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What is "[Embedded - Microcontrollers](#)"?

"[Embedded - Microcontrollers](#)" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "[Embedded - Microcontrollers](#)"

Details

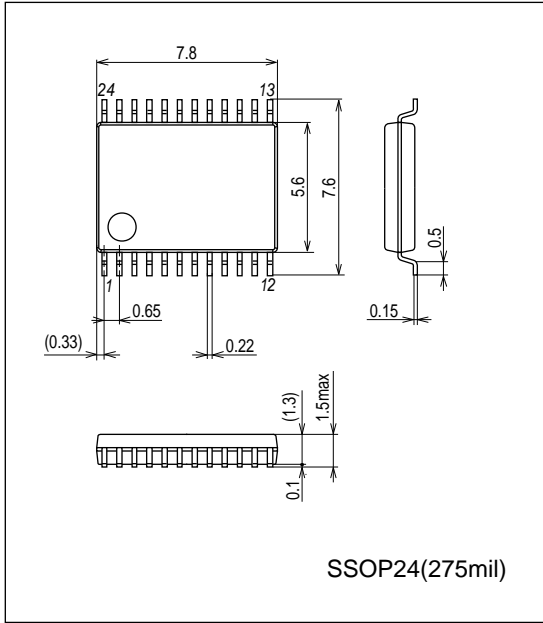
Product Status	Active
Core Processor	-
Core Size	8-Bit
Speed	12MHz
Connectivity	SIO, UART/USART
Peripherals	LVD, POR, PWM, WDT
Number of I/O	20
Program Memory Size	8KB (8K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	256 x 8
Voltage - Supply (Vcc/Vdd)	1.8V ~ 5.5V
Data Converters	A/D 9x12b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 85°C (TA)
Mounting Type	Surface Mount
Package / Case	24-WFQFN
Supplier Device Package	24-VCT (3x3)
Purchase URL	https://www.e-xfl.com/product-detail/onsemi/lc87fbg08aure-te-l-h

Package Dimensions

unit : mm (typ)

3175C

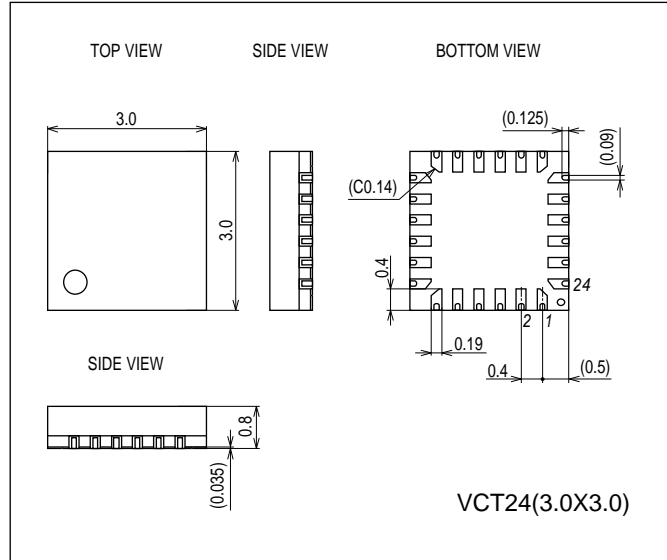
(build-to-order)



Package Dimensions

unit : mm (typ)

3366



■ Minimum Bus Cycle

- 83.3ns (12MHz at $V_{DD}=2.7V$ to 5.5V, $T_a=-40^{\circ}C$ to $+85^{\circ}C$)
- 100ns (10MHz at $V_{DD}=2.2V$ to 5.5V, $T_a=-40^{\circ}C$ to $+85^{\circ}C$)
- 250ns (4MHz at $V_{DD}=1.8V$ to 5.5V, $T_a=-40^{\circ}C$ to $+85^{\circ}C$)

Note: The bus cycle time here refers to the ROM read speed.

■ Minimum Instruction Cycle Time

- 250ns (12MHz at $V_{DD}=2.7V$ to 5.5V, $T_a=-40^{\circ}C$ to $+85^{\circ}C$)
- 300ns (10MHz at $V_{DD}=2.2V$ to 5.5V, $T_a=-40^{\circ}C$ to $+85^{\circ}C$)
- 750ns (4MHz at $V_{DD}=1.8V$ to 5.5V, $T_a=-40^{\circ}C$ to $+85^{\circ}C$)

■ Ports

- Normal withstand voltage I/O ports
 - Ports I/O direction can be designated in 1-bit units 12 (P1n, P20, P21, P70, CF2/XT2)
 - Ports I/O direction can be designated in 4-bit units 8 (P0n)
- Dedicated oscillator ports/input ports 1 (CF1/XT1)
- Reset pin 1 (\overline{RES})
- Power pins 2 (V_{SS1} , V_{DD1})

■ Timers

- Timer 0: 16-bit timer/counter with a capture register.
 - Mode 0: 8-bit timer with an 8-bit programmable prescaler (with an 8-bit capture register) \times 2 channels
 - Mode 1: 8-bit timer with an 8-bit programmable prescaler (with an 8-bit capture register) + 8-bit counter (with an 8-bit capture register)
 - Mode 2: 16-bit timer with an 8-bit programmable prescaler (with a 16-bit capture register)
 - Mode 3: 16-bit counter (with a 16-bit capture register)
- Timer 1: 16-bit timer/counter that supports PWM/toggle outputs
 - Mode 0: 8-bit timer with an 8-bit prescaler (with toggle outputs) + 8-bit timer/counter with an 8-bit prescaler (with toggle outputs)
 - Mode 1: 8-bit PWM with an 8-bit prescaler \times 2 channels
 - Mode 2: 16-bit timer/counter with an 8-bit prescaler (with toggle outputs) (toggle outputs also possible from the lower-order 8 bits)
 - Mode 3: 16-bit timer with an 8-bit prescaler (with toggle outputs) (The lower-order 8 bits can be used as PWM)

■Interrupts

- 19 sources, 10 vector addresses
 - 1) Provides three levels (low (L), high (H), and highest (X)) of multiplex interrupt control. Any interrupt requests of the level equal to or lower than the current interrupt are not accepted.
 - 2) When interrupt requests to two or more vector addresses occur at the same time, the interrupt of the highest level takes precedence over the other interrupts. For interrupts of the same level, the interrupt into the smallest vector address takes precedence.

No.	Vector Address	Level	Interrupt Source
1	00003H	X or L	INT0
2	0000BH	X or L	INT1
3	00013H	H or L	INT2/T0L/INT4
4	0001BH	H or L	INT3/base timer
5	00023H	H or L	T0H
6	0002BH	H or L	T1L/T1H
7	00033H	H or L	SIO0/UART1 receive
8	0003BH	H or L	SIO1/UART1 transmit
9	00043H	H or L	ADC/T6/T7/ PWM4, PWM5
10	0004BH	H or L	Port 0

- Priority levels $X > H > L$
- Of interrupts of the same level, the one with the smallest vector address takes precedence.

■Subroutine Stack Levels: 128levels (The stack is allocated in RAM.)

■High-speed Multiplication/Division Instructions

- 16 bits \times 8 bits (5 tCYC execution time)
- 24 bits \times 16 bits (12 tCYC execution time)
- 16 bits \div 8 bits (8 tCYC execution time)
- 24 bits \div 16 bits (12 tCYC execution time)

■Oscillation Circuits

- Internal oscillation circuits
 - Low-speed RC oscillation circuit (SRC): For system clock / For Watchdog timer (100kHz)
 - Medium-speed RC oscillation circuit (RC): For system clock (1MHz)
 - Frequency variable RC oscillation circuit (MRC): For system clock (8MHz \pm 1.5%, Ta=-10°C to +85°C)
- External oscillation circuits
 - Hi-speed CF oscillation circuit (CF): For system clock, with internal Rf
 - Low speed crystal oscillation circuit (X'tal): For low-speed system clock / For Watchdog timer, with internal Rf
 - 1) The CF and crystal oscillation circuits share the same pins. The active circuit is selected under program control.
 - 2) Both the CF and crystal oscillator circuits stop operation on a system reset. After reset is released, oscillation is stopped so start the oscillation operation by program.

■System Clock Divider Function

- Can run on low current.
- The minimum instruction cycle selectable from 300ns, 600ns, 1.2 μ s, 2.4 μ s, 4.8 μ s, 9.6 μ s, 19.2 μ s, 38.4 μ s, and 76.8 μ s (at a main clock rate of 10MHz).

