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Applications of "<u>Embedded - Microcontrollers</u>"

Details	
Product Status	Active
Core Processor	PIC
Core Size	8-Bit
Speed	32MHz
Connectivity	I ² C, SPI, UART/USART
Peripherals	Brown-out Detect/Reset, POR, PWM, WDT
Number of I/O	16
Program Memory Size	7KB (4K x 14)
Program Memory Type	FLASH
EEPROM Size	256 x 8
RAM Size	384 x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 3.6V
Data Converters	A/D 12x10b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Through Hole
Package / Case	18-DIP (0.300", 7.62mm)
Supplier Device Package	18-PDIP
Purchase URL	https://www.e-xfl.com/product-detail/microchip-technology/pic16lf1827-i-p

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TABLE 1-2: PIC16(L)F1826/27 PINOUT DESCRIPTION (CONTINUED)

Name	Function	Input Type	Output Type	Description
VDD	VDD	Power	_	Positive supply.
Vss	Vss	Power	_	Ground reference.

Legend: AN = Analog input or output CMOS = CMOS compatible input or output OD = Open Drain

 $TTL = TTL \ compatible \ input \ ST \ = \ Schmitt \ Trigger \ input \ with \ CMOS \ levels \ \ I^2C^{TM} = Schmitt \ Trigger \ input \ with \ I^2C$

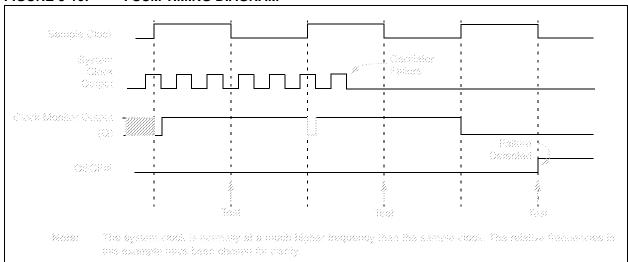
HV = High Voltage XTAL = Crystal levels

Note 1: Pin functions can be moved using the APFCON0 or APFCON1 register.

2: Functions are only available on the PIC16(L)F1827.

3: Default function location.

FIGURE 5-10: FSCM TIMING DIAGRAM



6.5 Reference Clock Control Register

REGISTER 6-1: CLKRCON: REFERENCE CLOCK CONTROL REGISTER

R/W-0/0	R/W-0/0	R/W-1/1	R/W-1/1	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
CLKREN	CLKROE	CLKRSLR	CLKRD	C<1:0>	(CLKRDIV<2:0>	•
bit 7							bit 0

Legend:R = Readable bitW = Writable bitU = Unimplemented bit, read as '0'u = Bit is unchangedx = Bit is unknown-n/n = Value at POR and BOR/Value at all other Resets'1' = Bit is set'0' = Bit is cleared

bit 7 **CLKREN:** Reference Clock Module Enable bit 1 = Reference Clock module is enabled 0 = Reference Clock module is disabled bit 6 CLKROE: Reference Clock Output Enable bit(3) 1 = Reference Clock output is enabled on CLKR pin 0 = Reference Clock output disabled on CLKR pin bit 5 CLKRSLR: Reference Clock Slew Rate Control limiting enable bit 1 = Slew Rate limiting is enabled 0 = Slew Rate limiting is disabled bit 4-3 CLKRDC<1:0>: Reference Clock Duty Cycle bits 11 = Clock outputs duty cycle of 75% 10 = Clock outputs duty cycle of 50% 01 = Clock outputs duty cycle of 25% 00 = Clock outputs duty cycle of 0% bit 2-0 CLKRDIV<2:0> Reference Clock Divider bits 111 = Base clock value divided by 128 110 = Base clock value divided by 64 101 = Base clock value divided by 32 100 = Base clock value divided by 16

011 = Base clock value divided by 8

010 = Base clock value divided by 4

001 = Base clock value divided by 2⁽¹⁾

000 = Base clock value⁽²⁾

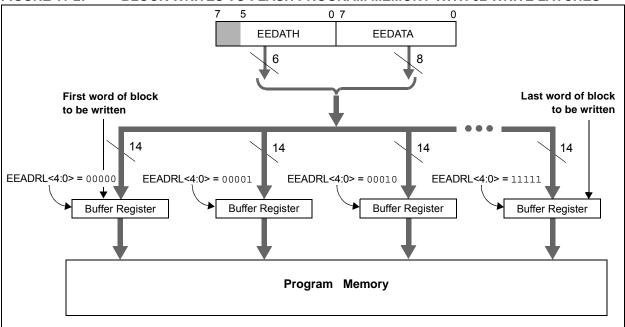
Note 1: In this mode, the 25% and 75% duty cycle accuracy will be dependent on the source clock duty cycle.

