	F14h	IOCBP	EE6h	PMD5	EB8h	SSP1DATPPS		
F41h	CWG1ISM	F13h	IOCBN	EE5h	PMD4	EB7h	SSP1CLKPPS		
F40h	CWG1CLKCON	F12h	IOCBF	EE4h	PMD3	EB6h	TX1PPS		
F3Fh	CLKRCLK	F11h	ANSELA	EE3h	PMD2	EB5h	RX1PPS		
F3Eh	CLKRCON	F10h	WPUA	EE2h	PMD1	EB4h	MDSRCPPS		
F3Dh	CMOUT	F0Fh	ODCONA	EE1h	PMD0	EB3h	MDCARHPPS		
F3Ch	CM1PCH	F0Eh	SLRCONA	EE0h	BORCON	EB2h	MDCARLPPS		
F3Bh	CM1NCH	F0Dh	INLVLA	EDFh	VREGCON ⁽¹⁾	EB1h	CWGINPPS		
F3Ah	CM1CON1	F0Ch	IOCAP	EDEh	OSCFRQ	EB0h	CCP2PPS		
F39h	CM1CON0	F0Bh	IOCAN	EDDh	OSCTUNE	EAFh	CCP1PPS		
F38h	CM2PCH	F0Ah	IOCAF	EDCh	OSCEN	EAEh	ADACTPPS		
F37h	CM2NCH	F09h	RE2PPS ⁽²⁾	EDBh	OSCSTAT	EADh	T6INPPS		
F36h	CM2CON1	F08h	RE1PPS ⁽²⁾	EDAh	OSCCON3	EACH	T4INPPS		
F35h	CM2CON0	F07h	RE0PPS ⁽²⁾	ED9h	OSCCON2	EABh	T2INPPS		
F34h	DAC1CON1	F06h	RD7PPS ⁽²⁾	ED8h	OSCCON1	EAAh	T5GPPS		
F33h	DAC1CON0	F05h	RD6PPS ⁽²⁾	ED7h	CPUDOZE	EA9h	T5CKIPPS		
F32h	ZDCON	F04h	RD5PPS ⁽²⁾	ED6h	WDTTMR	EA8h	T3GPPS		

Note 1: Not available on LF parts

2: Not available on PIC18(L)F26K40 (28-pin variants).

11.1 Program Flash Memory

The Program Flash Memory is readable, writable and erasable during normal operation over the entire VDD range.

A read from program memory is executed one byte at a time. A write to program memory or program memory erase is executed on blocks of n bytes at a time. Refer to Table 11-3 for write and erase block sizes. A Bulk Erase operation cannot be issued from user code.

Writing or erasing program memory will cease instruction fetches until the operation is complete. The program memory cannot be accessed during the write or erase, therefore, code cannot execute. An internal programming timer terminates program memory writes and erases.

A value written to program memory does not need to be a valid instruction. Executing a program memory location that forms an invalid instruction results in a NOP.

It is important to understand the PFM memory structure for erase and programming operations. Program memory word size is 16 bits wide. PFM is arranged in

rows. A row is the minimum size that can be erased by user software. Refer to Table 11-3 for the row sizes for the these devices.

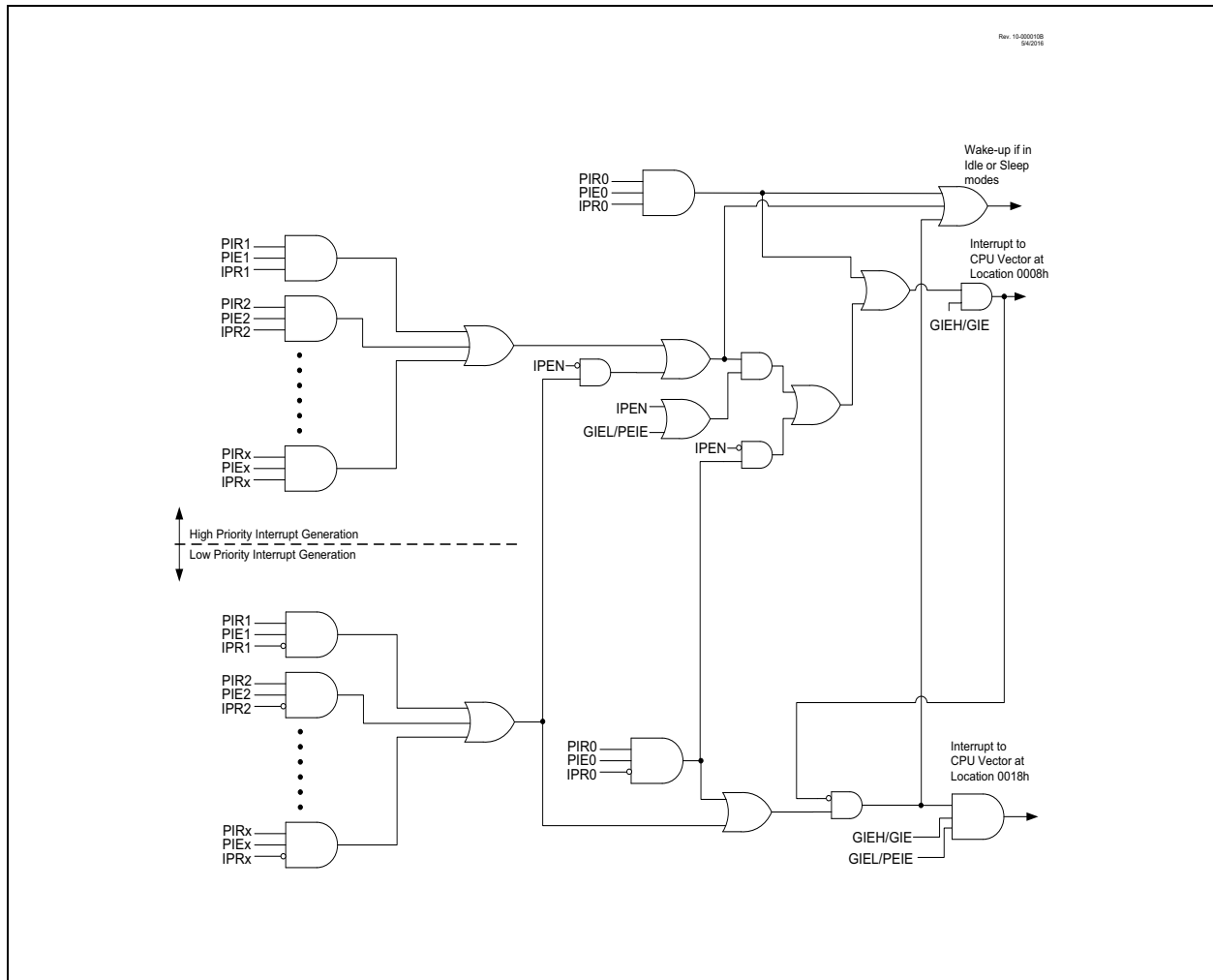
After a row has been erased, all or a portion of this row can be programmed. Data to be written into the program memory row is written to 6-bit wide data write latches. These latches are not directly accessible, but may be loaded via sequential writes to the TABLAT register.