■Internal Reset Function

- Power-on reset (POR) function
 - 1) POR reset is generated only at power-on time.
 - 2) The POR release level can be selected from 8 levels (1.67V, 1.97V, 2.07V, 2.37V, 2.57V, 2.87V, 3.86V, and 4.35V) through option configuration.
- Low-voltage detection reset (LVD) function
 - 1) LVD and POR functions are combined to generate resets when power is turned on and when power voltage falls below a certain level.
 - 2) The use or disuse of the LVD function and the low voltage threshold level (7 levels: 1.91V, 2.01V, 2.31V, 2.51V, 2.81V, 3.79V, 4.28V) can be selected by optional configuration.

■ Standby Function

- **HALT mode:** Halts instruction execution while allowing the peripheral circuits to continue operation.
 - 1) Oscillation is not halted automatically.
 - 2) There are four ways of resetting the HALT mode.
 - (1) Setting the reset pin to the low level
 - (2) System resetting by low-voltage detection
 - (3) System resetting by watchdog timer
 - (4) Occurrence of an interrupt
- **HOLD mode:** Suspends instruction execution and the operation of the peripheral circuits.
 - 1) The CF, low-/medium-/ Frequency variable RC, and crystal oscillators automatically stop operation.

Note: The oscillation of the low-speed RC oscillator is also controlled directly by the watchdog timer and its standby-mode-time oscillation is also controlled.
 - 2) There are five ways of resetting the HOLD mode.
 - (1) Setting the reset pin to the lower level.
 - (2) System resetting by low-voltage detection
 - (3) System resetting by watchdog timer
 - (4) Having an interrupt source established at either INT0, INT1, INT2, INT4
 - * INT0 and INT1 HOLD mode reset is available only when level detection is set.
 - (5) Having an interrupt source established at port 0.
- **X'tal HOLD mode:** Suspends instruction execution and the operation of the peripheral circuits except the base timer.
 - 1) The CF, low-/medium-/ Frequency variable RC oscillators automatically stop operation.

Note: The oscillation of the low-speed RC oscillator is also controlled directly by the watchdog timer and its standby-mode-time oscillation is also controlled.
 - 2) The state of crystal oscillation established when the X'tal HOLD mode is entered is retained.
 - 3) There are six ways of resetting the X'tal HOLD mode.
 - (1) Setting the reset pin to the low level.
 - (2) System resetting by watchdog timer or low-voltage detection.
 - (3) System resetting by watchdog timer or low-voltage detection.
 - (4) Having an interrupt source established at either INT0, INT1, INT2, INT4
 - * INT0 and INT1 HOLD mode reset is available only when level detection is set.
 - (5) Having an interrupt source established at port 0.
 - (6) Having an interrupt source established in the base timer circuit.

Note: Available only when X'tal oscillation is selected.

■ Onchip Debugger (flash versions only)

- Supports software debugging with the microcontroller mounted on the target board.
- Software break setting
- Stepwise execution of instructions
- Real time RAM data monitoring function

All the RAM data map contents can be monitored and rewritten on the screen when the program is running.
(Part of the SFR data cannot be rewritten.)
- Two channels of on-chip debugger pins are available to be compatible with small pin count devices.

DBGP0 (P0), DBGP1 (P1)

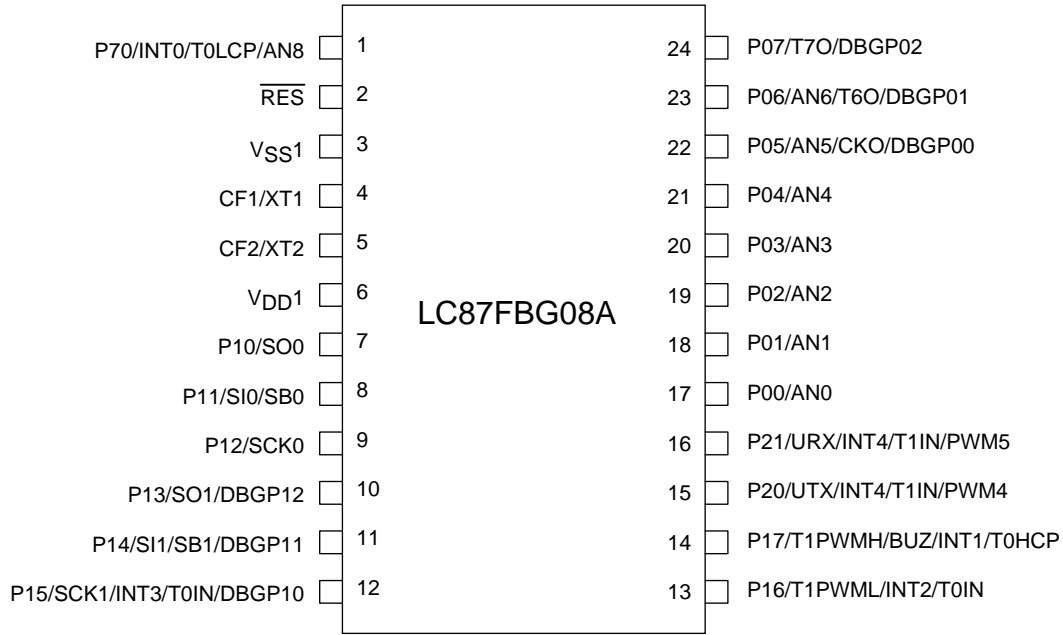
■ Data Security Function (flash versions only)

- Protects the program data stored in flash memory from unauthorized read or copy.

Note: This data security function does not necessarily provide absolute data security.

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Pin Assignment



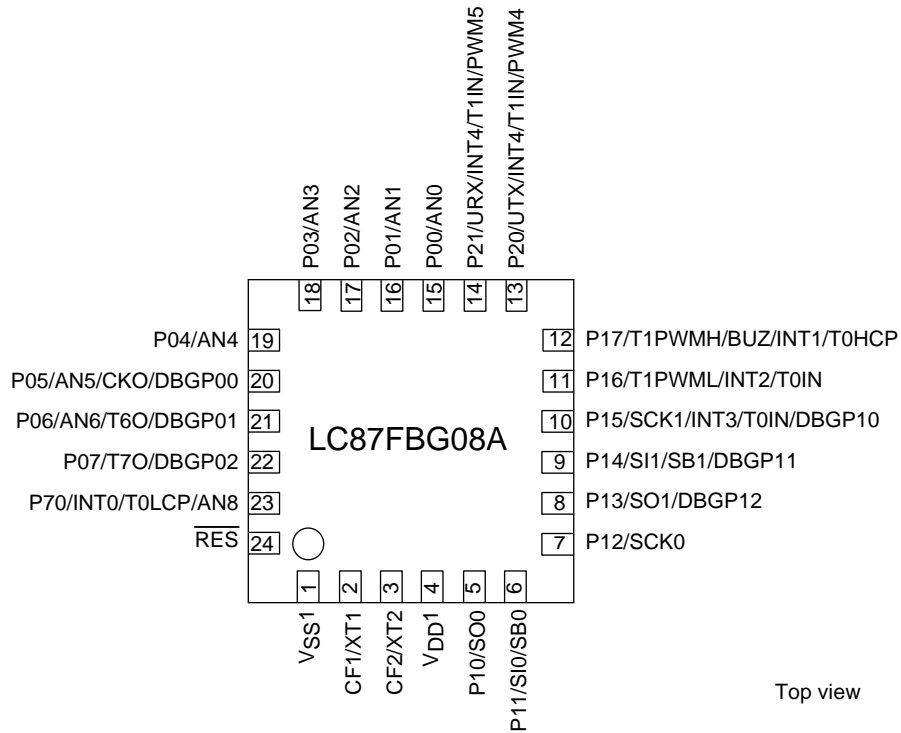
Top view

SSOP24(225mil) “Lead-/Halogen-free Type”
SSOP24(275mil) “Lead-/Halogen-free Type”

SSOP24	NAME
1	P70/INT0/T0LCP/AN8
2	RES
3	VSS1
4	CF1/XT1
5	CF2/XT2
6	VDD1
7	P10/SO0
8	P11/SI0/SB0
9	P12/SCK0
10	P13/SO1/DBGP12
11	P14/SI1/SB1/DBGP11
12	P15/SCK1/INT3/T0IN/DBGP10