- 2: In this mode, the duty cycle will always be equal to the source clock duty cycle, unless a duty cycle of 0% is selected.
- 3: To route CLKR to pin, CLKOUTEN of Configuration Word 1 = 1 is required. CLKOUTEN of Configuration Word 1 = 0 will result in Fosc/4. See Section 6.3 "Conflicts with the CLKR Pin" for details.

NOTES:

After the "BSF EECON1, WR" instruction, the processor requires two cycles to set up the write operation. The user must place two NOP instructions after the WR bit is set. The processor will halt internal operations for the typical 2 ms, only during the cycle in which the write takes place (i.e., the last word of the block write). This is not Sleep mode as the clocks and peripherals will continue to run. The processor does not stall when LWLO = 1, loading the write latches. After the write cycle, the processor will resume operation with the third instruction after the EECON1 write instruction.

FIGURE 11-2: BLOCK WRITES TO FLASH PROGRAM MEMORY WITH 32 WRITE LATCHES



REGISTER 16-3: ADRESH: ADC RESULT REGISTER HIGH (ADRESH) ADFM = 0

| R/W-x/u |
|---------|---------|---------|---------|---------|---------|---------|---------|
| | | | ADRES | 6<9:2> | | | |
| bit 7 | | | | | | | bit 0 |

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'

u = Bit is unchanged x = Bit is unknown -n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set '0' = Bit is cleared

bit 7-0 ADRES<9:2>: ADC Result Register bits

Upper 8 bits of 10-bit conversion result

REGISTER 16-4: ADRESL: ADC RESULT REGISTER LOW (ADRESL) ADFM = 0

| R/W-x/u |
|---------|---------|---------|---------|---------|---------|---------|---------|
| ADRES | 6<1:0> | _ | _ | _ | _ | _ | _ |
| bit 7 | | | | | | | bit 0 |

Legend:R = Readable bitW = Writable bitU = Unimplemented bit, read as '0'u = Bit is unchangedx = Bit is unknown-n/n = Value at POR and BOR/Value at all other Resets'1' = Bit is set'0' = Bit is cleared

bit 7-6 ADRES<1:0>: ADC Result Register bits

Lower 2 bits of 10-bit conversion result

bit 5-0 **Reserved**: Do not use.

FIGURE 16-4: ANALOG INPUT MODEL

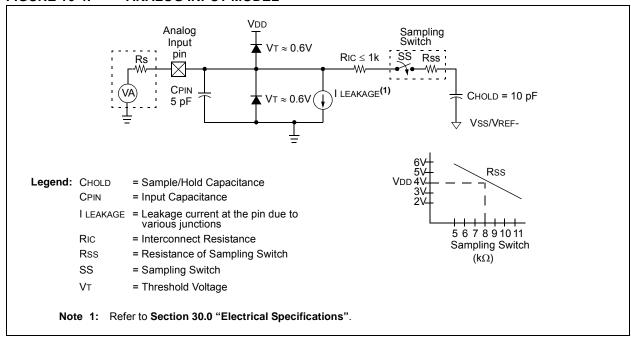
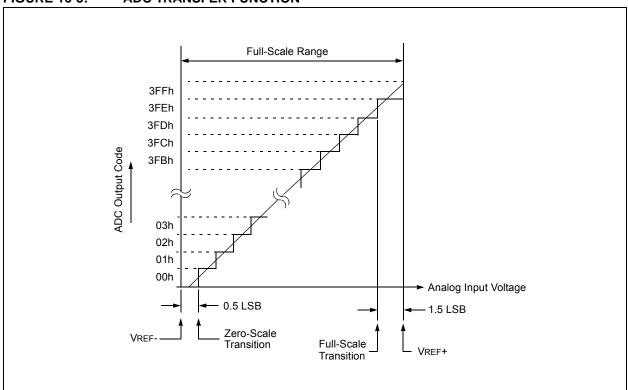


