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"Embedded - Microcontrollers" refer to small, integrated circuits designed to perform specific tasks within larger systems. These microcontrollers are essentially compact computers on a single chip, containing a processor core, memory, and programmable input/output peripherals. They are called "embedded" because they are embedded within electronic devices to control various functions, rather than serving as standalone computers. Microcontrollers are crucial in modern electronics, providing the intelligence and control needed for a wide range of applications.

Applications of "<u>Embedded -</u> <u>Microcontrollers</u>"

Details

2014110	
Product Status	Obsolete
Core Processor	M8C
Core Size	8-Bit
Speed	24MHz
Connectivity	I ² C, SPI, UART/USART
Peripherals	POR, PWM, WDT
Number of I/O	24
Program Memory Size	4KB (4K x 8)
Program Memory Type	FLASH
EEPROM Size	-
RAM Size	256 × 8
Voltage - Supply (Vcc/Vdd)	2.4V ~ 5.25V
Data Converters	A/D 12x14b; D/A 2x9b
Oscillator Type	Internal
Operating Temperature	-40°C ~ 125°C (TA)
Mounting Type	Surface Mount
Package / Case	28-SSOP (0.209", 5.30mm Width)
Supplier Device Package	28-SSOP
Purchase URL	https://www.e-xfl.com/product-detail/infineon-technologies/cy8c24423a-24pvxa

Email: info@E-XFL.COM

Address: Room A, 16/F, Full Win Commercial Centre, 573 Nathan Road, Mongkok, Hong Kong



More Information

Cypress provides a wealth of data at www.cypress.com to help you to select the right PSoC device for your design, and to help you to quickly and effectively integrate the device into your design. Following is an abbreviated list for PSoC 1:

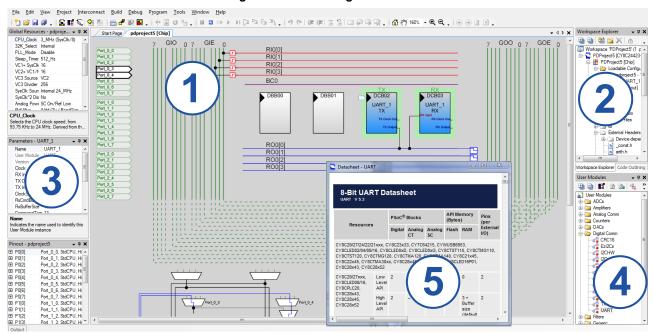
- Overview: PSoC Portfolio, PSoC Roadmap
- Product Selectors: PSoC 1, PSoC 3, PSoC 4, or PSoC 5LP In addition, PSoC Designer offers a device selection tool within PSoC 1, at the time of creating a new project.
- Datasheets: Describe and provide electrical specifications for all the PSoC 1 family of devices. Visit the PSoC 1 datasheets web page for a complete list
- Application notes and code examples:
 - □ Visit the PSoC 1 Code Examples web page for a comprehensive list of code examples
 - Cypress offers a large number of PSoC application notes covering a broad range of topics, from basic to advanced level. Recommended application notes for getting started with PSoC 1 are:
 - AN75320: Getting Started with PSoC® 1
 - AN2094: PSoC[®] 1 Getting Started with GPIO
 - AN2015: PSoC[®] 1 Getting Started with Flash & E2PROM
 - AN2014: Basics of PSoC[®] 1 Programming
 - AN32200: PSoC[®] 1 Clocks and Global Resources
 - AN2010: PSoC[®] 1 Best Practices and Recommendations
- Technical Reference Manual (TRM):

- Visit the PSoC 1 TRM page for the complete list of TRMs. Following documents provide detailed descriptions of the Architecture, Programming specification and Register map details of CY8C2XXXX PSoC 1 device family. PSoC1 CY8C2XXXX TRM
 - PSoC1 ISSP Programming Specifications
- Development Kits:
 - CY3210 CY8C24x23 PSoC(R) Evaluation Pods (EvalPod) are 28-pin PDIP adapters that seamlessly connect any PSoC device to the 28-pin PDIP connector on any Cypress PSoC development kit. CY3210-24x23 provides evaluation of the CY8C24x23A PSoC device family on any PSoC developer kit. PSoC developer kits are sold separately.
 - □ Visit the PSoC® 1 Kits page and refer the Kit Selector Guide document to find out the suitable development kits and debuggers for all PSoC 1 families.
- The CY3217-MiniProg1 and CY8CKIT-002 PSoC® MiniProg3 device provide an interface for flash programming.
- Knowledge Base Articles (KBA): Provide design and application tips from experts on the devices/kits. For example, Flash read/write access from firmware, explains how we can read and write to flash in PSoC 1 devices

PSoC Designer

PSoC Designer is a free Windows-based Integrated Design Environment (IDE). It enables concurrent hardware and firmware design of systems based on CapSense (see Figure 1). With PSoC Designer, you can:

- 1. Drag and drop user modules to build your hardware system design in the main design workspace
- 2. Codesign your application firmware with the PSoC hardware, using the PSoC Designer IDE C compiler
- 3. Configure user module
- 4. Explore the library of user modules
- 5. Review user module datasheets
- - Figure 1. PSoC Designer Features





Additional System Resources

System resources, some of which are listed in the previous sections, provide additional capability useful to complete systems. Additional resources include a multiplier, decimator, switch-mode pump, low-voltage detection, and power-on-reset (POR). Statements describing the merits of each system resource follow:

- Digital clock dividers provide three customizable clock frequencies for use in applications. The clocks can be routed to both the digital and analog systems. Additional clocks may be generated using digital PSoC blocks as clock dividers.
- A multiply accumulate (MAC) provides a fast 8-bit multiplier with 32-bit accumulate, to assist in both general math and digital filters.

- The decimator provides a custom hardware filter for digital signal processing applications including the creation of Delta Sigma ADCs.
- The I²C module provides 100- and 400-kHz communication over two wires. slave, master, and multi-master are supported.
- Low-voltage detection (LVD) interrupts can signal the application of falling voltage levels, while the advanced POR circuit eliminates the need for a system supervisor.
- An internal 1.3 V reference provides an absolute reference for the analog system, including ADCs and DACs.
- An integrated switch-mode pump generates normal operating voltages from a single 1.2 V battery cell, providing a low cost boost converter.