SSOP24	NAME
13	P16/T1PWML/INT2/T0IN
14	P17/T1PWMH/BUZ/INT1/T0HCP
15	P20/UTX/INT4/T1IN/PWM4
16	P21/URX/INT4/T1IN/PWM5
17	P00/AN0
18	P01/AN1
19	P02/AN2
20	P03/AN3
21	P04/AN4
22	P05/AN5/CKO/DBGP00
23	P06/AN6/T6O/DBGP01
24	P07/T7O/DBGP02

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VCT24(3×3) “Lead-/Halogen-free Type”

VCT24	NAME
1	VSS1
2	CF1/XT1
3	CF2/XT2
4	VDD1
5	P10/SO0
6	P11/SI0/SB0
7	P12/SCK0
8	P13/SO1/DBGP12
9	P14/SI1/SB1/DBGP11
10	P15/SCK1/INT3/T0IN/DBGP10
11	P16/T1PWML/INT2/T0IN
12	P17/T1PWMH/BUZ/INT1/T0HCP

VCT24	NAME
13	P20/UTX/INT4/T1IN/PWM4
14	P21/URX/INT4/T1IN/PWM5
15	P00/AN0
16	P01/AN1
17	P02/AN2
18	P03/AN3
19	P04/AN4
20	P05/AN5/CKO/DBGP00
21	P06/AN6/T6O/DBGP01
22	P07/T7O/DBGP02
23	P70/INT0/T0LCP/AN8
24	RES

Recommended Unused Pin Connections

Port Name	Recommended Unused Pin Connections	
	Board	Software
P00 to P07	Open	Output low
P10 to P17	Open	Output low
P20 to P21	Open	Output low
P70	Open	Output low
CF1/XT1	Pulled low with a 100kΩ resistor or less	General-purpose input port
CF2/XT2	Pulled low with a 100kΩ resistor or less	General-purpose input port

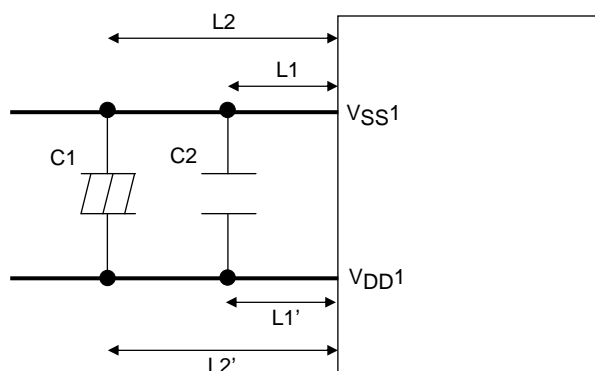
On-chip Debugger Pin Connection Requirements

For the treatment of the on-chip debugger pins, refer to the separately available documents entitled "RD87 on-chip debugger installation manual".

Power Pin Treatment Recommendations (VDD1, VSS1)

Connect bypass capacitors that meet the following conditions between the VDD1 and VSS1 pins:

- Connect among the VDD1 and VSS1 pins and bypass capacitors C1 and C2 with the shortest possible heavy lead wires, making sure that the impedances between the both pins and the bypass capacitors are as possible ($L1=L1'$, $L2=L2'$).
- Connect a large-capacity capacitor C1 and a small-capacity capacitor C2 in parallel.
The capacitance of C2 should approximately 0.1μF.



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Absolute Maximum Ratings at Ta = 25°C, VSS1 = 0V

Parameter	Symbol	Pin/Remarks	Conditions	Specification				
				V _{DD} [V]	min	typ	max	unit
Maximum supply voltage	V _{DD} max	V _{DD} 1			-0.3		+6.5	V
Input voltage	V _I	CF1			-0.3		V _{DD} +0.3	
Input/output voltage	V _{IO}	Ports 0, 1, 2, P70, CF2, $\overline{\text{RES}}$			-0.3		V _{DD} +0.3	
High level output current	Peak output current	IOPH	Ports 0, 1, 2	CMOS output select Per 1 applicable pin		-10		
	Mean output current (Note 1-1)	IOMH	Ports 0, 1, 2	CMOS output select Per 1 applicable pin		-7.5		
	Total output current	ΣIOAH(1)	Ports 0, 1, 2	Total of all applicable pins		-25		
Low level output current	Peak output current	IOPL(1)	P02 to P07 Ports 1, 2	Per 1 applicable pin			20	mA
		IOPL(2)	P00, P01	Per 1 applicable pin			30	
		IOPL(3)	P70, CF2	Per 1 applicable pin			10	
	Mean output current (Note 1-1)	IOML(1)	P02 to P07 Ports 1, 2	Per 1 applicable pin			15	
		IOML(2)	P00, P01	Per 1 applicable pin			20	
		IOML(3)	P70, CF2	Per 1 applicable pin			7.5	
	Total output current	ΣIOAL(1)	Ports 0, 1, Ports 2, 7, CF2	Total of all applicable pins			70	
Power dissipation	Pd max(1)	SSOP24(225mil)	Ta=-40 to +85°C Package only				111	mW
	Pd max(2)		Ta=-40 to +85°C Package with thermal resistance board (Note 1-2)				334	
	Pd max(3)	VCT24(3 × 3)	Ta=-40 to +85°C Package only				66	
	Pd max(4)		Ta=-40 to +85°C Package with thermal resistance board (Note 1-3)				335	
Operating ambient temperature	Topr				-40		+85	°C
Storage ambient temperature	Tstg				-55		+125	

Note 1-1: The mean output current is a mean value measured over 100ms.

Note 1-2: SEMI standards thermal resistance board (size: 76.1×114.3×1.6mm, glass epoxy) is used.

Note 1-3: Thermal resistance board (size: 40×50×0.8mm, glass epoxy, 4-layer(2S2P)) is used.

Stresses exceeding Maximum Ratings may damage the device. Maximum Ratings are stress ratings only. Functional operation above the Recommended Operating Conditions is not implied. Extended exposure to stresses above the Recommended Operating Conditions may affect device reliability.

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Allowable Operating Conditions at Ta = -40°C to +85°C, V_{SS}1 = 0V

Parameter	Symbol	Pin/Remarks	Conditions	Specification				
				V _{DD} [V]	min	typ	max	unit
Operating supply voltage (Note 2-1)	V _{DD} (1)	V _{DD} 1	0.245μs ≤ tCYC ≤ 200μs		2.7		5.5	V
	V _{DD} (2)		0.294μs ≤ tCYC ≤ 200μs		2.2		5.5	
	V _{DD} (3)		0.735μs ≤ tCYC ≤ 200μs		1.8		5.5	
Memory sustaining supply voltage	V _{HD}	V _{DD} 1	RAM and register contents sustained in HOLD mode.		1.6			
High level input voltage	V _{IH} (1)	Ports 1, 2, 7		1.8 to 5.5	0.3V _{DD} +0.7		V _{DD}	
	V _{IH} (2)	Ports 0		1.8 to 5.5	0.3V _{DD} +0.7		V _{DD}	
	V _{IH} (3)	CF1, CF2, $\overline{\text{RES}}$		1.8 to 5.5	0.75V _{DD}		V _{DD}	
Low level input voltage	V _{IL} (1)	Ports 1, 2, 7		4.0 to 5.5	V _{SS}		0.1V _{DD} +0.4	
				1.8 to 4.0	V _{SS}		0.2V _{DD}	
	V _{IL} (2)	Ports 0		4.0 to 5.5	V _{SS}		0.15V _{DD} +0.4	
				1.8 to 4.0	V _{SS}		0.2V _{DD}	
	V _{IL} (3)	CF1, CF2, $\overline{\text{RES}}$		1.8 to 5.5	V _{SS}		0.25V _{DD}	
High level output current	I _{OH} (1)	Ports 0, 1, 2	Per 1 applicable pin	4.5 to 5.5	-1.0			mA
	I _{OH} (2)			2.7 to 4.5	-0.35			
	I _{OH} (3)			1.8 to 2.7	-0.15			
	I _{OH} (4)	P05 (System clock output function used)	Per 1 applicable pin	4.5 to 5.5	-6.0			
	I _{OH} (5)			2.7 to 4.5	-1.4			
	I _{OH} (6)			1.8 to 2.7	-0.8			
	ΣI _{OH} (1)	Ports 0, 1, 2	Total of all applicable pins	4.5 to 5.5	-25			
	ΣI _{OH} (2)			2.7 to 4.5	-8.0			
	ΣI _{OH} (3)			1.8 to 2.7	-3.5			
Low level output current	I _{OL} (1)	Ports 0, 1, 2	Per 1 applicable pin	4.5 to 5.5			7	
	I _{OL} (2)			2.7 to 4.5			1	
	I _{OL} (3)			1.8 to 2.7			0.5	
	I _{OL} (4)	P70, CF2	Per 1 applicable pin	2.7 to 5.5			1	
	I _{OL} (5)			1.8 to 2.7			0.5	
	I _{OL} (6)	P00, P01	Per 1 applicable pin	4.5 to 5.5			15	
	I _{OL} (7)			2.7 to 4.5			2	
	I _{OL} (8)			1.8 to 2.7			1	
	ΣI _{OL} (1)	Ports 0	Total of all applicable pins	4.5 to 5.5			40	
	ΣI _{OL} (2)			2.7 to 4.5			10	
	ΣI _{OL} (3)			1.8 to 2.7			5	
	ΣI _{OL} (4)	Ports 0, 1, 2, CF2	Total of all applicable pins	4.5 to 5.5			70	
	ΣI _{OL} (5)			2.7 to 4.5			21	
	ΣI _{OL} (6)			1.8 to 2.7			10.5	
	ΣI _{OL} (7)	Ports 7	Total of all applicable pins	2.7 to 5.5			1	
	ΣI _{OL} (8)			1.8 to 2.7			0.5	
Instruction cycle time (Note 2-2)	tCYC			2.7 to 5.5	0.245		200	μs
				2.2 to 5.5	0.294		200	
				1.8 to 5.5	0.735		200	
External system clock frequency	FEXCF	CF1	• CF2 pin open	2.7 to 5.5	0.1		12	MHz
			• System clock frequency division ratio=1/1	1.8 to 5.5	0.1		4	
			• External system clock duty=50±5%	3.0 to 5.5	0.2		24.4	
			• CF2 pin open • System clock frequency division ratio=1/2 • External system clock duty=50±5%	2.0 to 5.5	0.2		8	