FIGURE 16-5: ADC TRANSFER FUNCTION



17.7 DAC Control Registers

REGISTER 17-1: DACCONO: VOLTAGE REFERENCE CONTROL REGISTER 0

R/W-0/0	R/W-0/0	R/W-0/0	U-0	R/W-0/0	R/W-0/0	U-0	R/W-0/0
DACEN	DACLPS	DACOE	_	DACPS	SS<1:0>	_	DACNSS
bit 7							bit 0

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'

u = Bit is unchanged x = Bit is unknown -n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set '0' = Bit is cleared

bit 7 DACEN: DAC Enable bit

1 = DAC is enabled0 = DAC is disabled

bit 6 DACLPS: DAC Low-Power Voltage State Select bit

1 = DAC Positive reference source selected0 = DAC Negative reference source selected

bit 5 DACOE: DAC Voltage Output Enable bit

1 = DAC voltage level is also an output on the DACOUT pin
 0 = DAC voltage level is disconnected from the DACOUT pin

0 - BAO voltage level is disconficeted from the BAO

bit 4 Unimplemented: Read as '0'

bit 3-2 DACPSS<1:0>: DAC Positive Source Select bits

00 = VDD 01 = VREF+ pin 10 = FVR Buffer2 output 11 = Reserved, do not use

bit 1 Unimplemented: Read as '0'

bit 0 DACNSS: DAC Negative Source Select bits

1 = VREF-0 = VSS

REGISTER 17-2: DACCON1: VOLTAGE REFERENCE CONTROL REGISTER 1

U-0	U-0	U-0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0	R/W-0/0
_	_	_			DACR<4:0>		
bit 7							bit 0

Legend:

R = Readable bit W = Writable bit U = Unimplemented bit, read as '0'

u = Bit is unchanged x = Bit is unknown -n/n = Value at POR and BOR/Value at all other Resets

'1' = Bit is set '0' = Bit is cleared

bit 7-5 **Unimplemented:** Read as '0'

bit 4-0 DACR<4:0>: DAC Voltage Output Select bits

TABLE 17-1: SUMMARY OF REGISTERS ASSOCIATED WITH THE DAC MODULE

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on page
FVRCON	FVREN	FVRRDY	Reserved	Reserved	CDAFVR1	CDAFVR0	ADFVR1	ADFVR0	138
DACCON0	DACEN	DACLPS	DACOE	_	DACPSS1	DACPSS0	_	DACNSS	156
DACCON1	_		_	DACR4	DACR3	DACR2	DACR1	DACR0	156

Legend: — = unimplemented, read as '0'. Shaded cells are unused with the DAC module.

21.7 Timer1 Interrupt

The Timer1 register pair (TMR1H:TMR1L) increments to FFFFh and rolls over to 0000h. When Timer1 rolls over, the Timer1 interrupt flag bit of the PIR1 register is set. To enable the interrupt on rollover, you must set these bits:

- · TMR1ON bit of the T1CON register
- · TMR1IE bit of the PIE1 register
- PEIE bit of the INTCON register
- · GIE bit of the INTCON register

The interrupt is cleared by clearing the TMR1IF bit in the Interrupt Service Routine.

Note: The TMR1H:TMR1L register pair and the TMR1IF bit should be cleared before enabling interrupts.

21.8 Timer1 Operation During Sleep

Timer1 can only operate during Sleep when setup in Asynchronous Counter mode. In this mode, an external crystal or clock source can be used to increment the counter. To set up the timer to wake the device:

- TMR1ON bit of the T1CON register must be set
- TMR1IE bit of the PIE1 register must be set
- · PEIE bit of the INTCON register must be set
- T1SYNC bit of the T1CON register must be set
- TMR1CS bits of the T1CON register must be configured
- T10SCEN bit of the T1CON register must be configured

The device will wake-up on an overflow and execute the next instructions. If the GIE bit of the INTCON register is set, the device will call the Interrupt Service Routine.

Timer1 oscillator will continue to operate in Sleep regardless of the $\overline{\text{T1SYNC}}$ bit setting.

21.9 ECCP/CCP Capture/Compare Time Base

The CCP modules use the TMR1H:TMR1L register pair as the time base when operating in Capture or Compare mode.

In Capture mode, the value in the TMR1H:TMR1L register pair is copied into the CCPR1H:CCPR1L register pair on a configured event.

In Compare mode, an event is triggered when the value CCPR1H:CCPR1L register pair matches the value in the TMR1H:TMR1L register pair. This event can be a Special Event Trigger.

For more information, see Section 24.0 "Capture/Compare/PWM Modules".