PSoC Device Characteristics

Depending on your PSoC device characteristics, the digital and analog systems can have 16, 8, or 4 digital blocks, and 12, 6, or 4 analog blocks. Table 1 on page 6 lists the resources available for specific PSoC device groups. The PSoC device covered by this datasheet is highlighted in this table.

PSoC Part Number	Digital I/O	Digital Rows	Digital Blocks	Analog Inputs	Analog Outputs	Analog Columns	Analog Blocks	SRAM Size	Flash Size
CY8C29x66	up to 64	4	16	up to 12	4	4	12	2 K	32 K
CY8C28xxx	up to 44	up to 3	up to 12	up to 44	up to 4	up to 6	up to 12 + 4 ^[2]	1 K	16 K
CY8C27x43	up to 44	2	8	up to 12	4	4	12	256	16 K
CY8C24x94	up to 56	1	4	up to 48	2	2	6	1 K	16 K
CY8C24x23A	up to 24	1	4	up to 12	2	2	6	256	4 K
CY8C23x33	up to 26	1	4	up to 12	2	2	4	256	8 K
CY8C22x45	up to 38	2	8	up to 38	0	4	6 ^[2]	1 K	16 K
CY8C21x45	up to 24	1	4	up to 24	0	4	6 ^[2]	512	8 K
CY8C21x34	up to 28	1	4	up to 28	0	2	4 ^[2]	512	8 K
CY8C21x23	up to 16	1	4	up to 8	0	2	4 ^[2]	256	4 K
CY8C20x34	up to 28	0	0	up to 28	0	0	3 ^[2,3]	512	8 K
CY8C20xx6	up to 36	0	0	up to 36	0	0	3 ^[2,3]	up to 2 K	up to 32 K

Table 1. PSoC Device Characteristics

2. Limited analog functionality.

3. Two analog blocks and one CapSense[®].



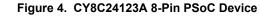
Pinouts

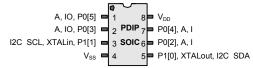
This section describes, lists, and illustrates the CY8C24x23A PSoC device pins and pinout configurations. Every port pin (labeled with a "P") is capable of digital I/O. However, V_{SS} , V_{DD} , SMP, and XRES are not capable of digital I/O.

8-Pin Part Pinout

Pin	Type Pin		Pin	Description
No.	Digital	Analog	Name	Description
1	I/O	I/O	P0[5]	Analog column mux input and column output
2	I/O	I/O	P0[3]	Analog column mux input and column output
3	I/O		P1[1]	Crystal input (XTALin), I ² C serial clock (SCL), ISSP-SCLK ^[4]
4	Po	wer	V _{SS}	Ground connection
5	I/O		P1[0]	Crystal output (XTALout), I ² C serial data (SDA), ISSP-SDATA ^[4]
6	I/O	I	P0[2]	Analog column mux input
7	I/O	I	P0[4]	Analog column mux input
8	Po	wer	V_{DD}	Supply voltage

Table 2. 8-Pin PDIP and SOIC





LEGEND: A = Analog, I = Input, and O = Output.



20-Pin Part Pinout

Table 3. 20-Pin PDIP, SSOP, and SOIC

Pin	Ту	ре	Pin	Description			
No.	Digital	Analog	Name	Description			
1	I/O	I	P0[7]	Analog column mux input			
2	I/O	I/O	P0[5]	Analog column mux input and column output			
3	I/O	I/O	P0[3]	Analog column mux input and column output			
4	I/O	I	P0[1]	Analog column mux input			
5	Po	wer	SMP	SMP connection to external components required			
6	I/O		P1[7]	I ² C SCL			
7	I/O		P1[5]	I ² C SDA			
8	I/O		P1[3]				
9	I/O		P1[1]	XTALin, I ² C SCL, ISSP-SCLK ^[5]			
10	Po	wer	V _{SS}	Ground connection.			
11	I/O		P1[0]	XTALout, I ² C SDA, ISSP-SDATA ^[5]			
12	I/O		P1[2]				
13	I/O		P1[4]	Optional external clock input (EXTCLK)			
14	I/O		P1[6]				
15	Inj	put	XRES	Active high external reset with internal pull-down			
16	I/O	I	P0[0]	Analog column mux input			
17	I/O	I	P0[2]	Analog column mux input			
18	I/O	I	P0[4]	Analog column mux input			
19	I/O	I	P0[6]	Analog column mux input			
20	Po	wer	V _{DD}	Supply voltage			

Figure 5. CY8C24223A 20-Pin PSoC Device

LEGEND: A = Analog, I = Input, and O = Output.

 Note

 5. These are the ISSP pins, which are not high Z at POR. See the PSoC Technical Reference Manual for details.



28-Pin Part Pinout

Table 4. 28-Pin PDIP, SSOP, and SOIC

Pin			Pin	Description	Figure 6. CY8C24423A 28-Pin PSoC Device
No.	Digital	Analog	Name	Description	
1	I/O	Ι	P0[7]	Analog column mux input	A, I, P0[7] = 1 28 D V _{DD}
2	I/O	I/O	P0[5]	Analog column mux input and column output	
3	I/O	I/O	P0[3]	Analog column mux input and column output	A, IO, P0[3] = 3 26 = P0[4], A, I A, I, P0[1] = 4 25 = P0[2], A, I
4	I/O	I	P0[1]	Analog column mux input	P2[7] = 5 24 = P0[0], A, I
5	I/O		P2[7]		P2[5]
6	I/O		P2[5]		A, I, P2[3] = 7 SSOP 22 = P2[4], External AGND A, I, P2[1] = 8 21 = P2[2], A, I
7	I/O	I	P2[3]	Direct switched capacitor block input	A, I, P2[1] = 8 21 = P2[2], A, I SMP = 9 SOIC 20 = P2[0], A, I
8	I/O	I	P2[1]	Direct switched capacitor block input	12CSCL, P1[7] = 10 19 EXRES
9	Pov	wer	SMP	SMP connection to external components	I2C SDA, P1[5] ■ 11 18 ■ P1[6]
- 10				required	P1[3] ■ 12 17 ■ P1[4], EXTCLK 12C SCL, XTALin, P1[1] ■ 13 16 ■ P1[2]
10	I/O		P1[7]	I ² C SCL	V _{ss} = 14 15 = P1[0], XTALout, I2(SD.
11	I/O		P1[5]	I ² C SDA	
12	I/O		P1[3]	2	
13	I/O		P1[1]	XTALin, I ² C SCL, ISSP-SCLK ^[6]	
14		wer	V _{SS}	Ground connection.	
15	I/O		P1[0]	XTALout, I ² C SDA, ISSP-SDATA ^[6]	
16	I/O		P1[2]		
17	I/O		P1[4]	Optional EXTCLK	-
18	I/O		P1[6]		-
19	Inp	out	XRES	Active high external reset with internal pull-down	
20	I/O	I	P2[0]	Direct switched capacitor block input	Not for Production
21	I/O	I	P2[2]	Direct switched capacitor block input	
22	I/O		P2[4]	External analog ground (AGND)	
23	I/O		P2[6]	External voltage reference (V _{REF})	
24	I/O	I	P0[0]	Analog column mux input	
25	I/O	I	P0[2]	Analog column mux input	
26	I/O	I	P0[4]	Analog column mux input	
27	I/O	I	P0[6]	Analog column mux input]
28	Pov	wer	V_{DD}	Supply voltage]