Note 2-1: V_{DD} must be held greater than or equal to 2.2V in the flash ROM onboard programming mode.

Note 2-2: Relationship between tCYC and oscillation frequency is 3/FmCF at a division ratio of 1/1 and 6/FmCF at a division ratio of 1/2.

Continued on next page.

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Continued from preceding page.

Parameter	Symbol	Pin/Remarks	Conditions	Specification				
				V _{DD} [V]	min	typ	max	unit
Oscillation frequency range (Note 2-3)	FmCF(1)	CF1, CF2	12MHz ceramic oscillation. See Fig. 1.	2.7 to 5.5		12		MHz
	FmCF(2)	CF1, CF2	10MHz ceramic oscillation. See Fig. 1.	2.2 to 5.5		10		
	FmCF(3)	CF1, CF2	4MHz ceramic oscillation. CF oscillation normal amplifier size selected. (CFLAMP=0) See Fig. 1.	1.8 to 5.5		4		
			4MHz ceramic oscillation. CF oscillation low amplifier size selected. (CFLAMP=1) See Fig. 1.	2.2 to 5.5		4		
	FmMRC(1)		Frequency variable RC oscillation. (Note 2-4)	1.8 to 5.5	7.84	8.0	8.16	
	FmMRC(2)		Frequency variable RC oscillation. • Ta=-10 to +85°C (Note 2-4)	1.8 to 5.5	7.88	8.0	8.12	
	FmRC		Internal medium-speed RC oscillation	1.8 to 5.5	0.5	1.0	2.0	
	FmSRC		Internal low-speed RC oscillation	1.8 to 5.5	50	100	200	
	FsX'tal	XT1, XT2	32.768kHz crystal oscillation See Fig. 1.	1.8 to 5.5		32.768		kHz
Oscillation stabilization time	tmsMRC		When Frequency variable RC oscillation state is switched from stopped to enabled. See Fig. 3.	1.8 to 5.5			100	μs

Note 2-3: See Tables 1 and 2 for the oscillation constants.

Note 2-4: When switching the system clock, allow an oscillation stabilization time of 100μs or longer after the frequency variable RC oscillator circuit transmits from the "oscillation stopped" to "oscillation enabled" state.

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Electrical Characteristics at Ta = -40°C to +85°C, VSS1 = 0V

Parameter	Symbol	Pin/Remarks	Conditions	Specification				
				VDD[V]	min	typ	max	unit
High level input current	I _{IH} (1)	Ports 0, 1, 2, P70, $\overline{\text{RES}}$	Output disabled Pull-up resistor off V _{IN} =V _{DD} (Including output Tr's off leakage current)	1.8 to 5.5			1	μA
	I _{IH} (2)	CF1, CF2	Input port selected V _{IN} =V _{DD}	1.8 to 5.5			1	
	I _{IH} (3)	CF1	Reset state V _{IN} =V _{DD}	1.8 to 5.5			15	
Low level input current	I _{IL} (1)	Ports 0, 1, 2, P70, $\overline{\text{RES}}$	Output disabled Pull-up resistor off V _{IN} =V _{SS} (Including output Tr's off leakage current)	1.8 to 5.5	-1			
	I _{IL} (2)	CF1, CF2	Input port selected V _{IN} =V _{SS}	1.8 to 5.5	-1			
High level output voltage	V _{OH} (1)	Ports 0, 1, 2	I _{OH} =-1mA	4.5 to 5.5	V _{DD} -1			V
	V _{OH} (2)		I _{OH} =-0.35mA	2.7 to 5.5	V _{DD} -0.4			
	V _{OH} (3)		I _{OH} =-0.15mA	1.8 to 5.5	V _{DD} -0.4			
	V _{OH} (4)	P05 (System clock output function used)	I _{OH} =-6mA	4.5 to 5.5	V _{DD} -1			
	V _{OH} (5)		I _{OH} =-1.4mA	2.7 to 5.5	V _{DD} -0.4			
	V _{OH} (6)		I _{OH} =-0.8mA	1.8 to 5.5	V _{DD} -0.4			
Low level output voltage	V _{OL} (1)	Ports 0, 1, 2	I _{OL} =7mA	4.5 to 5.5			1.5	V
	V _{OL} (2)		I _{OL} =1mA	2.7 to 5.5			0.4	
	V _{OL} (3)		I _{OL} =0.5mA	1.8 to 5.5			0.4	
	V _{OL} (4)	P70, CF2	I _{OL} =1mA	2.7 to 5.5			0.4	
	V _{OL} (5)		I _{OL} =0.5mA	1.8 to 5.5			0.4	
	V _{OL} (6)	P00, P01	I _{OL} =15mA	4.5 to 5.5			1.5	
	V _{OL} (7)		I _{OL} =2mA	2.7 to 5.5			0.4	
	V _{OL} (8)		I _{OL} =1mA	1.8 to 5.5			0.4	
Pull-up resistance	R _{pu} (1)	Ports 0, 1, 2 P70	V _{OH} =0.9V _{DD} When Port 0 selected low-impedance pull-up.	4.5 to 5.5	15	35	80	k Ω
	R _{pu} (2)			1.8 to 4.5	18	50	230	
	R _{pu} (3)	Port 0	V _{OH} =0.9V _{DD} When Port 0 selected high-impedance pull-up.	1.8 to 5.5	100	200	400	
Hysteresis voltage	V _{HYS} (1)	Ports 1, 2, P70, $\overline{\text{RES}}$		2.7 to 5.5		0.1V _{DD}		V
	V _{HYS} (2)			1.8 to 2.7		0.07V _{DD}		
Pin capacitance	CP	All pins	For pins other than that under test: V _{IN} =V _{SS} f=1MHz Ta=25°C	1.8 to 5.5		10		pF

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SIO0 Serial I/O Characteristics at Ta = -40°C to +85°C, VSS1 = 0V (Note 4-1-1)

Parameter			Symbol	Pin/ Remarks	Conditions	V _{DD} [V]	Specification				
							min	typ	max	unit	
Serial clock	Input clock	Frequency	tSCK(1)	SCK0(P12)	• See Fig. 5.	1.8 to 5.5	2			tCYC	
		Low level pulse width	tSCKL(1)				1				
		High level pulse width	tSCKH(1)		1						
			tSCKHA(1)		4						
	Output clock	Frequency	tSCK(2)	SCK0(P12)	• CMOS output selected • See Fig. 5.	1.8 to 5.5	4/3			tSCK	
		Low level pulse width	tSCKL(2)				1/2				
		High level pulse width	tSCKH(2)		1/2		tSCKH(2) +2tCYC	tSCKH(2) +(10/3) tCYC	tCYC		
			tSCKHA(2)								
Serial input	Data setup time		tsDI(1)	SB0(P11), SI0(P11)	• Must be specified with respect to rising edge of SIOCLK. • See Fig. 5.	1.8 to 5.5	0.05			μs	
	Data hold time						thDI(1)	0.05			
Serial output	Input clock	Output delay time	tdD0(1)	SO0(P10), SB0(P11)	• Continuous data transmission/reception mode (Note 4-1-3)	1.8 to 5.5			(1/3)tCYC +0.08		
			tdD0(2)		• Synchronous 8-bit mode (Note 4-1-3)				1tCYC +0.08		
	Output clock	tdD0(3)	(Note 4-1-3)					(1/3)tCYC +0.08			

Note 4-1-1: These specifications are theoretical values. Add margin depending on its use.