Note: To modify only a portion of a previously programmed row, then the contents of the entire row must be read and saved in RAM prior to the erase. Then, the new data and retained data can be written into the write latches to reprogram the row of PFM. However, any unprogrammed locations can be written without first erasing the row. In this case, it is not necessary to save and rewrite the other previously programmed locations

TABLE 11-2: FLASH MEMORY ORGANIZATION BY DEVICE

Device	Row Erase Size (Words)	Write Latches (Bytes)	Program Flash Memory (Words)	Data Memory (Bytes)
PIC18(L)F45K40	32	64	16384	256
PIC18(L)F26K40			32768	1024
PIC18(L)F46K40				
PIC18(L)F27K40	64	128	65536	
PIC18(L)F47K40				

FIGURE 14-1: PIC18 INTERRUPT LOGIC



18.3 Programmable Prescaler

A software programmable prescaler is available for exclusive use with Timer0. There are 16 prescaler options for Timer0 ranging in powers of two from 1:1 to 1:32768. The prescaler values are selected using the T0CKPS<3:0> bits of the T0CON1 register.

The prescaler is not directly readable or writable. Clearing the prescaler register can be done by writing to the TMR0L register or the T0CON0, T0CON1 registers or by any Reset.

18.4 Programmable Postscaler

A software programmable postscaler (output divider) is available for exclusive use with Timer0. There are 16 postscaler options for Timer0 ranging from 1:1 to 1:16. The postscaler values are selected using the T0OUTPS<3:0> bits of the T0CON0 register.

The postscaler is not directly readable or writable. Clearing the postscaler register can be done by writing to the TMR0L register or the T0CON0, T0CON1 registers or by any Reset.

18.5 Operation During Sleep

When operating synchronously, Timer0 will halt. When operating asynchronously, Timer0 will continue to increment and wake the device from Sleep (if Timer0 interrupts are enabled) provided that the input clock source is active.

18.6 Timer0 Interrupts

The Timer0 interrupt flag bit (TMR0IF) is set when either of the following conditions occur:

- 8-bit TMR0L matches the TMR0H value
- 16-bit TMR0 rolls over from 'FFFFh'

When the postscaler bits (T0OUTPS<3:0>) are set to 1:1 operation (no division), the T0IF flag bit will be set with every TMR0 match or rollover. In general, the TMR0IF flag bit will be set every T0OUTPS + 1 matches or rollovers.

If Timer0 interrupts are enabled (TMR0IE bit of the PIE0 register = '1'), the CPU will be interrupted and the device may wake from Sleep (see **Section 18.2 "Clock Source Selection"** for more details).

18.7 Timer0 Output

The Timer0 output can be routed to any I/O pin via the RxyPPS output selection register (see **Section 17.0 "Peripheral Pin Select (PPS) Module"** for additional information). The Timer0 output can also be used by other peripherals, such as the auto-conversion trigger of the Analog-to-Digital Converter. Finally, the Timer0 output can be monitored through software via the Timer0 output bit (T0OUT) of the T0CON0 register (Register 18-1).

TMR0_out will be a pulse of one postscaled clock period when a match occurs between TMR0L and PR0 (Period register for TMR0) in 8-bit mode, or when TMR0 rolls over in 16-bit mode. The Timer0 output is a 50% duty cycle that toggles on each TMR0_out rising clock edge.

PIC18LF26/45/46K40

REGISTER 21-3: CCPxCAP: CAPTURE INPUT SELECTION MULTIPLEXER REGISTER

U-0	U-0	U-0	U-0	U-0	U-0	R/W-0/x	R/W-0/x
—	—	—	—	—	—	CTS<1:0>	
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-2

Unimplemented: Read as '0'

bit 1-0

CTS<1:0>: Capture Trigger Input Selection bits

CTS<1:0>	Connection	
	CCP1	CCP2
11	IOC_Interrupt	
10	CMP2_output	
01	CMP1_output	
00	Pin selected by CCP1PPS	Pin selected by CCP2PPS

REGISTER 21-4: CCPRxL: CCPx REGISTER LOW BYTE

R/W-x/x	R/W-x/x	R/W-x/x	R/W-x/x	R/W-x/x	R/W-x/x	R/W-x/x	R/W-x/x
CCPRx<7:0>							
bit 7							bit 0

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

-n = Value at POR

'1' = Bit is set

'0' = Bit is cleared

x = Bit is unknown

bit 7-0

MODE = Capture Mode:

CCPRxL<7:0>: LSB of captured TMR1 value

MODE = Compare Mode:

CCPRxL<7:0>: LSB compared to TMR1 value

MODE = PWM Mode && FMT = 0:

CCPRxL<7:0>: CCPW<7:0> – Pulse-Width LS 8 bits

MODE = PWM Mode && FMT = 1:

CCPRxL<7:6>: CCPW<1:0> – Pulse-Width LS 2 bits

CCPRxL<5:0>: Not used

23.0 ZERO-CROSS DETECTION (ZCD) MODULE

The ZCD module detects when an A/C signal crosses through the ground potential. The actual zero-crossing threshold is the zero-crossing reference voltage, V_{CPINV} , which is typically 0.75V above ground.