LEGEND: A = Analog, I = Input, and O = Output.

 Note

 6. These are the ISSP pins, which are not high Z at POR. See the PSoC Technical Reference Manual for details.

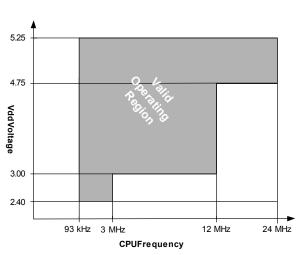


Electrical Specifications

This section presents the DC and AC electrical specifications of the CY8C24x23A PSoC device. For the latest electrical specifications, check if you have the most recent datasheet by visiting the website at http://www.cypress.com.

Specifications are valid for –40 $^\circ C \le T_A \le 85 \ ^\circ C$ and $T_J \le 100 \ ^\circ C,$ except where noted.

Refer to Table 29 on page 37 for the electrical specifications for the IMO using SLIMO mode.





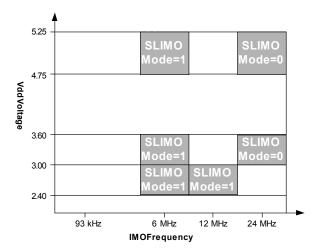


Figure 8. IMO Frequency Trim Options

Absolute Maximum Ratings

Exceeding maximum ratings may shorten the useful life of the device. User guidelines are not tested.

Symbol	Description	Min	Тур	Max	Units	Notes
T _{STG}	Storage temperature	-55	25	+100	°C	Higher storage temperatures reduce data retention time. Recommended storage temperature is +25 °C ± 25 °C. Extended duration storage temperatures above 65 °C degrades reliability.
T _{BAKETEMP}	Bake temperature	-	125	See package label	°C	
t _{BAKETIME}	Bake time	See package label	-	72	Hours	
T _A	Ambient temperature with power applied	-40	_	+85	°C	
V _{DD}	Supply voltage on V_{DD} relative to V_{SS}	-0.5	-	+6.0	V	
V _{IO}	DC input voltage	$V_{SS} - 0.5$	_	V _{DD} + 0.5	V	
V _{IOZ}	DC voltage applied to tri-state	$V_{SS} - 0.5$	-	V _{DD} + 0.5	V	
I _{MIO}	Maximum current into any port pin	-25	-	+50	mA	
ESD	Electrostatic discharge voltage	2000	-	-	V	Human body model ESD.
LU	Latch up current	_	-	200	mA	

Table 9. Absolute Maximum Ratings



DC GPIO Specifications

The following tables list the guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75 V to 5.25 V and –40 °C \leq T_A \leq 85 °C, 3.0 V to 3.6 V and –40 °C \leq T_A \leq 85 °C, or 2.4 V to 3.0 V and –40 °C \leq T_A \leq 85 °C, respectively. Typical parameters are measured at 5 V, 3.3 V, and 2.7 V at 25 °C and are for design guidance only.

Table 12. 5-V and 3.3-V DC GPIO Specifications

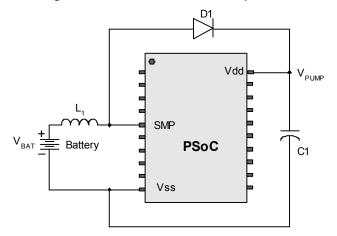
Symbol	Description	Min	Тур	Max	Units	Notes
R _{PU}	Pull-up resistor	4	5.6	8	kΩ	
R _{PD}	Pull-down resistor	4	5.6	8	kΩ	
V _{OH}	High output level	V _{DD} – 1.0	Ι	_	V	I_{OH} = 10 mA, V_{DD} = 4.75 to 5.25 V (maximum 40 mA on even port pins (for example, P0[2], P1[4]), maximum 40 mA on odd port pins (for example, P0[3], P1[5])). 80 mA maximum combined I_{OH} budget.
V _{OL}	Low output level	_	-	0.75	V	I_{OL} = 25 mA, V_{DD} = 4.75 to 5.25 V (maximum 100 mA on even port pins (for example, P0[2], P1[4]), maximum 100 mA on odd port pins (for example, P0[3], P1[5])). 150 mA maximum combined I_{OL} budget.
I _{ОН}	High level source current	10	-	-	mA	$V_{OH} = V_{DD} - 1.0 V$, see the limitations of the total current in the note for V_{OH}
I _{OL}	Low level sink current	25	-	-	mA	V_{OL} = 0.75 V, see the limitations of the total current in the note for V_{OL}
V _{IL}	Input low level	-	-	0.8	V	V _{DD} = 3.0 to 5.25
V _{IH}	Input high level	2.1	-		V	V _{DD} = 3.0 to 5.25
V _H	Input hysterisis	-	60	-	mV	
Ι _{ΙL}	Input leakage (absolute value)	-	1	-	nA	Gross tested to 1 µA
C _{IN}	Capacitive load on pins as input	-	3.5	10	pF	Package and pin dependent. Temp = 25 °C
C _{OUT}	Capacitive load on pins as output	-	3.5	10	pF	Package and pin dependent. Temp = 25 °C