Note 4-1-2: To use serial-clock-input in continuous trans/rec mode, a time from SI0RUN being set when serial clock is "H" to the first negative edge of the serial clock must be longer than tSCKHA.

Note 4-1-3: Must be specified with respect to falling edge of SIOCLK. Must be specified as the time to the beginning of output state change in open drain output mode. See Fig. 5.

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SIO1 Serial I/O Characteristics at Ta = -40°C to +85°C, VSS1 = 0V (Note 4-2-1)

Parameter			Symbol	Pin/ Remarks	Conditions	V _{DD} [V]	Specification			
							min	typ	max	unit
Serial clock	Input clock	Frequency	tSCK(3)	SCK1(P15)	• See Fig. 5.	1.8 to 5.5	2			tCYC
		Low level pulse width	tSCKL(3)				1			
		High level pulse width	tSCKH(3)				1			
	Output clock	Frequency	tSCK(4)	SCK1(P15)	• CMOS output selected • See Fig. 5.	1.8 to 5.5	2			tSCK
		Low level pulse width	tSCKL(4)				1/2			
		High level pulse width	tSCKH(4)				1/2			
Serial input	Data setup time		tsDI(2)	SI1(P14), SB1(P14)	• Must be specified with respect to rising edge of SIOCLK. • See Fig. 5.	1.8 to 5.5	(1/3)tCYC +0.01			μs
	Data hold time		thDI(2)				0.01			
Serial output	Output delay time		tdD0(4)	SO1(P13), SB1(P14)	• Must be specified with respect to falling edge of SIOCLK. • Must be specified as the time to the beginning of output state change in open drain output mode. • See Fig. 5.	1.8 to 5.5			(1/2)tCYC +0.05	

Note 4-2-1: These specifications are theoretical values. Add margin depending on its use.

Pulse Input Conditions at Ta = -40°C to +85°C, VSS1 = 0V

Parameter		Symbol	Pin/Remarks	Conditions	V _{DD} [V]	Specification			
						min	typ	max	unit
High/low level pulse width	tPIH(1) tPIL(1)	INT0(P70), INT1(P17), INT2(P16), INT4(P20 to P21)	• Interrupt source flag can be set. • Event inputs for timer 0 or 1 are enabled.	1.8 to 5.5	1				tCYC
	tPIH(2) tPIL(2)	INT3(P15) when noise filter time constant is 1/1	• Interrupt source flag can be set. • Event inputs for timer 0 are enabled.	1.8 to 5.5	2				
	tPIH(3) tPIL(3)	INT3(P15) when noise filter time constant is 1/32	• Interrupt source flag can be set. • Event inputs for timer 0 are enabled.	1.8 to 5.5	64				
	tPIH(4) tPIL(4)	INT3(P15) when noise filter time constant is 1/128	• Interrupt source flag can be set. • Event inputs for timer 0 are enabled.	1.8 to 5.5	256				
	tPIL(5)	RES	• Resetting is enabled.	1.8 to 5.5	200				μs

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Reference voltage (VREF17) Characteristics at Ta = -40°C to +85°C, VSS1 = 0V

Parameter	Symbol	Pin/Remarks	Conditions	Specification				
				V _{DD} [V]	min	typ	max	unit
Output voltage	VOVREF			2.0 to 5.5	1.67	1.75	1.83	V
Reference voltage operation current (Note 7-1)	IDDVREF			2.0 to 5.5		110		μA
Operation stabilization time (Note 7-2)	tVRW			2.0 to 5.5			100	μs

Note 7-1: IDDVREF denotes the currents that only flow to multivariable RC oscillator circuit's reference voltage circuit.

Note 7-2: tVRW denotes the stabilization time from starting multivariable RC oscillator.

Power-on Reset (POR) Characteristics at Ta = -40°C to +85°C, VSS1 = 0V

Parameter	Symbol	Pin/Remarks	Conditions	Option selected voltage	Specification			
					min	typ	max	unit
POR release voltage	PORRL		• Select from option. (Note 8-1)	1.67V	1.55	1.66	1.77	V
				1.97V	1.85	1.96	2.07	
				2.07V	1.93	2.05	2.17	
				2.37V	2.23	2.35	2.47	
				2.57V	2.43	2.55	2.67	
				2.87V	2.71	2.85	2.99	
				3.86V	3.65	3.83	4.00	
				4.35V	4.12	4.32	4.50	
Detection voltage unknown state	POUKS		• See Fig. 7. (Note 8-2)			0.7	0.95	
Power supply rise time	PORIS		• Power supply rise time from 0V to 1.6V.				100	ms

Note8-1: The POR release level can be selected out of 8 levels only when the LVD reset function is disabled.

Note8-2: POR is in an unknown state before transistors start operation.

Low Voltage Detection Reset (LVD) Characteristics at Ta = -40°C to +85°C, VSS1=0V

Parameter	Symbol	Pin/Remarks	Conditions	Option selected voltage	Specification			
					min	typ	max	unit
LVD reset voltage (Note 9-2)	LVDET		• Select from option. (Note 9-1) (Note 9-3) • See Fig. 8.	1.91V	1.81	1.91	2.01	V
				2.01V	1.90	2.00	2.10	
				2.31V	2.20	2.30	2.40	
				2.51V	2.40	2.50	2.60	
				2.81V	2.68	2.80	2.92	
				3.79V	3.62	3.78	3.94	
				4.28V	4.09	4.27	4.45	
LVD hysteresis width	LVHYS			1.91V		50		mV
				2.01V		50		
				2.31V		50		
				2.51V		50		
				2.81V		50		
				3.79V		50		
				4.28V		50		
Detection voltage unknown state	LVUKS		• See Fig. 8. (Note 9-4)			0.7	0.95	V
Low voltage detection minimum width (Reply sensitivity)	TLVDW		• LVDET-0.5V • See Fig. 9.		0.2			ms

Note9-1: The LVD reset level can be selected out of 7 levels only when the LVD reset function is enabled.

Note9-2: LVD reset voltage specification values do not include hysteresis voltage.

Note9-3: LVD reset voltage may exceed its specification values when port output state changes and/or when a large current flows through port.

Note9-4: LVD is in an unknown state before transistors start operation.

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Continued from preceding page.