21.10 ECCP/CCP Special Event Trigger

When any of the CCP's are configured to trigger a special event, the trigger will clear the TMR1H:TMR1L register pair. This special event does not cause a Timer1 interrupt. The CCP module may still be configured to generate a CCP interrupt.

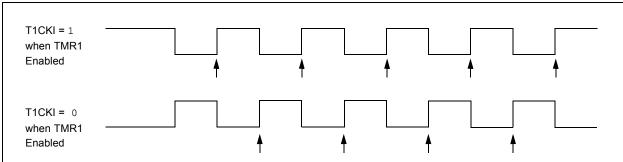
In this mode of operation, the CCPR1H:CCPR1L register pair becomes the period register for Timer1.

Timer1 should be synchronized and FOSC/4 should be selected as the clock source in order to utilize the Special Event Trigger. Asynchronous operation of Timer1 can cause a Special Event Trigger to be missed.

In the event that a write to TMR1H or TMR1L coincides with a Special Event Trigger from the CCP, the write will take precedence.

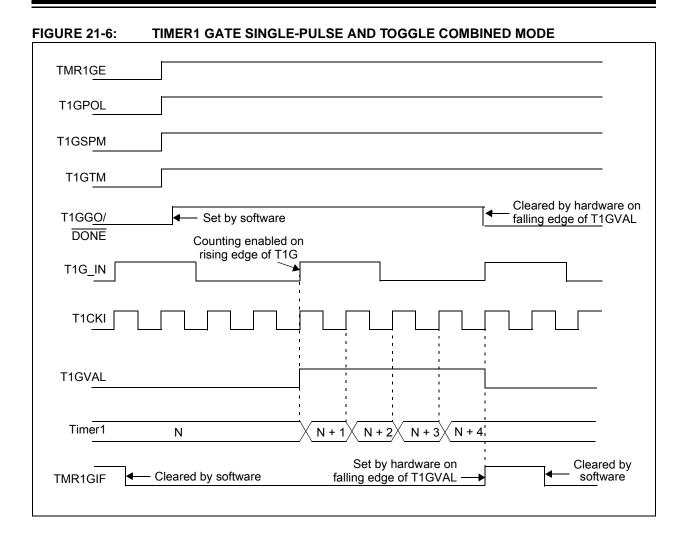
For more information, see **Section 16.2.5** "**Special Event Trigger**".

FIGURE 21-2: TIMER1 INCREMENTING EDGE



Note 1: Arrows indicate counter increments.

2: In Counter mode, a falling edge must be registered by the counter prior to the first incrementing rising edge of the clock.



NOTES:

23.1 DSM Operation

The DSM module can be enabled by setting the MDEN bit in the MDCON register. Clearing the MDEN bit in the MDCON register, disables the DSM module by automatically switching the carrier high and carrier low signals to the Vss signal source. The modulator signal source is also switched to the MDBIT in the MDCON register. This not only assures that the DSM module is inactive, but that it is also consuming the least amount of current

The values used to select the carrier high, carrier low, and modulator sources held by the Modulation Source, Modulation High Carrier, and Modulation Low Carrier control registers are not affected when the MDEN bit is cleared and the DSM module is disabled. The values inside these registers remain unchanged while the DSM is inactive. The sources for the carrier high, carrier low and modulator signals will once again be selected when the MDEN bit is set and the DSM module is again enabled and active.

The modulated output signal can be disabled without shutting down the DSM module. The DSM module will remain active and continue to mix signals, but the output value will not be sent to the MDOUT pin. During the time that the output is disabled, the MDOUT pin will remain low. The modulated output can be disabled by clearing the MDOE bit in the MDCON register.

23.2 Modulator Signal Sources

The modulator signal can be supplied from the following sources:

- CCP1 Signal
- · CCP2 Signal
- · CCP3 Signal
- CCP4 Signal
- MSSP1 SDO1 Signal (SPI Mode Only)
- MSSP2 SDO2 Signal (SPI Mode Only)
- Comparator C1 Signal
- · Comparator C2 Signal
- EUSART TX Signal
- · External Signal on MDMIN1 pin
- MDBIT bit in the MDCON register

The modulator signal is selected by configuring the MDMS <3:0> bits in the MDSRC register.

23.3 Carrier Signal Sources

The carrier high signal and carrier low signal can be supplied from the following sources:

- · CCP1 Signal
- · CCP2 Signal
- · CCP3 Signal
- · CCP4 Signal
- · Reference Clock Module Signal
- External Signal on MDCIN1 pin
- · External Signal on MDCIN2 pin
- Vs

The carrier high signal is selected by configuring the MDCH <3:0> bits in the MDCARH register. The carrier low signal is selected by configuring the MDCL <3:0> bits in the MDCARL register.