Table 13. 2.7-V DC GPIO Specifications

Symbol	Description	Min	Тур	Мах	Units	Notes
R _{PU}	Pull-up resistor	4	5.6	8	kΩ	
R _{PD}	Pull-down resistor	4	5.6	8	kΩ	
V _{OH}	High output level	V _{DD} – 0.4	-	_	V	I_{OH} = 2 mA (6.25 Typ), V_{DD} = 2.4 to 3.0 V (16 mA maximum, 50 mA Typ combined I_{OH} budget).
V _{OL}	Low output level	-	-	0.75	V	I_{OL} = 11.25 mA, V_{DD} = 2.4 to 3.0 V (90 mA maximum combined I_{OL} budget).
I _{OH}	High level source current	2	-	-	mA	$V_{OH} = V_{DD} - 0.4$, see the limitations of total current in note for V_{OH} .
V _{IL}	Input low level	-	-	0.75	V	V _{DD} = 2.4 to 3.0
V _{IH}	Input high level	2.0	-	-	V	V _{DD} = 2.4 to 3.0
V _H	Input hysteresis	-	90	-	mV	
I _{OL}	Low level sink current	11.25	_	-	mA	V_{OL} = .75, see the limitations of total current in note for V_{OL} .
IIL	Input leakage (absolute value)	-	1	-	nA	Gross tested to 1 µA
C _{IN}	Capacitive load on pins as input	-	3.5	10	pF	Package and pin dependent. Temp = 25 °C
C _{OUT}	Capacitive load on pins as output	-	3.5	10	pF	Package and pin dependent. Temp = 25 °C



Figure 10. Basic Switch Mode Pump Circuit





DC POR, SMP, and LVD Specifications

Table 24 lists the guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75 V to 5.25 V and -40 °C \leq T_A \leq 85 °C, 3.0 V to 3.6 V and -40 °C \leq T_A \leq 85 °C, or 2.4 V to 3.0 V and -40 °C \leq T_A \leq 85 °C, respectively. Typical parameters are measured at 5 V, 3.3 V, and 2.7 V at 25 °C and are for design guidance only.

Note The bits PORLEV and VM in the following table refer to bits in the VLT_CR register. See the PSoC Programmable Sytem-on-Chip Technical Reference Manual for more information on the VLT_CR register.

Table 26. DC POR and LVD Specifications

Symbol	Description	Min	Тур	Max	Units	Notes
V _{PPOR0} V _{PPOR1} V _{PPOR2}	V _{DD} value for PPOR trip PORLEV[1:0] = 00b PORLEV[1:0] = 01b PORLEV[1:0] = 10b	_	2.36 2.82 4.55	2.40 2.95 4.70	V V V	V _{DD} must be greater than or equal to 2.5 V during startup, reset from the XRES pin, or reset from watchdog.
V _{LVD0} V _{LVD1} V _{LVD2} V _{LVD3} V _{LVD4} V _{LVD5} V _{LVD6} V _{LVD7}	$ \begin{array}{l} V_{DD} \text{ value for LVD trip} \\ VM[2:0] = 000b \\ VM[2:0] = 001b \\ VM[2:0] = 010b \\ VM[2:0] = 011b \\ VM[2:0] = 100b \\ VM[2:0] = 100b \\ VM[2:0] = 101b \\ VM[2:0] = 111b \\ \end{array} $	2.40 2.85 2.95 3.06 4.37 4.50 4.62 4.71	2.45 2.92 3.02 3.13 4.48 4.64 4.73 4.81	2.51 ^[12] 2.99 ^[13] 3.09 3.20 4.55 4.75 4.83 4.95	V V V V V V V V	
Vpumpo Vpump1 Vpump2 Vpump3 Vpump3 Vpump5 Vpump5 Vpump6 Vpump7	$\begin{array}{l} V_{DD} \text{ value for SMP trip} \\ VM[2:0] = 000b \\ VM[2:0] = 001b \\ VM[2:0] = 010b \\ VM[2:0] = 011b \\ VM[2:0] = 100b \\ VM[2:0] = 101b \\ VM[2:0] = 110b \\ VM[2:0] = 111b \end{array}$	2.50 2.96 3.03 3.18 4.54 4.62 4.71 4.89	2.55 3.02 3.10 3.25 4.64 4.73 4.82 5.00	2.62 ^[14] 3.09 3.16 3.32 ^[15] 4.74 4.83 4.92 5.12	>>>>>>>>>>>>>>>>>>>>>>>>>>>>>>>>>>>>>>>	

Notes

- 12. Always greater than 50 mV above V_{PPOR} (PORLEV=00) for falling supply. 13. Always greater than 50 mV above V_{PPOR} (PORLEV=01) for falling supply. 14. Always greater than 50 mV above V_{LVD0}. 15. Always greater than 50 mV above V_{LVD0}.



AC Electrical Characteristics

AC Chip-Level Specifications

These tables list the guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75 V to 5.25 V and -40 °C \leq T_A \leq 85 °C, 3.0 V to 3.6 V and -40 °C \leq T_A \leq 85 °C, or 2.4 V to 3.0 V and -40 °C \leq T_A \leq 85 °C, respectively. Typical parameters are measured at 5 V, 3.3 V, and 2.7 V at 25 °C and are for design guidance only.