Parameter	Symbol	Pin/ remarks	Conditions	V _{DD} [V]	Specification			
					min	typ	max	unit
HALT mode consumption current (Note 10-1) (Note 10-2)	IDDHALT(7)	V _{DD} 1	<ul style="list-style-type: none">• HALT mode• FsX'tal=32.768kHz crystal oscillation mode• Internal low speed and medium speed RC oscillation stopped.• System clock set to 8MHz with frequency variable RC oscillation• 1/1 frequency division ratio	1.8 to 5.5		1.3	2.3	mA
			1.8 to 3.6		0.91	1.5		
	IDDHALT(8)		<ul style="list-style-type: none">• HALT mode• External FsX'tal and FmCF oscillation stopped.• System clock set to internal low speed RC oscillation.• Internal medium speed RC oscillation stopped.• Frequency variable RC oscillation stopped.• 1/1 frequency division ratio	1.8 to 5.5		18	68	μA
			1.8 to 3.6		11	35		
	IDDHALT(9)		<ul style="list-style-type: none">• HALT mode• External FsX'tal and FmCF oscillation stopped.• System clock set to internal low speed RC oscillation.• Internal medium speed RC oscillation stopped.• Frequency variable RC oscillation stopped.• 1/1 frequency division ratio• Ta=-10 to +50°C	5.0		18	46	
			3.3		11	27		
			2.5		7.4	19		
	IDDHALT(10)		<ul style="list-style-type: none">• HALT mode• FsX'tal=32.768kHz crystal oscillation mode• System clock set to 32.768kHz side• Internal low speed and medium speed RC oscillation stopped.• Frequency variable RC oscillation stopped.• 1/2 frequency division ratio	1.8 to 5.5		24	98	
			1.8 to 3.6		8.0	35		
	IDDHALT(11)		<ul style="list-style-type: none">• HALT mode• FsX'tal=32.768kHz crystal oscillation mode• System clock set to 32.768kHz side• Internal low speed and medium speed RC oscillation stopped.• Frequency variable RC oscillation stopped.• 1/2 frequency division ratio• Ta=-10 to +50°C	5.0		24	63	
			3.3		8.0	23		
			2.5		3.5	11		
HOLD mode consumption current (Note 10-1) (Note 10-2)	IDDHOLD(1)	<ul style="list-style-type: none">• HOLD mode• CF1=V_{DD} or open (External clock mode)	1.8 to 5.5		0.019	23		
		1.8 to 3.6		0.011	11			
	IDDHOLD(2)	<ul style="list-style-type: none">• HOLD mode• CF1=V_{DD} or open (External clock mode)• Ta=-10 to +50°C	5.0		0.019	1.2		
		3.3		0.011	0.59			
		2.5		0.010	0.30			
	IDDHOLD(3)	<ul style="list-style-type: none">• HOLD mode• CF1=V_{DD} or open (External clock mode)• LVD option selected	1.8 to 5.5		2.6	26		
		1.8 to 3.6		2.0	13			
	IDDHOLD(4)	<ul style="list-style-type: none">• HOLD mode• CF1=V_{DD} or open (External clock mode)• Ta=-10 to +50°C• LVD option selected	5.0		2.6	3.8		
3.3			2.0	2.8				
2.5			1.7	2.5				
Timer HOLD mode consumption current (Note 10-1) (Note 10-2)	IDDHOLD(5)	<ul style="list-style-type: none">• Timer HOLD mode• FsX'tal=32.768kHz crystal oscillation mode	1.8 to 5.5		22	84		
		1.8 to 3.6		6.5	30			
	IDDHOLD(6)	<ul style="list-style-type: none">• Timer HOLD mode• FsX'tal=32.768kHz crystal oscillation mode• Ta=-10 to +50°C	5.0		22	53		
		3.3		6.5	16			
		2.5		2.7	7.2			

Note10-1: Values of the consumption current do not include current that flows into the output transistors and internal pull-up resistors.

Note10-2: The consumption current values do not include operational current of LVD function if not specified.

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F-ROM Programming Characteristics at Ta = +10°C to +55°C, V_{SS1} = 0V

Parameter	Symbol	Pin/Remarks	Conditions	Specification				
				V _{DD} [V]	min	typ	max	unit
Onboard programming current	IDDFW(1)	V _{DD1}	• Only current of the Flash block.	2.2 to 5.5		5	10	mA
Programming time	tFW(1)		• Erasing time	2.2 to 5.5		20	30	ms
	tFW(2)		• Programming time			40	60	μs

UART (Full Duplex) Operating Conditions at Ta = -40°C to +85°C, V_{SS1} = 0V

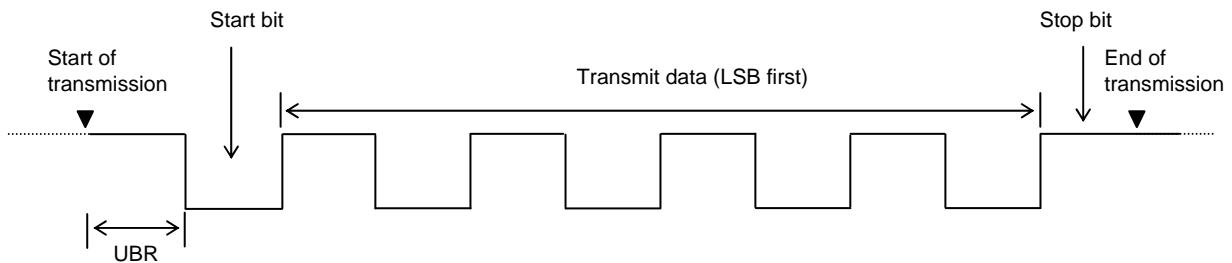
Parameter	Symbol	Pin/Remarks	Conditions	Specification				
				V _{DD} [V]	min	typ	max	unit
Transfer rate	UBR	P20, P21		1.8 to 5.5	16/3		8192/3	tCYC

Data length: 7/8/9 bits (LSB first)

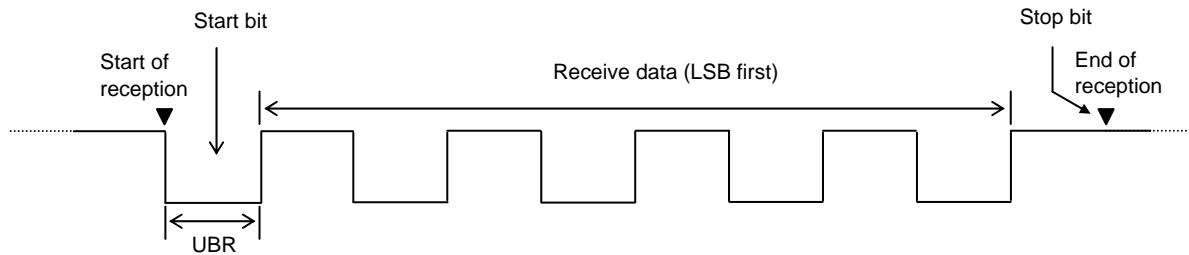
Stop bits: 1 bit (2-bit in continuous data transmission)

Parity bits: None

Example of Continuous 8-bit Data Transmission Mode Processing (First Transmit Data=55H)



Example of Continuous 8-bit Data Reception Mode Processing (First Receive Data=55H)



Characteristics of a Sample Subsystem Clock Oscillator Circuit

Given below are the characteristics of a sample subsystem clock oscillation circuit that are measured using a Our designated oscillation characteristics evaluation board and external components with circuit constant values with which the oscillator vendor confirmed normal and stable oscillation.

Table 2 Characteristics of a Sample Subsystem Clock Oscillator Circuit with a Crystal Oscillator

■EPSON TOYOCOM

Nominal Frequency	Type	Oscillator Name	Circuit Constant				Operating Voltage Range [V]	Oscillation Stabilization Time		Remarks
			C1 [pF]	C2 [pF]	Rf [Ω]	Rd [Ω]		typ [s]	max [s]	
32.768kHz	SMD	MC-306	9	9	Open	330k	1.8 to 5.5	1.4	4.0	Applicable CL value = 7.0pF

■SEIKO INSTRUMENTS

Nominal Frequency	Type	Oscillator Name	Circuit Constant				Operating Voltage Range [V]	Oscillation Stabilization Time		Remarks
			C1 [pF]	C2 [pF]	Rf [Ω]	Rd [Ω]		typ [s]	max [s]	
32.768kHz	SMD	SSP-T7-F	18	22	Open	330k	1.8 to 5.5	0.75	2.0	Applicable CL value = 12.5pF

The oscillation stabilization time refers to the time interval that is required for the oscillation to get stabilized after VDD goes above the operating voltage lower limit (see Figure 3).

- The time interval that is required for the oscillation to get stabilized after the instruction for starting the subclock oscillation circuit is executed.
- The time interval that is required for the oscillation to get stabilized after the Hold mode, under the state which the subclock oscillation is enabled, is reset and oscillation is started.

(Notes on the implementation of the oscillator circuit)

- Oscillation is influenced by the circuit pattern layout of printed circuit board. Place the oscillation-related components as close to the CPU chip and to each other as possible with the shortest possible pattern length.
- Keep the signal lines whose state changes suddenly or in which large current flows as far away from the oscillator circuit as possible and make sure that they do not cross one another.
- Be sure to insert a current limiting resistor (Rd) so that the oscillation amplitude never exceeds the input voltage level that is specified as the absolute maximum rating.
- The oscillator circuit constants shown above are sample characteristic values that are measured using the Our designated oscillation evaluation board. Since the accuracy of the oscillation frequency and other characteristics vary according to the board on which the IC is installed, it is recommended that the user consult the resonator vendor for oscillation evaluation of the IC on a user's production board when using the IC for applications that require high oscillation accuracy. For further information, contact your resonator vendor or Our company sales representative serving your locality.
- It must be noted, when replacing the flash ROM version of a microcontroller with a mask ROM version, that their operating voltage ranges may differ even when the oscillation constant of the external oscillator is the same.