23.4 Carrier Synchronization

During the time when the DSM switches between carrier high and carrier low signal sources, the carrier data in the modulated output signal can become truncated. To prevent this, the carrier signal can be synchronized to the modulator signal. When synchronization is enabled, the carrier pulse that is being mixed at the time of the transition is allowed to transition low before the DSM switches over to the next carrier source.

Synchronization is enabled separately for the carrier high and carrier low signal sources. Synchronization for the carrier high signal can be enabled by setting the MDCHSYNC bit in the MDCARH register. Synchronization for the carrier low signal can be enabled by setting the MDCLSYNC bit in the MDCARL register.

Figure 23-1 through Figure 23-5 show timing diagrams of using various synchronization methods.

TABLE 24-10: SUMMARY OF REGISTERS ASSOCIATED WITH ENHANCED PWM

Name	Bit 7	Bit 6	Bit 5	Bit 4	Bit 3	Bit 2	Bit 1	Bit 0	Register on Page
APFCON0	RXDTSEL	SDO1SEL	SS1SEL	P2BSEL ⁽²⁾	CCP2SEL ⁽²⁾	P1DSEL	P1CSEL	CCP1SEL	119
CCPxCON	PxM<	1:0> ⁽¹⁾	DCxB	<1:0>		CCPxI	M<3:0>		226
CCPxAS	CCPxASE	(CCPxAS<2:0	>	PSSxA	C<1:0>	PSSxB	D<1:0>	228
CCPTMRS	C4TSE	L<1:0>	C3TSE	L<1:0>	C2TSE	L<1:0>	C1TSE	L<1:0>	227
INTCON	GIE	PEIE	TMR0IE	INTE	IOCIE	TMR0IF	INTF	IOCIF	86
PIE1	TMR1GIE	ADIE	RCIE	TXIE	SSPIE	CCP1IE	TMR2IE	TMR1IE	87
PIE2	OSFIE	C2IE	C1IE	EEIE	BCLIE	_	_	CCP2IE	88
PIE3 ⁽²⁾	_	_	CCP4IE	CCP3IE	TMR6IE	_	TMR4IE	_	89
PIR1	TMR1GIF	ADIF	RCIF	TXIF	SSPIF	CCP1IF	TMR2IF	TMR1IF	91
PIR2	OSFIF	C2IF	C1IF	EEIF	BCLIF	_	_	CCP2IF	92
PIR3 ⁽²⁾	_	_	CCP4IF	CCP3IF	TMR6IF	_	TMR4IF	_	93
PR2	Timer2 Perio	d Register							189*
PR4	Timer4 Modu	ıle Period Re	gister						189*
PR6	Timer6 Modu	ıle Period Re	gister						189*
PSTRxCON	_	_	_	STRxSYNC	STRxD	STRxC	STRxB	STRxA	230
PWMxCON	PxRSEN			•	PxDC<6:0>		•	•	229
T2CON	_	T2OUTPS3	T2OUTPS2	T2OUTPS1	T2OUTPS0	TMR2ON	T2CKPS1	T2CKPS0	191
T4CON	_	T4OUTPS3	T4OUTPS2	T4OUTPS1	T4OUTPS0	TMR40N	T4CKPS1	T4CKPS0	191
T6CON	_	T6OUTPS3	T6OUTPS2	T6OUTPS1	T6OUTPS0	TMR6ON	T6CKPS1	T6CKPS0	191
TMR2	Holding Reg	ister for the 8	-bit TMR2 Tin	ne Base					189*
TMR4	Holding Reg	Holding Register for the 8-bit TMR4 Time Base ⁽¹⁾						189*	
TMR6	Holding Reg	ister for the 8	-bit TMR6 Tin	ne Base ⁽¹⁾					189*
TRISA	TRISA7	TRISA6	TRISA5	TRISA4	TRISA3	TRISA2	TRISA1	TRISA0	122
TRISB	TRISB7	TRISB6	TRISB5	TRISB4	TRISB3	TRISB2	TRISB1	TRISB0	127

Legend: — = Unimplemented location, read as '0'. Shaded cells are not used by the PWM.

Note 1: Applies to ECCP modules only.

2: PIC16(L)F1827 only.

^{*} Page provides register information.