Table 29. 5-V and 3.3-V AC Chip-Level Specifications

Symbol	Description	Min	Тур	Max	Units	Notes
F _{IMO24} ^[19]	Internal main oscillator (IMO) frequency for 24 MHz	22.8	24	25.2 ^[20,21]	MHz	Trimmed for 5 V or 3.3 V operation using factory trim values. See Figure 8 on page 18. SLIMO mode = 0.
F _{IMO6}	IMO frequency for 6 MHz	5.5	6	6.5 ^[20,21]	MHz	Trimmed for 5 V or 3.3 V operation using factory trim values. See Figure 8 on page 18. SLIMO mode = 1.
F _{CPU1}	CPU frequency (5 V nominal)	0.937	24	24.6 ^[20]	MHz	SLIMO mode = 0.
F _{CPU2}	CPU frequency (3.3 V nominal)	0.937	12	12.3 ^[21]	MHz	SLIMO mode = 0.
F _{48M}	Digital PSoC block frequency	0	48	49.2 ^[20,22]	MHz	Refer to the AC Digital Block Specifications.
F _{24M}	Digital PSoC block frequency	0	24	24.6 ^[22]	MHz	
F _{32K1}	ILO frequency	15	32	64	kHz	
F _{32K2}	External crystal oscillator	-	32.768	_	kHz	Accuracy is capacitor and crystal dependent. 50% duty cycle.
F _{32K_U}	ILO untrimmed frequency	5	-	100	kHz	After a reset and before the M8C starts to run, the ILO is not trimmed. See the System Resets section of the PSoC Technical Reference Manual for details on timing this
F _{PLL}	PLL frequency	-	23.986	_	MHz	Is a multiple (x732) of crystal frequency.
T _{PLLSLEW}	PLL lock time	0.5	-	10	ms	
T _{PLLSLEWSLOW}	PLL lock time for low gain setting	0.5	-	50	ms	
T _{OS}	External crystal oscillator startup to 1%	-	1700	2620	ms	
TOSACC	External crystal oscillator startup to 100 ppm	_	2800	3800	ms	The crystal oscillator frequency is within 100 ppm of its final value by the end of the T _{osacc} period. Correct operation assumes a properly loaded 1 μ W maximum drive level 32.768 kHz crystal. 3.0 V \leq V _{DD} \leq 5.5 V, $-40 \degree$ C \leq T _A \leq 85 \degree C.
t _{XRST}	External reset pulse width	10	-	-	μS	

Notes

- 19. Errata: When the device is operated within 0 °C to 70 °C, the frequency tolerance is reduced to $\pm 2.5\%$, but if operated at extreme temperature (below 0 °C or above 70 °C), frequency tolerance deviates from $\pm 2.5\%$ to $\pm 5\%$. For more information, see "Errata" on page 67. 20. 4.75 V < V_{DD} < 5.25 V. 21. 3.0 V < V_{DD} < 3.6 V. See application note Adjusting PSoC[®] Trims for 3.3 V and 2.7 V Operation AN2012 for information on trimming for operation at 3.3 V.

- 22. See the individual user module datasheets for information on maximum frequencies for user modules.
- 23. Refer to Cypress Jitter Specifications application note, Understanding Datasheet Jitter Specifications for Cypress Timing Products AN5054 for more information.



Table 30. 2.7-V AC Chip-Level Specifications

Symbol	Description	Min	Тур	Мах	Units	Notes
F _{IMO12}	IMO frequency for 12 MHz	11.5	12	12.7 ^[27, 28]	MHz	Trimmed for 2.7 V operation using factory trim values. See Figure 8 on page 18. SLIMO mode = 1.
F _{IMO6}	IMO frequency for 6 MHz	5.5	6	6.5 ^[27, 28]	MHz	Trimmed for 2.7 V operation using factory trim values. See Figure 8 on page 18. SLIMO mode = 1.
F _{CPU1}	CPU frequency (2.7 V nominal)	0.937	3	3.15 ^[27]	MHz	SLIMO mode = 0.
F _{BLK27}	Digital PSoC block frequency (2.7 V nominal)	0	12	12.7 ^[27, 28]	MHz	Refer to the AC Digital Block Specifications.
F _{32K1}	ILO frequency	8	32	96	kHz	
F _{32K_U}	ILO untrimmed frequency	5	-	100	kHz	After a reset and before the M8C starts to run, the ILO is not trimmed. See the System Resets section of the PSoC Technical Reference Manual for details on timing this
t _{XRST}	External reset pulse width	10	-	-	μs	
DC12M	12 MHz duty cycle	40	50	60	%	
DC _{ILO}	ILO duty cycle	20	50	80	%	
F _{MAX}	Maximum frequency of signal on row input or row output.	-	-	12.7	MHz	
SR _{POWER_UP}	Power supply slew rate	-	-	250	V/ms	V _{DD} slew rate during power-up.
t _{POWERUP}	Time from end of POR to CPU executing code	-	16	100	ms	Power-up from 0 V. See the System Resets section of the PSoC Technical Reference Manual.
t _{jit_IMO} ^[29]	12 MHz IMO cycle-to-cycle jitter (RMS)	_	400	1000	ps	N = 32
	12 MHz IMO long term N cycle-to-cycle jitter (RMS)	-	600	1300	ps	
	12 MHz IMO period jitter (RMS)	-	100	500	ps	
t _{jit_PLL} ^[29]	12 MHz IMO cycle-to-cycle jitter (RMS)	_	400	1000	ps	N = 32
	12 MHz IMO long term N cycle-to-cycle jitter (RMS)	-	700	1300		
	12 MHz IMO period jitter (RMS)	-	300	500		

Notes 27. 2.4 V < V_{DD} < 3.0 V. 28. Refer to application note Adjusting PSoC[®] Trims for 3.3 V and 2.7 V Operation – AN2012 for information on trimming for operation at 3.3 V. 29. Refer to Cypress Jitter Specifications application note, Understanding Datasheet Jitter Specifications for Cypress Timing Products – AN5054 for more information.



Table 35. 2.7-V AC Operational Amplifier Specifications

Symbol	Description	Min	Тур	Мах	Units
t _{ROA}	Rising settling time from 80% of ΔV to 0.1% of ΔV (10 pF load, unity gain) Power = low, Opamp bias = low Power = medium, Opamp bias = high			3.92 0.72	hs hs
t _{SOA}	Falling settling time from 20% of ΔV to 0.1% of ΔV (10 pF load, unity gain) Power = low, Opamp bias = low Power = medium, Opamp bias = high			5.41 0.72	hs hs
SR _{ROA}	Rising slew rate (20% to 80%) (10 pF load, unity gain) Power = low, Opamp bias = low Power = medium, Opamp bias = high	0.31 2.7			V/µs V/µs
SR _{FOA}	Falling slew rate (20% to 80%) (10 pF load, unity gain) Power = low, Opamp bias = low Power = medium, Opamp bias = high	0.24 1.8			V/µs V/µs
BW _{OA}	Gain bandwidth product Power = low, Opamp bias = low Power = medium, Opamp bias = high	0.67 2.8			MHz MHz
E _{NOA}	Noise at 1 kHz (Power = medium, Opamp bias = high)	-	100	-	nV/rt-Hz

When bypassed by a capacitor on P2[4], the noise of the analog ground signal distributed to each block is reduced by a factor of up to 5 (14 dB). This is at frequencies above the corner frequency defined by the on-chip 8.1 K resistance and the external capacitor.