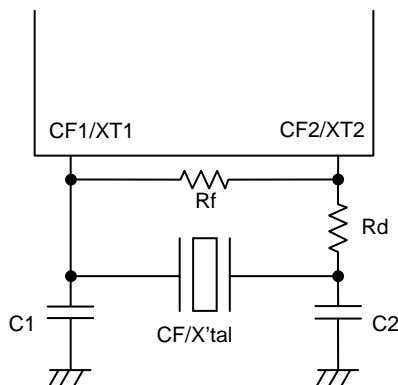


Figure 1 CF and XT Oscillator Circuit

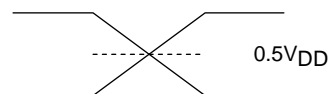
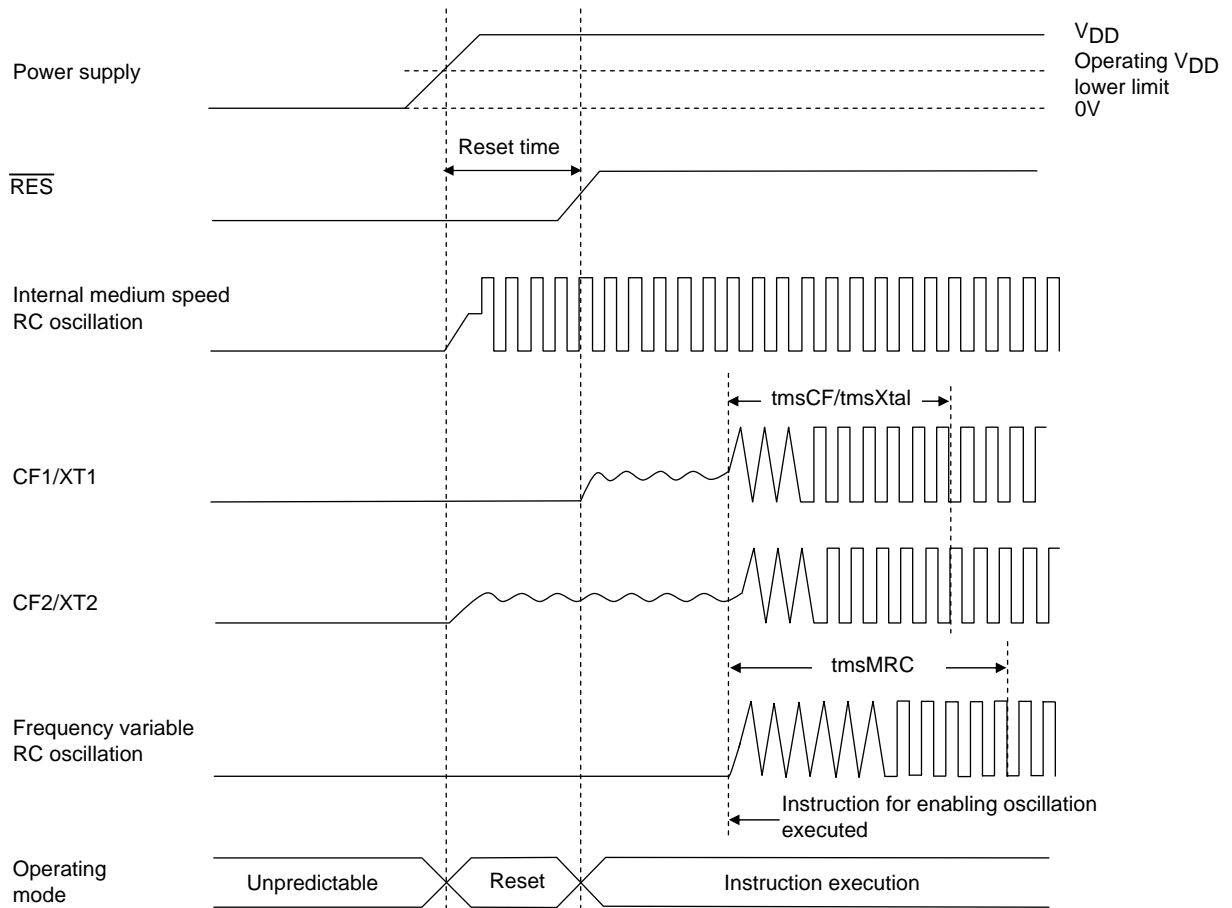
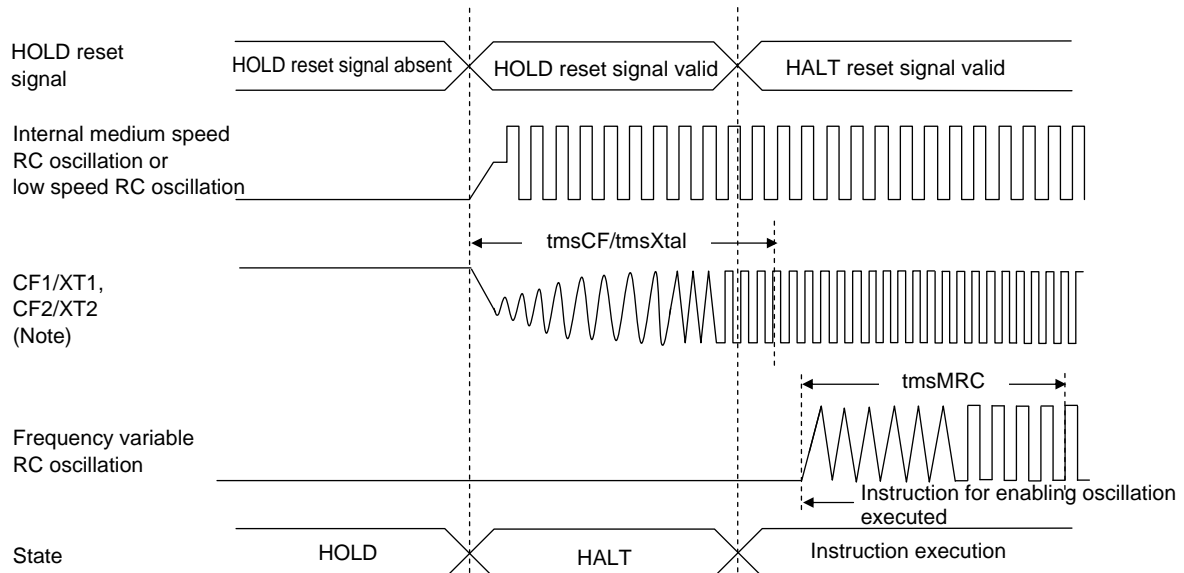


Figure 2 AC Timing Measurement Point



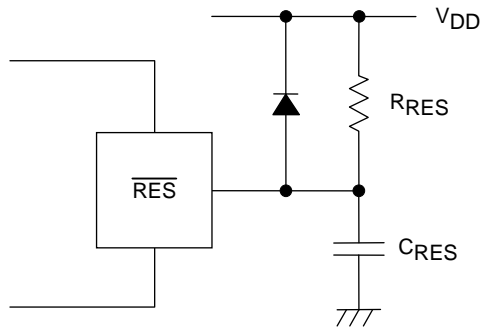
Reset Time and Oscillation Stabilization Time



HOLD Reset Signal and Oscillation Stabilization Time

Note: External oscillation circuit is selected.

Figure 3 Oscillation Stabilization Times



Note:
External circuits for reset may vary depending on the usage of POR and LVD. Please refer to the user's manual for more information.