The connection to the signal to be detected is through a series current-limiting resistor. The module applies a current source or sink to the ZCD pin to maintain a constant voltage on the pin, thereby preventing the pin voltage from forward biasing the ESD protection diodes. When the applied voltage is greater than the reference voltage, the module sinks current. When the applied voltage is less than the reference voltage, the module sources current. The current source and sink action keeps the pin voltage constant over the full range of the applied voltage. The ZCD module is shown in the simplified block diagram Figure 23-2.

The ZCD module is useful when monitoring an A/C waveform for, but not limited to, the following purposes:

- A/C period measurement
- Accurate long term time measurement
- Dimmer phase delayed drive
- Low EMI cycle switching

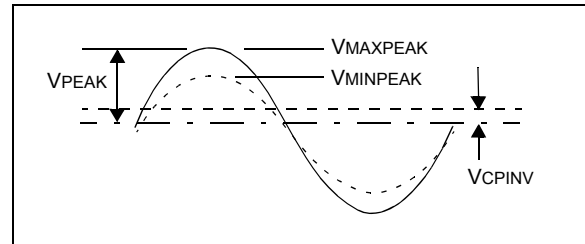
23.1 External Resistor Selection

The ZCD module requires a current-limiting resistor in series with the external voltage source. The impedance and rating of this resistor depends on the external source peak voltage. Select a resistor value that will drop all of the peak voltage when the current through the resistor is nominally 300 μ A. Refer to Equation 23-1 and Figure 23-1. Make sure that the ZCD I/O pin internal weak pull-up is disabled so it does not interfere with the current source and sink.

EQUATION 23-1: EXTERNAL RESISTOR

$$R_{SERIES} = \frac{V_{PEAK}}{3 \times 10^{-4}}$$

FIGURE 23-1: EXTERNAL VOLTAGE



REGISTER 26-11: SSPxADD: MSSP ADDRESS REGISTER (I²C MASTER MODE)

R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0	R/W-0
ADD<7:0>							
bit 7				bit 0			

Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

Master mode: I²C mode

bit 7-0 Baud Rate Clock Divider bits⁽¹⁾
 $SCK/SCL \text{ pin clock period} = ((SSPxADD<7:0> + 1) * 4) / F_{osc}$

10-Bit Slave mode – Most Significant Address Byte:

bit 7-3 **Not used:** Unused for Most Significant Address Byte. Bit state of this register is a don't care. Bit pattern sent by master is fixed by I²C specification and must be equal to, '11110'. However, those bits are compared by hardware and are not affected by the value in this register.

bit 2-1 **ADD<9:8>:** Two Most Significant bits of 10-bit Address

bit 0 **Not used:** Unused in this mode. Bit state is a don't care.

10-Bit Slave mode – Least Significant Address Byte:

bit 7-0 **ADD<7:0>:** Eight Least Significant bits of 10-bit Address

7-Bit Slave mode:

bit 7-1 7-bit Slave Address

bit 0 **Not used:** Unused in this mode. Bit state is a don't care.

Note 1: Values of 0x00, 0x01 and 0x02 are not valid for SSPxADD when used as a Baud Rate Generator for I²C. This is an implementation limitation.

REGISTER 26-12: SSPxMSK: MSSPx ADDRESS MASK REGISTER

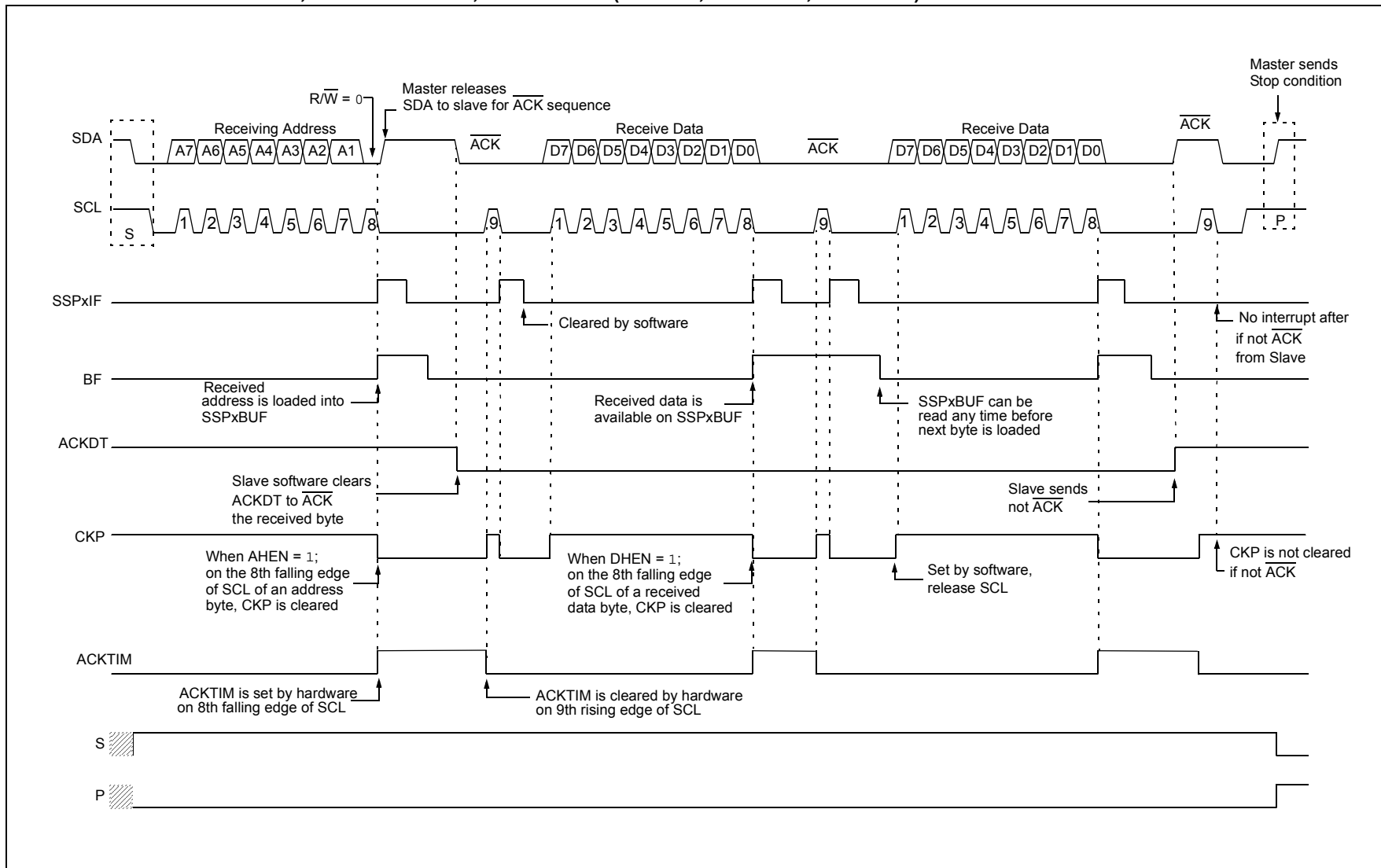
R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1	R/W-1
MSK<7:1>							MSK0
bit 7				bit 0			

Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7-1 **MSK<7:1>:** Mask bits
 1 = The received address bit n is compared to SSPxADDn to detect I²C address match
 0 = The received address bit n is not used to detect I²C address match

bit 0 **MSK0:** Mask bit for I²C Slave mode, 10-bit Address
 I²C Slave mode, 10-bit address (SSPM<3:0> = 0111 or 1111):
 1 = The received address bit 0 is compared to SSPxADD0 to detect I²C address match
 0 = The received address bit 0 is not used to detect I²C address match
 I²C Slave mode, 7-bit address, the bit is ignored.

FIGURE 26-17: I²C SLAVE, 7-BIT ADDRESS, RECEPTION (SEN = 1, AHEN = 1, DHEN = 1)

PIC18(L)F26/45/46K40

REGISTER 31-9: ADPRE: ADC PRECHARGE TIME CONTROL REGISTER

R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
ADPRE<7:0>							
bit 7				bit 0			

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

bit 7-0

ADPRE<7:0>: Precharge Time Select bits

11111111 = Precharge time is 255 clocks of the selected ADC clock

11111110 = Precharge time is 254 clocks of the selected ADC clock

•

•

•

00000001 = Precharge time is 1 clock of the selected ADC clock

00000000 = Precharge time is not included in the data conversion cycle

REGISTER 31-10: ADACQ: ADC ACQUISITION TIME CONTROL REGISTER

R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
ADACQ<7:0>							
bit 7				bit 0			

Legend:

R = Readable bit

W = Writable bit

U = Unimplemented bit, read as '0'

u = Bit is unchanged

x = Bit is unknown

-n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set

'0' = Bit is cleared

bit 7-0

ADACQ<7:0>: Acquisition (charge share time) Select bits

11111111 = Acquisition time is 255 clocks of the selected ADC clock

11111110 = Acquisition time is 254 clocks of the selected ADC clock

•

•

•

00000001 = Acquisition time is 1 clock of the selected ADC clock

00000000 = Acquisition time is not included in the data conversion cycle

Note: If ADPRE is not equal to '0', then ADACQ = b'00000000 means Acquisition time is 256 clocks of the selected ADC clock.

REGISTER 31-27: ADERRL: ADC SETPOINT ERROR LOW BYTE REGISTER

R-x	R-x	R-x	R-x	R-x	R-x	R-x	R-x
ADERR<7:0>							
bit 7							bit 0

Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7-0 **ADERR<7:0>**: ADC Setpoint Error LSB. Lower byte of ADC Setpoint Error calculation is determined by ADCALC bits of ADCON3, see Register 23-1 for more details.

REGISTER 31-28: ADLTHH: ADC LOWER THRESHOLD HIGH BYTE REGISTER

R/W-x/x	R/W-x/x	R/W-x/x	R/W-x/x	R/W-x/x	R/W-x/x	R/W-x/x	R/W-x/x
ADLTH<15:8>							
bit 7							bit 0

Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7-0 **ADLTH<15:8>**: ADC Lower Threshold MSB. ADLTH and ADUTH are compared with ADERR to set the ADUTHR and ADLTHR bits of ADSTAT. Depending on the setting of ADTMD, an interrupt may be triggered by the results of this comparison.

REGISTER 31-29: ADLTHL: ADC LOWER THRESHOLD LOW BYTE REGISTER

R/W-x/x	R/W-x/x	R/W-x/x	R/W-x/x	R/W-x/x	R/W-x/x	R/W-x/x	R/W-x/x
ADLTH<7:0>							
bit 7							bit 0

Legend:

R = Readable bit	W = Writable bit	U = Unimplemented bit, read as '0'
u = Bit is unchanged	x = Bit is unknown	-n/n = Value at POR and BOR/Value at all other Resets
'1' = Bit is set	'0' = Bit is cleared	

bit 7-0 **ADLTH<7:0>**: ADC Lower Threshold LSB. ADLTH and ADUTH are compared with ADERR to set the ADUTHR and ADLTHR bits of ADSTAT. Depending on the setting of ADTMD, an interrupt may be triggered by the results of this comparison.