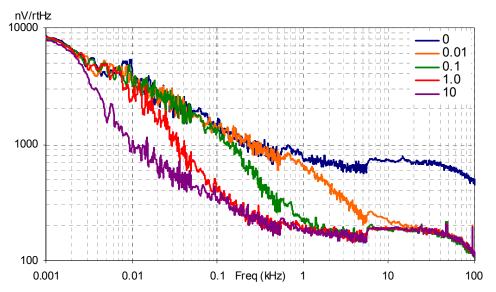


Figure 14. Typical AGND Noise with P2[4] Bypass

At low frequencies, the opamp noise is proportional to 1/f, power independent, and determined by device geometry. At high frequencies, increased power level reduces the noise spectrum level.



Table 44. 2.7-V AC External Clock Specifications

Symbol	Description	Min	Тур	Max	Units	Notes
F _{OSCEXT}	Frequency with CPU clock divide by 1 ^[34]	0.093	-	12.3	MHz	
F _{OSCEXT}	Frequency with CPU clock divide by 2 or greater ^[35]	0.186	-	12.3	MHz	
-	High period with CPU clock divide by 1	41.7	-	5300	ns	
-	Low period with CPU clock divide by 1	41.7	-	-	ns	
-	Power-up IMO to switch	150	-	-	μs	

AC Programming Specifications

Table 45 lists the guaranteed maximum and minimum specifications for the voltage and temperature ranges: 4.75 V to 5.25 V and -40 °C \leq T_A \leq 85 °C, 3.0 V to 3.6 V and -40 °C \leq T_A \leq 85 °C, or 2.4 V to 3.0 V and -40 °C \leq T_A \leq 85 °C, respectively. Typical parameters are measured at 5 V, 3.3 V, and 2.7 V at 25 °C and are for design guidance only.

Table 45. AC Programming Specifications

Symbol	Description	Min	Тур	Max	Units	Notes
t _{RSCLK}	Rise time of SCLK	1	1 – 20 ns			
t _{FSCLK}	Fall time of SCLK	1	-	20	ns	
t _{SSCLK}	Data setup time to falling edge of SCLK	40	-	-	ns	
t _{HSCLK}	Data hold time from falling edge of SCLK	40	-	-	ns	
F _{SCLK}	Frequency of SCLK	0	-	8	MHz	
t _{ERASEB}	Flash erase time (block)	-	20	-	ms	
t _{WRITE}	Flash block write time	-	80	-	ms	
t _{DSCLK}	Data out delay from falling edge of SCLK	-	-	45	5 ns V _{DD} > 3.6	
t _{DSCLK3}	Data out delay from falling edge of SCLK	-	-	50 ns $3.0 \le V_{DD} \le 3.6$		$3.0 \le V_{DD} \le 3.6$
t _{DSCLK2}	Data out delay from falling edge of SCLK	-	-	70	70 ns $2.4 \le V_{DD} \le 3$	
t _{ERASEALL}	Flash erase time (Bulk)	-			Erase all blocks and protection fields at once	
t _{PROGRAM_HOT}	Flash block erase + flash block write time	-	-	200 ^[36]	ms	$0~^\circ C \leq Tj \leq 100~^\circ C$
t _{PROGRAM_COLD}	Flash block erase + flash block write time	-	-	400 ^[36]	ms	$-40~^\circ C \le Tj \le 0~^\circ C$

Notes

34. Maximum CPU frequency is 12 MHz at 3.3 V. With the CPU clock divider set to 1, the external clock must adhere to the maximum frequency and duty cycle requirements.

^{35.} If the frequency of the external clock is greater than 12 MHz, the CPU clock divider must be set to 2 or greater. In this case, the CPU clock divider ensures that the fifty percent duty cycle requirement is met.

^{36.} For the full industrial range, you must employ a temperature sensor user module (FlashTemp) and feed the result to the temperature argument before writing Refer to the Flash APIs application note Design Aids – Reading and Writing PSoC[®] Flash – AN2015 for more information.