26.3.1 AUTO-BAUD DETECT

The EUSART module supports automatic detection and calibration of the baud rate.

In the Auto-Baud Detect (ABD) mode, the clock to the BRG is reversed. Rather than the BRG clocking the incoming RX signal, the RX signal is timing the BRG. The Baud Rate Generator is used to time the period of a received 55h (ASCII "U") which is the Sync character for the LIN bus. The unique feature of this character is that it has five rising edges including the Stop bit edge.

Setting the ABDEN bit of the BAUDCON register starts the auto-baud calibration sequence (Figure 26-6). While the ABD sequence takes place, the EUSART state machine is held in Idle. On the first rising edge of the receive line, after the Start bit, the SPBRG begins counting up using the BRG counter clock as shown in Table 26-6. The fifth rising edge will occur on the RX pin at the end of the eighth bit period. At that time, an accumulated value totaling the proper BRG period is left in the SPBRGH, SPBRGL register pair, the ABDEN bit is automatically cleared and the RCIF interrupt flag is set. The value in the RCREG needs to be read to clear the RCIF interrupt. RCREG content should be discarded. When calibrating for modes that do not use the SPBRGH register the user can verify that the SPBRGL register did not overflow by checking for 00h in the SPBRGH register.

The BRG auto-baud clock is determined by the BRG16 and BRGH bits as shown in Table 26-6. During ABD, both the SPBRGH and SPBRGL registers are used as a 16-bit counter, independent of the BRG16 bit setting. While calibrating the baud rate period, the SPBRGH

and SPBRGL registers are clocked at 1/8th the BRG base clock rate. The resulting byte measurement is the average bit time when clocked at full speed.

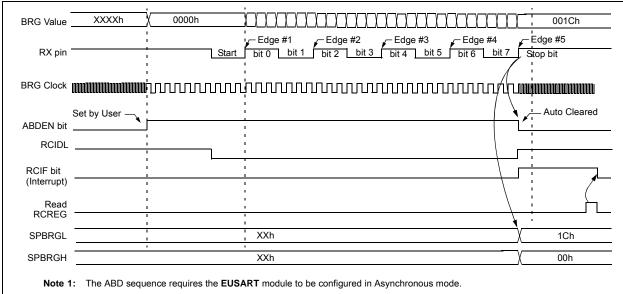
- Note 1: If the WUE bit is set with the ABDEN bit, auto-baud detection will occur on the byte following the Break character (see Section 26.3.3 "Auto-Wake-up on Break").
 - 2: It is up to the user to determine that the incoming character baud rate is within the range of the selected BRG clock source. Some combinations of oscillator frequency and EUSART baud rates are not possible.
 - 3: During the auto-baud process, the auto-baud counter starts counting at 1. Upon completion of the auto-baud sequence, to achieve maximum accuracy, subtract 1 from the SPBRGH:SPBRGL register pair.

TABLE 26-6: BRG COUNTER CLOCK RATES

BRG16	BRGH	BRG Base Clock	BRG ABD Clock
0	0	Fosc/64	Fosc/512
0	1	Fosc/16	Fosc/128
1	0	Fosc/16	Fosc/128
1	1	Fosc/4	Fosc/32

Note: During the ABD sequence, SPBRGL and SPBRGH registers are both used as a 16-bit counter, independent of BRG16 setting.

FIGURE 26-6: AUTOMATIC BAUD RATE CALIBRATION



NOTES:

28.2 Low-Voltage Programming Entry Mode

The Low-Voltage Programming Entry mode allows the PIC16(L)F1826/27 devices to be programmed using VDD only, without high voltage. When the LVP bit of Configuration Word 2 is set to '1', the low-voltage ICSP programming entry is enabled. To disable the Low-Voltage ICSP mode, the LVP bit must be programmed to '0'.

Entry into the Low-Voltage Programming Entry mode requires the following steps:

- 1. MCLR is brought to VIL.
- A 32-bit key sequence is presented on ICSPDAT, while clocking ICSPCLK.

Once the key sequence is complete, $\overline{\text{MCLR}}$ must be held at VIL for as long as Program/Verify mode is to be maintained.

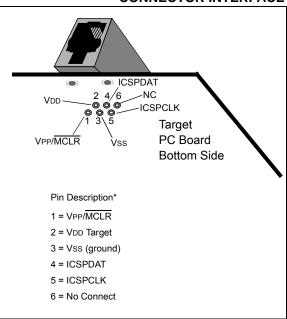
If low-voltage programming is enabled (LVP = 1), the $\overline{\text{MCLR}}$ Reset function is automatically enabled and cannot be disabled. See **Section 7.3 "MCLR"** for more information.