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TABLE 31-5: SUMMARY OF REGISTERS ASSOCIATED WITH ADC

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on Page	
INTCON	GIE/GIEH	PEIE/GIEL	IPEN	—	—	INT2EDG	INT1EDG	INT0EDG	170	
PIE1	OSCFIE	CSWIE	—	—	—	—	ADTIE	ADIE	180	
PIR1	OSCFIF	CSWIF	—	—	—	—	ADTIF	ADIF	172	
ADCON0	ADON	ADCON	—	ADCS	—	ADFM	—	ADGO	448	
ADCON1	ADPPOL	ADIPEN	ADGPOL	—	—	—	—	ADDSSEN	449	
ADCON2	ADPSIS	ADCRS<2:0>			ADACLRL	ADMMD<2:0>			450	
ADCON3	—	ADCALC<2:0>			ADSOI	ADTMD<2:0>			451	
ADACT	—	—	—	—	ADACT<4:0>				450	
ADRESH	ADRESH<7:0>								458, 458	
ADRESL	ADRESL<7:0>								458, 459	
ADPREVH	ADPREV<15:8>								459	
ADPREVL	ADPREV<7:0>								460	
ADACCH	ADACC<15:8>								460	
ADACCL	ADACC<7:0>								460	
ADSTPTH	ADSTPT<15:8>								461	
ADSTPT	ADSTPT<7:0>								461	
ADERRL	ADERR<7:0>								462	
ADLTHH	ADLTH<15:8>								462	
ADLTHL	ADLTH<7:0>								462	
ADUTHH	ADUTH<15:8>								463	
ADUTHL	ADUTH<7:0>								463	
ADSTAT	ADAOV	ADUTHR	ADLTHR	ADMATH	ADSTAT<3:0>				452	
ADCLK	—	—	ADCS<5:0>						453	
ADREF	—	—	—	ADNREF	—	—	ADPREF<1:0>		453	
ADPCH	—	—	ADPCH<5:0>						454	
ADPRE	ADPRE<7:0>								455	
ADACQ	ADACQ<7:0>								455	
ADCAP	—	—	—	ADCAP<4:0>					456	
ADRPT	ADRPT<7:0>								456	
ADCNT	ADCNT<7:0>								457	
ADFLTRH	ADFLTR<15:8>								457	
ADFLTRL	ADFLTR<7:0>								457	
FVRCON	FVREN	FVRRDY	TSEN	TSRNG	CDAFVR<1:0>		ADFVR<1:0>		423	
DAC1CON1	—	—	—	DAC1R<4:0>						429
OSCSTAT	EXTOR	HFOR	MFOR	LFOR	SOR	ADOR	—	PLLRL	39	

Legend: — = unimplemented read as '0'. Shaded cells are not used for the ADC module.

32.0 COMPARATOR MODULE

Note: The PIC18(L)F26/45/46K40 devices have two comparators. Therefore, all information in this section refers to both C1 and C2.

Comparators are used to interface analog circuits to a digital circuit by comparing two analog voltages and providing a digital indication of their relative magnitudes. Comparators are very useful mixed signal building blocks because they provide analog functionality independent of program execution.

The analog comparator module includes the following features:

- Programmable input selection
- Programmable output polarity
- Rising/falling output edge interrupts
- Wake-up from Sleep
- CWG Auto-shutdown source
- Selectable voltage reference
- ADC Auto-trigger
- TMR1/3/5 Gate
- TMR2/4/6 Reset
- CCP Capture Mode Input
- DSM Modulator Source
- Input and Window signal to Signal Measurement Timer

32.1 Comparator Overview

A single comparator is shown in Figure 32-1 along with the relationship between the analog input levels and the digital output. When the analog voltage at V_{IN+} is less than the analog voltage at V_{IN-} , the output of the comparator is a digital low level. When the analog voltage at V_{IN+} is greater than the analog voltage at V_{IN-} , the output of the comparator is a digital high level.

FIGURE 32-1: SINGLE COMPARATOR

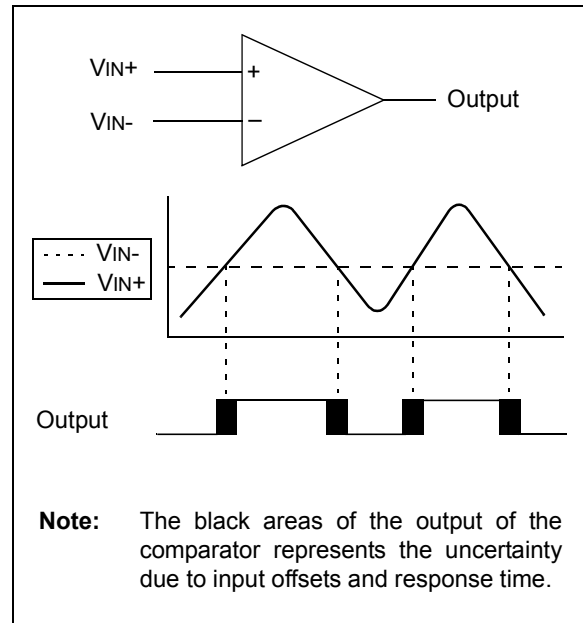
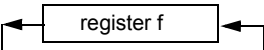