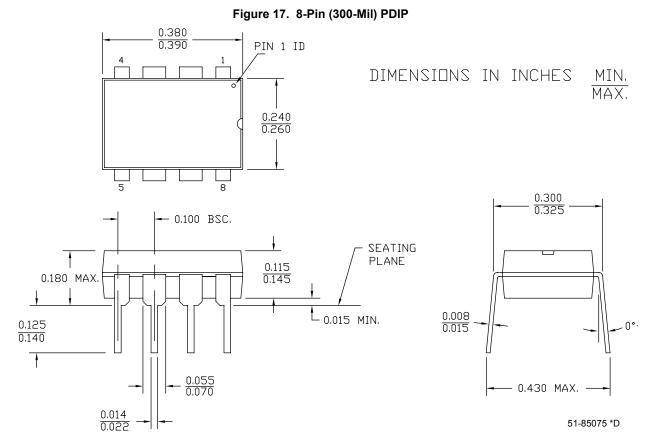


Packaging Information

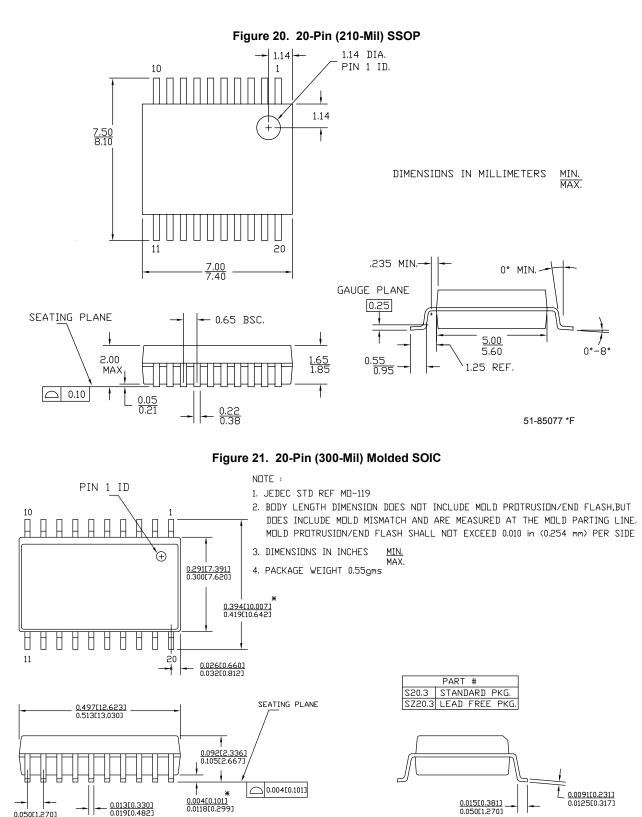
This section illustrates the packaging specifications for the CY8C24x23A PSoC device, along with the thermal impedances for each package and the typical package capacitance on crystal pins.

Important Note Emulation tools may require a larger area on the target PCB than the chip's footprint. For a detailed description of the emulation tools' dimensions, see the emulator pod drawings at http://www.cypress.com/design/MR10161.

Packaging Dimensions







0.050[1.270] TYP.

0.013[0.330] 0.019[0.482]

0.015[0.381] 0.050[1.270]

51-85024 *F



Acronyms

Acronyms Used

Table 53 lists the acronyms that are used in this document.

Table 53. Acronyms Used in this Datasheet

Acronym	Description	Acronym	Description
AC	alternating current	MIPS	million instructions per second
ADC	analog-to-digital converter	OCD	on-chip debug
API	application programming interface	PCB	printed circuit board
CMOS	complementary metal oxide semiconductor	PDIP	plastic dual-in-line package
CPU	central processing unit	PGA	programmable gain amplifier
CRC	cyclic redundancy check	PLL	phase-locked loop
СТ	continuous time	POR	power on reset
DAC	digital-to-analog converter	PPOR	precision power on reset
DC	direct current	PRS	pseudo-random sequence
DTMF	dual-tone multi-frequency	PSoC®	Programmable System-on-Chip
ECO	external crystal oscillator	PWM	pulse width modulator
EEPROM	electrically erasable programmable read-only memory	QFN	quad flat no leads
GPIO	general purpose I/O	RTC	real time clock
ICE	in-circuit emulator	SAR	successive approximation
IDE	integrated development environment	SC	switched capacitor
ILO	internal low speed oscillator	SLIMO	slow IMO
IMO	internal main oscillator	SMP	switch mode pump
I/O	input/output	SOIC	small-outline integrated circuit
IrDA	infrared data association	SPI [™]	serial peripheral interface
ISSP	in-system serial programming	SRAM	static random access memory
LCD	liquid crystal display	SROM	supervisory read only memory
LED	light-emitting diode	SSOP	shrink small-outline package
LPC	low power comparator	UART	universal asynchronous receiver / transmitter
LVD	low voltage detect	USB	universal serial bus
MAC	multiply-accumulate	WDT	watchdog timer
MCU	microcontroller unit	XRES	external reset

Reference Documents

CY8CPLC20, CY8CLED16P01, CY8C29x66, CY8C27x43, CY8C24x94, CY8C24x23, CY8C24x23A, CY8C22x13, CY8C21x34, CY8C21x23, CY7C64215, CY7C603xx, CY8CNP1xx, and CYWUSB6953 PSoC® Programmable System-on-Chip Technical Reference Manual (TRM) (001-14463)

Design Aids – Reading and Writing PSoC[®] Flash – AN2015 (001-40459)

Application Notes for Surface Mount Assembly of Amkor's MicroLeadFrame (MLF) Packages – available at http://www.amkor.com.



Document Conventions

Units of Measure

Table 54 lists the unit sof measures.

Table 54. Units of Measure

Symbol	Unit of Measure	Symbol	Unit of Measure
kB	1024 bytes	μs	microsecond
dB	decibels	ms	millisecond
°C	degree Celsius	ns	nanosecond
fF	femto farad	ps	picosecond
pF	picofarad	μV	microvolts
kHz	kilohertz	mV	millivolts
MHz	megahertz	mVpp	millivolts peak-to-peak
rt-Hz	root hertz	nV	nanovolts
kΩ	kilohm	V	volts
Ω	ohm	μW	microwatts
μA	microampere	W	watt
mA	milliampere	mm	millimeter
nA	nanoampere	ppm	parts per million
pА	pikoampere	%	percent
mH	millihenry		· ·

Numeric Conventions

Hexadecimal numbers are represented with all letters in uppercase with an appended lowercase 'h' (for example, '14h' or '3Ah'). Hexadecimal numbers may also be represented by a '0x' prefix, the C coding convention. Binary numbers have an appended lowercase 'b' (for example, 01010100b' or '01000011b'). Numbers not indicated by an 'h' or 'b' are decimals.

Glossary

active high	10.A logic signal having its asserted state as the logic 1 state. 11.A logic signal having the logic 1 state as the higher voltage of the two states.
analog blocks	The basic programmable opamp circuits. These are SC (switched capacitor) and CT (continuous time) blocks. These blocks can be interconnected to provide ADCs, DACs, multi-pole filters, gain stages, and much more.
analog-to-digital (ADC)	A device that changes an analog signal to a digital signal of corresponding magnitude. Typically, an ADC converts a voltage to a digital number. The digital-to-analog (DAC) converter performs the reverse operation.
API (Application Programming Interface)	A series of software routines that comprise an interface between a computer application and lower level services and functions (for example, user modules and libraries). APIs serve as building blocks for programmers that create software applications.
asynchronous	A signal whose data is acknowledged or acted upon immediately, irrespective of any clock signal.
Bandgap reference	A stable voltage reference design that matches the positive temperature coefficient of VT with the negative temperature coefficient of VBE, to produce a zero temperature coefficient (ideally) reference.
bandwidth	 The frequency range of a message or information processing system measured in hertz. The width of the spectral region over which an amplifier (or absorber) has substantial gain (or loss); it is sometimes represented more specifically as, for example, full width at half maximum.