The LVP bit can only be reprogrammed to '0' by using the High-Voltage Programming mode.

28.3 Common Programming Interfaces

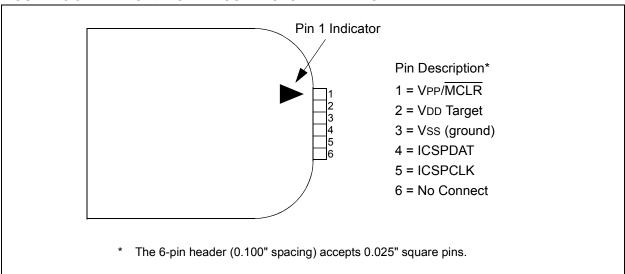
Connection to a target device is typically done through an ICSP™ header. A commonly found connector on development tools is the RJ-11 in the 6P6C (6 pin, 6 connector) configuration. See Figure 28-2.

FIGURE 28-2: ICD RJ-11 STYLE CONNECTOR INTERFACE



Another connector often found in use with the PICkit™ programmers is a standard 6-pin header with 0.1 inch spacing. Refer to Figure 28-3.

FIGURE 28-3: PICkit™ STYLE CONNECTOR INTERFACE



CALL	Call Subroutine
Syntax:	[label] CALL k
Operands:	$0 \leq k \leq 2047$
Operation:	(PC)+ 1→ TOS, k → PC<10:0>, (PCLATH<6:3>) → PC<14:11>
Status Affected:	None
Description:	Call Subroutine. First, return address (PC + 1) is pushed onto the stack. The eleven-bit immediate address is loaded into PC bits <10:0>. The upper bits of the PC are loaded from PCLATH. CALL is a two-cycle instruction.

CLRWDT	Clear Watchdog Timer
Syntax:	[label] CLRWDT
Operands:	None
Operation:	$\begin{array}{l} \text{O0h} \rightarrow \text{WDT} \\ \text{0} \rightarrow \underline{\text{WDT}} \text{ prescaler,} \\ \text{1} \rightarrow \overline{\text{TO}} \\ \text{1} \rightarrow \overline{\text{PD}} \end{array}$
Status Affected:	TO, PD
Description:	CLRWDT instruction resets the Watchdog Timer. It also resets the prescaler of the WDT. Status bits $\overline{\text{TO}}$ and $\overline{\text{PD}}$ are set.

CALLW	Subroutine Call With W	
Syntax:	[label] CALLW	
Operands:	None	
Operation:	$(PC) +1 \rightarrow TOS,$ $(W) \rightarrow PC <7:0>,$ $(PCLATH <6:0>) \rightarrow PC <14:8>$	
Status Affected:	None	
Description:	Subroutine call with W. First, the return address (PC + 1) is pushed onto the return stack. Then, the contents of W is loaded into PC<7:0>, and the contents of PCI ATH into	

PC<14:8>. CALLW is a two-cycle

COMF	Complement f	
Syntax:	[label] COMF f,d	
Operands:	$0 \le f \le 127$ $d \in [0,1]$	
Operation:	$(\overline{f}) \rightarrow (destination)$	
Status Affected:	Z	
Description:	The contents of register 'f' are complemented. If 'd' is '0', the result is stored in W. If 'd' is '1', the result is stored back in register 'f'.	

CLRF	Clear f		
Syntax:	[label] CLRF f		
Operands:	$0 \leq f \leq 127$		
Operation:	$00h \to (f)$ $1 \to Z$		
Status Affected:	Z		
Description:	The contents of register 'f' are cleared and the Z bit is set.		

instruction.

DECF	Decrement f
Syntax:	[label] DECF f,d
Operands:	$0 \le f \le 127$ $d \in [0,1]$
Operation:	(f) - 1 \rightarrow (destination)
Status Affected:	Z
Description:	Decrement register 'f'. If 'd' is '0', the result is stored in the W register. If 'd' is '1', the result is stored back in register 'f'.

CLRW	Clear W
Syntax:	[label] CLRW
Operands:	None
Operation:	$00h \to (W)$ $1 \to Z$
Status Affected:	Z
Description:	W register is cleared. Zero bit (Z) is set

RRF Rotate Right f through Carry

Syntax: [label] RRF f,d

Operands: $0 \le f \le 127$

 $d \in [0,1]$

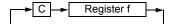
Operation: See description below

Status Affected: C

Description: The contents of register 'f' are rotated

one bit to the right through the Carry flag. If 'd' is '0', the result is placed in the W register. If 'd' is '1', the result is

placed back in register 'f'.