TABLE 35-2: INSTRUCTION SET

Mnemonic, Operands	Description	Cycles	16-Bit Instruction Word				Status Affected	Notes	
			MSb		LSb				
BYTE-ORIENTED OPERATIONS									
ADDWF	f, d, a	Add WREG and f	1	0010	01da	ffff	ffff	C, DC, Z, OV, N	1, 2
ADDWFC	f, d, a	Add WREG and CARRY bit to f	1	0010	00da	ffff	ffff	C, DC, Z, OV, N	1, 2
ANDWF	f, d, a	AND WREG with f	1	0001	01da	ffff	ffff	Z, N	1, 2
CLRF	f, a	Clear f	1	0110	101a	ffff	ffff	Z	2
COMF	f, d, a	Complement f	1	0001	11da	ffff	ffff	Z, N	1, 2
CPFSEQ	f, a	Compare f with WREG, skip =	1 (2 or 3)	0110	001a	ffff	ffff	None	4
CPFSGT	f, a	Compare f with WREG, skip >	1 (2 or 3)	0110	010a	ffff	ffff	None	4
CPFSLT	f, a	Compare f with WREG, skip <	1 (2 or 3)	0110	000a	ffff	ffff	None	1, 2
DECf	f, d, a	Decrement f	1	0000	01da	ffff	ffff	C, DC, Z, OV, N	1, 2, 3, 4
DECFSZ	f, d, a	Decrement f, Skip if 0	1 (2 or 3)	0010	11da	ffff	ffff	None	1, 2, 3, 4
DCFSNZ	f, d, a	Decrement f, Skip if Not 0	1 (2 or 3)	0100	11da	ffff	ffff	None	1, 2
INCF	f, d, a	Increment f	1	0010	10da	ffff	ffff	C, DC, Z, OV, N	1, 2, 3, 4
INCFSZ	f, d, a	Increment f, Skip if 0	1 (2 or 3)	0011	11da	ffff	ffff	None	4
INFSNZ	f, d, a	Increment f, Skip if Not 0	1 (2 or 3)	0100	10da	ffff	ffff	None	1, 2
IORWF	f, d, a	Inclusive OR WREG with f	1	0001	00da	ffff	ffff	Z, N	1, 2
MOVF	f, d, a	Move f	1	0101	00da	ffff	ffff	Z, N	1
MOVFF	f _s , f _d	Move f _s (source) to f _d (destination)	2	1100	ffff	ffff	ffff	None	
		1st word		1111	ffff	ffff	ffff		
		2nd word							
MOVWF	f, a	Move WREG to f	1	0110	111a	ffff	ffff	None	
MULWF	f, a	Multiply WREG with f	1	0000	001a	ffff	ffff	None	1, 2
NEGF	f, a	Negate f	1	0110	110a	ffff	ffff	C, DC, Z, OV, N	
RLCF	f, d, a	Rotate Left f through Carry	1	0011	01da	ffff	ffff	C, Z, N	1, 2
RLNCF	f, d, a	Rotate Left f (No Carry)	1	0100	01da	ffff	ffff	Z, N	
RRCF	f, d, a	Rotate Right f through Carry	1	0011	00da	ffff	ffff	C, Z, N	
RRNCF	f, d, a	Rotate Right f (No Carry)	1	0100	00da	ffff	ffff	Z, N	
SETF	f, a	Set f	1	0110	100a	ffff	ffff	None	1, 2
SUBFWB	f, d, a	Subtract f from WREG with borrow	1	0101	01da	ffff	ffff	C, DC, Z, OV, N	
SUBWF	f, d, a	Subtract WREG from f	1	0101	11da	ffff	ffff	C, DC, Z, OV, N	1, 2
SUBWFB	f, d, a	Subtract WREG from f with borrow	1	0101	10da	ffff	ffff	C, DC, Z, OV, N	
SWAPF	f, d, a	Swap nibbles in f	1	0011	10da	ffff	ffff	None	4
TSTFSZ	f, a	Test f, skip if 0	1 (2 or 3)	0110	011a	ffff	ffff	None	1, 2
XORWF	f, d, a	Exclusive OR WREG with f	1	0001	10da	ffff	ffff	Z, N	

- Note 1:** When a PORT register is modified as a function of itself (e.g., `MOVF PORTB, 1, 0`), the value used will be that value present on the pins themselves. For example, if the data latch is '1' for a pin configured as input and is driven low by an external device, the data will be written back with a '0'.
- 2:** If this instruction is executed on the TMR0 register (and where applicable, 'd' = 1), the prescaler will be cleared if assigned.
- 3:** If Program Counter (PC) is modified or a conditional test is true, the instruction requires two cycles. The second cycle is executed as a `NOP`.
- 4:** Some instructions are two-word instructions. The second word of these instructions will be executed as a `NOP` unless the first word of the instruction retrieves the information embedded in these 16 bits. This ensures that all program memory locations have a valid instruction.

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RLNCF		Rotate Left f (No Carry)							
Syntax:	RLNCF f {,d {,a}}								
Operands:	$0 \leq f \leq 255$ $d \in [0,1]$ $a \in [0,1]$								
Operation:	$(f < n) \rightarrow \text{dest} < n + 1 >$, $(f < 7) \rightarrow \text{dest} < 0 >$								
Status Affected:	N, Z								
Encoding:	<table><tr><td>0100</td><td>01da</td><td>ffff</td><td>ffff</td></tr></table>					0100	01da	ffff	ffff
0100	01da	ffff	ffff						
Description:	<p>The contents of register 'f' are rotated one bit to the left. If 'd' is '0', the result is placed in W. If 'd' is '1', the result is stored back in register 'f' (default). If 'a' is '0', the Access Bank is selected. If 'a' is '1', the BSR is used to select the GPR bank.</p> <p>If 'a' is '0' and the extended instruction set is enabled, this instruction operates in Indexed Literal Offset Addressing mode whenever $f \leq 95$ (5Fh). See Section 35.2.3 “Byte-Oriented and Bit-Oriented Instructions in Indexed Literal Offset Mode” for details.</p>								
									
Words:	1								
Cycles:	1								
Q Cycle Activity:									
	Q1	Q2	Q3	Q4					
	Decode	Read register 'f'	Process Data	Write to destination					

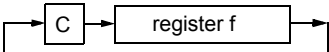
Example: RLNCF REG, 1, 0

Before Instruction

REG = 1010 1011

After Instruction

REG = 0101 0111

RRCF									
Syntax:	RRCF f {,d {,a}}								
Operands:	0 ≤ f ≤ 255 d ∈ [0,1] a ∈ [0,1]								
Operation:	(f<n> → dest<n – 1>, (f<0> → C, (C) → dest<7>								
Status Affected:	C, N, Z								
Encoding:	<table><tr><td>0011</td><td>00da</td><td>ffff</td><td>ffff</td></tr></table>	0011	00da	ffff	ffff				
0011	00da	ffff	ffff						
Description:	<p>The contents of register 'f' are rotated one bit to the right through the CARRY flag. If 'd' is '0', the result is placed in W. If 'd' is '1', the result is placed back in register 'f' (default).</p> <p>If 'a' is '0', the Access Bank is selected. If 'a' is '1', the BSR is used to select the GPR bank.</p> <p>If 'a' is '0' and the extended instruction set is enabled, this instruction operates in Indexed Literal Offset Addressing mode whenever f ≤ 95 (5Fh). See Section 35.2.3 “Byte-Oriented and Bit-Oriented Instructions in Indexed Literal Offset Mode” for details.</p>								
									