Glossary (continued)

duty cycle	The relationship of a clock period high time to its low time, expressed as a percent.
emulator	Duplicates (provides an emulation of) the functions of one system with a different system, so that the second system appears to behave like the first system.
external reset (XRES)	An active high signal that is driven into the PSoC device. It causes all operation of the CPU and blocks to stop and return to a pre-defined state.
flash	An electrically programmable and erasable, non-volatile technology that provides users with the programmability and data storage of EPROMs, plus in-system erasability. Non-volatile means that the data is retained when power is off.
Flash block	The smallest amount of Flash ROM space that may be programmed at one time and the smallest amount of Flash space that may be protected. A Flash block holds 64 bytes.
frequency	The number of cycles or events per unit of time, for a periodic function.
gain	The ratio of output current, voltage, or power to input current, voltage, or power, respectively. Gain is usually expressed in dB.
I ² C	A two-wire serial computer bus by Philips Semiconductors (now NXP Semiconductors). I2C is an Inter-Integrated Circuit. It is used to connect low-speed peripherals in an embedded system. The original system was created in the early 1980s as a battery control interface, but it was later used as a simple internal bus system for building control electronics. I2C uses only two bi-directional pins, clock and data, both running at +5 V and pulled high with resistors. The bus operates at 100 kbits/second in standard mode and 400 kbits/second in fast mode.
ICE	The in-circuit emulator that allows users to test the project in a hardware environment, while viewing the debugging device activity in a software environment (PSoC Designer).
input/output (I/O)	A device that introduces data into or extracts data from a system.
interrupt	A suspension of a process, such as the execution of a computer program, caused by an event external to that process, and performed in such a way that the process can be resumed.
interrupt service routine (ISR)	A block of code that normal code execution is diverted to when the M8C receives a hardware interrupt. Many interrupt sources may each exist with its own priority and individual ISR code block. Each ISR code block ends with the RETI instruction, returning the device to the point in the program where it left normal program execution.
jitter	1. A misplacement of the timing of a transition from its ideal position. A typical form of corruption that occurs on serial data streams.
	The abrupt and unwanted variations of one or more signal characteristics, such as the interval between successive pulses, the amplitude of successive cycles, or the frequency or phase of successive cycles.
low-voltage detect (LVD)	A circuit that senses V_{DD} and provides an interrupt to the system when V_{DD} falls lower than a selected threshold.
M8C	An 8-bit Harvard-architecture microprocessor. The microprocessor coordinates all activity inside a PSoC by interfacing to the Flash, SRAM, and register space.
master device	A device that controls the timing for data exchanges between two devices. Or when devices are cascaded in width, the master device is the one that controls the timing for data exchanges between the cascaded devices and an external interface. The controlled device is called the <i>slave device</i> .



Errata

This section describes the errata for the CY8C24xxxA device family. Details include errata trigger conditions, scope of impact, available workaround, and silicon revision applicability. Contact your local Cypress Sales Representative if you have questions.

Part Numbers Affected

Part Number	Ordering Information
CY8C24123A	CY8C24123A-24PXI
	CY8C24123A-24SXI
	CY8C24123A-24SXIT
	CY8C24223A-24PXI
	CY8C24223A-24PVXI
	CY8C24223A-24PVXIT
	CY8C24223A-24SXI
	CY8C24223A-24SXIT
	CY8C24423A-24PXI
	CY8C24423A-24PVXI
	CY8C24423A-24PVXIT
	CY8C24423A-24SXI
	CY8C24423A-24SXIT
	CY8C24423A-24LFXI
	CY8C24423A-24LTXI
	CY8C24423A-24LTXIT
	CY8C24000A-24PVXI

CY8C24123A Qualification Status

Product Status: Production

CY8C24123A Errata Summary

The following table defines the errata applicability to available CY8C24123A family devices.

Items	Part Number	Silicon Revision	Fix Status
[1.]. Internal Main Oscillator (IMO) Tolerance Deviation at Temperature Extremes	CY8C24123A		No silicon fix planned. Workaround is required.

1. Internal Main Oscillator (IMO) Tolerance Deviation at Temperature Extremes

Problem Definition

Asynchronous Digital Communications Interfaces may fail framing beyond 0 to 70 °C. This problem does not affect end-product usage between 0 and 70 °C.

Parameters Affected

The IMO frequency tolerance. The worst case deviation when operated below 0° C and above +70 °C and within the upper and lower datasheet temperature range is $\pm 5\%$.

Trigger Condition(S)

The asynchronous Rx/Tx clock source IMO frequency tolerance may deviate beyond the data sheet limit of $\pm 2.5\%$ when operated beyond the temperature range of 0 to +70 °C.

- Scope of Impact
 - This problem may affect UART, IrDA, and FSK implementations.
- Workaround

Implement a quartz crystal stabilized clock source on at least one end of the asynchronous digital communications interface.

Fix Status

Silicon fix is not planned. The workaround mentioned above should be used.



Document History Page (continued)

	Document Title: CY8C24123A/CY8C24223A/CY8C24423A, PSoC [®] Programmable System-on-Chip Document Number: 38-12028				
Revision	ECN	Orig. of Change	Submission Date	Description of Change	
*T	4066332	PMAD	07/17/2013	Added Errata Footnotes (Note 1, 19). Updated PSoC Functional Overview: Updated PSoC Core: Added Note 1 and referred the same note in 4th paragraph in PSoC Core. Updated Electrical Specifications: Updated AC Electrical Characteristics: Updated AC Chip-Level Specifications: Added Note 19 and referred the same note in F _{IMO24} parameter. Updated minimum and maximum values of F _{IMO24} parameter. Updated AC Digital Block Specifications: Replaced all instances of maximum value "49.2" with "50.4" and "24.6" with "25.2" in Table 37.	
*U	4479672	RJVB	08/20/2014	Updated in new template. Updated Packaging Information: Updated Packaging Dimensions: spec 51-85011 – Changed revision from *C to *D. spec 51-85024 – Changed revision from *E to *F. spec 51-85026 – Changed revision from *G to *H. Updated Errata: Updated CY8C24123A Errata Summary: Updated details in "Fix Status" column in the table. Updated details in "Fix Status" bulleted point below the table.	
*V	4622083	RKRM	01/13/2015	Completing Sunset Review. Added More Information section.	