Figure 4 Reset Circuit

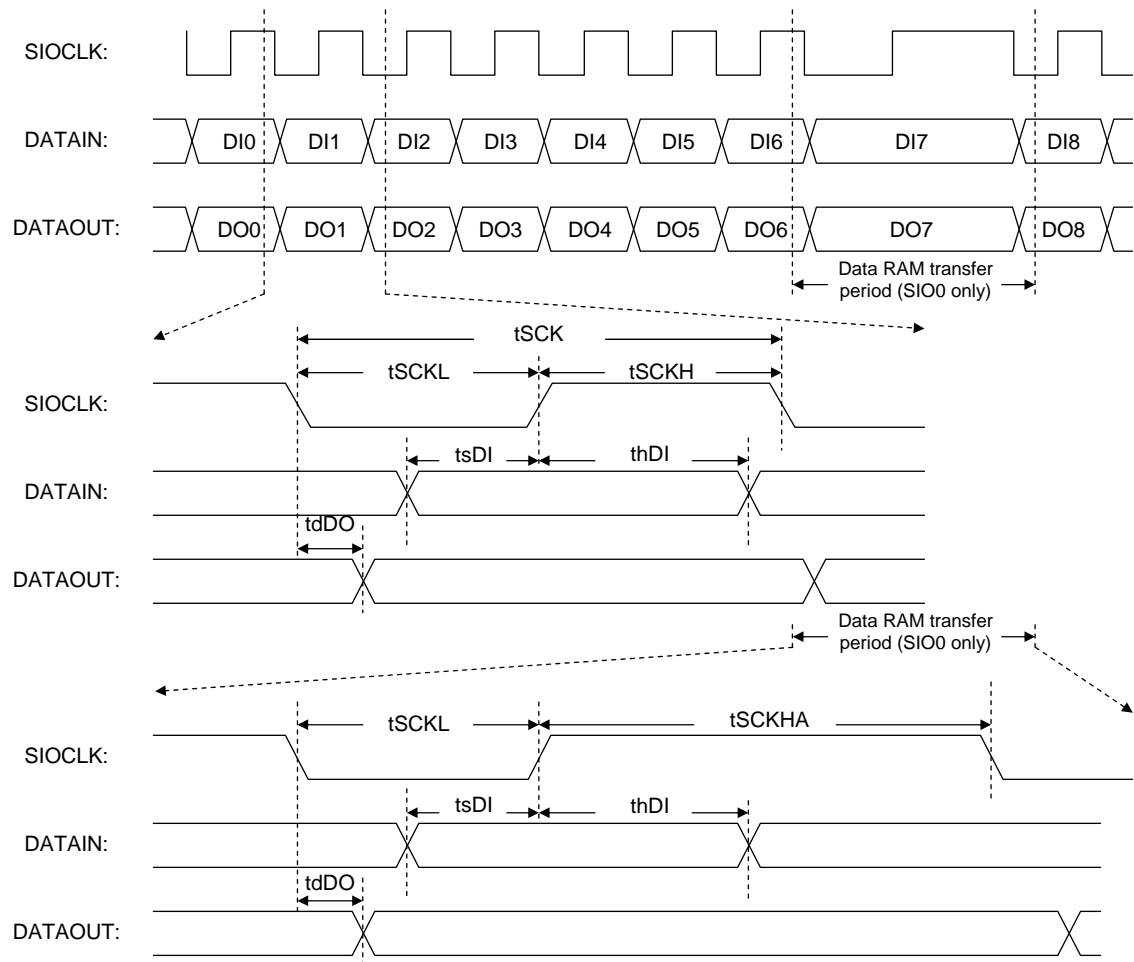


Figure 5 Serial I/O Output Waveforms

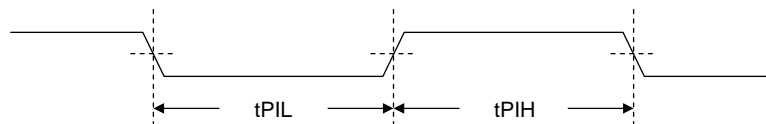


Figure 6 Pulse Input Timing Signal Waveform

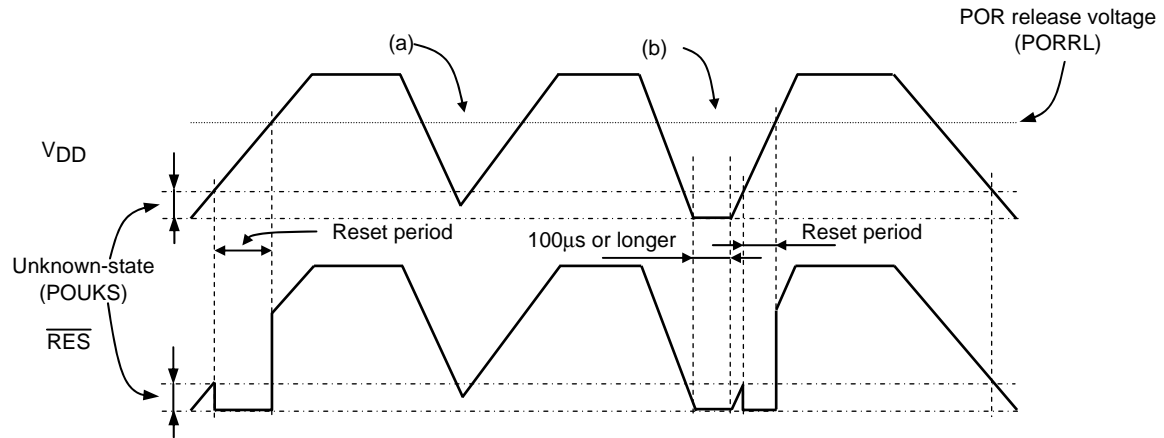


Figure 7 Waveform observed when only POR is used (LVD not used)
(RESET pin: Pull-up resistor R_{RES} only)

- The POR function generates a reset only when power is turned on starting at the V_{SS} level.
- No stable reset will be generated if power is turned on again when the power level does not go down to the V_{SS} level as shown in (a). If such a case is anticipated, use the LVD function together with the POR function or implement an external reset circuit.
- A reset is generated only when the power level goes down to the V_{SS} level as shown in (b) and power is turned on again after this condition continues for 100µs or longer.

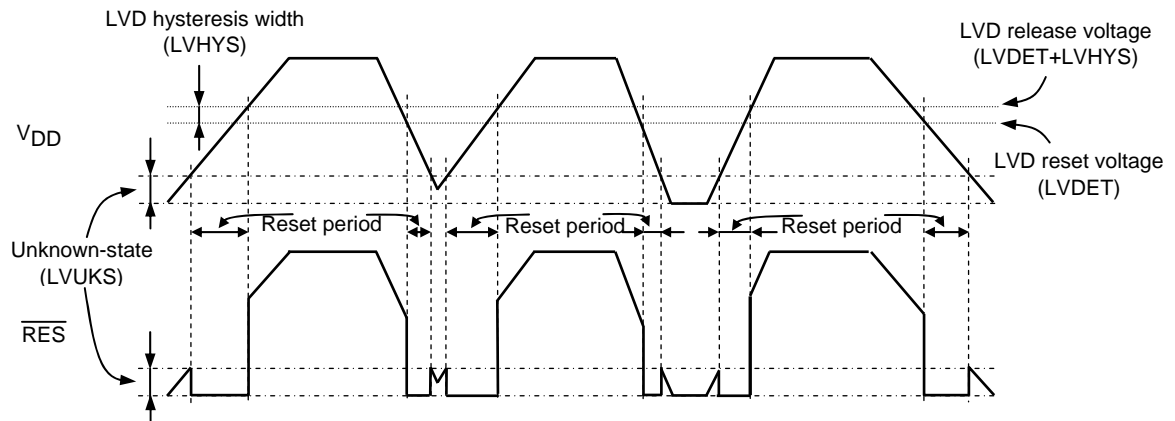


Figure 8 Waveform observed when both POR and LVD functions are used
(RESET pin: Pull-up resistor R_{RES} only)

- Resets are generated both when power is turned on and when the power level lowers.
- A hysteresis width (LVHYS) is provided to prevent the repetitions of reset release and entry cycles near the detection level.

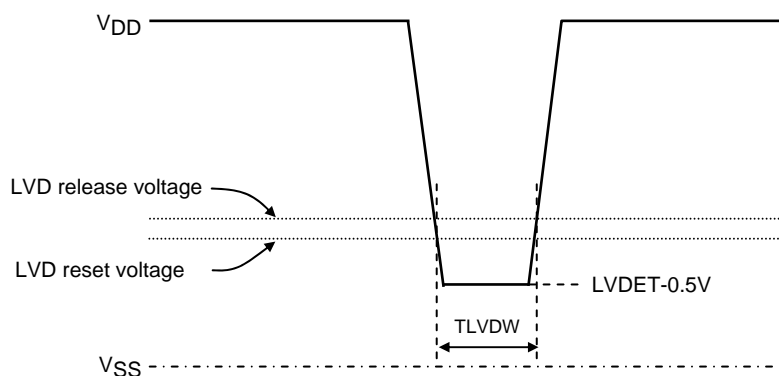


Figure 9 Low voltage detection minimum width
(Example of momentary power loss/Voltage variation waveform)

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