Words:	1								
Cycles:	1								
Q Cycle Activity:	<table><tr><th>Q1</th><th>Q2</th><th>Q3</th><th>Q4</th></tr><tr><td>Decode</td><td>Read register 'f'</td><td>Process Data</td><td>Write to destination</td></tr></table>	Q1	Q2	Q3	Q4	Decode	Read register 'f'	Process Data	Write to destination
Q1	Q2	Q3	Q4						
Decode	Read register 'f'	Process Data	Write to destination						

Example: RRCF REG, 0, 0

Before Instruction

REG = 1110 0110

C = 0

After Instruction

REG = 1110 0110

W = 0111 0011

C = 0

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SLEEP Enter Sleep mode

Syntax:	SLEEP				
Operands:	None				
Operation:	00h → WDT, 0 → WDT postscaler, 1 → \overline{TO} , 0 → \overline{PD}				
Status Affected:	\overline{TO} , \overline{PD}				
Encoding:	<table border="1"><tr><td>0000</td><td>0000</td><td>0000</td><td>0011</td></tr></table>	0000	0000	0000	0011
0000	0000	0000	0011		
Description:	<p>The Power-down Status bit (\overline{PD}) is cleared. The Time-out Status bit (\overline{TO}) is set. Watchdog Timer and its postscaler are cleared.</p> <p>The processor is put into Sleep mode with the oscillator stopped.</p>				
Words:	1				
Cycles:	1				
Q Cycle Activity:					

Q1	Q2	Q3	Q4
Decode	No operation	Process Data	Go to Sleep

Example: SLEEP

Before Instruction

\overline{TO} = ?

\overline{PD} = ?

After Instruction

\overline{TO} = 1†

\overline{PD} = 0

† If WDT causes wake-up, this bit is cleared.

SUBFWB Subtract f from W with borrow

Syntax:	SUBFWB f {,d {,a}}				
Operands:	$0 \leq f \leq 255$ $d \in [0,1]$ $a \in [0,1]$				
Operation:	$(W) - (f) - (\overline{C}) \rightarrow \text{dest}$				
Status Affected:	N, OV, C, DC, Z				
Encoding:	<table border="1"><tr><td>0101</td><td>01da</td><td>ffff</td><td>ffff</td></tr></table>	0101	01da	ffff	ffff
0101	01da	ffff	ffff		
Description:	<p>Subtract register 'f' and CARRY flag (borrow) from W (2's complement method). If 'd' is '0', the result is stored in W. If 'd' is '1', the result is stored in register 'f' (default).</p> <p>If 'a' is '0', the Access Bank is selected. If 'a' is '1', the BSR is used to select the GPR bank.</p> <p>If 'a' is '0' and the extended instruction set is enabled, this instruction operates in Indexed Literal Offset Addressing mode whenever $f \leq 95$ (5Fh). See Section 35.2.3 "Byte-Oriented and Bit-Oriented Instructions in Indexed Literal Offset Mode" for details.</p>				

Words: 1

Cycles: 1

Q Cycle Activity:

Q1	Q2	Q3	Q4
Decode	Read register 'f'	Process Data	Write to destination

Example 1: SUBFWB REG, 1, 0

Before Instruction

REG = 3

W = 2

C = 1

After Instruction

REG = FF

W = 2

C = 0

Z = 0

N = 1 ; result is negative

Example 2: SUBFWB REG, 0, 0

Before Instruction

REG = 2

W = 5

C = 1

After Instruction

REG = 2

W = 3

C = 1

Z = 0

N = 0 ; result is positive

Example 3: SUBFWB REG, 1, 0

Before Instruction

REG = 1

W = 2

C = 0

After Instruction

REG = 0

W = 2

C = 1

Z = 1

N = 0 ; result is zero

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CALLW Subroutine Call Using WREG

Syntax:	CALLW				
Operands:	None				
Operation:	(PC + 2) → TOS, (W) → PCL, (PCLATH) → PCH, (PCLATU) → PCU				
Status Affected:	None				
Encoding:	<table><tr><td>0000</td><td>0000</td><td>0001</td><td>0100</td></tr></table>	0000	0000	0001	0100
0000	0000	0001	0100		
Description:	<p>First, the return address (PC + 2) is pushed onto the return stack. Next, the contents of W are written to PCL; the existing value is discarded. Then, the contents of PCLATH and PCLATU are latched into PCH and PCU, respectively. The second cycle is executed as a NOP instruction while the new next instruction is fetched. Unlike CALL, there is no option to update W, Status or BSR.</p>				
Words:	1				
Cycles:	2				

Q Cycle Activity:

Q1	Q2	Q3	Q4
Decode	Read WREG	PUSH PC to stack	No operation
No operation	No operation	No operation	No operation

Example: HERE CALLW

Before Instruction

PC = address (HERE)
PCLATH = 10h
PCLATU = 00h
W = 06h

After Instruction

PC = 001006h
TOS = address (HERE + 2)
PCLATH = 10h
PCLATU = 00h
W = 06h

MOVSF Move Indexed to f

Syntax:	MOVSF [z _s], f _d			
Operands:	0 ≤ z _s ≤ 127 0 ≤ f _d ≤ 4095			
Operation:	((FSR2) + z _s) → f _d			
Status Affected:	None			
Encoding:				
1st word (source)	1110	1011	0zzz	zzzz _s
2nd word (destin.)	1111	ffff	ffff	ffff _d
Description:	<p>The contents of the source register are moved to destination register 'f_d'. The actual address of the source register is determined by adding the 7-bit literal offset 'z_s' in the first word to the value of FSR2. The address of the destination register is specified by the 12-bit literal 'f_d' in the second word. Both addresses can be anywhere in the 4096-byte data space (000h to FFFh).</p> <p>The MOVSF instruction cannot use the PCL, TOSU, TOSH or TOSL as the destination register.</p> <p>If the resultant source address points to an indirect addressing register, the value returned will be 00h.</p>			