SUBLW Subtract W from literal

Syntax: [label] SUBLW k

Operands: $0 \le k \le 255$ Operation: $k - (W) \rightarrow (W)$ Status Affected: C, DC, Z

Description: The W register is subtracted (2's com-

plement method) from the eight-bit literal 'k'. The result is placed in the W

register.

C = 0	W > k
C = 1	$W \leq k $
DC = 0	W<3:0> > k<3:0>
DC = 1	W<3:0> ≤ k<3:0>

SLEEP Enter Sleep mode

Syntax: [label] SLEEP

Operands: None

Operation: $00h \rightarrow WDT$,

 $0 \rightarrow WDT$ prescaler,

 $\begin{array}{c}
1 \to \overline{\mathsf{TO}}, \\
0 \to \overline{\mathsf{PD}}
\end{array}$

Status Affected: TO, PD

Description: The power-down Status bit, \overline{PD} is

cleared. Time-out Status bit, $\overline{\text{TO}}$ is set. Watchdog Timer and its pres-

caler are cleared.

The processor is put into Sleep mode

with the oscillator stopped.

SUBWF Subtract W from f

Syntax: [label] SUBWF f,d

Operands: $0 \le f \le 127$

 $d \in [0,1]$

Operation: (f) - (W) \rightarrow (destination)

Status Affected: C, DC, Z

Description: Subtract (2's complement method) W

register from register 'f'. If 'd' is '0', the

result is stored in the W

register. If 'd' is '1', the result is stored

back in register 'f.

C = 0	W > f
C = 1	$W \leq f$
DC = 0	W<3:0> > f<3:0>
DC = 1	W<3:0> ≤ f<3:0>

SUBWFB Subtract W from f with Borrow

Syntax: SUBWFB f {,d}

Operands: $0 \le f \le 127$

 $d \in [0,1]$

Operation: $(f) - (W) - (\overline{B}) \rightarrow dest$

Status Affected: C, DC, Z

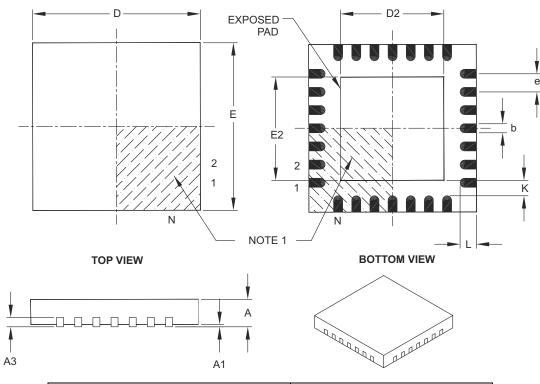
Description: Subtract W and the BORROW flag

(CARRY) from register 'f' (2's complement method). If 'd' is '0', the result is stored in W. If 'd' is '1', the result is

stored back in register 'f'.

28-Lead Plastic Quad Flat, No Lead Package (ML) – 6x6 mm Body [QFN] with 0.55 mm Contact Length

Note: For the most current package drawings, please see the Microchip Packaging Specification located at http://www.microchip.com/packaging



	Units	MILLIMETERS			
	Dimension Limits		NOM	MAX	
Number of Pins	N	28			
Pitch	е		0.65 BSC		
Overall Height	Α	0.80	0.90	1.00	
Standoff	A1	0.00	0.02	0.05	
Contact Thickness	A3	0.20 REF			
Overall Width	E	6.00 BSC			
Exposed Pad Width	E2	3.65	3.70	4.20	
Overall Length	D	6.00 BSC			
Exposed Pad Length	D2	3.65	3.70	4.20	
Contact Width	b	0.23	0.30	0.35	
Contact Length	L.	0.50	0.55	0.70	
Contact-to-Exposed Pad	K	0.20	_	_	

Notes:

- 1. Pin 1 visual index feature may vary, but must be located within the hatched area.
- 2. Package is saw singulated.
- 3. Dimensioning and tolerancing per ASME Y14.5M.

BSC: Basic Dimension. Theoretically exact value shown without tolerances.

REF: Reference Dimension, usually without tolerance, for information purposes only.

Microchip Technology Drawing C04-105B