Words: 2

Cycles: 2

Q Cycle Activity:

Q1	Q2	Q3	Q4
Decode	Determine source addr	Determine source addr	Read source reg
Decode	No operation No dummy read	No operation	Write register 'f' (dest)

Example: MOVSF [05h], REG2

Before Instruction

FSR2 = 80h
Contents of 85h = 33h
REG2 = 11h

After Instruction

FSR2 = 80h
Contents of 85h = 33h
REG2 = 33h

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MOVSS Move Indexed to Indexed

Syntax: MOVSS [z_s], [z_d]

Operands: 0 ≤ z_s ≤ 127
0 ≤ z_d ≤ 127

Operation: ((FSR2) + z_s) → ((FSR2) + z_d)

Status Affected: None

Encoding:

1110	1011	1zzz	zzzz _s
1111	xxxx	xzzz	zzzz _d

1st word (source)

2nd word (dest.)

Description The contents of the source register are moved to the destination register. The addresses of the source and destination registers are determined by adding the 7-bit literal offsets 'z_s' or 'z_d', respectively, to the value of FSR2. Both registers can be located anywhere in the 4096-byte data memory space (000h to FFFh). The MOVSS instruction cannot use the PCL, TOSU, TOSH or TOSL as the destination register. If the resultant source address points to an indirect addressing register, the value returned will be 00h. If the resultant destination address points to an indirect addressing register, the instruction will execute as a NOP.

Words: 2

Cycles: 2

Q Cycle Activity:

Q1	Q2	Q3	Q4
Decode	Determine source addr	Determine source addr	Read source reg
Decode	Determine dest addr	Determine dest addr	Write to dest reg

Example: MOVSS [05h], [06h]

Before Instruction

FSR2 = 80h

Contents of 85h = 33h

Contents of 86h = 11h

After Instruction

FSR2 = 80h

Contents of 85h = 33h

Contents of 86h = 33h

PUSHL Store Literal at FSR2, Decrement FSR2

Syntax: PUSHL k

Operands: 0 ≤ k ≤ 255

Operation: k → (FSR2),
FSR2 – 1 → FSR2

Status Affected: None

Encoding:

1111	1010	kkkk	kkkk
------	------	------	------

Description: The 8-bit literal 'k' is written to the data memory address specified by FSR2. FSR2 is decremented by 1 after the operation. This instruction allows users to push values onto a software stack.

Words: 1

Cycles: 1

Q Cycle Activity:

Q1	Q2	Q3	Q4
Decode	Read 'k'	Process data	Write to destination

Example: PUSHL 08h

Before Instruction

FSR2H:FSR2L = 01ECh

Memory (01ECh) = 00h

After Instruction

FSR2H:FSR2L = 01EBh

Memory (01ECh) = 08h

PIC18(L)F26/45/46K40

TABLE 37-4: I/O PORTS

Standard Operating Conditions (unless otherwise stated)							
Param No.	Sym.	Characteristic	Min.	Typ†	Max.	Units	Conditions
D300 D301 D302 D303 D304 D305	V _{IL}	Input Low Voltage					
		I/O PORT:					
		with TTL buffer	—	—	0.8	V	4.5V ≤ V _{DD} ≤ 5.5V
			—	—	0.15 V _{DD}	V	1.8V ≤ V _{DD} ≤ 4.5V
		with Schmitt Trigger buffer	—	—	0.2 V _{DD}	V	2.0V ≤ V _{DD} ≤ 5.5V
		with I ² C levels	—	—	0.3 V _{DD}	V	
		with SMBus levels	—	—	0.8	V	2.7V ≤ V _{DD} ≤ 5.5V
		MCLR	—	—	0.2 V _{DD}	V	
D320 D321 D322 D323 D324 D325	V _{IH}	Input High Voltage					
		I/O PORT:					
		with TTL buffer	2.0	—	—	V	4.5V ≤ V _{DD} ≤ 5.5V
			0.25 V _{DD} + 0.8	—	—	V	1.8V ≤ V _{DD} ≤ 4.5V
		with Schmitt Trigger buffer	0.8 V _{DD}	—	—	V	2.0V ≤ V _{DD} ≤ 5.5V
		with I ² C levels	0.7 V _{DD}	—	—	V	
		with SMBus levels	2.1	—	—	V	2.7V ≤ V _{DD} ≤ 5.5V
		MCLR	0.7 V _{DD}	—	—	V	
D340 D341 D342	I _{IL}	Input Leakage Current⁽¹⁾					
		I/O Ports	—	± 5	± 125	nA	V _{SS} ≤ V _{PIN} ≤ V _{DD} , Pin at high-impedance, 85°C
			—	± 5	± 1000	nA	V _{SS} ≤ V _{PIN} ≤ V _{DD} , Pin at high-impedance, 125°C
		MCLR ⁽²⁾	—	± 50	± 200	nA	V _{SS} ≤ V _{PIN} ≤ V _{DD} , Pin at high-impedance, 85°C
D350	I _{PUR}	Weak Pull-up Current					
			25	120	200	μA	V _{DD} = 3.0V, V _{PIN} = V _{SS}
D360	V _{OL}	Output Low Voltage					
		I/O ports	—	—	0.6	V	I _{OL} = 10.0mA, V _{DD} = 3.0V
D370	V _{OH}	Output High Voltage					
		I/O ports	V _{DD} - 0.7	—	—	V	I _{OH} = 6.0 mA, V _{DD} = 3.0V
D380	C _{IO}	All I/O pins	—	5	50	pF	

† Data in "Typ" column is at 3.0V, 25°C unless otherwise stated. These parameters are for design guidance only and are not tested.

Note 1: Negative current is defined as current sourced by the pin.

Note 2: The leakage current on the MCLR pin is strongly dependent on the applied voltage level. The specified levels represent normal operating conditions. Higher leakage current may be measured at different input voltages.